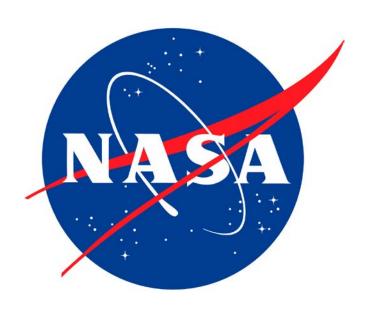
Recent progress in using CYGNSS to investigate relationships between wind-driven surface fluxes and tropical oceanic convection

Timothy Lang, Xuanli Li, Brent Roberts, John Mecikalski, Piyush Garg

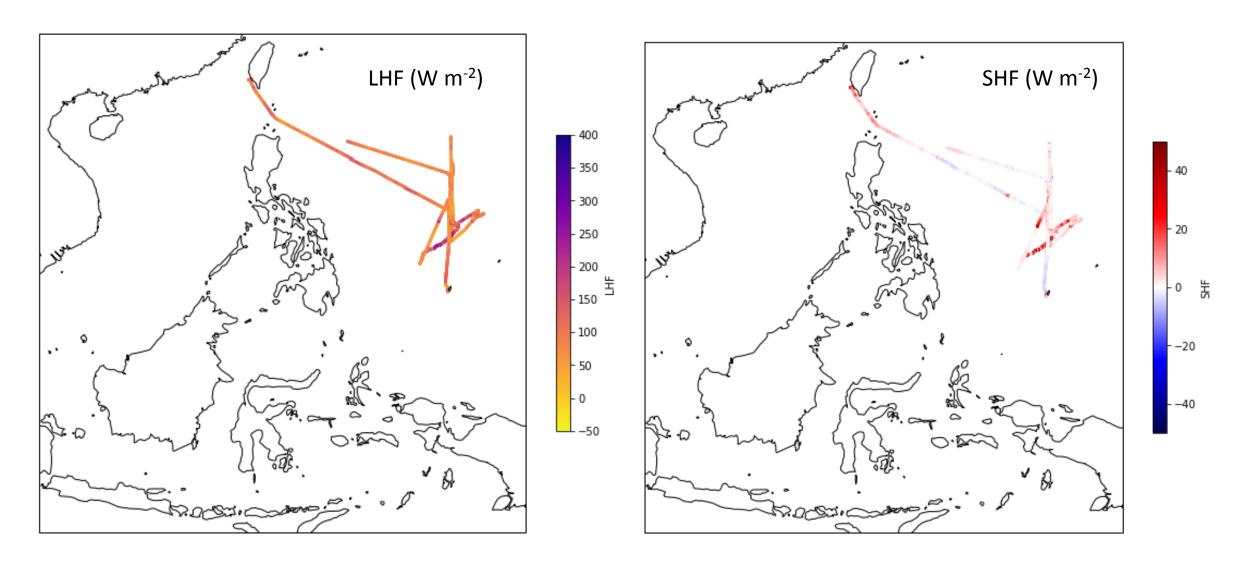


