



Overview of RS-25 Adaptation Hot-Fire Test Series for SLS, Status and Lessons Learned

Naveen Vetcha

ERC Inc./Jacobs Space Exploration Group

NASA Marshall Space Flight Center

7/9/2018

Contributions from:

Matt Strickland, Jacobs Space Exploration Group

Ken Philippart, BRC/Jacobs Space Exploration Group

Tom Giel, ERC Inc./Jacobs Space Exploration Group

JACOBS[®]

www.jacobs.com | worldwide



Outline

1. Introduction
2. System Requirements
3. Controller Development
4. System DDT&E
5. Engine System Testing
6. Conclusion





Introduction



NASA authorization act - 2010

42 USC 18322. **SEC. 302. SPACE LAUNCH SYSTEM AS FOLLOW-ON LAUNCH VEHICLE TO THE SPACE SHUTTLE.**

(a) **UNITED STATES POLICY.**—It is the policy of the United States that NASA develop a Space Launch System as a follow-on to the Space Shuttle that can access cis-lunar space and the regions of space beyond low-Earth orbit in order to enable the United States to participate in global efforts to access and develop this increasingly strategic region.

Minimum Capability requirements for the launch vehicle are:

- Capability to lift payloads weighing between 70 to 100 metric tons into low-Earth orbit (LEO) in preparation for transit for missions beyond LEO,
- Capability to carry an integrated upper Earth departure stage bringing the total lift capability to 130 metric tons or more,
- Capability to lift the Orion Multi-Purpose Crew Vehicle (MPCV), and
- Capability to serve as a backup system for supplying and supporting International Space Station (ISS) cargo requirements or crew delivery requirements not otherwise met by available vehicles.

Space Launch System (SLS)

CPL = Co-manifested Payload

EUS = Exploration Upper Stage

ICPS = Interim Cryogenic Propulsion Stage

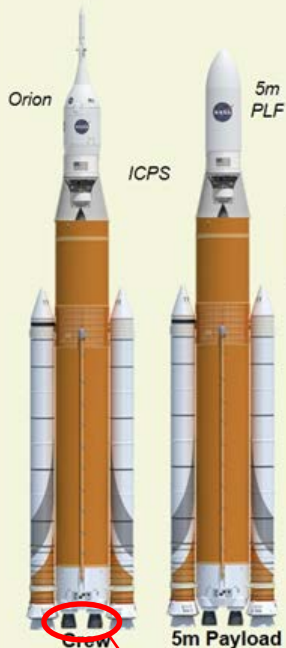
LEO = Low Earth Orbit

PLF = Payload Fairing

SLS = Space Launch System

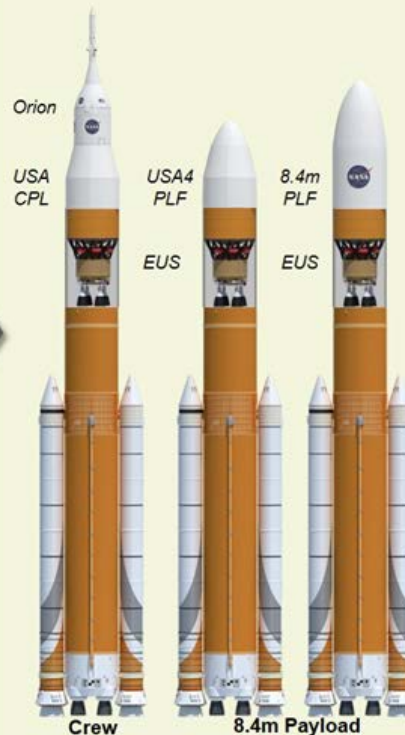
USA = Universal Stage Adapter

SLS Block 1 70t+ to LEO

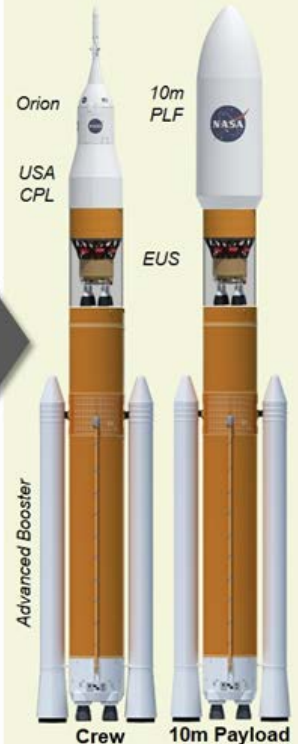


RS-25 engines

SLS Block 1B 105t+ to LEO



SLS Block 2 130t+ to LEO





SLS EM-1 Launch Animation



Space Shuttle Main Engine (SSME)



