

Solid Rocket Motor Incremental Modeling for System Impacts

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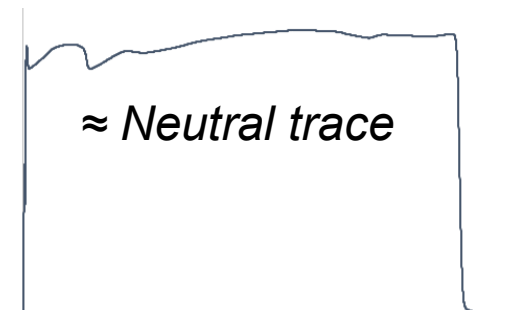
JACOBS Space Exploration Group

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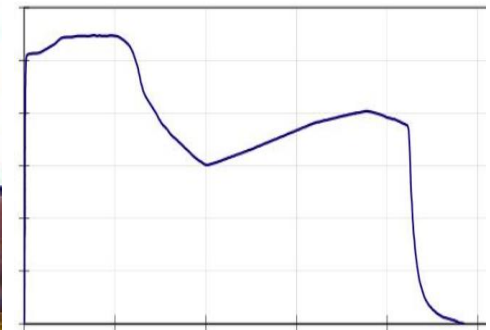
Distribution A: Approved for public release; distribution is unlimited

In-space motors are finding new roles

- In-space motors have the same components as launch vehicle boosters or stages
- In-space motors have had different design drivers



Thrust vs. time



Space Solids experience highlights

- **Inertial Upper Stage (IUS)¹** – 2 solid stages
flown out of Shuttle, Titan



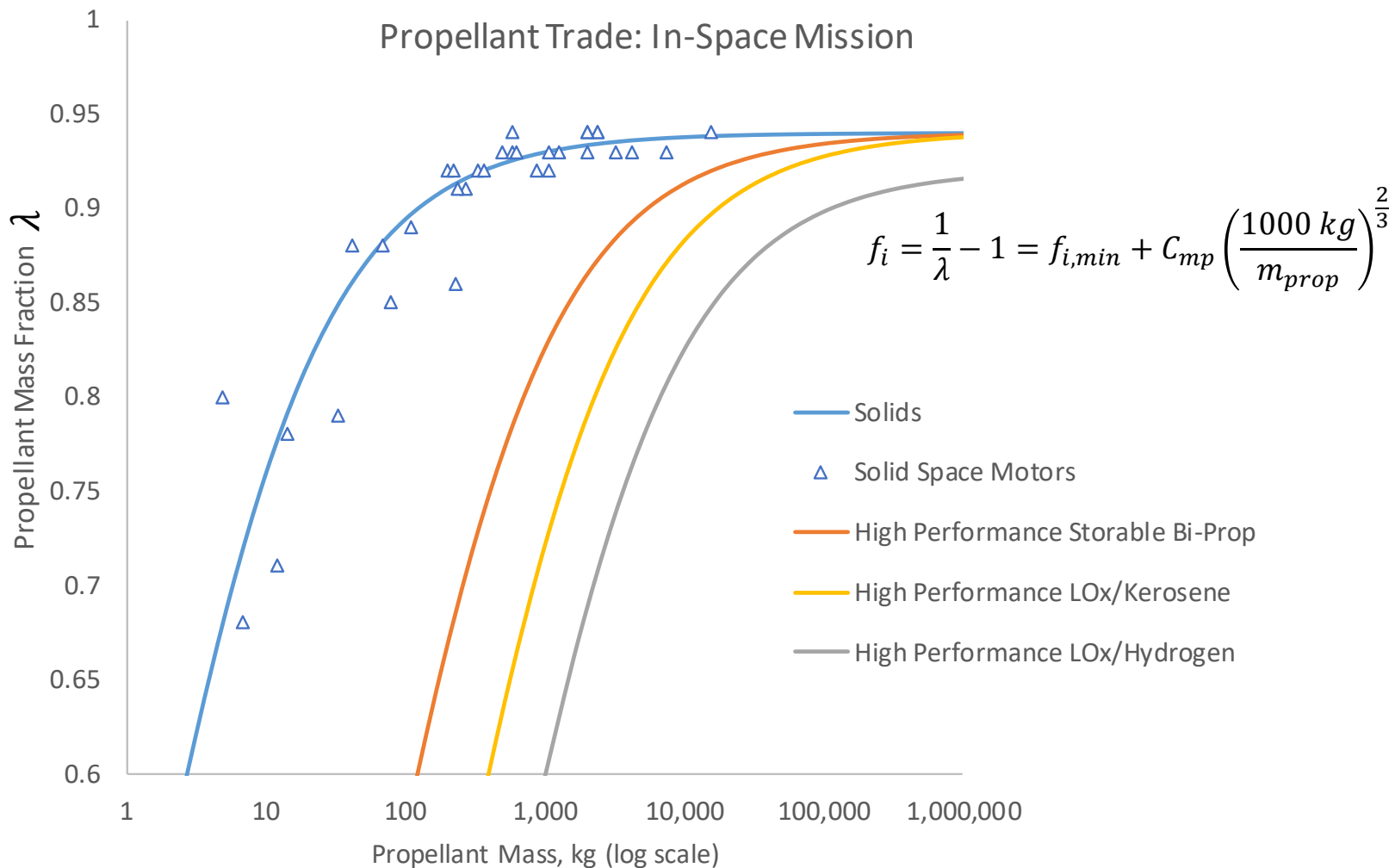
- **Leonidas Stg 2 & 3²** – Super Strypi upper stages

