



Advantages of a Modular Mars Surface Habitat Approach

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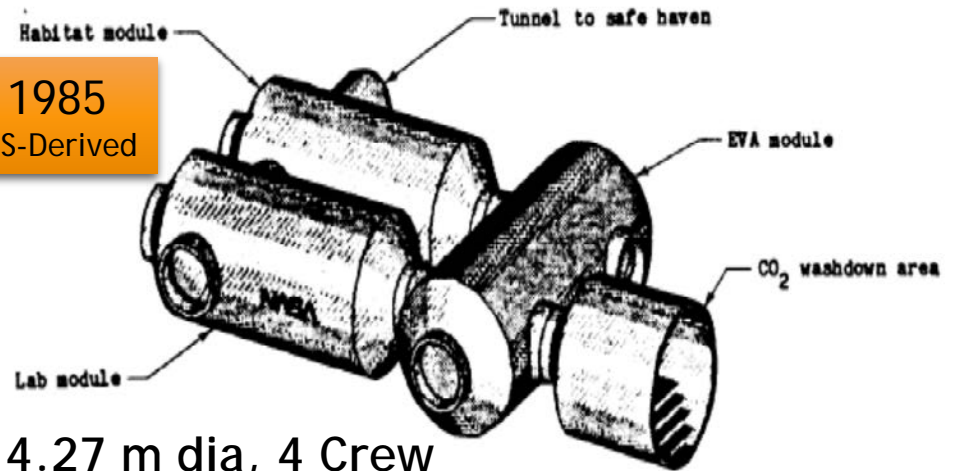
Mars Surface Habitat Evolution

1969
Von Braun



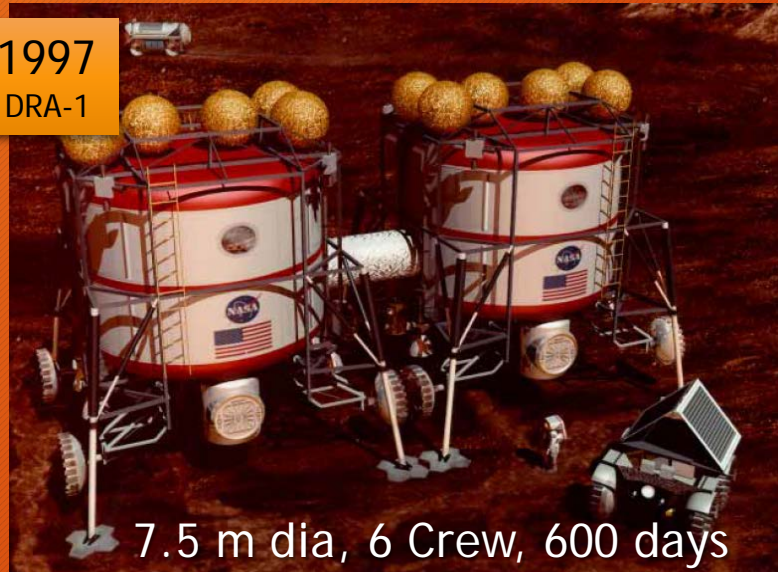
9.1 m dia, 3 Crew, 30-60 days

1985
ISS-Derived



4.27 m dia, 4 Crew

1997
DRA-1



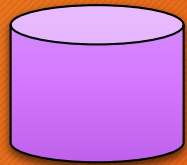
7.5 m dia, 6 Crew, 600 days

2016
EMC



7.2 m dia, 4 Crew, 550 days

Monolithic vs. Modular Habitats



Monolithic
Single, Large
Habitat

vs.

Modular
Multiple, Small
Habitats



□ Monolithic

- Works well for a single visit to one site (Apollo-style missions)
- Crew has everything they need without leaving the lander
- Size limited by Earth launch vehicle payload shroud + lander payload constraints

□ Modular

- Works well for repeat visits to the same site
- Smaller → more vehicle options for Earth launch or Mars lander
- Have to configure multiple elements on Mars

Two Important Considerations



- **Post-landing crew recovery period**
 - After long microgravity transit, crews *may* need physical recovery period before “Mars-walk” medical clearance
 - Strength + neurovestibular recovery

Whatever crew lands in may have to carry everything they need for a few days



- **Single vs. multiple visits to the same landing site**
 - If first crew lands in monolithic habitat...what do subsequent crews to the same site land in?
 - Leave habitat on lander or off-load it?
 - Multi-expedition habitat must be more robust than one-time use habitat
 - Can we use empty logistics containers as habitable modules?

