

# Initial Results from The Sixth Community Achieving, Affording, and Sustaining Human Exploration of Mars Workshop (AM VI)



Lunar Operations, Technologies, and Activities to Enable Human Exploration of Mars

28-30 August 2018, The Elliott School

The George Washington University

Sponsored by Explore Mars, Inc. & the American Astronautical Society

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24 October 2018

Reports available at https://www.exploremars.org/affording-mars



# Goal of AM VI workshop . . .

A critical assessment by approximately 70 community representatives from NASA, academia, industry, research institutions, and international organizations of candidate activities on the lunar surface and its vicinity that may feed forward to support affordable and sustainable human missions to the surface of Mars in the 2030s.



# **Relevant Previous AM Community Workshops**





#### AM III (December, 2015 at the Space **Policy Institute, GWU)**

Integration of priority science goals with increasingly detailed human space flight scenarios: modify science goals and elements of human exploration to improve integration. Included planetary protection.



#### AM IV (December, 2016, **Doubletree Hotel, Pasadena)**

Critical comparison of major technological "long poles" necessary for achievable, affordable, and sustainable human exploration of Mars.



AM V (December, 2017, **Washington Plaza Hotel, Washington, DC)** Developed in detail three distinctly different scenarios for human exploration of Mars by the end of the 2030s that were required to be affordable.



# **Workshop Scenario Ground Rules**

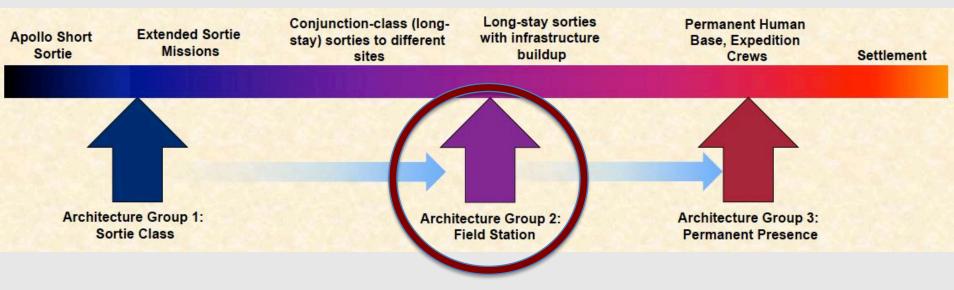
- The first human mission to the surface of Mars will take place during the 2030s. [cf., AM I V]
- Budgets for the space agencies will grow approximately with inflation. Modestly greater budget growth is possible in response to broad public and stakeholder support for lunar exploration and travel to Mars.
- No technological, political, or budget "miracles" are permitted or, if so, they must be clearly identified and justified.
- SLS, Orion, the Gateway, and commercially available medium-lift launch vehicles will be available during the time period considered here, so will not be assessed in depth in this workshop
- The presented Moon and Mars scenarios may not be altered in significant ways.
- Teams are not to advocate for any lunar scenario, but rather accept the scenarios as presented.
- There will be a continuous human presence in low Earth orbit to provide research and development opportunities via the ISS and/or other (e.g., commercial) platforms throughout the timeframe considered in this workshop.
- Partnerships (international, industrial, commercial, academic . . .) will be an essential component of human exploration.

# **Workshop Process**



# The Human Exploration of Mars Mission Continuum From AM V

Three different "end states" for human exploration of Mars were adopted in AM V as representative of the goals widely identified and an architecture was developed that sought to achieve each of them under common ground rules and constraints.



## Adopted for AM VI Assessment:

The engineering Long Poles were essentially the same in the medium to long term across all three scenarios examined at the AM V workshop. For this reason, the Field Station was used as the baseline for AM VI.