- **Delta II** – 60+ STAR 48B launches



- **Magellan** – Longest in-space aging before firing, 15 mos³
- **Ulysses** – highest ΔV (4 km/s), max acceleration (11 g's)
- **New Horizons** – highest final velocity leaving earth
- **LADEE Minotaur V** – recent 5-solids lunar launch vehicle
– 3 Peacekeeper stages, STAR 48BV, STAR 37FMV
- **SFDT⁴** – Demonstrated offload repeatability and lots of data
- **Parker Solar Probe** –
STAR 48BV atop a Delta IV-Heavy – high ΔV mission

When to use Solids? When the mass fraction *pro* outweighs the Specific Impulse *con*



What's new now?

Missions where time and shape is of the essence



- **0 impulse**
 - Specific impulse
- **1 burn time and dimensions**
- **2 shape-limiting**
 - Limit Q or g: approximate regressive trace
 - Scaling a catalog design
- **3 variation sensitive**

ΔV ,
impulse
estimate



Detail
design &
analysis

0: Estimate Propellant Mass & Specific Impulse

$$\Delta V = I_{sp} \ln \left(1 + \frac{m_{prop}}{m_{final}} \right) = I_{sp} \ln \left(1 + \frac{1}{\left(\frac{m_{payload}}{m_{prop}} \right) + f_i} \right)$$

• A: General target motor

- Assume typical high-performance propellant (c^* contribution to I_{sp})
 - For first iteration, $f_i = 0.9$ and $I_{sp} = 290$ s
- Expansion ratio (ϵ) is primary driver for I_{sp}
 - propellant mass can change it, but less drastically than for f_i
- Correlations:

$$I_{sp} = a_{I_{sp}} \ln \left(\frac{\epsilon}{\epsilon_0} \right) + b_{I_{sp}} \qquad f_i = f_{i,min} + C_{mp} \left(\frac{1000 \text{ kg}}{m_{prop}} \right)^{\frac{2}{3}}$$

• B: Departing from a reference motor

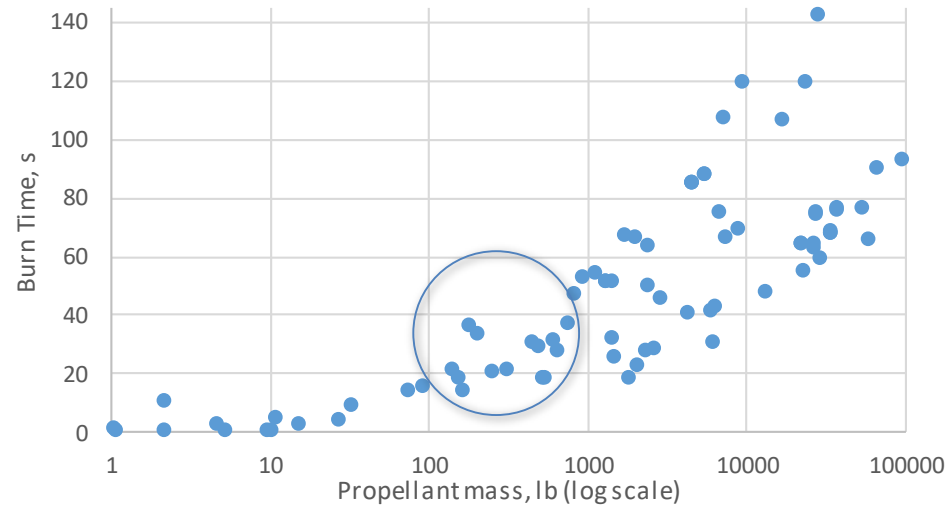
$$I_{sp2} = I_{sp1} + a_{I_{sp}} \ln \left(\frac{\epsilon_2}{\epsilon_1} \right) \qquad f_{i2} = f_{i1} + C_{mp} \left[\left(\frac{1000 \text{ kg}}{m_{prop2}} \right)^{\frac{2}{3}} - \left(\frac{1000 \text{ kg}}{m_{prop1}} \right)^{\frac{2}{3}} \right]$$

