

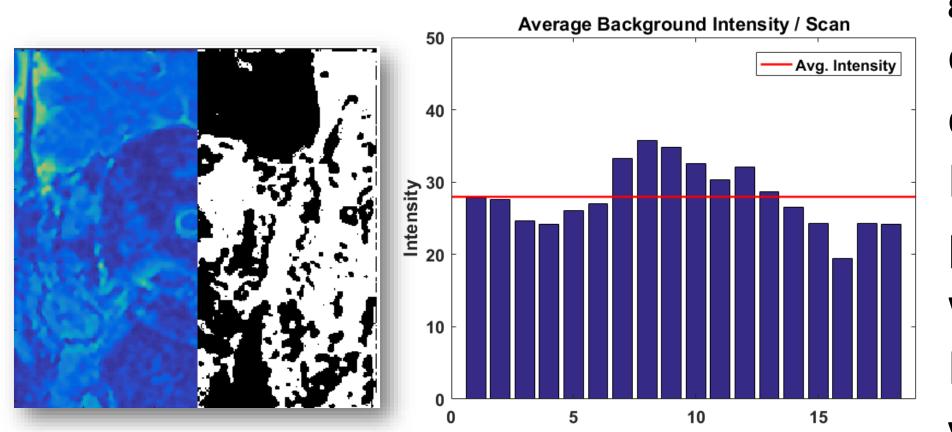
MRI-BASED QUANTIFICATION OF OPTIC NERVE TORTUOSITY AND SUBARACHNOID SPACE 3D GEOMETRY: RELIABILITY ASSESSMENT

Abstract

In some astronauts, long-duration space flight results in ophthalmic structure changes such as optic nerve (ON) kinking, ON distention, and globe flattening. Assessment of the ON and ON sheath may provide insight into the (ONS) mechanisms responsible for ophthalmic structure changes seen in a subset of astronauts. Automated and manual methods were developed to quantify 3D ON/ONS geometry and ON tortuosity.

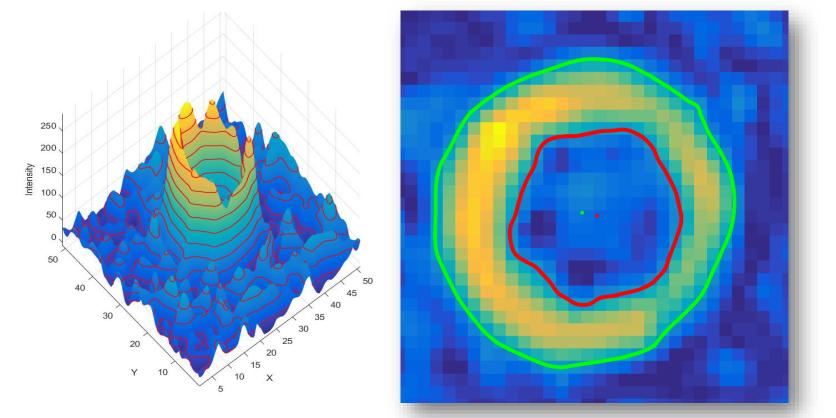
3D Assessment

High-resolution T2-weighted Method: coronal magnetic resonance (MR) images were collected. An offsetting procedure was applied to correct for variations in scan intensities. A threshold chosen by the user is used for segmentation of all slices in all scans. The result is ON and ONS contours area, perimeter, and hydraulic with diameter as parameters with respect to distance from the ON head (ONH)

