

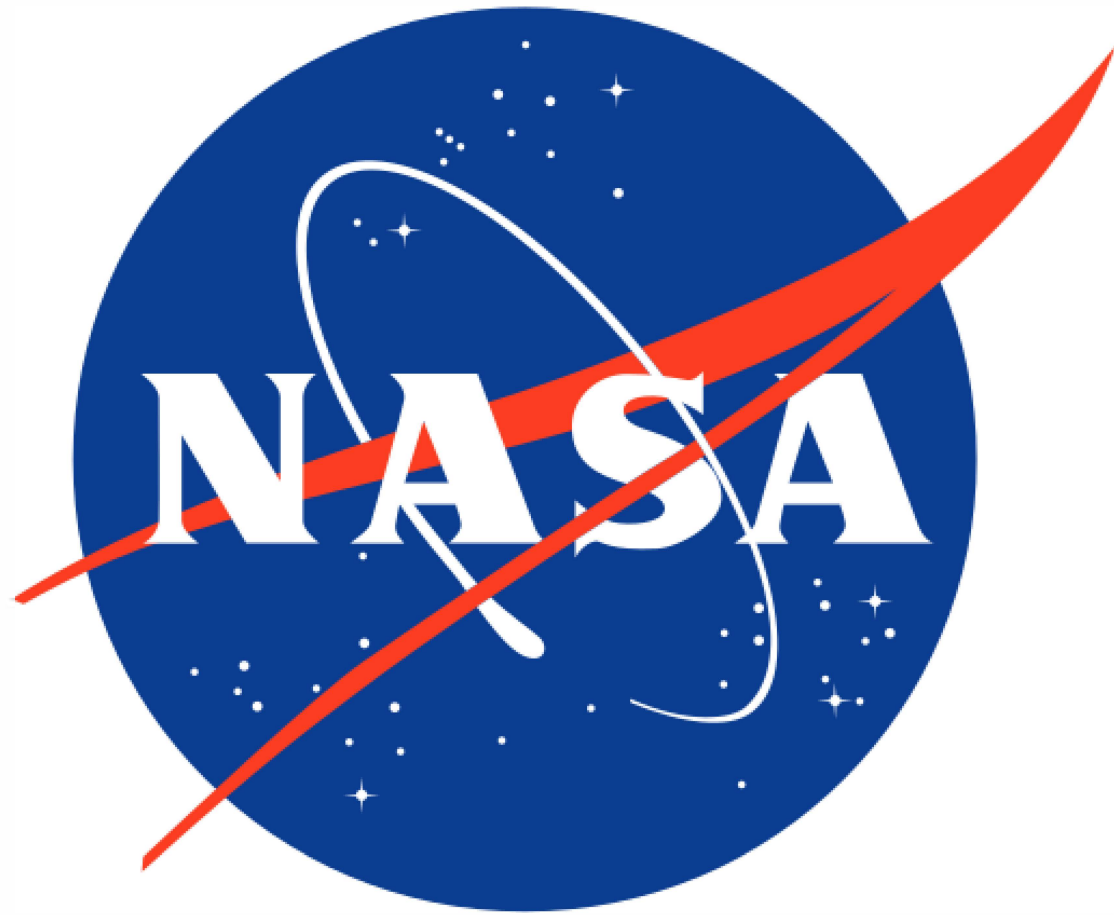
# NASA + Pratt

## X-HAB

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# OASIS HABITAT





**oasis**

**Pratt**

**PI-FAB**

**CONSORTIUM**  
RESEARCH & ROBOTICS  
HOSTED BY PRATT INSTITUTE

## Project Goal

The goal of **Habitat: Oasis** is to create an in depth functioning **lunar habitat** that would serve **NASA's Artemis Project** and create a **resupply point on the moon that would allow for future space exploration**. This habitat would allow spacecraft to travel directly from the moon towards other planets within our solar system in a more efficient manner when compared to launching from Earth. We believe that our project is unique in its **focus on mitigating internal physical and mental distress** that our inhabitants would face with **extended stay on the lunar surface**.

The project from this semester focused on the efficient method-based **design of structure through 3D printing** and development of a **lunar landing pad**. Our study additionally focused on **how a research team could comfortably live** on this lunar surface we integrated a **GreenHouse/Zen Garden** with the addition of providing lunar views and a **comfortable program layout within the structure**. These additional focuses work in tandem with our priorities of safety and function through the **research and development** we generated earlier this semester and the ones prior.

# OASIS

## TABLE OF CONTENTS

- PRECEDENT PROJECTS
- SITE ANALYSIS
- HABITAT DESIGN
- GREENHOUSE
- STRUCTURE
- LANDING PAD
- DISPLAY MODEL
- BUDGET AND SCHEDULE
- RESEARCH

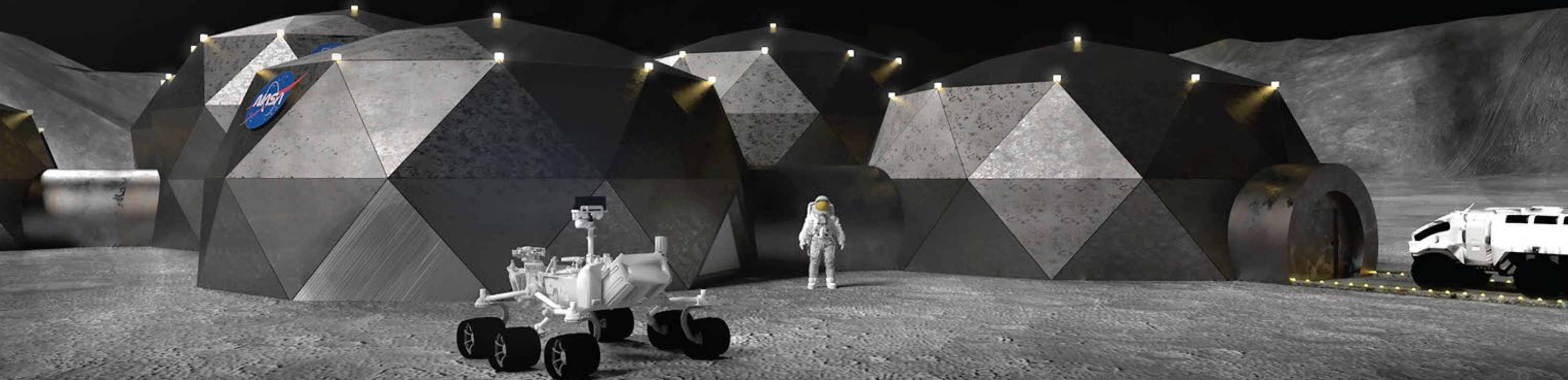
## PRECEDENT PROJECTS

- CRATER HABITAT
- SCHROTER VALLEY RESEARCH HUB

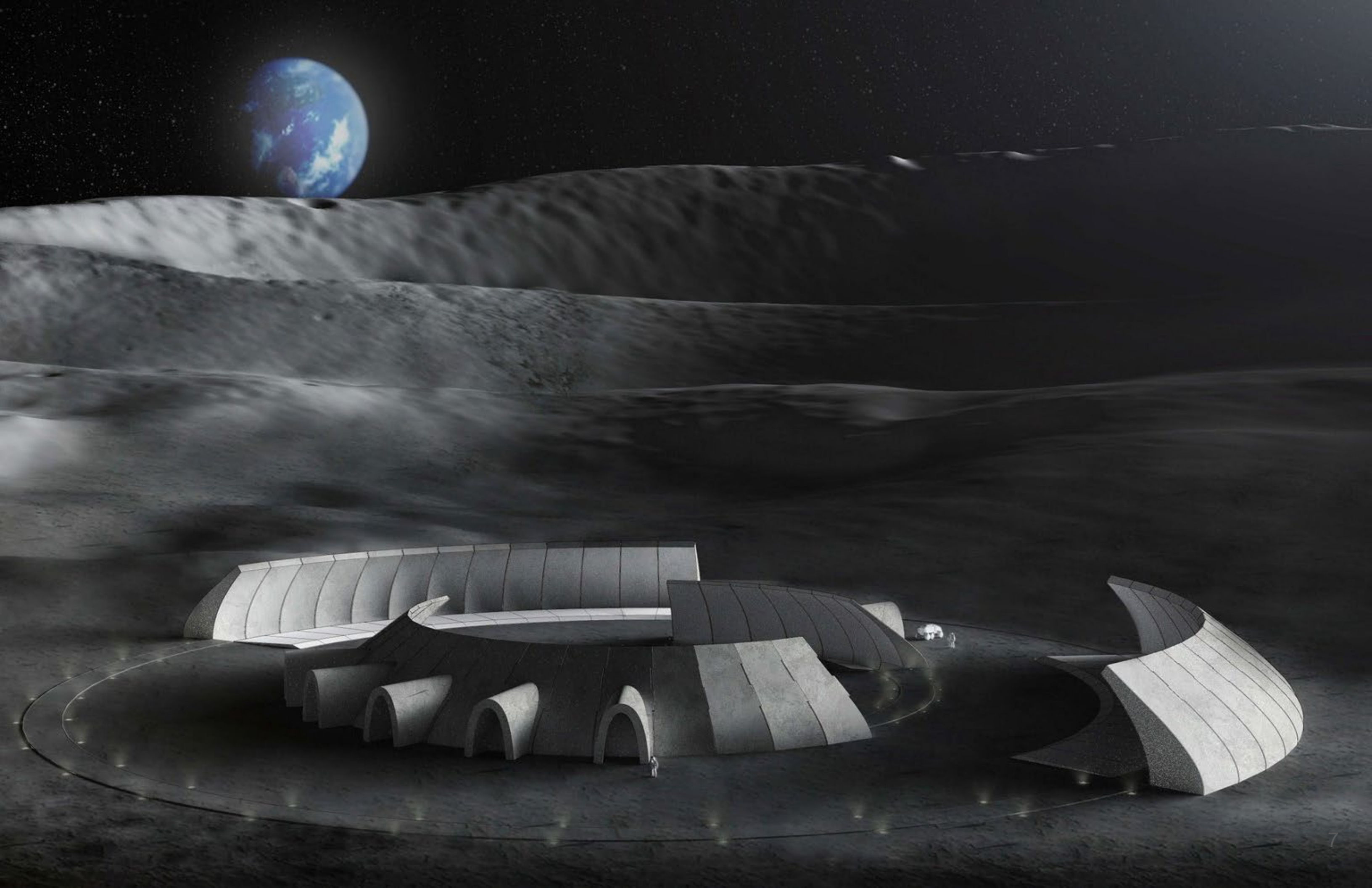
# NASA + Pratt

X-HAB: MOON TO MARS

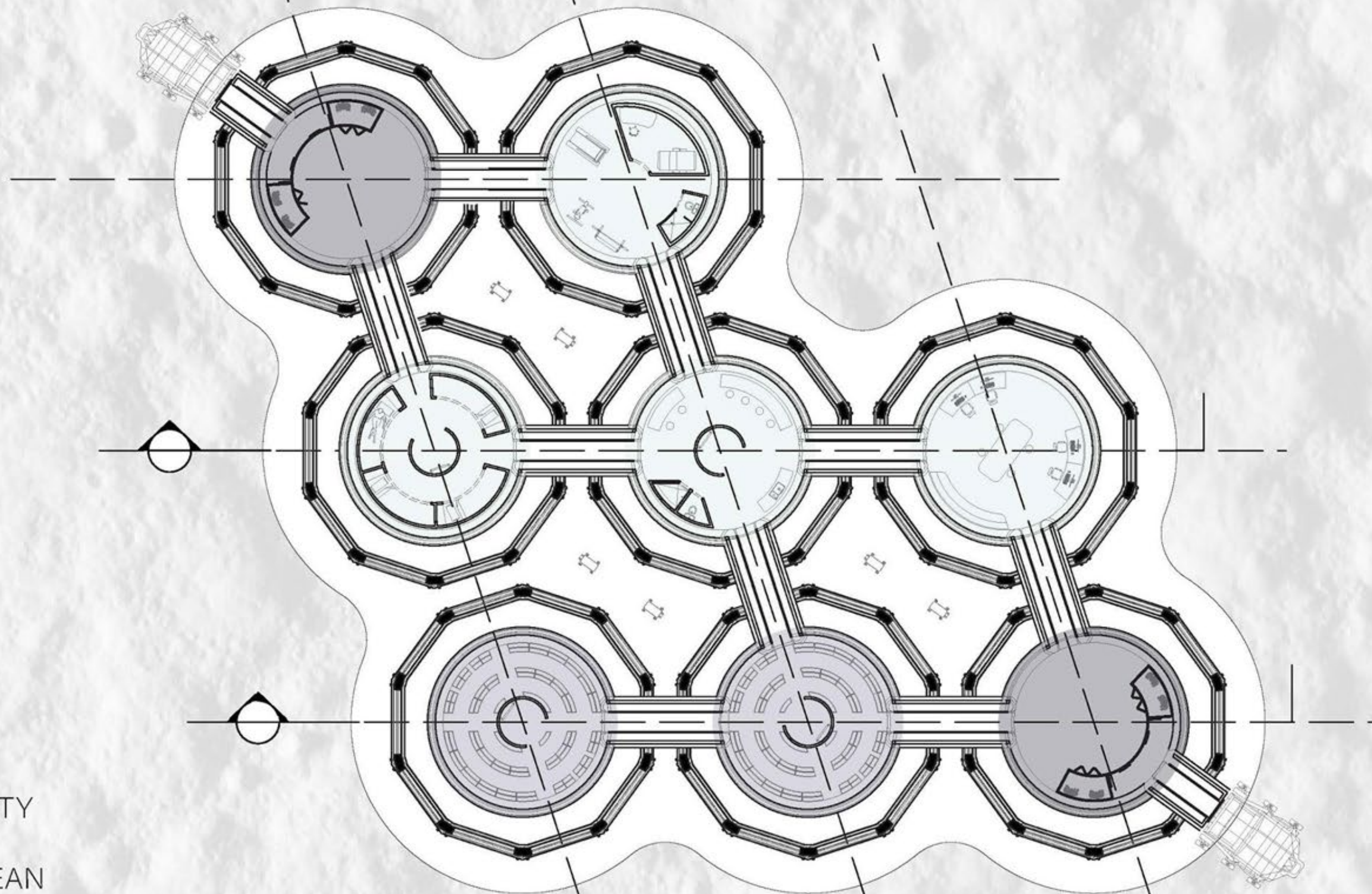
## CRATER HABITAT



GROUP MEMBERS: - BENNY DENG, - MICHELLE SHIN, - CHAO QUN ZHANG, - KESHAN GOBERDHAN, - SUNG UK CHOI,  
- SEUNG HYUN LIM, - GOSSSELLE ASTUDILLO



# FIRST FLOOR PLAN

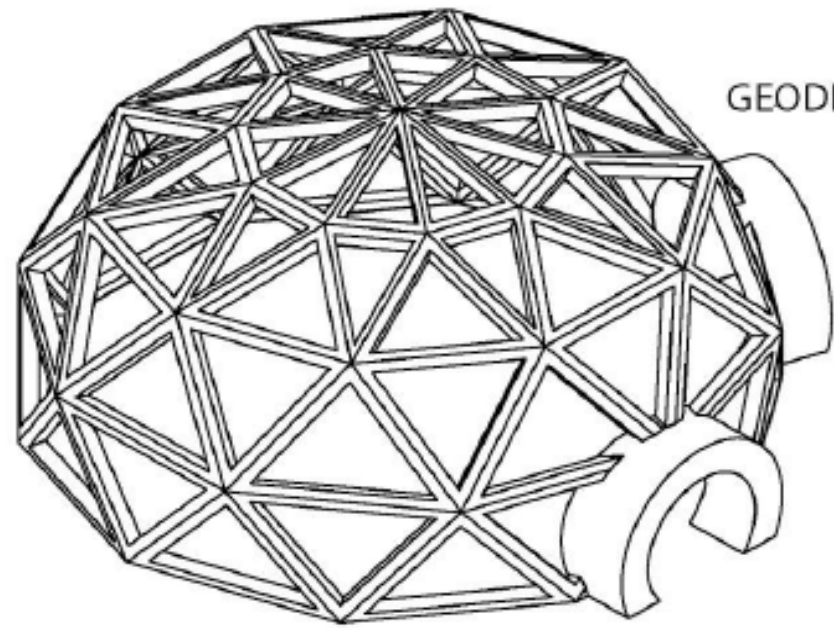


- DIRTY
- CLEAN
- GREEN

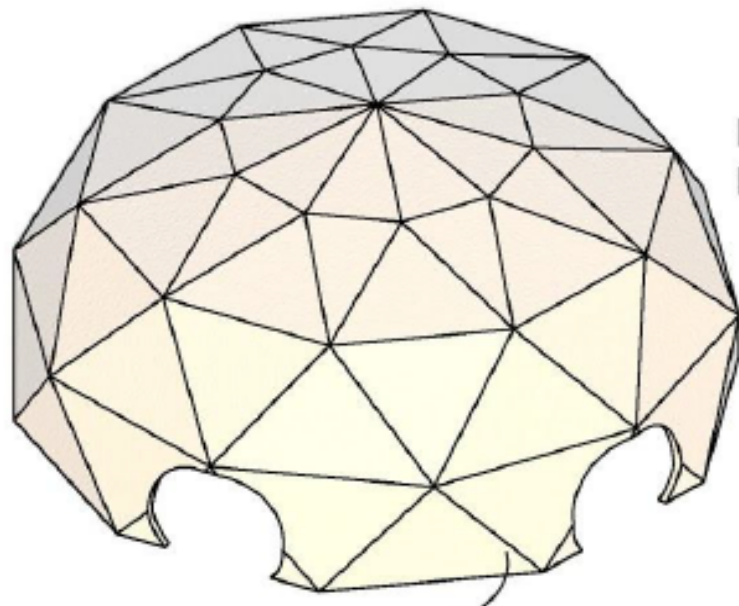




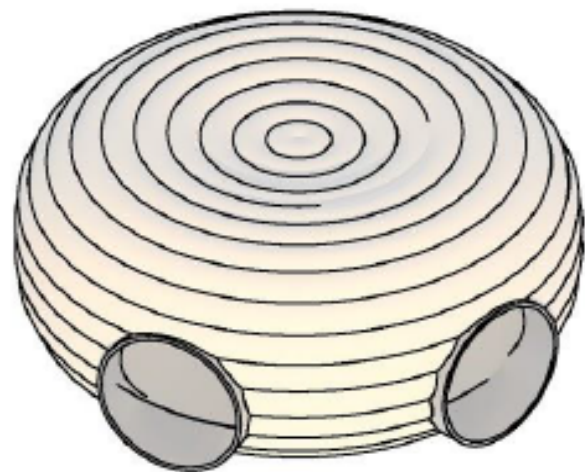
# COMPONENTS



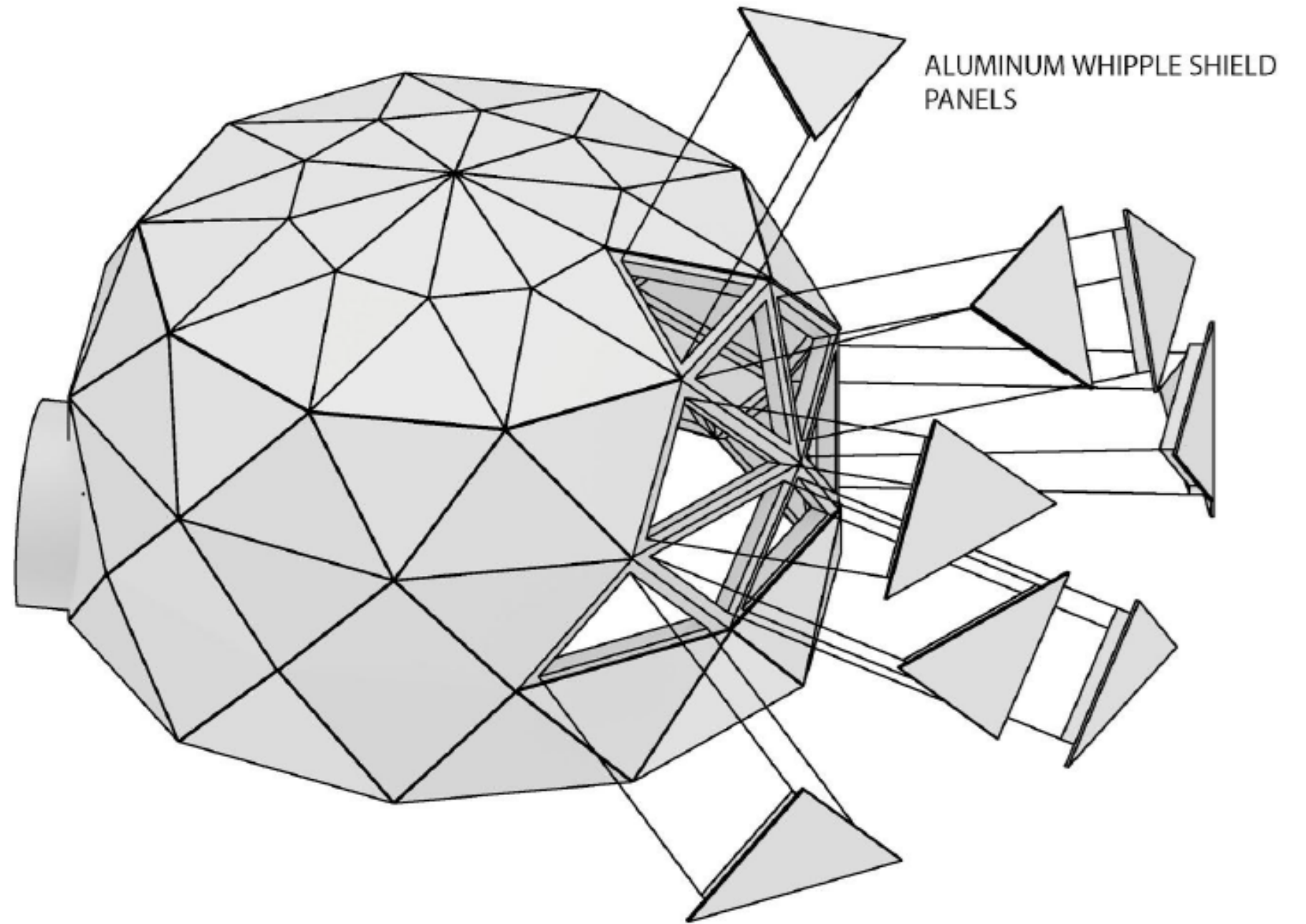
GEODESIC STRUCTURE



HIGH DENSITY  
POLYETHYLENE PANELS

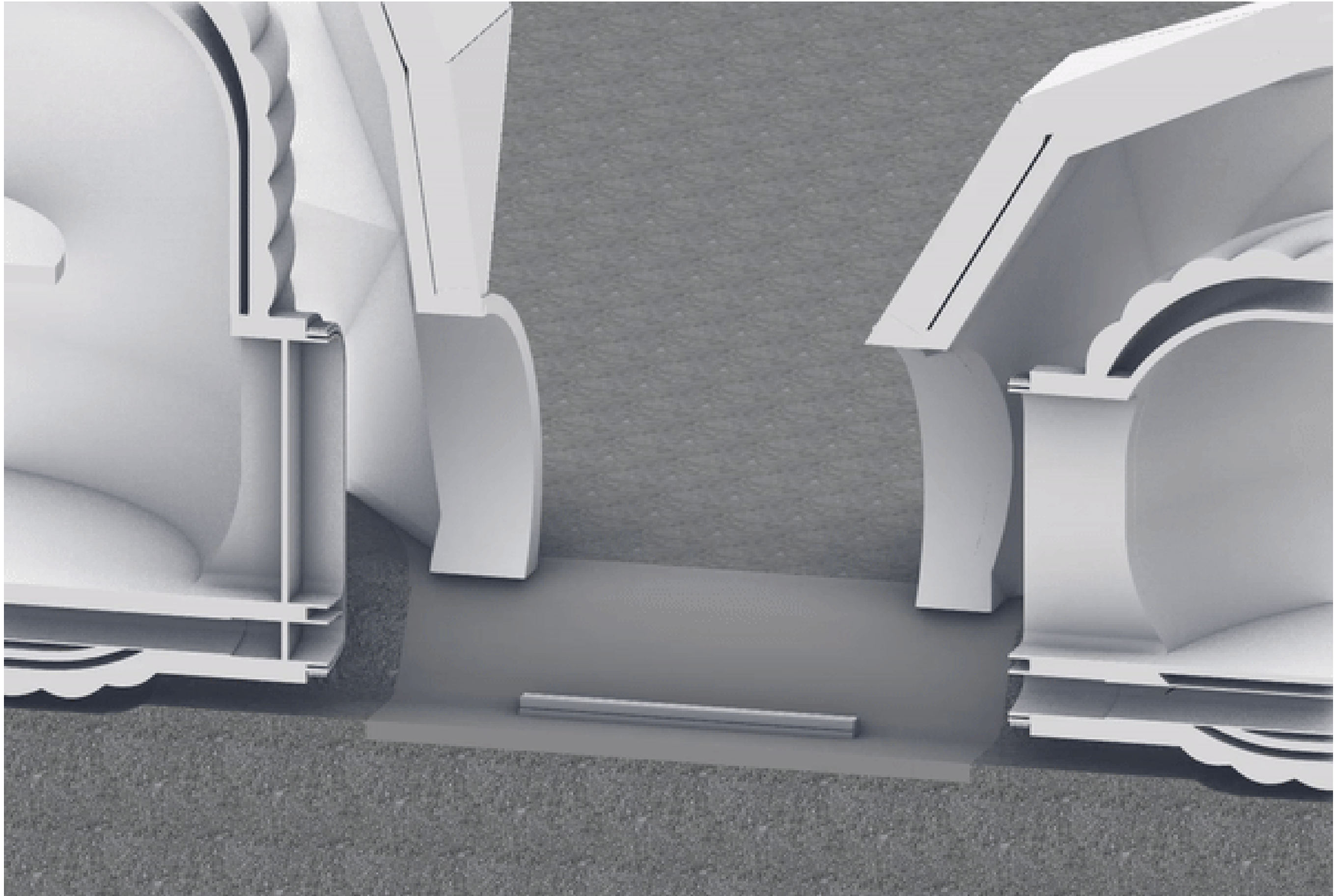


INFLATABLE HABITAT



ALUMINUM WHIPPLE SHIELD  
PANELS

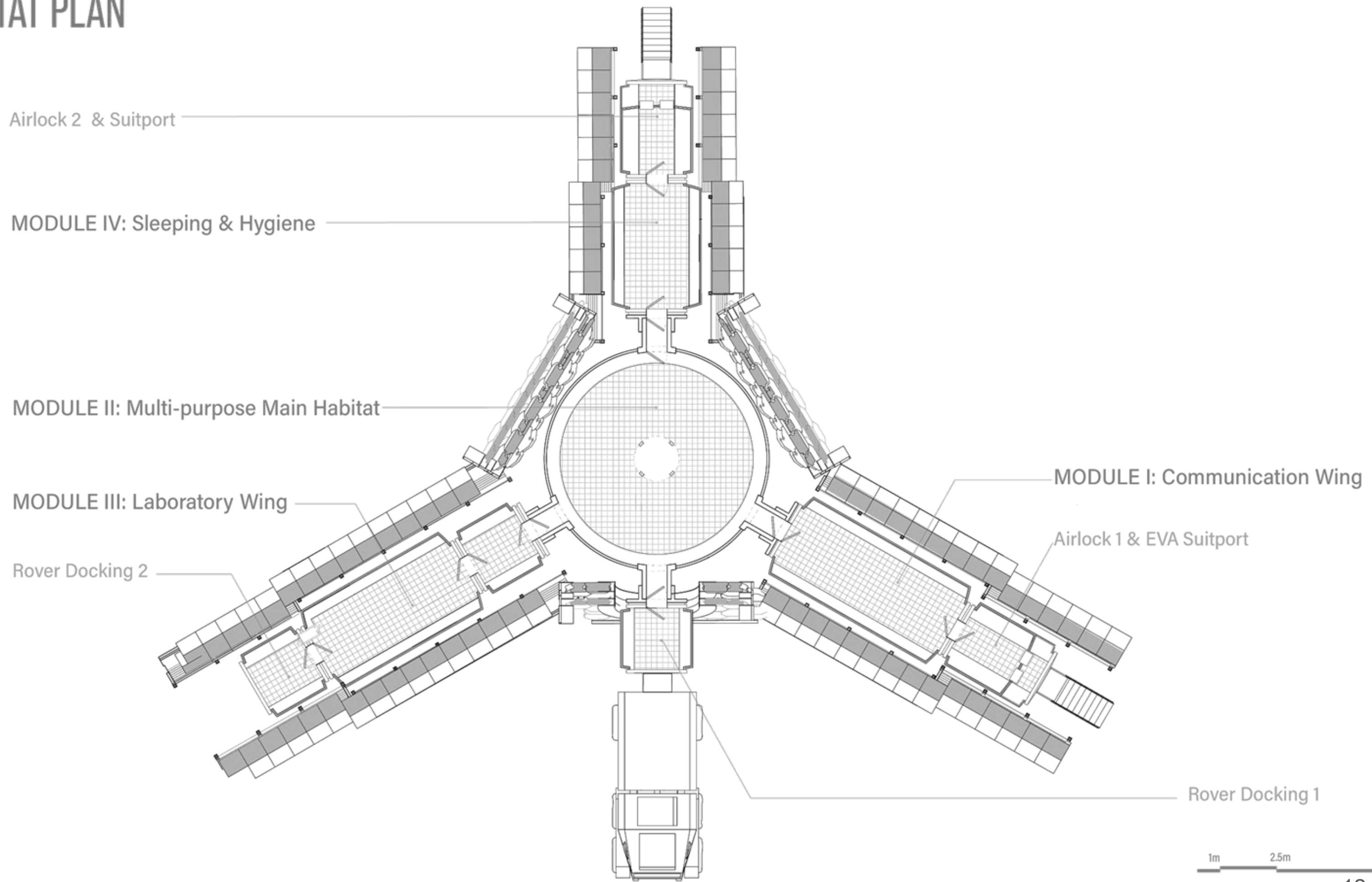
# EXPANDABLE AIRLOCK



# SCHROTER'S VALLEY RESEARCH HUB



# HABITAT PLAN

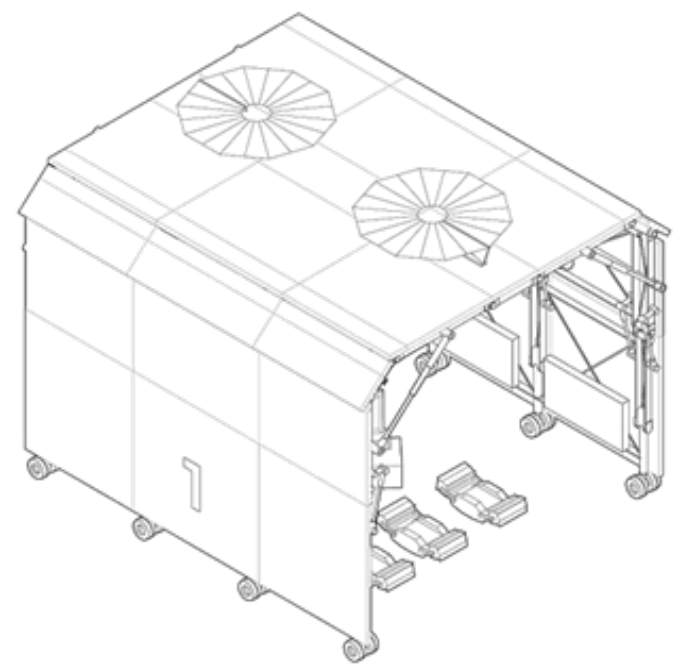


1m 2.5m 5m

# GANTRY SYSTEM

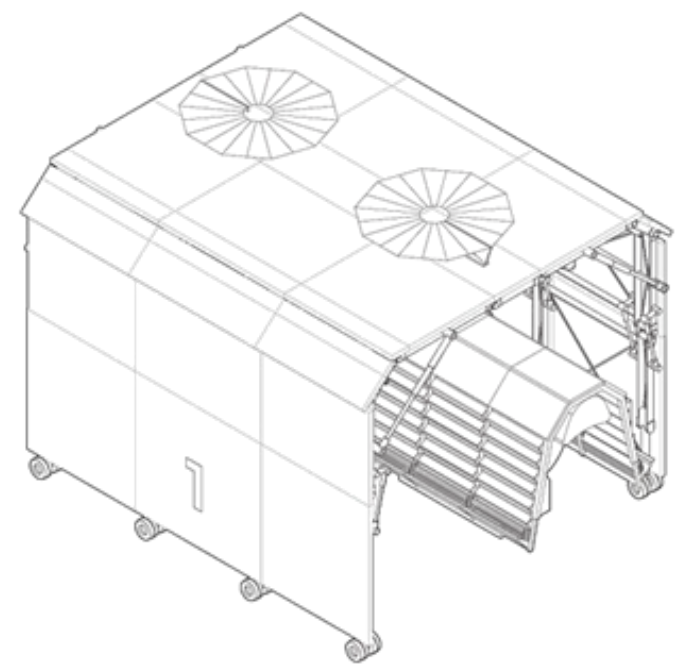
## i. PROTECTION

Upon arrival, Gantry (MPCS) will autonomously deploy and protect construction process.



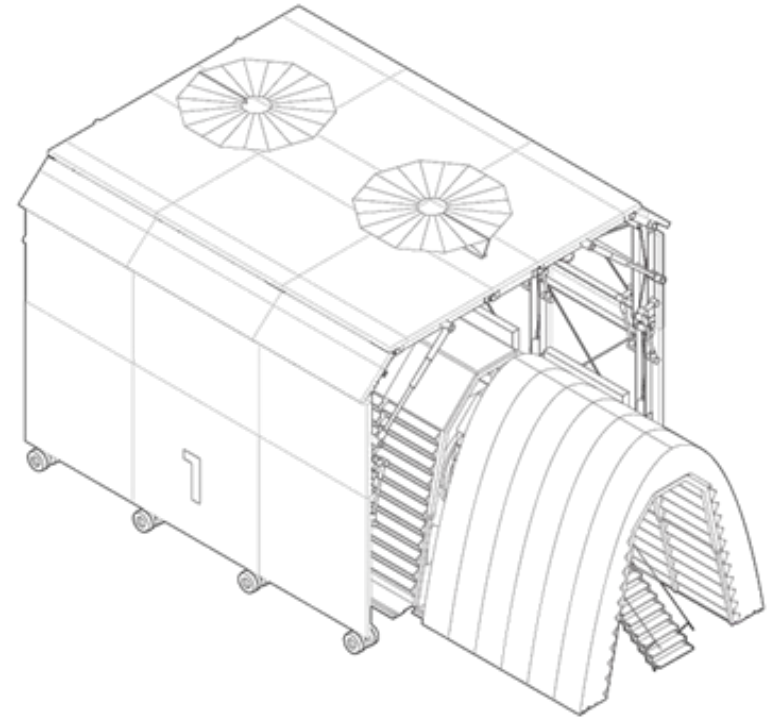
## ii. DELIVERY

The MPCS will also autonomously deliver modules from landing to construction sites.



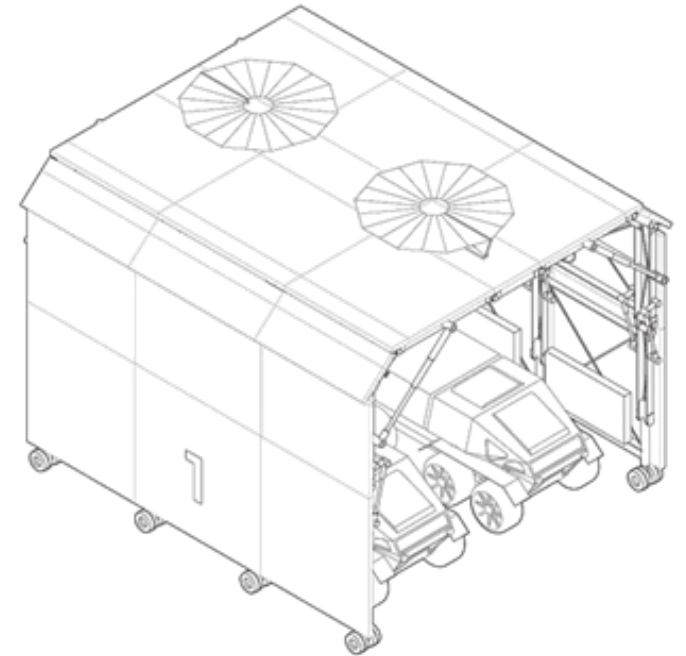
## iii. CONSTRUCTION

Will provide a protected environment to assemble regolith blocks.



## iv. CONTINUED USE

Will be on standby, and provide unpressurized protection for LRVs.

