

Considerations of Oblique Impacts of Non-Spherical, Graphite-Epoxy Projectiles

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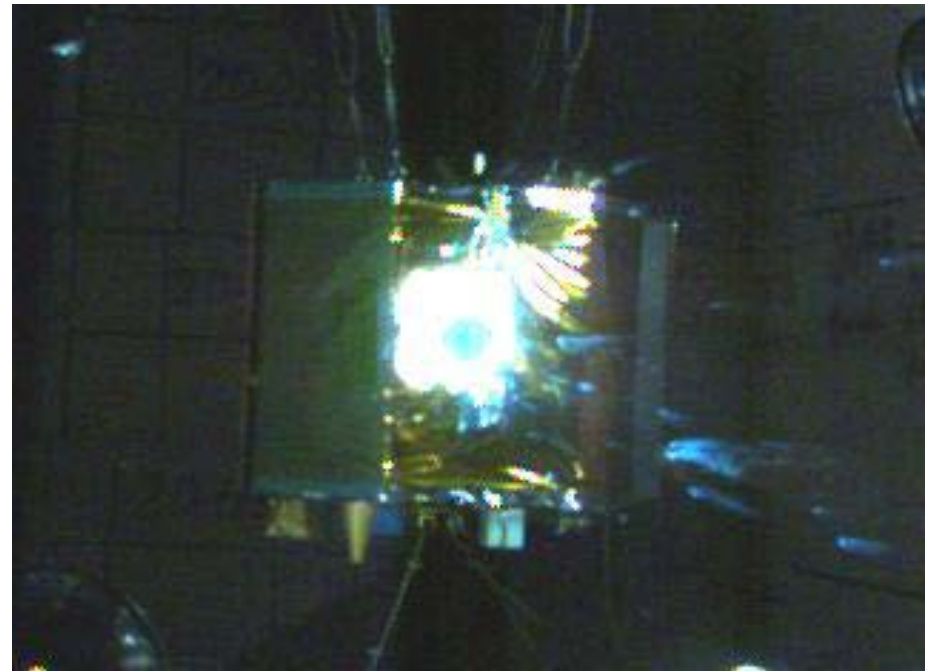
^bJacobs, NASA Johnson Space Center, Houston, TX 77058

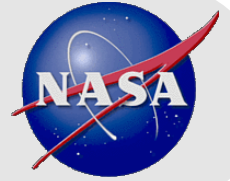
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Acknowledgements

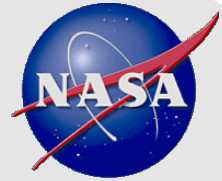
- Hypervelocity Impact Tech. Group (HVIT)
 - Dr. Eric Christiansen
 - Dana Lear
- Jacobs JSC Engineering and Technical Support Team
 - Robert McCandless
 - Tyson Judd
 - Bruce Alan Davis
- Remote Hypervelocity Test Laboratory (RHTL)
 - Daniel Wentzel
- Jacobs RHTL Engineering and Technical Support Team
 - Marcus Sandy
 - Donald Henderson
 - Daniel Rodriguez
 - Arturo Pardo





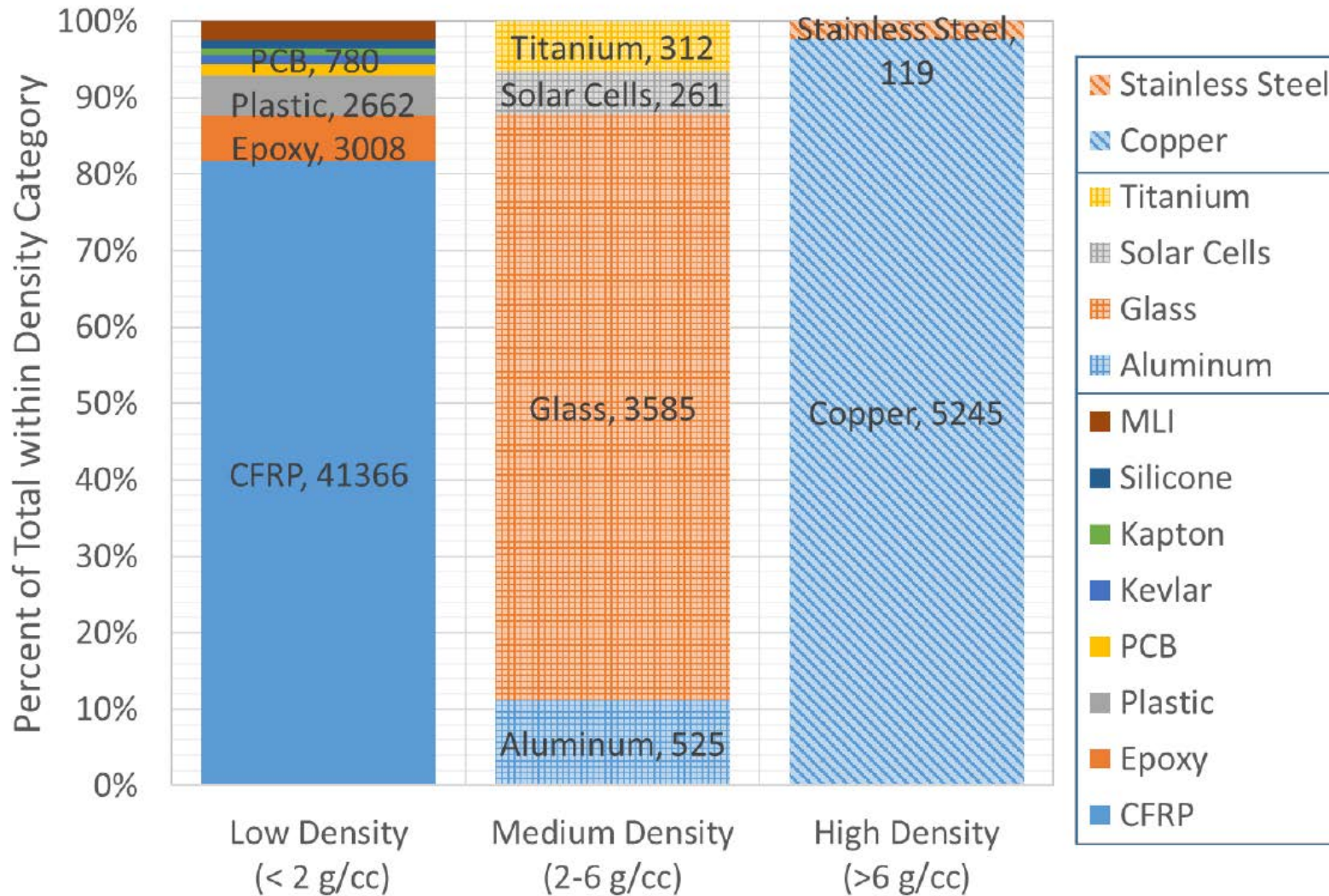
Orbital debris fragment shape study

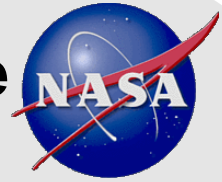
- **The DebrisSat experiment has greatly expanded NASA's understanding of large-scale, modern-construction, catastrophic satellite breakups**
 - Using modern materials DebrisSat has pointed to a significant presence of carbon-fiber composite material in the sub-cm range.
 - Much of the carbon-fiber composite material had shapes that differed significantly from equidimensional shapes like spheres and cubes.
- **Impact experiments have generated validation data for numerical simulation models for an aluminum Whipple shield representative of shields in human space flight.**
 - Multiple Length to Diameter ($L : D$) ratios have been considered
 - Numerical simulation models have been developed that compare well against the obtained experimental data.
- **The numerical simulation models have been used to extrapolate away from the original data to develop impact models for shaped, carbon-fiber composites that includes impact obliquity for reliability assessments**



