



Development of a High-Propellant Throughput Small Spacecraft Electric Propulsion (SSEP) to Enable Lower Cost NASA Science Missions

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Outline

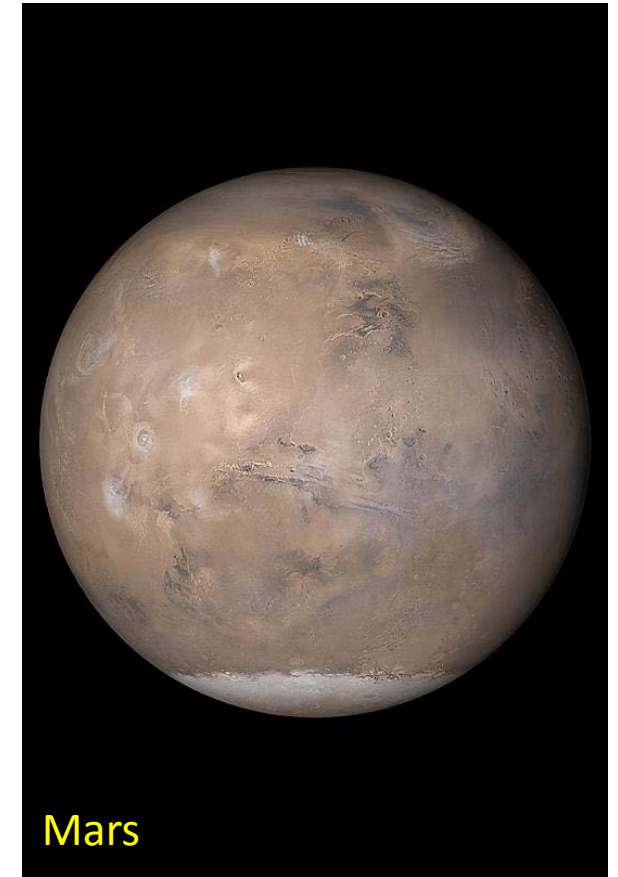
1. Motivation
2. Background
3. Stakeholders, CONOPS, and Requirements
4. Thruster and PPU Development
5. Test Results
6. Concluding Remarks

HT-SSEP: High-Propellant Throughput Small Spacecraft Electric Propulsion

Motivation

“NASA is ... expanding the use of lower-cost CubeSats and SmallSats to accomplish our science goals,” NASA Strategic Plan 2018

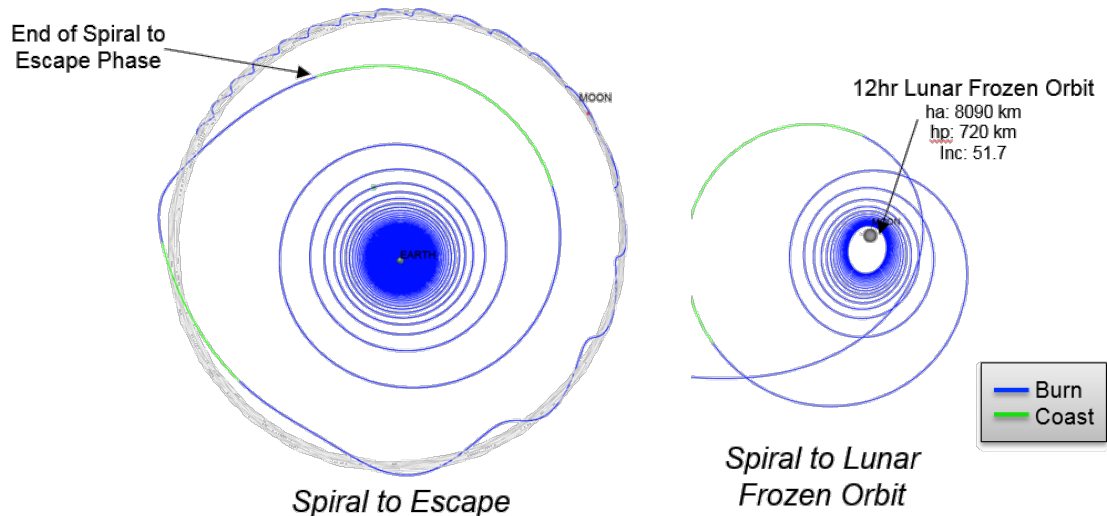
- The lower development cost of smaller spacecraft have the potential to increase the cadence of NASA missions.
- Interesting destinations within reach include asteroids, moons, and Mars.



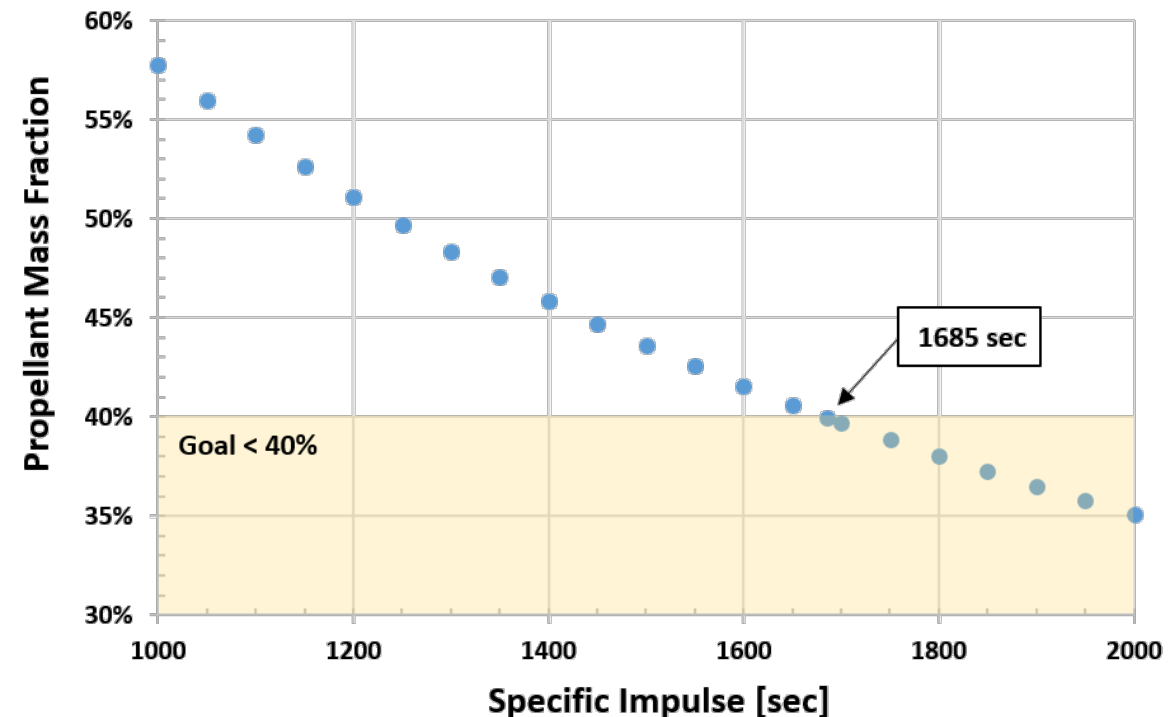
Example Mission Requiring HT-SSEP

A pair of small spacecraft in a 12-hour lunar frozen orbit could provide near continuous communication between Earth and rovers or other science instruments located near the poles.

- **Delta-v requirement ~ 7.1 km/s**
 - transfer from 350-km LEO to 12-hr lunar frozen orbit.
- **Specific impulse > 1685 s**
 - to achieve a S/C propellant mass fraction less than 0.4.
- **Assume 200-kg S/C, 80-kg propellant**
 - 69.9 kg used for transit.