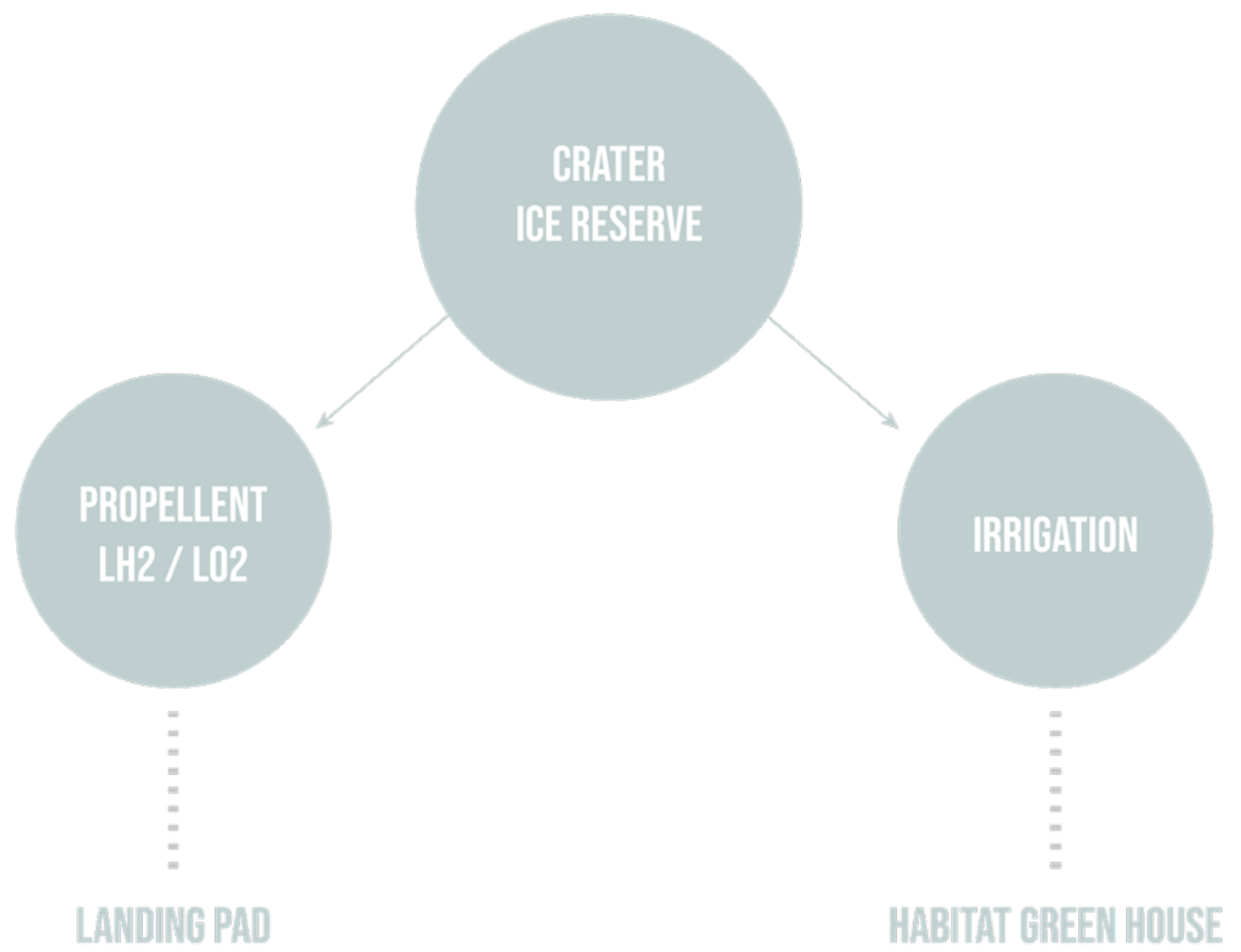


\* Mobile Protected Construction System (MPCS)

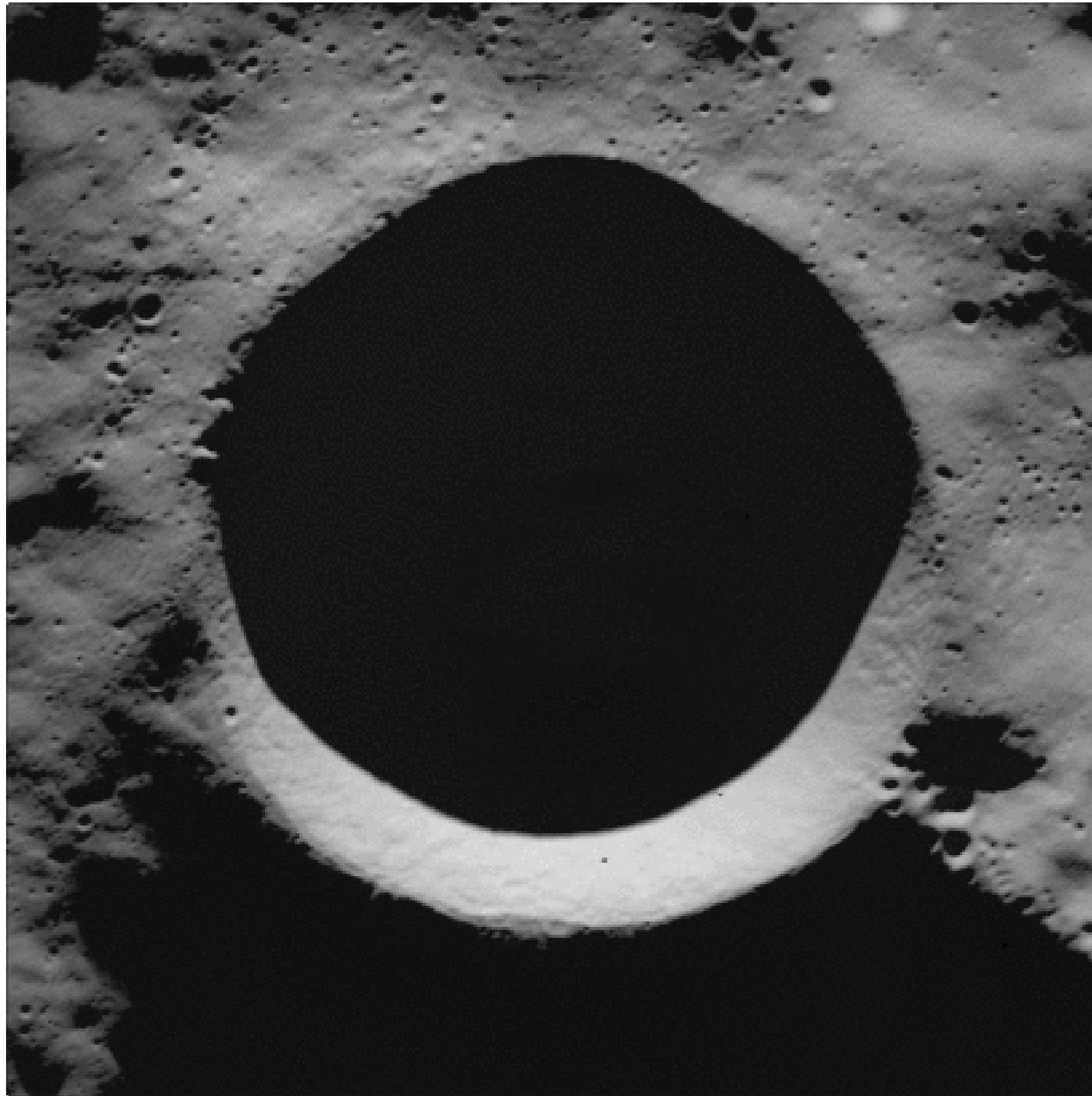
## SITE ANALYSIS

- SITE RESOURCE
- SITE CONDITION

# SITE STRATEGIES: SOUTH POLE

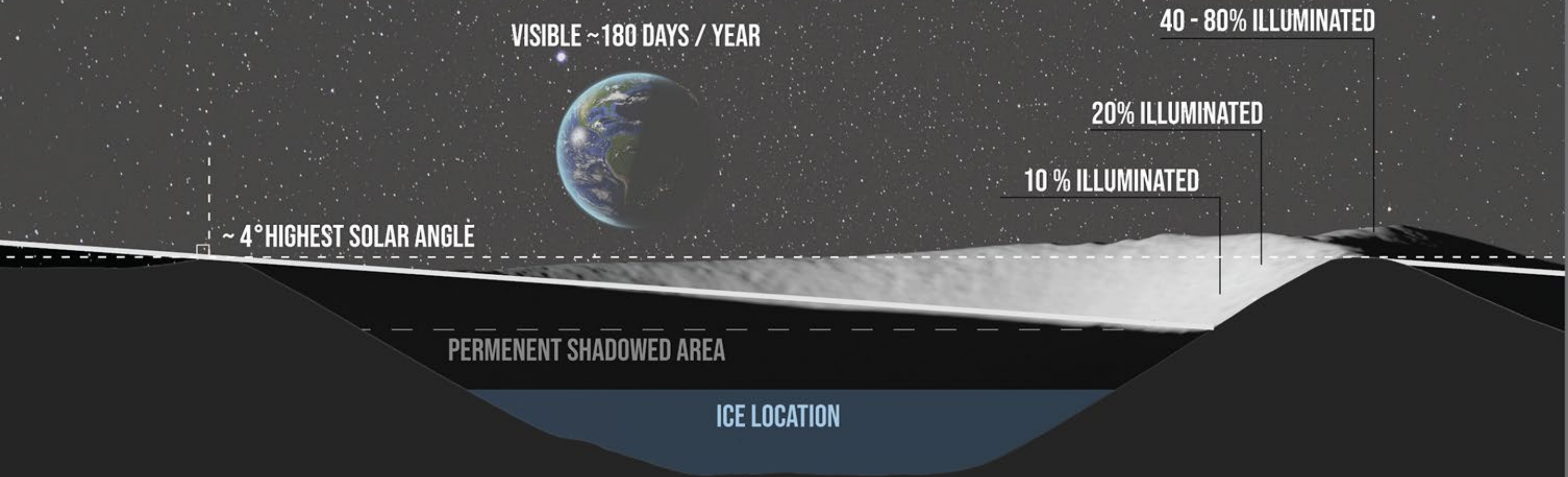


# ■ SUN STUDY

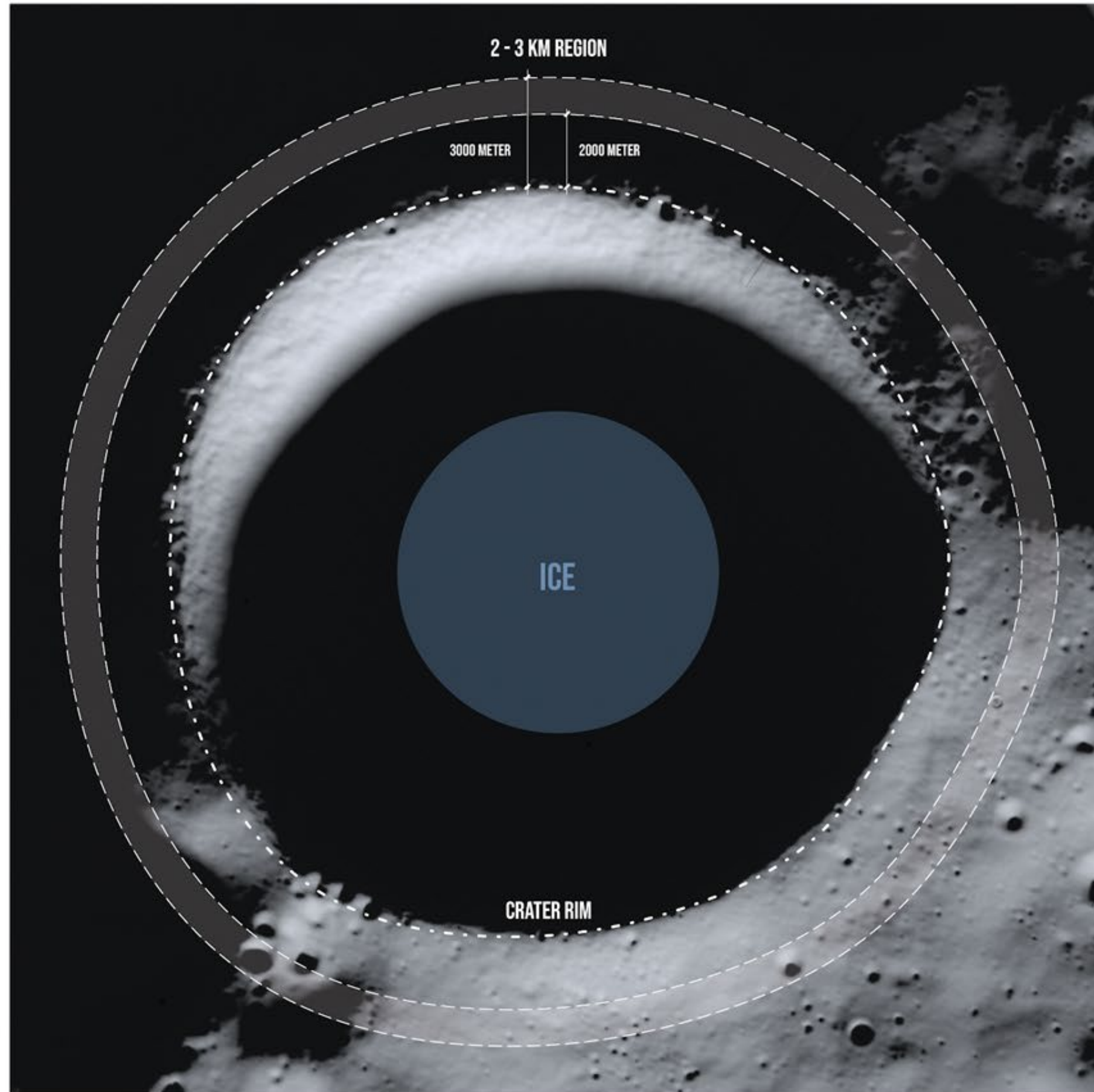




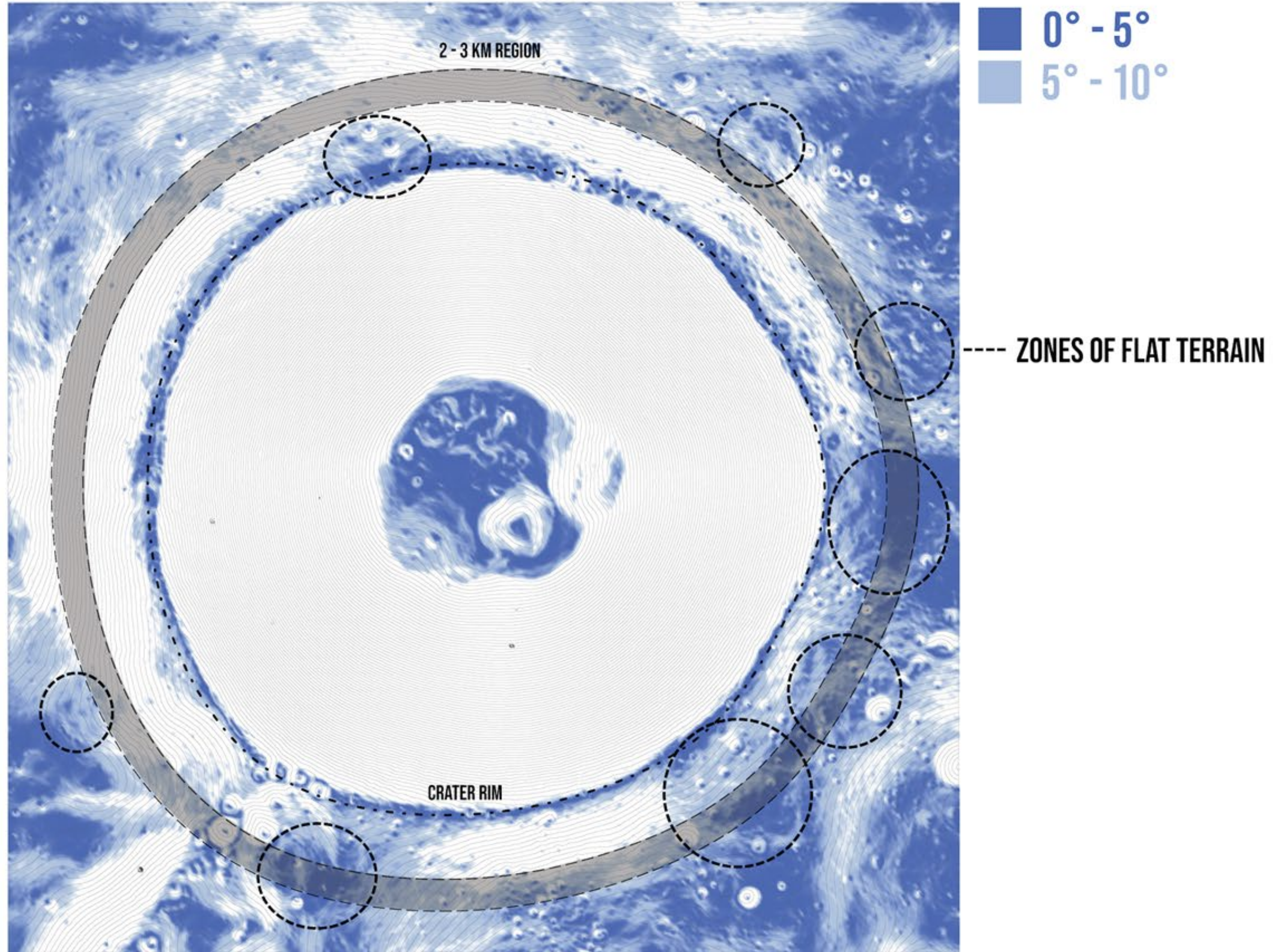
# SITE CONDITION

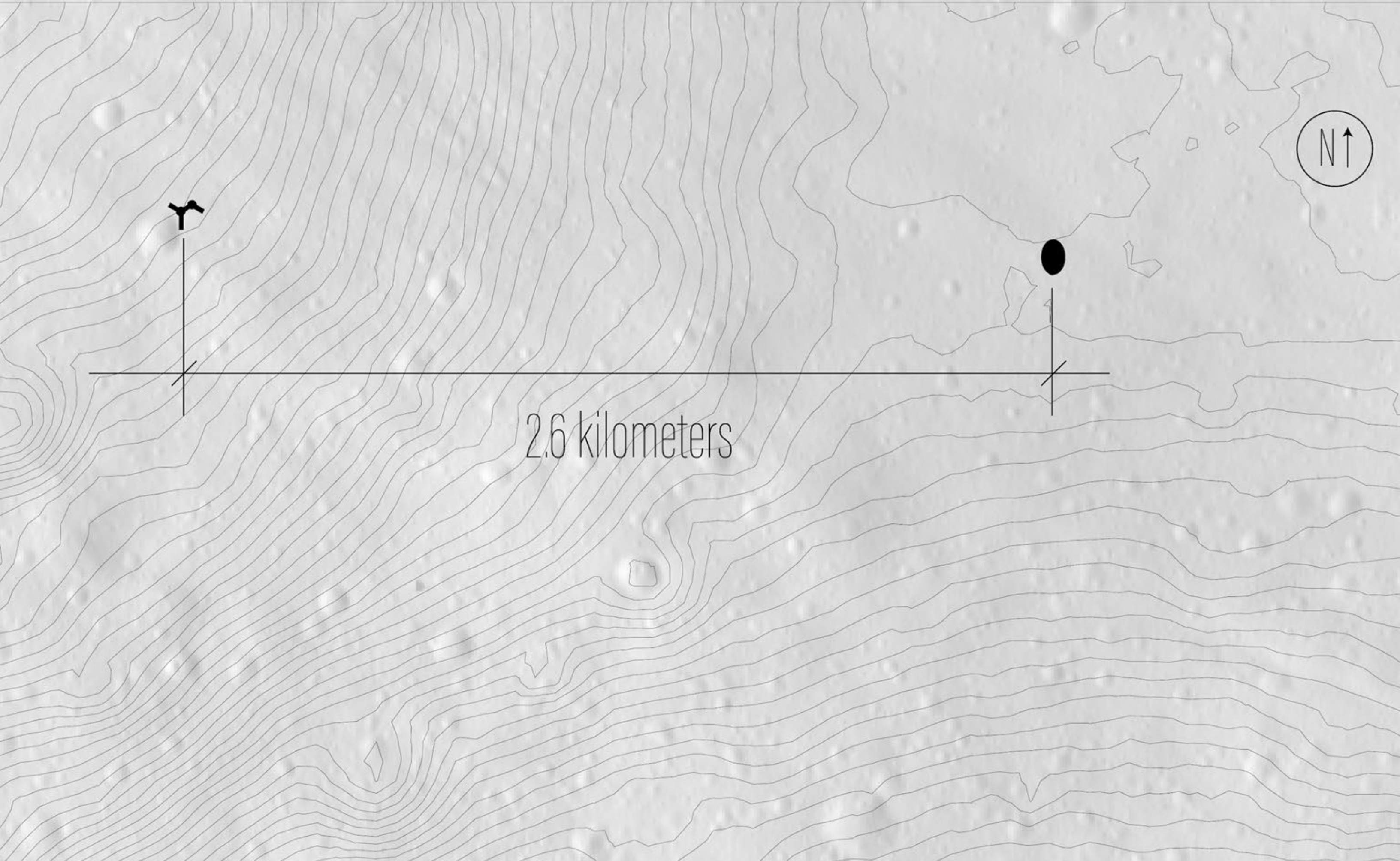


# CRATER RIM OFFSET REGION

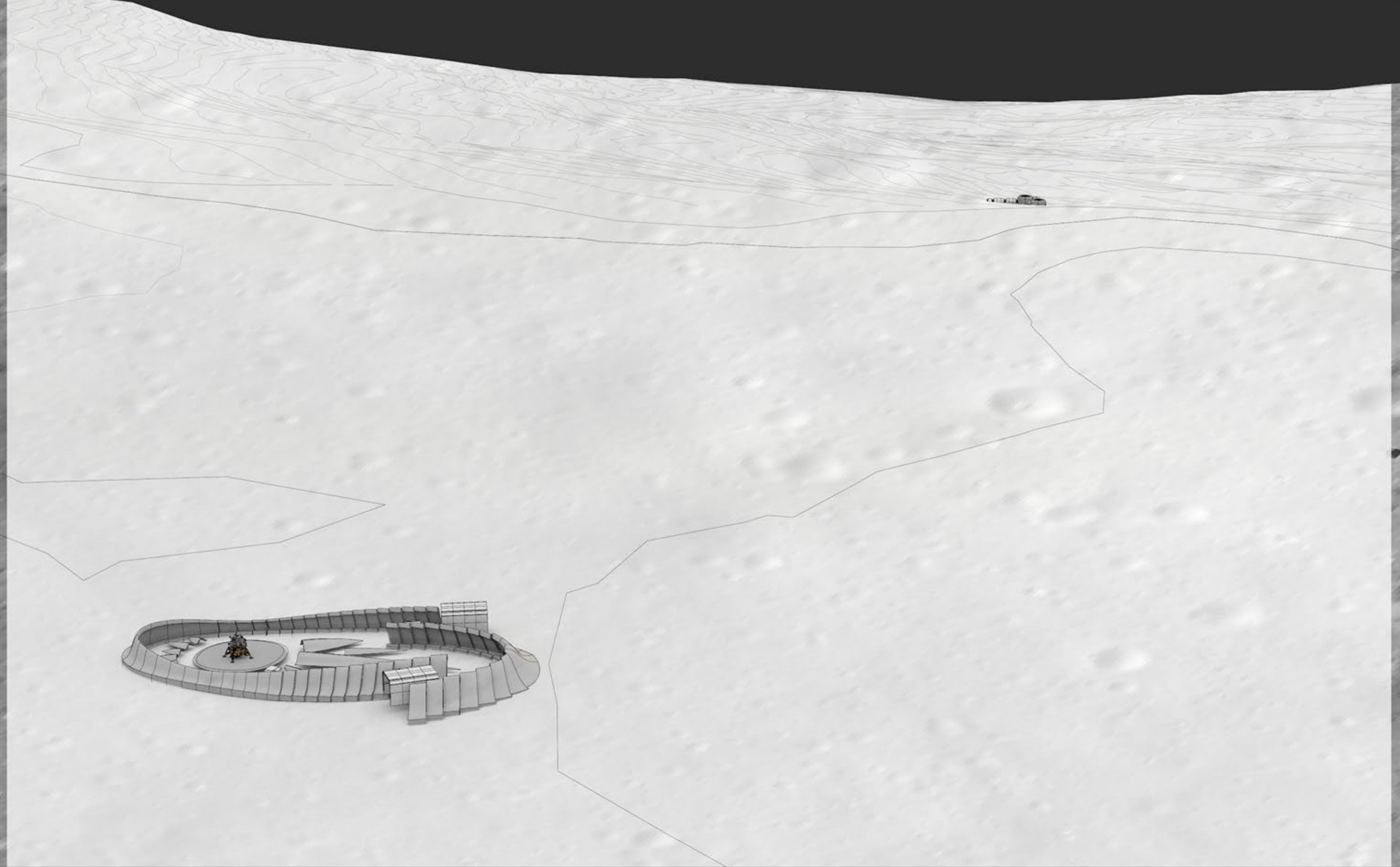


# FLAT REGION





2.6 kilometers

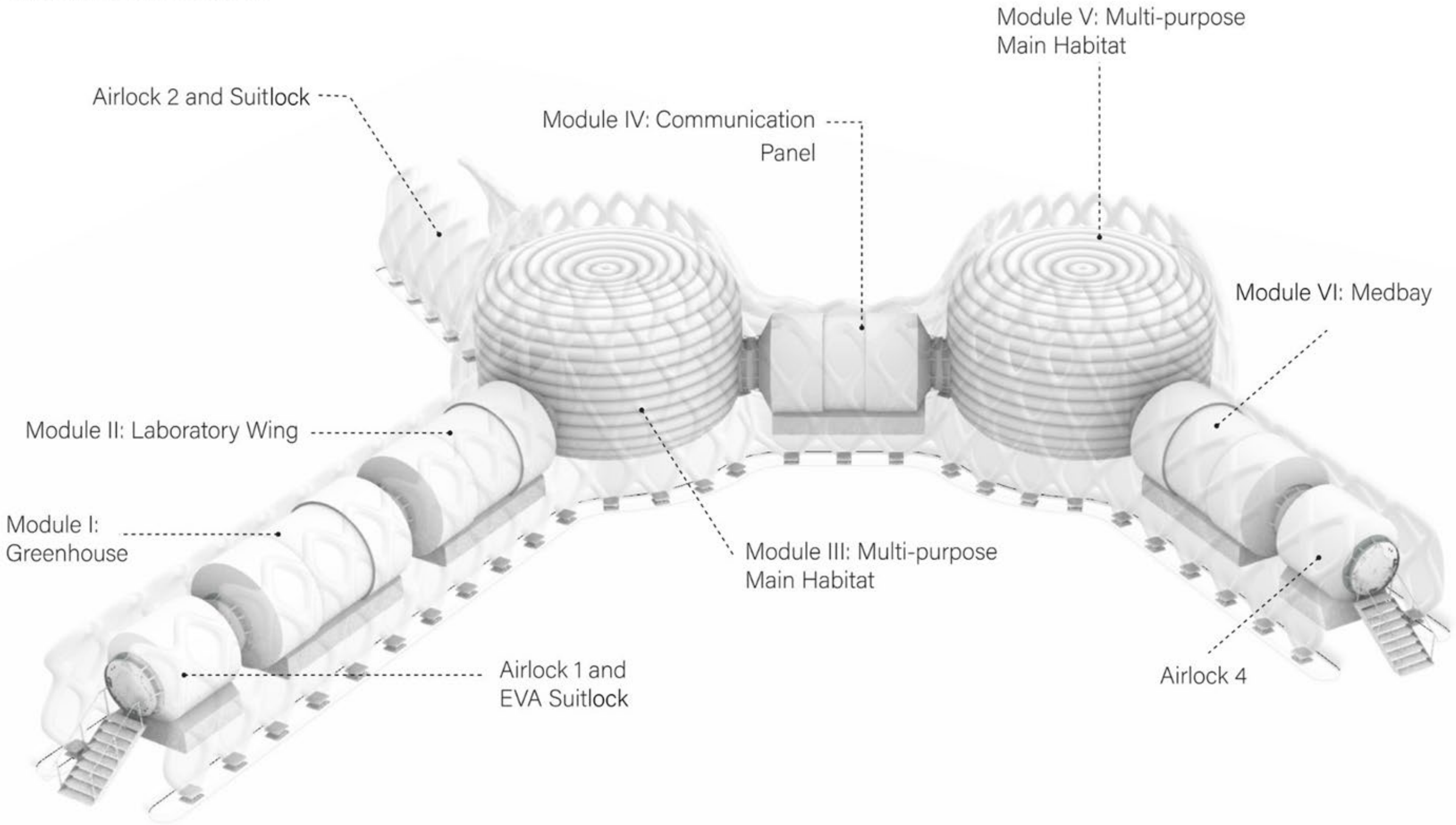


## HABITAT DESIGN

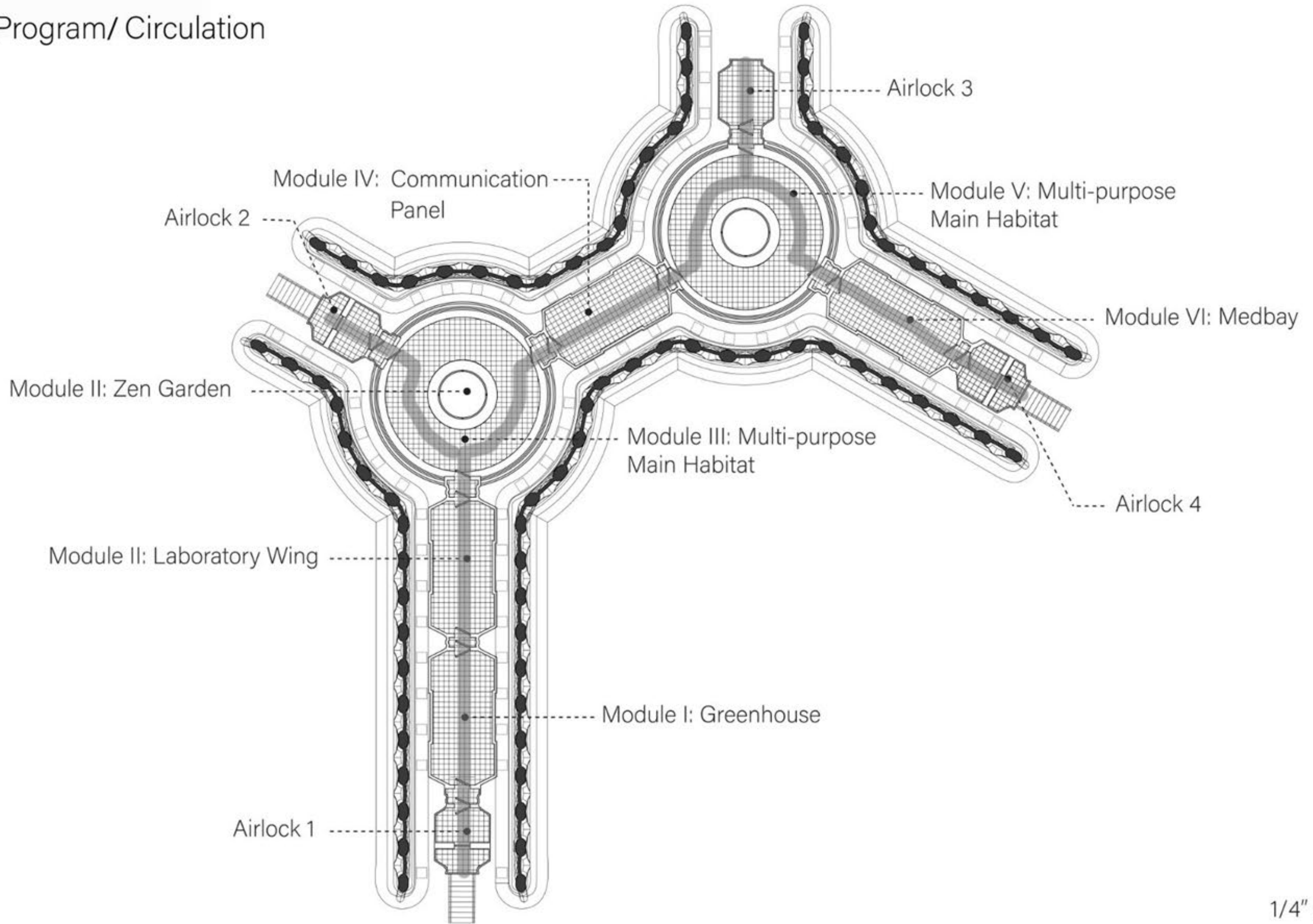
- AXONOMETRIC X-RAY
- FLOOR PLANS
- SECTIONS
- RENDERS

# OASIS HABITAT

SHACKLETON CRATER, SOUTH POLE

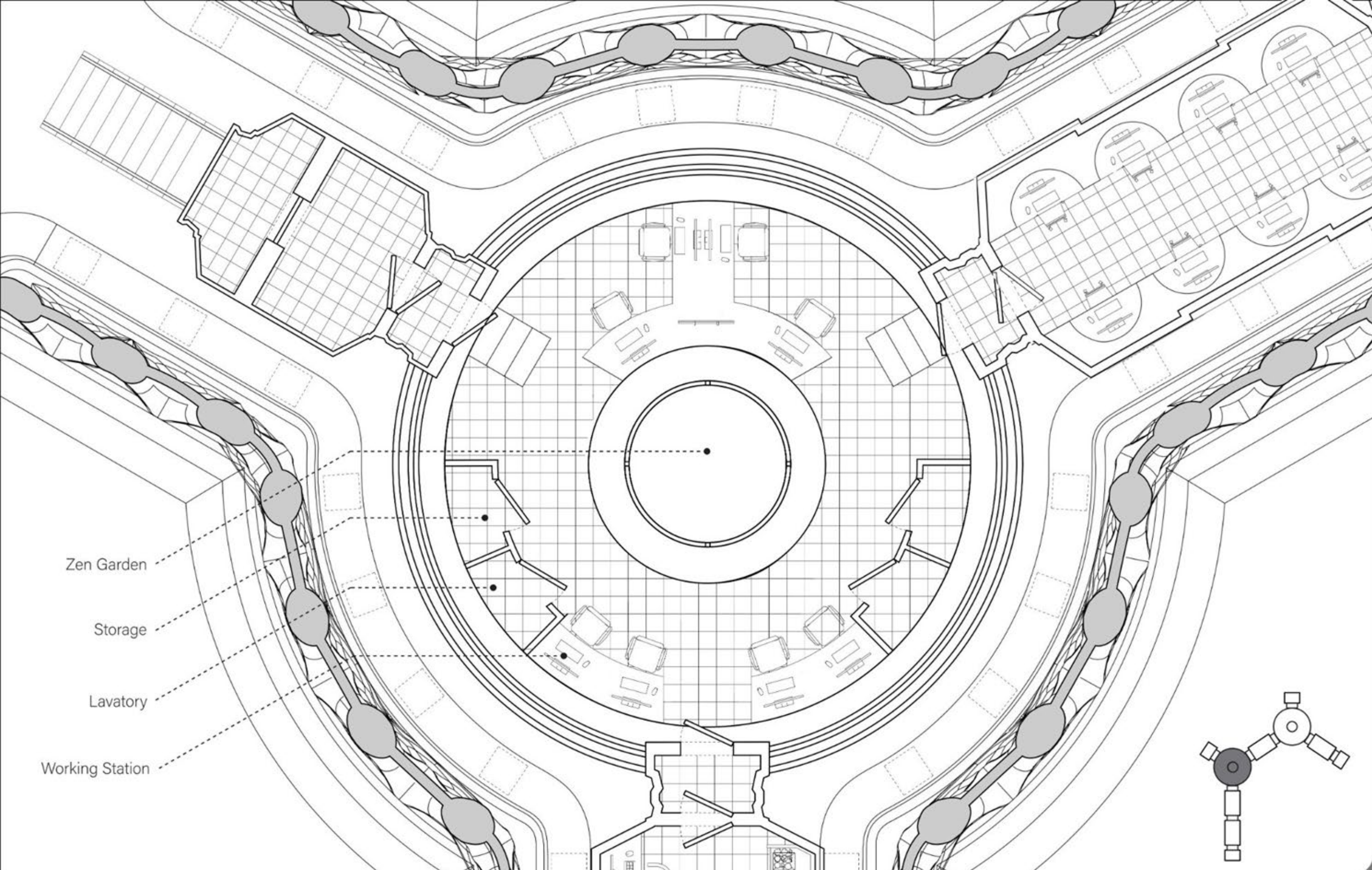


# Habitat: Program/ Circulation



1/4" = 1'-0"



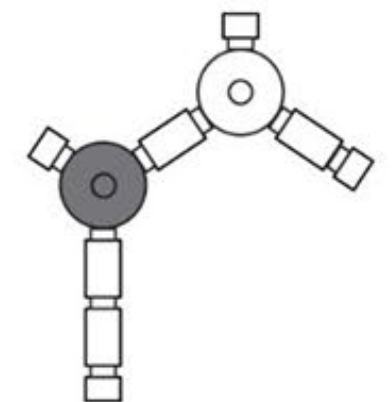


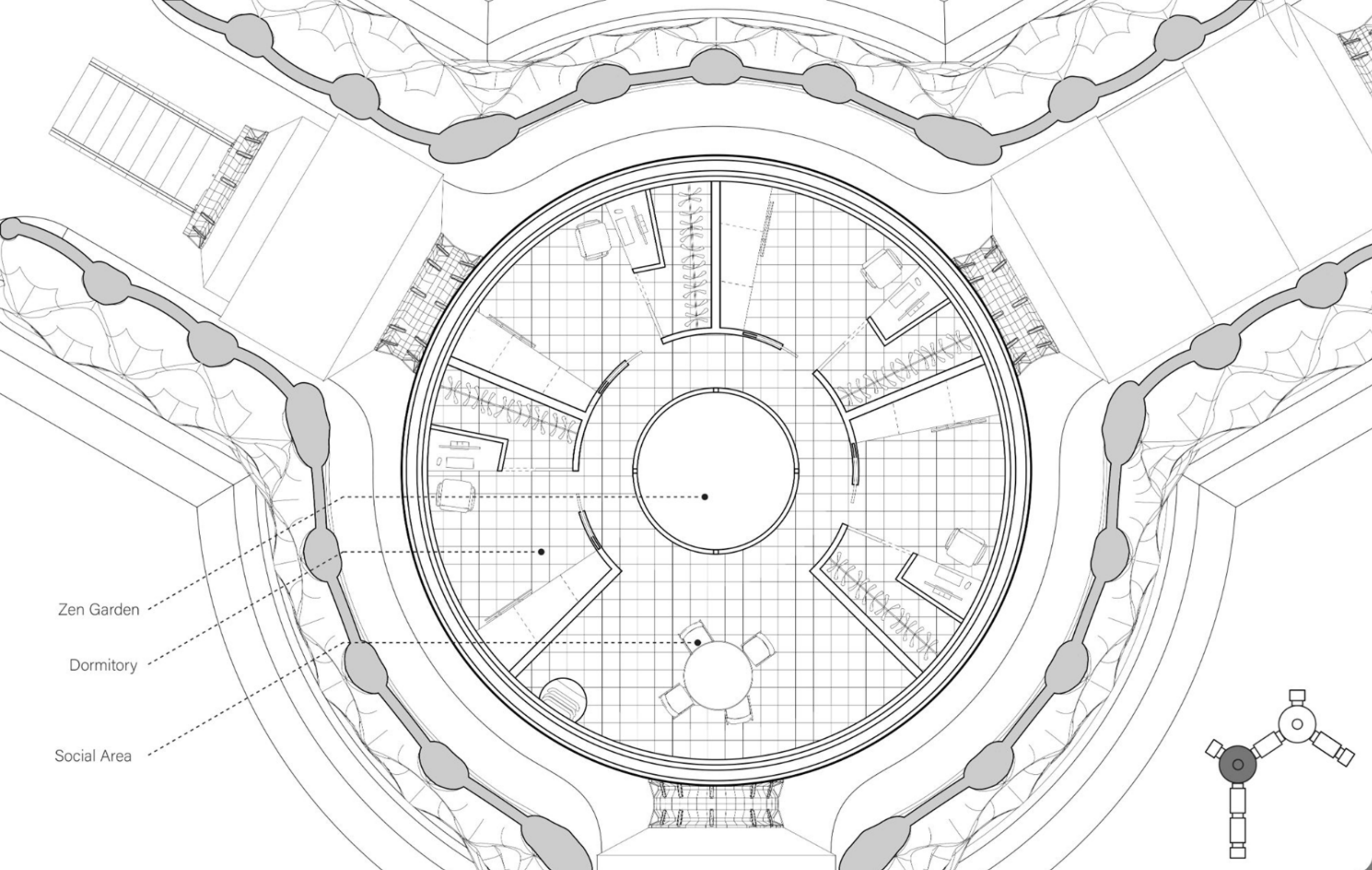
Zen Garden

Storage

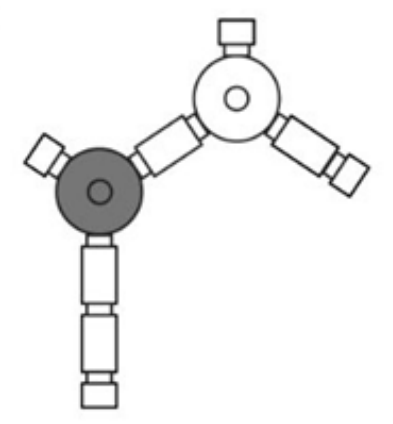
Lavatory

Working Station

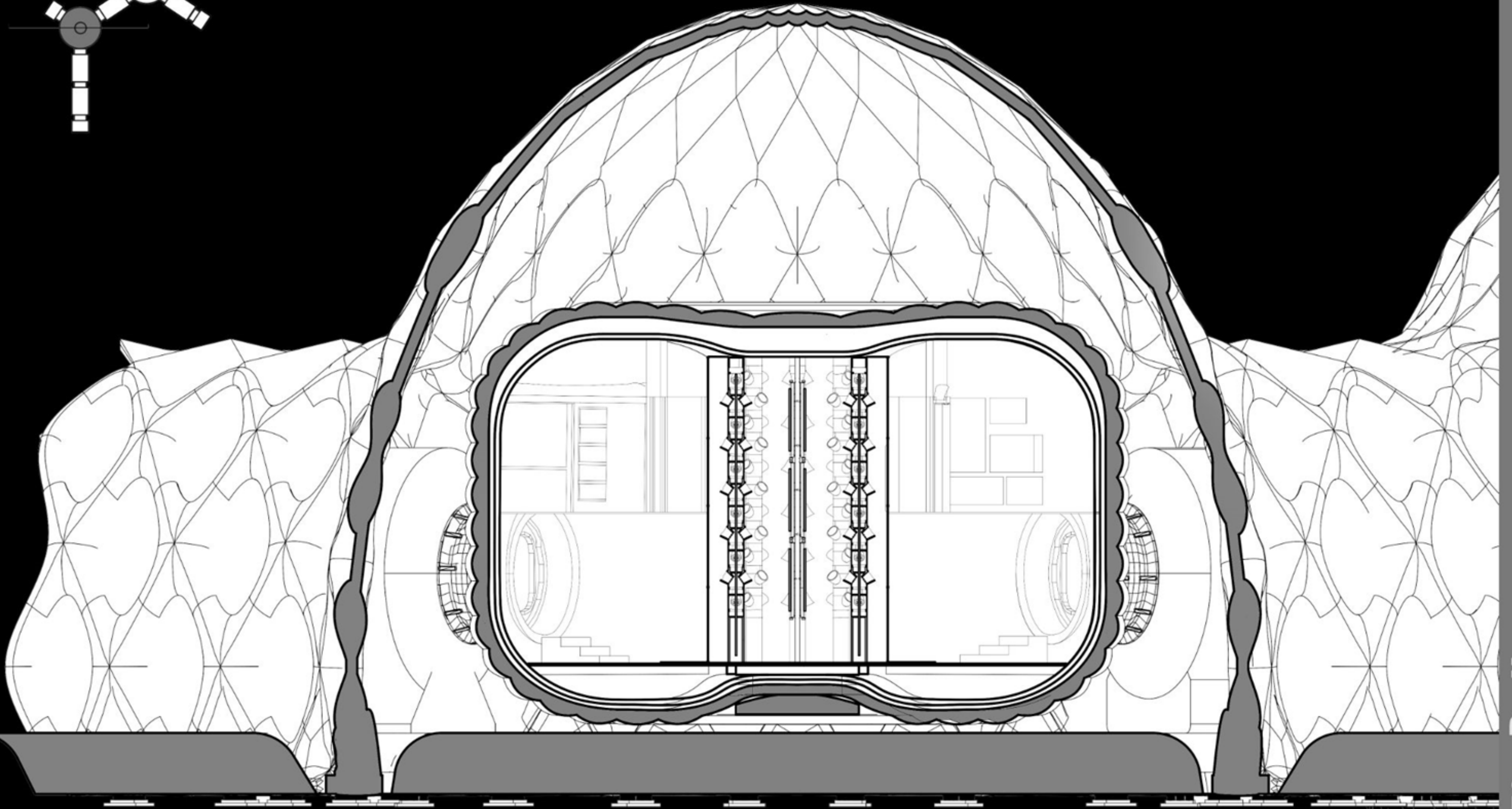
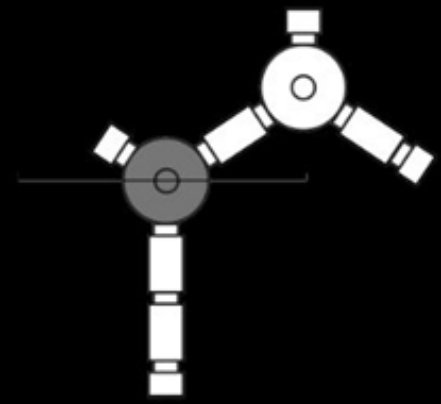




