



# **Calibration Plan for the Ocean Color Instrument (OCI) Engineering Test Unit**

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# OCI calibration overview

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- The basic product measured by OCI is the top-of atmosphere (TOA) radiance at different wavelengths
- Three types of calibration/characterization are necessary for ocean color processing:
  - Prelaunch calibration/characterization (absolute/spectral calibration and image artifacts)
  - On-orbit calibration (solar diffuser and lunar measurements)
  - Vicarious calibration (in-situ measurements of water-leaving radiance)



# OCI calibration overview



Artifact	Measured Prelaunch	Measured Postlaunch	Applied during L1 processing	Applied during L2 processing
<b>Absolute gain (K1)</b>	Instrument level, TVAC	Solar calibration and vicarious calibration <sup>1</sup>	Yes (calibration equation)	
<b>Temporal response (K2)</b>	Instrument level, reduced accuracy	Solar and lunar calibration	Yes (calibration equation)	
<b>Temperature correction (K3)</b>	Instrument level, TVAC	Solar and lunar calibration <sup>2</sup>	Yes (calibration equation)	
<b>Response vs. scan angle (RVS) (K4)</b>	Instrument level, ambient	Verification with ocean color products	Yes (calibration equation)	
<b>Linearity (K5)</b>	Instrument level, TVAC	Solar calibration <sup>3</sup>	Yes (calibration equation)	
<b>Tilt angle (K6)</b>	Spacecraft level (verification only)	Verification with ocean color products	N/A	
<b>Polarization sensitivity</b>	Instrument level, ambient	Verification with ocean color products		Yes (atmosphere polarization)
<b>Stray light sensitivity</b>	Instrument level, ambient	Verification with lunar cal.		Yes
<b>Crosstalk</b>	Instrument level, ambient	Verification with lunar cal.	Maybe	Yes
<b>Relative spectral response</b>	Instrument level, TVAC	Verification with solar calibration (Fraunhofer and atm. abs. lines)	N/A (part of K1 calculation)	Yes(atmospheric correction)
<b>Offset (DN0)</b>	Every scan	Every scan	Yes	

<sup>1</sup>Vic. Cal.: Visible and some NIR bands only  
<sup>2</sup>If seasonal variations are observed in K2  
<sup>3</sup>New technique developed for OCI (dim diffuser)



# Ground support equipment: 20inch integrating sphere (8inch exit aperture)

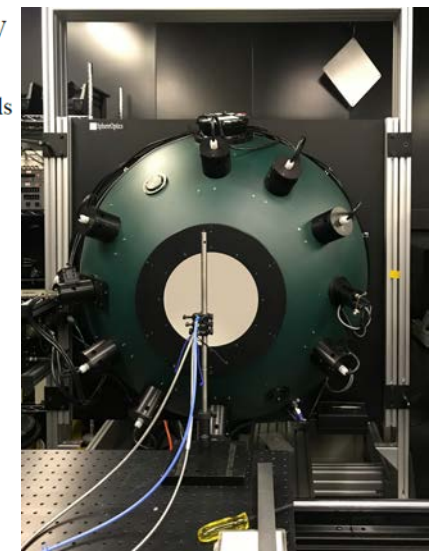
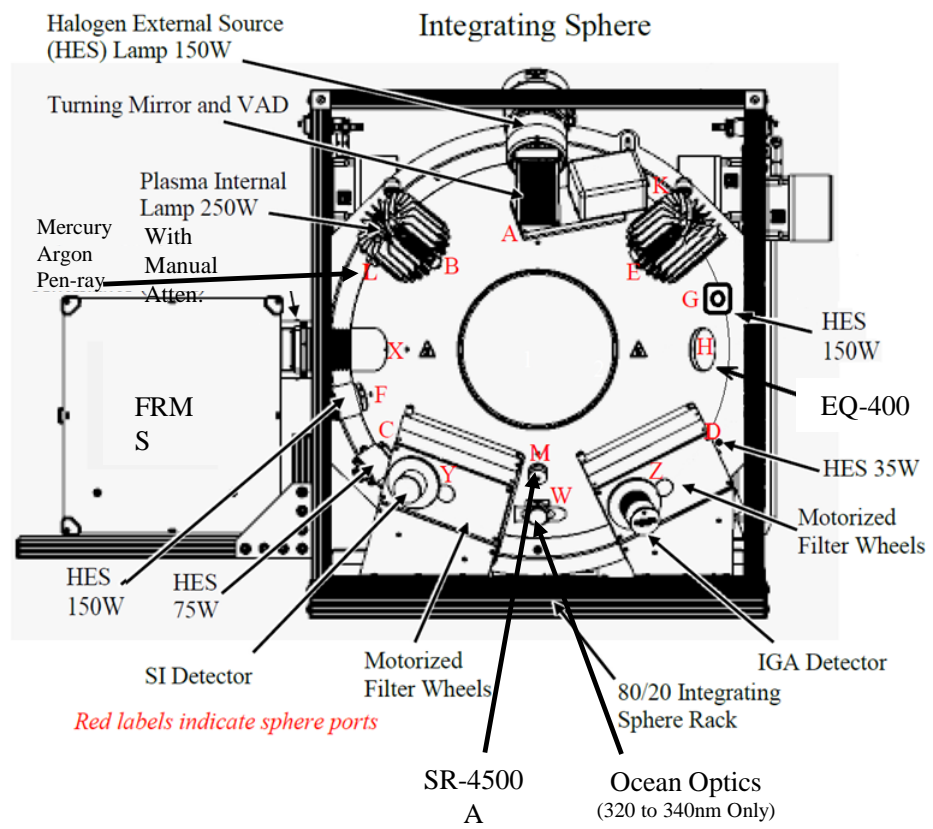
All light sources will be calibrated by NASA GSFC Code 618 Calibration Facility

