

TESS Data Release Notes: Sector 23, DR32

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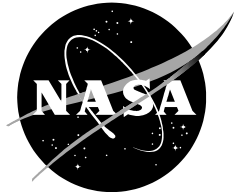
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Acknowledgements

These Data Release Notes provide information on the processing and export of data from the Transiting Exoplanet Survey Satellite (TESS). The data products included in this data release are full frame images (FFIs), target pixel files, light curve files, collateral pixel files, cotrending basis vectors (CBVs), and Data Validation (DV) reports, time series, and associated xml files.

These data products were generated by the TESS Science Processing Operations Center (SPOC, [Jenkins et al., 2016](#)) at NASA Ames Research Center from data collected by the TESS instrument, which is managed by the TESS Payload Operations Center (POC) at Massachusetts Institute of Technology (MIT). The format and content of these data products are documented in the [Science Data Products Description Document \(SDPDD\)](#)¹. The SPOC science algorithms are based heavily on those of the Kepler Mission science pipeline, and are described in the Kepler Data Processing Handbook ([Jenkins, 2019](#)).² The Data Validation algorithms are documented in [Twicken et al. \(2018\)](#) and [Li et al. \(2019\)](#). The [TESS Instrument Handbook](#) ([Vanderspek et al., 2018](#)) contains more information about the TESS instrument design, detector layout, data properties, and mission operations.

The TESS Mission is funded by NASA's Science Mission Directorate.

This report is available in electronic form at
<https://archive.stsci.edu/tess/>

¹<https://archive.stsci.edu/missions/tess/doc/EXP-TESS-ARC-ICD-TM-0014.pdf>

²<https://archive.stsci.edu/kepler/manuals/KSCI-19081-003-KDPH.pdf>

1 Observations

TESS Sector 23 observations include physical orbits 53 and 54 of the spacecraft around the Earth. Data collection was paused for 0.96 days between the orbits to download data. In total, there are 25.81 days of science data collected in Sector 23. The spacecraft passed through the shadow of Earth from approximately TJD 1940.38 – 1940.48. The instrument was not turned off, and other than the instrument heaters turning on resulting in a minor pointing offset, there is no indication that science quality was affected.

Table 1: Sector 23 Observation times

	UTC	TJD ^a	Cadence #
Orbit 53 start	2020-03-19 14:21:20	1928.09965	504464
Orbit 53 end	2020-04-01 08:51:20	1940.87047	513659
Orbit 54 start	2020-04-02 07:55:20	1941.83159	514351
Orbit 54 end	2020-04-15 08:57:19	1954.87464	523742

^a TJD = TESS JD = JD - 2,457,000.0

The spacecraft was pointing at RA (J2000): 217.29°; Dec (J2000): 43.81°; Roll: 327.42°. Two-minute cadence data were collected for 20,000 targets, and full frame images were collected every 30 minutes. See the TESS project [Sector 23 observation page](#)³ for the coordinates of the spacecraft pointing and center field-of-view of each camera, as well as the detailed target list. Fields-of-view for each camera and the Guest Investigator two-minute target list can be found at the TESS Guest Investigator Office [observations status page](#)⁴.

1.1 Notes on Individual Targets

Two bright stars ($T_{\text{mag}} \lesssim 1.8$) with large pixel stamps were not processed in the photometric pipeline. Target pixel files with raw data are provided, but no light curves were produced. The affected TIC IDs are 411188061 and 459832522.

Six target stars (367758676, 159164209, 310362805, 283819432, 1102093577, 341873045) are blended with comparably bright stars—the contaminating flux for these objects is very large, and the resulting photometry for such targets is expected to be unreliable.

1.2 Spacecraft Pointing and Momentum dumps

Camera 1 suffered from strong scattered light signals at the beginning of orbit 53 and orbit 54, and so Camera 4 alone was used for guiding during this sector. The reaction wheel speeds were reset with a momentum dump 8.0 days after the beginning of each orbit. Figure 1 summarizes the pointing performance over the course of the sector based on Fine Pointing telemetry.

Spacecraft operations has been slowly increasing the time between momentum dumps while monitoring the response of the attitude control system and resulting pointing jitter.

