

An aerial photograph of a city and airport. In the foreground, there's a residential area with houses and a large truck. In the middle ground, an airport runway and taxiway are visible with several small aircraft parked. In the background, a city skyline is visible against a backdrop of green hills and mountains under a blue sky with scattered clouds. Various aircraft are shown in flight, including a large commercial jet, a smaller propeller plane, and several drones. White curved lines represent communication signals emanating from a satellite in the upper right and from ground stations on the ground.

UAV Panel

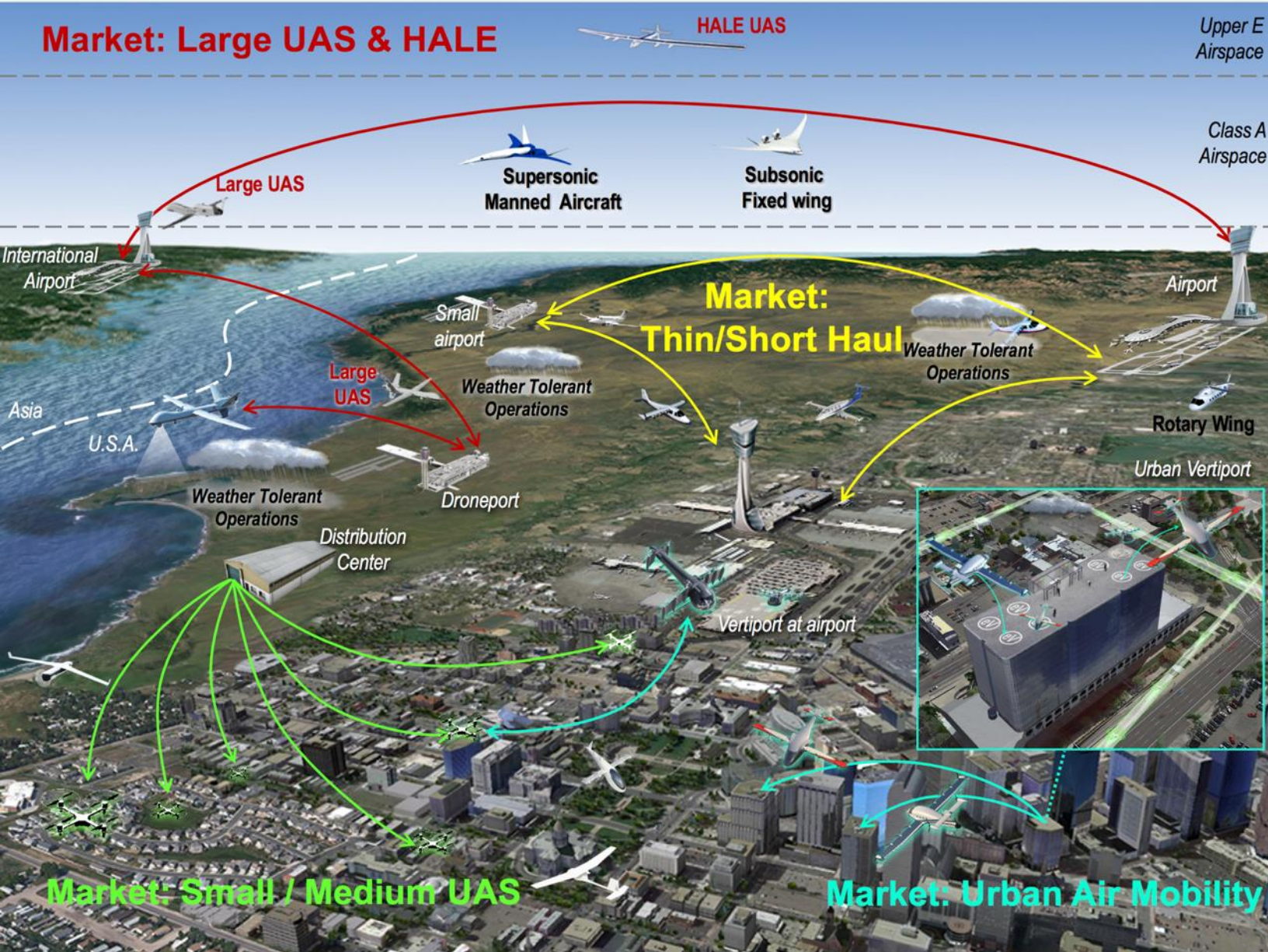
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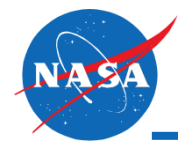
PHM Conference 2018