State of the Art

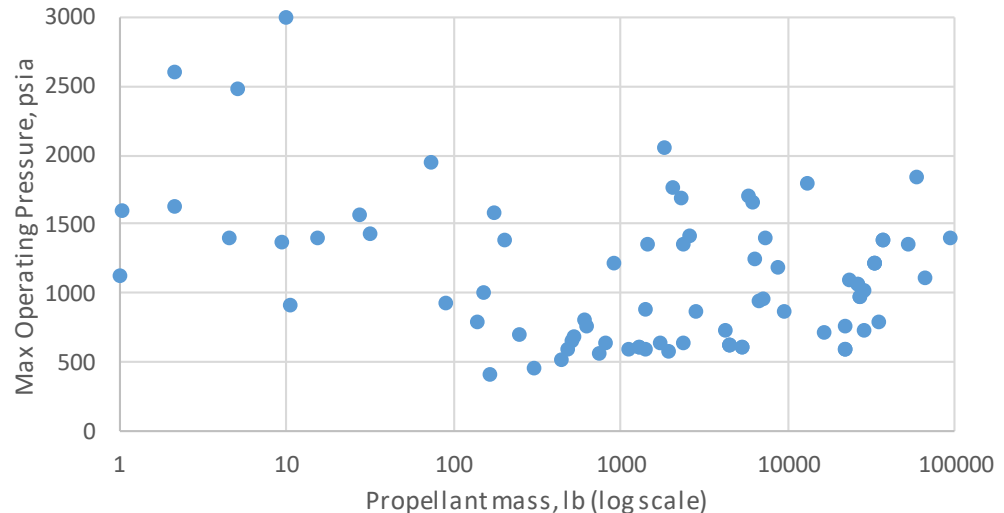
- **Longer burn times drive innovation for smaller motors**
 - End burners possible, but increase fi

- **Smaller motors → higher pressure easier**
 - “Min gage”

Most Motors Burn Time



Most Motors Max Pressure



1: Burn time and dimensions

- If burn rate is limited:
4 equations, 7 unknowns =
2 independent variables

– Often, case diameter and pressure drive

- Burn Time
- Thrust
- Case Length
- Throat Area

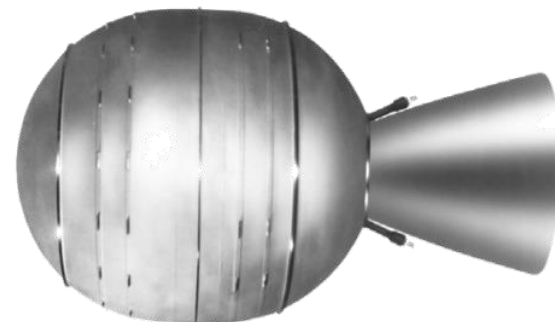
$$P_{avg} A_t t_{b,max} = m_{prop} c^*$$

$$t_{b,max} \approx \frac{0.8 D_{case} / 2}{\dot{r}_{ref} \left(\frac{P_{avg}}{P_{ref}} \right)^n}$$

$$F_{avg} = \frac{m_{prop} I_{sp}}{t_{b,max}}$$

$$m_{prop} \approx f_v \rho_{prop} \pi D_{case}^2 \left[\frac{1}{6} D_{case} + \frac{1}{4} (L_{case} - D_{case}) \right]$$

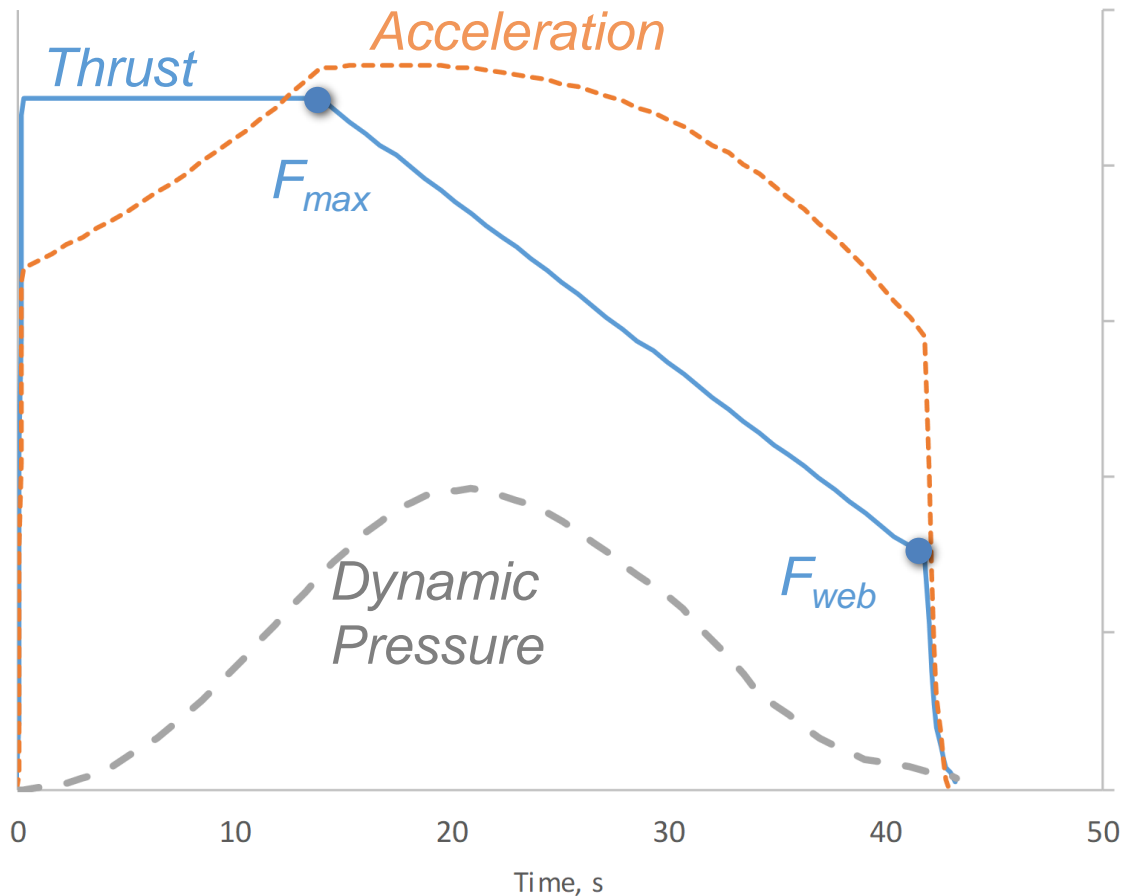
- With selectable burn rate,
one more free variable