³<https://tess.mit.edu/observations/sector-23>

⁴<https://heasarc.gsfc.nasa.gov/docs/tess/status.html>

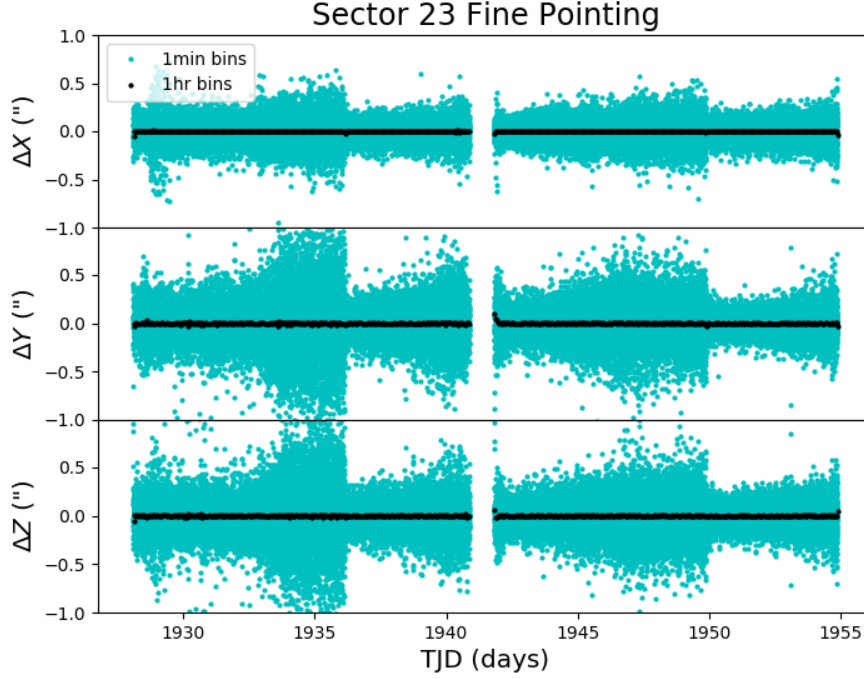


Figure 1: Guiding corrections based on spacecraft fine pointing telemetry. The jitter in orbit 1 near TJD=1935 is higher than observed in previous sectors. The delta-quaternions from each camera have been converted to spacecraft frame, binned to 1 minute and 1 hour, and averaged across cameras. Long-term trends (such as those caused by differential velocity aberration) have also been removed. The $\Delta X/\Delta Y$ directions represent offsets along the detectors’ rows/columns, while the ΔZ direction represents spacecraft roll.

In orbit 1 of Sector 23, anomalously high pointing jitter was observed for about 1.5 days before the momentum dump starting at $\sim$ TJD 1936.15. The peak-to-peak amplitude of the jitter is less than 1.5 arcseconds on 2 minute timescales. Although the jitter results in a substantially larger number of data anomaly flags in this sector compared to previous data releases, it does not otherwise affect the quality of the science processing. The anomalous jitter is described in more detail in §2 and §4.2.

1.3 Scattered Light

Figure 2 shows the median value of the background estimate for all targets on a given CCD as a function of time. Figure 3 shows the angle between each camera’s boresight and the Earth or Moon—this figure can be used to identify periods affected by scattered light and the relative contributions of the Earth and Moon to the image backgrounds.

In Sector 23, the Earth is a significant source of scattered light at the start of both orbits. The Moon also passes close to the field of view of Camera 1 during orbit 54.

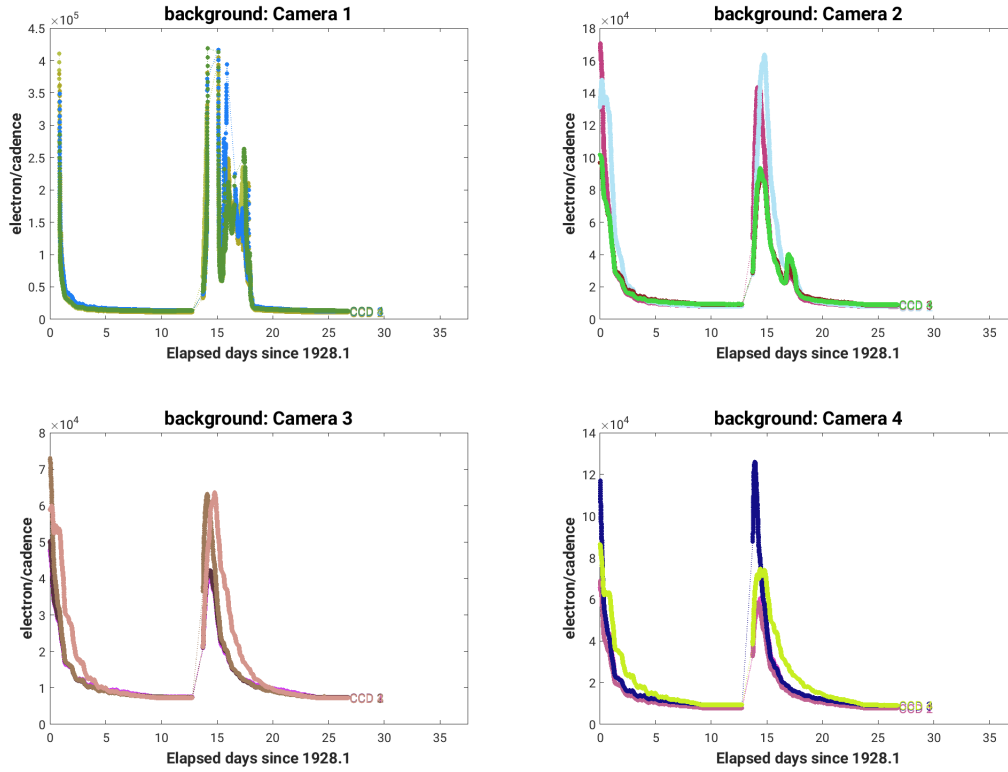


Figure 2: Median background flux across all targets on a given CCD in each camera. The changes are caused by variations in the orientation and distance of the Earth and Moon.

