



Inclusion of Radiation Effects in the NASA Reliability & Maintainability Standard

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26th Annual
Single Event Effects (SEE) Symposium

Acronyms and Abbreviations



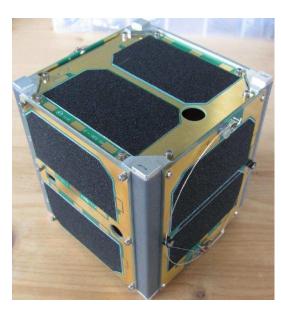
- AMSAT: Radio Amateur Satellite Corporation
- BN: Bayesian Network
- COTS: Commercial Off-the-Shelf
- GSN: Goal Structuring Notation
- IUCF: Indiana University Cyclotron Facility
- LEO: Low Earth Orbit
- NASA: National Aeronautics and Space Administration
- R&M: Reliability and Maintainability
- REM: Experiment Board
- RHA: Radiation Hardness Assurance
- SEE: Single-Event Effects
- SEFI: Single-Event Functional Interrupt
- SEL: Single Event Latch-up

- SEU: Single-Event Upset
- SRAM: Static Random Access Memory
- SysML: System Modeling Language
- TID: Total lonizing Dose
- VUC: Controller Board
- VUMC: Vanderbilt University Medical Center
- WDT: Watchdog Timer
- WDI: WDT Input
- WDO: WDT Output

Motivation: CubeSats



- CubeSats: Platform for affordable, quick-turn spaceflight
 - Volume, mass, and power constraints
 - Use of rad-hard parts prohibitive
- Traditional Radiation Hardness Assurance (RHA)
 - System reliability based on parts reliability
- Commercial off-the-shelf (COTS) RHA
 - System reliability based on system mitigation of part faults and failures



AO-85 Engineering Prototype (AMSAT)

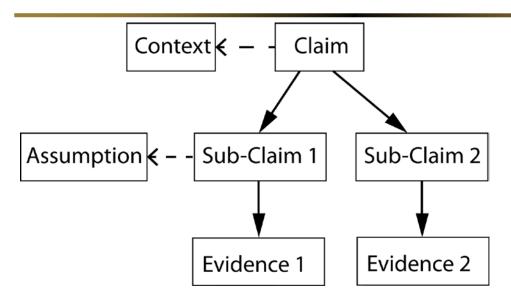
Motivation: NASA Reliability & Maintainability (R&M) Hierarchy



Moves from document-based Context: Expectations derived from crew safety, MMOD development to model-based concerns, facility safety, public safety, mission obj., sustainment, ..., development considerations and associated risk tolerance Top Objective: System performs as required Moves to over the lifecycle to satisfy mission objectives Context: System/function objectives-based description and requirements, including design information and interfaces reliability Context: Reference mission + requirements Strategy: Prevent faults and failures, provide before/after mitigation capabilities as needed to maintain an acceptable level of functionality **Adding goals** considering safety, performance, and Context: Range of nominal/ sustainability objectives off-nominal usage and specifically for conditions/environments radiation effects Objective: System Objective: System is Objective: System is Objective: System remains functional for designed to have an tolerant to faults, conforms to design intended lifetime, acceptable level of failures and other intent and performs environment, availability and anomalous internal operating conditions as planned maintenance and external events and usage demands (1)

Graphical Assurance Cases





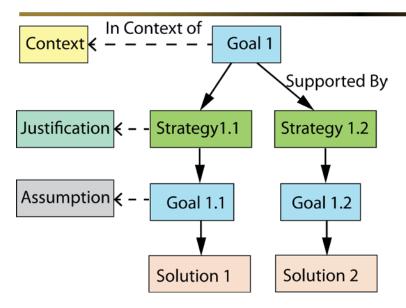
Argument: "A connected series of claims intended to support an overall claim." [1]

Assurance Case: "A reasoned and compelling argument, supported by a body of evidence, that a system, service or organization will operate as intended for a defined application in a defined environment." [1]

[1] GSN Community Standard Version 1 2011

Goal Structuring Notation (GSN)





Colors/Shapes
Denote Function

GSN is a visual representation of a hierarchy of claims [1]

University of York U.K.

