



# **GENERAL BACKGROUND ON SHAPE MEMORY ALLOYS**

**Santo Padula, II**  
**High Temperature and Smart Alloys Branch**  
**Materials and Structures Division**  
**NASA Glenn Research Center**



# NASA GRC Shape Memory Alloy (SMA) Team

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- A photograph of the Glenn Research Center building at night, illuminated from within. The building has a large, curved roof and the words "Glenn Research Center" are visible on the facade. The scene is set against a dark sky with some lights in the distance.
- **Othmane Benafan**
  - **Glen Bigelow**
  - **Chris Dellacorte**
  - **Malcolm Stanford**
  - **Fransua Thomas**
  - **Santo Padula II**
  - **Darrell Gaydosh**
  - **Anita Garg**
  - **Timothy Halsmer**
  - **Ron Noebe**

**Branch Chief: Bob Carter**



# Shape Memory Alloys (SMAs): An Introduction

- ✓ **Metal alloys that have a “memory.”**
- ✓ **These materials have the ability to remember and recover their original shapes against significant externally applied loads.**
- ✓ **SMAs exhibit a solid-to-solid, reversible phase transformation that can be induced by the application of force or temperature.**
- ✓ **NiTi most common alloy – highest work output/energy density.**



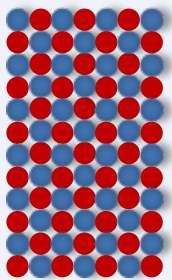
# **Basic Differences between Conventional Metals and Shape Memory Alloys (SMA)**



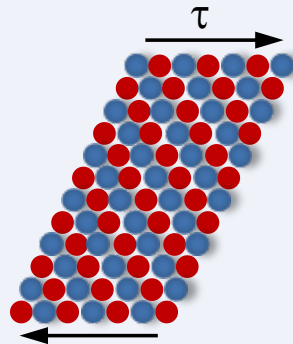
# Conventional Material Deformation

- Require imposed forces/stresses only generate **ELASTIC** deformation.

## Undeformed Crystal



→  
Elastic  
Deformation

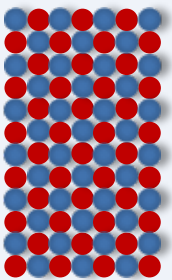


### *Elastic deformations*

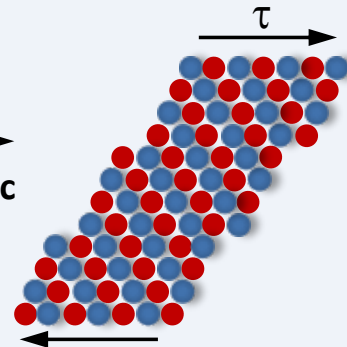
- ✓ Distort the material lattice through bond stretch.
- ✓ Deformations are **REVERSIBLE**.

- If imposed forces/stresses create deformations that can't be accommodated by **ELASTIC** distortion of lattice – **PLASTIC** deformation (bond breakage).

## Undeformed Crystal



→  
Elastic & Plastic  
Deformation



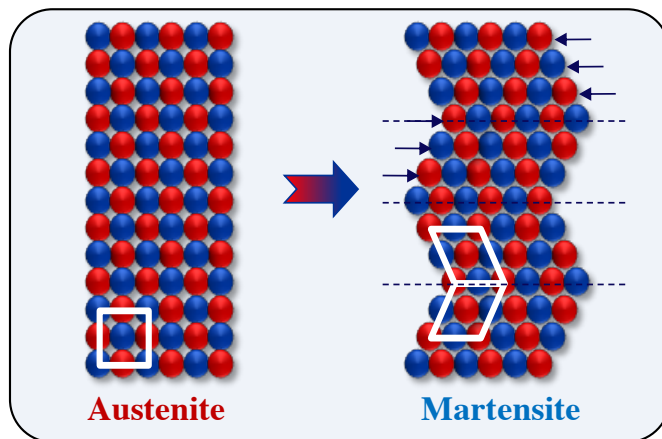
### *Inelastic deformations - Plasticity*

- ✓ Distort the material lattice through microstructural rearrangement (metallic materials - slip).
- ✓ Deformations are **IRREVERSIBLE**.
- ✓ Can only dissipate energy.

# Shape Memory Alloys: An Introduction

- ❑ Don't accommodate deformations through elastic bond stretch.
- ❑ SMAs exhibit a solid-to-solid, reversible phase transformation.
- ❑ Transformation capable of storing **over 30x** the deformation that can be done in an **elastic** bond stretch.

