

Understanding the Impacts of Soil Moisture Initial Conditions on NWP in the Context of Land-Atmosphere Coupling

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1 **ABSTRACT**

2 The role of soil moisture in NWP has gained more attention in recent years, as studies have
3 demonstrated impacts of land surface states on ambient weather from diurnal to seasonal scales.
4 However, soil moisture initialization approaches in coupled models remain quite diverse in terms
5 of their complexity and observational roots, while assessment using bulk forecast statistics can be
6 simplistic and misleading. In this study, a suite of soil moisture initialization approaches is used
7 to generate short-term coupled forecasts over the U.S. Southern Great Plains using NASA’s Land
8 Information System (LIS) and NASA Unified WRF (NU-WRF) modeling systems. This includes
9 a wide range of currently used initialization approaches, including soil moisture derived from ‘off-
10 the-shelf’ products such as atmospheric models and land data assimilation systems, high-resolution
11 land surface model spinups, and satellite-based soil moisture products from SMAP. Results
12 indicate that the spread across initialization approaches can be quite large in terms of soil moisture
13 conditions and spatial resolution, and that SMAP performs well in terms of heterogeneity and
14 temporal dynamics when compared against high resolution land surface model and in-situ soil
15 moisture estimates. Case studies are analyzed using the local land-atmosphere coupling (LoCo)
16 framework that relies on integrated assessment of soil moisture, surface flux, boundary layer, and
17 ambient weather, with results highlighting the critical role of inherent model background biases.
18 In addition, simultaneous assessment of land vs. atmospheric initial conditions in an integrated,
19 process-level fashion can help address the question of whether improvements in traditional NWP
20 verification statistics are achieved for the right reasons.

22 1. Introduction

23 The role of the land surface in numerical weather prediction (NWP) has been traditionally
24 overlooked by the atmospheric modeling community (Santanello et al. 2018), who often employ
25 primitive initialization approaches for soil moisture and temperature based on coarse atmospheric
26 model products. These surface conditions have been treated simply as lower boundary conditions,
27 with early LSM development driven by the atmospheric communities and little emphasis on the
28 accuracy and observability of land surface states and processes (Dirmeyer and Halder 2016).
29 However, recent studies have demonstrated the critical role of the land surface, and in particular
30 soil moisture, in terms of impacts on precipitation (Welty and Zeng, 2018; Ford et al. 2015; Taylor
31 et al. 2012; Koster et al. 2004; Findell and Eltahir 2003), temperature and humidity (Kala et al.
32 2015; Seneviratne et al. 2013; Mueller and Seneviratne 2012), and L-A coupling as a whole
33 including the planetary boundary layer (PBL) (Johnson and Hitchens 2018; Dirmeyer and Halder
34 2016; Santanello et al. 2007, 2005). In particular, the initial condition (IC) of soil moisture has
35 been shown to influence predictability on near-term (Dirmeyer and Halder 2016; Santanello et al.
36 2016, 2013a) and seasonal (Rajesh et al. 2018, Xiang et al. 2018; Hirsch et al. 2014; Koster et al.
37 2010) scales. Thus, quantification of the sensitivity of coupled models to the soil moisture
38 initialization approach is an often overlooked, but potentially high-impact, exercise that should be
39 performed by model evaluation and development communities.

40 From a process-level perspective, the connection of soil moisture to ambient weather and
41 precipitation can be considered using the GEWEX local land-atmosphere coupling (LoCo;
42 Santanello et al. 2018) paradigm and ‘process chain’, as follows:

$$43 \quad \Delta SM \xrightarrow{\text{(a)}} \Delta EF \xrightarrow{\text{(b)}} \Delta PBL \xrightarrow{\text{(c)}} \Delta Ent \xrightarrow{\text{(d)}} \Delta T_{2m}, Q_{2m} \Rightarrow \Delta P, Cloud \quad (1)$$

44 where the links (a-d) represent the sensitivities of: (a) evaporative fraction (EF; i.e. surface fluxes)
45 to soil moisture (SM), (b) PBL evolution to surface fluxes, (c) entrainment (Ent) fluxes to PBL
46 evolution, (d) the collective feedback of the free atmosphere on ambient weather, and the
47 cumulative support of these links on cloud and precipitation formation. By parsing out the
48 stepwise impact of soil moisture on surface fluxes and, likewise, the vertical coupling impacts of
49 surface fluxes on PBL development and entrainment feedbacks, an understanding of the interaction
50 of the coupled model sensitivities to soil moisture can be ascertained.

51 To this end, the LoCo community has been developing metrics to quantify the links in the
52 chain of Eq. (1) that can also be used to better understand traditional ‘bulk’ statistics of ambient
53 weather (e.g. 2-meter temperature (T2m) and humidity (Q2m), RMSE and bias) commonly used
54 by operational centers as benchmarks, in the context of the influence of soil moisture on model
55 accuracy and development. Such approaches have been previously employed to assess the
56 coupling behavior in modern global climate reanalysis products (Santanello et al. 2015), to
57 quantify the impact of LSM calibration and assimilation on short-term coupled forecasts
58 (Santanello et al. 2013a, 2015b), and to intercompare the coupled behavior of different
59 parameterization combinations in regional NWP (Santanello et al. 2013b).

60 These studies assumed that the land surface IC was based on an offline, high-resolution,
61 high-quality, long-term spinup of soil states from a land data assimilation system (LDAS) such as
62 NASA’s Land Information System (LIS; Kumar et al. 2008). However, despite their advantages,
63 such spinup approaches are still not the norm outside of the land modeling community. In addition,
64 with recent advances in satellite-based soil moisture retrievals such as those from SMOS and
65 SMAP, and long-term in-situ networks such as those comprising the International Soil Moisture
66 Network (Dorigo et al. 2011), there are now additional observationally-driven initialization

67 approaches that need to be considered (Dirmeyer et al. 2018, 2016). Overall, there is a wide array
68 of soil moisture IC approaches that are being used across the NWP and climate modeling
69 communities (both research and operational), ranging in complexity, resolution, quality, and
70 observability.

71 In this paper, we assess the impacts of soil moisture IC approaches in an NWP context
72 using the NASA Unified WRF model (NU-WRF; Peters-Lidard et al. 2015), focused on an
73 integrative, process-level assessment of L-A coupling and ambient weather implications.
74 Specifically, we intercompare a suite of initializations of high resolution (1 km) short-term weather
75 forecasts using ‘off-the-shelf’ soil moisture products from large scale atmospheric and land surface
76 reanalysis products, high-resolution LIS spinups, and SMAP satellite retrievals which range in
77 horizontal resolution from 1-33 km. Section 2 reviews the current suite of soil moisture IC
78 approaches being used by the community. Section 3 describes the model and observation products
79 used for initialization, and the LIS and NU-WRF modeling systems, along with case study and site
80 descriptions for the coupled experiments. Section 4 presents an offline intercomparison of SMAP
81 soil moisture with that of in-situ networks and LIS-based simulations over the domain of interest.
82 Section 5 then presents the full suite of coupled NU-WRF experiments with varying ICs, and
83 corresponding LoCo analysis and ambient weather evaluations. Discussion and conclusions then
84 follow in Section 6.

85 **2. Review of Soil Moisture Initialization Approaches**

86 Figure 1 shows the suite of soil moisture initialization approaches for NWP and regional
87 modeling commonly used by the operational and research communities. Despite their wide range
88 in complexity, studies using each of these approaches have been published recently, and the typical
89 usage by the community tends to favor the lower complexity approaches.

90 Going from least to most complex (in Fig. 1), while a uniform (homogeneous) soil moisture
91 IC may have been commonly employed decades ago during the early years of atmospheric and L-
92 A coupled model development, this approach lacks an accurate representation of surface
93 heterogeneity and likely leads to poor NWP results in terms of surface flux partitioning and impact
94 on PBL and atmospheric processes. There remain a few regional modeling applications (including
95 operational) that employ homogeneous soil moisture ICs, such as those using RAMS (Gomez et
96 al. 2016, 2015), where only recently has the sensitivity to varying ICs been evaluated in a
97 systematic manner (Gomez et al. 2018). These studies affirm that there are significant impacts of
98 soil moisture IC values on NWP, and point to the potential for satellite data to inform on improved,
99 heterogeneous IC approaches. It should also be noted that homogeneous and idealized surface
100 conditions are still the norm for the LES and cloud resolving model communities (focused on
101 ~100m scales).

