

# GRC Remote Sensing Campaign of Harmful Algal Blooms 2017-2019



Presented to:

HAB Algorithm Development Meeting

NASA Glenn Research Center

Presented by:

Roger Tokars

Optical Systems Research Engineer

NASA Glenn Research Center



## **GRC Remote Sensing Campaign of Harmful Algal Blooms 2017-2019**

by Roger Tokars

- Campaign Summary
- Aircraft install
- HSI versions and specifications
- Flight/HSI issues

# Campaign Summary

## Remote Sensing of Harmful Algal Blooms in the Great Lakes Region

### A Leader in Airborne Hyperspectral Imaging

- A focus on Western Lake Erie.
- Monitoring HABs for local water treatment operators
- Validating future HAB sensing technologies

### GRC Operations past and present

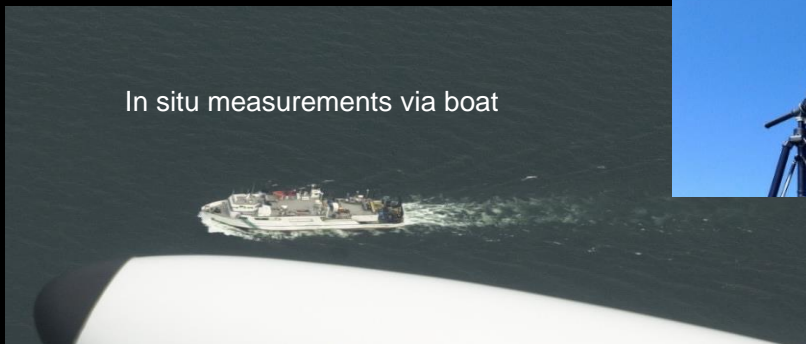
- 2014 Expanded from 4 to 14 NASA flights to meet demand
- 2015 26 NASA flights at about 80 flight hours
- 2016 17 NASA flights.
- 2017 13 NASA Flights at about 31 flight hours.
- 2018 13 NASA Flights at about 32 flight hours.
- 2019 9 NASA Flights at about 26 flight hours.

### Research partners also conduct water sampling and ground optical measurements

- NOAA GLERL
- University of Toledo
- Kent State University
- Michigan Tech Research Institute
- Bowling Green State University
- University of Cincinnati
- Naval Research Lab
- University of Alabama



Shore radiance measurements



***HAB information provided by remote sensing and water sampling can provide for early warning to ensure proper water treatment and shutoff avoidance***



# Hyperspectral Imager on Twin Otter (2015, 2017, 2018, 2019 )



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### Installation from 2015



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# HSI 2.0

Flown on T-34, Twin Otter, and Viking S3 (2007-2017)