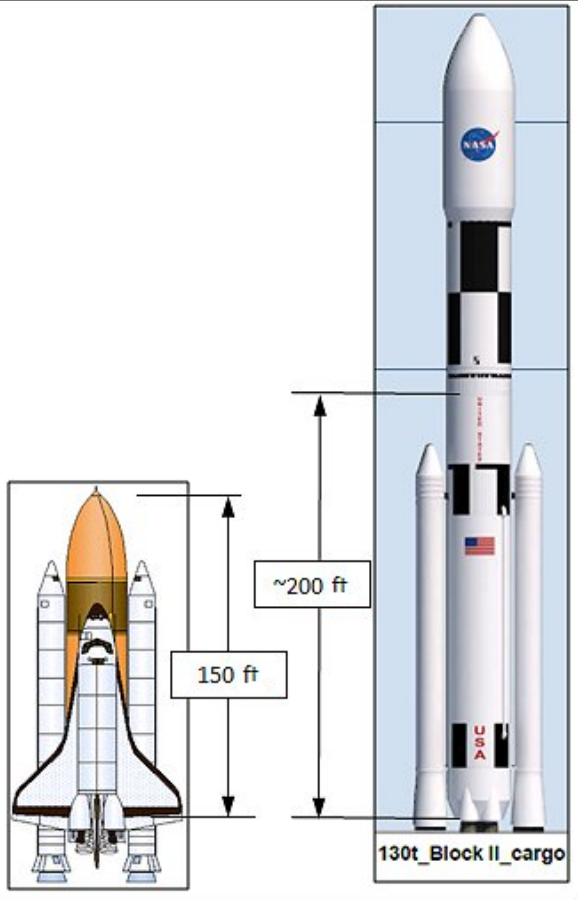
14 ft

7.5 ft

Propellants	O ₂ /H ₂
Rated power level (RPL)	469,448 lb
Nominal power level (104.5% RPL)	490,847 lb
Full power level (109% RPL)	512,271 lb
Chamber pressure (109% RPL)	2,994 psia
Specific impulse at altitude	452 sec
Throttle range (% RPL)	67 to 109
Gimbal range	+/- 11°
Weight	7,748 lb
Service life	55 flights 27,000 sec
Total program hot-fire time	3,171 starts 1,095,677 sec

Image: NASA

SSME → RS-25 Adaptation



- Four RS-25 engines are used to power the core stage of SLS
- Initial flights will use RS-25 engines recovered from Space Shuttle program (RS-25 Adaptation program)
- Future flights will use the engines manufactured using cheaper and more affordable processes (RS-25 Restart Production)
- A hot-fire testing program was planned to test the engine performance over a range of operating conditions to demonstrate the capability to meet mission requirements
- Engine static fire testing is conducted on A1 test stand at NASA Stennis Space Center



System Requirements



RS-25 requirements overview

Vacuum Thrust

- Rated = 470,000 lbf
- Precision = ± 6000 lbf
- Closed-loop control

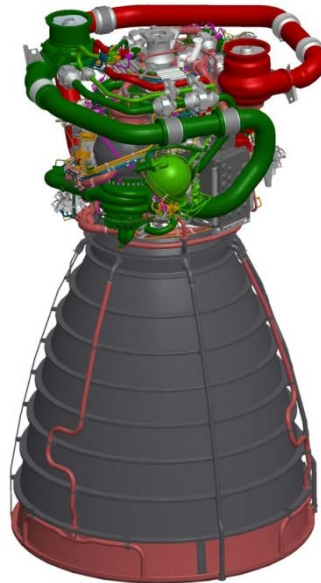
Minimum Vacuum Isp

451.3 s (at 109% rated thrust)

Mixture Ratio

- Nominal = 6.00
- Precision:
 - $\pm 1.7\%$ (65% to 90% rated thrust)
 - $\pm 1\%$ (90% to 109% rated thrust)
- Closed-loop control

Engine Gimbal = 8° circle



Engine Throttling

Steps 1% between 65% to 109% of rated thrust

Engine Mass = 8280 lbm

Engine Dimensions = 94" D X 167" L

Operational Life (Post delivery)

- 6 starts, 2500 seconds (1st and 2nd SLS flight)
- 3 starts, 1100 seconds (3rd and 4th SLS flight)