CFRP is a major debris component of a modern satellite break-up

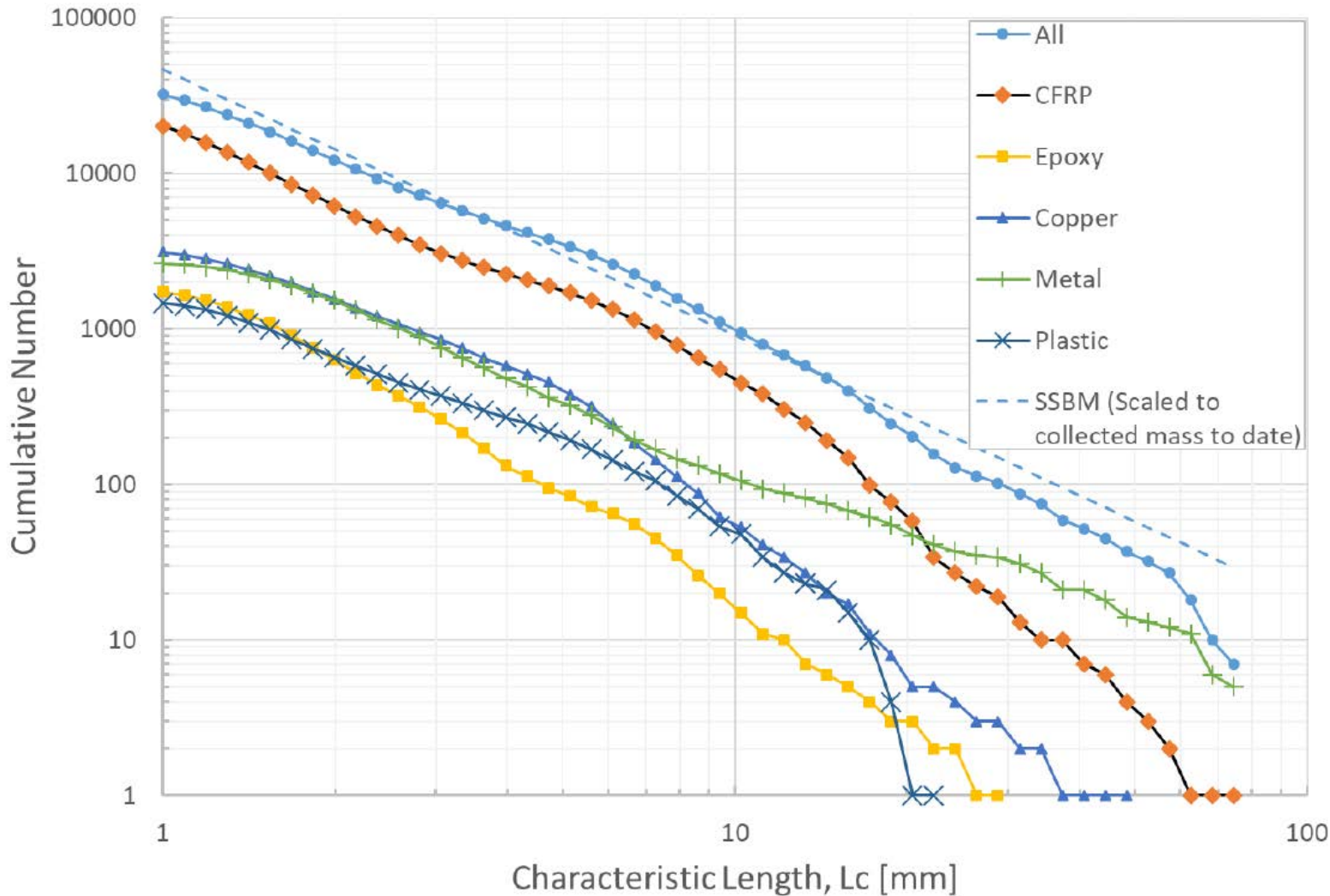
Density Category Breakdown

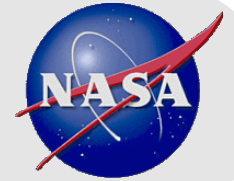




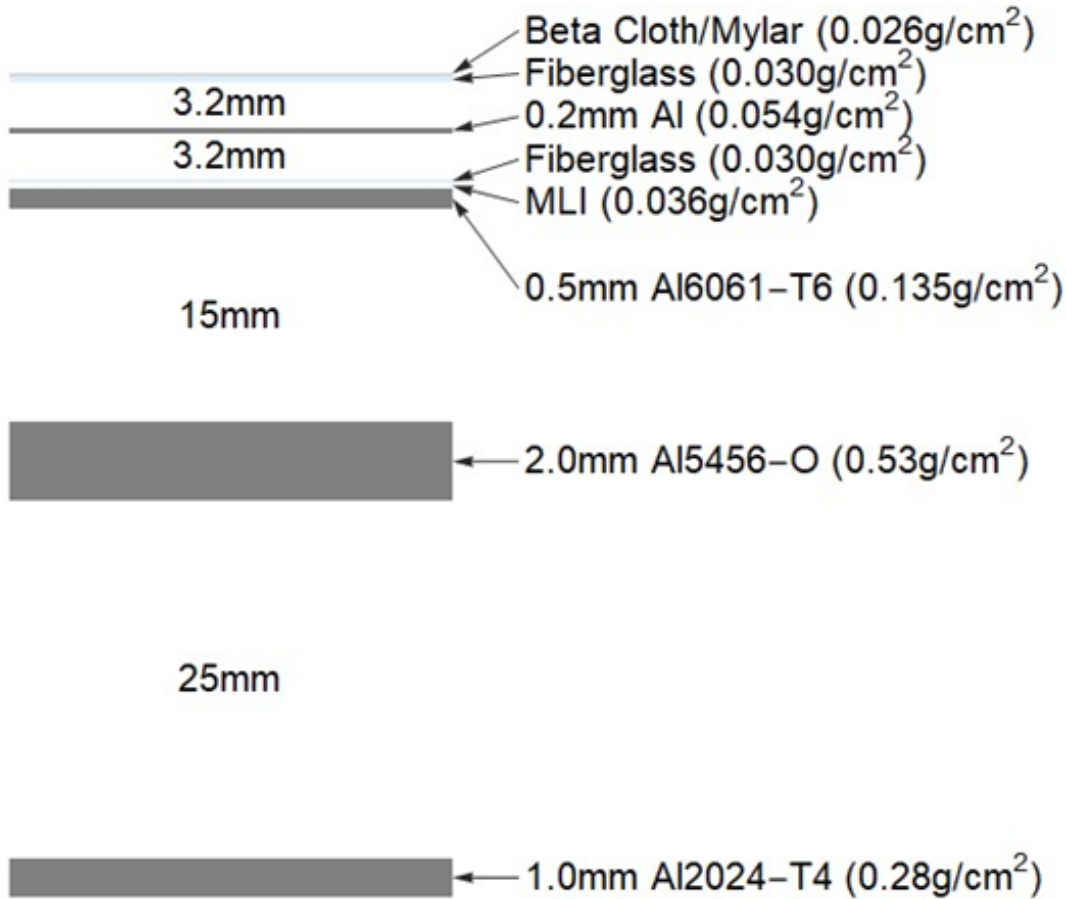
CFRP is the principal component of untrackable debris from a modern satellite break-up

