



# **Rapid Aero Modeling for Urban Air Mobility Aircraft in Computational Experiments**

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# *Motivation for Rapid Aero Modeling (RAM)*

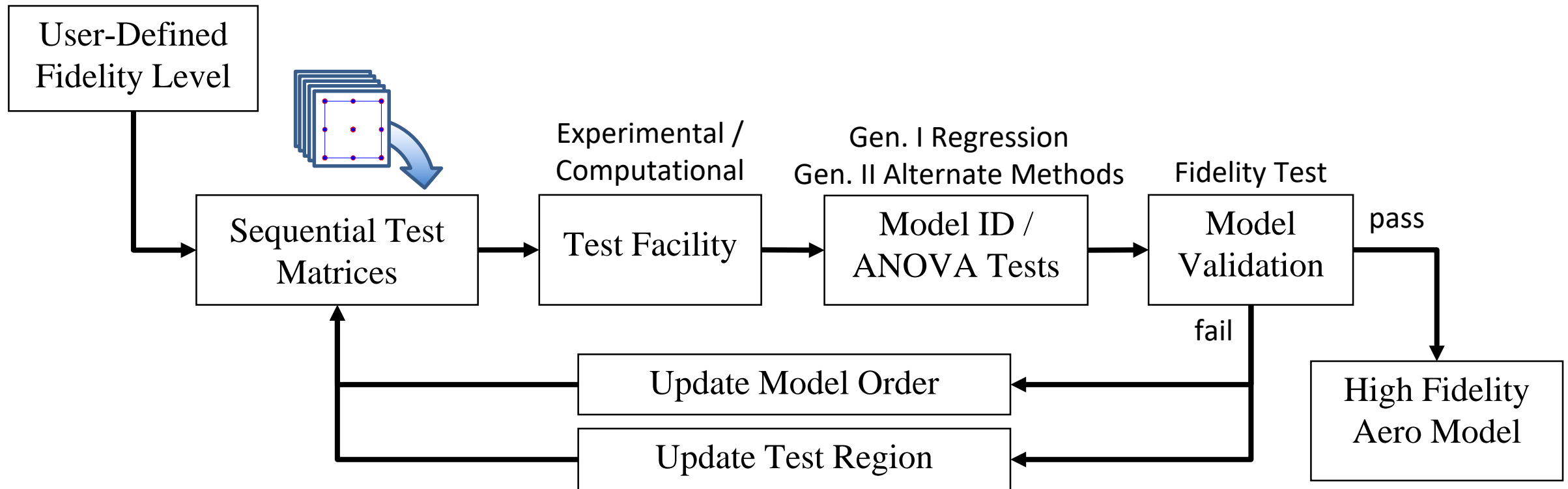


- Challenges in Urban Air Mobility Transportation Systems:
  - Aircraft features
    - Hybrid aircraft-rotorcraft.
    - Complexity, nonlinearity, and large numbers of interacting factors.
  - Conventional test methods (one-factor-at-a-time testing)
    - Fail to capture the complexity and numerous interactions.
    - Results in costly studies in terms of time and resources.
    - Produces models with limited information.
- Objectives:
  - Produce models suitable for nonlinear flight dynamics simulations.
  - Develop automated testing process.
  - Take advantage of well-established experiment design methods.



# Rapid Aero Modeling (RAM) Process - Introduction

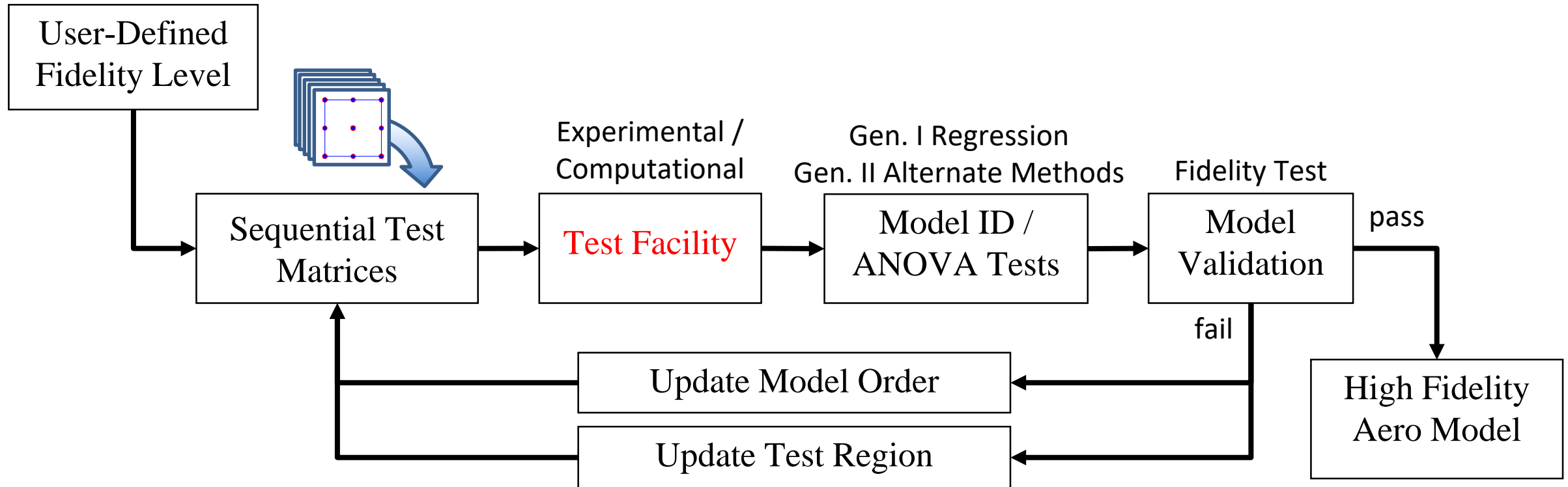
- RAM provides an automated, run efficient, statistically rigorous, testing process.
- Fidelity levels defined for each aero coefficient in terms of prediction error.