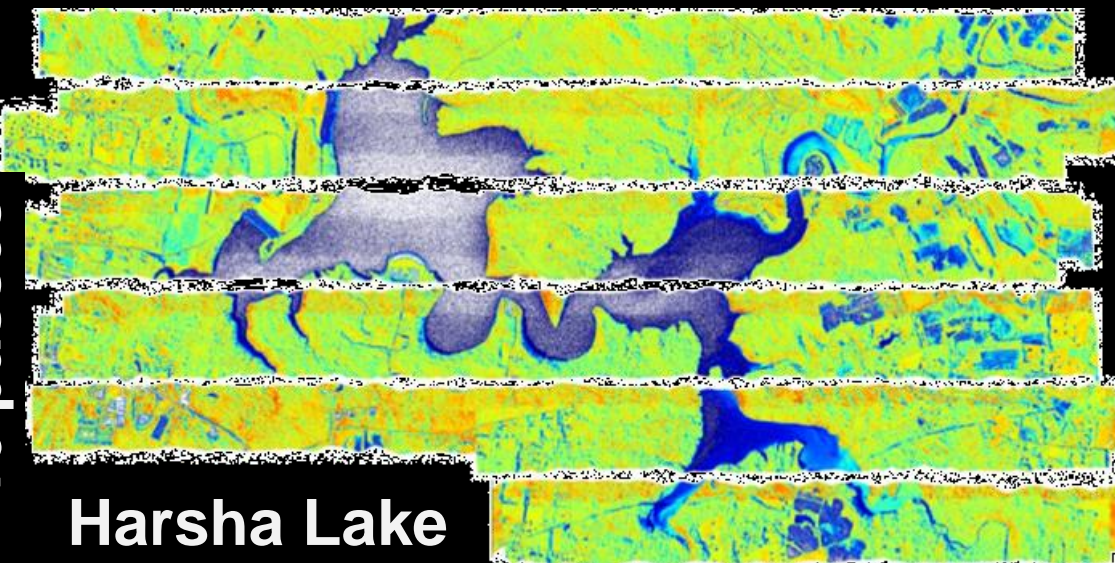


Installation on Viking S3

Legacy unit: flown since 2007 on several NASA aircraft

GRC HSI2.0	
Wavelength range	400-900 nm
Optical spectral resolution	2.5 nm
Spectral sampling resolution	1 nm
Optical throughput	f/2.0
Digitization bit depth	14 bit
Maximum spatial resolution along travel direction (imager rate limited)	1 m
Field of view (angle)	12.4° with 23 mm focal length lens
Field of view (swath width)	2102' @ 10k' altitude
Imaging rate	25 frames per sec
Camera pixels	658 x 496 (0.3 MP)
Camera interface	USB 2.0
System mass	3.7 kg
Volume	12 cm x 15 cm x 18 cm
Power consumption	35 W

16 passes



Harsha Lake

# HSI 2.1

Flown Twin Otter (2018)



Installation on Twin Otter  
with temp sensors

Upgrade: New hi-resolution Zyla  
camera with narrow field of view.

GRC HSI2.1	
Wavelength range	400-900 nm
Spectral sampling resolution	1 nm
Digitization bit depth	16 bit
Maximum spatial resolution along travel direction (imager rate limited)	1 m
Field of view	16.6° with 8mm focal length lens
Field of view (swath width)	2917' @ 10k' altitude
Imaging rate	30 frames per sec (adjustable)
Camera pixels	2560 x 2160 (960 cropped)
Camera interface	USB 3.0
System mass	≈3.8kg
Volume	9 cm x 9 cm 33 cm
Power consumption	30 W, 12VDC, 5 A inrush



High Resolution passes over Western Lake Erie,  
Sept 17, 2018



# HSI 3.0

Flown on Twin Otter  
and Viking S3 (2016)



Installation on Viking S3

Advantages: 6x the field of view,  
4x the camera pixels, twice the frame  
rate, more reliable GigE interface

GRC HSI3.0	
Wavelength range	350-1000 nm
Spectral sampling resolution	2 nm
Signal-to-noise ratio	250:1 at 600 nm @ white body 9500' no atmospheric correction
Digitization bit depth	14 bit
Maximum spatial resolution along travel direction (imager rate limited)	1 m
Field of view	72° with 8mm focal length lens
Field of view (swath width)	14531' @ 10k' altitude
Imaging rate	60 frames per sec
Camera pixels	1032 x 1032kg
Camera interface	Gig Ethernet
System mass	1.42 kg
Volume	8 cm x 9 cm 28 cm
Power consumption	6 W, 12VDC, 1.5 A inrush



2 passes

Harsha Lake

# HSI 3.1

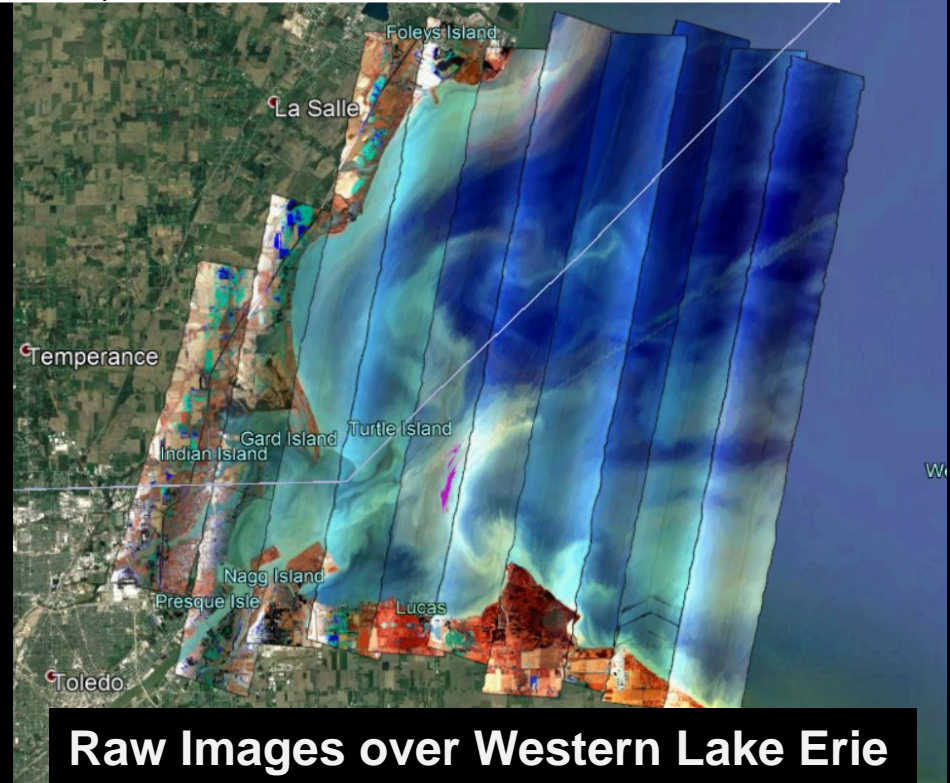
Flown on Twin Otter (2017)