# Adopted Mars Scenario: Surface Field Station Similar to Evolvable Mars Campaign (EMC)



• **Goal of Surface Field Station:** To learn how to live and operate on Mars in preparation for continuous human presence on Mars, via the deployment of a temporary Mars surface field station that is visited by multiple crews over the lifespan of the infrastructure

#### • Activities:

- **Engineering testing** of surface hardware (e.g., ISRU, in-situ materials, civil engineering, pressurized rovers, etc.)
- **Environmental monitoring and characterization** (e.g., ground-truthing of orbital recon datasets such as water mapping and surface winds, better informing planetary protection practices)
- Understanding long-term human health impacts of long duration deep space and surface missions and demonstrating appropriate countermeasures
- Learn how best to do in-situ science with human crewmembers as a resource (e.g., to address MEPAG goals)

#### End State:

- When sufficient knowledge and operational experience is gained to decide on the location and architecture of the first continuously occupied permanent base on Mars.
- Chosen to occur at the same time that Mars surface equipment wears out (thus avoiding the need for system recertification and/or replacement)



## **AM V Field Station Key Features**



- Built upon NASA's Evolvable Mars Campaign (EMC) study (2014-2016) with additional options considered to increase program sustainability
  - Conjunction-class missions with gradually increasing time spent on the Martian surface as more surface capabilities are delivered and more experience is gained
  - Baseline atmospheric O<sub>2</sub> ISRU with water-based ISRU considered within the trade space depending on selected landing site and precursors/field station activities
  - Reuse of Transit Habitat and in-space propulsion for crew and cargo transit, which are sent back to lunar gateway for refurbishment
  - Reuse of Mars Surface Habitat
- Modular build-up of in-space and Mars surface assets (incl. human habitat and laboratory modules) using multiple commercial and international providers
- Small/mid-size Mars landers derived directly from lunar surface program
  - Develops experience base and distributes cost for Mars program across longer timeline
  - Smaller, modular payloads (~10mT) allows for increased commercial / international participation (e.g. launch vehicles, landers, and payloads)
    - → increases cost sustainability and political sustainability
  - Allows deployment of larger science payloads (than currently considered)
    - → increased opportunities for scientific discovery and public engagement
  - Increases system flexibility and robustness by allowing individual components to be repaired and/or upgraded as they degrade, or as more experience is gained in their operations



# **Comparison of Mars Architectural Philosophies**



DRA 5.0 (2009)  Minimize risks and exposure of crew/cargo to the deep space environment with short duration transits separated by a long surface stay. Three crewed missions in 10 years with overlapping predeployed cargo missions.	Evolvable Mars Campaign (2013 – 2017) Progressive expansion of capabilities through the cis-lunar "Proving Ground" to a sustainable human presence on Mars with reasonable extension of ISS, SLS, Orion and DSG. Emphasis on affordability and sustainability.	AM V Team 2 (2018)  Looked for ideas to enable an "enterprise sustainable" architecture for an initial human Mars Field Station.  Do not necessarily represent completed trades.
	Key Architectural Similarities	
Conjunction Class – 900-1000d	Conjunction w/ depart & arrival windows to 1200d	Conjunction Class
Pre-deployment of cargo	Pre-deployment of cargo	Pre-deployed cargo on a range of lander sizes
ISRU (O <sub>2</sub> for ascent)	ISRU (O <sub>2</sub> for ascent)	ISRU O <sub>2</sub> , but also include H <sub>2</sub> O as early as possible
Long surface stay	Evolve to long surface stay	Long surface stay
Round-trip crew vehicle	Round-trip crew vehicle (hybrid SEP/Chemical option)	Round-trip crew vehicle
	Key Architectural Differences	
Crew of 6	Crew of 4	Examine crew of 6
Cost profile – high peak	Cost profile – long medium	Cost profile – long medium
In-space prop: fast transit, NTR	In-space prop: Minimum energy SEP/Chemical, Chemical, NTP	In-space prop: NTP, Minimum energy SEP/Chemical, Chemical
All crew to surface	1st crew to orbit, 2nd to surface	No orbital only missions; All crew to surface
Vehicle assembly in LEO	Vehicle assembly in cis-lunar, HEO departure and arrival	Vehicle assembly in cis-lunar, HEO departure and arrival
Max launch cadence – 6/yr.	Max launch cadence – 2/yr. (1 crew and 1 cargo)	Launch cadence depends on commercial landers
Crew trip to Mars each opportunity	Crew trip to Mars every other opportunity	Aim for frequent opportunities
Minimize crew space exposure	Crew 1100 days in space ok	Minimize crew space exposure (surface stays + NTP)
Redundant surface systems possible	Single string of elements	Modular habs and labs likely have redundancy
Each landing site different for science	Single site build-up infrastructure	Single site with broad science exploration
All systems expended	Reuse of habitat, transportation, surf. Sys.	Reuse of habitat, transport, and surface & examine MAV reuse
		1



