



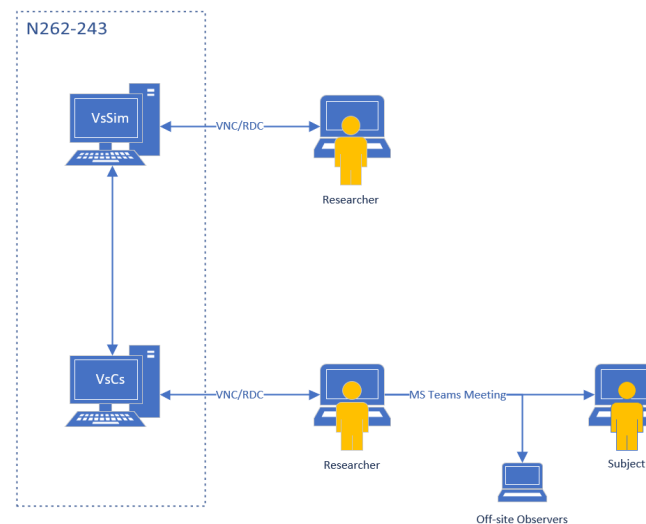
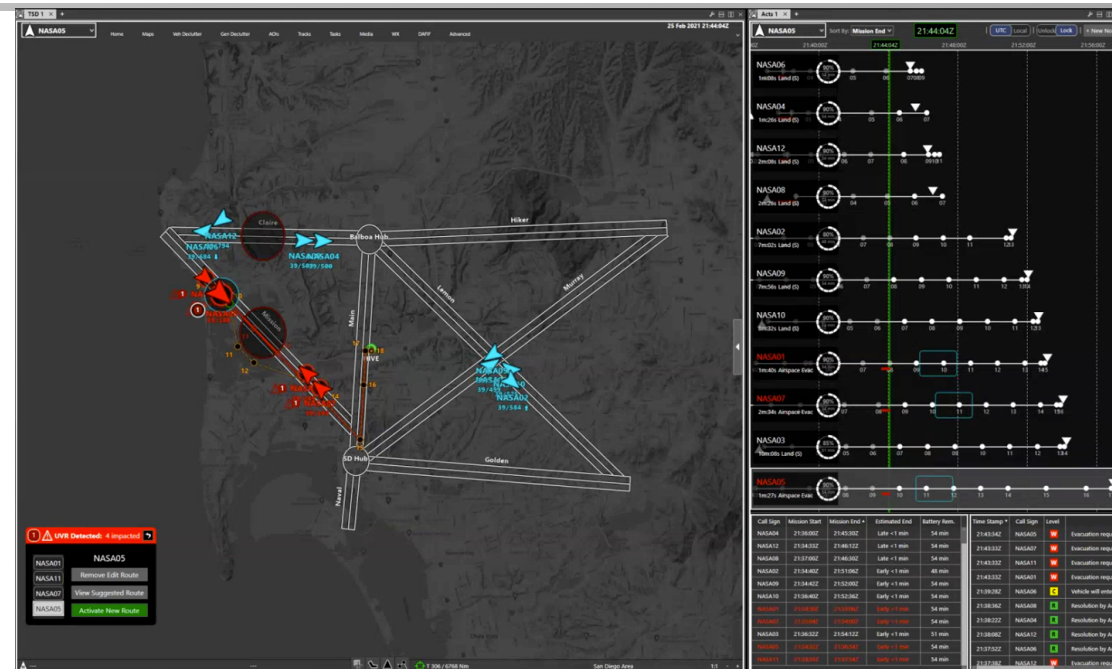
m:N ConOps/R&R Remote Simulation