Spacecraft Propellant Mass Fraction Required to Transit from 350 km LEO to 12-hr Lunar Frozen Orbit (Assumes 7.1 km/s, 2% residual, 5% margin, 5 kg remaining at destination)





Example Mission Requiring HT-SSEP

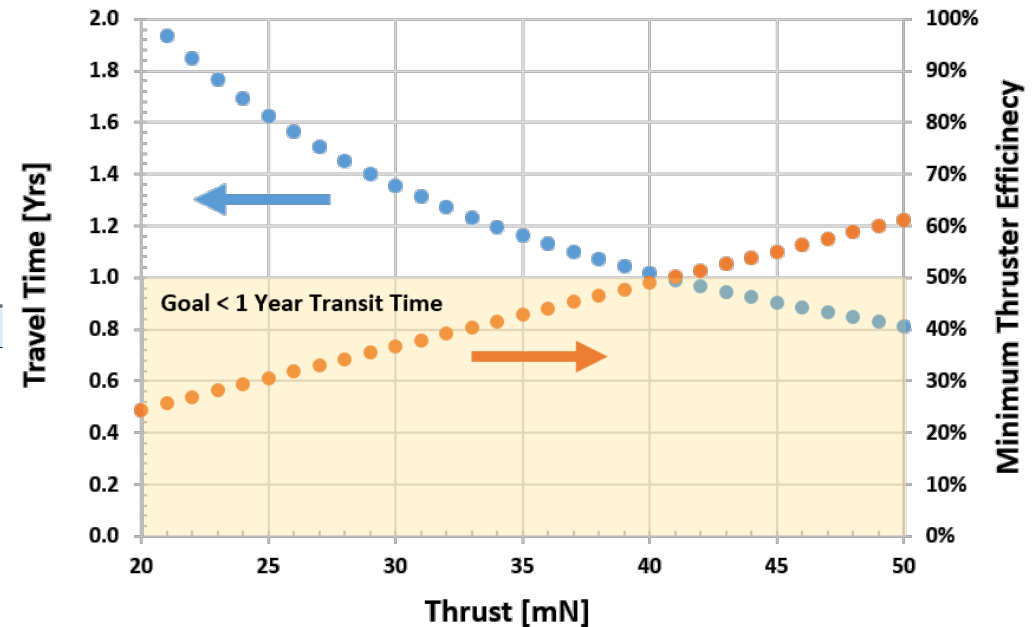
A pair of small spacecraft in a 12-hour lunar frozen orbit could provide near continuous communication between Earth and rovers or other science instruments located near the poles.

- Transit time from 350-km LEO to 12-hr lunar frozen orbit assuming I_{sp} of 1685 seconds and 90% duty cycle.
- Minimum thruster efficiency assuming 750-W input to PPU and 90% PPU total efficiency.
- Transit can be accomplished in 1 year if thruster discharge input to beam power conversion efficiency exceeds 49%.

| Example HT-SSEP Specification | |
|----------------------------------|------------|
| Specific Impulse | 1685 s |
| Thrust | 40 mN |
| Thruster Efficiency | 49 % |
| PPU Total Efficiency | 90 % |
| Propellant Throughput Capability | 80 kg |
| Lifetime | 10,200 hrs |

| Example Mission: 350 km LEO to 12-Hr Lunar Frozen Orbit | |
|---|----------|
| Delta-V | 7.1 km/s |
| Power to Propulsion System | 750 W |
| Transit Time | 1 Year |
| Duty Cycle | 90 % |
| Spacecraft Wet Mass | 200 kg |
| Initial Propellant Mass | 80 kg |
| Propellant Consumed in Transit | 69.9 kg |

Transit Time from 350 km LEO to 12-hr Lunar Frozen Orbit and Minimum Thruster Efficiency (Assumes $I_{sp}=1685$ sec, 90% Duty Cycle, Total Power=750 W, 90% PPU Efficiency)





Motivation for HT-SSEP

- Most Hall thruster technologies under development are known to have capabilities optimized for LEO missions, rather than deep space.
- Significant focus on servicing growth in the LEO constellation market.
- NASA requirements typically drive product cost beyond viable for commercial use in LEO/GEO applications.
- Lack of a clear source for flight-ready, low-power HT-SSEP results in considerable technical risk for NASA to undertake small spacecraft missions beyond LEO using EP.
- NASA GRC is well positioned to advance the state-of-the-art in sub-kW electric propulsion to support future NASA mission needs by leveraging recent advances in Hall thruster technology.
- **Goal:** Develop HT-SSEP technology and provide a no-cost, non-exclusive license U.S. industry.

GRC has identified no domestic flight-ready sub-kW high-propellant throughput electric propulsion systems proven capable of meeting NASA high delta-v mission needs beyond LEO.



Background – SKEP Project

Sub-Kilowatt Electric Propulsion (SKEP) Project

- In FY18, NASA STMD funded the Sub-Kilowatt Electric Propulsion (SKEP).
- The project pursued development of a high-propellant throughput sub-kW thruster and power processing unit (PPU). ([Patent Pending: LEW-20035-1, LEW-20041-1, LEW-19799-1](#))

Commercialization path from project inception:

- Project sought industry input from project inception in definition of system requirements, identification of commercial applications benefiting from high delta-v propulsive capability, and further optimization of the commercialization (i.e., technology transfer) strategy.
- Project sought to compile a comprehensive package of design / process documents licensable at no cost non-exclusively to U.S. industry.
- Project benefited from the existing, competitively-selected Space Flight Systems Development and Operations Contract (NNC13ZMA015R) for engineering support toward delivery of a qualification unit.

The project sought to limit recurring unit cost and improve commercial viability by systematically optimizing the propulsion system (*thruster, power processing unit, and feed system*), rather than exclusively optimizing the thruster.



Background - Stakeholders

- The HT-SSEP development is a technology push.
 - The stakeholders were not well defined at project inception.
 - The project sought interest from NASA mission directorates and U.S. industry (specifically potential end-users).
- A key NASA stakeholder identified was the SMD Planetary Sciences Division (PSD).
- A handful of U.S. industry stakeholders were identified.
 - Interest in the technology was first identified at a JANNAF conference in May 2018.
- A Request for Information (RFI) was drafted to further engage U.S. industry
 - Release of the RFI was blocked by NASA HQ (concerned industry was receiving too many RFIs).
- Feedback from PSD and U.S. industry was sufficient to develop a useful requirements set to focus the SKEP project effort and provide a high likelihood of meeting future mission needs.



Concept of Operations (subset)

Through discussions with the identified stakeholders, a concept of operations was formulated.

The HT-SSEP system should:

- impart ~2 MN-s on a small spacecraft, while consuming less than 1-kW input power,
- be capable of more than 8,000 cycles to support station keeping,
- have a reversible magnetic field (to switch direction of swirl torque),
- be electrically isolated and thermally insulated from the spacecraft bus,
- protect the spacecraft against all conceivable propulsion system electrical faults,
- accept an unregulated low-voltage power bus consistent with most small spacecraft,
- accept commands and return telemetry via a common small spacecraft communication protocol,
- operate at two qualified firing conditions, including nominal power and a reduced power state,
- operate at additional higher and lower than nominal power firing conditions,
 - although they may not be fully qualified to minimize development cost
- employ a scalable, low-cost PPU architecture able to accommodate more than one domestic small spacecraft Hall-effect thruster, and
- require no on-orbit maintenance by the spacecraft other than survival heaters.

