



Embracing Innovation in Aviation While Respecting Its Safety Tradition

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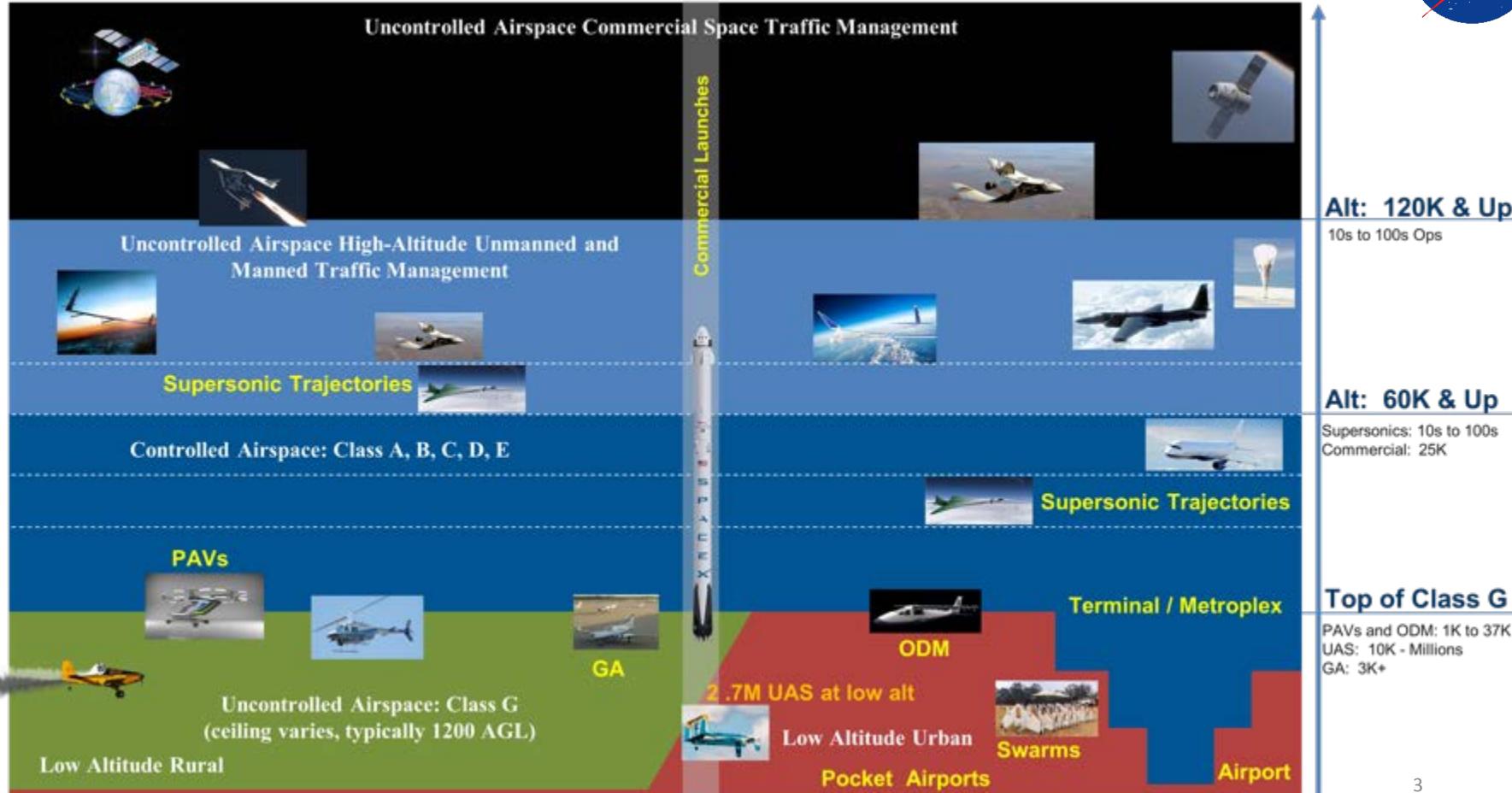
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CURRENT AIRSPACE OPERATIONS





