



Earth-Based Analogs & Modeling for Exercise Biomechanics in Space


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- **University Collaboration**
- **Digital Astronaut Simulation**
- **Experimental Study**
- **Results & Takeaways**
- **Next Steps**

A composite space scene. On the left, a lunar lander with two bright lights and a yellow flag is on the surface of the Moon. In the center, the Earth is visible as a small orange and red sphere. On the right, the Moon is shown as a large, detailed grey sphere. At the bottom right, the International Space Station (ISS) is orbiting Earth, with its complex structure and solar panels clearly visible against the blue and white horizon of the planet.

University Collaboration

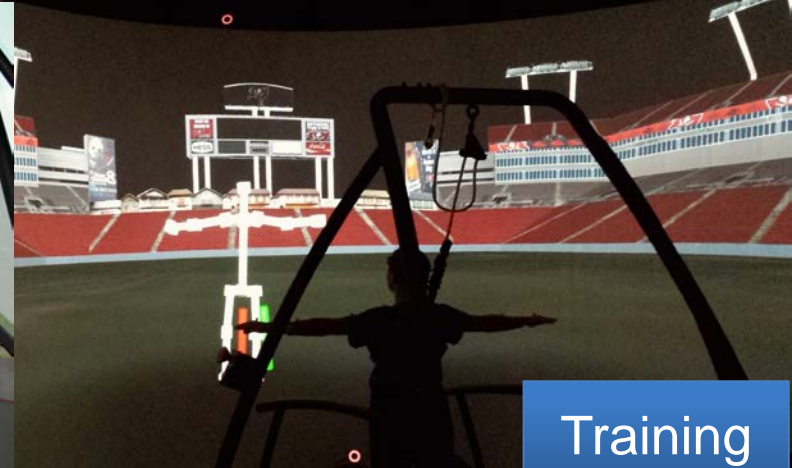
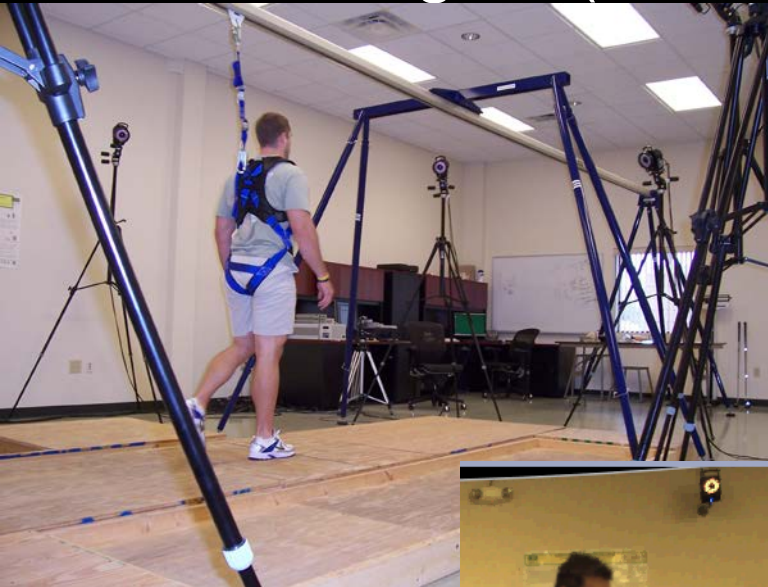
Digital Astronaut Simulation

Experimental Study

Results & Takeaways

Next Steps

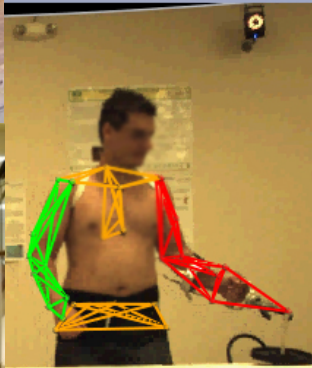
Center for Assistive, Rehabilitation & Robotics Technologies (CARRT) @ USF



Training

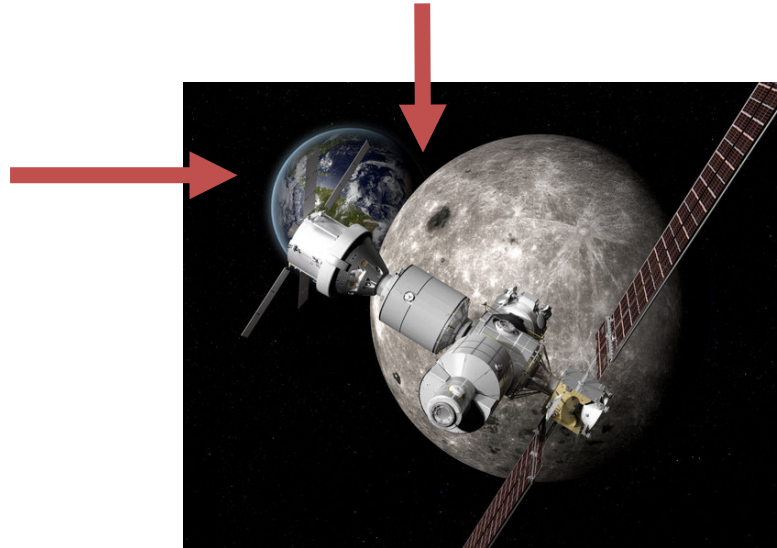


Human-Robot Interaction



Performance & Physical Rehabilitation

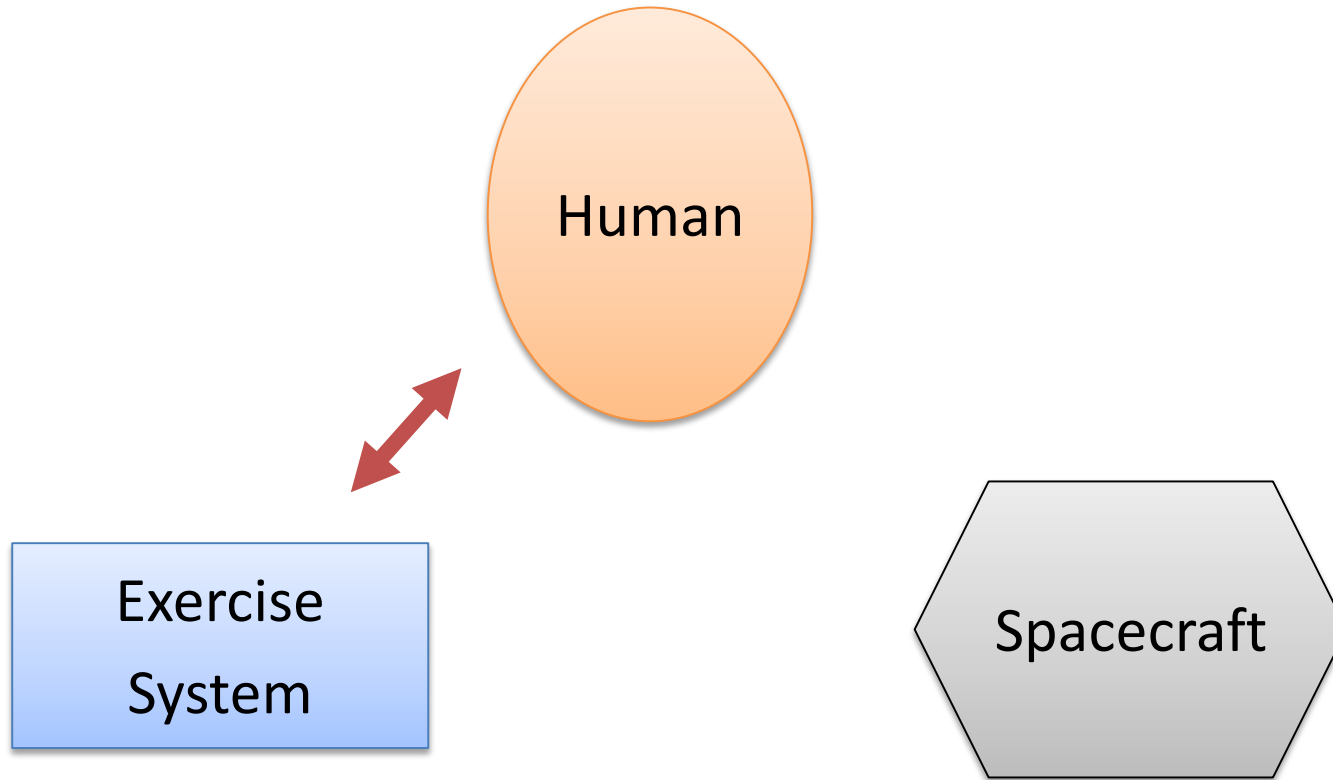
NASA Space Technology Research Fellowship (NSTRF17)