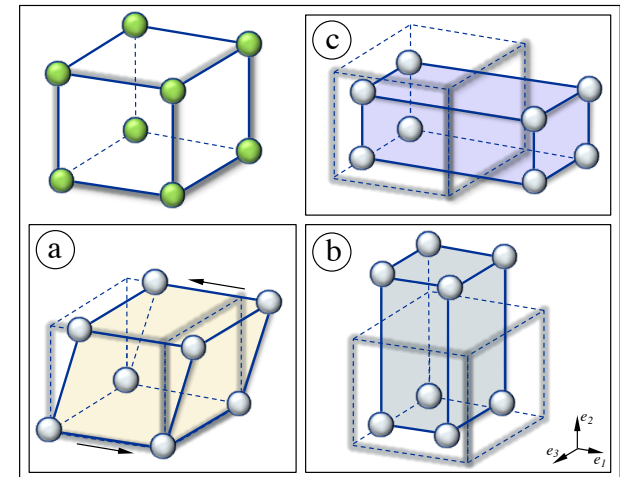
Simplified 2D



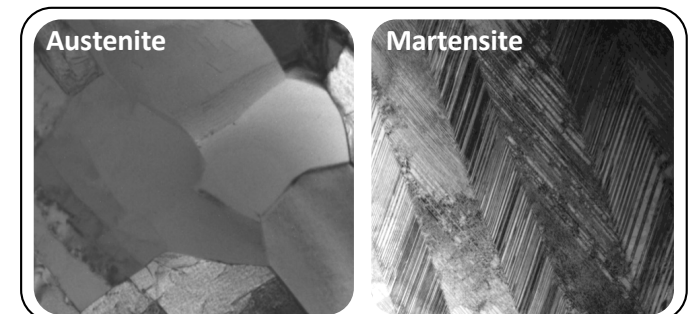
## ❑ How?

- ✓ Bain strain → (lattice deformation)
- ✓ Lattice invariant shear → (accommodation)
- ✓ **Inelastic** deformation (transient twinning) → **REVERSIBLE**