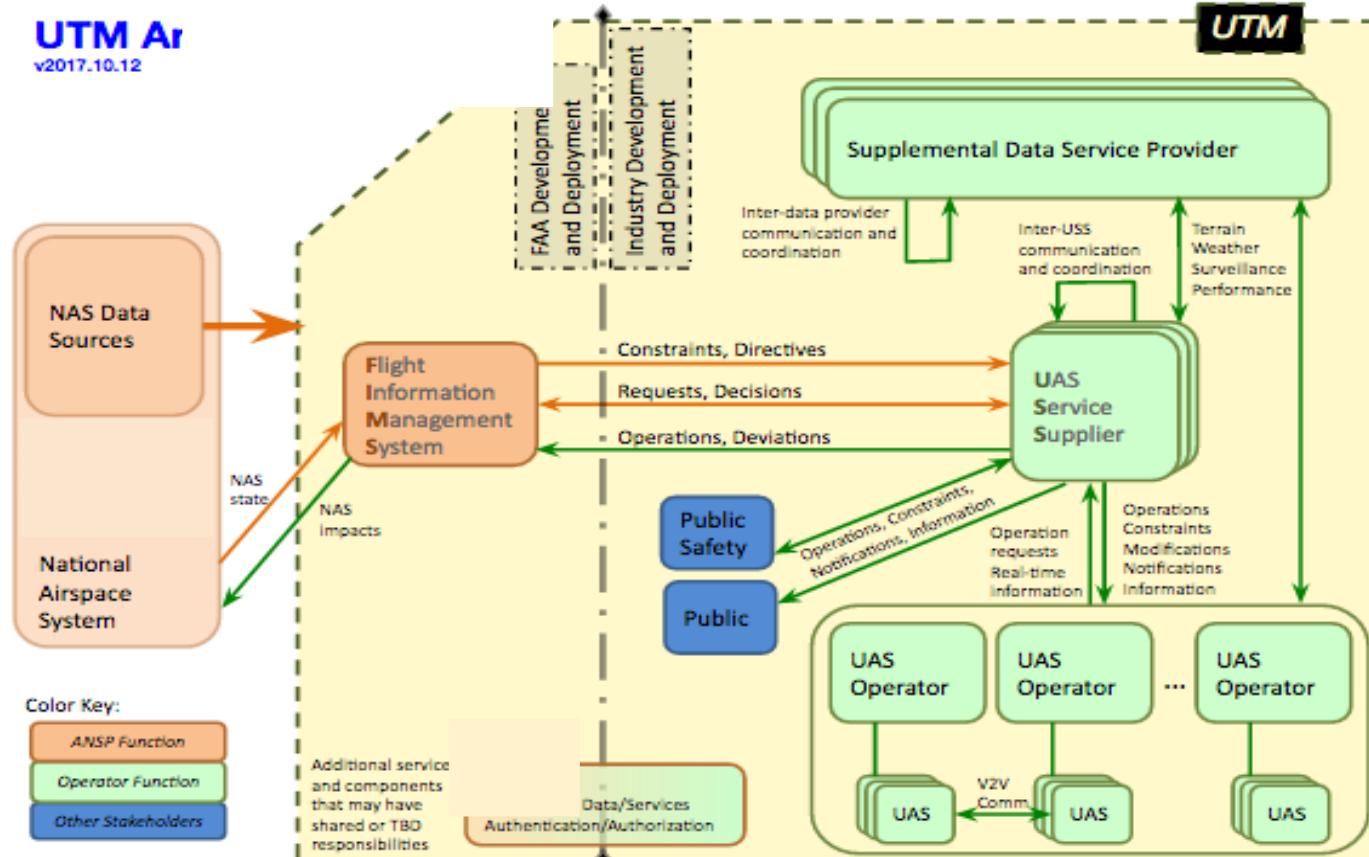
SMALL UNMANNED AIRCRAFT SYSTEMS



UAS Traffic Management Architecture



UTM Ar
v2017.10.12



*Connections & communications are internet-based & built on industry standards & protocols

Technology Capability Levels (TCLs)



TCL 1, 2 and 3 (in progress)

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TCL 1

- Nat'l Campaign1: May 2016
- TCL 1 demo: August 2015

TCL 2

- Nat'l Campaign 2: May 2017
- Operational Area: UAS Range, Aviation, Aviation, Distant Terrain, Missions up to 500 ft, Category 3 UAS, SPRINT Radar, Weather Equipment, LST, Weather Equipment, LST
- TCL-2 demo: Oct 2016
- Nat'l Campaign 2