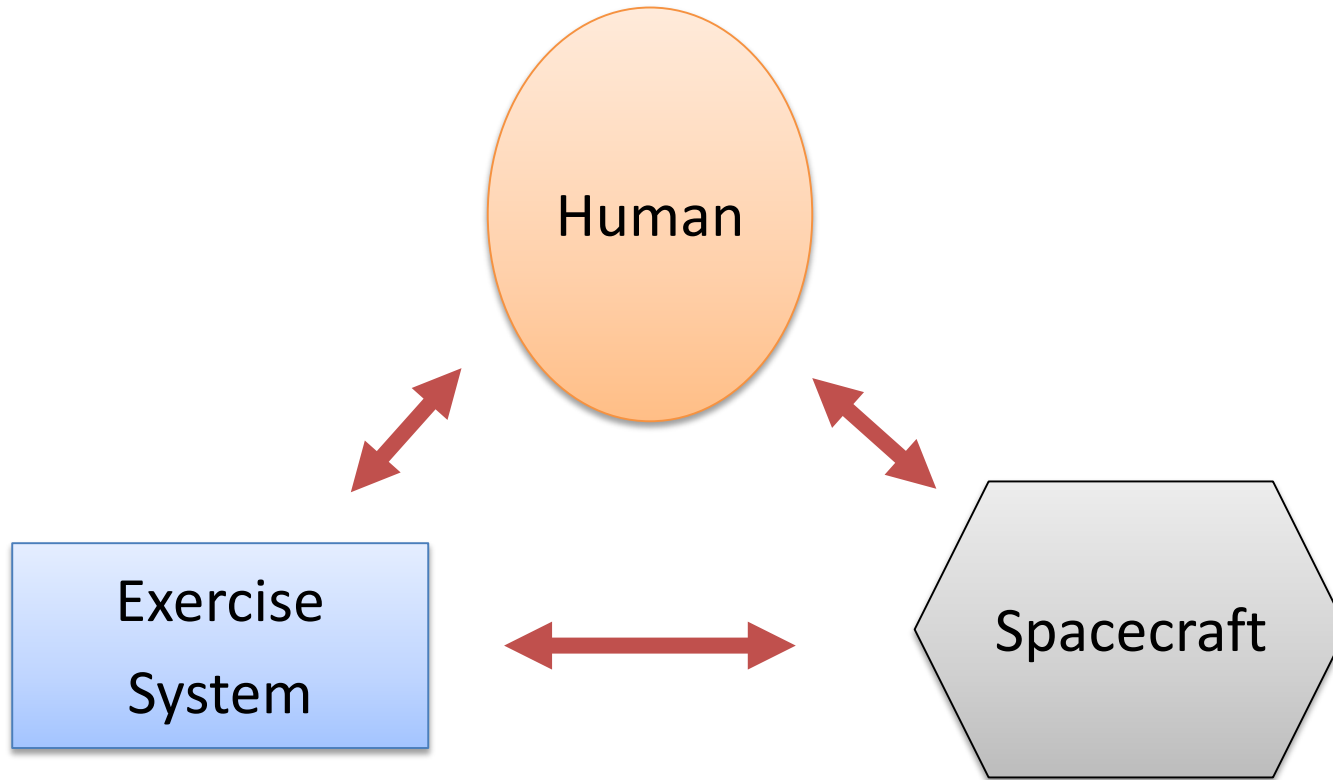
A detailed space simulation background. On the left, a portion of a grey, cratered celestial body is visible. In the center, a small satellite with a yellow antenna and solar panels is illuminated. To its right, the reddish-orange planet Mars is visible. In the upper right, the full, bright white moon is shown. In the lower right, the blue and white horizon of Earth is visible with the International Space Station (ISS) orbiting. The background is a dark field of stars and a faint grid pattern.

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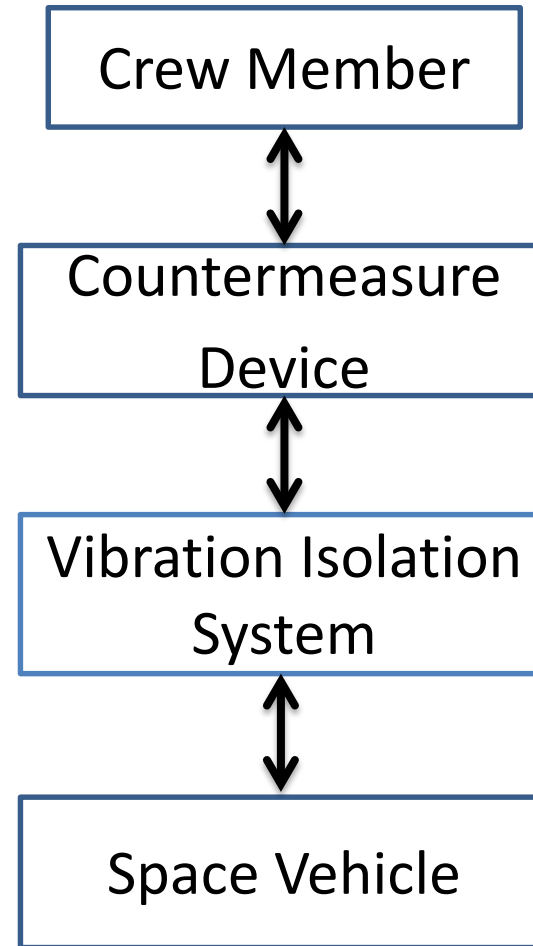
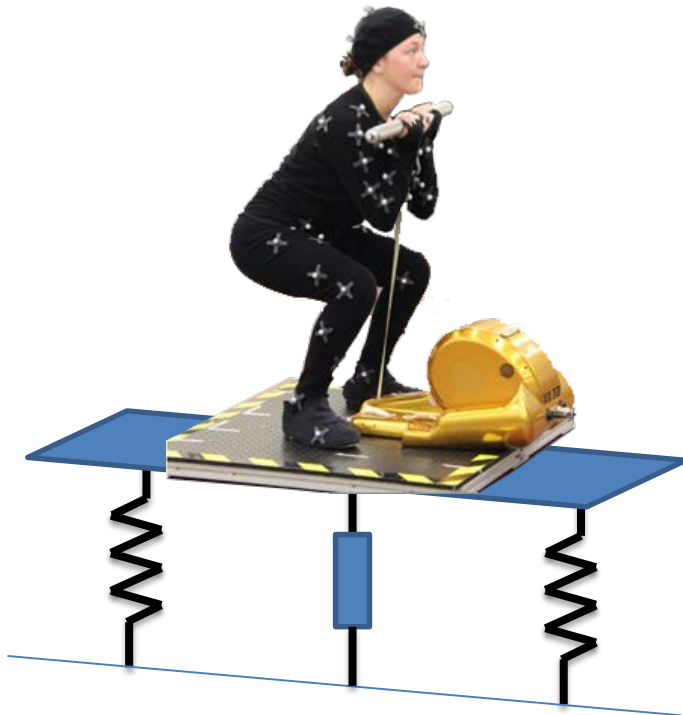
Digital Astronaut Simulation (DAS)