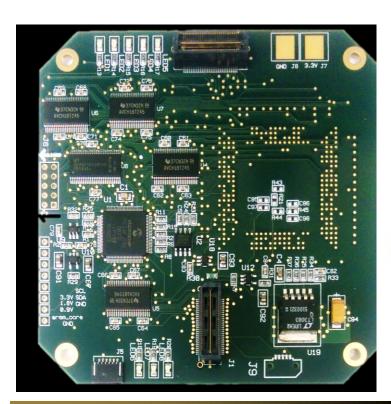
Goal=Claim
Strategy=Inference
Solution=Evidence
Context=Background
Justification=Rationale
Assumption=Unsubstantiated
Claim

[1] GSN Community Standard Version 1 2011

CubeSat Experiment



Mission Objective: Record the number of SEUs in 28nm bulk SRAM in LEO for a period of 1 year.

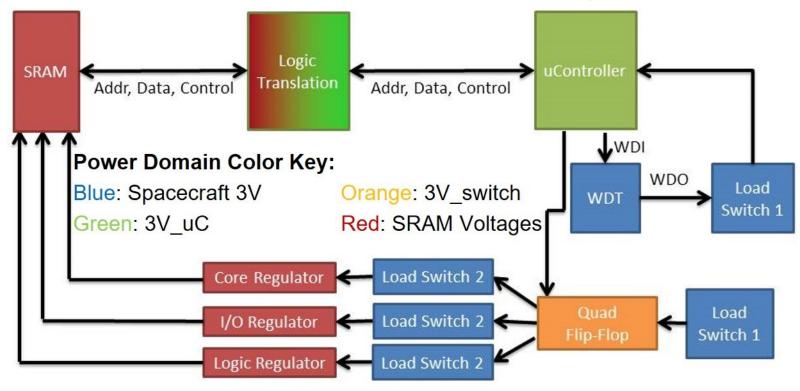




CubeSat Experiment Block Diagram



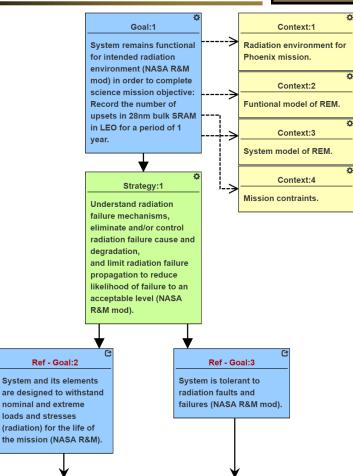
Mission Objective: Record the number of SEUs in 28nm bulk SRAM in LEO for a period of 1 year.



CubeSat Experiment Top Level GSN Model



- Top level goal: Based on top level goal of R&M hierarchy, adds specific science mission objective
- Sub-goals: Use both partlevel radiation tolerance and system-level radiation tolerance to achieve top level goal



CubeSat Experiment GSN Model for System-Level Mitigation Test Results



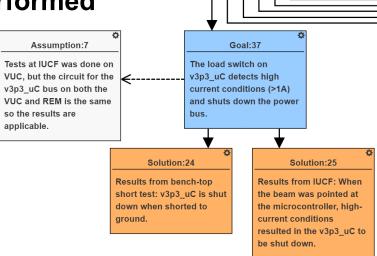
Goal:31

Isolate and contain Latch
up fault effects close to
the fault source.

