

Talk for the T&E group

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Robust Software Engineering Tech Area

RSE/Ames intro

- **CAST: Core Avionics and Software Technologies**

- cFS/cFE based FSW
- Model-based development
- Swarm simulation
- Small spacecraft swarm
- FSW Monitoring & Review

- **STMD**

- LCROSS, LADEE
- BioSentinel
- Starling, CASAS, DSA
- RP, VIPER

- **ASSET: Automated Software & System Engineering Technologies**

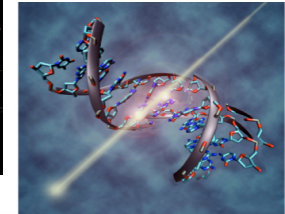
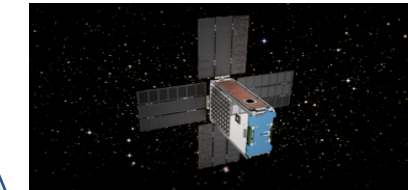
- Formal methods
 - Requirement Elicitation/Analysis
 - Design Model Analysis
 - Static Code Analysis
 - Run-Time Analysis
- Adaptive stress testing
- Assurance Cases
- Machine learning V&V

- **ARMD**

- AOSP: System-Wide Safety
 - Aviation software assurance
 - Autonomous systems assurance
- AAM: Automated Flight and Contingency Management
- Low Boom Flight Demonstrator

- **Others**

- Gateway contractors V&V
- BlueOrigin: ROS 2 V&V
- DoD Autonomous Systems T&E



- **Traditional Aviation**

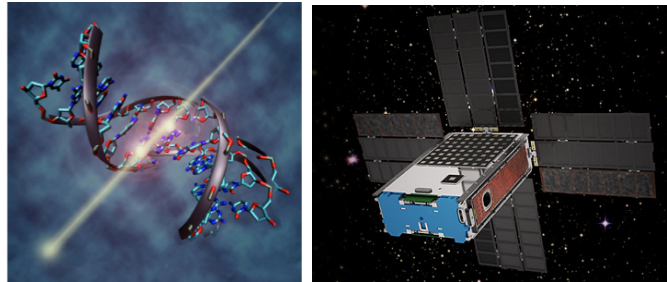
- US Airframers, OEMs, Airlines
- FAA, NTSB
- AFRL

- **Emerging Markets**

- Urban Air Mobility
- Plant inspection, disaster response, precision agriculture, USGS

V&V for Traditional Systems

- Motivation for funding:
faster and cheaper
Aviation certification
through V&V earlier in
the lifecycle
 - Focus on flight software



- Applications in our own group
working on flight software for small
spacecraft
 - Using a model-based, agile process
 - Streamline cost

- Tried it out when “auditing”
defense contractors
 - Reluctance to using new
methods



V&V for certification

- Motivation for funding:
faster and cheaper
Aviation certification
through V&V earlier in
the lifecycle
 - Focus on flight software



DO-178C

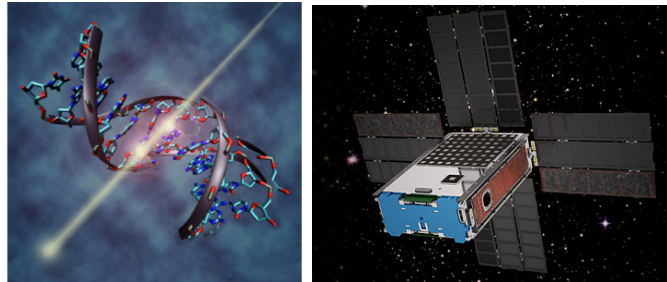
DO-333

- Current standard
for getting software
certification credits
 - Traceability
throughout
 - Track, record, and
document
- Formal methods
supplement:
 - Model checking
 - Abstract
interpretation
 - ...