TCL 3

- TCL3 UAS towards controlled airspace
- TCL3 First Responders
- TCL3 March 2018

Participating Orgs

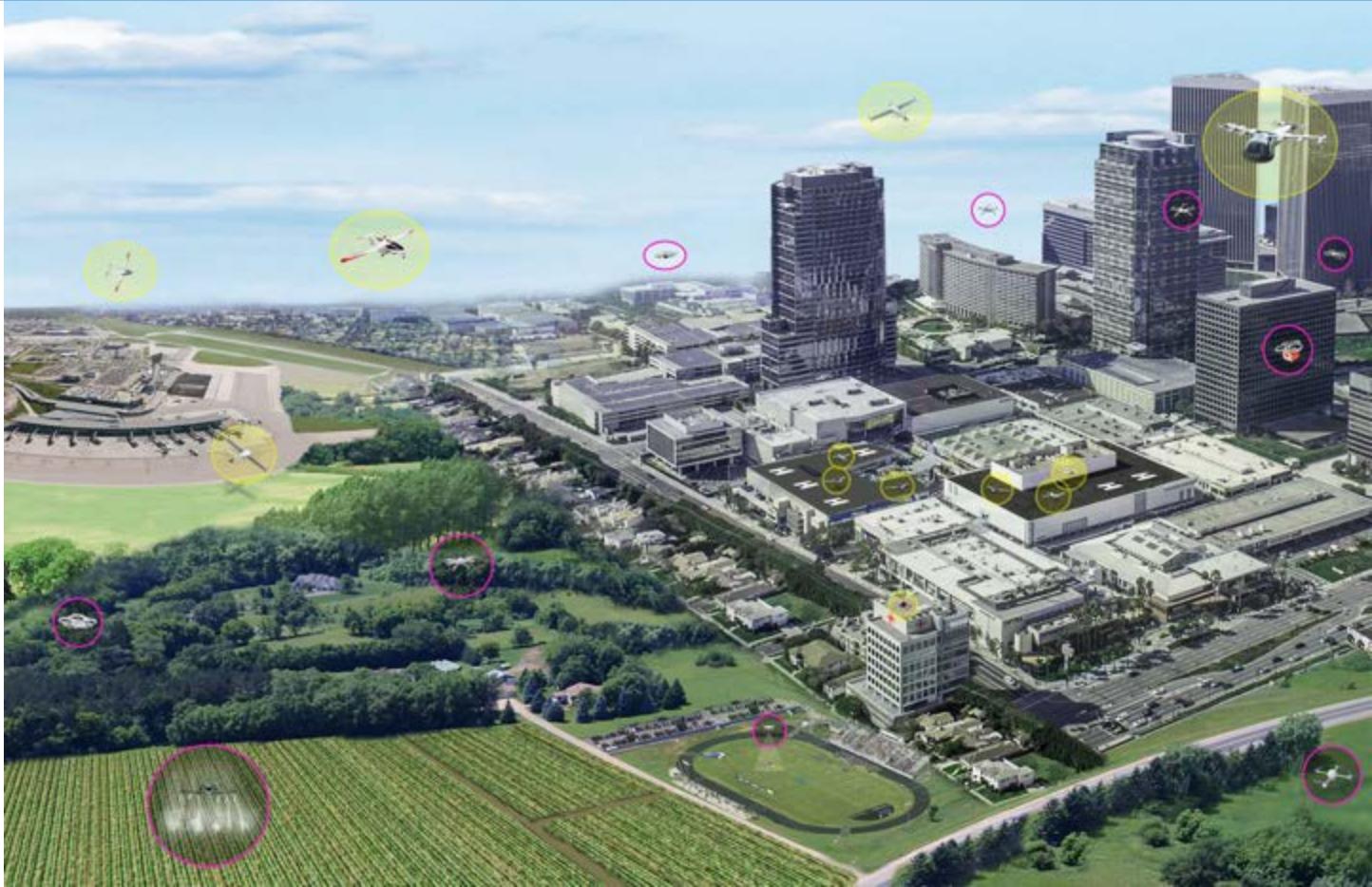
TCL	Count
TCL 1	19