# Rapid Aero Modeling (RAM) Process – Test Facilities

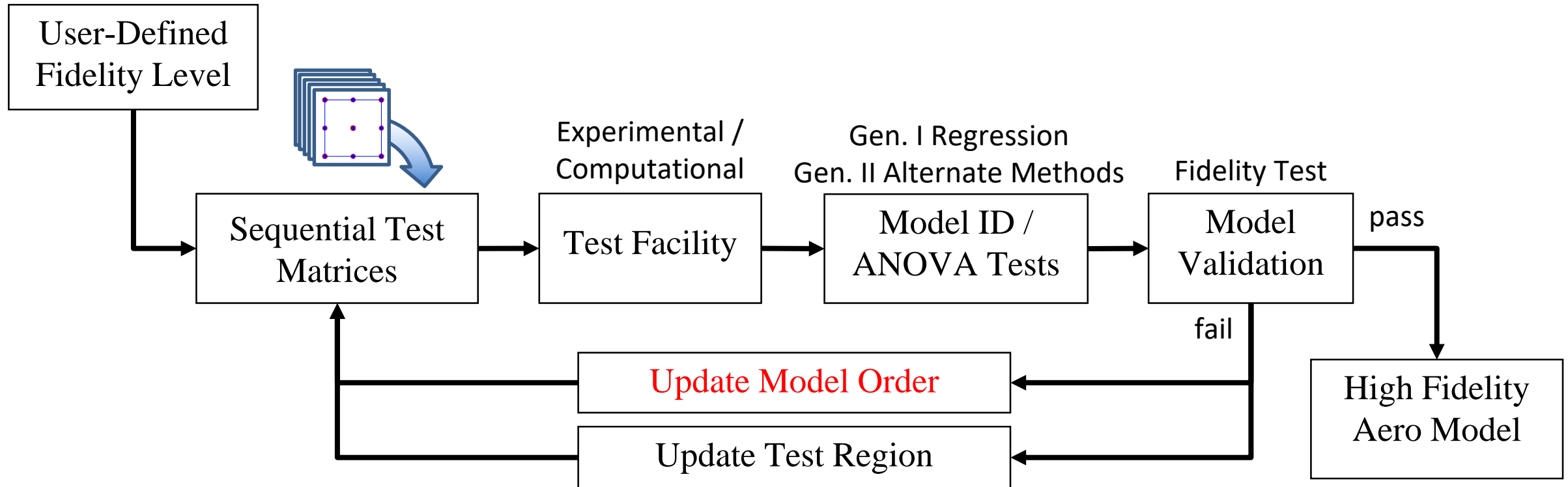
- First applications to static wind-tunnel (RAM-T) and computational experiments (RAM-C).





# Rapid Aero Modeling (RAM) Process – Inner Loop

- New data blocks requested only as needed to satisfy more complex polynomial models.

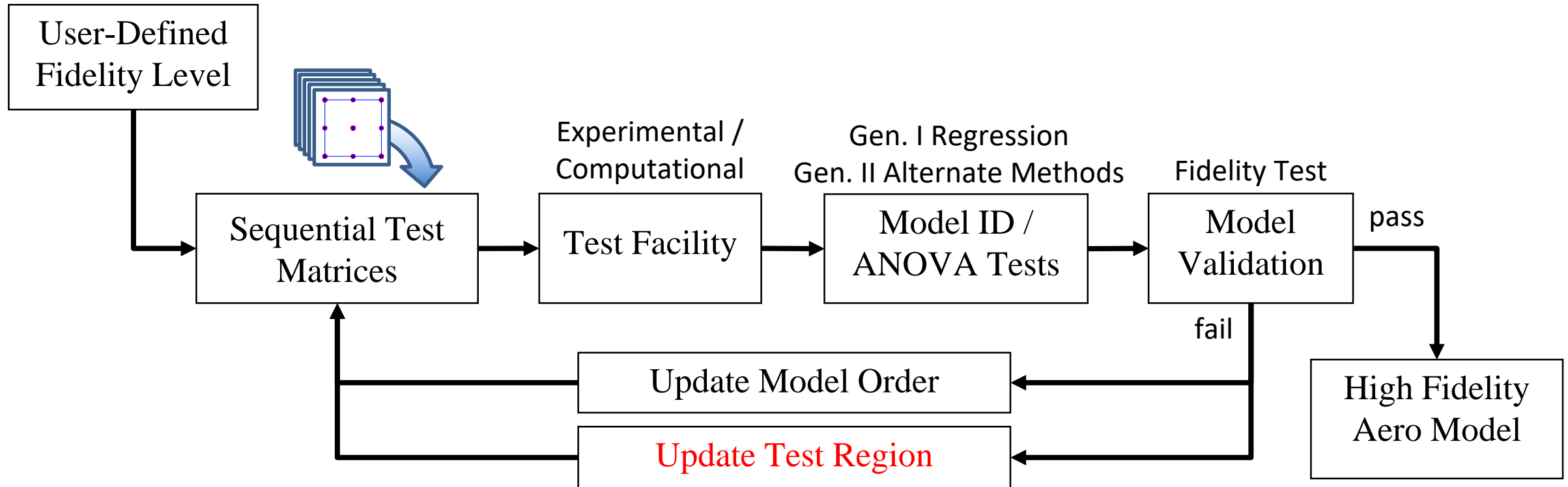




# Rapid Aero Modeling (RAM) Process – Outer Loop



- Test region is split when validation fails with highest-order polynomial.

