



Embracing Innovation in Aviation While Respecting Its Safety Tradition

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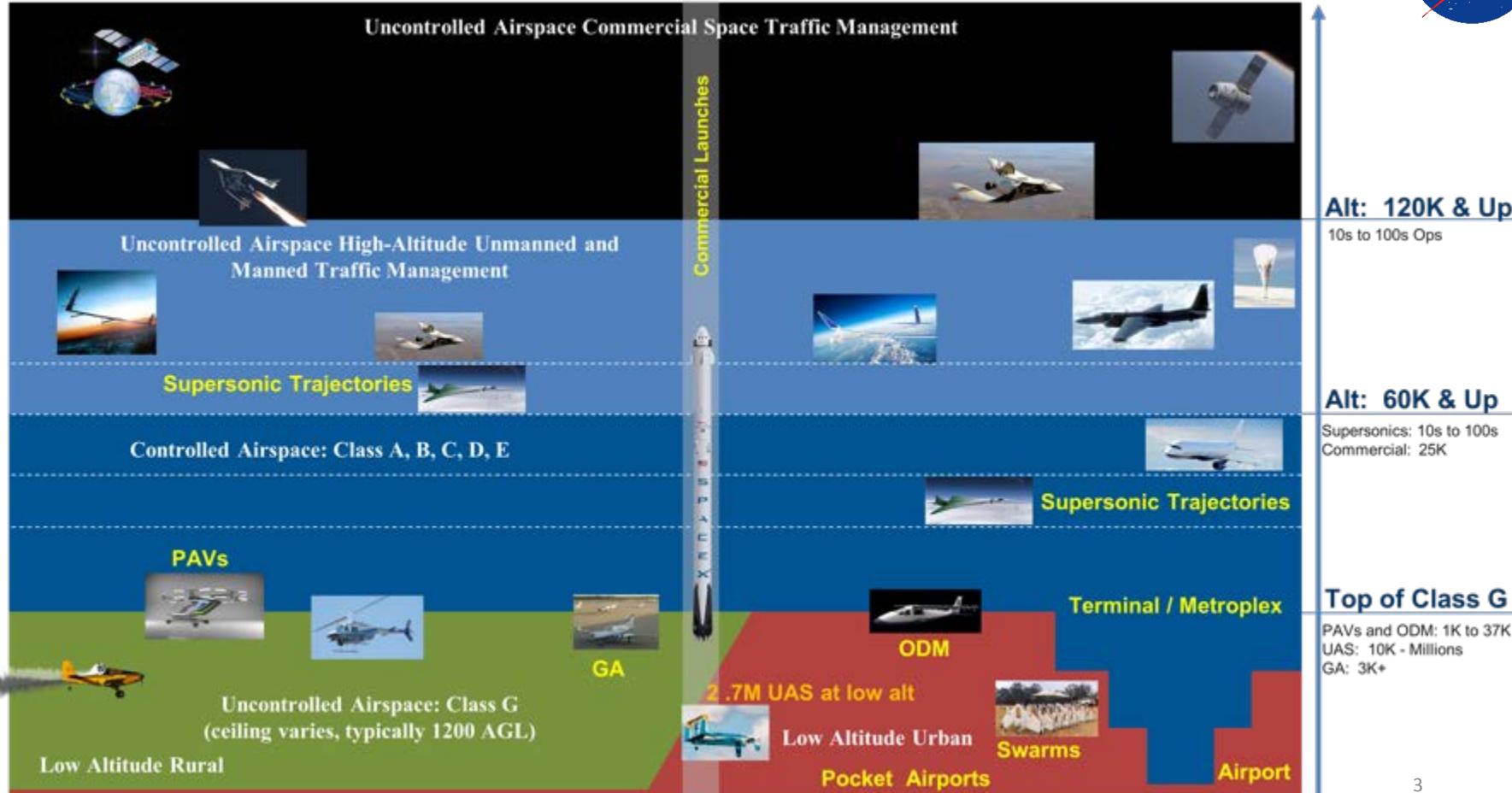
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CURRENT AIRSPACE OPERATIONS





