

Conjunction Assessment Risk Analysis



Quantifying Shortcomings in the 2-D Pc Calculation

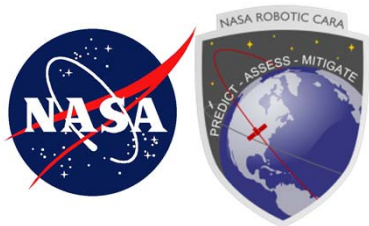
D. Hall, L. Baars, and M. Hejduk

15 NOV 2018



Agenda

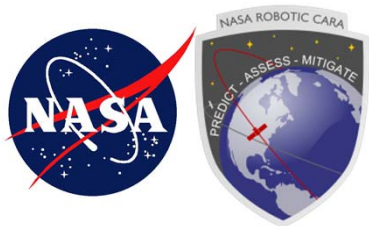
- **Motivation and Objectives**
- **Methodology**
 - Critically examine the three assumptions required for 2D-Pc estimates
- **Analysis**
 - Temporal variations of cumulative Pc and Pc rate
 - Mahalanobis distance variations as an efficient proxy for Pc variations
 - Proposed testing and test statistics for evaluating the viability of 2D-Pc assumptions using Mahalanobis distances
- **Conclusions and Ongoing/Future Work**



Motivation and Objective

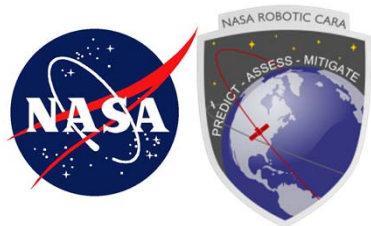
- **Motivation** The probability of collision, P_c , between two Earth-orbiting satellites can often, **but not always**, be approximated adequately using the “2D- P_c ” formulation
- **Objective** Find a set of “boundary conditions” that ensure the 2D- P_c approximation be sufficiently accurate, so that it may be determined when computationally-intensive *Brute Force Monte Carlo*¹ (BFMC) P_c estimates are required

¹D.Hall *et al* “High-Fidelity Collision Probabilities Estimated Using Brute Force Monte Carlo Simulations” AAS 18-244, Aug. 2018



Methodology

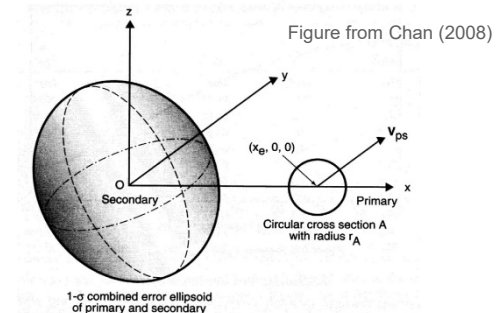
- **Critically examine the assumptions used in the formulation of the 2D-Pc approximation**
 - Assumption 1: During the conjunction, the satellite trajectories can be approximated as linear
 - Assumption 2: During the conjunction, the TCA relative position covariance can be approximated as constant
 - *Ancillary Assumption: The input TCA states and covariances for the primary and secondary satellites are valid*
- **Formulate “2D-Pc boundary condition” tests to check if these assumptions are satisfied adequately**
 - Examine assumptions one at a time, yielding different tests
 - Base the tests on Mahalanobis distances, used here as a computationally-efficient proxy measure



The 2D-Pc Formulation

- **Foster and Estes¹ presented the original 2D-Pc formulation in 1992**

- Through marginalized probability analysis reduces dimension of conjunction
- Performs numerical integration of joint covariance probability density over circular region that represents hard-body radius



- **Akella and Alfriend² used the same assumptions to reformulate the 2D-Pc derivation in 2000, showing that**

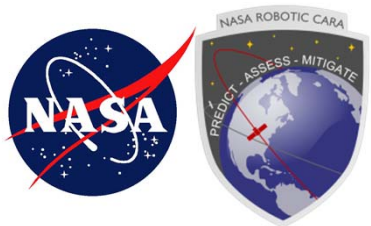
$$P_c = \int_{-\infty}^{+\infty} \dot{P}_c(t) dt$$

- **The probability rate, $\dot{P}_c(t)$, peaks during the conjunction near the time of closest approach (TCA)**

- Exactly at TCA for spherical relative-position uncertainty PDFs
- Offset from TCA for ellipsoidal uncertainty PDFs

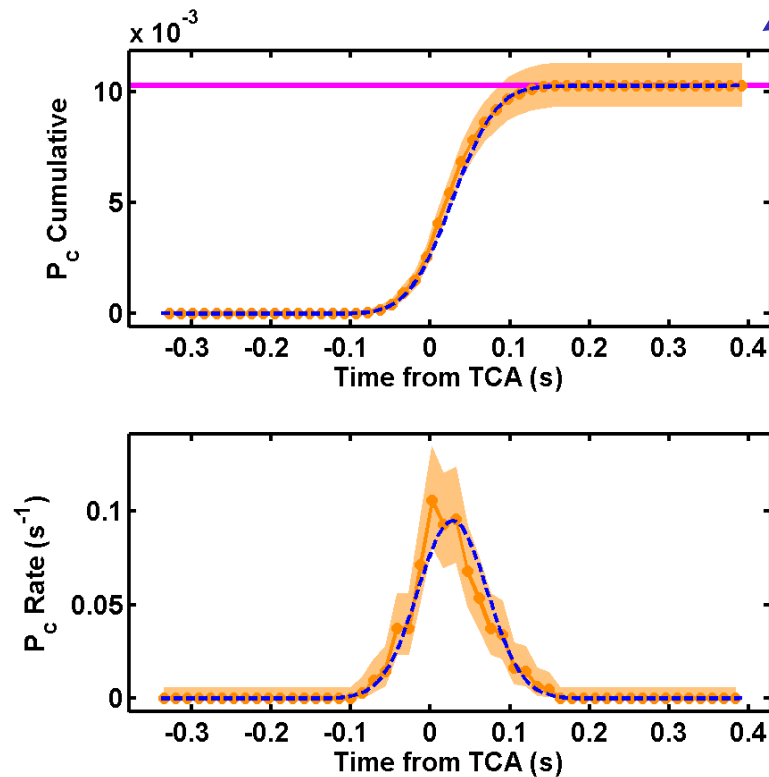
¹J.L. Foster and H.S. Estes, "A Parametric Analysis of Orbital Debris Collision Probability and Maneuver Rate for Space Vehicles," NASA/JSC-25898, Aug. 1992.