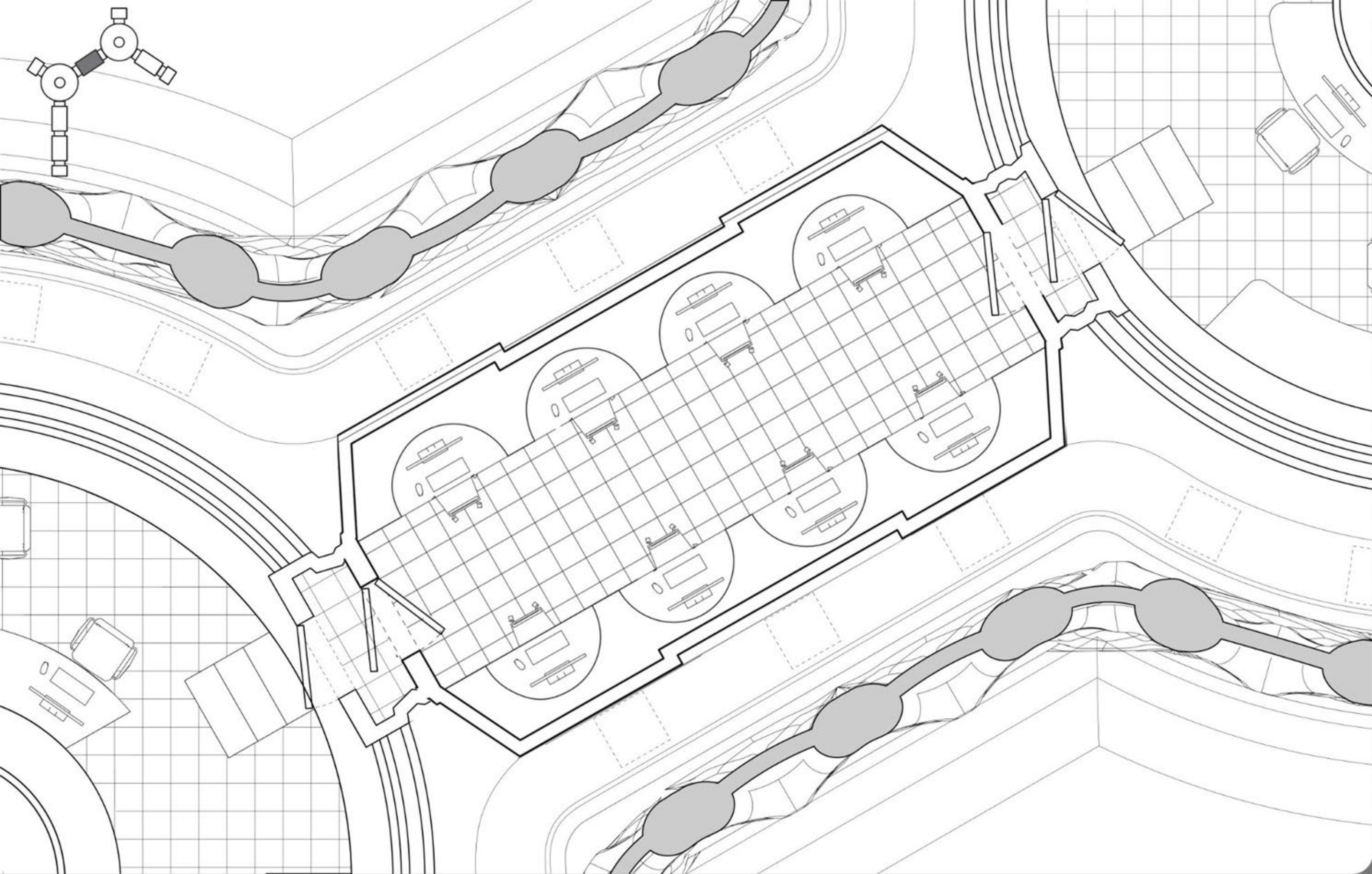
Zen Garden  
Dormitory  
Social Area



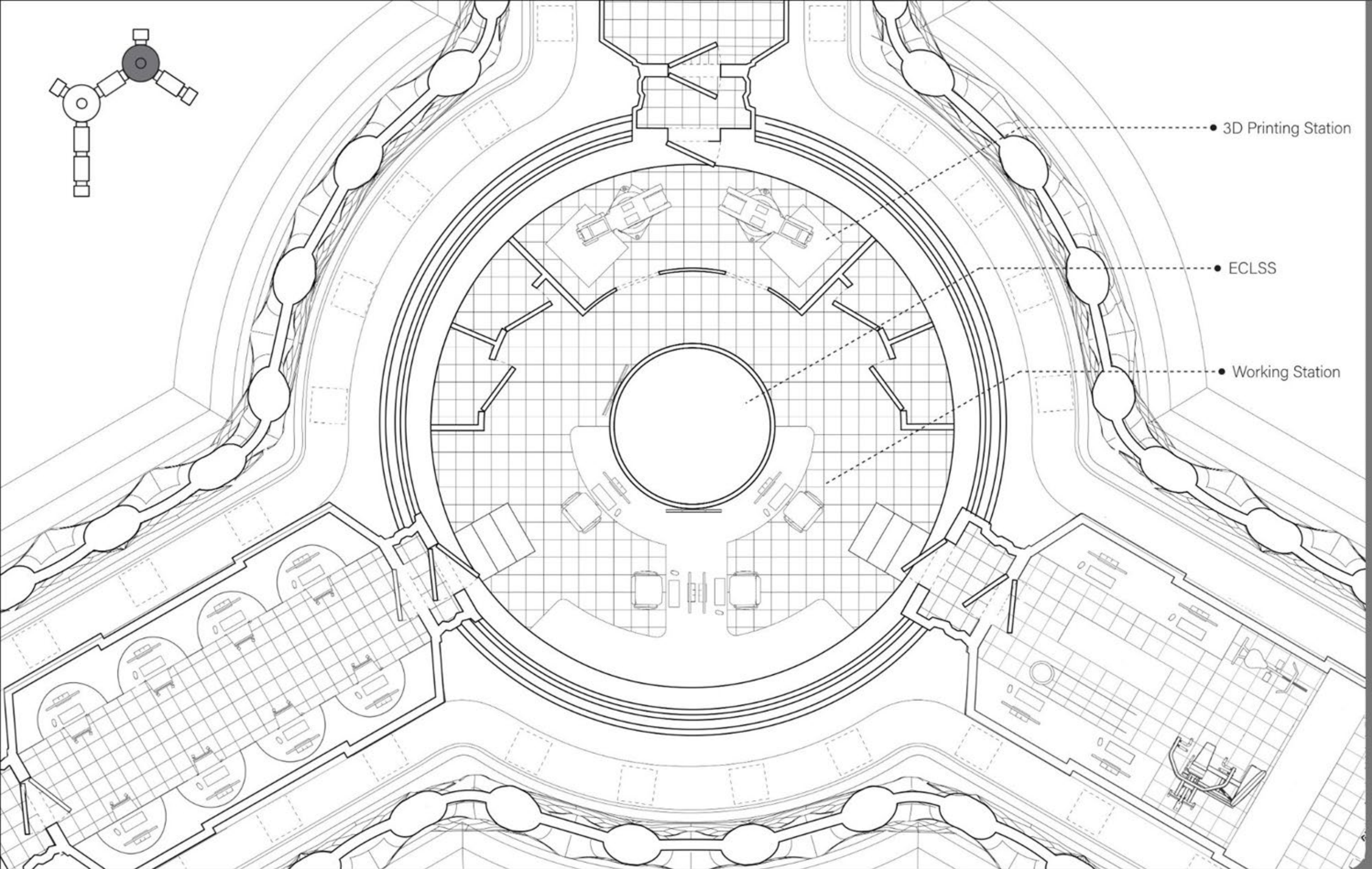
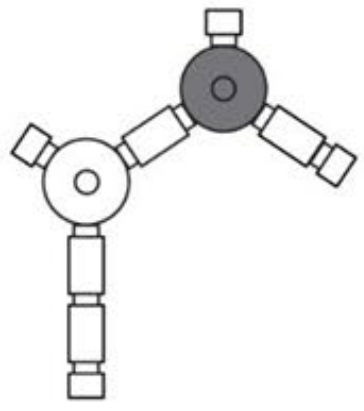
# MODULE III: MULTI-PURPOSE MAIN







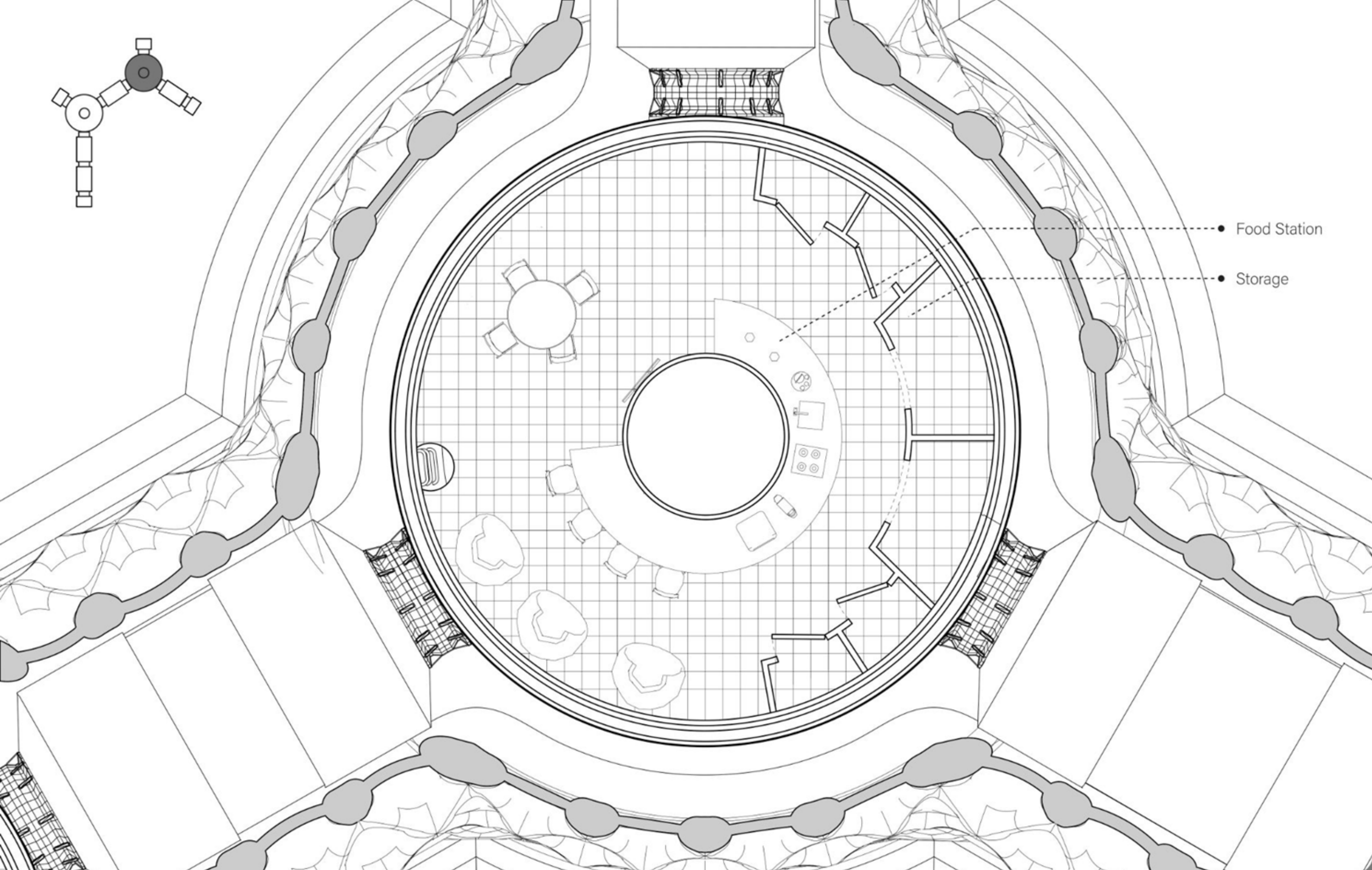




• 3D Printing Station

• ECLSS

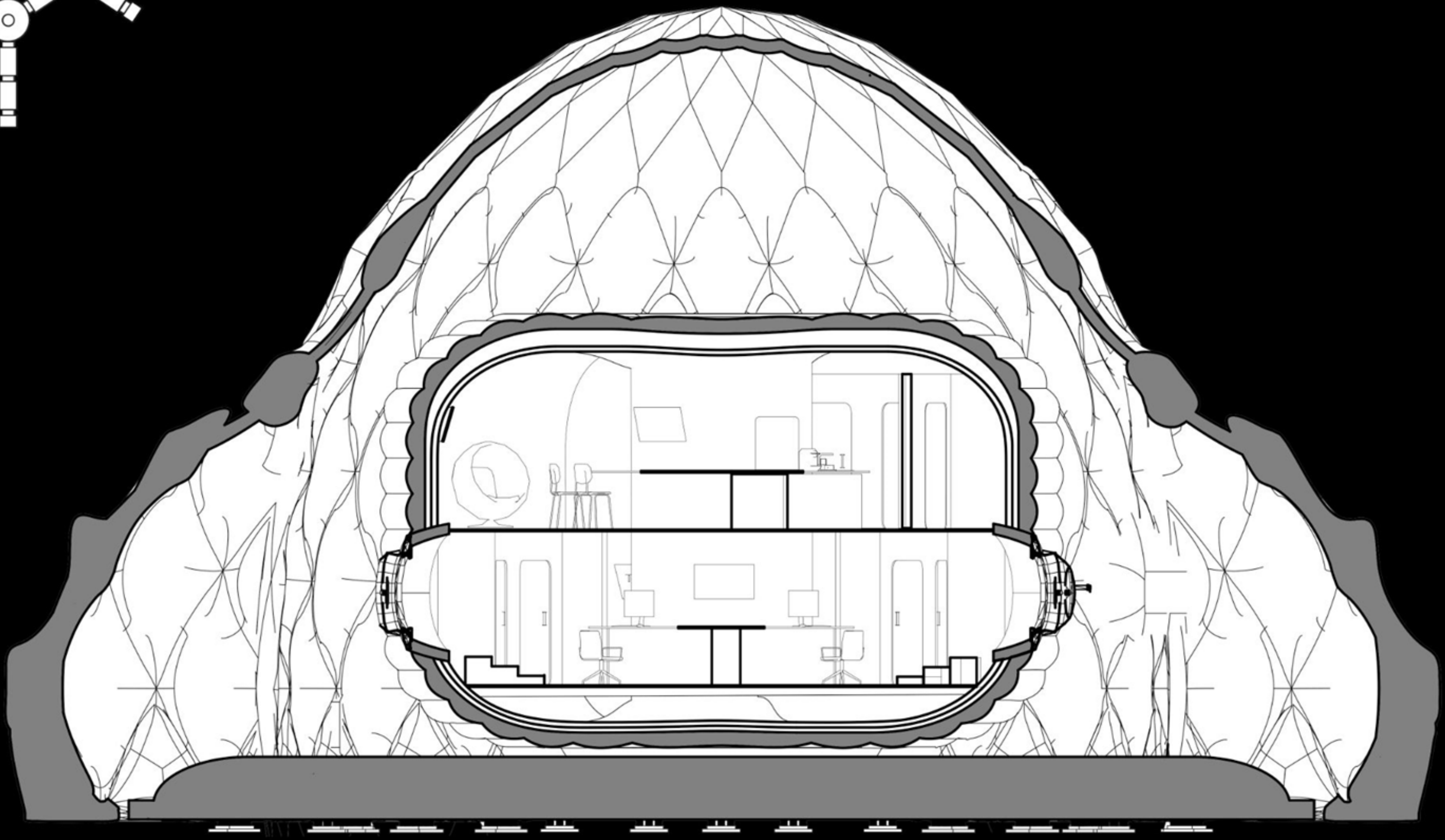
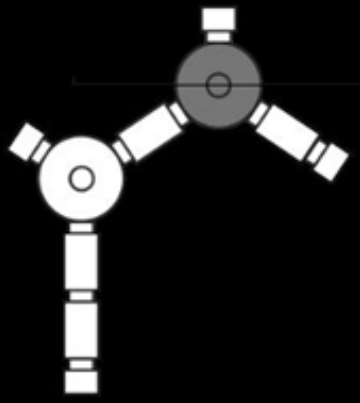
• Working Station



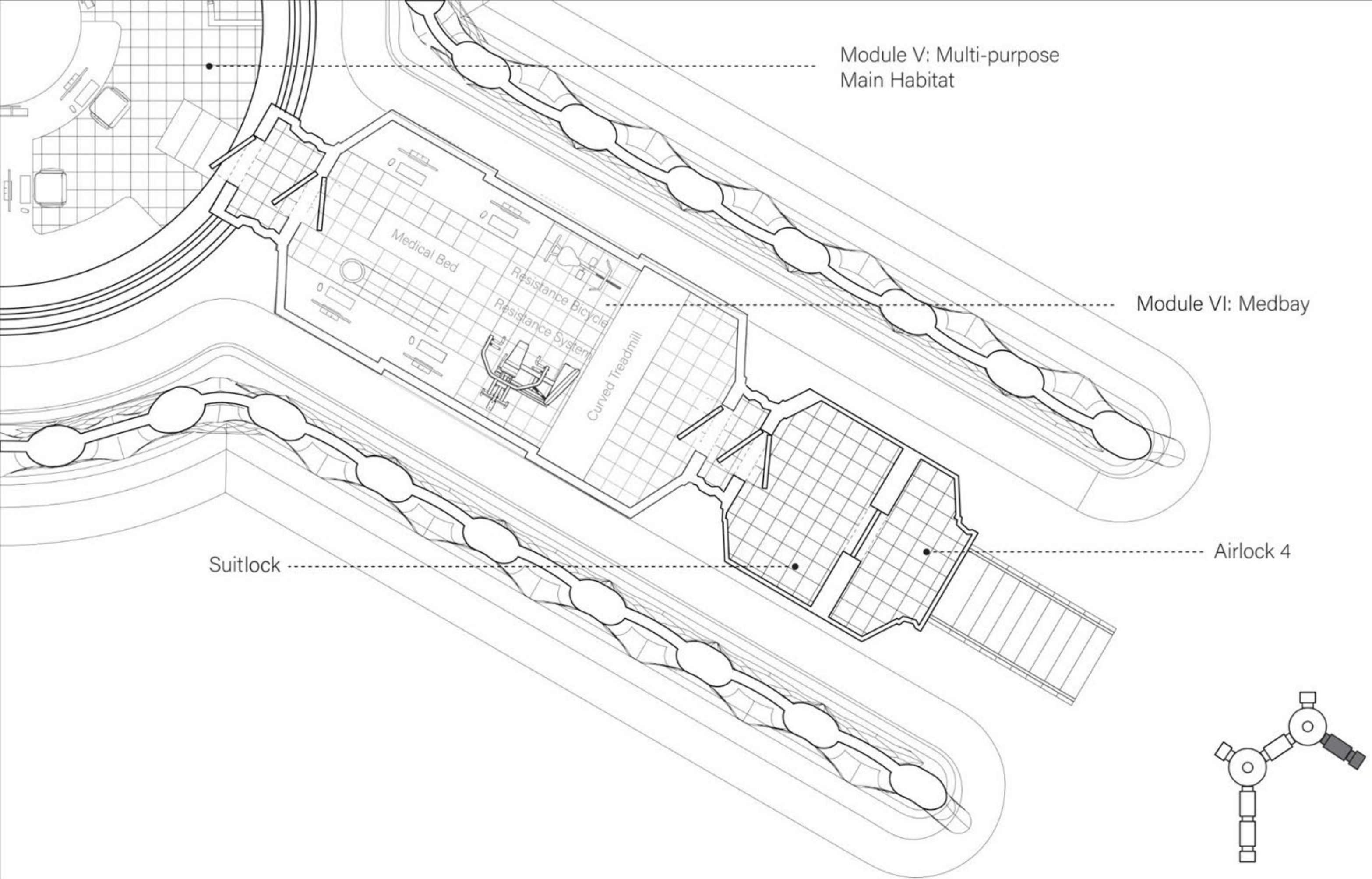
● Food Station

● Storage







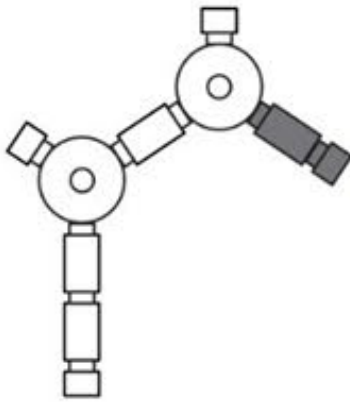


Module V: Multi-purpose  
Main Habitat

Module VI: Medbay

Airlock 4

Suitlock





# ASSEMBLY SEQUENCE

- HABITAT DEPLOYMENT



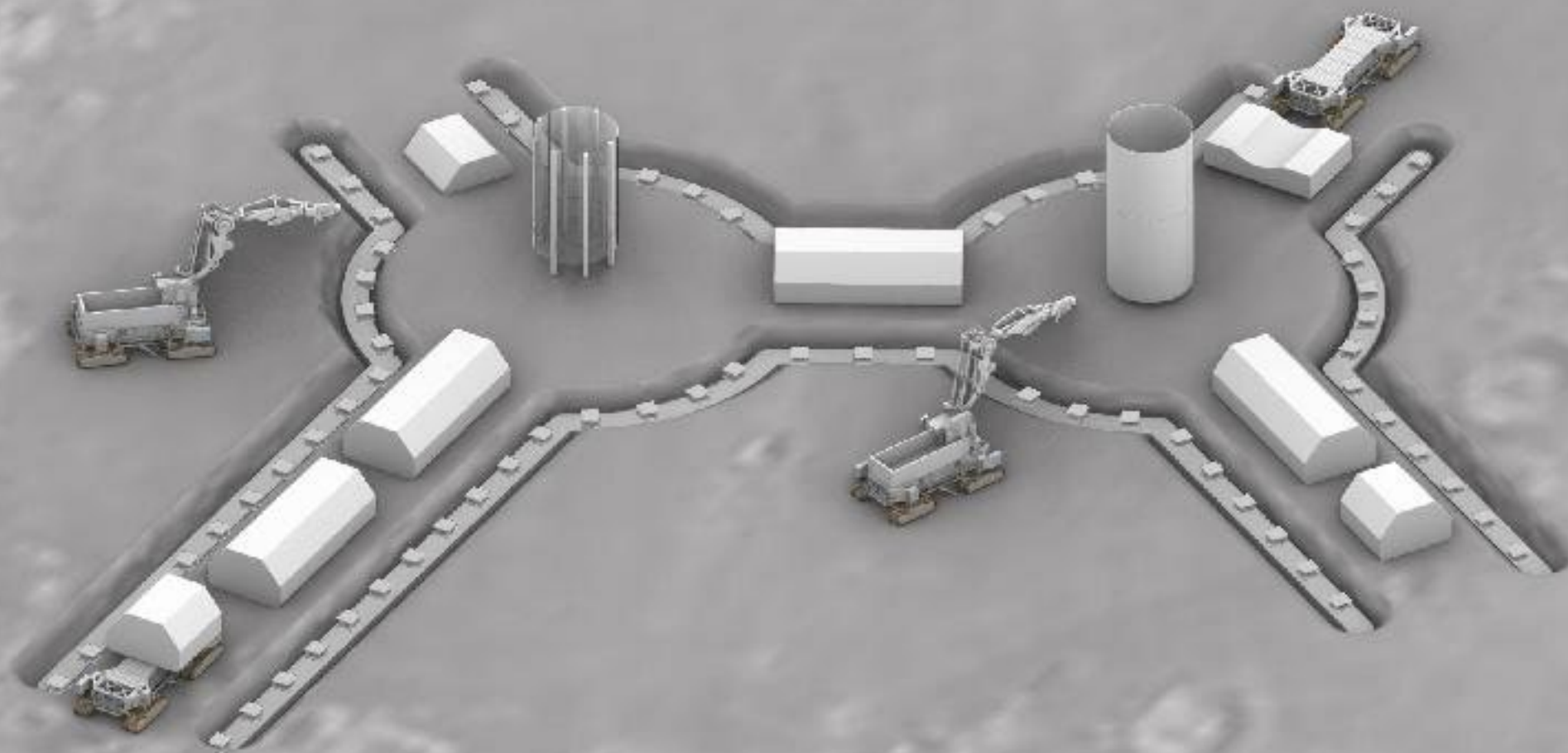
# HABITAT: DEPLOYMENT

1. Excavators deployed for site excavation



# HABITAT: DEPLOYMENT

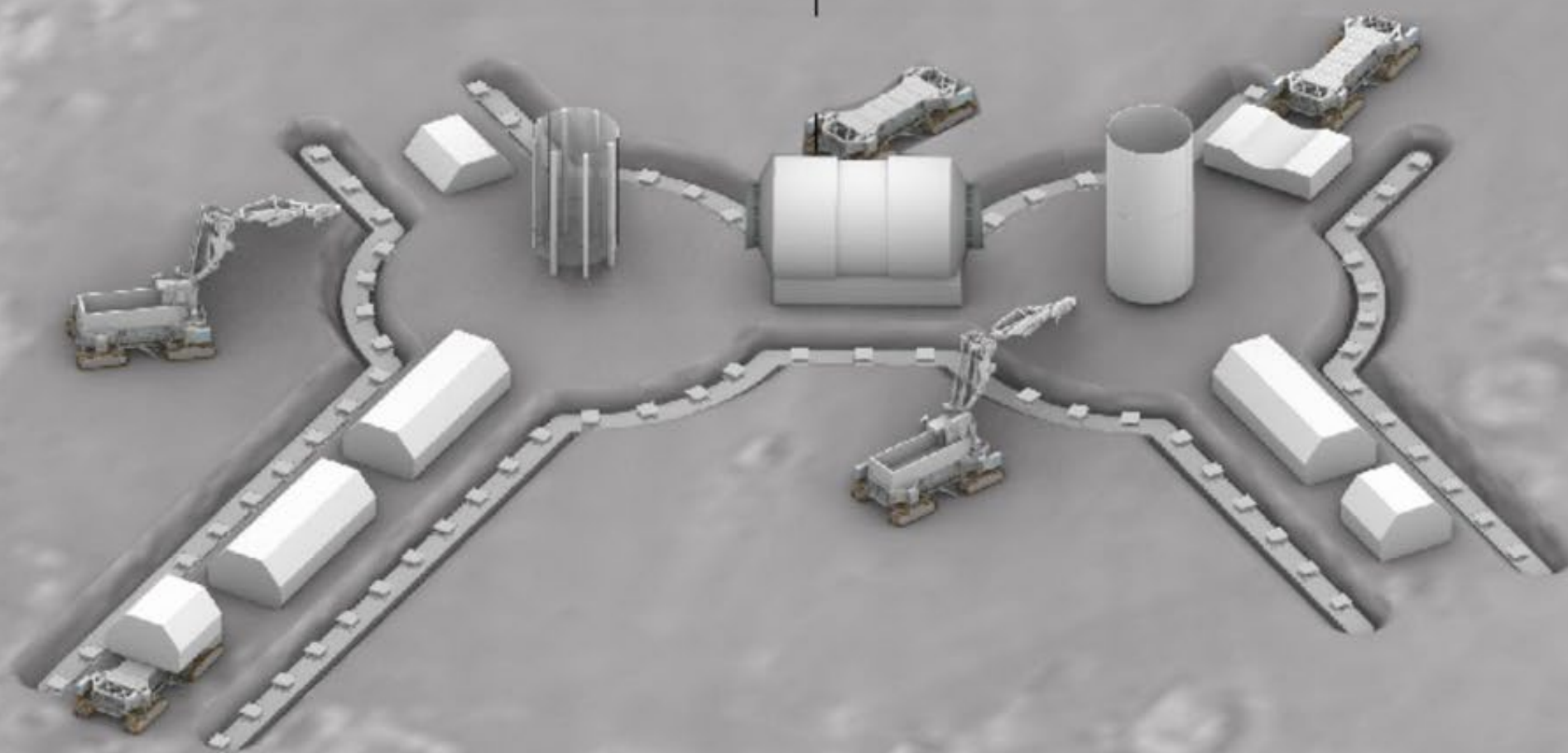
2. Base isolators and hab frames transported to site.





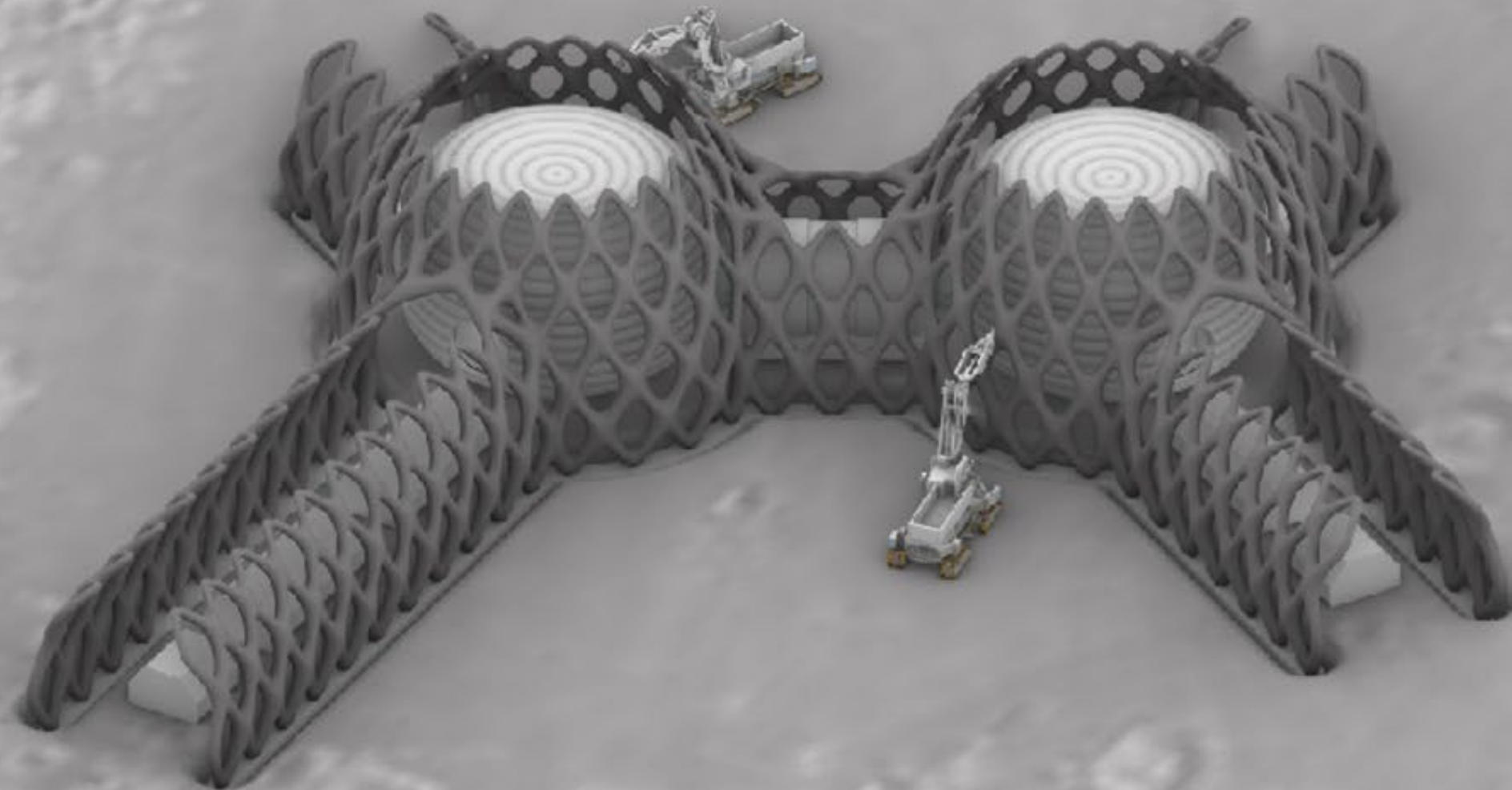
# HABITAT: DEPLOYMENT

3. Center module is transported to site.



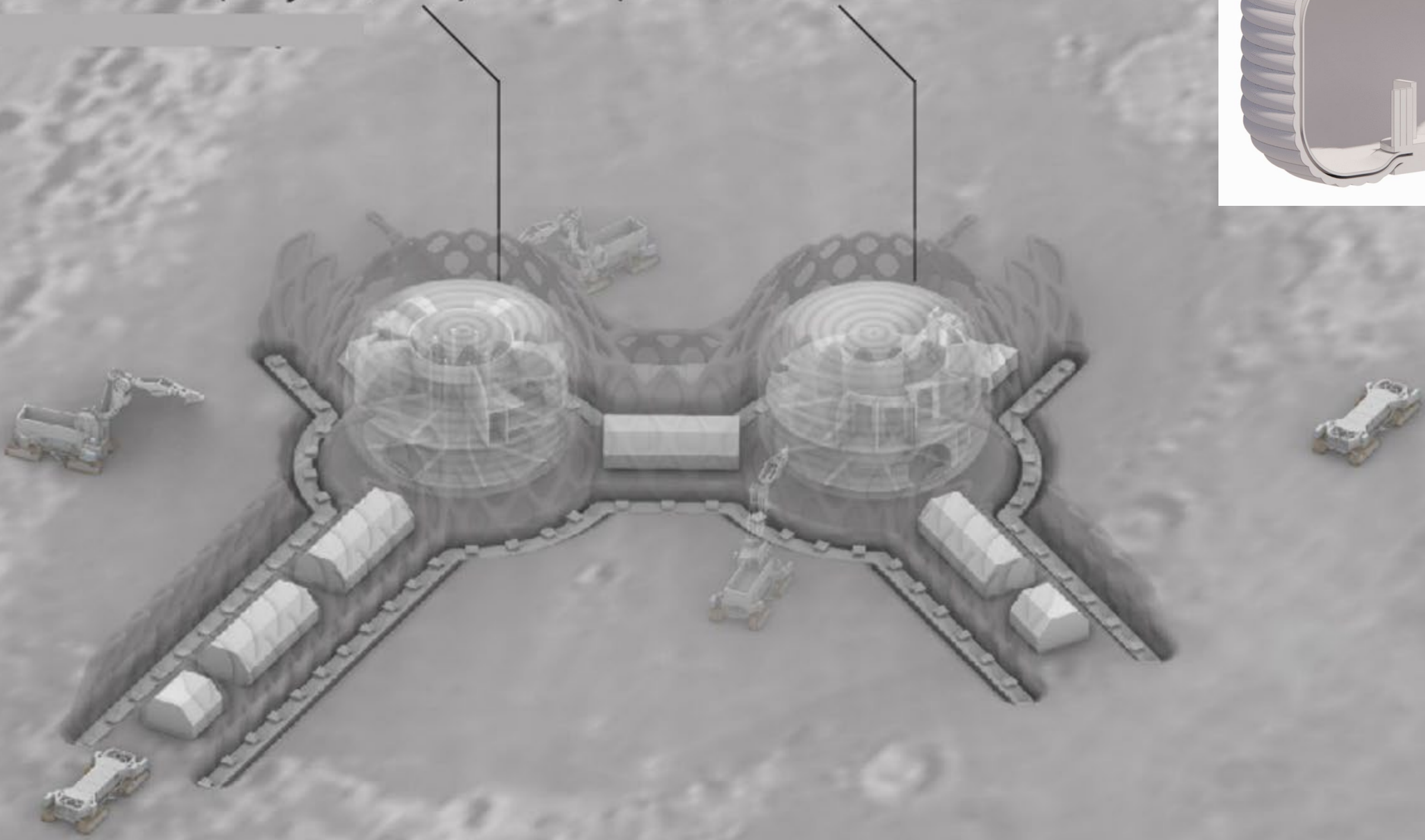
# HABITAT: DEPLOYMENT

4. Outer structure is assembled. Inflatable is deployed.



# HABITAT: DEPLOYMENT

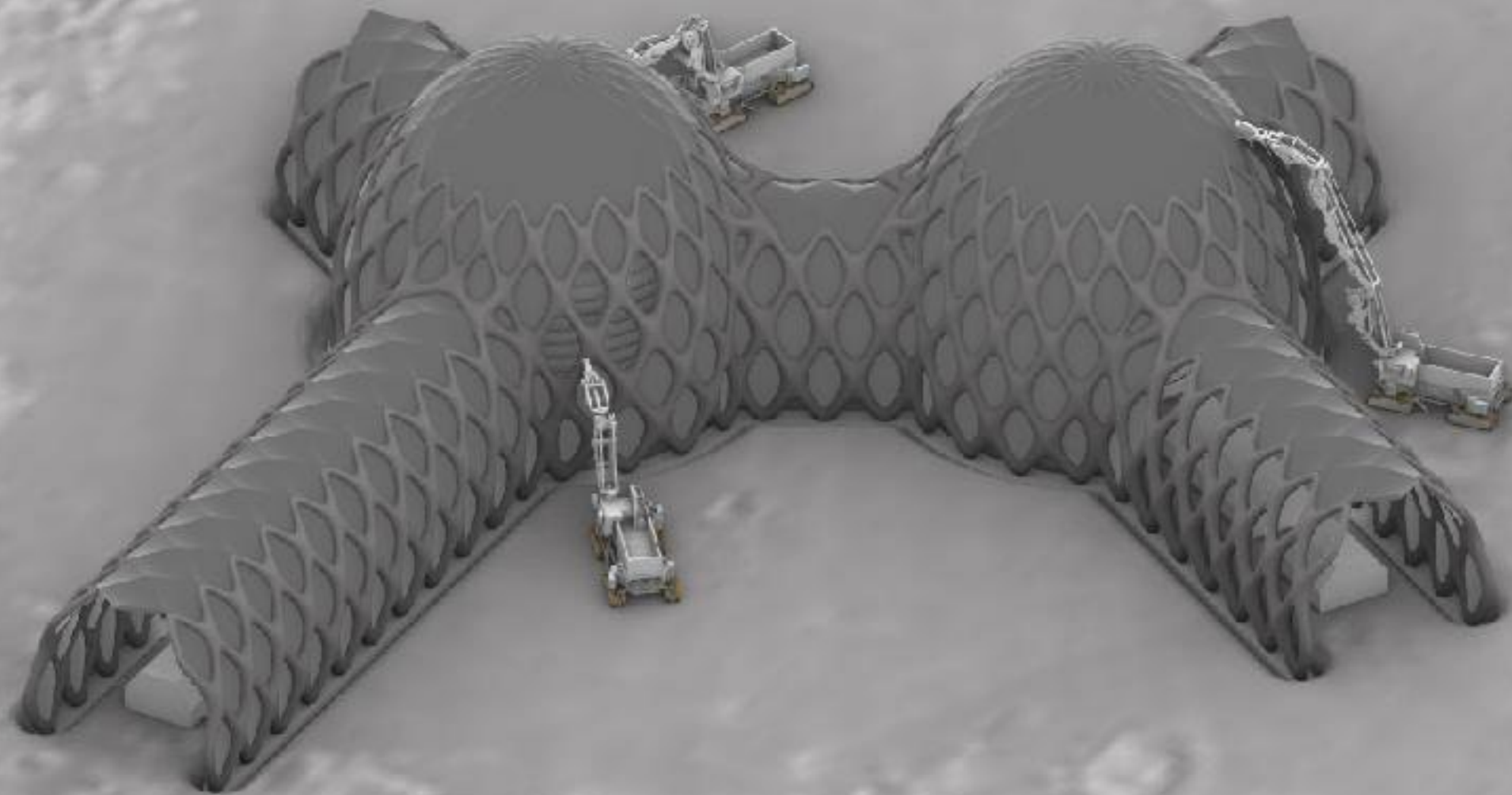
5. Hab frames are deployed, wall/ floor panels are added



# ASSEMBLY SEQUENCE

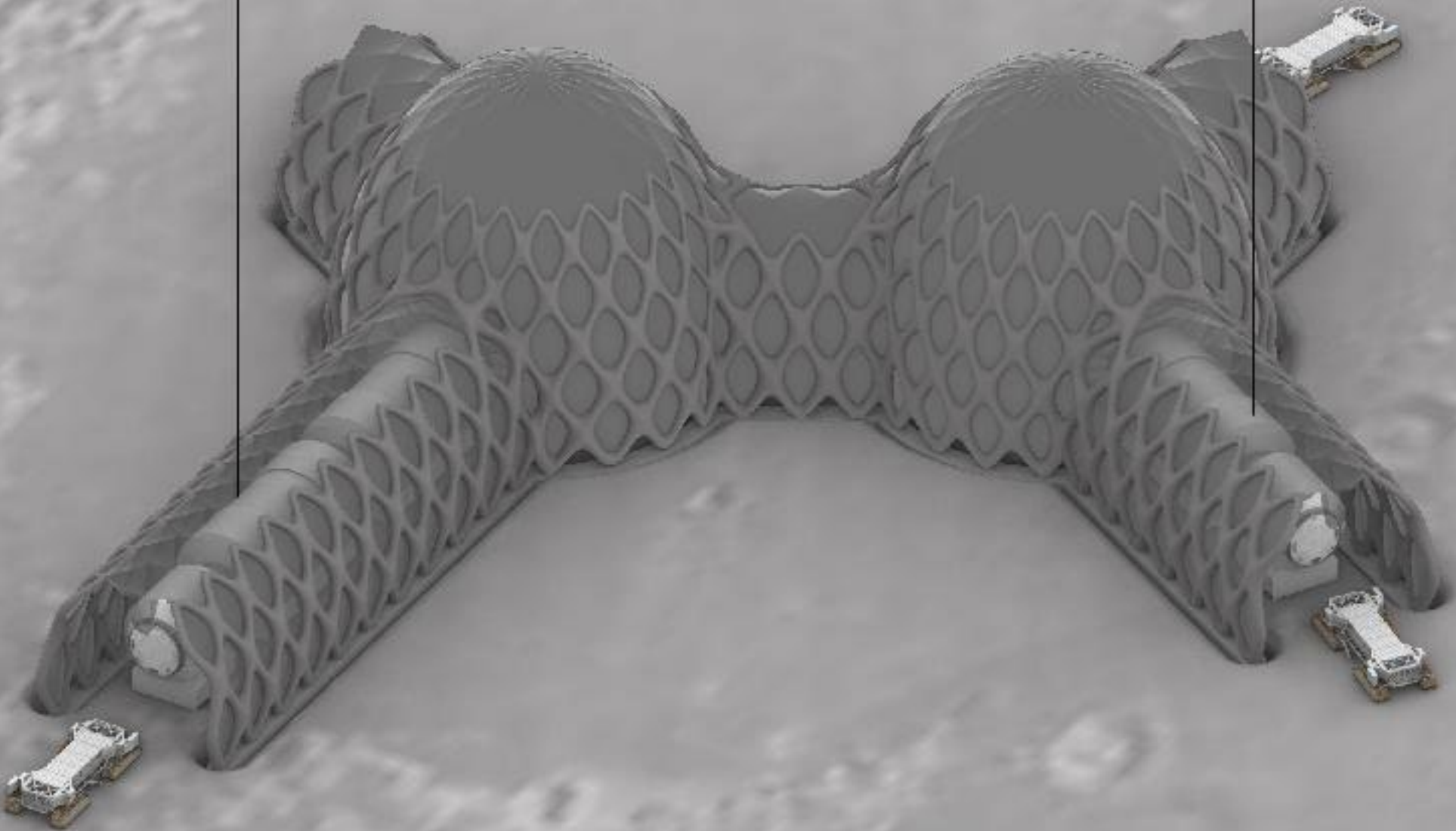
# HABITAT: DEPLOYMENT

6. Paneling system is applied to outer structure.



# HABITAT: DEPLOYMENT

7. Remainder of modules are transported and placed on site.



TIMELINE

TIMELINE

TIMELINE

1	TASKS	START	END	2024	2025	2035	2045	2050	2060
2	EQUIPMENT DELIVERY	2024	2024						
3	RASSOR	2024	2024						
4	3D Printer	2024	2024						
5	Crane	2024	2024						
6	ROBOTIC BAY	2024	2060						
7	Polyethylene and Regolith Collecting	2024	2060						
8	Energy Grid	2024	2024						
9	HABITAT CONSTRUCTION AID	2024	2060						
10	Excavating and Collecting with RASSOR	2024	2025						
11	3D Printing Base	2024	2035						
12	3D Print Regolith Frame	2025	2060						
13	Inflatable Delivery	2035	2060						
14	Airlock Delivery + Installation	2035	2060						
15	Panel Delivery + Installation	2025	2035						
16	Crane Lifting Capstone	2060	2060						
17	LANDING PAD	2024	2060						
18	FAST Landing Pad	2024	2024						
19	Excavating	2024	2026						
20	Phase 1 Barrier Printing	2025	2045						
21	Phase 2 Barrier Printing	2045	2060						
22	Phase 3 Robotic Bay Printing	2050	2060						