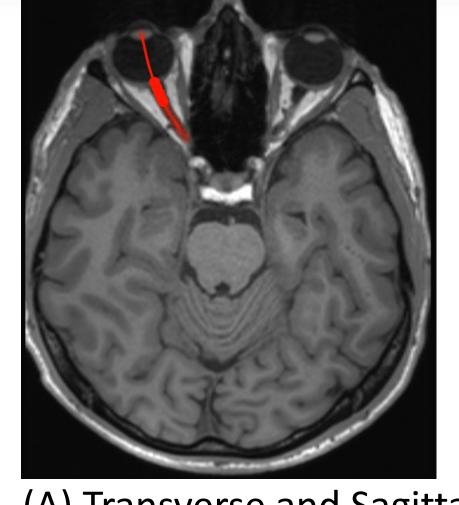


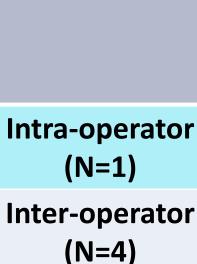
MR imaging (MRI) scan intensities were offset with the difference between average background intensity per scan.

Threshold value chosen by user and left unchanged for all subjects.



Interpolated contour generated at the specified threshold using MATLAB "Contour" and "Meshgrid" functions.

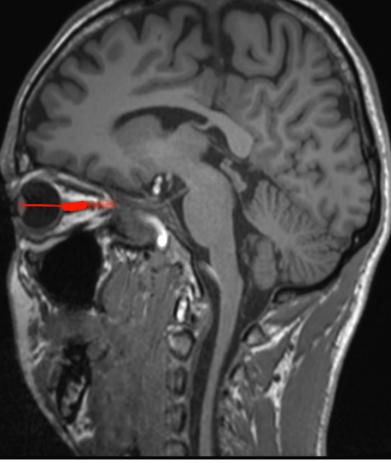


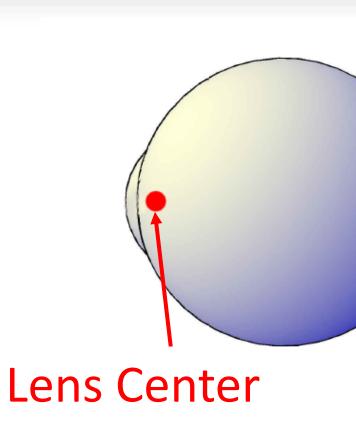


Test

ON trajectories (A) were generated manually in Osirix error for ON and ONS area parameters was computed MD Switzerland) using 3D multi-planar reconstruction (MPR) Validation will be performed using micro-CT in the future. with high-resolution T1 weighted MRI. Lens and ONH points (B) were collected manually as the first two points of the ON trajectory. Axial length defines the Euclidean distance between these two points. Lateral and vertical gaze angles (C) were calculated using the gaze vector originating at the ONH and terminating at the lens center. Porion and orbitale points (D,E) defined the Frankfort horizontal [1] and mid-sagittal orientation planes. Lateral and vertical gaze angles were computed with respect to Frankfort and mid-sagittal planes. Insertion angle was calculated by comparing the gaze vector to a vector originating from the ONH and terminating at a point exactly 3 mm along the ON trajectory. Tortuosity Index (TI) was computed based on the ratio of 3D ON trajectory length to the Euclidean length (B). For TI calculation, the first 20 mm of ON trajectory posterior to the ONH was included. Tortuosity Map (F) is a plot of the orthogonal distances from each point along ON trajectory pathway to the respective Tortuosity 3D trajectory into a 2D map. T_{map}max corresponds to the peak orthogonal distance from the Euclidean pathway.

six geometries within field of view.





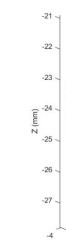
(A) Transverse and Sagittal views of example ON trajectory

