

NASA Station Explorer for X-ray Timing and Navigation Technology (SEXTANT) Mission Operations Architecture

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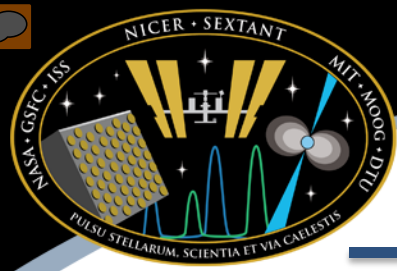
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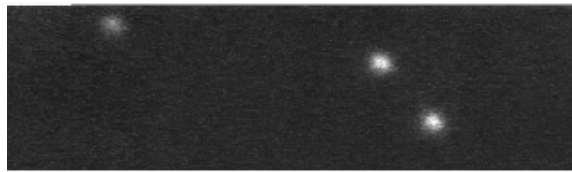
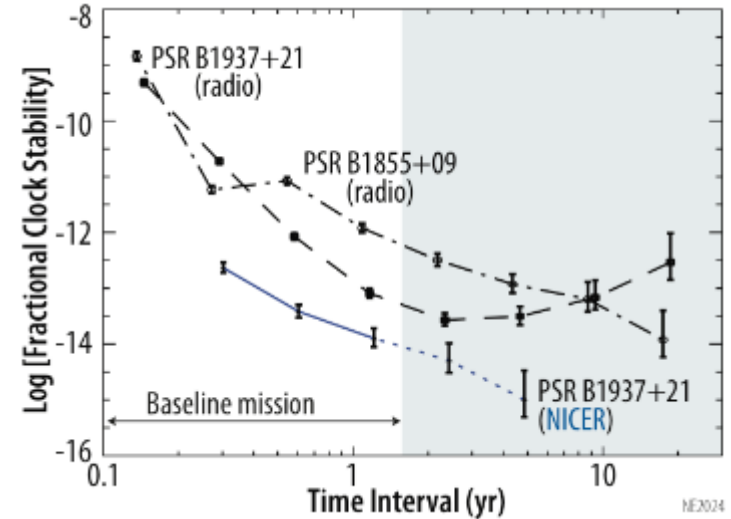
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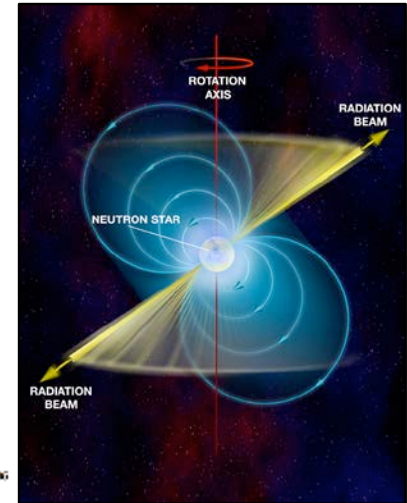
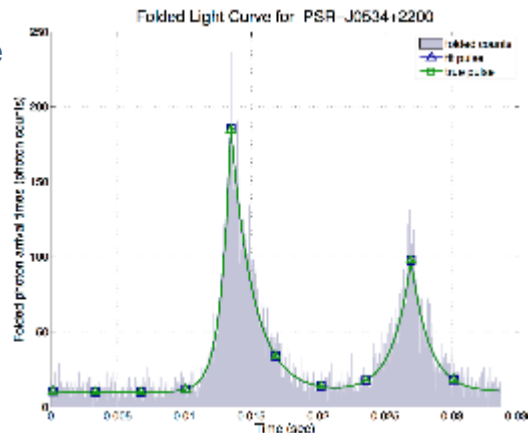


X-ray Pulsar Navigation (XNAV)

- Millisecond pulsars (MSPs): rapidly rotating neutron stars that pulsate across electromagnetic spectrum
- Some MSPs rival atomic clock stability at long time-scales
 - Predict pulse arrival phase with great accuracy at any reference point in the Solar System via pulsar timing model on a spacecraft
 - Compare observed phase to prediction for navigation information
- Why X-rays?
 - Many stable MSPs conveniently detectable in (soft) X-ray band
 - X-rays immune to interstellar dispersion thought to limit radio pulsar timing models
 - Highly directional compact detectors possible
- **Main Challenge: MSPs are very faint!**



