



# *ATM-X UAM Subproject*

Principal Engineer, Dr. Ian Levitt

+ CENTURY MEDICAL CENTER +

Dec 17, 2020



# Purpose

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*Provide a high level overview of ATM-X UAM Subproject, and NASA's Advanced Aerial Mobility (AAM) mission.*



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NASA Critical Commitment

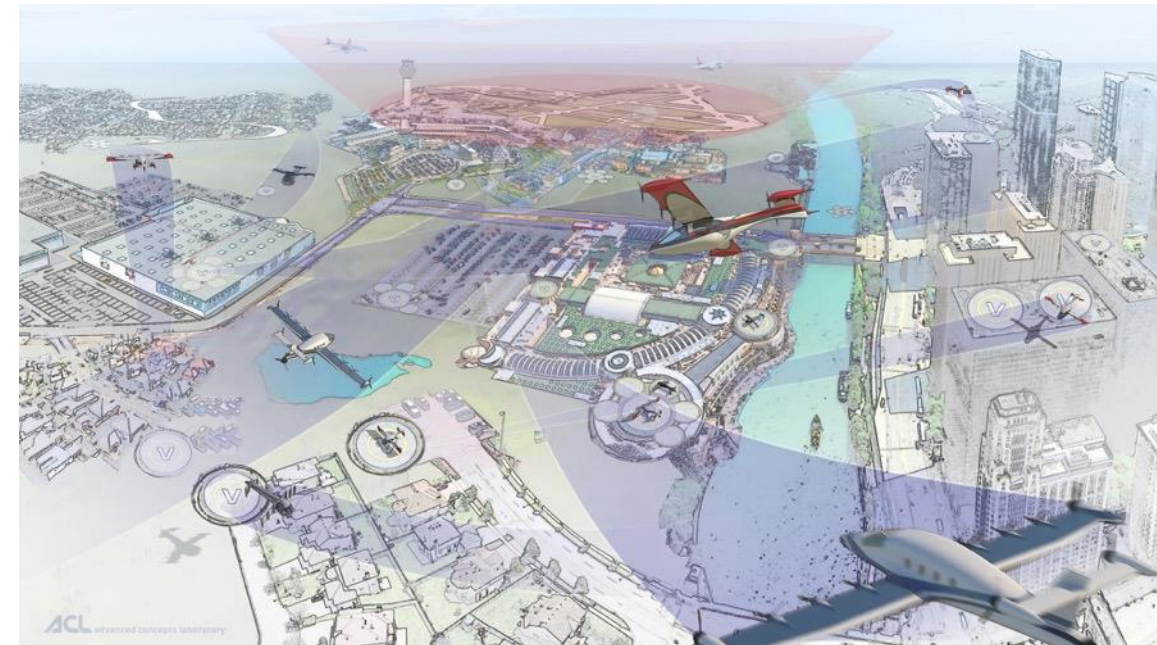
# **AAM MISSION**

# Advanced Air Mobility (AAM)

*Safe, sustainable, affordable, and accessible aviation for transformational local and intraregional missions*

*Local mission < ~75nmi, and intraregional mission < ~300nmi*

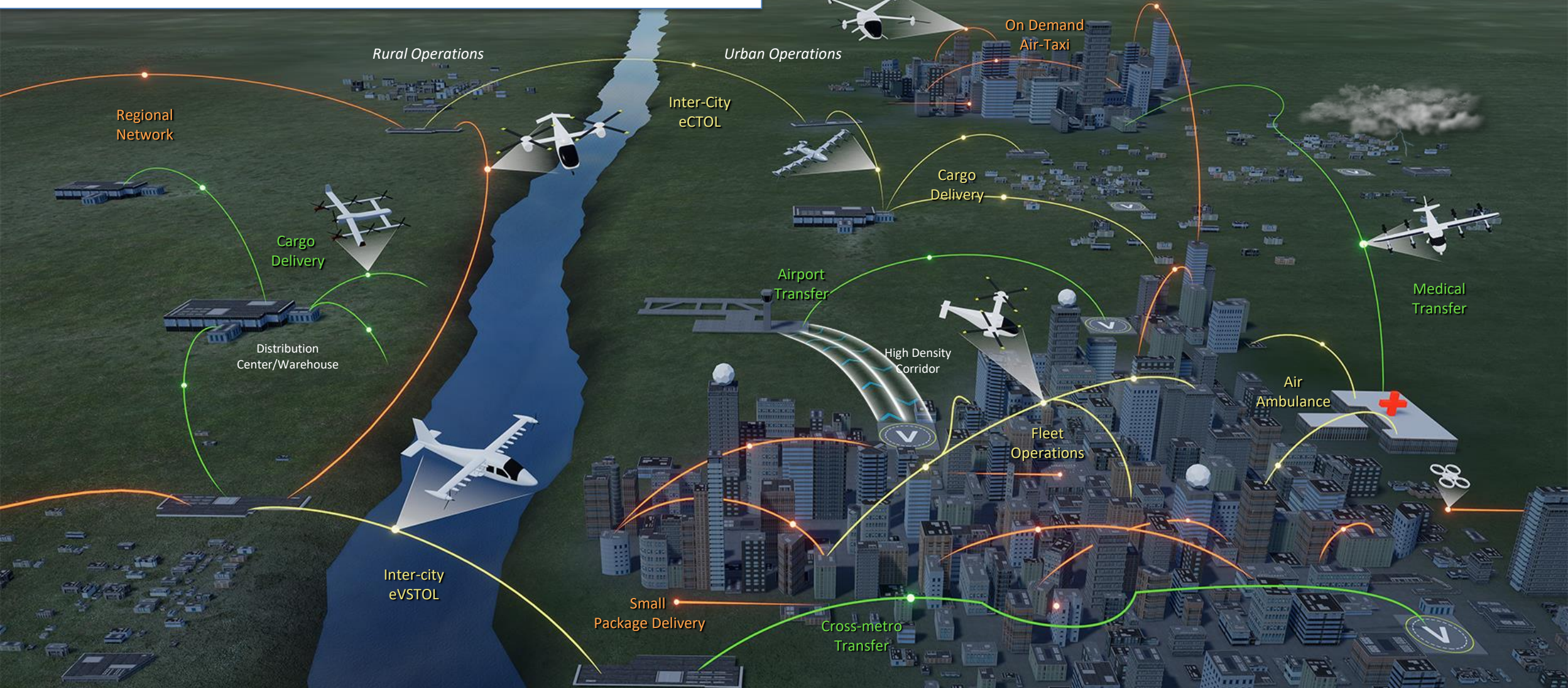
- Includes “rural” and “urban” applications
  - Cargo transport, pax-carrying, aerial work, etc.
  - eVTOL, sUAS, eCTOL, hybrid-electric, etc.
  - Urban Air Mobility (UAM) as a challenging use-case with high benefit
- Enabled by electrification and automation
- Does not include:
  - Supersonic or hypersonic transport
  - Existing hub-and-spoke air service with large transport aircraft