Installation on Twin Otter  
with HSI2 and INS

Advantages: 6x the field of view,  
17x the camera pixels, and utilizes  
low noise thermoelectric cooler.

GRC HSI3.1	
Wavelength range	400-900 nm
Spectral sampling resolution	1 nm
Digitization bit depth	16 bit
Maximum spatial resolution along travel direction (imager rate limited)	1 m
Field of view	72° with 8mm focal length lens
Field of view (swath width)	14531' @ 10k' altitude
Imaging rate	30 frames per sec (adjustable)
Camera pixels	2560 x 2160 (5.5 MP)
Camera interface	USB 3.0
System mass	≈2.2kg
Volume	9 cm x 9 cm 33 cm
Power consumption	30 W, 12VDC, 5 A inrush



Raw Images over Western Lake Erie



# HSI 3.2

Flown on Twin Otter (2018, 2019)



Installation on Twin Otter with INS and temp sensors

Advantages: more consistent SNR, less vignetting

GRC HSI3.2	
Wavelength range	400-900 nm
Spectral sampling resolution	1 nm
Digitization bit depth	16 bit
Maximum spatial resolution along travel direction (imager rate limited)	1 m
Field of view	56° with 8mm focal length lens
Field of view (swath width)	10634' @ 10k' altitude
Imaging rate	30 frames per sec (adjustable)
Camera pixels	2560 x 2160 (960 cropped)
Camera interface	USB 3.0
System mass	≈2.2kg
Volume	9 cm x 9 cm 33 cm
Power consumption	30 W, 12VDC, 5 A inrush



# HSI 4

Flown on Altavian  
F6500 (2016)



HyDRUS 1 Payload (4  
lbs)

GRC HSI4	
Wavelength range	350-950 nm
Spectral sampling resolution	2 nm
Digitization bit depth	12 bit
Maximum spatial resolution along travel direction (imager rate limited)	sub meter
Field of view	55° with 8mm FL
Field of view (swath width)	425' @ 400' altitude
Imaging rate	30 frames per sec
Camera pixels	1288 x 964
Camera interface	USB 3.0
System mass	0.4 kg
Volume	4 cm x 11.6 cm x 16.5 cm
Power consumption	3 W max, 5V USB



Google Earth Map



Overlaid HSI Data



UAV Flight Path



Installation on  
Altavian F6500

Advantages: 5x the field of view, 4x the camera pixels, USB 3.0 speeds, compact and lightweight design, cost effective



# HSI 4

Flown on Altavian  
F7200 (2017 2018)



HyDRUS 2 Payload (4 lbs)

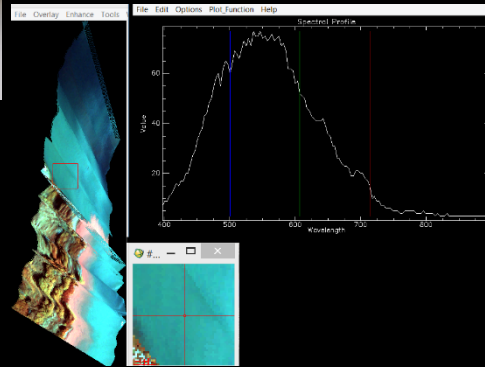


Installation on Altavian F7200

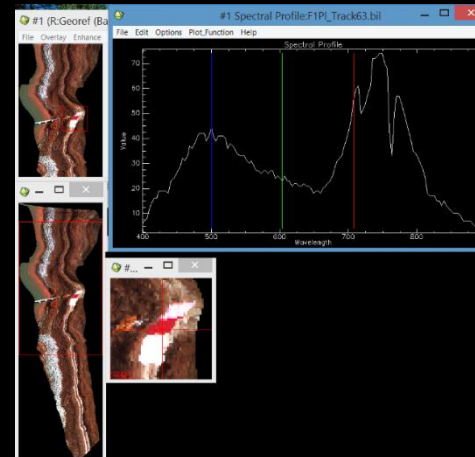
GRC HSI4	
Wavelength range	350-950 nm
Spectral sampling resolution	2 nm
Digitization bit depth	12 bit
Maximum spatial resolution along travel direction (imager rate limited)	sub meter
Field of view	55° with 8mm FL
Field of view (swath width)	425' @ 400' altitude
Imaging rate	30 frames per sec
Camera pixels	1288 x 964
Camera interface	USB 3.0
System mass	0.4 kg
Volume	4 cm x 11.6 cm x 16.5 cm
Power consumption	3 W max, 5V USB