Crab Pulsar (1/3 speed), Cambridge University, Lucky Image Group





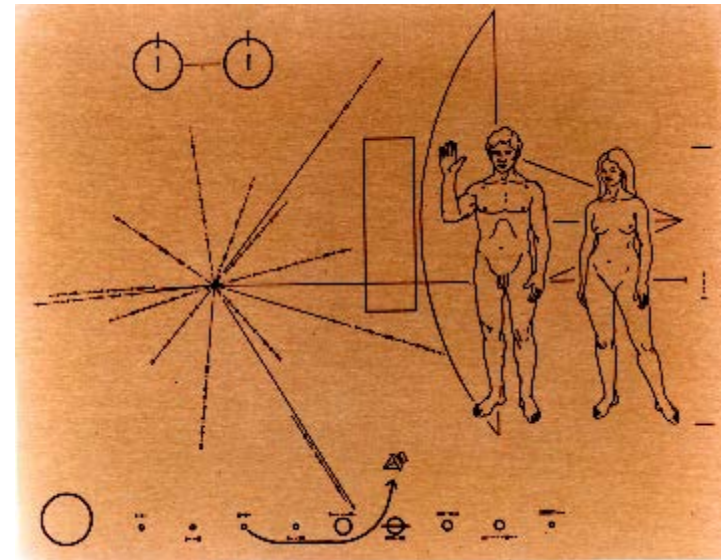
X-ray Pulsar Navigation (XNAV)

Applications

- XNAV can provide autonomous navigation and timing that is of uniform quality throughout the solar system
 - Is enabling technology for very deep space missions
 - Provides backup autonomous navigation for crewed missions
 - Augments Deep Space Network (DSN) or op-nav techniques
 - Allows autonomous navigation while occulted, e.g., behind Sun

History

- Pulsars were discovered in 1967 and immediately recognized as a potential tool for Galactic navigation
- US Naval Research Laboratory (NRL) (1999-2000)
 - Unconventional Stellar Aspect (USA) Experiment
- DARPA XNAV, XTIM Projects (2005-2006, 2009-2012)
- Significant body of research (international interest, academic research, several Ph.D. dissertations, etc.)
- **NICER/SEXTANT successfully demonstrates real-time, onboard, autonomous XNAV (Nov 2017)**



*Pioneer plaque (Pioneer 10,11 1972-73)
with pulsar periods and relative
distances to our Sun*