# Advanced Air Mobility (AAM) Mission

## UAM Maturity Levels (UML)

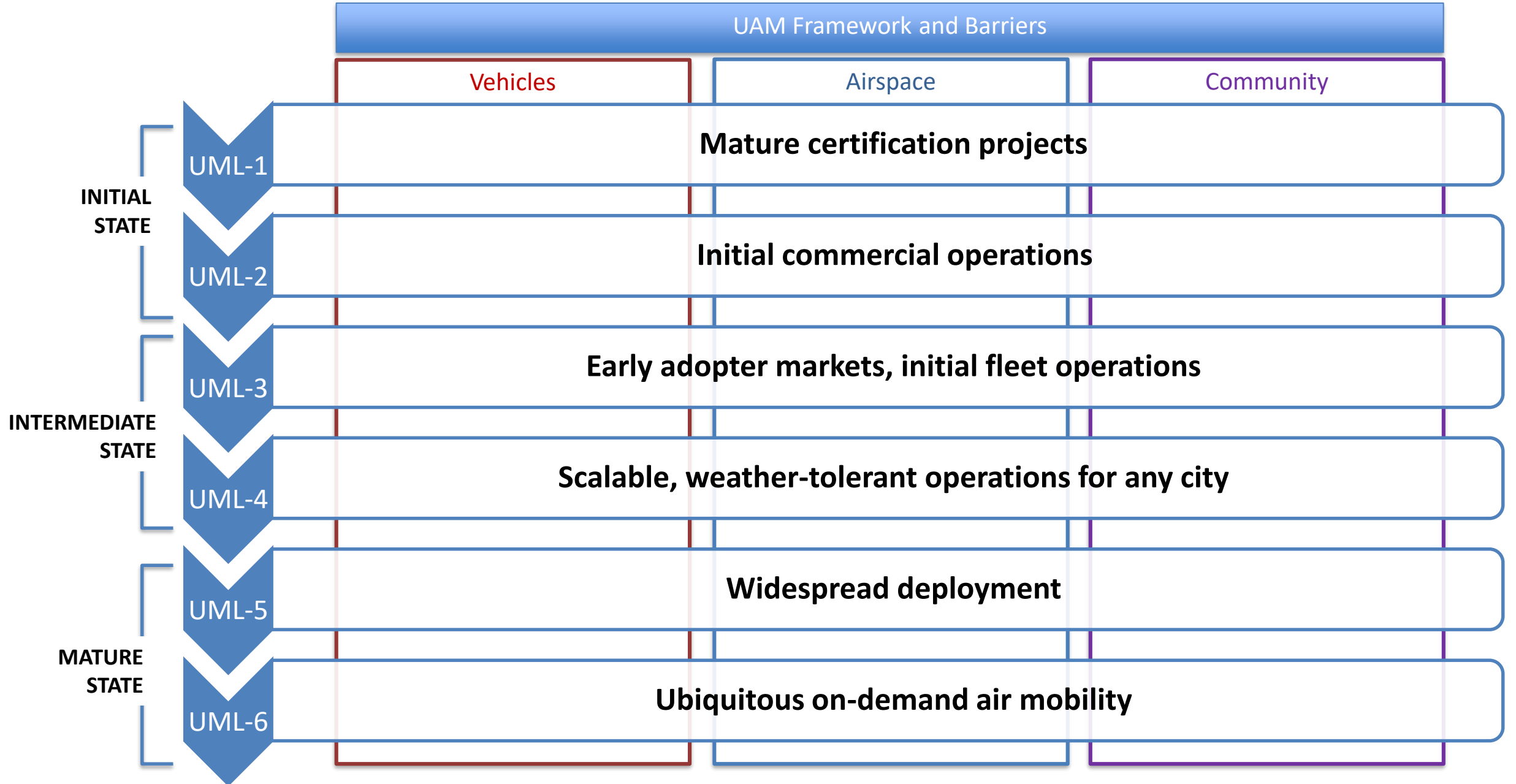
- UML-4 Medium Density/Complexity, assistive automation
- UML-3 Low Density, Medium Complexity, comprehensive safety assurance automation
- UML-2 Low Density/Complexity, collaborative and responsible automated systems
- UML-1 Conforming prototypes



Aircraft, airspace, and infrastructure system and architecture requirements to enable scalable medium density operations



# UAM Maturity Levels (UMLs): Top-Level View





ATM-X Project

# **UAM AIRSPACE SUBPROJECT**



# ATM-X Project Organization

## Air Traffic Management – eXploration

**Project Support**  
 Coordinator: Roxana Corzo  
 Lead Analyst: Warcquel Frieson  
 Center Analysts: Brenda McKay, Meredith Irwin  
 Schedulers: Natalie Condon, Donna Gilchrist

**Project Office**  
 Project Manager: William Chan  
 Deputy Proj. Mgr.: Mike Madson  
 Deputy Proj. Mgr. - Tech: Dr. Bryan Barmore  
 Chief Engineer: Dr. Joey Rios

**ARD Office**  
 ARC APM: Lindsay Stevens  
 LARC APM: Dr. Taumi Daniels  
 GRC APM: Rafael Apaza

**Vision 2045**  
 Lead: Shawn Engelland

**Systems Engineering**  
 Lead: Dr. James Chartres  
 Risk Mgr: Joshua Moody

Management approach governed by NPR 7120.8A

**SUB-PROJECTS**

**Digital Information Platform – (DIP)**  
 SPM: Mirna Johnson

**UAM Airspace Management (UAM)**  
 SPM: Kevin Witzberger  
 DSPM: Arwa Aweiss  
 PE: Dr. Ian Levitt

**Pathfinding for Airspace with Autonomous Vehicles (PAAV)**  
 SPM: Rob Fong  
 TL: Kurt Swieringa

**Collaborative Traffic Management (CTM)**  
 SPM: Dr. Jaewoo Jung  
 TL: Dr. Min Xue





# Work Package 1: Urban Air Mobility Foundational Research

- **Task 1.1: UAM Demand Analysis**

- The objective of this task is to identify potential demand for Urban Air Mobility (UAM) in cities/urban areas, in suburban areas/regions, between nearby cities/regions.
  - Jeremy Smith, [jeremy.c.smith@nasa.gov](mailto:jeremy.c.smith@nasa.gov)

- **Task 1.2: UAM Network**

- The objective of this task is to develop the necessary knowledge to quantify and qualify the advantages and disadvantages of different designs for a UAM network designs utilizing cost functions, network scheduling algorithms, and UAM demand prediction models.
  - Hanbong Lee, [hanbong.lee@nasa.gov](mailto:hanbong.lee@nasa.gov)