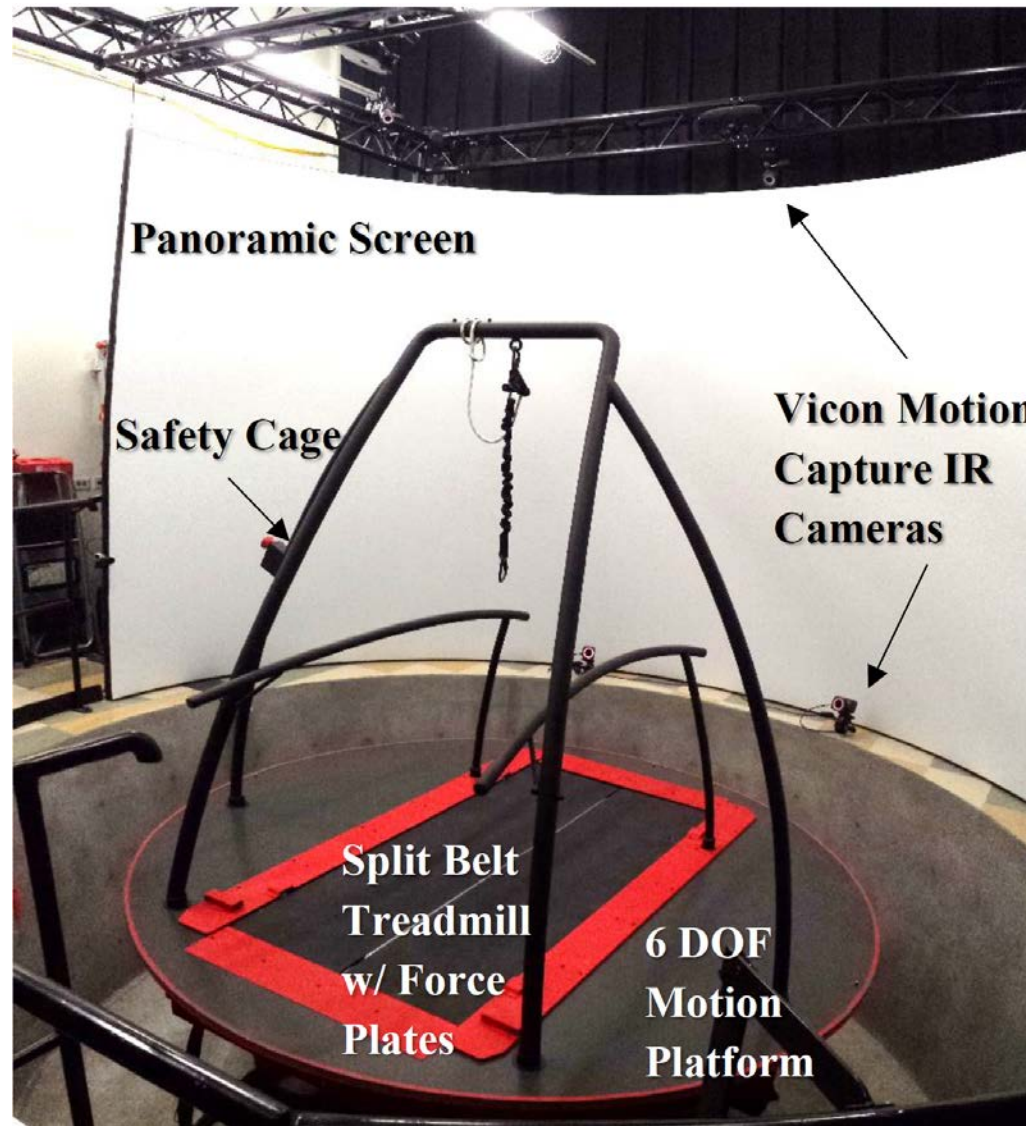
Digital Astronaut Simulation (DAS)



Vibration Isolation System (VIS)



Computer Assisted Rehabilitation Environment (CAREN) @ USF





University Collaboration
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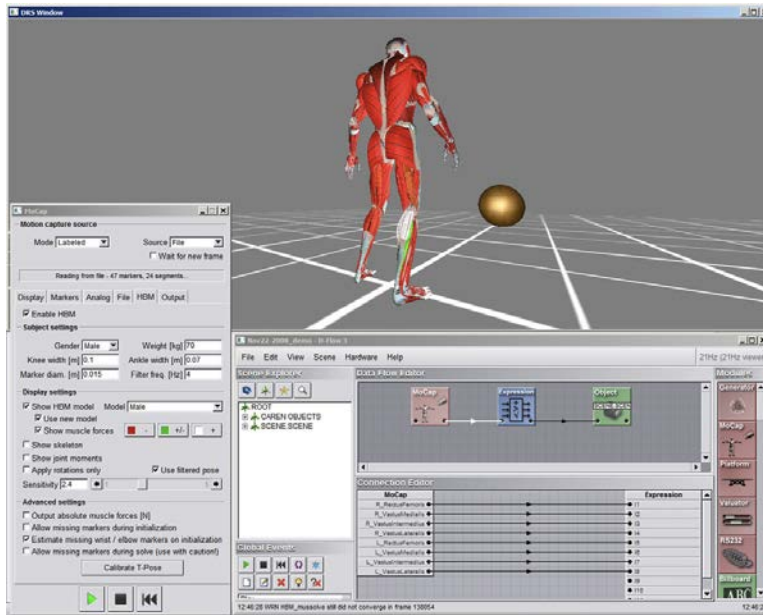


Computer Assisted Rehabilitation Environment (CAREN) @ USF

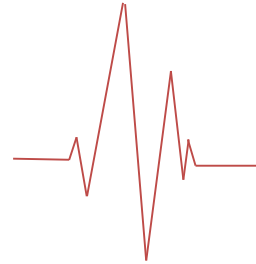


Human Body Model

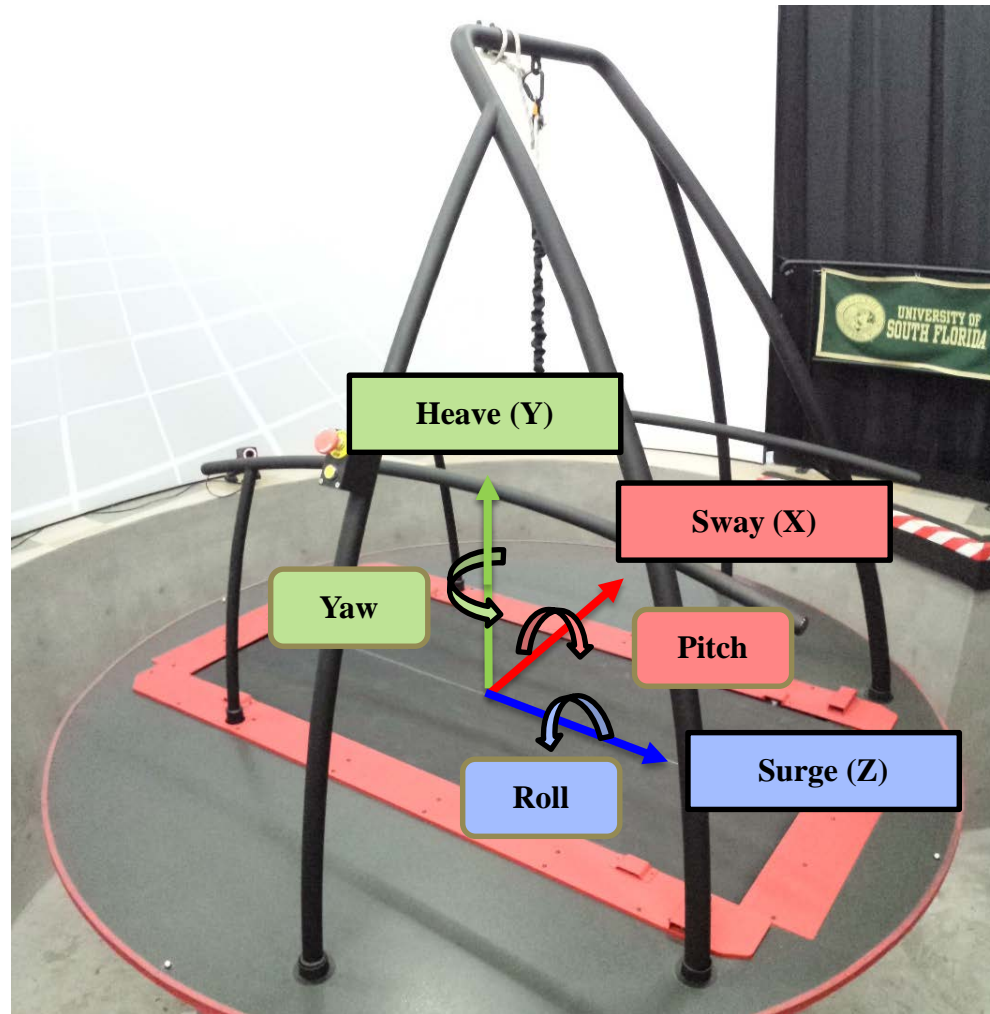
van den Bogert, A.J., Geijtenbeek, T., Even-Zohar, O. et al. A real-time system for biomechanical analysis of human movement and muscle function. Med Biol Eng Comput (2013) 51: 1069.