Credit: NASA Ames



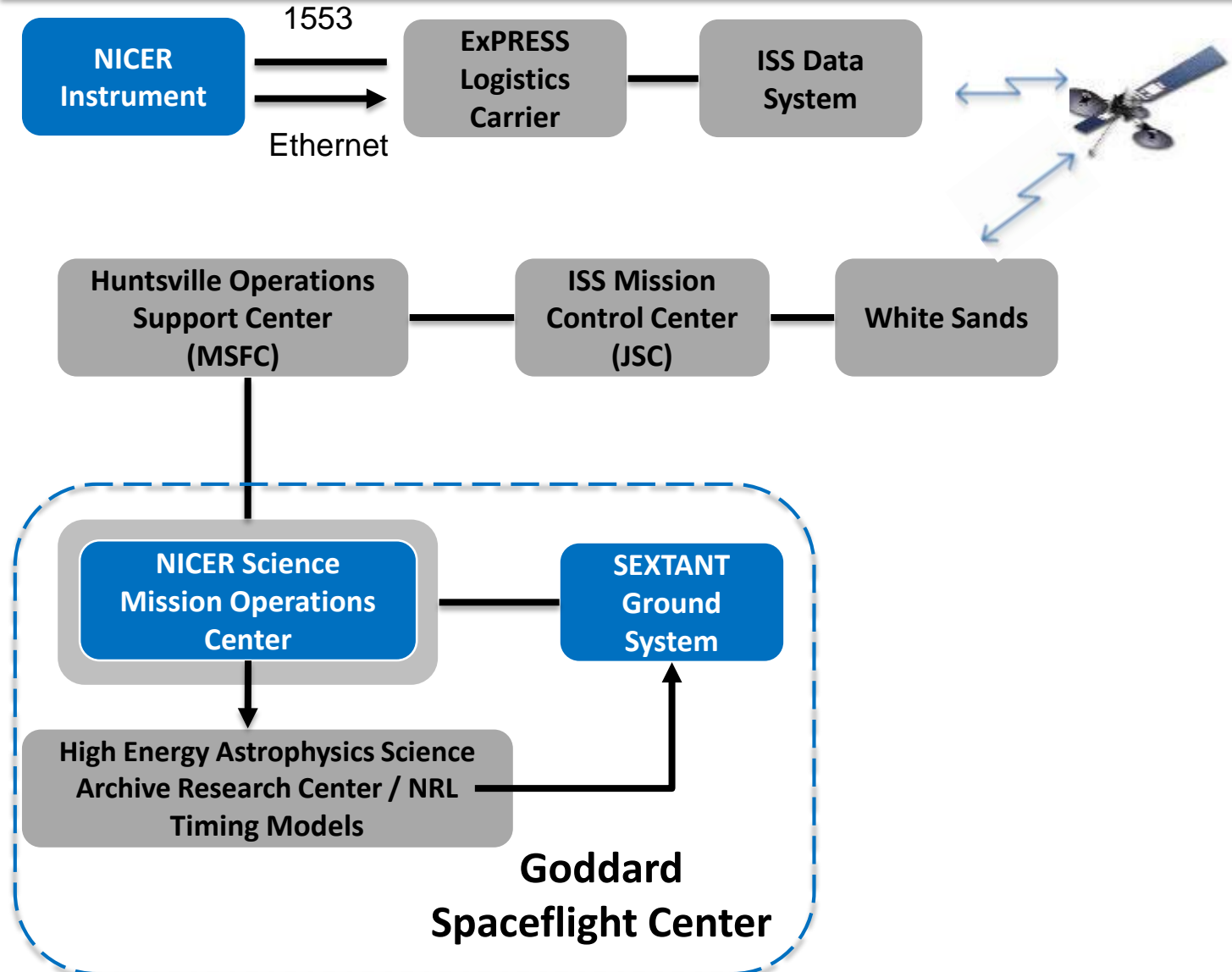
NICER/SEXTANT Overview

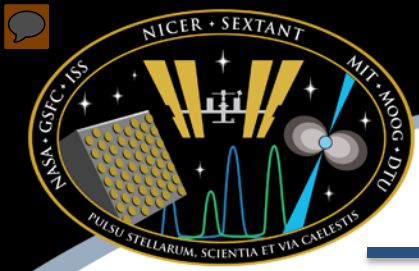
- Launched on June 3, 2017 on Space-X CRS-11 to ISS
- Neutron-star Interior Composition Explorer (NICER)
 - Fundamental investigation of ultra-dense matter: structure, dynamics, & energetics
 - Nearly ideal XNAV detector combination: low-background, large effective collecting area, precise timing, scalability, and low-cost
 - Assembly of 56 X-ray concentrators and detectors, $\sim 1800 \text{ cm}^2$ effective collecting area in soft X-ray band
 - Scalable design, e.g., reduce to 1,4,10, etc. concentrators
- SEXTANT – Successful demonstration results reported in Mitchell (2018) and Winternitz (2018)





Operations Overview





Operations Architecture (1/3)

NRL

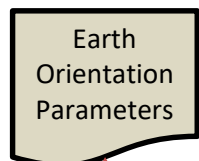
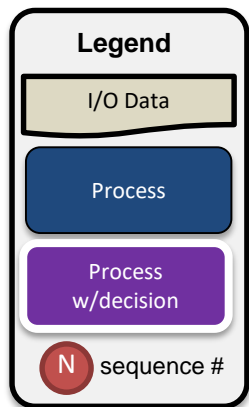
Radio and X-ray observations

1

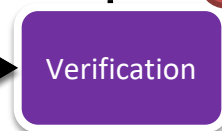
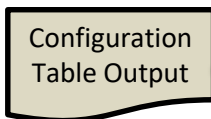
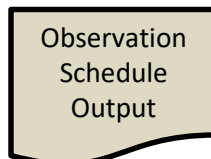
SEXTANT

ISS State Data

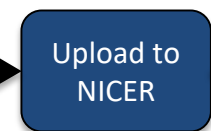
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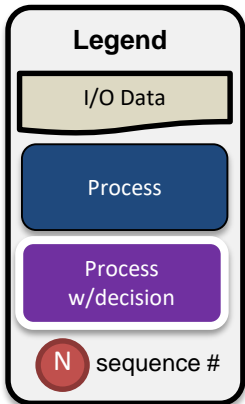
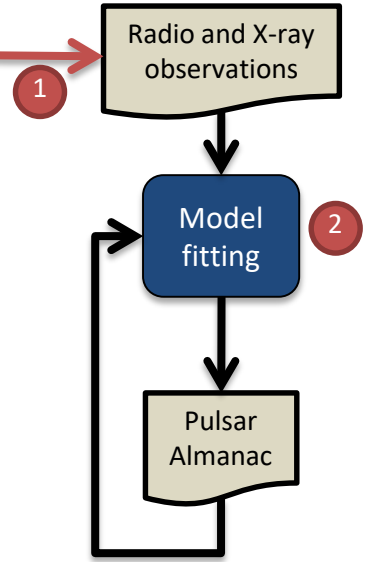
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NICER SMOC

