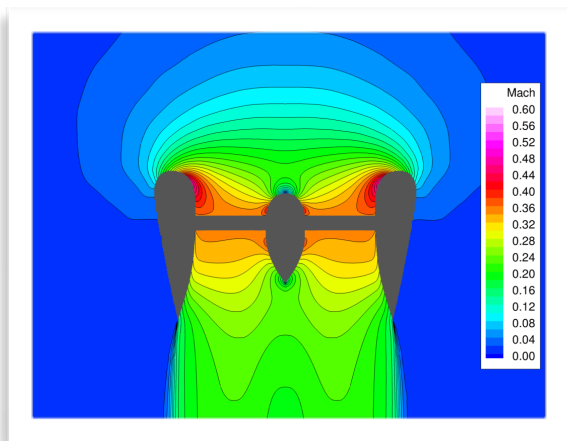


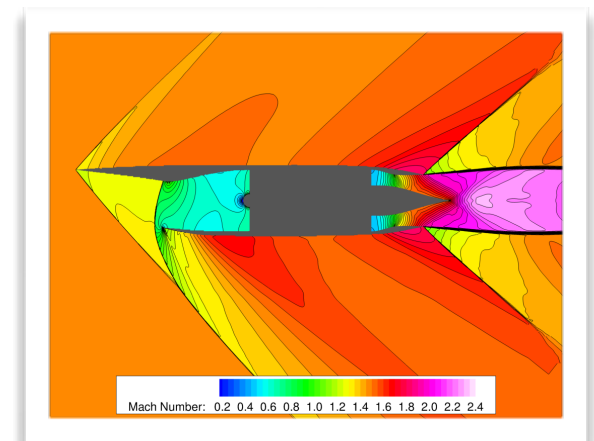
# Formulation and Implementation of Inflow/Outflow Boundary Conditions to Simulate Propulsive Effects



David L Rodriguez  
Michael Aftosmis  
Marian Nemec

May 10, 2018  
AMS Seminar Series

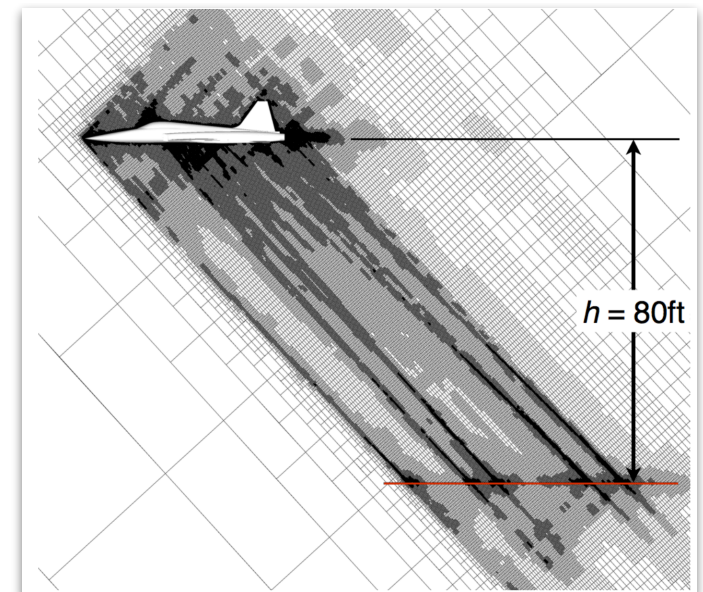
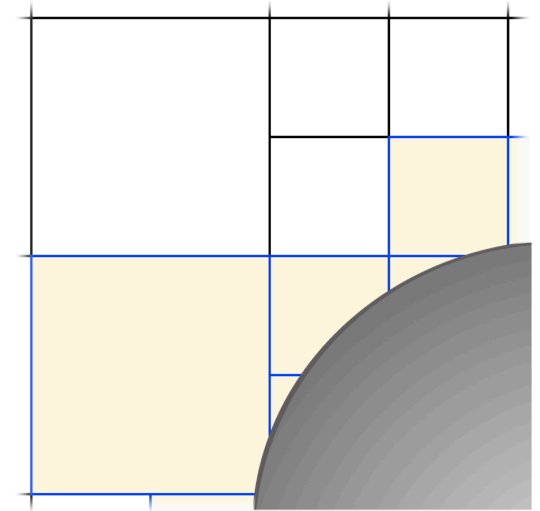
*NASA Ames Research Center  
Science & Technology Corporation*

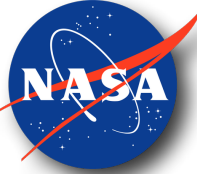


# Cart3D Aerodynamic Analysis & Design Package



- Automated multilevel Cartesian mesh generation with adjoint-driven adaptive refinement
- Cut-cell approach in cells that include model surface
- Finite volume, 2nd-order accurate Euler solver with explicit Runge-Kutta time stepping and multigrid
- Steady or time-accurate
- Part of a design framework allowing for gradient-based aerodynamic shape optimization of user-specified functional
- Shown to be highly effective for analysis and design of low boom aircraft





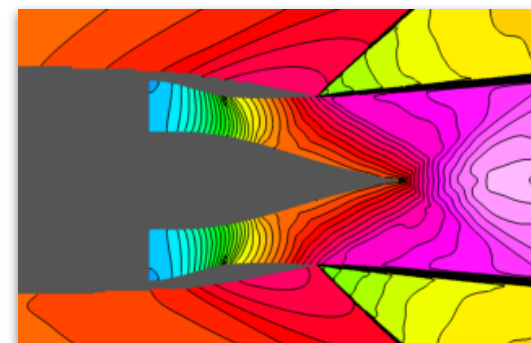
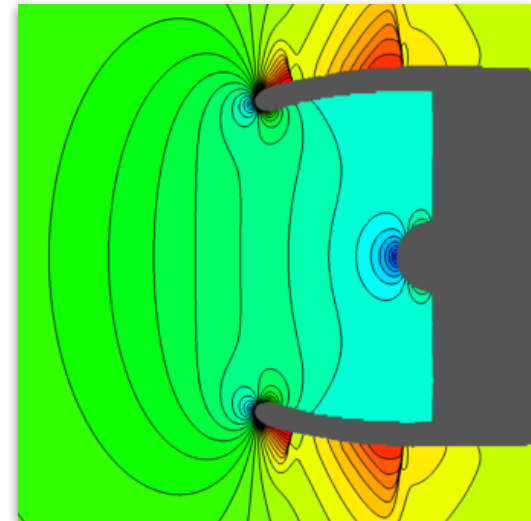
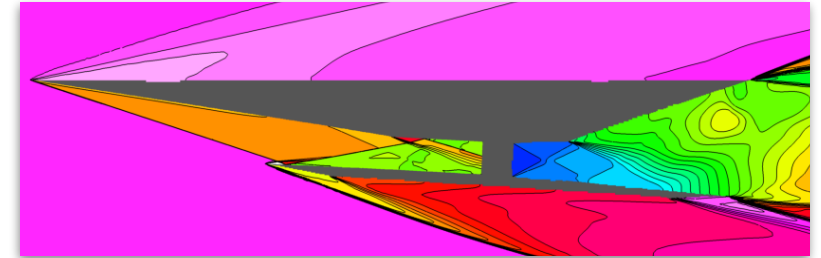
# Motivation for New Boundary Conditions

---

- Current **SurfBC** inflow/outflow boundary condition requires user to specify an entire state ( $\rho, u, v, w, p$ ) at the boundary (Pandya, 2004)
  - Riemann solver is applied to compute flux at the boundary and thus boundary condition is always well-posed
  - Robust and flexible since it can be used for both inflow and outflow, subsonic and supersonic
- Inconvenient when user wants to specify inflow or outflow with minimal information
  - for subsonic flow through inlets, a common boundary condition is back pressure
  - for subsonic flow into nozzles, a common boundary condition is specifying total pressure and total temperature (and flow direction)
  - very difficult to specify mass flow rate, particularly in cases where nonlinear flow features are prevalent

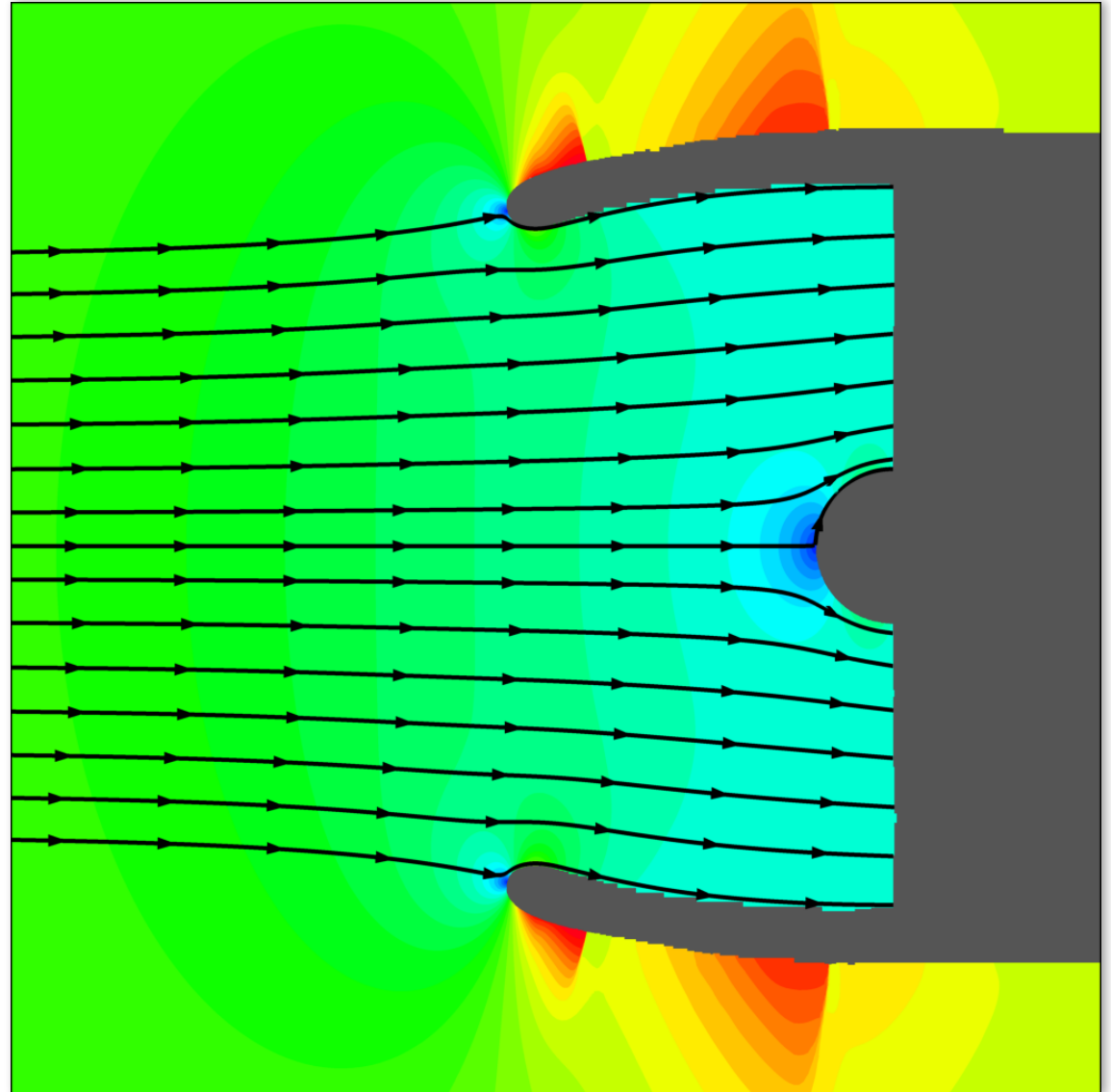
# Cart3D Surface Boundary Conditions

- Solid wall
- Specify full flow state and use Riemann solver (**SurfBC**)
  - Pandya, Murman, Aftosmis, 2004
  - for all inflows and outflows
- Subsonic Outflow
  - back pressure **NEW**
  - constant normal velocity **NEW**
- Subsonic Inflow
  - total pressure and total temperature **NEW**
  - mass flow rate and total temperature **NEW**



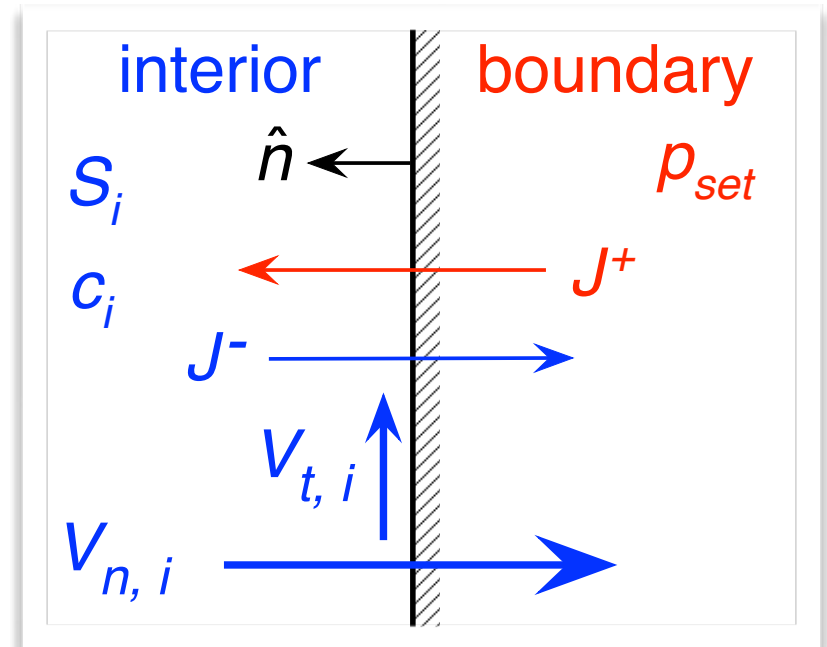
# Subsonic Outflow Boundary Conditions

- One flow quantity specified at boundary
  - back pressure
  - normal velocity
- Four flow quantities extrapolated from interior



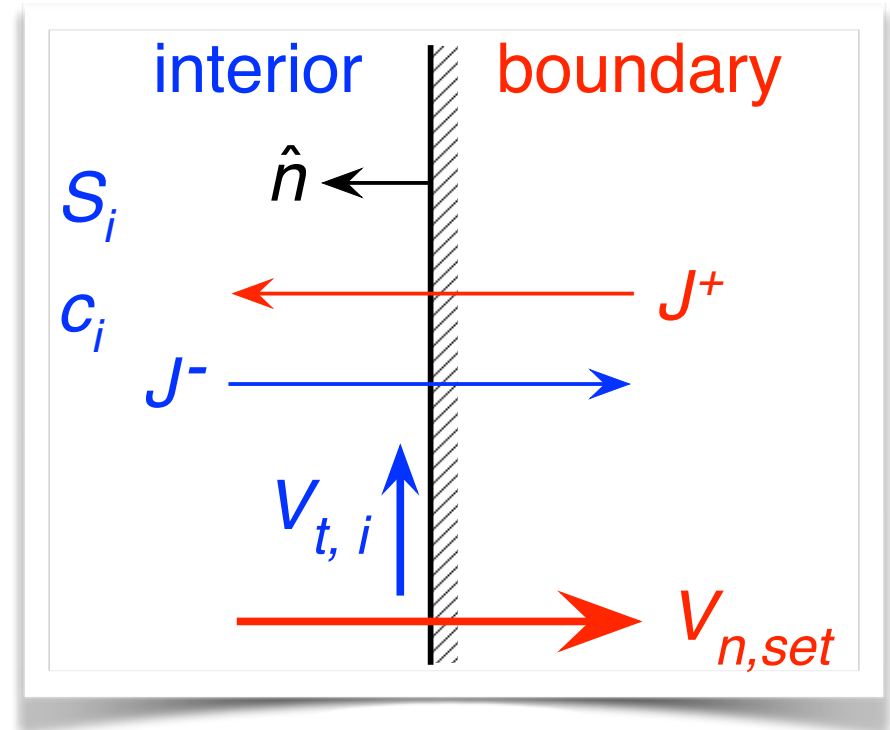
# Back Pressure Outflow

- Most other CFD solvers have this common option
- Pressure set to specified value at boundary
- Entropy and tangential velocity extrapolated from interior
- Riemann invariants used to compute boundary state
- Safeguards
  - if flow reverses back into interior (back pressure too high), solid wall boundary enforced
  - if interior flow goes supersonic, compare back pressure to pressure after normal shock occurring at boundary
    - if set back pressure is higher, use after-shock state at boundary, forcing subsonic flow in the interior
    - if set back pressure is lower, extrapolate all flow attributes from interior (supersonic outflow)
- Can be difficult to obtain specific mass flow rate for nonlinear flows



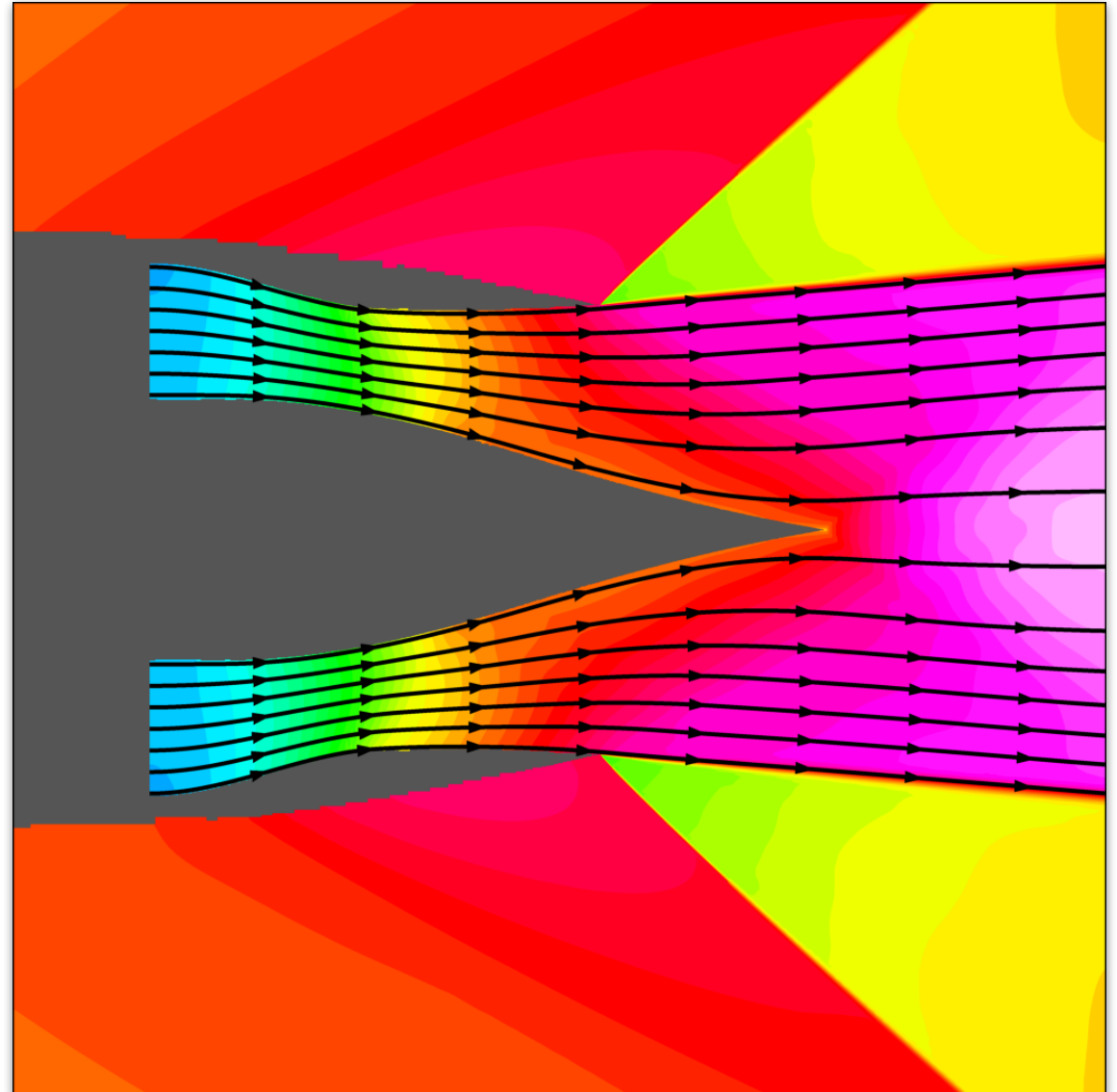
# Constant Normal Velocity Outflow

- Allows for robust mass flow rate steering
- Might better represent flow in front of an engine fan face (Pearson '59, Reid '69)
- Normal velocity set to specified value at boundary
- Entropy and tangential velocity extrapolated from interior
- Riemann invariants used to compute boundary state
- Safeguards
  - when interior flow is subsonic but boundary flow is supersonic (bad input velocity), flow is forced to be sonic (choked flow)
  - when interior and boundary flow are both supersonic, supersonic outflow is enforced (all interior quantities extrapolated)