102 Next, from an observational perspective, in-situ soil moisture measurements are direct
103 measurements at fixed depths while satellite measurements are indirect and only sensitive to a thin
104 layer near the surface typically less than a few centimeters. The in-situ measurements are typically
105 considered truth in the development and parameterization of the soil models themselves.
106 Therefore, soil moisture ICs based on a dense in-situ network that covers the model domain would
107 be an ideal approach. Such networks are rarely dense enough to meet NWP application
108 requirements. One example is the DOE's ARM Southern Great Plains (ARM-SGP) observatory
109 covering OK and KS, where ~20 sites measuring soil moisture are available. Even in this dense
110 network, 20 observations across a domain with 250,000 grid cells is hardly representative of land
111 surface and soil type heterogeneity, and interpolation procedures and assumptions do not readily
112 apply to obtain distributed estimates. Recent examples of utilizing a dense in-situ network in the

113 context of NWP ICs do exist (e.g. Massey et al. 2016), but remain limited due to the heterogeneous
114 nature of soil properties.

115 The next grouping of ICs in terms of complexity is what are deemed ‘off-the-shelf’
116 products, where soil moisture is extracted from existing LDAS or atmospheric modeling systems.
117 Atmospheric-based products are simply the soil moisture fields derived from the land surface
118 component of the commonly used initial/boundary condition datasets for NWP. These
119 atmospheric models include GFS, ECWMF, NARR, NAM, and others, and the advantage of using
120 these land ICs is that they are inherently consistent (spatially and temporally, as well as
121 climatologically) with the atmospheric ICs. The disadvantage is that these atmospheric models
122 are quite coarse spatially (~25–40 km) relative to the grid size of the NWP or WRF application
123 (e.g. 1–3 km in this case). Thus, initializing a domain with 1-km horizontal grid spacing with data
124 that has 30-km resolution will miss some crucial heterogeneity and likely does not capture the true
125 nature of the local L-A coupling. Another caveat to this approach is when the LSM used in the
126 NWP application differs from that in the atmospheric product, as soil moisture climatologies differ
127 across LSMs and thus are not easily transferable. In addition, any inherent biases (e.g.
128 precipitation) in the atmospheric model will be reflected in the land states (e.g. soil moisture) as
129 well.

130 From an LDAS perspective, the GLDAS (Rodell et al. 2004) and the NLDAS Version 2
131 (NLDAS-2; Xia et al. 2012) are examples of uncoupled environments, run routinely at 25 km and
132 12.5 km, respectively. Both are offline LSMs driven by high-quality, ground-observation based
133 atmospheric forcing and parameters, though there is still a significant gap in resolution compared
134 with the target model (1 km vs. 12.5–25 km). The land ICs from LDAS systems are likely to be
135 more accurate and heterogeneous versus atmospheric model-based ICs described above, however

136 there may be inconsistency issues with the LSM used in the LDAS and that used in the NWP
137 application (e.g. soil or vegetation parameters). These ‘canned’ spinups have been largely
138 underutilized by the NWP community and represent a spinup shortcut that does not require a multi-
139 year spinup or access to forcing data. A recent study from Dillon et al. (2016) compared the
140 impacts of using GLDAS versus GFS soil moisture ICs on short-term WRF forecasts, and neither
141 approach consistently outperformed the other over South America. Gomez et al. (2018) updated
142 RAMS with spatially distributed soil ICs from GLDAS, and found significant improvement in
143 ambient weather forecasts. Jacobs et al. (2017) used an Australian LDAS (Australian Water
144 Availability Project (AWAP); <http://www.csiro.au/awap/>) to generate a 5–km gridded soil
145 moisture IC product for WRF heatwave simulations, and found that forecasts improved
146 significantly over those using ERA-I-based soil moisture ICs, as AWAP corrected for the cool,
147 wet bias inherent in ERA-I. Lin and Cheng (2016) also compared the impacts of GLDAS versus
148 GFS-based ICs on WRF forecasts over Taiwan, and showed improvements over certain regions
149 where GFS was biased and where soil exerts more control over surface fluxes. Overall, these
150 studies demonstrate general improvement from LDAS-based ICs over those of coarser
151 atmospheric-based products.

152 In terms of model-observation fusion, LSM spinup approaches, as described earlier, can
153 generate high resolution, accurate ICs at the resolution of the target model using observed forcing
154 and parameter data. LSM spinups are necessary to generate soil moisture and temperature profiles
155 that have equilibrated over time, and thus are often on the order of a few years to decades in length
156 leading up to the time of coupled model initialization (Rodell et al. 2005). Spinups are facilitated
157 by systems such as LIS and the High Resolution LDAS (HRLDAS; Chen et al. 2017), and require
158 multi-year offline simulations driven by high quality forcing data. As a result, the advantages are

159 in resolution, representativeness and quality (including consistency of LSM states with observed
160 meteorology), but can be limited by the availability of accurate forcing data and computational
161 demand. As compared to LDAS systems, LSM spinups can further resolve spatial heterogeneity
162 down to 1km or less, and in coupled systems such as LIS/NU-WRF, will ensure identical LSM
163 settings in both the offline spinup and coupled simulations. To date, LSM spinups have been
164 employed in numerous regional (WRF) modeling studies, but are typically only employed by those
165 in the land (LIS and HRLDAS) communities (Santanello et al. 2013ab, Case et al. 2011, 2008,
166 Kumar et al. 2008, Rajesh et al. 2017, Hirsch et al. 2014), while atmospheric modelers have been
167 much less inclined to invest in this approach.

168 Recent advances in satellite retrieval of land surface states now allow for soil moisture ICs
169 to be fully or partly derived from satellite data. Satellites such as SMAP can provide gridded
170 products comparable in spatial resolution to that of the off-the-shelf products described above (e.g.
171 SMAP 9- and 36-km products). However, using satellite products directly as ICs is not currently
172 advisable, due to differing climatologies and biases inherent in satellite versus LSM-based soil
173 moisture. As satellite soil moisture becomes more accurate (as is the case with SMAP), and LSM
174 soil moisture becomes more ‘observable’, opportunities to directly employ satellite products as
175 ICs will become apparent. The traditional method to incorporate satellite-based soil moisture into
176 ICs has been through data assimilation after utilizing bias correction techniques such as CDF
177 matching to account for the satellite versus LSM biases (Reichle and Koster 2004). Assimilation
178 incorporates some of the satellite signal that the LSM may miss, but impacts are typically muted
179 due to the low random error present in satellite and LSM products, and high accuracy of
180 atmospheric (i.e. precipitation) forcing of the LSM. Recent efforts at NCEP and Environment
181 Canada have employed SMAP data assimilation during LSM spinup to improve soil moisture ICs

182 for NWP, with results showing inconsistent improvements across large continental domains.
183 These approaches and results will be discussed in more detail in Sections 5 and 6 in the context of
184 the results presented in this study.

185 An additional IC approach that does not fall neatly into the categories in Fig. 1 is that of
186 ‘self-spinup’, as described by Angevine et al. (2014) and performed by Dy and Fung (2016). In
187 self-spinup, the NWP or regional model of interest can be initialized with coarse atmospheric-
188 based soil moisture ICs, then cycled over months or years at a time (resources permitting), which
189 improves the spatial resolution as it responds to precipitation and other forcing at the finer target
190 model resolution. A disadvantage is that the accuracy of resulting soil moisture is entirely
191 dependent on the free running model performance and precipitation accuracy, which likely is less
192 than that of the observationally-constrained atmospheric models. As with other IC approaches,
193 there are tradeoffs, and in this case that is gaining spatial heterogeneity but perhaps losing the
194 spatial accuracy of soil moisture anomalies.