V&V for certification

NPR-7150.2c

NASA-STD-8379.8a

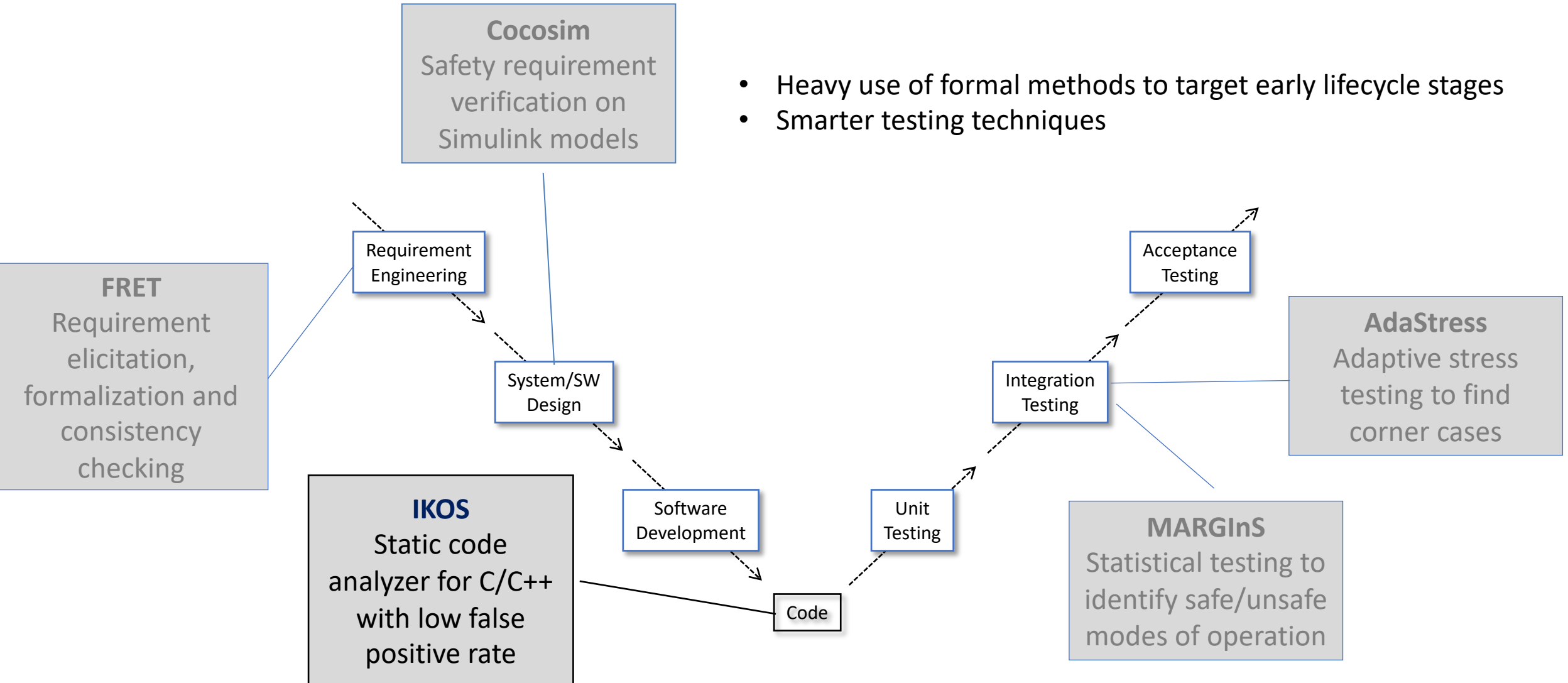


- Applications in our own group working on flight software for small spacecraft
 - Using a model-based, agile process
 - Streamline cost

- Current standard for getting software certification credits
 - Traceability throughout
 - Track, record, and document
- Analysis available as a V&V means
 - Model checking
 - Abstract interpretation
 - ...

V&V Strategy

- Heavy use of formal methods to target early lifecycle stages
- Smarter testing techniques



FRET at a Glance

Requirement ID	Parent Requirement ID	Project
FSM-001		LM_requirements

Rationale

Exceeding sensor limits shall latch an autopilot pullup when the pilot is not in control (not standby) and the system is supported without failures (not apfail).

Requirement Description

A requirement follows the sentence structure displayed below, where fields are optional unless indicated with "*". For information on a field format, click on its corresponding bubble.

SCOPE

CONDITIONS

COMPONENT*

SHALL*

TIMING

RESPONSES*

FSM shall always satisfy (limits & autopilot) => pullup

user types requirement

parser recognizes fields and color codes them dynamically

SEMANTICS

Semantics

Always, the component "*FSM*" shall satisfy $((limits \ \& \ autopilot) \Rightarrow pullup)$.

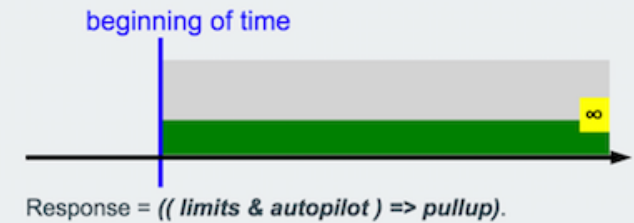


Diagram Semantics

Formalizations

Future Time LTL

$G \ ((limits \ \& \ autopilot) \Rightarrow pullup)$

Target: *FSM* component.

Past Time LTL

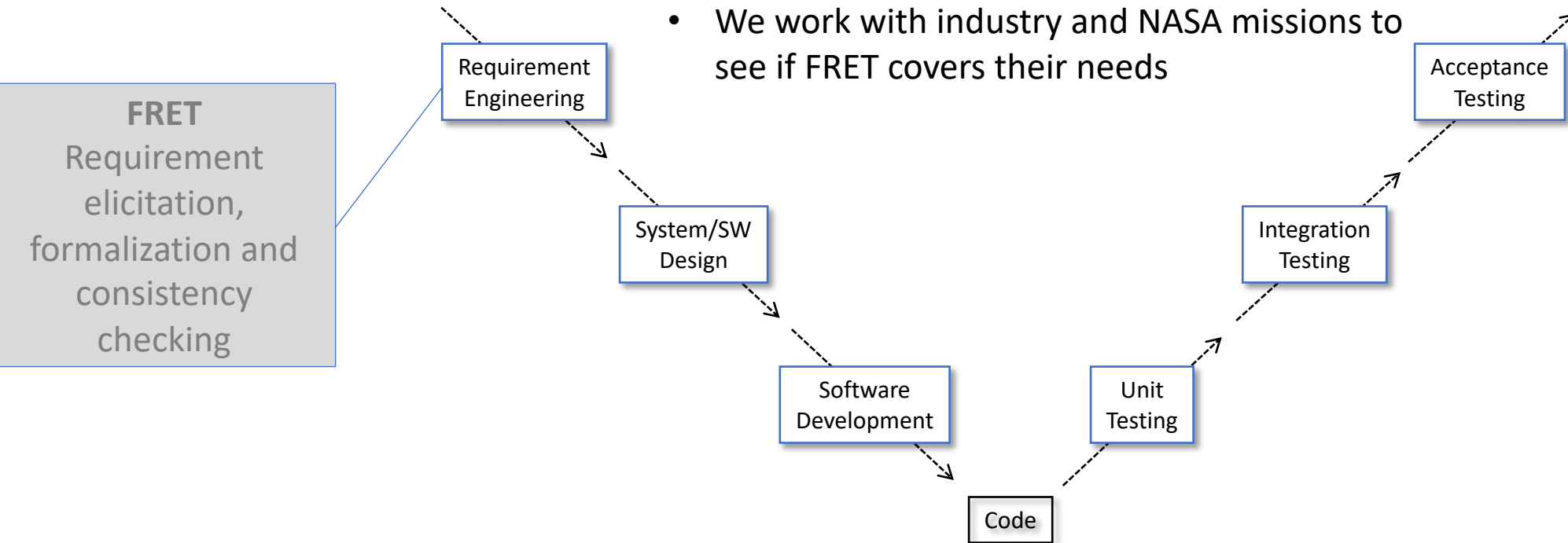
$((limits \ \& \ autopilot) \Rightarrow pullup) \ S \ (((limits \ \& \ autopilot) \Rightarrow pullup) \ \& \ FTP)$