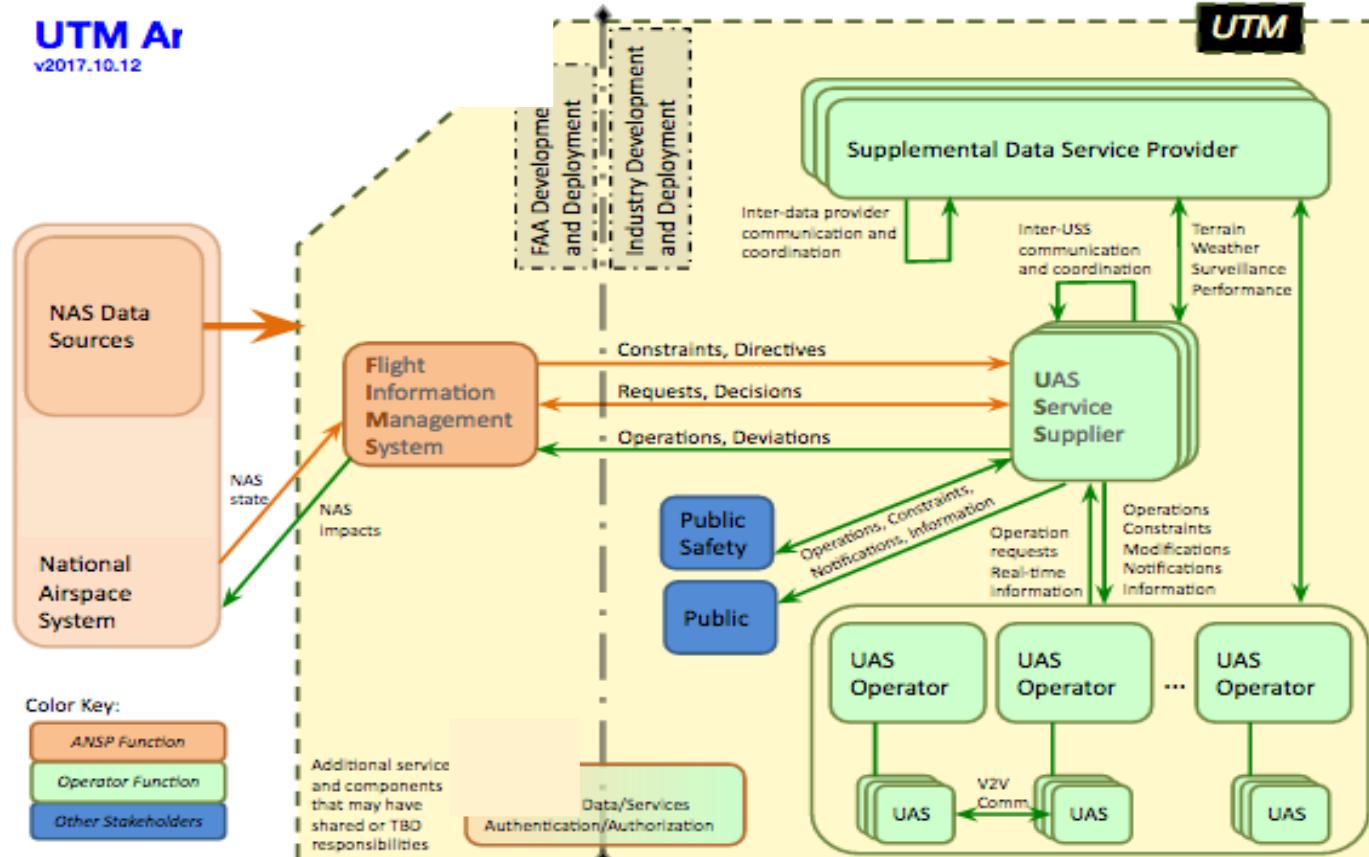
SMALL UNMANNED AIRCRAFT SYSTEMS



UAS Traffic Management Architecture



UTM Ar
v2017.10.12



*Connections & communications are internet-based & built on industry standards & protocols

Technology Capability Levels (TCLs)



TCL 1, 2 and 3 (in progress)

TCL 1

- Nat'l Campaign1: May 2016
- TCL 1 demo: August 2015

TCL 2

- Nat'l Campaign 2: May 2017
- Operational Area: UAS Range, Aviation, Aviation, Distant Terrain, Missions up to 500 ft, Operations up to 500 ft, State of Nevada Test Site, Reno, SRF Hawk Radar, Weather Equipment, LST, Used to monitor aircraft
- TCL-2 demo: Oct 2016
- Nat'l Campaign 2