# Subsonic Inflow Boundary Conditions

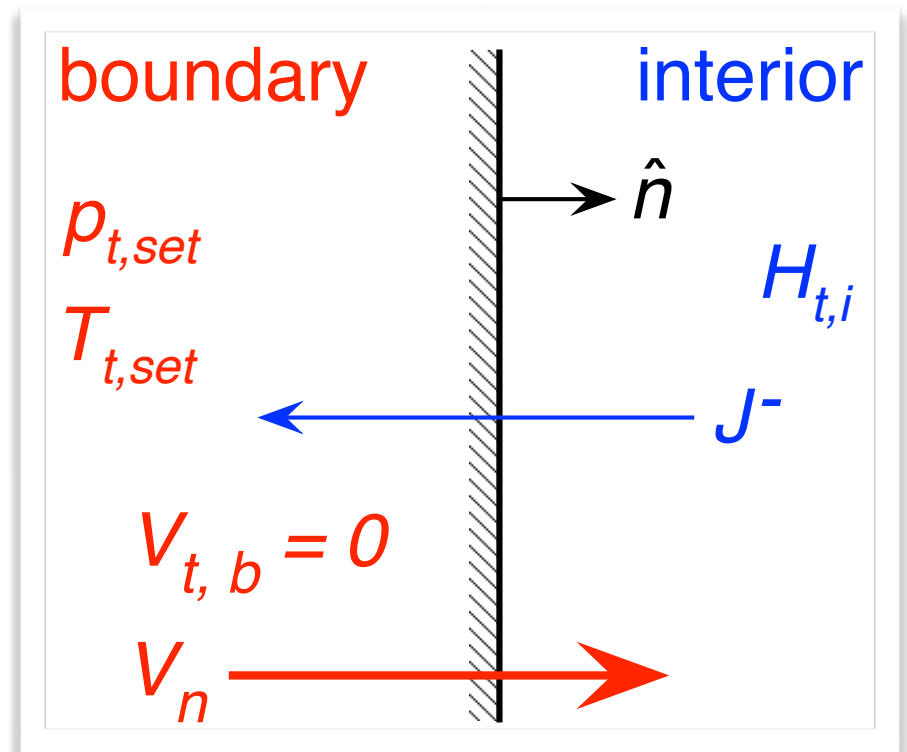
- Four flow quantities specified at boundary
  - velocity set to be normal to boundary (two flow quantities)
  - total pressure and total temperature
  - mass flow rate and total temperature
- One flow quantity extrapolated from interior

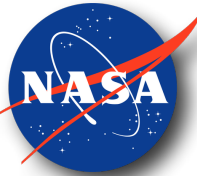




# Stagnation Property Inflow

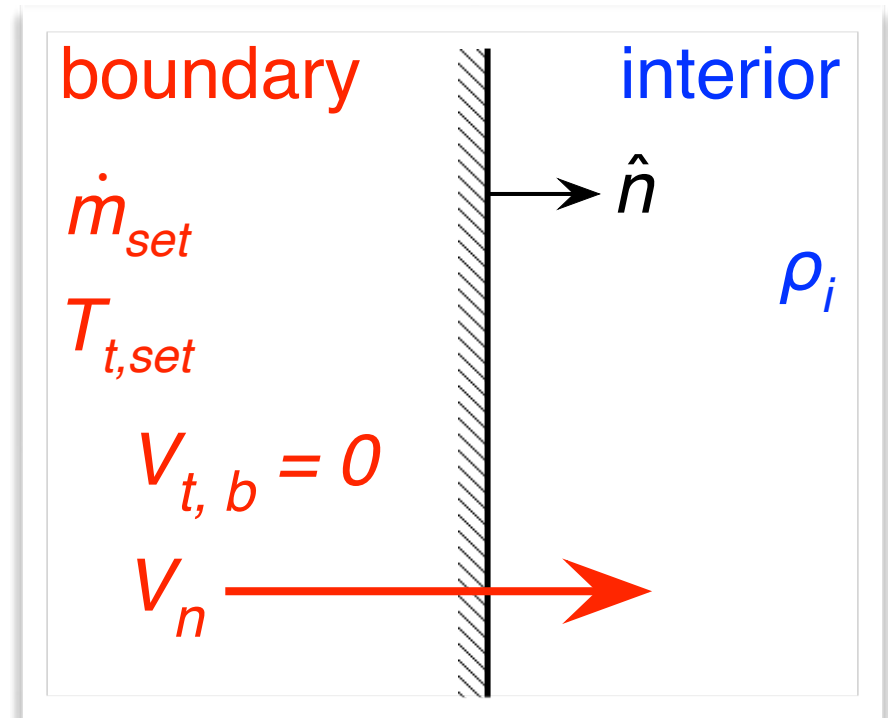
- Most other CFD solvers have this common option
- Total pressure and temperature set to specified value at boundary
- Tangential velocity set to zero, forcing inflow to be normal to surface
- Enthalpy is extrapolated from interior
- Riemann invariant used to computed boundary state
- Safeguards
  - when flow tries to reverse back into boundary, solid wall boundary enforced
  - inflow Mach number is limited to sonic, adjusting stagnation properties accordingly
- Cannot explicitly set a mass flow rate





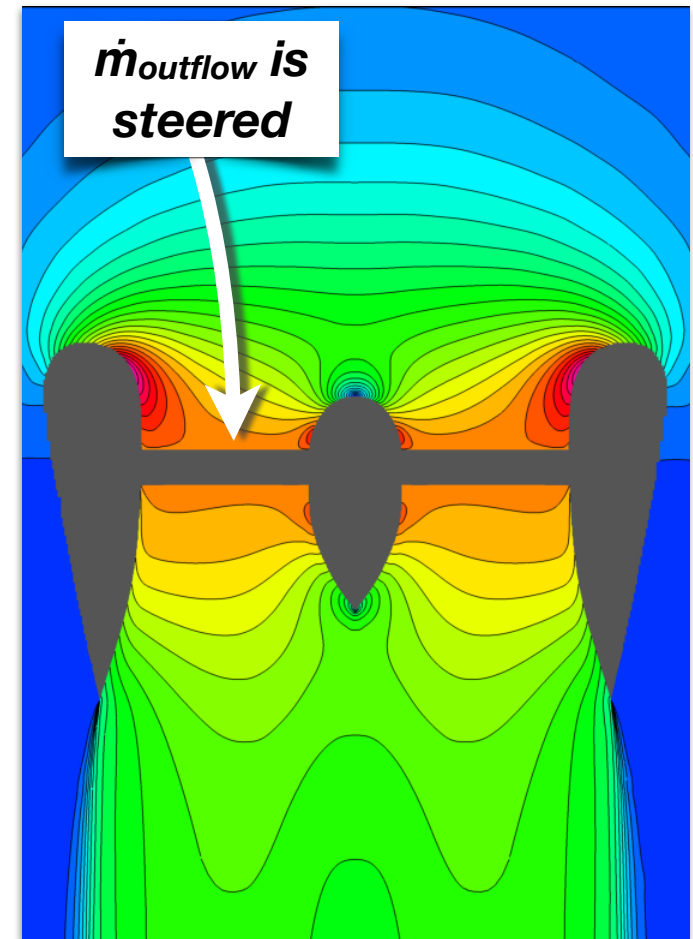
# Mass Flow Rate and Total Temperature Inflow

- Allows for explicit mass flow rate control
- Mass flow rate and total temperature set to specified value at boundary
- Tangential velocity set to zero, forcing inflow to be normal to surface
- Density is extrapolated from interior
- Boundary flux computed from boundary state
- Safeguard
  - inflow Mach number is limited to sonic, adjusting boundary values accordingly



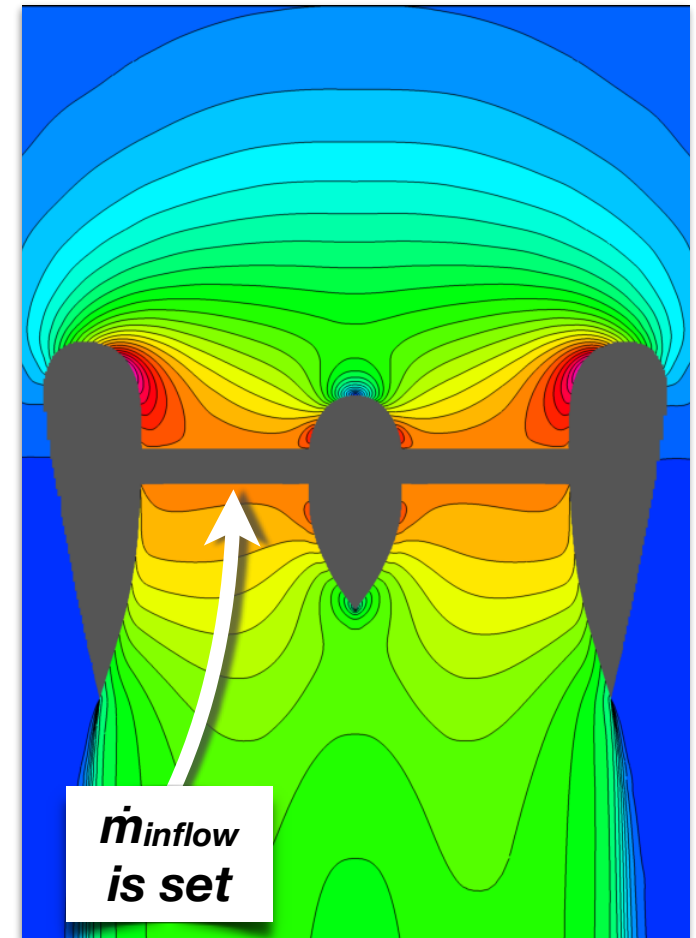
# Mass Flow Rate Control

- Constant velocity outflow boundary condition can be steered to obtain specified mass flow rate out of the domain
  - average density over surface is computed
  - velocity out of domain is set based on desired mass flow rate
  - repeat every few iterations until solution converged and mass flow rate within tolerance



# Mass Flow Rate Control

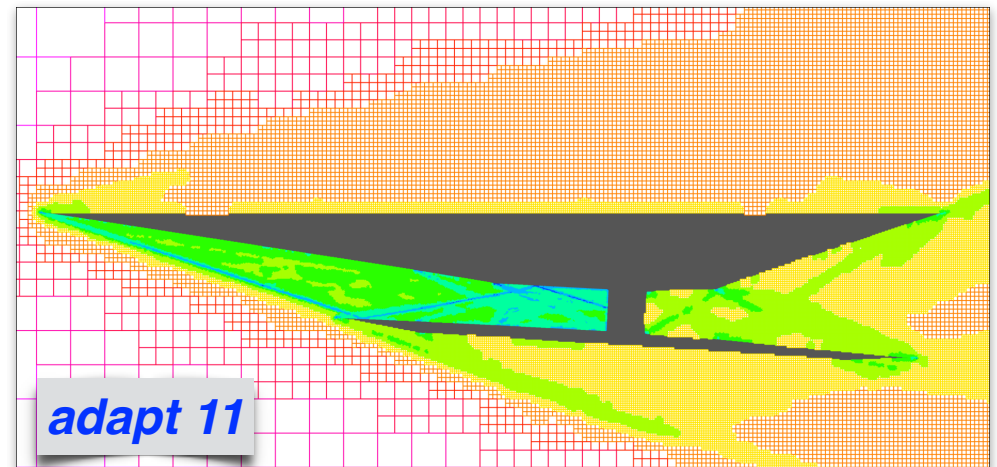
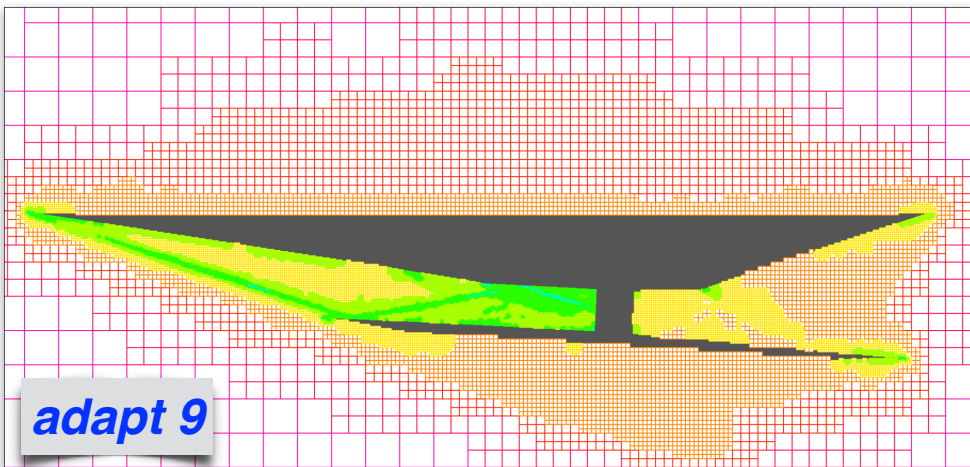
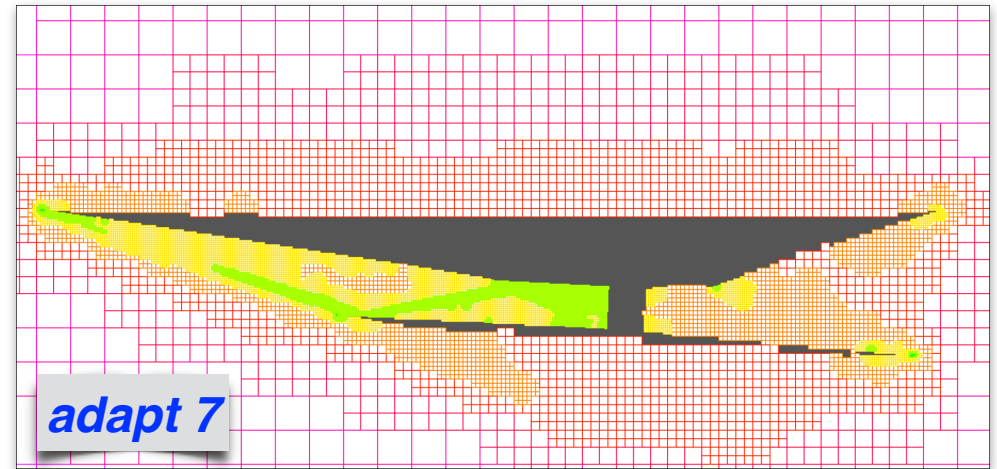
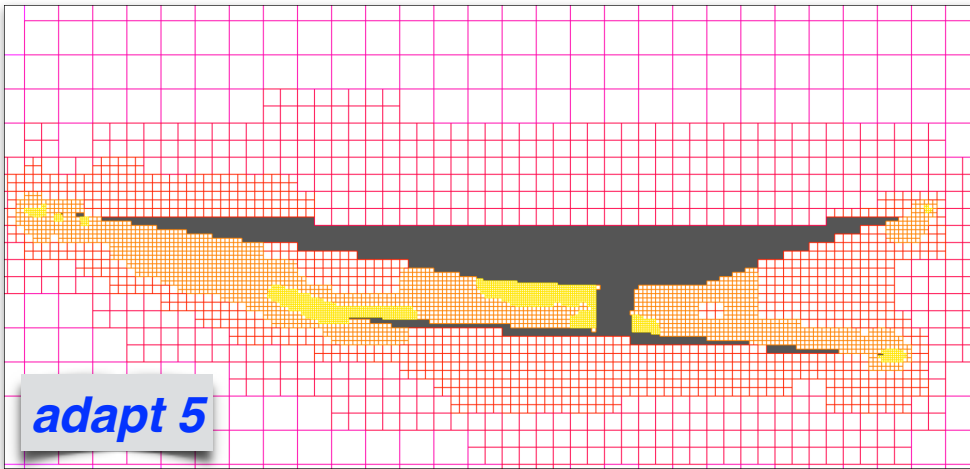
- Constant velocity outflow boundary condition can be steered to obtain specified mass flow rate out of the domain
  - average density over surface is computed
  - velocity out of domain is set based on desired mass flow rate
  - repeat every few iterations until solution converged and mass flow rate within tolerance
- Constant mass flow rate inflow boundary condition explicitly sets mass flow rate into the domain





# Adjoint-Driven Adaptive Mesh Refinement

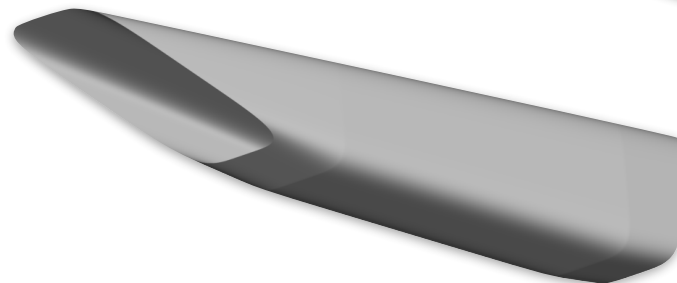
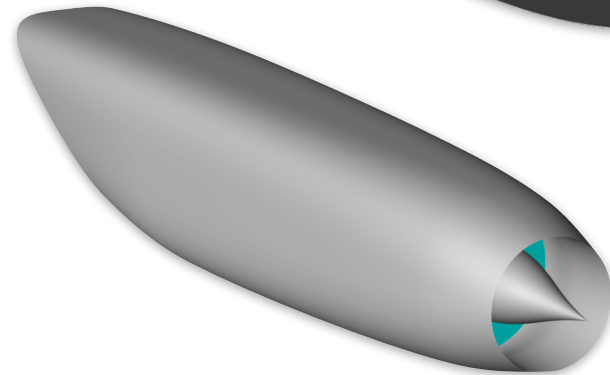
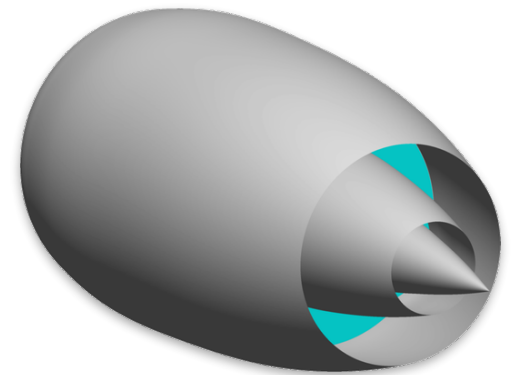
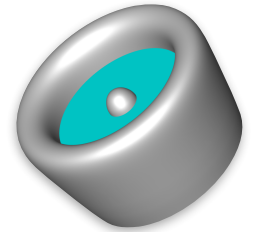
- All boundary conditions now implemented in adaptive mesh refinement process
- Updates to `adjointCart`, `xSensit`, `adjointErrorEstQuad`, etc.



# Application of New Boundary Conditions

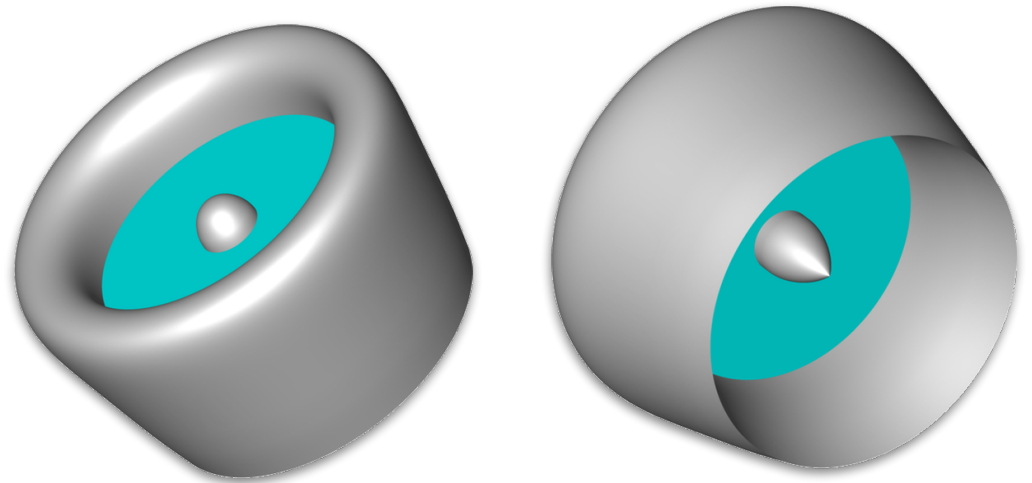
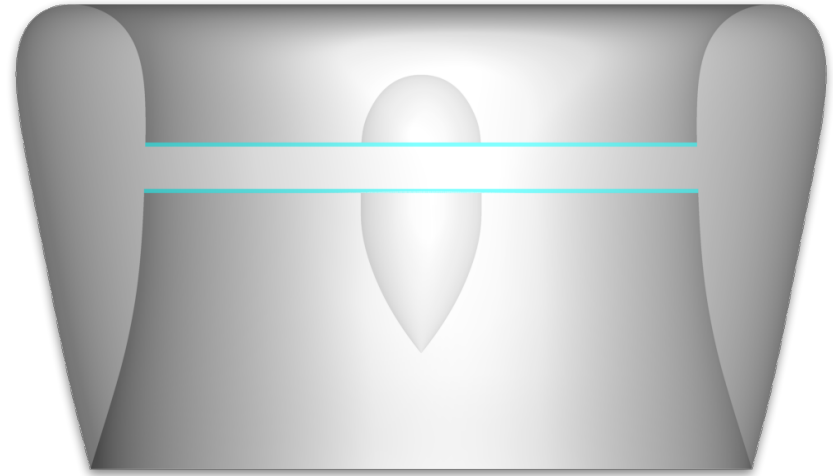


- Ducted fan in near-hover (subsonic)
  - verification of back pressure outflow and mass flow rate inflow boundary conditions
  - mesh convergence through adaptive refinement
  - mass flow rate steering example
- Turbofan with both fan and turbine exhaust streams (transonic)
  - verification of constant velocity outflow and stagnation property inflow boundary conditions
  - mesh convergence through adaptive refinement
  - mass flow rate steering example
- Turbojet with 2-D ramp inlet (supersonic)
  - mesh convergence through adaptive refinement
  - mass flow rate steering example
- Scramjet (hypersonic)
- Low boom demonstrator
- Validation cases