Engine Control system

- Electronic controller and software
- Reprogrammable

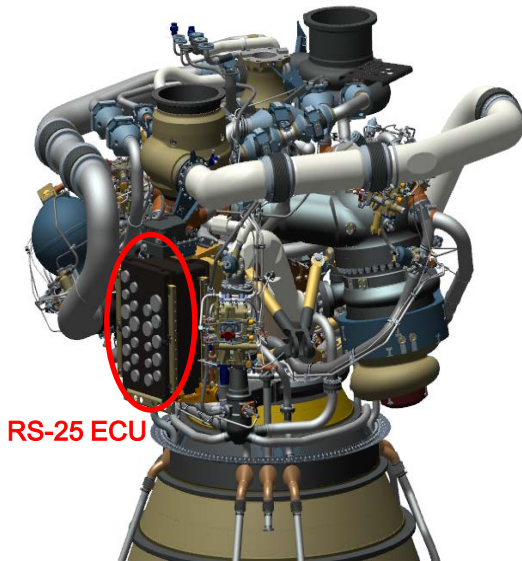


Controller Development



Controller Development

- In the RS-25 Engine Adaptation program, the only engine component that was upgraded was the Engine Controller (ECU)
- The Engine Control (EC) system is composed of ECU (hardware/software) and the new cabling/harness



ECU Functions

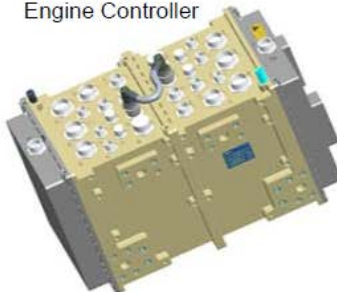
- Receive and respond to commands from the vehicle.
- Provide closed-loop thrust and mixture ratio control of the engine during mainstage operation through position control of variable position propellant valves to the separate preburners.
- Manage engine state (i.e., start enable, start, mainstage, shutdown, etc.) transition and timing of effectors used during the different states. This includes the control of numerous purges and bleed flows.
- Continuously monitor engine health.
- Provide data and health status to the vehicle flight controllers.
- Provide electrical power to all engine control elements, sensors and effectors.

Controller Development

SSME
Engine Controller



RS-25
Engine Controller



J-2X
Engine Controller



Test Acceptance Path

Test Purpose

Printed Wiring Assembly
(PWA) Card Level Testing

Screen Electronic, Electrical, and
Electromagnetic (EEE) integrity and
workmanship issues at board level



Acceptance Test Procedure

Screen EEE integrity, workmanship,
and board integration issues at
assembly level



Post engine installation
checkouts

EC integration of Engine Hardware
and Flight Software

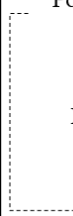


Hot Fire Green Run

Hot Fire Environment – EC
Integration of Engine Hardware and
Flight Software



If needed

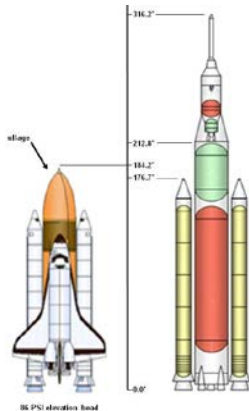




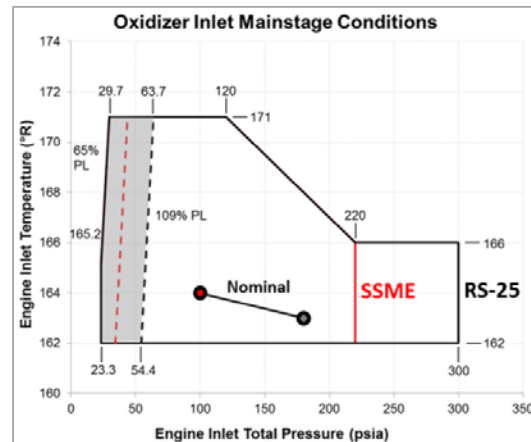
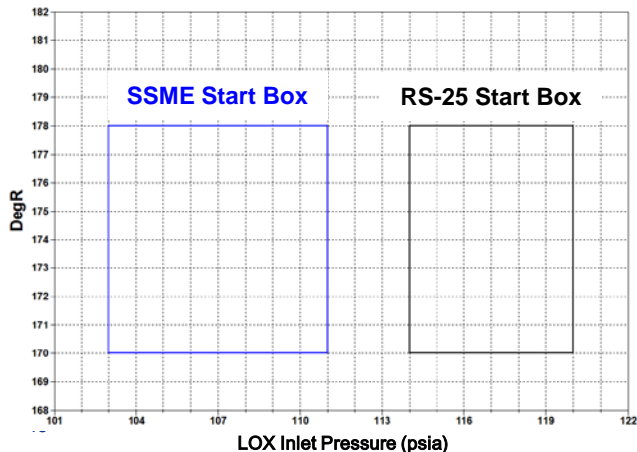
System DDT&E