2 Data Anomaly Flags

See the [SDPDD](#) (§9) for a list of data quality flags and the associated binary values used for TESS data, and the [TESS Instrument Handbook](#) for a more detailed description of each flag.

The following flags were not used in Sector 23: bits 1, 2, 7, 9, and 11 (Attitude Tweak, Safe Mode, Cosmic Ray in Aperture, Discontinuity, Cosmic Ray in Collateral Pixel).

Cadences marked with bits 3, 4, 6, and 12 (Coarse Point, Earth Point, Reaction Wheel Desaturation Event, and Straylight) were marked based on spacecraft telemetry.

Cadences marked with bit 5 and 10 (Argabrightening Events and Impulsive Outlier) were identified by the SPOC pipeline. Bit 5 marks a sudden change in the background measurements. In practice, bit 5 flags are caused by rapidly changing glints and unstable pointing at times near momentum dumps. Bit 10 marks an outlier identified by PDC and omitted from the cotrending procedure.

Cadences marked with bit 8 (Manual Exclude) are ignored by PDC, TPS, and DV for cotrending and transit searches. In Sector 23, these cadences were identified using spacecraft telemetry from the fine pointing system. All cadences with pointing excursions >7 arcsec (~ 0.3 pixel) were flagged for manual exclude. This is the same threshold as used in previous sectors, and, because of anomalously high pointing jitter in orbit 1, a higher fraction of

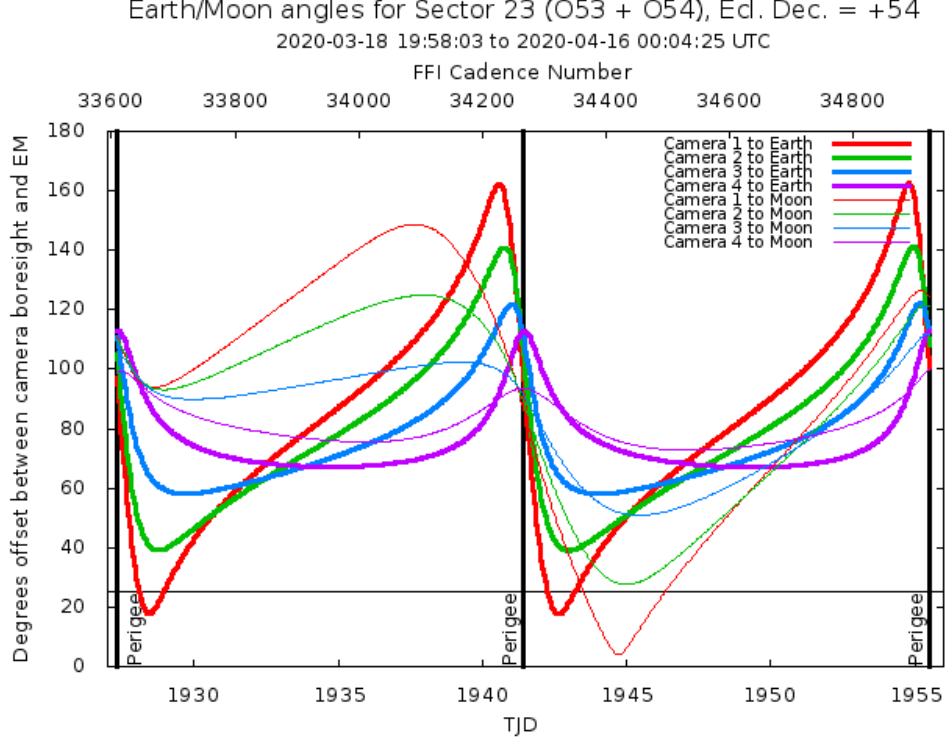


Figure 3: Angle between the four camera boresights and the Earth/Moon as a function of time. When the Earth is within $\sim 25^\circ$ of a camera’s boresight, transiting planet searches may be compromised by high levels of scattered light. At larger angles, up to $\sim 35^\circ$, scattered light patterns and complicated structures may be visible. At yet larger angles, low level patchy features may be visible. Scattered light from the Moon is generally only noticeable below $\sim 35^\circ$. This figure can be used to identify periods affected by scattered light and the relative contributions of the Earth and Moon to the background. However, the background intensity and locations of scattered light features depend on additional factors, such as the Earth/Moon azimuth and distance from the spacecraft.

cadences were flagged with bit 8 in Sector 23 than in previous data releases. Using these manual exclude flags, the overall quality of the final data products is very similar to previous sectors, despite the larger number of manual exclude flags (see §4). See Figure 4 for an assessment of the performance of the cotrending based on the final set of manual excludes.