2: Design-to regressive trace

- **Goal: Notional but realistic traces limiting dynamic pressure at separation**

- 0: Set
 - m_{prop} & Isp
- 1: Set
 - Propellant
 - Case Diameter
 - Throat Area
- 2: Set F_{max}/F_{web}
- Results in
 - Pressure (max & avg)
 - Thrust (max & avg)
 - Burn Time
 - Case Length



- Burn time and dynamic pressure or acceleration not acceptable?
iterate

2: “Can I get this thrust trace in a size XXL?”

- Assume same propellant

- 2 steps:

- Scale to new diameter and propellant mass, at constant pressure

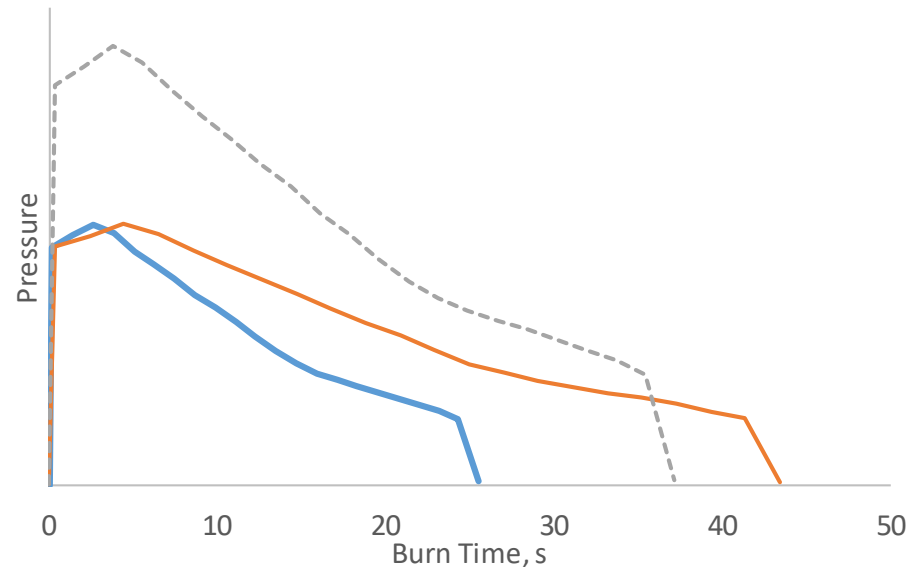
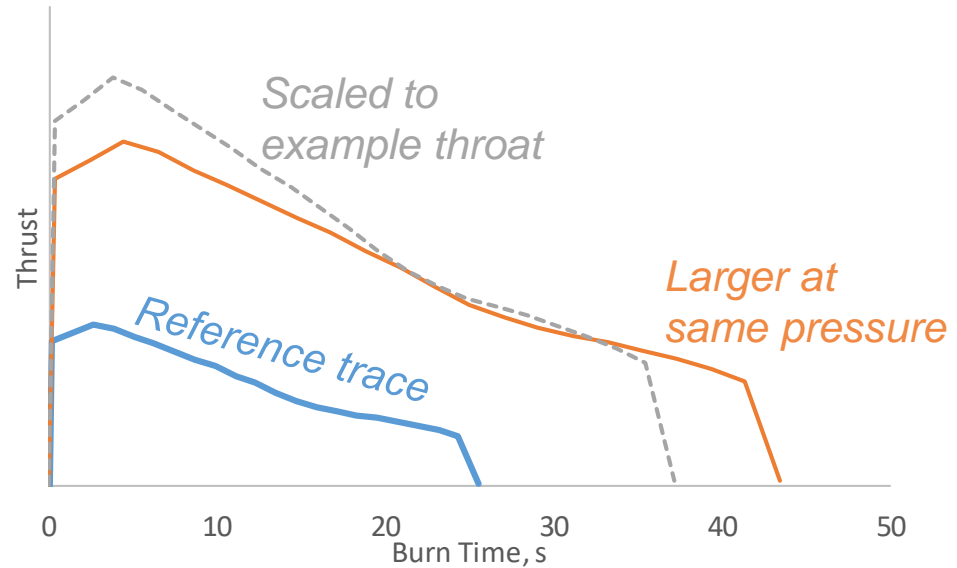
$$\frac{t_2}{t_1} \approx \frac{D_2}{D_1} \quad \frac{\dot{m}_2}{\dot{m}_1} = \frac{m_{p2}}{m_{p1}} \left(\frac{t_2}{t_1} \right)^{-1}$$

$$\frac{A_{t2}}{A_{t1}} = \frac{\dot{m}_2}{\dot{m}_1} \quad \frac{F_2}{F_1} = \frac{\dot{m}_2 Isp_2(\epsilon_2)}{\dot{m}_1 Isp_1(\epsilon_1)}$$

