



Practical Multiple-Input Design for Aircraft System Identification Flight Tests

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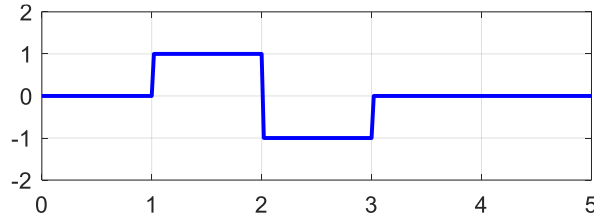
Introduction

Aircraft System Identification is the process of building mathematical models for aircraft based on measured data

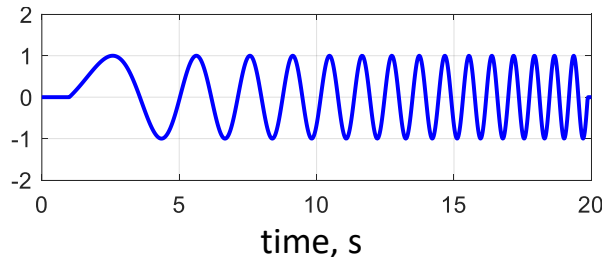
Single-input design:

- One-at-a-time sequential

Doublet



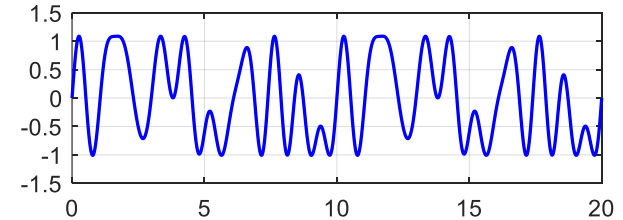
Frequency Sweep



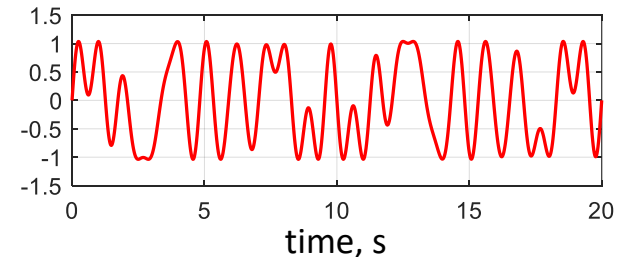
Multiple-input design:

- Many simultaneous in parallel

u_1



u_2





Multiple Input Design

Advantages of Multiple Inputs Applied Simultaneously:

- Better flight test efficiency
- Richer multi-axis aircraft response
- Higher rate of multi-axis excitation
- Control interaction effects

- Optimal multiple-input design approaches exist, but depend on prior models
- This work focuses on orthogonal optimized multisine input design:
 - Practical, multi-input design, does not require prior models
 - Very successful in past flight tests
 - Useful variations and practical flight test implementation considerations