Attachments:

Various light sources (halogen, plasma, EQ-400, attenuators)

and sensors (SR4500, Ocean

Optics, FRMS, Filter wheel (Si and InGaAs)





# GSE: rotating table

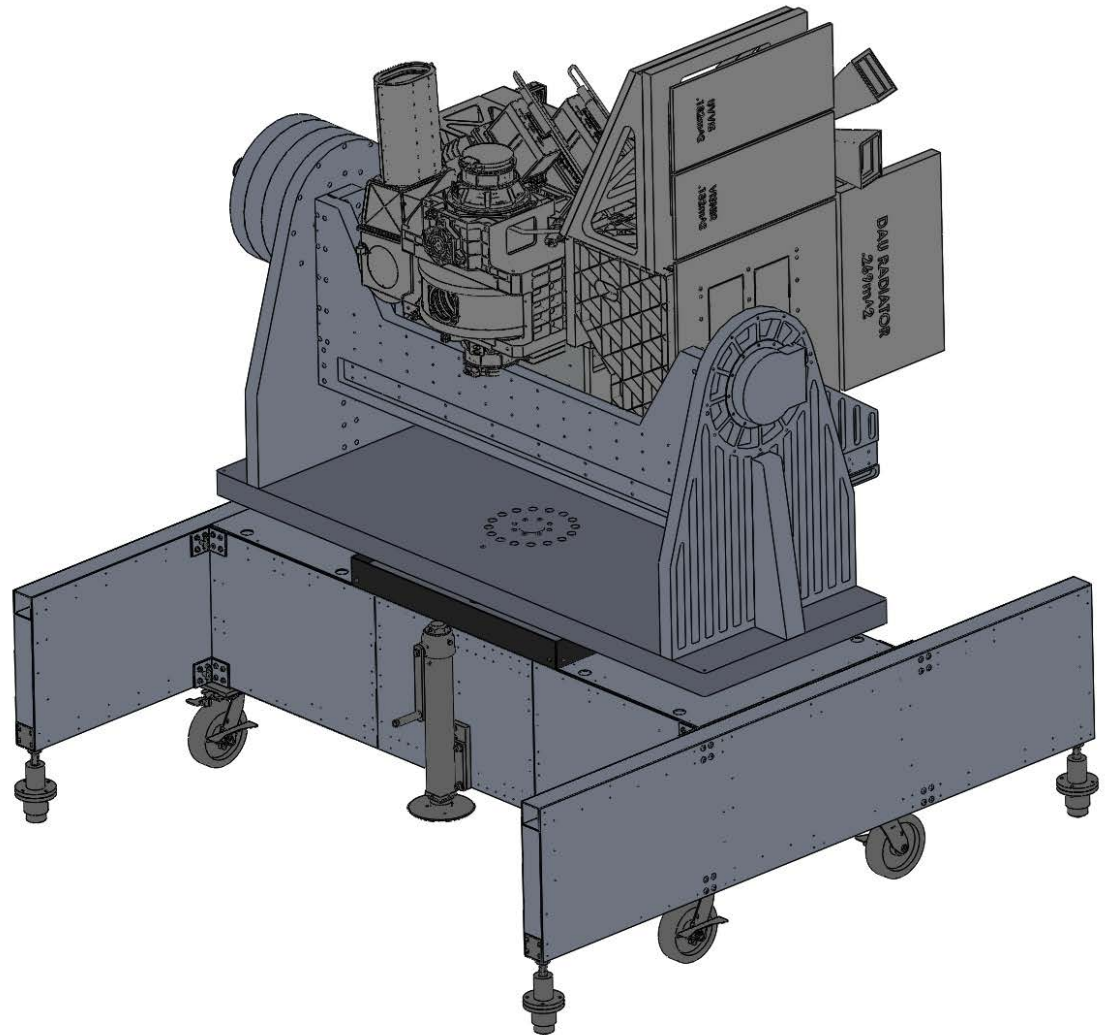


Two axis rotation  
(scan and track)