- Scale to new condition by setting throat

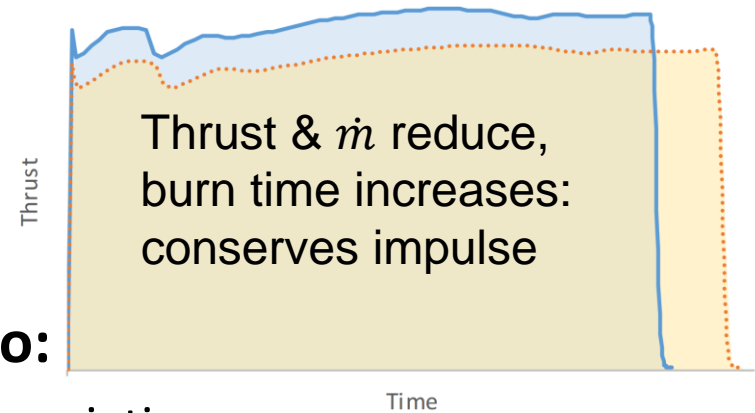
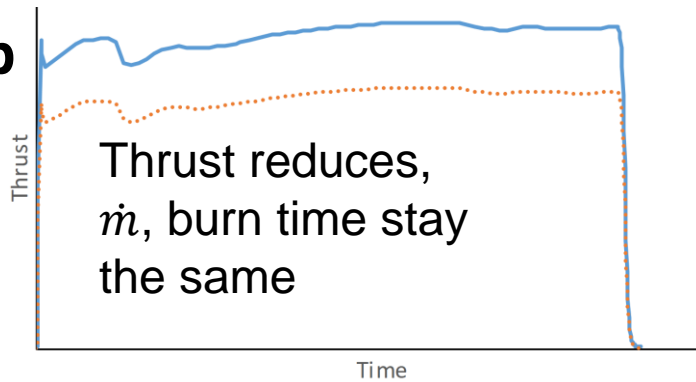
$$\frac{t_3}{t_2} = \left(\frac{A_{t3}}{A_{t2}} \right)^{\frac{n}{1-n}} \quad \frac{\dot{m}_2}{\dot{m}_1} = \left(\frac{A_{t3}}{A_{t2}} \right)^{-\frac{n}{1-n}}$$

$$\frac{P_3}{P_2} = \left(\frac{A_{t3}}{A_{t2}} \right)^{-\frac{1}{1-n}} \quad \frac{F_3}{F_2} = \frac{\dot{m}_3 Isp_3(\epsilon_3)}{\dot{m}_2 Isp_2(\epsilon_2)}$$



3: Lander mission driven by variation

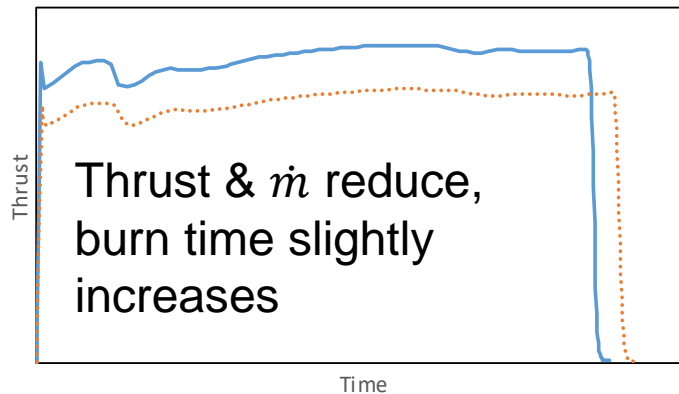
- Isp



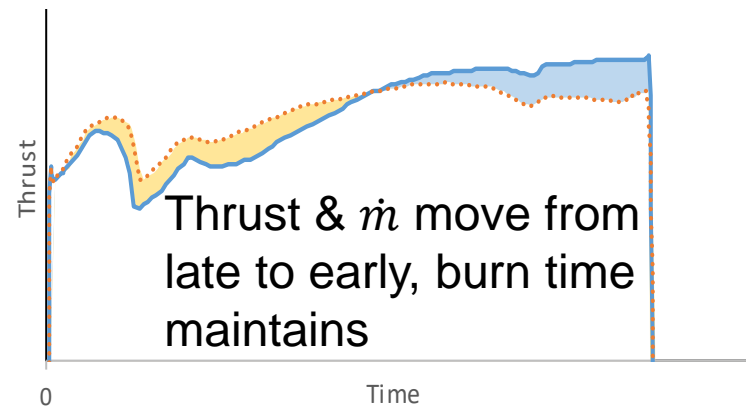
- **Burn time, due to:**

- intrinsic burn rate variation
- Propellant Mean Bulk Temperature (PMBT)