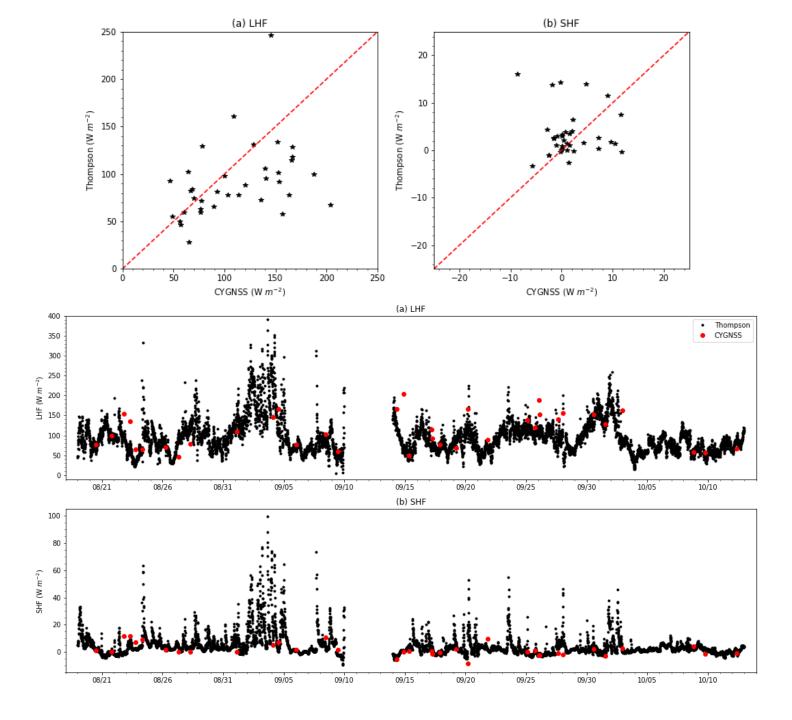


Presentation Overview

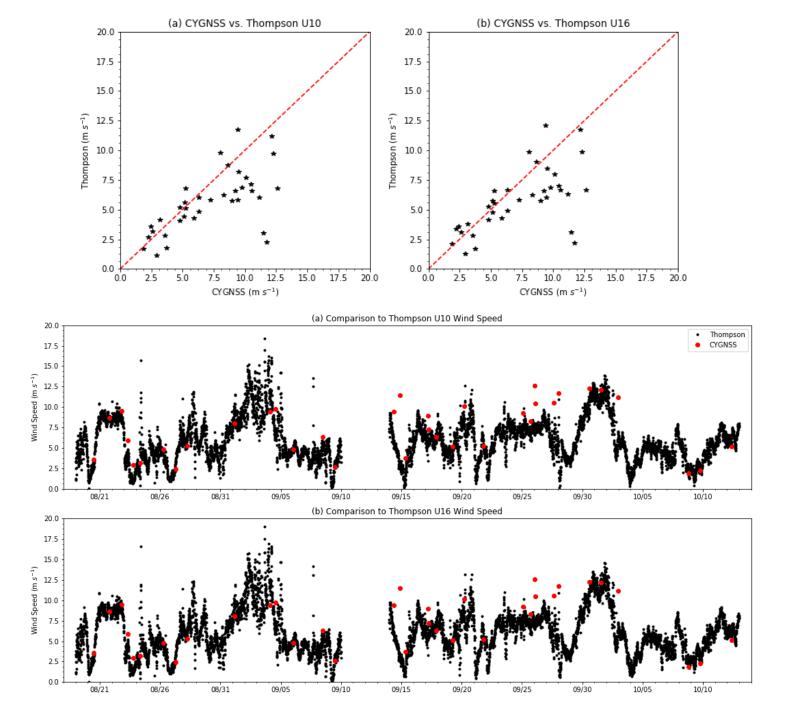
- Comparisons between CYGNSS and PISTON observations
- CYGNSS and MERRA-2 Kalman filter analysis
- CYGNSS tropical convection data assimilation experiments