Overlaid data



Water Measurement



Tarp Measurement

Advantages:  
5x the field of view, 4x the camera pixels, USB 3.0 speeds, compact and lightweight design, cost effective

# 2017 Flight Schedule and Issues

Flew HSI2.0 and new HSI3.1

HSI2.0 old Toughbook CF-74 laptop  
HSI3.1 new Toughbook CF-31 laptop

- Pre-flight: Upgraded HSI3.0 to HSI3.1 with new Zyla camera.

- Flight 1: June 21 first HSI3.1 flight Western Lake Erie
- Flight 2: July 5
- Flight 3: July 17
- Flight 4: July 25
- Flight 5: July 26
- Flight 6: Aug 23

- Flight 7: Aug 25 Harsha Lake

- Flight 8: Sept 11 Western Lake Erie
- Flight 9: Sept 25

- Flight 10: Oct 2 Harsha Lake

- Flight 11: Oct 3 Western Lake Erie
- Flight 12: Oct 18

- Post-flight: Upgraded HSI2.0 to HSI2.1 with new Zyla camera.



# 2018 Flight Schedule and Issues

Flew new HSI2.1 and new HSI3.2

HSI2.1 new rack servo comp  
HSI3.2 CF-31 laptop  
(original install was opposite)

- Pre-flight: HSI3.1 upgraded to HSI3.2 with new frame and lenses.

HSI3.2 camera failed. HSI2.1 camera transferred to HSI3.2

- |                     |                           |                   |
|---------------------|---------------------------|-------------------|
| • Flight 1: July 3  | no HSI2.1                 | Western Lake Erie |
| • Flight 2: July 9  | no HSI2.1                 |                   |
| • Flight 3: Aug 2   | no HSI2.1                 |                   |
| • Flight 4: Aug 14  | no HSI2.1                 |                   |
| • Flight 5: Aug 23  | HSI2.1 INS not working    | Harsha Lake       |
| • Flight 6: Aug 27  | HSI2.1 and HSI3.2 working | Western Lake Erie |
| • Flight 7: Sept 14 |                           |                   |
| • Flight 8: Sept 17 |                           |                   |
| • Flight 9: Sept 28 | note: HSI3 on laptop      |                   |
| • Flight 10: Oct 1  |                           |                   |
| • Flight 11: Oct 12 |                           | Harsha Lake       |

# 2019 Flight Schedule and Issues

Flew HSI3.2 and new HSI Cubesat

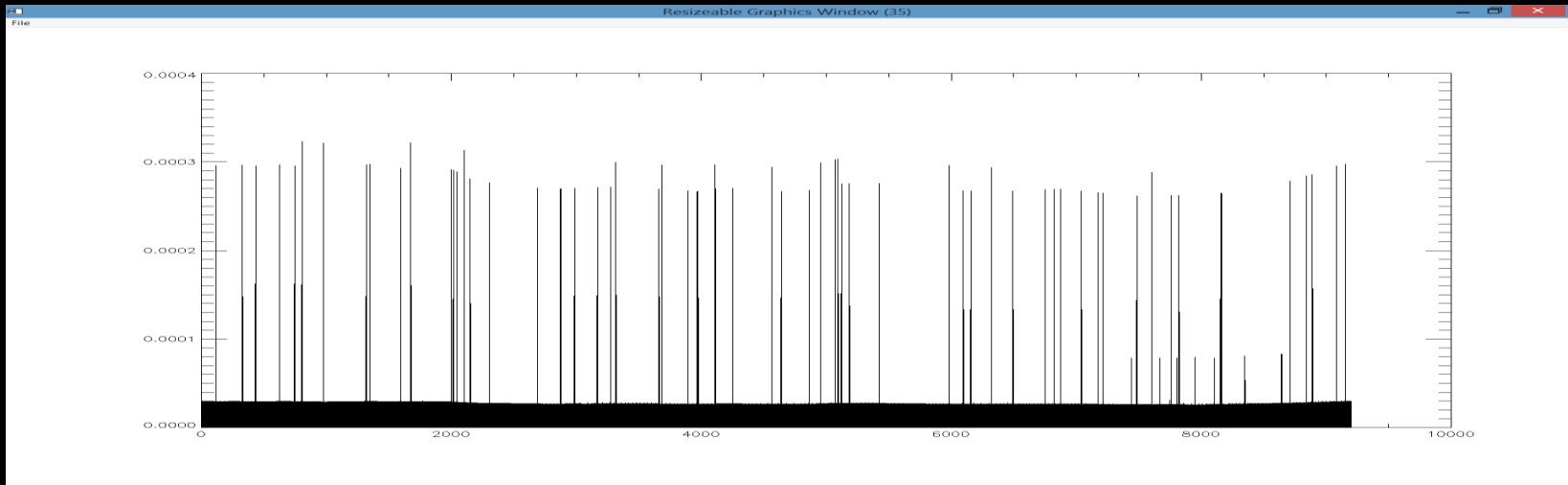
HSI3.2: new rack servo comp swapped to CF-31 laptop