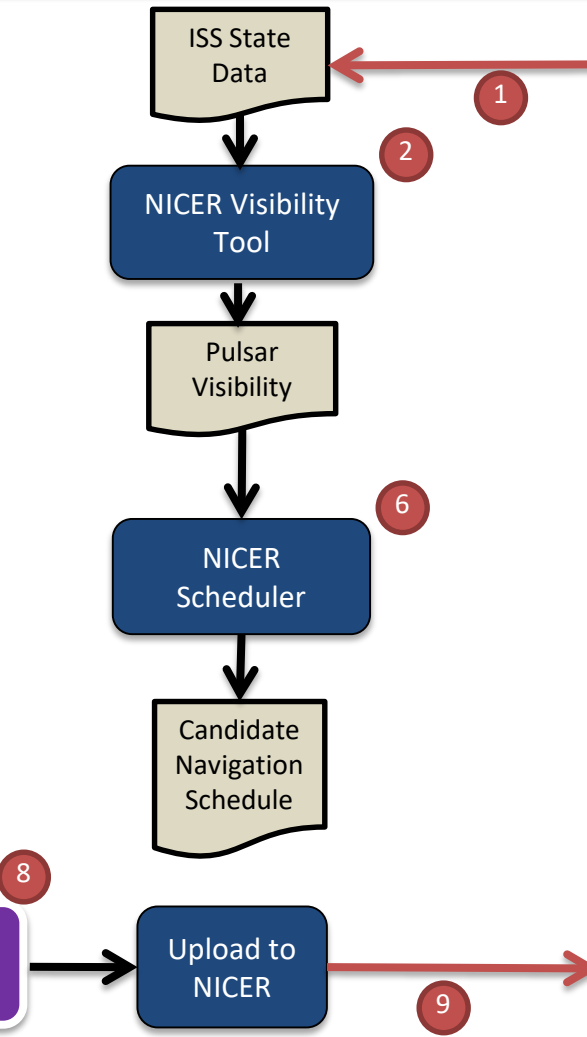
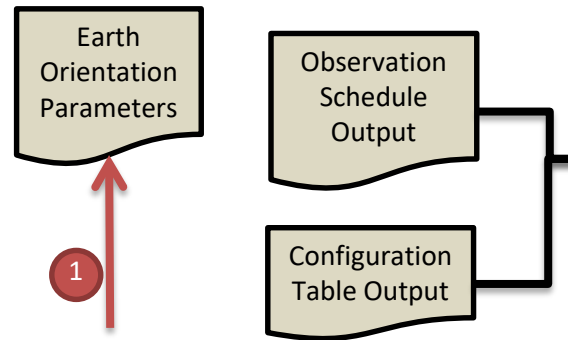


Operations Architecture (2/3)