Single vs. multiple visits to a given site have different optimal architectures

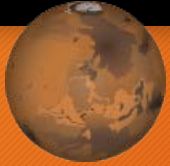
Surface Systems Approach

2018 Mars Study Capability (MSC) Team

- Established surface system functional requirements within the integrated mission architecture
- Identified needed cargo elements
 - Emphasized commonality to eliminate unique elements
- Developed operational concept details
 - Which pieces need to arrive on which lander?
 - How do we unload and assemble everything?
- Established manifesting “rules” to better compare concepts
- Tried to minimize unique elements
 - Similar shell for Logistics, Descent, and Airlock Modules
 - Common mobility chassis, with pressurized, unpressurized or robotic rover outfitting

2018 Basis of Comparison Architecture

Mars Study Capability (MSC) Team



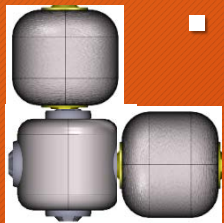
- Retained Evolvable Mars Campaign's (EMC) "Field Station"
 - Multiple missions to a single landing site



- 22 t payload capacity Mars landers
 - 3-3-2 lander cadence



- Low-energy, hybrid in-space transit architecture
 - Longer in-space transit decreases surface stay to **~300 days** per expedition
 - 5 sol Mars Ascent Vehicle rendezvous point



- Modular surface habitation
 - Four-hatch Airlock Module serves as the cornerstone
 - Crews land in a Logistics Module-sized Descent Module, which then becomes a habitable surface module

Requires fewer landers relative to the EMC concept, with lower landed mass over 3 expeditions than most previous schemes

Notional Mars Surface Mission Elements





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Major Elements (Dedicated Lander)



Mars Ascent Vehicle (MAV)

Supporting Elements (Deck Mounted)

Rover Cabin	Descent Module	Logistics Module	Airlock Module
			
MODULAR HABITATION			



Off-loading Hoist

Stowed Elements (In Another Element)