Cumulative Number V. Characteristic Length by Primary Material





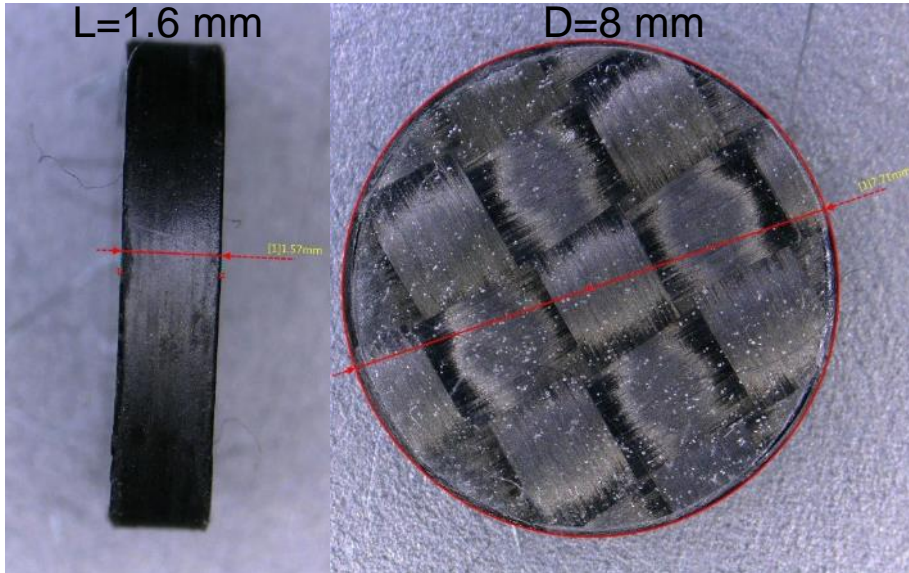
Impact experiments used a realistic Whipple shield with an external, thermal-blanket



Schematic for experimental layup (layers scaled by mass; separations to scale), which represents a previously considered shield. [Lyons2013, Davis2013]

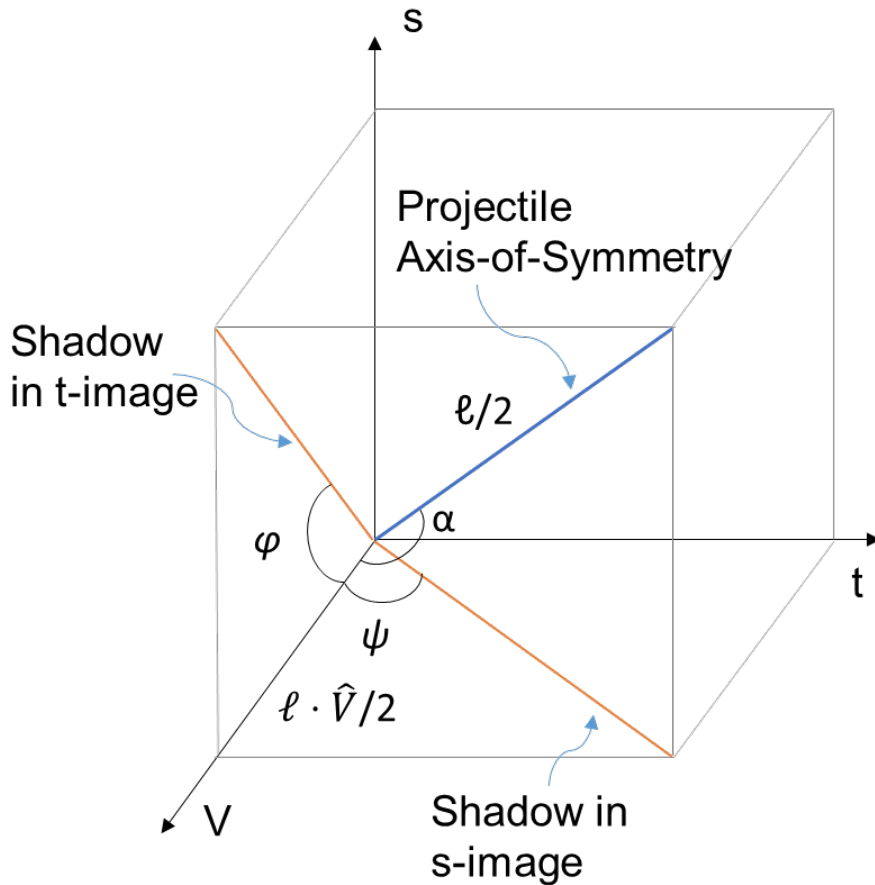


A total of eleven experiments have been considered with varying L : D aspect ratios

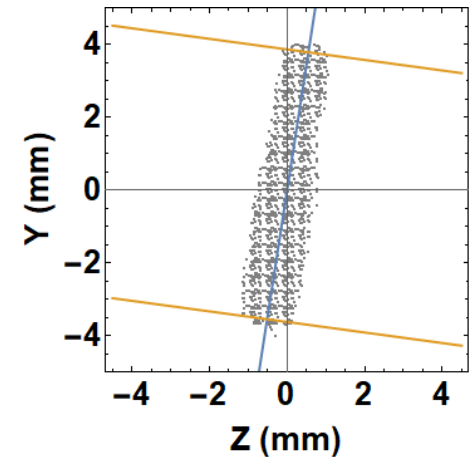
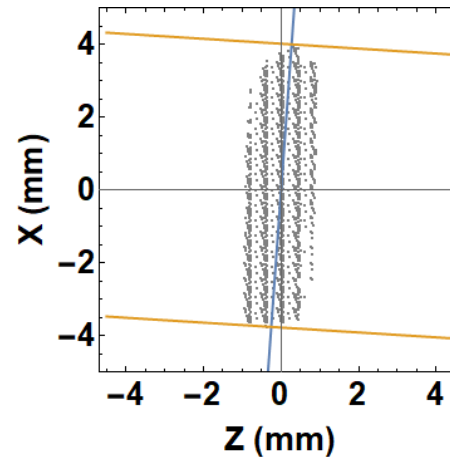
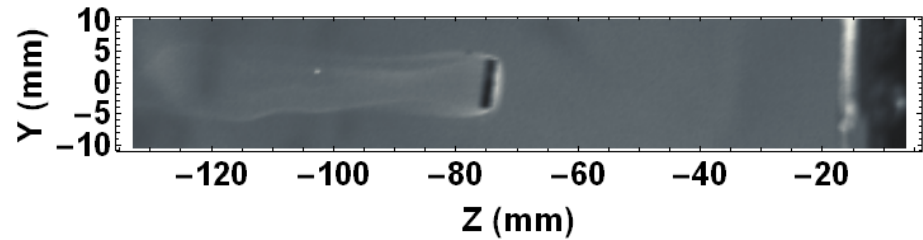
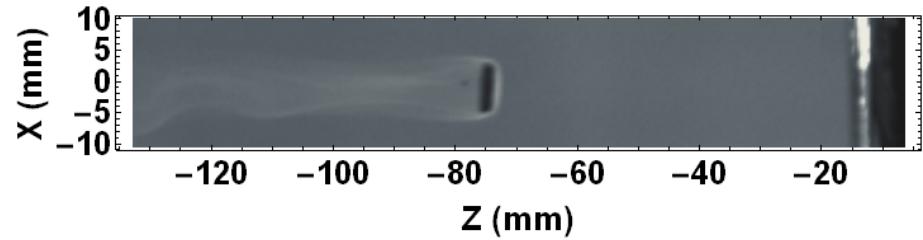