NRL



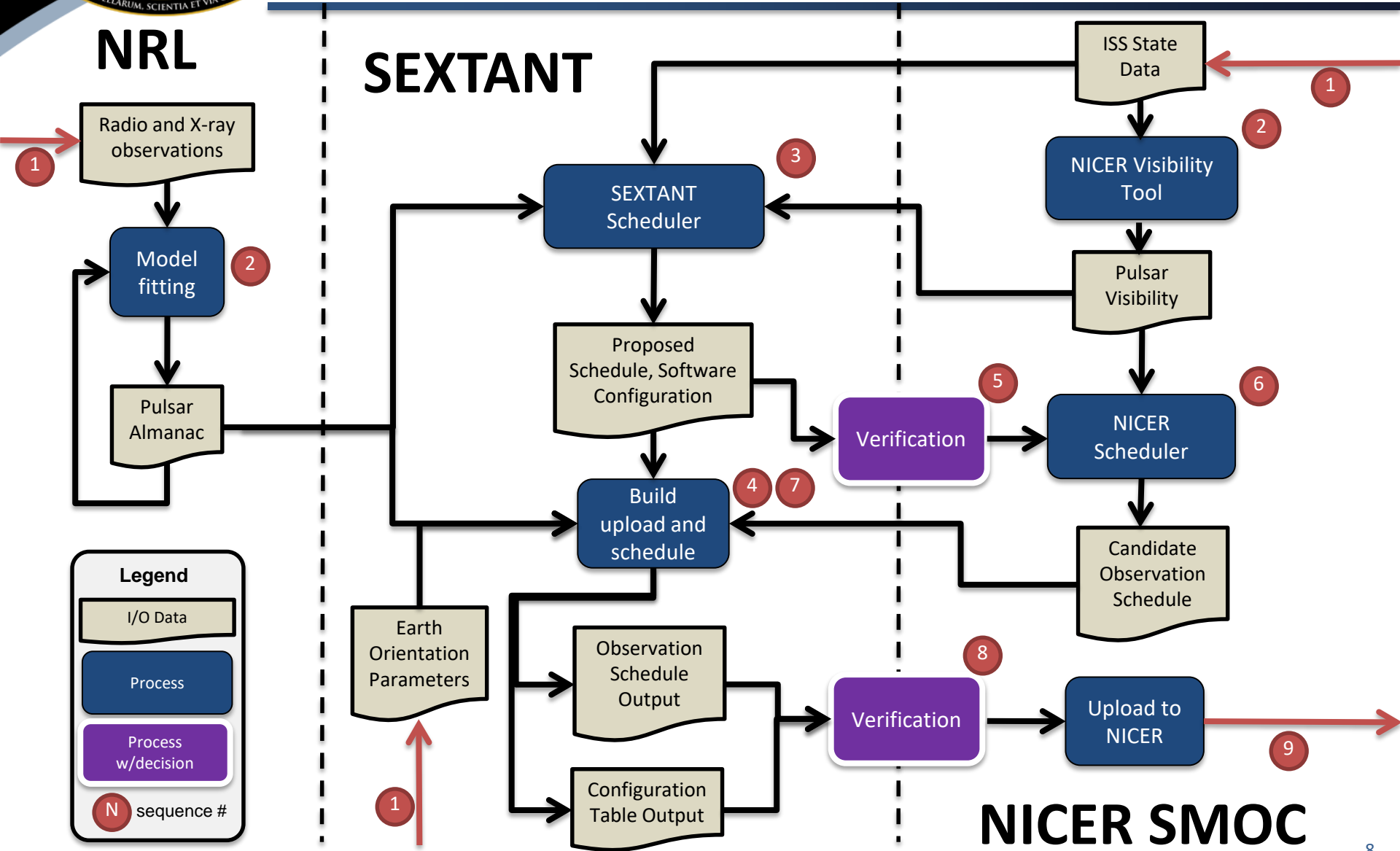
SEXTANT



NICER SMOC



Operations Architecture (3/3)





Concept of Operations

Beginning of the SEXTANT
Demo
Upload to NICER
T-0 days

Optional
2 day
upload
(T+1 day)

Optional
2 day
upload
(T+3 days)

Optional 2
day
upload
(T+5 days)

Continue
for 2nd
week



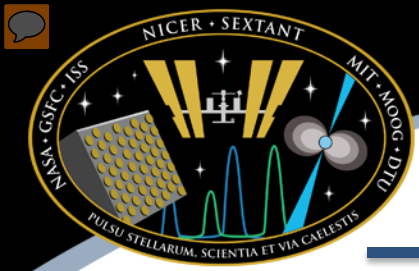
Optional
ISS
Ephemeris
Update
(T+0.5
days)

Optional
ISS
Ephemeris
Update
(T+2.5
days)

Optional
ISS
Ephemeris
Update
(T+4.5
days)

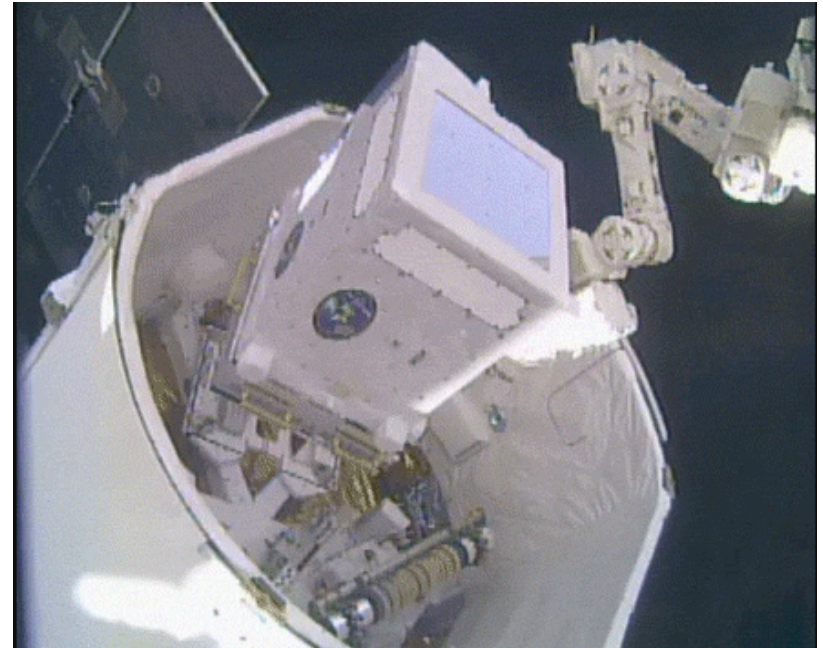
Optional
ISS
Ephemeris
Update
(T+6.5
days)

Cycle Repeats for the 2nd
week of the SEXTANT
Demonstration.



On Orbit Demo Preparation

Date	ISS Critical Operations Event
6/5/2017	SpaceX Dragon (NICER payload) docks
6/16/2017	Progress 67 resupply ship docks
7/3/2017	SpaceX Dragon capsule departs
7/20/2017	Progress 66 departs
7/28/2017	Soyuz MS-05 docks
8/16/2017	SpaceX Dragon docks
9/17/2017	SpaceX Dragon departs
9/27/2017	ISS orbital reboost
10/16/2017	Progress 68 docks