PISTON Surface Flux Measurements

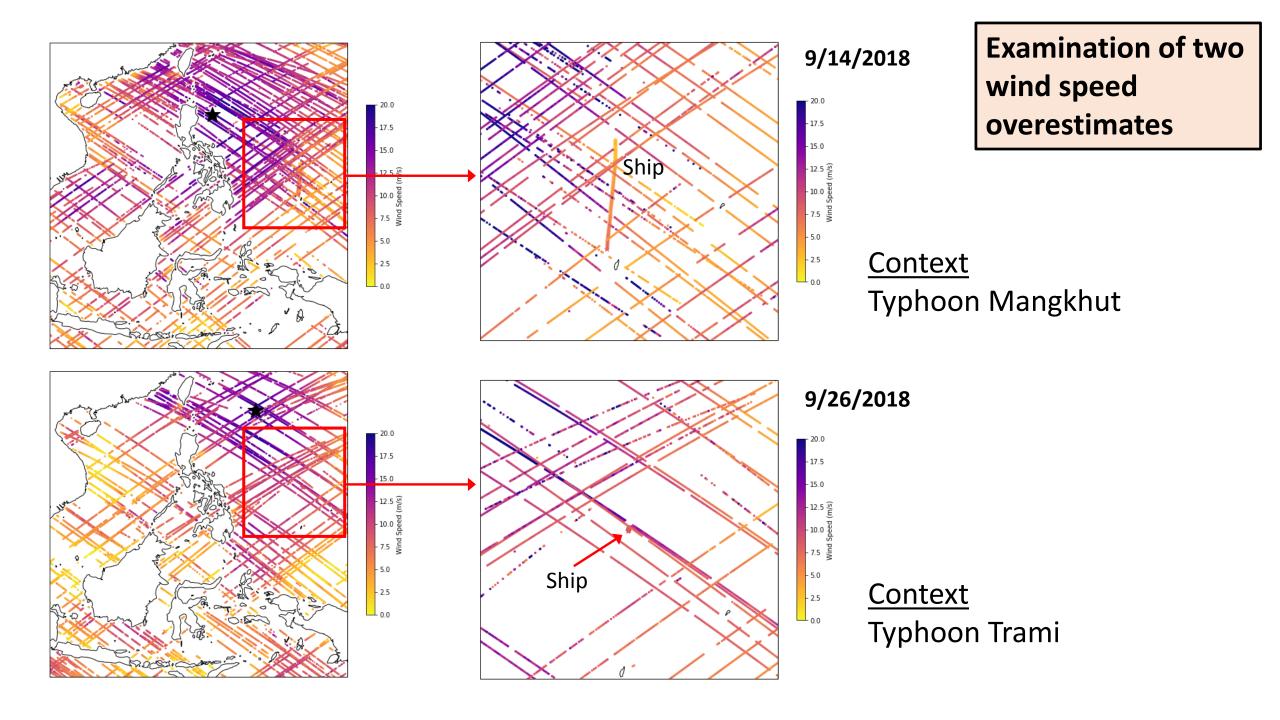


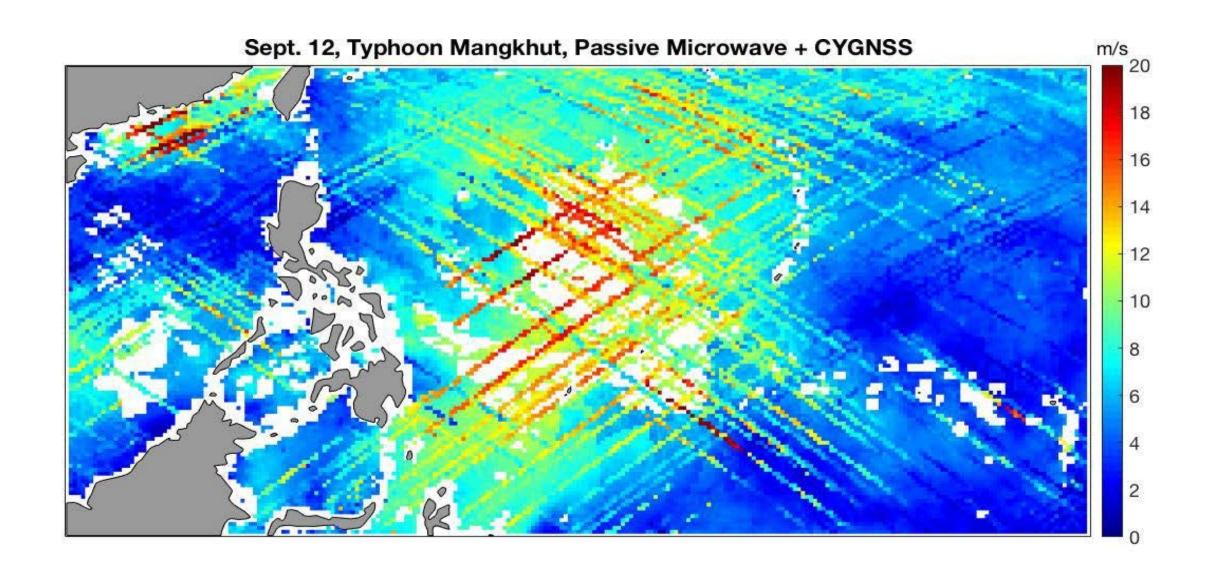


- Hourly averaged observations bookending overpasses within 25 km of ship
- 36 data points
- RMSDs of 50 W m⁻² for LHF and 7 W m⁻² for SHF
- CYGNSS bias is +20 W m⁻² and -2 W m⁻², respectively.



- 36 points for wind speed obs as well
- CYGNSS bias for U10 of +1.7 m/s and an RMSD of 3.1 m/s
- U16 comparison is +1.5 & 3.0 m/s, respectively





Summary

- CYGNSS flux measurements commonly compare reasonably well with PISTON observations, but few data points due to low latitudes of ship and short duration of cruises;
- Flux outliers due to CYGNSS wind estimates; context is ship near outskirts of significant typhoons

Kalman Filtering

- Goal: Generate a blended product that leverages the continuity and modeldynamics based evolution from the reanalysis with the available sampling from CYGNSS
- Challenge: Must take into account uncertainties of the CYGNSS observations and uncertainties in model background/evolution
- Solution: Make use of a local Kalman Filter*, and in particular make use of the "control-input" formulation

$$x_k = Ax_{k-1} + Bu_{k-1} + w_{k-1}, \quad p(w) = \mathcal{N}(0, Q)$$

 $z_k = Hx_k + v_k, \qquad p(v) = \mathcal{N}(0, R)$

where:

 x_k is the desired surface wind speed state, for a single map grid box z_k are CYGNSS observations,