TCL 2	42
TCL 3	35

Transformation – Urban Air Mobility

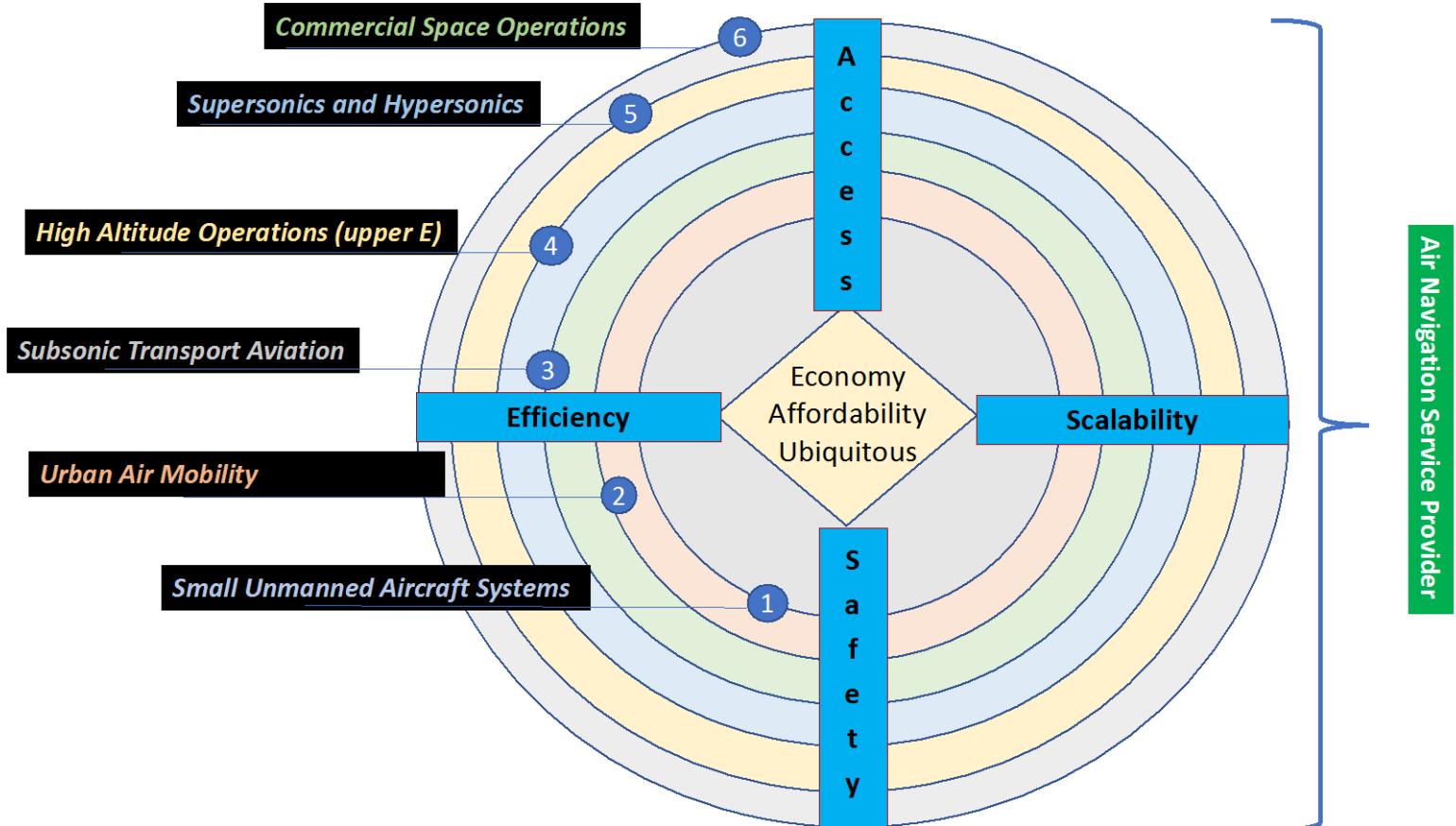
Increasingly autonomous – focused on access, safety and scalability