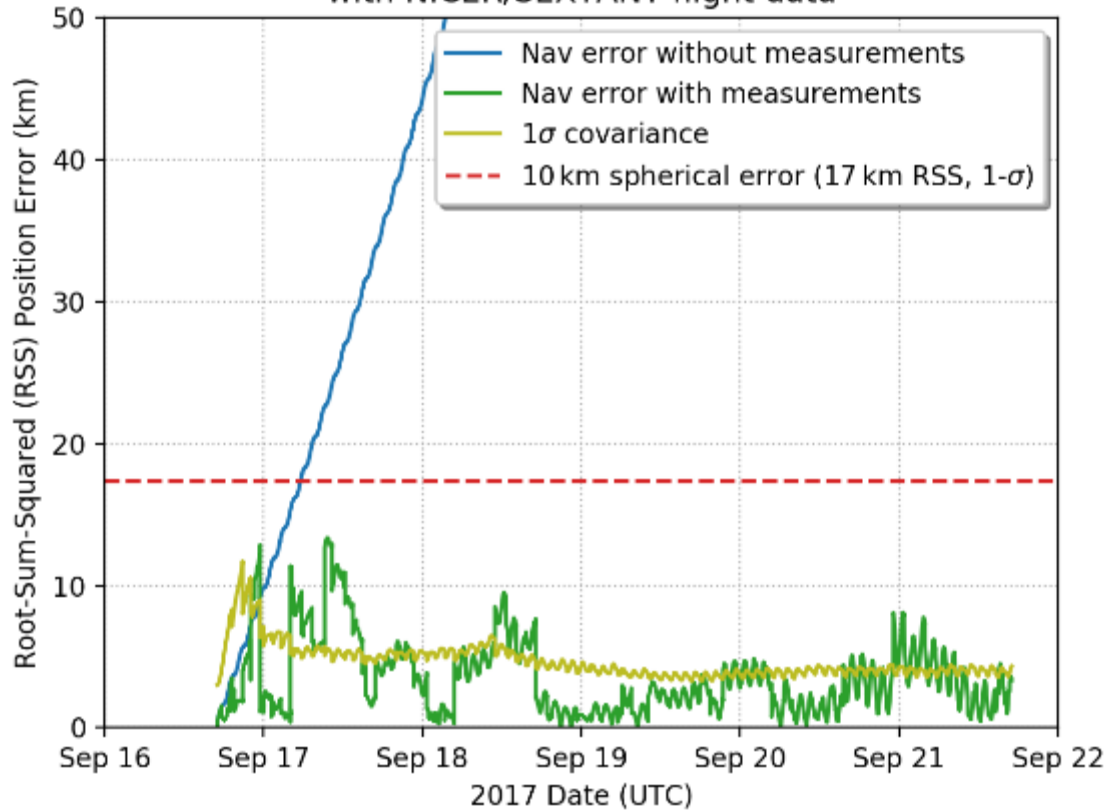


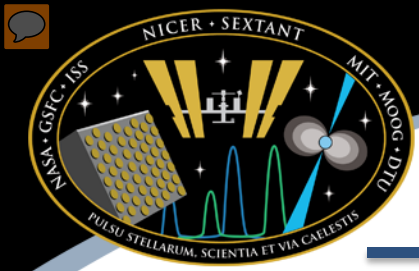
https://heasarc.gsfc.nasa.gov/docs/nicer/nicer_gallery.html