195 Also not considered in the suite of ICs in Fig. 1 are basic sensitivity studies that vary the
196 soil moisture IC, often uniformly, in ‘brute force’ fashion in order to assess impacts on NWP (e.g.
197 Kalverla et al. 2016, Ament et al. 2006, Daniels et al. 2016, Collow et al. 2014). There have been
198 a host of studies in this regard, each emphasizing a different aspect of coupled impacts, typically
199 focusing on singular impacts on temperature or precipitation. Overall, these sensitivity studies
200 highlight the importance of soil moisture ICs, and underscore the need for high-quality and high-
201 resolution ICs (preferably from satellite or LSM spinup).

202 **3. Experimental Design**

203 The suite of soil moisture IC approaches in Fig. 1 will be intercompared in this study using

204 SMAP for satellite observations, LIS for LSM spinup, NU-WRF as the coupled forecast model,
205 along with the standard off-the-shelf products from NARR, GFS, and NLDAS-2 and in-situ
206 evaluation data from the ARM-SGP network.

207 *a. SMAP Soil Moisture*

208 NASA's SMAP mission was launched in January 2015, and has been providing passive
209 microwave retrievals of soil moisture from April 2015 to present. SMAP soil moisture has
210 performed well to date, reaching the mission target of $\pm 0.04 \text{ m}^3 \text{ m}^{-3}$ accuracy over most regions
211 (Chan et al. 2018), and with higher temporal consistency (i.e. less noise) and overall information
212 content than other passive microwave-based soil moisture products from missions such as SMOS,
213 AMSR-E, and ASCAT (Kumar et al. 2017). SMAP soil moisture also exhibits wetting and
214 drydown responses that are consistent with those modeled by LSMs (Shellito et al. 2017), and has
215 been useful in detecting the timing and spatial extent of irrigation (Lawston et al. 2017). In
216 addition, SMAP has been used successfully in data assimilation studies by operational and research
217 centers (e.g. Fang et al. 2018, Carrera et al. 2018). In this study, we use the SMAP L3 enhanced
218 soil moisture retrieval, based on the 33-km retrieval algorithm but posted at 9-km spatial resolution
219 after utilizing the oversampling of the SMAP footprint. Section 4 presents a comparison of SMAP
220 products against in-situ and modeled soil moisture in order to assess any relative biases or
221 observability issues amongst these products before they are infused into offline or coupled
222 modeling applications.

223 *b. LIS and NU-WRF Modeling Systems*

224 As mentioned in Section 1, we now have the ability to generate high resolution, high-
225 quality, long-term integrations in offline land data assimilation systems such as LIS, which
226 incorporate high resolution, observed forcing and satellite parameter and state datasets. LIS, with

227 its choice of LSMs, parameter and forcing data, and assimilation and calibration modules, can be
228 run in offline (uncoupled) mode for multiyear spinups that can then be used to initialize coupled
229 models such as NU-WRF.

230 NU-WRF is NASA-GSFC's version of the community WRF-ARW model, and is
231 essentially a superset of the ARW model that includes unique NASA assets and physics
232 capabilities including radiation, microphysics, chemistry, and land surface (via LIS). In addition
233 to providing the soil ICs via LSM spinup, LIS is also coupled to NU-WRF and can be used as the
234 LSM during fully coupled simulations. This is advantageous in terms of utilizing the identical
235 model, grid, and configuration in the offline spinup as during the coupled experiment. The
236 LIS/NU-WRF coupling (Kumar et al. 2008) has been used extensively in research focused on
237 quantifying forecast impacts of different land cover (Case et al. 2011, 2008), irrigation (Lawston
238 et al. 2015), soil condition (Zaitchik et al. 2013), atmospheric forcing (Santanello et al. 2016),
239 LSM calibration (Santanello et al. 2013a), and land data assimilation formulation (Santanello et
240 al. 2016, Feng et al. 2018, Carrera et al. 2018), and serves as an ideal testbed to examine the
241 sensitivity to soil moisture initialization approaches. For this study, LIS version 7 (LISv7.0;
242 lis.gsfc.nasa.gov) is employed with the Noah LSM, version 3.3 LSM (Ek et al. 2003) and coupled
243 to NU-WRF, version 8 patch 4 (<https://nuwrf.gsfc.nasa.gov/>).

244 *c. Off-the-Shelf Products*

245 The Global Forecast System (GFS; Environmental Modeling Center 2003) is an
246 operational, global spectral model driven by the Global Data Assimilation System (GDAS), which
247 incorporates satellite, surface, aircraft, and other observations from across the globe into a gridded,
248 model space. The land component of GFS was upgraded to the Noah LSM version 2.7.1 in the
249 mid-2000's, reducing prominent biases in snow pack, evaporation, and precipitation. The GFS

250 analyses are generated at 6-hourly intervals and gridded at 0.25° spatial resolution (available via
251 rda.ucar.edu/datasets/ds084.1). The North American Regional Reanalysis (NARR; Mesinger et al.
252 2006) uses the Eta model, the Noah LSM, and advances in data assimilation to create long term,
253 consistent weather data at 32-km spatial resolution and 3-hourly intervals (available via
254 rda.ucar.edu/datasets/ds608.0). NARR was the first reanalysis to include precipitation assimilation
255 and shows considerable improvement over the previous NCEP reanalysis system (Kennedy et al.
256 2011). Finally, NLDAS-2 provides near-real time, $1/8^\circ$ (~ 12 -km) resolution, quality-controlled
257 datasets of atmospheric forcing needed to run LSMs, as well as LSM output from four different
258 models driven by these data. We use both the NLDAS-2 meteorological forcing (to drive LIS
259 offline simulations) and the NLDAS-2 model output from the Noah LSM (version 2.8) for land
260 initial conditions, discussed further in the experimental design.

261 *d. Experimental Design*

262 An extensive survey of potential coupled case study dates was performed over a regional
263 modeling domain over the U.S. SGP region (NE, KS, OK, and TX). The initial time of the case
264 studies was limited to those that had full coverage from SMAP at 6am local time, and due to the
265 geographical location and SMAP orbital pattern, this occurred every ~ 6 days. A relatively clear-
266 sky morning, with weak synoptic flow and potential locally-induced convection in the afternoon
267 was desirable. This would allow local land effects due to surface and soil moisture heterogeneity
268 to be maximized. In addition, contrasts in soil moisture across the domain were deemed as
269 advantageous to the goals of this study in terms of highlighting differences in ICs captured by
270 approaches in Fig. 1. Lastly, the Enhanced Soundings for Local Coupling Studies (ESLCS;
271 Ferguson et al. 2016) campaign took place in Summer 2015, which was comprised of 12 IOP days
272 with hourly radiosondes launches during the daytime that were deemed useful for model

273 validation. Taking all of these factors into account, 11 July 2015 was chosen as the primary
274 coupled case study for this study, with 10 June 2015 as a secondary case to support any conclusions
275 made from the July case.

276 Thus, LIS and NU-WRF are run on a single 750-km x 1100-km domain over the SGP at
277 1-km spatial resolution (Fig. 2) using a 3-s time step, GSFC microphysics, GSFC long- and
278 shortwave radiation, Mellor–Yamada–Nakanishi–Niino (MYNN) PBL scheme, and Monin–
279 Obukhov surface layer scheme. NARR and GFS data were used for atmospheric initialization for
280 different simulations that will be discussed below, with 3-hourly lateral boundary condition
281 nudging, and 61 vertical levels. Simulations were initialized at 12 UTC on the morning of 11 July,
282 and run for 24 hours.

283 Each of the soil moisture IC approaches were implemented as in Table 1 for a total of eight
284 coupled simulations. The ‘off-the-shelf ICs from NLDAS-2, NARR, and GFS were performed by
285 using the soil moisture (and temperature) profile ICs from those atmospheric model products.
286 Three LIS spinups were performed beginning on 1 January 2010 through 31 December 2016, the
287 domain of which along with input land cover and soil type data as well as ARM-SGP site locations
288 are shown in Fig. 2. The LIS-Control run used NLDAS-2 atmospheric forcing along with default
289 climatological greenness vegetation fraction (GVF) data from NCEP. Two permutations of LIS
290 spinup were also performed, one using GDAS atmospheric forcing data (LIS-GDAS) instead of
291 NLDAS-2, and the other with real-time GVF data from the VIIRS satellite (LIS-VIIRS) instead of
292 climatological GVF. The goal of the LIS suite of runs was to create a mini-ensemble of the range
293 of IC spread that would be generated from different LSM spinup approaches and forcing/parameter
294 data quality. Atmospheric forcing was varied to provide spread based on uncertainty in
295 precipitation forcing, while GVF was varied to account for uncertainty in soil moisture due to

296 vegetation amount and evaporation. For the three spinup runs, NU-WRF was then run coupled to
297 LIS throughout the 24h simulation, thus ensuring consistency from spinup through coupled
298 forecast in terms of the LSM configuration. The off-the-shelf ICs were taken as described above
299 from the NLDAS-2, GFS, and NARR products which provided the 4 layers of soil moisture and
300 temperature data to the Noah LSM in NU-WRF. Each of these runs employed climatological GVF
301 during the coupled NU-WRF.