RS-25 Changes: LOX Inlet Pressure

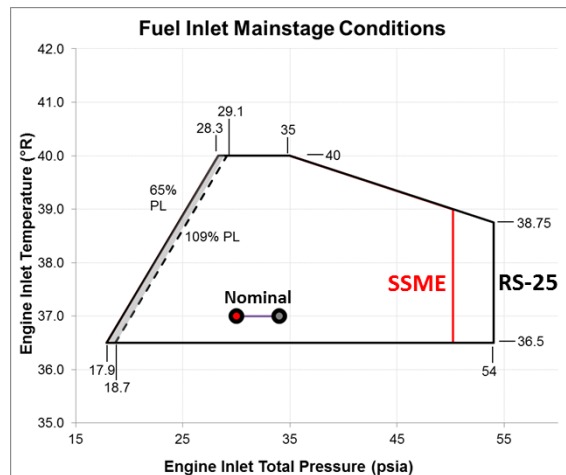
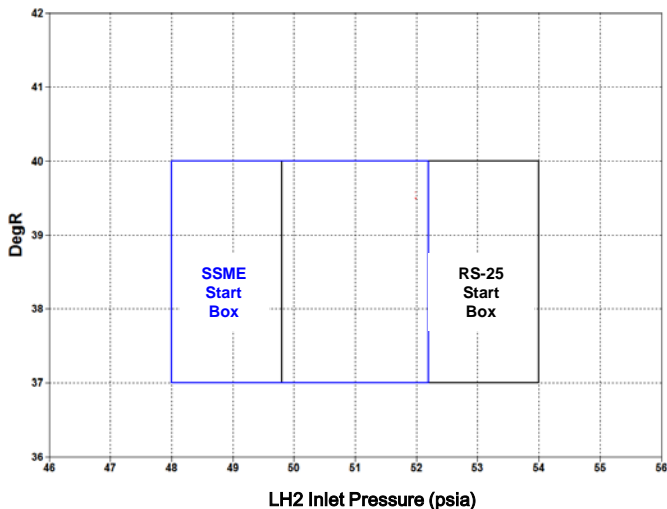


- Increased tank height
- Increased acceleration
- Changes in ullage schedule
- New start box
- New main stage envelope
- Beyond SSME start experience



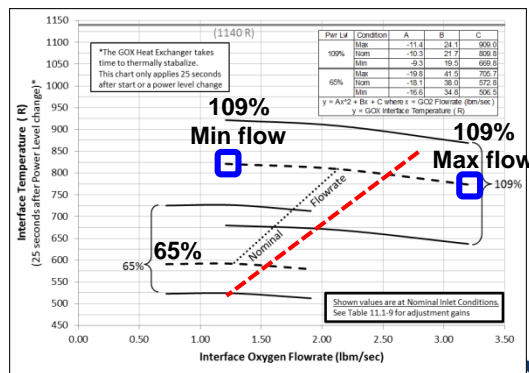
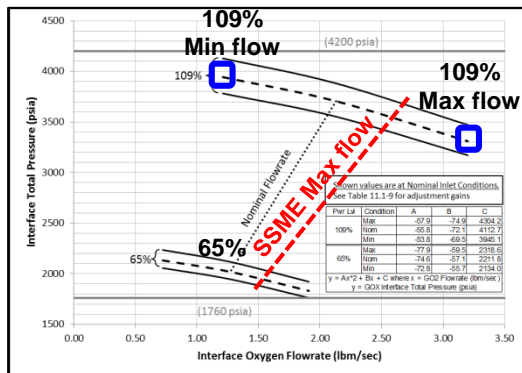
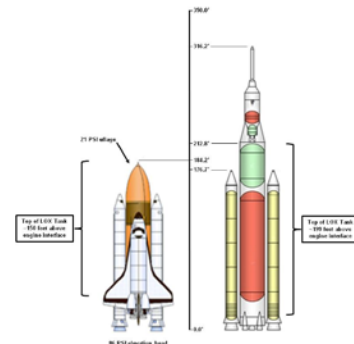
RS-25 Changes: Fuel Inlet Pressure

- Increased tank height
- Changes in ullage schedule
- Fuel tank pressurized to maintain gauge pressure
- Modified start box
- Main stage exposed to higher inlet pressure for extended period
- Beyond SSME start experience



