

## Low Size, Weight, and Power (SWaP) Sensors

- Gap in SC-228 Phase 1 DAA MOPS (DO-365)
- ADS-B and active surveillance are fairly low SWaP
- Radar consumes much power (> 1000 W ) and is heavy ( $>60 \mathrm{lbs}$ ), making it unsuitable for many UAS operations
- Low SWaP sensors considered in Phase 2 work
- Radar
- EO/IR
- Low SWaP work inherits most of the operational assumptions of DAA MOPS, such as
- Extended operations in airspace classes D, E (non-terminal), or G (non-terminal), or
- Transit operations in classes B and C
- Above 500 ft AGL
- UA performance assumptions for low SWaP operations
- Mission speed range 40 to 110 KTAS
- Capability of turning at a rate 7 degrees/sec


## Non-Cooperative DAA Well Clear (DWC)

- Phase I DWC was largely driven by TCAS II interoperability considerations, which are not a factor for encounters with noncooperative aircraft
- Phase 1 DWC is large and deemed very safe; however, the same level of safety might be achieved with a smaller DWC
- A smaller DWC may mitigate difficulty for UAS with Low SWaP sensors to remain well clear
- Non-cooperative aircraft
- Assumed to fly at 170 KTAS (95 percentile according to MIT Lincoln Lab's study) or less
- Predominantly in classes E and G below 10,000 ft MSL


## NASA's Encounter Set

- 17,100 hours of projected UAS mission trajectories in one day overlaid with each of 21 days' radar recorded visual flight rules (VFR) traffic
- Low SWaP encounters are a subset



## Candidate DWCs



## Alerting and Guidance Timeline



## Average Warning Alert Time before LoDWC



|  | DWC1 | DWC2 | DWC3 | DWC4 |
| :---: | :---: | :---: | :---: | :---: |
| HMD* $^{*}$ | 2000 ft | 2200 ft | 1500 ft | 2500 ft |
| $\boldsymbol{\tau}_{\text {mod }}{ }^{*}$ | 15 s | 0 s | 15 s | 25 s |

NMAC Risk Ratios


Loss of Well Clear Ratios


- Risk ratios are comparable among the DWC candidates
- No statistically significant difference for risk ratios
- DWC1 and DWC2 have the lowest loss of well clear ratios


## Non-Cooperative DAA Well Clear (DWC)

- On March 6th, 2019, SC-228 selected a Detect-and-Avoid (DAA) Well Clear (DWC) (previously referred to as DWC2) for non-cooperative aircraft for additional studies
- The non-coop DWC and Phase 1 DWC yield comparable safety metrics such as the NMAC risk ratio and loss of DWC ratio
- Simulations were based on
- Truth aircraft states
- Phase 1 pilot response model in a deterministic mode
- Version 1.0 of the DAIDALUS algorithm

| DWC | $\Gamma_{\bmod }(\mathrm{sec})$ | HMD* $(\mathrm{ft})$ | $h^{*}(\mathrm{ft})$ |
| :---: | :---: | :---: | :---: |
| Non-Coop | 0 sec | 2200 ft | 450 ft |
| Phase 1 | 35 sec | 4000 ft | 450 ft |

## Maneuver Initiation Analysis



INT Airspeed, KTAS

- 100
- 130
- 170


## Radar Declaration Range

RDR $=$ MIR +25 seconds alerting time converted distance


INT Airspeed, KTAS

- 100
- 130
- 170


## Current Activities

- NASA/Honeywell Flight Test 6 (Aug. - Dec. 2019)
- NASA closed-loop fast time simulation with sensor uncertainties
- Low SWaP human-in-the-loop simulation (Sep. 2019)
- Low SWaP sensor surveillance volume analysis (Jul. to Dec. 2019)
- DAA closed-loop simulation with an EO/IR sensor Lincoln Lab., May to Dec. 2019)
- Active surveillance omnidirectional antenna analysis (MIT Lincoln Lab., May to Dec. 2019)


## Backup Slides

## UAS Missions

| Number | Mission Types | Airspace | UAS Group | Cruise Altitude | Cruise Speed (KTAS) | Flight Pattern |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 1 | Aerial Imaging and Mapping | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, E, and G (including Mode C Veil) with Class B or C transition | Aerosonde Mk 4.7 | 3000 ft . AGL | 44 to 51 | Radiator-grid pattern or circular pattern |
| 2 | Air Qualtiy Monitoring | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, E, and G (including Mode C Veil) with Class B or C transition | Shadow-B (RQ7B)/NASA Sierra | $4 k, 5 k$, and $6 k \mathrm{ft}$ AGL | 74 to 89 | Radiator-grid pattern |
| 3 | Airborne Pathogen Tracking | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, E, and G (including Mode C Veil) with Class B or C transition | Shadow-B (RQ7B)/NASA Sierra | 3,000 ft., 5,000 ft. and 10,000 ft. AGL | 72 to 97 | Radiator-grid pattern |
| 4 | Flood Inund. Mapping | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, Mode C Veil, E, and G | Aerosonde Mk 4.7 | 4,000 ft. AGL | 46 to 51 | Grid pattern |
| 5 | Flood Stream Flow | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, Mode C Veil, E, and G | Aerosonde Mk 4.7 | 4,000 ft. AGL | 46 to 51 | Grid pattern and/or along stream direction |
| 6 | Law Enforcement | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, E, and G (including Mode C Veil) with Class B or C transition | Aerosonde Mk 4.7 | 3,000 ft. AGL | 44 to 51 | Three types of pattern: <br> 1) grid pattern, 2) random, 3) outward spirial |
| 7 | Point Source Emission | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, Mode C Veil, E, and G | Shadow-B | 3,000 ft. AGL | 72 to 80 | Grid pattern and/or along stream direction |
| 8 | Spill Monitoring | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, Mode C Veil, E, and G | Shadow-B/Sierra | $\begin{gathered} 3,000 \mathrm{ft} \text {. to } 13,000 \\ \mathrm{ft} . \mathrm{AGL} \end{gathered}$ | 72 to 93 | Up and down-wind flights in a radiator-grid pattern, Round-theclock |
| 9 | Tactical Fire Monitoring | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, E, and G (including Mode C Veil) with Class B or C transition | ScanEagle/Shadow-B | 3,000 ft. AGL | 72 to 75 | Circular flight path following the perimeter of a wildfire |
| 10 | Traffic Monitoring | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, E, and G (including Mode C Veil) with Class B or C transition | Shadow-B | 1,500 ft. AGL | 58 to 84 | Geo-spatial monitoring flight path |
| 11 | Wildlife Monitoring | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, Mode C Veil, E, and G | Aerosonde Mk 4.7 | 3,000 ft. AGL | 44 to 51 | Radiator-grid pattern |
| 12 | News Gathering | Flights depart from and return to a regional airport located within 40 nmi . of OEP 35 airports; Class D, E, and G (including Mode C Veil) with Class B or C transition | Aerosonde Mk 4.7 | $\begin{gathered} 1,500 \mathrm{ft} \text {. to } 3,000 \\ \mathrm{ft} . \mathrm{AGL} \end{gathered}$ | 44 to 51 | Random-path: e.g., police-chase; Circular orbit: |

## Speed and Altitude of UAS and VFR Traffic