²M.R. Akella and K.T. Alfriend, "The Probability of Collision Between Space Objects," *Journal of Guidance, Control, and Dynamics*, Vol. 23, No. 5, pp. 769-772, 2000.



Temporal Risk Analysis Plots for a CARA Conjunction with a Valid 2D-Pc Estimate

Conjunction Duration¹



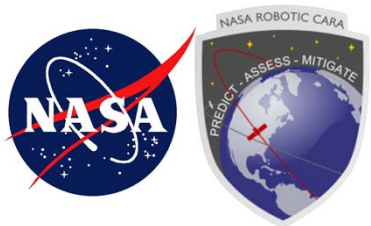
The cumulative collision probability grows during the event up to the overall Pc value for the conjunction

27424_conj_26294_20171016_153343_20171013_060918
HBR=20m

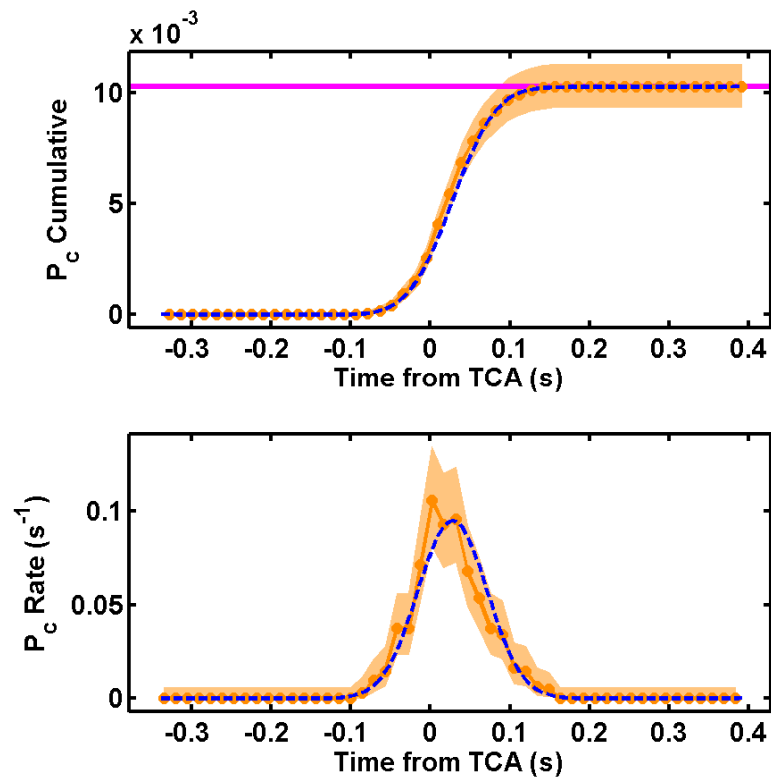
- Foster & Estes (1992) $P_c = 0.0102813$
- - - Akella & Alfriend (2000) $P_c = 0.0102813$
- BFMC CDM mode ($N_s = 4.2e4$) $P_c = 0.0103$
- BFMC 95% confidence $9.4e-3 \leq P_c \leq 0.0113$

The probability rate, $\dot{P}_c(t)$, peaks during the conjunction, at a time that can be offset from the TCA

¹V.Coppola “Evaluating the Short Encounter Assumption of the Probability of Collision Formula” AAS 12-247, Feb. 2012



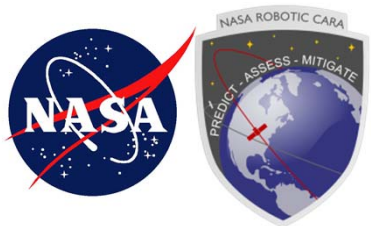
Well-Behaved 2-D Pc Conjunction: Temporal Analysis Curves



27424_conj_26294_20171016_153343_20171013_060918
HBR=20m

- Foster & Estes (1992) $P_c = 0.0102813$
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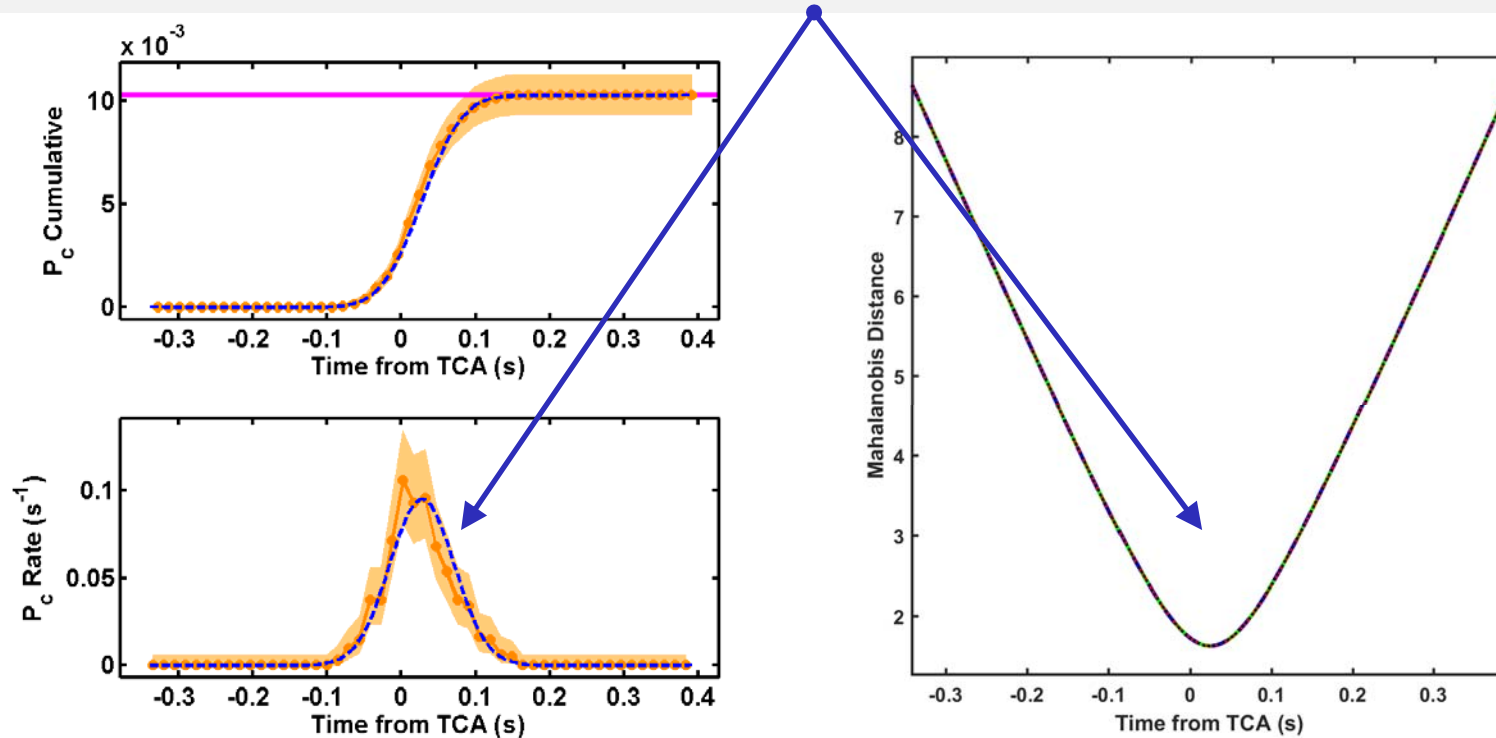
**Example conjunction with
valid 2D-Pc estimate**



