



# Arcus Mission Design

## Stable Lunar Resonant HEO for X-ray Astronomy

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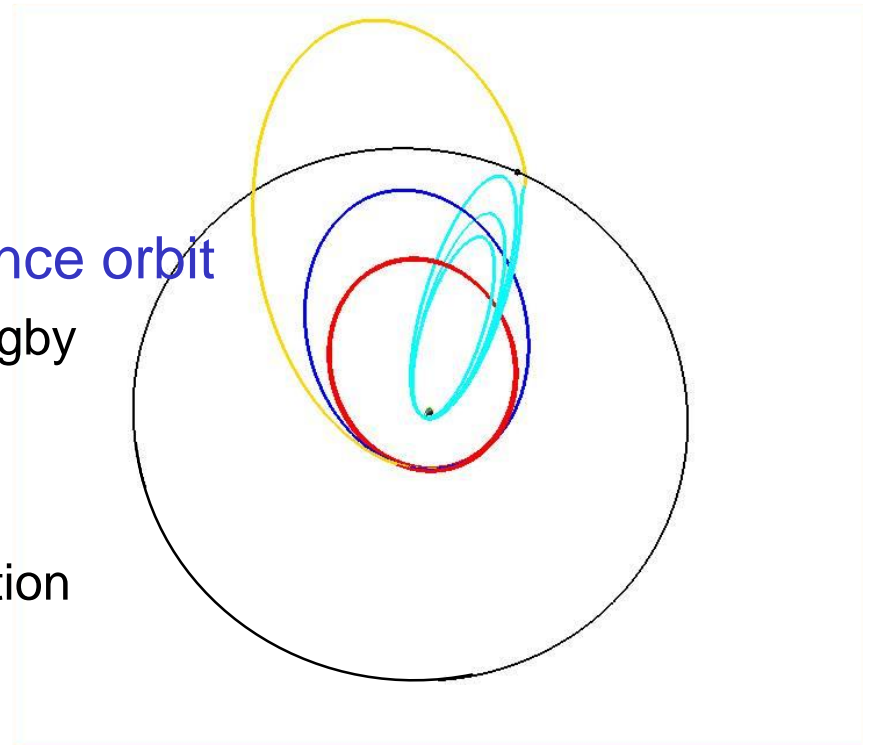
Lisa Policastri, John Carrico, Mike Loucks (Space Exploration Engineering)





# Arcus Mission Design - Overview

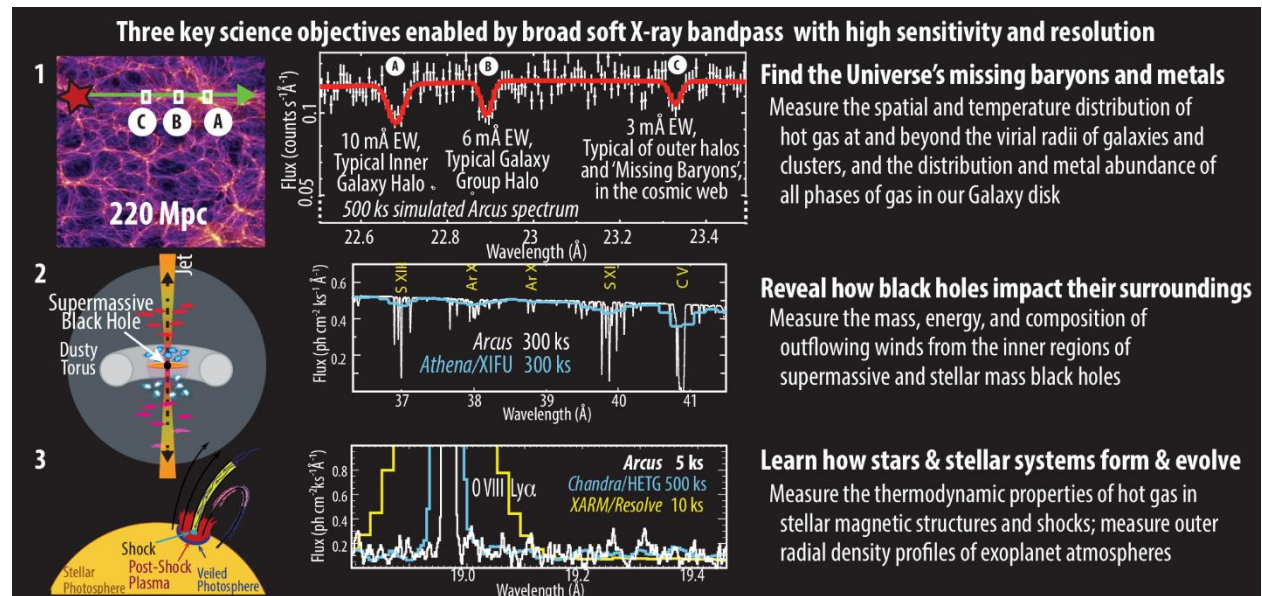
- Arcus mission
  - Project currently in Step 1 of NASA SMD 2016 MIDEX AO in Astrophysics
- Spacecraft and instrument
  - X-ray telescope, 14m long
- Transfer trajectory and science orbit
  - Phasing loops to lunar swingby
  - P/4 lunar resonant HEO
- Ground segment design
  - Tracking & Orbit Determination





# Arcus Science

- Soft X-ray grating spectroscopy
- Understanding the formation and evolution of clusters of galaxies, black holes, and stars
- Find and characterize the universe's missing matter