- **Task 1.3: UAM Impacts Analysis**

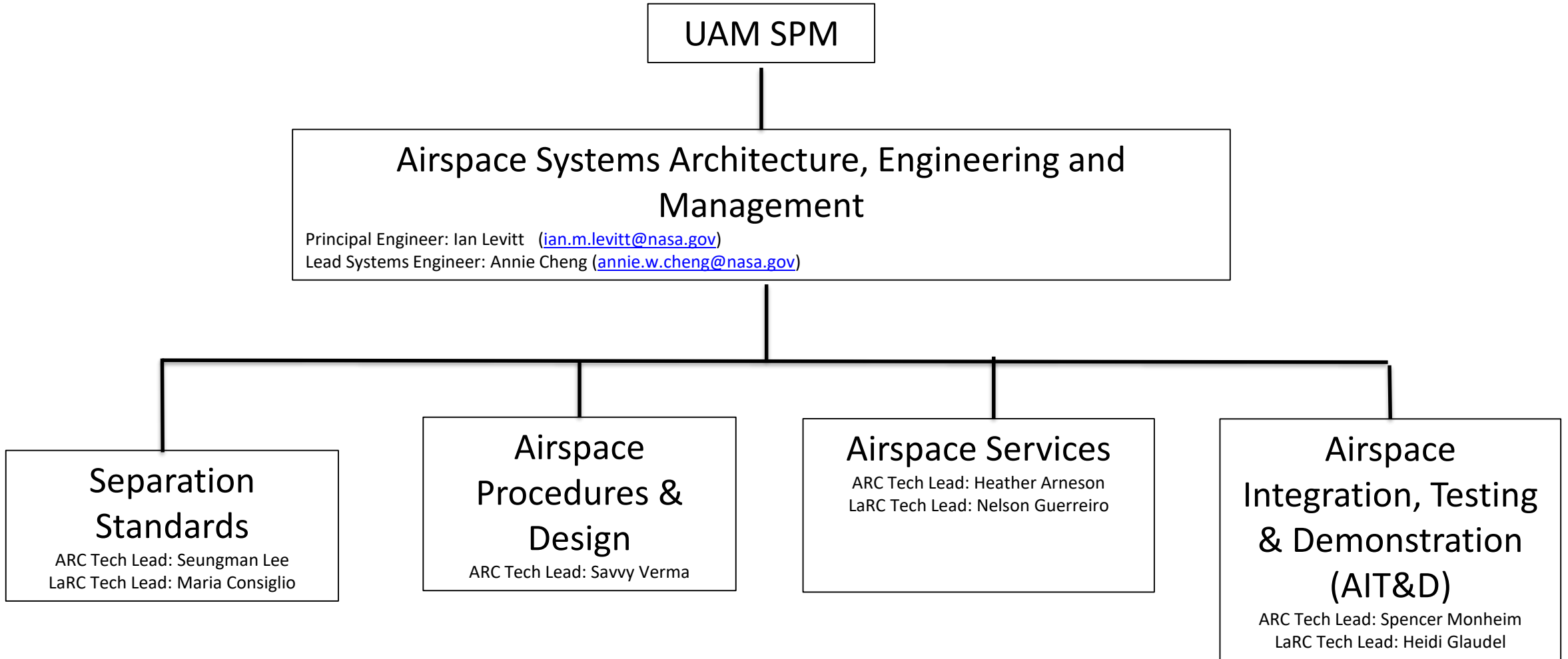
- The objective of this task is to develop fast-time simulated system-level impact assessments of weather and localized sub-system failures on potential UAM operations and environmental impacts due to UAM operations in selected urban/rural areas.
  - Hokkwan Ng, [hokkwan.ng@nasa.gov](mailto:hokkwan.ng@nasa.gov)

- **Task 1.4: UAM Flight Performance**

- The objective of this task is to develop a database for typical Urban Air Mobility (UAM) vehicles especially considered as V/STOL configurations will be used for the development and analysis of UAM-concepts dedicated to various urban regions and operational concepts.
  - John Foster, [John.v.foster@nasa.gov](mailto:John.v.foster@nasa.gov)