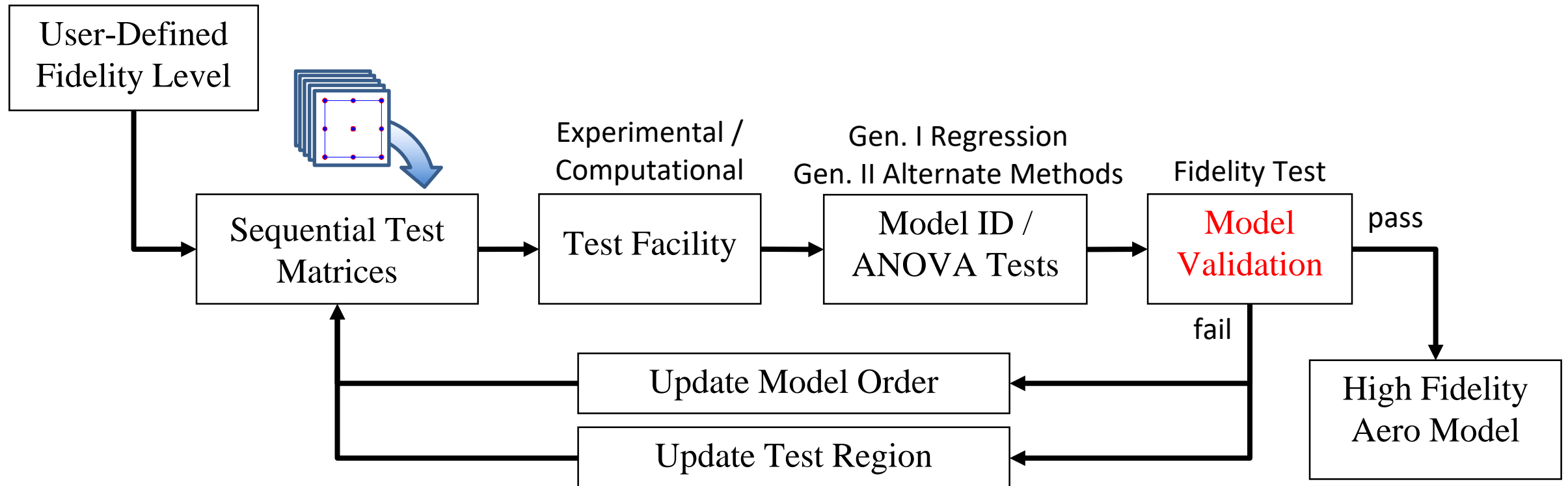




# Rapid Aero Modeling (RAM) Process – Model Validation



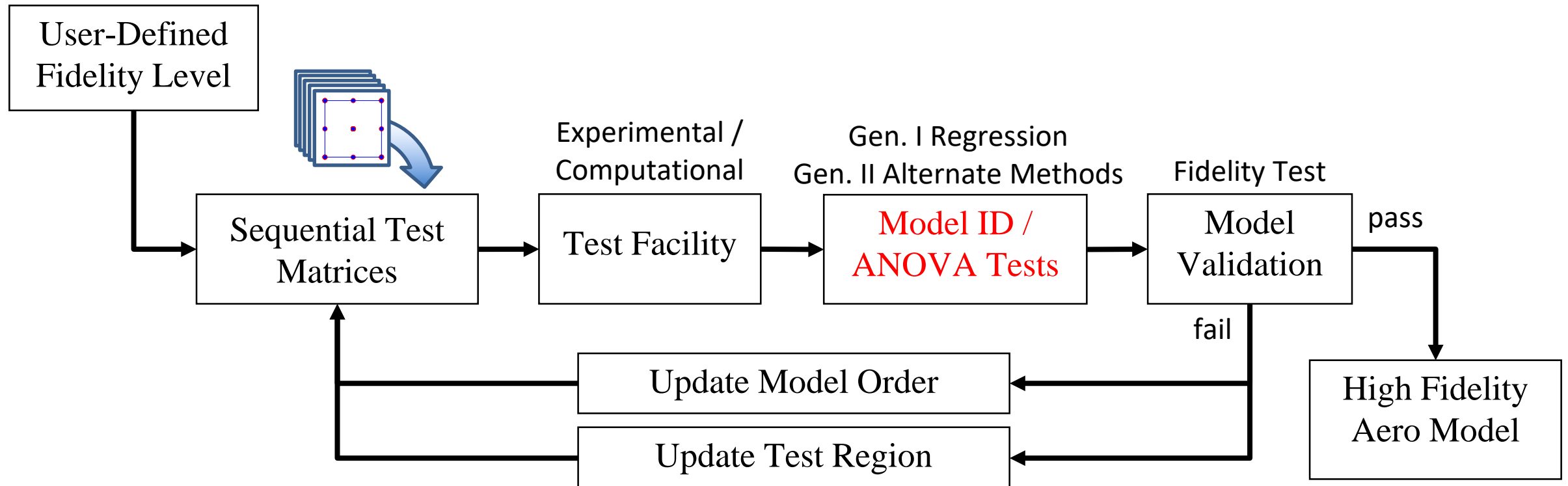
- Data for validation are not used for model identification.





# Rapid Aero Modeling (RAM) Process – Model Validation

- Stepwise regression is used for Model ID.