Orthogonal Optimized Multisine Inputs

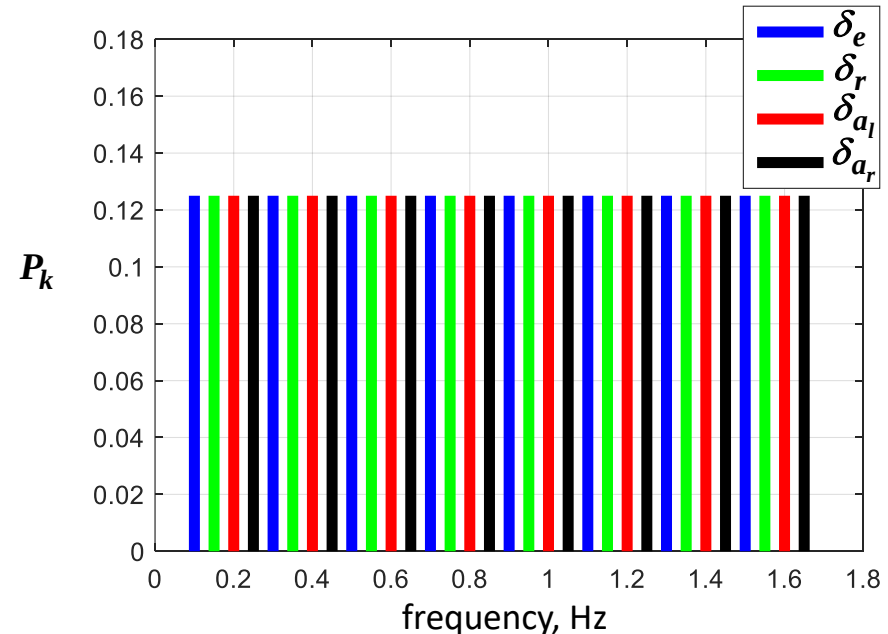


$$u = \sum_{k \in \{1, 2, \dots, M\}} A \sqrt{P_k} \sin\left(\frac{2\pi k t}{T} + \phi_k\right)$$

T = maneuver length, s

A = input amplitude

- Time/Frequency orthogonal
- Simultaneous multi-input
- Phase angles optimized for minimum peak-to-peak amplitude
- Robust to various dynamics
- Decorrelated with good coverage
- Balanced, minimal excursions
- Easy to design
- Successful in past flight tests



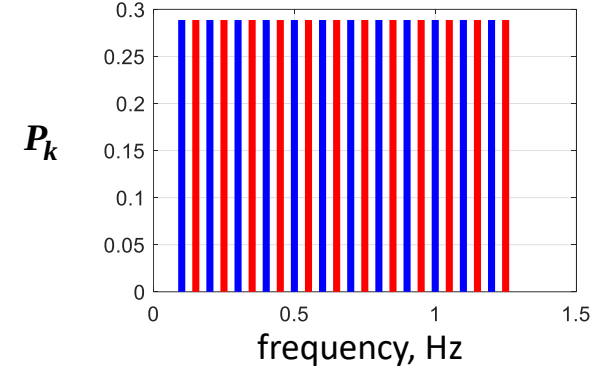
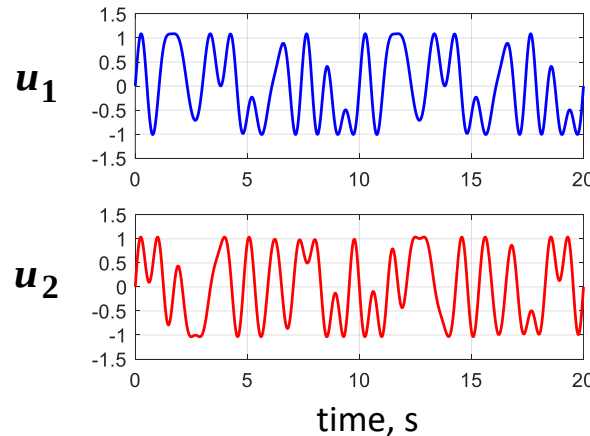
Useful Design Variations

$$u = \sum_{k \in \{1, 2, \dots, M\}} A \sqrt{P_k} \sin\left(\frac{2\pi k t}{T} + \phi_k\right)$$