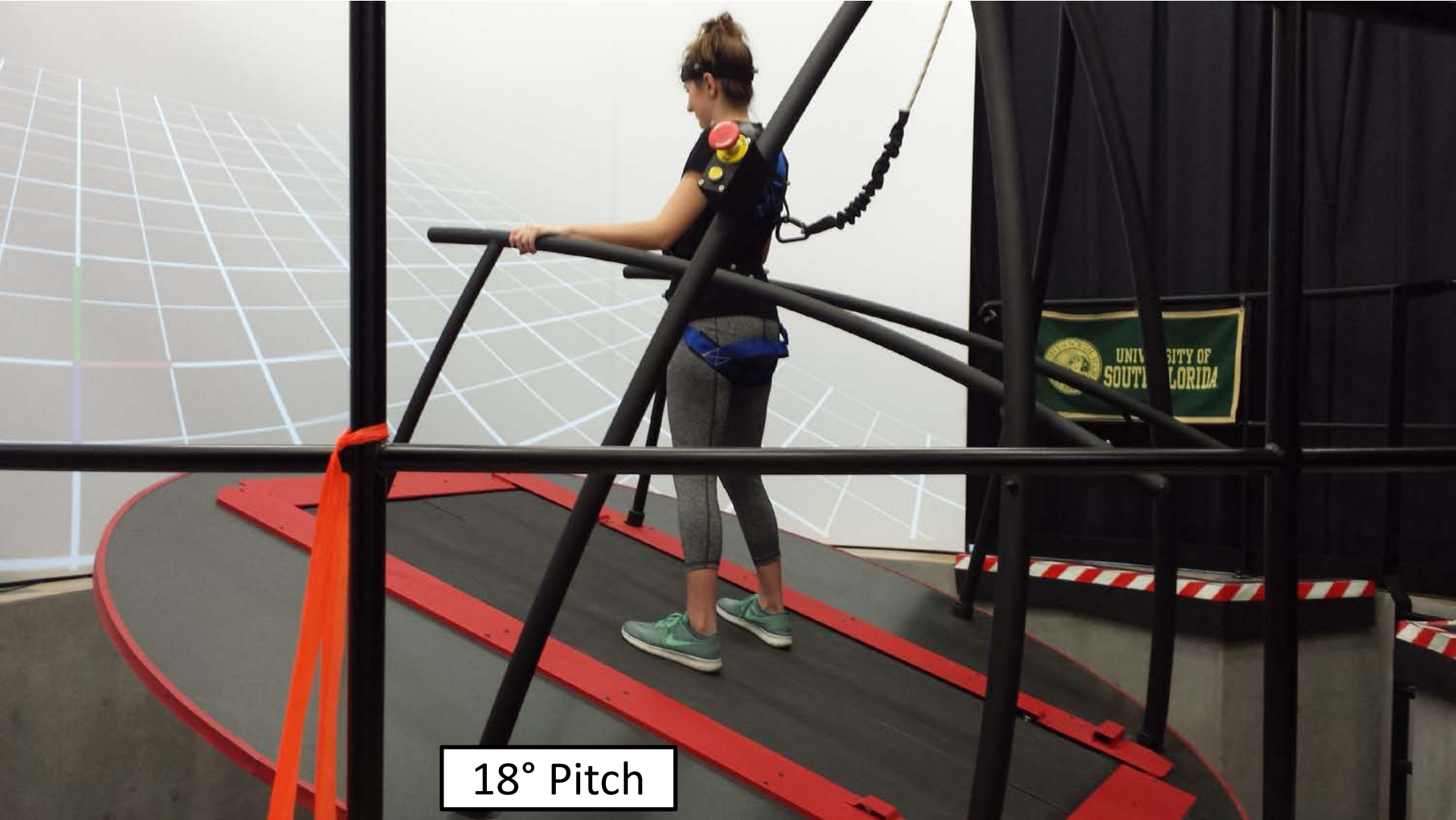
Analog & Digital Signals



Computer Assisted Rehabilitation Environment (CAREN) @ USF



Computer Assisted Rehabilitation Environment (CAREN) @ USF



18° Pitch

Specific Objectives



1. To develop proof-of-concept for ground based environment for human-in-the-loop testing of VIS dynamics
2. To study the effect of platform motion on human kinematic and kinetic response while completing resistive and aerobic exercise.

Specific Objectives



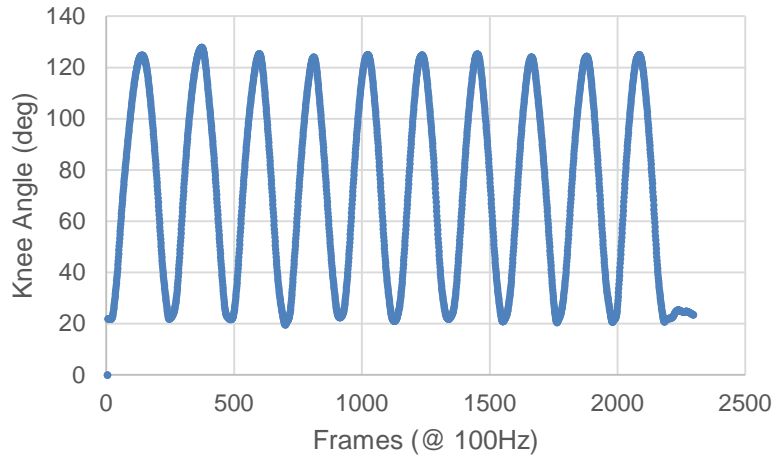
1. To develop proof-of-concept for ground based environment for human-in-the-loop testing of VIS dynamics
2. To study the effect of platform motion on human kinematic and kinetic response while completing resistive and aerobic exercise.

- DOFs of Interest:
 - 1 Translational
 - 1 Rotational
- Exercises of Interest:
 - Squats
 - Rowing
- Parameters of Interest:
 - Force
 - Motion