Variant selection



Microstructure

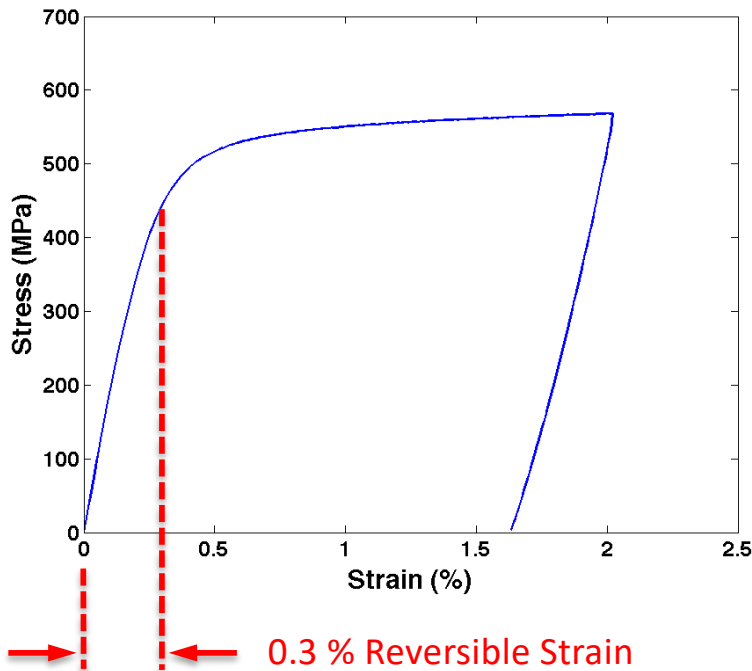


Courtesy of A. Garg



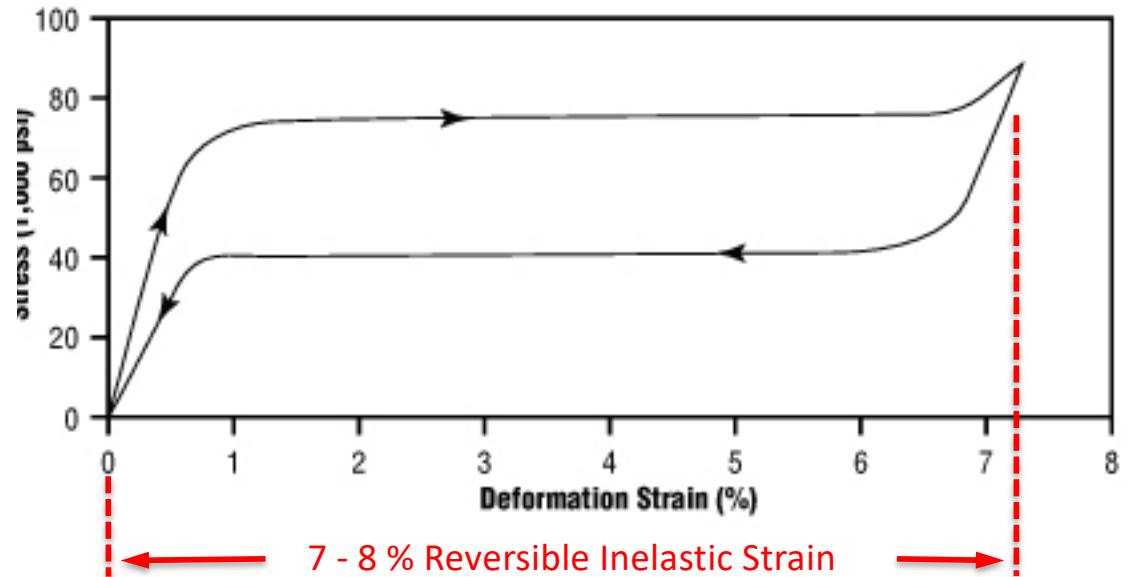
# Mechanical Component Design Constructs

### Conventional Design



Design so that component remains *elastic*

### SMA Design



Design so that component takes advantage of *inelastic*

Shape Memory Alloys (SMAs) allow for > 10 times the strain to be accommodated in the component, allowing designs that could never be contemplated with conventional materials



# Practical Example of Difference between Conventional Material and Shape Memory Alloys

**Brass**

*Plastic Buckling & Fracture*



**Stainless Steel**

*Plastic Deformation*



**Shape Memory Alloy**

*Reversible Pseudoelasticity*



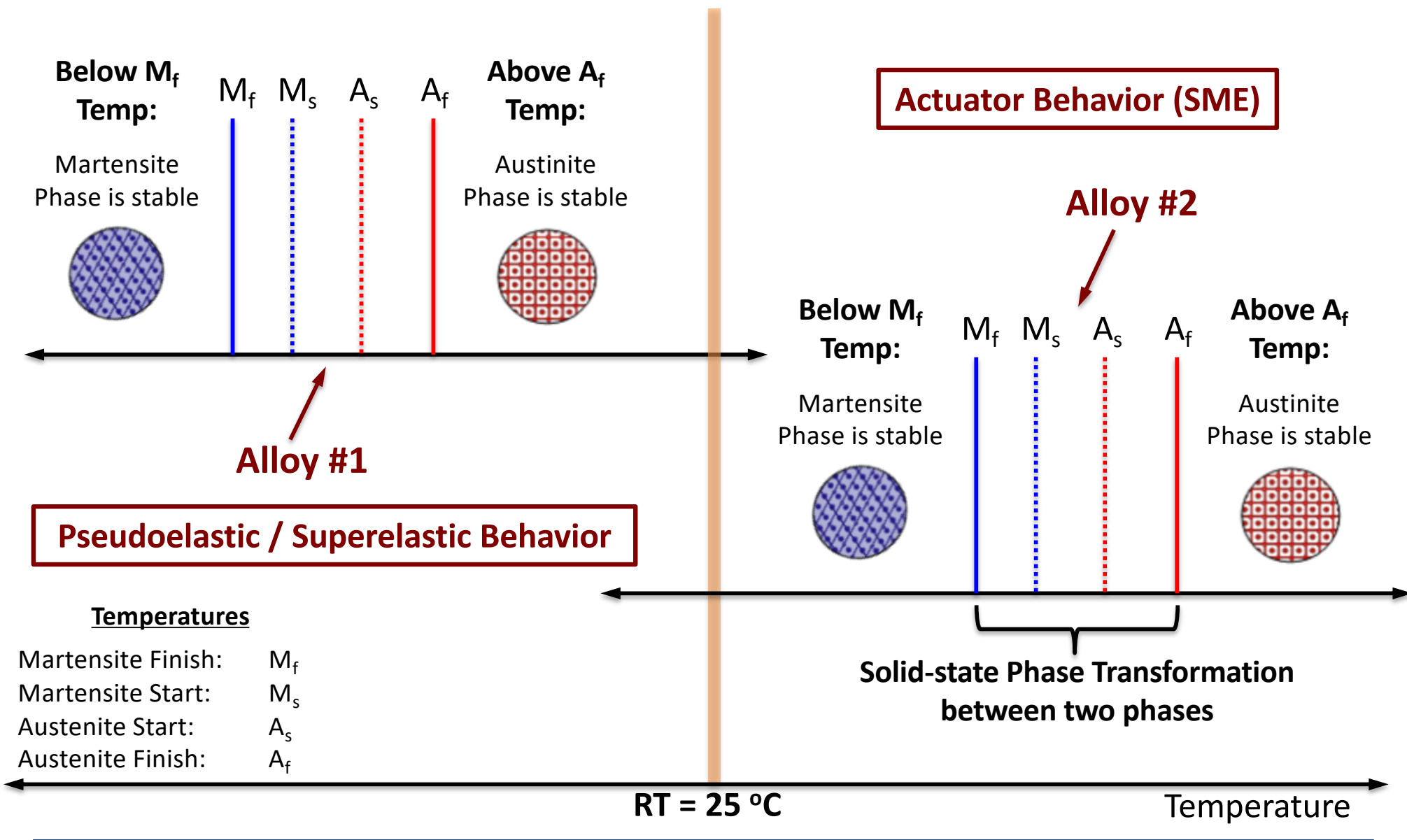
The reversible, solid-state phase transformation that occurs in Shape Memory Alloys (SMAs) is capable of storing **over 30x** the deformation that can be done in a material required to accommodate the deformation solely through **elastic** bond stretch.