$$A = H = B = I$$
,

 u_k are MERRA-2 hourly time-tendencies, and

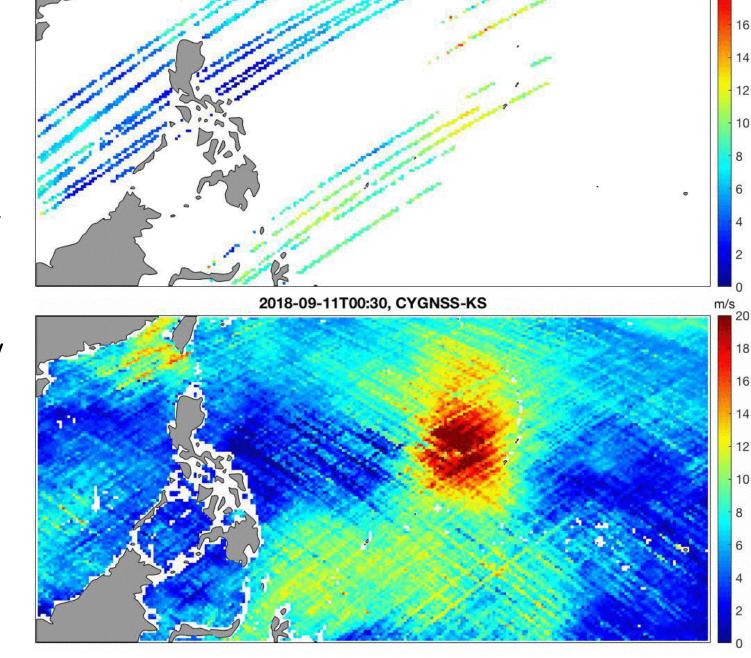
* Actually a Kalman Smoother is implemented using the RTS algorithm

w,v are zero-mean Gaussian noise with process noise Q and observational noise R; We use L3 wind speed errors for v

Typhoon Mangkhut

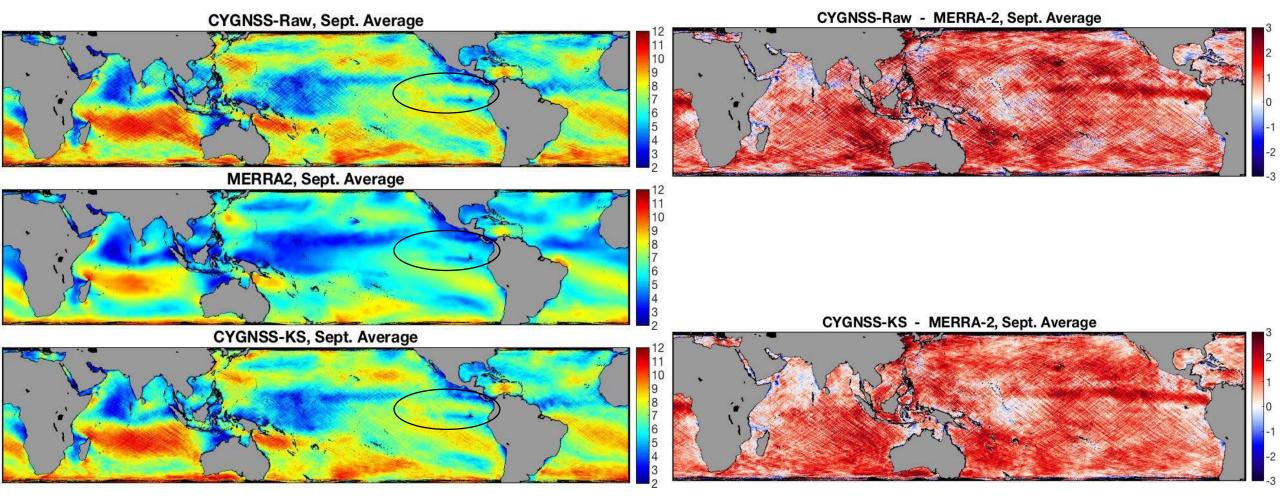
Raw and Kalman Estimate

- Top panel shows the hourly evolution of sampling by CYGNSS (L3) wind speed estimates
- Bottom panel shows the gap-free hourly evolution upon using the Kalman smoother to combine the CYGNSS observed winds with MERRA2.
- With Kalman estimate, we can develop more complete estimates of areaaverage turbulent fluxes, including their temporal evolution