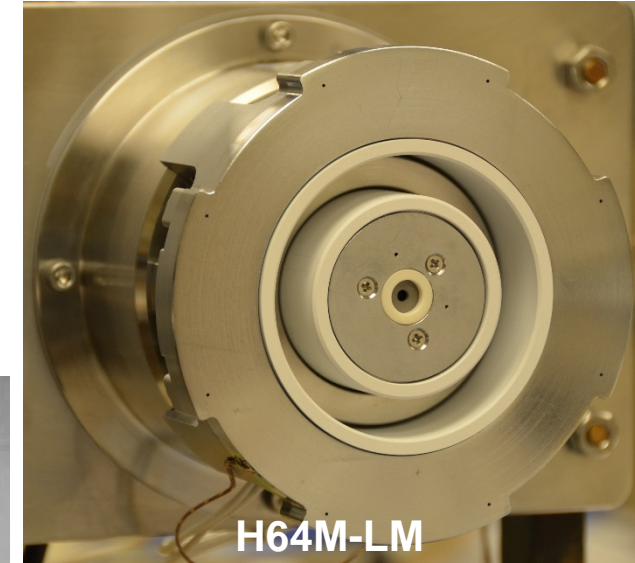


System Requirements (subset)

| Name | Requirement |
|--------------------------------|---|
| Nominal Thrust | The propulsion system shall generate ≥ 40 mN of thrust at the nominal operating condition over its full operational lifetime. |
| Nominal Total Specific Impulse | The propulsion system total (anode + cathode flow) specific impulse shall be ≥ 1600 seconds at the nominal operating condition over its full operational lifetime. |
| Propellant Throughput | The propulsion system shall have a total propellant throughput capability of ≥ 100 kg at the nominal operating condition. |
| Propellant | The propulsion system shall meet all performance requirements when fed xenon propellant. |
| Cyclic Lifetime | The propulsion system shall be capable of 8,000 on/off cycles over its full operational lifetime. |
| Reversible Swirl Torque | The propulsion system shall have the ability to set the direction of the swirl torque induced by thruster operation. |
| Input Voltage | The propulsion system shall operate over an input voltage range of 24 to 34 VDC . |
| Enable Time | The propulsion system shall reach 95% of steady-state thrust in less than 10 seconds following receipt of the enable command. |
| PMA Outlet Pressure | The propulsion system shall meet all performance requirements when exposed to or operating at a pressure management assembly (PMA) outlet pressures of 40 +/- 3 psia . |
| System Mass | The propulsion system shall have a mass ≤ 10 kg (including thruster, PPU, flow controller, and interconnects, but excluding tank, gimbal, and PMA). |

HT-SSEP Development Approach

- Project goals were achieved by leveraging prior NASA investments.
- **Development approach:**
 - Minimize parts count
 - Minimize “touch labor” in assembly
 - Maximize use of heritage components and/or processes (high TRL)
 - Leverage recent Hall-thruster technology advancements
 - Performance optimization was **not** included in the approach
 - Goal was to provide an initial robust capability
 - Reserve optimization for future projects
- **Key technologies leveraged:**
 - Advanced Hall-effect thruster magnetic circuit design
 - Centrally-mounted hollow cathode
 - GRC-pioneered hollow cathode assemblies (derived from the International Space Station plasma contactor units)
 - GRC-patented robust propellant manifold assembly design
 - Extensive in-house power processing unit development expertise



HT-SSEP Thruster Design Heritage



ISS PCU HCAs

Anode

- Cathode technology leverages over 35 years of flight cathode development that includes: Emitter and cathode assembly materials selection, swaged heater manufacturing, and flight assembly manufacturing process
- Cathode developments include: NASA ISS PCU HCAs, NSTAR, DAWN, NEXT-C, AR XR-5 (NASA heritage), and AEPS



SKEP Cathode

- Functional test procedures (electrical, magnetic, and flow) that assure thruster design will meet performance design objectives
- Developed detailed pre-test checkouts to confirm hardware test readiness



HERMeS TDU

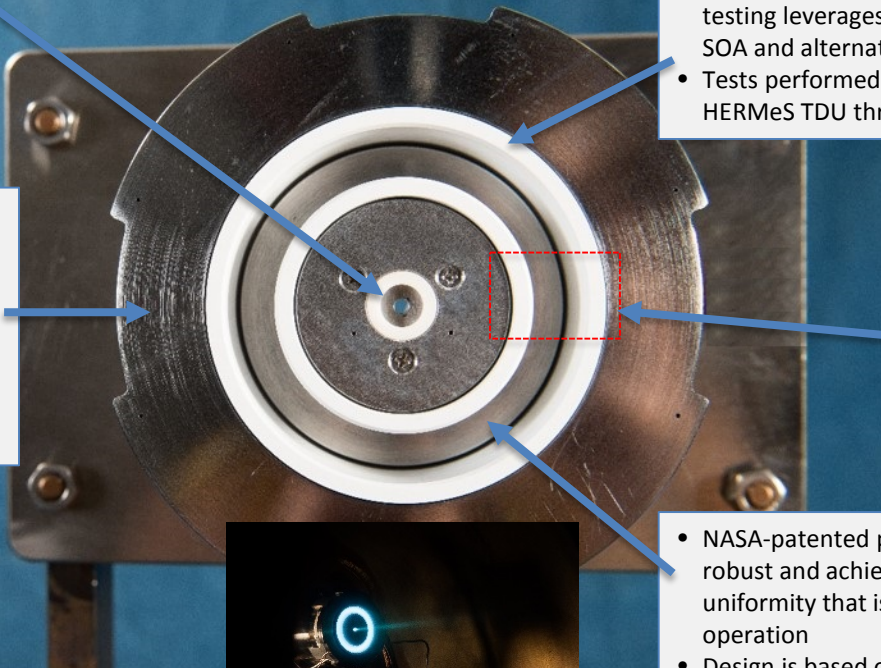


HiVHAc 77M

NASA 300M

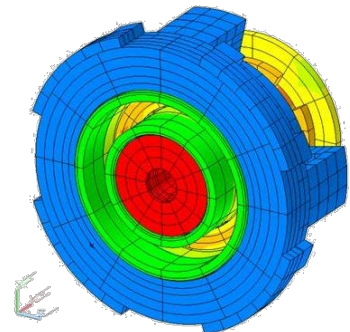
HiVHAc EDU

- Magnetic thruster components are key to attaining the designed magnetic field topology
- Magnetic material selection, processing, and manufacturing leverages knowledge gained from previous NASA programs that include: NASA 300M, HiVHAc, and HERMeS

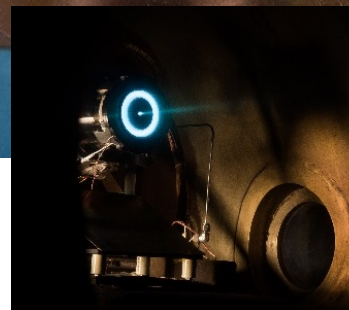


- Discharge channel material selection and testing leverages over 25 years of tests with SOA and alternate materials
- Tests performed with NASA HiVHAc and HERMeS TDU thrusters

- Magnetic field topology design leverages over 25 years of NASA GRC & JPL research and development efforts to optimize the magnetic field configuration to maximize thruster performance and lifetime
- Technology implemented and demonstrated on: NASA 120, 173, 300M, 300MS, 400M, 457M, HiVHAc, H6MS, and HERMeS thrusters



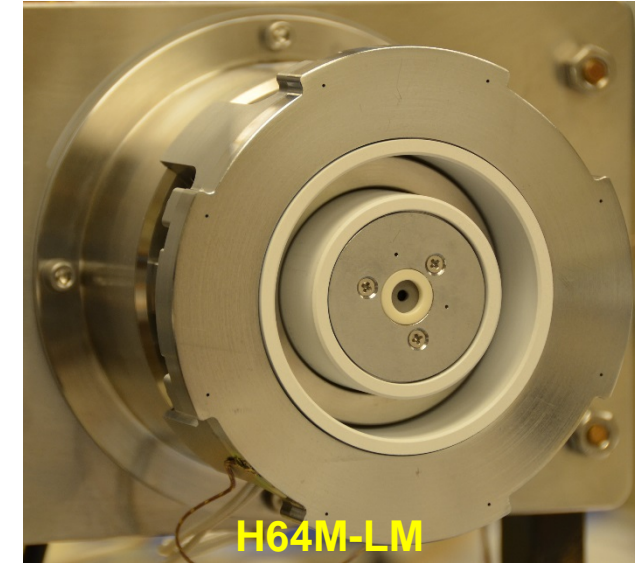
- Thruster magnetic, plasma, thermal, and structural modeling leverages NASA GRC and JPL extensive and validated modeling tools that can predict thruster performance, temperatures, structural viability, and lifetime
- Tools include: Magnet7, JPL Hall2De, JPL OrCad2, & Thermal Desktop



- NASA-patented propellant manifold that is robust and achieves excellent propellant flow uniformity that is critical for efficient thruster operation
- Design is based on the HERMeS TDUs and AEPS thruster design

NASA-H64M and NASA-H71M

- While system requirements were being developed, a proof-of-concept thruster called the H64M was manufactured and evaluated.
 - H64M is a nominally a 600-W thruster at 350 V that produces around 37 mN of thrust with an Isp of approximately 1600 seconds.
 - Demonstration of the H64M indicated that all project goals were achievable.
- Following demonstration of the H64M and collection of NASA / industry inputs, the thruster design was iterated accordingly to a nominal power of 750 W at 350 V. This thruster iteration is known as the H71M.
 - The anticipated thrust is ~ 50 mN with an Isp of ~ 1700 seconds.
 - The H71M design is still in progress.
 - The H71M is a lower-cost implementation of the technology demonstrated with the H64M, while maintaining the key features that give the H64M its enhanced performance relative to the SOA low-power Hall thrusters.