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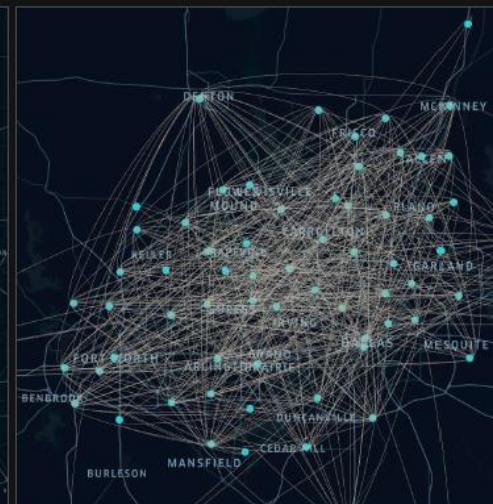
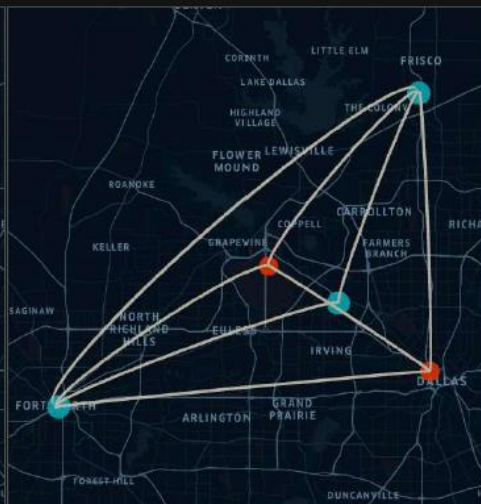


Emerging Aviation Markets





Proposed Crawl, Walk, Run Build-Up



2020

Demonstration flights

Experimental flights

Establish community & user acceptance

Reduced payload and/or range

Modular energy storage solution

2023

Commercial flights

All-electric on day 1

60-mile range

Commercial pilot + 4 pax

Fleets with several manufacturers across 3+ cities

2025

Early scaled operations

5+ cities

300-500 aircraft per city

60,000+ passenger trips per day per city

2030-2035

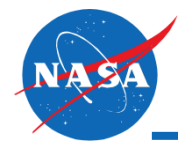
Fully-Scaled Operations

12+ cities

1000+ aircraft per city

100,000+ passenger flights per day per city

No pilot in vehicle (5 pax per flight)