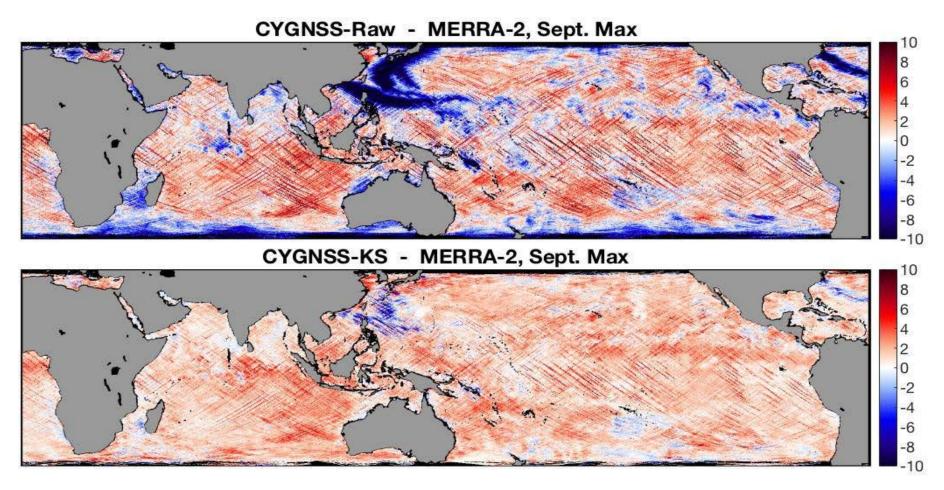
2018-09-11T00:30, CYGNSS-Raw

Monthly Statistics: Mean



- The Kalman smoothed estimates result in a slightly smoother monthly average than the raw observations
- However, the general patterns and amplitudes of the Kalman estimates closely mirror the raw CYGNSS observations

Monthly Statistics: Max Wind



- The CYGNSS raw samples show strong underestimation (compared to MERRA-2) of maximum observed wind in Sept. 2018. This is generally associated with the tropical cyclone storm tracks; This results from both the use of the fully-developed seas retrieval *and* sampling variability around the times of peak winds at a location.
- The Kalman estimates help strongly mitigate the underestimates related to sampling; but, it can't correct for the choice of using the fully-developed seas vs. limited-fetch retrievals

Summary & Future work – Kalman Filter

Summary

 We have developed an implementation of a Kalman Filter to leverage continuous large-scale dynamical evolution fields (i.e., the model tendencies) together with CYGNSS observations to result in a gap-free wind field estimate that can be used to mitigate the need to tradeoff temporal resolution of rapidly evolving systems.

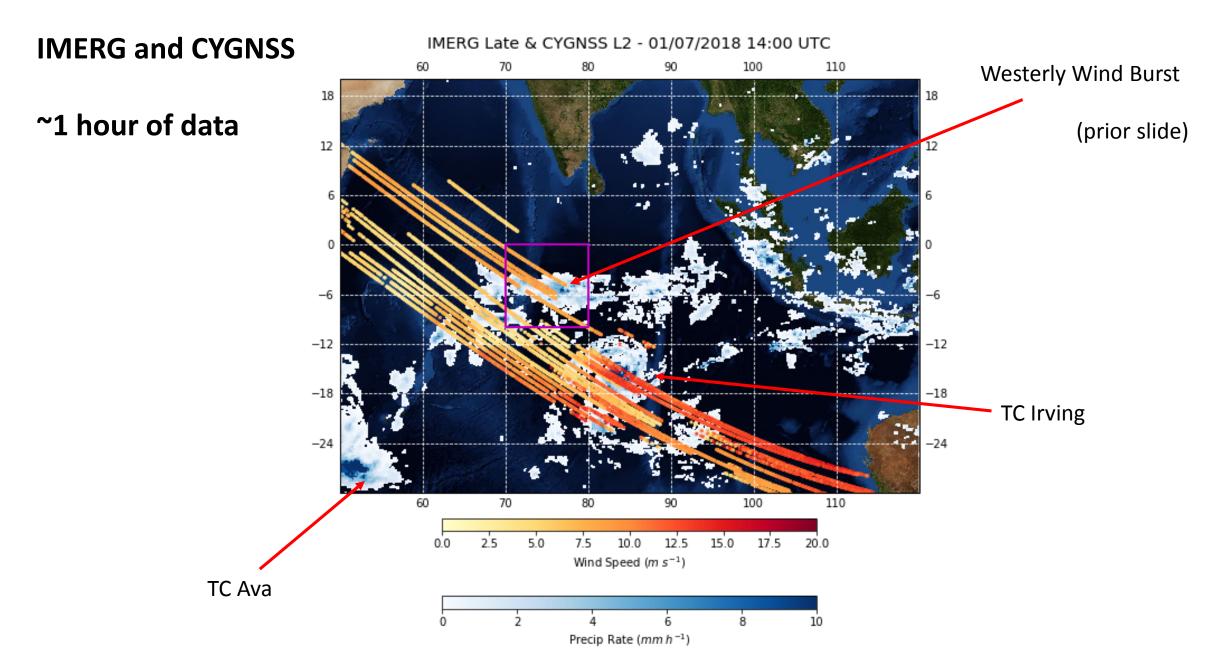
Future work

 Need to consider performing a spatial OI to mitigate the "edge" effects related to high pixel-to-pixel sampling variability. We have already developed code to do this but more testing is needed.