# **Key Characteristics of Lunar Activity Categories**

Lunar Attribute	unar Attribute Gateway-Only		GER-Class	Field Station					
All options assume Gateway staging, heavy lift, and 11 km/s return vehicles									
Human Surface Mission?	No	Yes, Multiple Sites	Yes, Multiple Sites	Yes, Fixed Base Site					
Crew to Surface	0	2-4	4	4+					
Surface Exploration Duration	n/a 3-5 Days		42 Days	6 Months					
Pre-Deployed Surface Assets	No	No	Yes	Yes					
Key Attributes	Earth or Gateway tele- operated robotic science & demonstrations	Unpressurized rover for local exploration	<ul> <li>Pressurized Rover</li> <li>Cryogenic lander/ascent</li> <li>Reusable ascent stage</li> <li>KiloPower</li> </ul>	<ul> <li>Pressurized Rover</li> <li>Cryogenic lander/ascent</li> <li>Reusable ascent stage</li> <li>KiloPower</li> <li>Habitat</li> <li>ISRU</li> </ul>					
<b>Exploration Range</b>	n/a	<10 km per site	100 km per site	100 km from base					

A range of lunar missions was considered in order to help drive key capability and technology needs and potential applicability toward future Mars missions

# **Engineering Long Poles to Enable Mars Exploration**

**AM VI** 

About a dozen engineering Long Poles required for eventual human missions to the martian surface were identified and assessed in our 2016 AM IV workshop.

In AM VI, these were used to assess the content of the lunar scenarios that most enabled exploration of Mars in the 2030s.