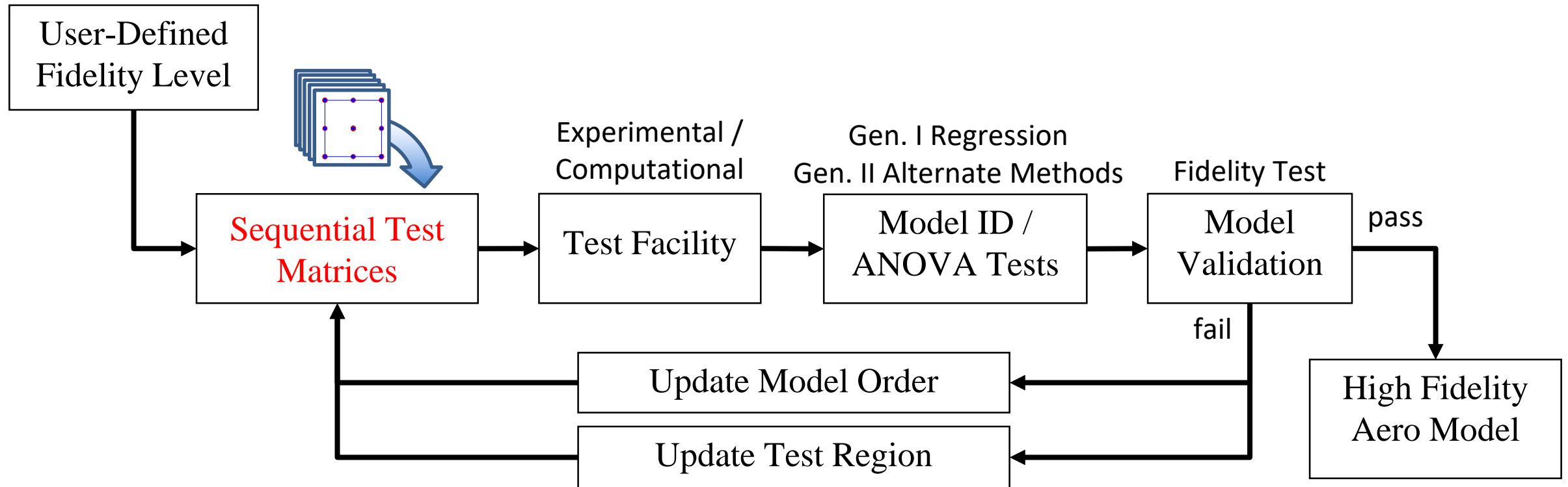




# Rapid Aero Modeling (RAM) Process – Test Matrices

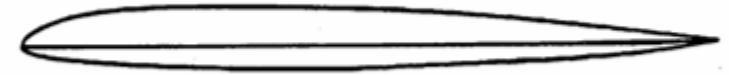


- RAM Block Library of test matrices based on DOE/RSM theory.

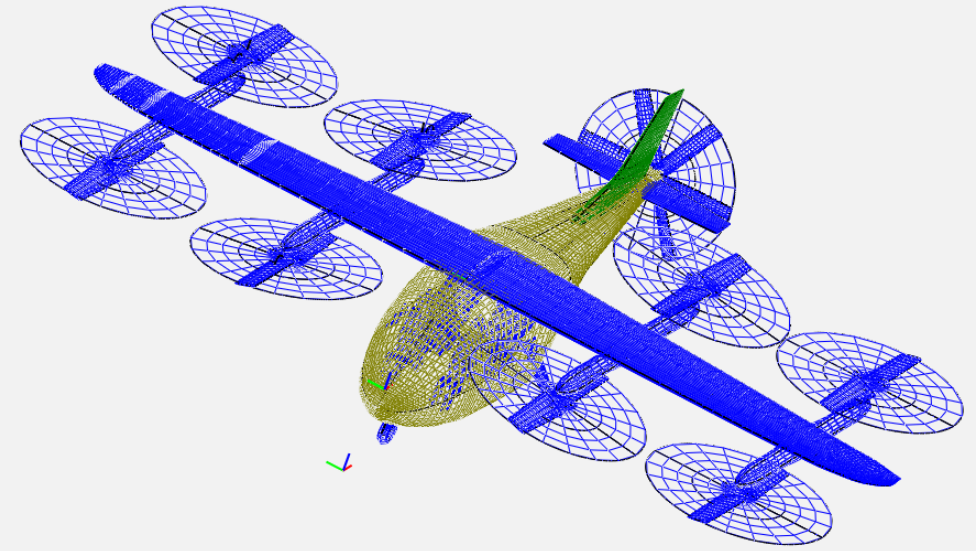


- “Test Facility” – OVERFLOW, a NASA developed high-fidelity CFD flow solver.
- Rotorcraft airfoil, 2-factor study
  - Mach number and angle of attack
  - Large factor ranges demonstrate splitting
- L+C, 17-factor study
  - 3 Body-axis velocities:  $u$ ,  $v$ ,  $w$
  - 5 Control surfaces: LA, RA, LE, RE, RUD
  - 8 Rotors: N1-N8
  - 1 Pusher propeller: N9

Rotor Airfoil (SSC-A09)



Lift+Cruise (L+C) Configuration



# Basic Block Designs & Supported Models – 2-factor Case



- Full factorial design

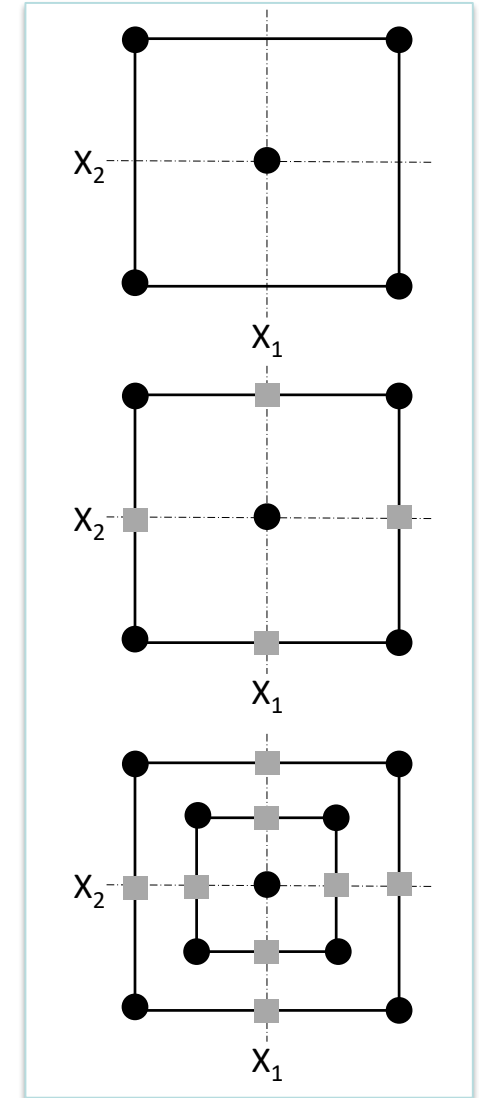
$$y = B_0 + \sum_i B_i x_i + \sum_{i \neq j} \sum B_{ij} x_i x_j + \dots + \varepsilon \quad i = 1, 2, \dots, k$$