Crew



Launch/Entry Suits



Mobility Chassis



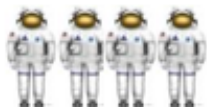
Unpressurized Rover



Pressurized Rover



Crew Support Rover



EVA Suit + Primary Life Support



Maintenance, Logistics & Consumables



Kilopower Unit



Power Management & Distribution



Atmospheric ISRU



Tunnel

General Concept of Operations

Conceptual Mission Series to a Single Exploration Site

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FIRST Pre-deploy cargo



Power System
+ Hab Module
+ Cargo

THEN Ascent Vehicle and ISRU



Ascent Vehicle
+ Propellant
Manufacturing

WHEN tanks are full, 1st crew lands



Hab Modules +
Crew + Cargo

SUBSEQUENT

crews add
modules



Rover
Cabin



Descent
Module

MODULAR
HABITATION



Habitable
Logistics
Module



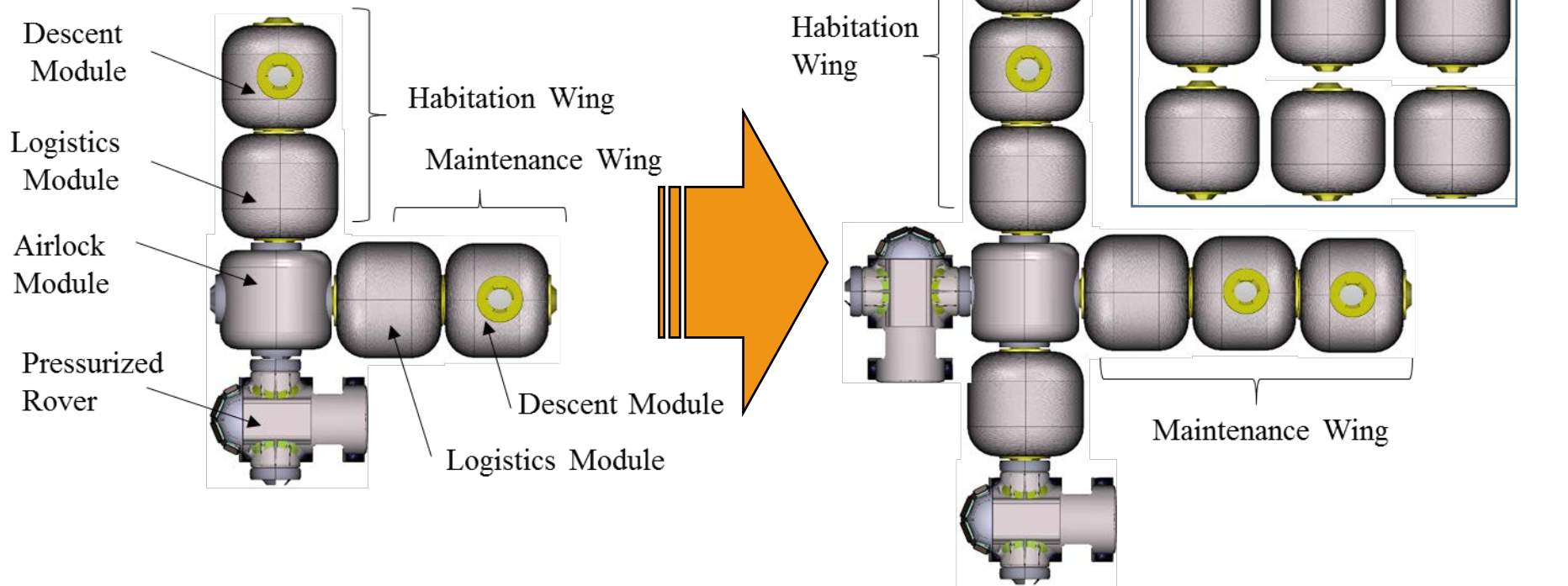
Airlock
Module

Field Station Build-up

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Expedition 1

Expedition 3



Landed Payload Mass Cumulative Over 3 Crew Expeditions

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	Mission Concept				
	1969 Von Braun	1997 SP 6107	2009 DRA 5	2016 EMC	2018 MSC
Number of Landers	3	8	6	10	8
Expedition 1	1	4	2	4	3
Expedition 2	1	2	2	3	3
Expedition 3	1	2	2	3	2
Payload Capacity per Lander (t)	12.68	65	40	20	22
3-Expedition Cumulative Landed Mass (t) = (#landers) x (payload/lander)	38.04	520	240	200	176