TCL 3

- TCL3 UAS towards controlled airspace
- TCL3 First Responders
- TCL3 March 2018

Participating Orgs

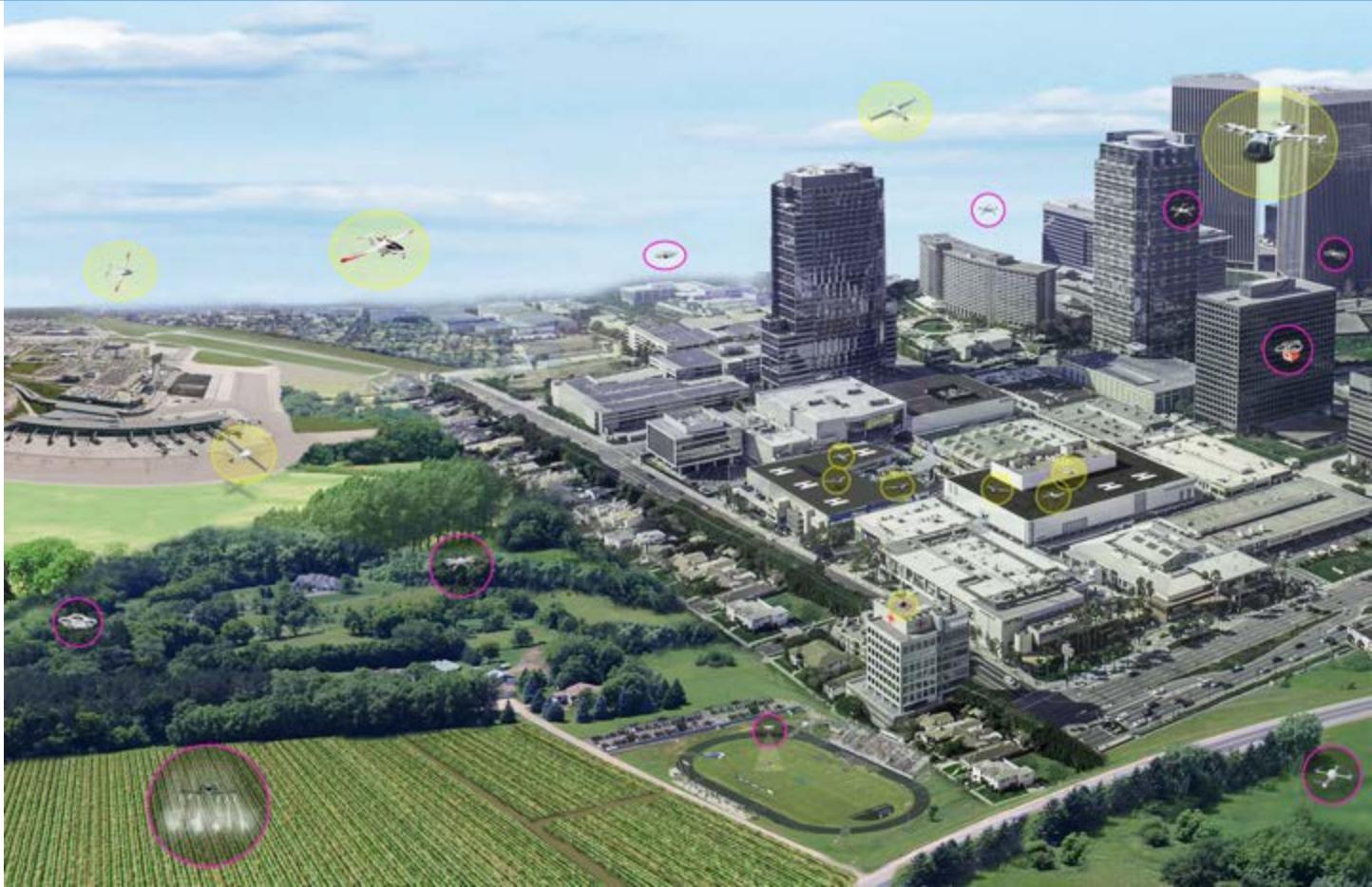
TCL	Count
TCL 1	19
