



Mars 2020 Entry, Descent, and Landing Instrumentation 2 (MEDLI2)

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June 2016 AIAA AVIATION



Outline



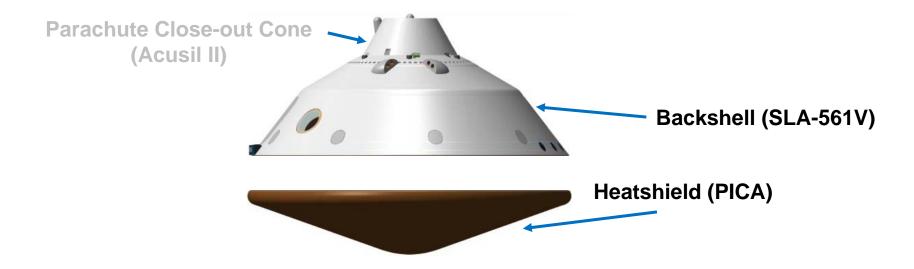
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 - Heat Flux Sensors and Radiometer
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Background: Mars 2020 Entry Vehicle



- The Mars 2020 Entry, Descent, and Landing Instrumentation 2 (MEDLI2) is the EDL sensor suite for the flagship-class Mars 2020 mission
- The Mars 2020 mission is a rover mission utilizing investments in Mars Science Laboratory (MSL) technologies
 - The entry vehicle, including the heatshield, is nearly "build to print"
 - Entry environments will be similar, if not more benign, than for MSL





MEDLI2 Science Goals

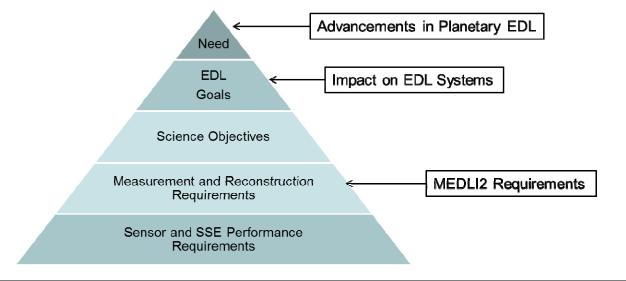


MEDLI2 goals are to acquire flight data, in order to:

- Define entry aerothermal environments and reduce aerothermal uncertainties
- Reduce entry vehicle thermal protection system (TPS) mass
- Improve future aerocapture and EDL performance

MEDLI2 science objectives are to:

- Reduce design margins and prediction uncertainties for aerothermal environments and TPS response
- Reduce uncertainty and enable validation of the aerodynamic database





MEDLI2 Science Objectives/Requirements



Aerothermal and TPS:

- Reconstruct forebody aerothermal heating
- Determine forebody TPS temperatures
- Reconstruct aftbody aerothermal heating
- Measure aftbody heat flux

Aerodynamics and Atmosphere:

- Reconstruct hypersonic and supersonic aerodynamic axial force coefficient
- Reconstruct wind relative vehicle attitude
- Reconstruct atmospheric density and winds
- Reconstruct vehicle Mach number





MEDLI2 Expands Scope of Instrumentation



MEDLI on MSL (2012)



7 Hypersonic Pressure Transducers



7 Instrumented Plugs

- 4 Thermocouples
- 1 HEAT sensor



1 Sensor Support Electronics Box

MEDLI2 on Mars 2020



Pressure Transducers: 1 Hypersonic, 6 Supersonic, and 1 Backshell



11 Instrumented PICA Plugs



6 Instrumented SLA Plugs



3 Heat Flux Gauges (including 1 Radiometer)



1 Sensor Support Electronics Box

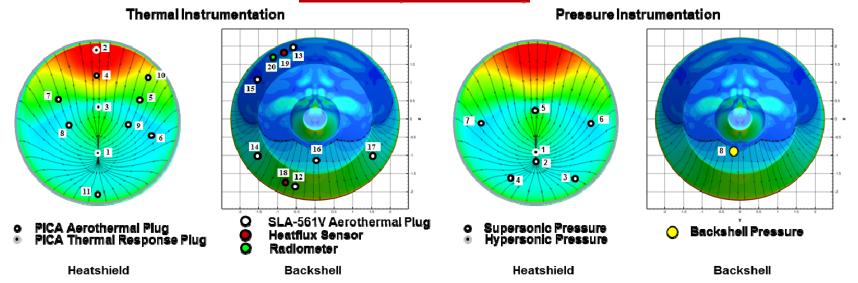


MEDLI2 Instrumentation Layout





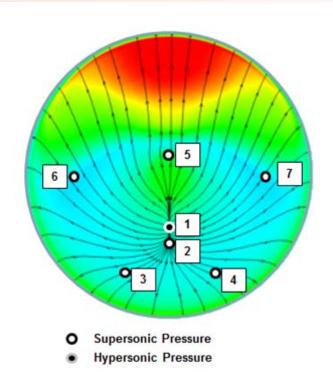
MEDLI2 (Mars 2020)