T = maneuver length, s

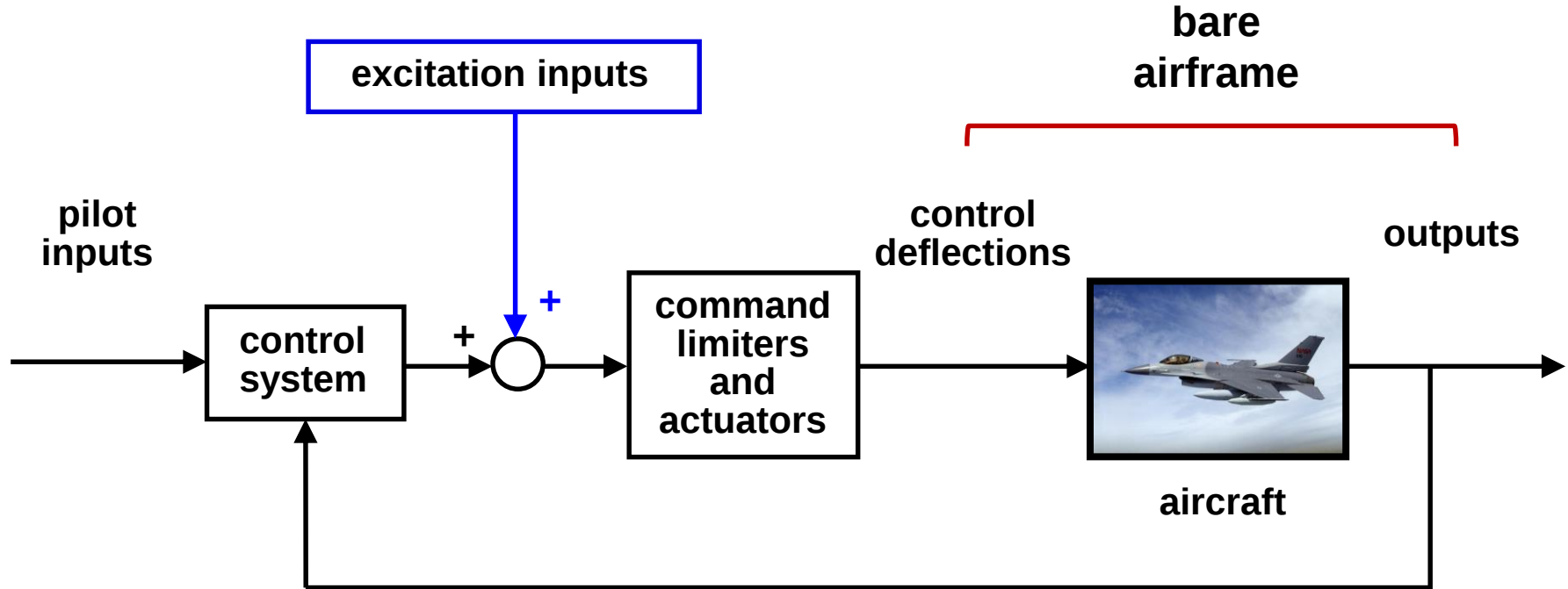
A = input amplitude

- Amplitudes and/or signs
- Assignments
- Linear combinations
- Time length T
- Harmonic square waves
- Power spectra
- Frequency content



Often the same multiple-input design can be used for different flight conditions or even different aircraft, with only simple amplitude changes

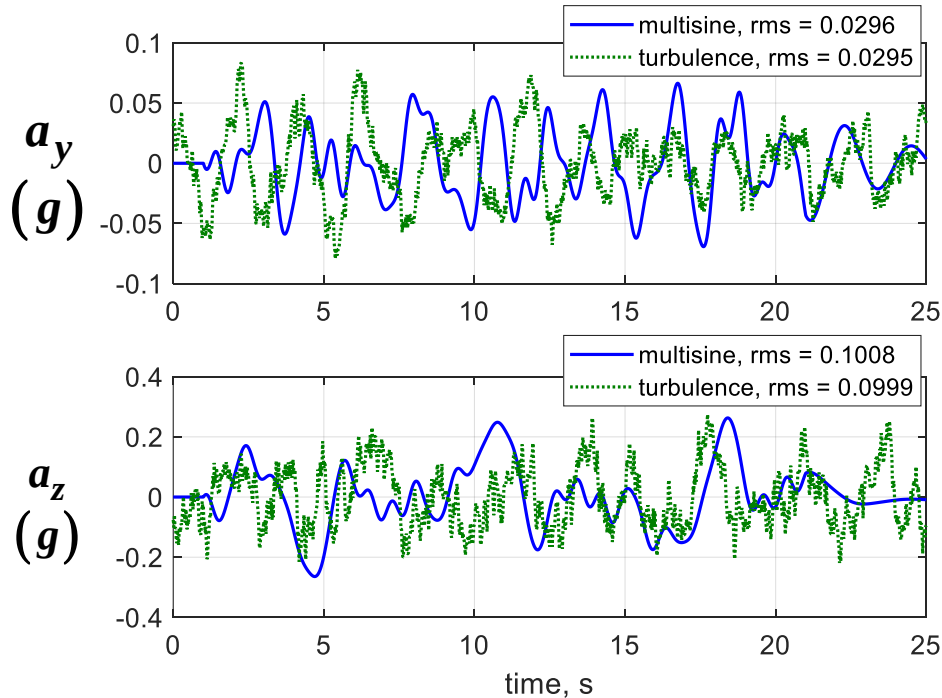
Flight Test Implementation



With this approach, informative flight data will be obtained
regardless of what the pilot or feedback control are doing

