

# SAFELY ENABLING LOW-ALTITUDE AIRSPACE OPERATIONS Unmanned Aerial System Traffic Management (UTM)

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# Consumer



# Public Service Commercial





# Integration Challenges

Technology

Detect and Avoid

Command and Control

**Human Factors / Autonomy** 

**Contingency Management** 

Size, Weight, and Power

**GPS-Denied Environment** 

Security

Public

Acceptance

Perception of risk, benefit and capability

Privacy, Liability, Admissible Evidence (Legal)

**Ethics** 

Noise/Environment

**Politics and Media** 

Regulation

Airworthiness

Certification

Registration

**Safety Case** 

Separation Standards

**Operational Flight Rules** 

**Economics** 

**Business Model** 

Size of Market

**Volume and Demand** 

**Market Inertia** 

**Market Entry Strategies** 

**Return on Investment** 

**Allowed Operations:** 

Model Aircraft
Public Operations
Civil Operations



**Rules:** 



# Grand Canyon June 1956

# **Unmanned Aerial System Traffic Management (UTM)**

Near-term Goal: Safely enable initial low-altitude UAS as early as possible Long-term Goal: Accommodate increased demand with highest safety, efficiency, and capacity



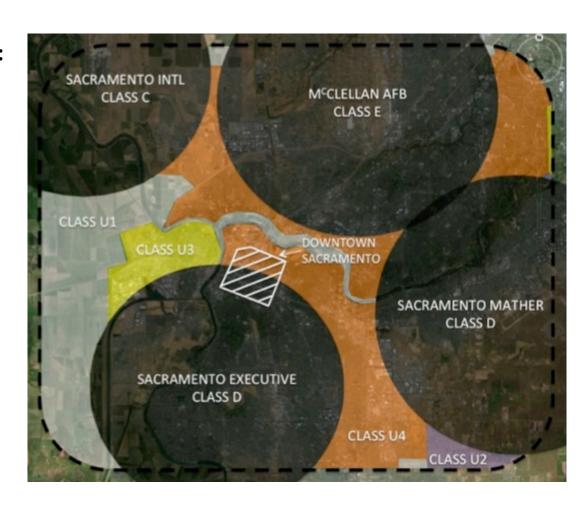
# Airspace Managed by UTM

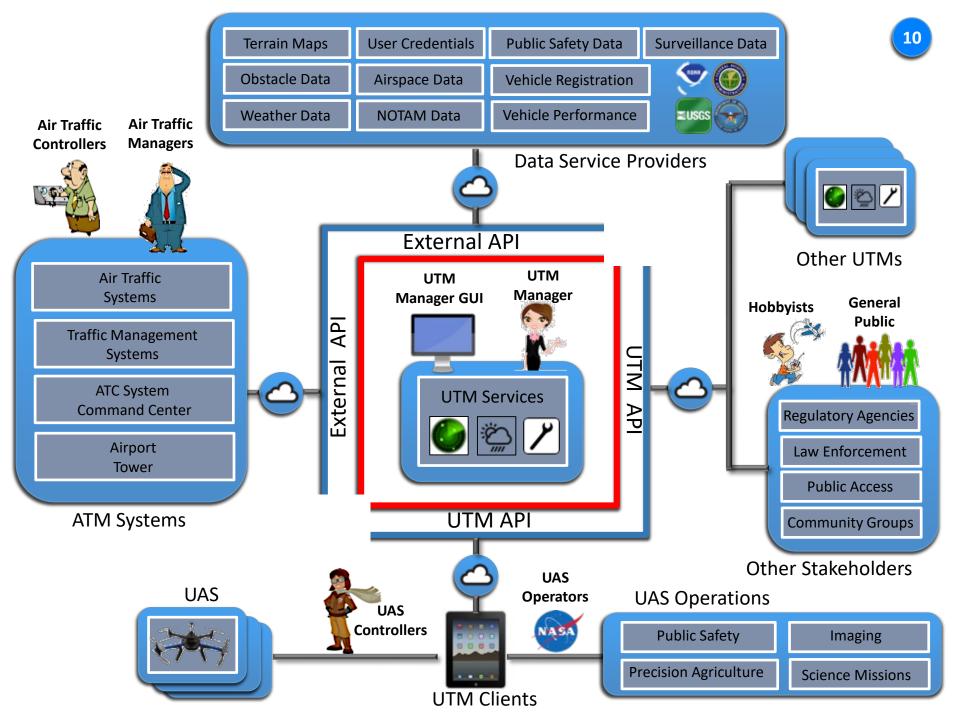
#### Based upon four risk-based criteria:

- Population Density
- Density of Man-made Structures
- Likelihood of Manned Operations
- Number of UTM operations

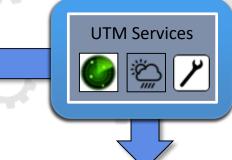
#### **Bounded by**

- Jurisdiction and Airspace
   Management Authority
- UTM Connectivity





# **UTM Services**



- System Health Monitoring
- Vehicle Registration
- User Authentication
- Flight Monitoring

- Flight Planning
- Scheduling and Demand Management
- Separation Assurance
- Contingency Management

**Flight** 

Services

• Spectrum Management

Information Services

Airspace Definition

Terrain and

**Obstructions** 

• Traffic Operations

• Weather Information



Security Services



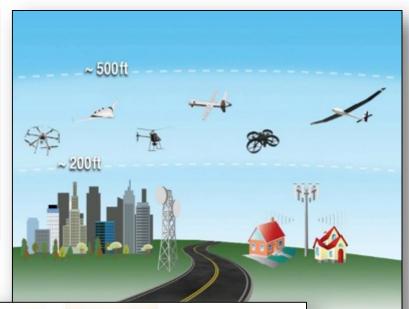


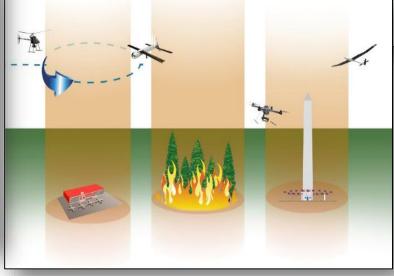
# **UTM Functions**

#### **AIRSPACE OPERATIONS & MANAGEMENT**

- ~500 ft. and below
- Geographical needs and applications
- Rules of the airspace: performancebased
- Geofences: dynamic and static







### **UTM Functions**

#### WIND & WEATHER INTEGRATION

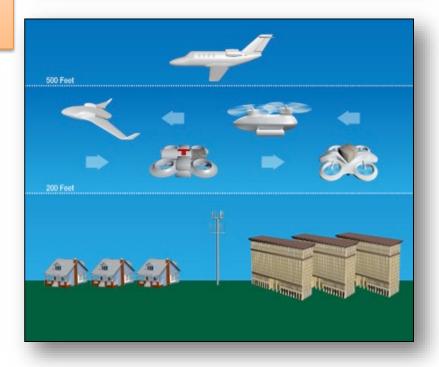
Actual and predicted winds/weather

#### **CONGESTION MANAGEMENT**

- Demand/capacity imbalance
- Only if needed corridors, altitude for direction, etc.







### **UTM Functions**

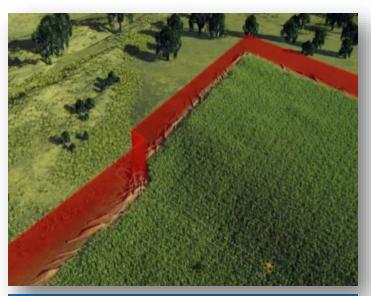
#### SEPARATION MANAGEMENT

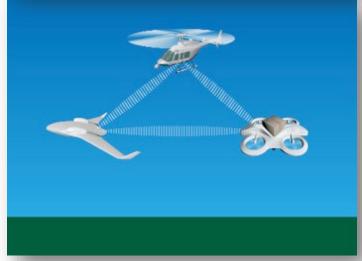
- Airspace reservation
- V2V and V2UTM
- Tracking: ADS-B, cellphone, & satellite based

## **CONTINGENCY MANAGEMENT**

- Large-scale GPS or cell outage
- 9-11 like situations







# Example Use Case: Precision Agriculture

- 1 Operation Plan Submitted (4am) LOS, 200 ft AGL, 6-7:30am, Circular Pattern (0.25 NM radius)
- 2 Operation Plan Rejected- Building Over-flight 3 Operation Plan Resubmit- Accepted