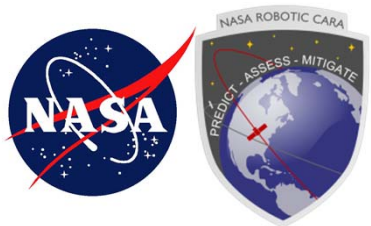
Mahalanobis Distance Time-History Plots

$\dot{P}_c(t)$ peaks very close to the time that the relative-position Mahalanobis distance reaches its minimum value¹

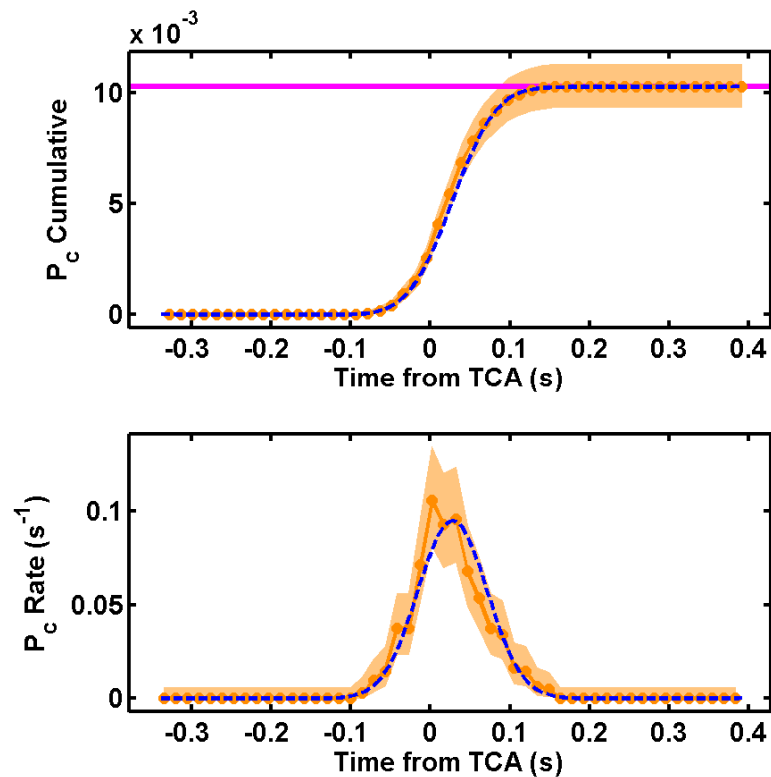
$$\mathbf{r} = \mathbf{r}_2 - \mathbf{r}_1 \quad \text{MD}(t) = (\mathbf{r} - \bar{\mathbf{r}})^T \mathbf{C}^{-1} (\mathbf{r} - \bar{\mathbf{r}})$$



¹D.Hall *et al* "Time Dependence of Collision Probabilities During Satellite Conjunctions" AAS 17-271, Feb. 2017