# **Different Modes of Operation When Using Shape Memory Alloys (SMA)**



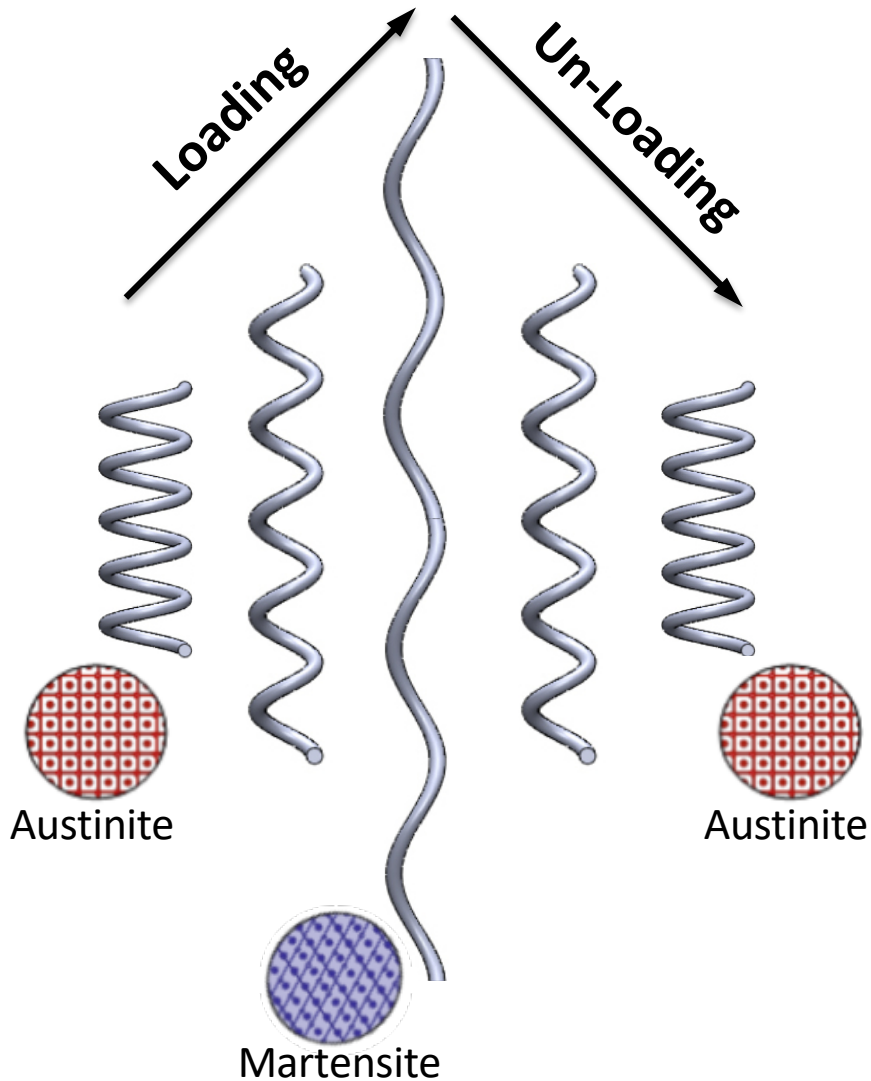
# Alloy Chemistry Alters Temperature at Which Phase Transformation Happens