In Sector 23, the predicted stray light flag (bit 12, value 2048) is disabled for the 2-minute data products. Instead, the scattered light exclude flag (bit 13, value 4096) identifies cadences at which individual targets are affected by scattered light. The predicted stray light flag (bit 12) continues to be marked in the FFIs and flags times when the Earth/Moon are near the camera FOVs and may interfere with guiding or saturate the detectors. We strongly recommend that users inspect the FFI data before removing images marked with bit 12, because this bit is set based on predictions from mission planning and is known to be conservative with respect to the quality of data usable for analysis.

If the Earth/Moon interference is strong enough to saturate the detector, all targets on a CCD slice will be affected and the data are unusable. Cadences with bad calibrations due to saturation are now explicitly marked with bit 15 (value 16384, “Bad Calibration Exclude”).

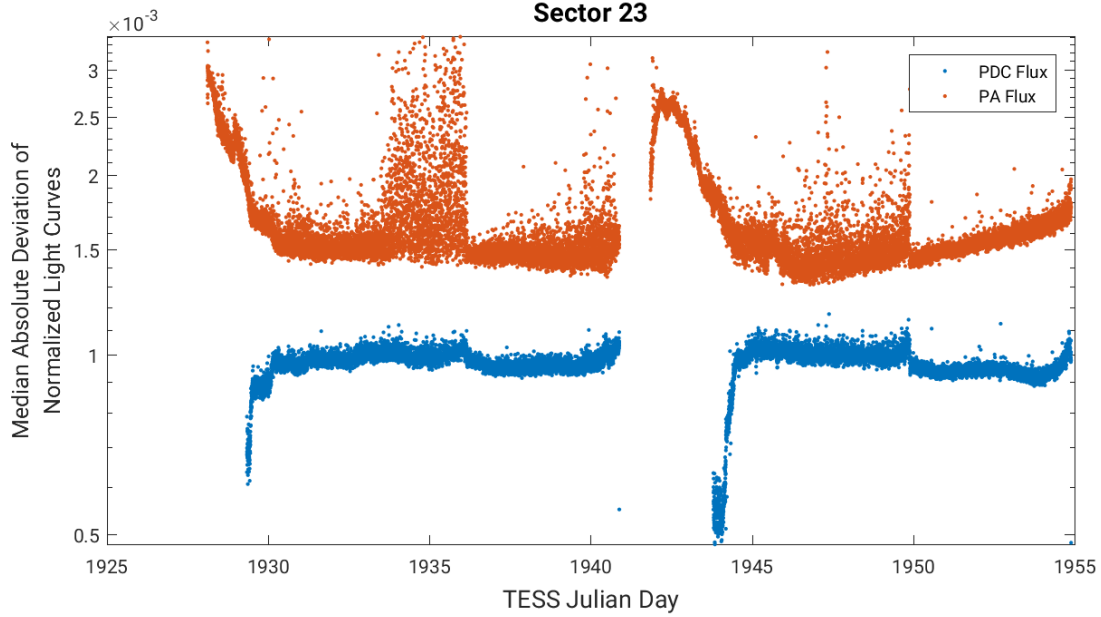


Figure 4: Median absolute deviation (MAD) for the 2-minute cadence data from Sector 23, showing the performance of the cotrending after identifying Manual Exclude data quality flags. The MAD is calculated in each cadence across stars with flux variations less than 1% for both the PA (red) and PDC (blue) light curves, where each light curve is normalized by its median flux value. The scatter in the PA light curves is much higher than that for the PDC light curves, and the outliers in the PA light curves are largely absent from the PDC light curves due to the use of the anomaly flags.

For some cadences, the majority of targets on a CCD may be flagged for scattered light and not enough valid data remains to derive cotrending basis vectors in PDC. No systematic error correction can be applied at these times. This situation is identified by bit 16 (value 32768, “Insufficient Targets for Error Correction Exclude”).

FFIs were only marked with bits 3, 6 and 12 (Course Point, Reaction Wheel Desaturation Events and Straylight). Only one FFI is affected by each momentum dump. There are no WCS coordinates for FFIs that coincide with momentum dumps.

3 Anomalous Effects

3.1 Smear Correction Issues

The following columns were impacted by bright stars in the science frame, and/or upper buffer rows, and/or lower science frame rows, which bleed into the upper serial register resulting in an overestimated smear correction.