H64M-LM Development Activities

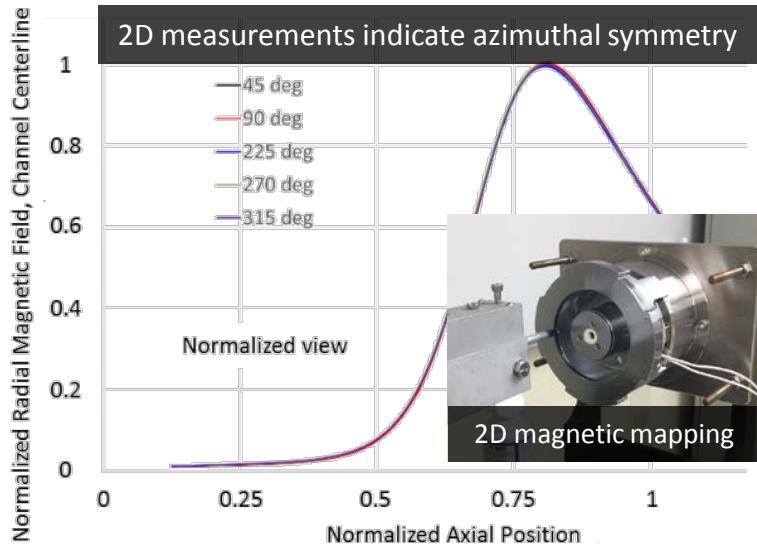
Magnetic Circuit

H64M-LM magnetic circuit design leverages NASA GRC's experience with magnetic topology design of several NASA Hall thrusters that include HiVHAc, 300M, and HERMeS.

The advanced magnetic circuit results in:

- High thruster performance by implementing a magnetic lens; and
- High-propellant throughput capability, which translates to long thruster life

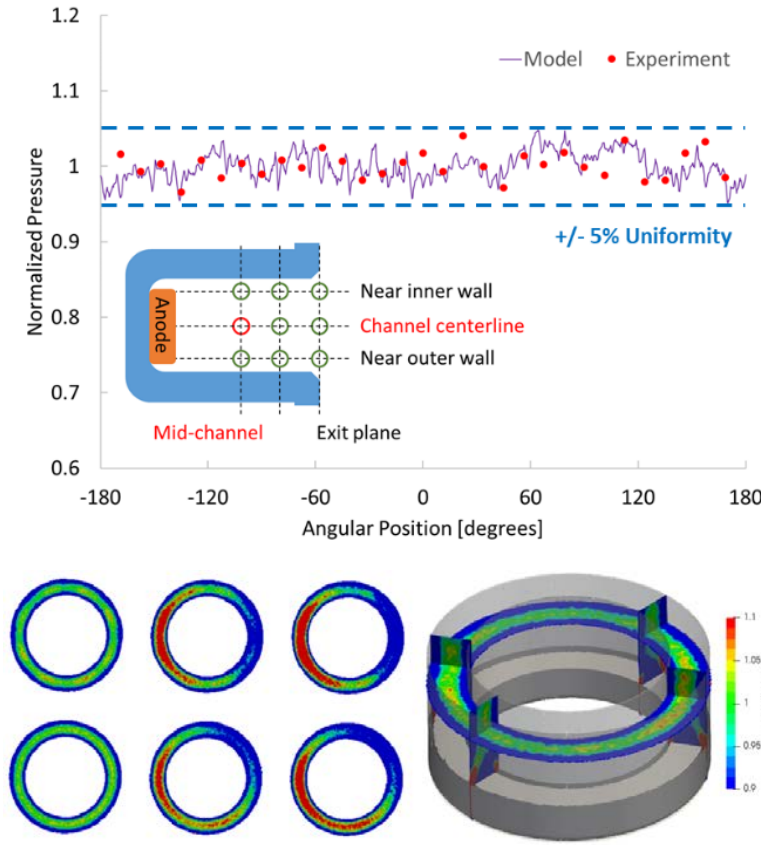
The H64M magnetic circuit has been assembled, tested, and mapped (matches model prediction).



Propellant Distributor / Anode

Must promote neutral flow uniformity and tolerate electron backstream heating.

Modeling suggests and testing agree azimuthal flow uniformity within $\pm 5\%$

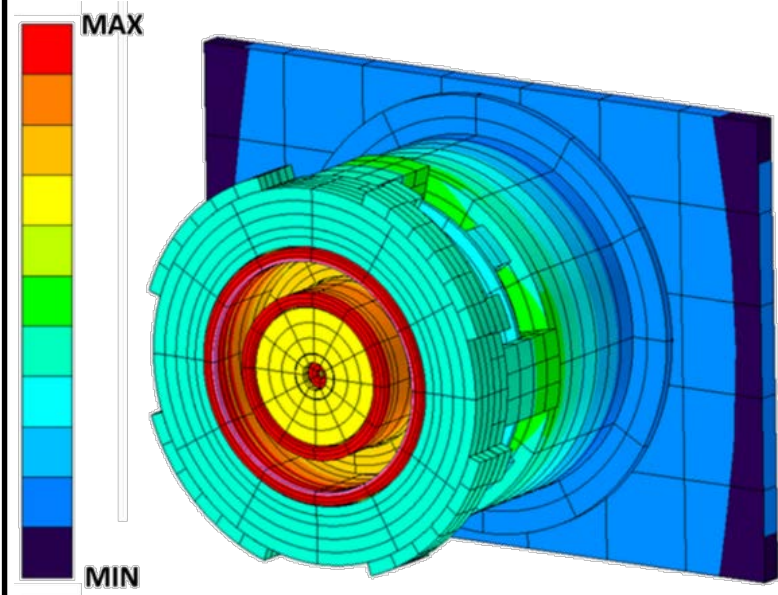


Thermal Design

Develop a thermal model of H64M-LM to aid the design process and assess thermal management options as the design evolves.