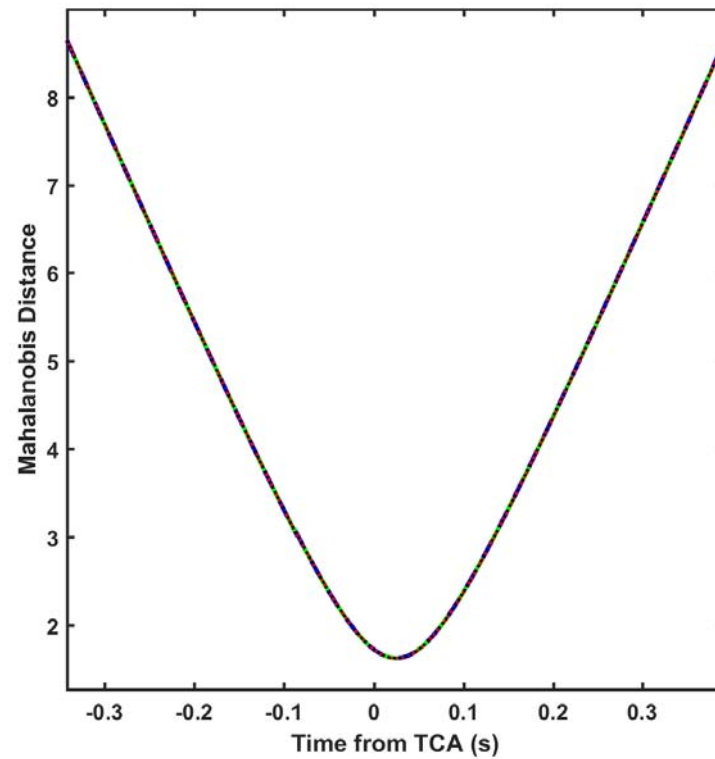


Well-Behaved 2-D Pc Conjunction: Alignment of Mahalanobis Distance Curves

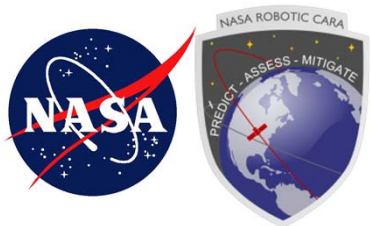


- Linear motion, zero vel.uncertainty, no eq.cov. remediation
- Linear motion, zero vel.uncertainty, eq.cov. remediation
- Linear motion, non-zero vel.uncertainty, no eq.cov. remediation
- Two-body motion, zero vel.uncertainty, no eq.cov. remediation

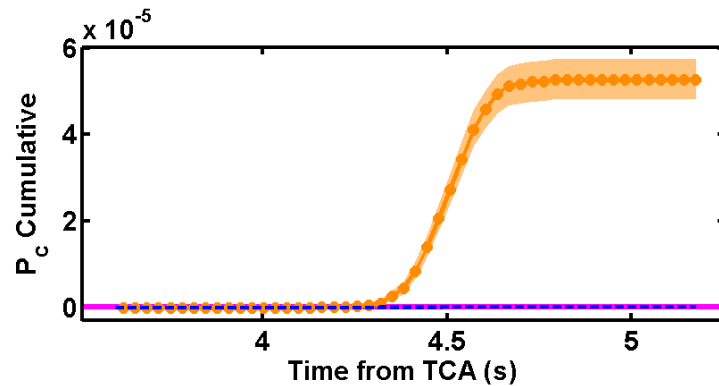
27424_conj_26294_20171016_153343_20171013_060918



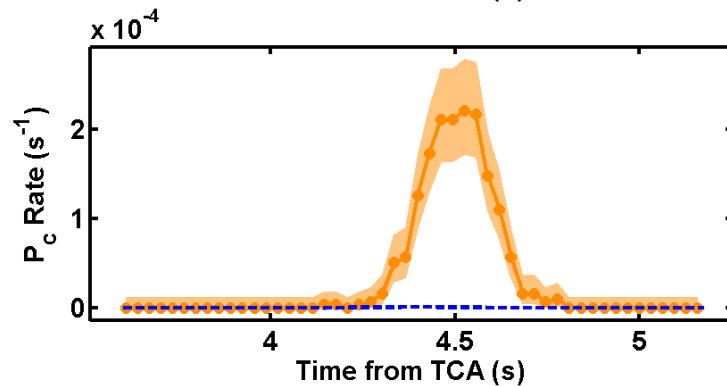
**No significant
Mahalanobis distance
differences**



Large Velocity Covariance Situation: $BFMC-P_c \approx 300 \times 2D-P_c \gg 2D-P_c$

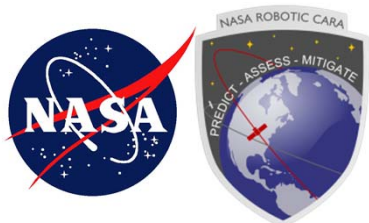


38753_conj_35072_20171016_000431_20171008_001641
 HBR=52.84m

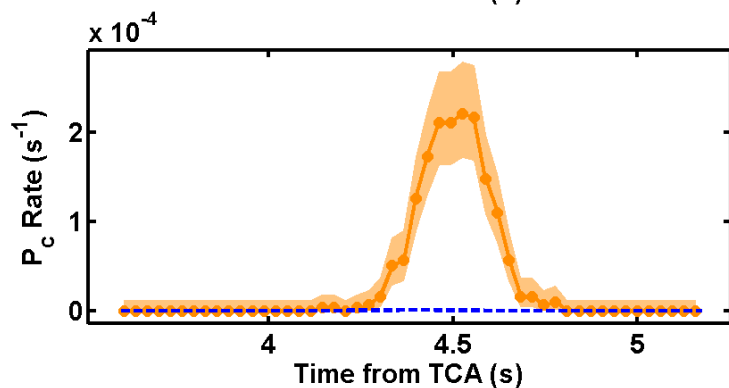
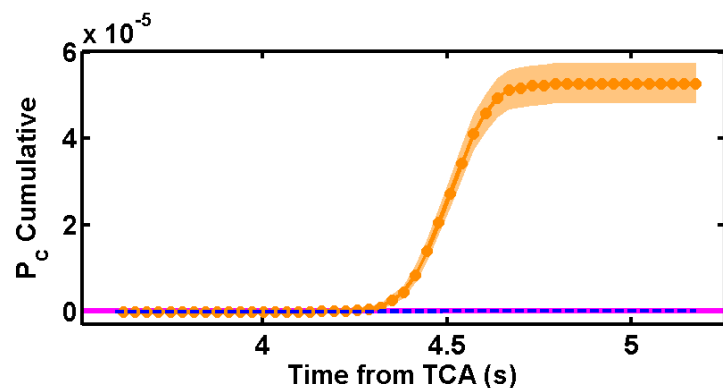


- Foster & Estes (1992) $P_c = 1.56839e-7$
- - - Akella & Alfriend (2000) $P_c = 1.56839e-7$
- BFMC CDM mode ($N_s=1e7$) $P_c = 5.27e-5$
- BFMC 95% confidence $4.83e-5 \leq P_c \leq 5.74e-5$