Theory



Sample Squat Data

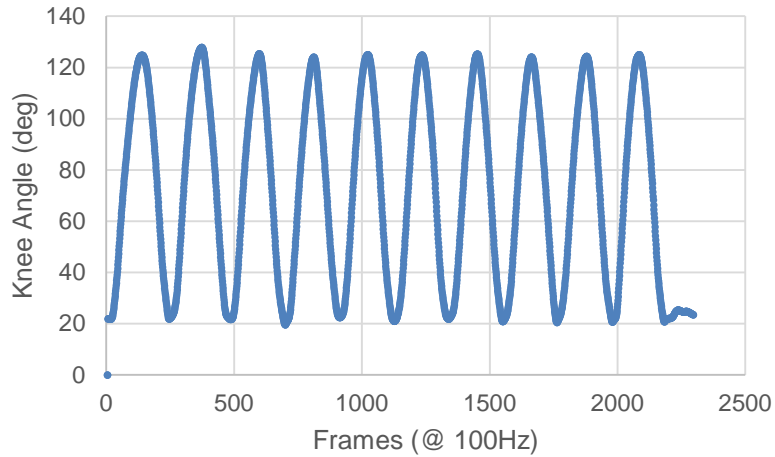


Bulk motion: Sinusoidal

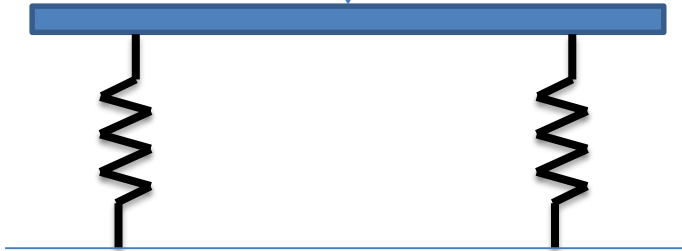
Theory



Sample Squat Data

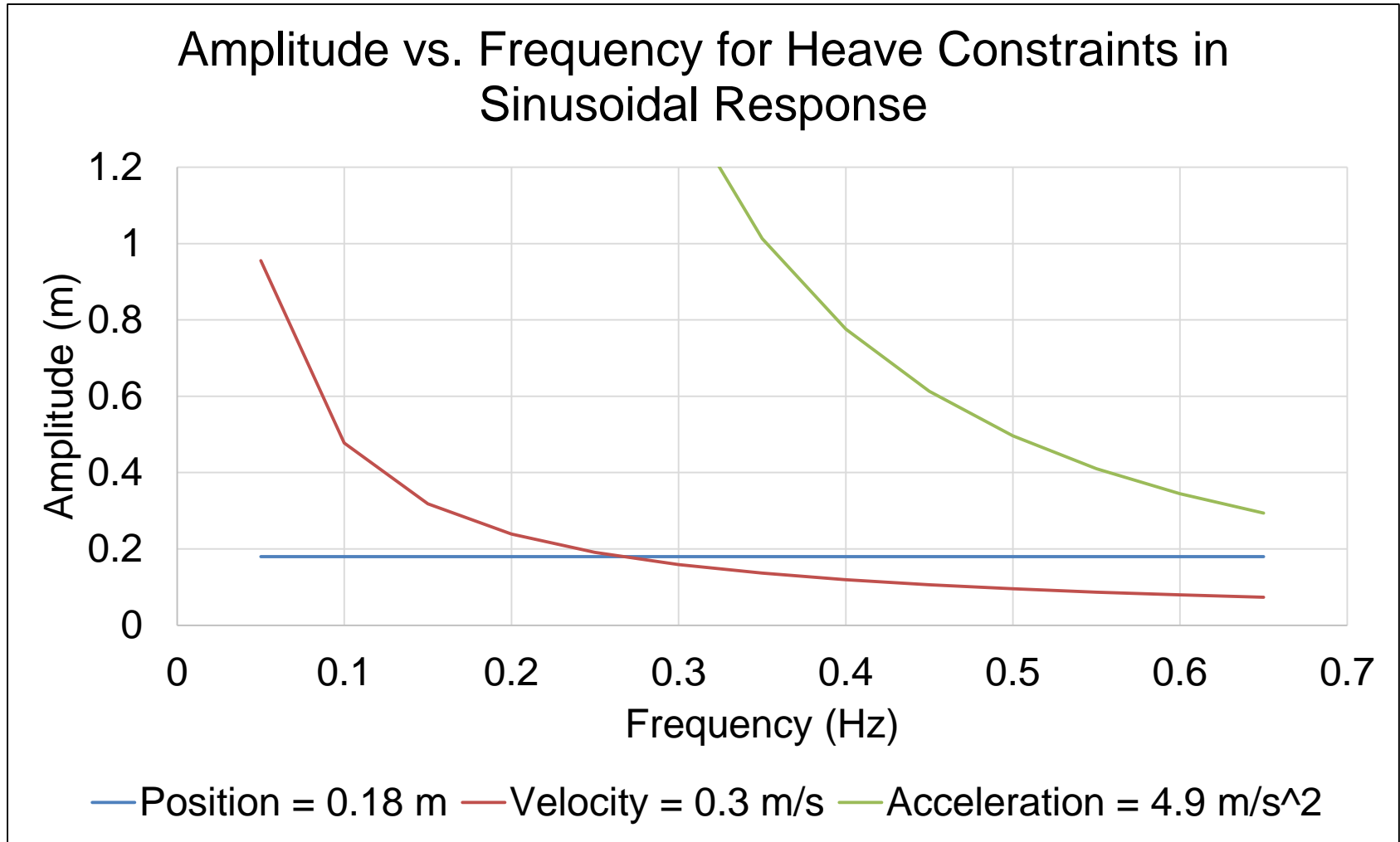


Bulk motion: Sinusoidal



Platform Dynamics:
 $y(t) = A \sin(2\pi ft)$

Constraint Determination



Exercise & Platform Motion Frequencies

Frequencies Selected	Reason
0.10 Hz	ARED MILT & ISS Acceleration Environment
0.35 Hz	ARED MILT & midway point
0.60 Hz	ARED MILT & exercise point of interest
Self-selected	Nominal

Participants instructed to match platform motion

Experimental Design



- **IRB Approved Human Subject Testing on CAREN**

System Components:

- 2 DOF of motion platform

Instrumentation:

- Motion Capture – Kinematics
- Force Plate Measurement – Kinetics

Environmental Distinctions:

- 1G
- No external weight

Experimental Method: Subjects



N = 4

Subject Designation	Gender	Age	Height (m)	Weight (lbs / N)
S1	Female	18	1.73	136.0 / 605.0
S2	Female	22	1.62	121.2 / 539.1
S3	Female	44	1.60	148.2 / 659.2
S4	Male	22	1.86	172.2 / 766.0

Inclusion Criteria

1. Be between the ages of 18 and 65 years old
2. Have no physical impairments
3. Be able to complete exercise motions such as squats and vertical rows

Participation

1 session, ~2 hours

Experimental Method: Pre-Test Preparations



Training

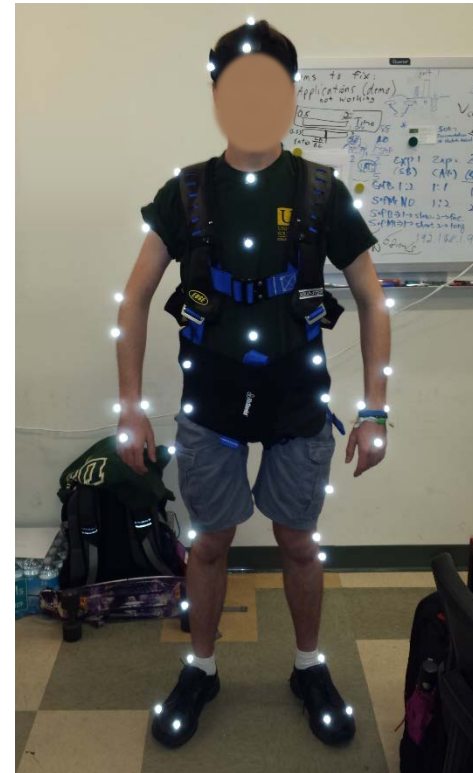
- Exercise Instruction
- Example Videos
- Instructed to match frequency of platform motion

Measurements

- Height & Weight
- Individualized Subject Parameters

Preparations

- Marker placement for motion capture



Experimental Method: Trials



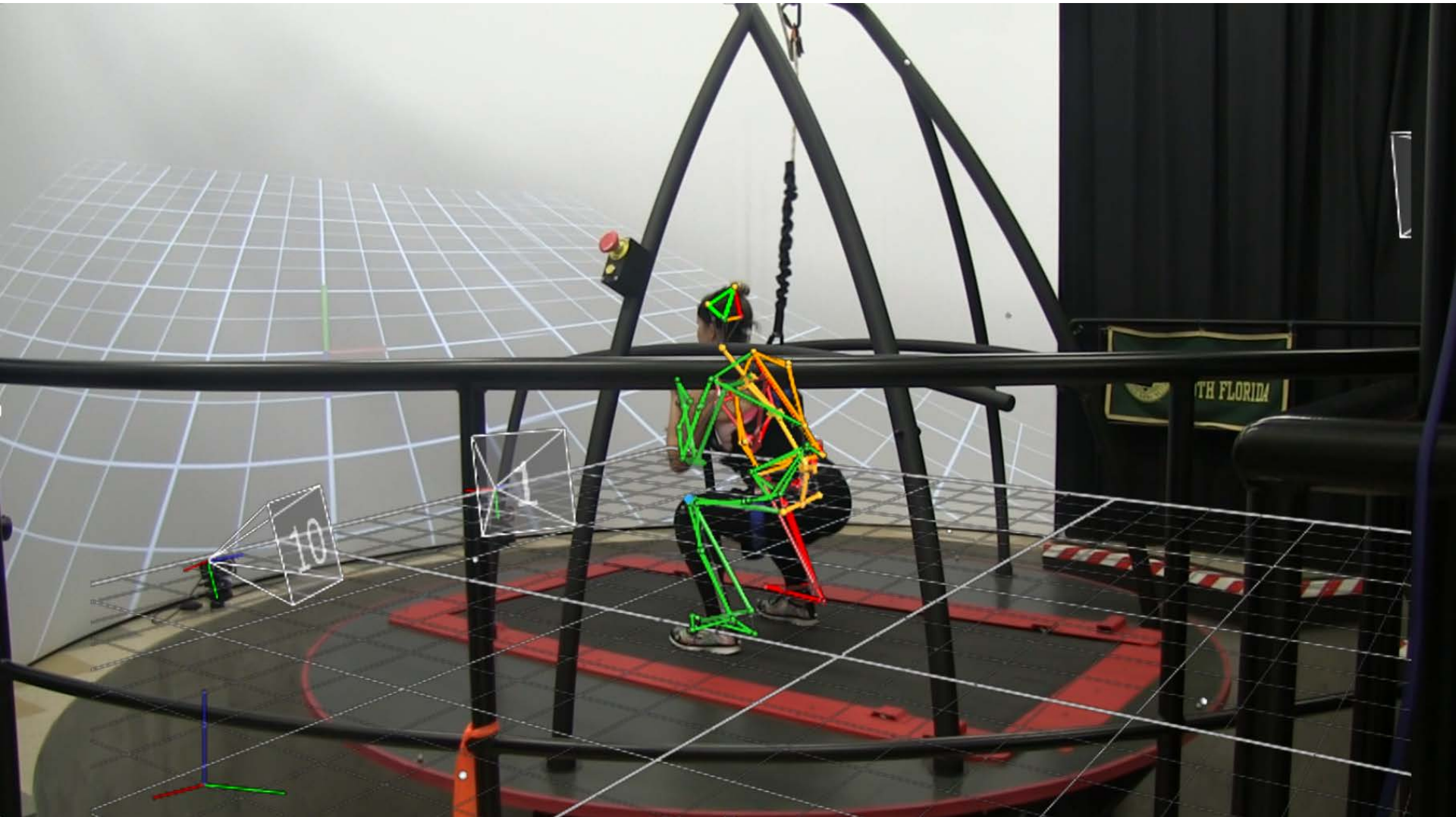
Squat:

#	Exercise	Heave Frequency	Heave Amplitude	Pitch Freq	Pitch Amp
3	Baseline Squat	N/A (Static)	N/A (Static)	N/A	N/A
4	Squat	0.10 Hz	Baseline Measured	N/A	N/A
5	Squat	0.35 Hz	Baseline Measured	N/A	N/A
6	Squat	0.60 Hz	Baseline Measured	N/A	N/A
7	Squat	Baseline Measured Hz	Baseline Measured	N/A	N/A

Row:

#	Exercise	Heave Frequency	Heave Amplitude	Pitch Freq	Pitch Amp
8	Baseline Row	N/A (Static)	N/A (Static)	N/A	N/A
9	Row	0.10 Hz	Baseline Measured	N/A	N/A
10	Row	0.35 Hz	Baseline Measured	N/A	N/A
11	Row	0.60 Hz	Baseline Measured	N/A	N/A
12	Row	Baseline Measured Hz	Baseline Measured	N/A	N/A
13	Row	Baseline Measured Hz	Baseline Measured	Baseline Measured Hz	0.5 deg
14	Row	Baseline Measured Hz	Baseline Measured	Baseline Measured Hz	1 deg
15	Row	Baseline Measured Hz	Baseline Measured	Baseline Measured Hz	2 deg
16	Row	Baseline Measured Hz	Baseline Measured	Baseline Measured Hz	3 deg

Testing





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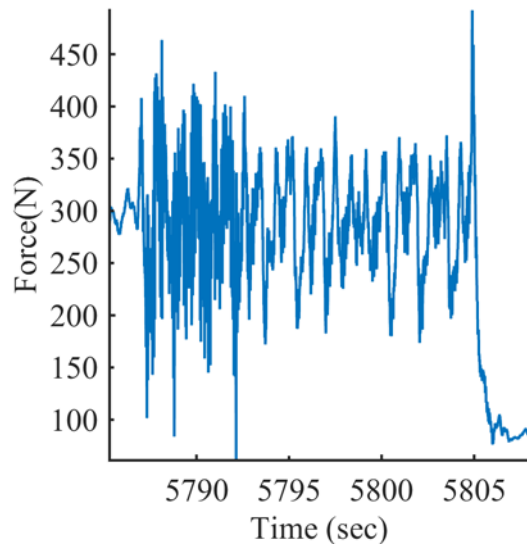


Kinetic Data Processing

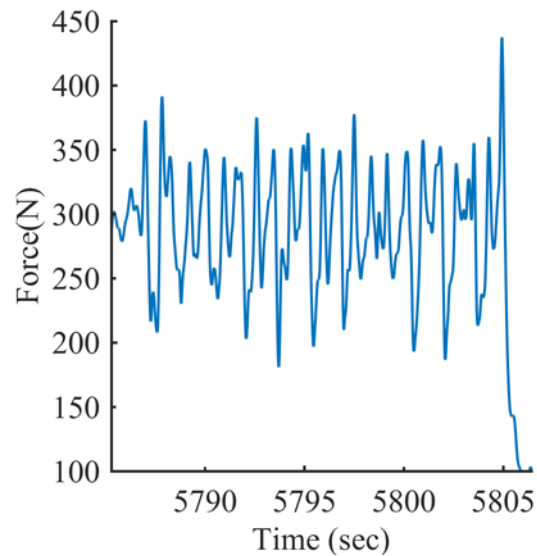


- **Data Extraction**
- **Filtering**

- **Computations**
 - Resultant Force
 - Average Maximum Force
 - Average Force Range
 - Force Frequency Matching



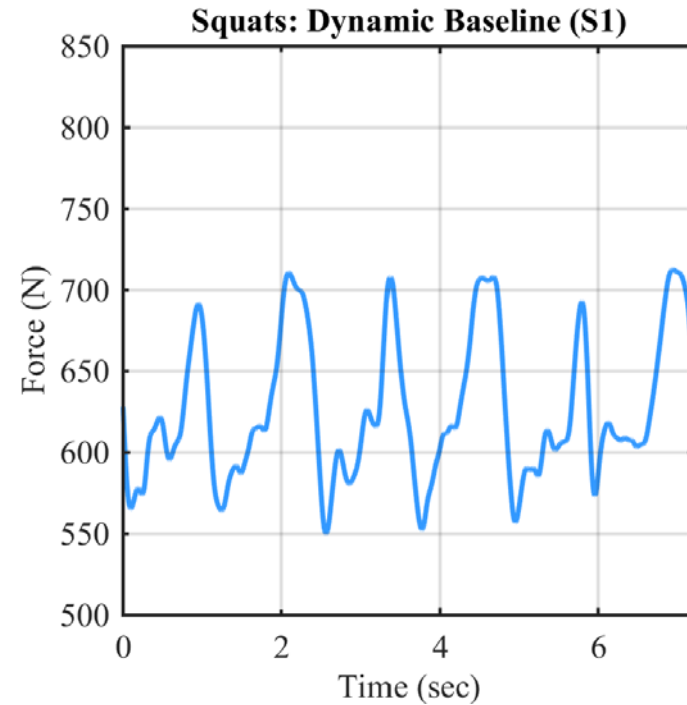
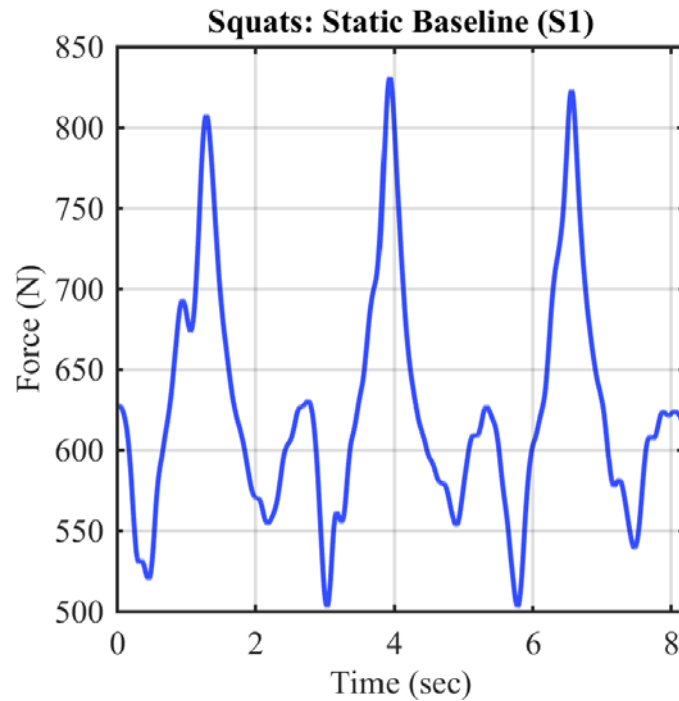
Unfiltered