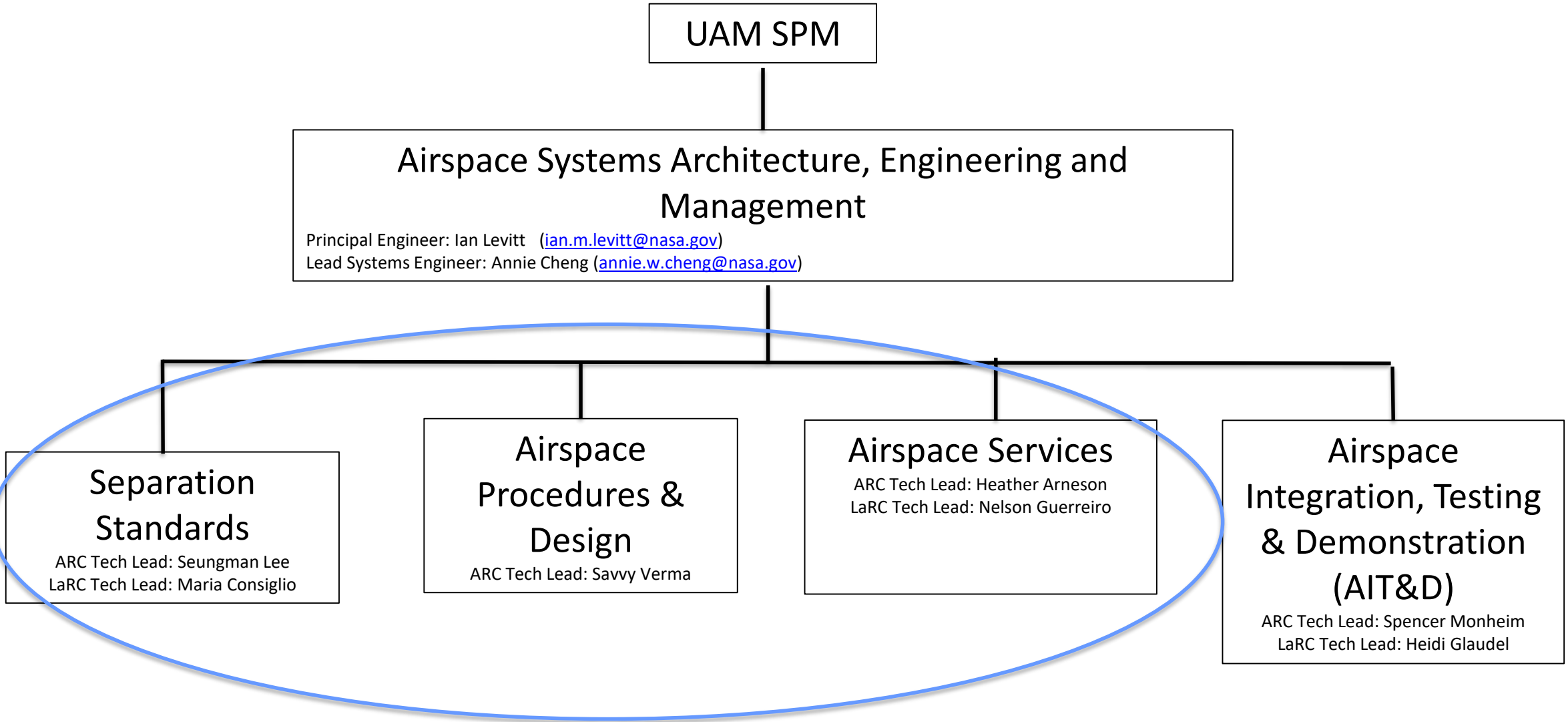


# UAM Airspace Sub-Project





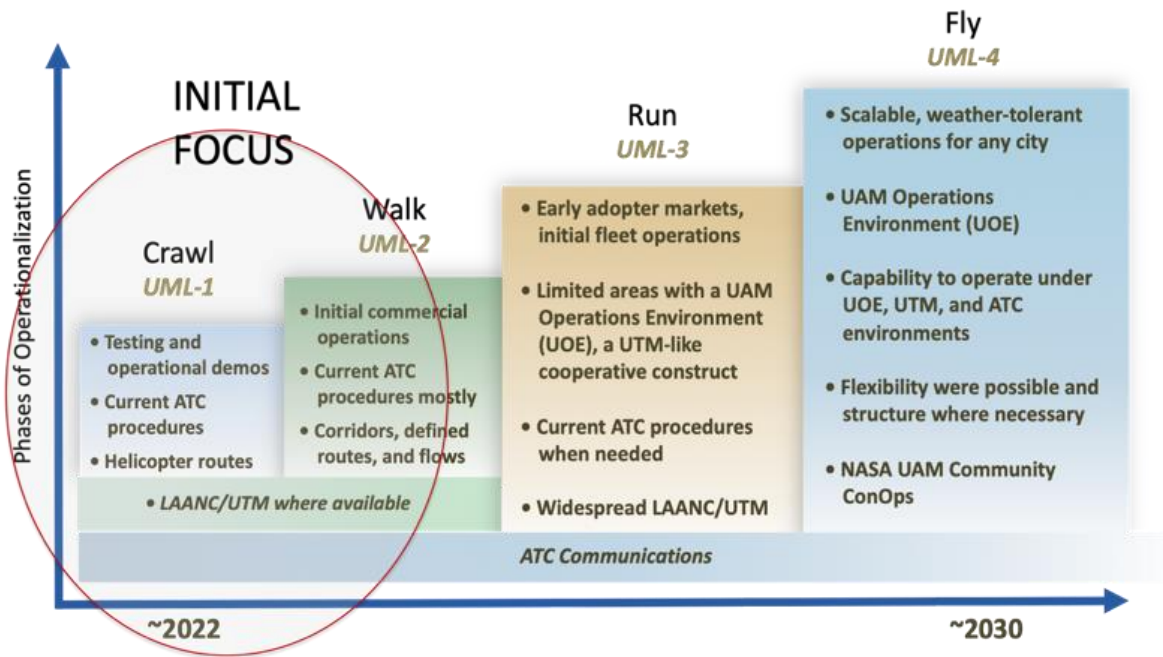
# UAM Airspace Sub-Project





# UAM Airspace Evolution

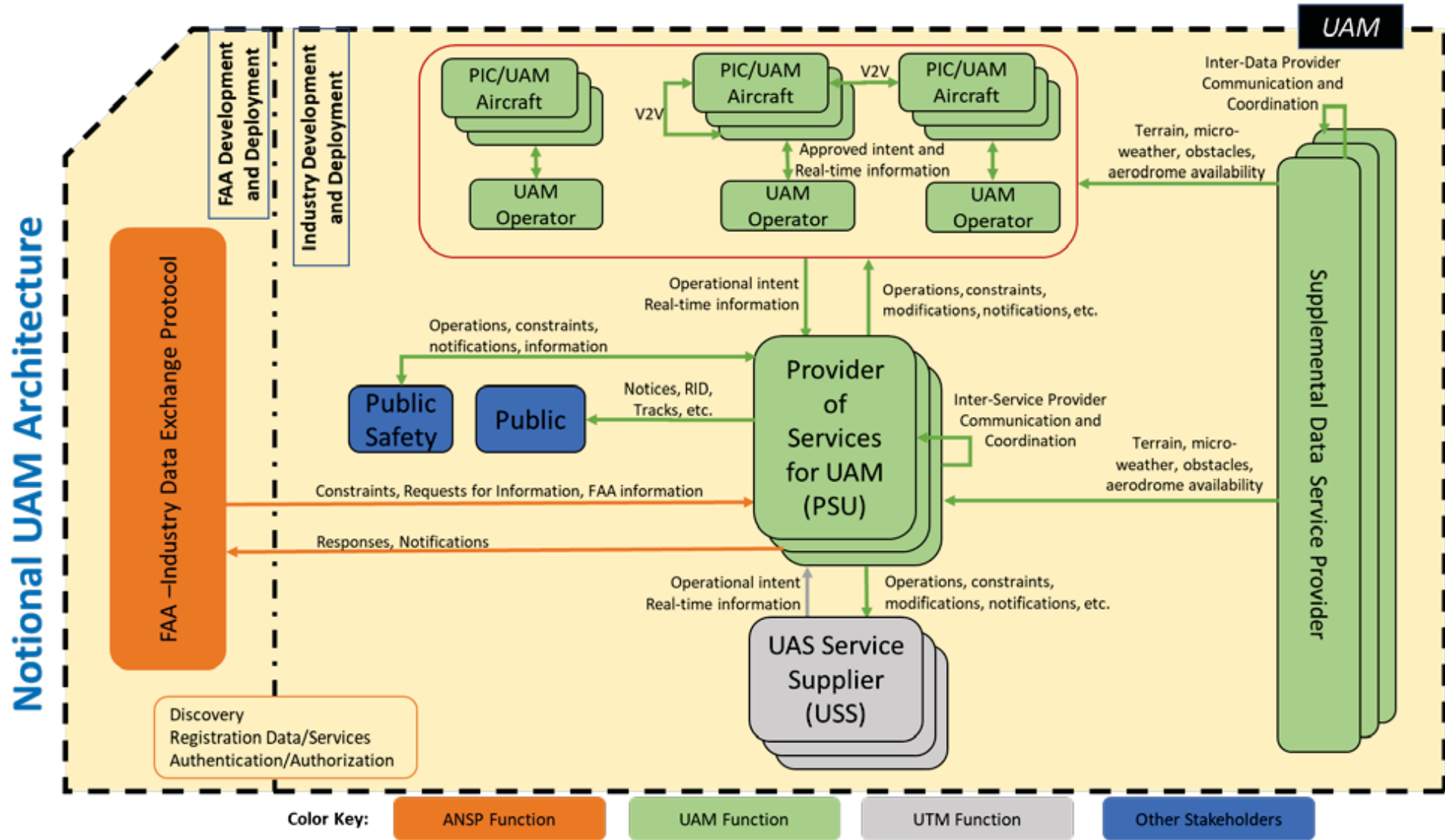
“Airspace is ready when the Vehicle is ready”



- Airspace domain has many components
- Each component *evolves* through the *UML progression*
  - Need to see how to get there from here



# Notional UAM Architecture (FAA NextGen Conops v1.0)





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**BACKUP**



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Backup Slides

# **AAM MISSION**



# AAM Mission Critical Commitment



**Vehicle Development and Operations** Develop concepts and technologies to define requirements and standards addressing key challenges such as safety, affordability, passenger acceptability, noise, automation, etc.