- Camera 1, CCD 4, Column 2040, Star CP Virginis
- Camera 2, CCD 2, Column 268, Star AW Canum Venaticorum
- Camera 2, CCD 2, Column 1339, Star CL Canum Venaticorum

- Camera 2, CCD 2, Column 2020, Star HD 113829
- Camera 2, CCD 4, Column 2063, Star Epsilon Bootis

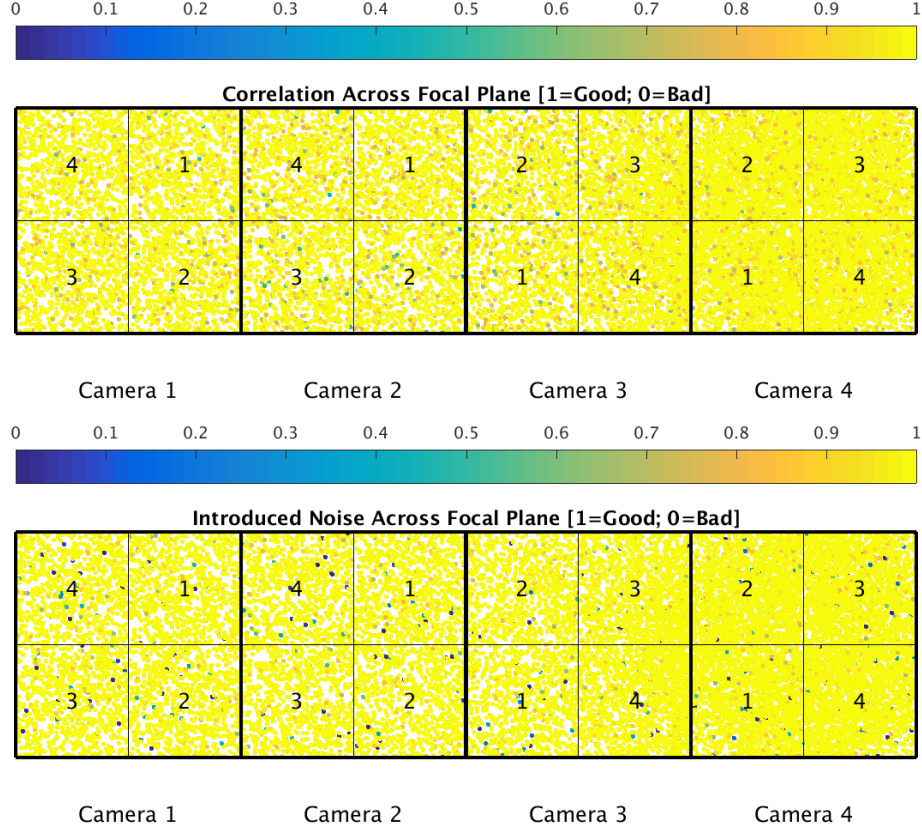


Figure 5: PDC residual correlation goodness metric (top panel) and PDC introduced noise goodness metric (bottom panel). The metric values are shown on a focal plane map indicating the camera and CCD location of each target. The correlation goodness metric is calibrated such that a value greater than 0.8 means there is less than 10% mean absolute correlation between the target under study and all other targets on the CCD. The introduced noise metric is calibrated such that a value greater than 0.8 means the power in broad-band introduced noise is below the level of uncertainties in the flux values.

3.2 Fireflies and Fireworks

Table 2 lists all firefly and fireworks events for Sector 23. These phenomena are small, spatially extended, comet-like features in the images—created by sunlit particles in the camera FOV—that may appear one or two at a time (fireflies) or in large groups (fireworks). See the [TESS Instrument Handbook](#) for a more complete description.