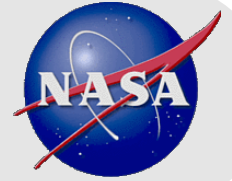


Orthogonal videocameras have been used to determine the projectiles orientation at impact



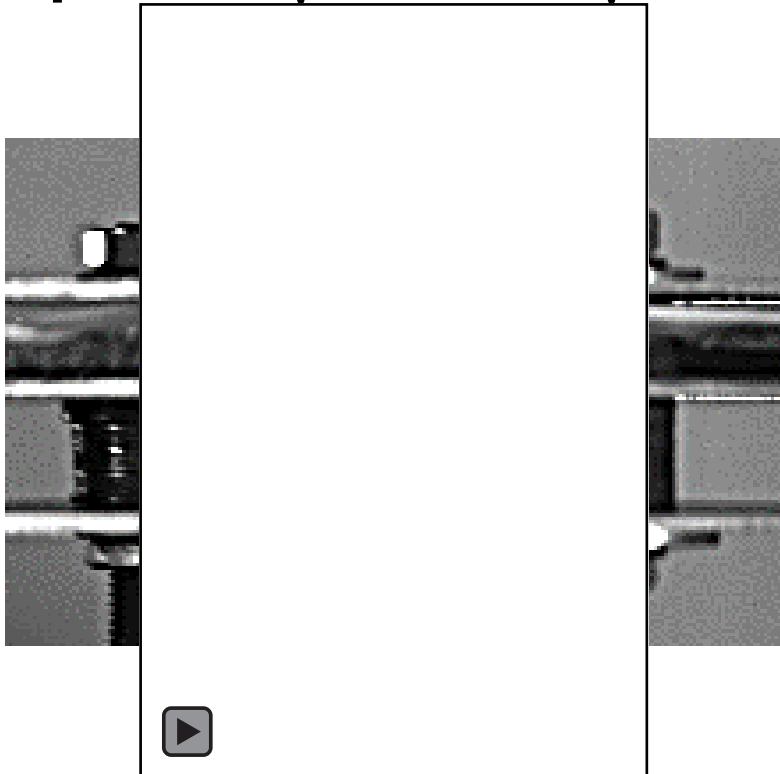
$$\alpha[\phi, \psi] = \text{ArcCos} \left[\sqrt{\frac{1}{1 + \text{Tan}[\phi]^2 + \text{Tan}[\psi]^2}} \right]$$





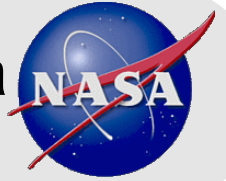
The experimental data is collected to assist in validation of numerical simulations

Impact: -2 μs to 28.5 μs



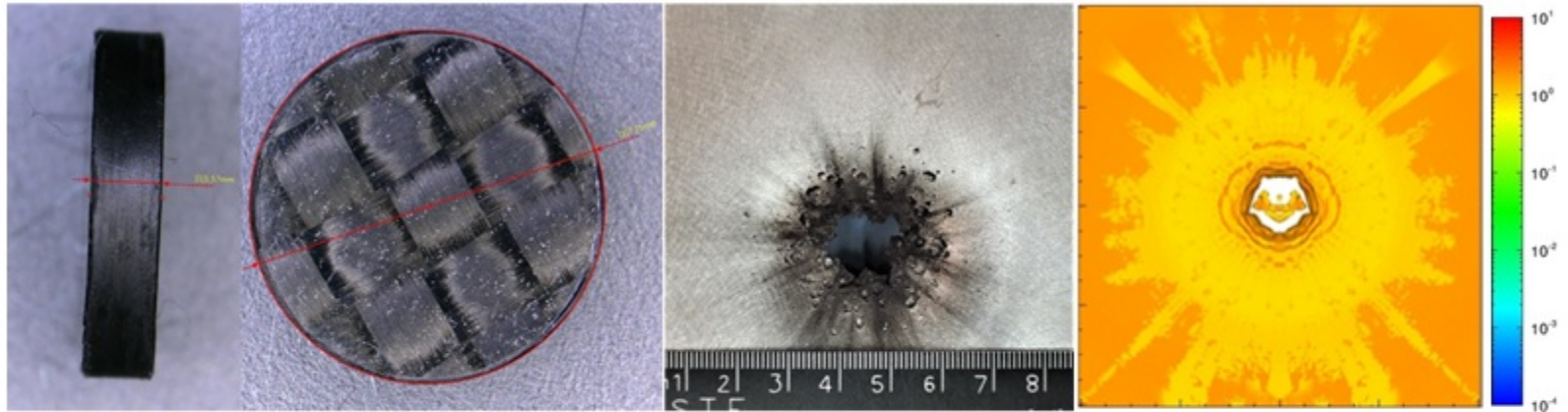
Simulation: 0 μs to 30 μs



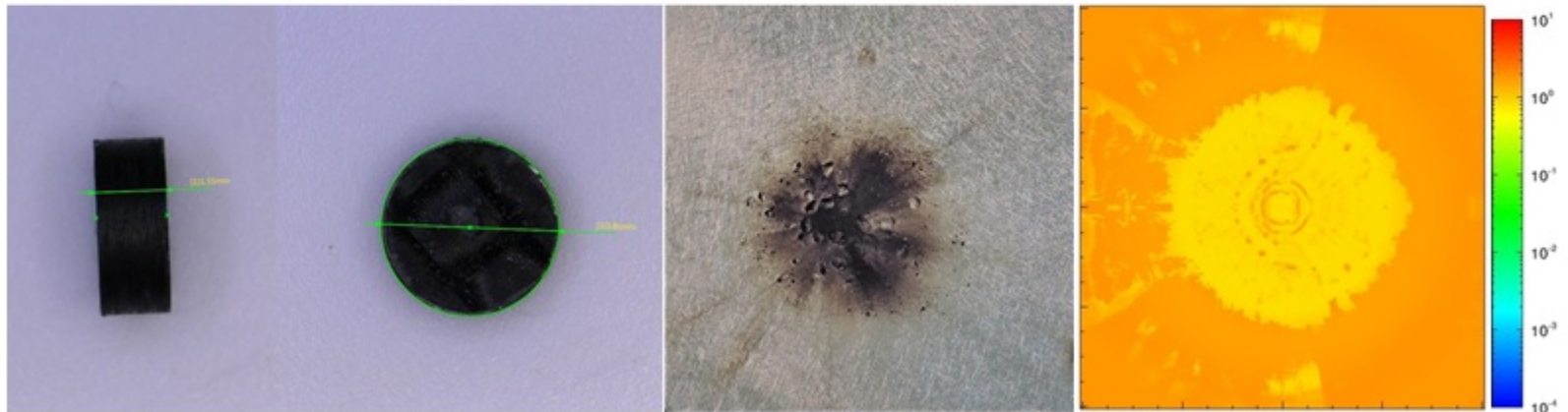


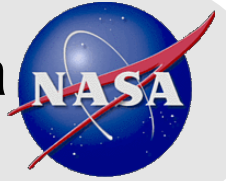
Comparisons of experimental to simulation data for $L : D < 1$ (~flat disk)