Just passed PDR

Vendor: Newton

Delivery in May 2019



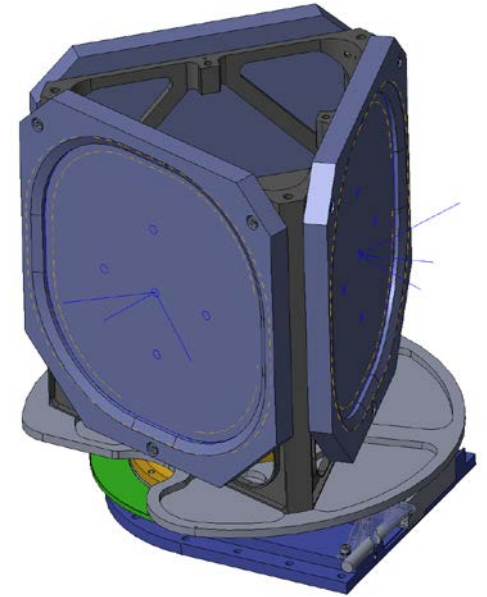
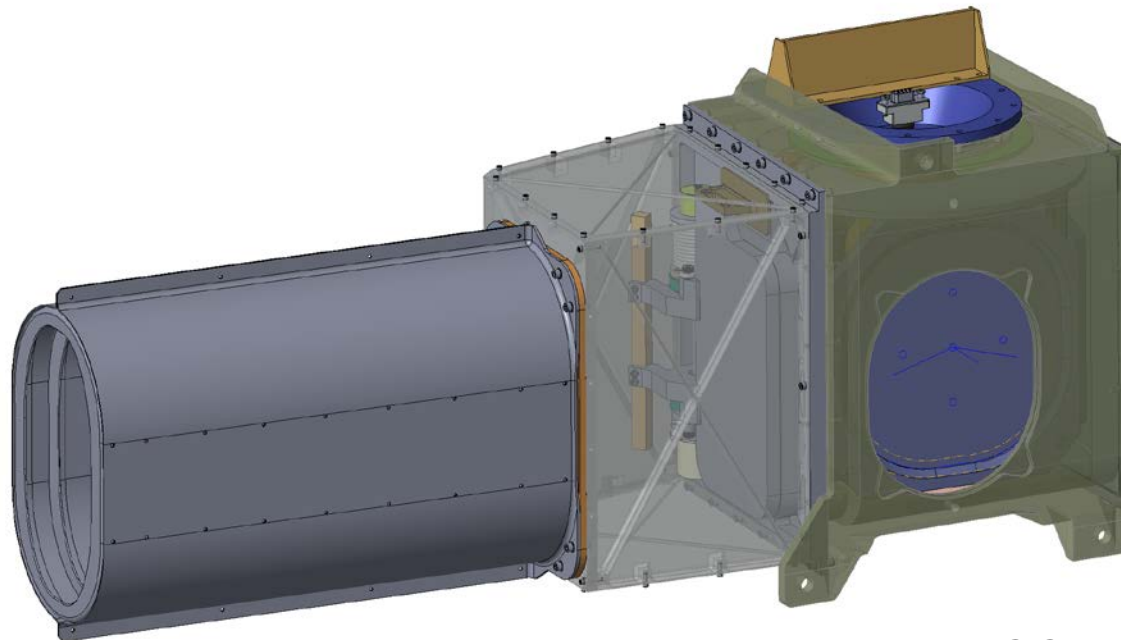


# OCI Solar Calibration Assembly



Preliminary design drawings

3 diffuser surfaces: 2 QVD (daily/monthly gain tracking) and 1 dim diffuser (linearity)



Linearity: hyperspectral CCDs accumulate several readout cycles (dim solar diffuser reflectance is lowest radiance, upper limit is saturation)



# Calibration Equation for each channel



$$L_m = K_1 * K_2(t) * (1 - K_3 * (T - T_{ref})) * K_4(\theta) * K_5(dn, T) * K_6(\omega) * dn$$

$L_m$  = radiance measured in a hyperspectral or SWIR band

$K_1$  = absolute gain factor

$K_2(t)$  = relative gain factor as a function of time  $t$

$K_3$  = temperature correction factor

$T$  = Instrument temperature measured at relevant location (electronics? housing? T.b.d.)