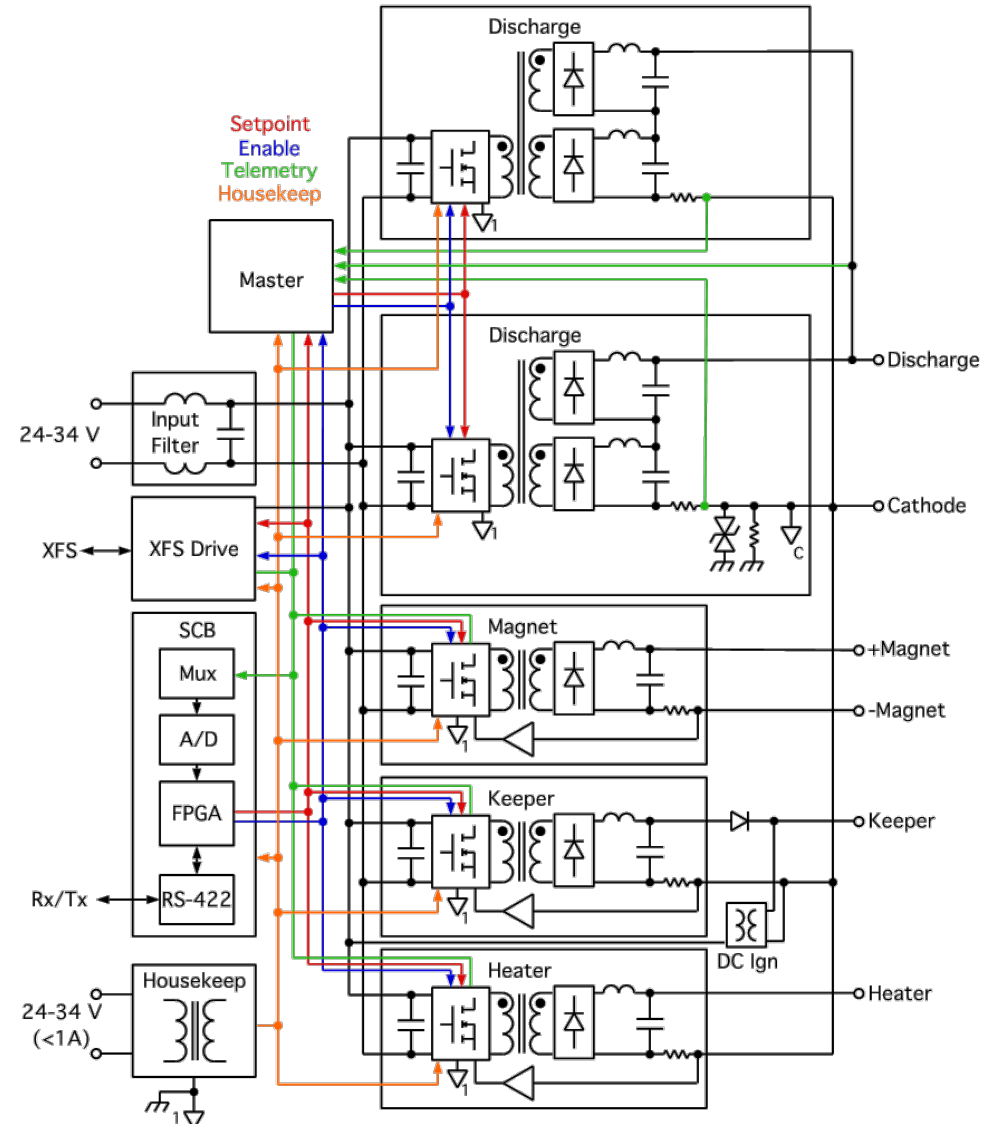
During the thermal characterization test, the thruster was equipped with ~ 20 thermocouples.

Comparison of correlated thermal model and experimental test results show good agreement. The results show moderate temps for all components with large thermal margins on traditional limits.



PPU Architecture

- Discharge module based on GRC heritage full-bridge designs
 - Paralleling modules enable scaling power for different thrusters, minimizing future PPU development costs
- Parallel module approach mitigates efficiency losses due to the low-voltage/high-current input
- Use of 2 series-stacked full wave rectifiers on the output allows the use of lower-voltage components
- An additional rectifier stage could be added for output voltages greater than 350 V, though electrical efficiency would be reduced
- A flyback converter is the baseline approach for each auxiliary.
 - The same architecture for each auxiliary supply reduces overall system costs.
 - Keeper differs only slightly with the addition of DC ignitor circuit.



Parallel Discharge Summary & Estimates

Pros: (compared to single module approach)

- Lower power per module
- Lower MOSFET and diode stress
- Higher efficiency
- Staggered switching reduces input current ripple/filter size
- Easy to scale power by adding/removing modules
- Lower development cost than a line of different power PPU's

Cons: (compared to single module approach)

- More complex, more parts, greater unit cost
- Greater mass
- Master controller required for current sharing

Preliminary Efficiency Est.:

- 93.0 % at 900 W

Preliminary Mass Est.:

- 4.9 kg for 900 W

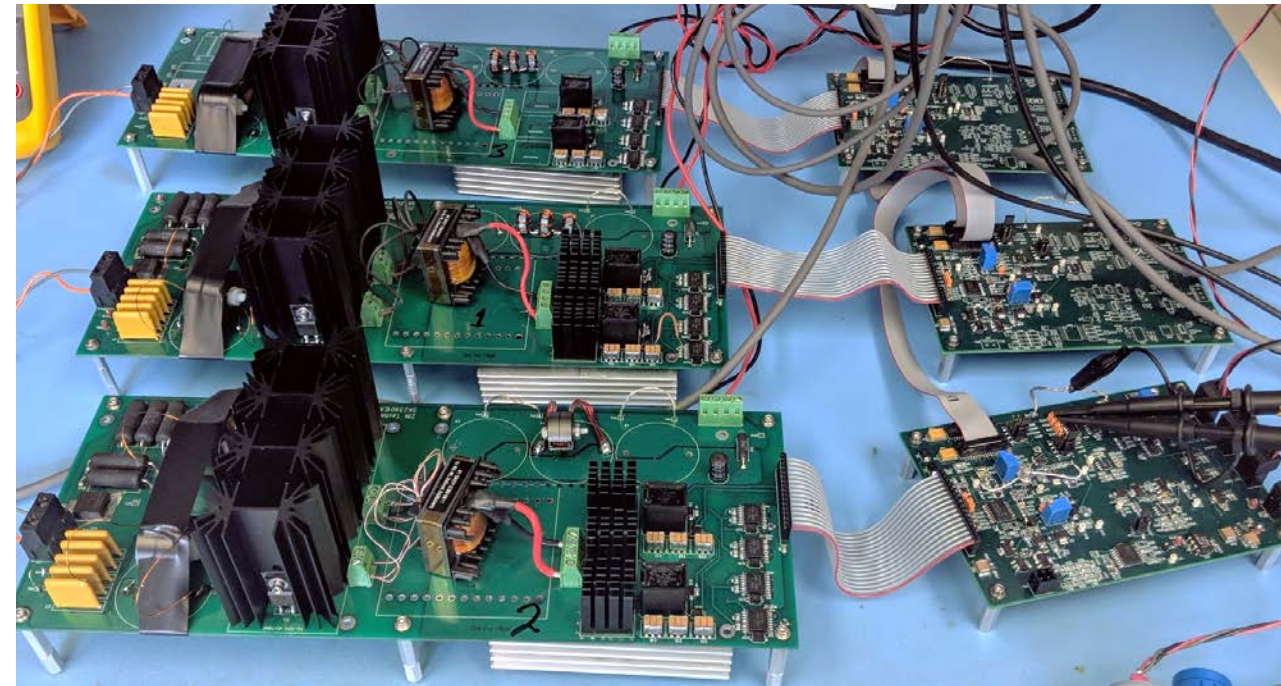
Preliminary Volume Est.:

- ~ 5 L for 900 W

Assumptions:

- 50-kHz PWM full-bridge discharge converter
- 100-kHz PWM flyback auxiliary converters
- FPGA-based SCB
- EMI/EMC low-pass input filter
- COTS housekeeping converters