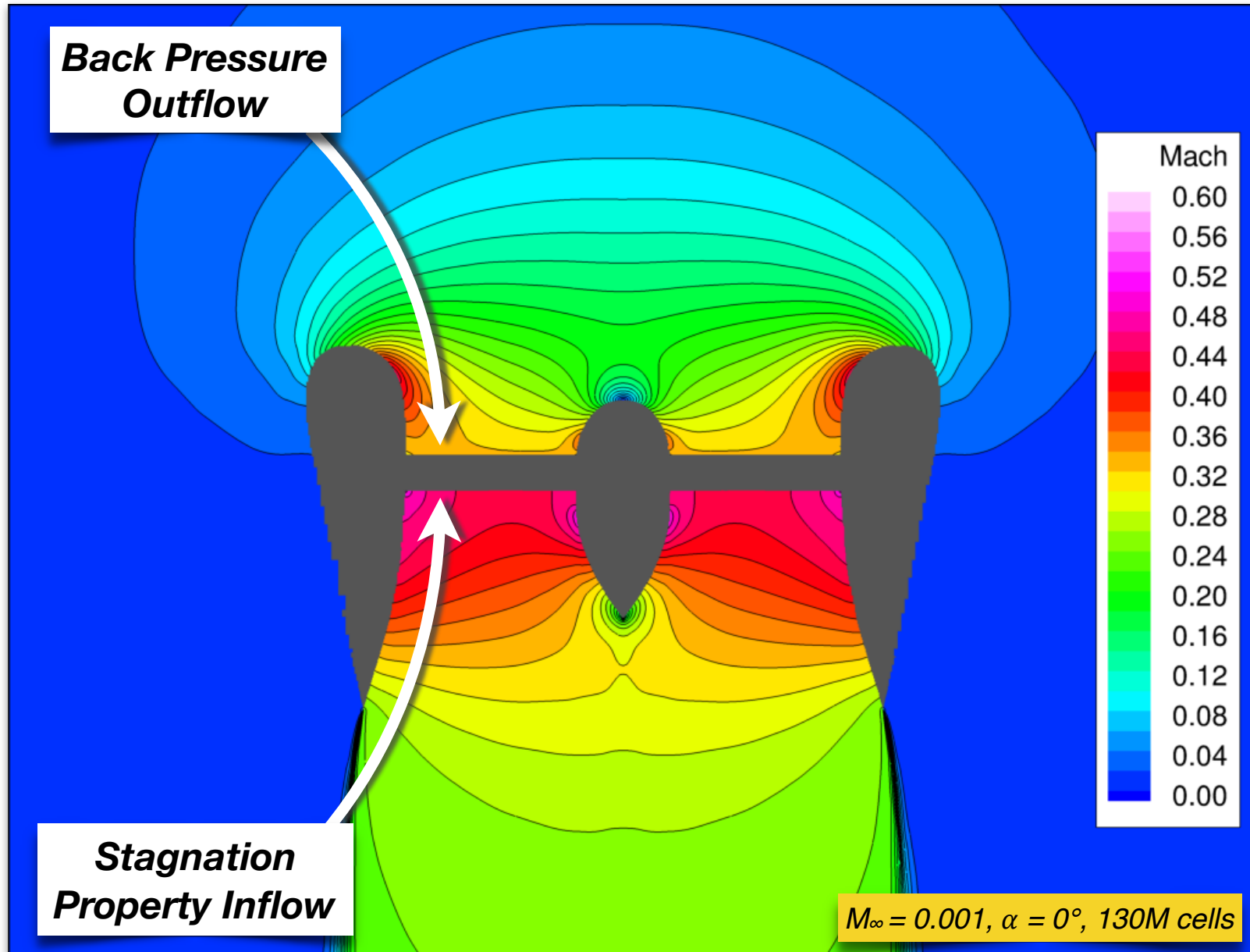


# Ducted Fan in Hover

- Duct and center body housing motor to drive fan
- Very low freestream Mach number (0.001) to simulate near hover
- No angle of attack - axisymmetric flow
- Fan modeled as **annular disk**
- Inflow / Outflow boundary conditions enforced on disk to model fan effects