**Example conjunction with
 invalid 2D- P_c estimate**



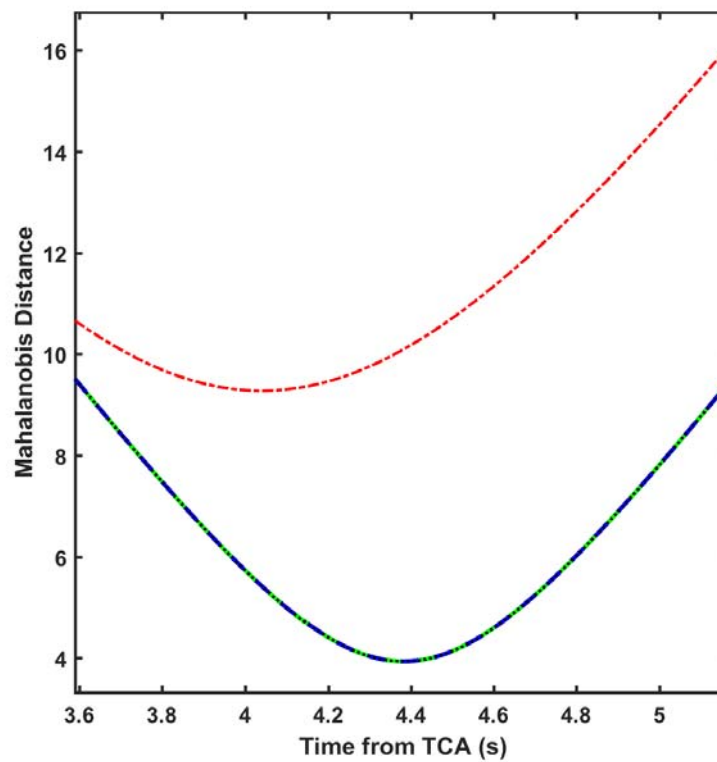
Large Velocity Covariance Situation: Mahalanobis Distance Curve Divergence



**Mahalanobis distance
minimum is shifted**

- Linear motion, zero vel.uncertainty, no eq.cov. remediation
- Linear motion, zero vel.uncertainty, eq.cov. remediation
- Linear motion, non-zero vel.uncertainty, no eq.cov. remediation
- ⋯ Two-body motion, zero vel.uncertainty, no eq.cov. remediation

38753_conj_35072_20171016_000431_20171008_001641





Mahalanobis Distance Minimum Shift: Proposed Test Statistics

- 1st M-Distance shift indicator:
 $VIa = |\Delta MD1| \ll a$ (perhaps 1)

- 2nd M-Distance shift indicator:

$$VIb = \left| \frac{\Delta t(\text{offset})}{\Delta t(1\sigma \text{ width})} \right| \ll a$$

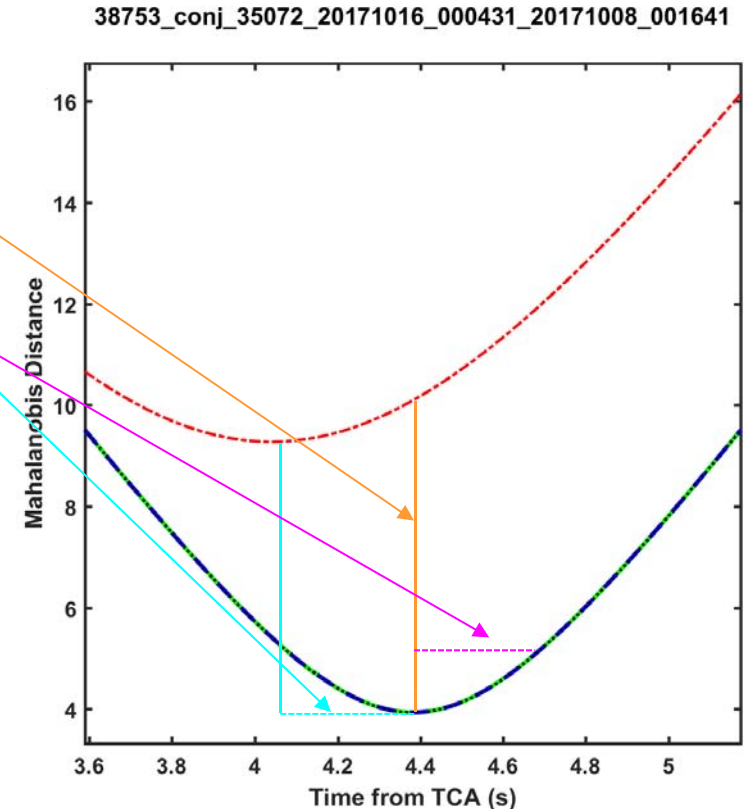
Combined M-Distance Shift Test:

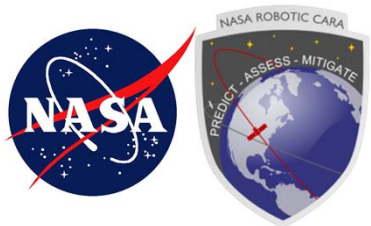
$$VI = \max(VIa, VIb) \ll a$$

⇒

2D-Pc approximation is not adversely affected by velocity covariances

- Linear motion, zero vel.uncertainty, no eq.cov. remediation
- Linear motion, zero vel.uncertainty, eq.cov. remediation
- - - Linear motion, non-zero vel.uncertainty, no eq.cov. remediation
- Two-body motion, zero vel.uncertainty, no eq.cov. remediation