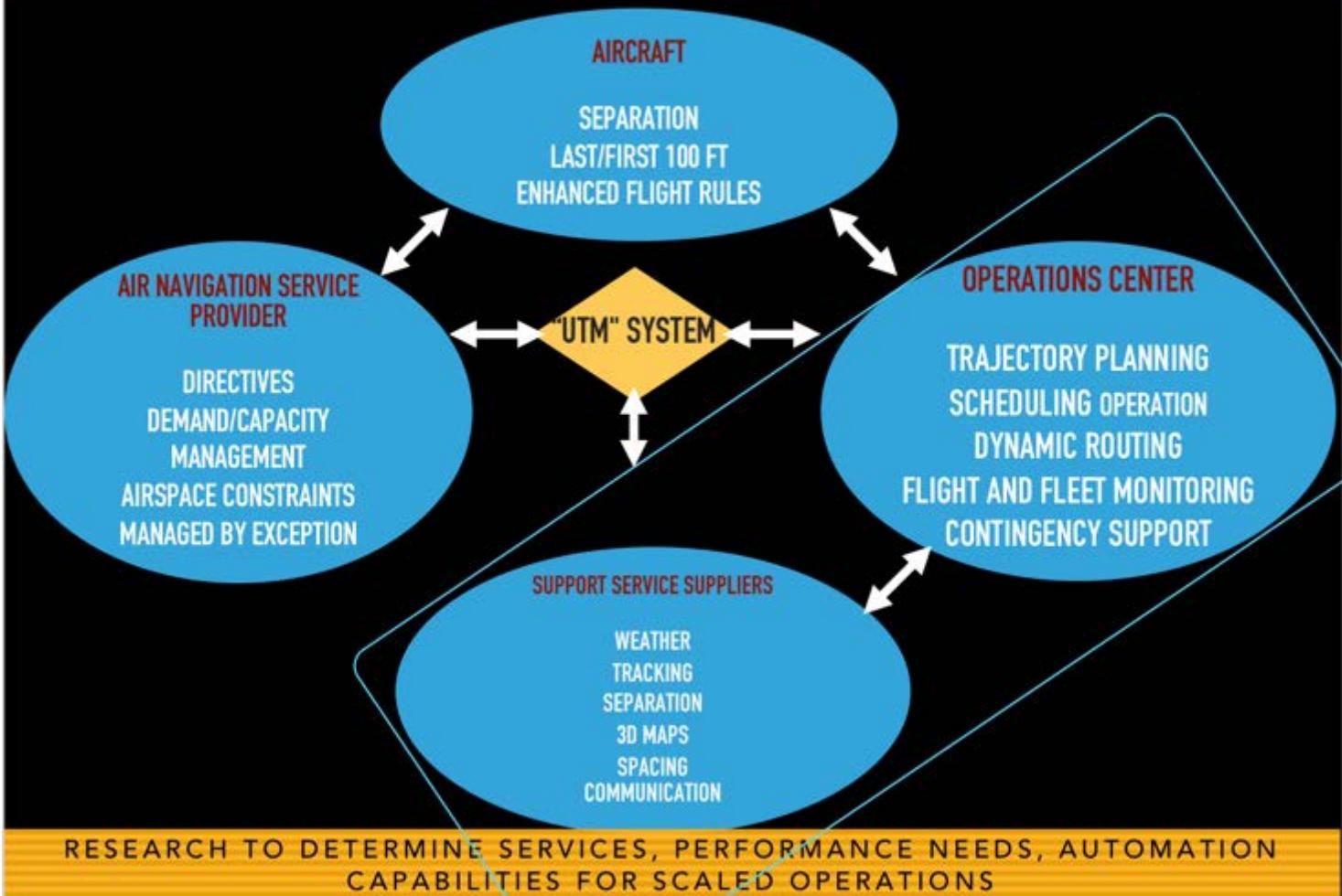


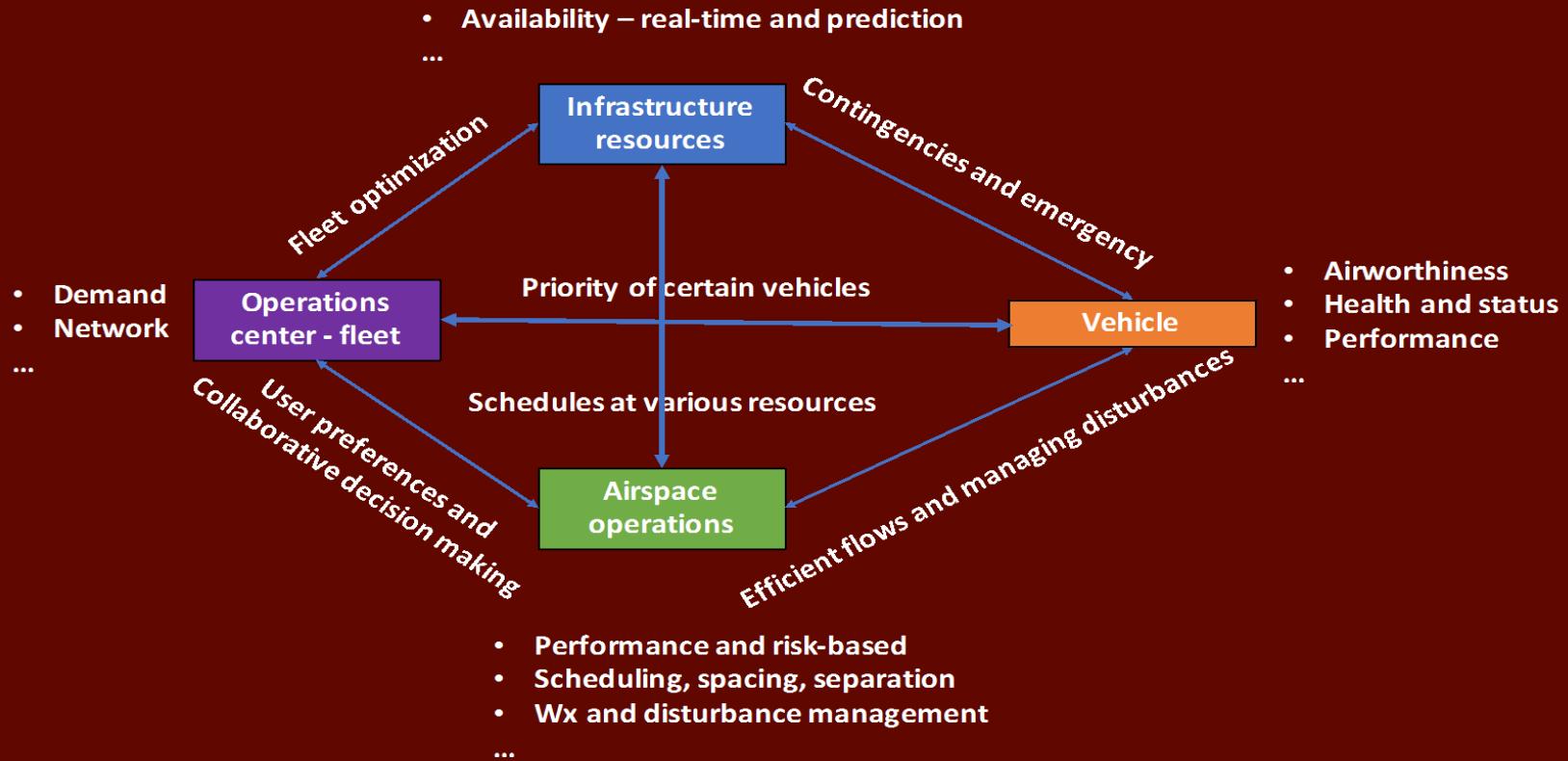
URBAN AIR MOBILITY: SMALL DRONES TO LARGER PASSENGER CARRYING VTOLS



Emerging and Heritage Users







Autonomy alone will not lead to efficiency and large-scale disturbance management
 Connectivity is crucial – air/ground/cloud/infrastructure integration will be key



- Cooperative
- Intent-sharing
- Digital: data exchanges among operators
- Standardized application protocol interfaces
- Air/ground integrated
- Service-oriented architecture
- Role for third parties

Space Traffic Management

High Altitude UTM (upper E)

Conventional Manned Aviation (Class A, B, C, D, E)

Urban Air Mobility

Low-altitude small UAS



Increasingly Autonomous and Connected Operations

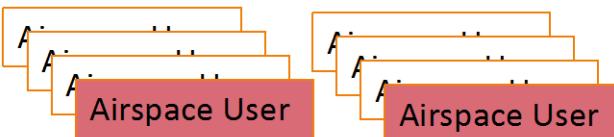
Current ATM

All services are provided by the FAA

- Traffic flow management
- Airspace directives/constraints
- Scheduling, sequencing and spacing
- Separation management
- Off-nominal management
- Every vehicle interaction in real-time

FAA Systems

Humans address off-nominal and contingencies



Very little interaction among users, and 3rd party services

- Human in the epi-center of information integration
- Every data moves through FAA systems for every vehicle
- Each change focused in on domain-specific FAA system

UTM-inspired-ATM

Some services are provided by FAA

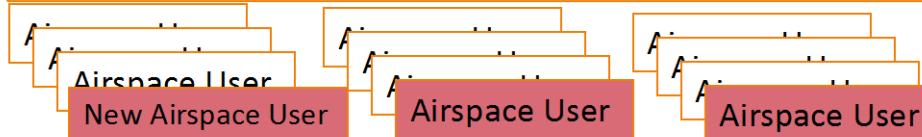
- Airspace directives/constraints
- Resource availability and changes to resources (e.g., arrival/departure rates, resource schedules)
- Separation

FAA Systems