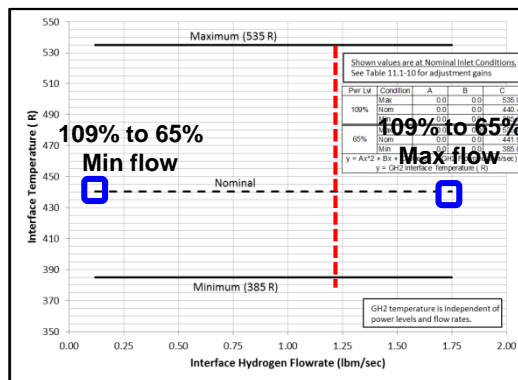
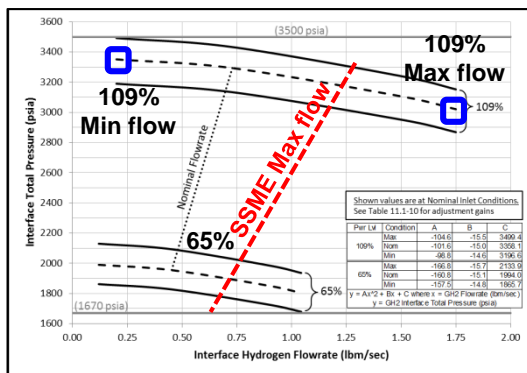
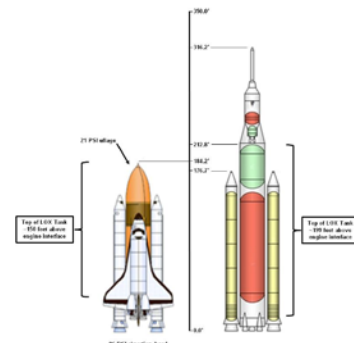
RS-25 Changes: GOX Tank Pressurization

- Increased tank pressurization flow (repress) to maintain ullage pressure
- Valve material sensitive to GOX temperature
- Additional requirements as a function of power level and flowrate
 - Interface Pressure
 - Interface Temperature
- Test Max and Min repress flows at various power levels for a set duration during the mainstage and also during the start and shut down.



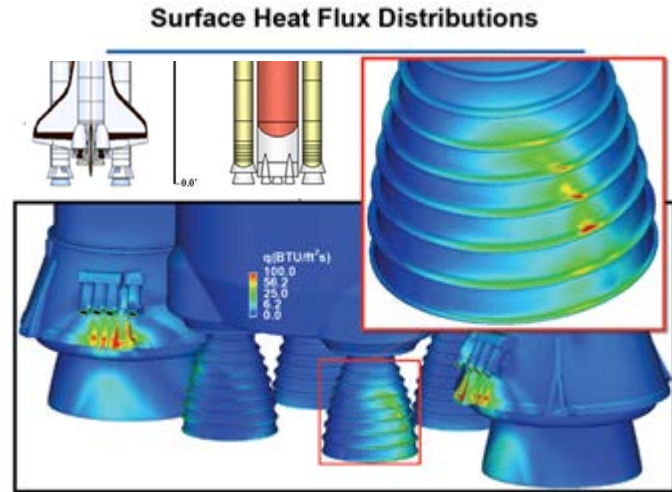
RS-25 Changes: Fuel Tank Pressurization

- Increased tank pressurization flow (repress) to maintain ullage pressure
- Core stage auxiliary power unit (CAPU) now driven by GH2 tap
 - Will power all hydraulics including thrust vector & valves
- Additional requirements as a function of power level and flowrate
 - Interface Pressure
 - Interface Temperature
- Test Max and Min repress flows at various power levels for a set duration during the mainstage and also during the start and shut down.