Airspace Operations Requirements

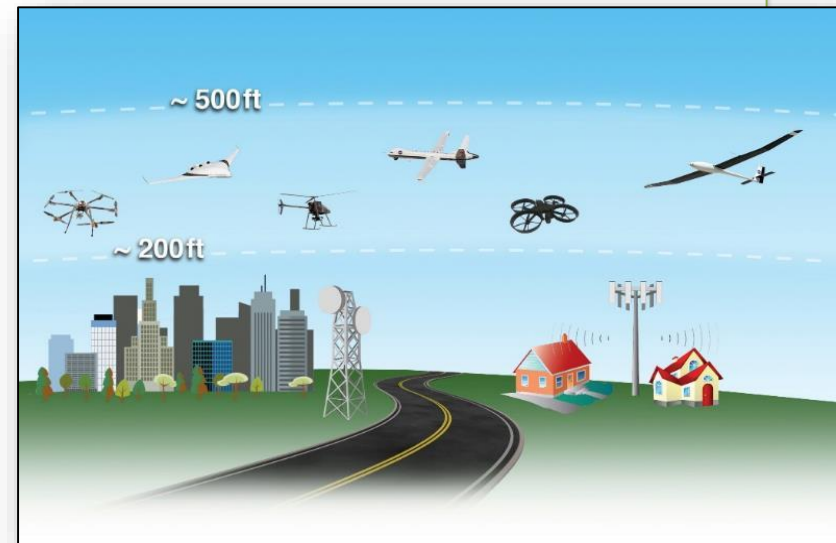
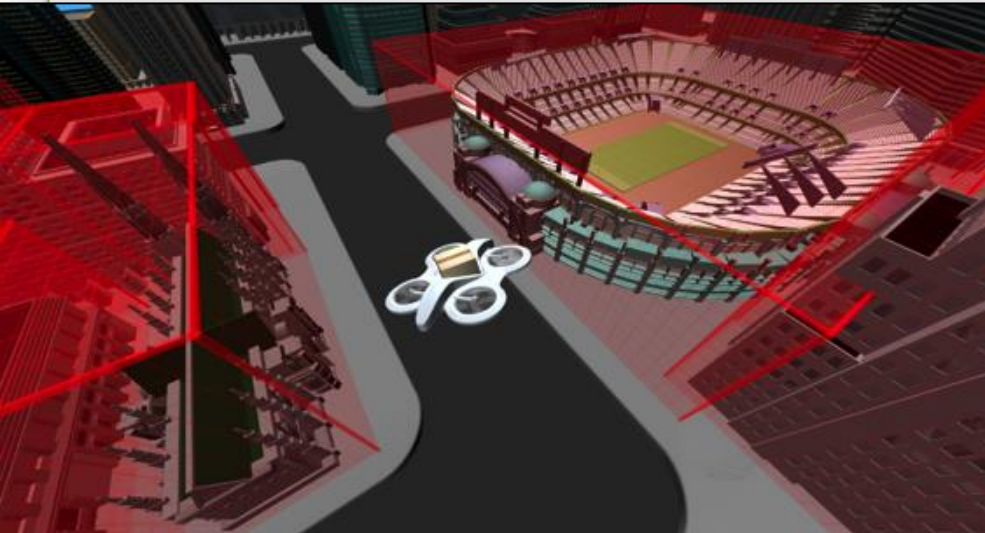
- Air-ground integrated concept of operations
- Roles/responsibilities
- Federated, networked, and interoperable data exchange
- Information architecture
- Airspace configuration (static and dynamic geo-fencing)
- Weather and wind (actual and predicted)
- Demand/capacity imbalance management
- 3D maps
- Track and locate (cell, ADS-B, satellite, pseudo-lites)
- Conflict (V2V, sense and avoid) and hazard avoidance
- Last and first 50 feet operation
- Contingency management