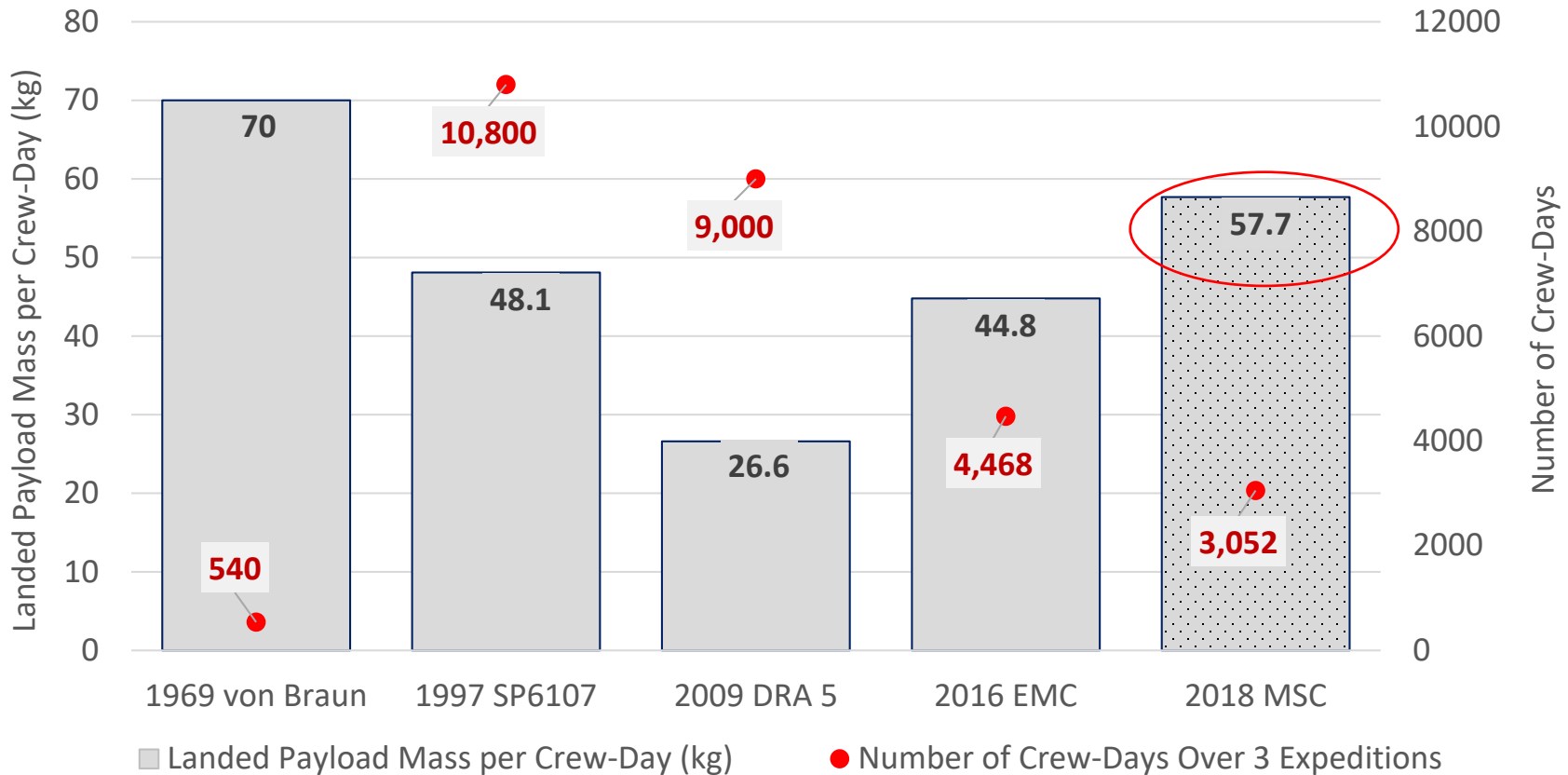


*If landed mass is the metric of choice,
MSC concept looks pretty good*

But landed mass alone is a misleading metric...

Landed Payload Mass **Per Crew Day** *Cumulative Over 3 Expeditions*

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If landed mass per crew day is metric of choice, MSC compares poorly

Why so much variation?