Target: *FSM* component.

FRET
generates
formal
semantics

Lessons Learned: FRET

- Going from natural English to formal logic is hard
 - FRET uses English patterns/modes
- Having enough patterns to cover most requirements possible is hard
 - We work with industry and NASA missions to see if FRET covers their needs

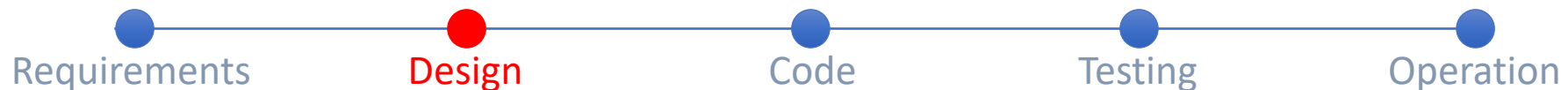


CoCoSim at a glance

- Integrated verification framework for Simulink models
- Fully automated analysis framework
- Shown effective in avionics applications

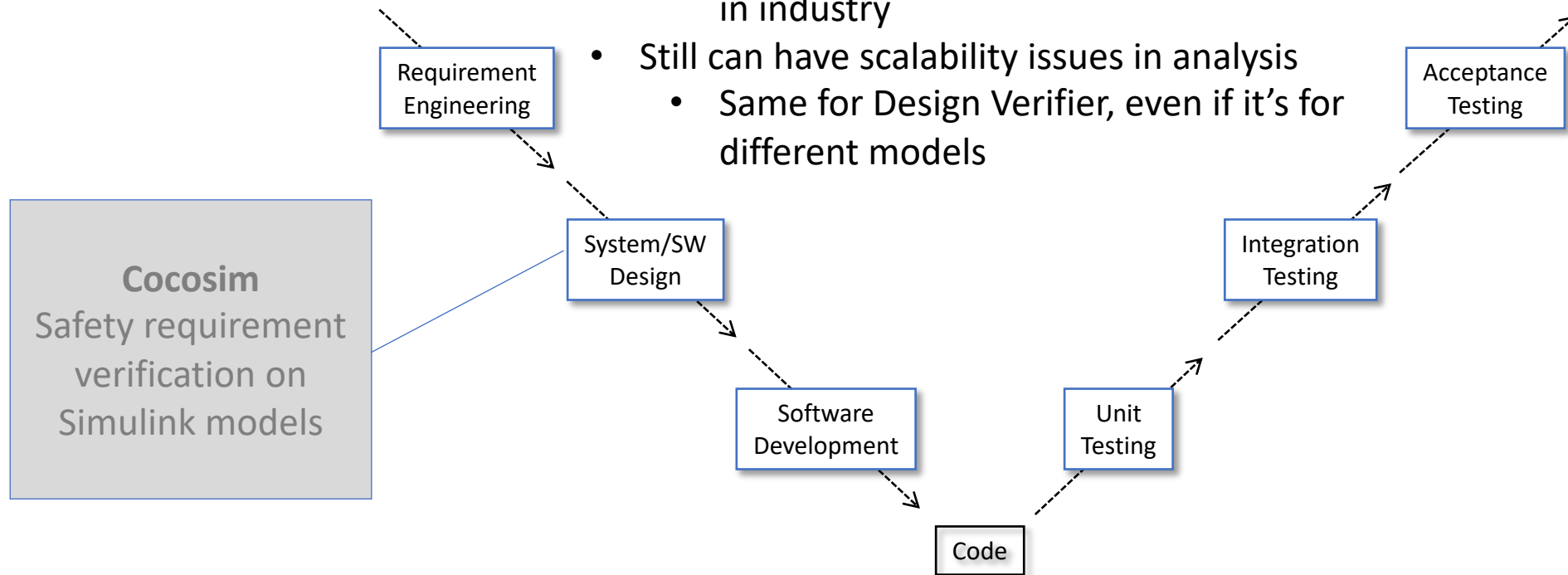
Limitations and future work

- Currently supports a subset of Simulink models described here <https://github.com/coco-team/cocoSim>
- Uses Z3 constraint solver – plan to integrate other solvers to extend the constraints that can be handled, for example trigonometric constraints
- Does support Stateflow but not embedded matlab