Filtered



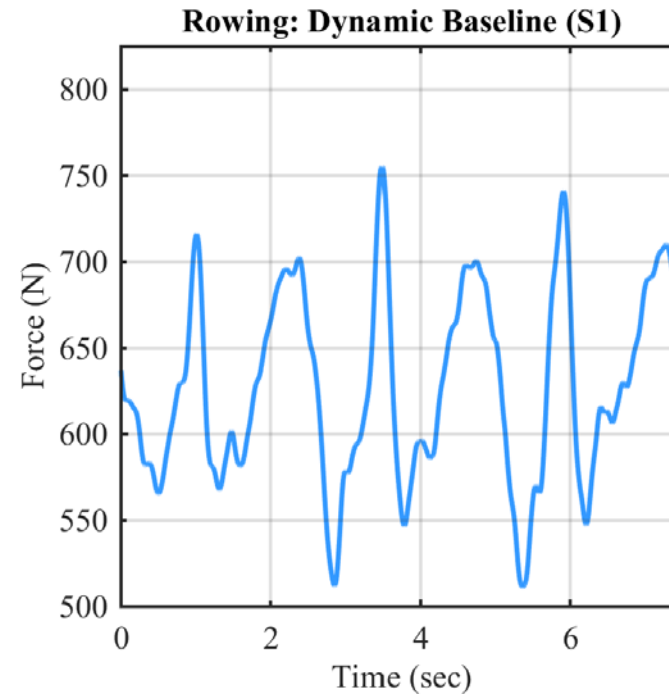
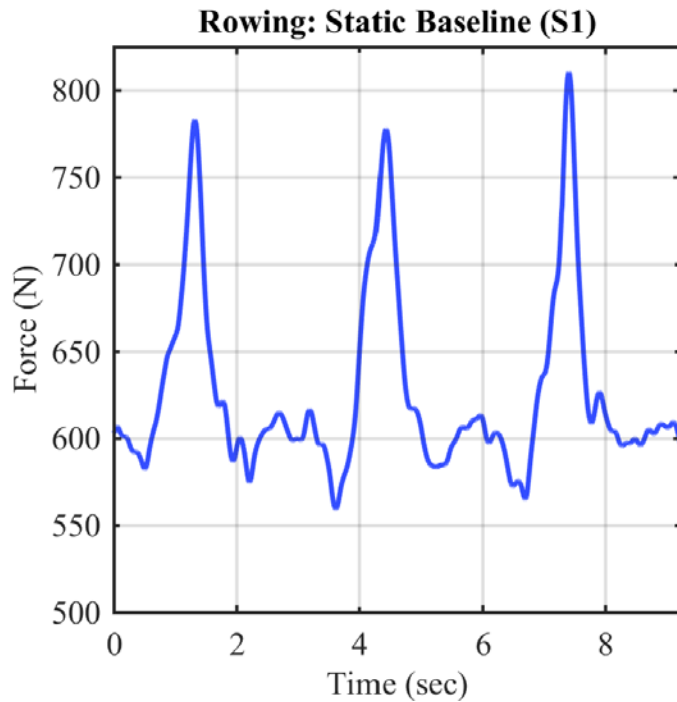
Squats



Kinetic Results: Ground Reaction Force Profiles



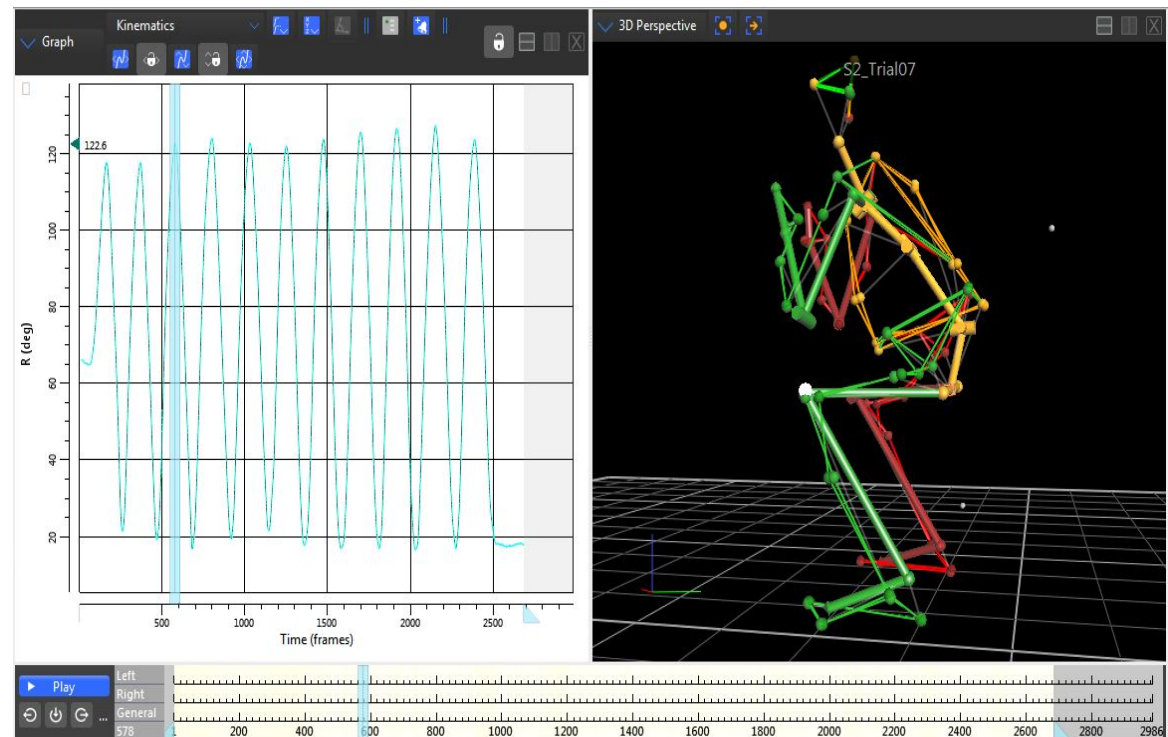
Rows



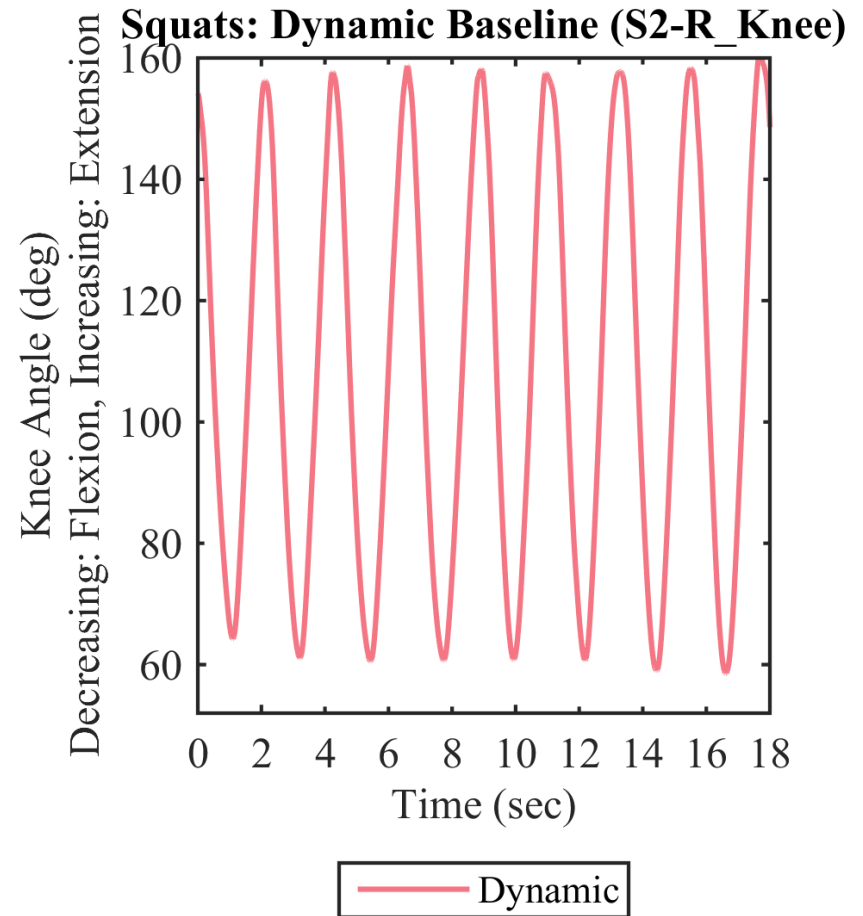
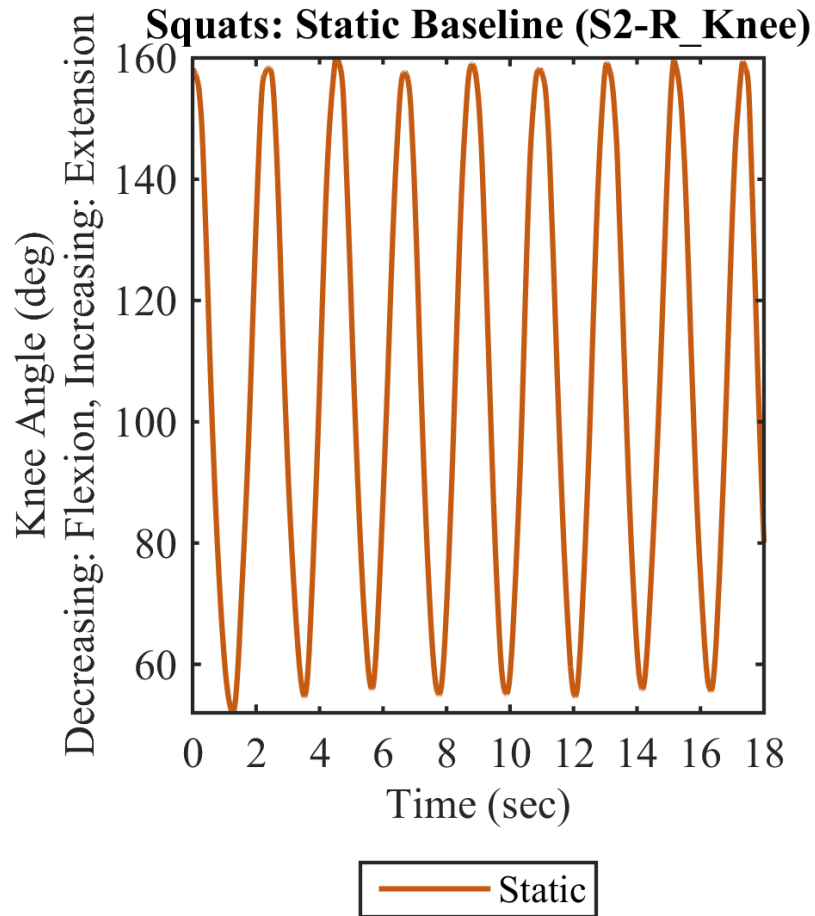
Kinematic Data Processing



