Modular Standards for Space Power Systems

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Brent G. Gardner

NASA Glenn Research Center Cleveland, Ohio







- Standardization
 - Interfaces
 - Modularization
- AMPS Project
- Modular Electronics Standard for Space Power Systems (MESSPS)
 - **Definitions**
 - Module "Trading Cards"
 - Examples
- Future Work & Conclusions













Standardization of interfaces:

- Focuses innovation on function/performance of device
- Increases competition by allowing easier injection into market
- Allows for multiple supply chain options
- Improves efficiency (fewer adapters, etc.)
- Reduces cost to consumer





Modularization is an extension of standardization, adding <u>functional</u> requirements to a standardized interface. However, the effects are mixed:

Pros:

- Commonality/Reusability
 - Interchangeable between systems
 - Allows scavenging from unused systems
 - Reduces sparing needs
- Flexibility
 - Meant for scalable systems
 - Unrestricted system architecture/topology
- Reliability/Maintainability
 - Reduced capability over complete loss of use
 - Removable replacements minimize downtime

Cons:

- Unoptimized Design
 - Higher mass/volume due to packaging and/or incremental nature
 - Greater complexity due to more interconnects
- System Verification
 - Integration of multiple vendor products
 - Replacing modules invalidates system testing
- Limited Extensibility
 - More difficult to ensure backwards compatibility ("future-proof")

As systems become larger and/or more complex, modularity can prove to be more economical.



NASA

Example: Battery design

For the same energy storage capacity, a modular design is more complex and has a higher mass, but offers less tangible benefits:

- Component reuse in dissimilar systems
- Lower-mass replaceables
- Fault tolerance (at reduced capacity)

Modularization can seem unappealing unless all factors are taken into account. This makes "selling" modularity a challenge.





Solution	Modular	Optimized
Components	15 "AAA"	1 "D"
Mass	172.5 g	139 g
Volume	57 cm ³	56 cm ³





Why is this project important?

- Modular power systems provide opportunities to minimize maintenance operations, improve power system availability, and reduce the number of unique spare parts, thus enabling sustainable future human exploration missions and systems
- This project matures modular power system technologies, inclusive of a modular power standard, modular power electronics, autonomous power controls, and a modular power testbed in support of NASA's cis-lunar Gateway

Objectives:

The AMPS project seeks to transform future space power system architectures with a modular approach, standardizing the power system at the electronics module level, and validating the modular approach through ground-based demonstrations





NASA

- **1995** Modular electric space power system proposed by Button & Baez (NASA GRC)
 - ... NASA focuses on Shuttle, ISS, & Constellation Program (no modular concepts) ...
- 2012 NASA's Advanced Exploration Systems (AES) program begins AMPS project
 - ... Early prototypes of modular concepts developed, interfaces formalized, 4 module types defined ...

2016 - First draft of modular electronics standard generated

- ... Prototype designs refined, 3 module types added, system-level testing ...
- 2019 Modular Electronics Standard for Space Power Systems (MESSPS) generated

 \ldots Being considered for lunar missions and beyond \ldots





NASA

AMPS targets:

- Larger, multi-kilowatt, multi-vehicle/element manned missions
- Power <u>distribution & conversion</u>, not generation or storage (yet)
- <u>120VDC</u> primary distribution bus (SAE AS5698/ISPSIS compatible)
- In-space <u>replacement</u> of modules (cold/warm swap, blind mate)
- Standardizing module <u>functions & interfaces</u>, not designs







Electronics <u>modules</u> can be arranged into <u>chassis</u> to form <u>assemblies</u>. <u>Backplanes</u> have unique <u>slot</u> arrangements and connections for each application.





The MESSPS currently defines 7 modules:

- Utility modules: supporting functions
 - Controller Module (CTLM)
 - Housekeeping Power Module (HKPM)

• Switchgear modules: remote control & fault protection

- Load Switchgear Module (LSGM)
- Bus Switchgear Module (BSGM)
- High Current Switchgear Module (HCSM)

• Converter modules: voltage conversion & regulation

- Portable Equipment Power Module (PEPM)
- Bidirectional Converter Module (BDCM)

No specific backplanes are defined (yet), but there are requirements for implementing any backplane.







Controller Module (CTLM)



Functions:

- Spacecraft-to-internal network adapter
- Validates chassis configuration
- Monitors module status
- Translates commands & telemetry



SCCN: Spacecraft Communications Network

Inputs/Outputs:

- Spacecraft communication network (Ethernet)
- Internal data bus (dual CAN)

Size: 3U x 1 Slot

<u>TRL</u>: 4

Status: 4th gen. prototype demonstrated in chassis

Prototype Design / Major Components:

- Raspberry Pi Compute Module running Raspbian operating system
- Ethernet & CAN controllers





Housekeeping Power Module (HKPM)



Functions:

Generates Housekeeping Power Bus (5VDC)
from 120VDC source



Inputs: 120VDC Outputs: 5VDC @ 30A (150W)

Size: 3U x 1 Slot

<u>TRL</u>: 4

<u>Status</u>:

• 3nd gen. prototype demonstrated in chassis

Prototype Design / Major Components:

- Digilent Cmod A7 FPGA module
- 150W Vicor "Micro" DC/DC converter





Bus Switchgear Module (BSGM)



Functions: Pre-Charge Bidirectional bus switch (supply & return, or Supply Switch Supply supply only with lower on-state resistance) TSC TSC Bus A Bus B **Bidirectional pre-charge circuit** Configurable, resettable trip Return Return Transient suppression Supply Supply Switch Return Return **TSC: Transient Suppression Circuit** 67.5°C Auto 1 71.5 Inputs/Outputs: 2 ports @ 120VDC, 40A a state and and and and all a Size: 3U x 1 Slot **TRL:** 4 Status: 22.0 5th gen. prototypes demonstrated in chassis ε=0.95 BG=22.0 τ=100% 1/30/19 08:07:08

Thermal Test

Pre-Charge/Make Test





Functions:

- 4-channel unidirectional switch
- Current-limiting with configurable levels
- Resettable trip
- Parallelable channels can form "virtual power channels" (VPCs)
- Inductive load protection, safe discharge

Inputs: 4 @ 120VDC, 4A Outputs: 4 @ 120VDC, 4A

Size: 3U x 1 Slot

<u>TRL</u>: 4

<u>Status</u>:

• 6th gen. prototypes demonstrated in chassis, paralleled 8 channels across 2 modules



RPC: Remote Power Controller TSC: Transient Suppression Ckt. BFC: Bleeder-Flyback Ckt.



Short-Circuit Load Test (Current-Limiting)





Flexibility!

The 4x4A outputs of the Load Switchgear Modules (inside a single PDU) can be paralleled to form higher-current VPCs.

Parallelization can take place on the backplane, cables, and/or at the load.

Current-limiting algorithms handle timing mismatches to prevent single-channel faults during transient events.







Functions:

- Variable output, isolating DC/DC converter ("universal adapter")
- Load cable or user programmable output
- Remote voltage sense



Input: 120VDC Output: 3-28VDC @ 5.3A (up to 150W @ 28VDC)

Size: 3U x 1 Slot

<u>TRL</u>: 4

<u>Status</u>:

- Jointly funded by JSC and GRC
- 3rd gen. prototypes demonstrated in chassis





Efficiency Test

Featured on Instagram @nasaglenn





Functions:

- Bidirectional DC/DC converter
- Configurable current & voltage setpoints
- Configurable, resettable trip
- Configurable secondary: 120VDC or 28V
- Parallelable: synchronized, staggered switching for reduced EMI

Inputs/Outputs:

- "Primary": 120VDC @ 10A (~1kW)
- "Secondary": 120VDC @ 10A or 28VDC @ 40A

Size: 3U x 3 Slots

<u>TRL</u>: 4

<u>Status</u>:

 3rd gen. prototypes demonstrated in chassis, paralleled 4 module sets @ 4kW





Thermal Test

Efficiency Test



High Current Switchgear Module (HCSM)



Functions:

- Bidirectional supply-side switch
- Bidirectional pre-charge circuit*
- Configurable, resettable trip
- Transient suppression*



TSC: Transient Suppression Circuit

Input/Outputs: 2 ports @ 120VDC, 200A

Size: 3U x 3 Slots

<u>TRL</u>: 4

<u>Status</u>:

- 1st gen. prototype demonstrated
- *Next: Add pre-charge, transient suppression, additional connectors; integrate into chassis



Thermal Test @ 200A

Electrical Test







Rear

Тор

Front







This diagram represents the power system of a notional space station.

Each large box is a separate "dockable" spacecraft, or "element".

Each small box is a functional power system assembly, or "unit":

- **MBSU**: Main Bus Switching Unit
- **DDCU**: DC/DC Converter Unit
- **BCDU**: Battery Charge/Discharge Unit
- **PDU**: Power Distribution Unit
- **PEP**: Portable Equipment Panel



Example Spacecraft Power System









• Verification of MESSPS with "flight" parts and designs

- Advance Technology Readiness Level (TRL) from 4 to 6+
- Support from one or more aerospace vendors

• End-to-end power distribution system testing

- Validates interactions between sources, modules, and loads
- Testbeds at NASA's Glenn Research Center and Johnson Space Center
- Architectures representative of planned missions
- Promote adoption by current and future missions
 - Currently challenging due to immaturity/low TRL
 - Current missions have shown interest, but not fully committed
 - Continue to involve domestic and international partners





- Standardization and modularization provide benefits to the end user
 - In this case, NASA and its missions are the end user
 - Needed to enable deep space/long duration missions
- NASA's AMPS project developed the MESSPS
 - Prototypes used to prove concepts and validate requirements
 - 7 module types; including utility, switchgear, and converter modules
- AMPS project promoting adoption of the MESSPS
 - Near term: Lunar orbiting space station
 - Long term: Lunar and/or Martian surface habitat
 - Domestic and international aerospace agencies and commercial vendors







Questions?