Strategy:12

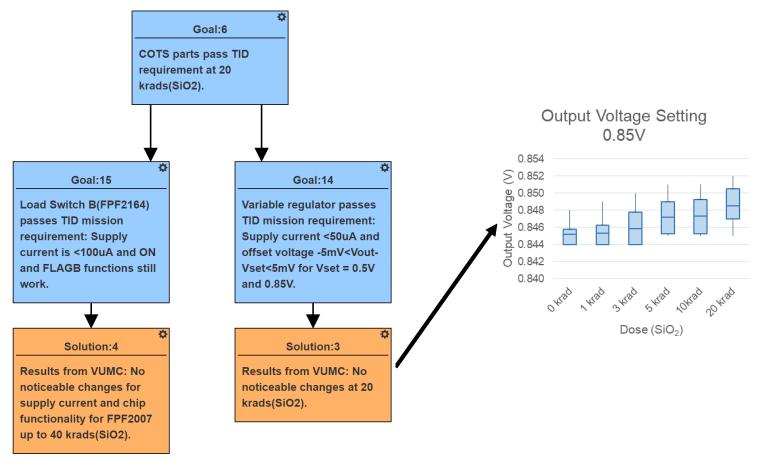
Use load switches on different power buses on REM to detect high-current conditions and to shut down the power bus.

- Proton test performed at IUCF using RB1
- Component test performed with a 1 inch square collimator
- System level tests also performed
 - Showed that the board recovers from SEL and SEFI



CubeSat Experiment GSN Model for Part-Level Mitigation Test Results



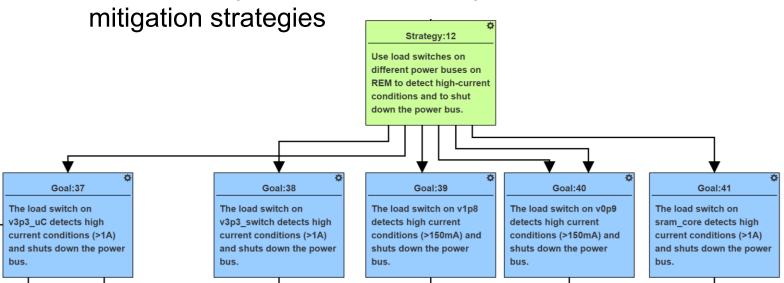


CubeSat Experiment Design Changes from use of GSN



- Missing load switched identified
 - Discovered during creation of argument for the system mitigation of latch-up events
- Influenced future experiment board designs

- Addition of system level telemetry to evaluate



Integrated System Design for Radiation Environments



Goal Structuring Notation:

R&M Template

Visual representation of argument

System Modeling Language (SysML):

 Specification of systems through standard notation

Bayesian Network (BN)

 Nodes describe probabilities of states

 Calculate conditional probabilities from observations

Requirements System Goal Modeling Structuring **Notation** Language (GSN) (SysML) Bayesian Design Reliability **Networks** (BN) Model

Overview of Modeling Languages Used

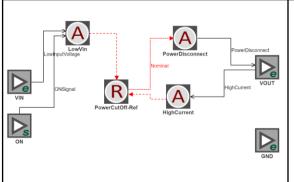


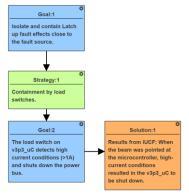
SysML+Fault Modeling

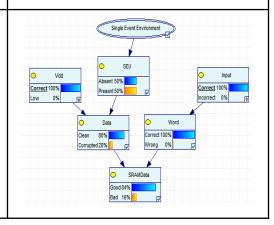
GSN

BN Model

- Extends SysML with fault propagation models
- "[F]aults" cause
 "[A]nomalies", potentially
 triggering "[R]esponses"
- Arguments show mitigation measures to address faults and anomalies
- Captures probabilities that faults result in anomalies







Integrated System Design for Radiation Environments



 R&M Hierarchy (using the GSN modeling language) provides the connection between Requirements and Reliability

Developing models between

Design and Requirements and adding fault propagation

- Design and Reliability

 Applying to same CubeSat experiment board

 Considerations for the use of COTS and related mitigation strategies

Requirements System Goal Structuring Modeling **Notation** Language (GSN) (SysML) Bayesian Design Reliability **Networks** (BN) Model