302 The model-data fusion approaches to ICs were performed using SMAP data and direct
303 insertion. The SMAP overpass provided nearly complete spatial coverage of the domain, but
304 where necessary, a nearest-neighbor approach was used to interpolate for missing values. For
305 these runs, SMAP was used as the top 5-cm soil moisture data on top of existing NARR and
306 NLDAS-2 soil moisture profiles (identical to those taken off-the-shelf above), which were used
307 for the remaining 3 soil layers (see Table 1 for layer specifications). While direct insertion is
308 certainly not an advisable practice for operational purposes due to the relative biases of SMAP and
309 LSM soil moisture climatologies, it serves a distinct purpose here to provide an upper bounds on
310 what could be expected from data assimilation (where increments would ultimately be much
311 smaller than what is seen here), as well as to see if the biases and noise of SMAP are indeed small
312 enough to begin to consider such approaches as direct insertion. It is possible that introduction of
313 SMAP on top of modeled profiles will result in a shock to the system and cause issues with
314 equilibrium of the soil profile and associated fluxes and states, which also can be examined here.
315 It should be noted that assimilation of SMAP into LIS spinups is an area of active research, and
316 one that deserves independent treatment in future studies. Nonetheless, based on prior soil
317 moisture assimilation experiments we would expect that such a spinup would fall somewhere near
318 or within the spread of the three existing LIS spinups produced here.

319 *e. In-Situ/Evaluation Data*

320 For the offline evaluation of LoCo metric application over the SGP domain, data is
321 acquired from the ARM-SGP network of sites and instruments at the Central Facility (CF) in
322 Lamont, OK, the Plains Elevated Convection at Night (PECAN; Geerts et al. 2017) site at Ellis,
323 KS, and 16 ARM Extended Facilities (EFs) across OK and KS (see Fig. 2ab) These include high-
324 quality, nearly continuous meteorological, surface flux, and atmospheric profile measurements
325 going back to the mid-1990's. Specifically, soil moisture from the recently installed Soil
326 Temperature and Moisture Profile (STAMP) in-situ probes at the CF and 16 EFs are used, and
327 represent a major improvement in ARM-SGP measurements of soil moisture quality and ancillary
328 data (Cook 2018). Surface sensible and latent heat flux data from the Eddy Correlation Flux
329 Measurement System (ECOR) towers at the CF and 7 EFs are also used. Temperature and
330 humidity data at 2-meters is taken from the meteorological sites at CF and EFs. Vertical profiles
331 of temperature and humidity are acquired at the CF and Ellis, KS sites. CF typically provides
332 4x/daily (2 daytime) launches, but as a result of the ESLCS campaign, 11 July produced hourly
333 profiles from radiosonde that could be utilized in the LoCo analysis. Likewise, the Ellis, KS site
334 was a supersite of the PECAN field campaign in Summer 2015 which took additional
335 measurements from ground-based lidar (Weckwerth et al. 2016) to produce temperature and
336 moisture profiles almost continuously during the daytime of 11 July. The radiosondes at CF and
337 DIAL at Ellis were then used to characterize the diurnal structure and evolution of the PBL, derive
338 PBL height estimates, and compare with NU-WRF simulations using LoCo metrics.

339 *f. LoCo Metrics*

340 The integrative nature and application of LoCo metrics to NWP and NU-WRF studies

341 has been described in detail in Santanello et al. (2009, 2011, 2013, 2015). This includes the mixing
342 diagram approach and evaporative fraction versus PBL height metrics that are employed in this
343 study to better understand the impacts of soil moisture ICs on the coupled system, including the
344 PBL response and the relative influence of atmospheric ICs as well. The reader is referred to
345 Santanello et al. (2018) for an overview of LoCo metrics, and resources for the community.

346 **4. Offline Soil Moisture Intercomparison**

347 We first assess the behavior of near-surface soil moisture derived from SMAP, LIS, and
348 in-situ measurements during the offline spinup period, followed by an intercomparison of the suite
349 of soil moisture ICs and the coupled case study impacts.

350 Timeseries of near-surface soil moisture from the SMAP retrieval, LIS simulations, and
351 in-situ STAMP probes are shown in Fig. 3 for three ARM-SGP extended facilities during Summer
352 2016. Overall, SMAP shows a comparable dynamic range to in-situ measurements, responding to
353 precipitation events and drydown periods with little evidence of noise or spurious (outlier) values.
354 To this end, the temporal consistency and absolute value of SMAP soil moisture appear realistic,
355 and comparable to the STAMP measurements. Note that none of these sites were used as part of
356 SMAP calibration/validation activities, and this is a true independent test of SMAP performance
357 across sites with varying vegetation and soil characteristics.

358 The LIS simulations, on the other hand, have a distinct timeseries at E33 (Newkirk, OK)
359 and E38 (Omega, OK) that shows a much narrower dynamic range and values on the wetter end
360 of the soil moisture spectrum (relative to SMAP and STAMP). The spread across the three LIS
361 simulations is rather small overall, but there are brief periods where the quality of atmospheric
362 forcing (GDAS vs. Control; particularly in July and August) and, to a lesser extent, vegetation
363 greenness (VIIRS vs. Control) do impact the soil moisture values. Regardless, the envelope of

364 soil moisture across these simulations is one that is narrow, and it is bounded by a maximum
365 (during precipitation spikes), and a minimum (during dry periods). The timescale of the drying
366 events is controlled by the Noah LSM soil type and hydraulic parameters as specified by the lookup
367 table at each site. At E33 and E38 (and the remaining 17 sites (not shown)), it is apparent that
368 these parameters do not permit the model to dry down at a steep enough rate to reach the drier soil
369 moisture levels observed by SMAP and STAMP.

370 Site E31 (Anthony, KS; Fig. 3c) is shown as an outlier, where LIS soil moisture tracks very
371 close to that observed in terms of absolute range and drydown behavior. Interestingly, this is a
372 site where the prescribed soil type in LIS is sand, but the observed type is silt loam. The hydraulic
373 parameters corresponding to sand are the most extreme in terms of allowing for rapid drying and
374 overall drier wilting point and minimum soil moisture values. So in a sense, at E31 the model
375 obtains a better result for the wrong reasons by designating the site as sand in order for it to exhibit
376 behavior like that of silt loam.

377 Figure 4 presents scatterplots of the timeseries data in Fig. 3, and compares the in-situ
378 STAMP data directly with that of LIS and SMAP. The higher range of soil moisture values in LIS
379 is apparent at E33 and E38, as are the comparable SMAP and STAMP values. The higher peaks
380 during precipitation events in SMAP are also evident, and not unexpected as L-band sensing depths
381 are much shallower during wet conditions (Liu et al. 2012; Escorihuela et al. 2010) and retrievals
382 characterize a wetter and more dynamic quantity of soil moisture immediately after rainfall than
383 at other times (Schneeberger et al. 2004; Rondinelli et al. 2015).

384 The linear slopes that can be seen in the data (e.g. Fig. 4a) actually reflect the inherent
385 drying rates in each product. For example, at E33 LIS has a much lower drying rate (as seen in
386 Figs. 3ab) compared with STAMP, which is reflected in the lesser slope of Fig. 4a (less than 1:1)

387 as compared to that seen in Fig. 4b (nearly 1:1). The greater scatter seen at E38 in Fig. 4c is the
388 result of mismatches in the number of modeled precipitation events vs. those observed locally at
389 this site (as in Fig. 3b). At E31 (Fig. 4e), the tighter relationship and slope approaching 1:1 is the
390 result of the unrealistic sandy soil parameters, as discussed above.