MEDLI2 Forebody Pressure Measurement





- One pressure transducer to measure stagnation point pressure during hypersonic flight for reconstruction of atmospheric density, and C_A
 - MEDLI flight spare
 - Target range: 1650 Pa 35 kPa
 - Target accuracy: 1% of reading
- Six pressure transducers measure surface pressure in the range relevant for supersonic flight
 - Target range: 650 Pa 7 kPa
 - Target accuracy: 1% of reading
- The supersonic port locations are based on a constrained-optimization process to minimize error in the reconstruction of angles of attack and side-slip



Supersonic Pressure Sensor Proof-of-Concept







Driving requirement:

- Heatshield during cruise phase estimated to be as low as -130 °C
- No commercially availably sensor can withstand the temperature range required

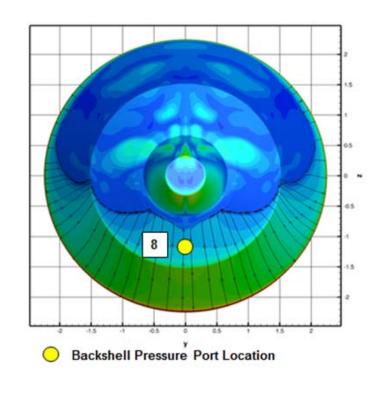
Proof of concept sensor constructed

- Disassemble and remove foil-backed strain gauge
- Replace with COTS semiconductor piezoresistive unit
- 12-point calibration conducted
- Gain of more than 60 times of effective output signal compared to unmodified sensor
- Based on this concept, custom sensors will be assembled for flight
- Extensive testing and calibration scheduled for later this year



MEDLI2 Aftbody Pressure Measurement





Science Objectives:

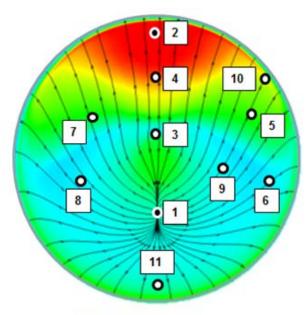
- Improve backshell pressure model
- Estimate backshell contribution to drag
- One pressure sensor in the afterbody
 - Target Range: 40 700 Pa
 - Target Accuracy: 4 Pa
- The current port location is defined based on available wind tunnel data and CFD analysis
- Further refinement of the location will occur based on the results of recently completed ballistics range test

From: John Van Norman



MEDLI2 Forebody Thermal Instrumentation





- O PICA Aerothermal Plug
- PICA Thermal Response Plug

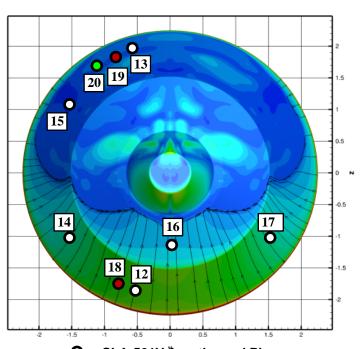


- Science objectives: Measure baseline heating, transition to turbulence, and turbulent heating footprint
- Forebody thermal instrumentation includes 11 PICA plugs with embedded thermocouples
 - Three plugs (1-3) with three thermocouples each to measure in-depth thermal response
 - Eight plugs (4-11) with one thermocouple for aerothermal reconstruction
- A combination of Type R and Type K TCs
 - Near surface:
 - Type R: -50 to 1480 °C, for depths < 0.1 inches
 - Target Accuracy: ±15 W/cm²
 - In-depth:
 - Type K: -270 to 1260 °C, for depths ≥ 0.1 inches
 - Target Accuracy: ±50 °C



MEDLI2 Aftbody Thermal Instrumentation





- SLA-561V Aerothermal Plug
- Heatflux Sensor
- Radiometer



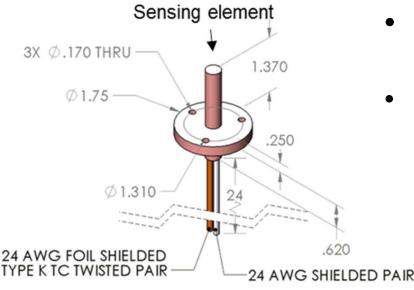


- Science objectives:
 - Aeroheating (both reconstructed and direct measurement)
 - Measure radiative vs. total heating
- Aftbody instrumentation includes 6 SLA-561V thermal plugs, 2 heat flux gauges, and 1 radiometer
- Each plug will have 1 or 2 Type K thermocouple for aerothermal reconstruction
 - Range: -270 to 1260 °C
 - Target Accuracy: ±3 W/cm²
- Heat flux gauges will directly measure total heating
 - Target Range: 0 15 W/cm²
 - Target Accuracy: ±1 W/cm²
 - Radiometer will measure radiative heating at location predicted to be have peak radiative component
 - Target Range: 0 15 W/cm²
 - Target Accuracy: ±1 W/cm²