TCL 2	42
TCL 3	35

Transformation – Urban Air Mobility

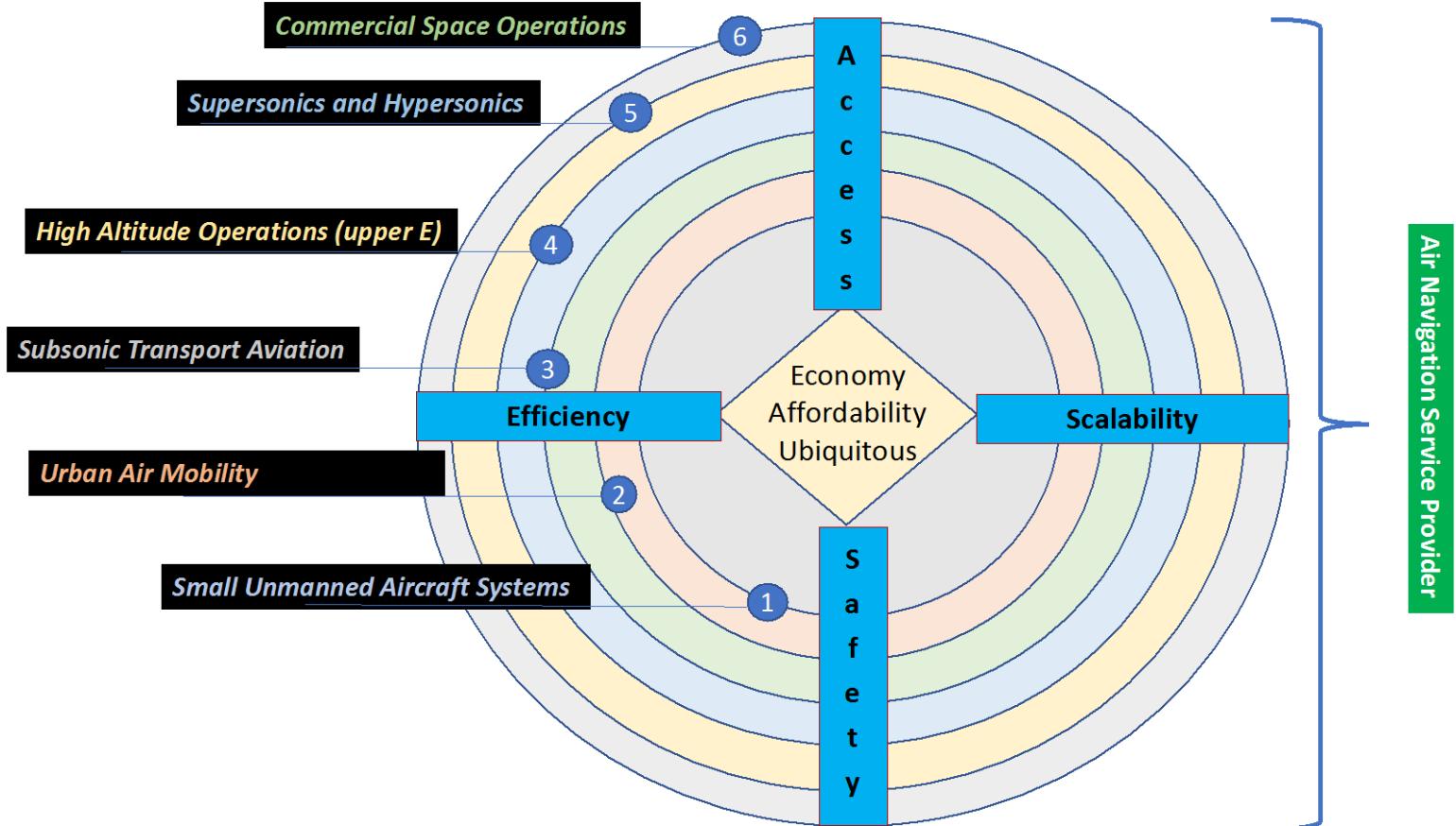
Increasingly autonomous – focused on access, safety and scalability