391 A summary of the performance of LIS and SMAP versus that of STAMP at all 17 ARM-
392 SGP sites is presented in Table 2 in terms of bias, unbiased RMSE, and RMSE statistics over the
393 JJA 2016 period. At 13 of the sites, SMAP bias is within +/- 0.04 m³m⁻³ and unbiased RMSE is
394 within 0.06 m³m⁻³, not far from the mission target of +/- 0.04 m³m⁻³ at the SMAP
395 calibration/validation sites, which is impressive given these sites are independent (uncalibrated)
396 and varied in terms of soil type and land cover characteristics. The performance of LIS is largely
397 inconsistent, with quite large bias and RMSE values (> 0.10 m³m⁻³) at a number of sites possibly
398 due to mismatches in soil type versus those observed and the rigid parameter values that determine
399 the overall soil moisture climatology in the Noah LSM. Other potential influences are the rooting
400 depth, litter, and GVF in the LSM not matching what is observed at these sites. The unbiased
401 RMSE statistics for LIS are much better, further indicating the importance of reducing the
402 systematic error in the LIS results and the potential benefit of LSM calibration and parameter
403 estimation approaches.

404 As discussed in Section 1, the ultimate impact of soil moisture on coupled NWP is felt
405 through the surface flux connections of latent and sensible heat. Thus, it is not only important to
406 intercompare the different soil moisture products as above, but also to assess what the implications
407 of those soil moisture characteristics (and climatologies) are in terms of the surface energy balance
408 and transfer of heat and moisture to the atmosphere. In Fig. 5, fluxes from the LIS simulations
409 (averaged across the Control, GDAS, and VIIRS runs) at the three sites in Figs. 3–4 are shown

410 versus those observed by the ARM ECOR stations. Averaged daytime diurnal cycles (hourly data)
411 are calculated for the JJA 2016 period, and they show that at E33 and E38 there is a distinct
412 overestimation of latent heat flux by LIS-Noah. Sensible heat fluxes are generally comparable
413 between the model and flux towers.

414 When looking at all six ECOR sites (Fig. 5d), the overestimation of latent heat flux is more
415 apparent, with differences approaching 200 Wm^2 . However, there is not the typical Bowen ratio
416 compensation of lower sensible heat flux, which indicates (and is confirmed in Fig. 5e) that there
417 is a significant overestimation of available energy in LIS at these sites. The tendency for LIS to
418 have ample soil moisture then leads to the partitioning of excess available energy into latent, rather
419 than sensible, heat flux. A detailed radiation analysis at these sites indicates that the extra available
420 energy in LIS is a result of slight phase differences in downward shortwave radiation from LIS
421 (NLDAS-2 forcing) vs. observed, in combination with a lower albedo in LIS vs. observed over
422 this region. Overall, these higher evaporation rates into the atmosphere should have coupled L-A
423 implications, which may lead to reduced PBL growth, more humidity and lower temperatures near
424 the surface and in the PBL, and could impact moist processes and feedbacks that support clouds
425 and precipitation.

426 **5. Coupled Case Study Results**

427 *a. Intercomparison of Soil Moisture ICs*

428 Near-surface soil moisture from the suite of IC approaches discussed in Section 2 are
429 shown in Fig. 6, valid on 12 UTC on 9 June, 11 July, and 28 August 2015. Although the coupled
430 case study focuses on 11 July, the June and August dates are shown to compare soil moisture
431 conditions earlier and later in the summer season, both before and after the typical seasonal
432 drydown in the SGP region. The spatial heterogeneity of SMAP across the domain is comparable

433 to that of the other products in terms of overall variability and range of soil moisture (from dry to
434 wet). The LIS simulations have the highest spatial resolution (1km) and therefore depict more
435 local-scale features, many of which reflect the soil type dataset. The ‘off-the-shelf’ products show
436 only coarser features, limited by the model resolution in each (ranging from 12.5–33 km). SMAP
437 also shows regions of higher soil moisture (compared to other products) just after precipitation
438 events (e.g. 11 July in Eastern Kansas), which is consistent with the behavior seen in Fig. 3
439 regarding the precipitation peaks in SMAP being larger than observed or modeled using thicker
440 soil layers.

441 Generally, over dry regions SMAP tends to be drier than the other products, while GFS
442 and NARR tend to be wetter. SMAP is known to dry down faster than the Noah LSM (Shellito et
443 al. 2016), and likely has a true retrieval depth that is shallower than the published ‘5 cm’, as near-
444 surface soil layers (top 2–3 cm) dry down much faster than the 5–10 cm layer. The true SMAP
445 retrieval depth is further complicated by vegetation effects and the soil moisture itself, and likely
446 varies both in time and space as a result. The coarse model products (using Noah LSM and the 0-
447 10cm layer) are wetter. This is likely due to a combination of a deeper top soil layer (0–10-cm
448 depth), inaccuracy of the soil hydraulic parameters, and the coarse horizontal model resolution,
449 which all contribute to restricting the model’s response to higher resolution land surface data. LIS,
450 on the other hand, shows regions of very dry soil (consistent with the SMAP patterns) as a result
451 of retaining the 1 km soils information as well as local vegetation and precipitation patterns that
452 allow for more extensive dry downs (particularly in late August).

453 It should be noted that it is not possible to objectively evaluate which is the most accurate
454 soil moisture IC. Each IC approach provides a representation of soil moisture that is reliant on
455 (physical or retrieval) model assumptions, and in-situ data is too sparse to convincingly validate

456 each across a large 1 km resolution domain. However, understanding the differences and what
457 causes them (e.g. resolution, SMAP retrieval, layer depth, input parameters, etc.) is key to
458 understanding the potential coupled impacts of each IC. To better parse out these differences, Fig.
459 7 presents PDFs of the soil moisture ICs in Fig. 6 on each of the three dates. SMAP is skewed
460 towards drier values, as discussed above, and the coarser products are much wetter (GFS, NLDAS)
461 with the LIS runs in between. On 11 July, there is a bimodal distribution in SMAP and the LIS
462 runs, as a result of each capturing the spatial heterogeneity generated by recent localized
463 precipitation over part of the domain creating distinct wet and dry regimes. Notably, the coarser
464 products (GFS) do not capture this bimodal distribution nearly as well. Another striking difference
465 can be seen on 28 August, where GFS is much wetter and more narrowly distributed as compared
466 to LIS, SMAP, and NLDAS-2.

467 Overall, there are three important takeaways from Figs. 6–7, in that 1) the climatologies of
468 soil moisture differ significantly based on the source of the IC (i.e. SMAP, high-resolution LSM
469 spinup, or off-the-shelf products), 2) ICs based solely on SMAP tend to be drier overall, but capture
470 the spatial variability of the region, and 3) stark differences in spatial distributions suggest that the
471 choice of IC is likely to have significant downstream coupled impacts across the domain.

472 *b. Coupled Case Study – 11 July 2015*

473 I. LOCO ANALYSIS

474 Coupled NU-WRF simulations, initialized by the suite of soil moisture conditions in Fig.
475 6b, were performed for 24h beginning at 12 UTC on 11 July, 2015. As described in Section 3,
476 SMAP soil moisture values were directly inserted as the top layer soil moisture in the NLDAS-2
477 and NARR profiles and are referred to as SMAP+NARR and SMAP+NLDAS. The impact of
478 each IC is reflected in the process chain (Eq. 1) variables that connect soil moisture to evaporation

479 (sensible and latent heat flux), PBL evolution (mixed-layer temperature, humidity), PBL height,
480 ambient weather (2-meter temperature and humidity), and clouds and precipitation. Seven hours
481 into the simulation (19 UTC), there are large differences across the runs in each of these variables,
482 reflecting the relative impact of wetter soil moisture conditions on increased evaporation,
483 decreased PBL growth, lower temperature, higher humidity, and modification of precipitation
484 intensity and location. An example is shown in Fig. 8 in terms of soil moisture IC differences
485 between NARR and LIS-GDAS at 12 UTC, and the downstream impacts on latent and sensible
486 heat flux ($\sim 200\text{-}300 \text{ Wm}^{-2}$), PBL height ($\sim 800\text{-}1000$ meters), and 2-meter temperature and
487 humidity ($\sim 2\text{-}3\text{K}$; $\sim 3\text{-}4 \text{ g kg}^{-1}$, respectively) in midafternoon (19 UTC). The impact of the soil
488 moisture IC differences and drier (wetter) regions can clearly be seen carried through towards
489 higher (lower) sensible (latent) heat fluxes, larger (reduced) PBL growth, warmer (cooler)
490 temperatures, and lower (higher) humidity at 2-meters. The relatively drier LIS-GDAS conditions
491 overall support higher sensible heat flux, PBL heights, and temperatures later in the day throughout
492 much of the domain, illustrating the coupled impacts of soil moisture ICs.