Yrs to close 2	Driving Gaps <sup>3</sup>	Long Term Goal		Enabled H	uman Mis	sions	
		Mars Surface Long Stay	Cislunar Shakedown Cruise	Mars Fly-By	Mars Orbital	Orbital + Martian Moon Sortie	Mars Surface Short Stay
11	<u>Design of logistics architecture and demonstration in deep space</u> , Autonomous operations at Mars. Xenon & cryogenic transfer.	x	x	x	×	×	х
HRP roadmap green +?	Hab: Space radiation protection for crew,	x	х	x	х	x	х
	300-kW Class Solar Array, ARV-derived Power Distribution, 12.5-kW Electric Propulsion Thruster, Low Thrust Navigation	x			x	x	х
12	Resource Reconnaissance for Landing Site Selection, ground truth of resource mapping Round-trip Demo / Sample Return, extant biology in soil (?), atmospheric recon for EDL,	x				x	x
13	Mars EDL system (30 t, <100 m precision), LOX/Methane Propulsion and CFM	x					x
6 (atmos) 8 (water)	Convert CO2 to O2, Dust effects on ISRU hw. Oxygen extraction from CO2. (DRM 5.0) Access H2Osubsurface ice/minerals. Resource Acquisition, Liquefaction and CFM	x	DI		F	1	
~5 17	Surface Habitation (architecture for livability and usability)	X		1	7.7		х
8 - 10	<u>SEP-derived Solar Arrays</u> , lightweight fuel cell/ battery storage, high power/high efficiency RPS	x					х
10 - 12	10s kW Fission Power, Heat pipe thermal transport, high efficiency energy conversion	x					
13	LOX/CH4 Propulsion and CFM, habitability, GN&C, Integrated System, ISRU Convert CO2 to O2,	x					x
	Deep Space, High-Rate Forward Link / Downlink and High Rate Proximity Communication	x			х	х	x 10
	11  HRP roadmap green +?  years  12  13  6 (atmos) 8 (water)  ~5 17  8 - 10  10 - 12	Design of logistics architecture and demonstration in deep space, Autonomous operations at Mars. Xenon & cryogenic transfer.  HRP roadmap green +?  years  300-kW Class Solar Array, ARV-derived Power Distribution, 12.5-kW Electric Propulsion Thruster, Low Thrust Navigation  Resource Reconnaissance for Landing Site Selection, ground truth of resource mapping Round-trip Demo / Sample Return, extant biology in soil (?), atmospheric recon for EDL,  13 Mars EDL system (30 t, <100 m precision), LOX/Methane Propulsion and CFM  Convert CO2 to O2, Dust effects on ISRU hw. Oxygen extraction from CO2. (DRM 5.0) Access H2O-subsurface ice/minerals. Resource Acquisition, Liquefaction and CFM  5-17 Surface Habitation (architecture for livability and usability)  8-10 SEP-derived Solar Arrays, lightweight fuel cell/ battery storage, high power/high efficiency RPS  10-12 10s kW Fission Power, Heat pipe thermal transport, high efficiency energy conversion  LOX/CH4 Propulsion and CFM, habitability, GN&C, Integrated System, ISRU Convert CO2 to O2, Deep Space, High-Rate Forward Link / Downlink and	Close 2  Design of logistics architecture and demonstration in deep space, Autonomous operations at Mars. Xenon & cryogenic transfer.  HRP roadmap green + ?  years  300-kW Class Solar Array, ARV-derived Power Distribution, 12.5-kW Electric Propulsion Thruster, Low Thrust Navigation  Resource Reconnaissance for Landing Site Selection, ground truth of resource mapping Round-trip Demo / Sample Return, extant biology in soil (?), atmospheric recon for EDL,  13  Mars EDL system (30 t, <100 m precision), LOX/Methane Propulsion and CFM  6 (atmos) 8 (water)  Convert CO2 to O2, Dust effects on ISRU hw. Oxygen extraction from CO2. (DRM 5.0) Access H2O-subsurface ice/minerals. Resource Acquisition, Liquefaction and CFM  ~5 17  Surface Habitation (architecture for livability and usability)  8 - 10  SEP-derived Solar Arrays, lightweight fuel cell/ battery storage, high power/high efficiency RPS  10 - 12  10 skW Fission Power, Heat pipe thermal transport, high efficiency energy conversion  LOX/CH4 Propulsion and CFM, habitability, GN&C, integrated System, ISRU Convert CO2 to O2, Deep Space, High-Rate Forward Link / Downlink and	Close 2  Driving Gaps 3  Goal  Mars Surface Long Stay  Cislunar Shakedown Cruise  11  Design of logistics architecture and demonstration in deep space, Autonomous operations at Mars. Xenon & X  X  X  X  HRP roadmap green +?  years  300-kW Class Solar Array, ARV-derived Power Distribution, 12.5-kW Electric Propulsion Thruster, Low Thrust Navigation  12  Resource Reconnaissance for Landing Site Selection, ground truth of resource mapping. Round-trip Demo / Sample Return, extant biology in soil (?), atmospheric recon for EDL,  13  Mars EDL system (30 t, <100 m precision), LOX/Methane Propulsion and CFM  Convert CO2 to O2, Dust effects on ISRU hw. Oxygen extraction from CO2. (DRM 5.0) Access H2O-subsurface ice/minerals. Resource Acquisition, Liquefaction and CFM  Surface Habitation (architecture for livability and usability)  8 - 10  SEP-derived Solar Arrays, lightweight fuel cell/ battery storage, high power/high efficiency RPS  10 - 12  10 SkW Fission Power, Heat pipe thermal transport, high efficiency energy conversion  LOX/CH4 Propulsion and CFM, habitability, GN&C, Integrated System, ISRU Convert CO2 to O2, Deep Space, High-Rate Forward Link / Downlink and	Close 2   Close 3   Coal   Closurary   C	Close 2  Mars Surface Long Stay  Design of logistics architecture and demonstration in deep space. Autonomous operations at Mars. Xenon & X X X X X X X X X X X X X X X X X X	Close 2   Close 3   Coal   Cistunar Shakedown   Cruise   Cisturar   Cruise   C