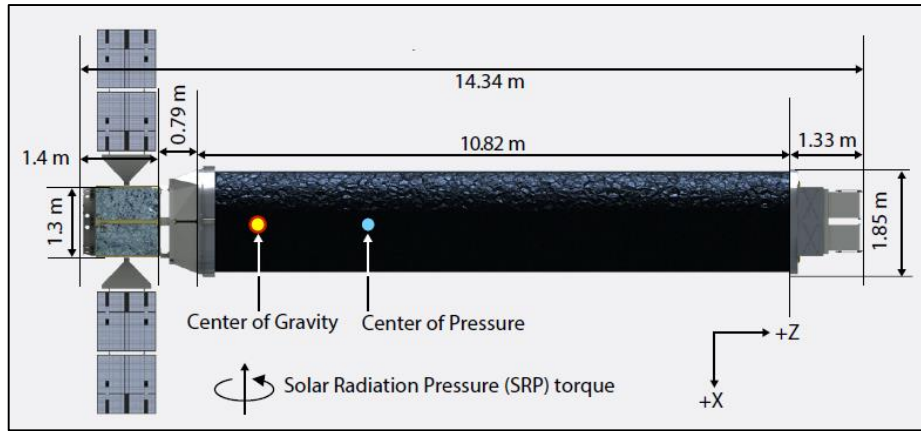


Arcus uniquely opens the soft X-ray bandpass



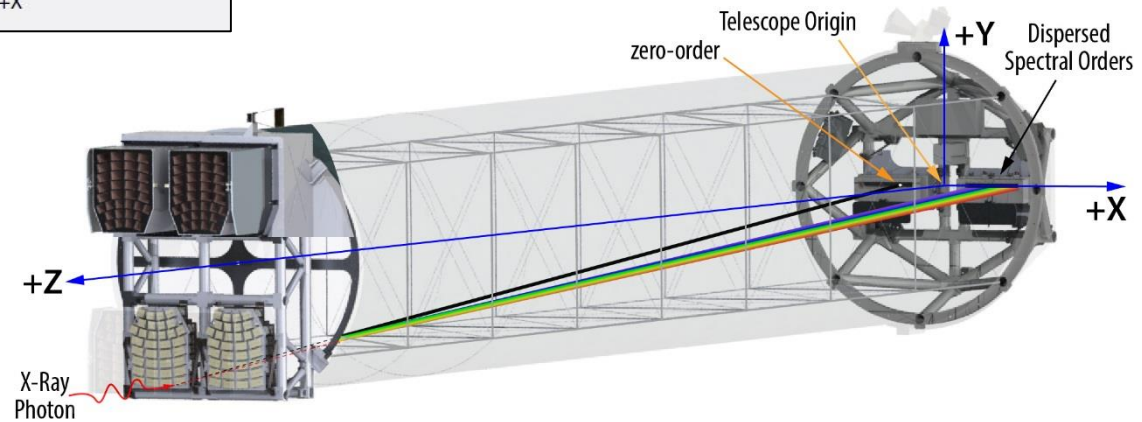


# Arcus Spacecraft and Instrument



- X-ray telescope cannot use a conventional mirror
  - X-rays pass through
- Silicon Pore Optics (SPO): gratings deflect X-ray photons slightly, to enter detector

X-Ray Photon





# Trajectory Requirements

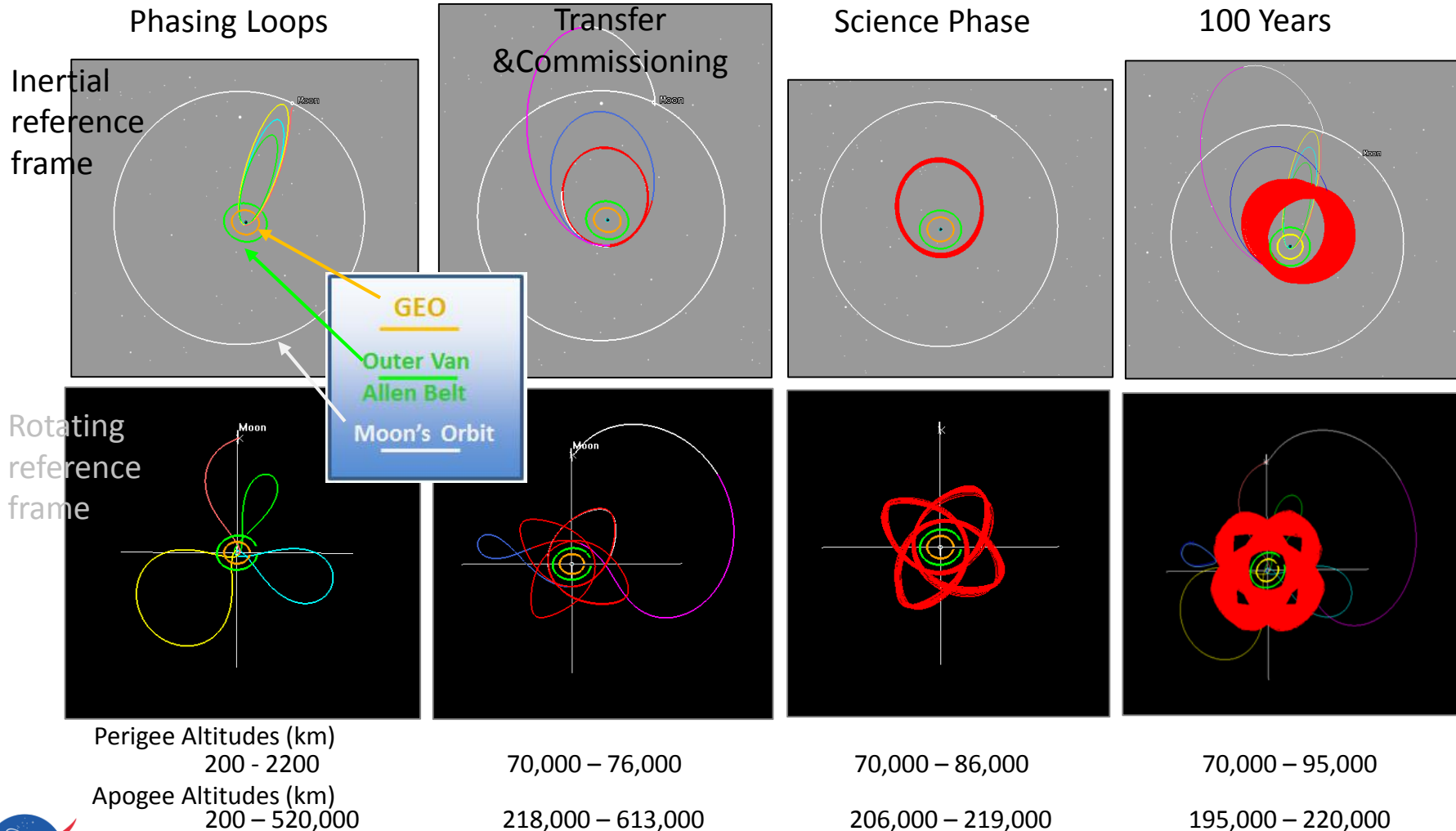
- The Arcus investigation places very little demand on the orbit design, needing only to be in space, above the Van Allen Belts, and with access to data downlink