$L : D = 1.6 \text{ mm} : 8.0 \text{ mm}$



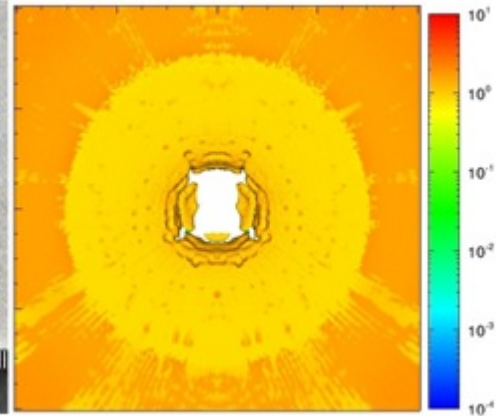
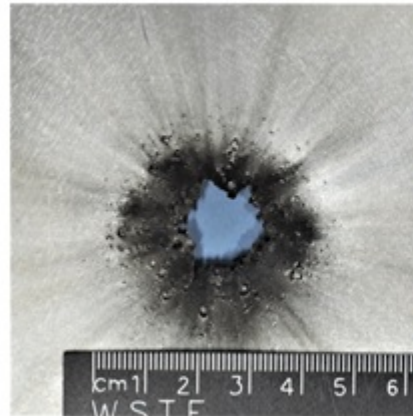
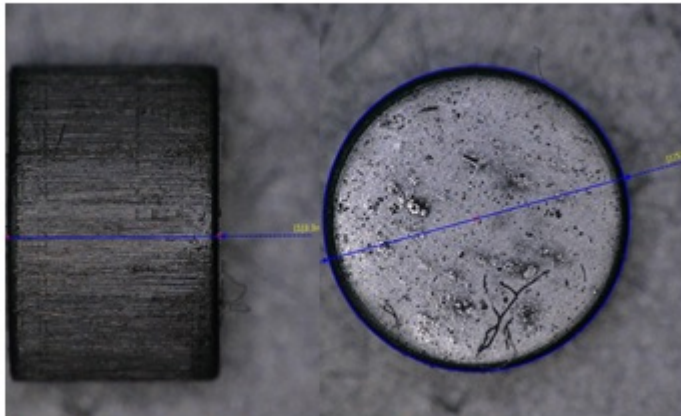
$L : D = 1.6 \text{ mm} : 4.0 \text{ mm}$



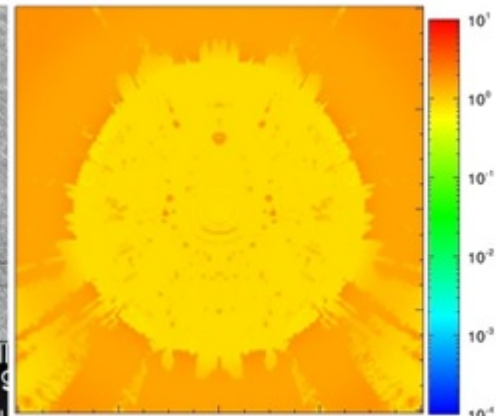
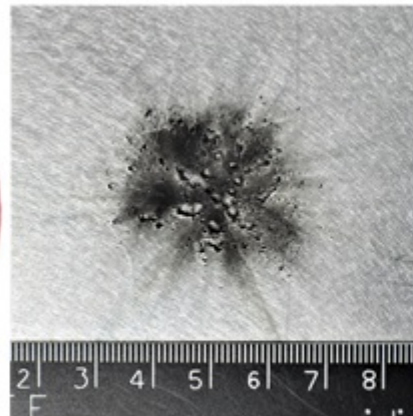
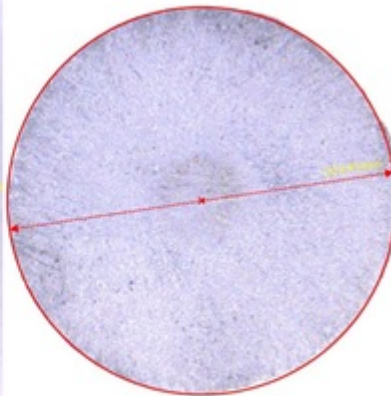
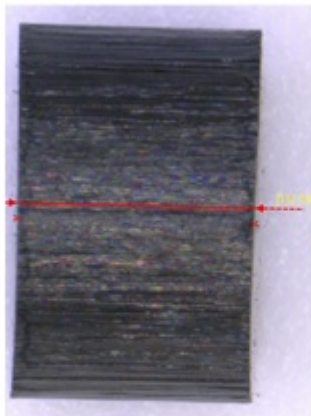


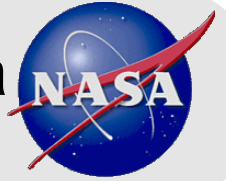
Comparisons of experimental to simulation data for $L : D = 2/3$ (mass equivalent to sphere)

$L : D = 3.33 \text{ mm} : 5.0 \text{ mm}$



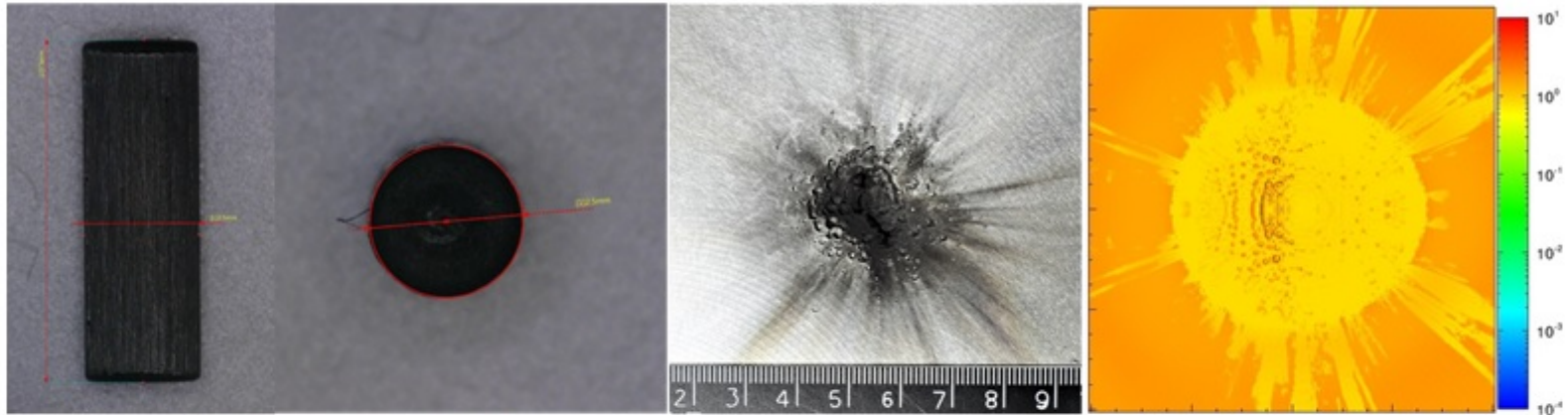
$L : D = 2.3 \text{ mm} : 3.45 \text{ mm}$