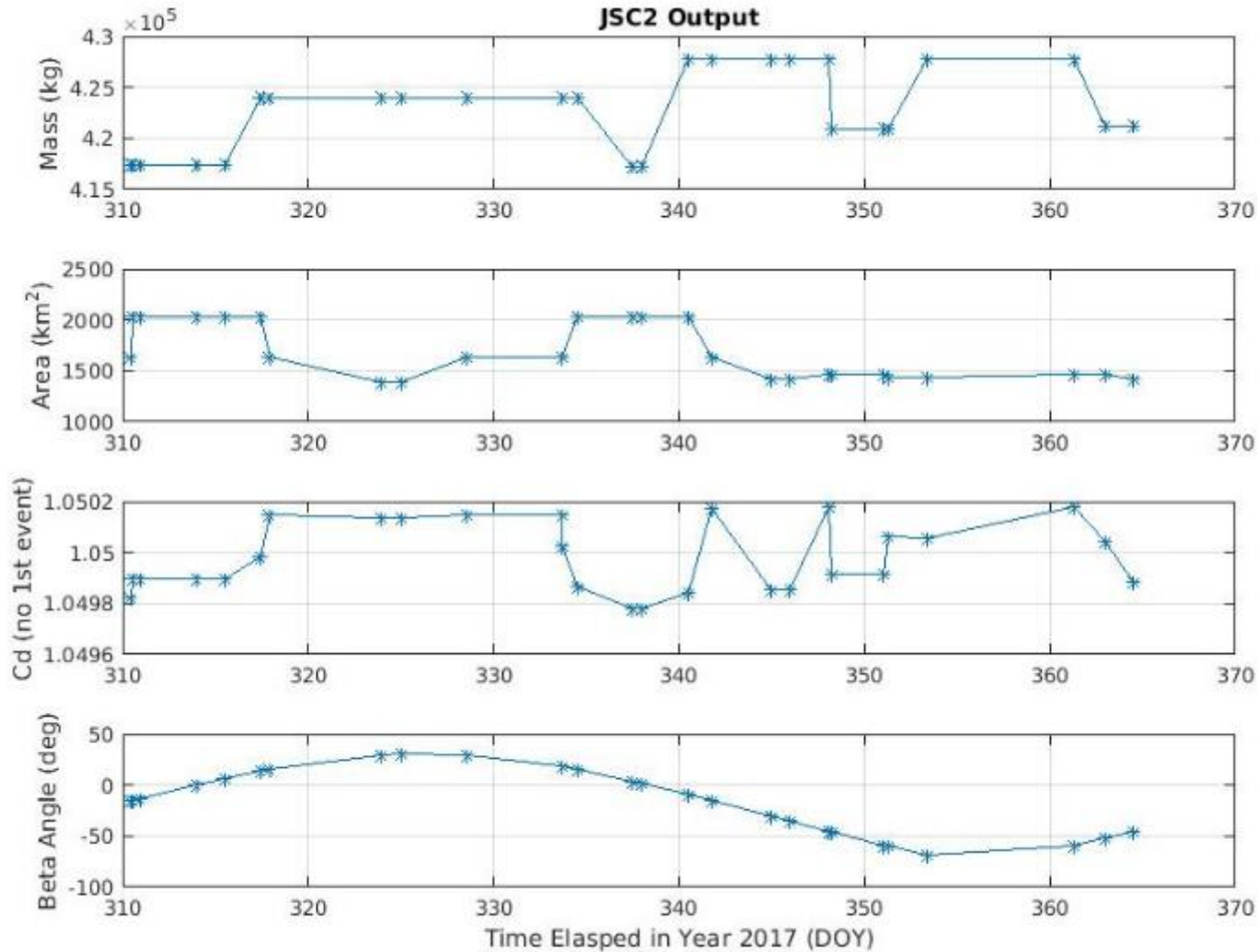
On Orbit Demo Preparation

Ground-processed navigation performance with NICER/SEXTANT flight data





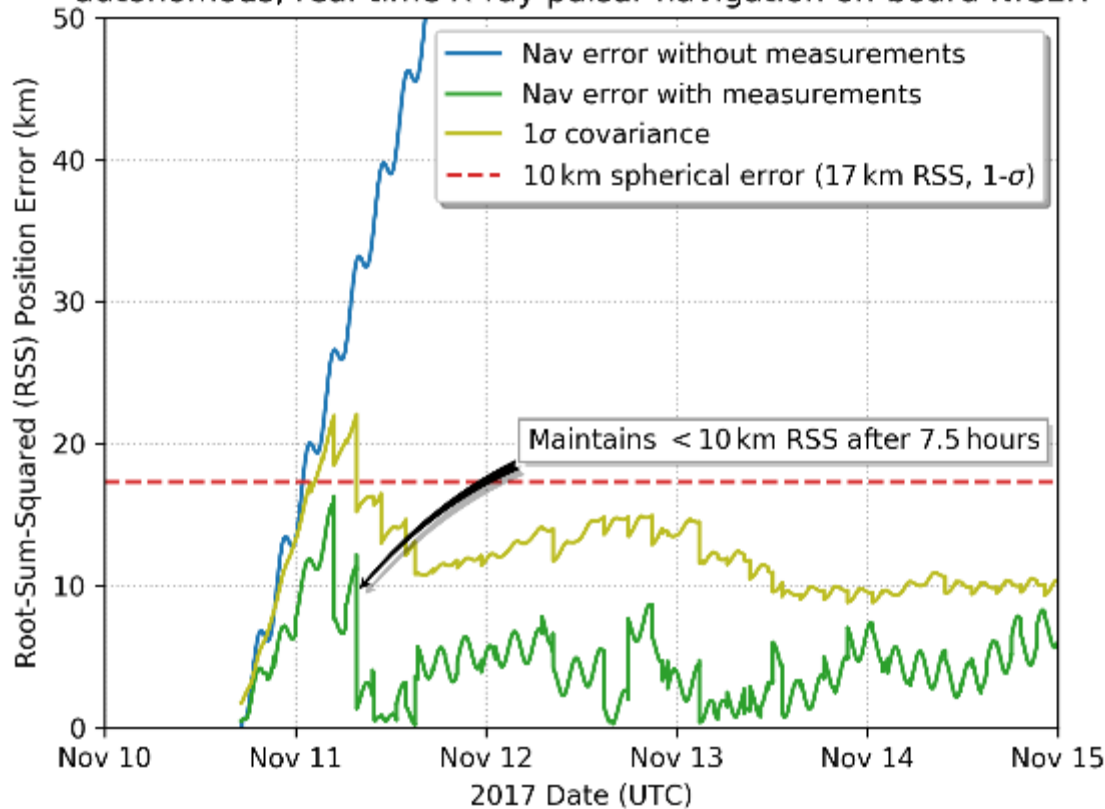
On Orbit Demo Preparation

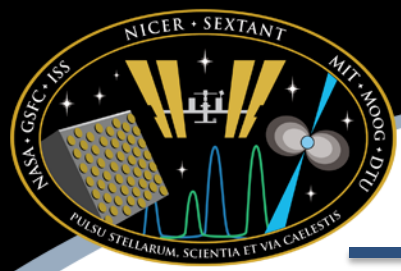




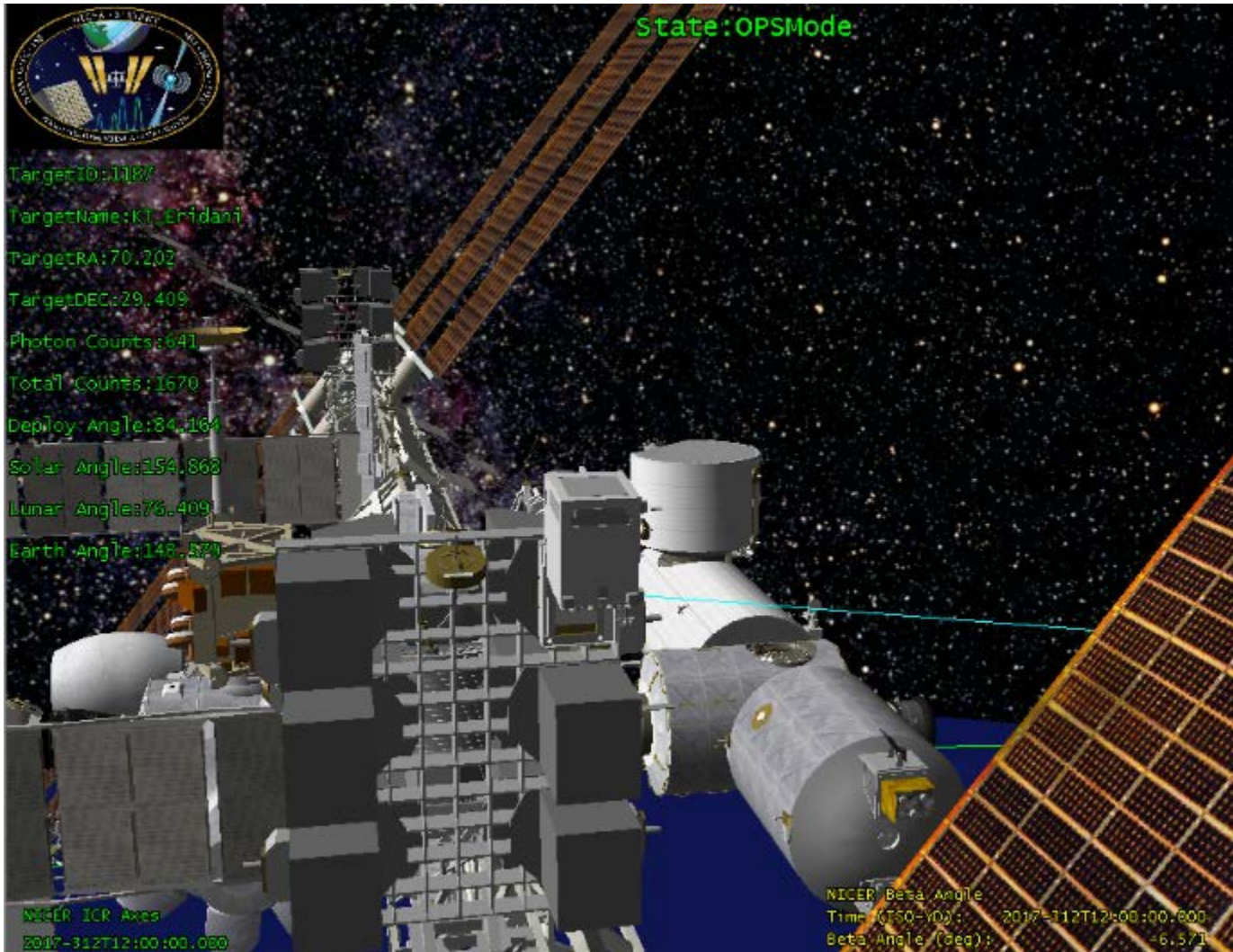
XNAV Demonstration

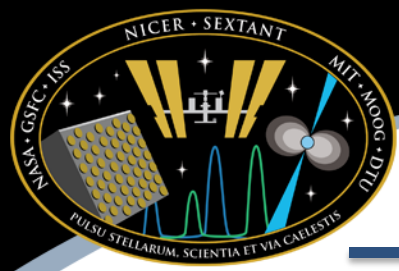
SEXTANT Experiment 1 successfully demonstrates fully autonomous, real-time X-ray pulsar navigation on-board NICER





XNAV Demonstration





Conclusions & Future Work

- SEXTANT demonstrated XNAV on board and in real time on the ISS in 2017
 - 10 km settled RSS in 7.5 hours with < 1 km point solutions
 - 33% duty cycle of observations on 4 pulsar targets
- Illustrated the SEXTANT Ground System used to execute the demonstration
 - Integrated with the NICER instrument/ops team, ISS JSC and MSFC payload operation teams
 - Performs navigation filtering while simultaneously supporting NICER science and ISS mission operations



https://heasarc.gsfc.nasa.gov/docs/nicer/nicer_gallery.html