	Requirement	Design Reference Mission	Notes
Minimum science orbit altitude above outer Van Allen belts (km)	60,000	71,124	
Science orbit stable for Science Phase duration (yrs)	2	100	Covers 5 yr extended mission
Maximum eclipse duration (hrs)	4.5	3.5	Some control with launch dates, maneuver tuning
Maximum Earth range (Re)	110	98	For link budget
Maximum delta-V burn (m/s)	175	130	3-thruster configuration
Delta-V budget	373	373	Full tanks
Minimum angle between the Sun vector and the thruster pointing direction (degrees)	> 20	22 – 163	Mitigated with launch date selection
Minimum altitude 300 km above GEO altitude for at least 100 years (km)	38,786	70,000	NASA-STD-8719.14A, §4.6.2.2
Moderate equatorial inclination for good DSN coverage (degrees)	< ~40	31 - 36	Investigating refinements





# Arcus Trajectory Design in Earth-Moon System



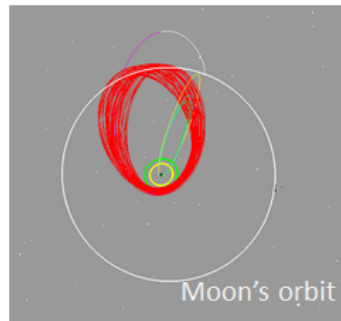
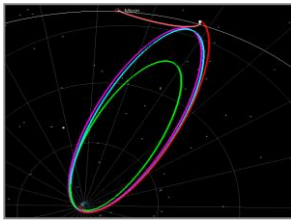