Assimilation of CYGNSS data for tropical convection

Objectives

- 1. Assimilation of CYGNSS v2.1 L2 wind speed data (LF product)
- 2. Assimilation of combined satellite data (IMERG precipitation, ASCAT ocean surface wind vector, and CYGNSS LF wind speed)
- 3. Examination of the impact of CYGNSS data on forecasts of mesoscale convection, specifically on WWBs and TCs
 - **LF "Limited Fetch" Geophysical Model Function (GMF) used for Young Seas**
 - FD "Fully Developed"



Assimilation of CYGNSS v2.1 L2 data for 2018 January MJO

WRFDA hybrid En3dvar (12 members)

WRF Domain: 9 km resolution (450x450x40)

WRF Model Simulation: 00 UTC 6 January – 00 UTC 09 January 2018

Data: CYGNSS v2.1 L2 wind speed

FD: Fully developed sea

LF: High winds for young sea around strong convection

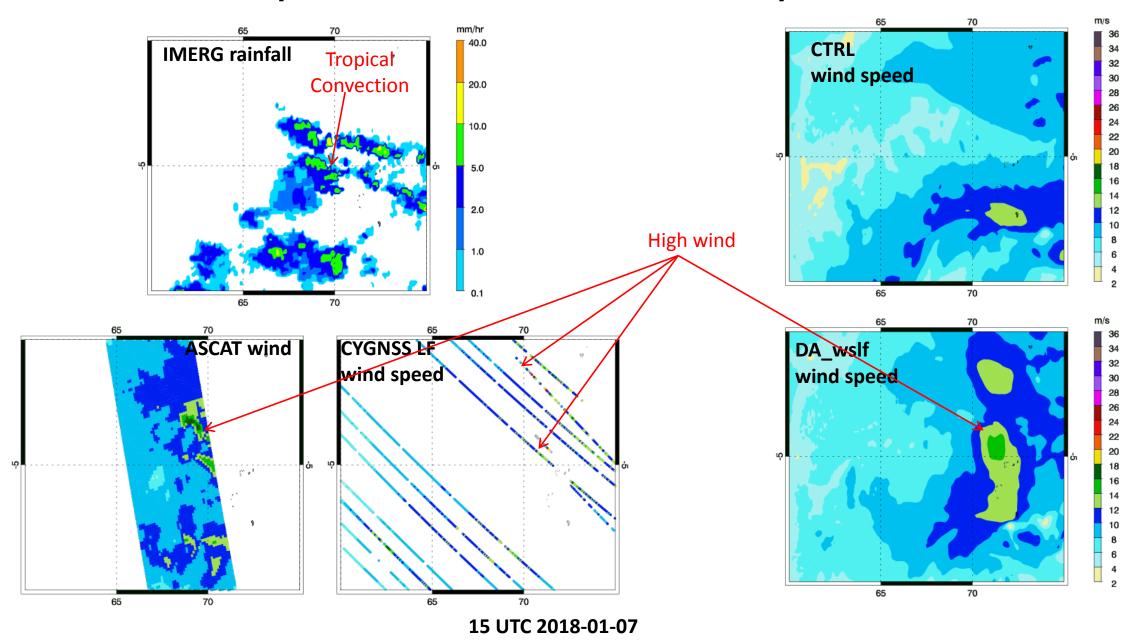
Focus: Continuous assimilation of v2.1 L2 wind speed data for the WWBs and Tropical Cyclone Irving