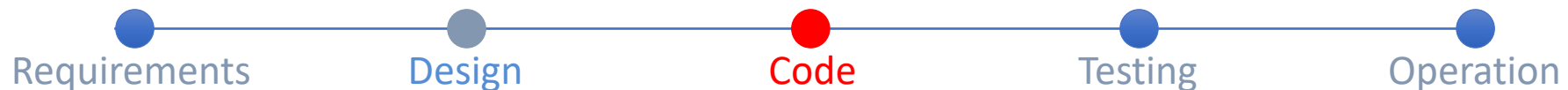
Lessons Learned: CoCoSim

- Formalizing properties is hard but we solved the problem by coupling with FRET.
- Covering all possible Simulink block is impossible
 - We are falling short of covering all blocks used in industry
- Still can have scalability issues in analysis
 - Same for Design Verifier, even if it's for different models



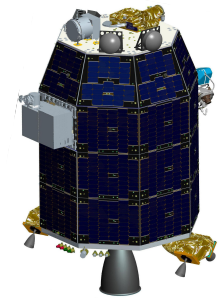
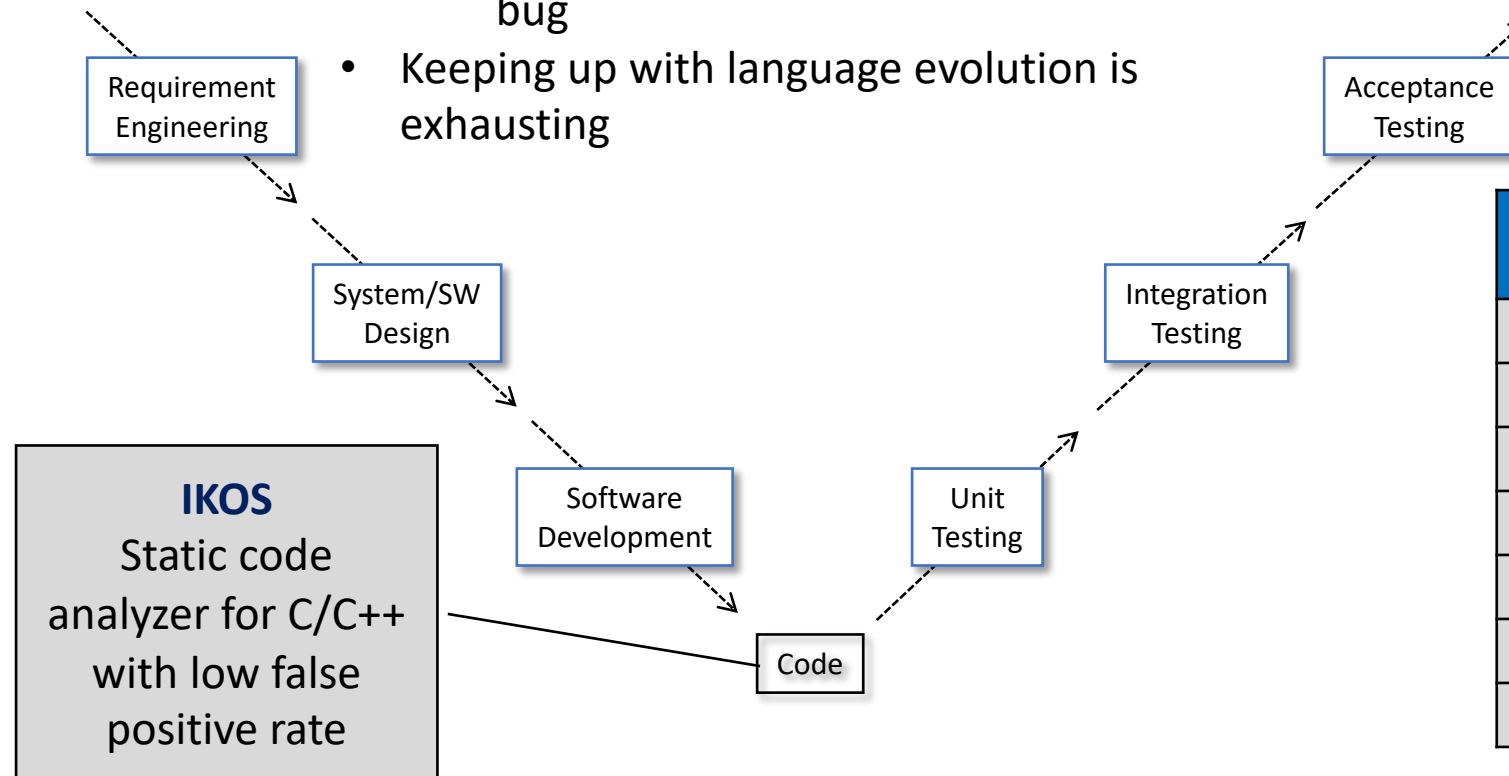
IKOS at a Glance

- Analyzes C code and C++ code
 - using the LLVM frontend
 - limited support for C++
- The code does not need to execute:
 - Libraries are not required, but knowledge on the environment and libraries is needed on a per case basis
- Available analyses:
 - Buffer overflow errors, Division by Zero, null pointer de-references, use of uninitialized variables
- No size restriction, but so far applied to 500 KLOC max



Lessons Learned: IKOS

- IKOS works/scales better for C than C++
- Possible to achieve less than 1% warnings
- Some users won't believe the results
 - Need better explanations on why a bug is a bug
- Keeping up with language evolution is exhausting



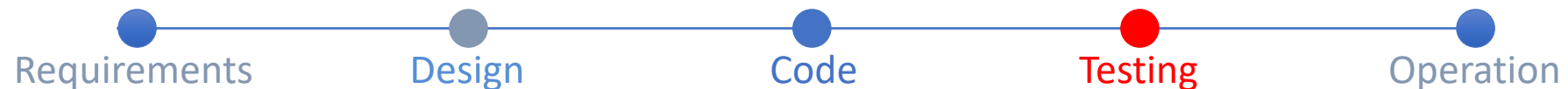
Module	Analysis Time	Precision
ACS	37mn	97%
ACT	35mn	99%
BCS	108mn	97%
CMP	89mn	99%
HIO	7mn	98%
SMC	37mn	98%
TCS	103mn	99%