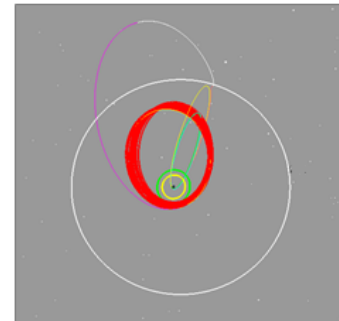
# Transfer Trajectory & Science Orbit

- Comparisons and early trades

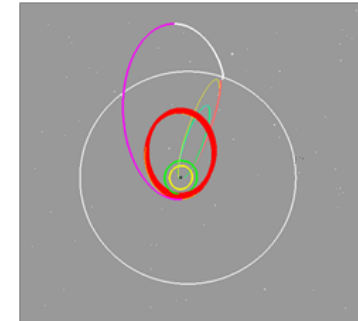
2 year propagations



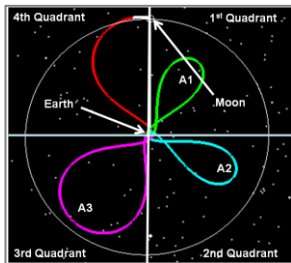
Example concept trajectory



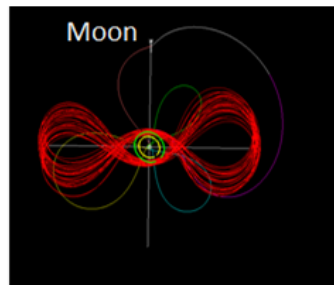
GEO



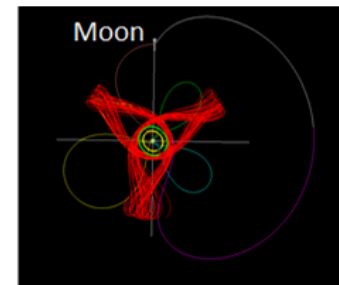
Outer Van Allen Belt 60,000 km



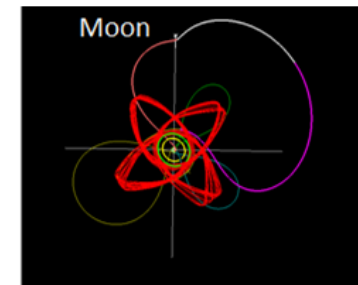
LADEE  
Phasing loops to lunar capture



2:1 Resonance TESS-like  
Phasing loops to lunar swingby  
67,000 x 404,000 km



3:1 Resonance IBEX-like  
Phasing loops to lunar swingby  
78,000 x 284,000 km



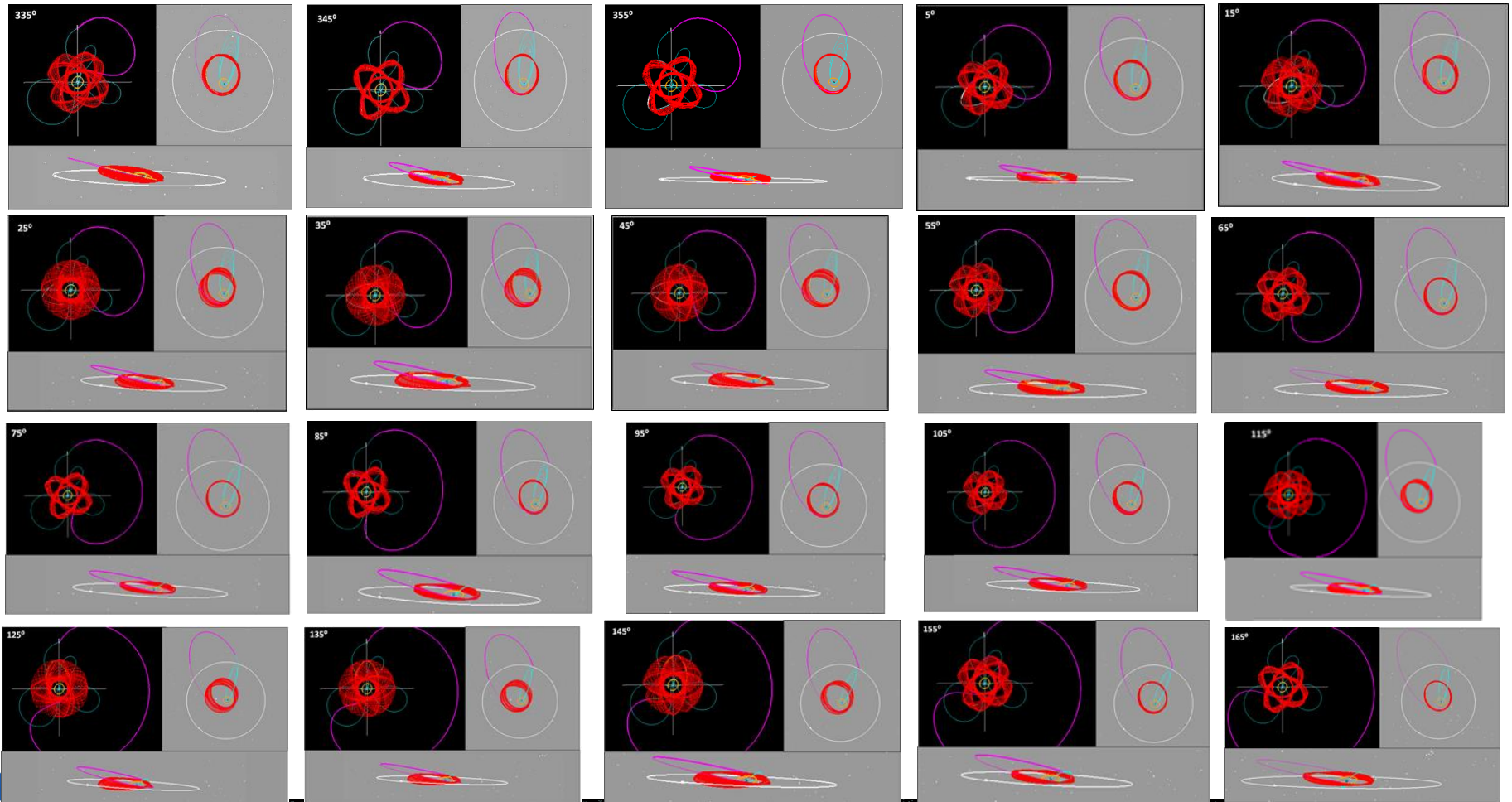
4:1 Resonance Arcus baseline  
Phasing loops to lunar swingby  
72,000 x 220,000 km





# Stable HEO with and without Resonance

- Targeting accesses the post-swingy perigee orientation relative to the Moon's position



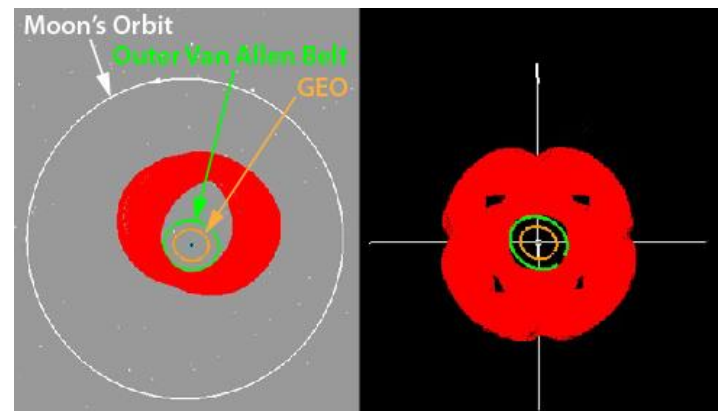




# Stability

- Orbit precesses but stays resonant
- One measure of stability shows in long term propagation
- Additional stability investigations of
  - SMA
  - Inclination
  - Line of nodes
  - Line of apsides