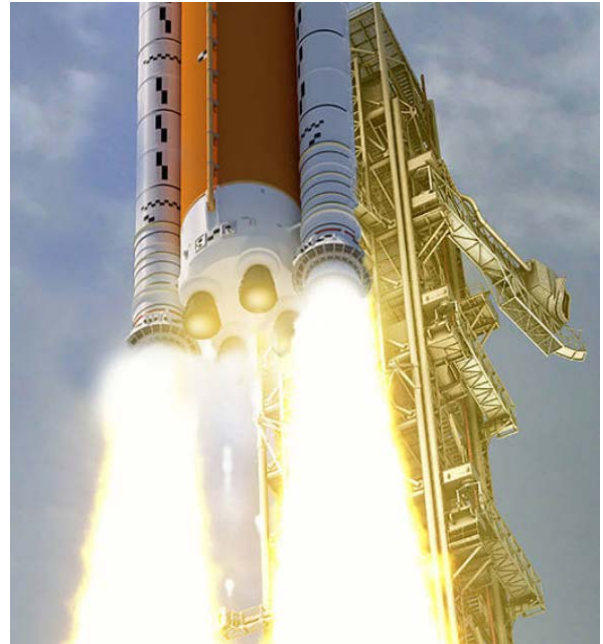
RS-25 Changes: Nozzle Heating

- Engine is now close to in-plane with Solid Rocket Boosters (SRBs) resulting in increased convective and radiant heating
- Additional heating due to plume recirculation and radiant heat
- GH2 dumped overboard is ignited to prevent free hydrogen buildup which will cause some more heating
- Test strip of nozzle ablative (Adhesion test)



RS-25 Adaptation Testing - Summary

- **Vehicle Changes & Engine Effects**
 - Thermal conditioning
 - Higher power level
 - Higher inlet pressures
 - Higher tank pressurization flows
 - Helium ingestion
 - Nozzle Heating
- **Controller Changes & Engine System**
 - Mixture ratio control
 - Throttle control
- **Adaptation Plan**
 - Green Run
 - Life Extension
 - DVR Verification Requirements
 - Development Objectives



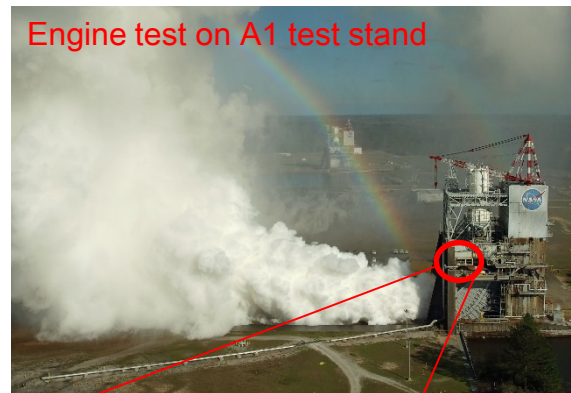


Engine System Testing



RS-25 Adaptation Test: A-1 Test Stand

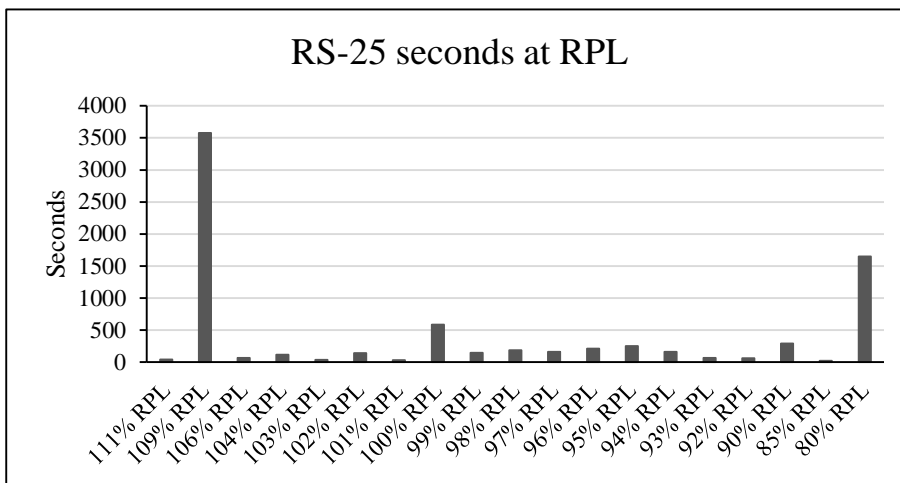
- The A-1 test stand located in NASA's Stennis Space Center was chosen to conduct all the tests
- Capabilities
 - Maximum test article size 33 ft in diameter
 - 1.1 M-lb (vertical)
 - 0.7 M-lb (horizontal)
 - Supplied with cryogenic fluids
- LOX and LH₂ are supplied from cryogenic barges
- Propellant feed lines and other run lines were changed as per RS-25 requirements
- Thrust Measurement System (TMS) was updated
- LOX runline piping spools were electropolished to remove any metal particles