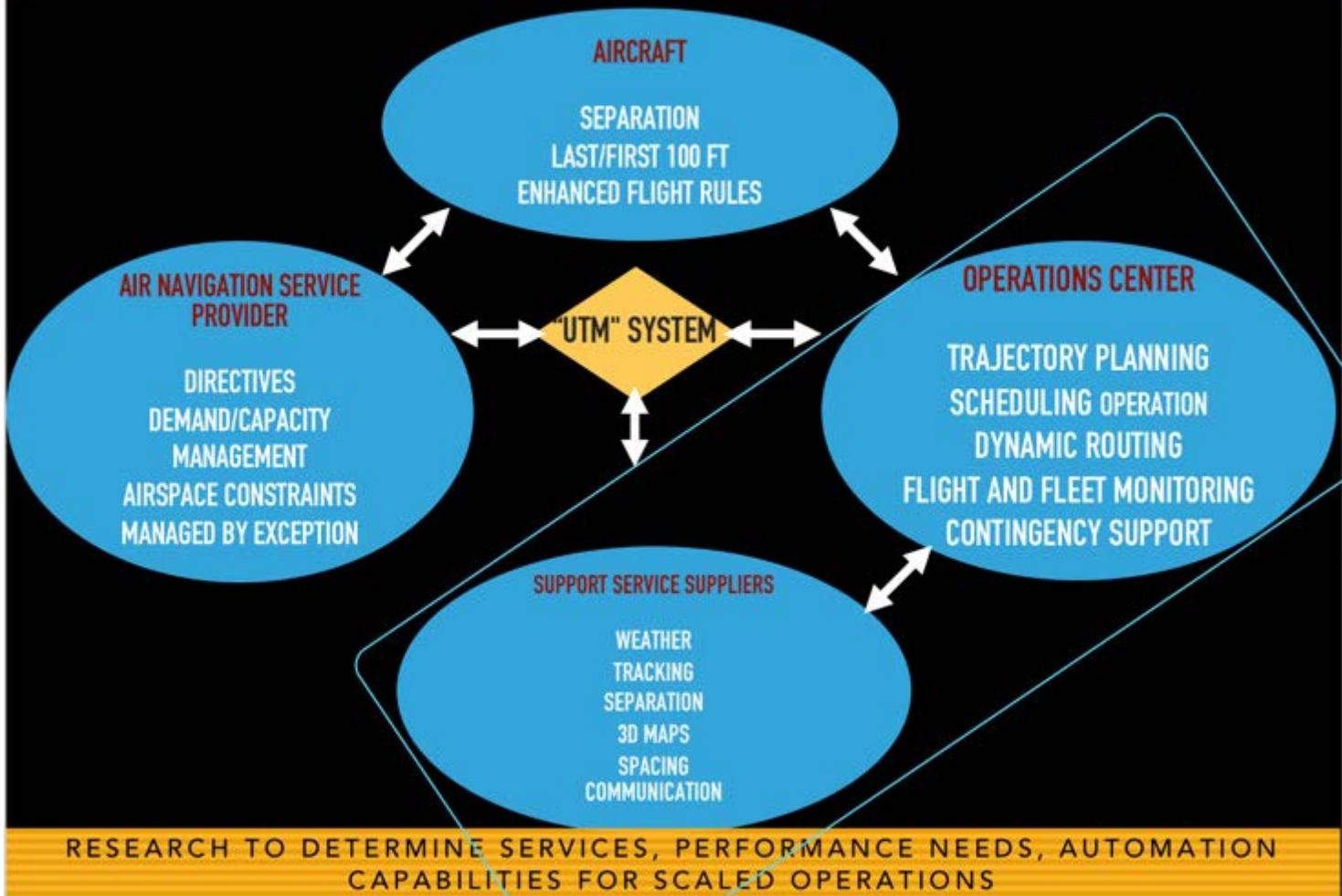


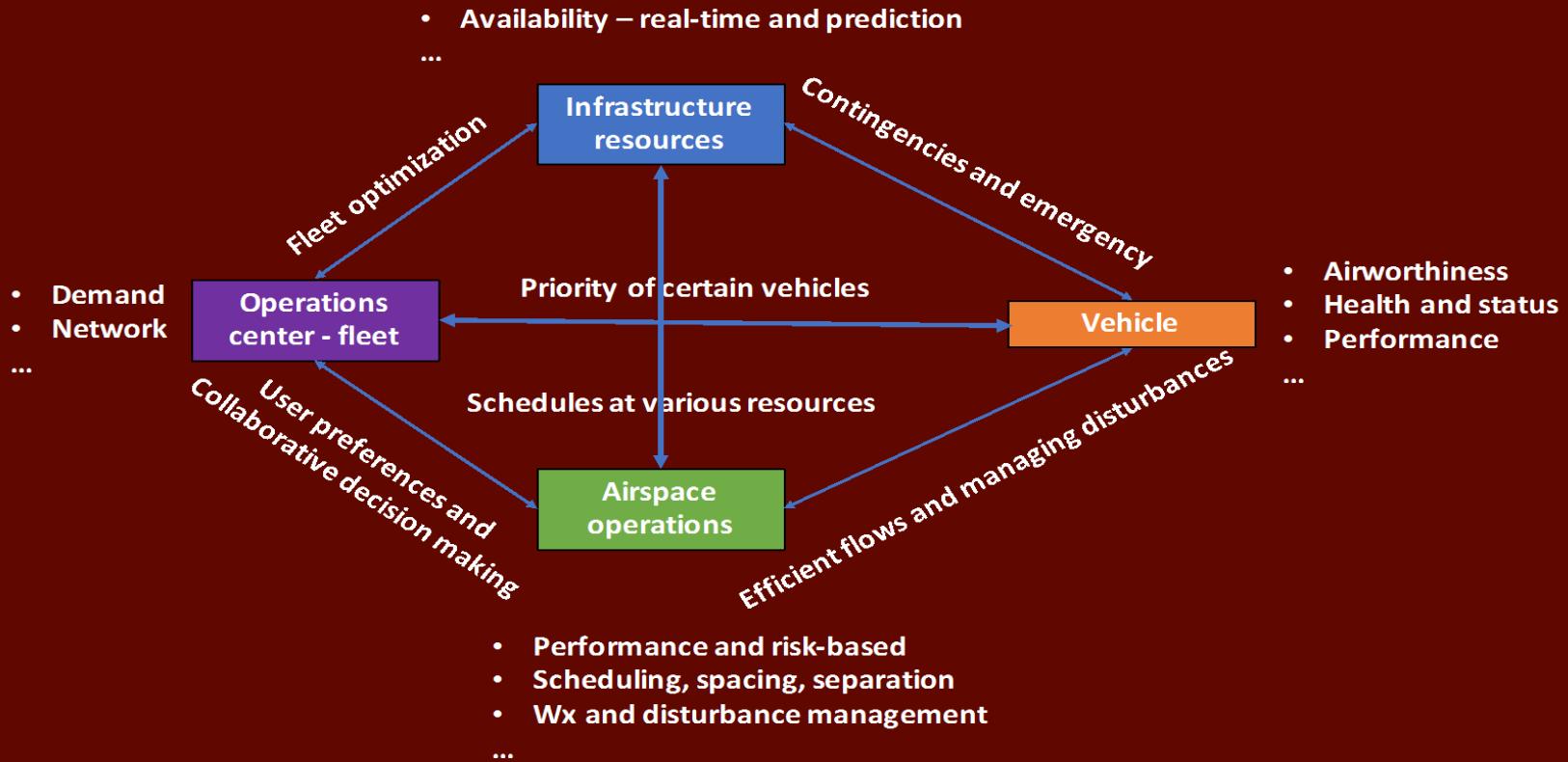
URBAN AIR MOBILITY: SMALL DRONES TO LARGER PASSENGER CARRYING VTOLS



Emerging and Heritage Users







Autonomy alone will not lead to efficiency and large-scale disturbance management
 Connectivity is crucial – air/ground/cloud/infrastructure integration will be key



- Cooperative
- Intent-sharing
- Digital: data exchanges among operators
- Standardized application protocol interfaces
- Air/ground integrated
- Service-oriented architecture
- Role for third parties

Space Traffic Management

High Altitude UTM (upper E)

Conventional Manned Aviation (Class A, B, C, D, E)

Urban Air Mobility

Low-altitude small UAS



Increasingly Autonomous and Connected Operations

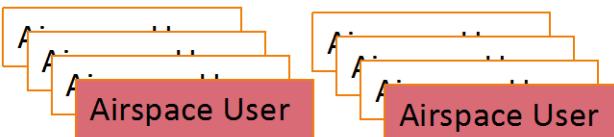
Current ATM

All services are provided by the FAA

- Traffic flow management
- Airspace directives/constraints
- Scheduling, sequencing and spacing
- Separation management
- Off-nominal management
- Every vehicle interaction in real-time

FAA Systems

Humans address off-nominal and contingencies



Very little interaction among users, and 3rd party services

- Human in the epi-center of information integration
- Every data moves through FAA systems for every vehicle
- Each change focused in on domain-specific FAA system

UTM-inspired-ATM

Some services are provided by FAA

- Airspace directives/constraints
- Resource availability and changes to resources (e.g., arrival/departure rates, resource schedules)
- Separation

FAA Systems