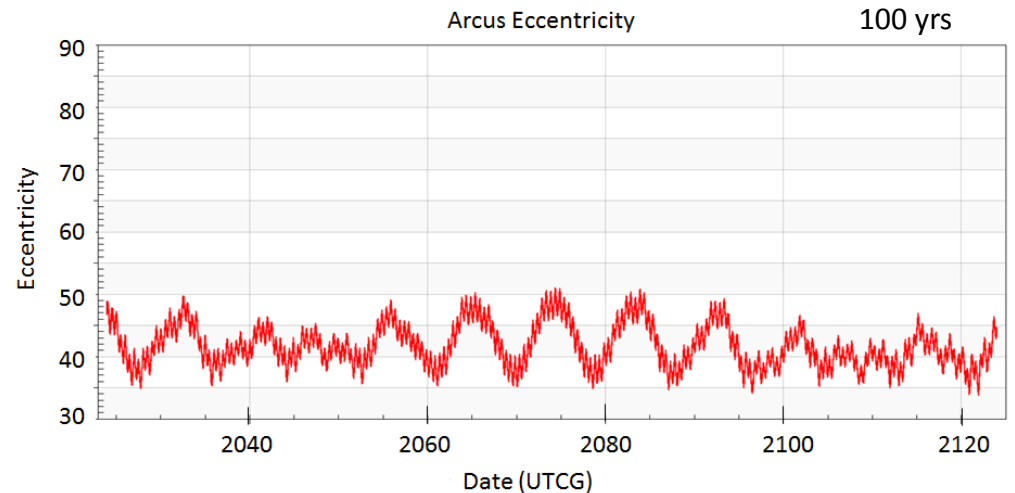
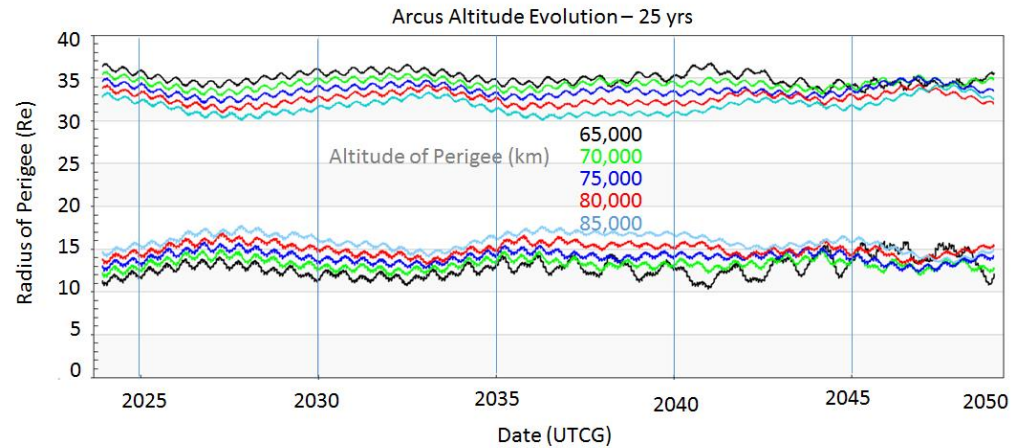
Resonance persists for at least 100 years





# Stability – Trends in SMA

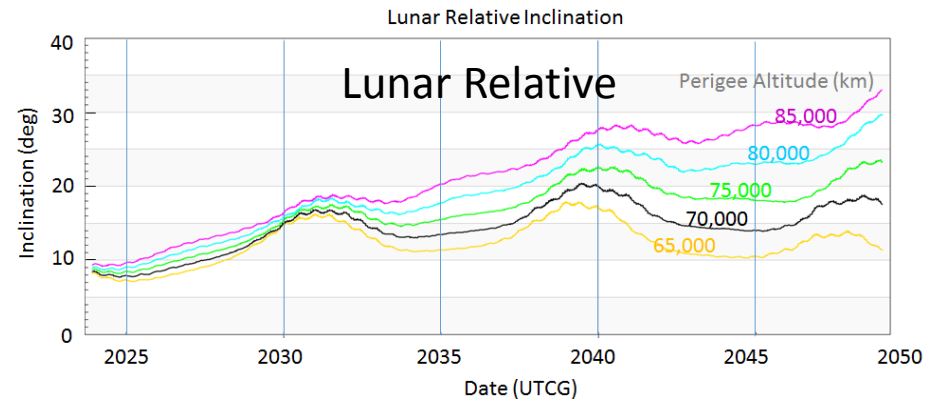
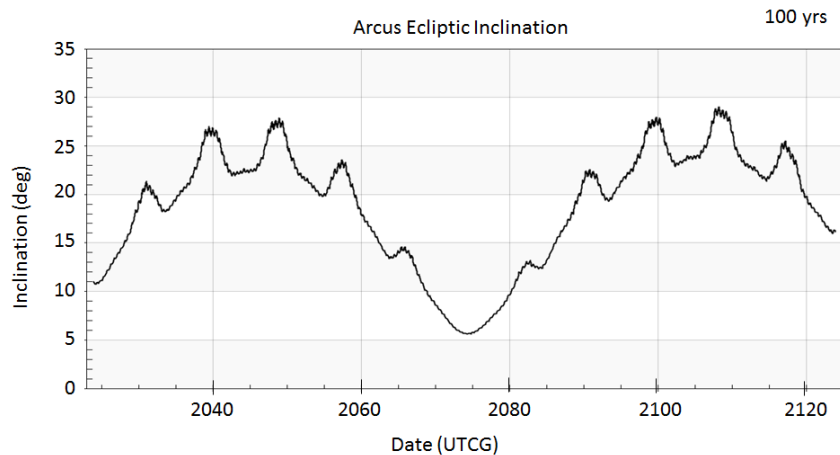
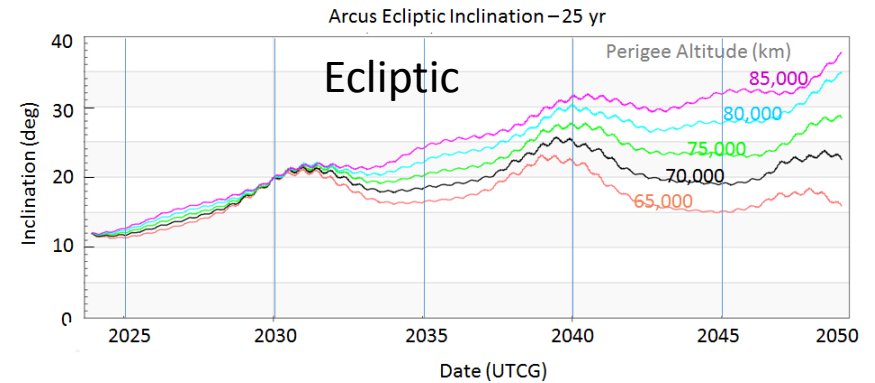
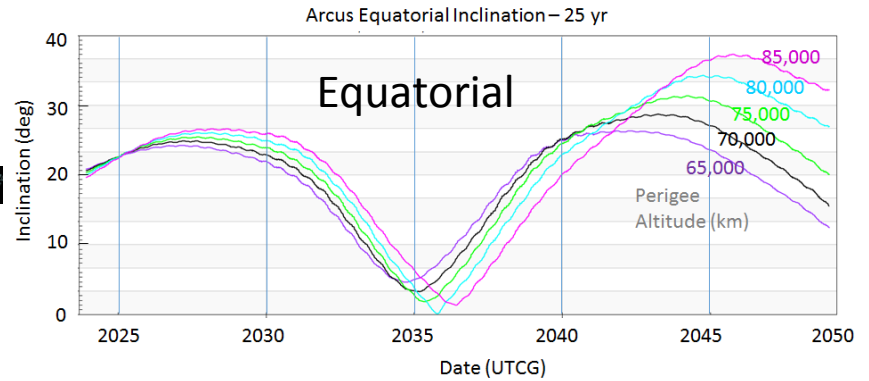
- Most of the trade space of P/4 solutions appears to hold altitude similarly to P/3 and P/2 results.
- Higher apogee altitudes have larger perturbations