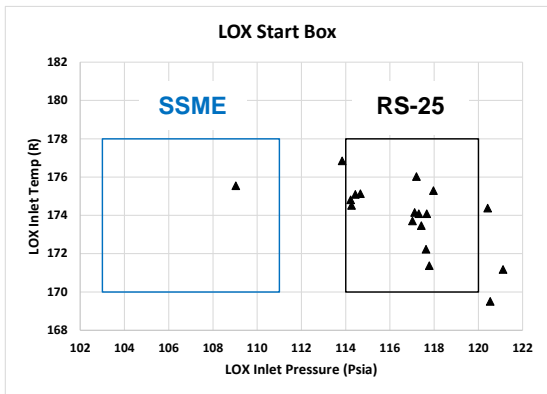
RS-25 Engine
mounted on
the stand

RS-25 Adaptation Test

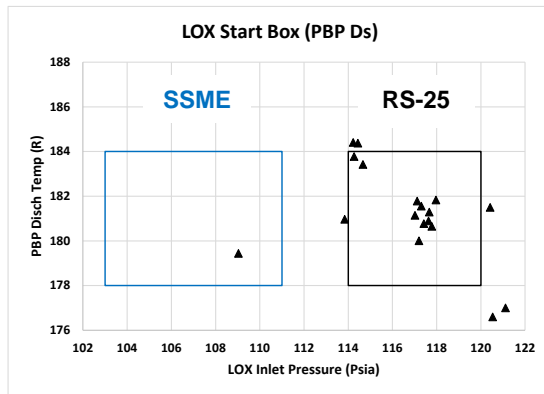
- A total of 18 hot-fire tests were performed as part of the Adaptation test series between Jan 2015 – Jan 2018.
- Two of the tests were engine acceptance tests where flight engines were tested and tagged.
- Sixteen tests were performed on two development engines



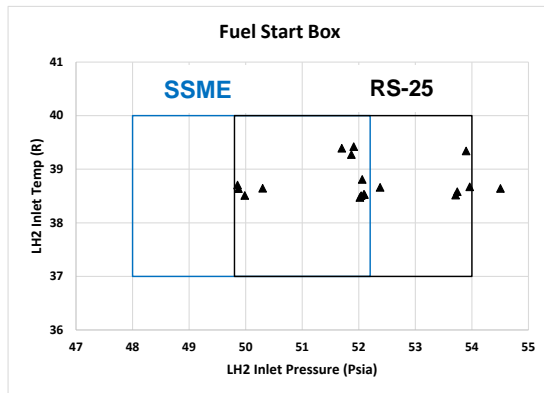
RS-25 Adaptation Test



▲ RS-25
adaptation
tests

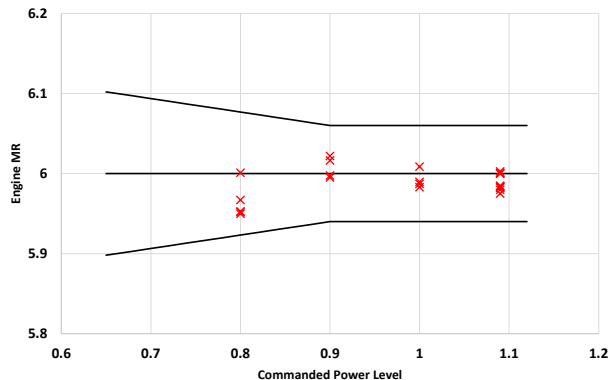


- The first test in the series was a baseline of the engine performance at SSME start propellant inlet conditions
- Some tests were conducted at the corners of the start boxes to test the system to component hardware operating limits