**Airspace Design and Operations** Develop UTM-inspired concepts and technologies to define requirements and standards addressing key challenges such as safety, access, scalability, efficiency, predictability, etc.



**Community Integration** Create robust implementation strategies that provide significant public benefits and catalyze public acceptance, local regulation, infrastructure development, insurance and legal frameworks, etc.

**Critical Commitment:**

**Based on validated operational concepts, simulations, analyses, and results from National Campaign demonstrations, the AAM Mission will deliver aircraft, airspace, and infrastructure system and architecture requirements to enable sustainable and scalable medium density advanced air mobility operations**

Achieving a “validated system architecture” will require enabling activities such as 1) the AAM National Campaign Series 2) a robust Ecosystem Partnership model and 3) NASA ARMD Portfolio Execution.

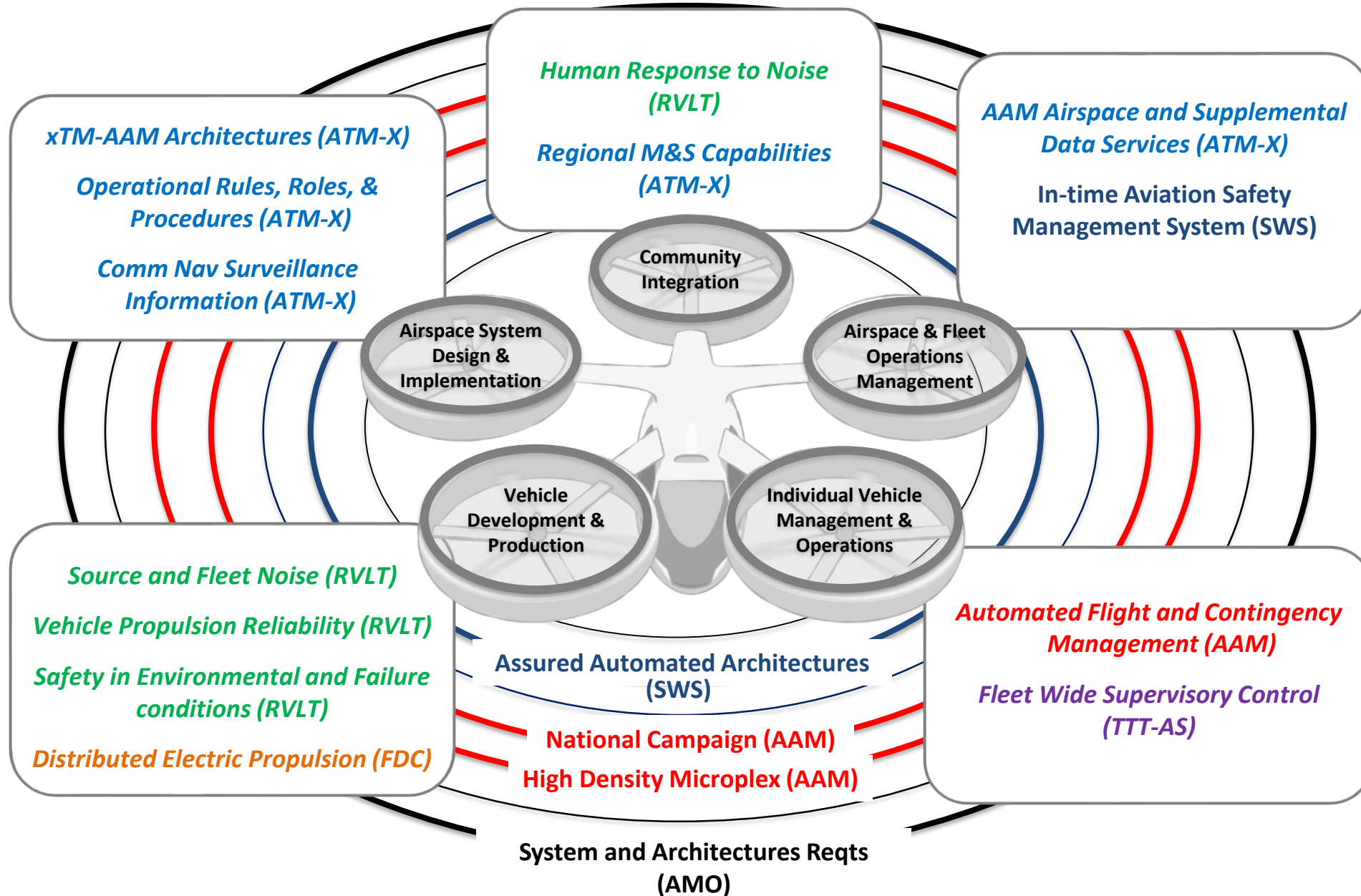




# NASA AAM Mission Priorities

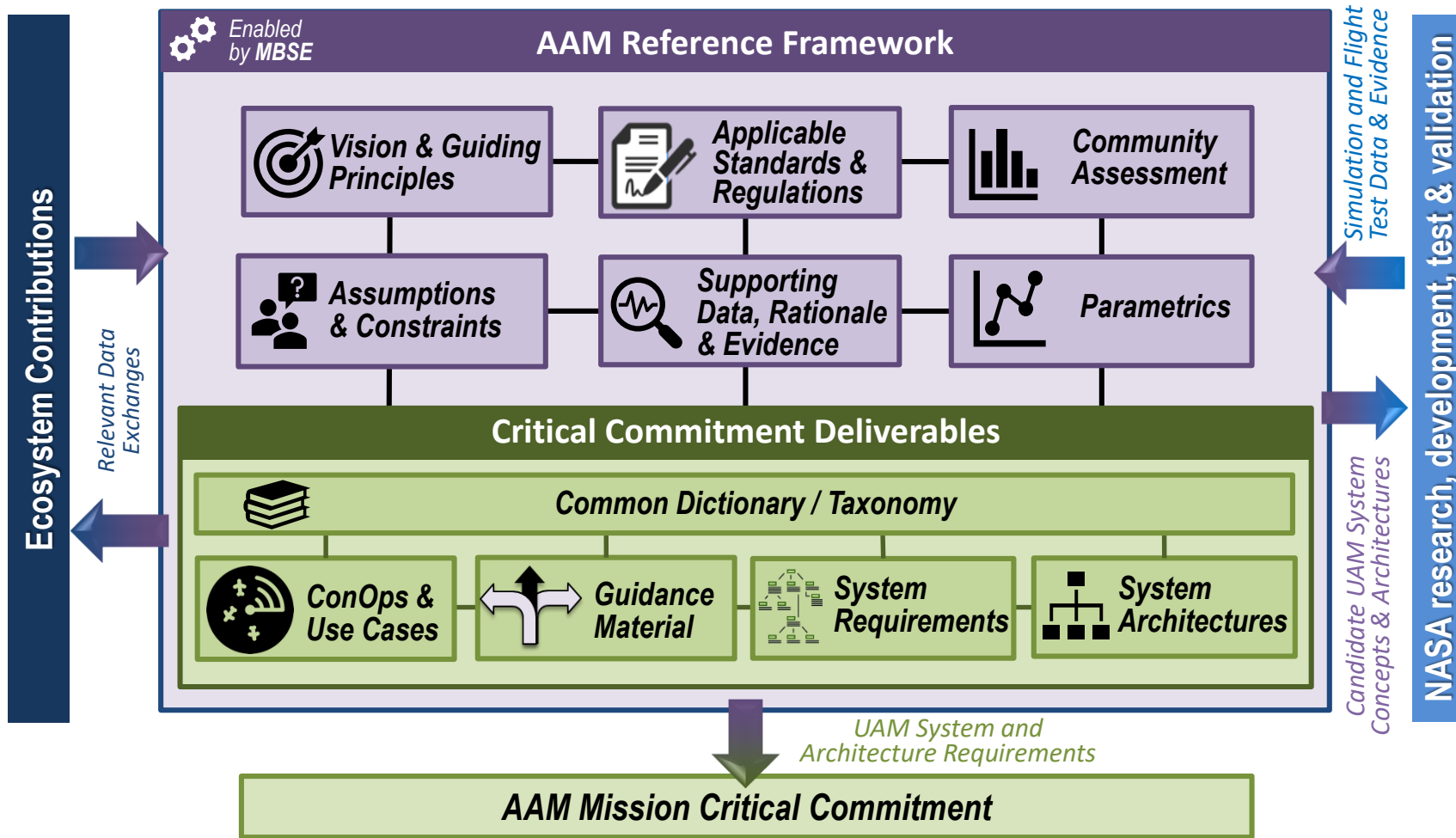
## Lead Project Legend

- AAM
- ATM-X
- RVLT
- SWS
- FDC
- TTT
- AMO