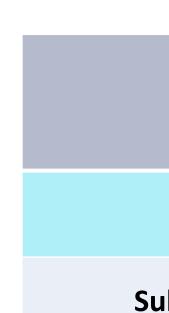
	Lens Center Location [µm] Ave. ± std	ONH Location [µm] Ave. ± std	Axial Length [mm] Ave. ± std	Left Porion Location [µm] Ave. ± std	Right Porion Location [µm] Ave. ± std	Orbitale Location [µm] Ave. ± std	Insertion Angle (Φ) [°] Ave. ± std	Lateral Gaze Angle [°] Ave. ± std	Vertical Gaze Angle [°] Ave. ± std	Tortuosity Index (TI) [mm/mm] Ave. ± std	T _{map} max [mm] Ave. ± std
or	206 ± 94	368 ± 225	$\textbf{0.157} \pm \textbf{0.166}$	452 ± 130	532 ± 298	773 ± 358	$\textbf{3.616} \pm \textbf{2.507}$	$\textbf{0.528} \pm \textbf{0.371}$	0.773 ± 0.576	$\textbf{0.002} \pm \textbf{0.001}$	$\textbf{0.152} \pm \textbf{0.112}$
or	266 ± 100	361 ± 202	$\textbf{0.167} \pm \textbf{0.128}$	866 ± 631	$\textbf{1234} \pm \textbf{817}$	$\textbf{1482} \pm \textbf{1059}$	$\textbf{4.110} \pm \textbf{3.075}$	0.575 ± 0.454	1.037 ± 0.757	$\textbf{0.003} \pm \textbf{0.002}$	$\textbf{0.132} \pm \textbf{0.114}$

Tortuosity Assessment

Average error with one standard deviation and percent software (version 8.0.1, Pixmeo, Geneva, with respect to the average measurement value.

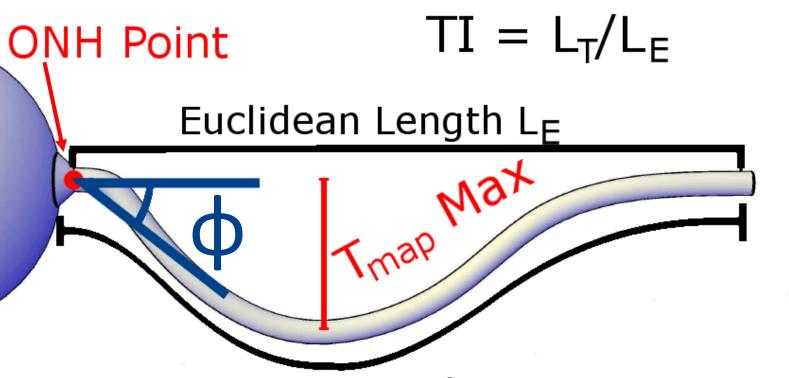






Verification: intra-operator assess 0 point on the Euclidean pathway. This plot transforms the reliability, a single operator completed all measurements five times at intervals of at least three days. To assess inter-operator reliability, four operators completed all measurements three times at intervals of at least three **3D Verification:** A 3D ON phantom model was developed days. Results were compared to find the average with three idealized (identical) and three subject specific difference from the mean, as well as the standard (identical) geometries. The model was scanned twice at deviation, for each parameter (see table). Results one MRI center using the original study protocol with all indicated a relatively high degree of intra- and interoperator reliability for all parameters analyzed.