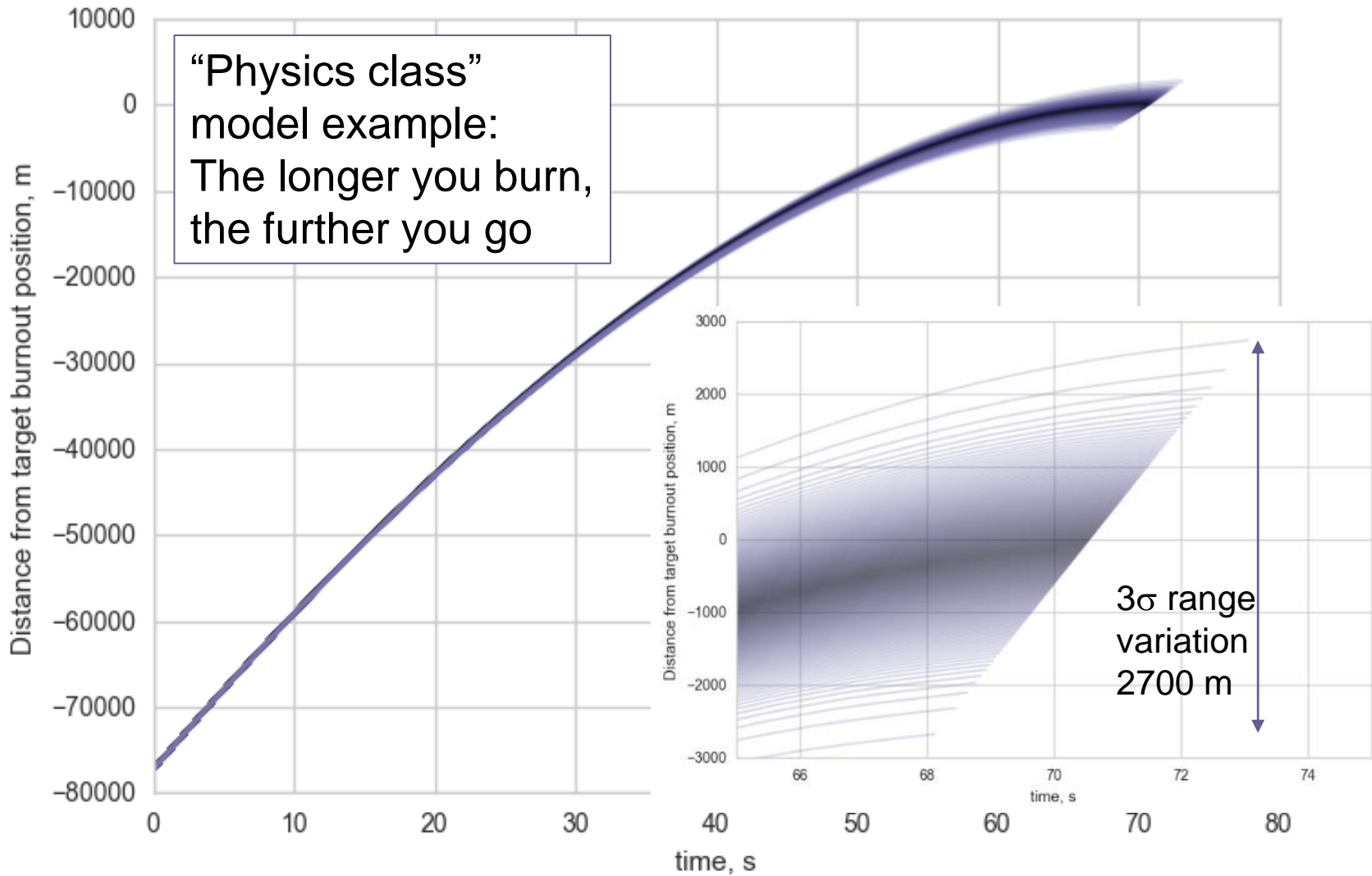
- Propellant mass



- Thrust Shape Magnitude



How does burn time affect mission performance?