MARGInS at a Glance

- Is an advanced test generation and test analysis toolset
- Implemented in MATLAB, C, and R – also runs in Octave
- Used for large and small scale space applications (Pad Abort, EFT-1, LADEE)

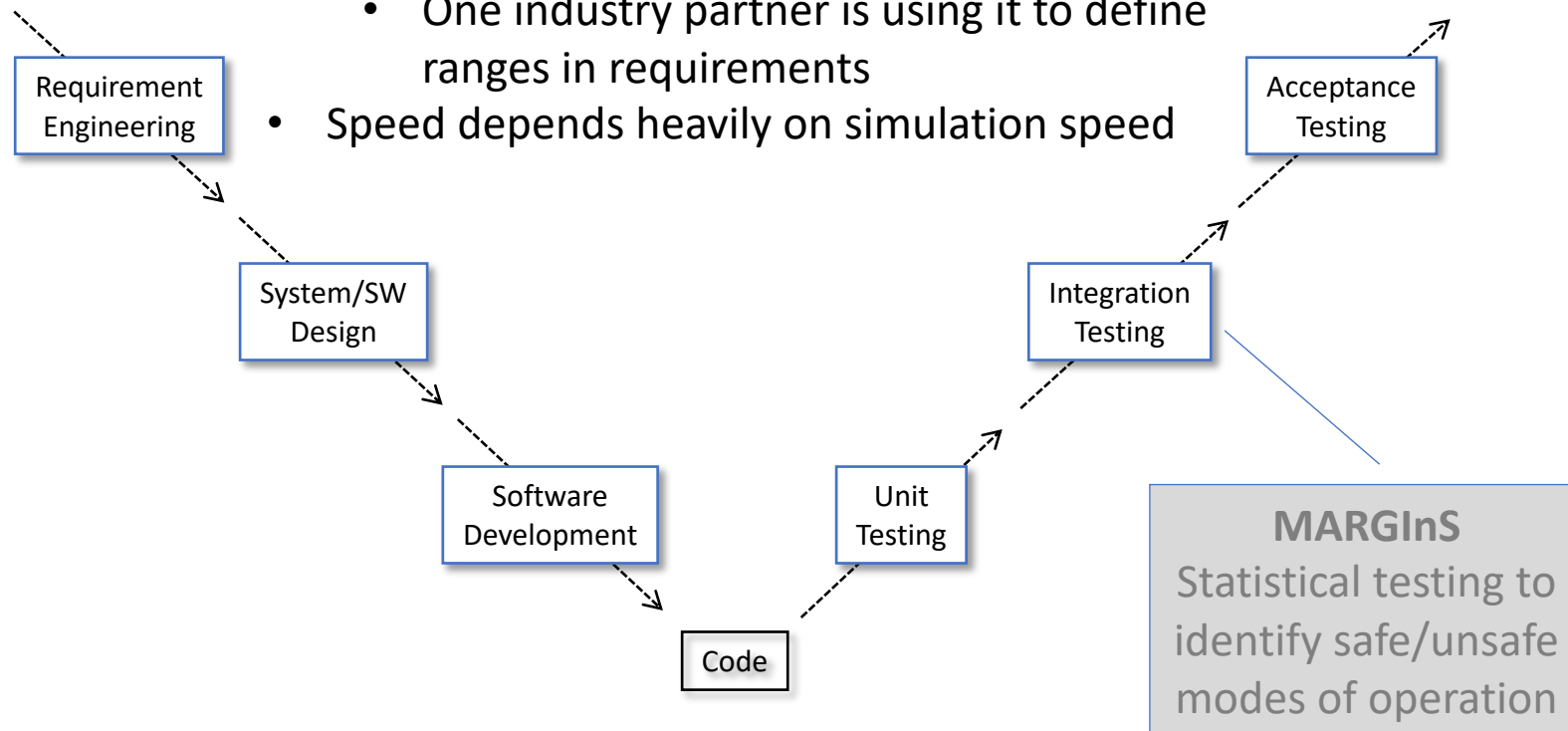
Limitations and future work

- Like any testing tool, MARGInS can increase confidence in the system but cannot guarantee the absence of errors
- Many of the results are visual, and require interpretation from domain experts
- Framework can be [extended](#) with additional components such as different machine learning techniques or test case generation schemes.