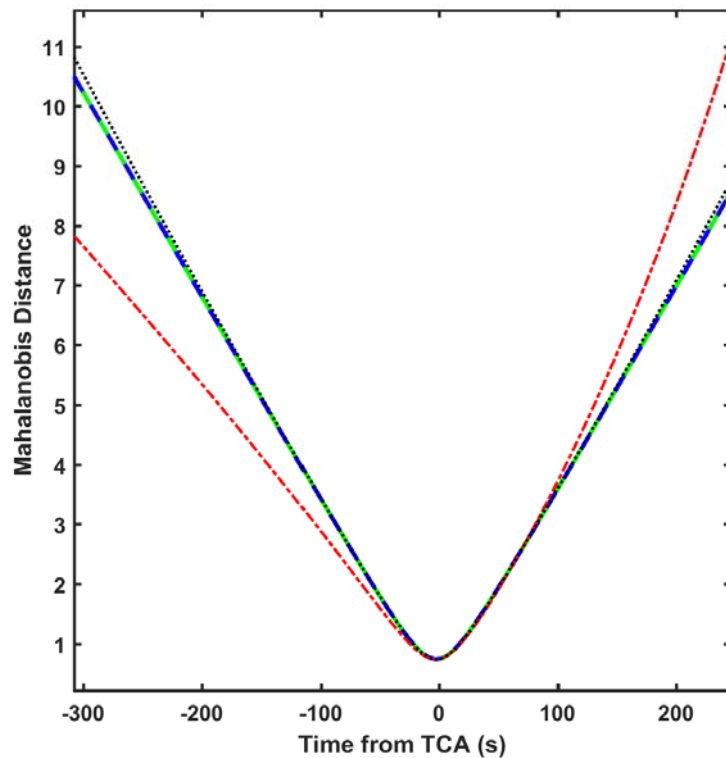


Mahalanobis Distance Differences: Long-Duration and Repeating Conjunctions

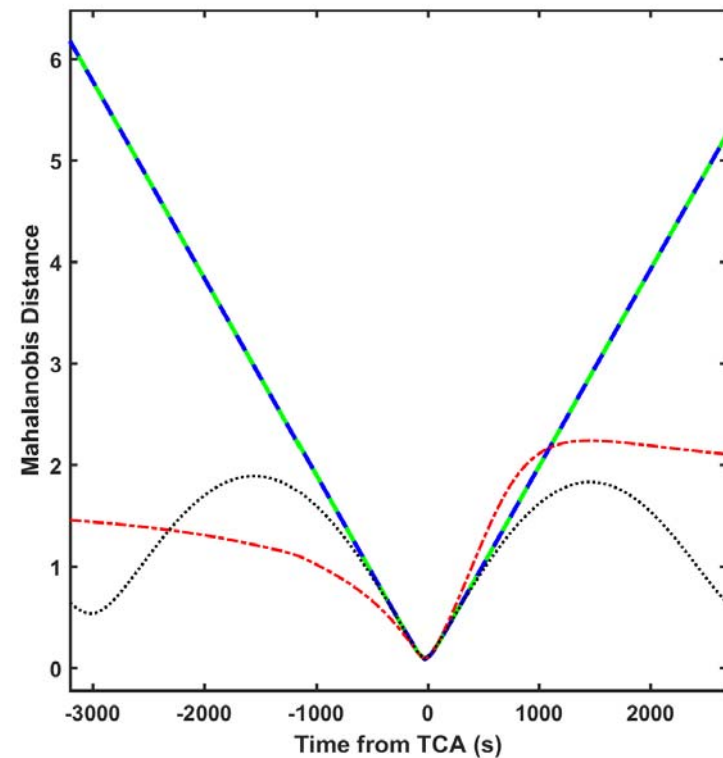
- Linear motion, zero vel.uncertainty, no eq.cov. remediation
- Linear motion, zero vel.uncertainty, eq.cov. remediation
- - - Linear motion, non-zero vel.uncertainty, no eq.cov. remediation
- Two-body motion, zero vel.uncertainty, no eq.cov. remediation

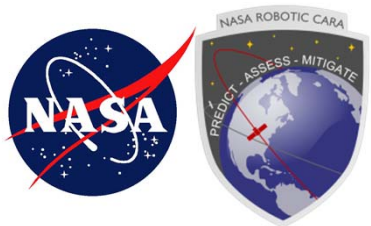
- Linear motion, zero vel.uncertainty, no eq.cov. remediation
- Linear motion, zero vel.uncertainty, eq.cov. remediation
- - - Linear motion, non-zero vel.uncertainty, no eq.cov. remediation
- Two-body motion, zero vel.uncertainty, no eq.cov. remediation

43127_conj_43130_20180118_074826_20180118_001047



39208_conj_39357_20170501_182817_20170501_062324





Mahalanobis Distance Curve Alignment: Proposed Test Statistics

- 1st M-curve divergence indicator:

$$V2a = |\Delta AMD| \ll q$$

- 2nd M-curve divergence indicator

$$V2b = |\Delta AMD| \ll q$$

Combined divergence test:

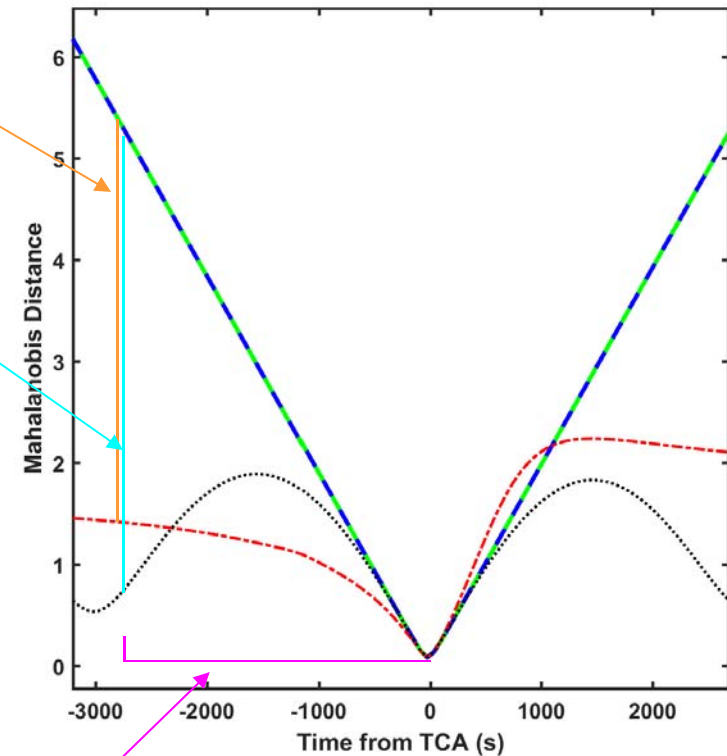
$$V2 = \max(V2a, V2b) \ll q$$

⇒

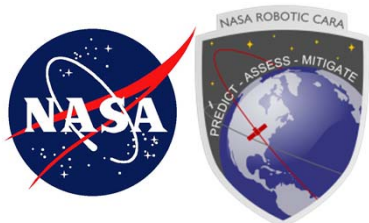
2D-Pc approximation is not adversely affected by velocity covariances or rectilinear motion assumption