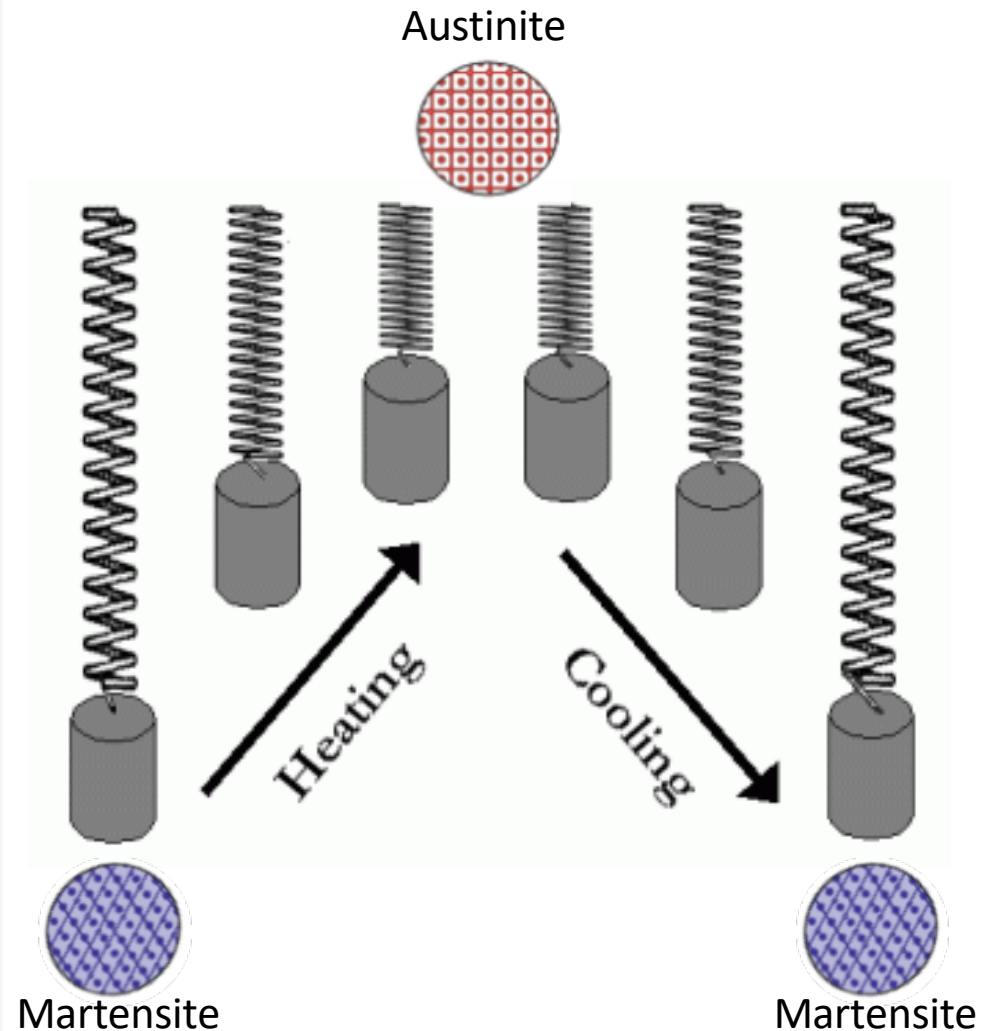


# Examples of Shape Memory Alloys in Action

## Mechanically Induced Transformation (Pseudoelastic / Superelastic Behavior)



## Thermally Induced Transformation Actuator Behavior (SME)





# Examples of the Two Transformation Types

## Mechanically Induced Transformation



## Thermally Induced Transformation



Courtesy of UCF

- SMA actuators can generate motion in one dimension (wire form), two dimensions (bending of a bar) or even motion in a more complex three dimensions (springs, honeycombs, panels)
- Functionality: Tension (e.g., wires, springs), compression (e.g., rods, springs), bending (e.g., beams, plates), torsion (e.g., rods, tubes, and springs)