Three Module Breadboard Discharge Supply





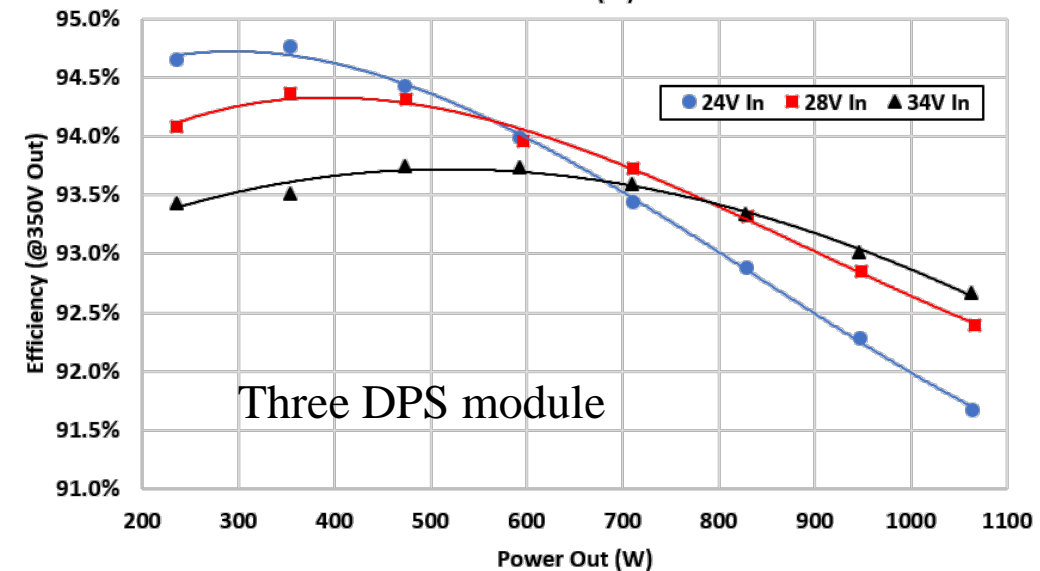
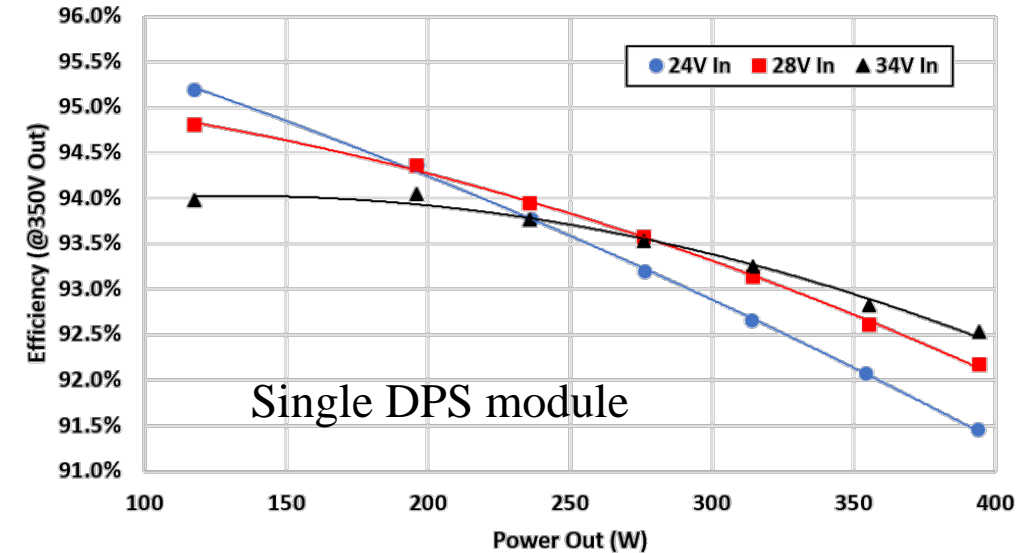
DPS Steady State Performance: Efficiency

➤ Single Module Efficiency

- Typical single module with all improvements to date performed with 92-95% efficiency across full power and input bus voltage.

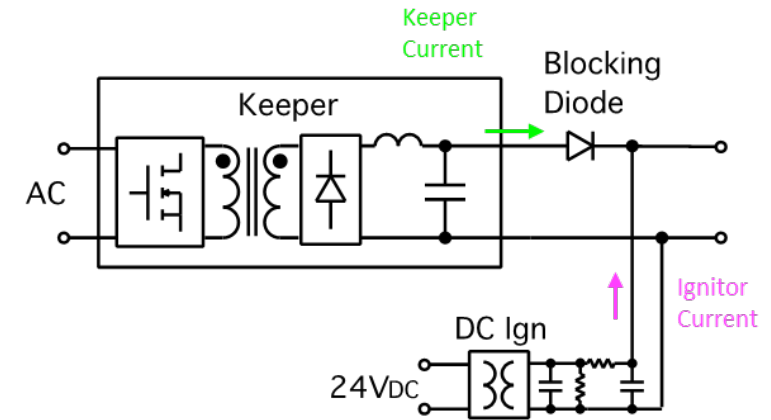
➤ Three Module Efficiency

- Three modules together at higher power levels had similar performance to a single module.
- Further improvement is anticipated after two remaining input filter inductors replaced with custom design.

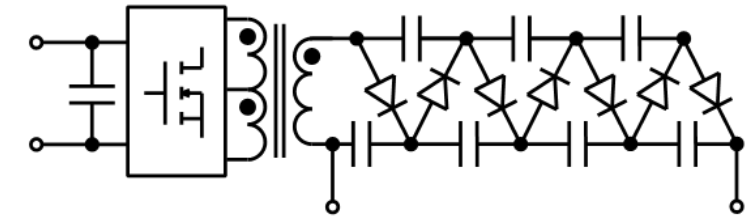


Auxiliary Supplies

- **Auxiliary supplies include the keeper, heater, and magnets**
 - The auxiliary supplies are anticipated to be nearly identical, although the cathode keeper will have modest differences.
- **A breadboard keeper supply has been designed and fabricated.**
 - Operating range has been demonstrated from ~300 mA to 1 Amp
 - Shown below is data for 1 Amp output, at both 15 and 30 ohm
 - Voltage on FET is acceptable, does not exceed derating
 - Circuit was tested with a cathode in GRC VF-8.
 - Test objectives were cathode ignition and steady-state operation.
 - Successfully demonstrated ignition and steady-state operation of an appropriately sized cathode.



Schematic of cathode keeper supply



Schematic of keeper voltage multiplier ignitor

| Load [Ohms] | V_{in} [V] | Power [W] | I_{out} [A] | Efficiency |
|-------------|--------------|-----------|---------------|------------|
| 15.2 | 24 | 19.3 | 1.0 | 78.8% |
| 15.2 | 29 | 19.1 | 1.0 | 79.6% |
| 15.2 | 34 | 19.1 | 1.0 | 79.6% |
| 30.1 | 24 | 37.5 | 1.0 | 80.3% |
| 30.1 | 29 | 37.2 | 1.0 | 80.9% |
| 30.1 | 34 | 37.0 | 1.0 | 81.4% |

H64M-LM Thruster Performance Testing

Objectives

1. Investigate the performance of the H64M-LM thruster across its entire design throttle table 200-600W, I_d of 0.67 to 2A, V_d of 200-350 V.
2. Measure select thruster component temperatures and use measurements to fine-tune thermal model.
3. Perform a preliminary assessment of the thruster stability across the design magnetic field range.

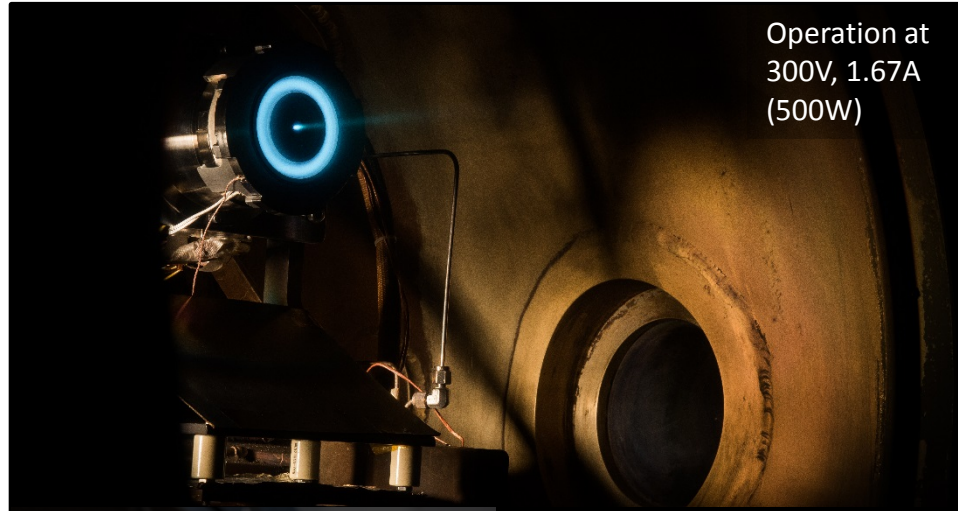
Summary conclusions

- *Thruster performance exceeds SOA.*
- *Thruster demonstrated ~ 450 hrs, including 110 hrs of uninterrupted operation @ 500W.*
- *Integrated demo with breadboard DPS*

- Facility background pressure was 7 μ Torr-Xe during thruster operation @ full power.
- Facility pressure conditions appropriate for thruster functional and performance assessment.
- Test setup enabled unattended duration tests of LM.