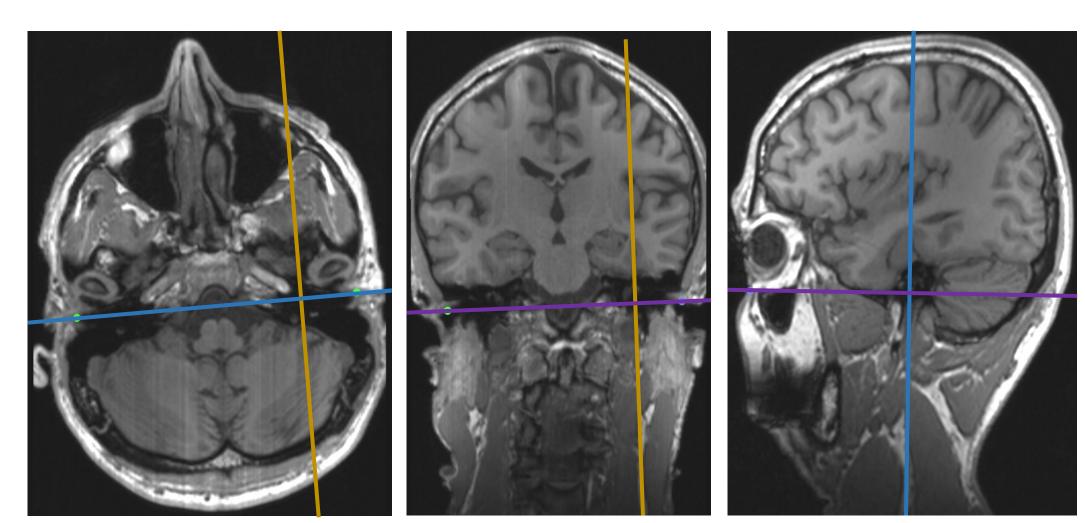


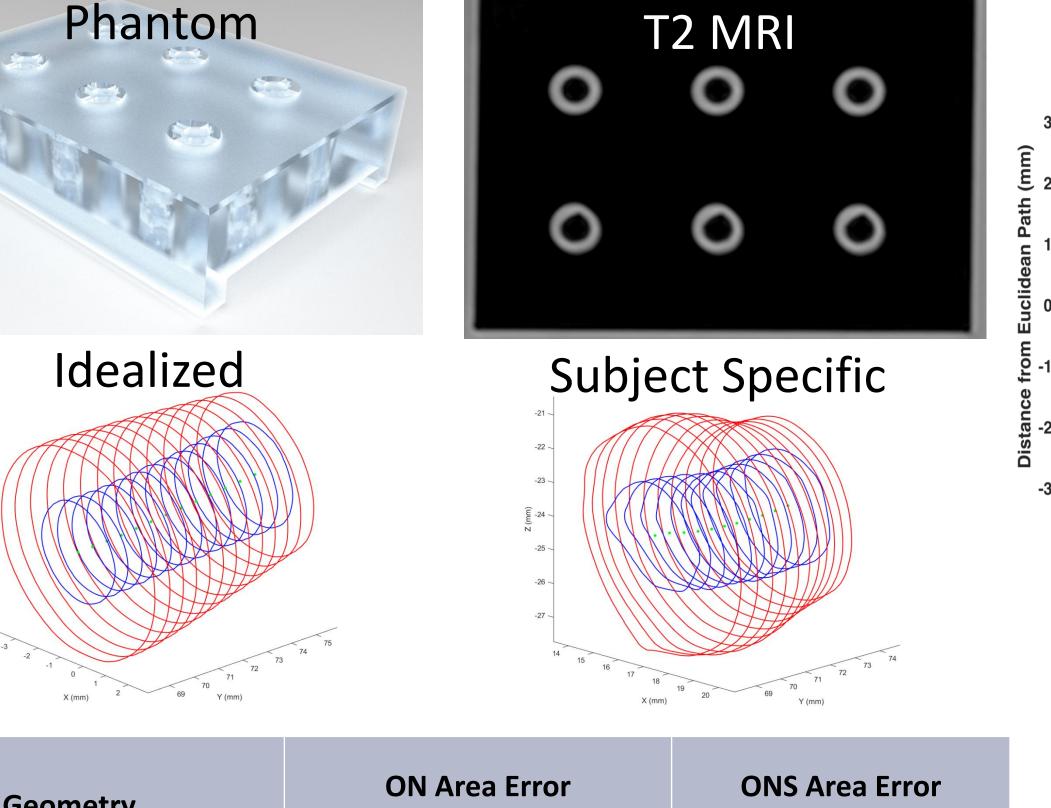


Trajectory Length L_T

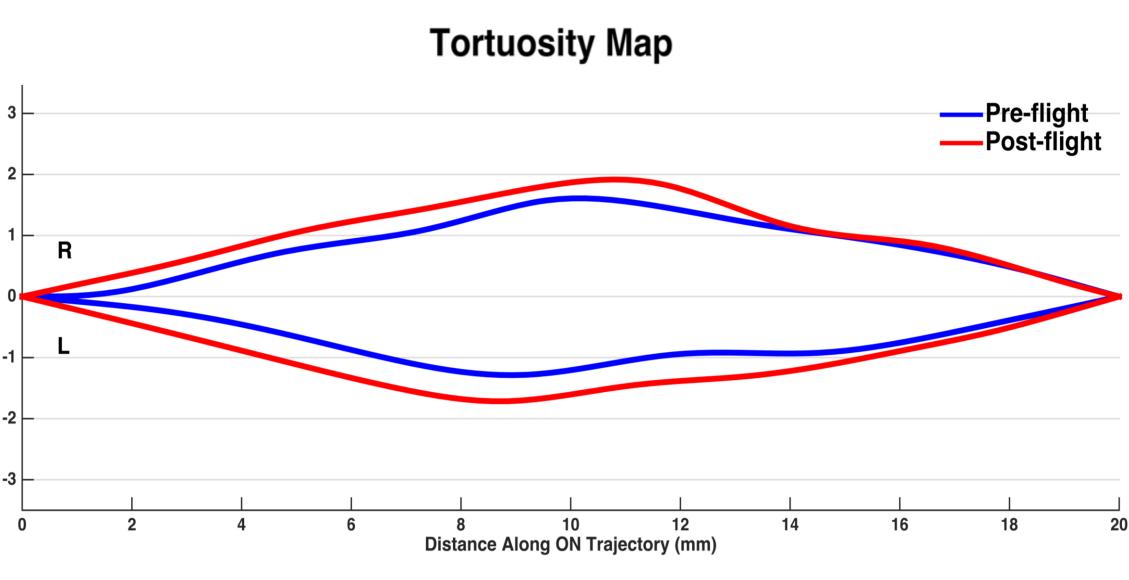
(B) Optic globe and nerve with tortuosity parameters

(C) Gaze vector (white) with lateral (green) and vertical (yellow) gaze angles





Geometry	ON Area Error [mm ² , %]	ONS Area Error [mm ² , %]		
Idealized	0.361 ± 0.239 (1.69%)	0.496 ± 0.412 (0.86%)		
ubject Specific	0.231 ± 0.188 (1.86%)	0.652 ± 0.727 (0.95%)		



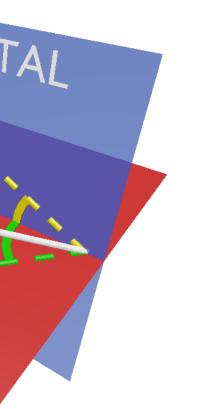
(F) Example tortuosity map showing pre-/post-flight change in ON trajectory curvature due to space flight

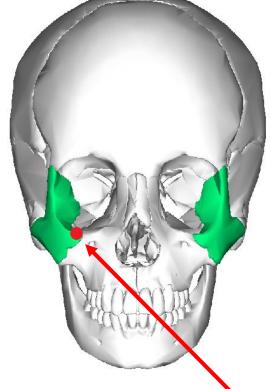
[1] Daboul A, et al. (2012) *PLoS ONE* 7(10), doi: ARTNe4828110.1371/journal/pone.0048281.

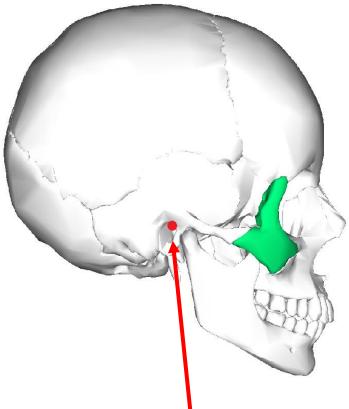
Author Affiliations and Acknowledgment

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(D) Example orbitale and porion locations

(E) Frankfort Plane highlighting porion and orbitale Points

Citations

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