# AAM Reference Framework & Deliverables Supporting the Critical Commitment



*Collaborating with other federal/state/local governments and industry organizations across the AAM Ecosystem to develop a comprehensive set of AAM system and architecture requirements for medium density operations.*



# AAM Ecosystem Working Groups (AEWG)

Align on a common vision for AAM

Learn about NASA's research and planned transition paths

Adopt a strategy for engaging the public on AAM



Collectively identify and investigate key hurdles and associated needs

Develop AAM system and architecture requirements

Support regulatory and standards development

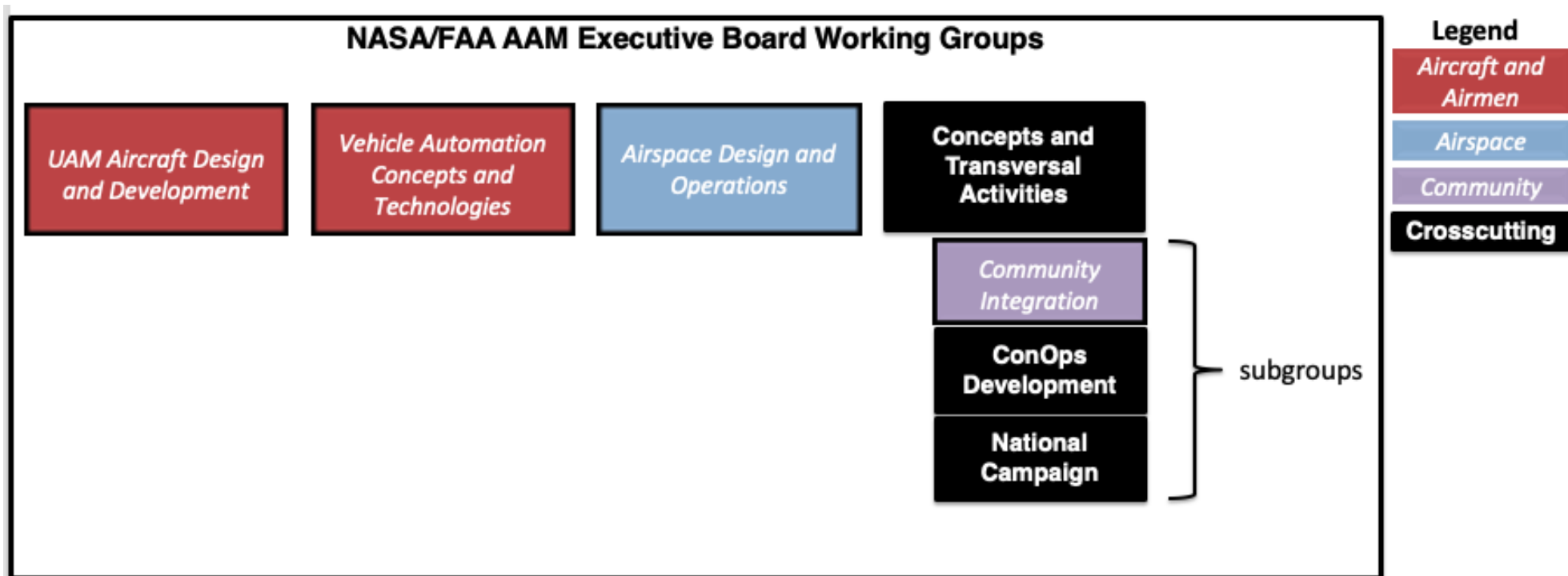
*Form a connected stakeholder community*

**Accelerate the development of safe and scalable AAM flight operations by bringing together the broad and diverse community involved in developing this new capability**



# NASA/FAA AAM WG Structure

- Executive leadership has jointly agreed to a WG structure to continue formalizing AAM planning and execution strategies
- Multiple working groups are extensions of previous collaborations
- All working groups have been through an iteration of a cross-agency planning cycle





Backup Slides

# **NATIONAL CAMPAIGN**



# AAM National Campaign (NC) Series

## Goal

Assure AAM safety and accelerate scalability through integrated demonstrations of candidate operational concepts and scenarios.