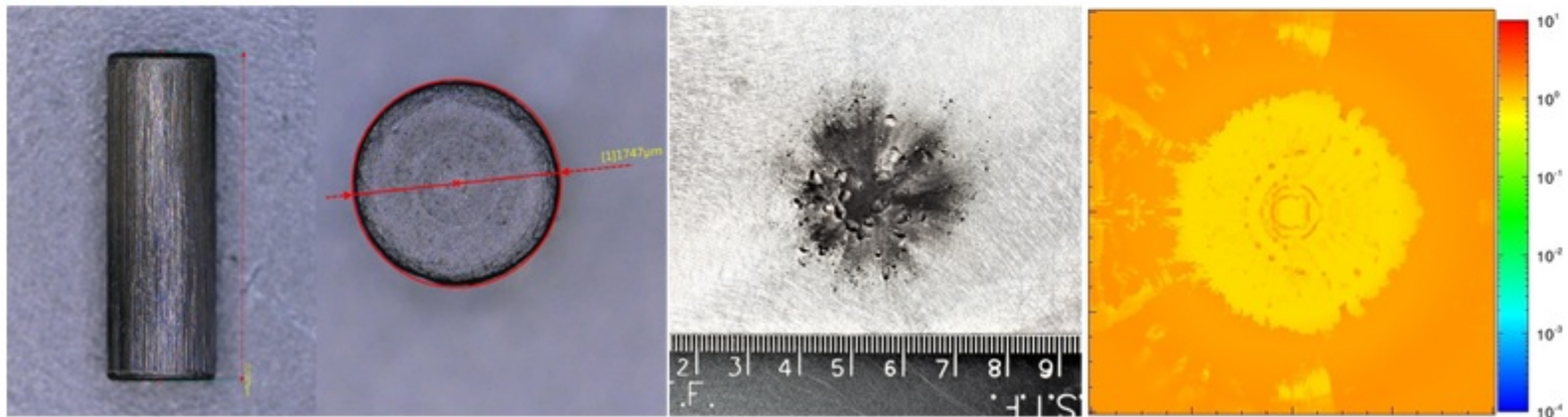


Comparisons of experimental to simulation data for $L : D > 1$ (~long rod)

$L : D = 7.5 \text{ mm} : 2.5 \text{ mm}$

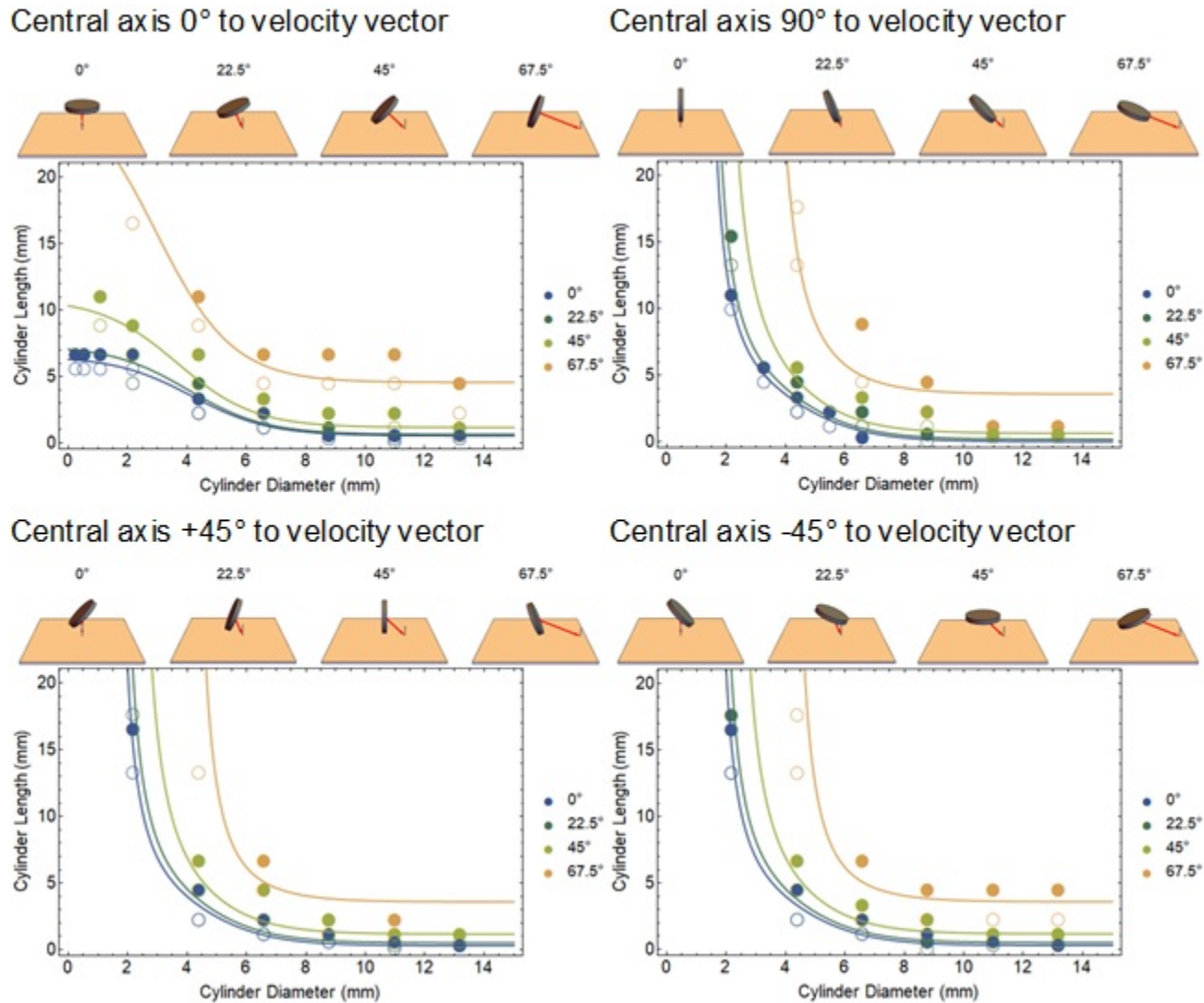


$L : D = 5.25 \text{ mm} : 1.75 \text{ mm}$





The critical length model for cylinders* has been adapted for unyawed, oblique impacts