# **Example: Long Pole Matrix**Mars Ascent Vehicle Assessed by Transportation/Propulsion Team

		Gateway	Lunar Sorties	GER Class	Field Station	Key			Capabilities
Long Poles and Associated Driving Gaps	Minimum Success Criteria and *other information	Lunar orbit only with surface telerobotics	Short duration stays with local crew exploration	Medium duration with local exploration, relocatable	Long duration with regional exploration, single site	environmental differences that impact Long Pole/driving gap reduction	Other Considerations	Capabilities which can be matured at the ISS now	with long lead times which must be developed specifically for Mars
1: Aggregation/Refuel/Resupply (11)									
Design of logistics architecture and demonstration in deep space	Demonstrate the autonomous delivery and transfer of fuel and cargo in deep space	Medium: Aggregation, assembly and refueling/resupplying of the Gateway will inform Mars mission assembly  Small quantities and scale	Low: Assuming expendable descent and ascent stage	Medium: Assuming at least a reusable ascent stage.  Vehicle Refurbishment at Gateway  High: If descent stage (ccyo) is fueled at Gateway  Medium scale logistics	High: Assuming fully reusable lander. Long duration operations on the surface of the Moon will help refine future Mars logistics strategies. Large scale logistics	N/A	*Note: Focus only on logistics here since fuel is covered below.	ISS analog possible	Yes  Cryo Fluid  Management needs to start immediately. The Moon should be used to develop the experience base prior to going to Mars
Autonomous operations at Mars	*Operations of systems at Mars distance with limited/no Earth support	Medium: Uncrewed/autonomous operation at Gateway provides an analogue for autonomous operation at Mars  Transition from autonomous to crewed operations  Demonstration of Comm Ops through Comms relay	Medium: Autonomous mating of lander with Gateway and checkout prior to human arrival  Potential autonomous landing operations	High: Repeated/extended autonomous operation of lander at Gateway	High: Assume field station is permanently occupied (less autonomous than previous). Initial operations similar to GER class	Time lag may influence autonomous operations		ISS analog possible (Proposed)	No

# Most Relevant Systems and Technologies (aka, "Long Poles") to Test/Demonstrate on the Moon to Feed Forward to Mars



# Prioritized Space Transportation and Propulsion Systems, Technologies, and Operations

# 1. Long-term cryogenic fluid management

Long-term storage of cryogenic propellants (LOX, LCH<sub>4</sub>, LH<sub>2</sub>), passive/active reduced boiloff tanking, liquid acquisition, tank mass gauging

Lander development (e.g., propulsion, precision & autonomous landing, hazard avoidance)

Cryogenic engines in the 40 - 100 kN range, deep-throttling engines, cryogenic reaction control system (RCS), precision landing, hazard avoidance

3. Vehicle aggregation (e.g., refueling, refurbishing, checkout)
Vehicle servicing, cryogenic refueling, refurbishment, repair, cleaning, re-certification for flight readiness

4. Human health and biomedicine (e.g., radiation, psychosocial)

Deep-space behavioral health monitoring, deep-space radiation

# Most Relevant Systems and Technologies (aka, "Long Poles") to Test/Demonstrate on the Moon to Feed Forward to Mars Surface Systems/Technologies/Operations



# **Highest priority** (Alphabetical Order)

- Human health and biomedicine (e.g., psychosocial, food & medicine)
- Power systems (e.g., fission for primary power, radioisotope power for mobility)
- Rovers for human exploration (e.g., operations, energy storage, airlocks, suitlocks)
- Surface suits (e.g., pressure garment, environmental protection layer, maintenance)

# **Next highest priority** (Alphabetical Order)

- Communication systems (e.g., orbital assets, local communication)
- In-situ resource utilization [See Notable Topic below]
- Surface habitats and laboratories (e.g., systems availability, operations)

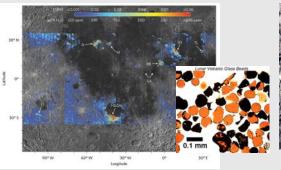
## **Notable Topic: In-Situ Resource Utilization**

In-situ resource utilization (ISRU), especially of lunar and Martian near-surface extractable water and the Martian atmosphere, has the potential to enable affordable and sustained human occupation of the Moon and/or Mars. However, critical information about these resources is not yet available. Therefore

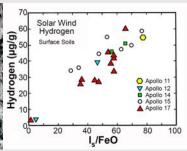
- ISRU surface and orbital reconnaissance of potential lunar and martian resources must continue to verify their potential, especially whether or not lunar water ice feeds forward to Mars exploration
- Verify the potential for lunar ISRU technologies, processes, and operations (e.g., excavation/drilling, water cleaning and electrolysis, liquefaction/storage) to feed forward to human Mars exploration.