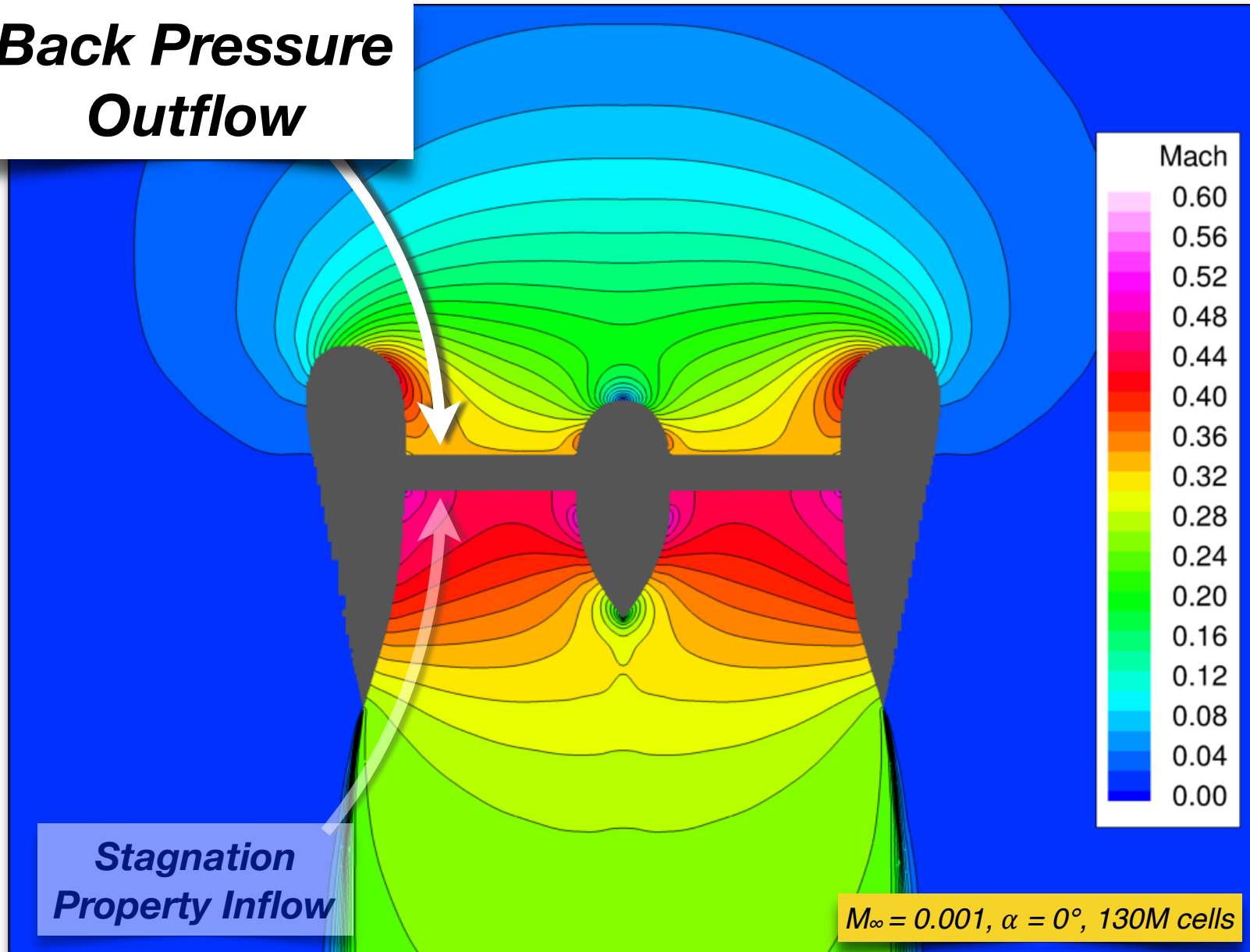
# Ducted Fan - Example Solution





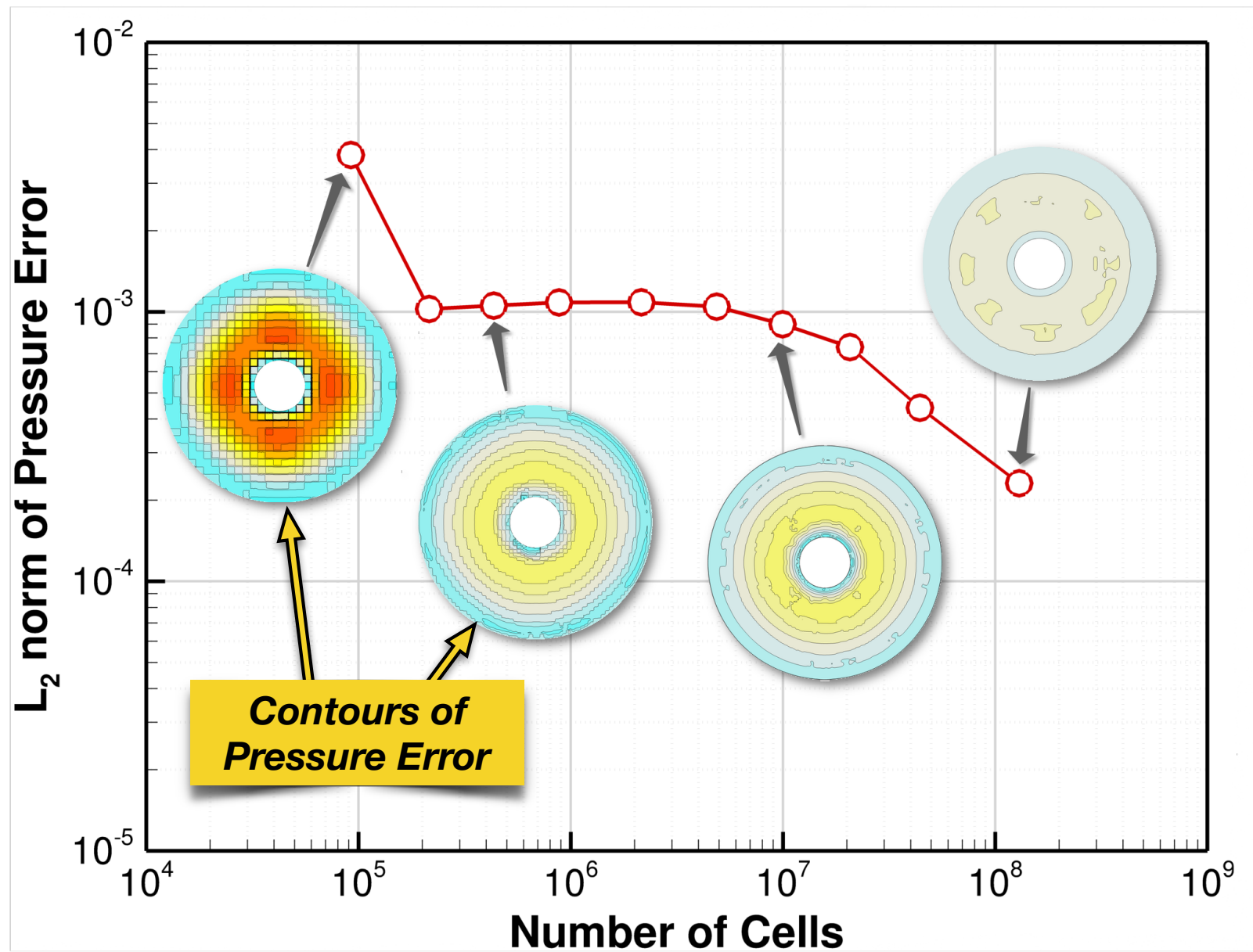
# Ducted Fan - Example Solution

**Back Pressure  
Outflow**

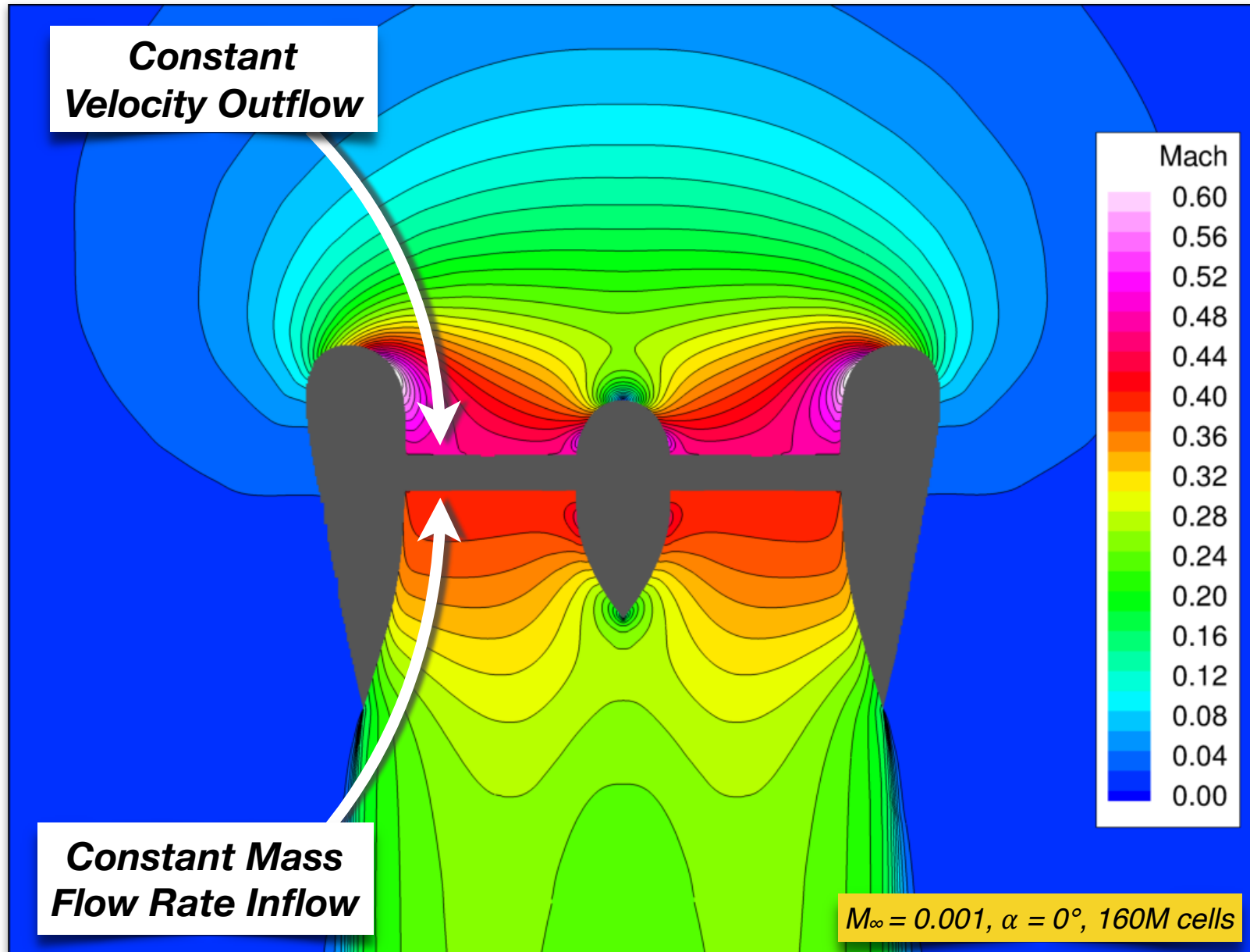


**Stagnation  
Property Inflow**

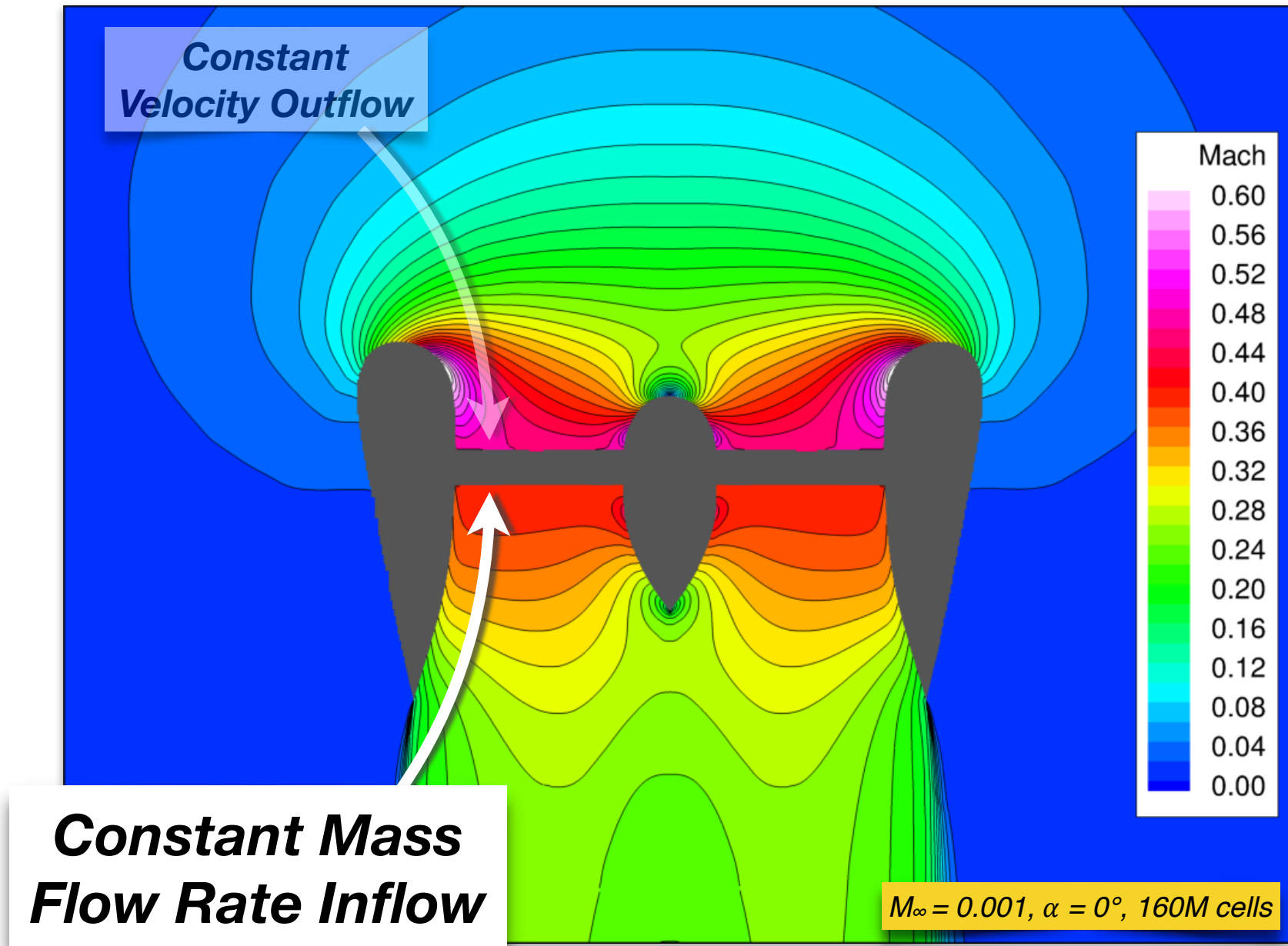
# Back Pressure B.C. Mesh Convergence



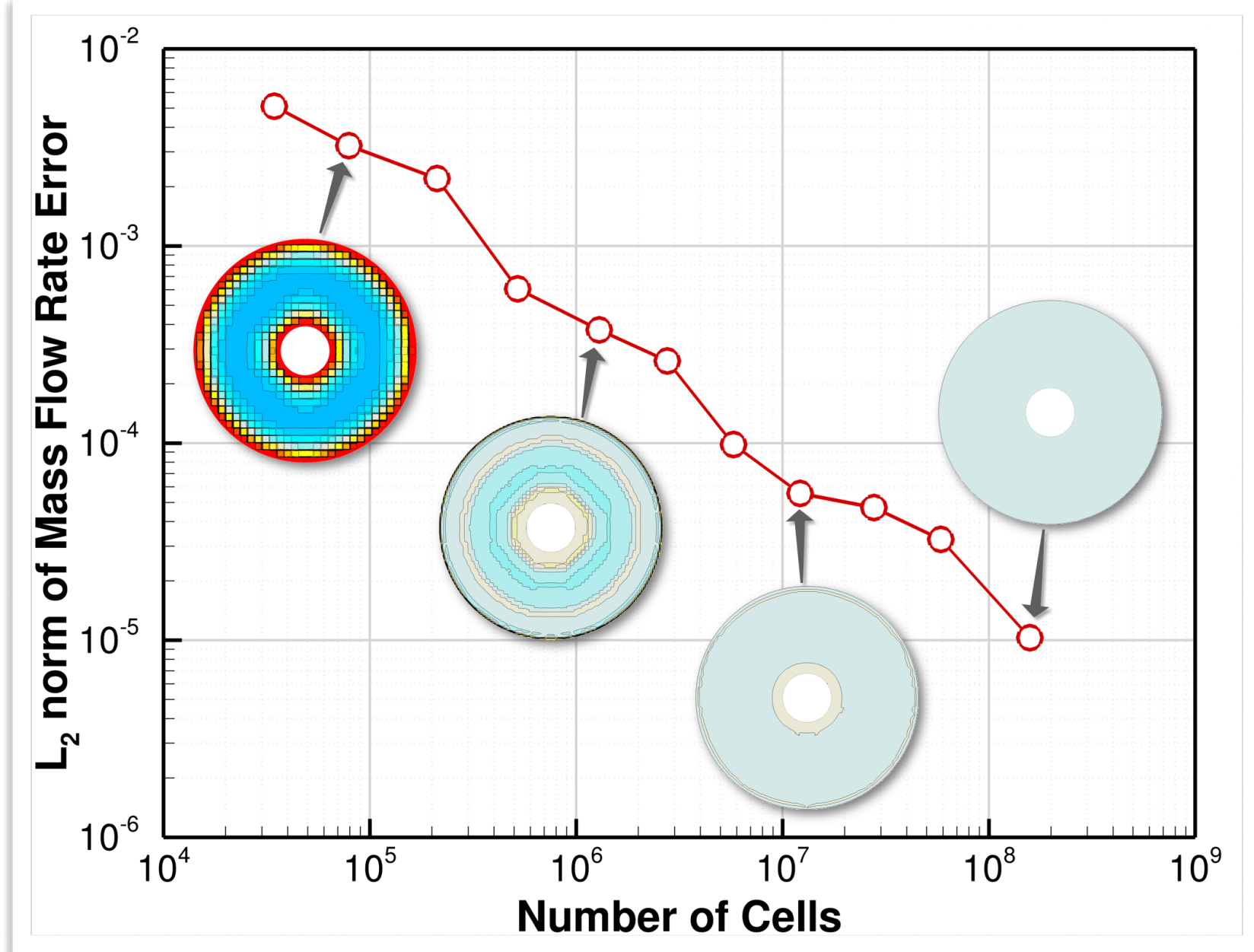
# Ducted Fan - Example Solution



# Ducted Fan - Example Solution



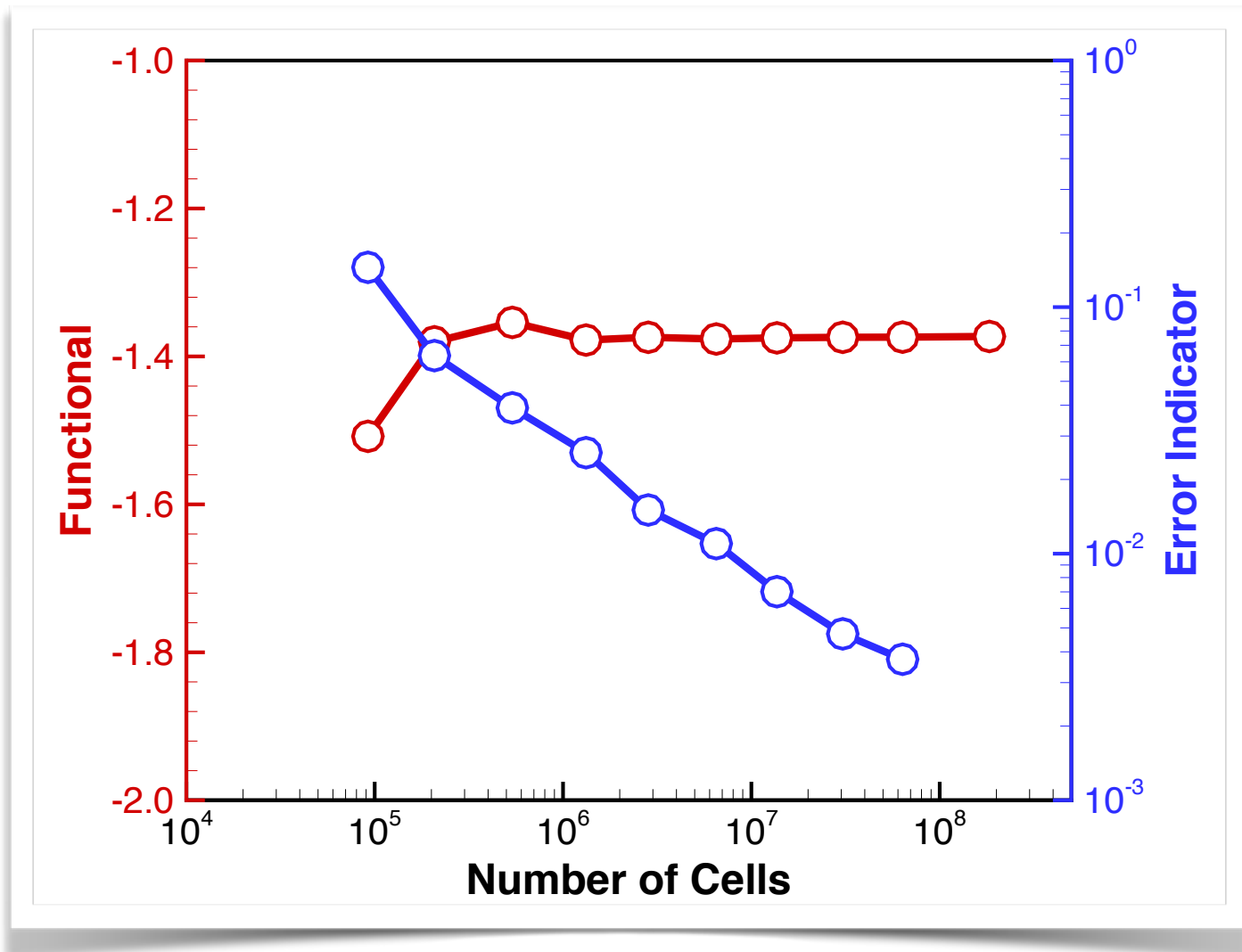
# Constant Mass Flow Rate B.C. Mesh Convergence





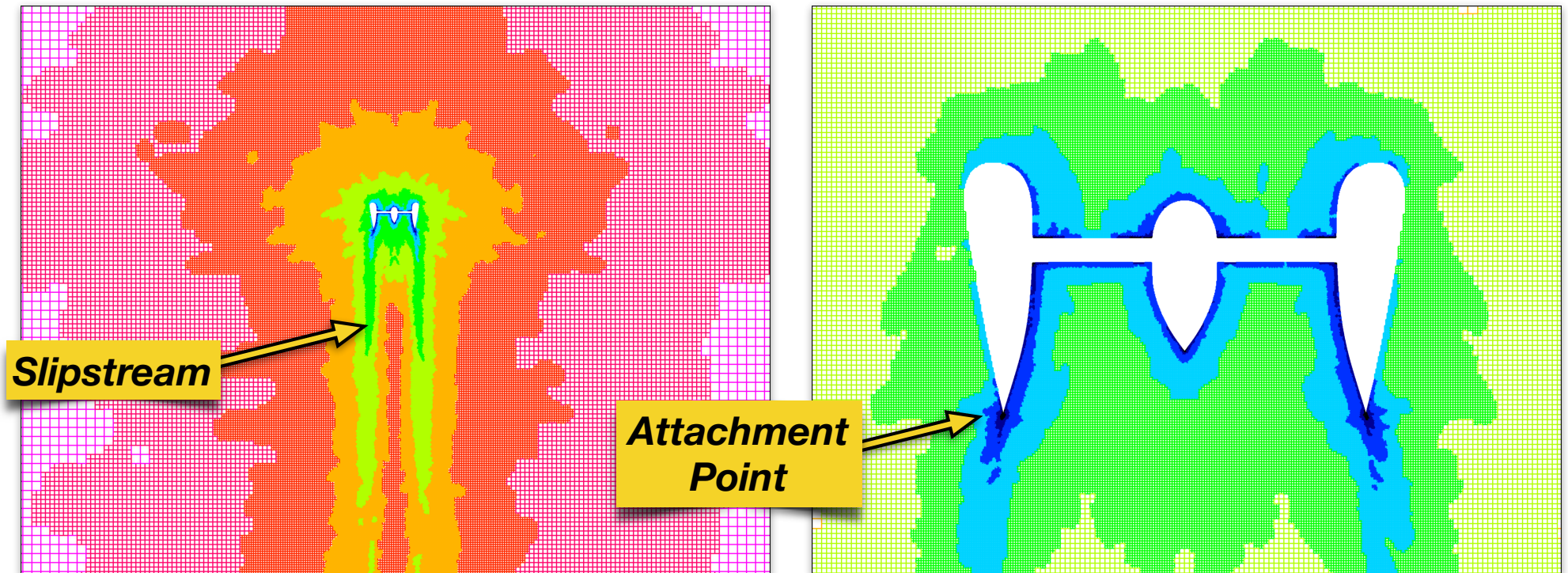
# Ducted Fan - Mesh Convergence

- Good convergence of functional (drag)
- Steady reduction in error estimate

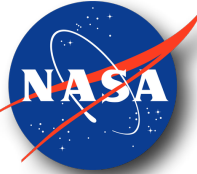


# Ducted Fan - Adaptively Refined Mesh

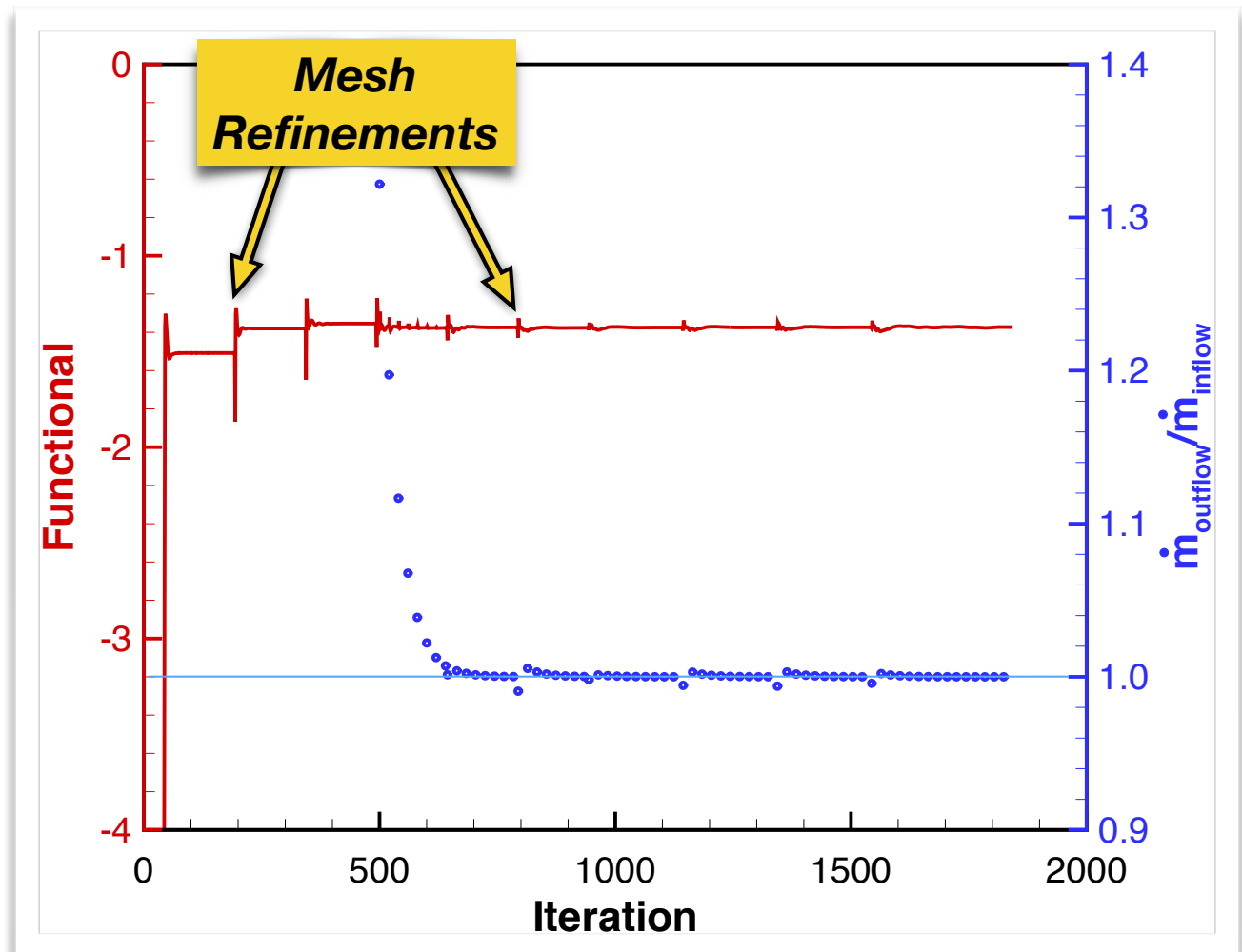
- Colors represent cells of same level of refinement
- Mesh was refined at surface, at shear layer of exhaust flow, and near attachment point



# Ducted Fan - Mass Flow Rate Steering

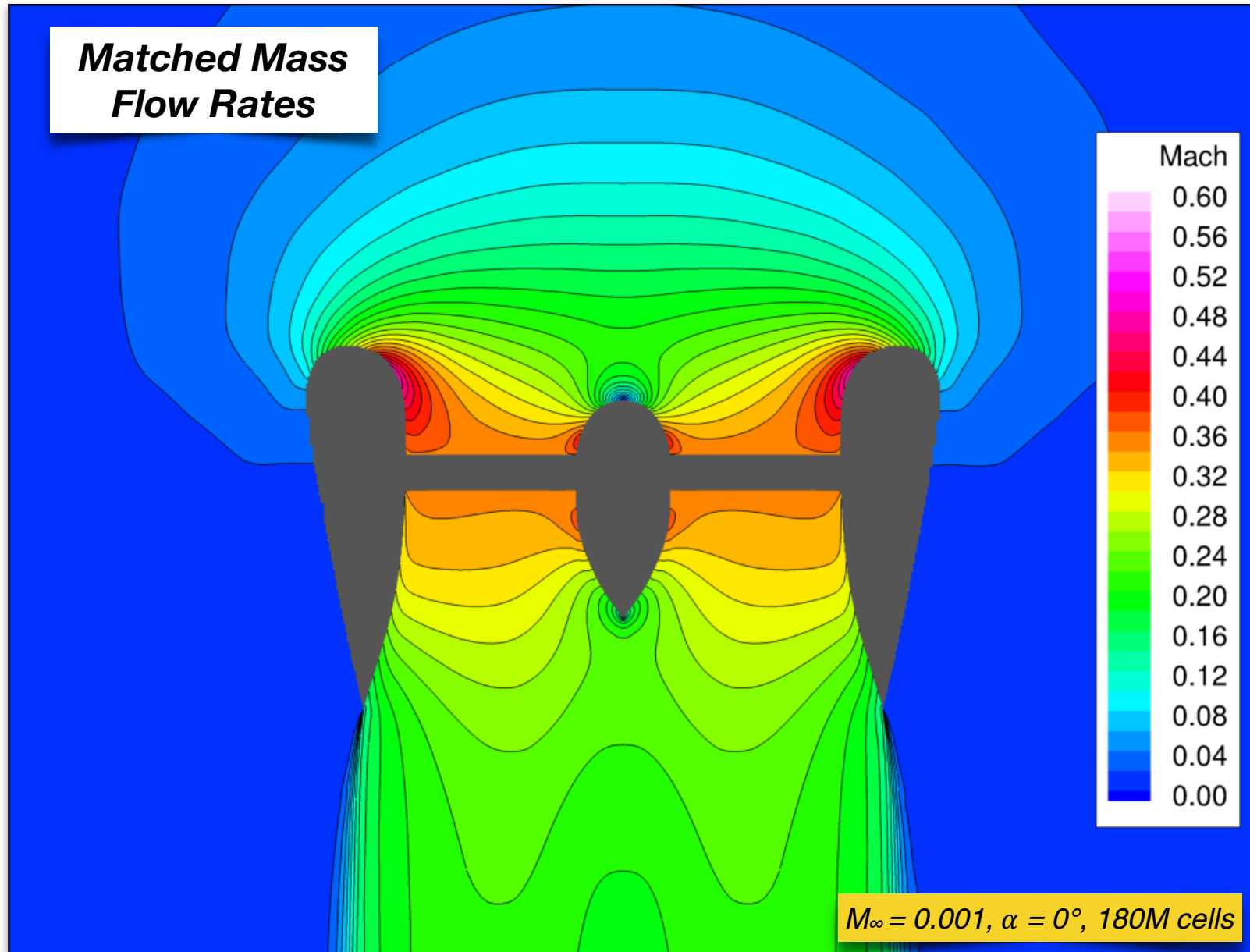


- Inflow mass flow rate ( $\dot{m}_{\text{inflow}}$ ) set through boundary condition
- Outflow mass flow rate ( $\dot{m}_{\text{outflow}}$ ) steered to match
- Mass flow rate quickly converges and continues to converge through each refined mesh



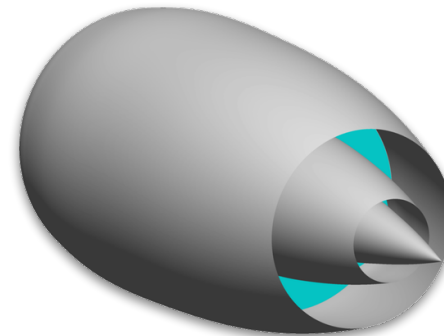
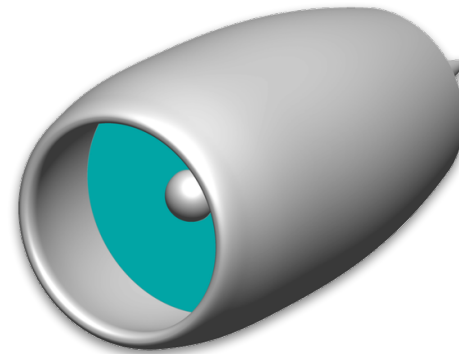
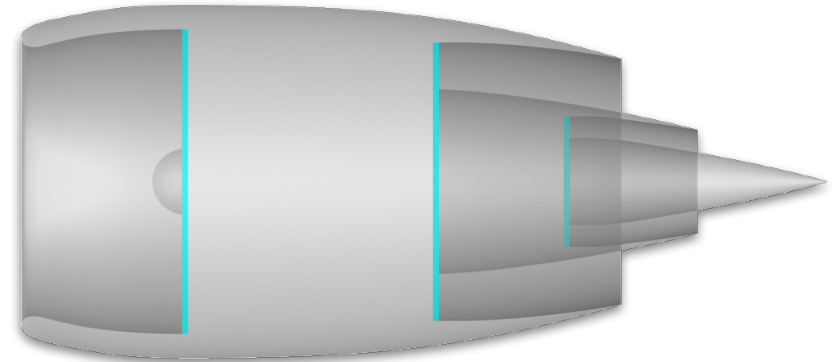