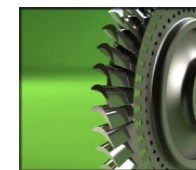
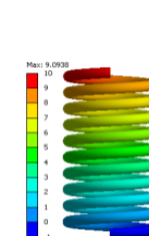
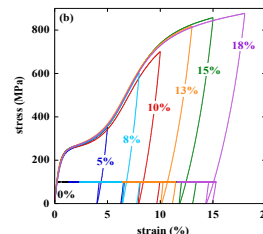
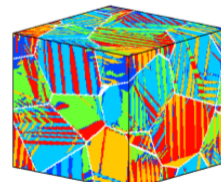
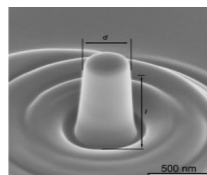
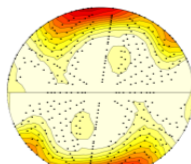
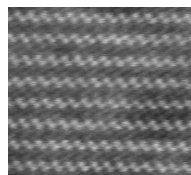




# **Work Being Conducted by Shape Memory Alloy (SMA) Team at GRC**



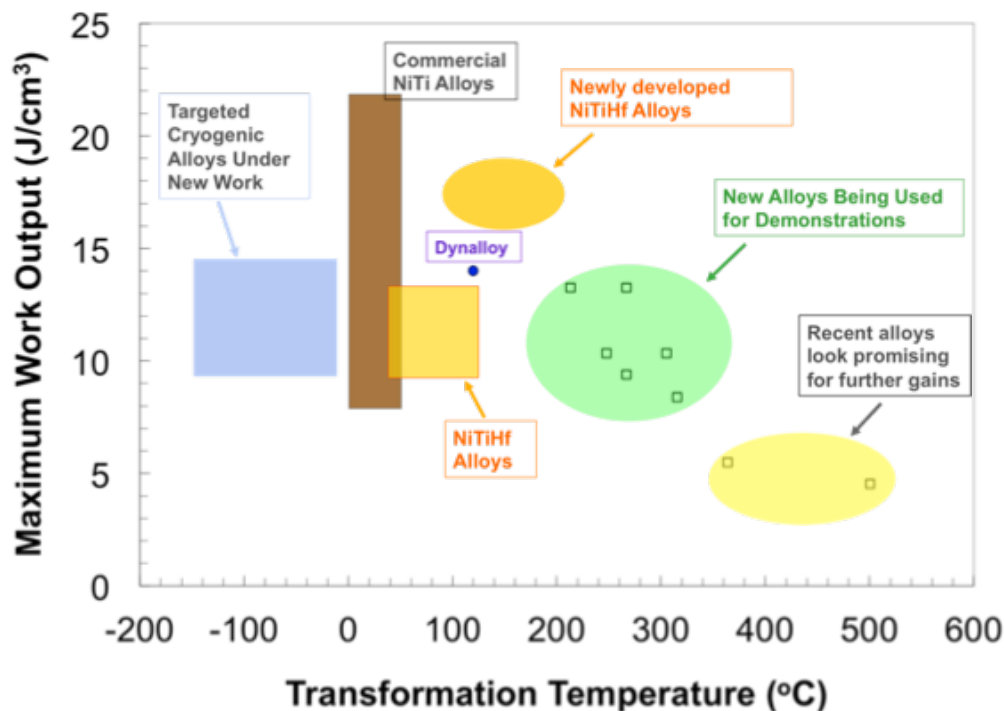
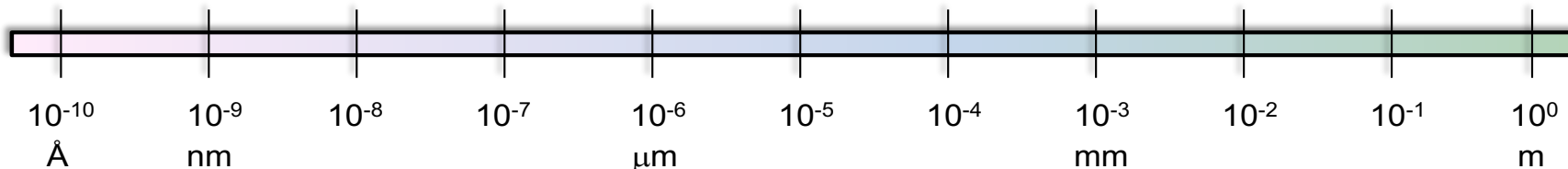
# Research Driven Approach to Product Development



**ATOMIC SCALE**  
(NANOMATERIALS)

**MICRO-SCALE**  
(MICROSTRUCTURES)

**STRUCTURAL SCALE**  
(COMPONENTS)



- **WIDEN TEMPERATURE** range over which they can be used.
- Improving **WORK** capability.
- Create materials that have **BETTER STABILITY (REPEATABLE PERFORMANCE)**.
- **BETTER WEAR** and **CORROSION RESITANCE**.
- **HIGHER DURABILITY** and **LONGER LIFE**.