Friday, March 26, 2021

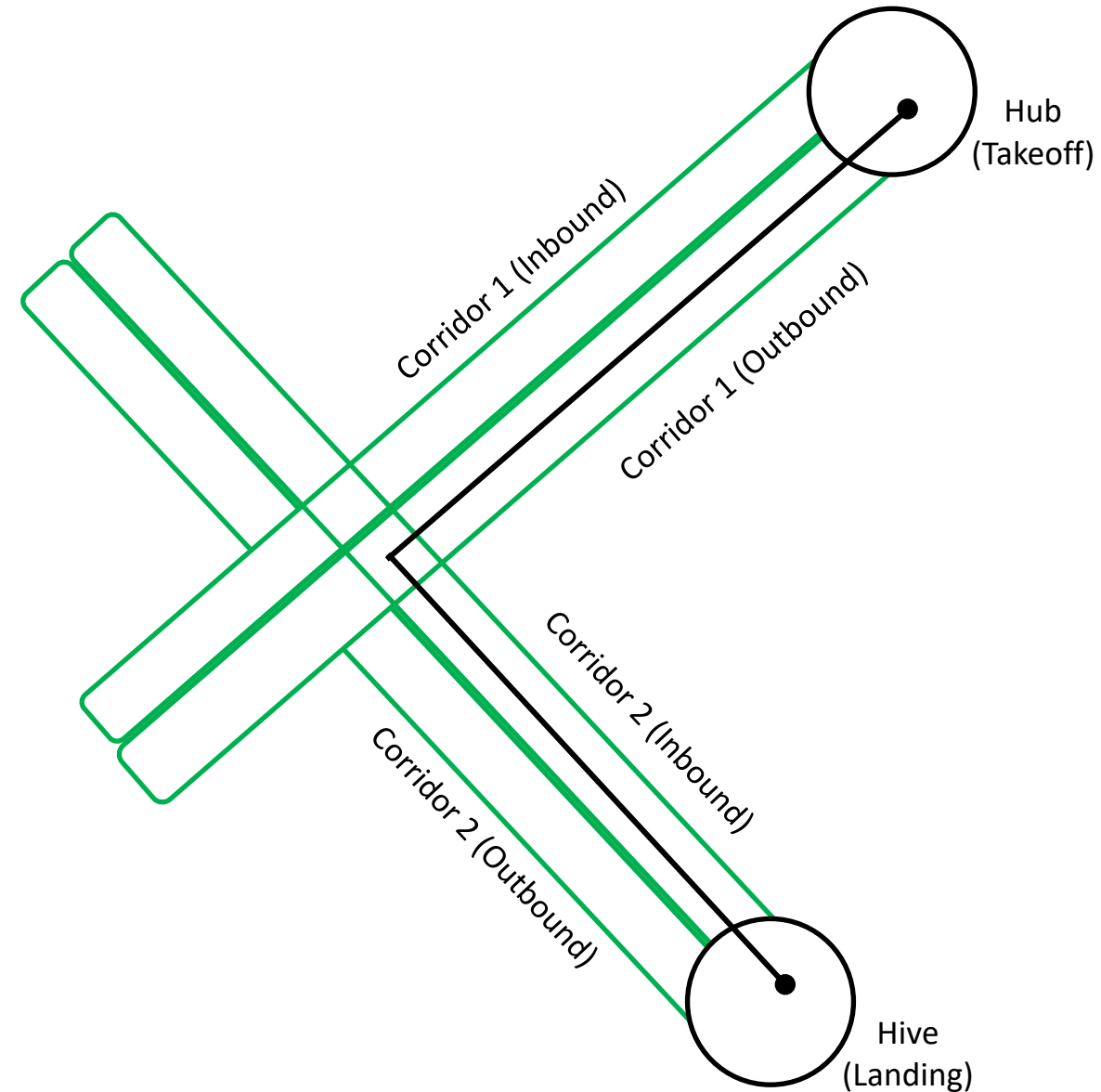
Garrett Sadler



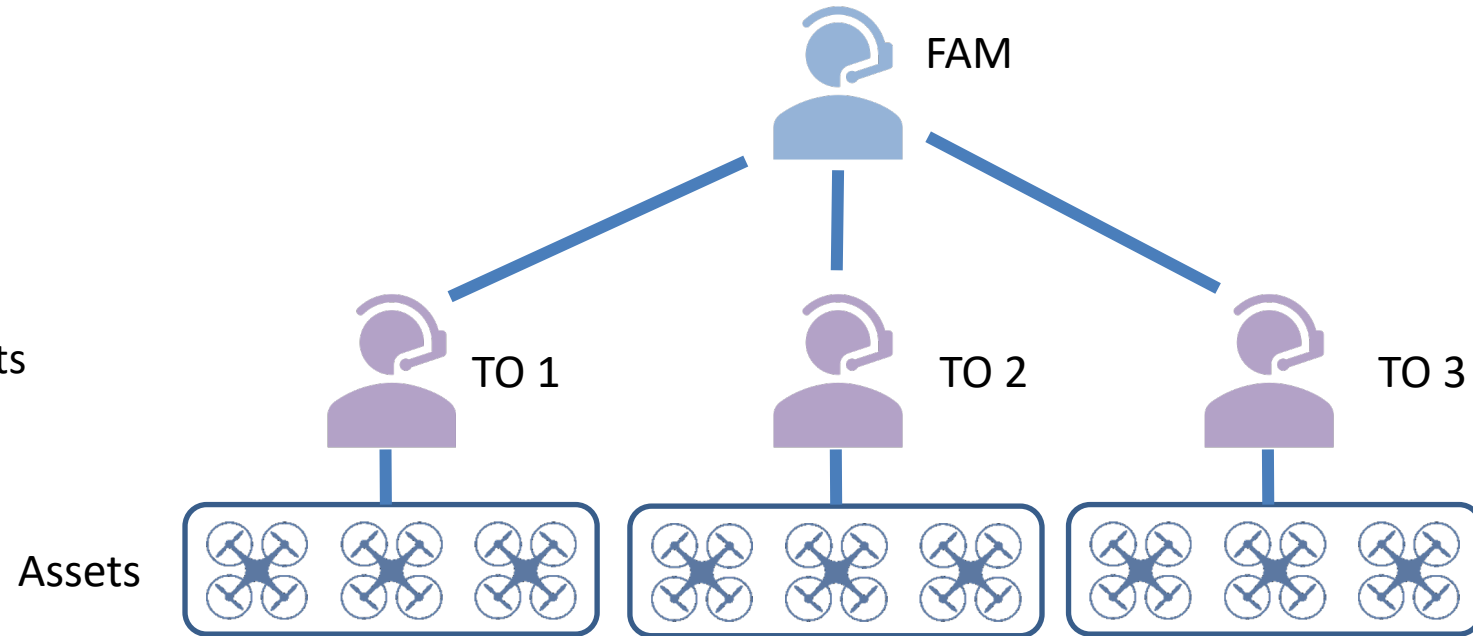
- NASA's Transformational Tools and Technologies (TTT) project seeks state-of-the-art tools and technologies necessary to meet the Aeronautics Research Mission Directorate's (ARMD) strategic needs such as the understanding of innovative control techniques and experimental methods.
- The Human-Autonomy Teaming (HAT) Laboratory is engaged in research to evaluate a concept of operations (ConOps), the roles and responsibilities (R&Rs) of key personnel and ground control station (GCS) displays and interfaces for m:N operations.
- HAT Lab developed a remote data collection procedure that utilized a verbal communication protocol and "subject-surrogate." Data was collected in February and March 2021.



- Food /small package delivery using a fleet of small UAS in San Diego, CA.
- Aircraft follow corridors developed in a simulated Authorized Area of Operation
 - Simulation used a “canned” UAS Service Supplier (USS)
- Each aircraft is remotely monitored by ground operators, and each operator is responsible for multiple aircraft simultaneously.
- Key personnel: the **Tactical Operator (TO)** and Fleet Area Manager (FAM)



- m:N Paradigm
 - Multiple operators managing multiple vehicles, where:
 - m = # of operators
 - N = # of vehicles
- Roles in m:N operations:
 - Tactical Operator (TO)
 - Pilot-in-Command (PIC) of multiple assets
 - Monitors airspace and hazards
 - Attends to assets
 - **Participant's role** in the study
 - Fleet Area Manager (FAM)
 - Responsible for overseeing a select number of TOs in a specific area
 - Monitors fleet health, monitors system health
 - Evaluates TO performance and workload online
 - Played by researcher confederate