# Ducted Fan - Example Solution

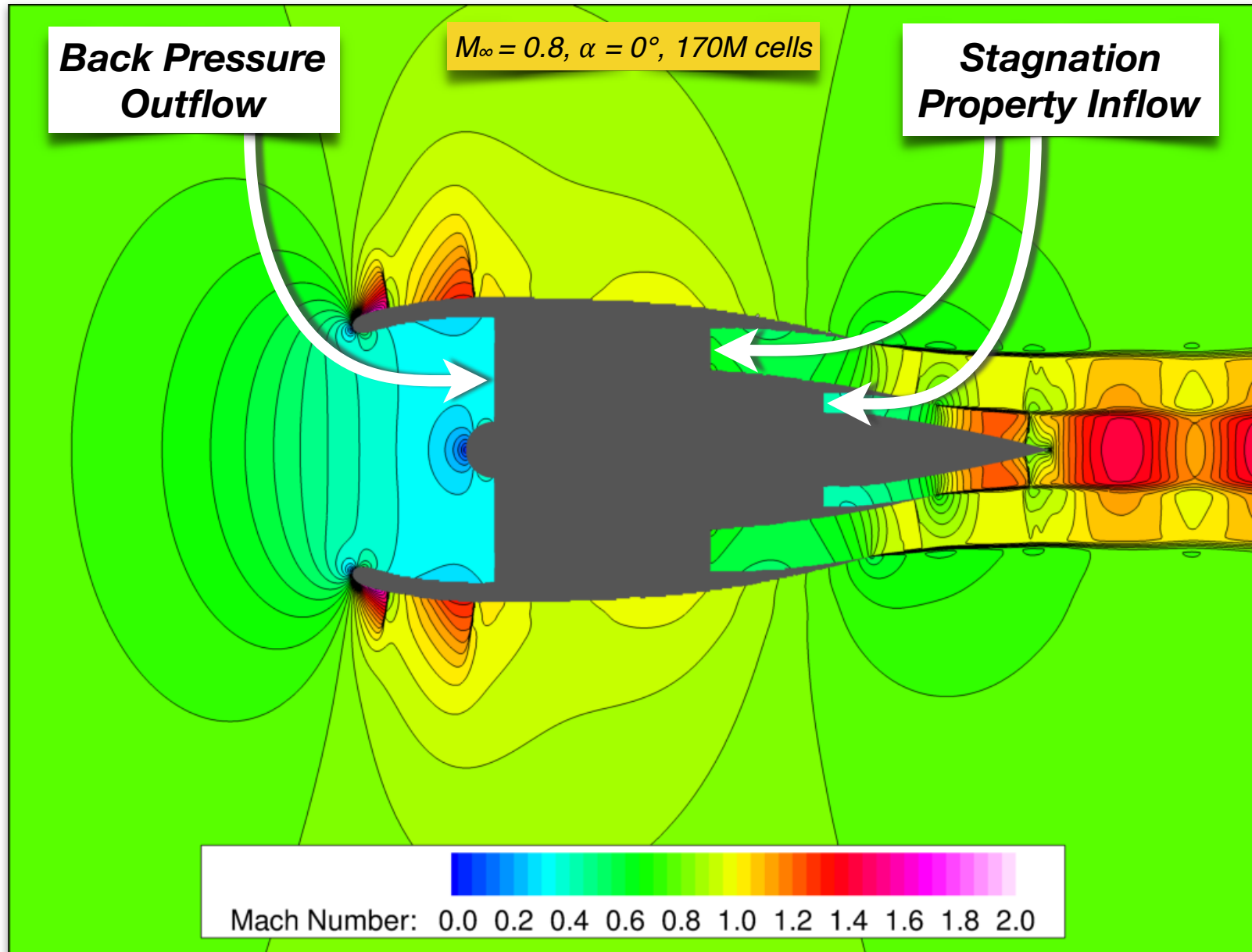


# Turbofan in Transonic Flow

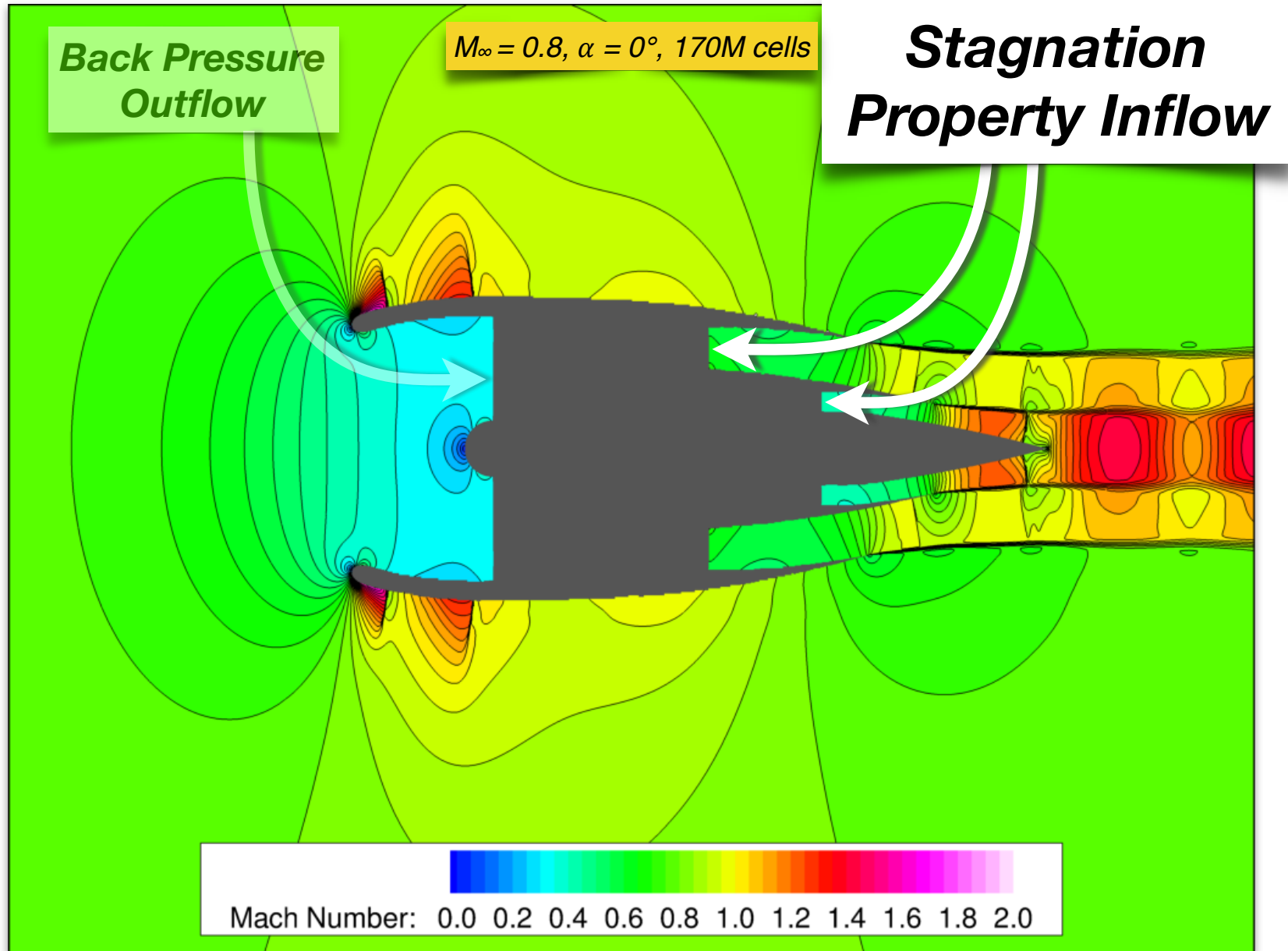
- Transonic diffuser with fan hub
- Two stream exhaust with cone nozzle for turbine flow
- Mach 0.8 freestream, no angle of attack (axisymmetric flow)
- Fan / Compressor face modeled as **annulus**, outflow boundary condition applied
- Fan and turbine exhaust planes modeled as **annuli**, inflow boundary conditions applied



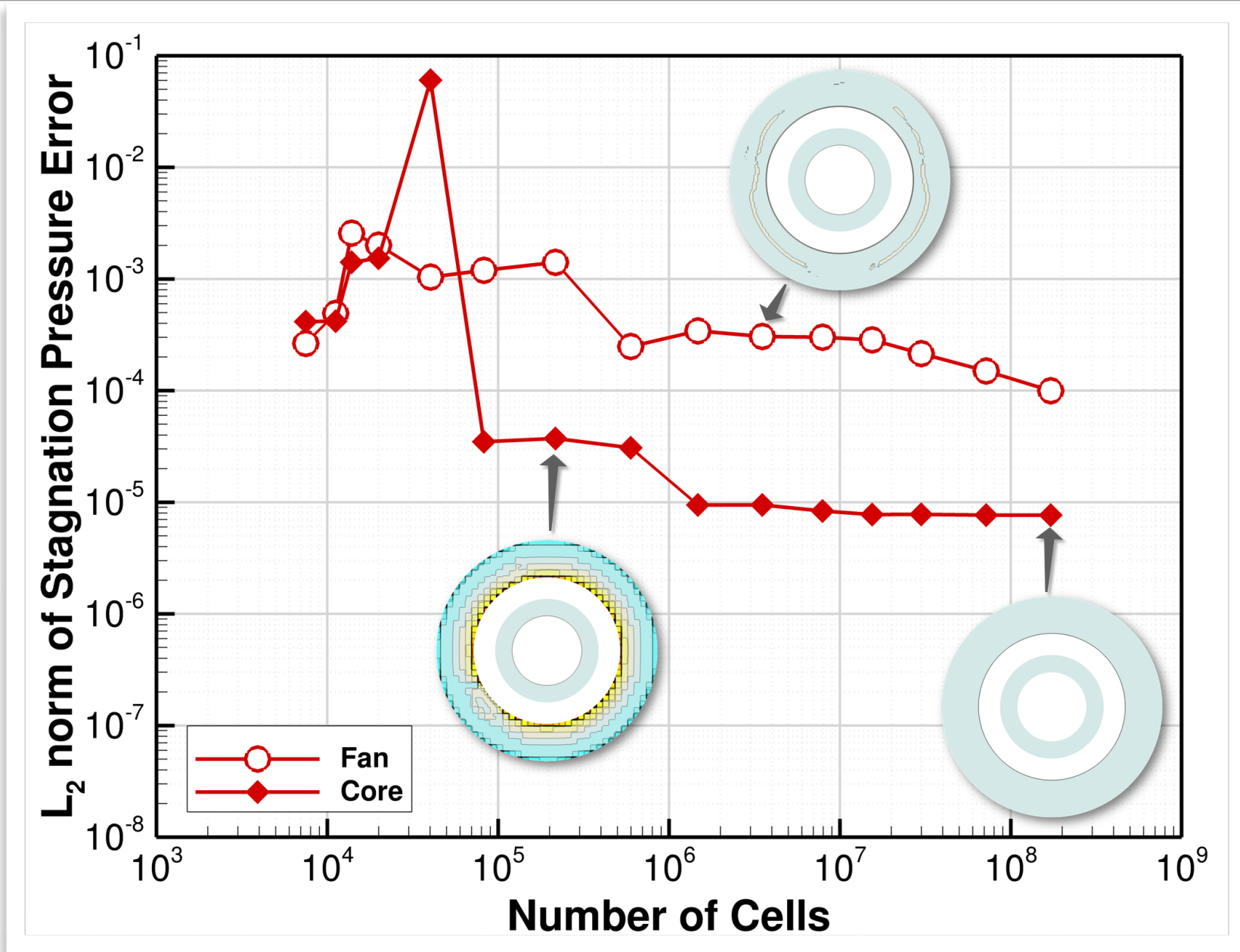
# Turbofan - Example Solution



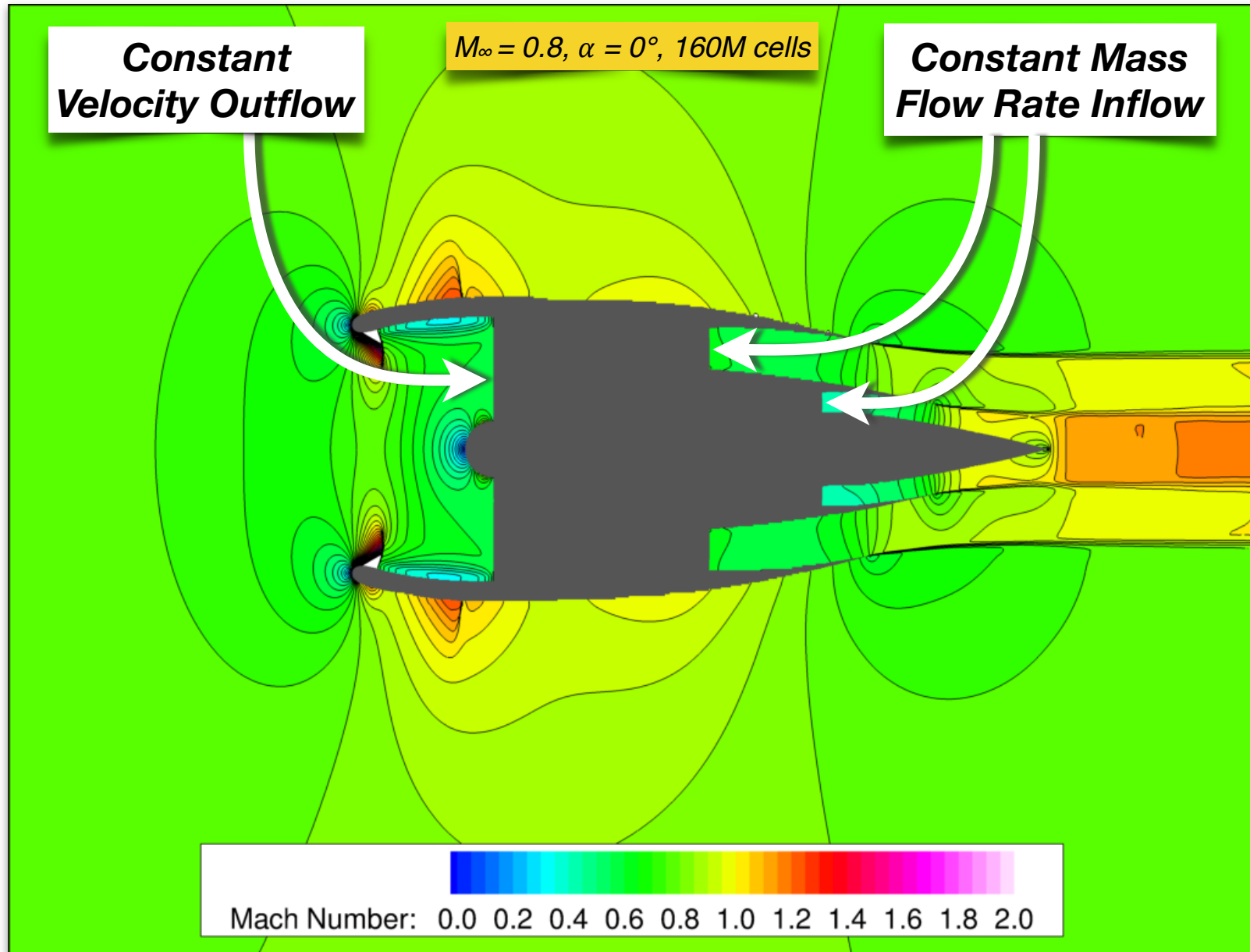
# Turbofan - Example Solution



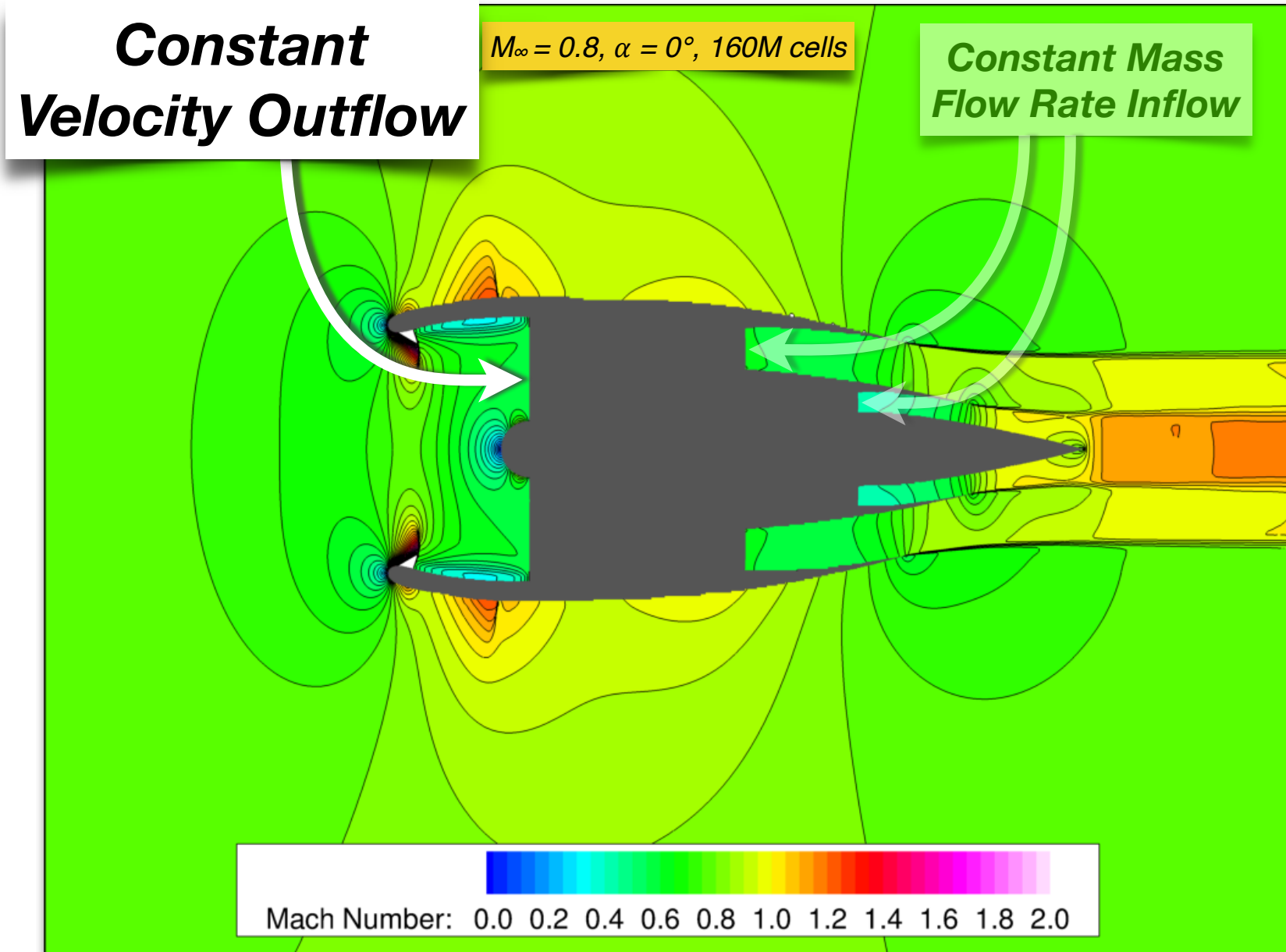
# Stagnation Property B.C. Mesh Convergence