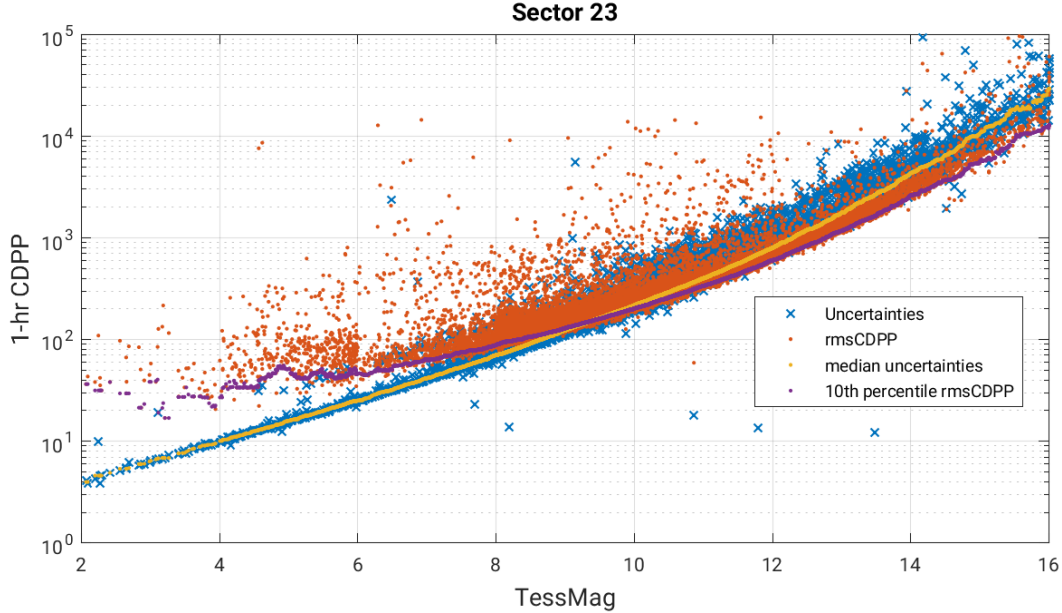


Figure 6: 1-hour CDPP. The red points are the RMS CDPP measurements for the 19998 light curves from Sector 23 plotted as a function of TESS magnitude. The blue x’s are the uncertainties, scaled to 1-hour timescale. The purple curve is a moving 10th percentile of the RMS CDPP measurements, and the gold curve is a moving median of the 1-hr uncertainties.

Table 2: Sector Fireflies and Fireworks

FFI Start	FFI End	Cameras	Description
2020087102920	2020087105920	2,3	Fireflies
2020091225920	2020091232920	1,2,3,4	Fireflies
2020102005919	2020102012919	2,3,4	Fireflies
2020104042919	2020104045919	1,2,3,4	Fireworks
2020106062919	2020106065919	1,2	Fireflies

4 Pipeline Performance and Results

4.1 Light Curves and Photometric Precision

Figure 5 gives the PDC goodness metrics for residual correlation and introduced noise on a scale between 0 (bad) and 1 (good). The performance of PDC is very good and generally uniform over most of the field of view. Figure 6 shows the achieved Combined Differential Photometric Precision (CDPP) at 1-hour timescales for all targets.

4.2 Transit Search and Data Validation

In Sector 23, the light curves of 19998 targets were subjected to the transit search in TPS. Of these, Threshold Crossing Events (TCEs) at the 7.1σ level were generated for 501 targets.

We employed an iterative method when conducting the Sector 23 transit search. The

top panel of Figure 7 shows the number of TCEs at a given cadence that exhibit a transit signal from an initial run of TPS. The $3\text{-}\sigma$ peaks were used to define deemphasis weights for a second run of TPS, the results of which are shown in the bottom panel of Figure 7. The final set of TCEs and the results reported here are based on the second run of TPS. The values of the adopted deemphasis weights are provided in the DV timeseries data products for targets with TCEs.

The top panel of Figure 8 shows the distribution of orbital periods for the final set of TCEs found in Sector 23. The vertical histogram in the right panel of Figure 8 shows the distribution of transit depths derived from limb-darkened transiting planet model fits for TCEs. The model transit depths range down to the order of 100 ppm, but the bulk of the transit depths are considerably larger.

A search for additional TCEs in potential multiple planet systems was conducted in DV through calls to TPS. A total of 726 TCEs were ultimately identified in the SPOC pipeline on 501 unique target stars. This is a somewhat smaller number of TCEs compared to previous sectors, which may be related to the larger number of manual excludes flags applied in orbit 1. However, the properties of the distributions of period, depth, and epoch in Figures 7 and 8 are in good agreement with previous sectors, indicating that the reliability of this transit search is comparable to that of previous data releases.

Table 3 provides a breakdown of the number of TCEs by target. Note that targets with large numbers of TCEs are likely to include false positives.

Table 3: Sector 23 TCE Numbers

Number of TCEs	Number of Targets	Total TCEs
1	315	315
2	152	304
3	30	90
4	3	12
5	1	5
—	501	726