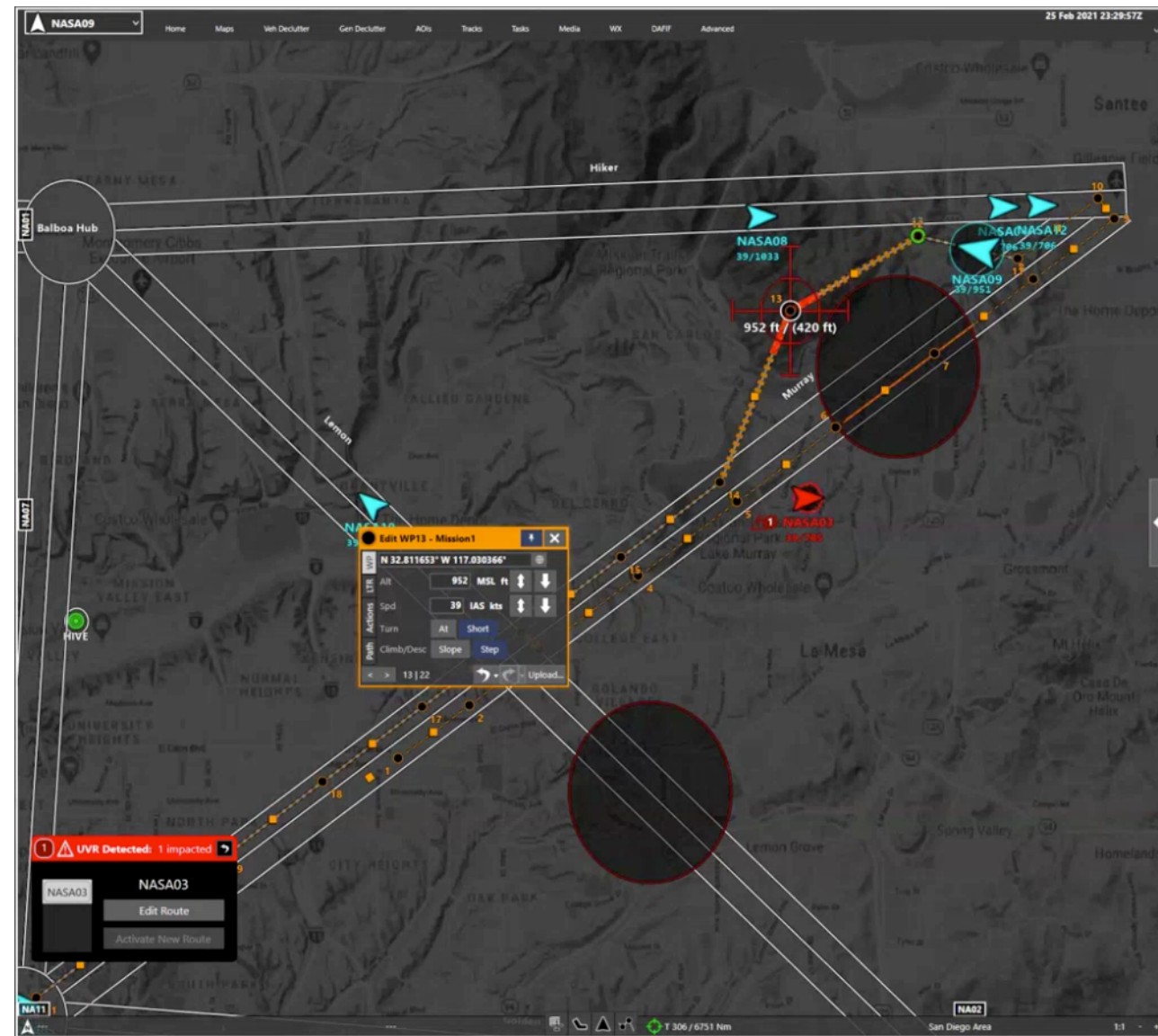


- Goal:

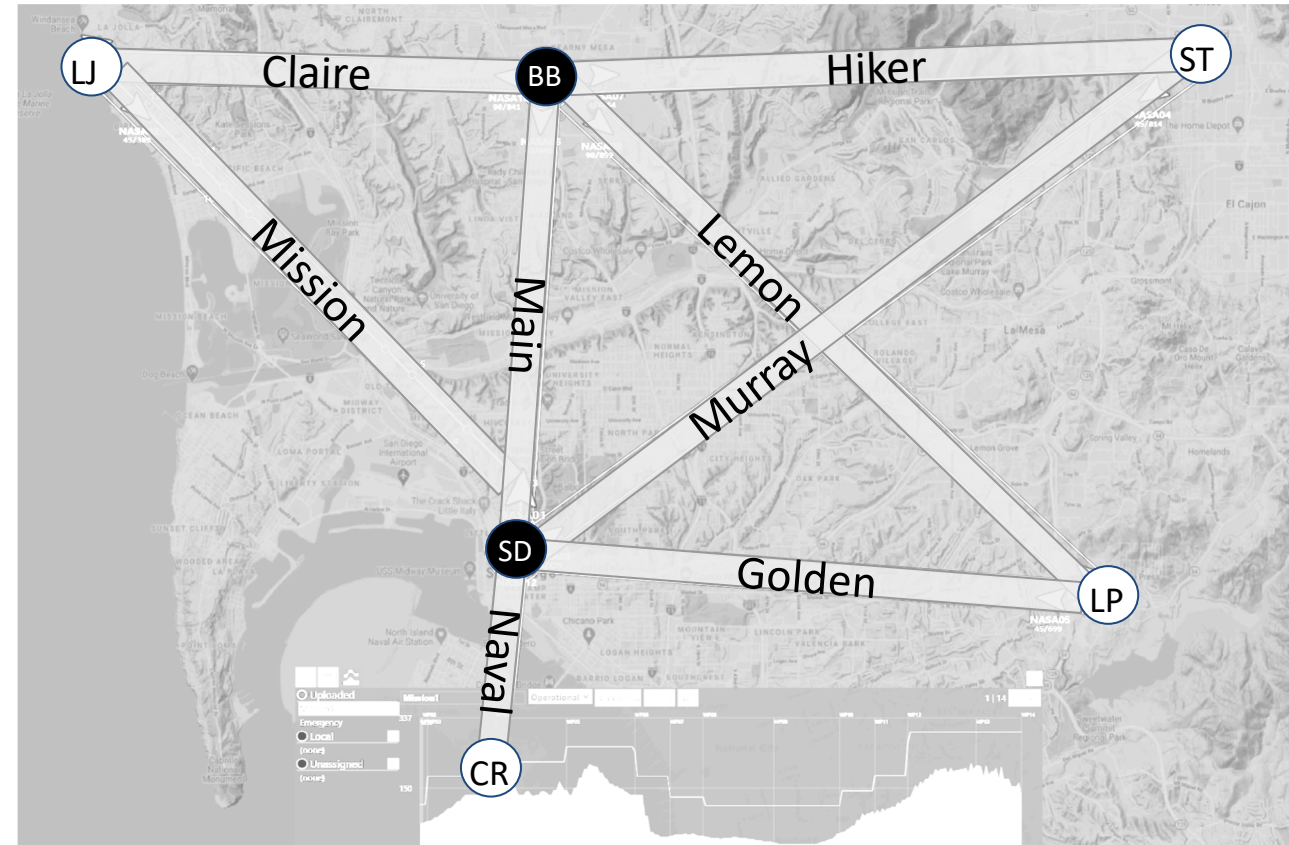
- Test and evaluate feasibility of ConOps, roles and responsibilities of the TO
- Examine meaningful human control under conditions of
 - Elevated workload
 - Varying automation support
- Gather feedback on how best to manage:
 - Hand-offs between tactical operators and/or the fleet manager (e.g., excessive workload, phase of flight)
 - Potential human-autonomy teaming tools (i.e., ‘plays’) that could alleviate workload strains while still keeping pilot informed
- Demonstrate subject-surrogate simulation configuration
- Evaluate the HAT Lab m:N GCS

- Research Question

- To what degree does the presence of automation improve performance?
 - What is the impact or size of the effect as a function of workload and automation support?
- Will the TO be able to maintain MHC under a ‘moderate’ vehicle load of 12 UAs?