# Trends in Inclination

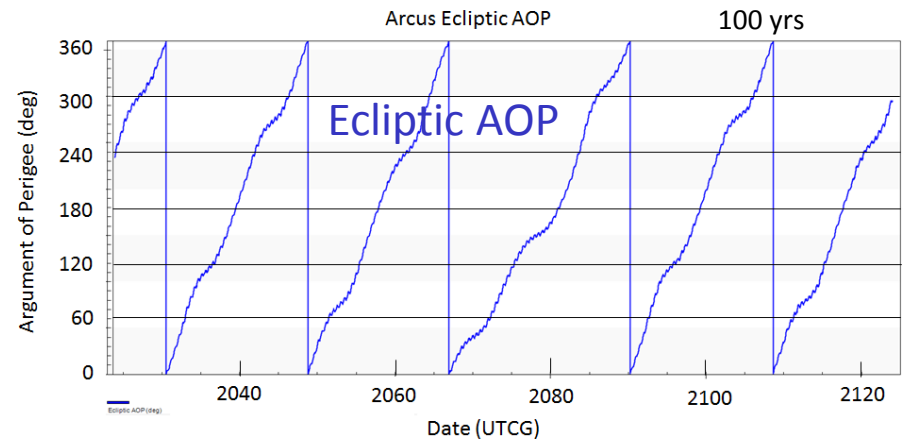
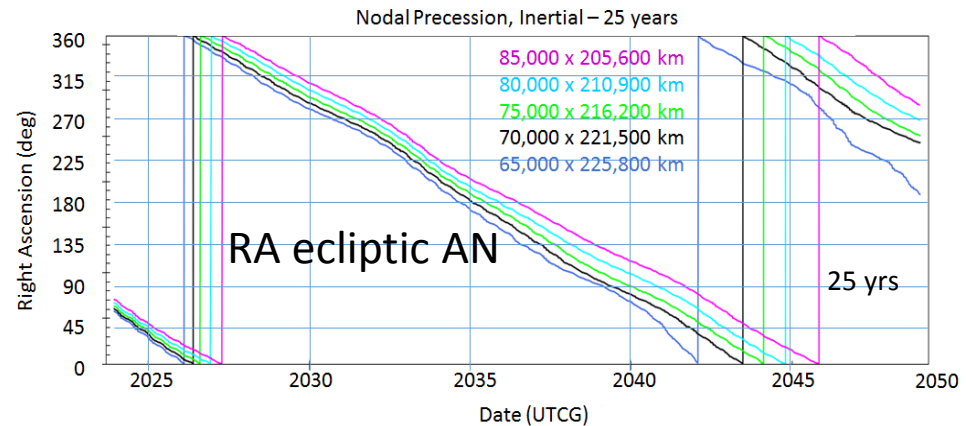
- Short and long cycles
- Reference planes
  - Equatorial
  - Ecliptic
  - Moon's orbit plane