User or third party services

- Flow management
- Sequencing, and spacing
- User participation strategic Separation (e.g., oceanic)

Automation addresses off-nominal and contingencies



Users collaborate/cooperate for efficiency, intra-user preferences for flights into constrained resources

- Automation in the epi-center of information integration
- New paradigm: digital and connected ecosystems- outside apps, scalability

NASA Unique Role: Architecture, data exchange, service allocation/roles/responsibilities, rules of engagement, service performance requirements, automation for contingency management and disruption handling, machine learning environment and algorithms for continuous improvement, safety assurance, certification/acceptance approaches, and technology transitions

Future airspace operations?

- Scalable – increasingly autonomous
- Cooperative – information needs, and technologies for cooperation among vehicles, and operators, and service providers
- Digital – data exchanges and standardized application protocols
- Resilient – technologies and procedures for faster recovery from disruptions
- Manage by exception – flexibility where possible and structure where necessary
- Safety assurance – in-time data, prognostics, V&V of increasingly autonomous systems
- Air/ground/cloud integrated
- Service oriented architecture – third party



Space Traffic Management

High Altitude UTM (upper E)

**Conventional Manned Aviation
(Class A, B, C, D, E)**

Urban Air Mobility

Low-altitude small UAS

airspace operations
enabling beyond possible!