Aircraft Response

Response to orthogonal optimized multisine input excitation is like flight in light-to-moderate turbulence



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Frequency Response

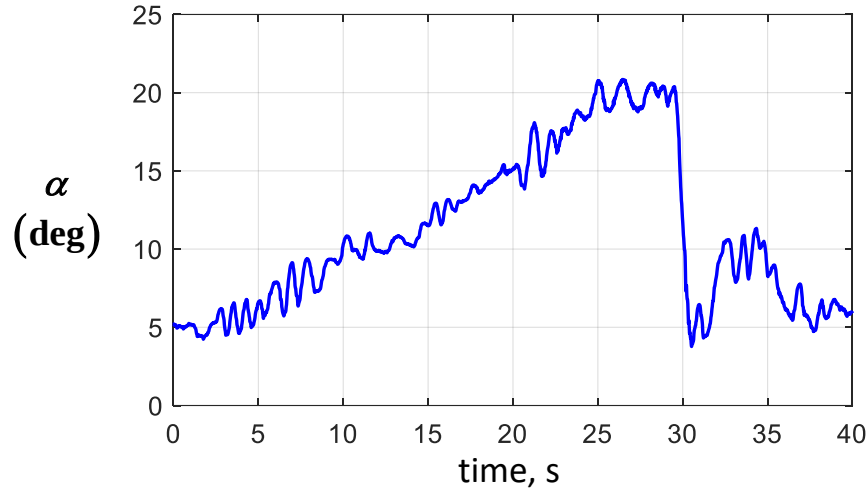
Because of the known frequency content of the orthogonal optimized multisine inputs, frequency responses can be computed simply and in real time

$$\hat{H}(\omega_k) = \frac{\tilde{y}(\omega_k)}{\tilde{u}(\omega_k)} = \frac{\text{Fourier transform of the output}}{\text{Fourier transform of the input}}$$

- Many frequency responses can be computed from a single maneuver
- Analogous to running parallel sine dwell tests at the input frequencies ω_k
- Interpolate to get the frequency response at other frequencies
- Modifications are necessary to use the technique with active feedback control

Varying Flight Conditions

T-2 flight test data: Maneuver length = 40 s



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Automated multi-axis excitations during slow flight condition changes:

- Low pilot workload
- Global multi-axis modeling data collected efficiently
- Applied as Mach number varied during hypersonic flight tests on X-43A and X-51A

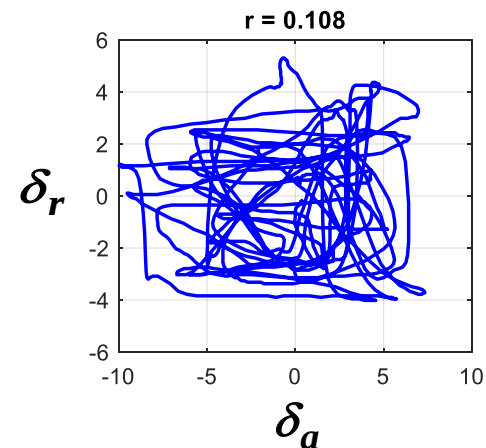
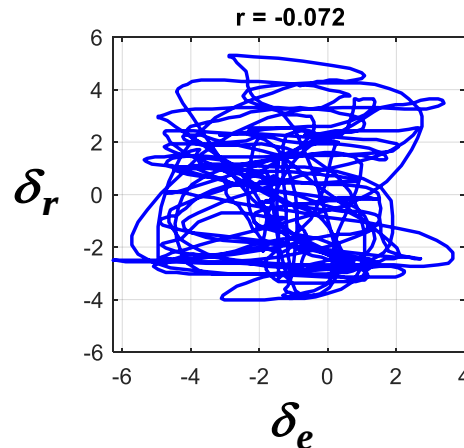
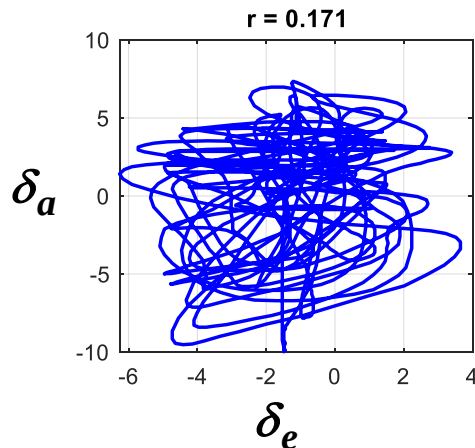
Pilot Implementation