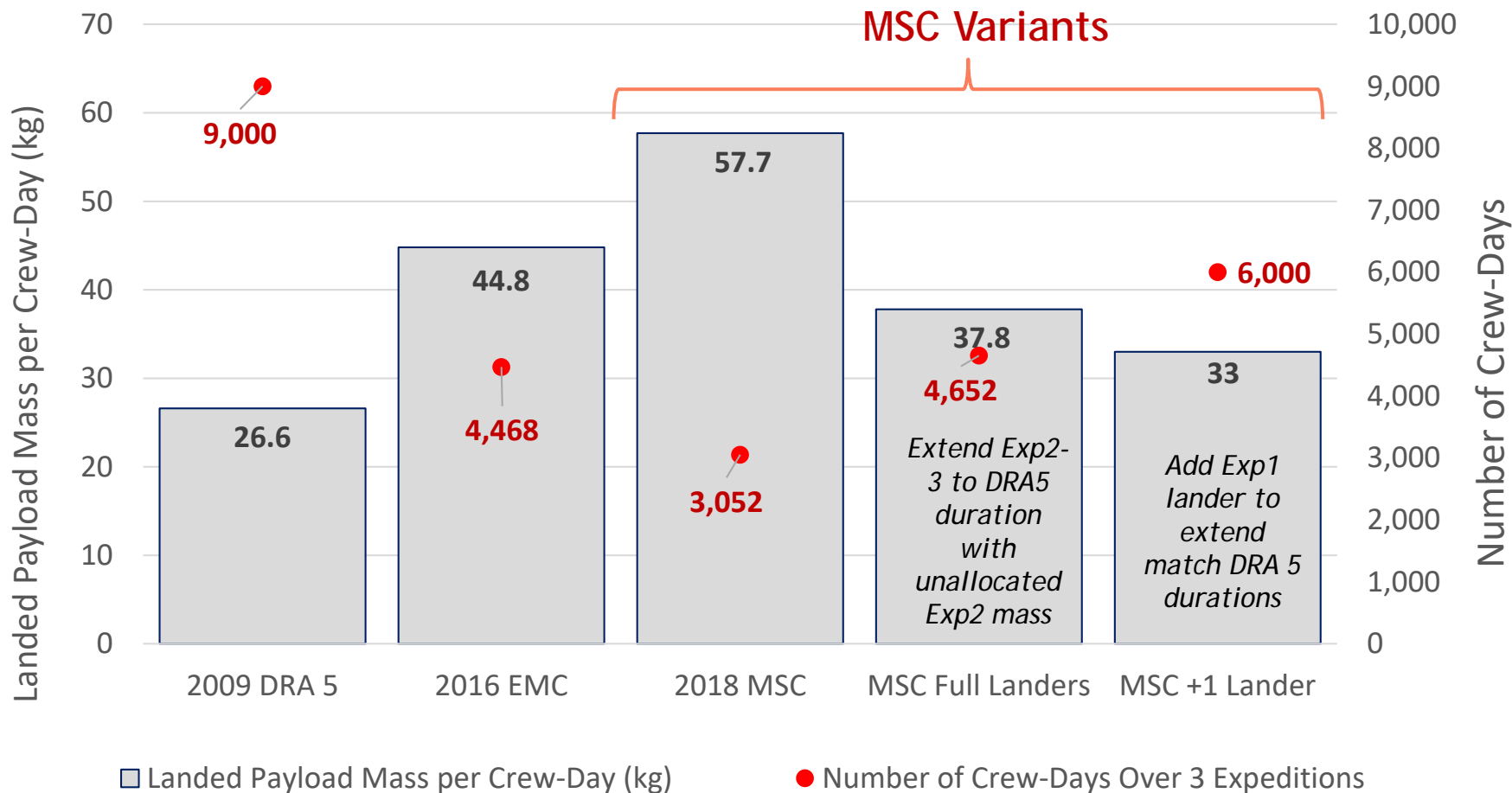
1. **Multi-module structure is less mass-efficient**
 - At current design fidelities, difficult to gauge by how much
2. **Mass estimates increase as concepts/models are refined**
 - Pressurized rover grew from 4.8 to >6 t from 2009 to 2018
 - Monolithic Habitat grew from 16.5 to 19.3 t
3. **Maintenance models are based on number of pressurized modules, not pressurized volume**
 - Baked-in disadvantage for modular architecture
4. **Surface stay duration is key**
 - Infrastructure—not consumables mass—is the driver

Best value: maximize stay duration to get the most out of landed mass

Longer Stay

Payload Landed Mass Per Crew Day (3 Expeditions)

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Advantages of a Modular Habitat Approach

1. **Smaller habitats fit on a smaller landers**
 - Eliminates a key lander size-driver → less cost/risk
 - More Earth launch system options
 - More commercial/international partner opportunities
2. **Reduced Risk**
 - A damaged module could be isolated and replaced
 - Smaller hab designed to be relocated is more tolerant of off-course landing
 - Off-course landing → loss of mission for monolithic hab
3. **Solves the “subsequent crew problem”**
 - Monolithic: either keep sending big habs, or design another element for subsequent crews to land in → costly
 - Modular: each crew lands in the same type of element, which is added to the field station as habitable volume

Advantages of a Modular Habitat Approach

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4. Improved Habitability

- Can separate clean/quiet area from dirty/noisy work space
- Pressurized volume increases over multiple expeditions
 - Or can replace worn-out modules as new modules arrive
- Retired modules can be dedicated for trash management
- More accessible than climbing up/down lander to a MonoHab

5. More Flexibility

- Can improve/add new tech to later Expedition modules
- Smaller modules are easier to build, transport and test on Earth
 - Easier for small/new providers to participate