Heat Flux Sensors and Radiometer





- Heat flux sensors and radiometer are Schmidt-Boelter gauges
- Radiometer is a heat flux sensor with a sapphire window at the sensing element tip
 - Sapphire blocks convective heating component
- Wide view angle (-150°) combined with highly radiating aftbody flowfield will lead to substantial signal
 - Sapphire window optical properties will be measured
 - Deposition of ablation products on window may alter readings—how large is this effect?



Reconstruction Targets



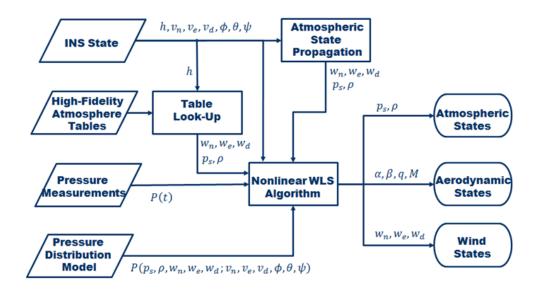
Quantity of Interest	Reconstruction Target	Relevant Sensors
Forebody Reconstructed Heating	$\pm 15 \text{ W/cm}^2$	Forebody Thermocouples
Boundary Layer Transition	±1 second	Forebody Thermocouples
In-depth Temperatures	±50 °C	Forebody Thermocouples
Aftbody Reconstructed Heating	$\pm 3 \text{ W/cm}^2$	Aftbody Thermocouples
Aftbody Heat Flux	$\pm 1 \text{ W/cm}^2$	Heat Flux Sensor/Radiometer
Axial Force Coefficient	±2%	All Pressure Transducers
Vehicle Attitude	±0.5 degrees	Supersonic Pressure Transducers
Atmospheric Winds	±10 m/s	Supersonic Pressure Transducers
Atmospheric Density	±5%	Forebody Pressure Transducers
Mach Number	±0.1	Forebody Pressure Transducers
Aftbody Pressure	±4 Pa	Aftbody Pressure Transducer

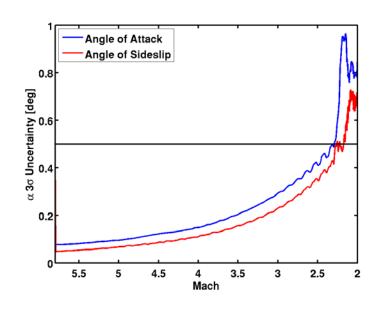


Pressure Measurements Reconstruction Methodology



- Algorithm is a weighted, least-squares (WLS) method to calculate bestfit estimates of atmospheric conditions based on inertial state of vehicle and a model of surface pressure
- Linear covariance tool maps input uncertainties to nonlinear WLS algorithm to output uncertainties
 - Predicts ability to meet science requirements for accuracy for angle of attack, density, Mach number, wind states, etc.







Thermal Measurements Reconstruction Methodology



- Similar to MEDLI, plan is to utilize inverse techniques to reconstruct surface heating
 - Whole-time domain least squares method that minimizes the sum of squared differences between TC data and predicted temperatures
 - For MEDLI, surface chemistry calculations could not be included due to inaccuracies of the PICA equilibrium gas-surface chemistry model. Surface heating estimates assumed no recession
- Improvements to reconstruction methods include:
 - Finite-rate chemistry model for PICA in CO₂ (developed by NASA's Entry System Modeling project) to estimate surface film coefficient as a function of time
 - Characterization of variations in material properties in flight-lot PICA to better estimate heating (e.g., thermal conductivity)
 - Merging multiple data sources for heating reconstruction in order to incorporate heat flux sensor measurements



Summary (and some parting thoughts)



- MEDLI2 builds upon the success of MEDLI, and extends the scope of measurements significantly
 - Aftbody measurements (pressure, near-surface thermal, direct heat flux, radiation)
 - Supersonic pressure measurements
 - Increased number of forebody thermal near-surface measurements
- Reducing the design margins for future Mars missions will continue to be critical
 - For small robotic missions, every kg counts, and being able to shave a few kg from the aftbody can result in increased delivered payload
 - For human-scale missions, every kg counts, plus robustness is also an issue. Being able to predict how the entry vehicle will perform with greater accuracy will be necessary
- With a successful Mars 2020 mission, MEDLI2 will be able to impact future Mars missions by reducing margins, improving models, with a better understanding of the uncertainties and risk





Questions?