## GREEN HOUSE

- LABORATORY WING
- ZEN GARDEN
- ROBOTS

Microgravity and organism's cells

Becoming self sufficient

How to maintain food quantity and quality

## STATED AIMS

Reduce the weight of supplies lifted off of earth

More effective agricultural growth

Increase health benefits, relief stress and boost morale

Lettuce // 30-50 days // 0.25 in /week

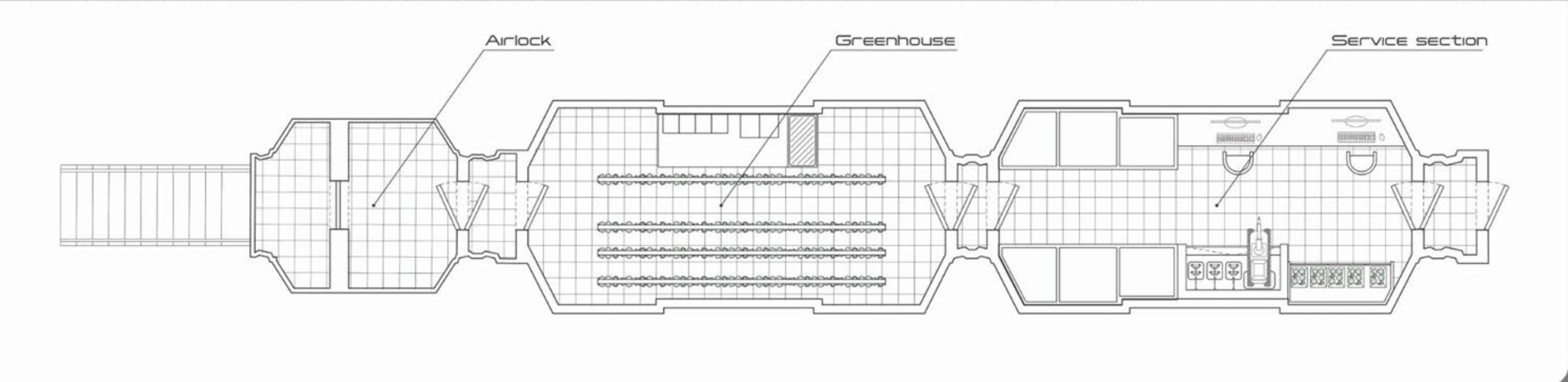
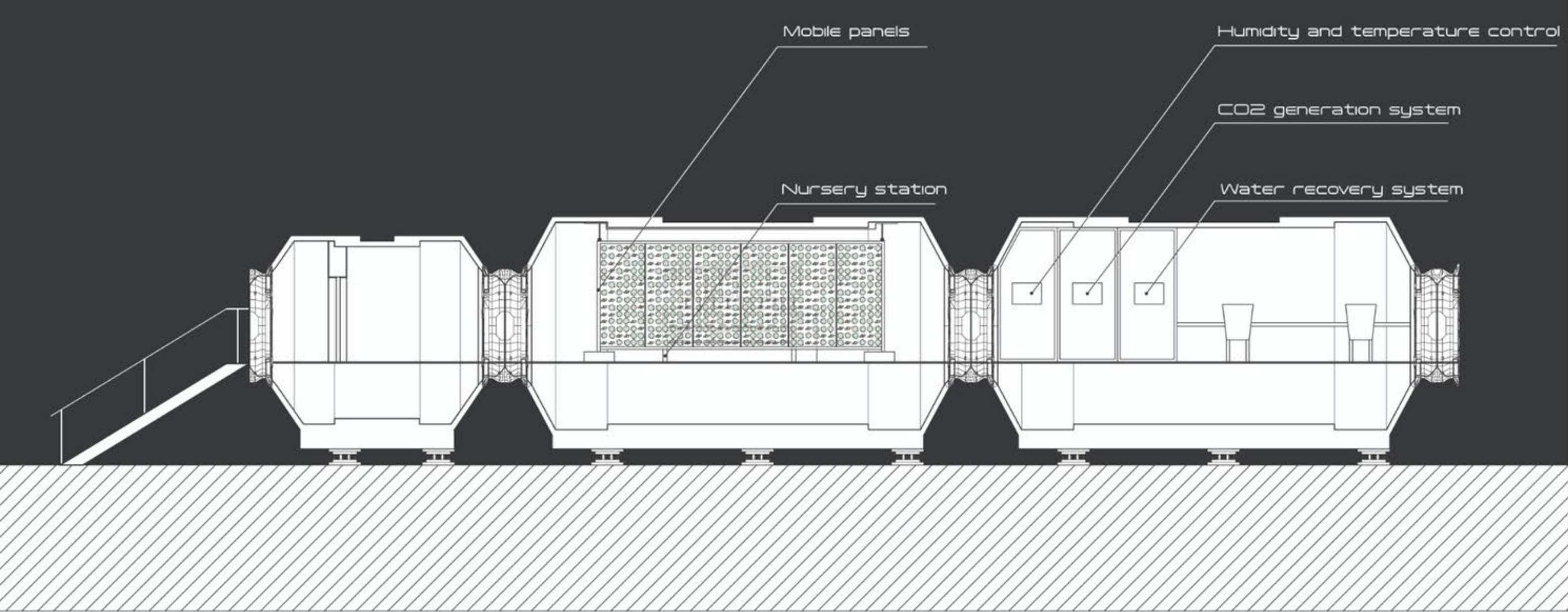
## SELECTED VEGETABLES

Cucumber // 55-70 days // 1 in/week

Radish // 30-40 days // 1in/week

Sweet pepper // 60-90 days // 2 in week





Drip irrigation tube

Plant panel

Gutters

Cultivation area tank

Nutrient and pH Reservoir

Dosing panels

Seeding trough

Nursery station tank

### Hydroponics system

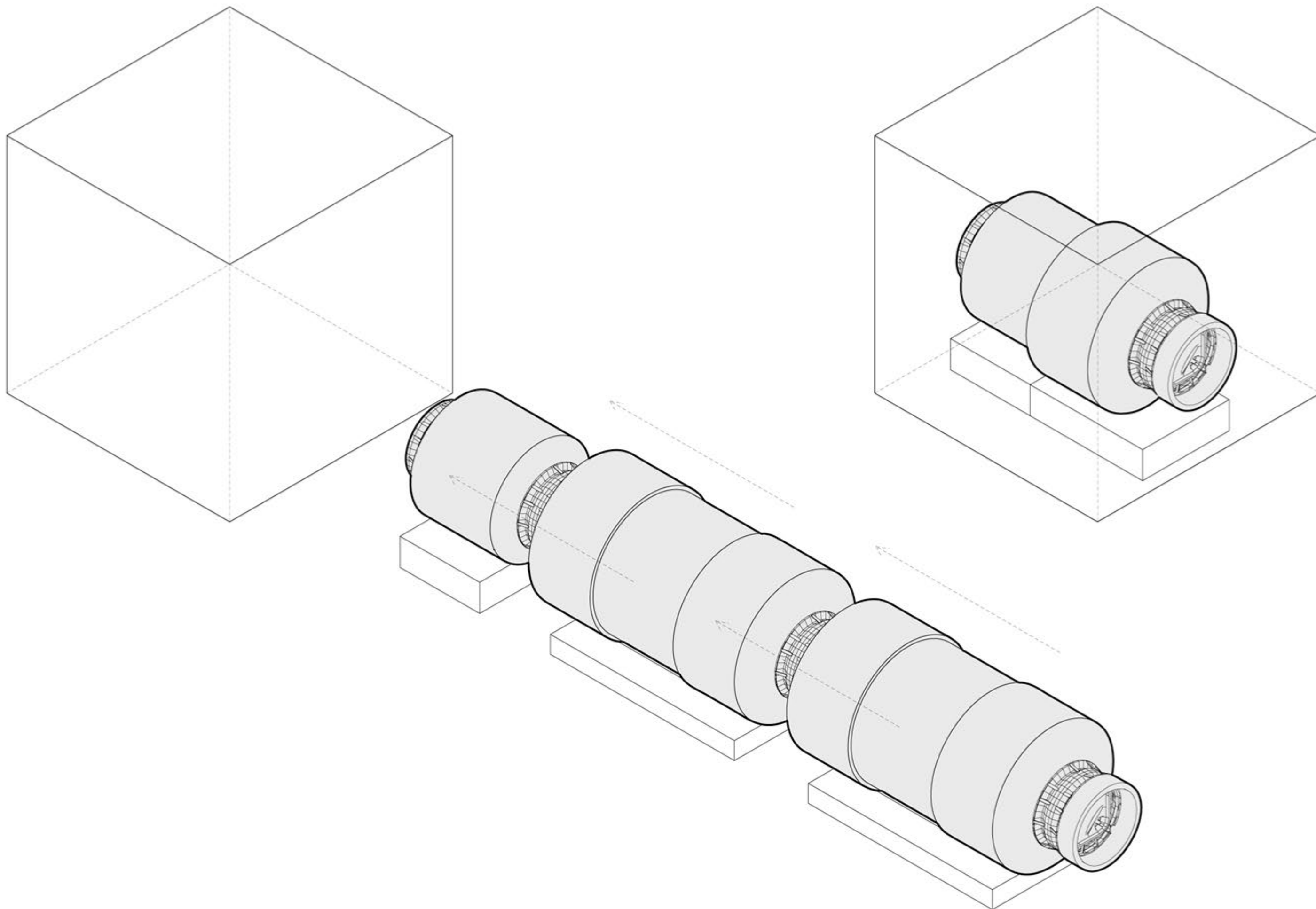
Overhead pipes drip water and nutrients to plants below

Uses 5 gallons of water a day

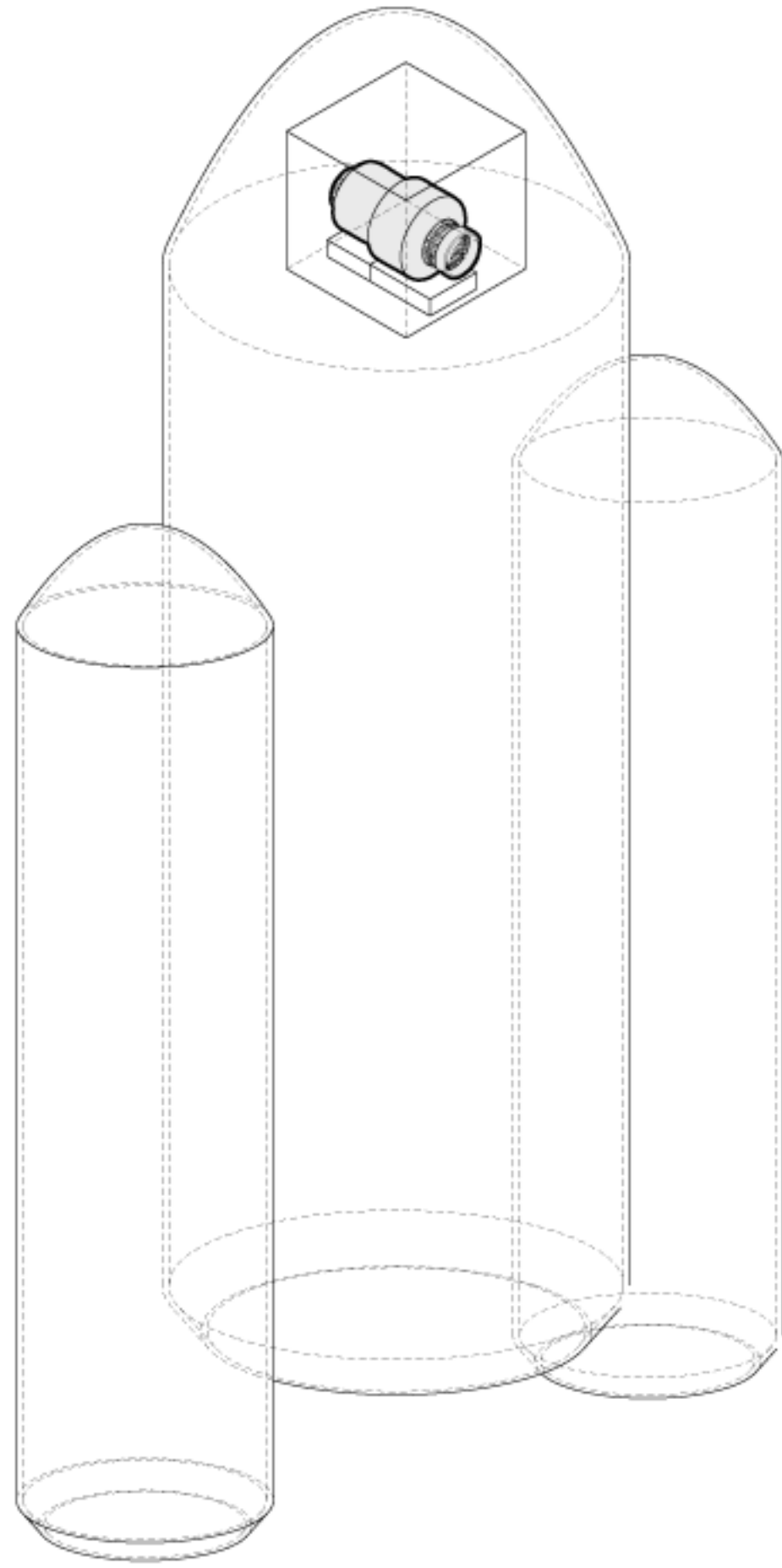
### Led Array

Red lights: essential for stem and leaf growth

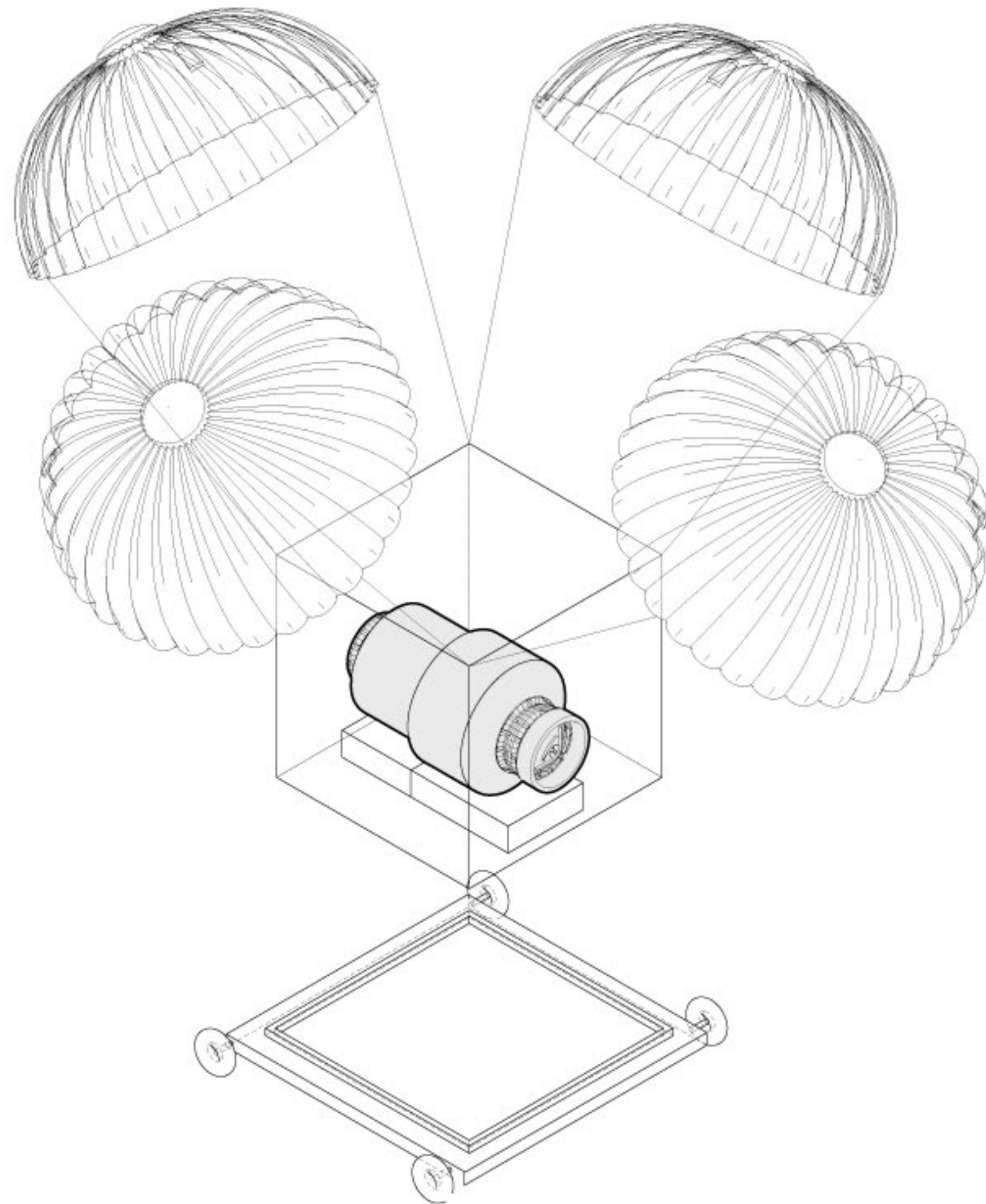
Blue Lights: develop thick stem and promote chlorophyll production



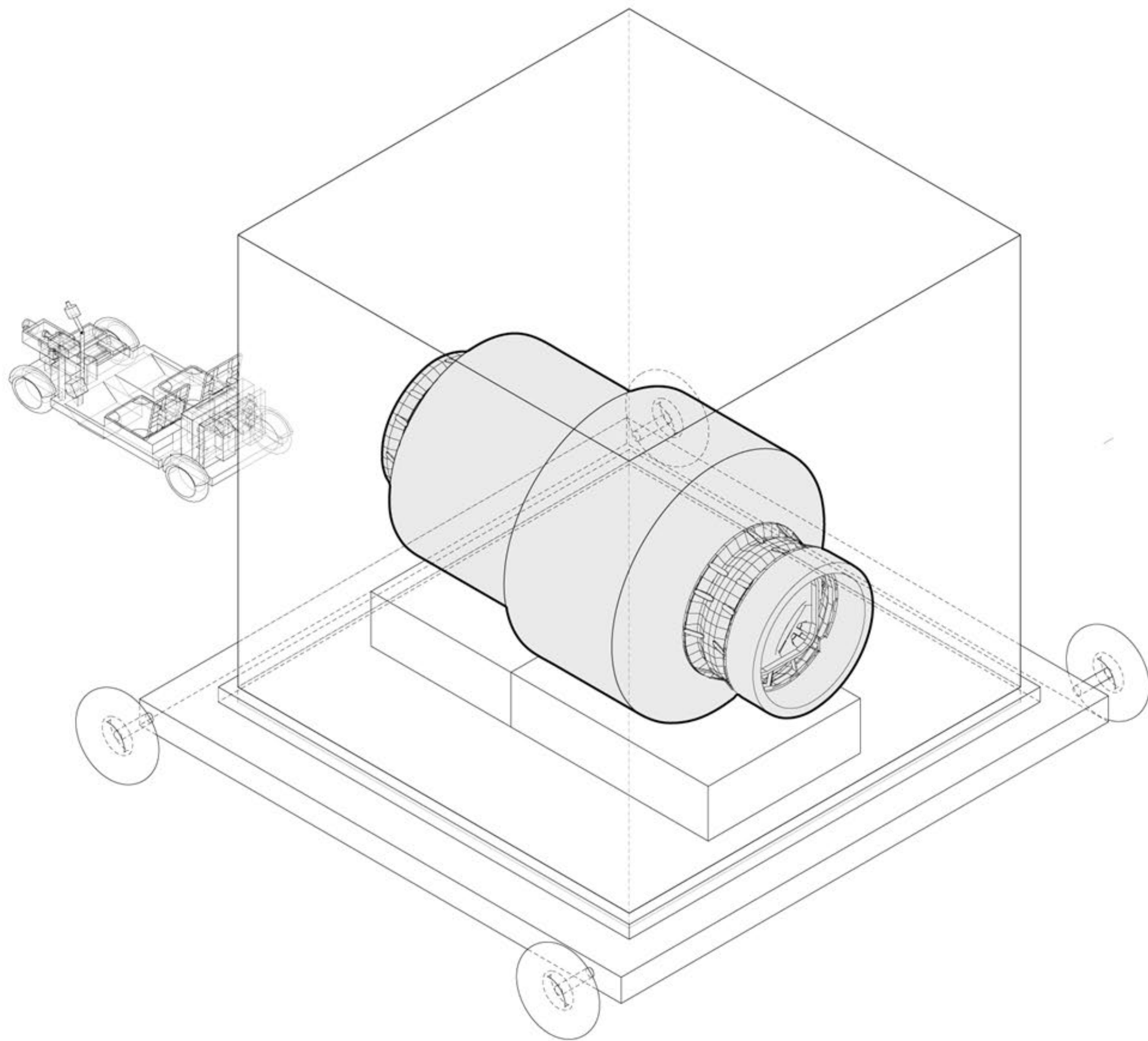
Installation in a 20x20x20ft cube



Launched in low earth orbit

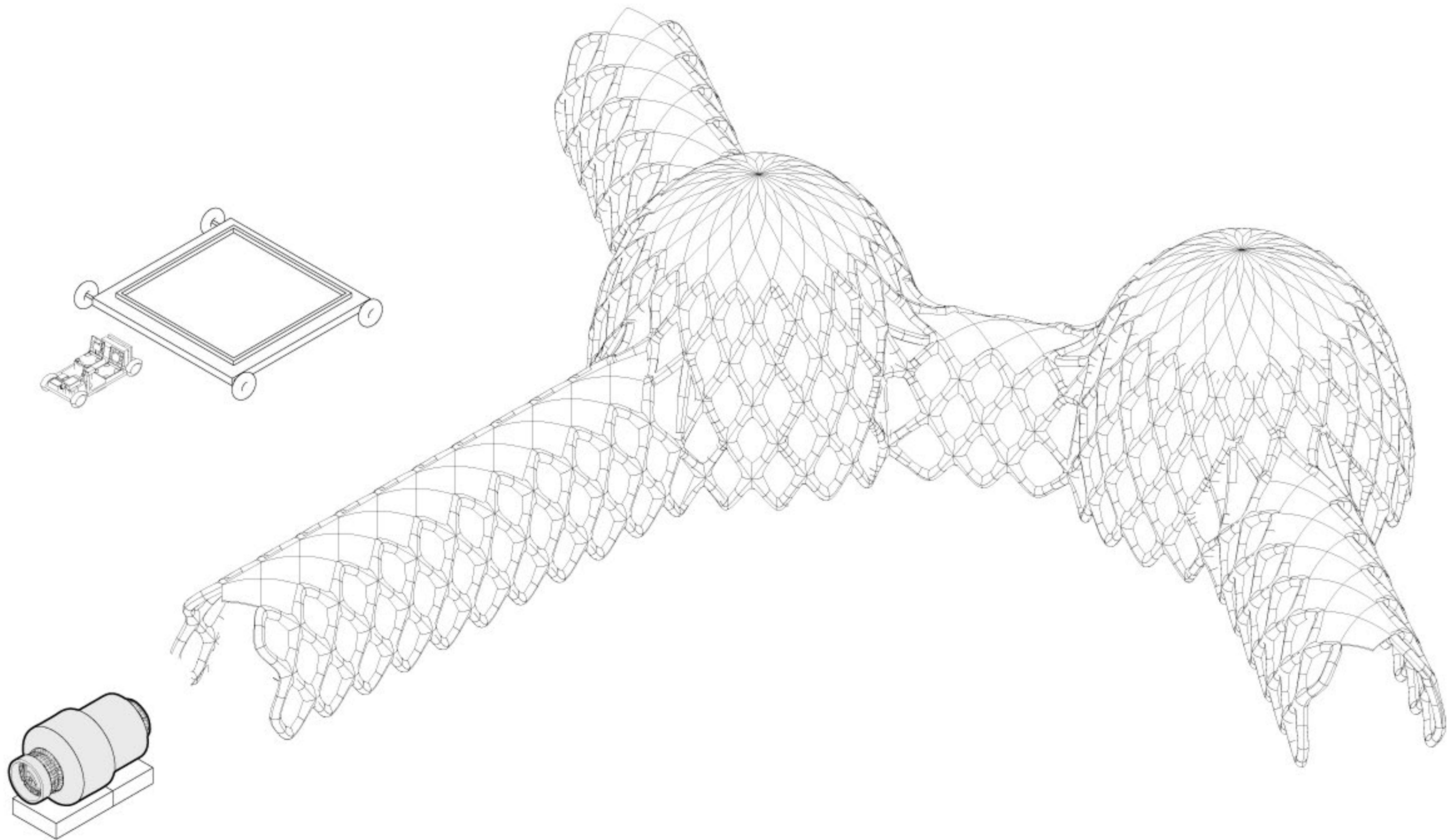


Docking stage

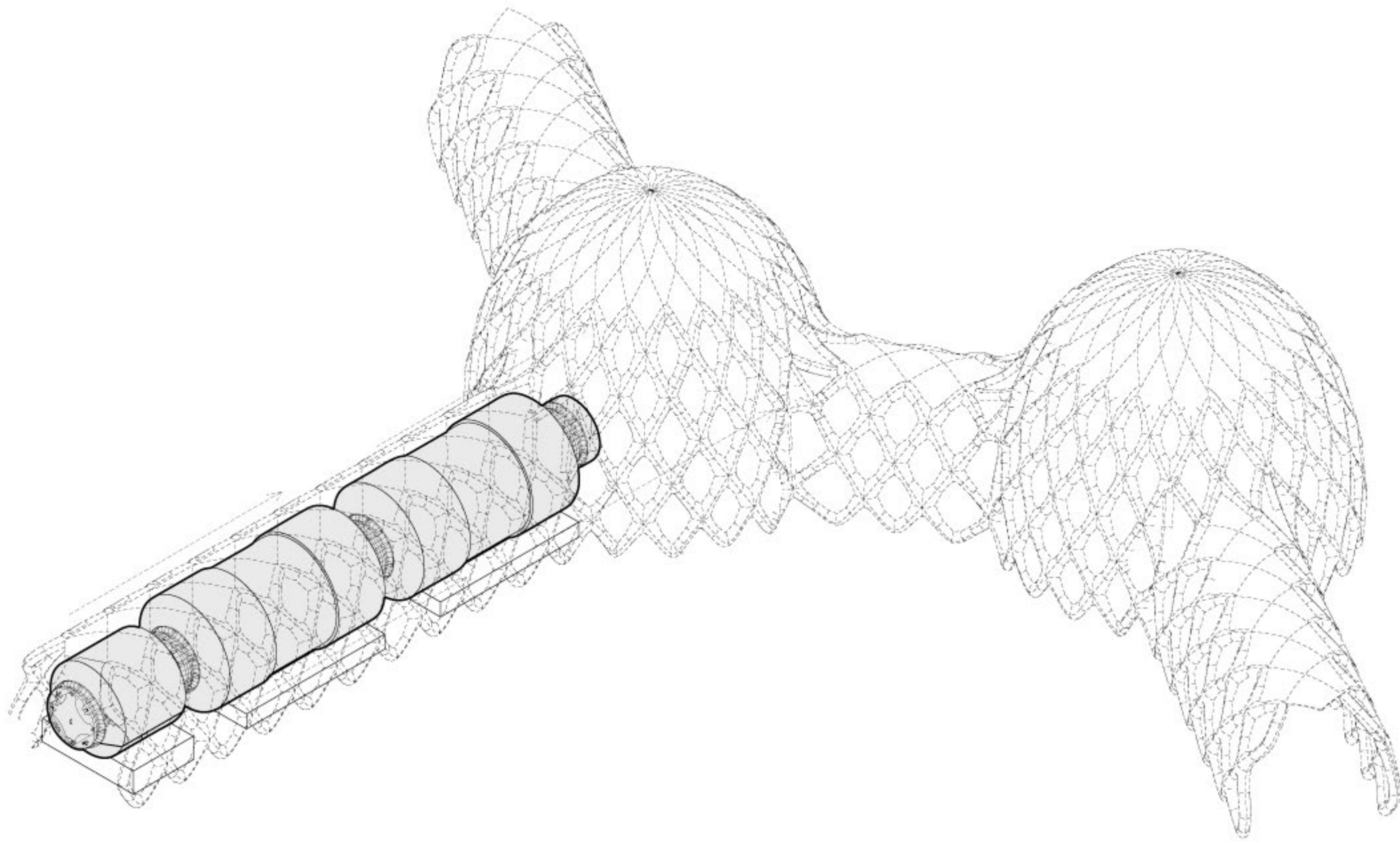


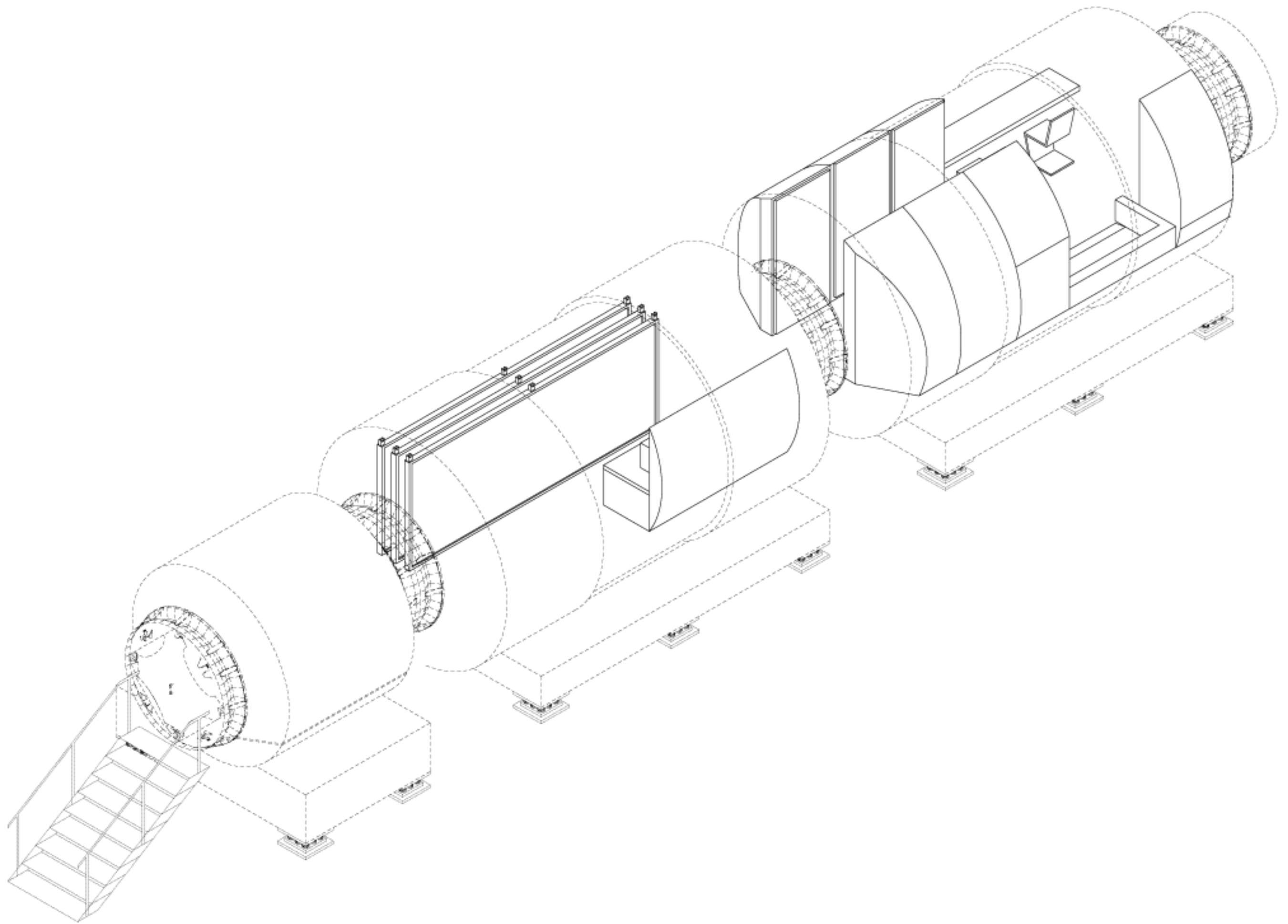


Transferred to desired location









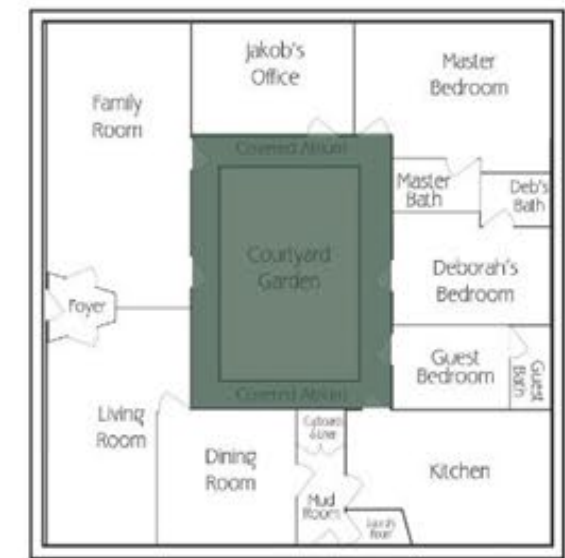
# ZEN GARDEN: CONCEPT/OBJECTIVES

## Prioritize Psychological Well-Being

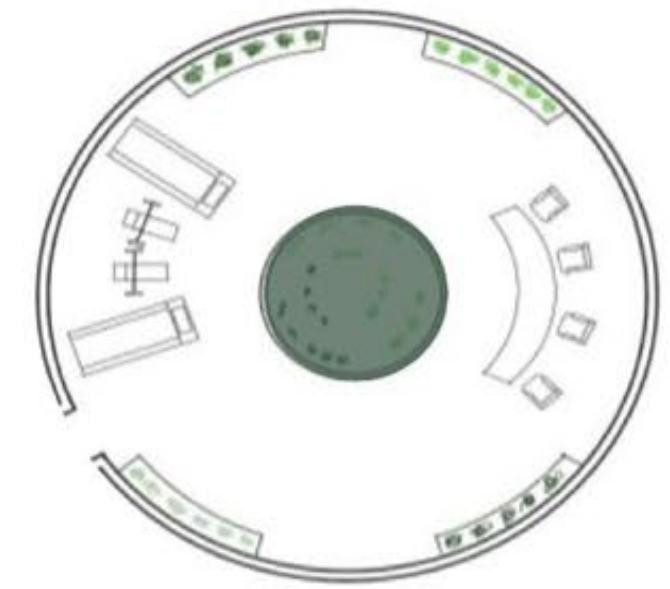
The desolate and lifeless environment will be detrimental to the psychological health of the astronauts on the habitat. We aim to mitigate this through integrating green space in Habitat: Oasis.

## Studying human interaction with plants has shown :

- individuals could reduce psychological and psychological stress (Journal of Physiological Anthropology)
- stress levels decrease significantly more with gardening as compared to other cortisol-lowering activities like reading (Journal of Health Psychology)
- being in the presence of plants helps improve memory and attention span by 20 percent and increases concentration. (University of Michigan)

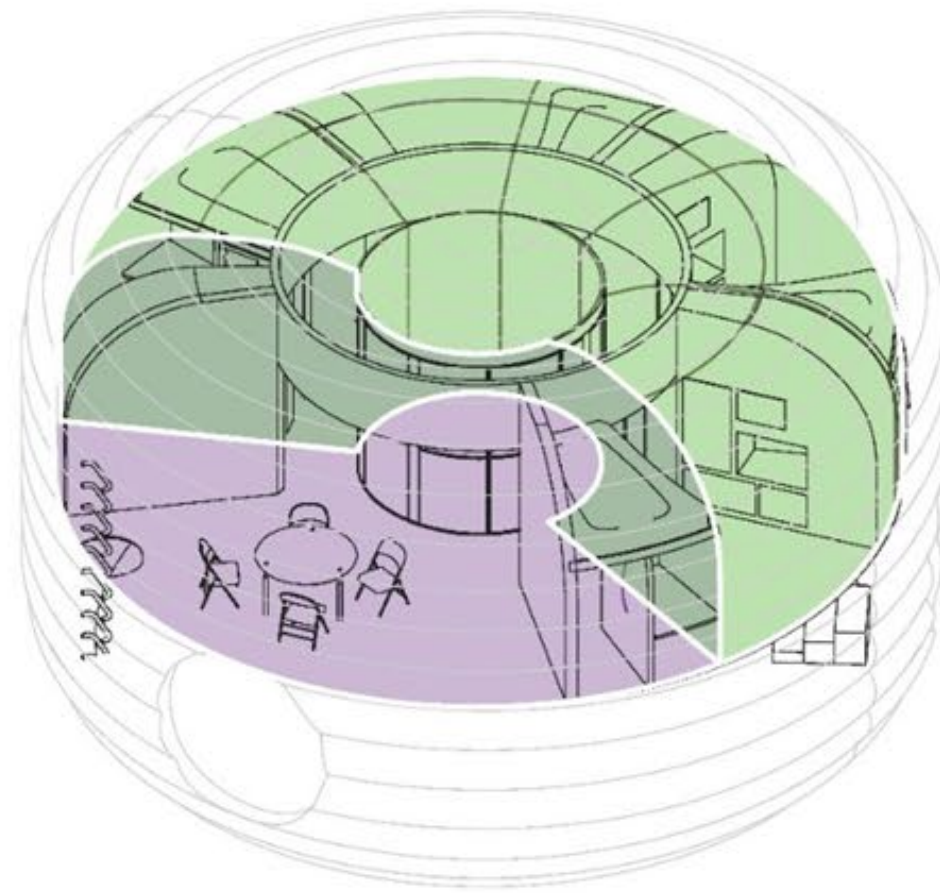
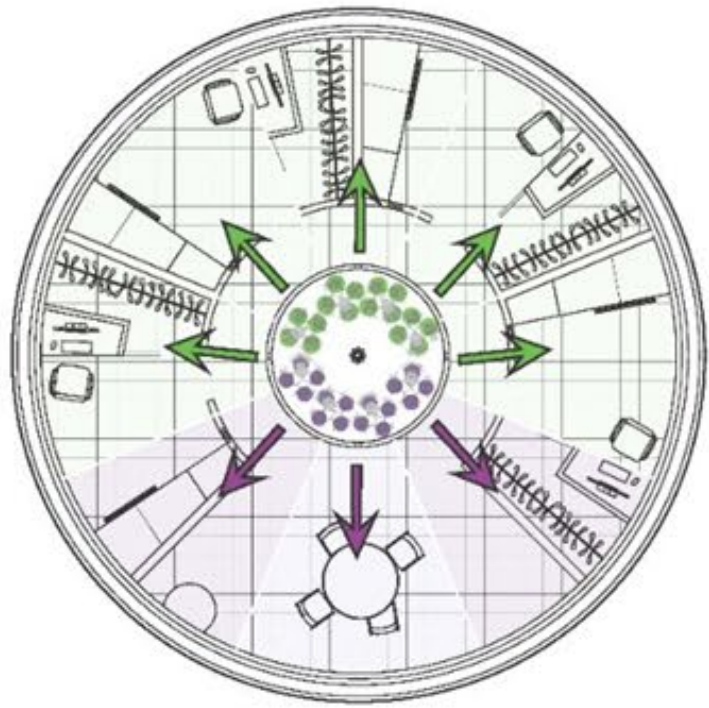


TYPICAL COURTYARD ON EARTH HOUSE



COURTYARD INTEGRATION ON LUNAR HABITAT

2nd  
Floor



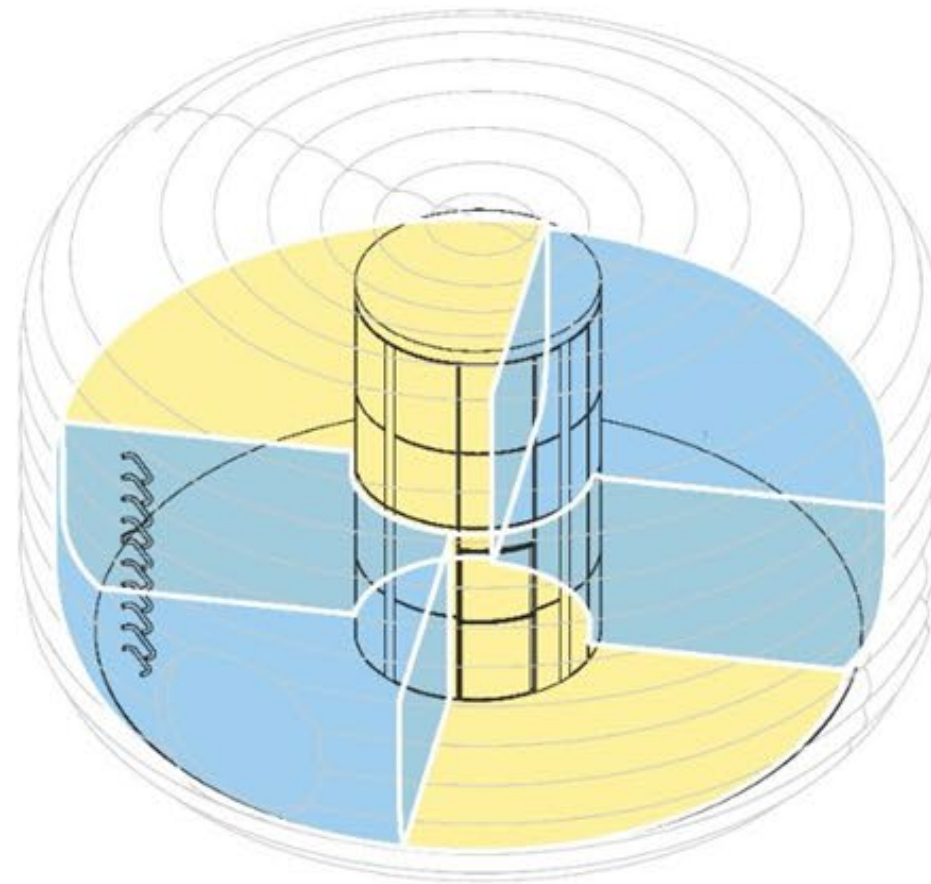
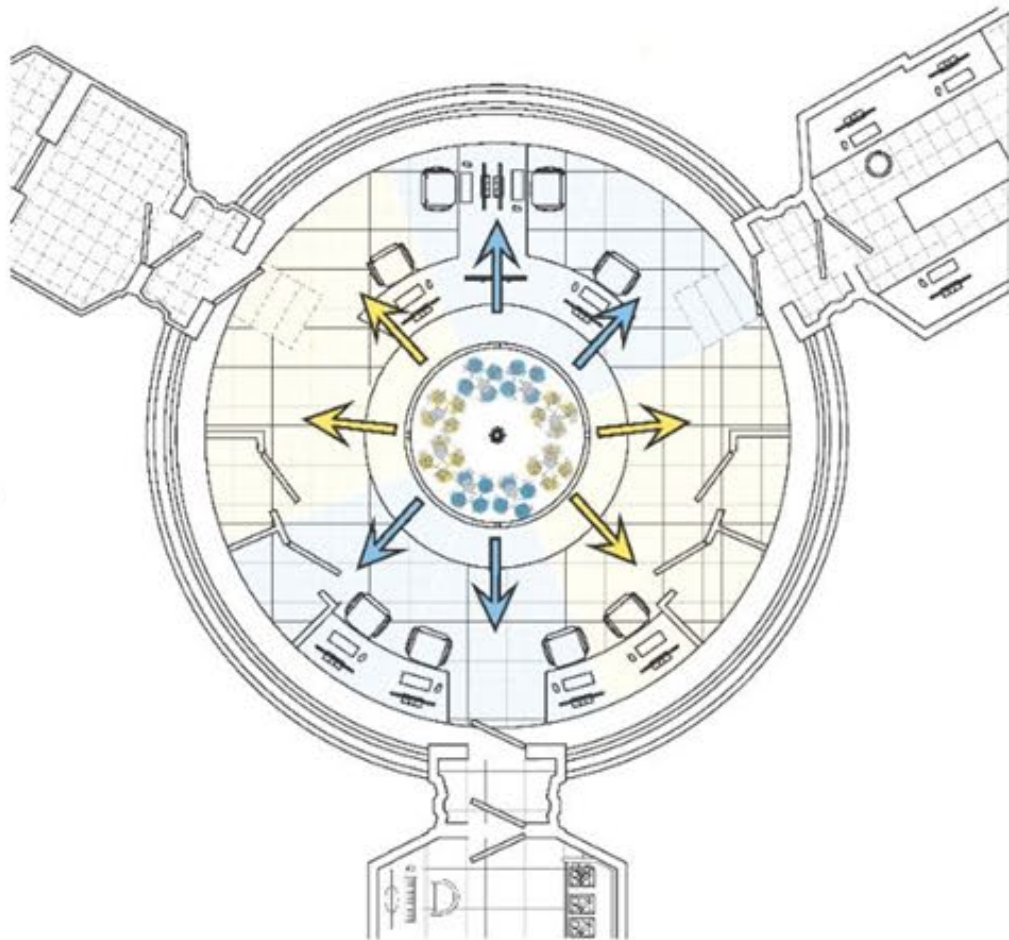
## Pilea