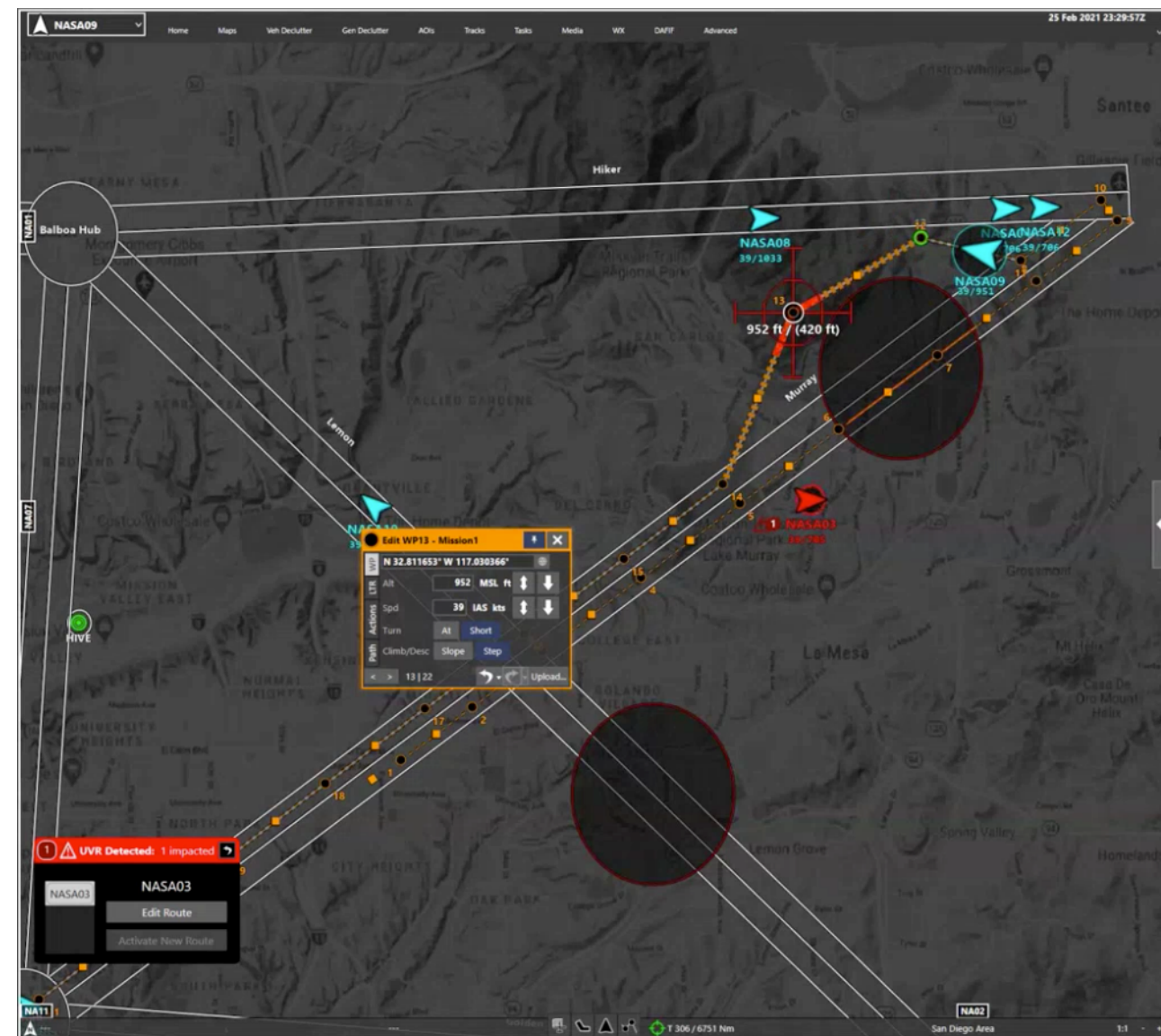


- Participants (sUAS Part 107 pilots)
 - 4 pretest subjects
 - 12 data collection subjects
- Experimental Trials
 - 4 experimental trails per pilot
 - ~15-minute trial duration
 - Simulate 1:12 delivery operations
 - San Diego area
 - 8 pre-authorized corridors
 - 1 Hive
 - 2 Restaurant Hubs
 - 4 delivery sites
 - Participant Tactical Operator
 - Maintain safety and conformance for aircraft under control/supervision
 - Resolve scripted contingency (1/scenario)
 - UVR requiring replanning for multiple UAs
 - Researcher will played role of the Fleet Area Manager