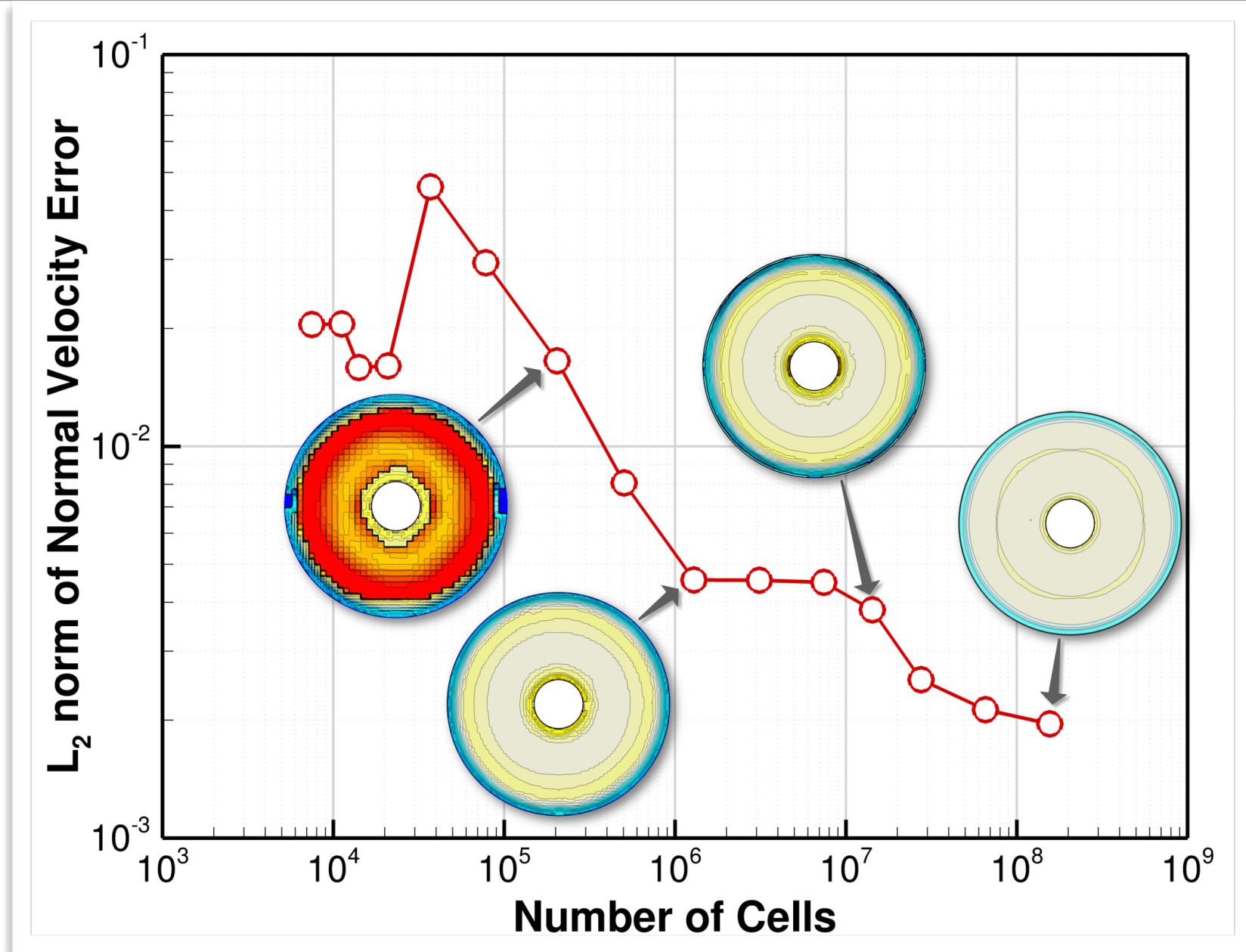
# Turbofan - Example Solution



# Turbofan - Example Solution



# Constant Velocity B.C. Mesh Convergence

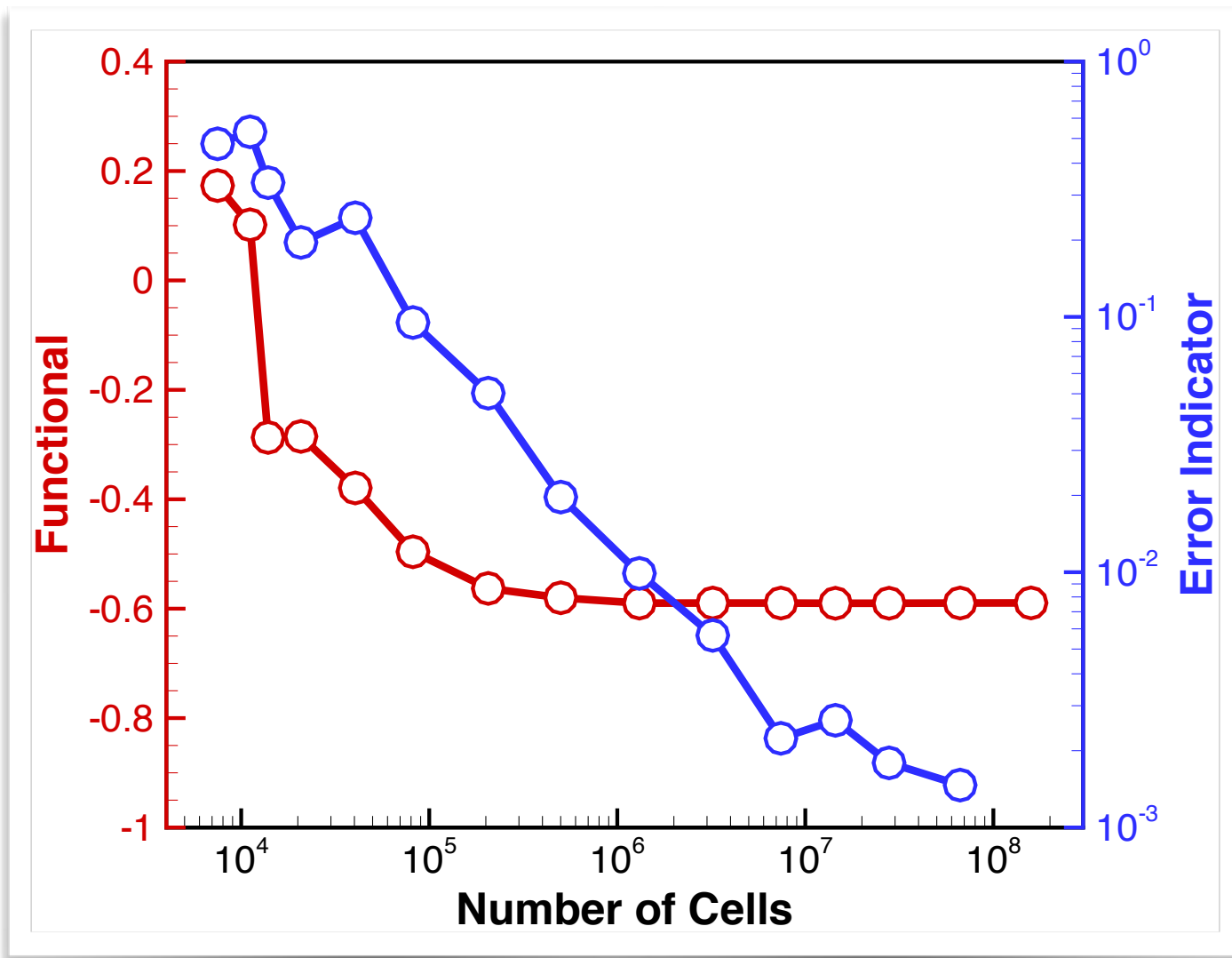






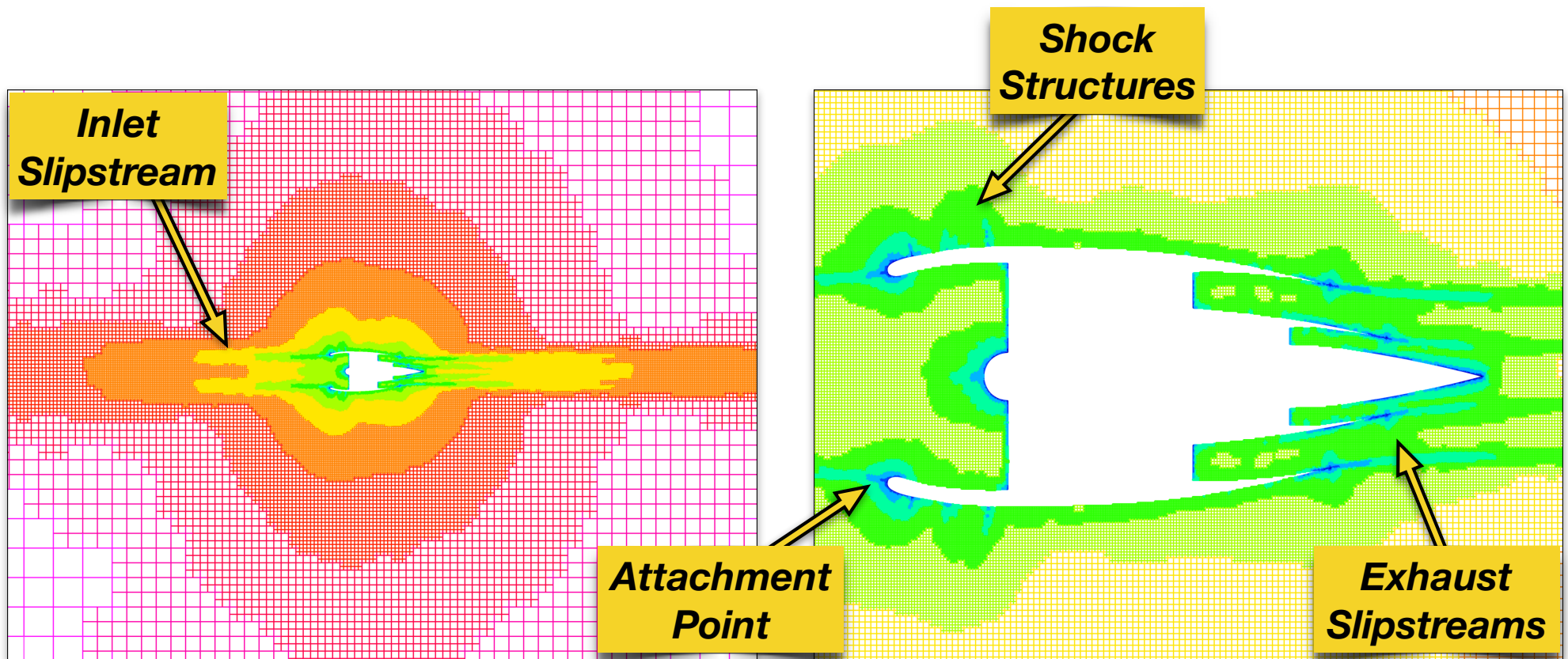
# Turbofan - Mesh Convergence

- Good convergence of functional (drag)
- Steady reduction in error estimate



# Turbofan - Adaptively Refined Mesh

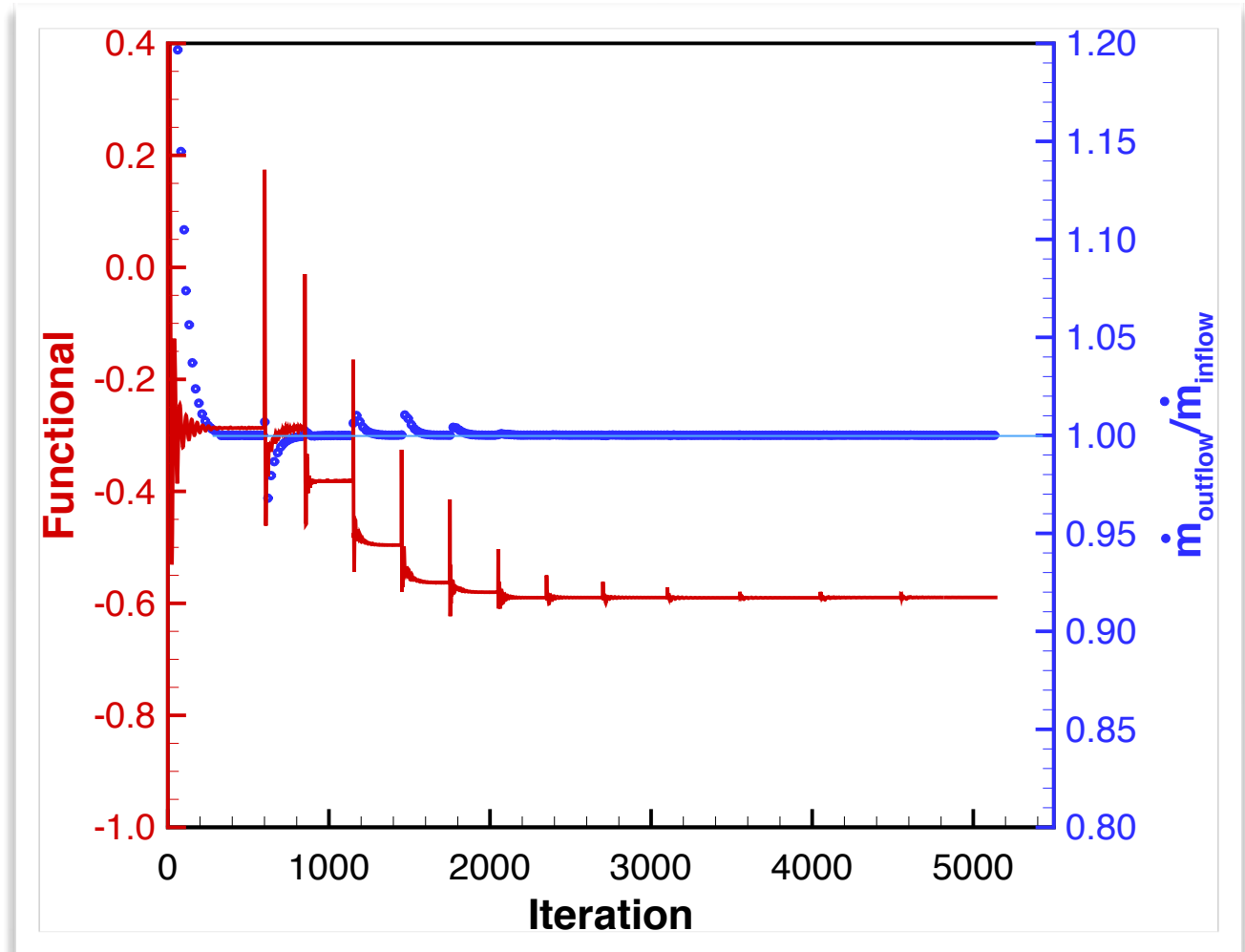
- Colors represent cells of same level of refinement
- Mesh was refined at surface, at shear layer of inlet and exhaust flow, near attachment point, and at shock structures



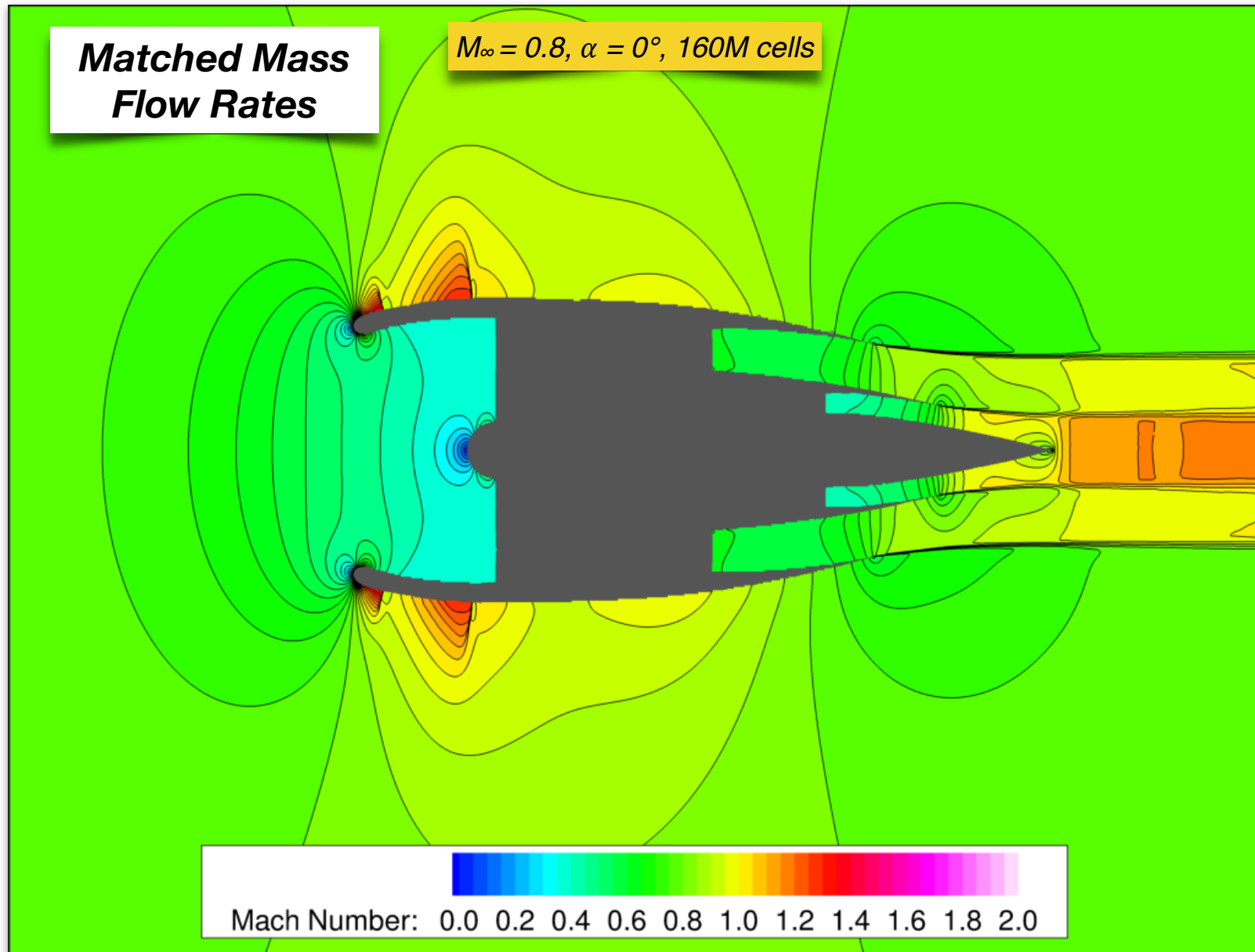


# Turbofan - Mass Flow Rate Steering

- Inflow mass flow rate ( $\dot{m}_{inflow}$ ) set through boundary condition
- Outflow mass flow rate ( $\dot{m}_{outflow}$ ) steered to match
- Mass flow rate quickly converges and continues to converge through each refined mesh

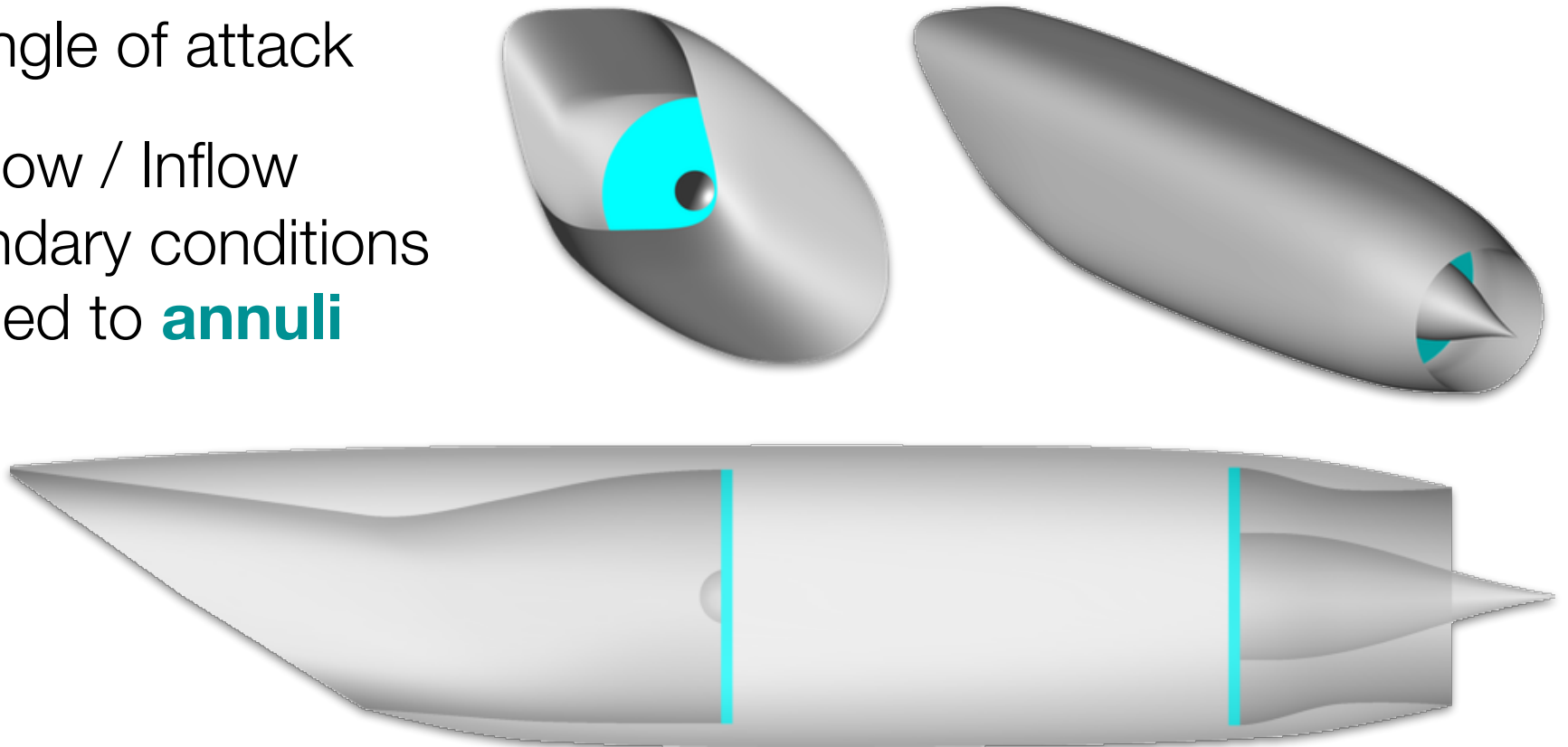


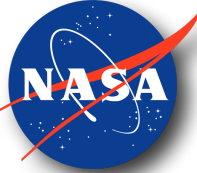
# Turbofan - Example Solution



# Turbojet in Supersonic Flow

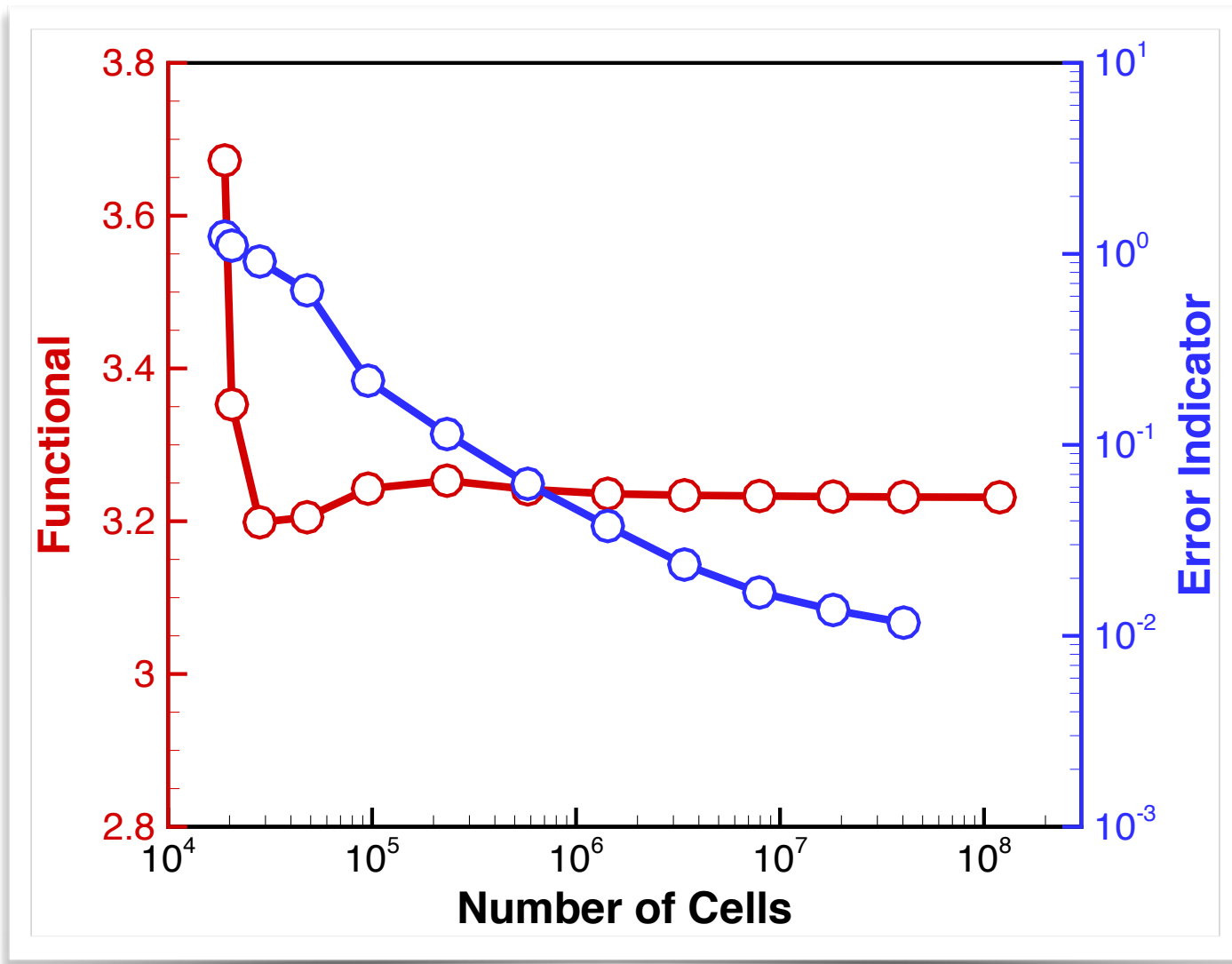
- 2-D ramp inlet design for normal terminal shock
- Converging-diverging duct with cone nozzle
- Mach 1.5 freestream,  $1^\circ$  angle of attack
- Outflow / Inflow boundary conditions applied to **annuli**