Green: Healing,  
Freshness

## Monarda

Purple: Communication,  
Socialization

1st  
Floor

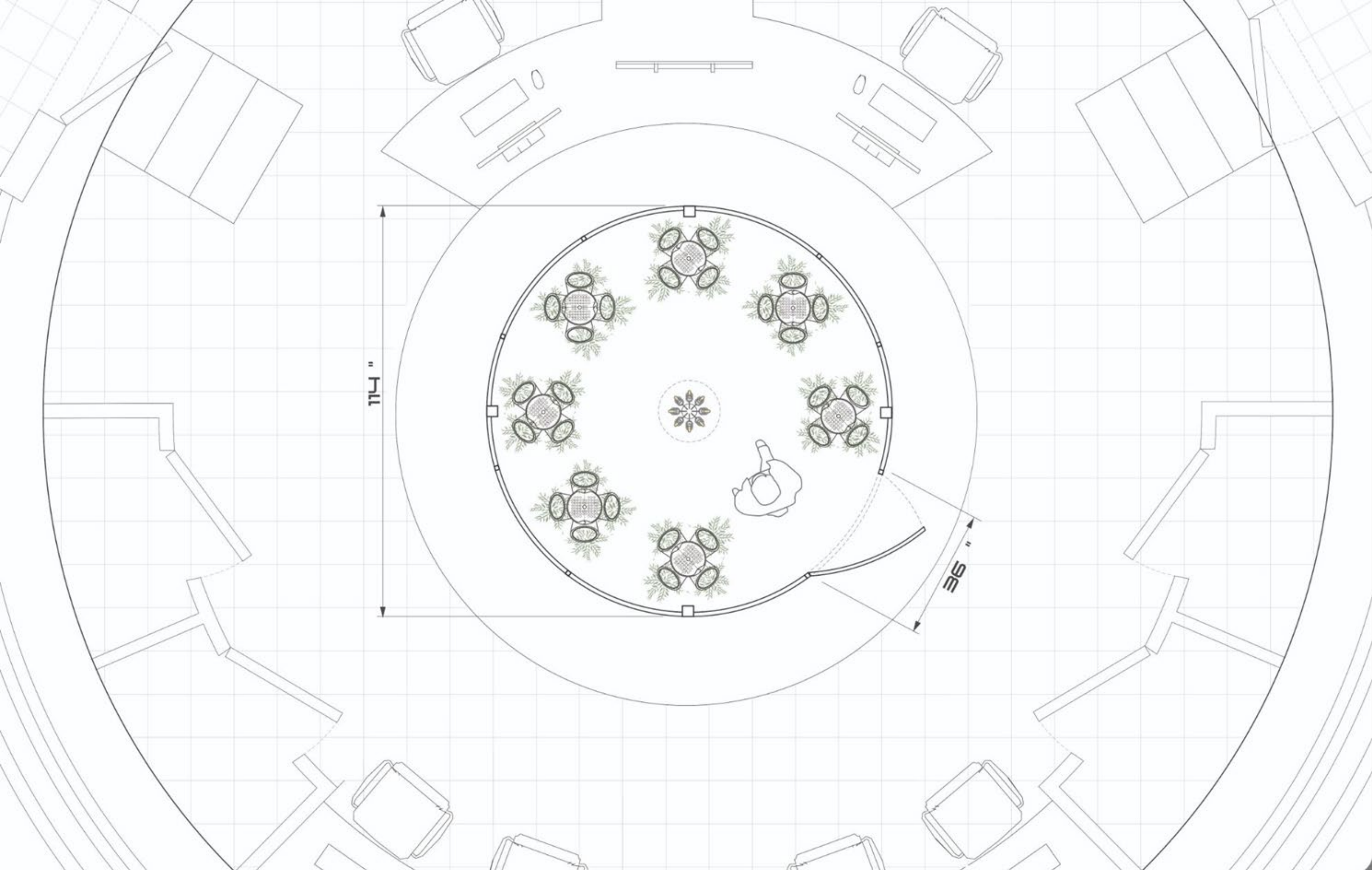


## Violas

Blue: Logical thinking,  
Productivity

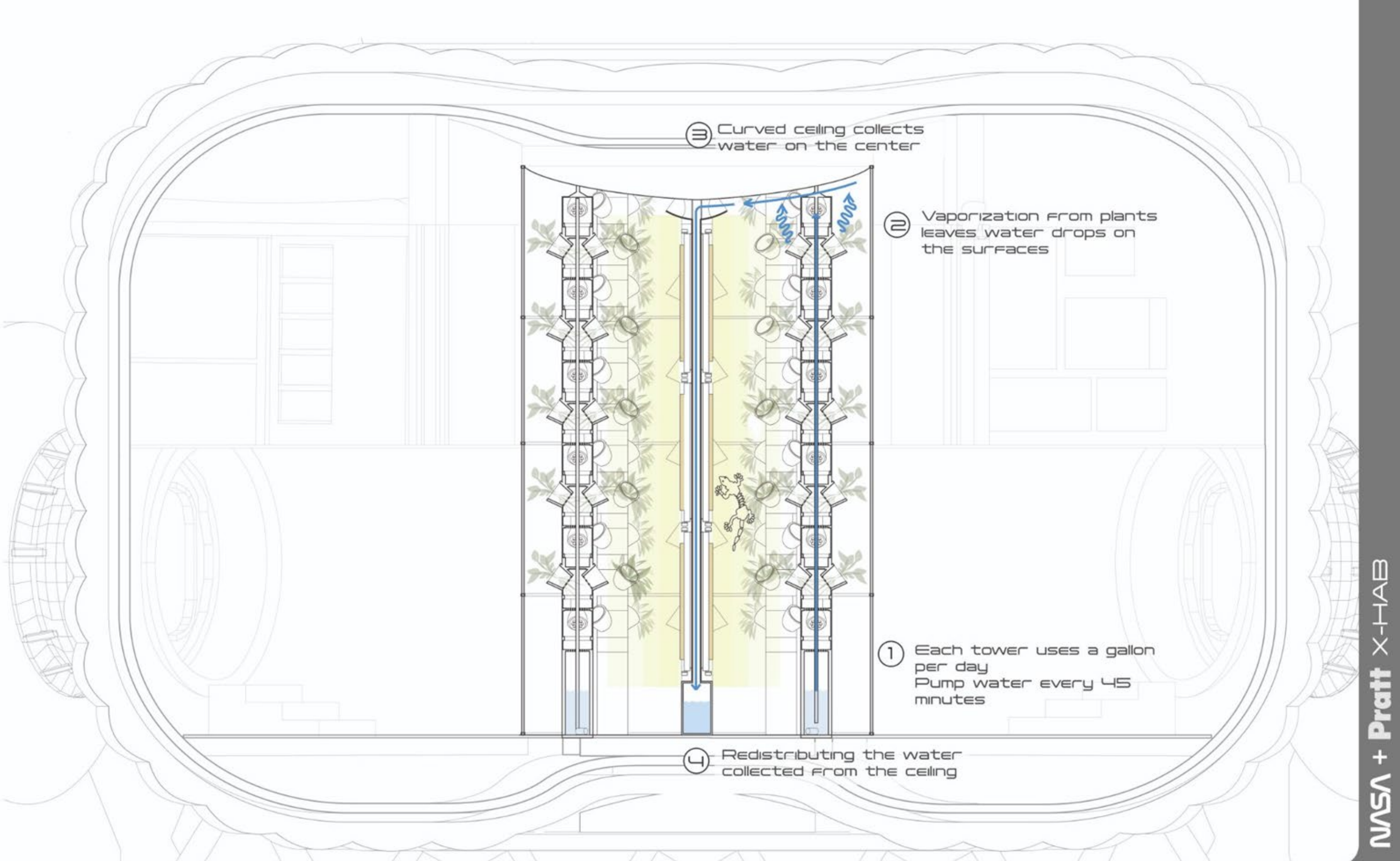
## Marigolds

Yellow: Creativity, Joy



114"

36"

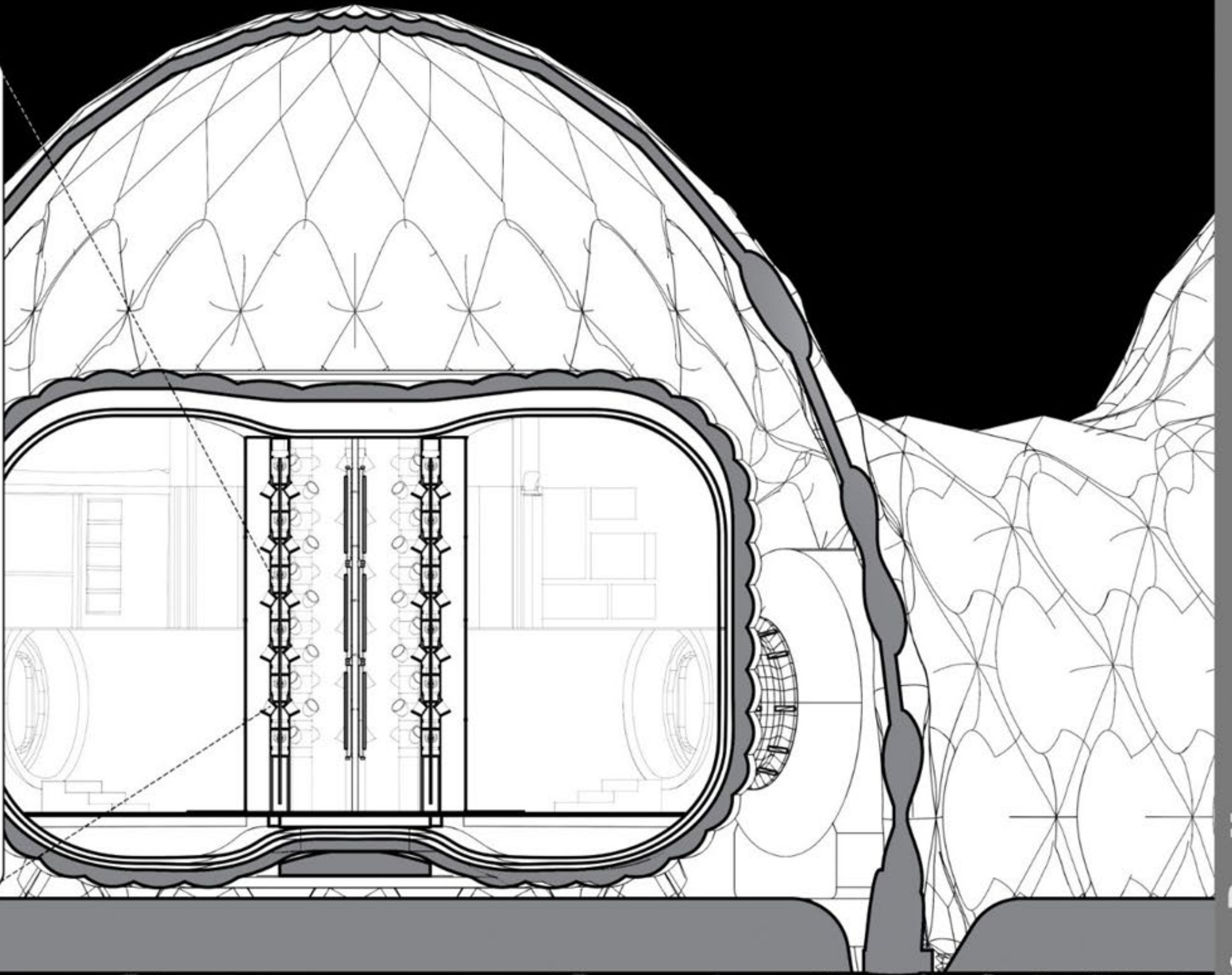
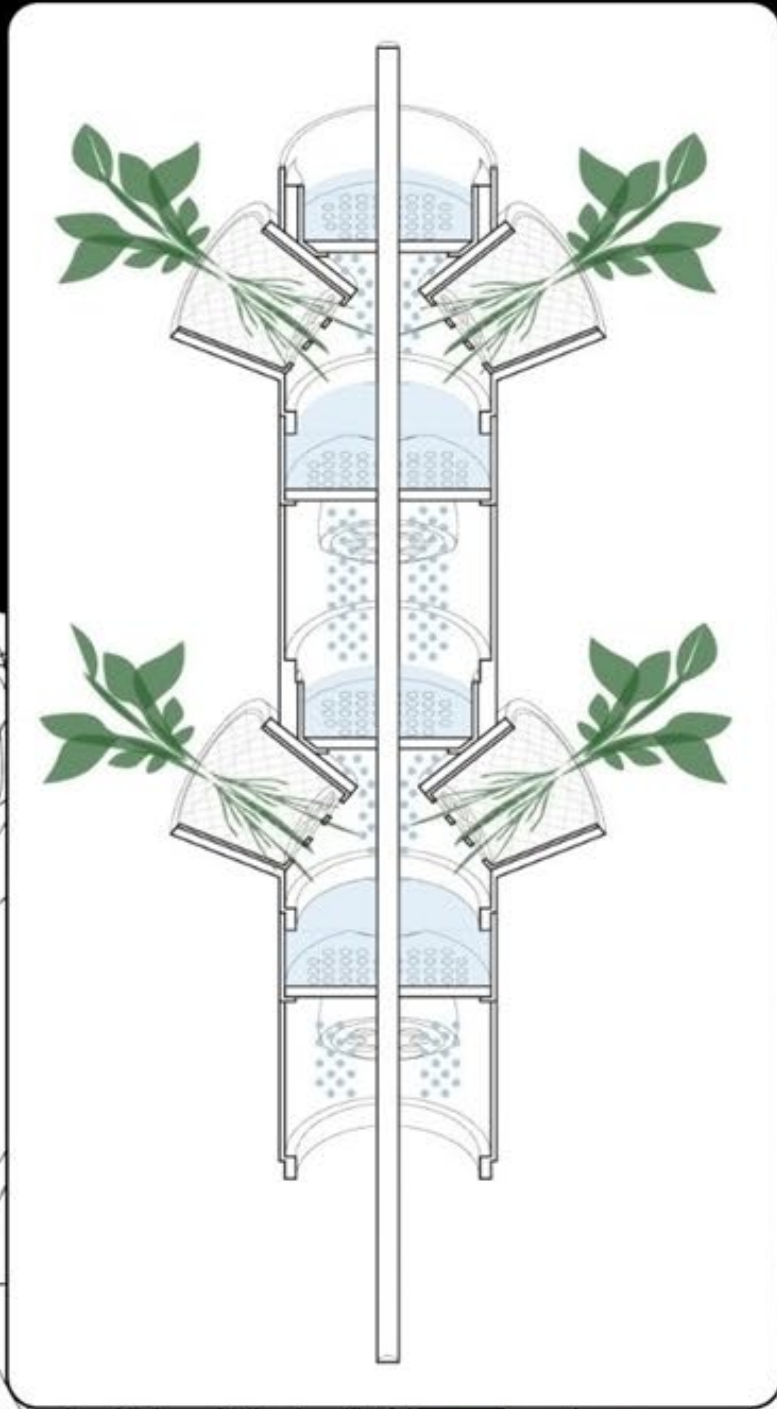
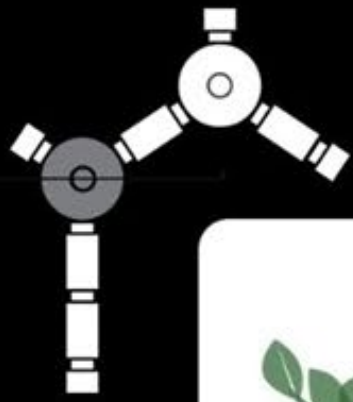


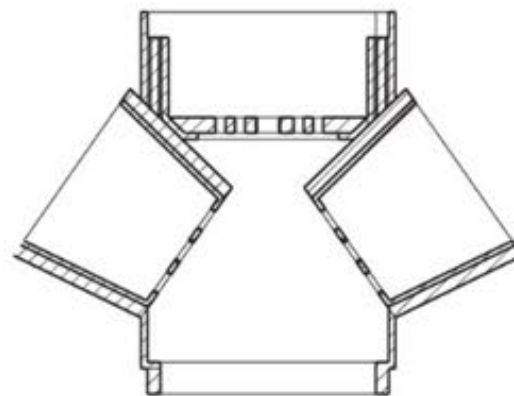
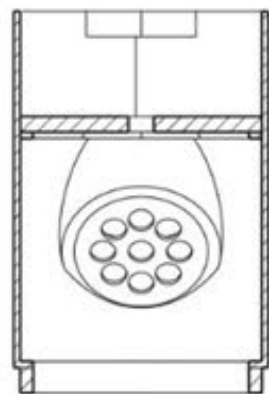
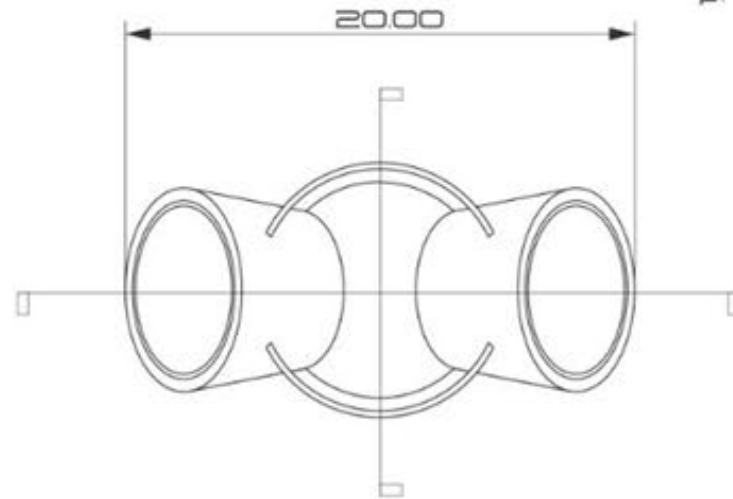
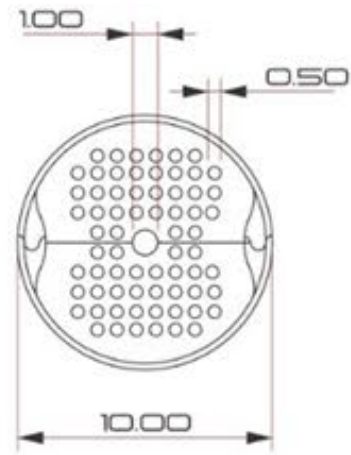
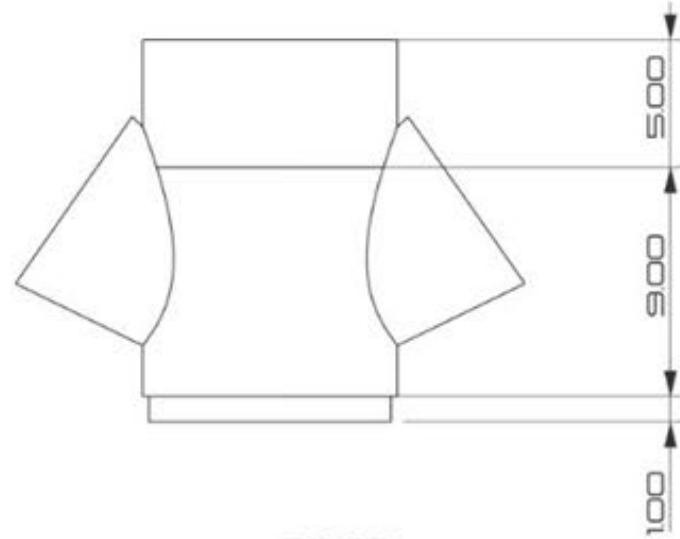
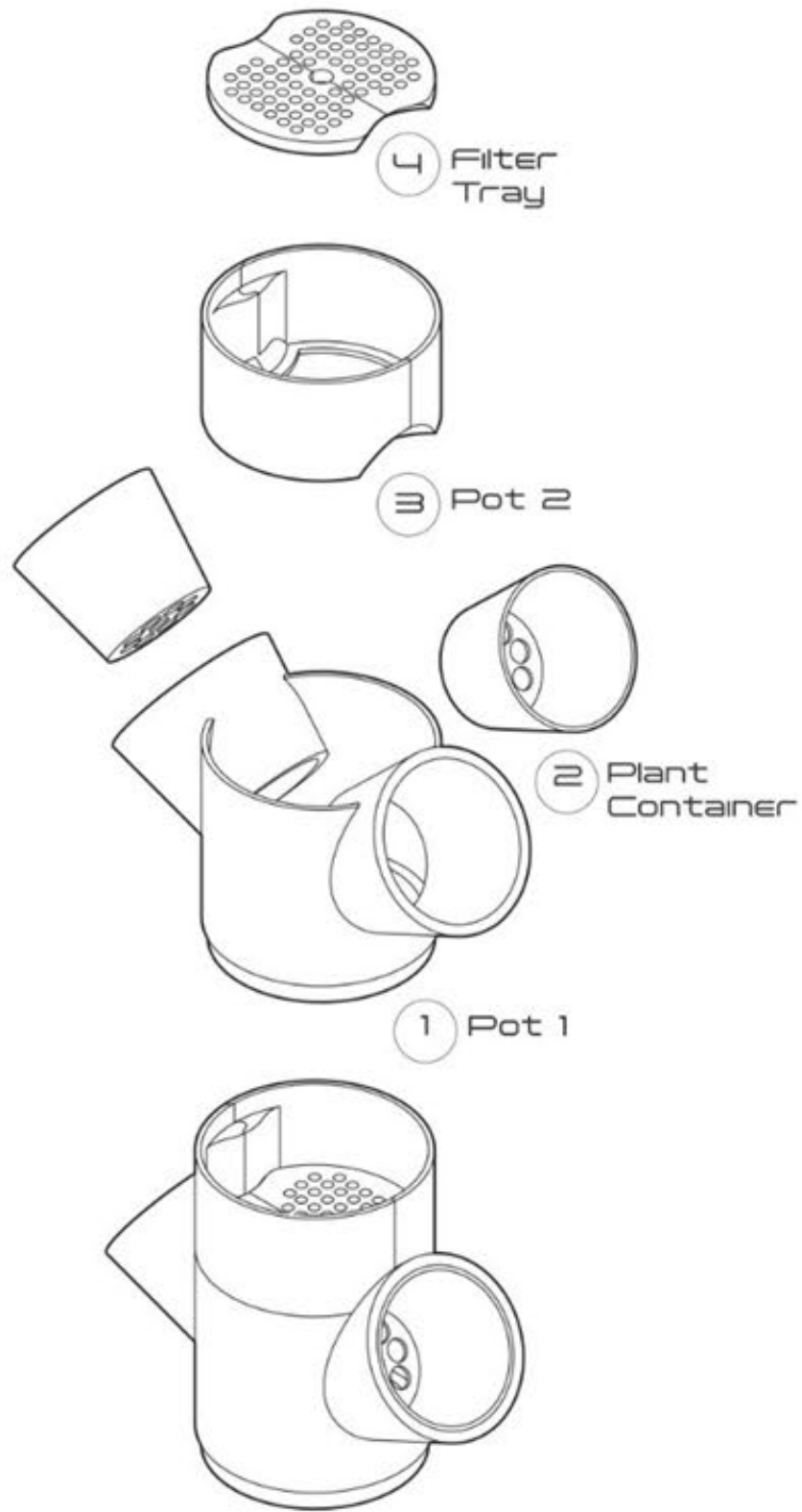
③ Curved ceiling collects water on the center

② Vaporization from plants leaves water drops on the surfaces

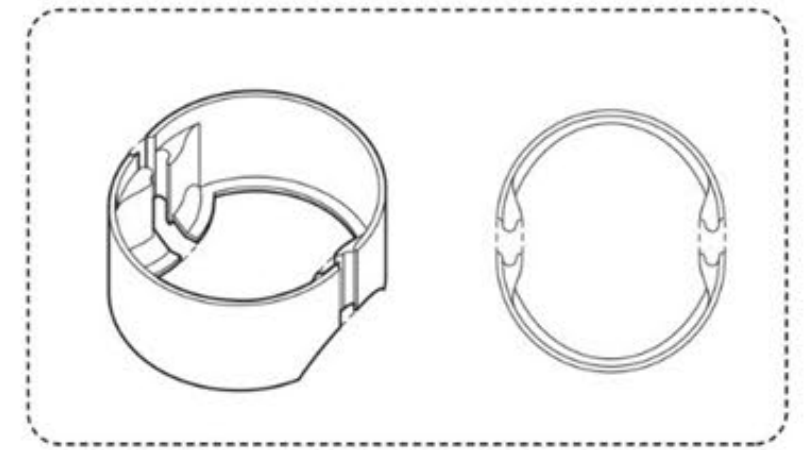
① Each tower uses a gallon per day  
Pump water every 45 minutes

④ Redistributing the water collected from the ceiling

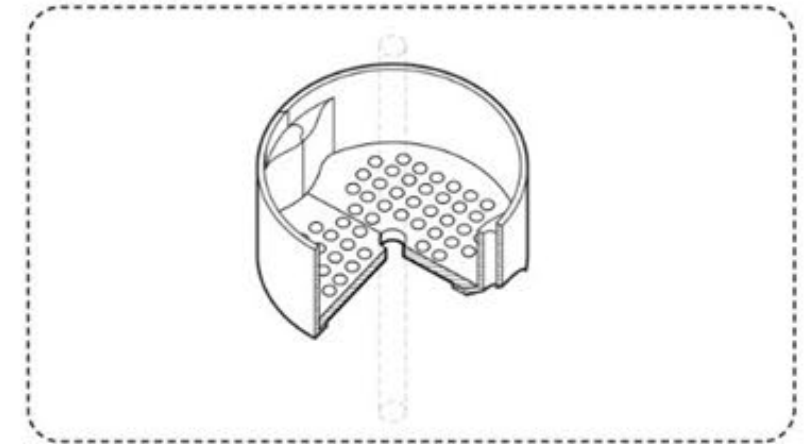




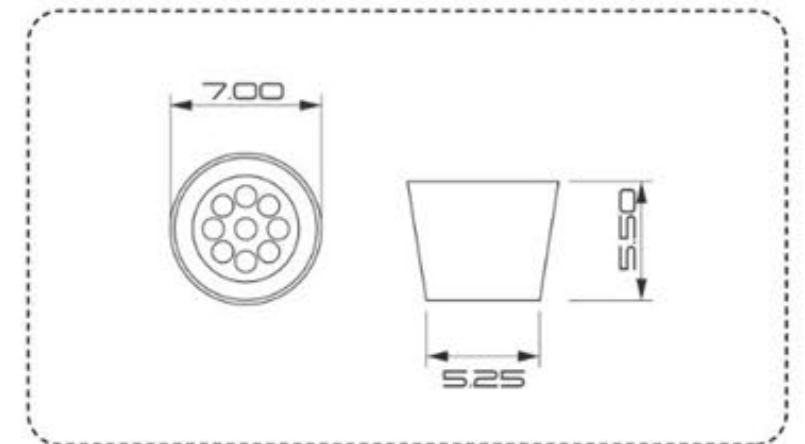
Detail 1



Detail 2

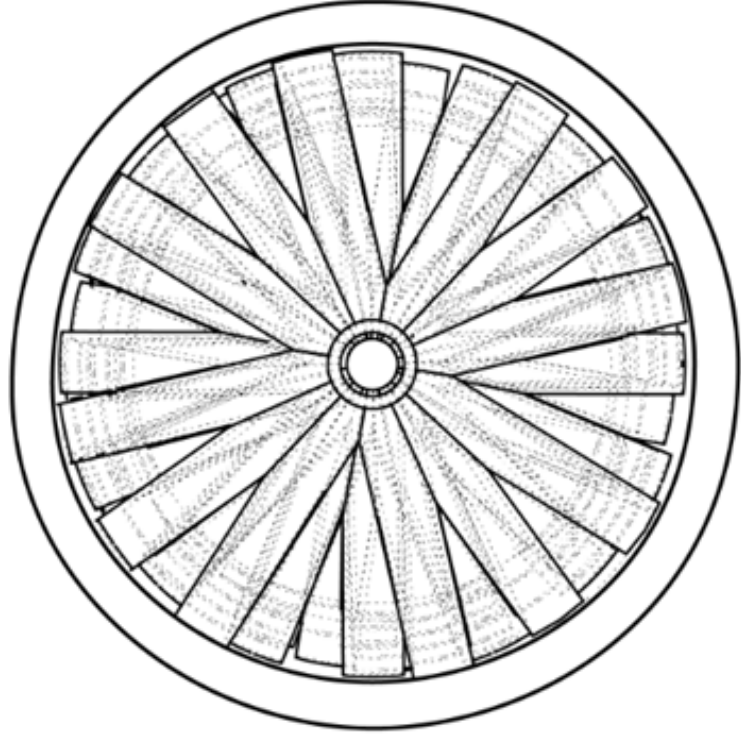


Plant Container Dimensions

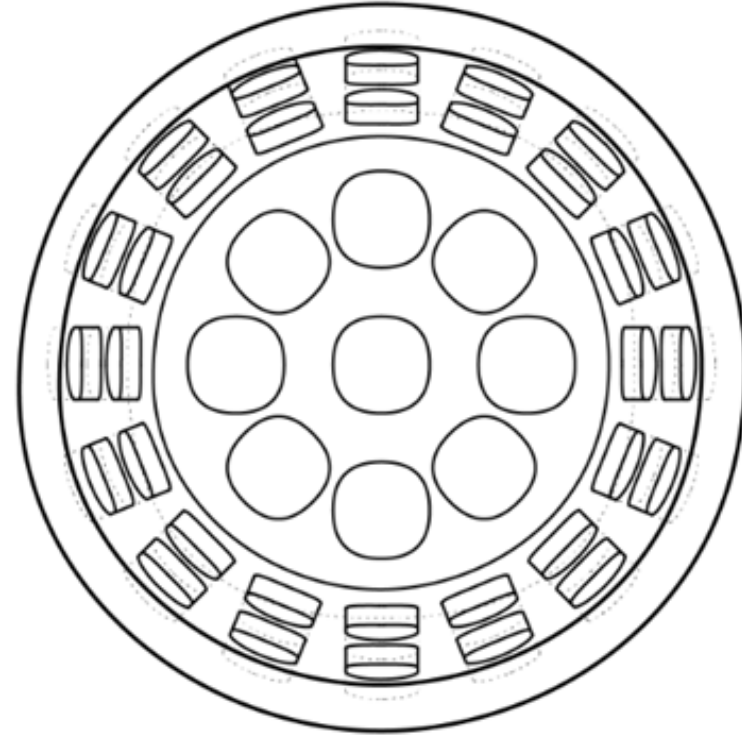
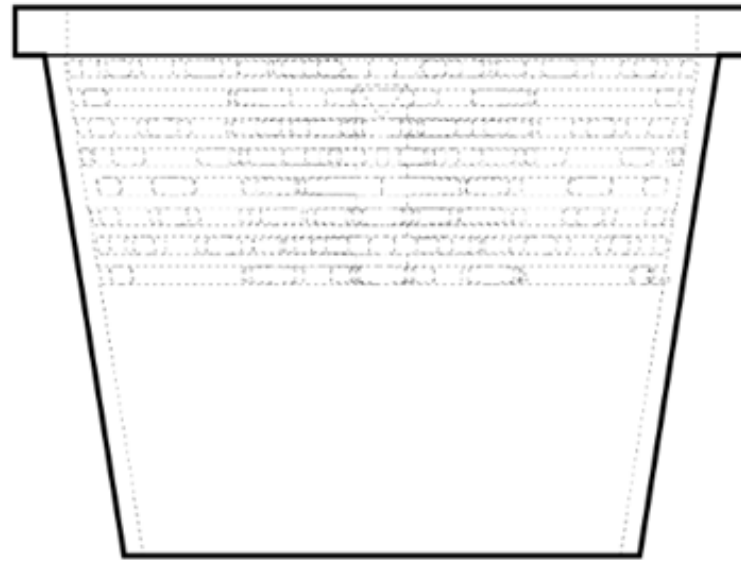




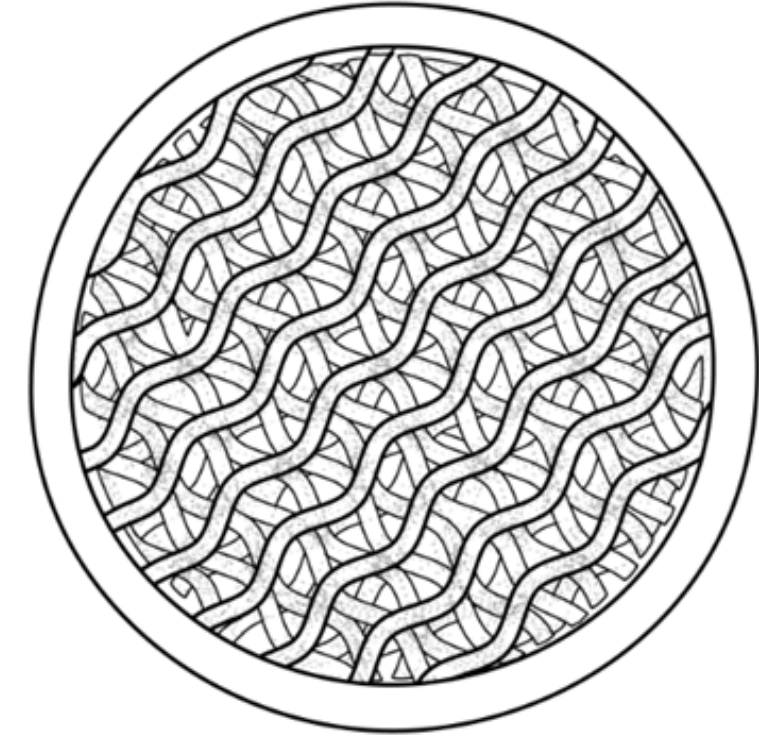
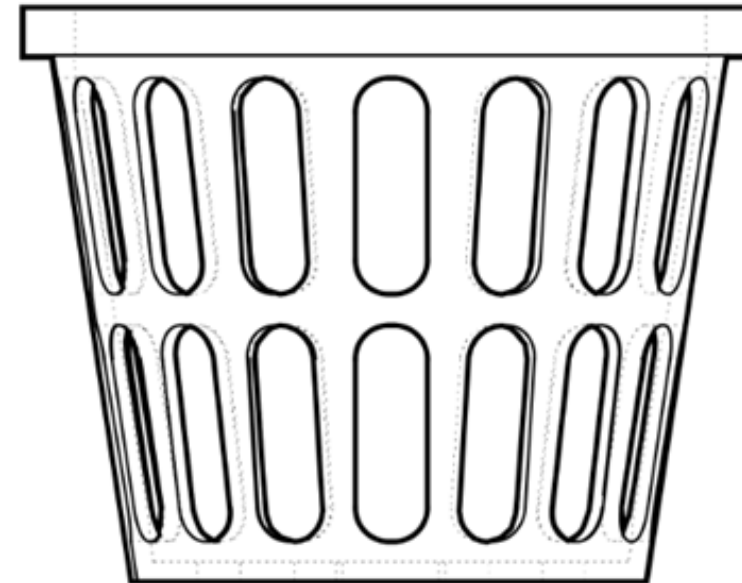
# PLANTER CUPS + MATERIAL



RADIAL GROWTH



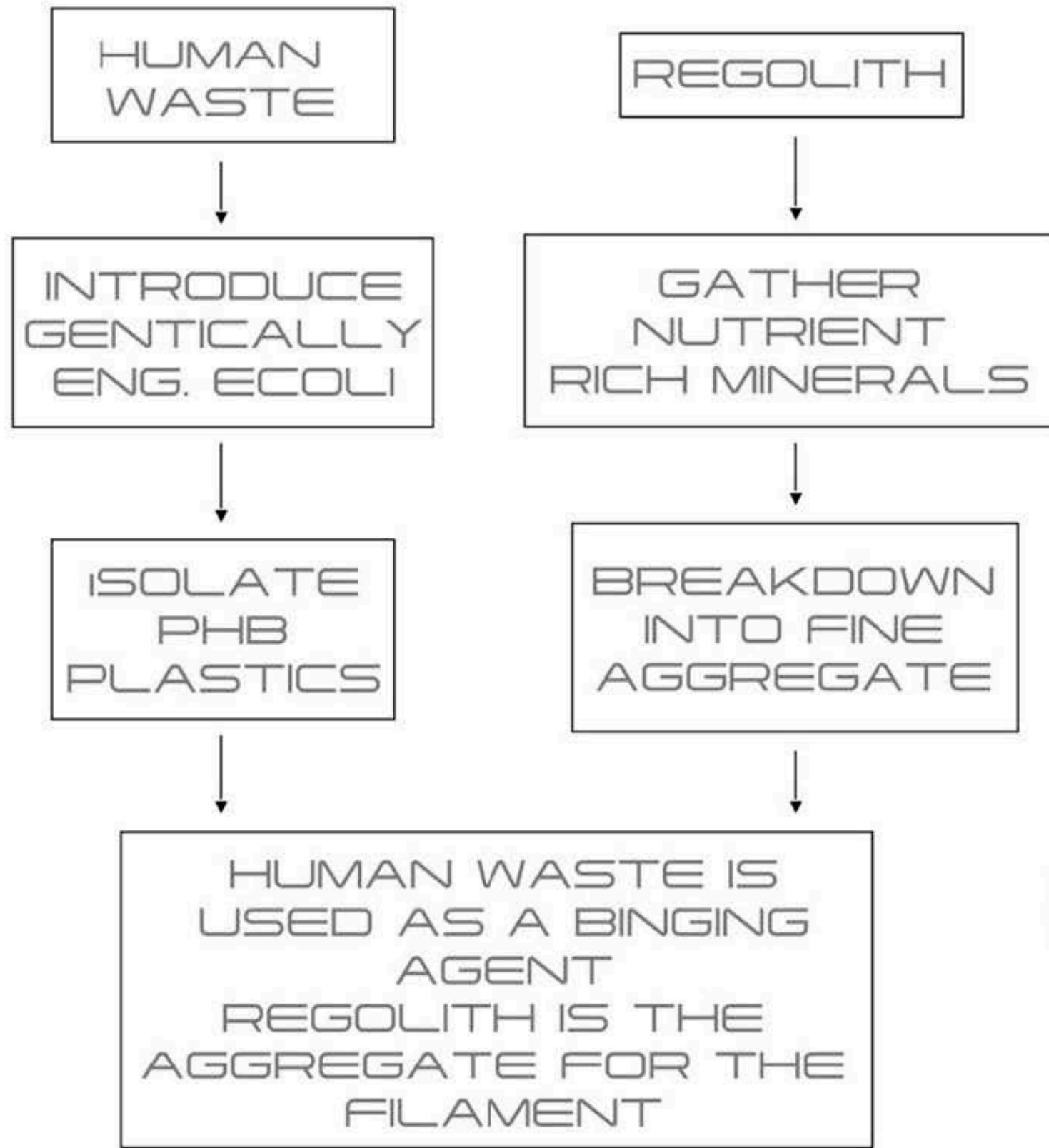
HYDROPONIC



OMNI-DIRECTIONAL



# PLANTER CUPS + MATERIAL



Pratt // ROSE (Robotic Organic Symbiotic Environment)

