Partially-Dressed Cavity-Closed Nose Landing Gear (PDCC-NLG) Problem Experiment Description and Results



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# This talk describes the nose landing gear experiments in BART

#### Background





#### Experiments







### The experimental model was derived from a highfidelity model of the Gulfstream G550 aircraft NLG



Baseline open geometry configuration for benchmarking aeroacoustic simulations

- High-Fidelity, 25% Scale
- Cavity, Lower Fuselage Section
- 16 Dynamic Pressure Transducers (1 Roving/Mobile)
- 120+ Static Pressure Ports
- PDCC => remove.....
  - Hydraulic Lines
  - Steering Mechanism
  - Light Cluster
  - Seal Gear Cavity
  - ➤ All Above ⇒ Partially dressed model (simplified gear)

### The model component details



## Removal of select components produces the PDCC-NLG configuration



### The Basic Aerodynamics Research Tunnel (BART) is where the NLG was tested



#### **BART Specifications**

Test section: 0.711m x 1.016m x 3.028m

#### **Test Conditions**

Velocity: 56.6 m/s Re/m:  $3.832 \times 10^{6}$  (Re<sub>D</sub> = 73,000) Mach No: 0.166 Turbulence Intensity: 0.077%  $\delta = 0.61$ " (1.55 cm),  $\delta^* = 0.086$ " (0.22 cm)

## The experimental data in the problem statement consists of steady and unsteady surface pressure and PIV

Steady surface pressures -

Port wheel – two radial rows

Door – five spanwise rows

Starboard wheel – one circumferential row

Fuselage – one streamwise and two spanwise rows

#### Fluctuating surface pressures -

P<sub>rms</sub> and PSD – all ten fixed sensors (mobile sensor at various gear locations can be made available) p' time history two on door one on port wheel one on torque arm

Planar PIV data – multiple planes around the model

#### The estimated experimental uncertainties are.....

- Steady Cp ~ 0.02
- PIV<sup>\*</sup>: Umean, Vmean ~ 1.4 m/s (2.5 % of  $U_{inf}$ )
- PIV: Vorticity ~ 729/s
- PIV: TKE ~ 4%
- PSD ~ 10-14%
- Cp'<sub>rms</sub> ~ 5-7%

\* the uncertainty in PIV quantities is based on the system velocity resolution, which relates to the minimum displacement (velocity) the system can measure.

## The steady Cp on the starboard wheel was invariant with rotation angle (M=0.166)



Steady pressure orifices spaced 20 deg



## The steady Cp on the door showed mild variation spanwise



### The removal of gear components shows the increase in coefficient of RMS Unsteady Pressure





### The effect of component removal on PSD is significant for areas of the model in the vicinity of the removed parts

Upper sensor on door

Lower sensor on door





#### Upper sensor on drag brace Sensor on back wall of wheel hub

FDCO

- PDCC

10<sup>4</sup>

### The PIV laser light sheets are shown relative to the model



#### The details of the 2-D PIV system are.....

- Lightsheet thickness 2 mm
- Dual, 220 mJ, Nd-YAG lasers
- Digital camera frame rate 5 Hz
- Sensor size 1360X1036 pixels
- Measurement volume
  - 1.3 mm<sup>2</sup> (50 mm lens, 24X24 interrogation window) (0.0175D)
- 50% interrogation window overlap
- Flow seeded by commercial fog generator
- 1000 image pairs per configuration

### The TKE in plane 2 (behind door) shows the concentration of energy in the shear layers trailing downstream



## Plane 2 (behind door) shows the flow of out-of-plane vorticity around edges trailing downstream



### The instantaneous vorticity and PSD give no evidence of persistent, coherent structure shed downstream of door



#### **PSD on Starboard Door Edge**



## The TKE in X-Y PIV plane (Mid-wheel, Starboard Side) shows concentration of energy in aft wheel hub area



#### Final Comments – 1 of 2

- Surface pressure spectra were found to be primarily broadband in character and devoid of any local peaks associated with Strouhal shedding
- Removal of select components resulted in stronger pressure fluctuations in certain surface locations
- PIV revealed no large-scale vortical structures shed from gear components corroborating unsteady pressure measurements
- The highest levels of TKE and Cp'<sub>rms</sub> for the PDCC were measured in the area of the wheel hub, torque arm, door, and the drag brace





### **Final Comments - concluded**

- simplified geometry, complicated physics
- ease/difficulty of performing the tests
  - Instrumentation in-situ calibration
  - Model changes
    - Clocking wheels
    - > Removing components
    - Moving mobile transducer
  - Data acquisition and processing
- what (if anything) would make the dataset better
  - Comments solicited during open discussion

### **Background material**

### The details of the data acquisition are.....

- Signal gain incorporated into sensitivity coefficients through in-situ calibration
- AC-coupled data
- Sample rate: 51.2 kHz
- Blocksize: 16384
- Number of blocks acquired: 100
- Anti-alias filter in front of A/D: 20 kHz, elliptic
- AC coupling frequency: 1 Hz
- Range: set as needed for each channel
- DC-coupled data
- Sample rate: 50 Hz
- Number of samples acquired: 1600
- DC coupling frequency: 1 Hz

#### References

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