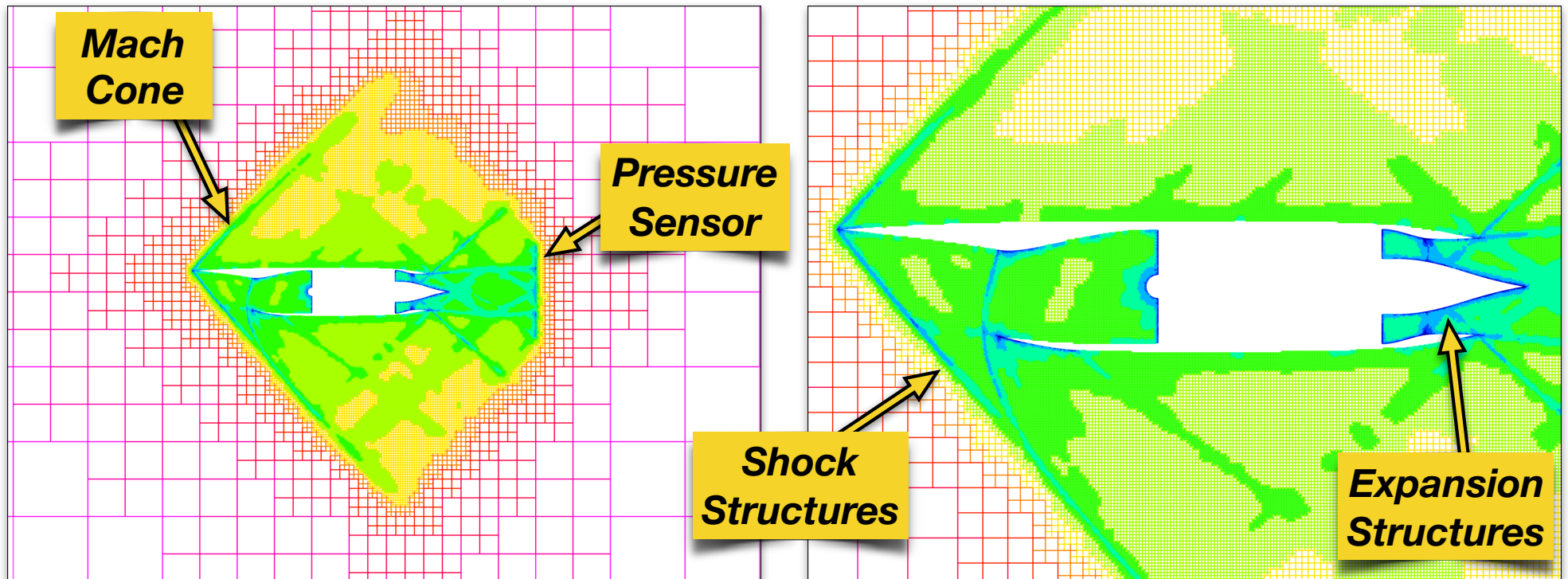
# Turbojet - Mesh Convergence

- Good convergence of functional (thrust + lift + plume sensor)
- Steady reduction in error estimate



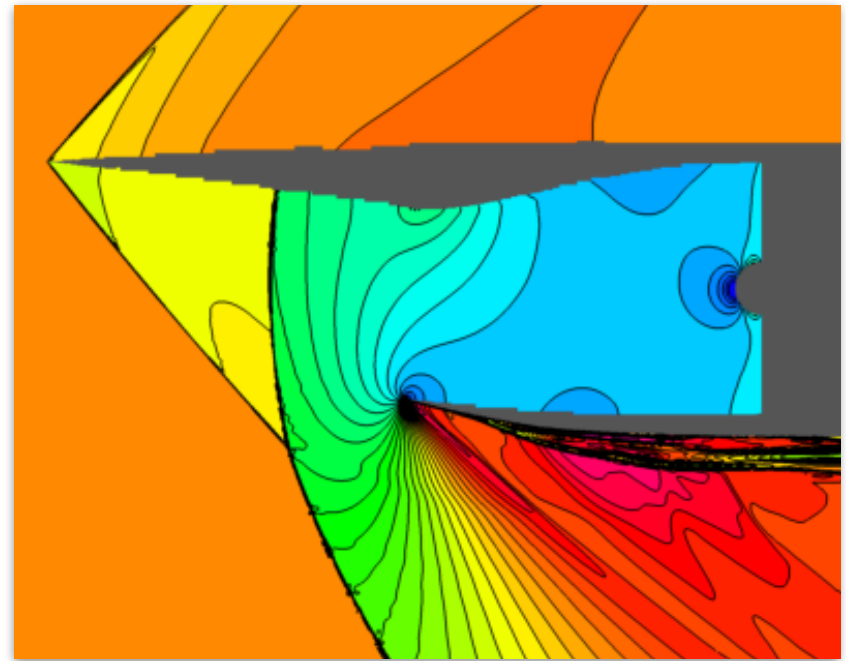
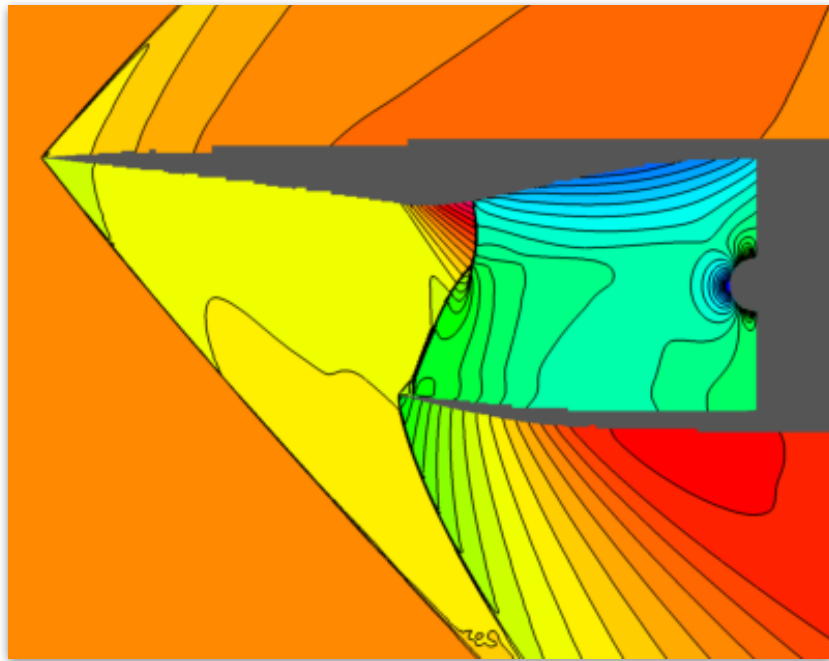
# Turbojet - Adaptively Refined Mesh

- Colors represent cells of same level of refinement
- Mesh was refined at surface, within Mach cone of influence, at shock and expansion structures, and at plume shear layer influencing pressure sensor



# Supersonic Inlet - Mass Flow Rate

- Usually need to specify mass flow rate through an inlet
- Often desirable to match nozzle mass flow rate if modeled
- Highly nonlinear flow features can make mass flow rate steering difficult in supersonic and even transonic inlets

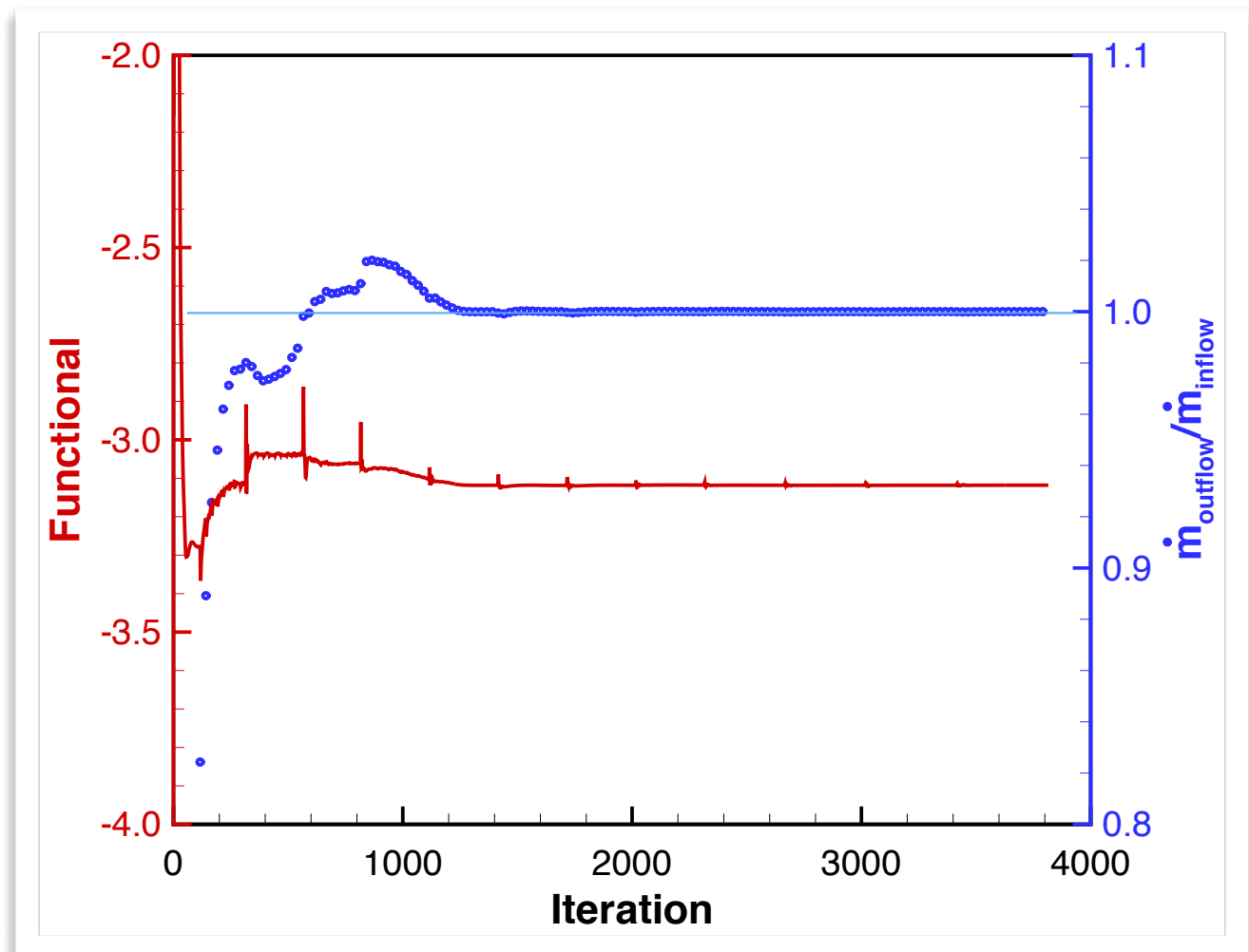






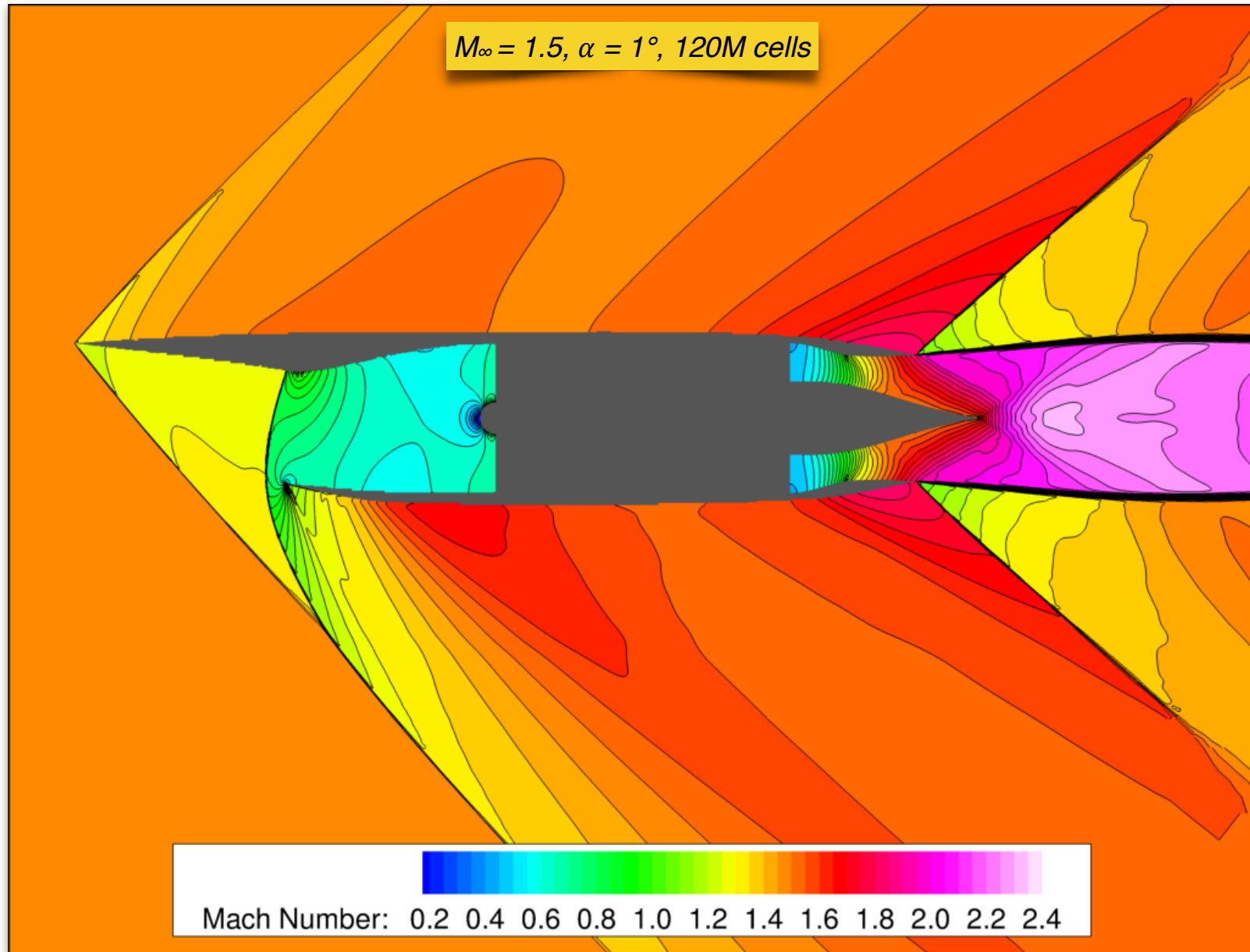
# Turbojet - Mass Flow Rate Steering

- Inflow mass flow rate ( $\dot{m}_{inflow}$ ) set through boundary condition
- Outflow mass flow rate ( $\dot{m}_{outflow}$ ) steered to match
- Mass flow rate quickly converges and continues to converge through each refined mesh



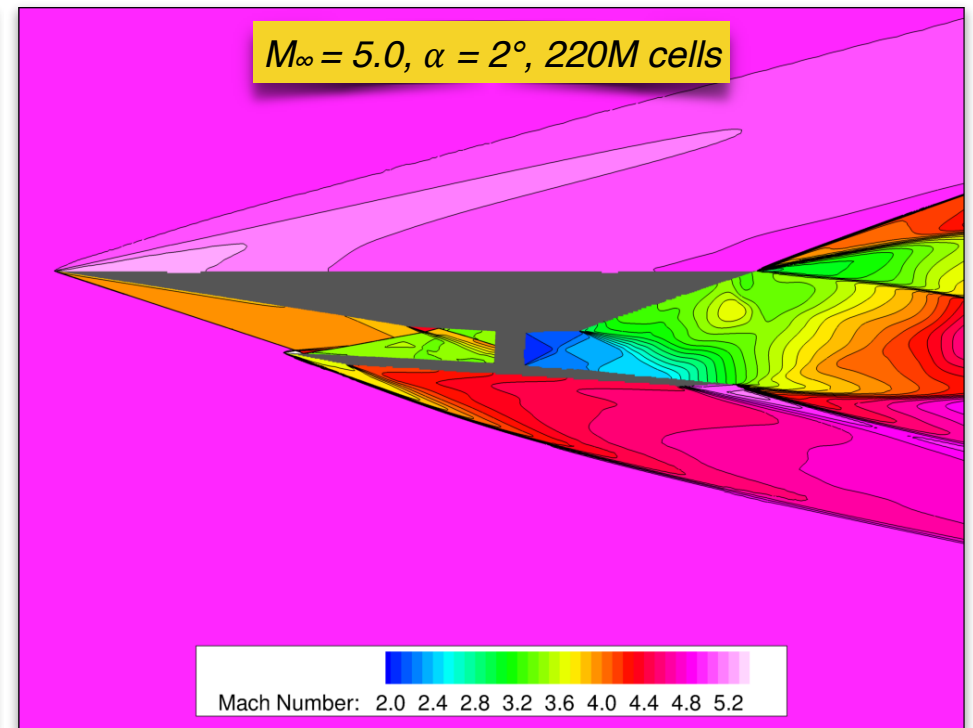
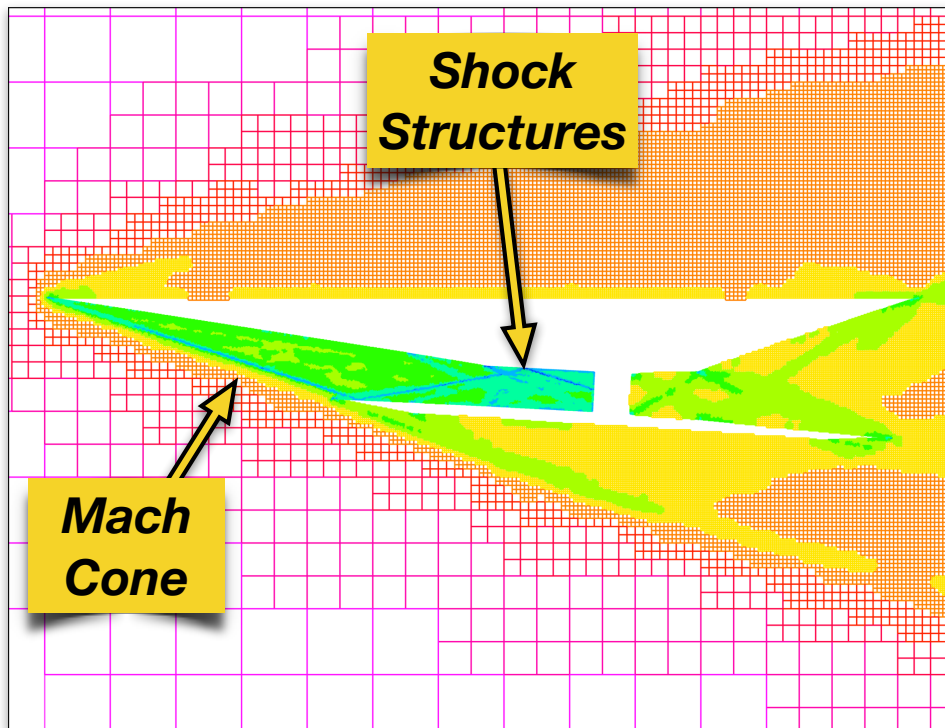