$T_{ref}$  = Reference Temperature (used during TVAC prelaunch characterization, close to expected on-orbit temperature)

$K_4$  = response versus scan

$\theta$  = scan angle (usually replaced by science pixel number per scan)

$K_5$  = nonlinearity factor

$K_6(\omega)$  = correction for tilt position  $\omega$  (+/- 20°)

DN = digital number measured at a certain  $\theta$

$DN_0$  = average of the digital numbers measured during dark current collection (average of ~40 numbers, once per scan)

$dn = DN - DN_0$

Note: out-of-band, polarization and straylight/crosstalk correction are handled later in the processing stage (need other information, such as surrounding radiances for straylight, amount of rayleigh/aerosol/glint for polarization)



# Absolute calibration K1: 3 uncertainties

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$$L_m = \mathbf{K}_1 * K_2(t) * (1 - K_3 * (T - T_{ref})) * K_4(\theta) * K_5(dn, T) * K_6(\omega) * dn$$

- K1 is a single number per band and mirror side, with units [radiance/dn]
- Prelaunch: GLAMR will provide absolute calibration, better than 0.5% accuracy
- Initial on-orbit calibration: solar diffuser will provide absolute calibration with <2% uncertainty
- Vicarious calibration will provide absolute calibration for most bands with 0.1% uncertainty after sufficient number of matchups have been acquired



# Temporal calibration K2

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$$L_m = K_1 * \mathbf{K}_2(\mathbf{t}) * (1 - K_3 * (T - T_{ref})) * K_4(\theta) * K_5(dn, T) * K_6(\omega) * dn$$

- Daily solar diffuser measurements will provide temporal trending
- A function of time (e.g. exponential, polynomial) will be fitted to the daily measurements
- A monthly solar diffuser (limited exposure) will provide correction to degradation of reflectance of daily solar diffuser
- After more than 2 years, lunar measurements will be used for temporal trending
- K2 uncertainty achieved with SeaWiFS lunar measurements: 0.13% (Eplee et al., Applied Optics, Vol. 51, Issue 36, 2012)
- K2 uncertainty allocation for OCI: 0.17%



# Solar Diffuser Reflectance Degradation

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- The monthly solar diffuser (limited exposure) will provide correction to degradation of reflectance of daily solar diffuser, but it will degrade as well
- The degradation pattern of the daily solar diffuser will be used to model the degradation of the monthly solar diffuser (heritage: MERIS, ozone instruments (OMI))
- If the degradation of the monthly solar diffuser is smaller than 0.6% over the mission life (or 2 years), an uncertainty of 0.1% can be achieved with the solar diffuser measurements alone (Meister, On-orbit trending of solar diffuser reflectance, PACE memo, 2017)
- Expected degradation for Quartz-Volume Diffuser: 0.15% (worst wavelength (350nm), based on on-orbit data from OMI/Aura)
- Daily solar diffuser will be used to monitor short term changes.

Expected degradation at 350nm: 6.7%



# Lunar Calibration

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## Lunar calibration background:

- Stable exo-atmospheric radiometric source with light levels comparable to TOA Earth observations.
- Moon used as reference by SeaWiFS, MODIS (2), and VIIRS.
- Observations require geometric correction for instrument-Moon and Sun-Moon distances, phase angle, libration angles.
- Frequency of observation: Twice per month (before and after full phase) over a limited range of phase angles (7deg +/- 0.5deg).
- Limitations:
  - Will require image oversampling correction.
  - Inherent scatter in observations (1-2%).
  - Multi-year time series required to identify radiometric trends.

## Geometric corrections:

- Complication: Heterogeneous albedo distribution over the lunar surface
- Corrections provided by USGS ROLO Lunar Photometric Model
- ROLO Model used as reference by most Earth-observing instruments



# Summary

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- OCI will start a rigorous calibration program in June 2019 with the ETU (Flight Unit: summer 2020)
- Goal is to minimize uncertainties due to image artifacts described here in order to achieve overall radiometric uncertainty of 0.5% (excluding absolute calibration)
- OCI will provide excellent temporal stability over mission life time (2 solar diffusers, lunar measurements twice a month)
- Linearity will be verified on-orbit with dim solar diffuser (new approach)