

Prognostics for Systems Health Management - Model and Hybrid Based Approaches. Where are we heading?

> Dr. Chetan S. Kulkarni Diagnostics and Prognostics Group NASA Ames Research Center 9<sup>th</sup> September 2020



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Research Team – Diagnostics and Prognostics Group – NASA Ames Research Center

Collaborators Prof. Felipe Viana, Renato Nascimento -University of Central Florida Prof. Olga Fink, Manuel Chao – ETH Zurich Dr. Kai Goebel - PARC

#### **Prognostics**

- Enables:
  - Adopting condition-based maintenance strategies, instead of time-based maintenance
  - Optimally scheduling maintenance
  - Optimally planning for spare components
  - Reconfiguring the system to avoid using the component before it fails
  - Prolonging component life by modifying how the component is used (e.g., load shedding)
  - Optimally plan or replan a mission
- System operations can be optimized in a variety of ways







# **Current Approaches**





Results tend to be Models can be reused sensor requirements Computationally efficient to implement Model development

#### **Data-Driven Methods**

#### Pros

Easy and Fast to implement

Several off-the-shelf packages are available for data mining May identify relationships that were not previously considered Can consider all relationships without prejudice

#### Cons

Requires lots of data and a "balanced" approach Most of the time, lots of run-to-failure data are not available High risk of "over-learning" the data Conversely, there's also a risk of "over-generalizing" Results may be counter- (or even un-)intuitive Correlation does not always imply causality! Can be computationally intensive, both for analysis and implementation

#### Example techniques

Regression analysis Neural Networks (NN) Bayesian updates Relevance vector machines (RVM)

# **Physics-Based Methods**

Description of a system's underlying physics using suitable representation Some examples:

Model derived from "First Principles" Encapsulate fundamental laws of physics •PDEs •Euler-Lagrange Equations Empirical model chosen based on an understanding of the dynamics of a system Lumped Parameter Model Classical 1<sup>st</sup> (or higher) order response curves Mappings of stressors onto damage accumulation Finite Element Model High-fidelity Simulation Model

Something in the model correlates to the failure mode(s) of interest

### **Physics-Based Models**

#### Pros

Results tend to be intuitive

Based on modeled phenomenon

And when they're not, they're still instructive (e.g., identifying needs for more fidelity or unmodeled effects) Models can be reused

Tuning of parameters can be used to account for differences in design

If incorporated early enough in the design process, can drive sensor requirements (adding or removing) Computationally efficient to implement

#### Cons

Model development requires a thorough understanding of the system High-fidelity models can be computationally intensive

#### Examples

Paris-Erdogan Crack Growth Model Taylor tool wear model Corrosion model Abrasion model

# **Model-based prognostics**

State vector includes dynamics of normal and degradation process

$$x_k = Ax_{k-1} + Bu_{k-1} + w_{k-1}$$





 EOL defined at time in which performance variable cross failure threshold

$$R(t_p) = t_{EOL} - t_p$$



## **Model-based prognostics**

- Tracking of health state based on measurements
- Forecasting of health state until failure threshold is crossed
- Compute RUL as function of EOL defined at time failure threshold is crossed



#### **Algorithm and Model Development TRL**











#### **Prior Work**



(Hanachi et al., 2017). A particle filter is used as a fusion mechanism to aggregate the diagnostic results from measurement signals and degradation models.



Overall architecture of the residual-based hybrid diagnostics in (Rausch et al., 2005). Feature engineering is carried out for the residuals between Kalman Filter estimates and sensor readings and are used as input to an SVM classifier.

# **Deep Learning + Physics Model Calibration**



Overall architecture of the hybrid prognostics framework fusing physics-based and deep learning models. Commercial Modular Aero-Propulsion System Simulation (C-MAPSS) : True and predicted RUL of the baseline model (top) and the proposed hybrid approach (bottom) for each test unit

20 30

40 50 60

50 60 70

40

Time [cvcles]

Time [cycles]

10

S 60

140 13 pa

Predic 05

80

RUL

& Tru

20

0 10 20 30

3CL

Unit 11
Unit 14

Unit 11

Unit 14
Unit 15

True-Unit 11

True-Unit 14

True-Unit 15

Unit 15 True-Unit 11

True-Unit 14

True-Unit 15

### Physics + RNN (Nascimento & Viana, 2019)





Overall architecture of the physics-informed recurrent neural network in

Y. A. Yucesan and F. A. C. Viana, "A physics-informed neural network for wind turbine main bearing fatigue," International Journal of Prognostics and Health Management, Vol. 11 (1), 2020. (ISSN: 2153-2648).

#### **Next Steps : Looking Ahead**



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### **Thank You**