493 While Fig. 8 presents a standard single variable assessment, the integrated metrics of LoCo
494 can be used for a more qualitative and comprehensive assessment of the fully coupled impacts of
495 soil moisture ICs. Figure 9 presents the mixing diagram analyses at the ARM CF and Ellis, KS
496 sites for each simulation, along with the derived Bowen and entrainment ratios (as in Santanello
497 et al. 2009). As shown in Fig. 6b and based on SMAP, the CF site is located in a wet region having
498 just received precipitation and Ellis is in the western much drier part of the domain, so there is a
499 natural contrast in conditions at these two sites. At the CF site, the mixing diagram signatures are
500 vertically oriented with little change in humidity throughout the day, as a result of only moderate
501 PBL growth and entrainment and little spread across simulations (Fig. 10a, 11a), as might be

502 expected for a wet site. There is only small divergence in the co-evolution of 2-meter temperature
503 and humidity across the runs, with the exception of the GFS simulation, which employs GFS
504 atmospheric IC/BCs, whereas the remainder of the simulations use NARR. Thus, soil moisture
505 does not seem to impact the results nearly as much as the choice of GFS or NARR atmospheric
506 data at this location.

507 At the Ellis site, there is much larger diurnal variability in temperature and humidity, and
508 larger entrainment fluxes of dry and warm air into the PBL, as would be expected at a dry site.
509 Bowen ratios also vary from 0.73 to 2.55 depending on the choice of soil moisture IC. Once again,
510 GFS is the outlier and evolves differently over time. Overall, the soil moisture ICs are directly
511 reflected in the surface Bowen ratio and EFs (Fig. 9b) with the SMAP-based runs (driest soil
512 moisture) having the lowest EF (high sensible heat flux) and the wetter off-the-shelf products
513 (GFS, NLDAS-2) producing the highest values (high latent heat flux). These differences in surface
514 energy balance are amplified at Ellis (vs. that seen at CF) by the much larger PBL growth and
515 spread across simulations (Fig. 10b, 11b). At this site, the wetter ICs of GFS and NLDAS tend to
516 limit PBL growth while the SMAP and LIS-GDAS runs easily reach over 3 km. It should also be
517 noted that all runs tend to overestimate PBL height at both sites throughout the daytime period, so
518 those with wetter ICs overall that limit PBL growth are closer to observed.

519 Overall, these two contrasting sites demonstrate that soil moisture ICs can impact PBL and
520 L-A coupling, but the magnitude depends on the relative range and spread of soil moisture (and
521 atmosphere vs. soil limited regime) across the ICs, and whether the PBL is sensitive to the surface
522 flux partitioning. A look at the four Noah LSM soil layers for each of the simulations provides
523 further insight as to the potential role of soil moisture ICs. At the CF site (Fig. 12a), the second
524 layer of soil moisture is generally similar across all IC products and greater than 0.25 m³ m⁻³.

525 This second layer (10-40 cm) represents more of the root zone, and thus controls the majority of
526 evapotranspiration. These soil moisture values are all in the atmosphere-limited regime, and there
527 is little difference across simulations with each producing high evaporative fraction that limits
528 PBL growth.

529 On the other hand, at the Ellis site (Fig. 12b) conditions are much drier, particularly in the
530 root zone, for the LIS and NARR ICs, but wetter in the second layer in NLDAS and GFS. This
531 creates a disparity in EF (Fig. 10b) across ICs. Furthermore, the SMAP direct insertion into
532 NLDAS-2 versus NARR produces different surface flux and resultant PBL growth as a result of
533 the wet (NLDAS-2) vs. dry (NARR) root zone of each. At this site, it is not the dry SMAP near-
534 surface soil moisture that controls the surface energy balance, rather the deeper soil layers which
535 in this case are derived from NLDAS-2 and NARR. This is an important result in that it highlights
536 the potential limited role of SMAP on L-A coupling if combined with other products that are not
537 consistent (and why a direct insertion approach is not recommended), even when SMAP is much
538 drier than the layers below.

539 II. LAND VS. ATMOSPHERIC IC IMPACTS

540 Having parsed out the soil moisture IC impacts, it is worthwhile isolating and examining
541 the impact of the atmospheric ICs as well, given the outlier behavior of the GFS simulation seen
542 in Fig. 9. Fig. 13 shows mixing diagrams and evaporative fraction versus PBL height analyses,
543 for only the GFS and NARR simulations, at the CF and Ellis sites in addition to two other sites
544 (36.0 N, 100.0 W; 39.0 N, 97.0 W) across the domain that represent different surface and
545 atmospheric conditions. Mixing diagrams can be used to show the diurnal behavior of humidity
546 (x-axis) and temperature (y-axis) simultaneously with the surface latent and sensible heat flux
547 vectors and atmospheric response (PBL entrainment and advection) vectors. In Fig. 13, the mixing

548 diagram plots show an initial dry bias in GFS 2-meter humidity at 12 UTC (7am local time) relative
549 to that of NARR and that observed at CF and Ellis. The ensuing daytime evolution of temperature
550 and humidity then differs considerably across the sites. At the CF site, GFS and NARR remain
551 parallel to each other, with the initial dry GFS bias persisting throughout the day (with comparable
552 temperature evolution in each). Fig. 13b shows that the EF (i.e. land ICs) and PBL height (i.e.
553 initial atmospheric profiles) are similar in GFS and NARR, and hence there was no coupled
554 mechanism to impact the GFS humidity bias during the day. In addition, low-level winds were
555 weak and variable, thus limiting any potential impact of horizontal advection.

556 In contrast, at Ellis the initial dry bias in GFS is overcome by NARR by the end of the day,
557 with NARR drying out significantly. This can be explained by the drier soil moisture IC at this
558 site in NARR, which promotes lower EF, combined with significant PBL growth and dry air
559 entrainment, and generates a PBL with lower humidity. NARR humidity ends up further from the
560 observations at this site, likely due to a dry IC of soil moisture. As NARR atmospheric IC/BCs
561 were used to drive all the soil moisture IC permutations except for GFS, this is an important result
562 particularly as the LIS and SMAP ICs tend to be even drier than the default NARR ICs (and thus
563 even further from observed 2-m humidity).

564 At the third site (Fig. 13ef), the GFS initial dry bias is apparent, but then eroded over time
565 with GFS approaching similar humidity values of NARR (which does not dry out during the day).
566 Each has similar soil moisture ICs at this site, so the land influence is eliminated. However, a
567 closer look at the vertical profiles of temperature and humidity (not shown) indicate that in GFS
568 the PBL grows more slowly and into a more humid layer than NARR, which tends to increase and
569 cap the overall humidity in the PBL including at 2 meters. At the final site (Fig. 13gh), the GFS
570 dry bias is also reduced over time as a combination of afternoon moistening in GFS and drying in

571 NARR, despite having similar soil moisture ICs and evaporative fraction. This can be attributed
572 to a combination of deeper PBL growth and dry air entrainment in NARR, along with GFS
573 eventually reaching a phase of PBL growth into a more humid layer in the afternoon (not shown).

574 Overall, these results demonstrate that land, atmospheric and PBL ICs and processes can
575 have varying relative impacts on L-A coupling and ambient weather prediction. They also suggest
576 that it is unlikely that changes in a single component of initialization (e.g. soil moisture) will have
577 uniform or spatially/temporally consistent impacts on NWP across the domain of interest, and will
578 still be modulated by the land or atmospheric conditions (and inherent biases) being introduced
579 elsewhere in the coupled system.