NASA GRC VF-8
Low-Power EP Test Chamber



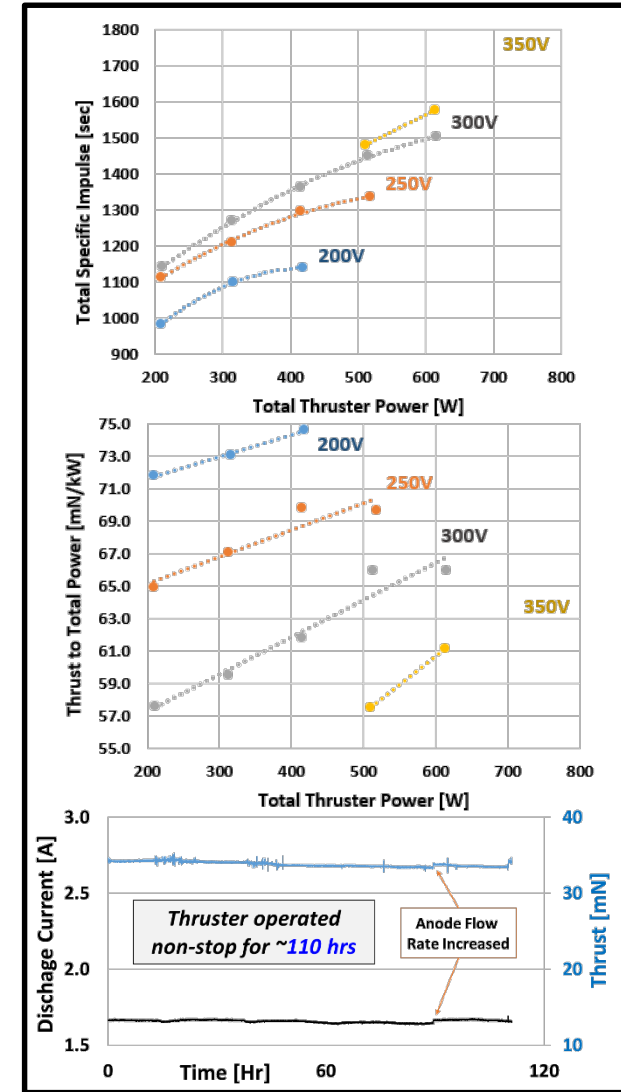
LM on VF-8 thrust stand

Operation at
300V, 1.67A
(500W)



Pathways student installing SKEP

IR camera showing thermal uniformity at 500-W operation



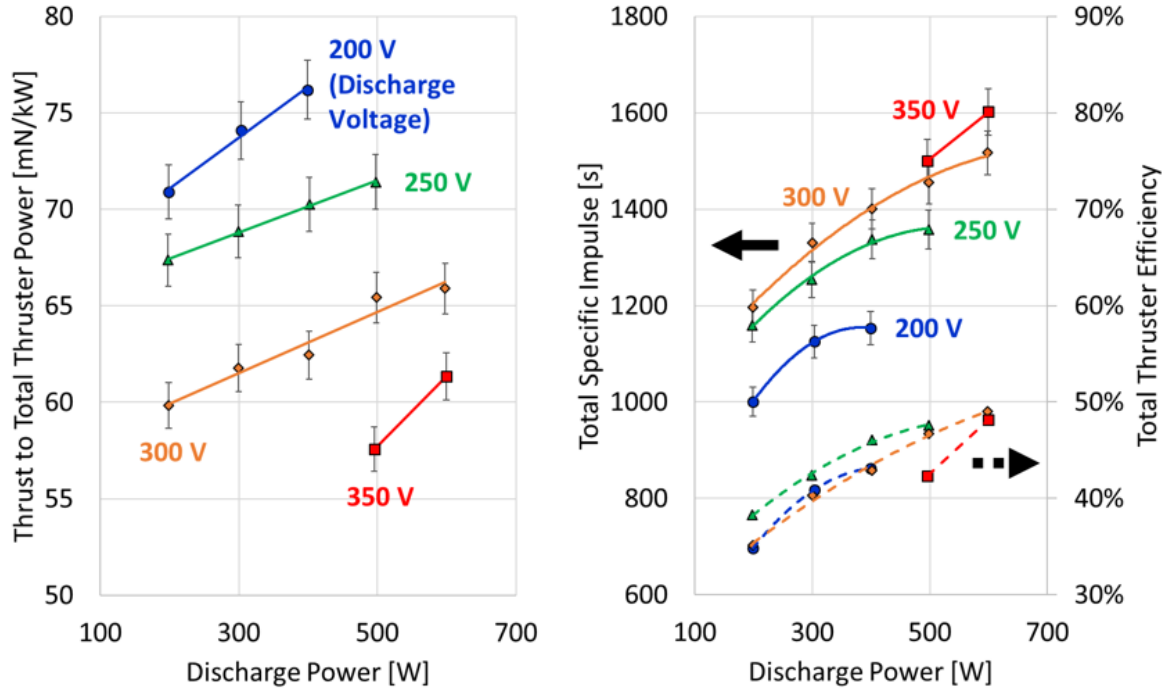


H64M-LM Test Phases

| Phase | Thruster | Description | Duration [hr] |
|--------------------------------------|----------|--|----------------|
| A | LM | Performance and stability characterization: 200 to 600-W discharge power, 200 to 350-V discharge voltage, magnetic and cathode flow fraction mapping | 27 |
| B | LM | Short-duration wear: 500-W, 300-V discharge condition | 275 |
| C | LM | Performance and stability characterization: 200 to 600-W discharge power, 200 to 350-V discharge voltage, magnetic and cathode flow fraction mapping | 5 |
| D | LM | Thermal characterization: 300 to 600-W discharge power, 300 and 350-V discharge voltage | 18 |
| E | LM | Accelerated wear characterization: 500-W, 300-V discharge condition | 108 |
| F | LMW | Performance and stability characterization: 300 to 700-W discharge power, 300 and 350-V discharge voltage, magnetic and cathode flow fraction mapping, integrated demonstration with breadboard discharge module | 10 |
| Cumulative Thruster Operation | | | 443 hrs |

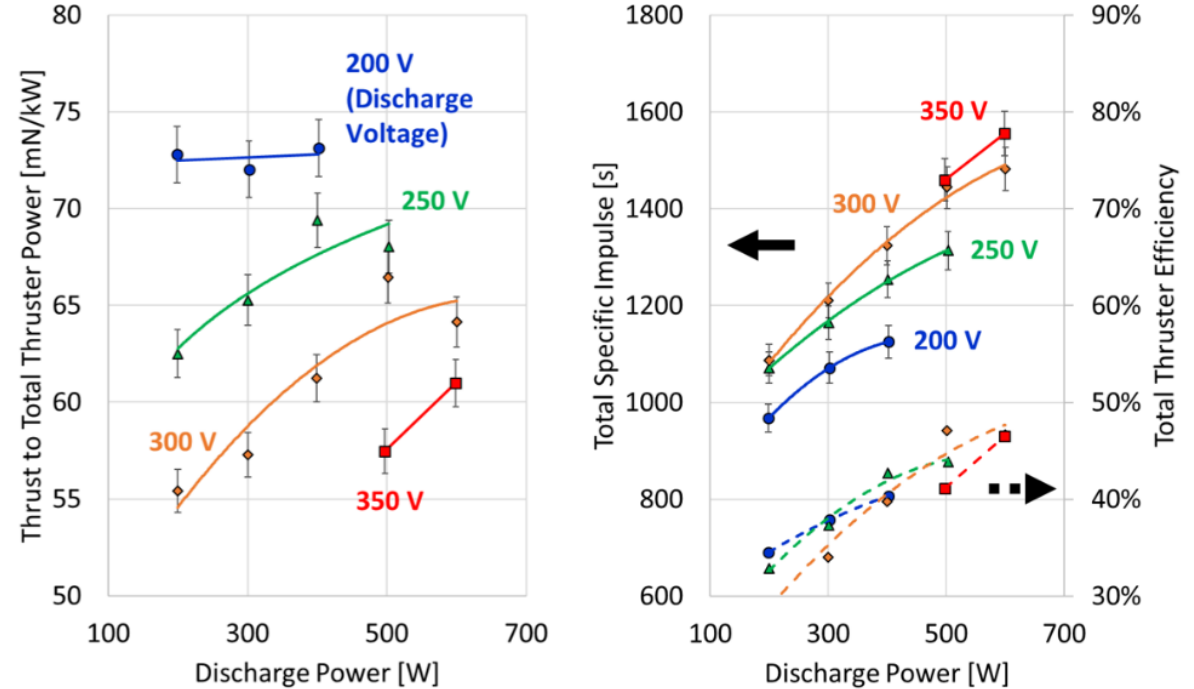
H64M-LM (BOL vs 300 Hours)