# Stability – Nodal & Apsidal Precession 1

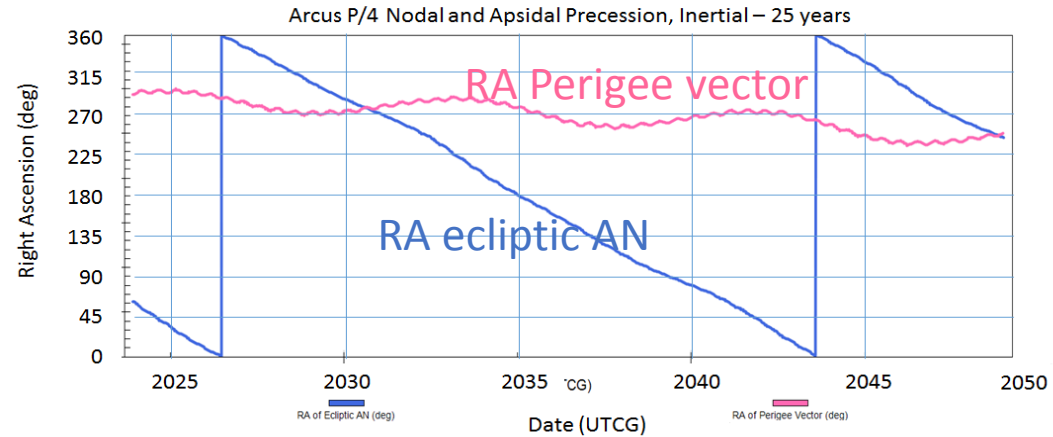
- Ascending node wrt the ecliptic plane
  - Using RA
  - Ecliptic longitude more appropriate for higher ecliptic inclinations
  - Precession varies with eccentricity, probably due to apogee altitude
- Argument of perigee has a long term secular trend
- Inertial direction of perigee is stable
  - (next slide)



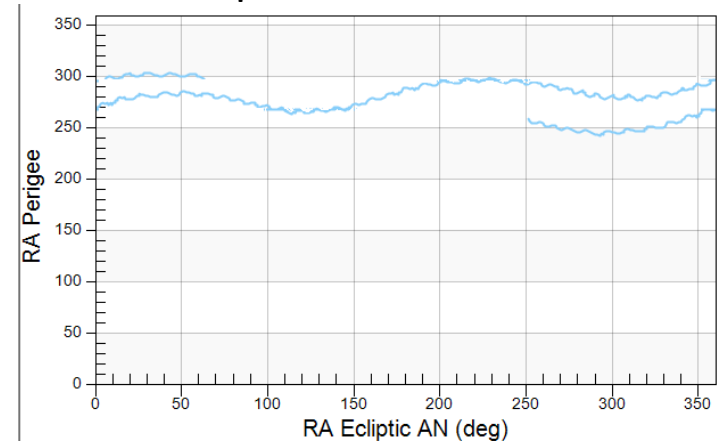


# Stability – Nodal & Apsidal Precession 2

- Inertially, the line of nodes precesses significantly while the line of apsides has a slower trend
  - Measured in Right Ascension
  - 25 year example



## Line of Apsides vs. Line of Nodes



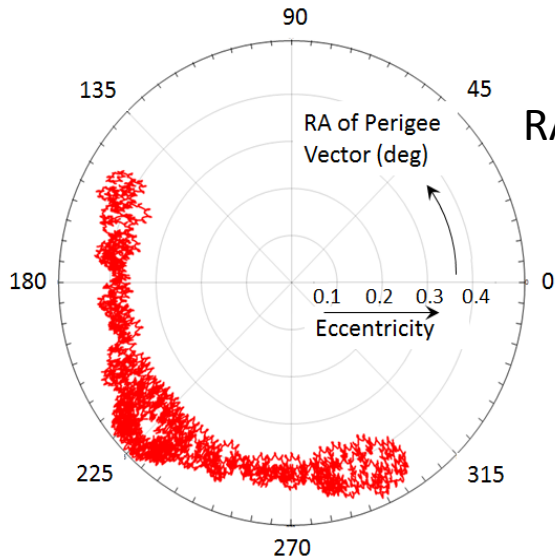




# Stability – e- $\omega$ Plots

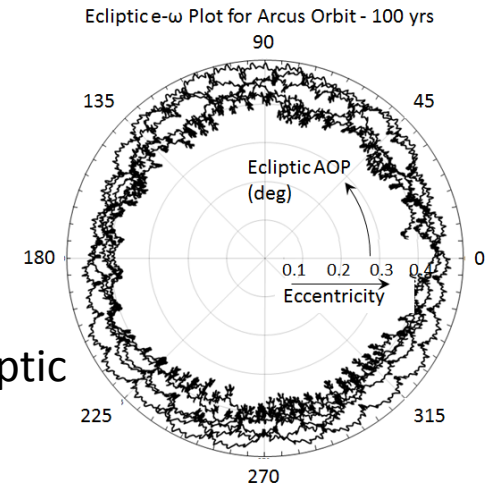
- P/4 is low enough in relation to the Moon that it starts to show characteristics of two-body perturbations
- AOP precesses 0-360° but the perigee vector varies less
- 100 year propagations