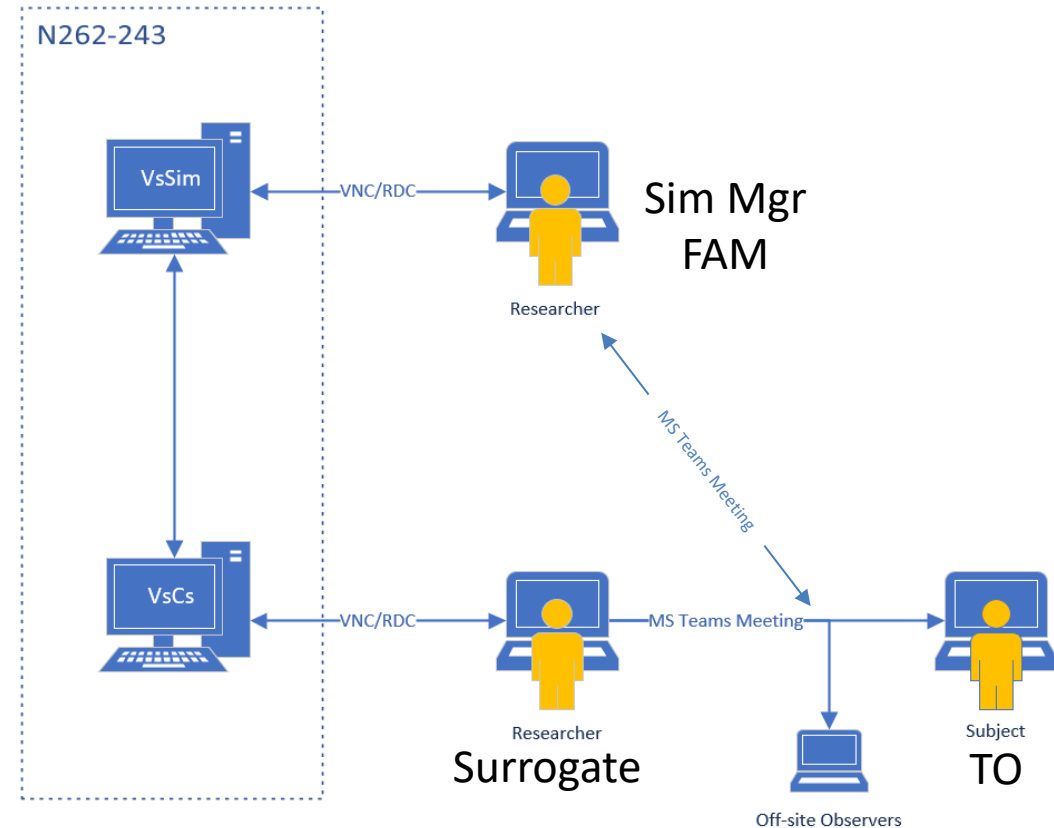


Simulation Area and Corridors

- Each participant, as the TO, monitored 12 assets on delivery missions in San Diego, CA.
- Participants responded to sudden, high-priority contingency events in the form of UAS Volume Reservations (UVRs, 2 per trial)
- Upon issuance of a UVR, pilots were responsible for rerouting affected aircraft around the restricted airspace
 - Automation support and workload were manipulated
 - Some vehicles required special considerations for terrain as part of the reroute
- Participants performed actions through coordination with the subject-surrogate
- Throughout trials, participants communicated with a FAM (played by researcher) who queried TOs with secondary tasks