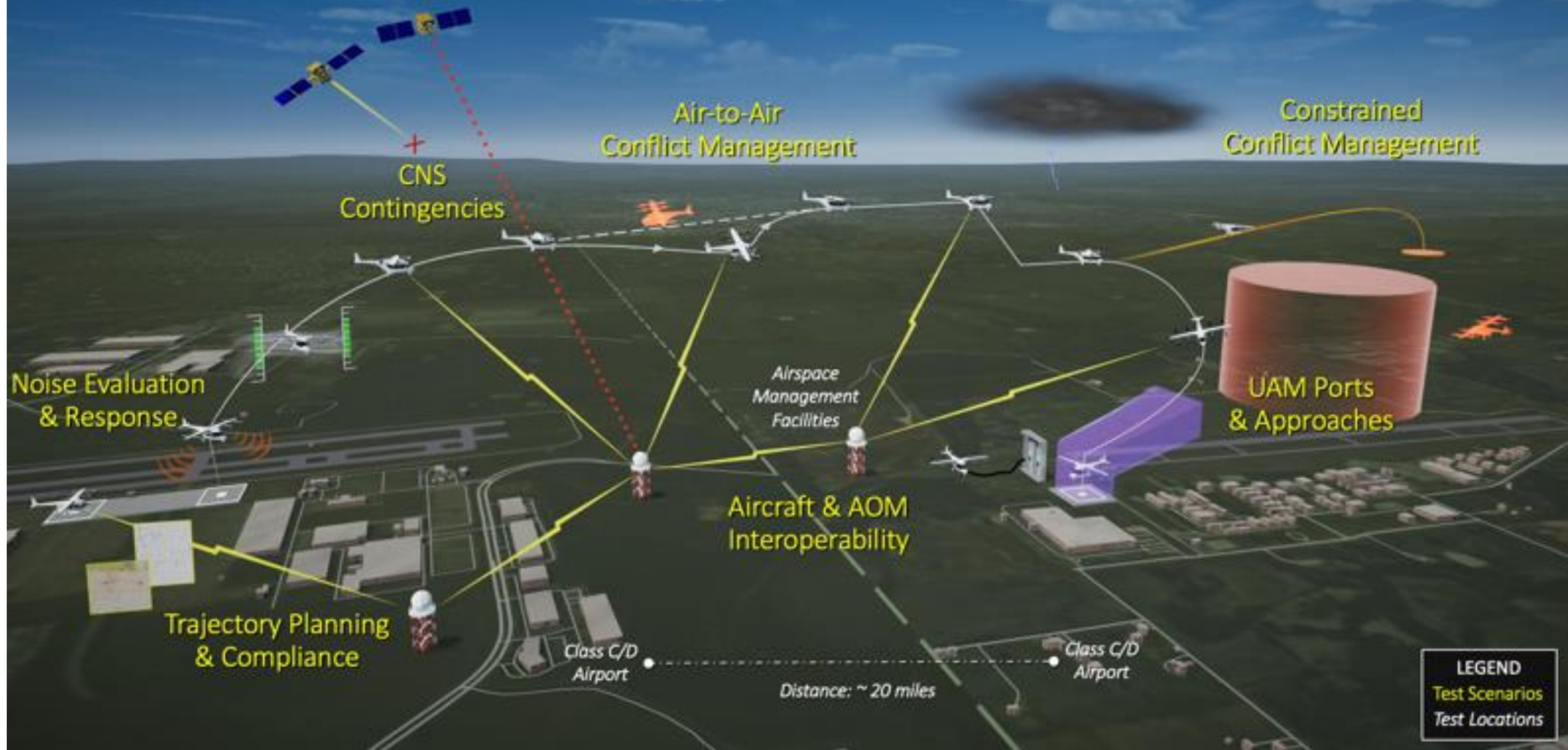
## Objectives

1. Accelerate Certification and Approval
2. Develop Flight Procedure Guidelines
3. Evaluate the CNS Trade-Space
4. Demonstrate an Airspace Operations Management (AOM) Architecture
5. Characterize Community Concerns