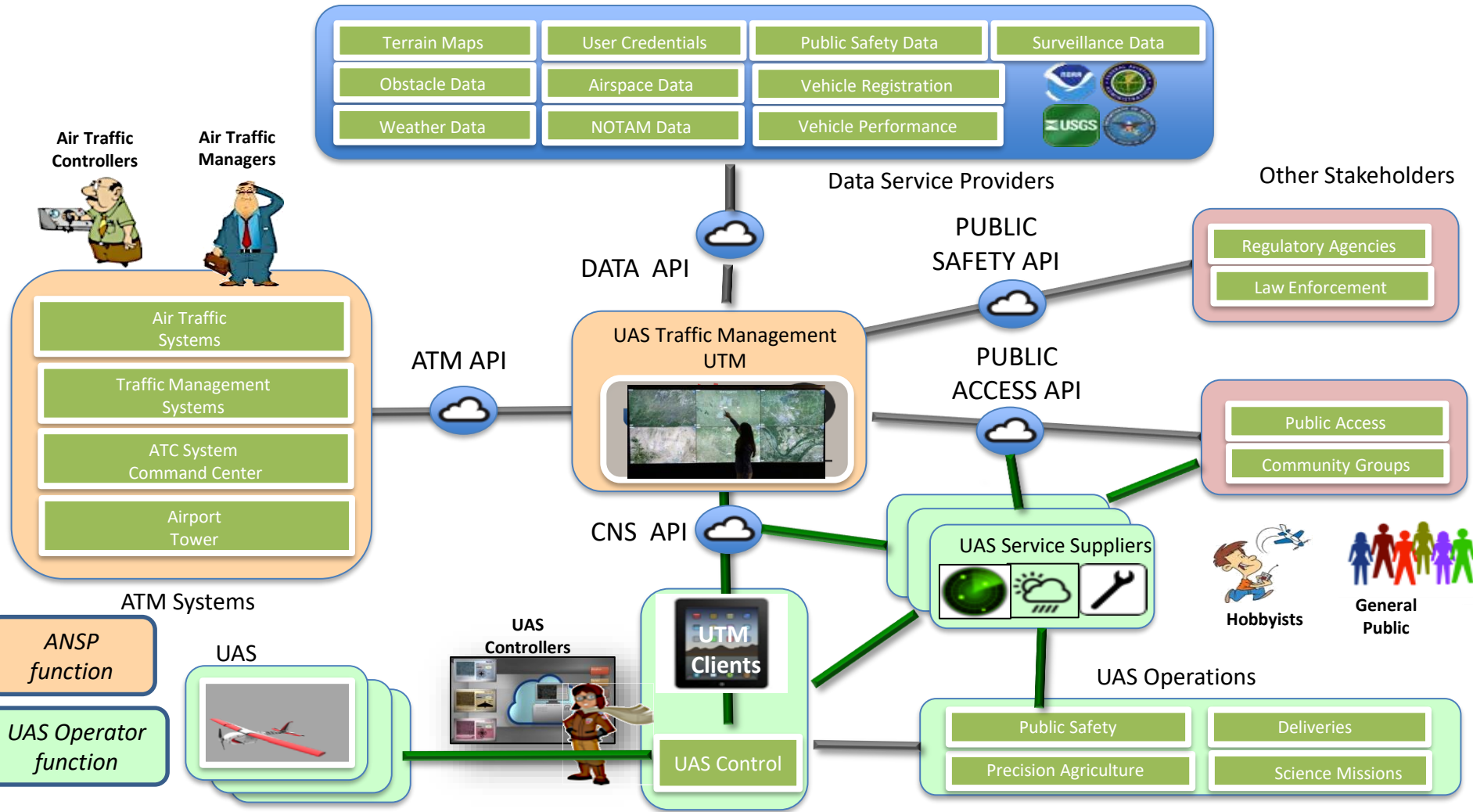
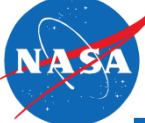


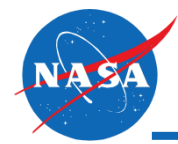
UAS Traffic Management (UTM)

Research Platform that

- (1) Gives situational awareness of all airspace constraints and info about other operations to UAS operators, support service suppliers, and regulators
- (2) Allows to exchange data among UAS operators as well as regulator
- (3) Allows UAS operators to submit flight plans to execute a specific mission in low-altitude airspace, and
- (4) Determines how to safely enable such single or multiple UAS operations either within visual line of sight or beyond visual line of sight
- (5) Integrates airspace and vehicle operations

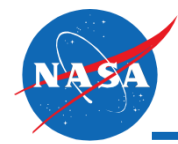






Vehicle Technology Challenges

- Low Size, Weight, Power, and cost – Sense and avoid
 - Detection of obstacles such as wires as well as other moving objects
- Tracking: Cell phone, ADS-B, Satellite, pseudo-lite
- Reliable control system
- Safe landing under failure or safety under malfunction
- Long endurance (45 min current battery life)
- Cyber secure/spoof free vehicles
- Graceful landing in case of failure with low kinetic energy – safe flying around people
- Ultra-low noise vehicles
- Operations under GPS-free or degraded conditions
- Last/first 50 feet safe autonomous operation



System Wide Safety Strategic Thrust

- **Continuous System-wide Safety Awareness (Monitor)**

Technical approaches and required architecture to support comprehensive safety monitoring through acquisition, integration and assurance of sensitive data from heterogeneous sources.