580 III. AMBIENT WEATHER STATISTICS

581 Following this approach, typical NWP benchmarking statistics can now be examined under
582 the context of LoCo and land versus atmospheric ICs. The LoCo analysis in Figs. 9–12 focused
583 on two well-instrumented sites with contrasting soil moisture conditions. However, as shown in
584 Fig. 8, there are widespread and larger impacts seen across the full domain particularly with respect
585 to 2-meter temperature ($\sim 2\text{--}6$ K) and humidity ($\sim 2\text{--}6$ g kg⁻¹). It is these ambient weather impacts
586 that are particularly important to NWP operational centers in terms of forecast performance and
587 improvement, as well as public perception.

588 Figure 14 shows the 2-m RMSE and bias statistics timeseries for temperature and humidity
589 from each of the coupled NU-WRF simulations, for the 24h period beginning at 12 UTC on 1 July
590 2015. These statistics were calculated hourly based on the NCEP ADP Global Upper Air Surface
591 Weather Observations (<https://rda.ucar.edu/datasets/ds337.0/>) dataset that includes 153 sites
592 sampled across the SGP domain. This is a typical NWP center approach, focused on sensible
593 weather impacts that are readily observable, when assessing the impacts of new datasets,

594 parameters, physics, ICs, and data assimilation. A bird’s eye assessment of Fig. 14 in this context
595 may be that soil moisture ICs do not have large or systematic impacts on temperature and humidity
596 forecasts, and in effect it would be difficult to conclude which is the ‘best’ IC. For the daytime
597 period (7am–7pm), it could be argued that NLDAS-2 and GFS have the lowest RMSE values and
598 biases, and that SMAP and the LIS runs have the largest. This would be counterintuitive to the
599 idea that NLDAS-2 and GFS are coarse, default and off-the-shelf products whereas LIS and SMAP
600 are higher-resolution and observationally-driven. This may lead to conclusions that improved land
601 ICs do not improve NWP.

602 However, based on the knowledge gleaned in the prior sections using integrated LoCo
603 metrics, we can better understand these results in the context of the role of land versus atmospheric
604 ICs, in particular that of soil moisture and SMAP. The lowest daytime temperature errors (Fig.
605 14ab) are seen in GFS and NLDAS-2, and the highest are in the SMAP+NARR simulation. As
606 GFS and NLDAS are the wettest ICs in terms of soil moisture, these act to reduce the overall warm
607 bias across the domain, while the SMAP and NARR runs are the driest, which tends to amplify
608 the warm bias over the domain. In terms of temperature bias overall, there is a slight warm bias
609 at initialization that is then amplified throughout the day, which is likely a result of a net radiation
610 (driven by downward shortwave and underestimation of localized cloud cover) overestimation at
611 the surface driven by the NU-WRF (GSFC) radiation and microphysics schemes in combination
612 with lower than observed surface albedo in LIS (as in the offline case). However, while the
613 temperature biases (Fig. 14b) appear to remain relatively constant over the daytime in each of the
614 runs, the actual locations of these biases shift significantly over time from the northern to southern
615 part of the domain (Fig. 15bcde).

616 The humidity statistics (Fig. 14d) also indicate that NLDAS-2 tends to have the lowest
617 bias, and that all the NARR-driven runs tend to dry out rapidly during the daytime despite higher
618 quality atmospheric ICs, with the driest (SMAP+NARR) runs performing worst. The GFS run
619 and the IC dry bias can be clearly seen here, even across all 153 sites in this analysis, and overall
620 remains constant during the daytime. Once again, the wetter soil moisture ICs tend to perform
621 best, as they are countering an inherent warm, dry bias in the coupled system. The envelope of
622 RMSE and biases in these plots is generally narrow, but these are averages across many points and
623 a large domain.

624 The inflection point seen in the temperature bias at 7–9pm is a notable feature as well in
625 these results, and is due to late afternoon precipitation in the northern part of the domain which is
626 overestimated compared to observations, and tends to cool down the region overall (compensating
627 for the warm biases in the south). What follows in the SMAP direct insertion runs is a linear
628 decrease in temperature bias, and a significant cooling that takes place during the entire nighttime
629 period (unrelated to precipitation) particularly in the western part of the domain. This is, in fact,
630 due to the direct insertion of much drier SMAP values on top of NARR and NLDAS-2 profiles.
631 As discussed earlier, this approach is not recommended as it disrupts the soil moisture and
632 temperature equilibrium from the top layer vs. three deeper layers in the Noah LSM. This direct
633 insertion did not show negative impacts during the daytime, and as mentioned it was often the root
634 zone soil moisture of NARR and NLDAS that dominated the surface energy balance. At nighttime,
635 however, the very low SMAP soil moisture and 5-cm upper soil layer led to changes in the thermal
636 properties of the near-surface soil that promote rapid cooling at night. The thermal impacts of the
637 daytime were overcome by the dominance of evaporation, but it is evident that a more robust

638 approach to merging SMAP with existing soil profiles from other products should be performed if
639 using as ICs for NWP.

640 Fig. 15 shows an example of how these 2-meter statistics vary in space and time, and in
641 response to the initial SM differences in GFS and NARR. These results indicate that there is much
642 more divergence across runs regionally and at specific sites than is evident in the lumped timeseries
643 statistics, often ranging in magnitude to near 6 K and 6 g kg⁻¹ in temperature and humidity,
644 respectively. The initial dry bias in GFS is evident across much of the central and southern SGP
645 (Fig. 15g), while NARR shows a slight wet bias. Because NARR soil moisture is drier than GFS
646 (Fig. 15a) especially over the central part of the domain, NARR ends up with a strong dry humidity
647 bias by the end of the day, whereas GFS improves its initial dry atmospheric bias where the soil
648 tends to be wetter. The location of the warm bias and shift from north to south over the course of
649 the day mentioned above is also apparent in Figs. 15bd. These plots show the components that
650 must be simultaneously considered when interpreting NWP statistics and assessing new
651 parameterization or initialization approaches, including the background atmospheric IC biases, the
652 change in land surface ICs, and the evolution of each as dictated by the LSM and PBL schemes
653 throughout the day.

654 Overall, this analysis demonstrates that the aggregated statistics commonly employed by
655 NWP centers are often not systematic in space or time, and can miss the important nuances and
656 drivers behind them thus confounding the conclusions made. In essence, each point in Fig. 15 has
657 its own ‘coupling story’ that is dependent on many factors, and thus a change to the land IC (or
658 LSM physics) is unlikely to produce uniform impacts or improvements. At the same time, any
659 perceived improvement could be compensating for errors elsewhere in the system. Although it
660 takes a bit more work using integrated analyses to understand these impacts, it becomes necessary

661 for a true assessment of the impact of soil moisture (or any other IC, physics package, or parameter
662 dataset) in coupled prediction.

663 **6. Discussion and Conclusions**

664 This study provides a review of current soil moisture initialization approaches used in
665 NWP, and in particular those employed by the regional weather and climate (i.e. WRF) research
666 and operational communities. Land ICs are often overlooked by atmospheric scientists, and as a
667 result there have been a wide range of approaches employed using vastly different datasets in terms
668 of quality and resolution. Soil moisture tends to get most of the focus (vs. soil temperature) due
669 to its strong control on surface energy balance and surface fluxes which are the only true LSM
670 variables that the atmospheric model is sensitive (and coupled) to. Here, we isolate the impacts of
671 these varied soil moisture initialization approaches on coupled forecasts using a very pragmatic,
672 yet integrative (in the L-A sense) approach using NASA's LIS, SMAP, and NU-WRF assets.

673 Results and their implications for NWP modeling communities are as follows:

674 1) Offline analysis of satellite, in-situ, and LSM products confirms that SMAP soil
675 moisture performs quite well in terms in spatial and temporal consistency (i.e. low noise),
676 capturing heterogeneity, precipitation and drydown events, and overall looks like a 'real'
677 observable soil moisture field.