User or third party services

- Flow management
- Sequencing, and spacing
- User participation strategic Separation (e.g., oceanic)

Automation addresses off-nominal and contingencies



Users collaborate/cooperate for efficiency, intra-user preferences for flights into constrained resources

- Automation in the epi-center of information integration
- New paradigm: digital and connected ecosystems- outside apps, scalability

NASA Unique Role: Architecture, data exchange, service allocation/roles/responsibilities, rules of engagement, service performance requirements, automation for contingency management and disruption handling, machine learning environment and algorithms for continuous improvement, safety assurance, certification/acceptance approaches, and technology transitions

Future airspace operations?

- Scalable – increasingly autonomous
- Cooperative – information needs, and technologies for cooperation among vehicles, and operators, and service providers
- Digital – data exchanges and standardized application protocols
- Resilient – technologies and procedures for faster recovery from disruptions
- Manage by exception – flexibility where possible and structure where necessary
- Safety assurance – in-time data, prognostics, V&V of increasingly autonomous systems
- Air/ground/cloud integrated
- Service oriented architecture – third party



Space Traffic Management

High Altitude UTM (upper E)

**Conventional Manned Aviation
(Class A, B, C, D, E)**

Urban Air Mobility

Low-altitude small UAS

airspace operations
enabling beyond possible!