A pilot can approximate orthogonal optimized multisine inputs when the aircraft has no feedback control

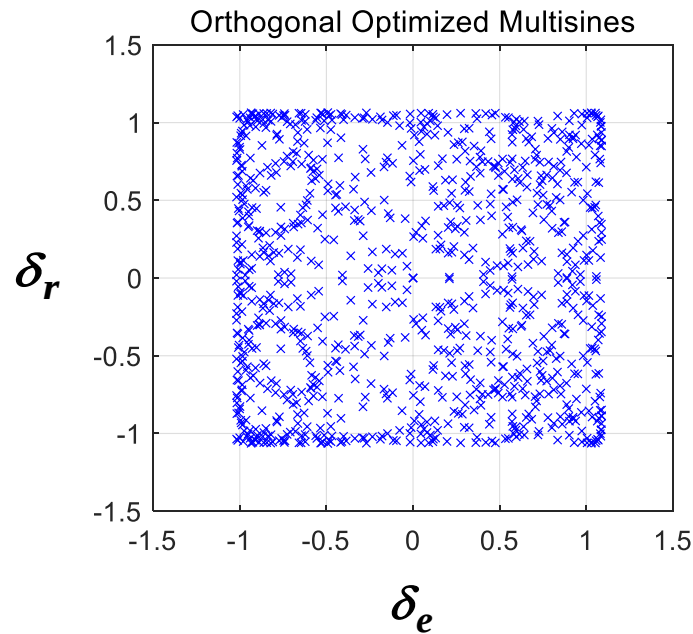
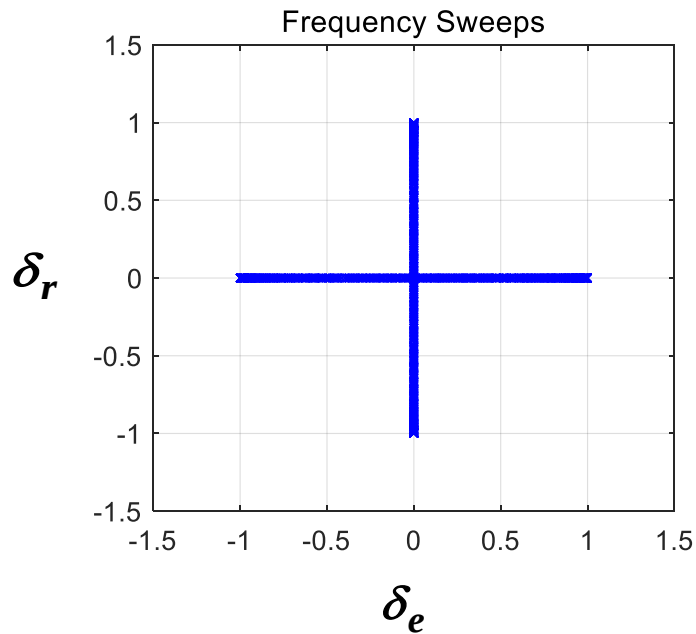
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Maneuver length = 27 s



Control Interaction Effects





Summary:

- Automated orthogonal optimized multisine inputs can be applied to multiple inputs simultaneously to collect informative multi-axis flight test data very efficiently without affecting the nominal flight trajectory, for a wide variety of flight test situations and aircraft system identification problems
- Adding automated excitation inputs just before the command limiters provides practical and effective flight test capability regardless of pilot inputs or feedback control
- Test pilots can effectively approximate orthogonal optimized multisine inputs for aircraft without feedback control
- Input design software (and much more) is available in SIDPAC:
<https://software.nasa.gov/software/LAR-16100-1>