- Face-centered design (FCD) – RAM Block #1

$$y = B_0 + \sum_i B_i x_i + \sum_i B_{ii} x_i^2 + \sum_{i \neq j} \sum B_{ij} x_i x_j + \varepsilon \quad i = 1, 2, \dots, k$$

- Nested face-centered design – RAM Blocks #1 & #2

$$y = B_0 + \sum_i B_i x_i + \sum_i B_{ii} x_i^2 + \sum_{i \neq j} \sum B_{ij} x_i x_j + \sum_i B_{iii} x_i^3 + \varepsilon \quad i = 1, 2, \dots, k$$



# Basic Block Designs & Supported Models – 2-factor Case

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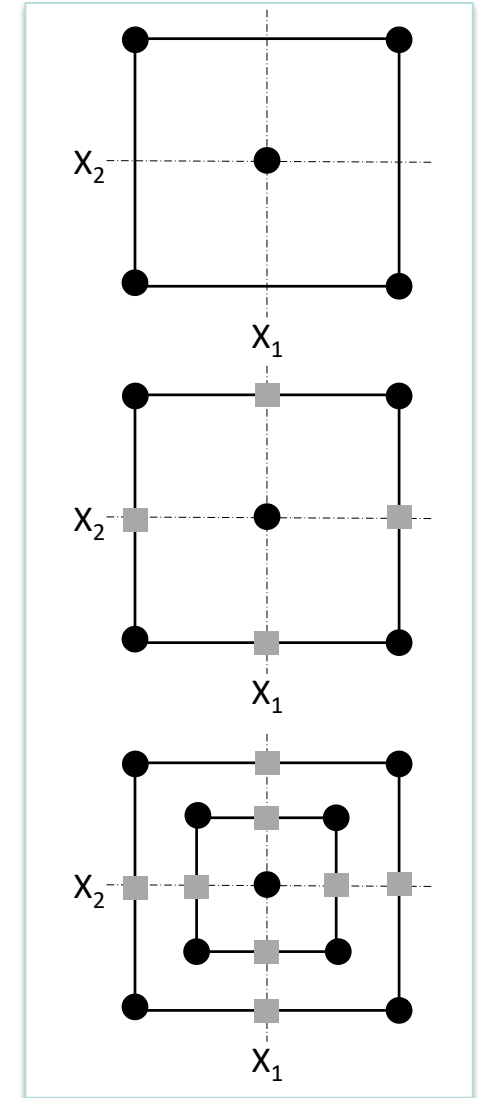


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# Basic Block Designs & Supported Models – 2-factor Case

- Full factorial design

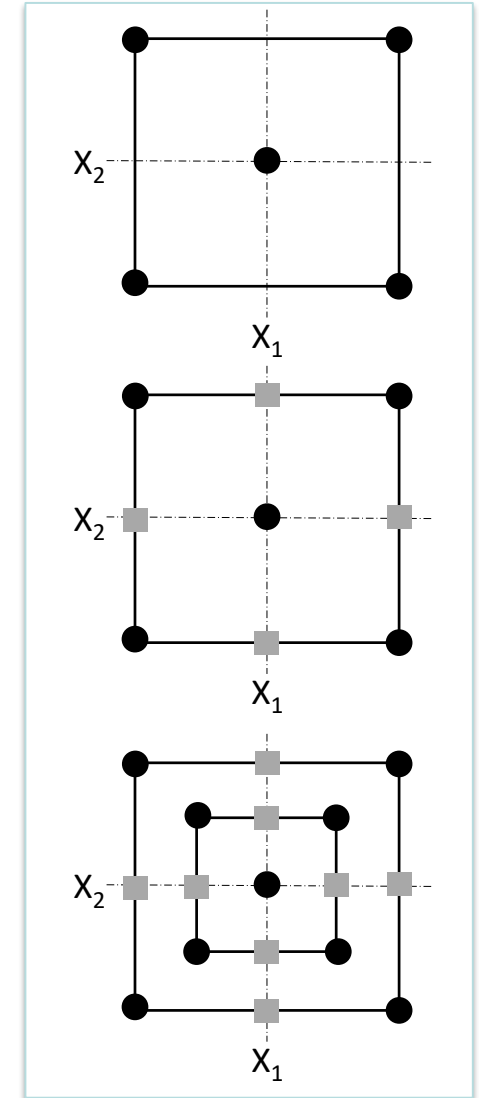
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- Nested face-centered design – RAM Blocks #1 & #2