# Turbojet - Matched Mass Flow Rates



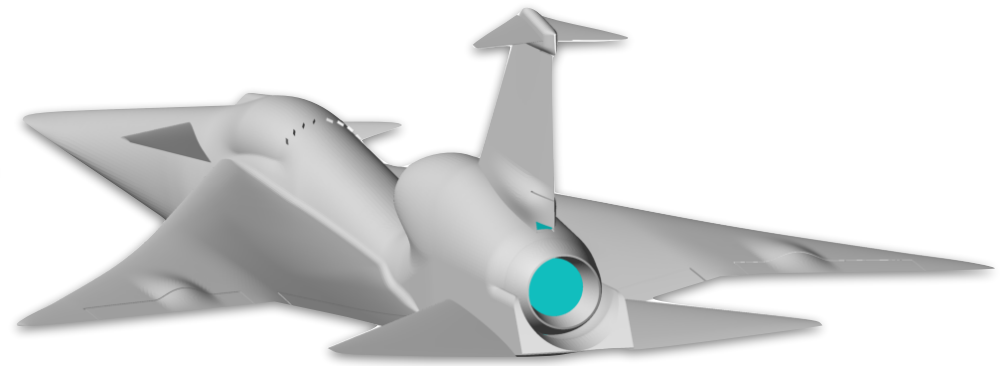
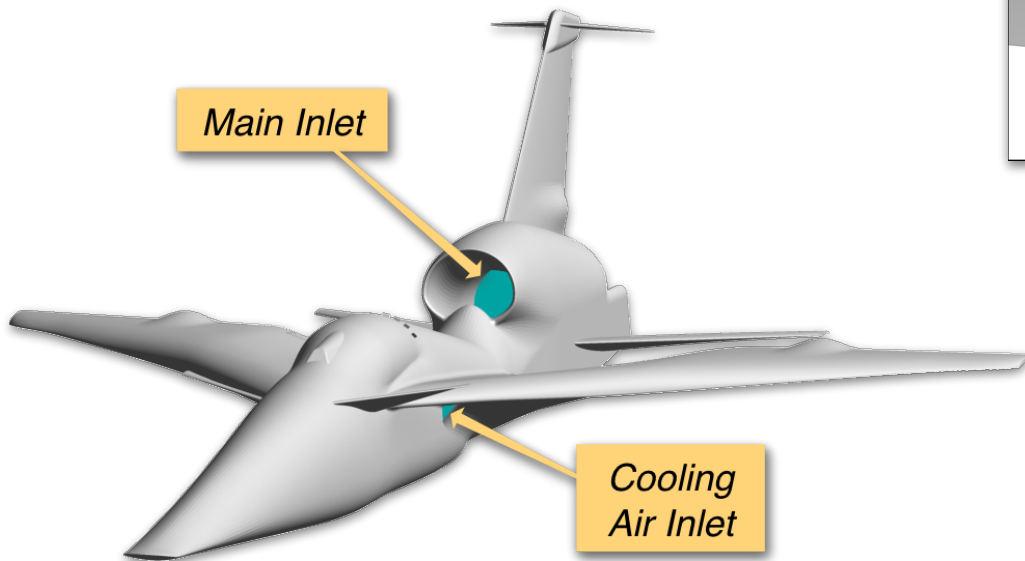
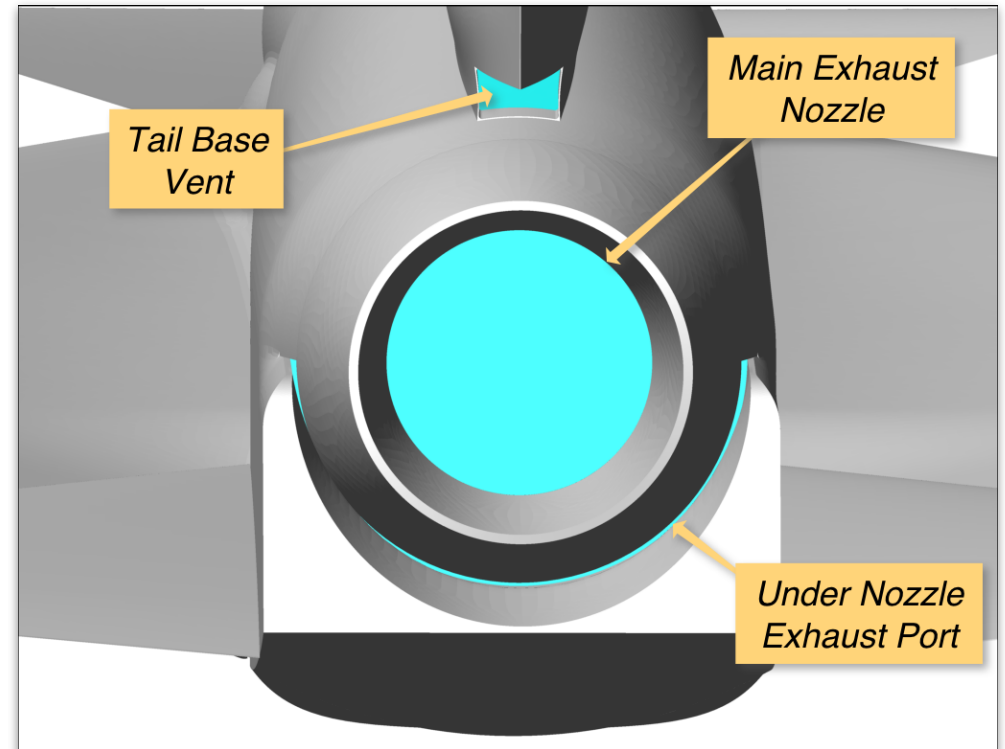
# Scramjet in Hypersonic Flow

- Multiple ramp inlet and outlet, flow through burner remains supersonic
- Mach 5.0 freestream,  $2^\circ$  angle of attack
- Subsonic inflow / outflow boundary conditions not applicable
- Original full state with Riemann solver (**SurfBC**) boundary condition applied
- Mesh was refined at surface, within Mach cone of influence, shock and expansion structures, and plume shear layer influencing pressure sensor



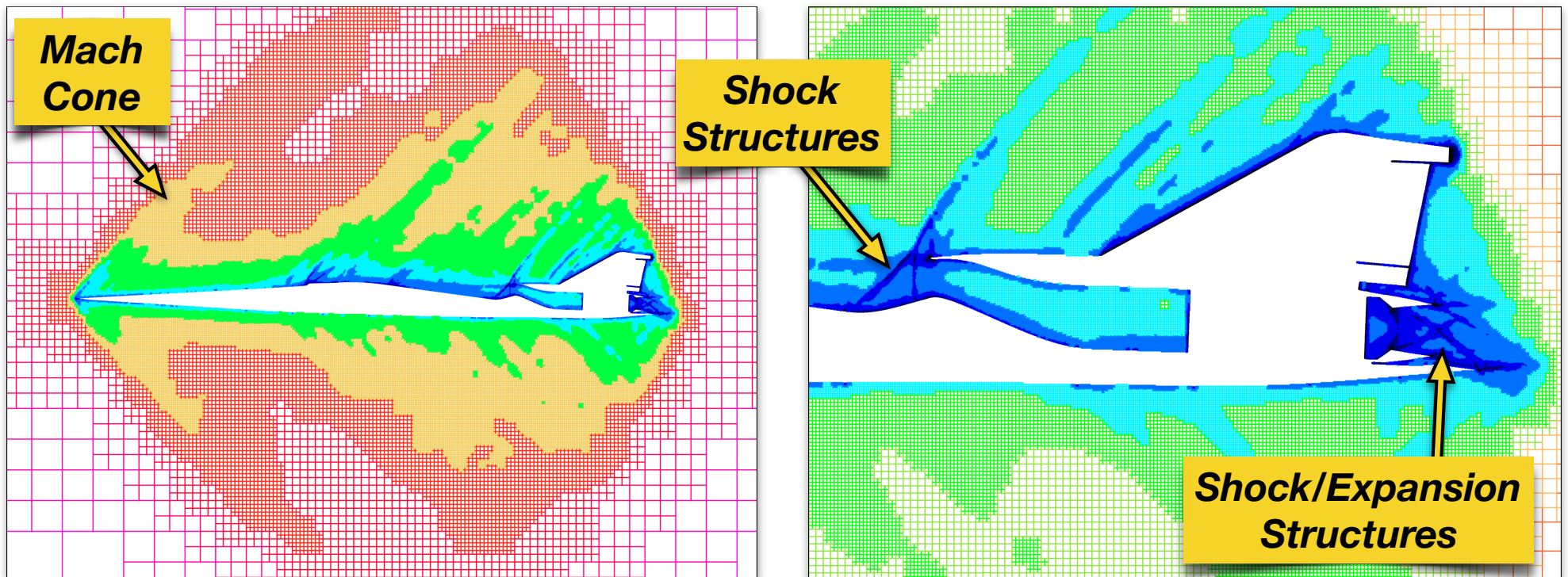
# Low Boom Supersonic Demonstrator

- Realistically complex geometry
- Mach 1.4 freestream,  $2.15^\circ$  angle of attack
- 3 inlets and 3 exhausts

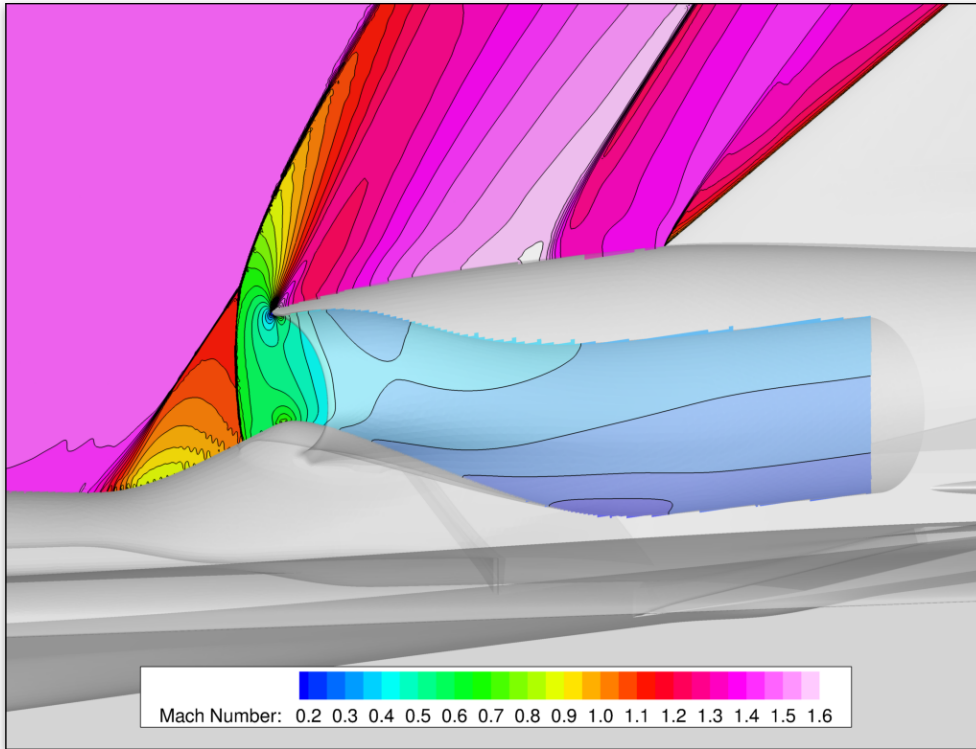


# Low Boom Aircraft - Adaptively Refined Mesh

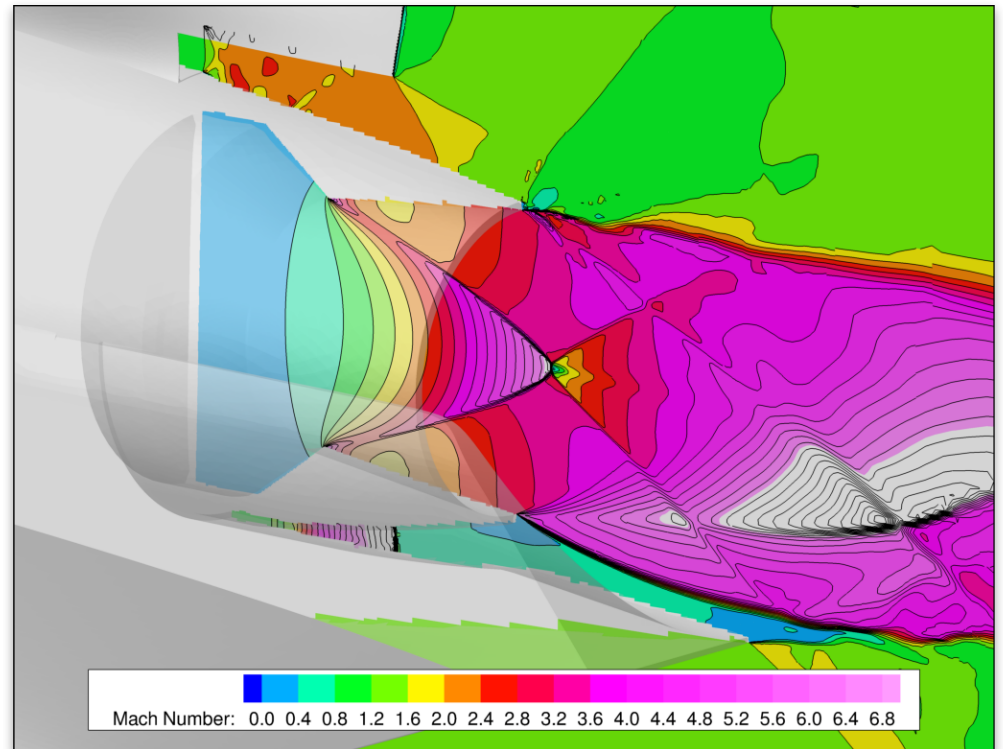
- Functional was aircraft drag
- Colors represent cells of same level of refinement
- Mesh was refined at surface, within Mach cone of influence, and at shock and expansion structures



# Low Boom Aircraft - Example Solution



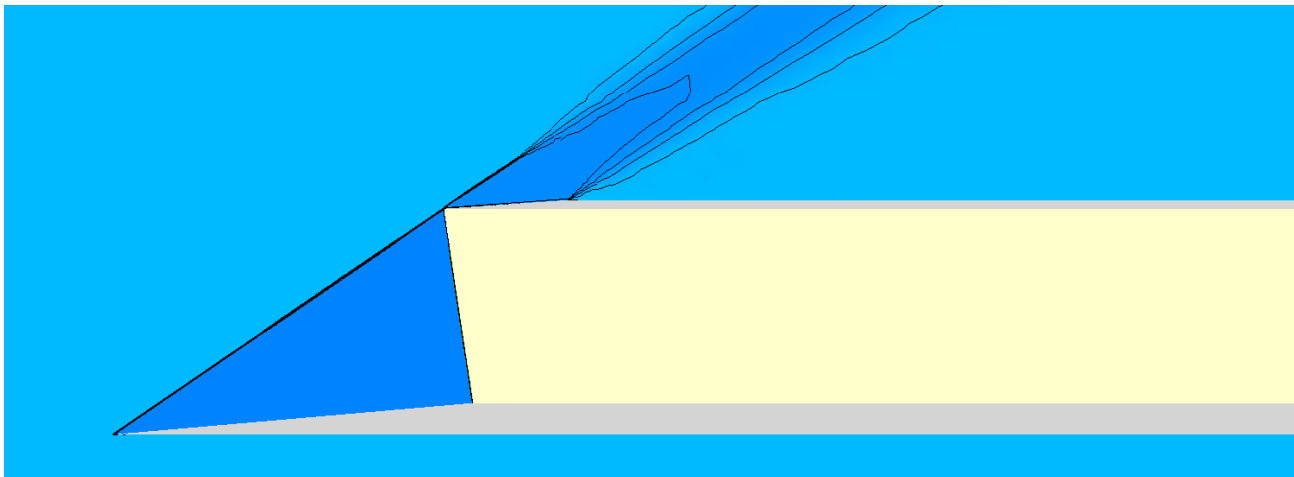
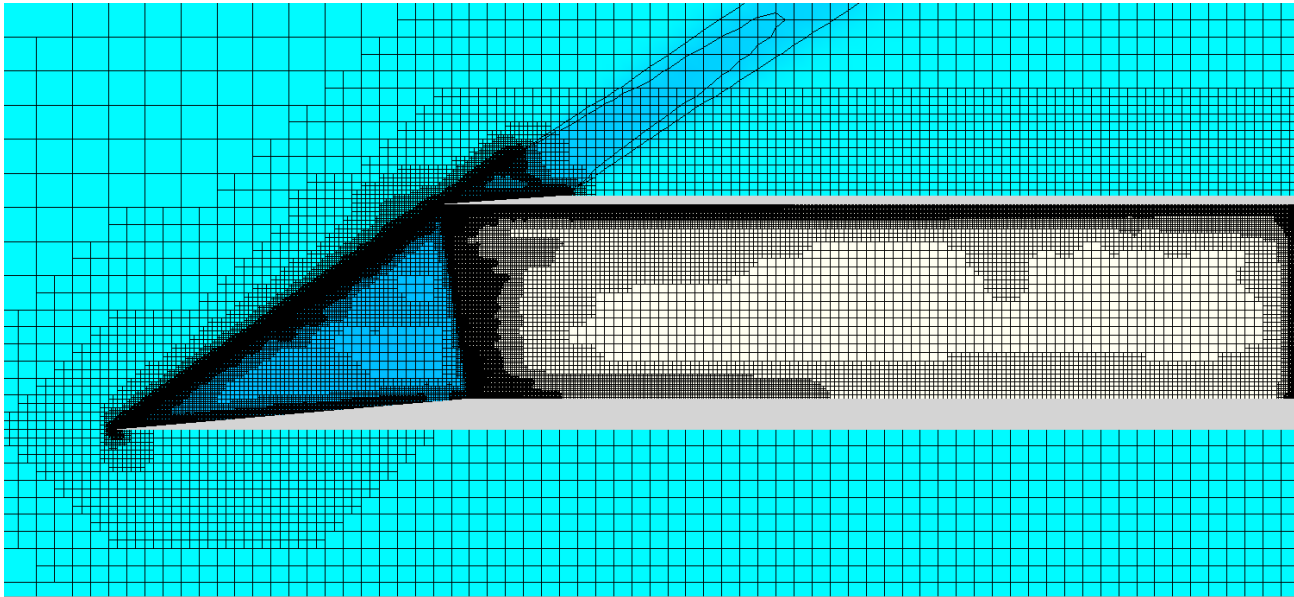
$M_\infty = 1.4$ ,  $\alpha = 2.15^\circ$ ,  
70M cells (half-body mesh)



- Underwing inlet geometry is not fully realized
- Safeguards were active in these inlets (solid wall to not allow reverse flow)

# Validation Case - 2-Shock Inlet

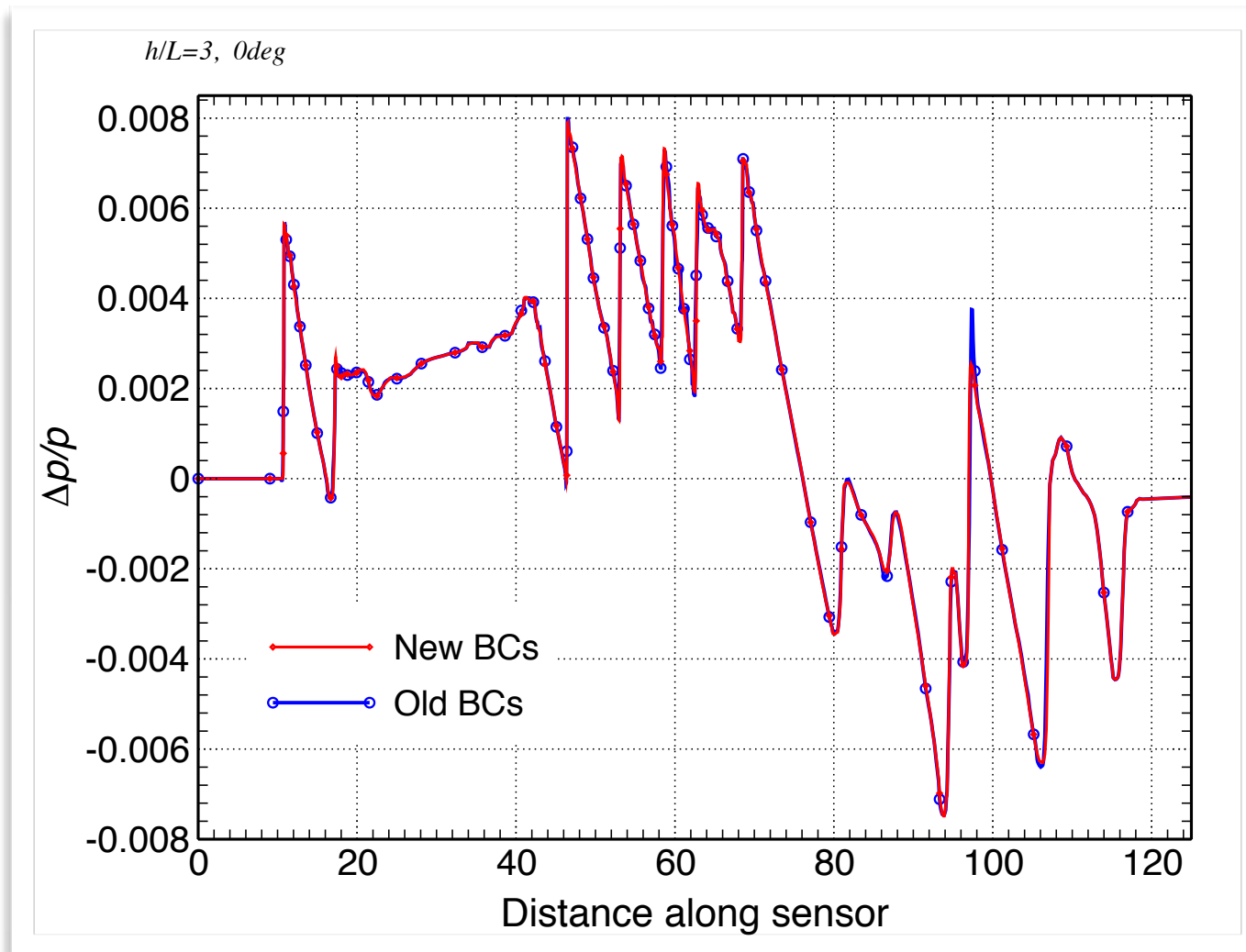
- Same validation case was run with SurfBC (Pandya, 2004)





# Verification Case - Low Boom Demonstrator Signature

- Low boom aircraft was analyzed original **SurfBC** and again new boundary conditions
- Near field signatures compared







# Summary and Ongoing Work

---

- Four new subsonic inflow/outflow boundary conditions implemented to improve modeling of propulsion systems
- Robust mass flow rate control implemented for both inflow and outflow
- Demonstrated on notional propulsion systems in flight regimes ranging from subsonic to hypersonic
  - adjoint-driven mesh refinement demonstrated with all propulsion boundary conditions
  - new boundary conditions verified mesh convergence studies on notional examples
- Demonstrated on realistically complex low boom aircraft
- Some validation completed
- *Ongoing work*
  - *Implement additional functionals appropriate for propulsion systems*
  - *Extend design framework to include new propulsion boundary conditions and functionals*



# Acknowledgements

---

- NASA ARMD Commercial Supersonic Technology (CST) Project provided funding
- NASA Advanced Supercomputing (NAS) Center provided computing resources
- Other colleagues in Computational Aerosciences Branch