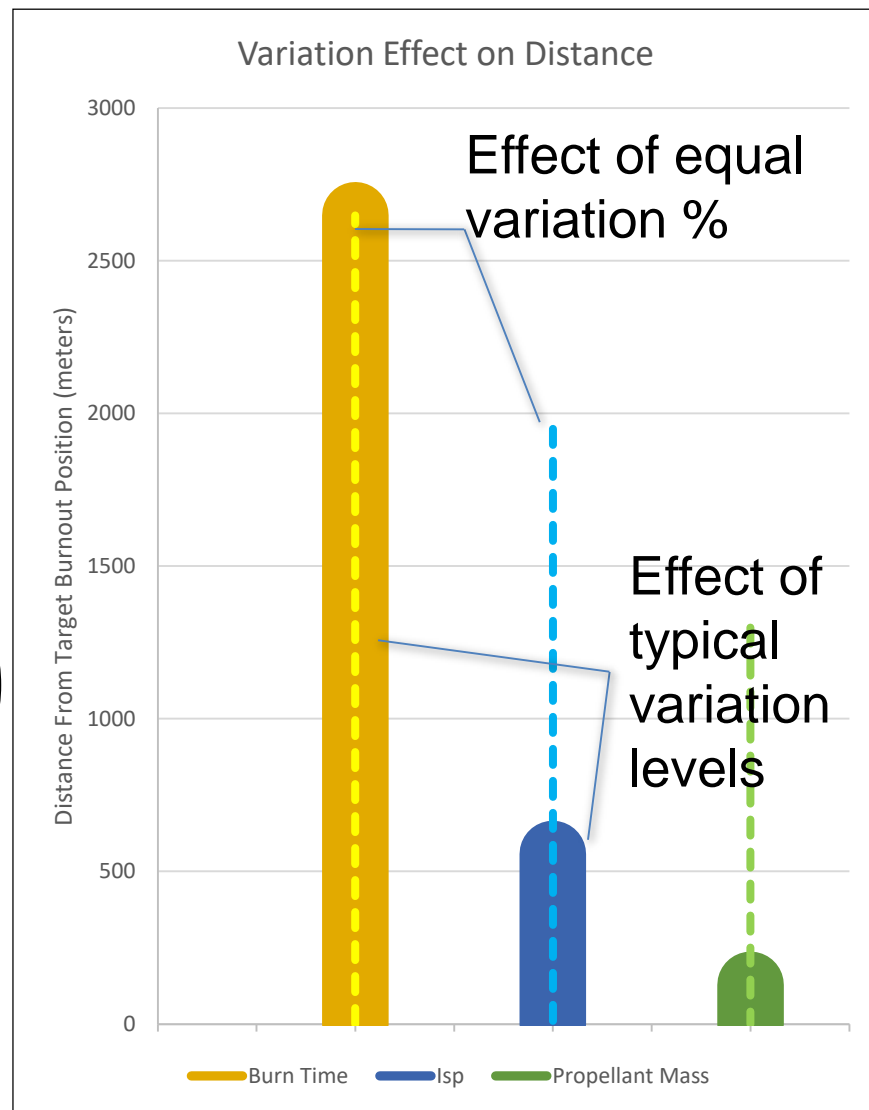
Variation Effects on Distance

- Isp proportional to ΔV

$$\Delta V = Isp \ln \left(\frac{1}{\frac{m_{prop}}{m_{final}} + 1} \right)$$

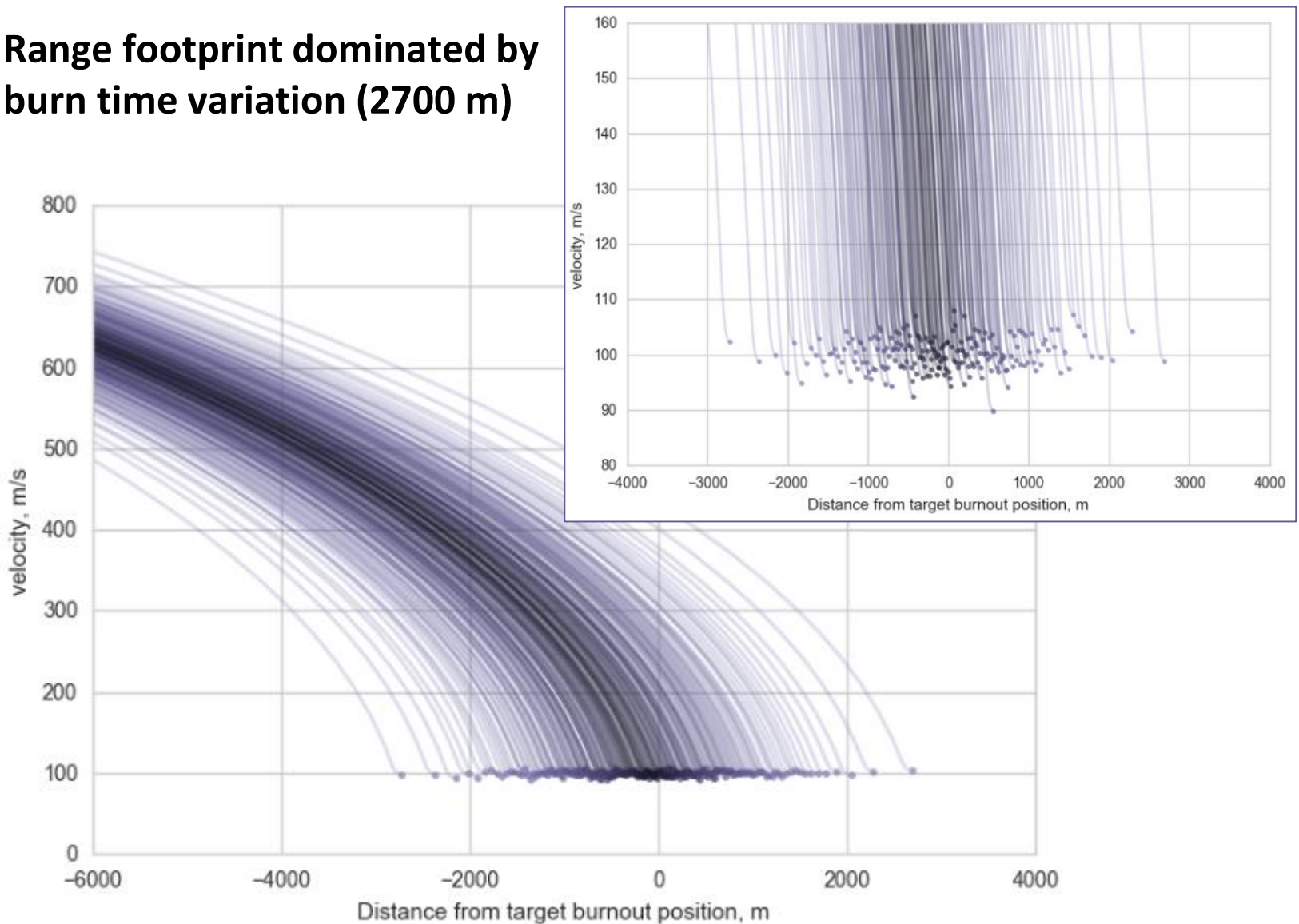
- Burn time proportional to range traveled; Isp affects less