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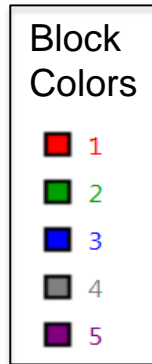
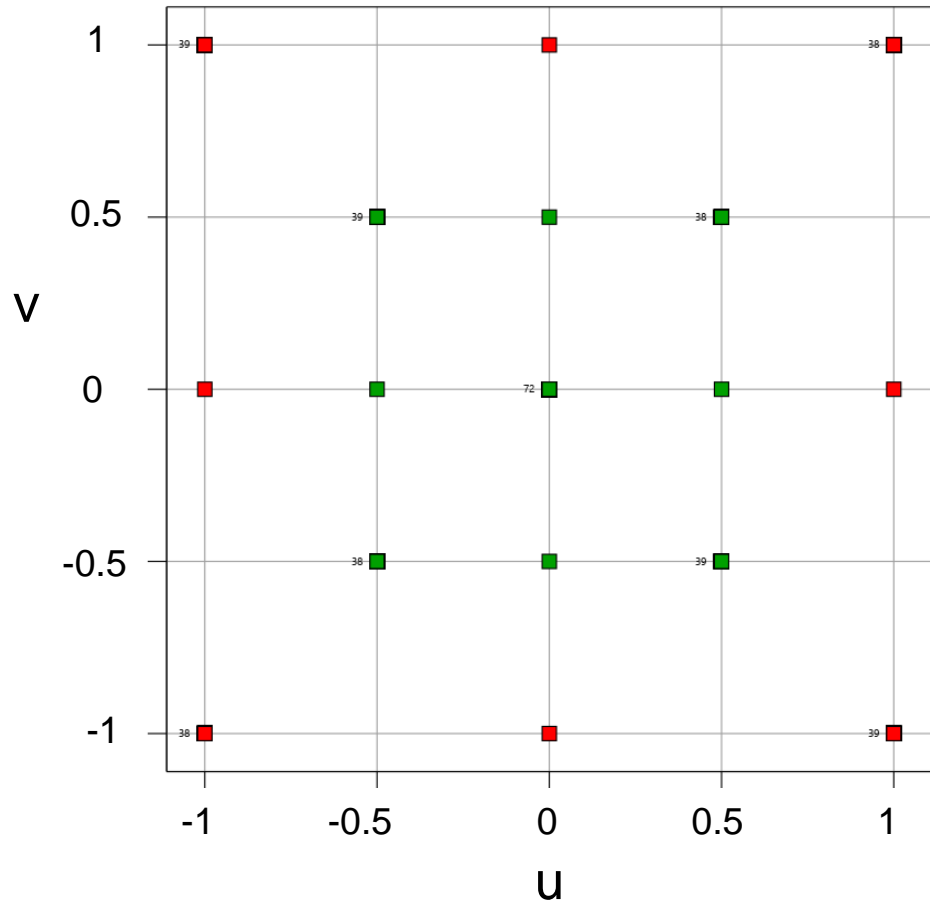




# RAM Design for L+C, 17-factor Test

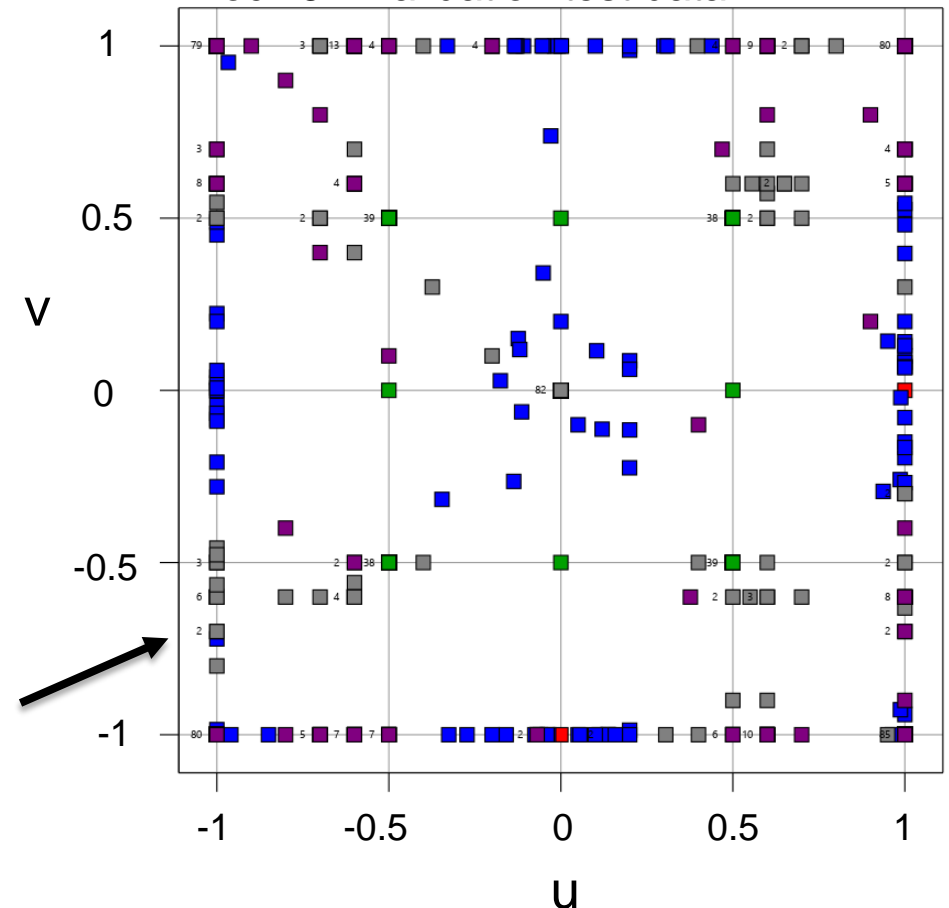
- 17-Factors: u, v, w, LA, RA, LE, RE, RUD, N1-N9
- 5-blocks (factors are scaled to +/- 1), 858 test points