BOL



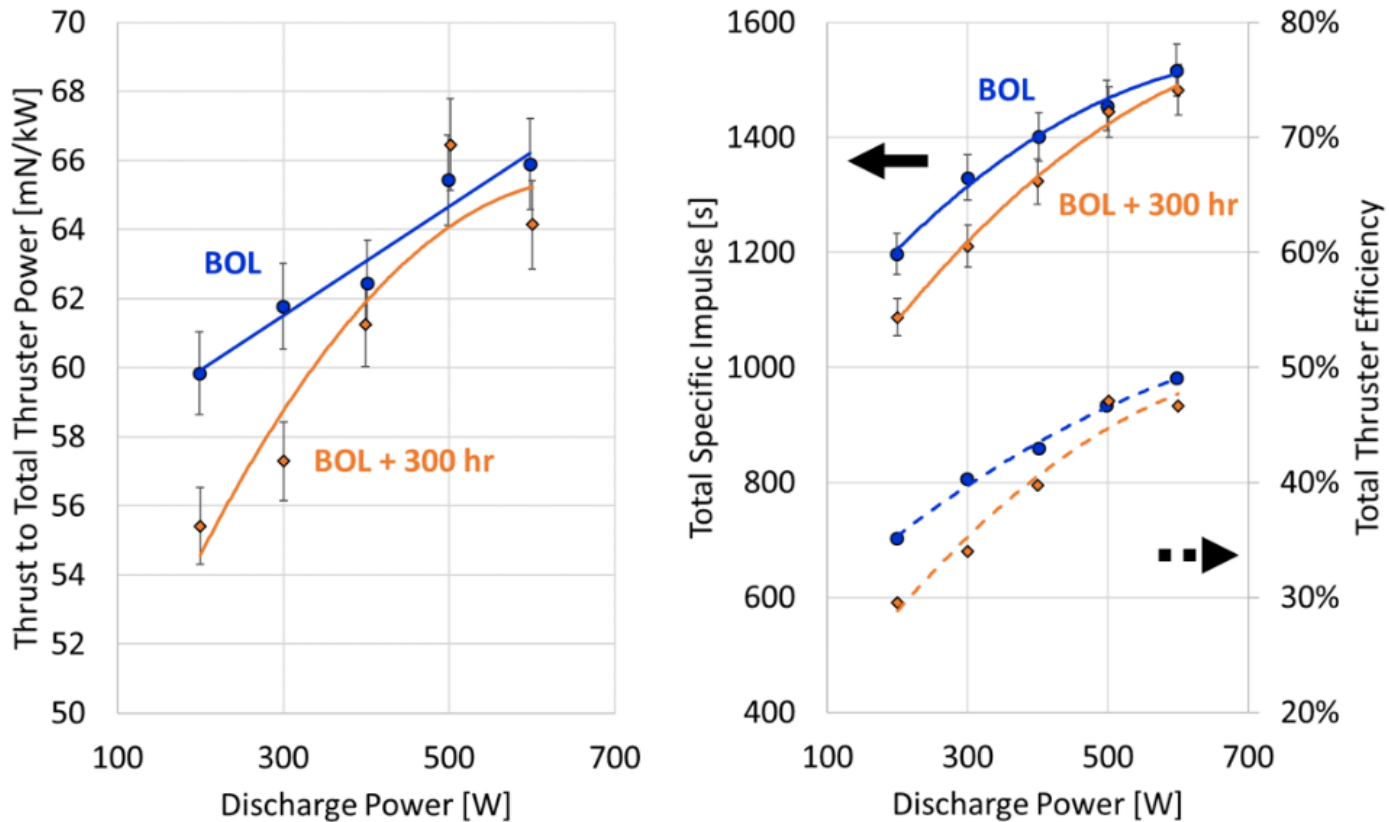
NASA-H64M-LM performance at beginning-of-life (BOL) with performance-optimized magnetic field strengths, 7% cathode flow fraction, and electrically floating configuration. The total thruster efficiency uncertainty bars (up to a maximum of $\pm 5\%$) are not shown for clarity.

300 Hrs



NASA-H64M-LM performance at BOL + 300 hr with the same magnetic field settings as the results in Figure Left, 7% cathode flow fraction, and electrically floating configuration. The total thruster efficiency uncertainty bars (up to a maximum of $\pm 5\%$) are not shown for clarity.

H64M-LM (BOL vs 300 Hours)



Comparison of NASA-H64M-LM performance at BOL versus BOL + 300 hr for 300-V discharge voltage, identical magnetic field settings, 7% cathode flow fraction, and electrically floating configuration. The total thruster efficiency uncertainty bars (up to a maximum of $\pm 5\%$) are not shown for clarity.



Wider Channel Variant (H64M-LMW)

| Thruster Configuration / Condition | Discharge Power [W] | Discharge Voltage [V] | Thrust [mN] | I_{sp} [s] | η_T |
|------------------------------------|---------------------|-----------------------|-------------|--------------|----------|
| LM BOL | 500 | 300 | 33 | 1455 | 47% |
| LM BOL | 600 | 300 | 41 | 1517 | 49% |
| LM BOL | 500 | 350 | 29 | 1500 | 42% |
| LM BOL | 600 | 350 | 38 | 1601 | 48% |
| LM BOL + 300 hr | 500 | 300 | 34 | 1444 | 47% |
| LM BOL + 300 hr | 600 | 300 | 40 | 1483 | 47% |
| LM BOL + 300 hr | 500 | 350 | 29 | 1460 | 41% |
| LM BOL + 300 hr | 600 | 350 | 37 | 1555 | 47% |
| LMW BOL | 600 | 300 | 42 | 1602 | 53% |
| LMW BOL | 700 | 300 | 48 | 1608 | 53% |
| LMW BOL | 600 | 350 | 38 | 1671 | 51% |
| LMW BOL | 700 | 350 | 44 | 1702 | 52% |

| Discharge Voltage [V] | Thrust to Total Thruster Power | Total Specific Impulse | Total Thruster Efficiency |
|-----------------------|--------------------------------|------------------------|---------------------------|
| 300 | 1.03X | 1.06X | +4% |
| 350 | 1.02X | 1.04X | +3% |



Concluding Remarks

- NASA is expanding the use of lower-cost SmallSats to accomplish science goals.
- Small spacecraft launched as secondary payloads can reduce the total mission cost of NASA robotic science missions (especially for constellations, swarms, or multiple spacecraft formation flying).
- No flight-ready sub-kW EP with sufficient propellant throughput to support small spacecraft beyond GEO.
- SKEP project was a low-risk, high-payoff technology development effort to rapidly fielded HT-SSEP.
- SKEP aimed to make available a comprehensive package of design/process documents to U.S. industry.
- SKEP project team enlisted the cooperation of U.S. industry to refine system requirements.
- NASA GRC engineering expertise, fabrication capabilities, and world-class test facilities in the field of electric propulsion facilitated the aforementioned work to be completed in one year in one design iteration.
- The thruster and PPU work leveraged numerous prior NASA investments and produced many innovations to solve the unique challenges of a miniaturized, long-life Hall-effect electric propulsion system.
- Pending continued funding, GRC aims to deliver an initial high total impulse capability for NASA small spacecraft science missions through collaborations with industry.
- The ultimate goal is to make the described thruster and PPU designs available domestically to credible electric propulsion developers on a non-exclusive no-cost basis.