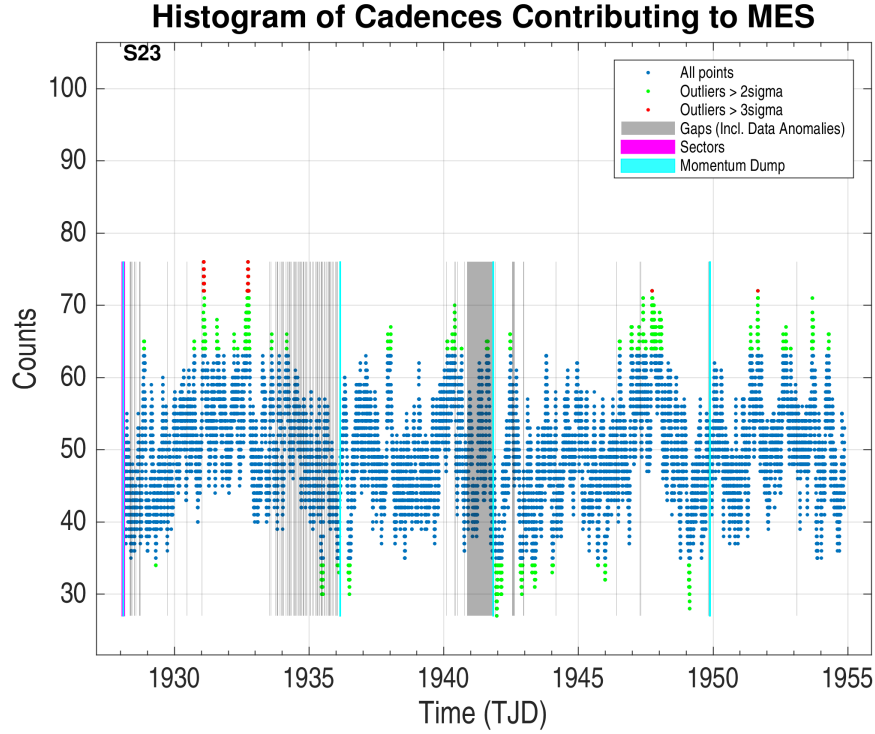
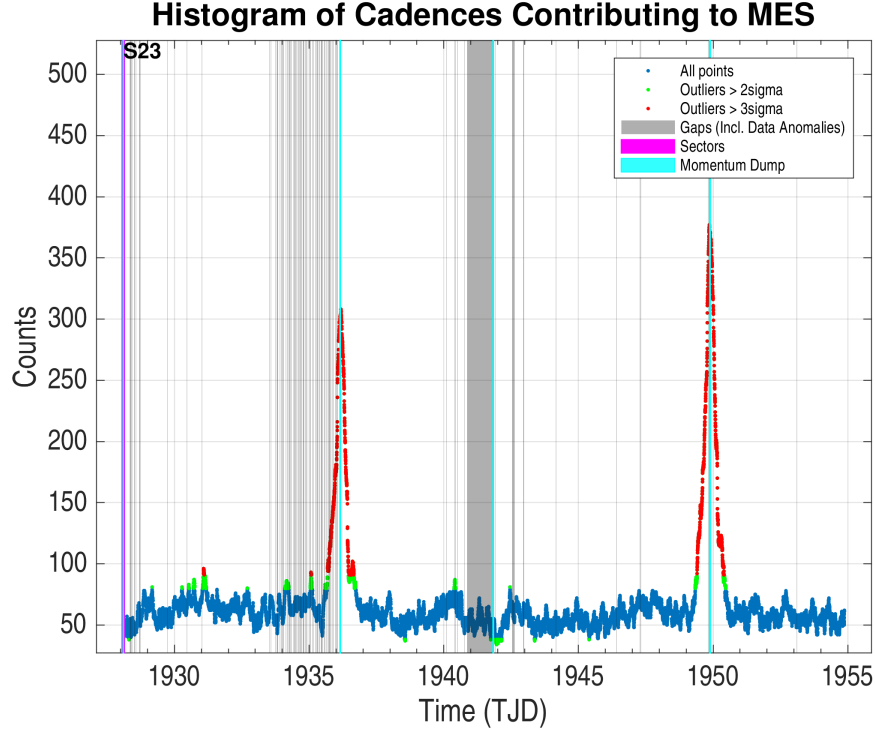


Figure 7: In both panels, the large number of data anomalies near $\text{TJD} = 1395$ are related to the increased pointing jitter observed in orbit 1, described in §1.2 and shown in Figure 1. Top panel: Number of TCEs at a given cadence exhibiting a transit signal, based on an initial run of TPS. Any isolated peaks are caused by single events that result in spurious TCEs. These peaks were used to define deemphasis weights that suppress problematic epochs for the transit detection statistics in a second iteration of TPS. Bottom panel: Results from the second run of TPS.