Block 1 – FCD  
Block 2 – nested FCD



Blocks 1-2

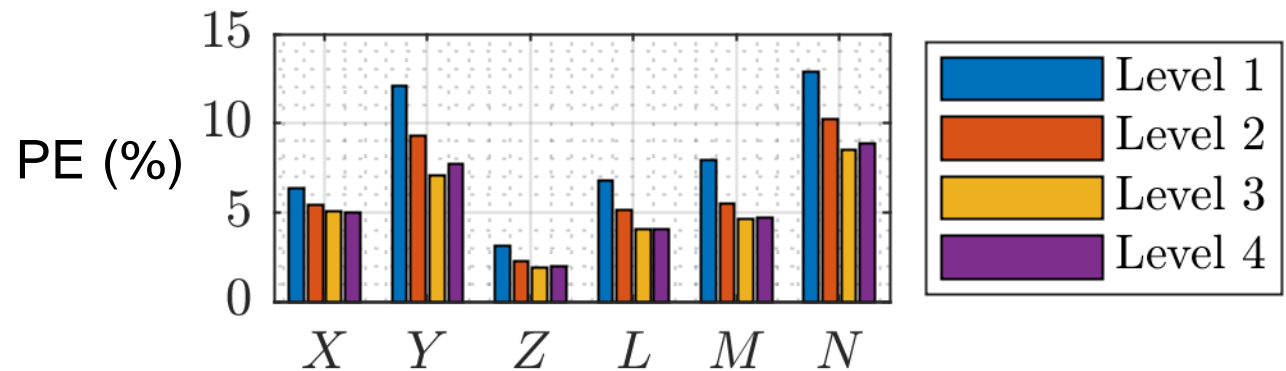
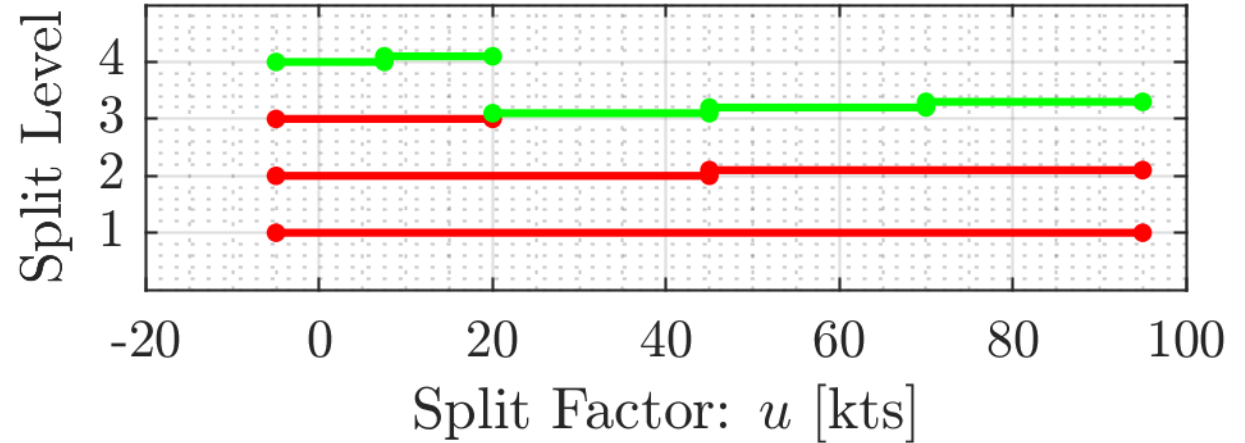
Blocks 3-4 – optimized for minimum PE  
Block 5 – validation test data



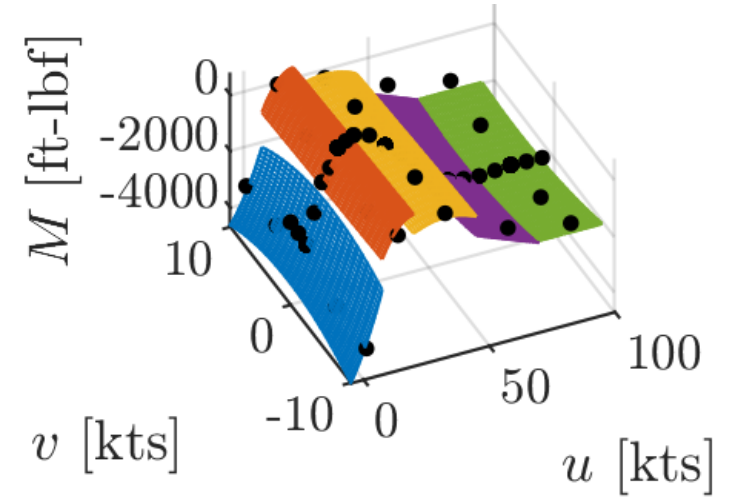
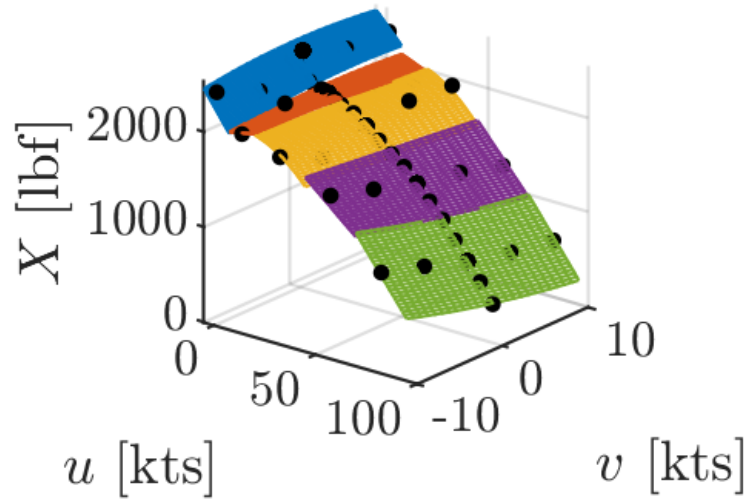
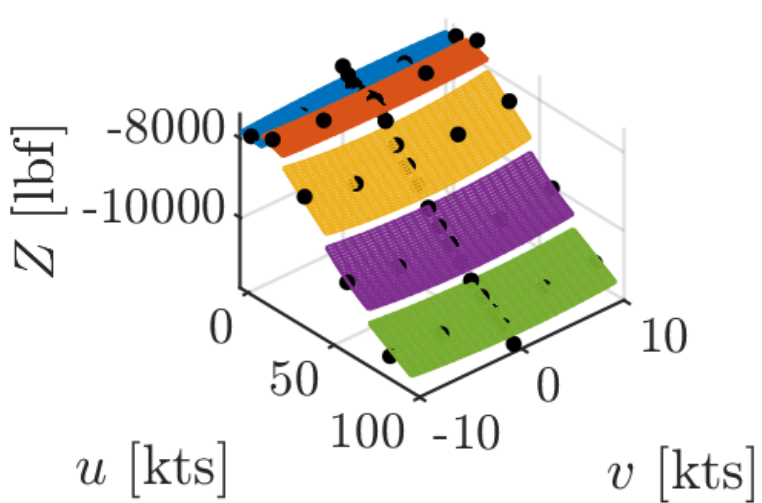
Blocks 1-5

# Speed-Regime Splits & PE Metric for L+C Study

- Test regions are split when models fail prediction goals.
  - Satisfactory model – green bars.
  - Unsatisfactory model – red bars.
- Regions are halved to improve data density & model fidelity.
- In final analysis for L+C study, 4 split levels were required, resulting in 5 separate modeling regions.