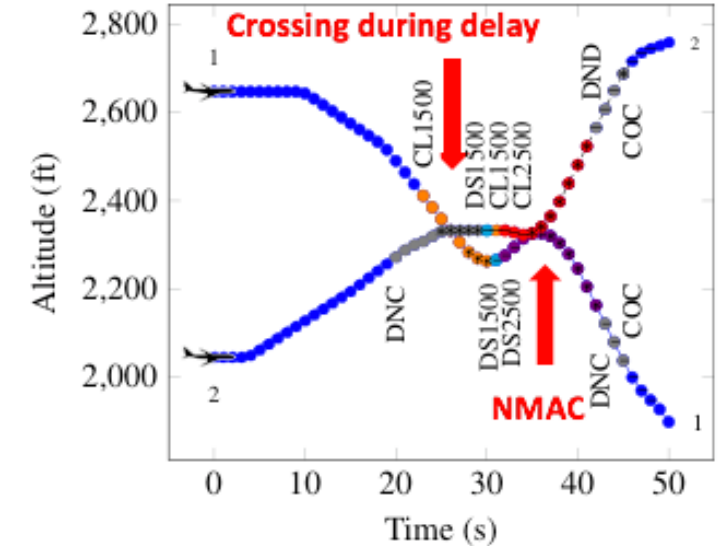
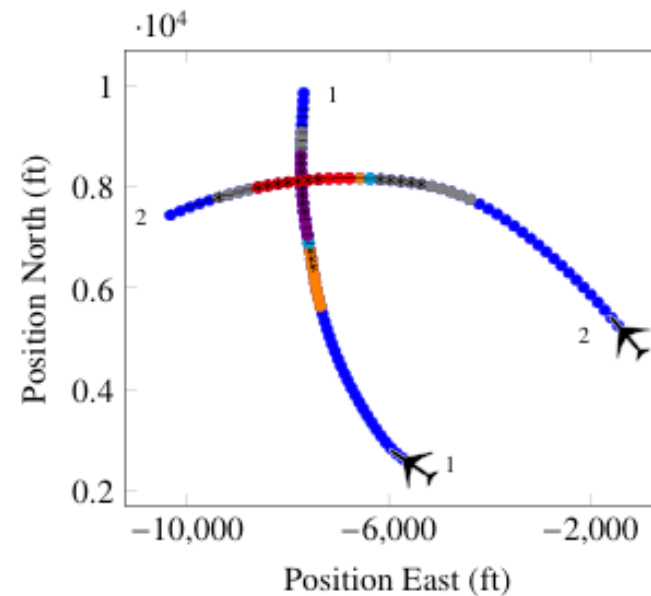
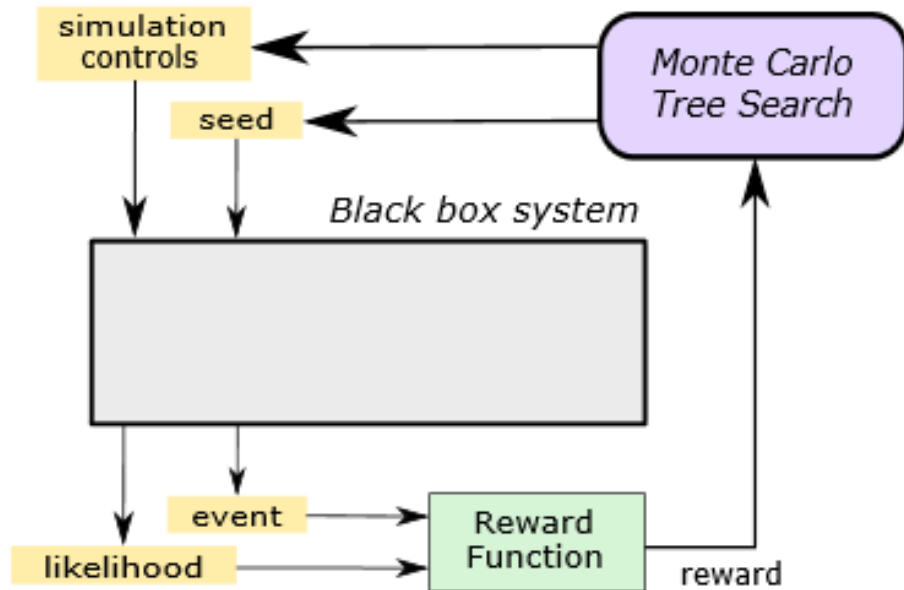
Lessons Learned: MARGInS

- Not a fully automated process
 - User needs to tell what is a result of interest
- Useful to find boundaries for safe operation
 - One industry partner is using it to define ranges in requirements
- Speed depends heavily on simulation speed



AdaStress at a Glance

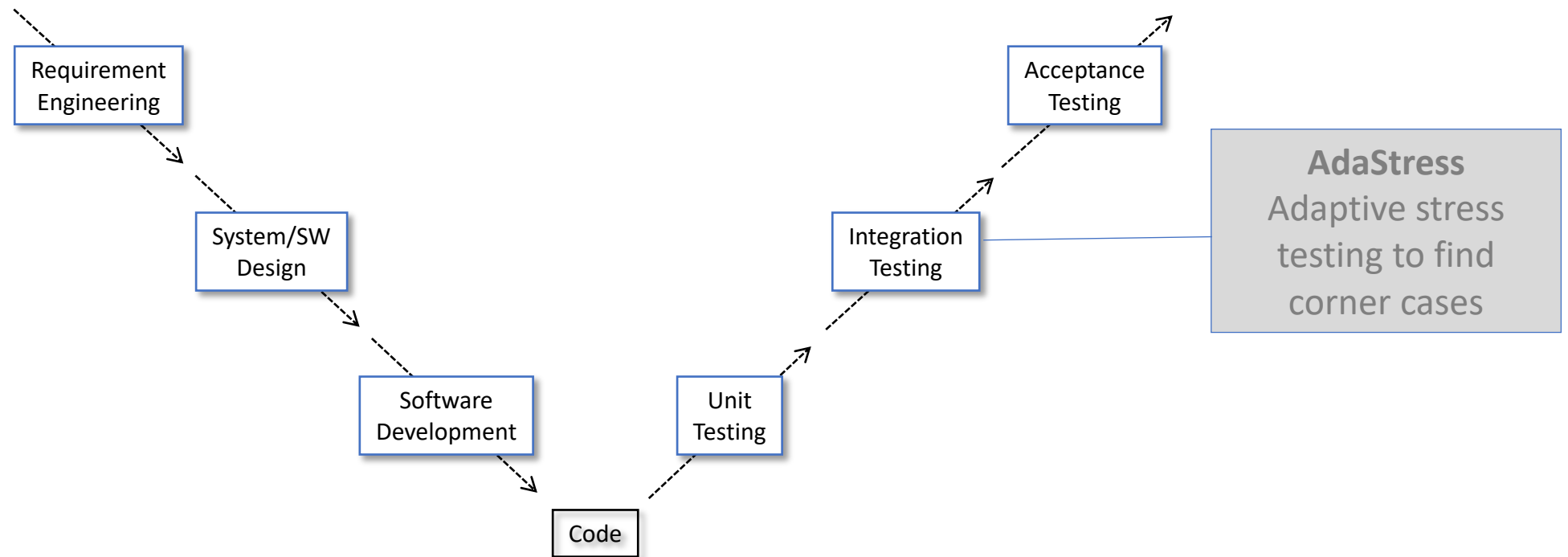
- AdaStress is a software package for an accelerated simulation-based stress testing method for finding the most likely path to a failure event