- **Safety Risk Identification and Evaluation (Assess)**

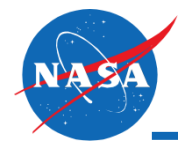
Assured tools that improve the accuracy of real-time detection, diagnosis and prediction of hazardous states and the impact of these states on system safety.

- **Coordinated Prevention, Mitigation and Recovery (Mitigate)**

Trusted methods for dynamic, multi-agent planning, evaluation, and execution of real-time risk mitigating response to hazardous events.

- **Experimentation, Demonstration and Assessment**

Experimentation, demonstration, benefits analysis and transition of new RSSA technologies within all elements of the airspace.

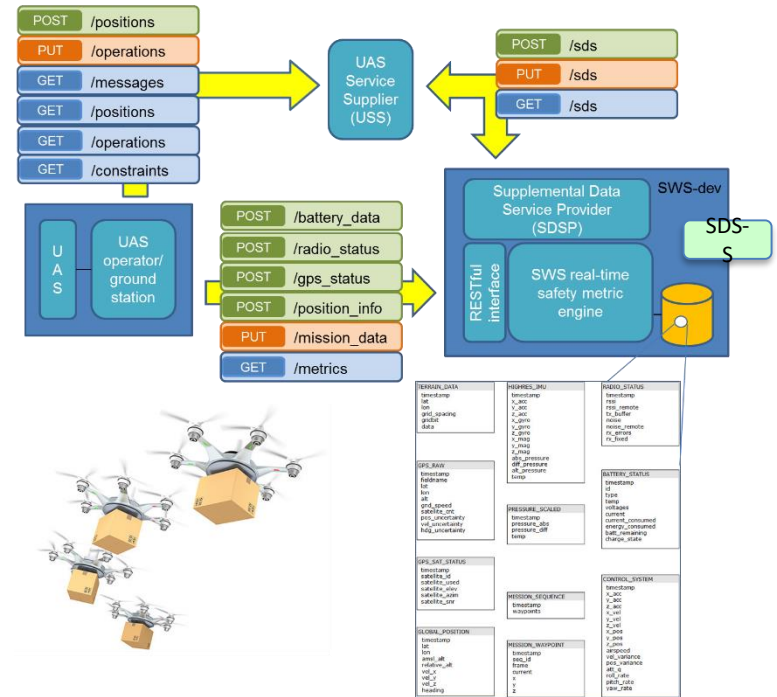


In-Time Safety Monitoring Service

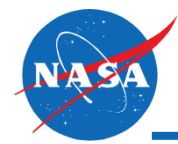
Objectives:

- Apply PHM principles to safety within the UAM domain.
 - Identify relevant in-time risk assessment metrics
 - On-vehicle subsystems considered
 - Electrical powertrain
 - Positioning sensors
 - Communications equipment
- Integrate such a safety framework with the UTM architecture
 - Consider safety assessment a “service” within that architecture
- Conduct flight test to demonstrate feasibility of approach
 - Collect data and publish where possible
 - Flight test planned for Fall 2018
 - Plan to participate in UTM campaign

Notional SWS Risk Assessment SDSP Architecture



MISSION_DATA	MISSION_ID	MISSION_STATUS
timestamp	timestamp	timestamp
lat	x_acc	ris_remote
lon	y_acc	ris_local
alt	z_acc	noise
gndswg	x_gyro	metric_remote
size	y_gyro	ris_bmp
	z_gyro	z_gyro
	x_mag	
	y_mag	
	z_mag	
GPS_RAW	GPS_PRESSURE	BATTERY_STATUS
timestamp	alt_pressure	timestamp
lat	alt_pressure	lat
lon	alt_pressure	lon
alt	alt_pressure	time
alt_speed		volts
sdswg		current
sdswg_max		consumed
sdswg_min		sdswg_consumed
sdswg_uncertainty		sdswg_remaining
		charge_state
GPS_RAW_STATS	MISSION_SCALES	MISSION_REFERENCE
timestamp	timestamp	timestamp
sdswg_max	consumed	x_acc
sdswg_min	sdswg_consumed	y_acc
sdswg_uncertainty	sdswg_remaining	z_acc
		x_gyro
		y_gyro
		z_gyro
		x_mag
		y_mag
		z_mag
GLOBE_POSITION	MISSION_REPORT	CONTROL_SYSTEM
timestamp	timestamp	timestamp
lat	ris_acc	x_acc
lon	ris_gyro	y_acc
alt	ris_mag	z_acc
sdswg_max	ris_gyro	x_gyro
sdswg_min	ris_mag	y_gyro
sdswg_uncertainty	ris_gyro	z_gyro
	ris_mag	x_mag
		y_mag
		z_mag