# Examples of NASA Applications Using Shape Memory Alloys (SMA)



# Shape Memory Alloy (SMA) Non-Pneumatic Tires

❑ Utilization of **Nickel-titanium (NiTi)**, “*psuedoelastic*” Shape Memory Alloy (SMA).

❑ Compliant tire technology:

- ✓ Carry significant load
- ✓ Envelop obstacles without permanent deformation or damage

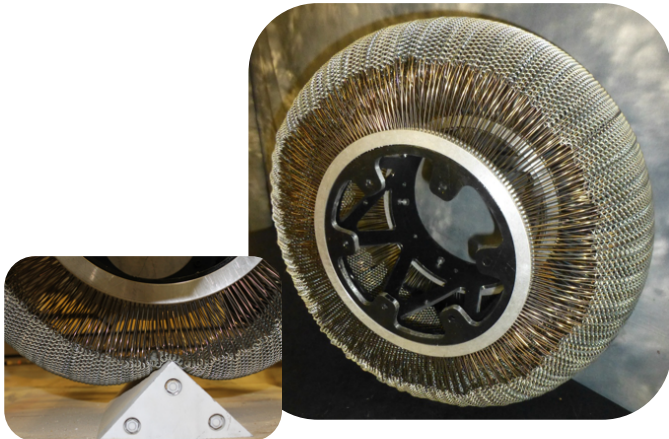
❑ Two types of construction currently available:

- ✓ Spring Tire
  - Can carry much higher loads than coiled designs
  - More easily scalable for changes in load and tire size requirements
- ✓ Radially Stiffened Tire

Generation 1 – 890 N (~200 lbf.)



Generation 2 – 2200 N (~500 lbf.)



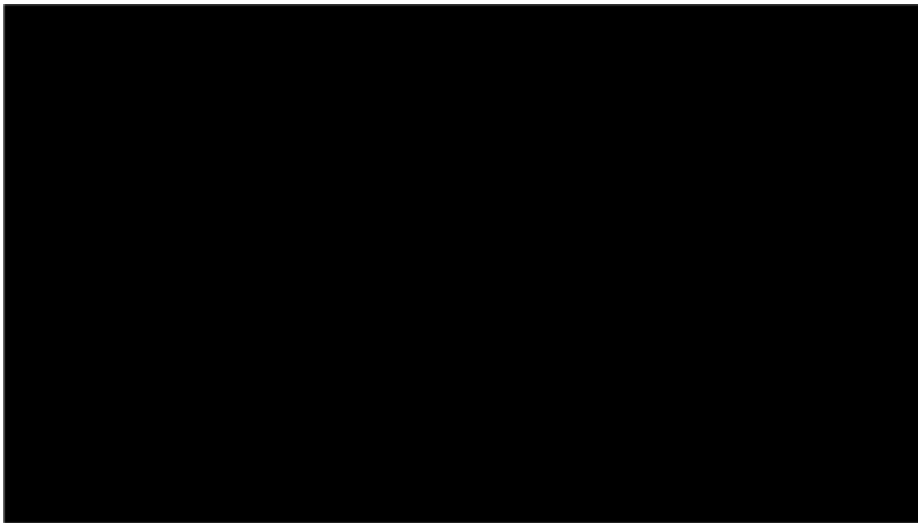
Generation 3 – 8900 N (~2000 lbf.)





# Shape Memory Alloy (SMA) Non-Pneumatic Tires

Generation 1 – Spring Tire



Generation 3 – Radially-Stiffened Tire



Non-pneumatic tire designs have the potential to open the door to thinking about wheel and brake assemblies in a way never before possible.