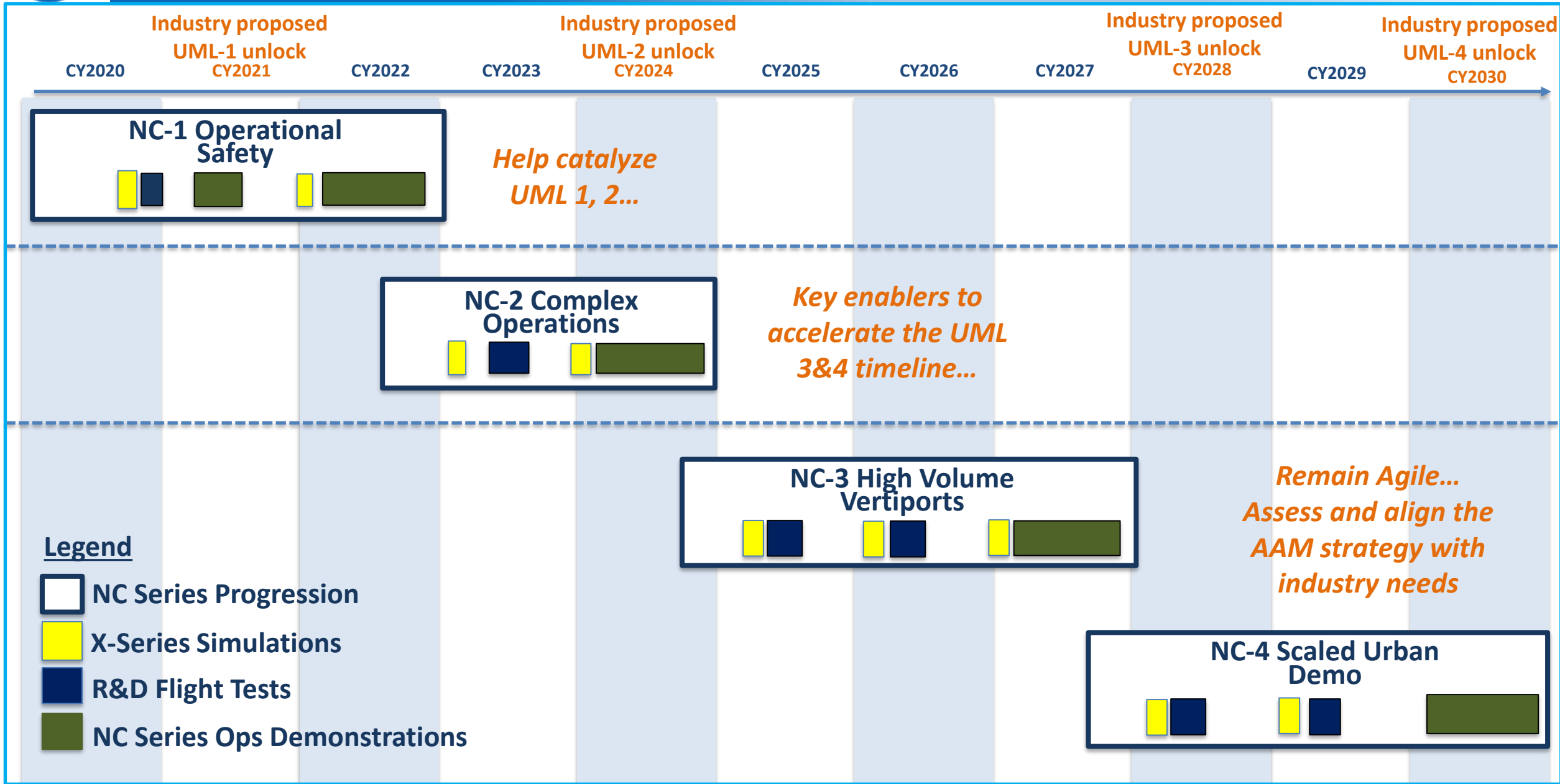
# NASA National Campaign One OV-1



**LEGEND**  
Test Scenarios  
Test Locations



# National Campaign Series support of the Industry Timeline



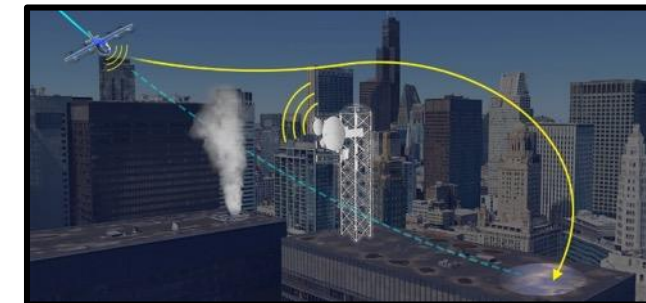
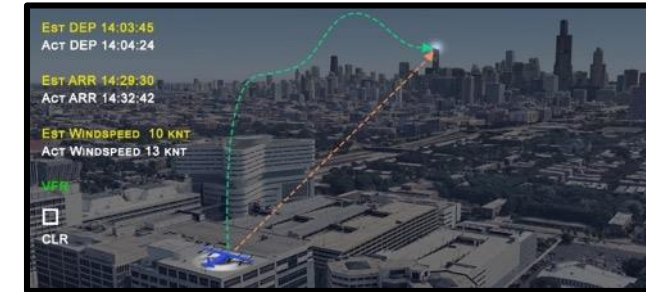
UML "unlocks" based on a range of publicly available industry projections and conversations with partners; not a consensus view





# NC DT – Scenarios 1-3

- Scenario 1: Nominal Integrated Flight Operations
  - Nominal flight planning for a flight with no activated contingencies
    - Flight planning, route negotiation and acceptance, route and time conformance
    - Simulated background traffic to study impacts on timing
- Scenario 2: Integrated Flight Operations with an Activated Contingency
  - Nominal point-to-point route, then a temporary flight restriction (TFR) requires the vehicle to re-route while en route
  - Leveraging airspace test infrastructure based on a UTM construct for initial flight plan submission and test re-route from the airspace perspective
- Scenario 3: Terminal Operations and Approach/Landing Contingencies
  - 3a: Airspace initiates the contingency; go-around, loiter, and land at original site
  - 3b: Vehicle initiates the contingency; balked landing and divert to an alternate site
  - 3c: Vehicle initiates the contingency; vehicle executes a go-around, requests immediate landing, and ATC works vehicle into simulated traffic to land on an active runway



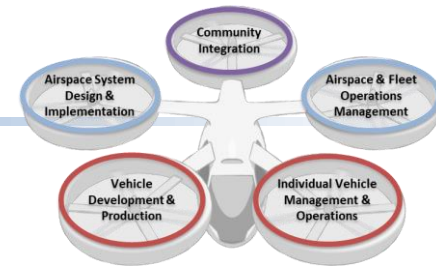


Backup Slides

# **RESEARCH, DEVELOPMENT, TEST & EVALUATION CAPABILITIES**



# NASA AAM Facilities and Capabilities



Airspace Operations Lab



Cockpit Motion Facility



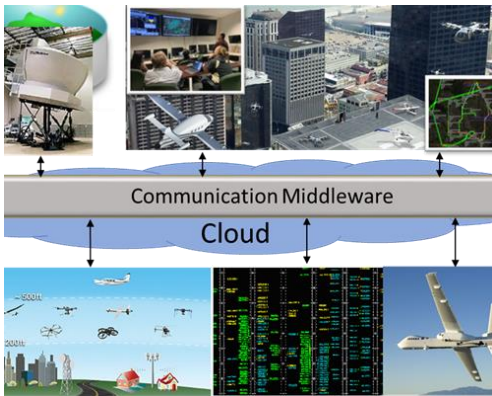
Developmental UAM Simulator - Flyer



Vertical Motion Simulator



Mobile Operations Facility



Testbed Virtual Infrastructure



Air Traffic Operations Lab



Future Flight Central



Cognitive Engineering Lab

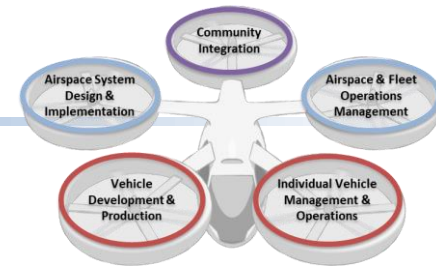


Research Flight Deck

\* This list of capabilities is a notional first cut and we are still in formulation, we have not yet assessed all the requirements or made commitments for each capability.



# NASA AAM Facilities and Capabilities Cont.



Ames UAM Lab



Mobile Acoustics Facility



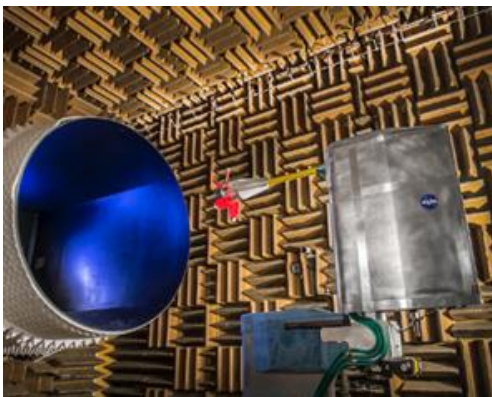
Icing Research



X-57 Maxwell



Exterior Effects Room



Low Speed Aeroacoustic Wind Tunnel



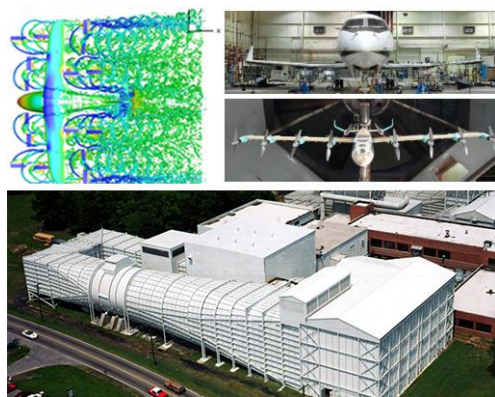
CERTAIN Range



Landing and Impact Research Facility



Dryden Aeronautical Test Range



Many others including wind tunnels, aircraft, ranges, cockpit sims, supercomputers, etc.

\* This list of capabilities is a notional first cut and we are still in formulation, we have not yet assessed all the requirements or made commitments for each capability.



# Strong Domestic eVTOL Industry Base



■ Bell

[ Not Flown ]



■ Beta



■ Boeing/Aurora



■ Elroy Air



■ Joby



■ Jaunt Air

[ Not Flown ]



■ Kitty Hawk



■ Wisk



■ Workhorse/Moog