Phoebe DeGroot & Ofer Shouval

1st meeting: Stated aims

2nd meeting: Robot selection

3rd meeting: Final thoughts

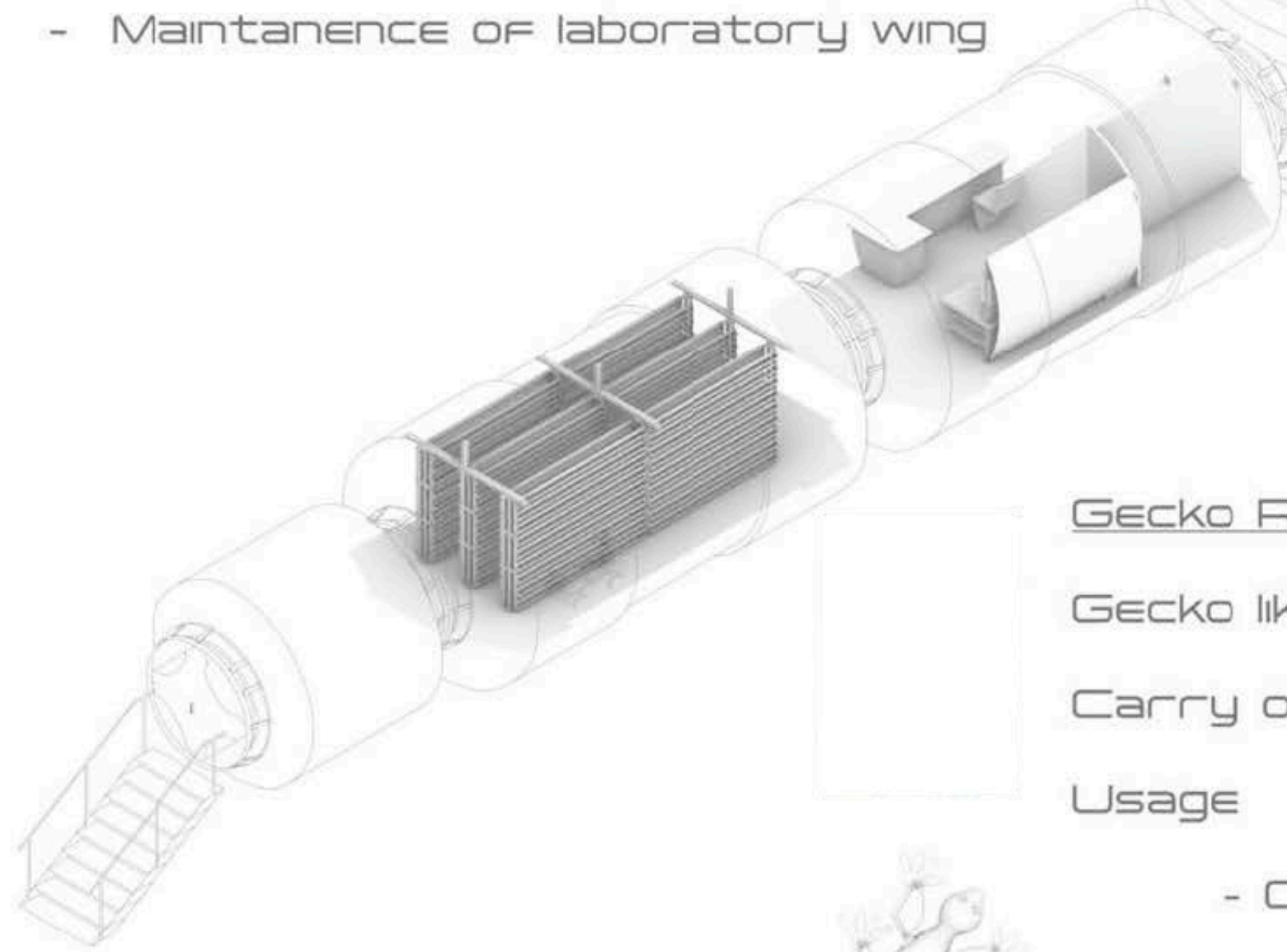
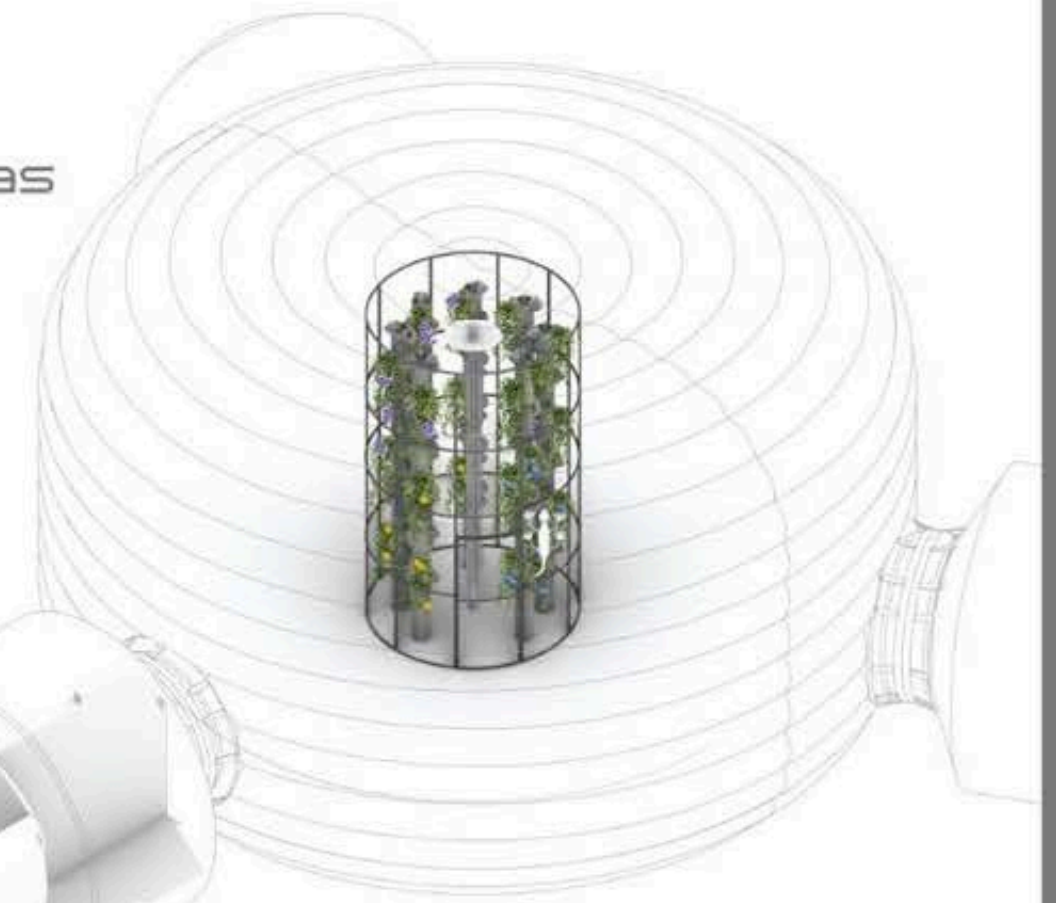
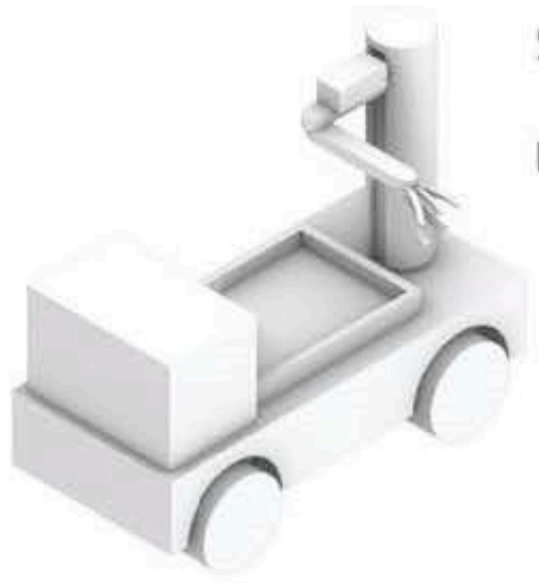
Final result: To create a robotic hub

## The Virgo

Self-driving robot with sensors and cameras

### Usage

- Harvesting
- Detecting growth
- Maintenance of laboratory wing



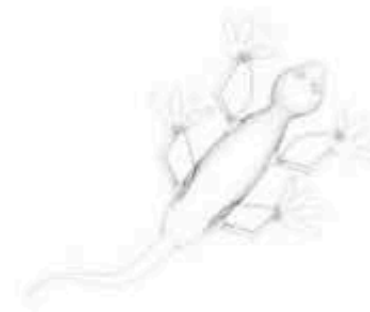
## Gecko Robot

Gecko like stick on the surface

Carry out objects

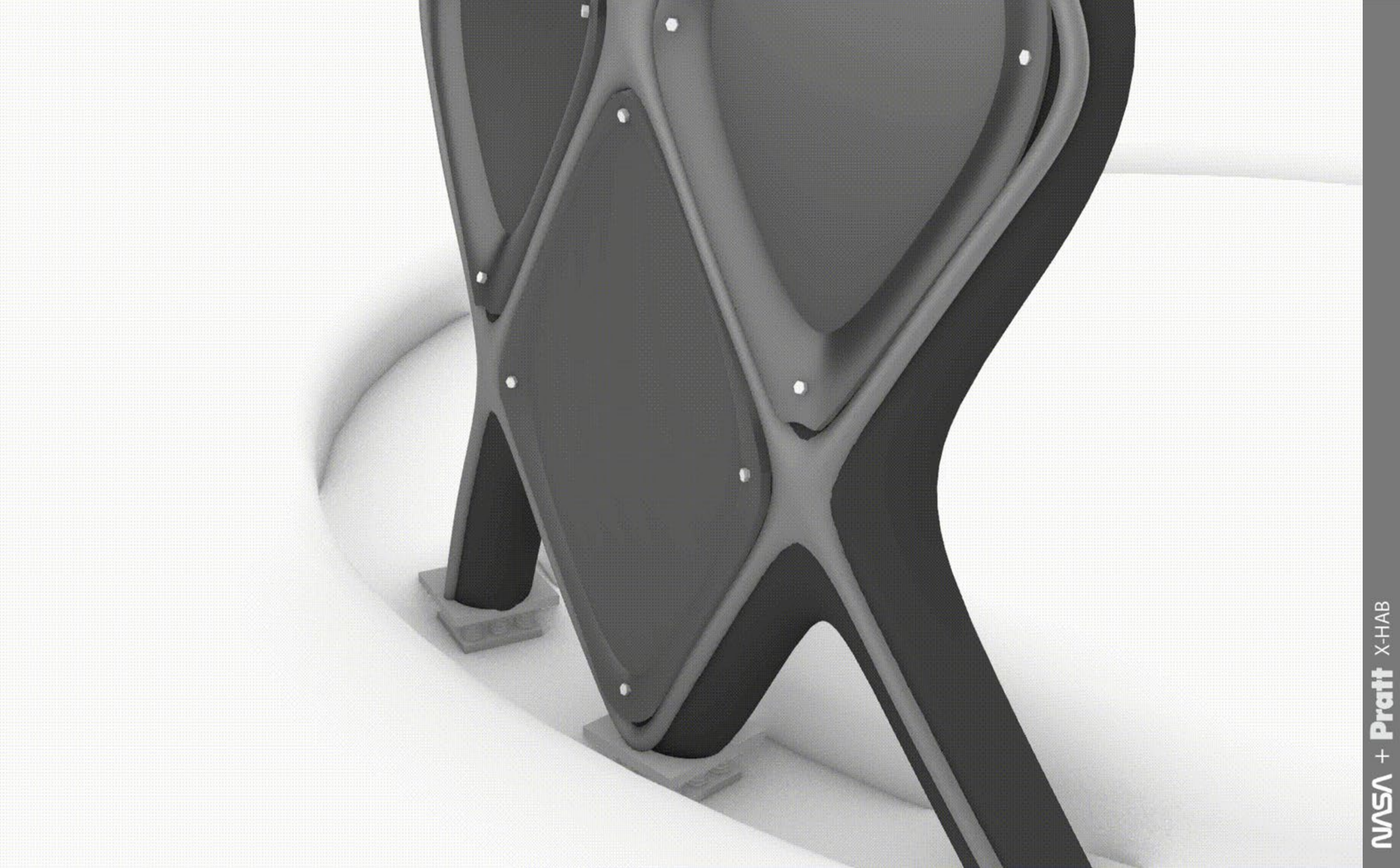
### Usage

- Cleaning surfaces
- Handling plants



## STRUCTURE

- HABITAT STRUCTURE
- HABITAT CONSTRUCTION
- MODEL LAYOUT
- MODEL CONSTRUCTION



# PANELING SYSTEM

3D PRINTED REGOLITH

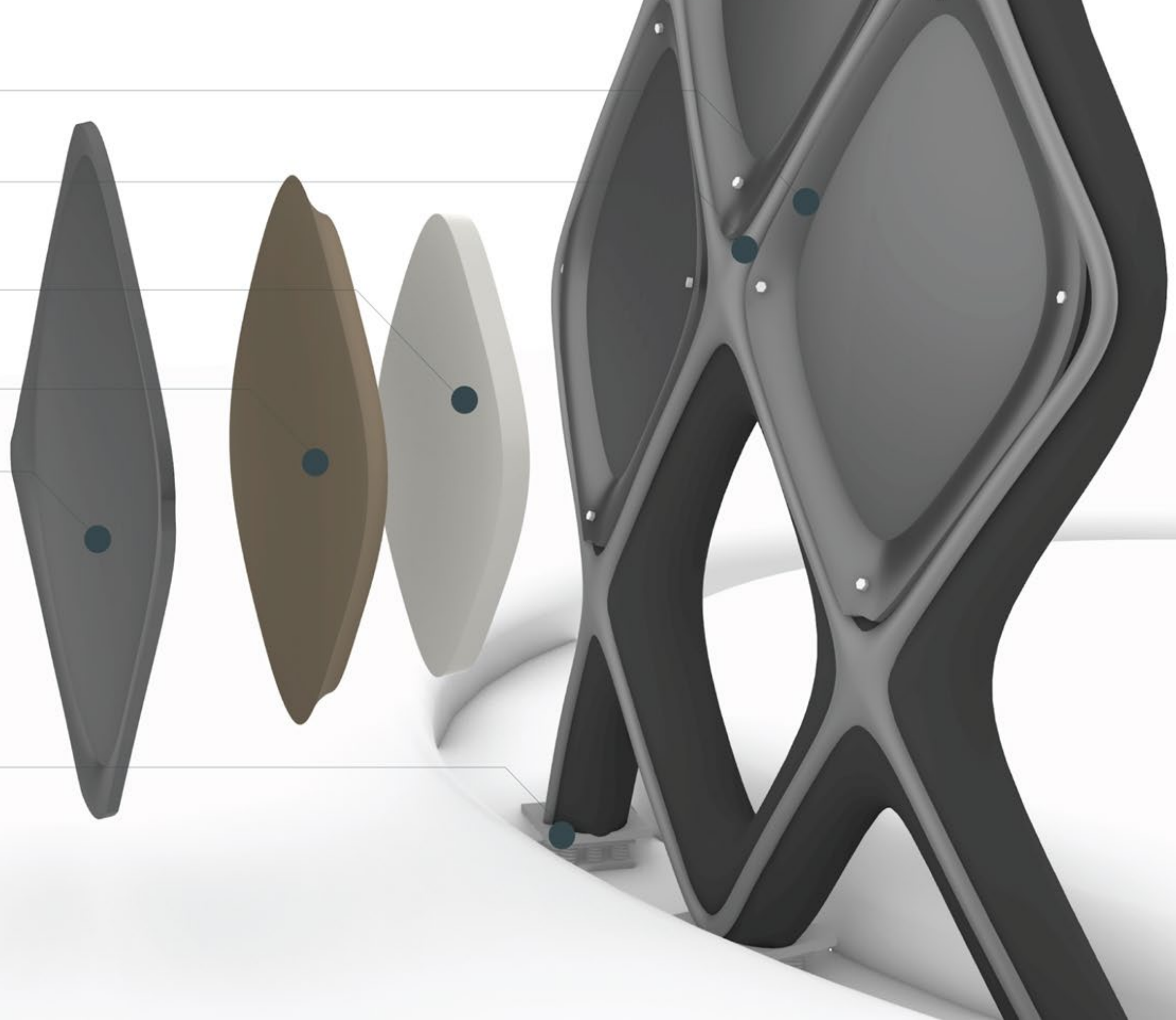
3D PRINTED ALUMINUM

HPE (HIGH DENSITY POLYETHLYN)

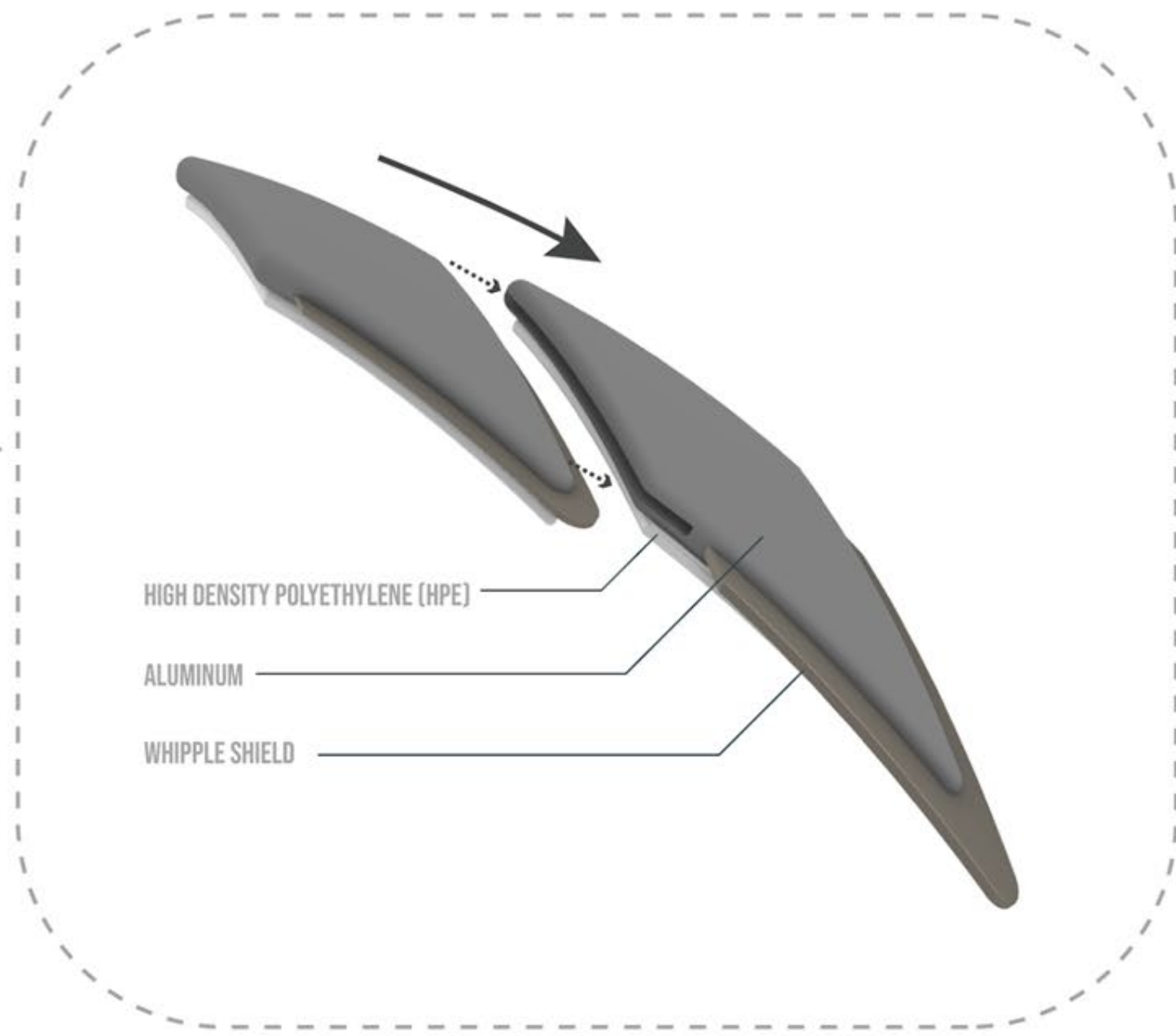
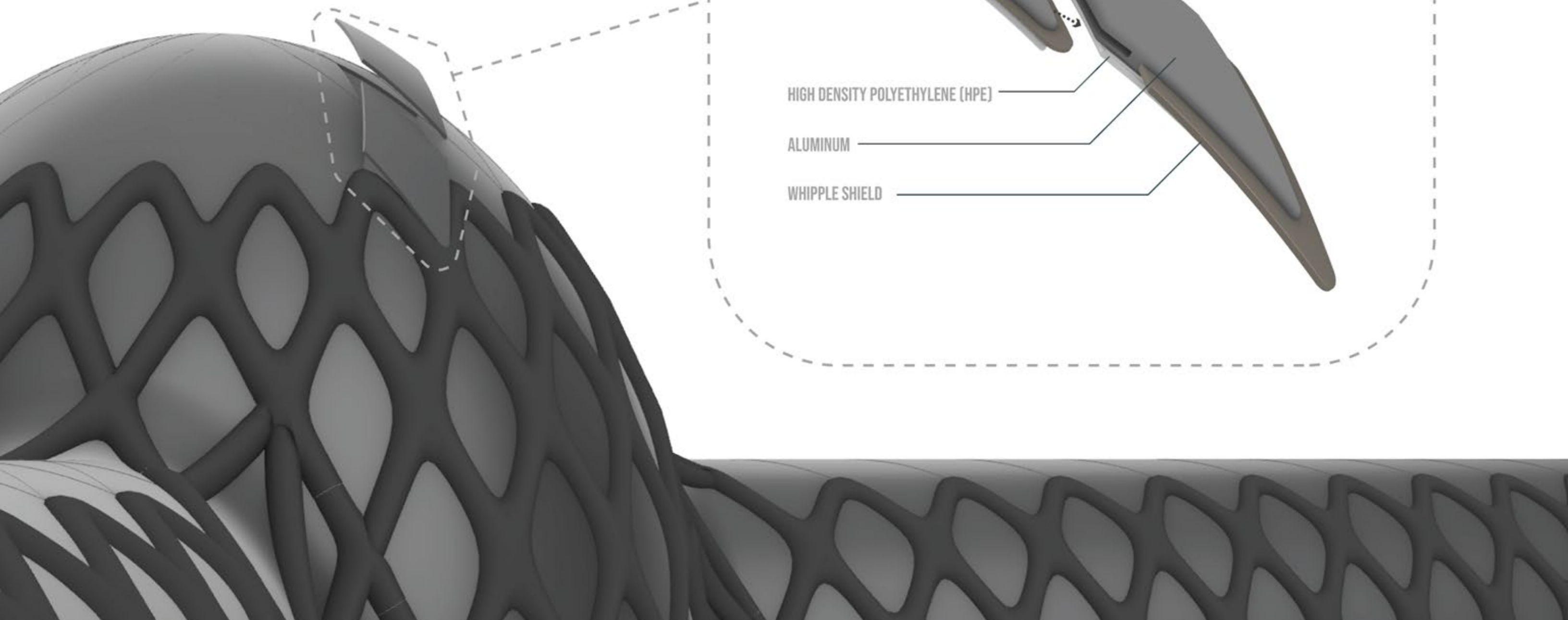
WHIPPLE SHIELD

ALUMINUM

BASE ISOLATOR

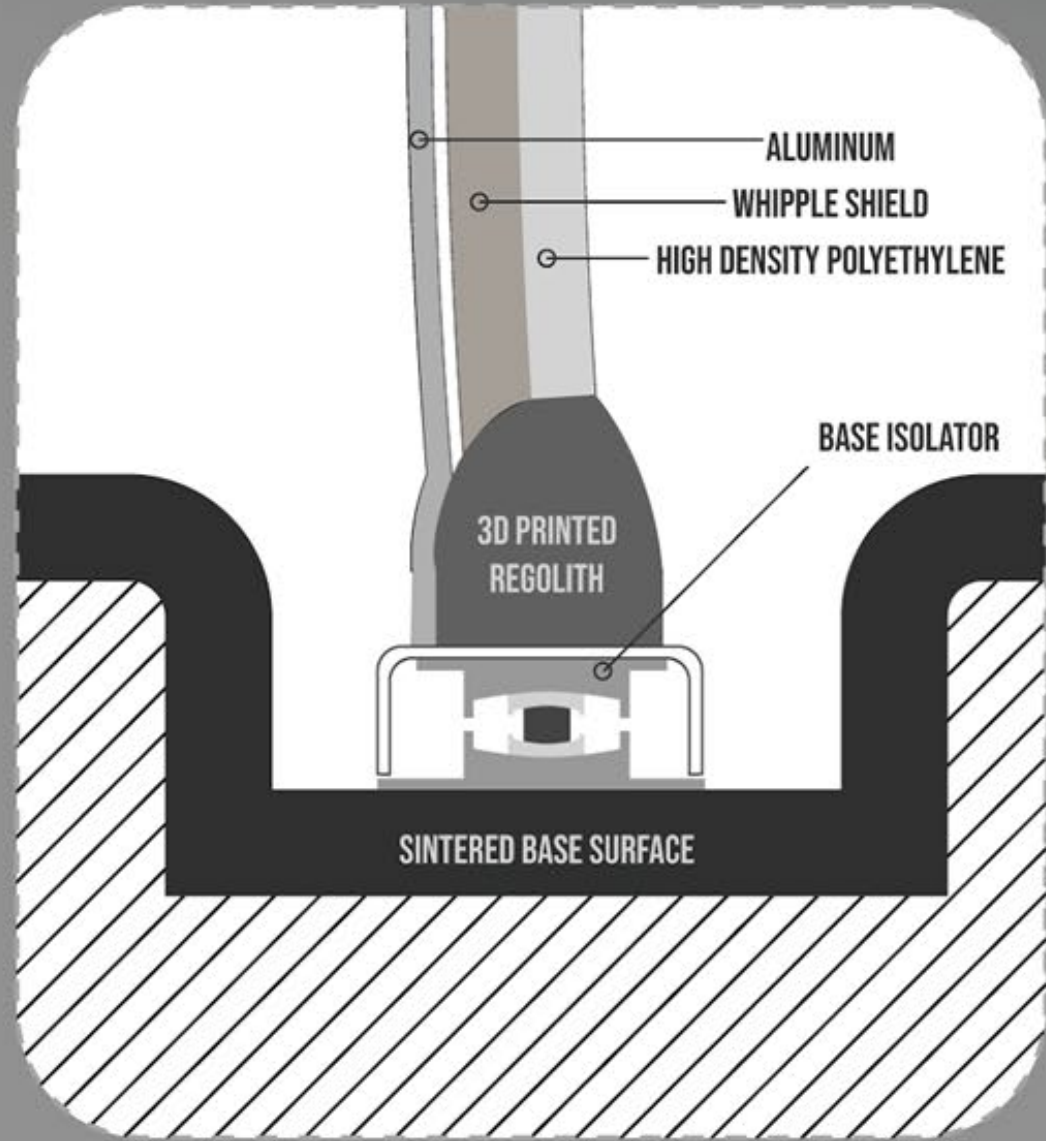


# CAPPING PANELS

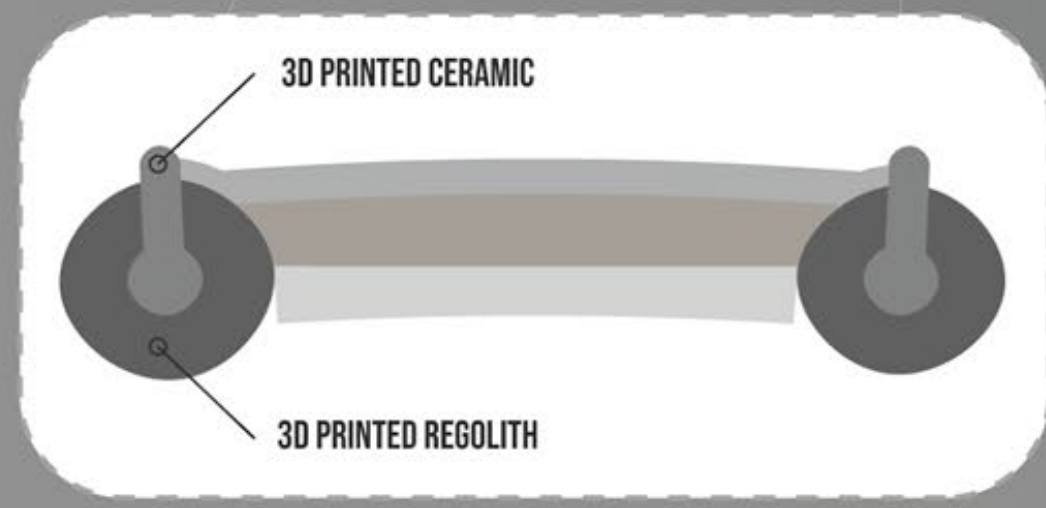




# DETAIL SECTIONS



BASE ISOLATOR



PANEL PROFILE

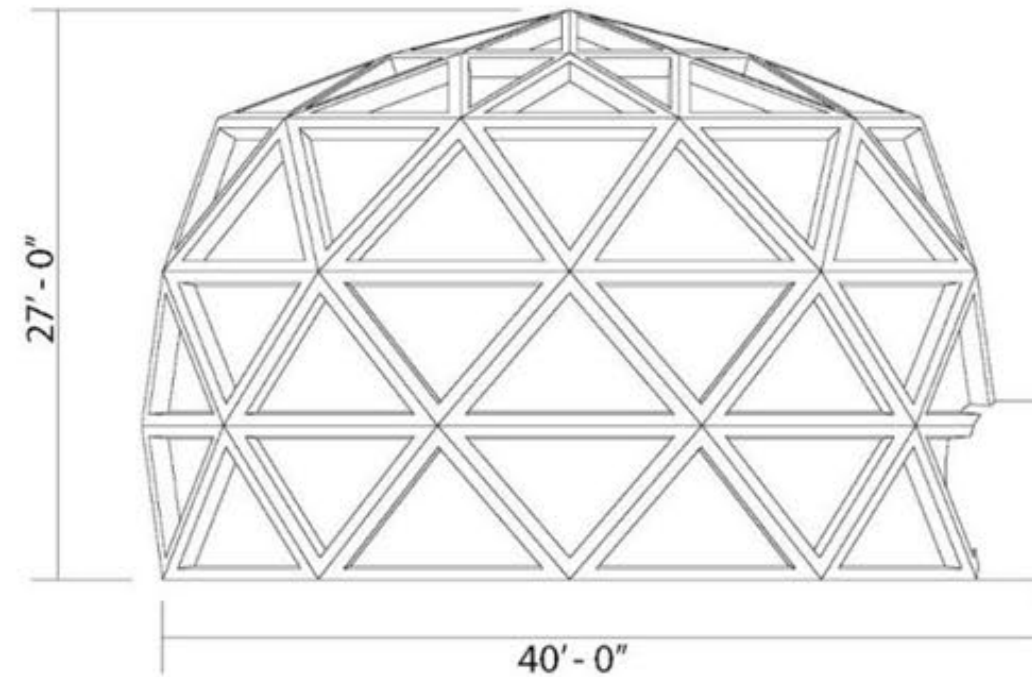
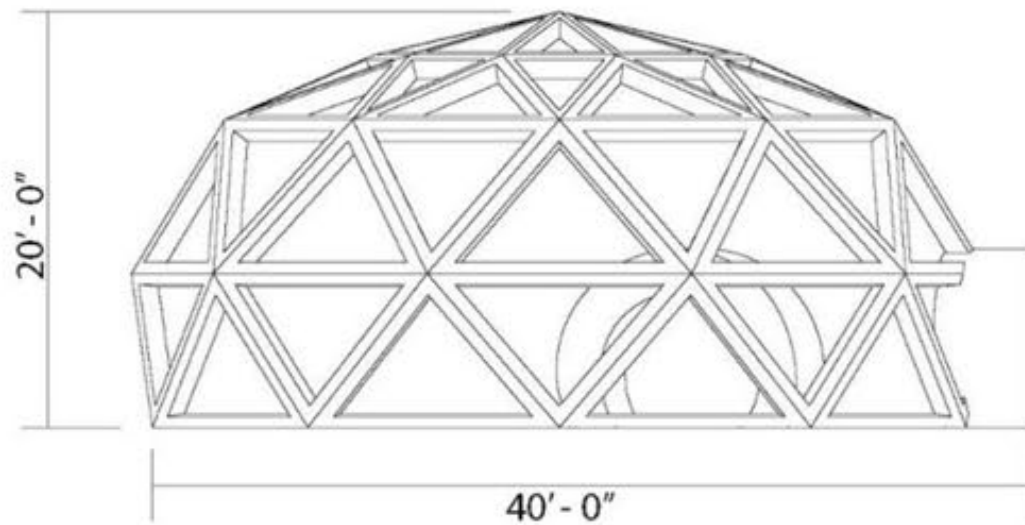
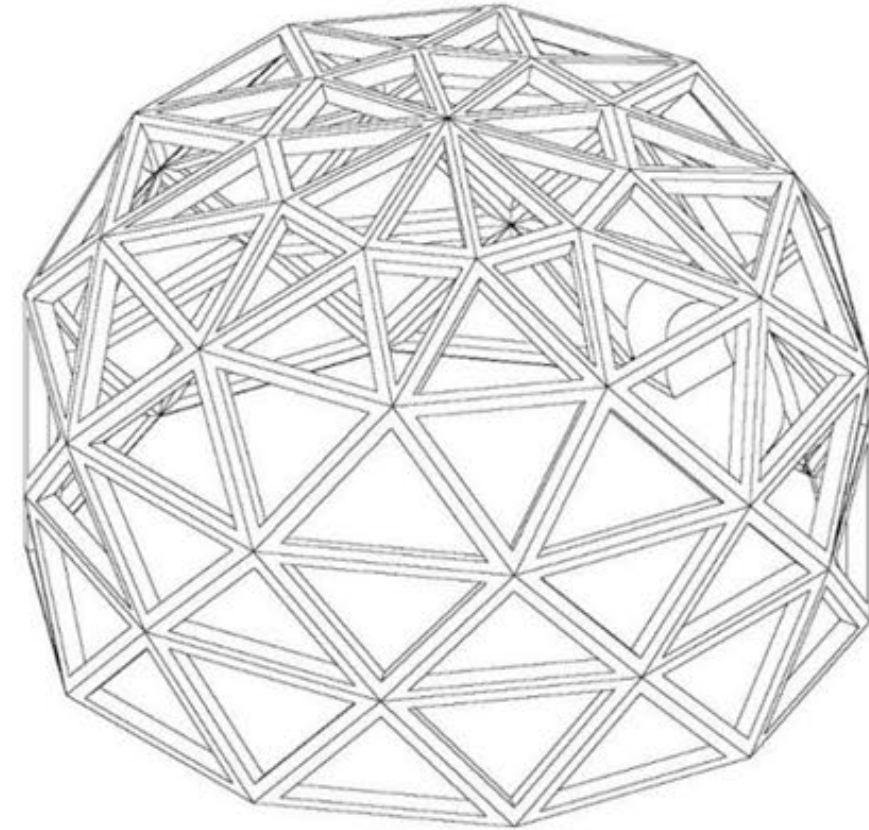
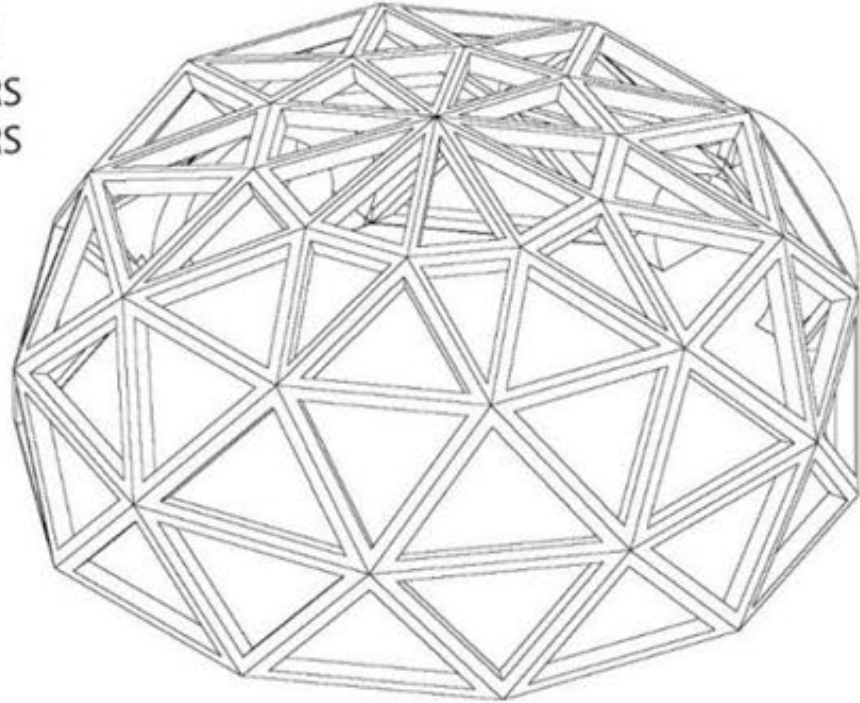
# 3D PRINTED REGOLITH

## SOLID DOMES

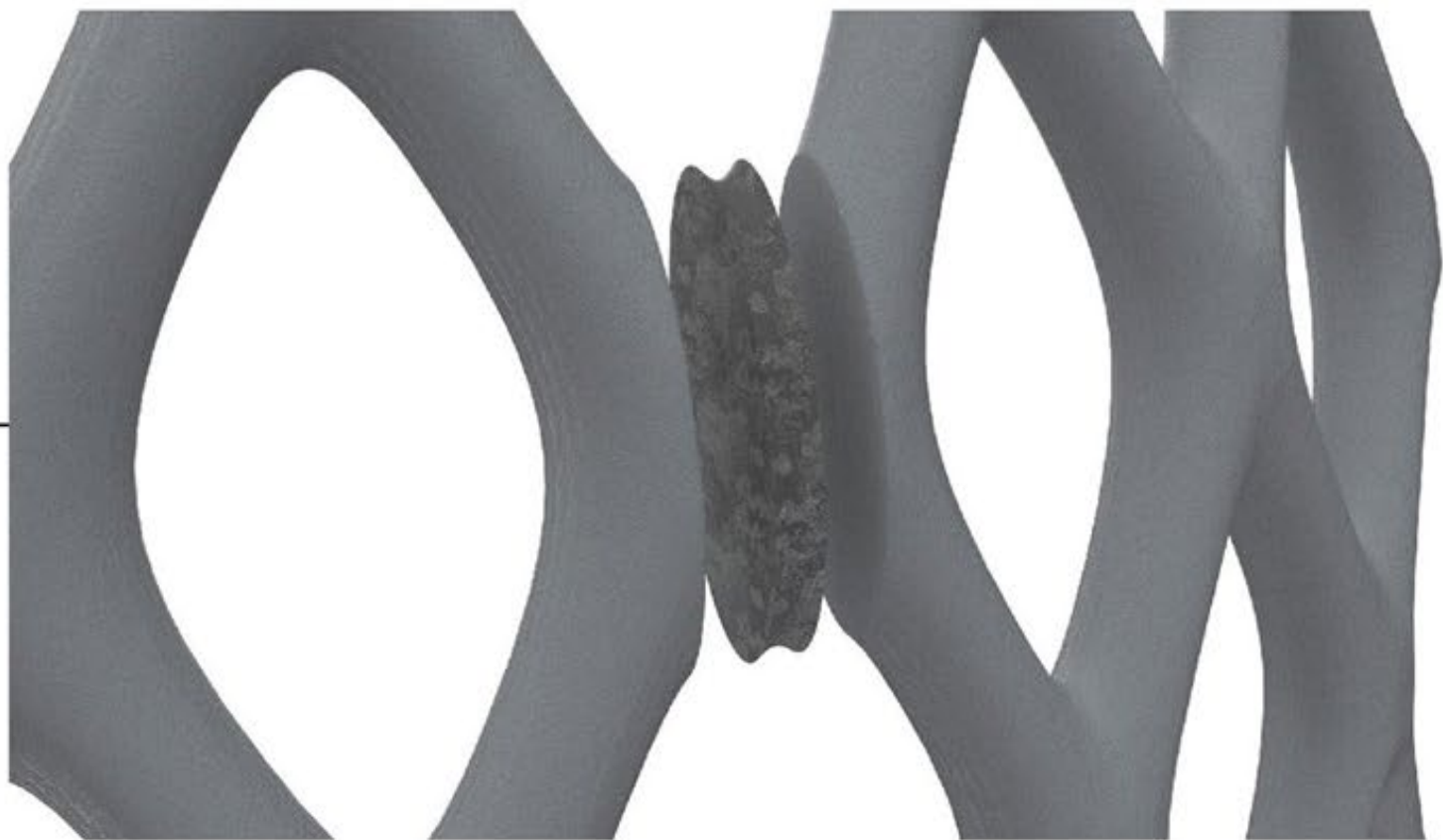
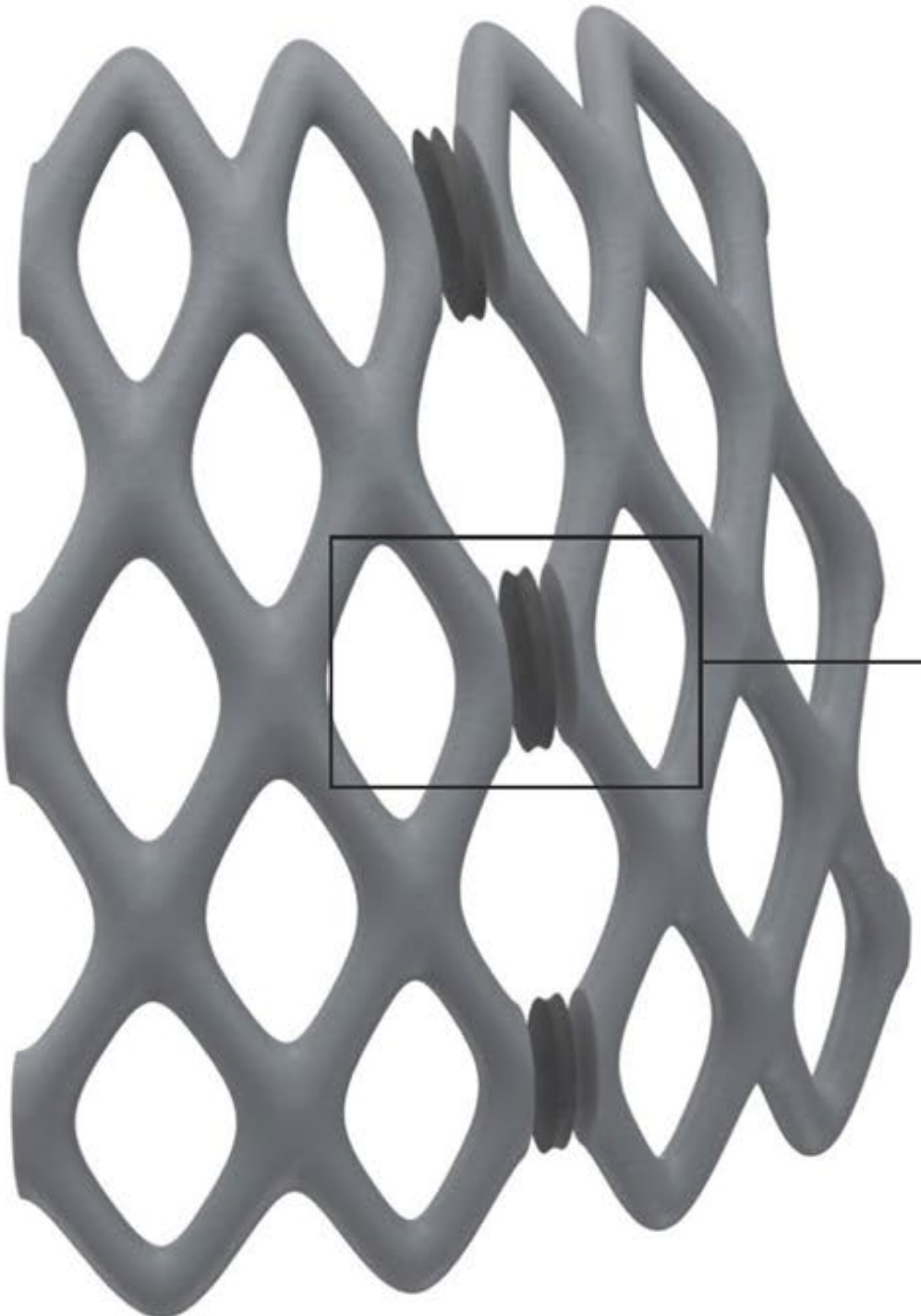
- 1 STORY - 233 CUBIC METERS
- 2 STORY - 283 CUBIC METERS