- Flight 1: Aug 9 HSI3.2 noticed image freezing issue Western Lake Erie
- Flight 2: Aug 16 HSI3.2 Freezing issue
- Flight 3: Aug 21 HSI3.2 rack computer swapped with laptop before flight. Freezing images reduced.
- Flight 4: Aug 23 Radiometer started late in flight
- Flight 5: Aug 28
- Flight 6: Aug 30
- Flight 7: Sept 6 Harsha Lake
- Flight 8: Sept 26 Video Documentary Western Lake Erie
- Flight 9: Sept 27 Harsha Lake



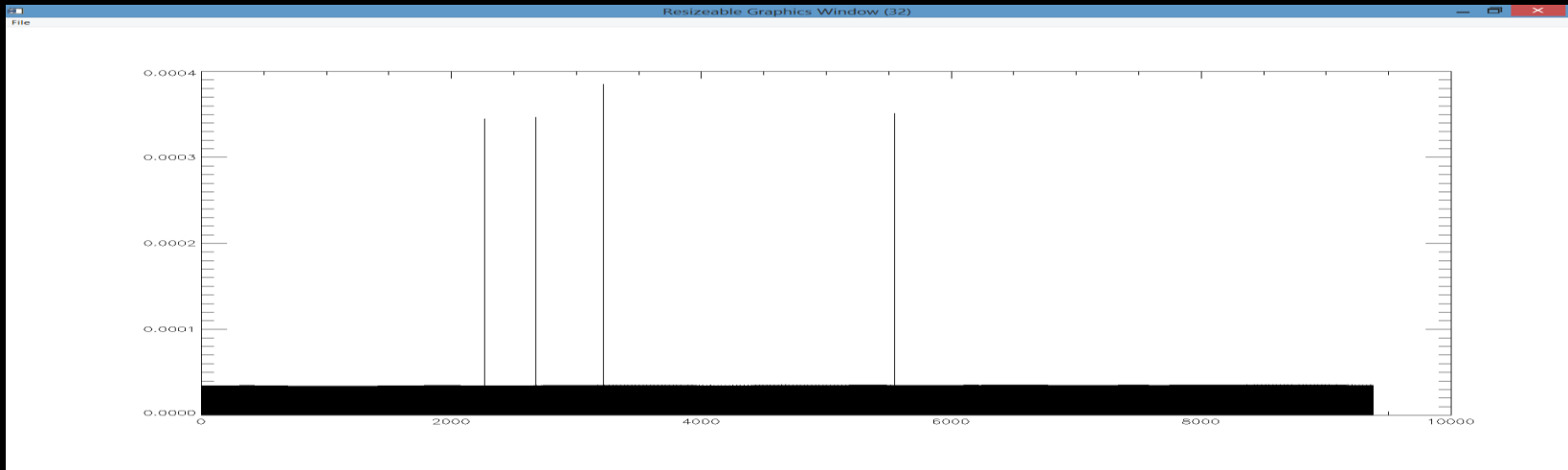
# Longitude noise comparison when rack computer swapped for laptop

Flight 2



TO\_20190816\_HSI3p2\Proc\SAV\_BIN\11\_LE00toLE48\_9500\_NW.sav

Flight 3



TO\_20190821\_HSI3p2\Proc\SAV\_BIN\11\_MOW12toMOW15\_10000\_S.sav



**Thank You**

**Roger Tokars**  
Optical Systems Research Engineer  
NASA Glenn Research Center  
21000 Brookpark Rd.  
Cleveland, Ohio 44135  
Phone: (216) 433-8771  
[Roger.P.Tokars@nasa.gov](mailto:Roger.P.Tokars@nasa.gov)