6. Lower cumulative mass compared to previous studies

- >30% savings vs. DRA 5.0 architecture
- Could be optimized with longer surface stays

Disadvantages of a Modular Habitat Approach

1. **Operationally less efficient**
 - Have to offload, transport, assemble modules on Mars
 - Have to connect distributed services - similar to ISS
2. **Larger footprint on Mars**
 - May require surface preparation
3. **Higher Handling Damage Risk (on Mars)**
 - Offloading/transporting/assembling modules
4. **Potentially less commonality with transit habitat**
5. **Adds complexity to Logistics Module**
 - Off-set by improved commonality
6. **More complicated lander packaging/balancing**



Key Take-Aways

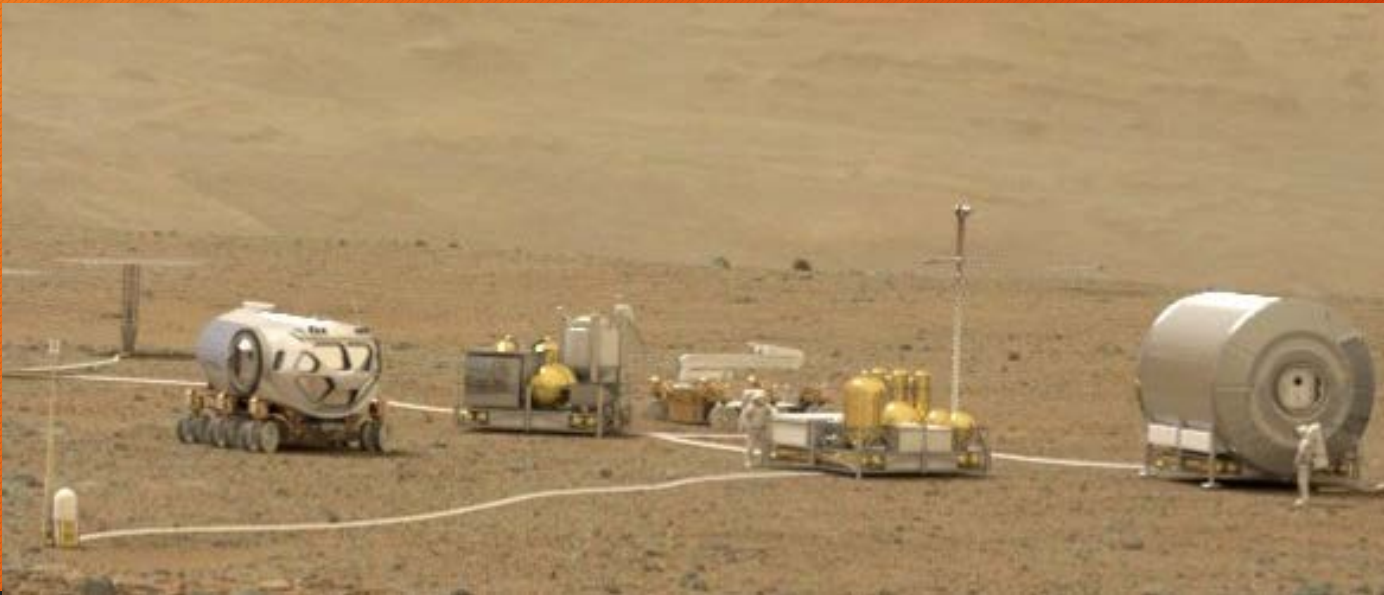
Modular vs. Monolithic Habitats

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- ❑ Modular habitats work well for repeat visits to one site
 - Monolithic habitats may work better for one-time visits
- ❑ Modular habitats offer:
 - ✓ Risk reduction
 - ✓ Increased launch/landing system options
 - ✓ Operational flexibility
 - ✓ Lower cumulative landed mass
- ❑ Landed mass doesn't tell the whole story
 - Normalized mass per crew-day doesn't either
 - Comparing to earlier references requires updating the earlier works for current usage models and element concepts
- ❑ If landed mass is the metric of choice, best "value" is to maximize Mars surface stay
 - Regardless of habitat type

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Questions?

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