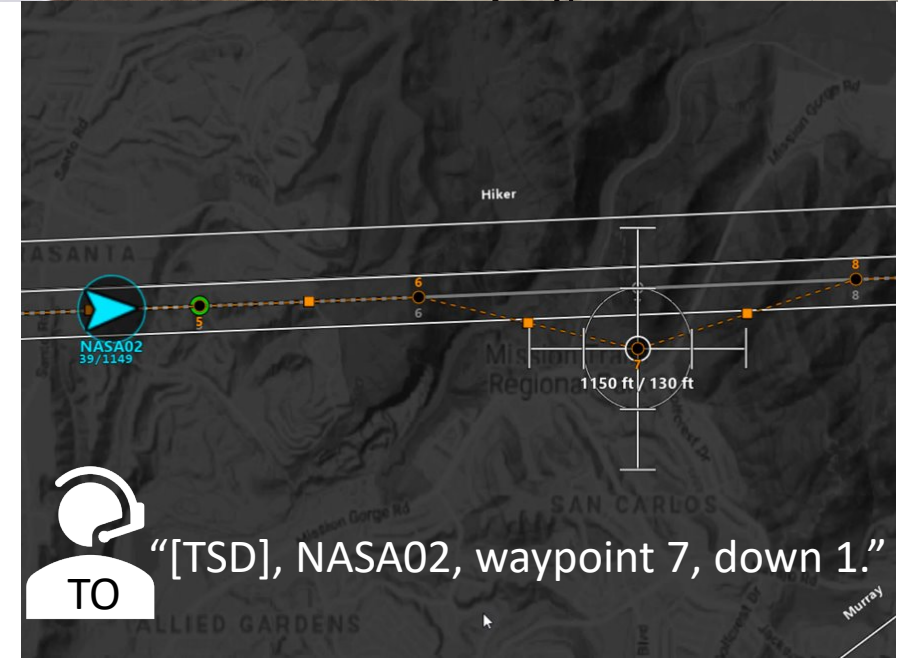
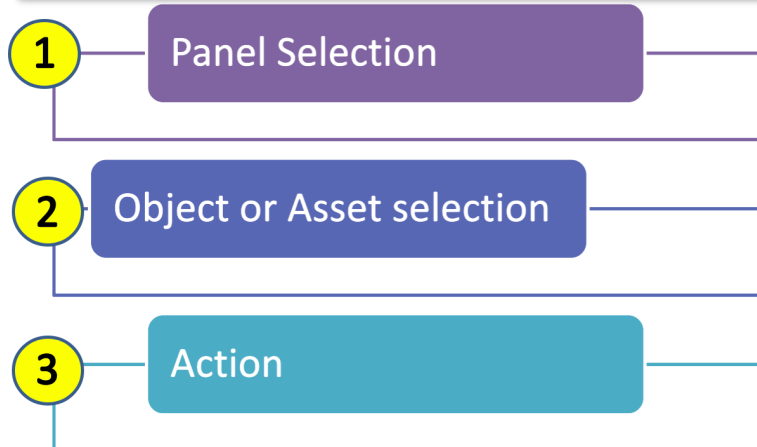
- **Access restricted due to COVID-19**
 - All participation (subjects/staff) was remote
- Cybersecurity policies prevented external control of GCS by participants
- Remote researcher connections:
 - Simulation Manager & FAM remote connection Vigilant Spirit Sim, Teams
 - Subject-Surrogate remote connection to Vigilant Spirit Control Station, Teams
 - Teams Broadcast for observers
- Remote subject on Teams conveys actions to Subject-Surrogate using verbal protocol



- Simulation managed, executed by remote researchers
- Subjects convey actions through the Subject- Surrogate
 - Surrogate controls GCS
 - Shared vocabulary for verbal instructions



Verbal Protocol Interaction Localization Workflow



- Objective Metrics
 - Time to resolve UVR conflicts
 - Time to resolve terrain conflicts
 - Number of UVR violations
 - Number of terrain collisions
 - Path efficiency of rerouted vehicles
- Subjective Metrics
 - Subjective performance ratings
 - Ability to manage vehicles
 - Ability to minimize impact of UVR
 - Interface ratings
 - Workload (NASA TLX)
 - Meaningful human control ratings
- Methodological impacts of remote/surrogate study
 - Connection lag/latency
 - Participant display size
 - Surrogate workload (NASA TLX)
 - “Messy” surrogate interactions
 - Miscommunications/stepped on comms
 - Departures from verbal protocol
 - UI/surrogate fumbles
 - Participant qualitative feedback on remote data collection, surrogate design
- Plan to brief results at next Multi-Vehicle Control (m:N) WG meeting!



Thanks!



Questions?

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