Concluding Remarks

- Need for change is real, current systems are not sustainable
- Sense of urgency due to emerging markets and diversity of operations
- Build-a-little-test-a-little and deploy
- Research issues remain – however goal should be "cross the finish line" to improve operations – research is means to an end and not an end in itself
- Highly scaled operations that are affordable and safe

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BACK UP

Scalable, Safe, and Efficient Autonomous Operations

Goal: Enable autonomous operations in the national airspace system



- **Motivation:**

- Smaller and medium size autonomous cargo delivery market is emerging
- Use of upper and lower airspace is increasing where there are no services
- Pilot shortage is looming – Regular transport category for short/long haul flights
- Future urban air mobility operations business case depends on autonomous operation

- **Enable autonomous freighter operations** by integrated air/ground/cloud capabilities

- Rationale: Regardless of level of autonomy, integration is key - SWA
- Initial operational evaluation (TRL 4)
- Demonstration leading up to daily use operations (TRL 6+)

- **Autonomous urban air mobility vehicle operations** – cargo and/or passengers through integrated air/ground/cloud capabilities under nominal and off-nominal condition

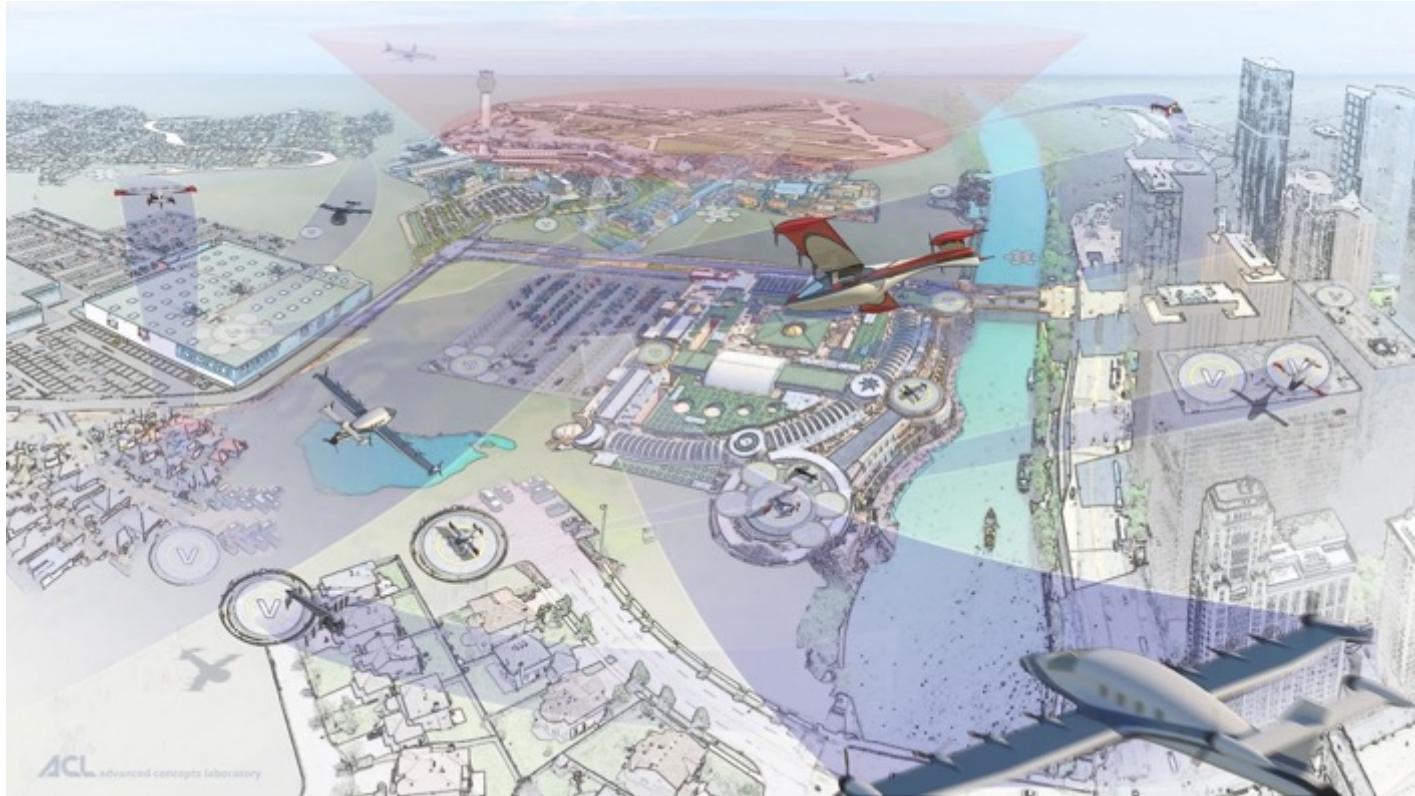
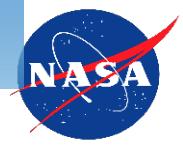
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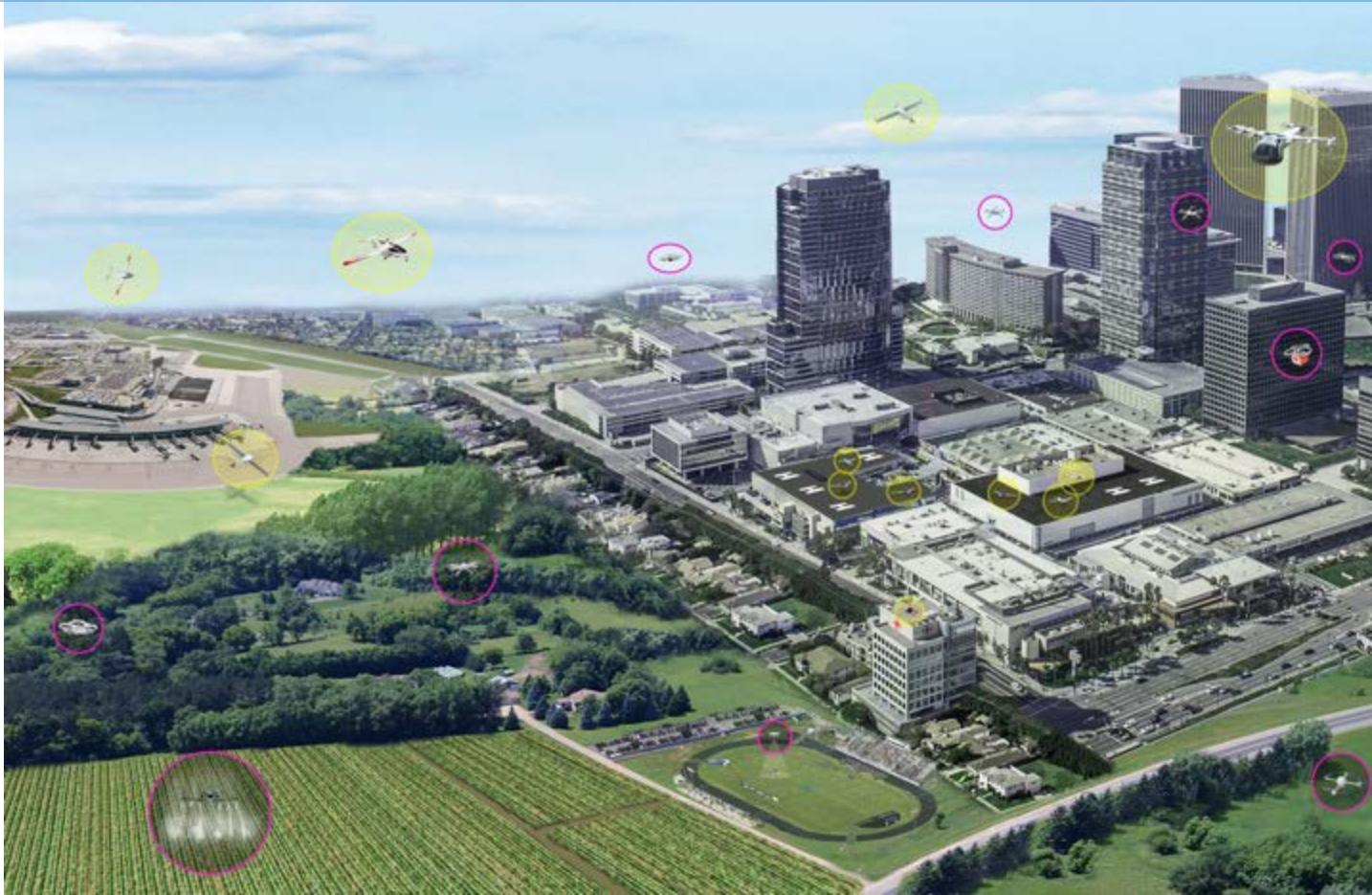


VERTICAL TAKE OFF AND LANDING



ACL advanced concepts laboratory

URBAN AIR MOBILITY: SMALL DRONES TO LARGER PASSENGER CARRYING VTOLS



Transformation – Urban Air Mobility

Increasingly autonomous – focused on access, safety and scalability