Orientation (RA) and Eccentricity of Arcus Orbit - 100 yrs

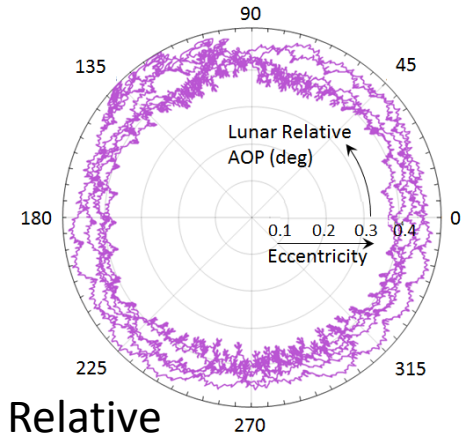


RA of perigee vector

AOP, Ecliptic



e- $\omega$  Plot Using Lunar Relative AOP for Arcus - 100 yrs



AOP, Lunar Relative

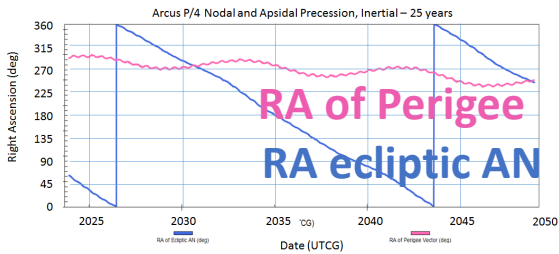




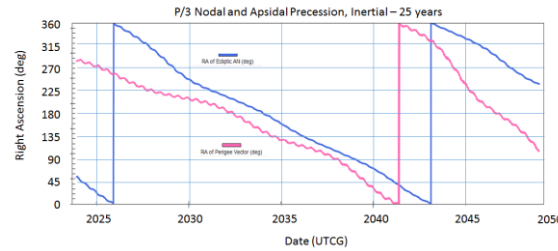
# Precession Comparison, P/3 and P/4

- Similar starting orientation
- 25 year propagations
- Apogee altitude difference between P/3 and P/4 orbits is enough to change the precession of the perigee vector RA
- 7/2 solutions exist between P/3 and P/4. Still to investigate.

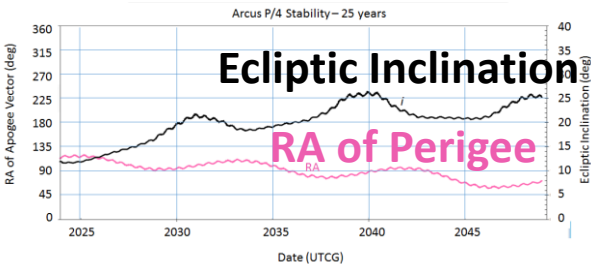
P/4



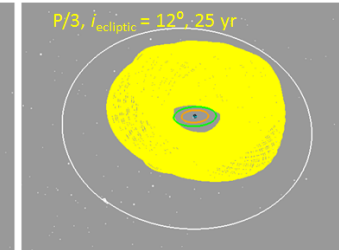
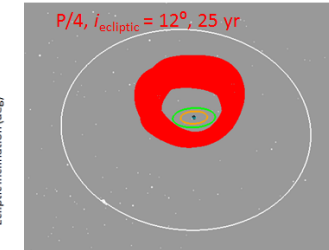
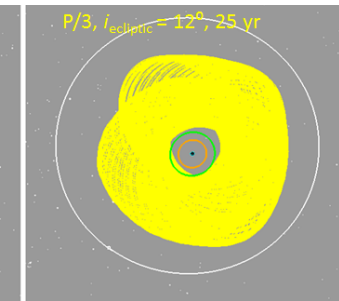
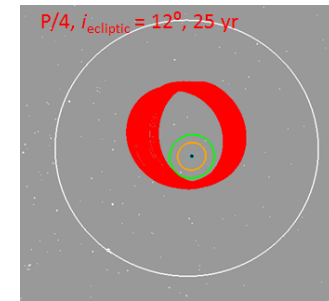
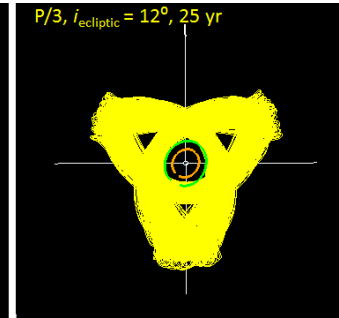
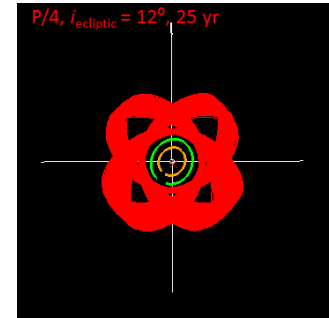
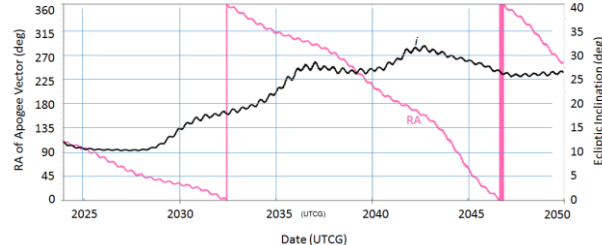
P/4



Ecliptic Inclination



Low Inclination P/3 Stability - 25 years





# Ground Segment Design

- NASA DSN 34-m antennas
  - Selected for high data rate
  - Two-way coherent Doppler & sequential range
  - Three 1-hour TT&C contacts per 6.8-day orbit
    - ascending side, apogee, descending side
  - Fourth DSN support at perigee for science data downloads
- NASA Ames Multi-Mission Operations Center
  - Flight Dynamics System (FDS) based on STK & ODTK
  - Same MMOC & FDS as LADEE mission





# Orbit Determination

- With science targets at infinity, the Arcus investigation places very little demand on estimation accuracy.
- Prediction accuracy requirements
  - Maneuver planning
  - DSN acquisition and scheduling
  - No accuracy requirements for science activity planning requirements
- Definitive accuracy requirements
  - Maneuver reconstruction & trending
  - No accuracy requirements for science data processing

***OD approach reflects goals to simplify mission ops***