- **Data Cleaning**
- **Functional Skeletal Model**
 - Calculates Joint Center
 - Joint Angles
- **Computations**
 - Joint Angle ROM



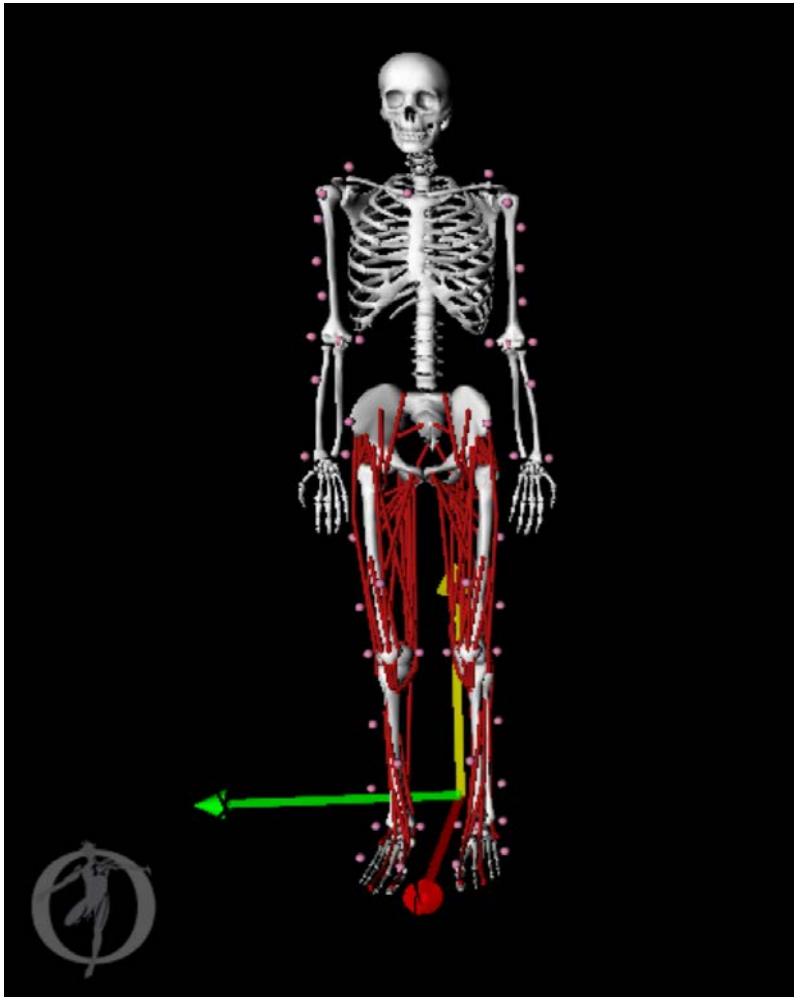
Kinematic Results





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OpenSim, displaying: Rajagopal, Apoorva, et al. "Full-Body Musculoskeletal Model for Muscle-Driven Simulation of Human Gait." *IEEE Transactions on Biomedical Engineering* 63.10 (2016): 2068-2079. (2016)

1. Scaling
2. Inverse Kinematics
3. Inverse Dynamics
4. Static Optimization

OpenSim: <http://opensim.stanford.edu/>

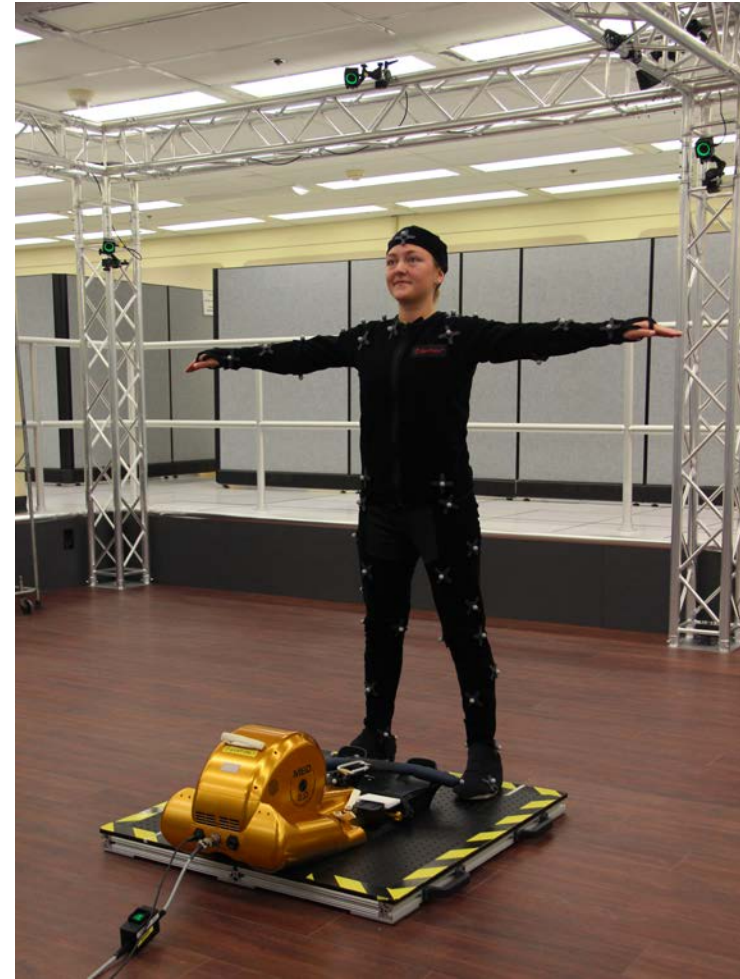
Seth, A., Hicks J.L., Uchida, T.K., Habib, A., Dembia, C.L., Dunne, J.J., Ong, C.F., DeMers, M.S., Rajagopal, A., Millard, M., Hamner, S.R., Arnold, E.M., Yong, J.R., Lakshmikanth, S.K., Sherman, n M.A., Delp, S.L. OpenSim: Simulating musculoskeletal dynamics and neuromuscular control to study human and animal movement. *Plos Computational Biology*, 14(7). (2018)

Delp, S.L., Anderson, F.C., Arnold, A.S., Loan, P., Habib, A., John, C.T., Guendelman, E., Thelan, D.G. OpenSim: Open-source software to create and analyze dynamic simulations of movement. *IEEE Transactions on Biomedical Engineering* , vol 55, pp 1940-1950. (2007)

JSC Facilities



Active Response Gravity Offload System (ARGOS)



Prototype Immersive Technology Lab (PIT)



- **Enhancing CAREN as an analog for a passive VIS**
- **Development for active VIS**
- **PIT & ARGOS data collections**
- **VIS analyses and design using motion capture & force data from human-in-the-loop testing**
- **Incorporation of data feedback in exercise systems**



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More information on this topic:

Lostroscio, Kaitlin, "Developing Motion Platform Dynamics for Studying Biomechanical Responses During Exercise for Human Spaceflight Applications" (2018). Graduate Theses and Dissertations.

<https://scholarcommons.usf.edu/etd/7191>