# **Lunar ISRU Strategy That Feeds Forward Moon-to-Mars**

### **Water Resources on the Moon**







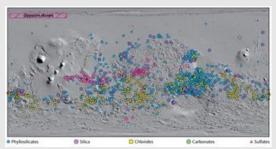
80°-90° N
30°-90° N
30° N

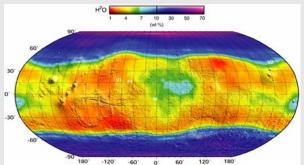
Volcanic glasses: ≥0.3 wt.% H<sub>2</sub>O

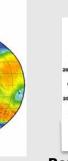
Regolith: solar wind implanted H

Polar water ice: up to 30 wt.% water ice at the surface

#### **Water Resources on Mars**







Massive ice <1m depth at poles

Potential near-surface ice >1m depth

## Mid-latitudes: Hydrated Minerals

#### Mars Forward Lunar ISRU Role and Focus

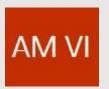
- Identify, characterize, and quantify resources/volatiles for future applications
- Important Demonstrations:
  - o Demonstrate ISRU concepts, technologies, & hardware that reduce the mass/cost/risk of human Mars missions:
    - ISRU for propellant production; Cryogenic storage & transfer to refuel ascent vehicle
    - Site engineering and infrastructure emplacement for repeated landing/ascent at same location
  - o Use Moon for operational experience and mission validation for Mars, such as:
    - Pre-deployment & remote activation and operation of ISRU assets without crew
    - Landing crew with 'empty' tanks with ISRU propellants already made and waiting
  - Long-duration surface operations
    - · Increase duration and autonomy; possibly polar location due to more benign solar/thermal environment
    - Build-up of power, communication, and mission support infrastructure after initial surface evaluation
    - Demonstrate Mars Forward human mission surface exploration operations and infrastructure

# **Selected Workshop Observations**



- Early Mars missions do not necessarily require lunar surface activities. However, an important number of
  possible human and robotic operations, technology developments, and demonstrations on the surface of
  the Moon and its vicinity were identified that would contribute to the Mars scenario adopted here (Field
  Station) by the end of the 2030s.
- A successful and sustainable Moon-to-Mars human space flight program requires a single "integrating" NASA Headquarters office with budget authority to apply the results of technology, operations, and science trade studies:
  - Lunar and martian priorities should not be assessed independently of one another.
  - Future priorities for Mars exploration may levy requirements on lunar exploration.
- The profound environmental differences between the Moon and Mars must be fully incorporated into scenarios that intend for the former to enable the latter.
- The Gateway could be an important test-bed for Mars transportation architectures.
- Using the ISS or a similar platform, where crews are continuously present using systems intended for Mars, is key for understanding how these systems will perform and potentially need to be maintained for a three-year Mars mission. In addition, permanent presence by crews in a zero-g and relatively isolated and stressful environment is critical for reducing human health and biomedicine risks for long-duration missions.
- Two martian engineering Long Poles Crew and Cargo Landers and Martian System Reconnaissance have very long development times. If development of these Long Poles is delayed, the goal of landing humans on the surface of Mars will be likewise delayed.

# Proposed Assessments of the Extent to which the Moon may be used to Further Mars Exploration (I)



### **Priority Follow-on Activity to AM VI**

We found significant value in the Moon and Mars communities working together to understand how lunar operations and capabilities can feed forward to Mars. We recommend a more extensive assessment with increased participation by these communities. This collaboration, under NASA leadership, should commence **as soon as possible** and use the ongoing NASA *Engineering Long Poles for Getting Humans to the Surface of Mars* effort as the basis for the activity.