Technical POC: Ritchie Lee

Lessons Learned: AdaStress

- Has found very useful corner cases for
 - ACAS-X suite of software
 - Industrial flight management system
- Speed depends heavily on simulation speed

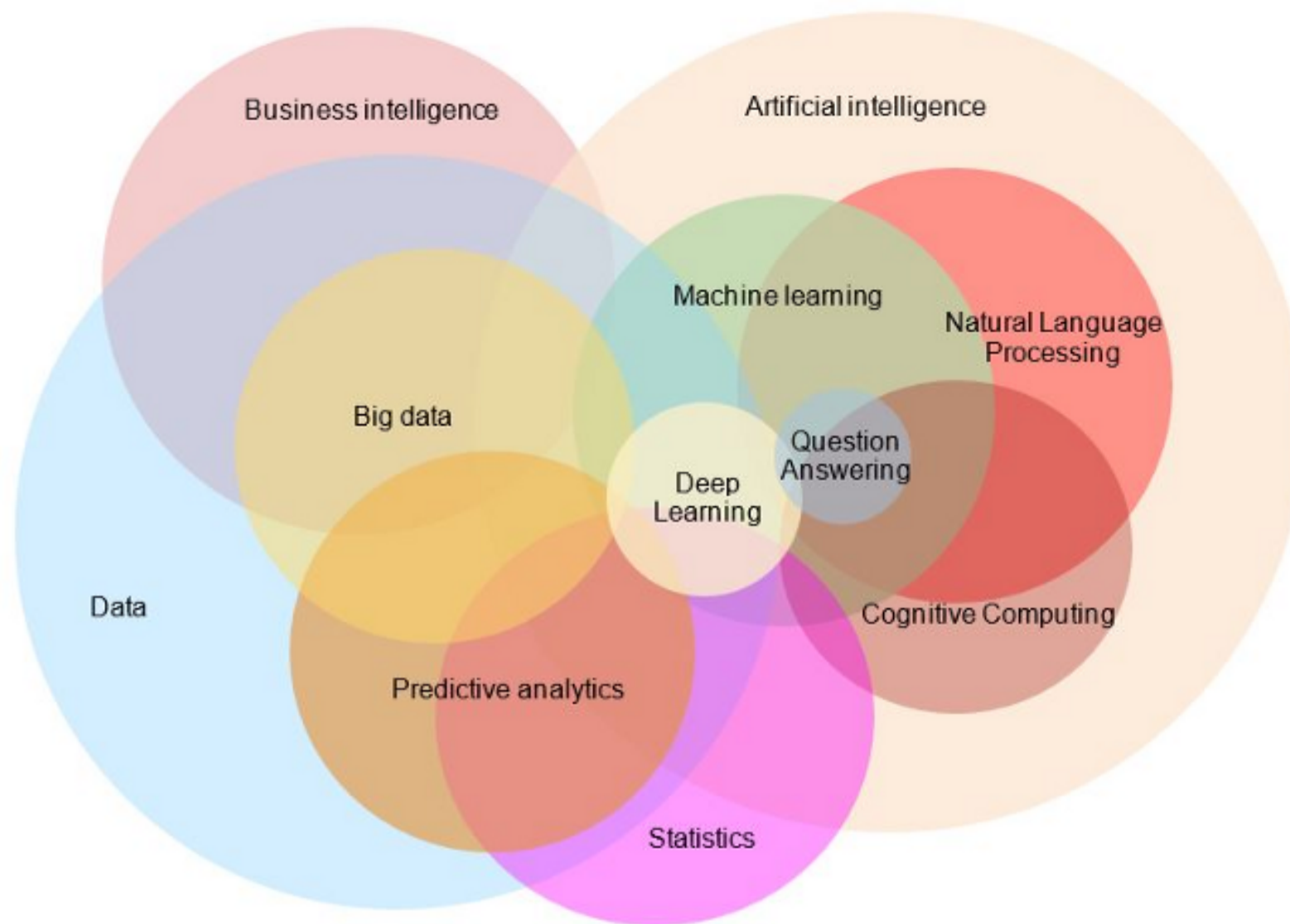


Move to autonomous systems

- Asked to address increasingly autonomous systems
- Different customers
 - Traditional: safety conscious but slow
 - New entrants: don't know about safety and want to go fast
 - Strategy: deploy asap, update regularly, very quick cycles
 - Doesn't fit with current certification processes