# Wing-tip actuation using SMAs (Ground test)



Wings at  
 $0^\circ$



Wings up  
 $+75^\circ$



Wings down  
 $-75^\circ$



# Wing-tip actuation using SMAs (Flight test)

[https://www.youtube.com/watch?v=9y1kkG2\\_QpE](https://www.youtube.com/watch?v=9y1kkG2_QpE)



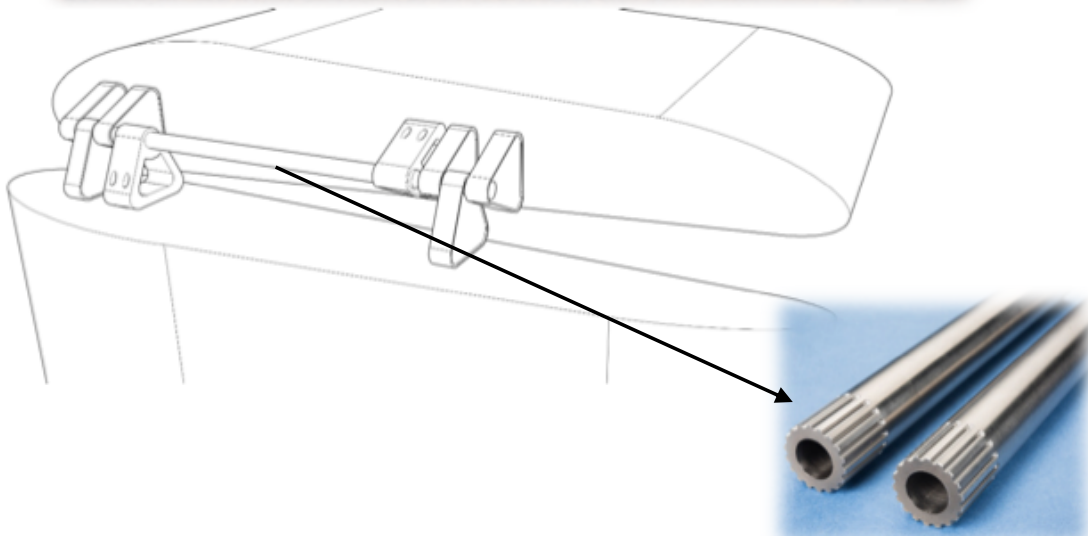
Wings at  $0^\circ$



Wings up  $+75^\circ$

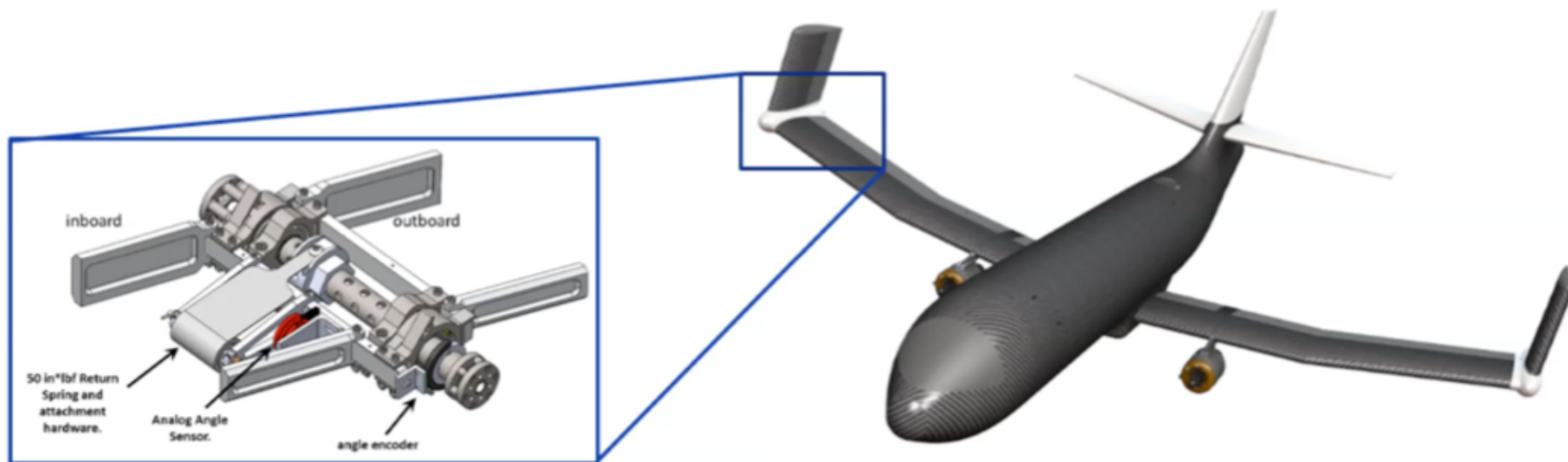


Wings down  $-75^\circ$





# Wing-tip actuation using SMAs (Close-up Demo)



## PTERA Test Aircraft Specs:

- Manufacturer: AREA-I
- 180 lb GVW, 40lb payload
- 11.3ft span
- 144 kts max airspeed
- Twin JetCat P220
- Research instrumentation

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*Questions?*