## GEODESIC DOMES

- 1 STORY - 32 CUBIC METERS
- 2 STORY - 37 CUBIC METERS



# MATERIALITY



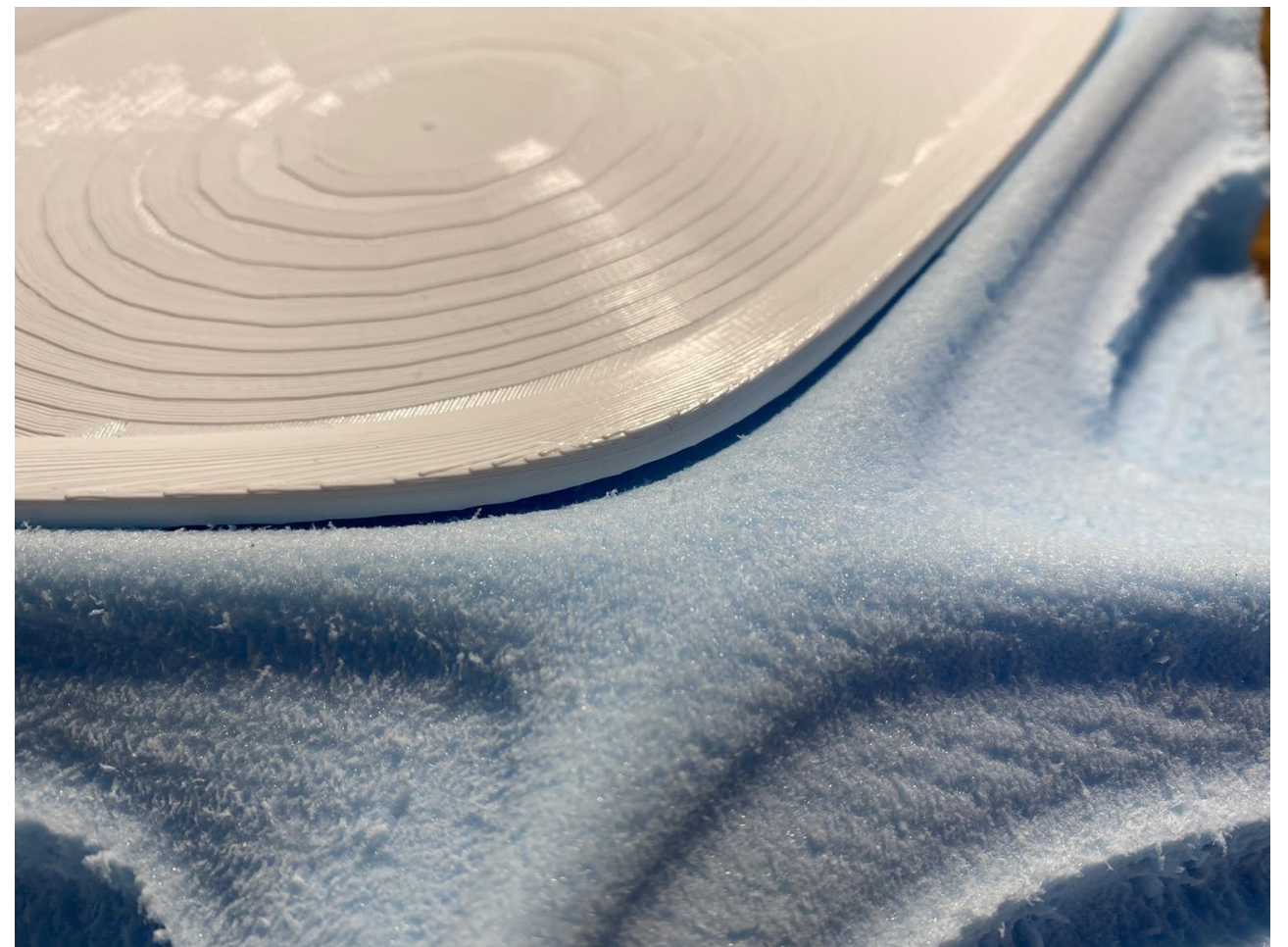
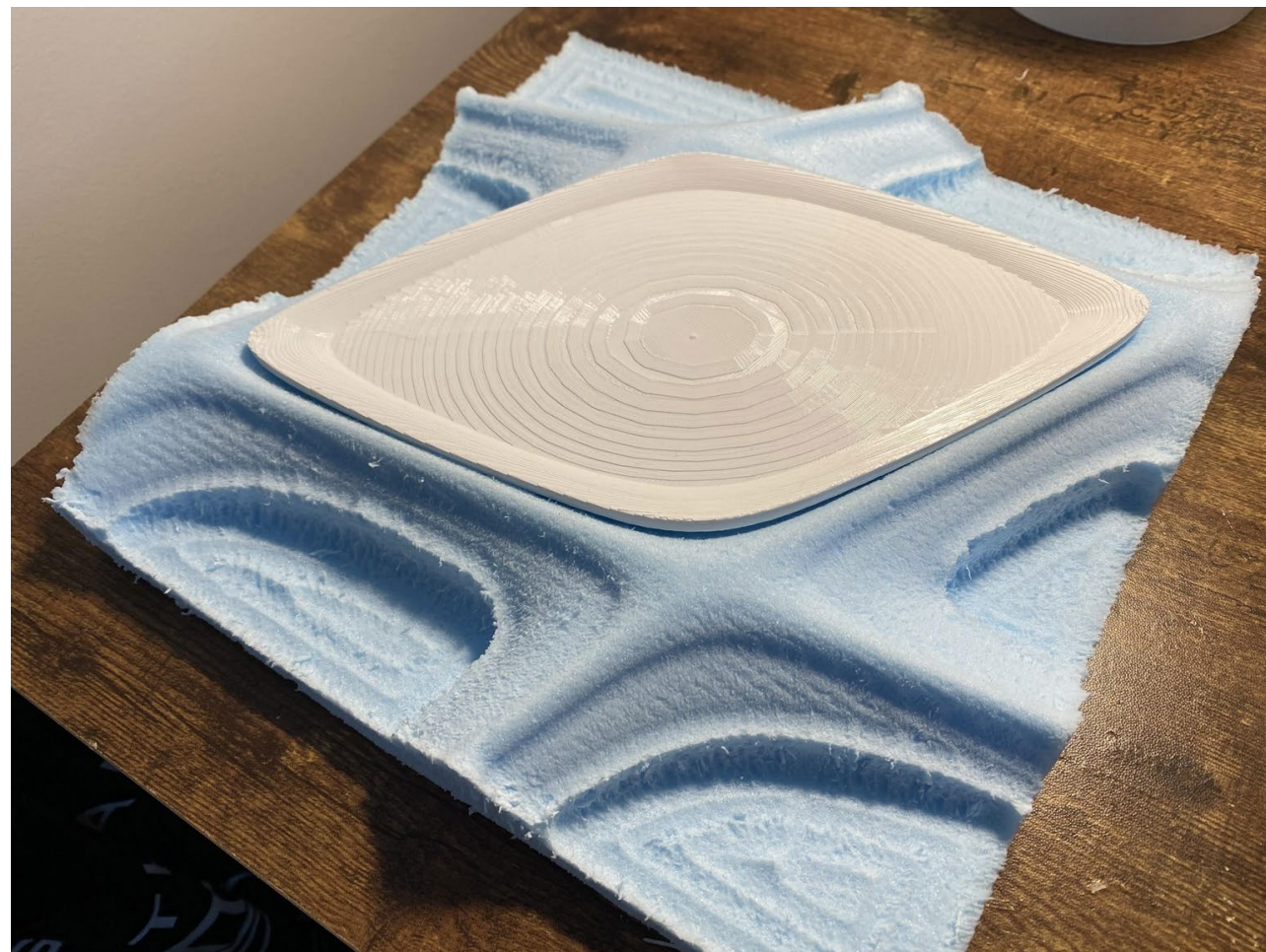
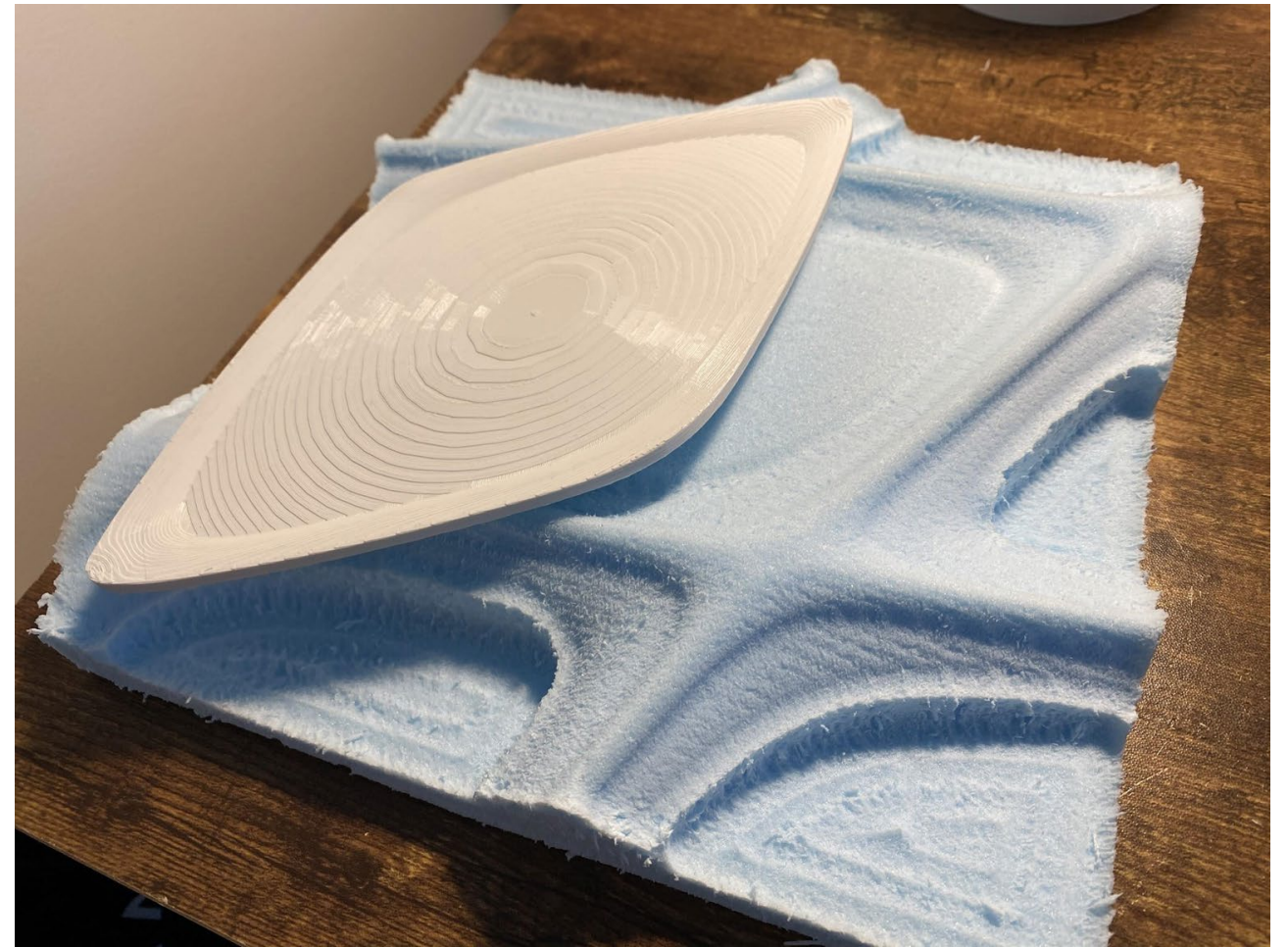
SINTERED LUNAR REGOLITH MIXED WITH SILICA ADDITIVES

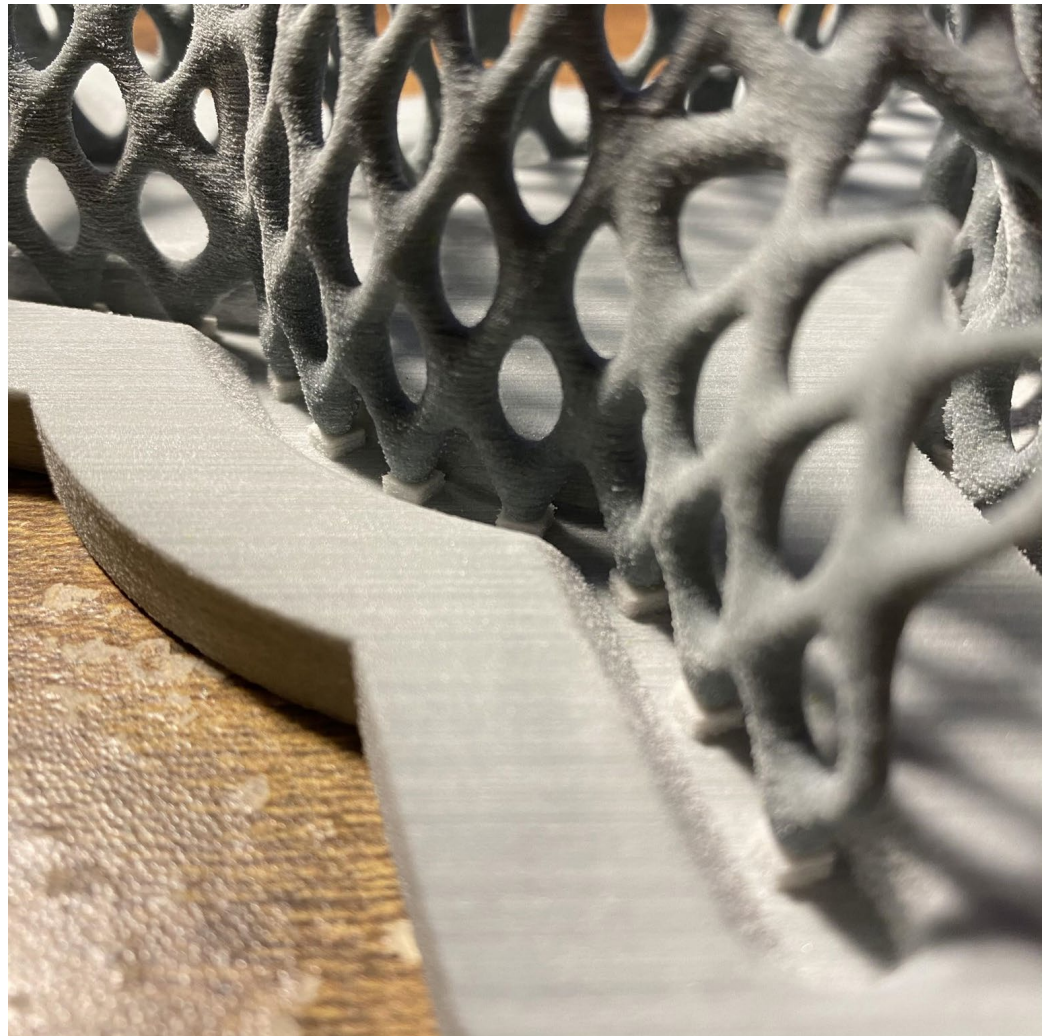
- SILICA IS AMONG THE MOST ABUNDANT RESOURCES FOUND ON THE MOON
- MITIGATES HEAT EXTREMELY WELL
- THIS REDUCES THE THERMAL EXPANSION AND CONTRACTION OF THE STRUCTURE AS WELL AS PROVIDE INSULATION FOR THE INFLATABLE

FELT REUSABLE SURFACE INSULATION

- CAN HANDLE THE TEMPURATURE FLUCTUATION ON THE MOON
- IT IS A RELATIVELY CHEAP AND LIGHT MATERIAL THAT CAN BE BROUGHT FROM EARTH
- IT WILL SERVE AS THE EXPANSION JOINT FOR THE STRUCTURE TO REDUCE CRACKING FROM SEISMIC ACTIVITY

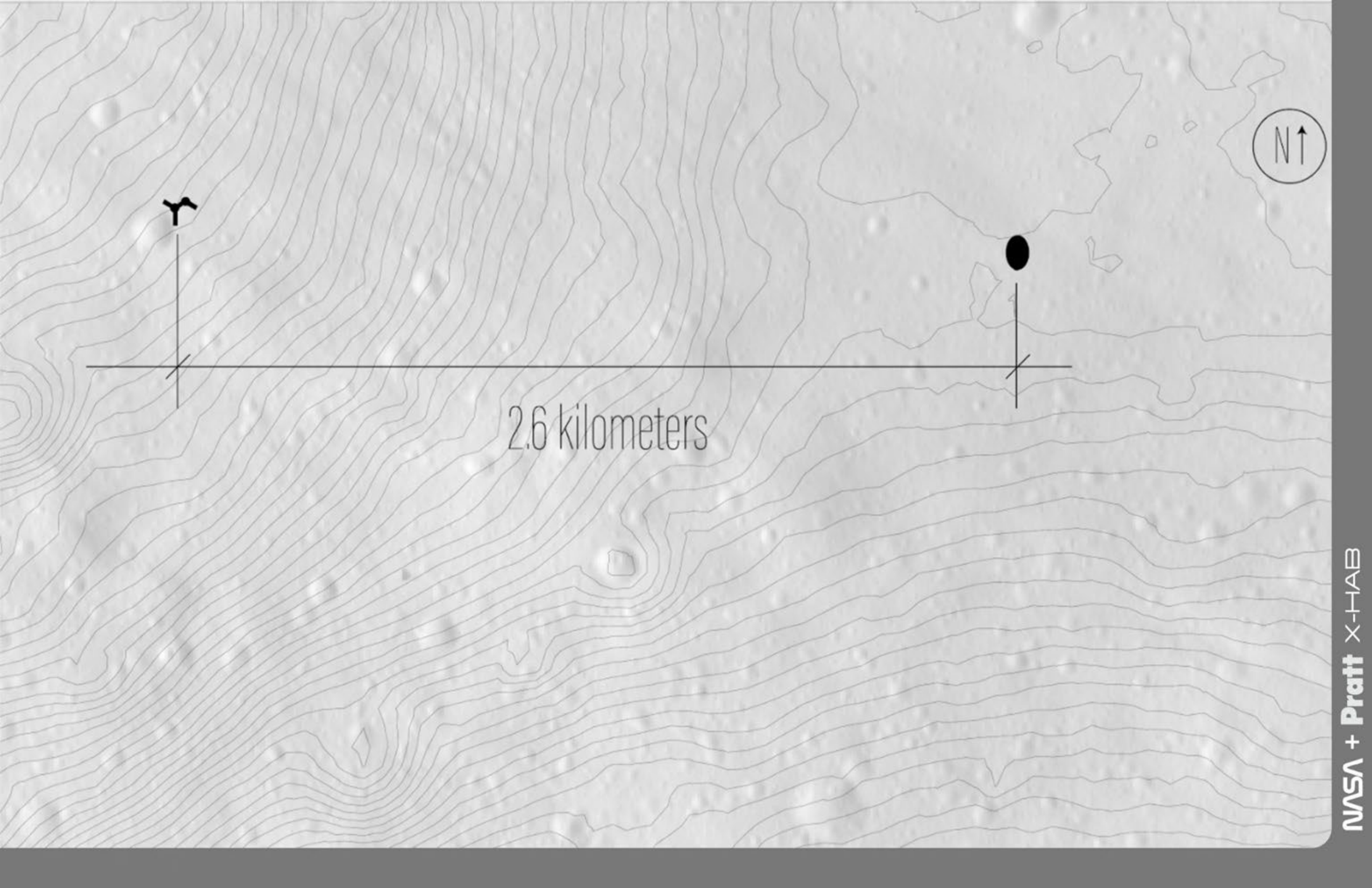
# STRUCTURE





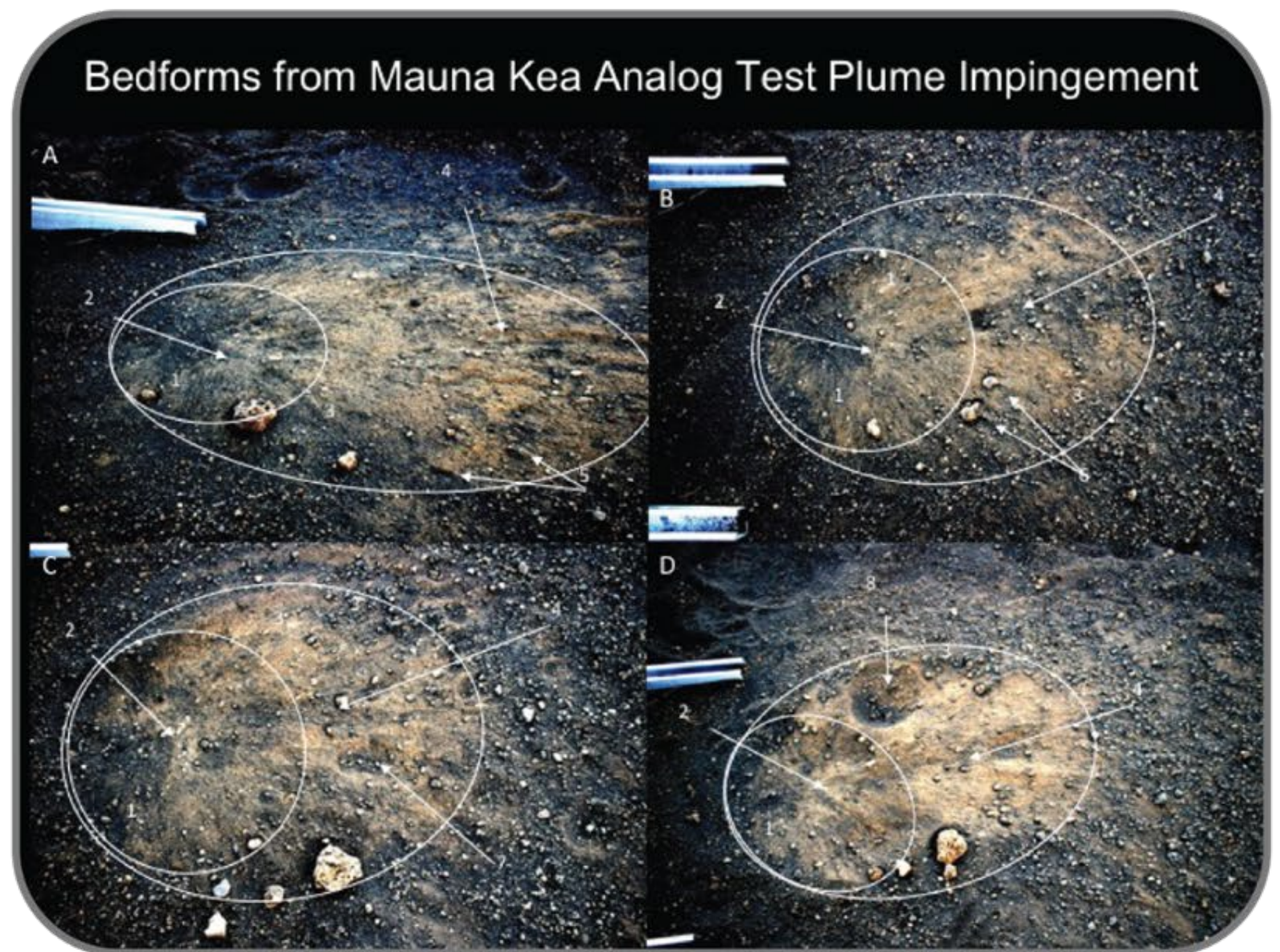
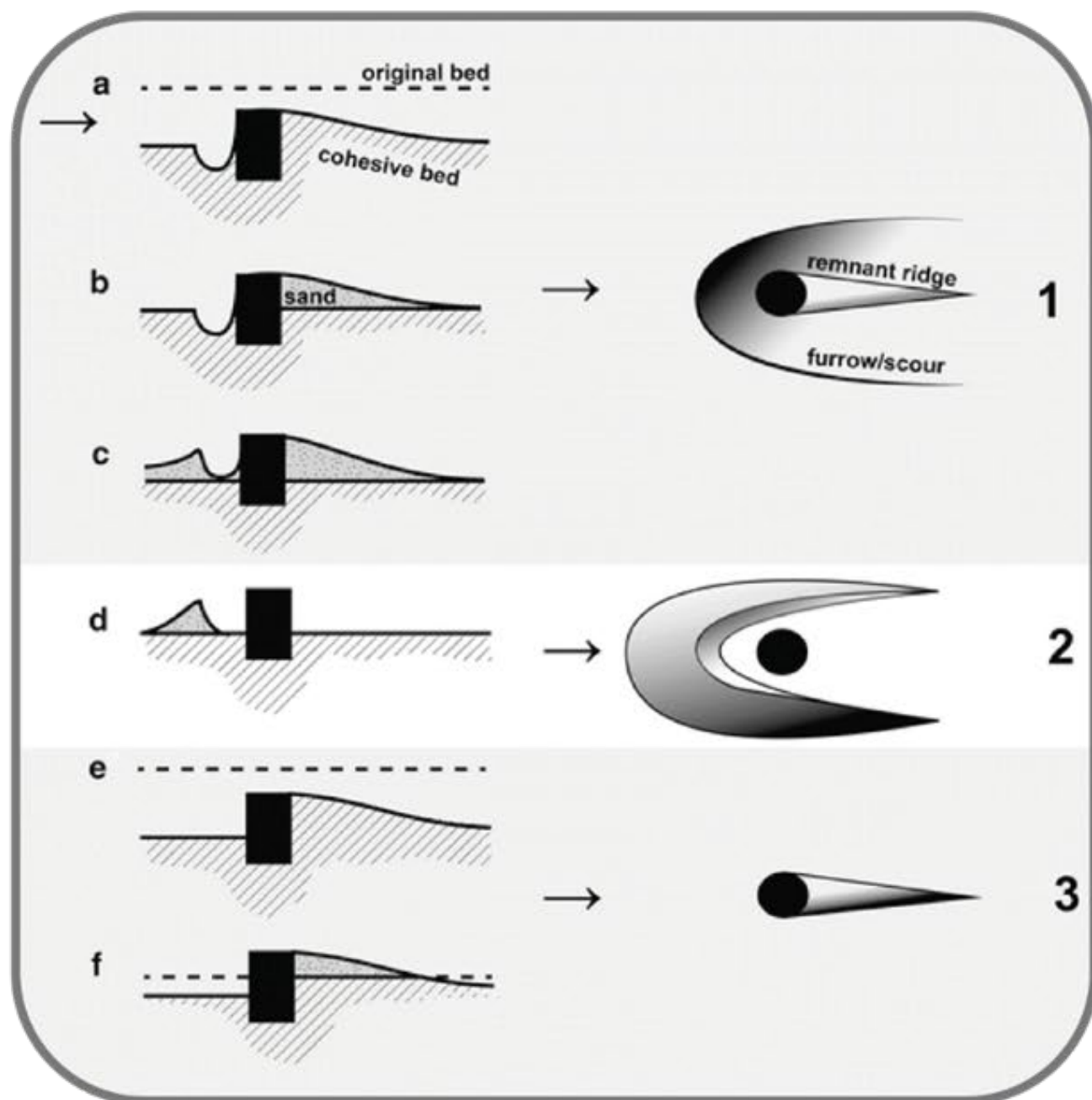
## LANDING PAD

- SECTION CUTS
- ITERATION THROUGH MODELING
- SHEET METAL GROUND INSERTS
- "MUSGUM" TYPOLOGY
- MODEL CONSTRUCTION

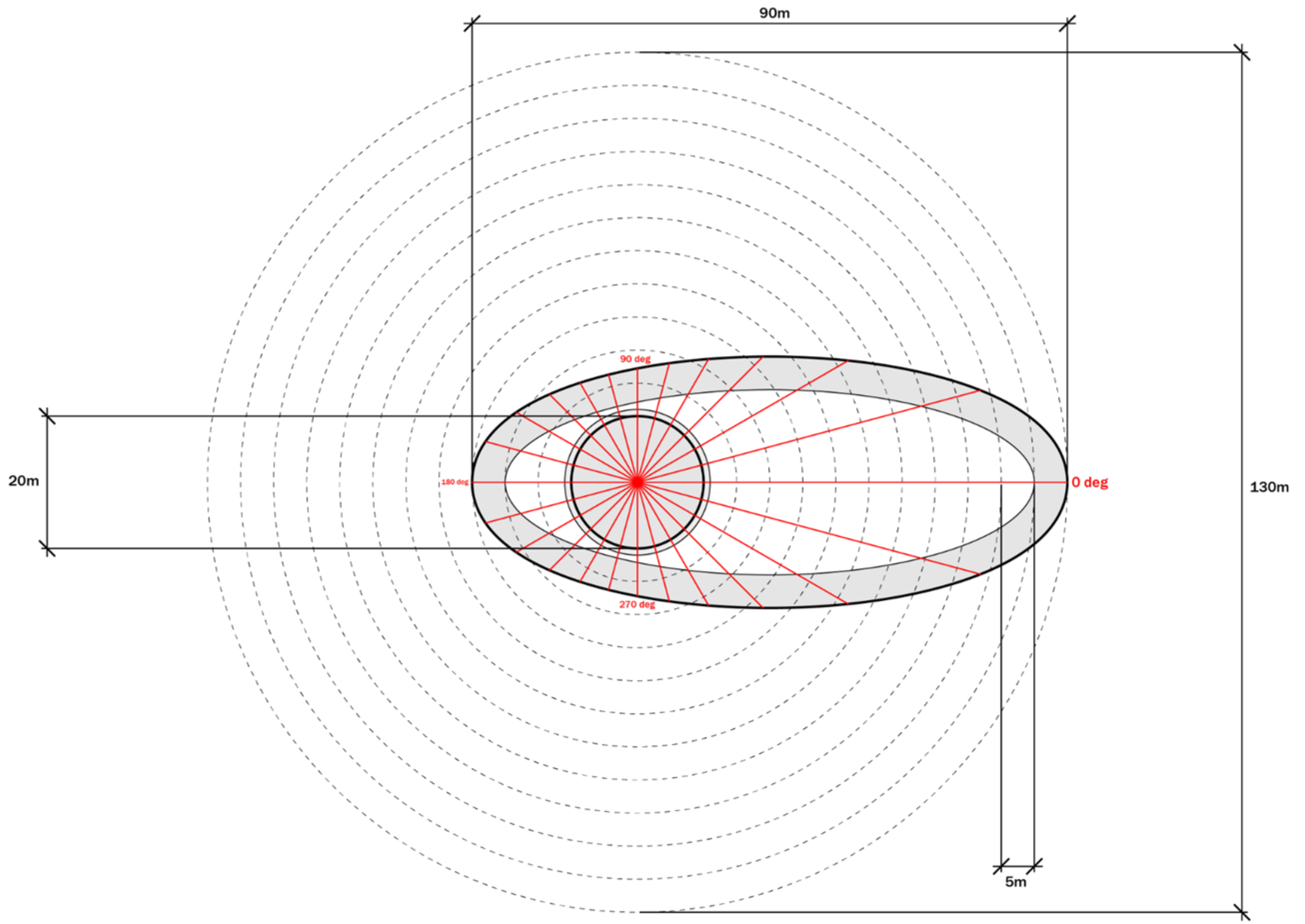


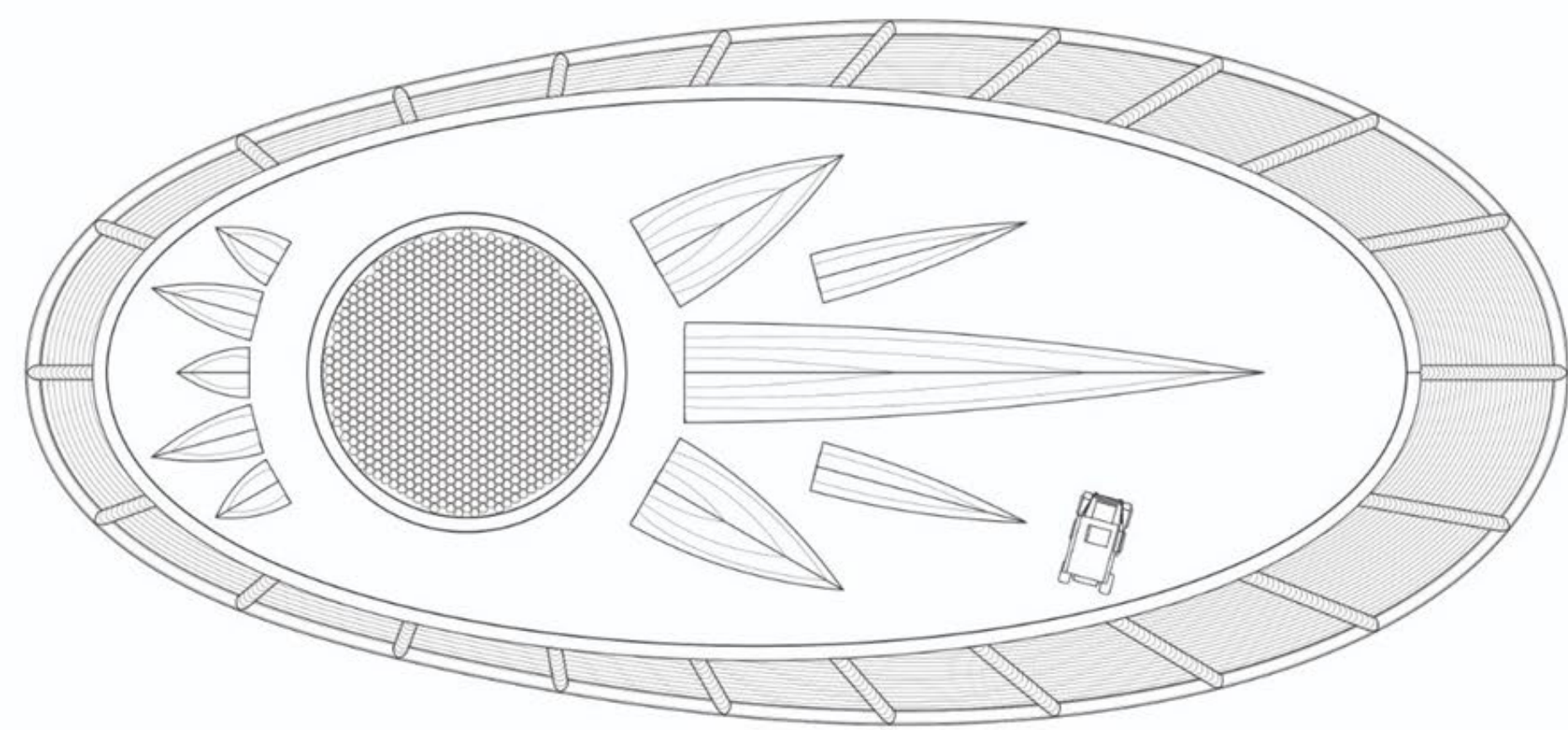
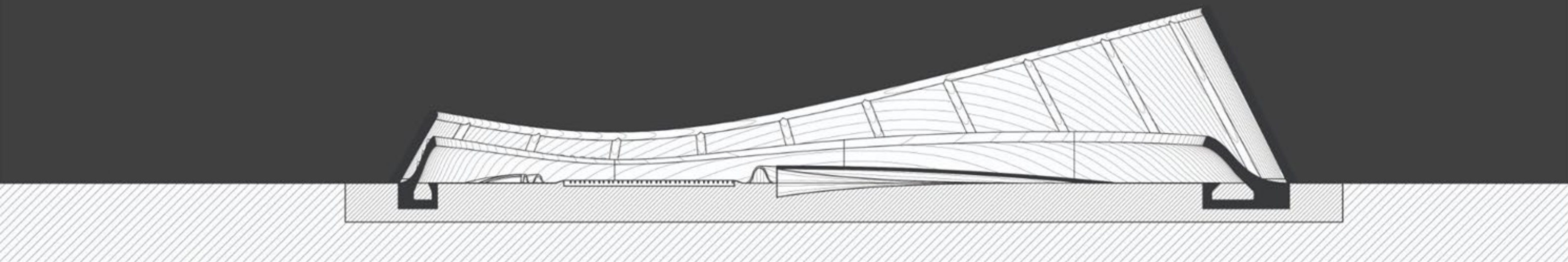
2.6 kilometers

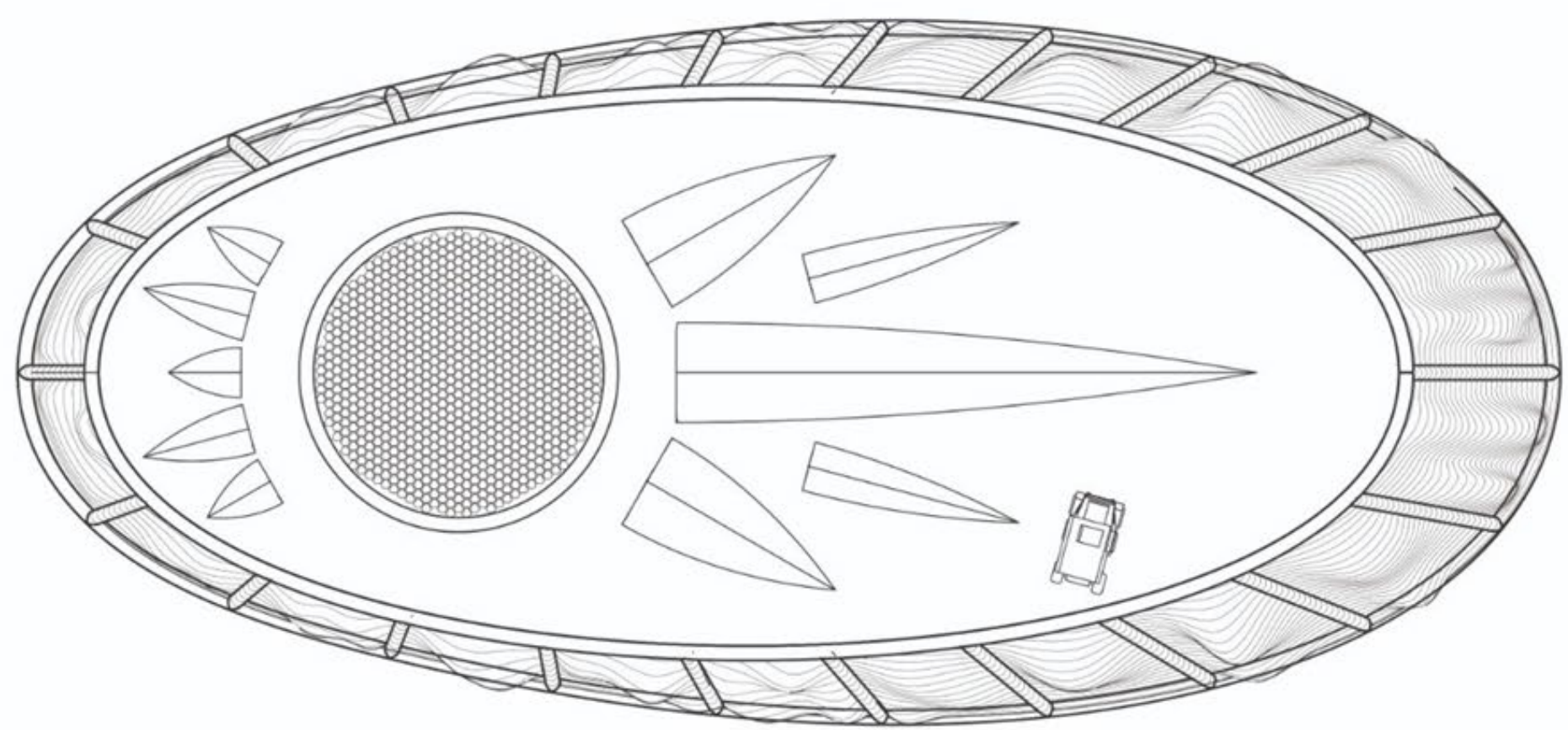
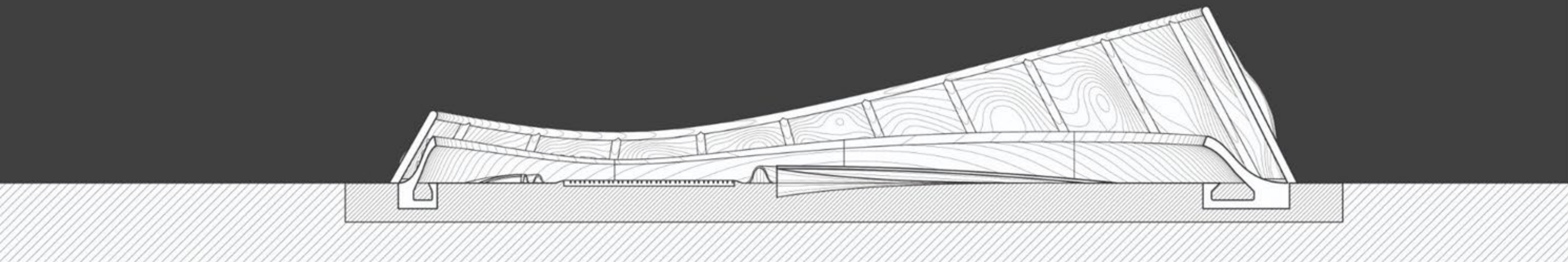
# PRECEDENT