Concluding Remarks

- Need for change is real, current systems are not sustainable
- Sense of urgency due to emerging markets and diversity of operations
- Build-a-little-test-a-little and deploy
- Research issues remain – however goal should be "cross the finish line" to improve operations – research is means to an end and not an end in itself
- Highly scaled operations that are affordable and safe

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BACK UP

Scalable, Safe, and Efficient Autonomous Operations

Goal: Enable autonomous operations in the national airspace system



- **Motivation:**

- Smaller and medium size autonomous cargo delivery market is emerging
- Use of upper and lower airspace is increasing where there are no services
- Pilot shortage is looming – Regular transport category for short/long haul flights
- Future urban air mobility operations business case depends on autonomous operation

- **Enable autonomous freighter operations** by integrated air/ground/cloud capabilities

- Rationale: Regardless of level of autonomy, integration is key - SWA
- Initial operational evaluation (TRL 4)
- Demonstration leading up to daily use operations (TRL 6+)

- **Autonomous urban air mobility vehicle operations** – cargo and/or passengers through integrated air/ground/cloud capabilities under nominal and off-nominal condition

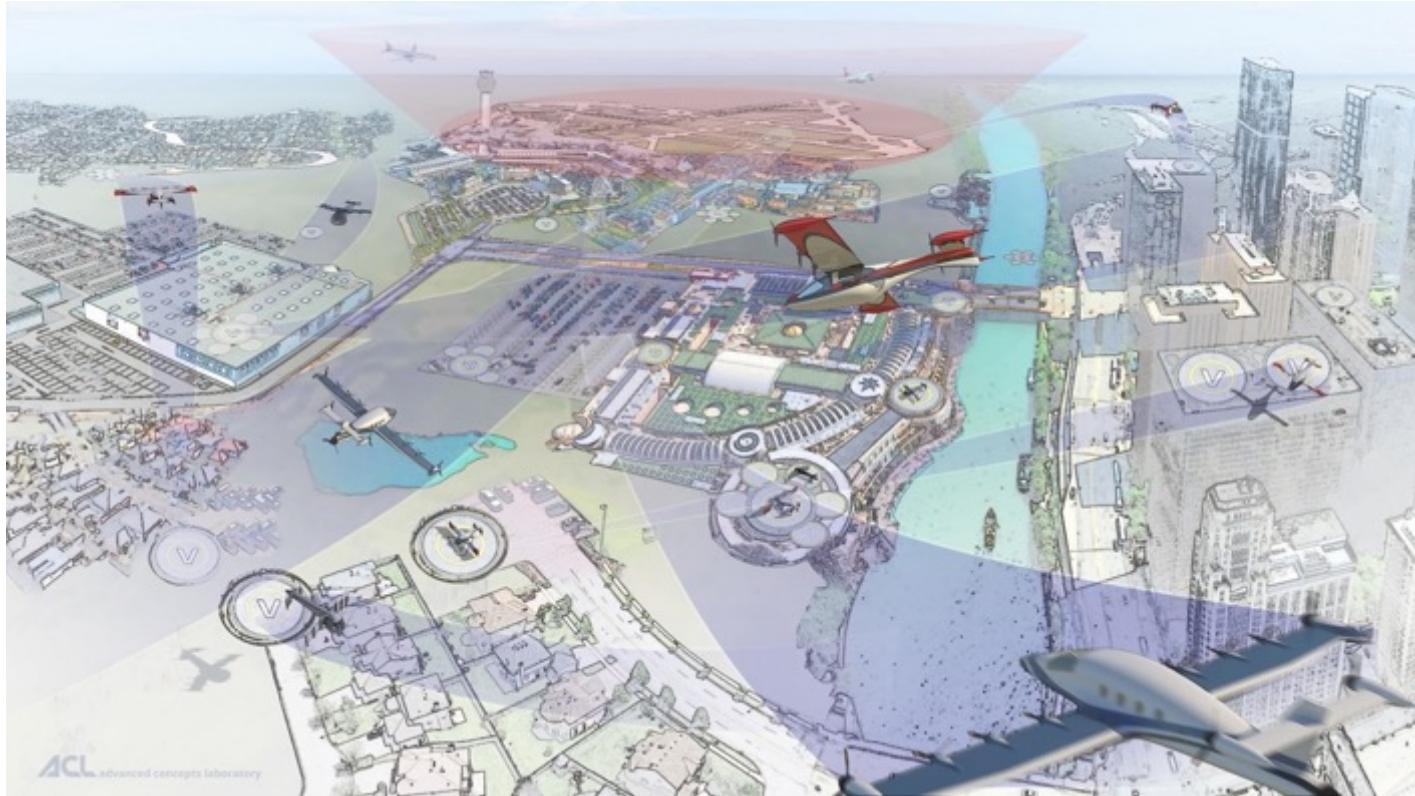
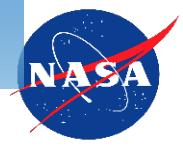
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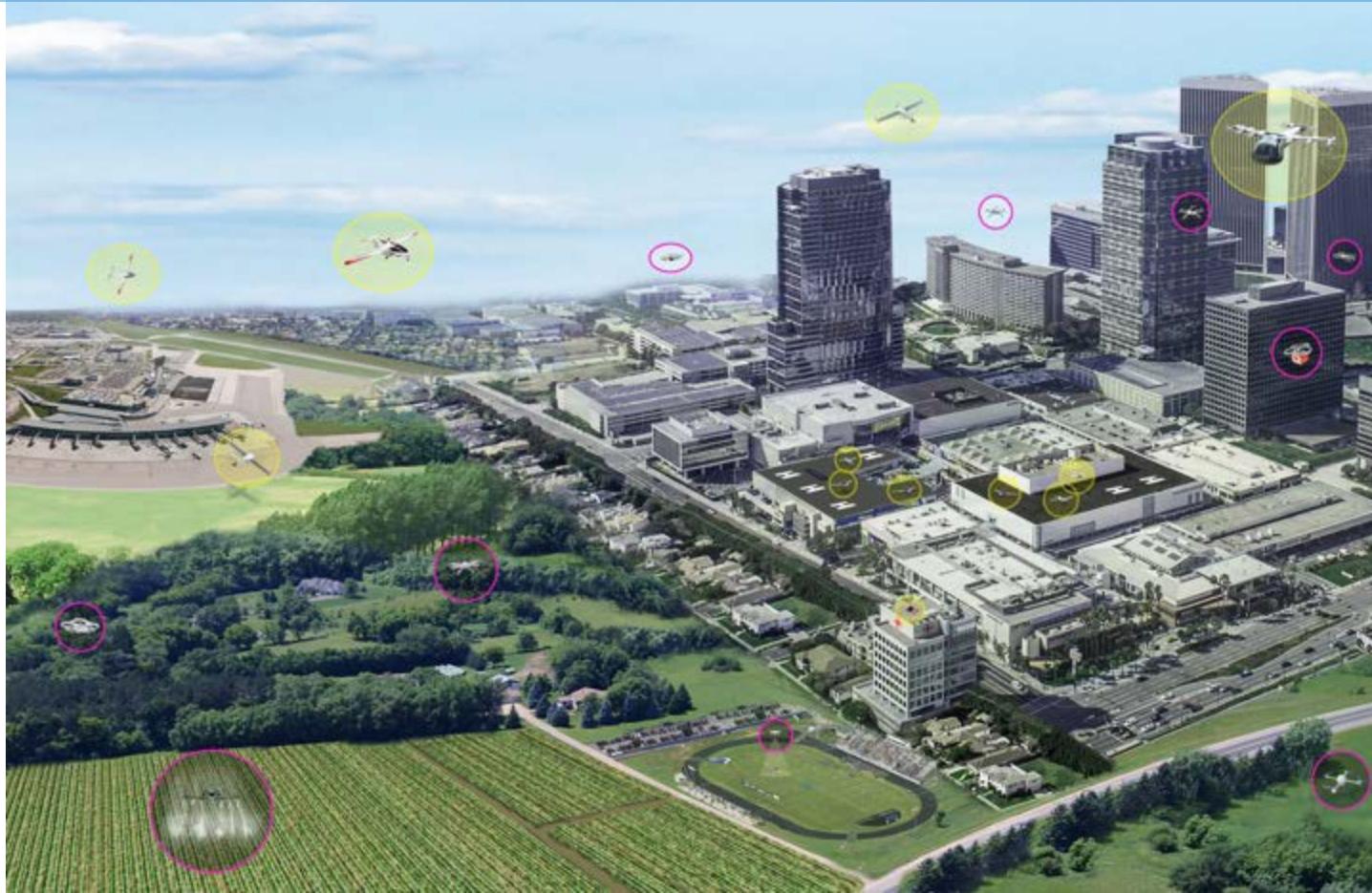


VERTICAL TAKE OFF AND LANDING



ACL advanced concepts laboratory

URBAN AIR MOBILITY: SMALL DRONES TO LARGER PASSENGER CARRYING VTOLS



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