- Linear motion, zero vel.uncertainty, no eq.cov. remediation
- Linear motion, zero vel.uncertainty, eq.cov. remediation
- - - Linear motion, non-zero vel.uncertainty, no eq.cov. remediation
- Two-body motion, zero vel.uncertainty, no eq.cov. remediation

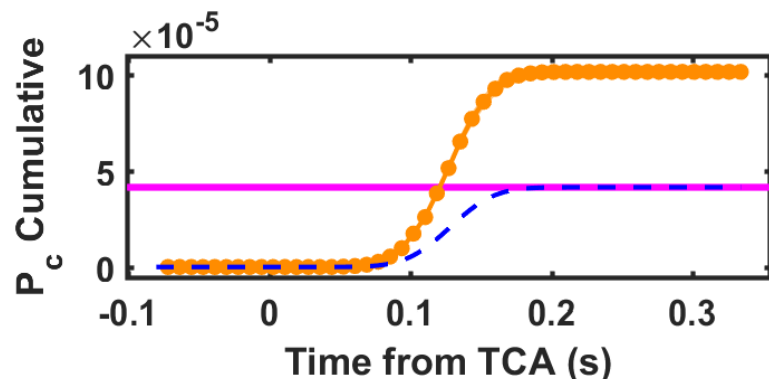
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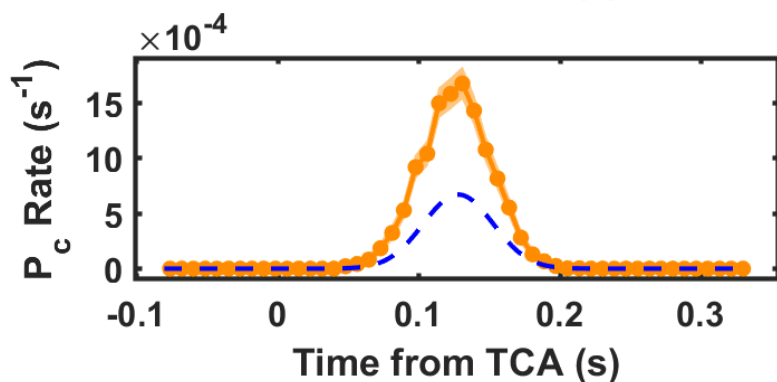
Coppola Conjunction Boundary



Non-Positive-Definite Covariance Event: BFMC- $P_c \approx 2.4 \times 2DP_c$

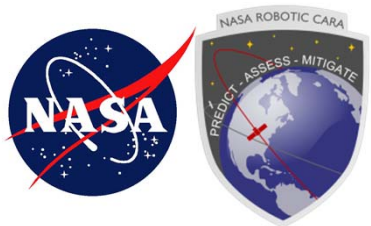


25338_conj_30266_20171213_215907_20171208_161008
HBR=7m MissDistance=1796.1m VelocityAngle=19.6°



- Foster & Estes (1992) $P_c = 4.15084e-5$
- - Akella & Alfriend (2000) $P_c = 4.15084e-5$
- BFMC CDM mode ($N_s = 4e7$) $P_c = 1.015e-4$
- BFMC 95% confidence $9.84e-5 \leq P_c \leq 1.047e-4$

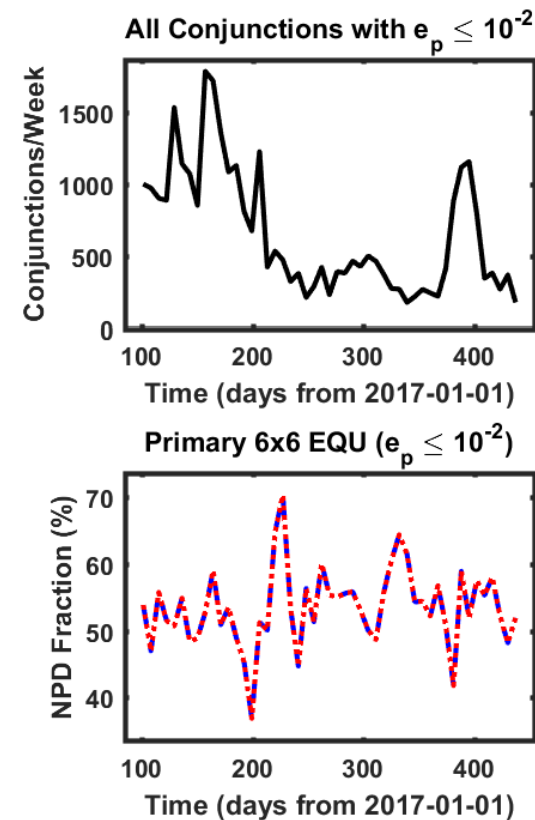
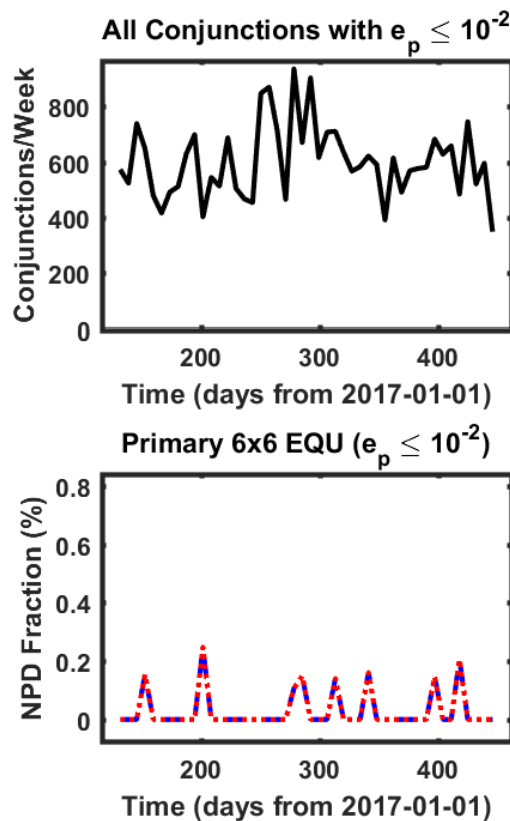
**Example conjunction with
invalid 2D- P_c estimate;
difference introduced by
remediating NPD condition**