- 4 UAS Controller Observes Clear Skies and sends "ALL CLEAR" message to UTM (5:55am)
- 5 Aircraft Takes Off (6:00 am) 6 UTM Reports Adverse Weather- UAS Controller continues (6:30 am)
- 7 Mission Complete- UAS Lands (7:15 am) 8 UAS Controller Terminates Operation Plan (7:20 am)

# Build 1: August 2015

Line of Sight Operations
Low Risk Environment
Airspace Reservation
Geo-fencing for Separation
No Fly Zones
User Authentication

# **Build 2: October 2016**

Beyond Line of Sight Operations
Low Risk Environment
Segmented Flight Plans
Weather and Traffic Advisories
Altitude Stratification
Contingency Management (Alerting)
System Health Monitoring



# **Build 3: January 2018**

Beyond Line of Sight Operations
Suburban Environment
In-Flight Separation Provisions
Contingency Management (Resolutions)
On-demand Public Service Operations
Spectrum Management
Interacting UTMs
Limited Connections to ATM
Weather and Traffic Avoidance

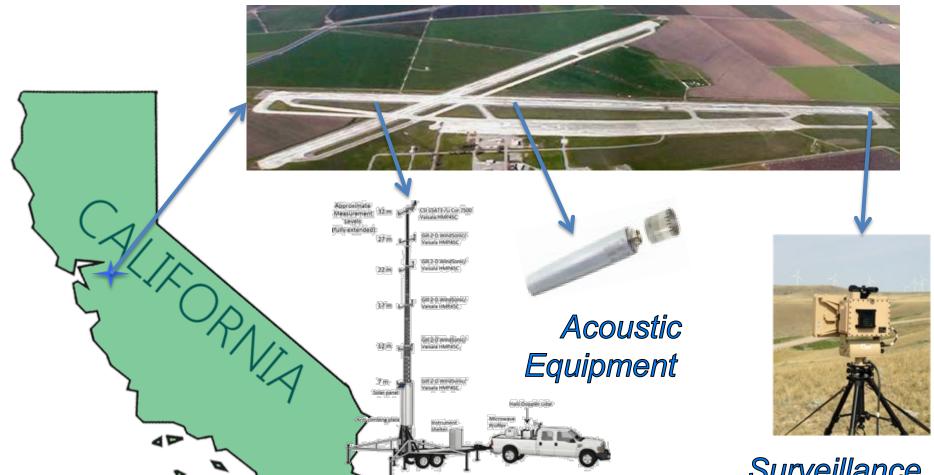
# Build 4: March 2019

Beyond Line of Sight Operations
Urban Environment
Detect and Avoid
GPS-Denied Environments
Large Scale Contingency Management
Dynamic Airspace Reconfiguration
High Density Operations



# UTM Build 1 Flight Test

# Crows Landing, CA



Weather

Equipment

Surveillance Equipment

# **Demonstration Objectives**

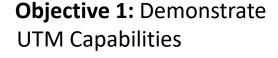
**Objective 5:** Collect Data on Noise Signature of UAS Vehicles





**Objective 2:** Collect Data on UAS Navigation Performance Error

**Objective 3:** Collect Data on Aircraft Tracking Performance





**Objective 4:** Collect Weather Observations for Forecasting Models





# **UTM Build 1 Demonstration Highlights**

- 8 Different types of UAS (2 fixed wing, 6 multi-rotors)
- Variety of surveillance, weather, and acoustic equipment
- Flight included 2 aircraft conducting missions simultaneously
- General Statistics:
  - 108 flights over 8 days
  - ~18 hours of flight time
  - Flights averaged about 11 minutes (ranging from 2- 38 minutes)
- Data analysis is being conducted and a draft report is expected by the end of Nov. 2015

- UAS is a divisive, multi-faceted topic
- A variety of integration challenges need to be overcome
- UTM is a solution to safely manage airspace for UAS operations
- Near-term goal is to safely enable initial lowaltitude operations within 1-5 years