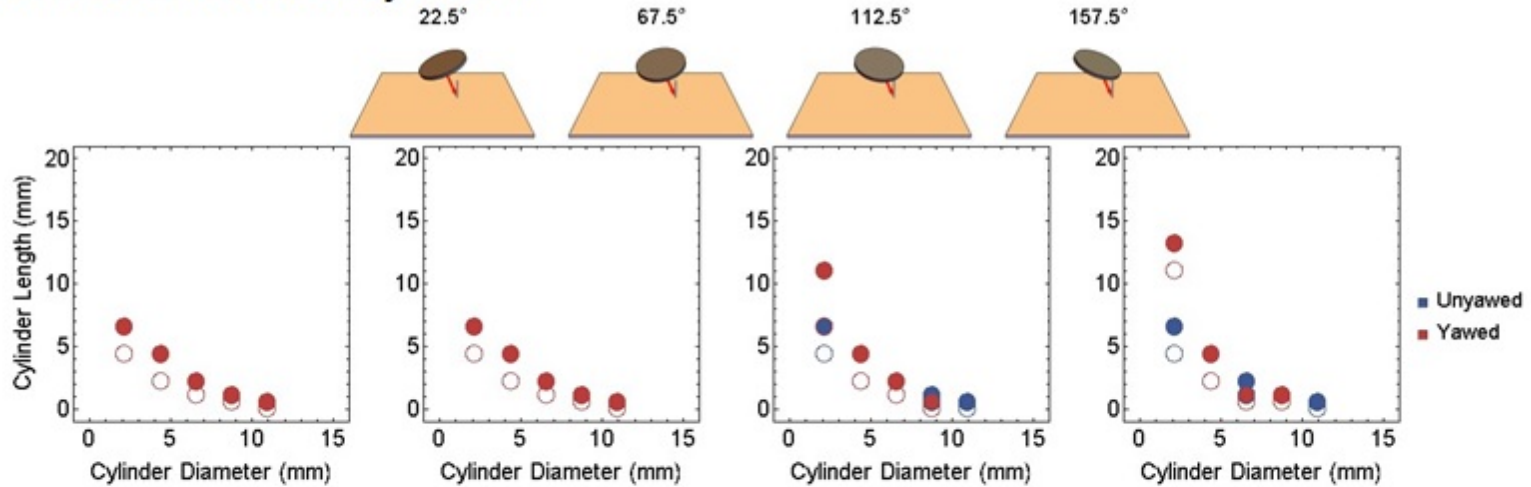


*Miller, J.E., Proceedings of the 2019 Hypervelocity Impact Society, Destin, FL, HVIS2019-044 (2019)

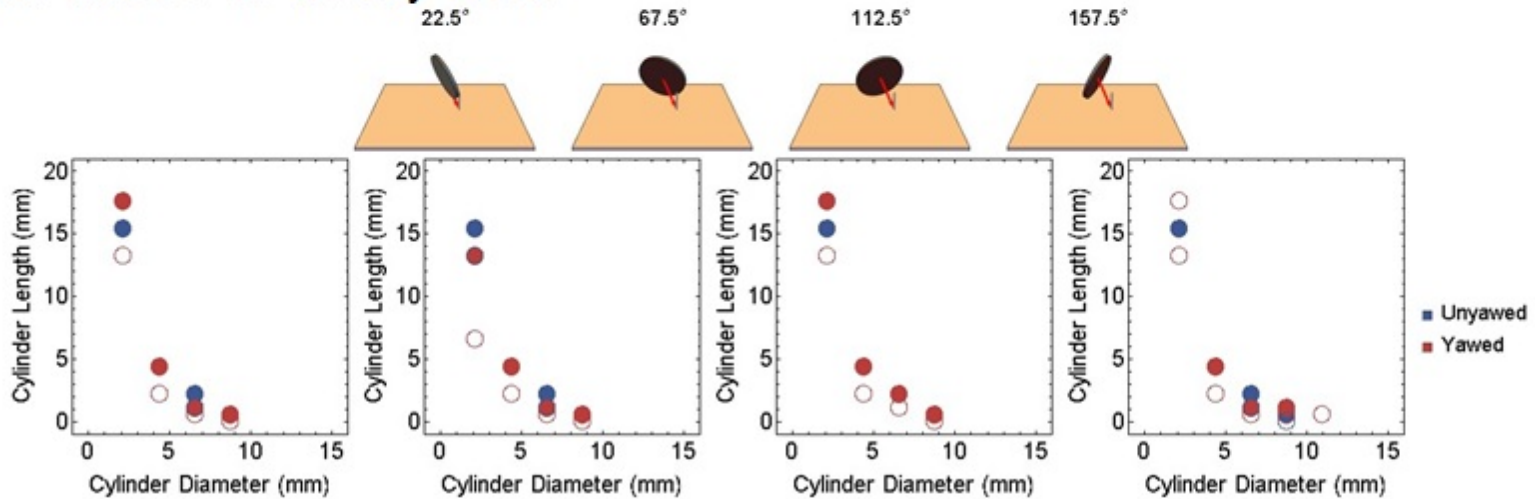


Simulations have been used to compare the yawed to unyawed for 22.5° oblique impacts