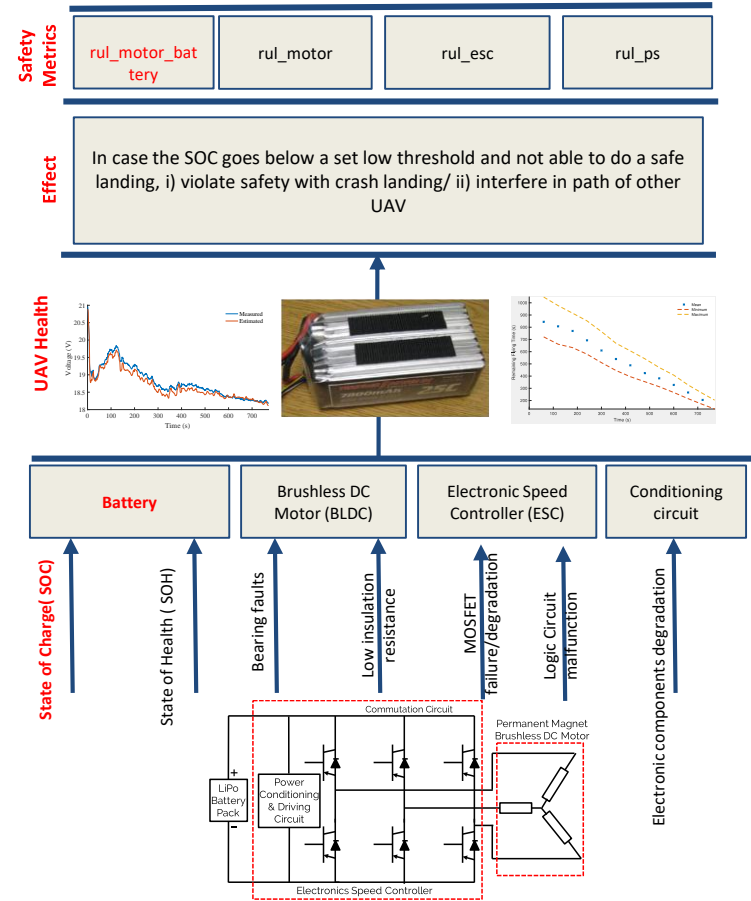
Electric Powertrain Health (EPT)

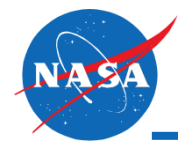
Objective:

- Predict effect of UAV system health on airspace safety in-time for decision-making

Approach:

- Leverage health management framework to predict faults in sub-systems of UAV electric powertrain
- Identify components within sub-systems that may affect its operation and airspace safety
 - Understand propagation timing of fault
 - Some faults progress over a single flight (fast),
 - battery state of charge (SOC)
 - Motor faults (some)
 - Some faults progress over several flights (slow),
 - battery state of health (SOH)
 - electronic speed controllers (ESC)
 - power conditioning circuits (PCC)
 - Select type of sensors and determined needed data rates required for vehicle based on identified faults
 - Model components, simulate, lab tests, flight tests





Baseline Capability Testing

Objective: (1) Test and evaluate baseline architecture and selected functional elements; (2) Collect data to support future development of envisioned capabilities

Status:

- Precursor tests conducted;
- Verification tests in fall