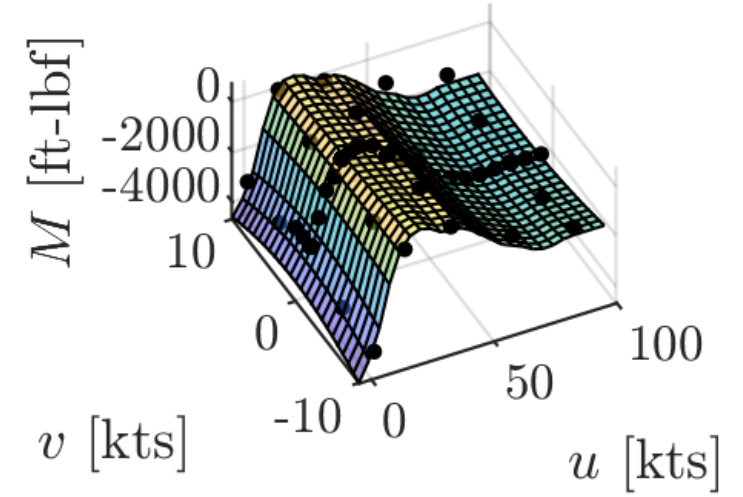
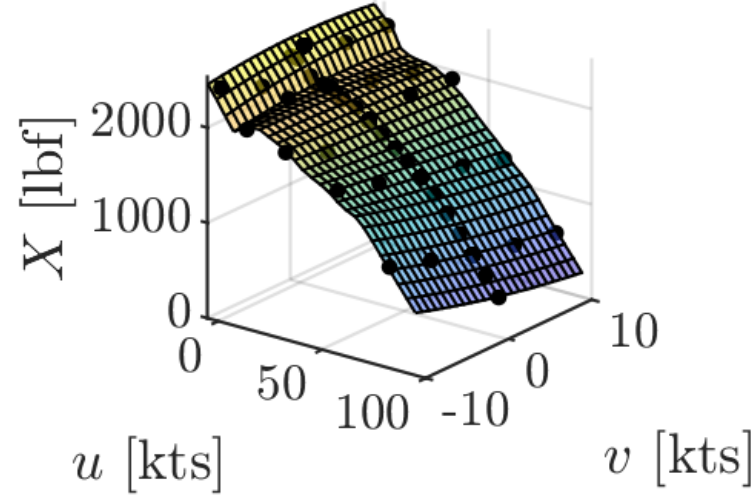
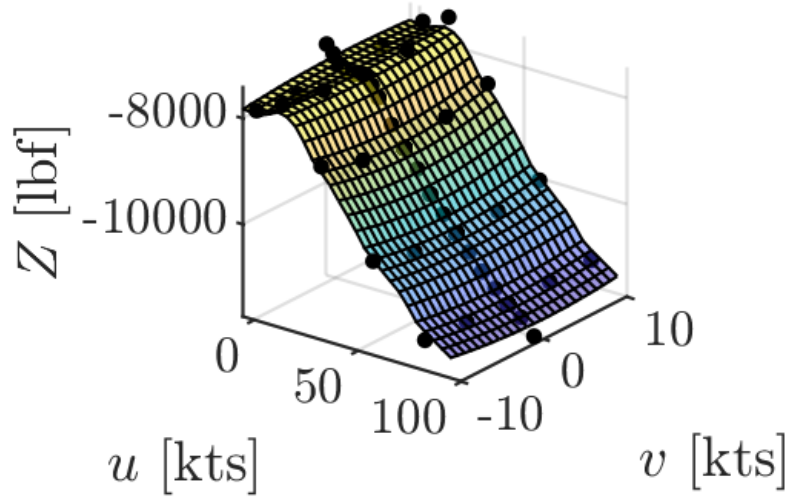


- L+C Longitudinal response models for separate regions as functions of  $(u, v)$ .





- L+C Final global longitudinal response models as functions of ( $u$ ,  $v$ ).





# Concluding Remarks



- RAM Motivation – complexity, factor count, interactions, and aero nonlinearities.
- RAM Process – automated, run efficient, and statistically rigorous testing.
- RAM Objective – desired model fidelity with limited data, save time and resources.
- RAM Applications – tunnel (RAM-T) or computational (RAM-C) test environments.
- RAM Demonstration – RAM-C applied to two computational experiments.



# Questions



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- B. M. Simmons, [Benjamin.M.Simmons@nasa.gov](mailto:Benjamin.M.Simmons@nasa.gov)

- Related papers

- Murphy, P. C., Simmons, B. M., Hatke, D. B., Busan, R. C., “Rapid Aero Modeling for Urban Air Mobility Aircraft in Wind-Tunnel Tests,” *AIAA SciTech 2021 Forum*, January 2021.
- Busan, R. C., Murphy, P. C., Hatke, D. B., and Simmons, B. M. “Wind Tunnel Testing Techniques for a Tandem Tilt-Wing, Distributed Electric Propulsion VTOL Aircraft,” *AIAA SciTech Forum*, January 2021.
- Simmons, B. M., and Murphy, P. C. “Wind Tunnel-Based Aerodynamic Model Identification for a Tilt-Wing, Distributed Electric Propulsion Aircraft,” *AIAA SciTech 2021 Forum*, January 2021.
- Simmons, B. M. “System Identification for Propellers at High Incidence Angles,” *AIAA SciTech Forum*, January 2021.

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