Central axis 0° to velocity vector



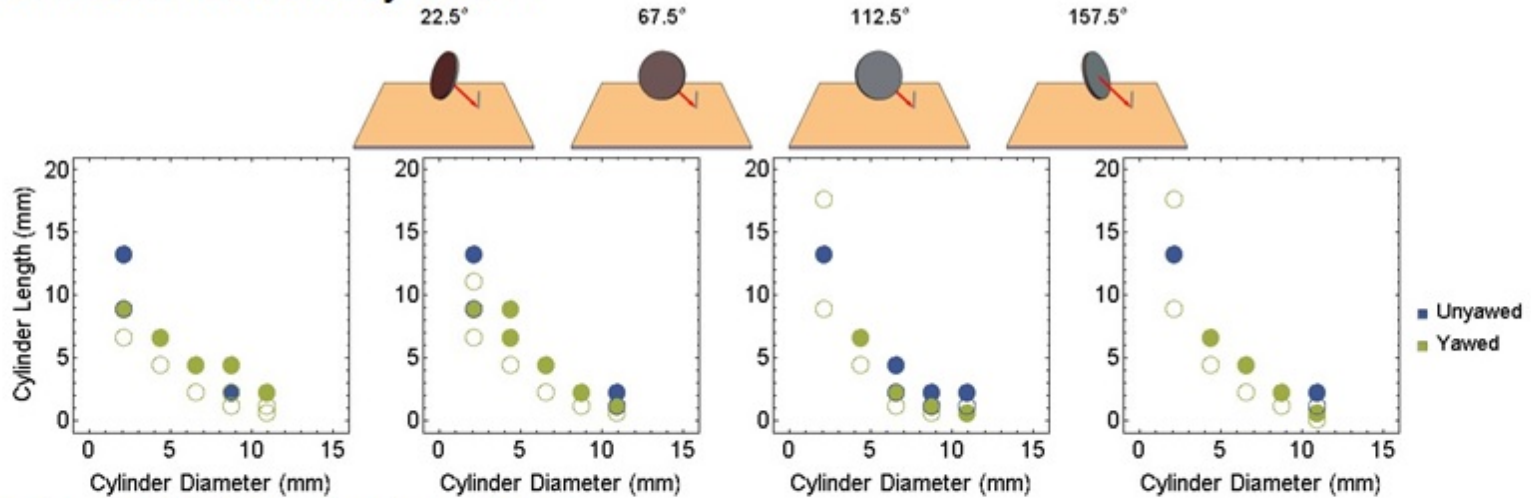
Central axis 90° to velocity vector



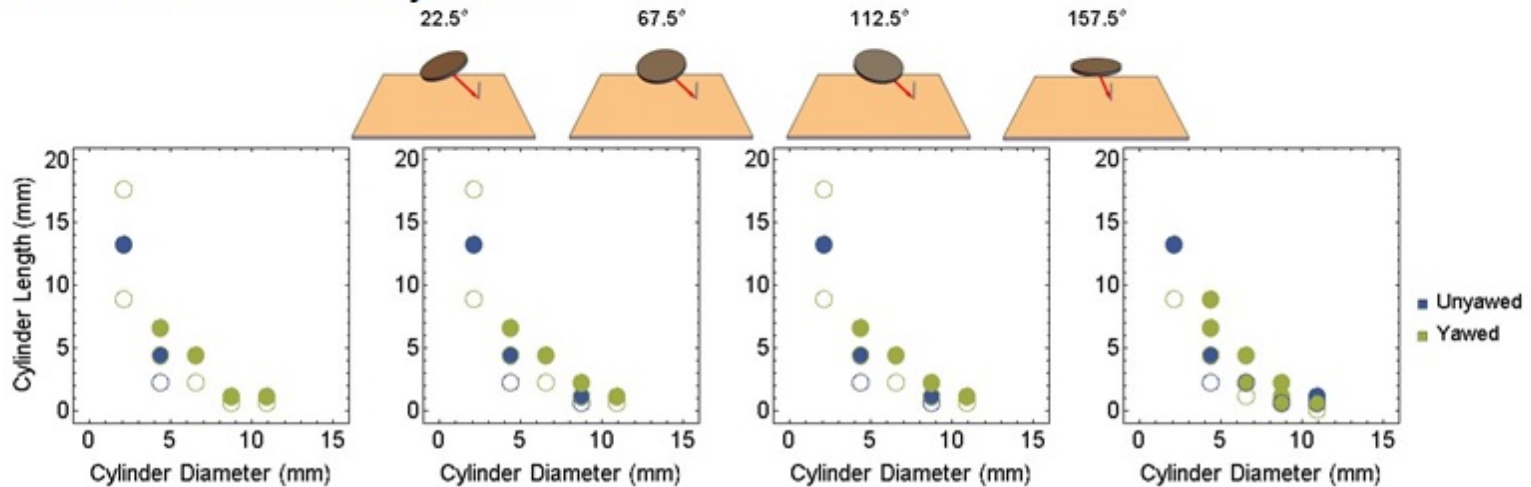


Simulations have been used to compare the yawed to unyawed for 45° oblique impacts

Central axis 0° to velocity vector



Central axis 90° to velocity vector

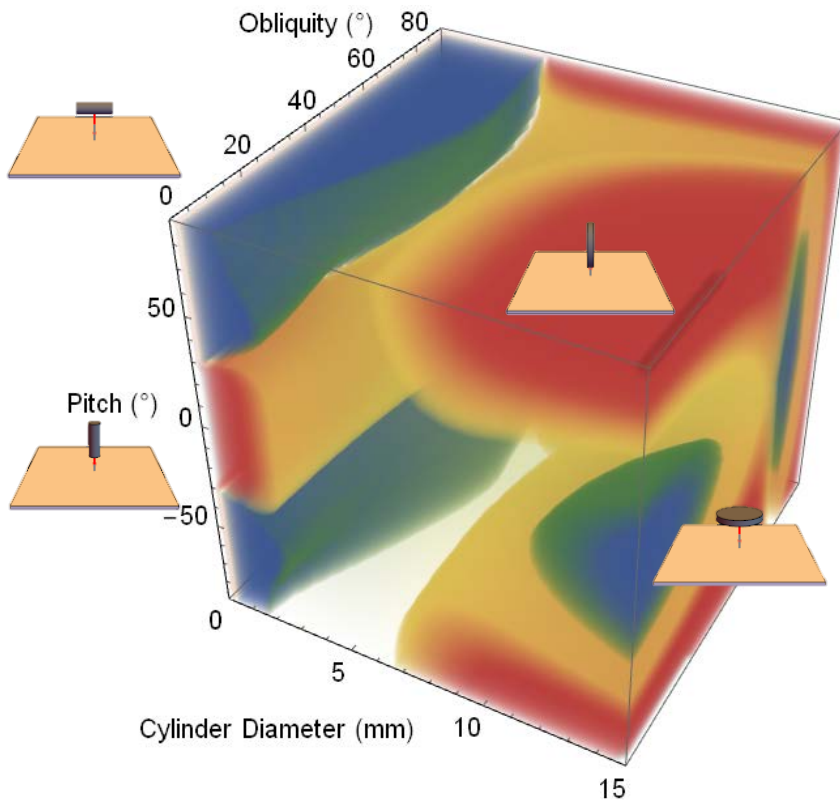




The critical cylinder length dependence can be used for other quantities of interest

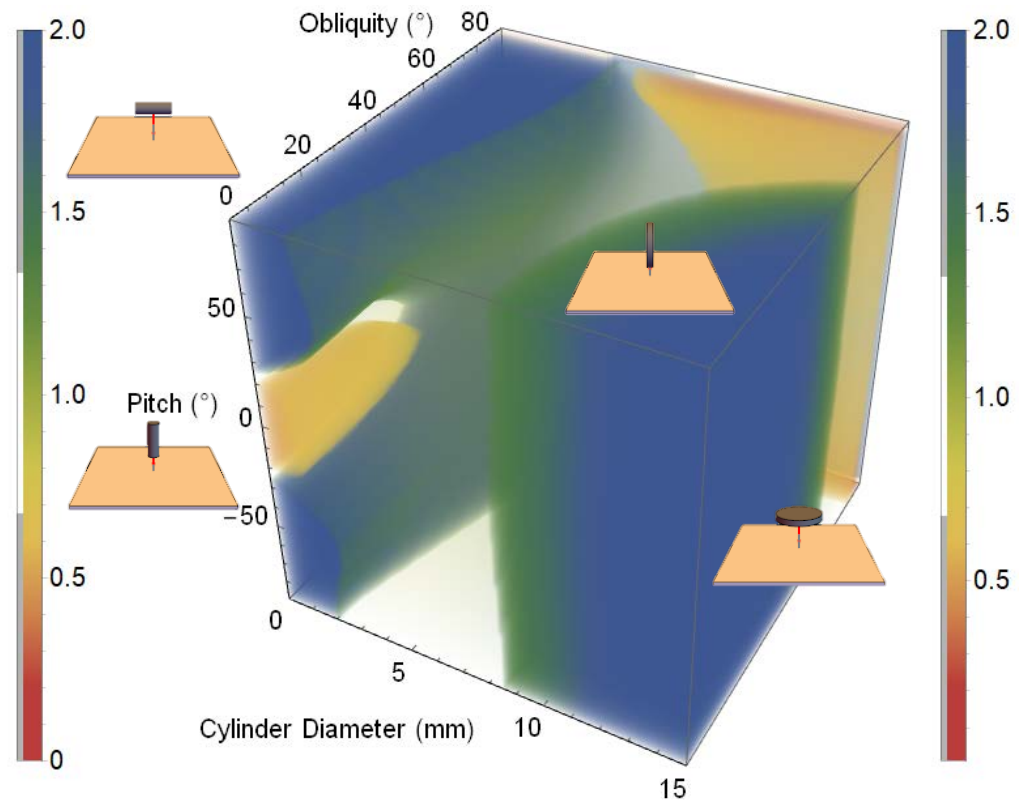
Critical cylinder to sphere mass

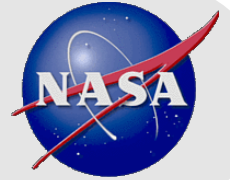
$$\frac{m_C}{m_S} = \frac{3}{2} \frac{D_C^2 L_C}{D_S^3}$$



Critical cylinder to sphere average length

$$\frac{RCS_C}{RCS_S} = \frac{2D_C + L_C}{3D_S}$$





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