Observational error: 2 m/s for windspeed < 20 m/s

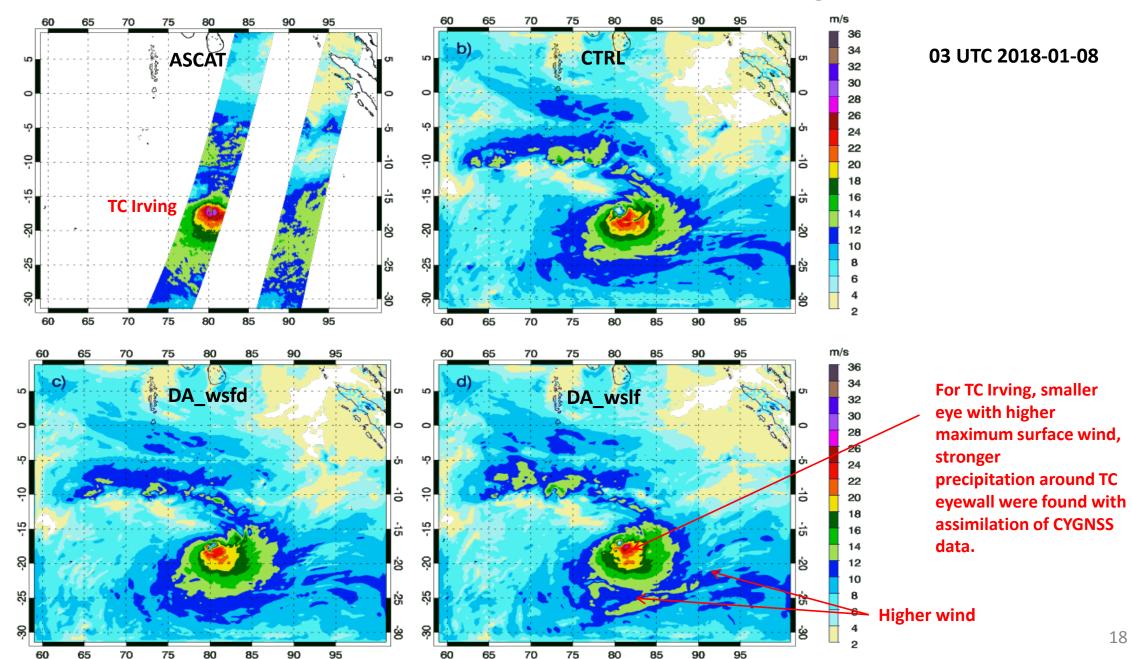
10% for windspeed > 20 m/s

Experiment	Data Assimilation
CTRL	No
DA_wsfd	CYGNSS Level 2 FD wind speed at 00, 12, 15, 21 UTC $06-08$ January 2018 using data ± 1.5 h around the analysis times
DA_wslf	CYGNSS Level 2 LF wind speed at 00, 12, 15, 21 UTC 06 – 08 January 2018 using data ±1.5 h around the analysis times

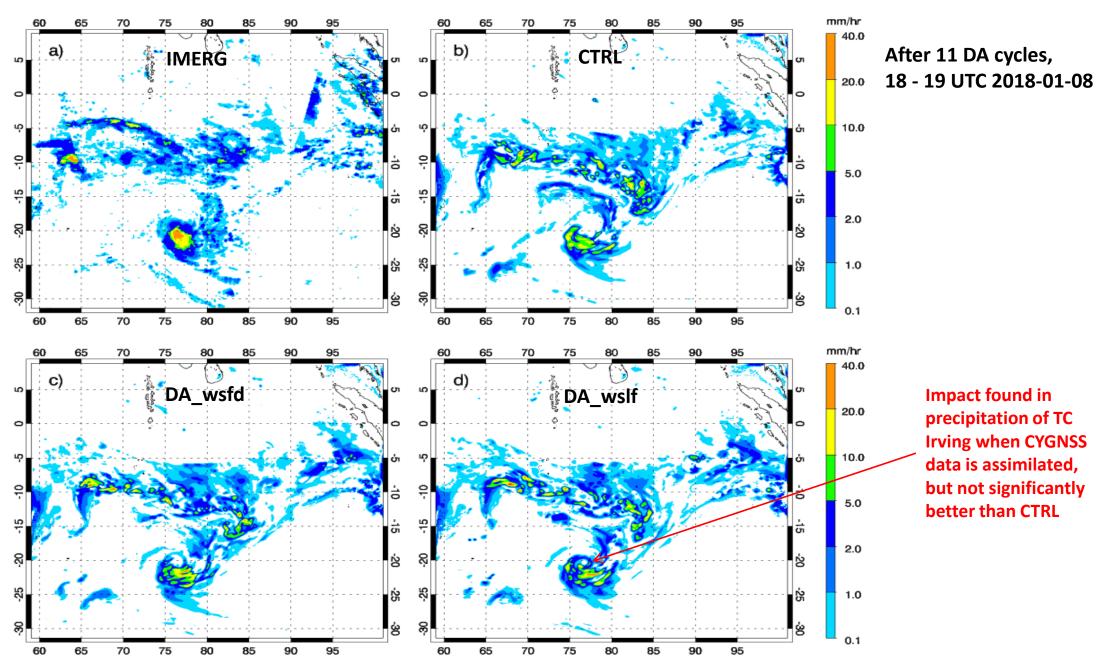
Impact of CYGNSS v2.1 L2 LF wind speed data