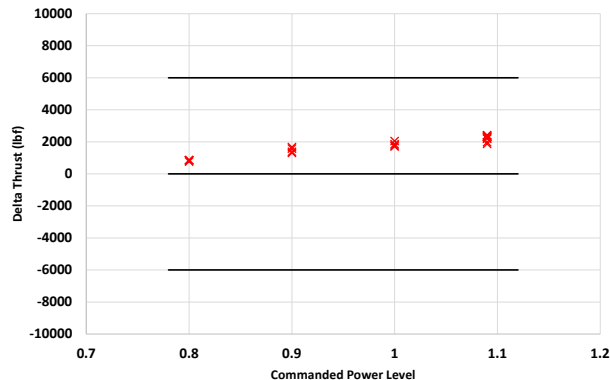


RS-25 Adaptation Test

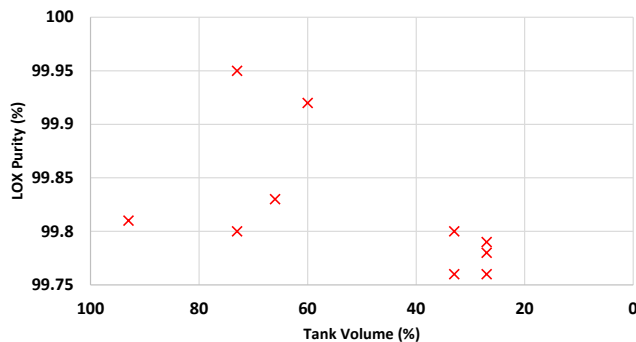
Mixture Ratio (MR) Precision



Thrust Precision

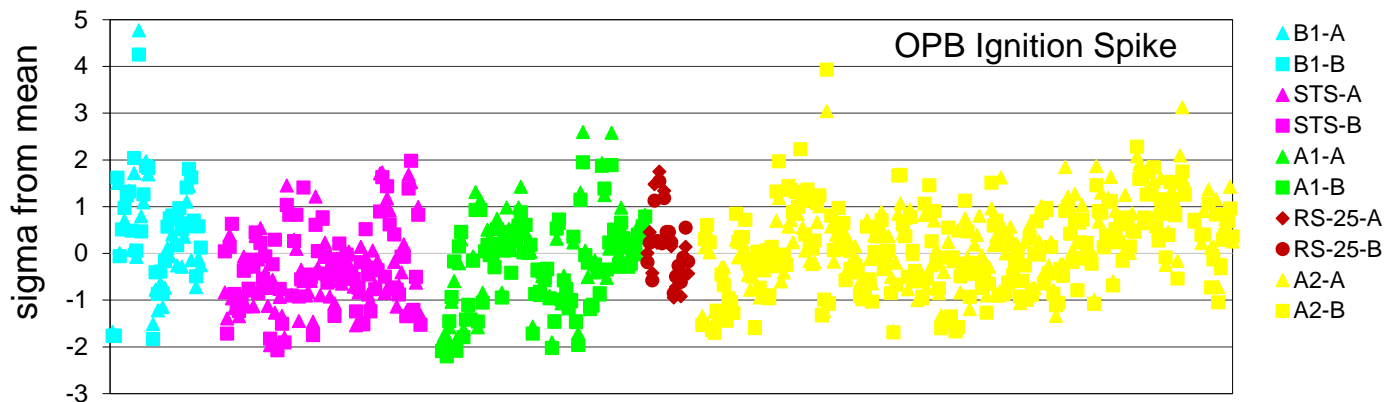
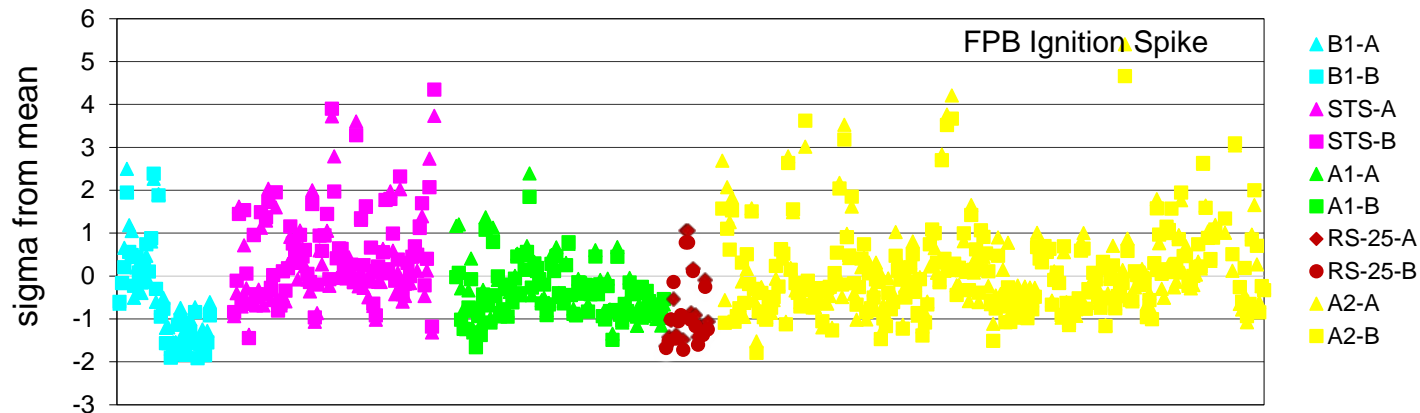


In-Run LOX Samples



x RS-25 adaptation tests

RS-25 Adaptation Test



Summary

- RS-25 adaptation test series successfully demonstrated that the flight controllers meet the mission requirements
- All the other RS-25 requirements have been successfully tested
- Lessons learned during the test program will help the future tests in the RS-25 restart production program



Acknowledgements

The authors wish to thank the following those who made valuable suggestions and helped in completion of this package and the manuscript: Richard Ballard (XP20), Michael Nelson (ER22), John Butas (ER21), and Tim Duquette (ER21).