$$\Delta x = t_b \left(V_0 - Isp \left[\frac{m_{final}}{m_{prop}} \ln \left(\frac{1}{\frac{m_{prop}}{m_{final}} + 1} \right) + 1 \right] \right)$$

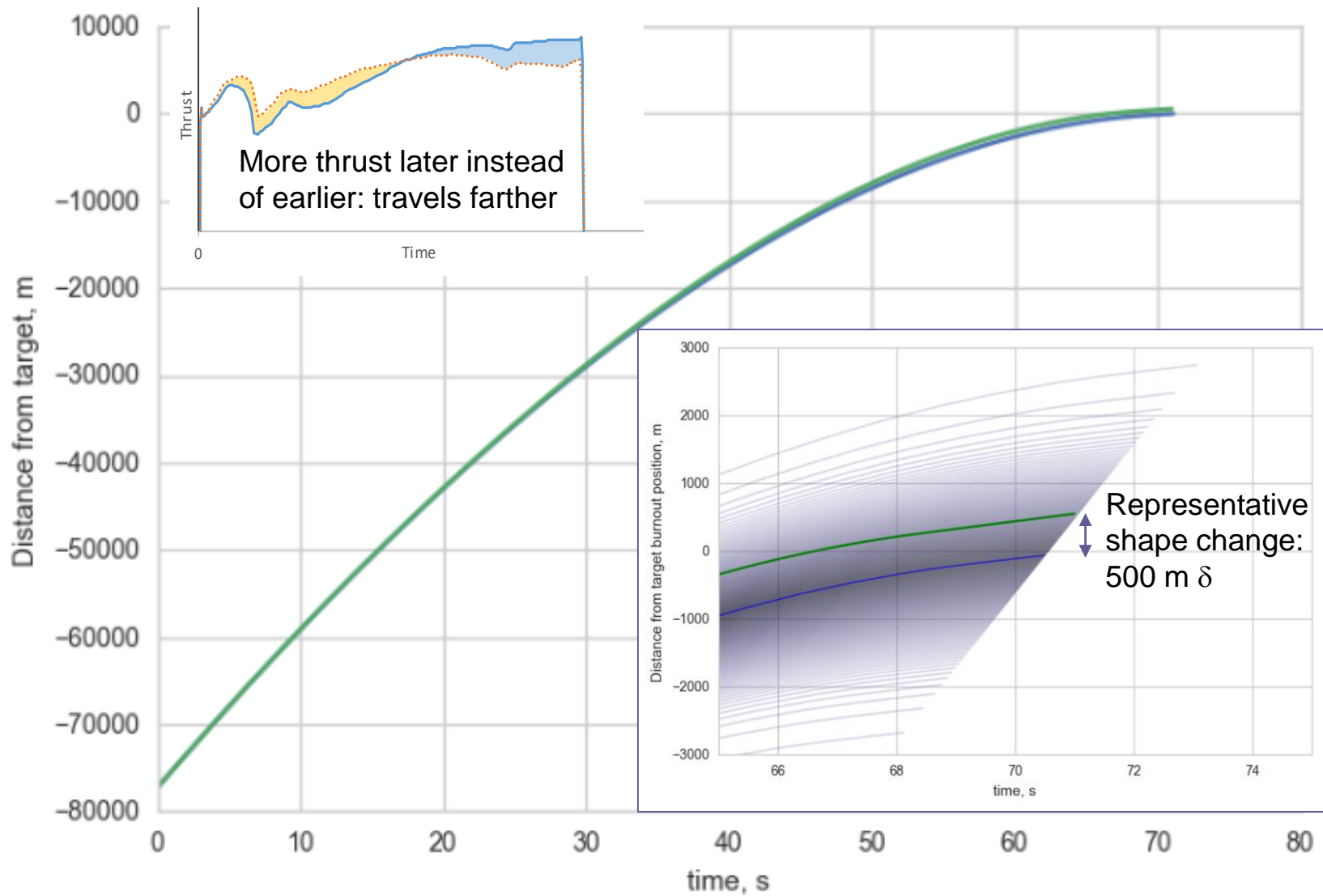


Example: Combined effect of burn rate and Isp

- Range footprint dominated by burn time variation (2700 m)



Thrust shape effect on range estimation



Conclusions

- **For lander de-orbit missions**
 - Variations matter
 - For planning estimates, a bit of margin on burn time variation should cover range variation from all sources

- **For loads-driven missions like Mars ascent**
 - Use dimensions, pressure, and thrust to extend burn times
 - Scale a desired regressive shape for other sizes

Questions?