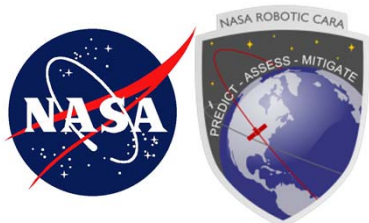


Frequency of NPD TCA Equinoctial States

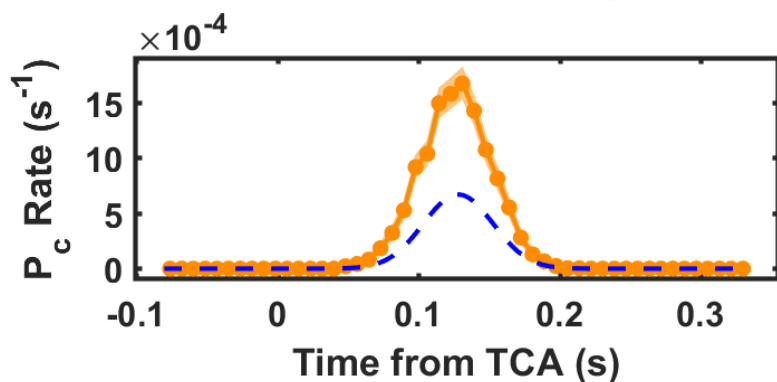
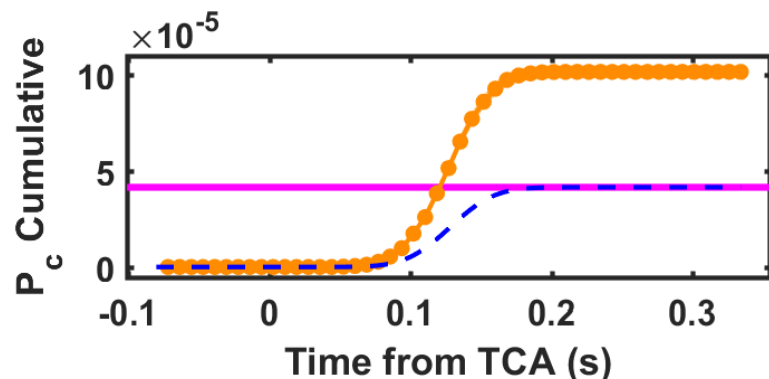
CARA Conjunction Data
 ~28,000 events with $2DPc > 1e-7$
 (from high-precision CDMs)

SSPAT Low Rel. Velocity Data
 ~32,000 events with $2DPc > 1e-7$
 (from low-precision CDMs)



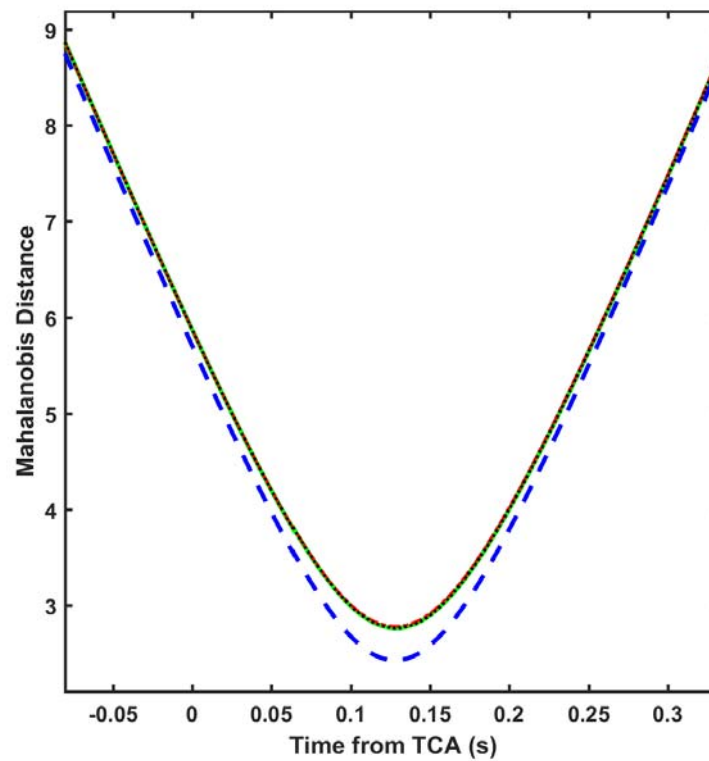


Non-Positive-Definite Covariance Event: Mahalanobis Distance Curve Alignment



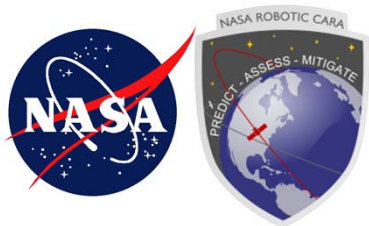
- Linear motion, zero vel.uncertainty, no eq.cov. remediation
- - Linear motion, zero vel.uncertainty, eq.cov. remediation
- - Linear motion, non-zero vel.uncertainty, no eq.cov. remediation
- Two-body motion, zero vel.uncertainty, no eq.cov. remediation

25338_conj_30266_20171213_215907_20171208_161008



Mahalanobis distance differences caused by NPD TCA equinoctial state covariances





Conclusions

- **2D-Pc boundary condition metrics can be developed to test the three assumptions used in the 2D-Pc formulation**
 - 1) Linear trajectories
 - 2) Constant covariances
 - 0) *Valid input data*
- **Proposed boundary condition metrics based on Mahalanobis distances (MD) variations**
 - Examine MD differences that occur when invoking/relaxing the three assumptions one at a time: $\{\Delta MD_1, \Delta MD_2, \Delta MD_3\}$
 - Conjunctions with small MD differences fall within the 2D-Pc boundaries:
Max(ΔMD_n) $\ll 1$ → 2D-Pc is reliably accurate
Otherwise → 2D-Pc is potentially inaccurate
 - Tests thus identify 2D-Pc failure candidates but also capture cases in which 2-D Pc is acceptable calculation
- **Ongoing and Future Work:**
 - Set test thresholds for producing acceptable Pmd and Pfa levels
 - Final results to be published next year
 - Reinforce fact that some Monte Carlo necessary for Pc calculation