## **Trade Studies (Not in Priority Order)**

- 1. Comparison of end-to-end costs of resources extracted from the Moon with those supplied from terrestrial sources
- 2. Lunar ascent vehicle/lander extensibility to Mars ascent vehicle/lander
- 3. Pros/cons of different cryogenic propellant combinations (i.e., LOX/CH<sub>4</sub> versus LOX/H<sub>2</sub>) for lunar and Mars scenarios
- 4. Value of remotely operated robot versus on-site astronaut operations on the lunar surface to feed forward to human missions to Mars
- 5. Airlock versus suitlock, including planetary protection, habitat access, and cognizance of different environment
- 6. Common development paths for Mars and Moon surface suit thermal systems
- 7. Long-lived pressurized rover energy production and storage (e.g., Kilopower versus radioisotope power system (RPS), fuel cells versus batteries)
- 8. Rover needs on the two worlds (e.g., duration of trips, what rovers are used for (science, construction, maintenance, transportation), day-night cycle, and crew size)
- 9. Study on ISRU-based site preparation and construction for landing, lift-off, and surface transportation operations on lunar and martian terrain.

# Proposed Assessments of the Extent to which the Moon may be used to Further Mars Exploration (II)



## **National Academies Studies**

- In-situ resource utilization (ISRU), especially of surface/shallow geological deposits containing extractable water, has the potential to enable affordable and sustained human occupation of both the Moon and Mars. However, certain critical information about these resources is not yet available and, consequently, how and when such resources might be exploited. Therefore,
  - What are the priority surface and orbital reconnaissance programs of potential lunar and martian resources to assess their potential?
  - What is the degree to which lunar resource exploration, production, beneficiation, and commodity storage processes feed forward to Mars?
  - What are the effects of declining launch costs and development of lunar resource extraction capabilities?
- Mitigation of environmental damage to human health (e.g., radiation, psychosocial, zero g, partial g) for lunar and Mars missions:
  - What needs to be carried out at ISS and Gateway, and what can be learned on the Earth?

# **AM VI Participants**

# Planning Team in **BOLD**



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Ben	Reed	Executive Office of the President
Mark	Robinson	Arizona State University
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Gerald	Sanders	NASA JSC
Laurent	Sibille	NASA KSC
John	Sims	NASA JSC
Ellen	Stofan	Director, NASM
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David	Turner	US State Department
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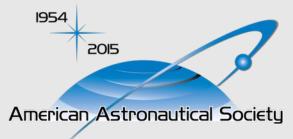




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# **Questions?**





Opening talk by Dr. Jim Green (NASA Chief Scientist) Closing talk by Dr. Ellen Stofan (Director, NASM)



# **Back Up**

# **AM VI**

Consensus Workshop

# Pre-workshop Mapping

# **AM IV Long-Poles**



**AMV** 

**Architectures** 







Ten key technology long-poles

## **Three Architectures**

- Sorties
- Research station
- Permanent habitation



## **Notional Lunar Architectures**

- Gateway only
- Sortie-Class
- **GER-Class**
- **Field Station**



For each long pole from the selected Mars architecture, rate the degree to which it can be advanced by each lunar architecture