CYGNSS data impact – Surface wind of TC Irving



CYGNSS data impact – 1-h Precipitation Forecast

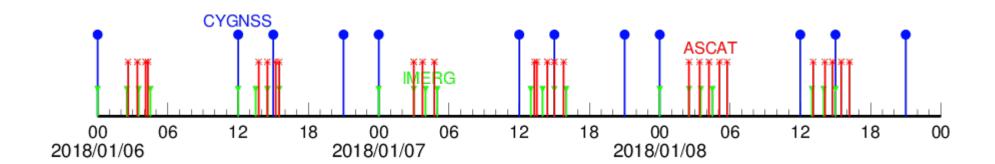


Assimilation of combined satellite data

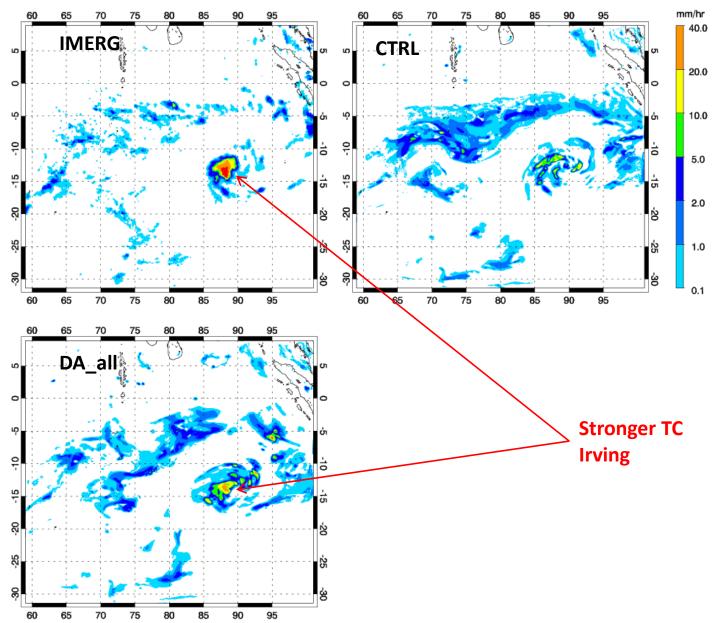
Data: IMERG hourly rainfall, ASCAT ocean surface wind vector, CYGNSS v2.1 L2 LF wind speed

WRFDA hybrid En4dvar (12 members)

Experiment: DA_all (Continuous assimilation of combined data with the following DA window)

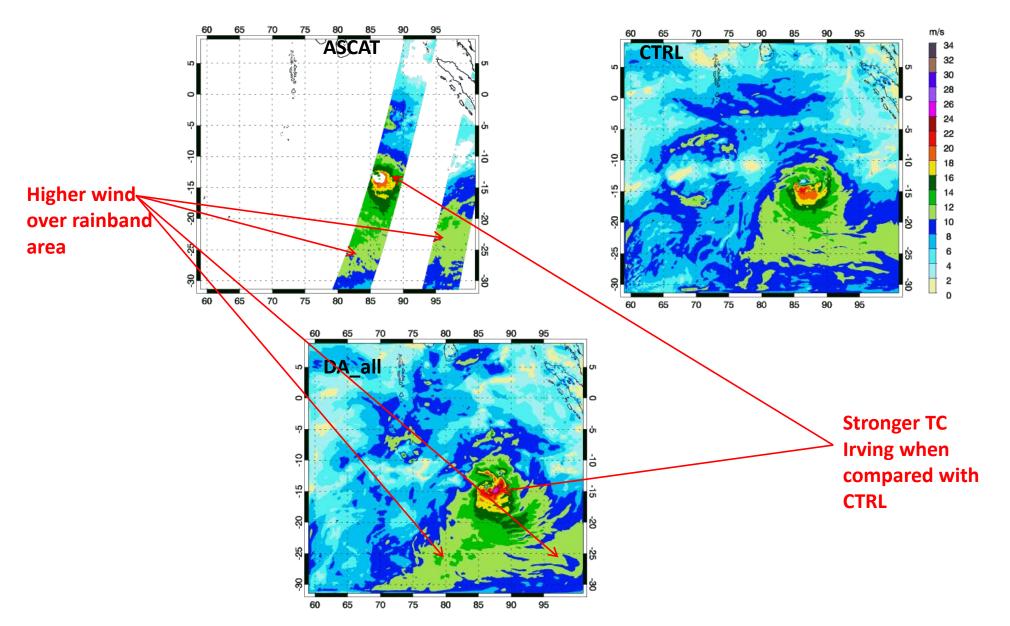


Impact of assimilation combined data on precipitation forecast



After the 3rd DA cycle 12 UTC 2018-01-06

Impact of assimilation combined data on wind forecast



After the 6th DA cycle 03 UTC 2018-01-07

Summary

- CYGNSS v2.1 data observes January 2018 MJO onset and associated WWB
- Positive impact of assimilation of v2.1 LF wind speed data found in wind field of both WWB and TC Irving (LF > FD)
- Impact of CYGNSS v2.1 wind speed data on precipitation is not significant
- Assimilation of combined data (IMERG, ASCAT, and CYGNSS) showed positive impact on precipitation and storm location -- this work is still ongoing.
- Future work: continue assimilation of combined datasets, high resolution simulation (~1km) to take advantage of the high frequency CYGNSS data