AI is a big world



New goals

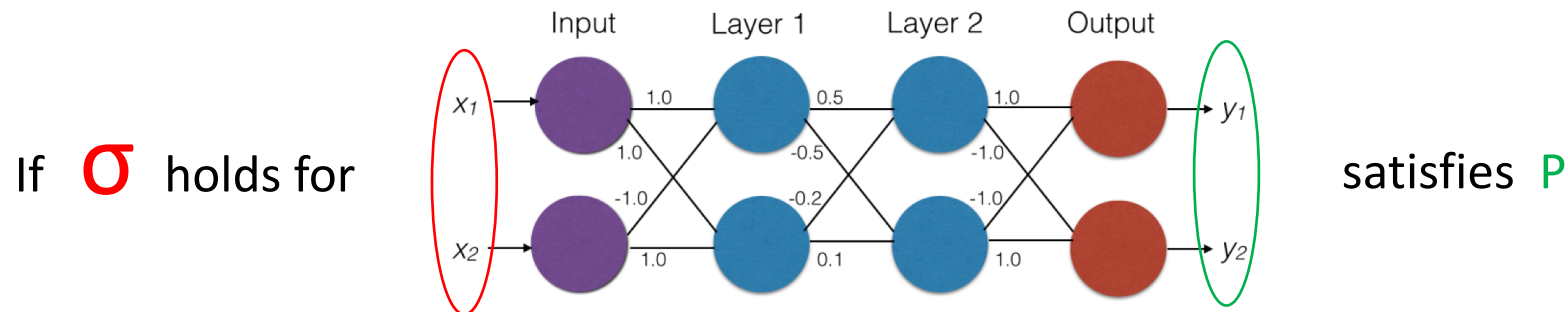
- Work on V&V techniques for autonomy
 - Adapt existing tools for autonomy
 - Solidify use of runtime monitoring
 - Rely on adaptive stress and statistical testing
 - Research formal V&V for Machine Learning (ML)
 - Explore the notion of explainability
- Deliver draft for new standards for autonomy
 - Practical: focus on ML-Enabled Components, then move to systems

Driving case studies

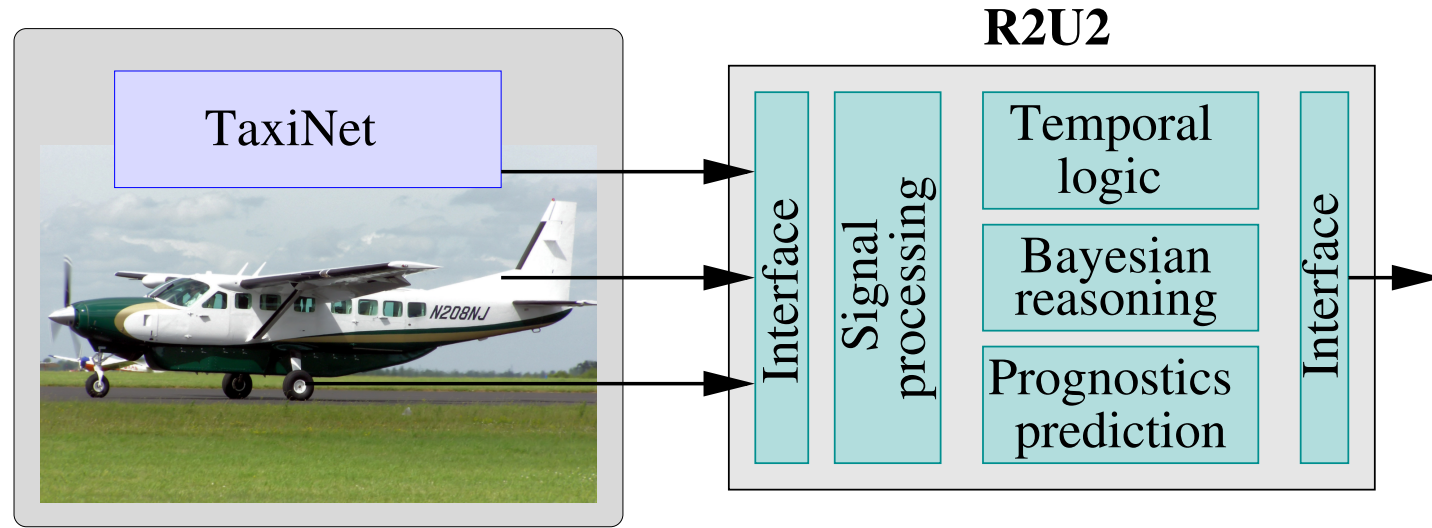
- Centerline tracking system for autonomous surface operations
 - DNN for image analysis
- Suite of ACAS-X software
 - Multi-optimization-based software
 - NN implementation
- RAV rover
 - Centerline tracking, fusion of various sensor data
- Multi rover coordination
 - TBD
 - Lots of V&V tools will be experimented on this (internal) mission

Prophecy: Contract Inference For NN

- Key Idea:
 - Infer “likely” properties, aka contracts, of a NN
 - Prove them using a decision procedure
- What is a contract? $\sigma \Rightarrow P$
 - σ is a precondition (“safe region”)
 - P is a postcondition; desired output behavior (e.g. some prediction)



R2U2: Runtime monitoring



R2U2 is a run-time monitoring and V&V tool that combines *Metric Temporal Logic* observers, *Bayesian Network* reasoners, and *model-based prognostics*.

Conclusions

- Lots of experience building V&V tools for traditional aviation systems
 - Most are being evaluated by industry right now
 - Also worked with AFRL
- Need to address autonomy
 - Our primary focus is Machine Learning
 - We'll go from a focus on specialized components to systems involving the use of ML in various places
- The end product is a draft for ML standards.
 - what V&V can be done will inform that