**Map criticality** 

of each long pole to one of **AMV** architectures

# **Example Long Pole Matrices**



# **Transportation Team -** Crew/Cargo Lander

#### **Surface Team – Mars Communications**

Long Poles and Associated Driving Gaps	Minimum Success Criteria and *other information	Gateway  Lunar orbit only with surface telerobotics	Lunar Sorties Short duration stays with local crew exploration	GER Class  Medium duration with local exploration, relocatable	Long duration with regional exploration, single site	Key environmental differences that impact Long Pole/driving gap reduction	Other considerations	Capabilities which can be matured at the ISS now	Capabilities with long lead times
									which must be developed specifically for Mars
5: Crew/Cargo Lander: Entry, Descent, and Landing (EDL) (13)	Perform a precursor mission to demonstrate EDL, prior to delivery of mission-critical cargo								
Human-scale Mars EDL system)	30 t, <100 m precision	Medium: Aeromaneuvering of Commercial Logistics/Earth Return	High: Precision landing and hazard avoidance Medium: Abort scenarios	High: Critical infrastructure near landing zone	High: Abort to surface. Humans present near landing site		*Consider lunar propulsion landing and Mars terminal landing phases	Commercial Resupply for atmospheric entry	Ys
Cryo Propulsion and Cryoffuid Management	*Demonstrate a relevant Coxo propulsion system and long-term cryogenic storage in Mars –like surface environmental conditions	N/A  Gateway does not use Cryogens  Medium: If commercial logistics vehicles use GD(2, propulsion	N/A	High: Strong similarity between lunar descent and Mars lander propulsion Medium: Potential storage of Cop, at Gateway (lander/tanker)	High: Strong similarity between lunar and Mars lander propulsion Surface production, storage and transfer to landers of cryofluids		*Assume hypergolics for lunar sortie missions	No	Yes Goog Fluid Management needs to start immediately
Footnotes	GER class missions ma	y have some ab	ort to surfac	e capability					

		Gateway	Lunar Sorties	GER Class	Field Station		
Long Poles and Associated Driving Gaps  Minimum Success Criteria and *other information	Lunar orbit only with surface telerobotics	Short duration stays with local crew exploration	Medium duration with local exploration, relocatable	Long duration with regional exploration, single site	Key environmental differences that impact Long Pole/driving gap reduction	Other considerations	
12: Surface EVA Suit **PRIMARY							How do we operate EVAs on the two surfaces? That can drive differences (relevant for all categories).
Pressure Garment Suit	Addresses abrasiveness and mobility to meet desired maintenance cadence and operations.	Low – elements of next gen Space Suit will provide learning for Surface Suit.	High "We would like it to be high. Depends on design decisions made for the suit. if suit is designed for longer duration mission, then High. Risk posture is different due to different due to different viewels of infrastructure available nearby.	High – Moon is a more extreme environment in terms of dust environment; the operations and methodology will be somewhat different but overall similar knowledge gain.	High – Moon is a more extreme environment in terms of dust environment; the operations and methodology will be somewhat different but overall similar knowledge gain.	Best practices of being dust tolerant are very common; some details may be different. Can get a lot of benefit by making Mars and Moon pressure garment same/very similar.	Assuming that this is just pressure garment and does not include the environmental protection layer. Want to be tolerant to suit damage — astronauts will kneel. For short duration missions (Sorties) astronauts can deal with more load and discomfort, so may be a different suit. In Apollo suit there was an environmental protection garment.
EVA system mobility, durability, and environmental protection layer (e.g., dust management)	Needs to include being able to accomplish science objectives.	n/a	Med – Depends on suit requirements and thus design decisions.	High – design suit to have mobility to accomplish science goals; not need maintenance for 40 days (limited by space, spare parts, esc).	High – design suit for repeated (about daily) use over 6mo, and to have mobility required to accomplish science and other field goals; maintenance possible on the station.	Sorbie requirements on the suit are much less, due to ability to maintain it after just "5 EVAs, back on Gateway or Earth, so meeting requirements will result in a different suit; could be designed for long duration use and the community recommends that a long surface duration suit is designed from the beginning. Do science and field operations have similar mobility needs?	This specifically addresses the durability of joints and other mobility-related components.

# AM VI

## **Mars Field Station Technology Impacts**

- Include Nuclear Thermal Propulsion (NTP) in the propulsion trade space, along with SEP-chemical and hybrid architectures, to understand potential performance improvements, such as:
  - Additional mass margin, potentially providing payload capability for additional commercial/international providers
  - Lower transit times
  - Expanded mission abort options
  - Enabling both conjunction and opposition class missions, thereby providing additional architectural flexibility
- Explore reusable Mars ascent vehicle, which
  - Requires exploration of crew size (4 6), number of crew transported per vehicle (2 - 6) and whether or not they are transported at the same time
    - As population size increases, crews will likely not all arrive and depart in the same vehicle at the same time
  - Exploits element reusability where feasible to reduce cost
  - Leverage/encourage development of reusable lunar surface lander and ascent vehicle technology