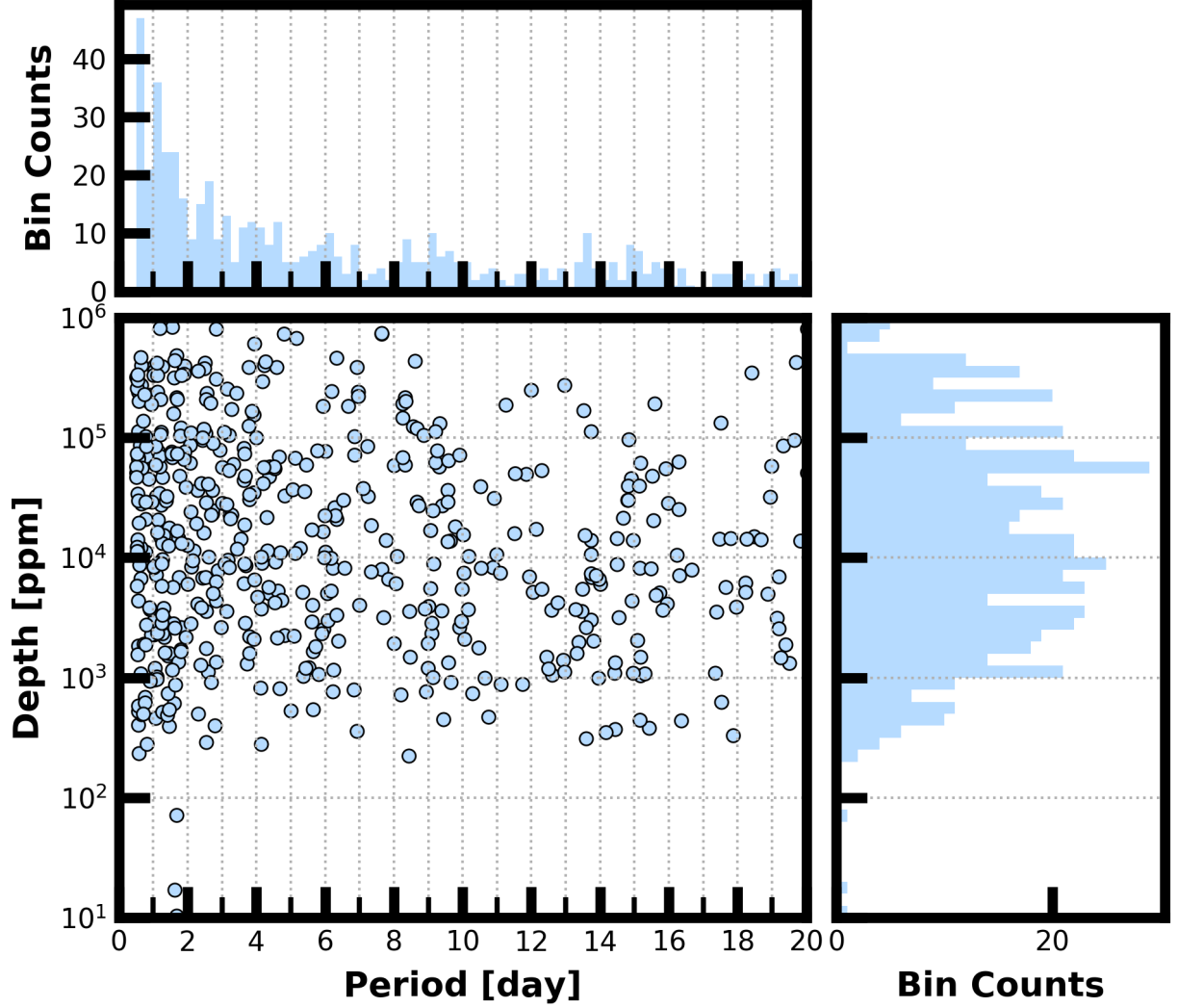


Figure 8: Lower Left Panel: Transit depth as a function of orbital period for the 726 TCEs identified for the Sector 23 search. For enhanced visibility of long period detections, TCEs with orbital period < 0.5 days are not shown. Reported depth comes from the DV limb-darkened transit fit depth when available, and the DV trapezoid model fit depth when not available. Top Panel: Orbital period distribution of the TCEs shown in the lower left panel. Right Panel: Transit depth distribution for the TCEs shown in the lower left panel.

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Acronyms and Abbreviation List

BTJD Barycentric-corrected TESS Julian Date

CAL Calibration Pipeline Module

CBV Cotrending Basis Vector

CCD Charge Coupled Device

CDPP Combined Differential Photometric Precision

COA Compute Optimal Aperture Pipeline Module

CSCI Computer Software Configuration Item

CTE Charge Transfer Efficiency

Dec Declination

DR Data Release

DV Data Validation Pipeline Module

DVA Differential Velocity Aberration

FFI Full Frame Image

FIN FFI Index Number

FITS Flexible Image Transport System

FOV Field of View

FPG Focal Plane Geometry model

KDPH Kepler Data Processing Handbook

KIH Kepler Instrument Handbook

KOI Kepler Object of Interest

MAD Median Absolute Deviation

MAP Maximum A Posteriori

MAST Mikulski Archive for Space Telescopes

MES Multiple Event Statistic

NAS NASA Advanced Supercomputing Division

PA Photometric Analysis Pipeline Module

PDC Pre-Search Data Conditioning Pipeline Module

PDC-MAP Pre-Search Data Conditioning Maximum A Posteriori algorithm

PDC-msMAP Pre-Search Data Conditioning Multiscale Maximum A Posteriori algorithm

PDF Portable Document Format

POC Payload Operations Center

POU Propagation of Uncertainties

ppm Parts-per-million

PRF Pixel Response Function

RA Right Ascension

RMS Root Mean Square

SAP Simple Aperture Photometry

SDPDD Science Data Products Description Document

SNR Signal-to-Noise Ratio

SPOC Science Processing Operations Center

SVD Singular Value Decomposition

TCE Threshold Crossing Event

TESS Transiting Exoplanet Survey Satellite

TIC TESS Input Catalog

TIH TESS Instrument Handbook

TJD TESS Julian Date

TOI TESS Object of Interest

TPS Transiting Planet Search Pipeline Module

UTC Coordinated Universal Time

WCS World Coordinate System

XML Extensible Markup Language