678 2) There remains an observability issue due to differing LSM and observed (satellite and
679 in-situ) soil moisture climatologies that are largely due to differences between LSM
680 physics and the actual soil hydraulic properties and vegetation characteristics which affect
681 the satellite and in-situ measurements.

682 3) There is a wide variation in the spatial distribution of soil moisture across commonly
683 used NWP initialization approaches, including those from satellite-infused, high-resolution
684 LSM spinup, and ‘off-the-shelf’ atmospheric model based products.

685 4) The sensitivity of coupled impacts is not limited to the near-surface soil layer as the root
686 zone may still play a dominant role in governing surface fluxes and L-A coupling, thus
687 limiting the potential impact of near-surface layer observations in isolation.

688 5) Coupled impacts of land ICs are clearly visible downstream in the NWP forecasts
689 (including surface fluxes, PBL evolution and entrainment, and ambient weather), and can
690 be better understood and quantified using integrated LoCo metrics.

691 6) By simultaneously assessing land vs. atmospheric ICs in a LoCo framework, the
692 question of whether improvements in traditional NWP statistics are achieved for the right
693 reasons can better be addressed, and in turn shed light on the true potential impact of
694 improved soil moisture ICs.

695 It should be noted that additional case study simulations were performed in June 2015,
696 (Fig. 4a), and the results were largely consistent with those from 11 July. Specifically, a warm
697 atmospheric IC bias dominated the region, and as a result the wettest soil moisture ICs (once again
698 the coarse GFS and NLDAS-2 products) produced the best 2-meter statistics. As for the July case,
699 in isolation this would suggest that the coarse soil moisture products are better than the high-
700 resolution or observed products, when actually the coarse products are only best for this particular
701 modeling system and atmospheric forcing where they are correcting inherent biases. Studies that
702 show uniform impacts (e.g. drying) after satellite assimilation across a wide domain are likely to
703 see some improvements in sub-regions simply as a matter of luck, correcting for inherent model
704 biases (and vice-versa for degradation).

705 This underscores the importance of understanding inherent coupled model behavior before
706 introducing new datasets or ICs, so that their impacts can be more accurately assessed. As satellite
707 data continues to improve in quality and resolution, there can be greater incorporation of more
708 accurate observations into coupled models. Understanding their impacts requires quantification
709 of process-chain impacts in order to avoid compensating errors. It will be difficult for highly-
710 tuned systems to incorporate new datasets and see direct improvements as a result, but the
711 approaches here will help aid in identifying what remaining model biases and deficiencies exist in
712 order to further fully integrated model development and improvement.

713 While the statistical significance of the limited number of deterministic simulations
714 performed here is clearly lacking, the methodology remains valid as an approach that can be
715 adopted by operational and cycled modeling centers. It is clear from this work that biases and
716 forecast errors can be best understood and improved via integrated (LoCo-type) assessment of
717 relative impacts of land surface and atmospheric (specifically in PBL vertical profiles) ICs that are
718 used to drive the coupled simulations. One example where this can be applied is in the work of
719 Fang et al. (2018), where novel approaches to assimilating satellite-based land surface temperature
720 were performed, and the regional and temporal impacts on 2-meter statistics could be better
721 understood with more integrated process-level understanding. This approach also reduces the
722 potential for mischaracterizing forecast impacts and improvements that may result from
723 compensating errors or misattribution.

724 In terms of the offline soil moisture analysis, it is clear that the governing soil and
725 vegetation physics and parameters in the Noah LSM do not allow for soil drying behavior that is
726 observed from satellite or in-situ. While likely due primarily to soil texture and rigid lookup tables
727 of soil hydraulic properties (setting the maximum and minimum range of soil moisture), there are

728 also potential impacts on soil moisture dynamics from improper rooting depth specification, lack
729 of leaf litter, and inconsistencies in GVF in the LSM versus what is observed. Incidentally, the
730 wetter LIS runs (compared with SMAP) were actually advantageous in the coupled runs due to the
731 warm, dry bias of NARR and GFS. Even when modifying the upper 10cm of soil layering to
732 create a 2, 3, or 5cm top layer, the soil drying dynamics were only marginally impacted indicating
733 there are structural limitations in the LSM that prohibit it from having the observability necessary
734 for unbiased data assimilation or direct comparison of soil moisture with satellite or in-situ
735 observations. Clearly, the structural deficiencies in the LSM and systematic errors need to be
736 addressed via calibration and parameter estimation approaches in order to better match the soil
737 moisture dynamics with those observed. However, avoiding so-called ‘effective’ parameters that
738 absorb additional unrelated model errors and estimating physically meaningful soil characteristics
739 remains a challenge.

740 These results highlight the critical nature of soil type information, parameter lookup tables,
741 and the difficulty in modeling soil moisture dynamics at the local scale using only coarse soils
742 information. It also highlights the relative inflexibility of LSM parameters and soil physics,
743 whereby soil moisture results can only be improved to a limited degree when introducing
744 improved, high-resolution inputs such as atmospheric forcing and vegetation characteristics. To
745 address this, there are community efforts underway in GEWEX focused on reexamination of
746 pedotransfer functions and soils in LSMs, and also to improve the collaboration between the soils
747 and LSM communities themselves.

748 Another interesting result (not shown) is that the soil moisture IC differences at 12 UTC
749 tend to diminish over time throughout the domain (e.g. by 19 UTC). When examining timeseries
750 at specific sites, it is apparent that when comparing two simulations with different ICs, the wetter

751 of the simulations tends to dry down over time and at a more rapid rate than the drier simulations.
752 This can be traced once again to the Noah LSM soil physics and hydraulic parameters that
753 determine the levels of atmosphere and soil limited evaporation. In the case of NLDAS-2 vs.
754 SMAP, for example, SMAP is already very dry and soil-limited such that it doesn't change much
755 or dry out further while at the same time the wetter NLDAS-2 is in a very active evaporative stage
756 and dries out rapidly, thus converging towards the SMAP values. As a result, it is common for IC
757 differences to be dampened over time due to evaporative physics, as opposed to an initial
758 perturbation that is amplified. Exceptions to this occur when wetter soil moisture promotes
759 precipitation, and vice-versa, over a more extended period of time.

760 A related variant of soil moisture ICs can be generated by performing data assimilation
761 during an offline spinup (e.g. Santanello et al. 2016). Based on the largely incremental soil
762 moisture DA impacts in studies to date combined with the results here in terms of the narrow
763 envelope of LIS simulations with different parameters and forcing, it is likely that SMAP
764 assimilation will not lead to vastly different results or ICs. The CDF matching approach to bias
765 correction makes large impacts even less likely, as discussed in Kumar et al. 2015 and Navari et
766 al. 2018. The SMAP direct insertion approach taken here, while not advisable (but still
767 used/published in the community), was chosen as a brute force approach to see what the maximum
768 impact of satellite soil moisture might be on the IC, while acknowledging that any proper EnKF
769 assimilation is likely to impact the ICs to a much lesser degree and be just another permutation of
770 a LIS run. Only via model calibration (discussed above, specifically targeting hydraulic
771 properties) that addresses systematic errors would we expect more distinct ICs and impacts on the
772 LSM climatology and drydown behavior.

773 Ongoing and future work on this topic includes performing formal EnKF data assimilation
774 with SMAP and LIS, as well as LIS calibration using in-situ networks in an effort to improve LSM
775 observability, and reduce the negative impacts of typical satellite bias correction approaches. In
776 addition, the capabilities of SMAP to detect agricultural and irrigation practices (largely missing
777 or mischaracterized in LSMs) are being evaluated in an effort to improve model-data-fusion efforts
778 and aid in offline and coupled model development. It is clear that the community is now
779 demonstrating that the land states and strength of land-atmosphere coupling can play a significant
780 role in the accuracy of ambient weather forecasts. Improving the initial conditions of soil moisture,
781 temperature, and vegetation using NASA satellite observations and assimilation systems therefore
782 becomes even more critical, and the combination of NASA's SMAP, LIS and NU-WRF resources
783 will continue to be used to develop and test these approaches and coupled impacts. As a result,
784 the continuity of missions (beyond SMAP) to provide accurate, global data records of near-surface
785 soil moisture remains important to consider going forward at NASA and other space agencies.

786
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