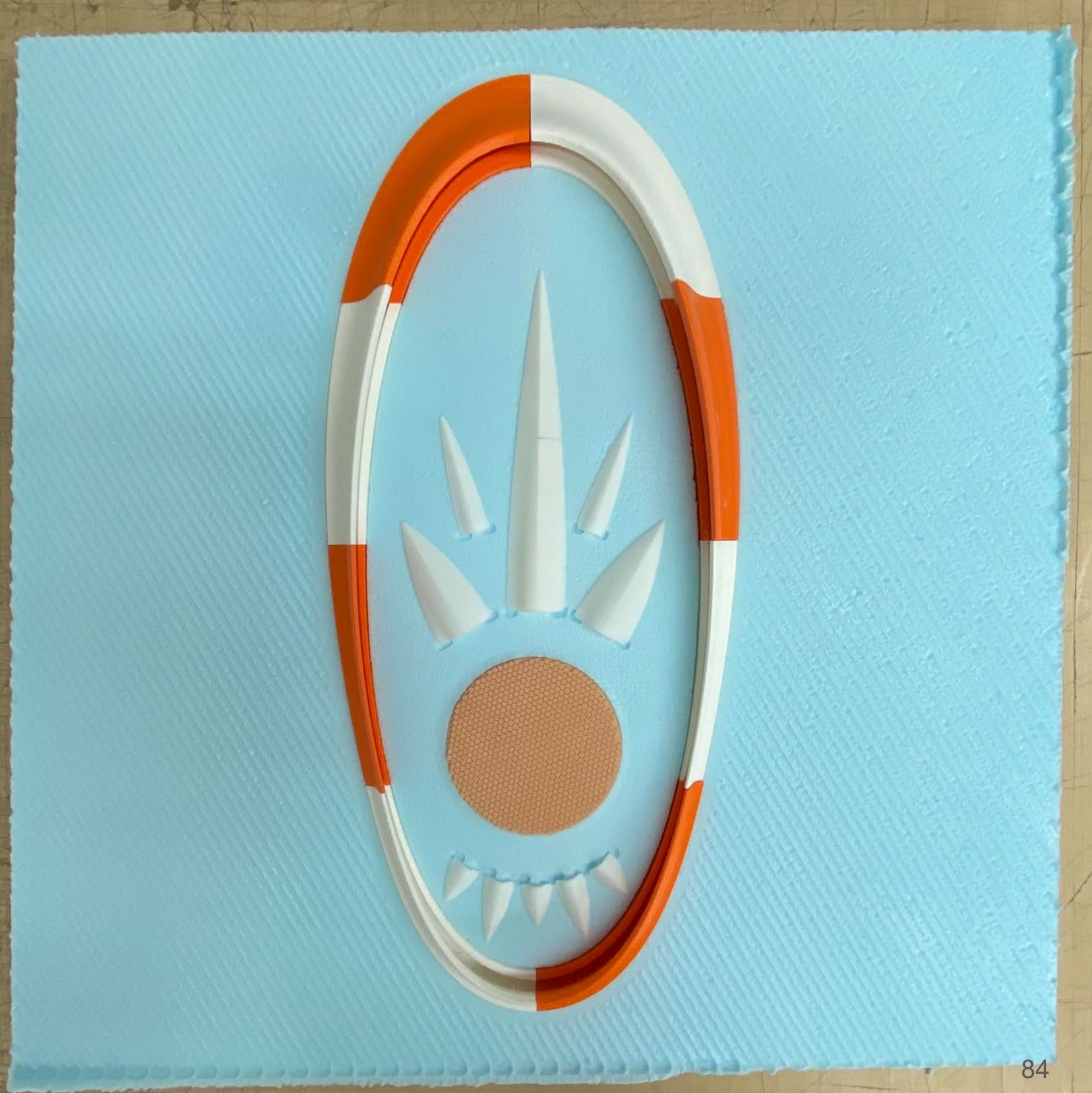




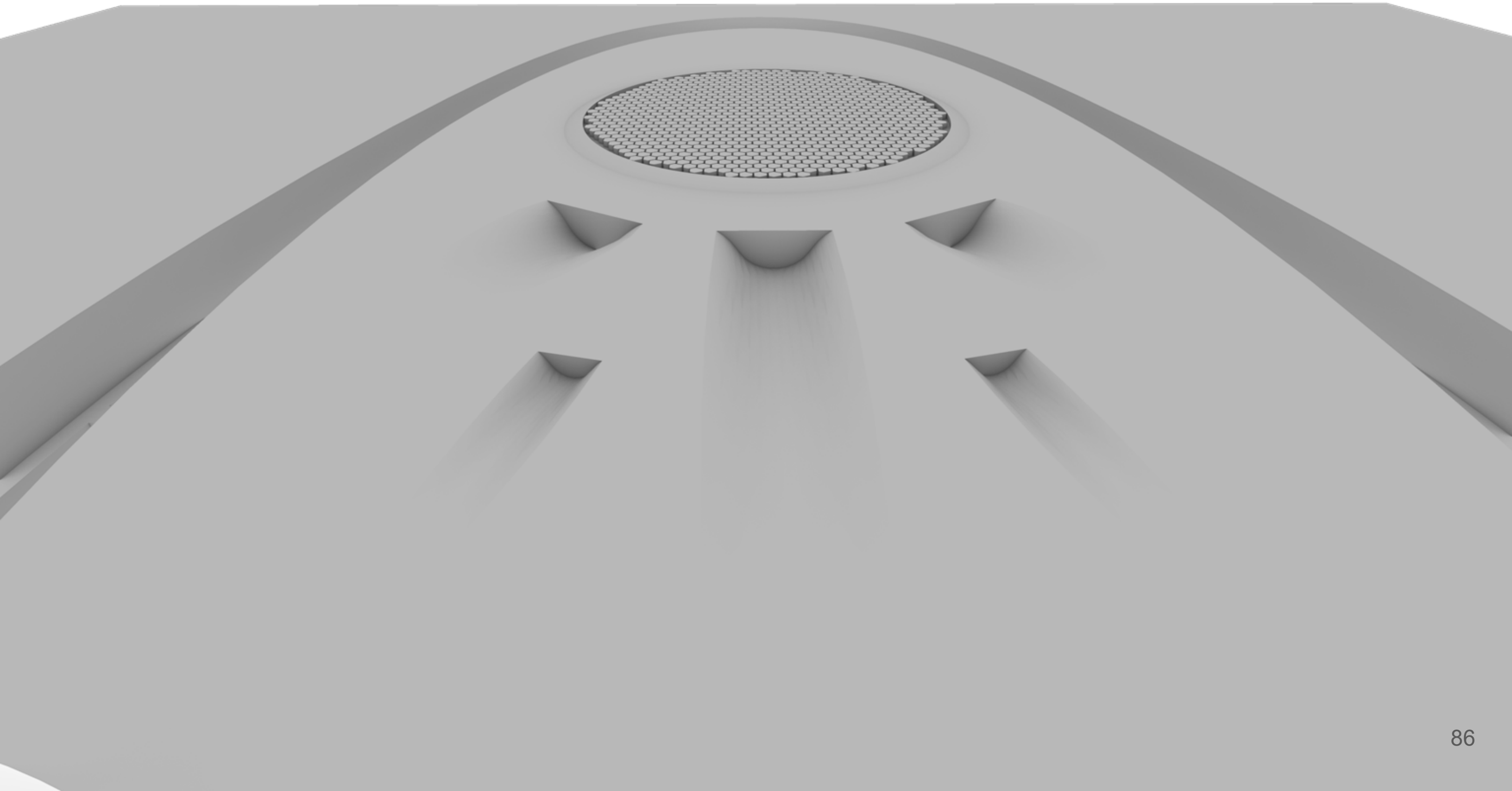


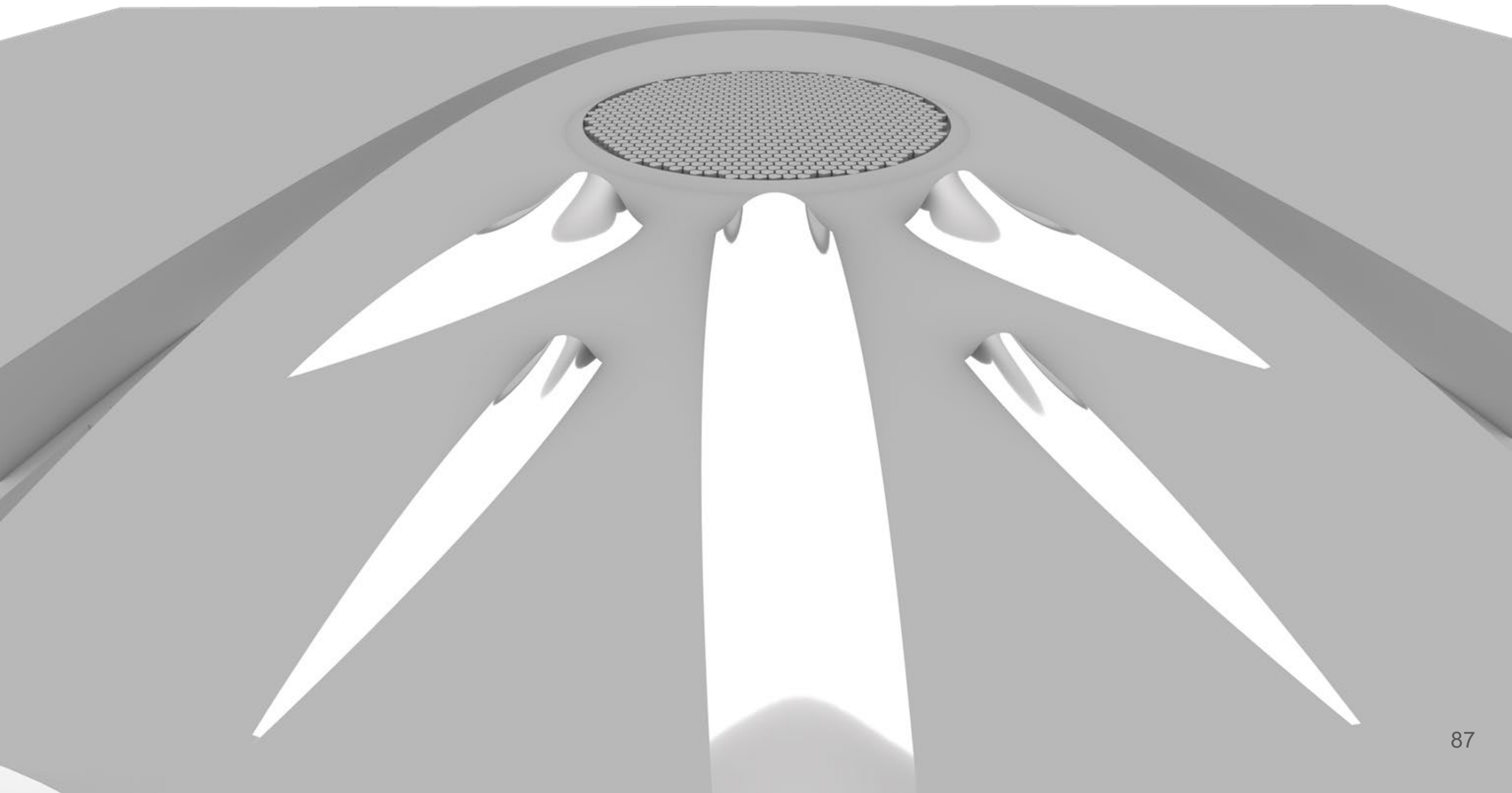


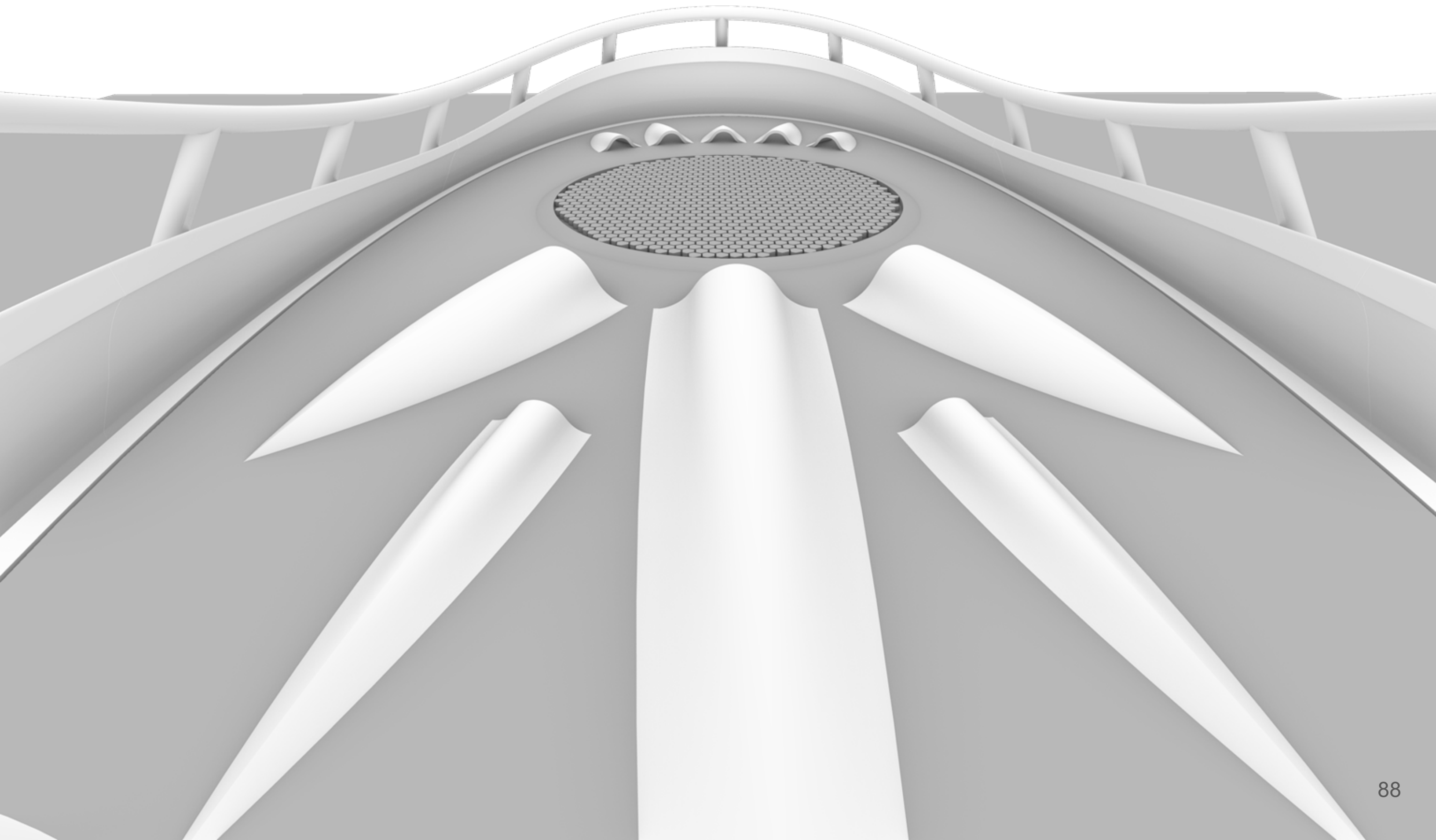
LANDING PAD: DEFLATED PLAN // SECTION



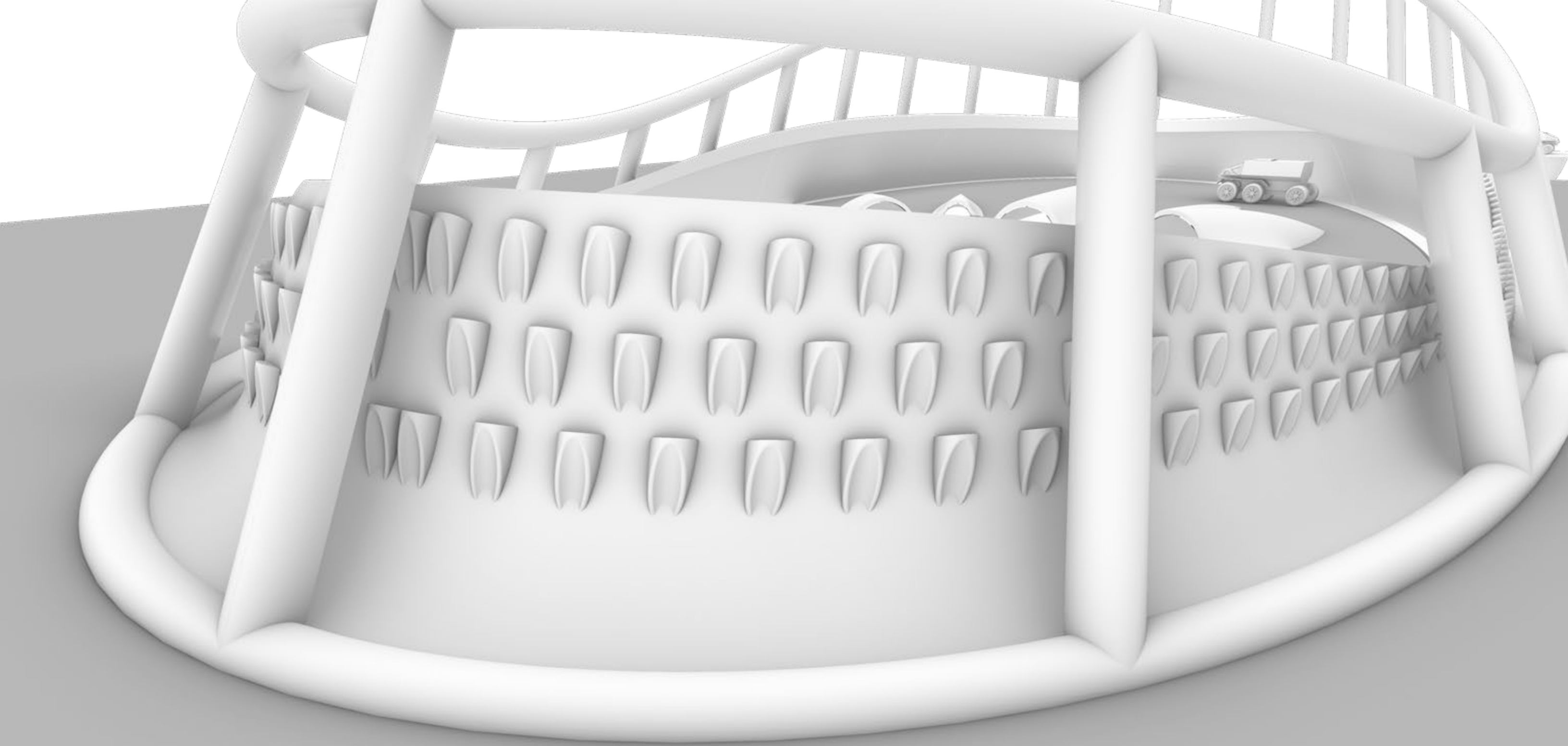




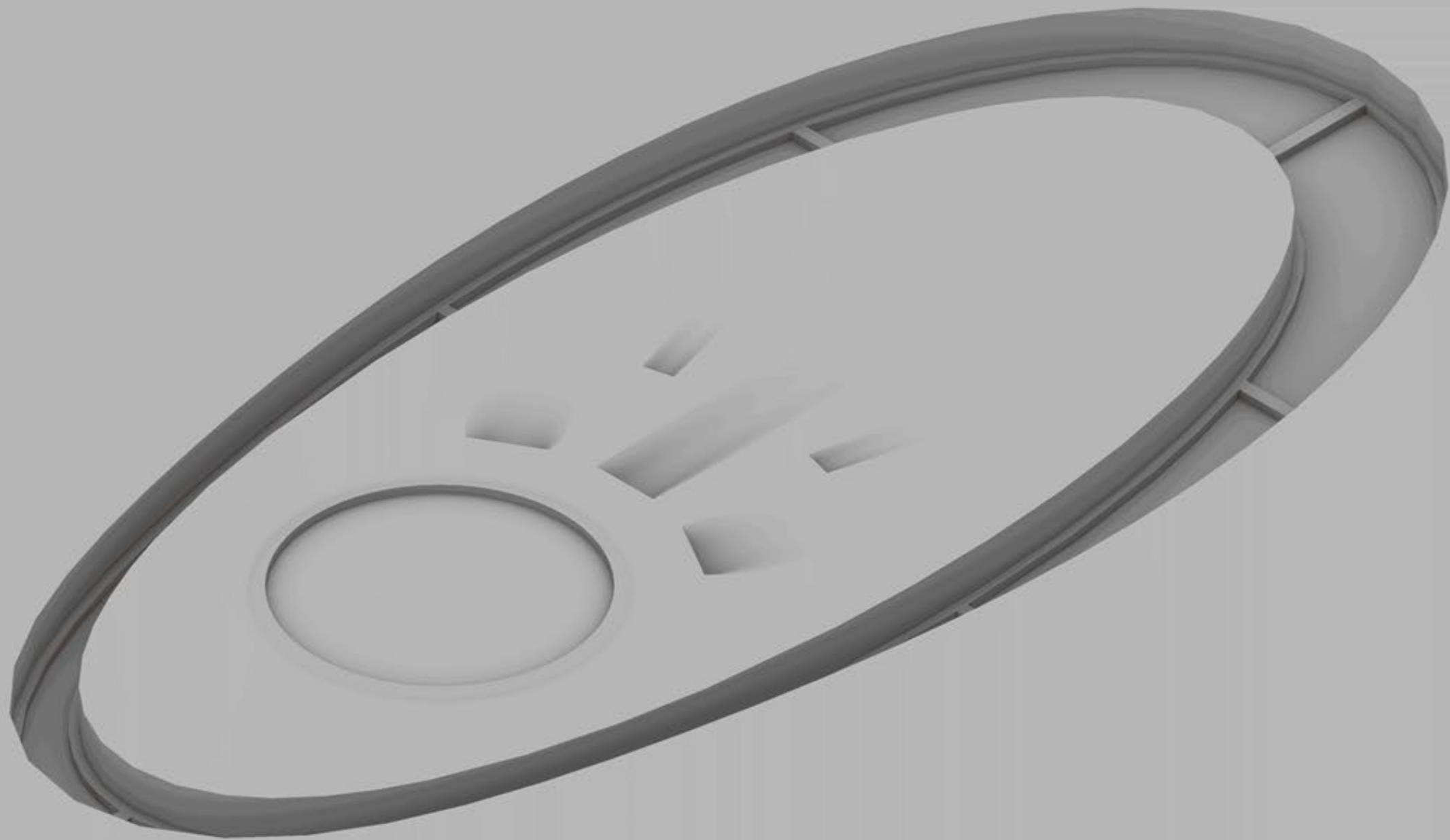


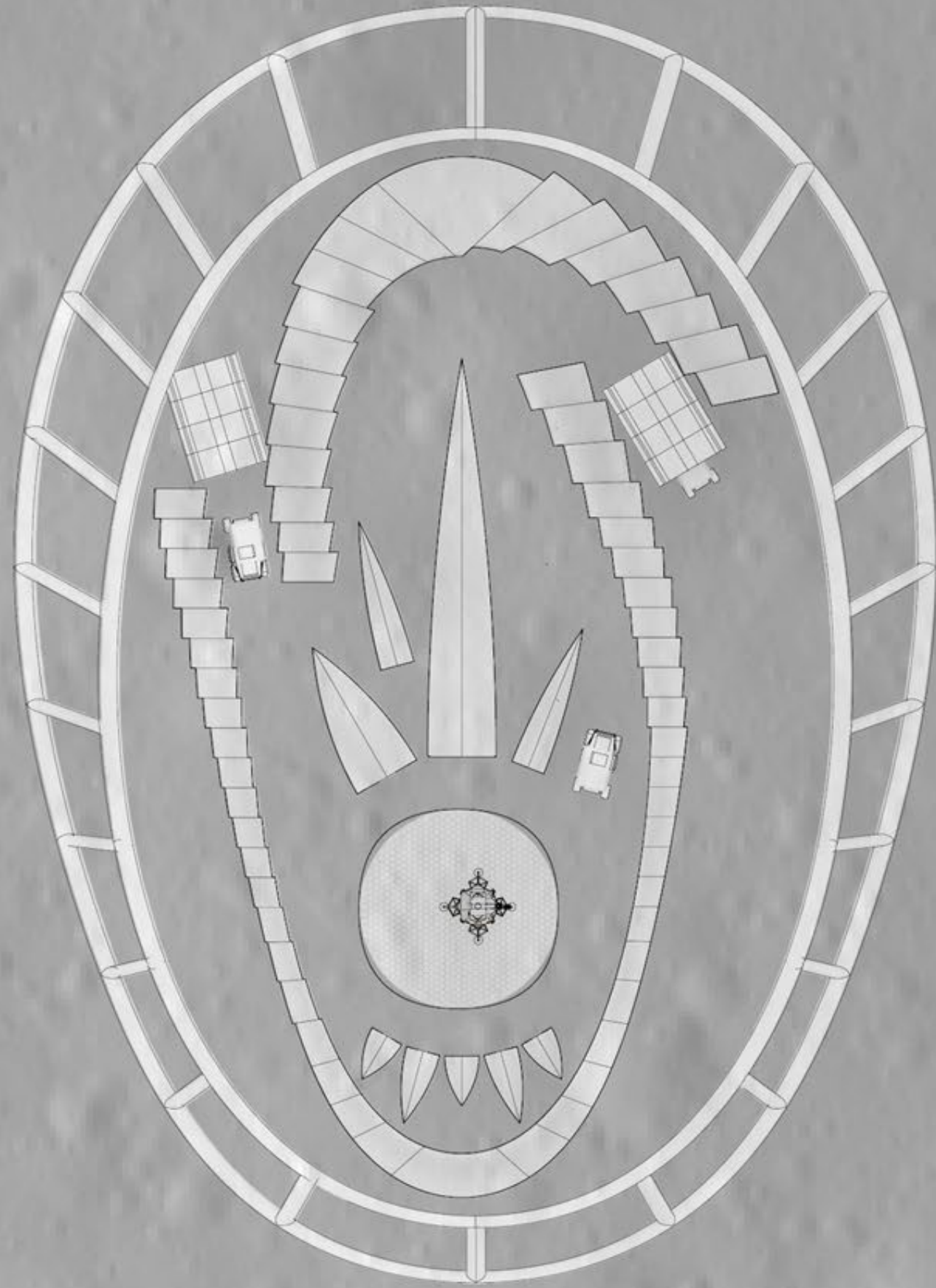




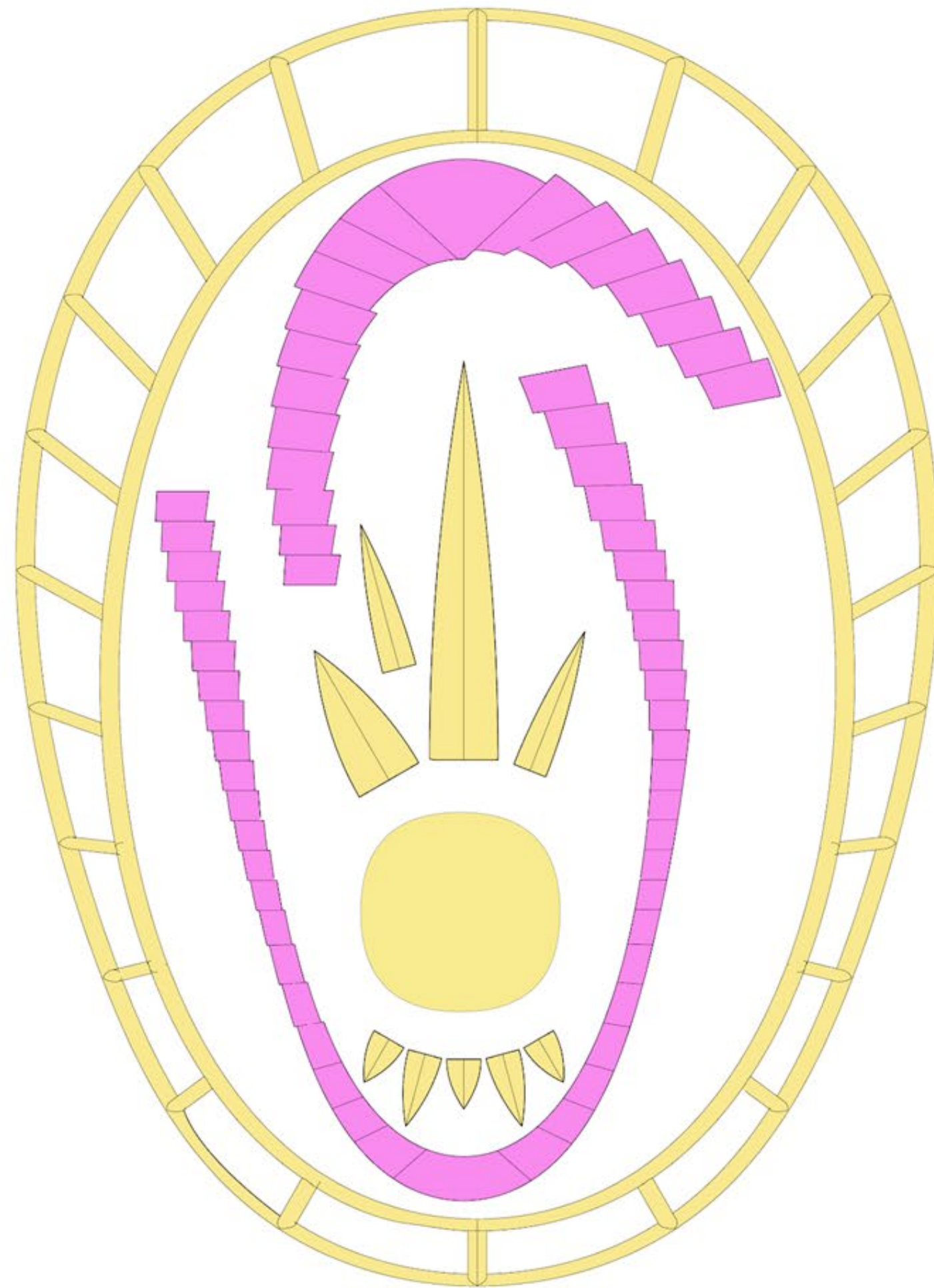


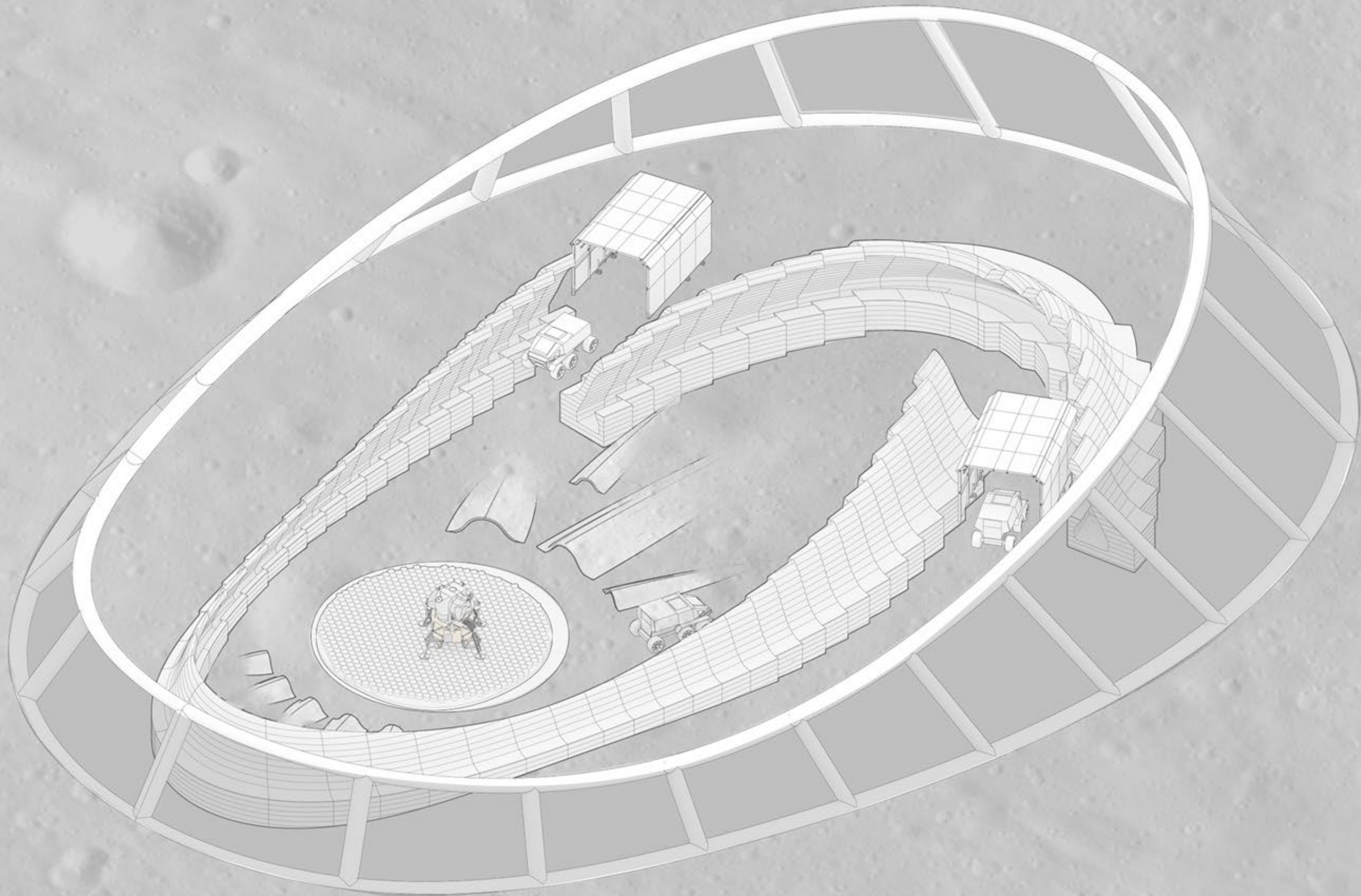






-  Brought from Earth
-  3D Printed Regolith





## BUDGET & SCHEDULE

- PROJECT OVERVIEW
- PROJECT BUDGET OVERVIEW

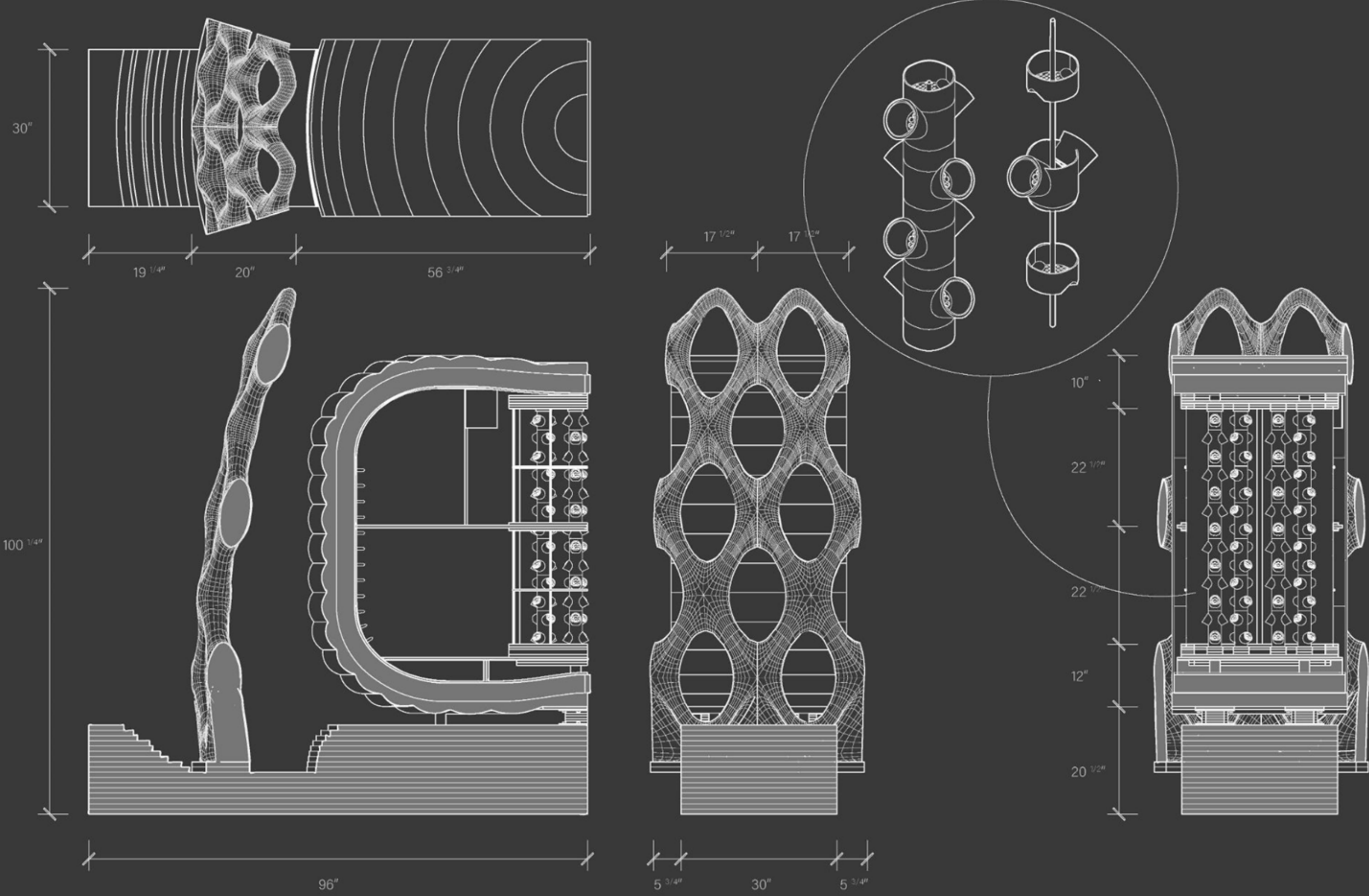
	Start	End	2/25	3/1	3/4	3/8	3/11	3/15	3/18	3/22	3/25	3/29	4/1	4/5	4/8	4/12	4/15	4/19	4/22	4/26	4/29	
<b>Research/Development</b>																						
Design Development	2/25	3/11																				
Material Selection	2/25	3/8																				
Protoyping	3/1	3/18																				
Material Sourcing	3/8	3/15																				
Sectional Detail Development	3/11	3/25																				
<b>Physical Production Start</b>																						
Construction	3/25	4/26																				
Construction: Frame	3/25	4/1																				
Construction: Interior	4/5	4/12																				
Construction: Details	4/15	4/26																				
Construction: Final Wrapup	4/22	4/26																				
<b>Final Documentation</b>																						
Physical Documentation	4/8	4/26																				
Drawing Development	4/8	4/26																				
Presentation Development	4/15	4/29																				
<b>Review</b>																						
Estimated Final Review Date		5/6																				



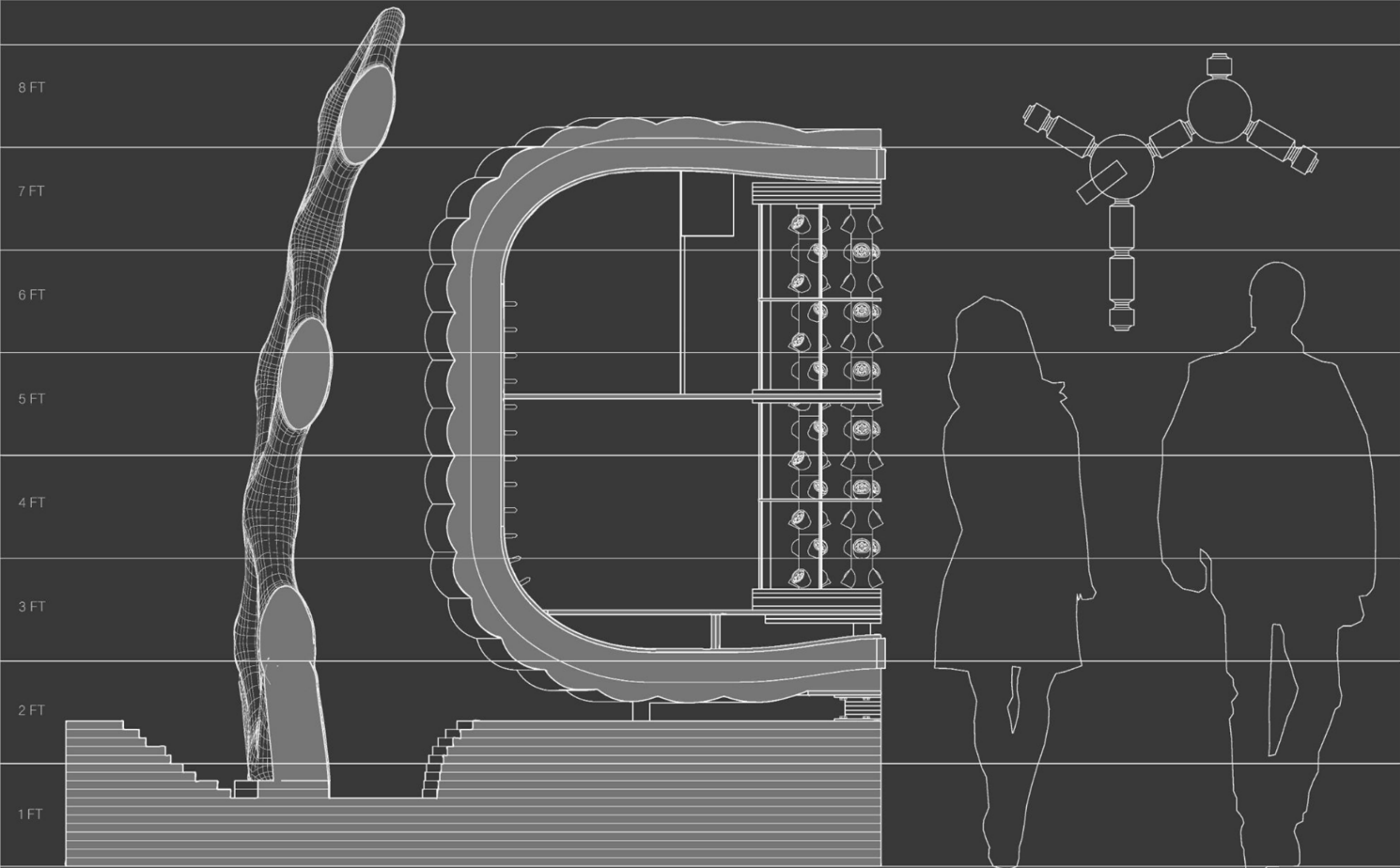
Name	Item	Description	Quantity	Receipt (Y/N)	Unit Cost	Total Cost	Tax	Delivery/Shipp	Total Cost of Transaction
EJ Maxwell	Ultimaker NFC PC - Black	0.75k 2.85m pc filament	1	Y					
	Ultimaker NFC Tough PLA - White	0.75k 2.85m pla filament	2	Y					
	Ultimaker NFC PLA - Yellow	0.75k 2.85m pla filament	1	Y					
	Ultimaker NFC PLA - Blue	0.75k 2.85m pla filament	1	Y					
	Birch Plywood Milling	Birch Plywood 1" X 4 X 8 VC	14	Y					
	Birch Plywood Milling	RIP Plywood 1" X 2'6" X 8		Y					
	Birch Plywood Milling	Birch Plywood 1/2 X 4 X 8 VC	6	Y					
	Aluminum Round Tubes	2" OD x 0.25" Wall x 1.5 ID A	2	Y					
	Aluminum Round Tubes	2" OD x 0.25" Wall x 1.5 ID A	2	Y					
	Keshan Gober	Clay	205 Stoneware Clay 50lb	1	Y				
Mark Parsons	Vacuum Forming		4	Y					
	Epoxy		1	Y					
	S and J Supply			Y					
	S and J Supply			Y					
	S & F SUPPLIES			Y					
	CFD Flower Inc			Y					
	WEST SYSTEM 105B Epoxy Resin	(126.6 fl oz) Bundle with 205	4	Y					
	3D Printlife Yoga Flex	1.75mm White Biodegradabl	2	Y					
	OVERTURE PETG Filament 1.75mm	3D Build Surface 200 x 200 r	1	Y					
	WEST SYSTEM 105B Epoxy Resin	(126.6 fl oz) Bundle with 205	3	Y					
	MIT 3D Printing Assistance	Advising and Services	1	Y					
	Baomain Gereral Purpose Relay MY	8 pin terminal with DIN Rail F	1	Y					
	Beata Heuman: Every Room Should Sing		1	Y					
	Etekcicy Lasergrip 1080	Non-Contact Digital Laser Inf	1	Y					
	Adafruit ALS-PT19	Analog Light Sensor Breakou	1	Y					
	Organic Coffee Co.	OneCUP Breakfast Blend 36	1	Y					
	Linenspa Heavy Mattress Storage B	Double Adhesive Closure, Ki	1	Y					
	ELEGOO Electronic Fun Kit	Breadboard Cable Resistor, C	1	Y					
	uxcell ASH-25DA Solid State Relay	3-32VDC to 24-480VAC 25A	1	Y					
	UEETEK 3D Printer Heating Control	MKS MOSFET for Heatbed E	1	Y					
	DROK 180051US Numerical Control	DC 5-32V to 0-30V 5A Buck	1	Y					
	Victory Pellets Extra Heavy (10 LBS)	Filling, Stuffing & Adding Wei	1	Y					
	SunFounder IIC I2C TWI 1602	1602 Serial LCD Module Disj	1	Y					
	5lb Premium Virgin ABS Pellets for 3	Natural Color	2	Y					
	HiLetgo 1pc A4988 Stepstick Stepper		2	Y					
	12V Power Supply 10A 120W DC		1	Y					
	Ximimark A4988 DRV8825 3D Printer Stepper Motor Driver		1	Y					
	Etekcicy Infrared Thermometer 1025D (Not for Human) Dual Laser		1	Y					
	Klein Tools TI250 Rechargeable Thermal Imager,		1	Y					
	Arduino Mega 2560 REV3		1	Y					
HiLetgo RAMPS 1.4 Control Panel 3D Printer		1	Y						
BIGTREETECH SKR Mini E3 V2.0 New Upgrade Control Board		1	Y						
USA Material CR10 S4 Silicone Heater Pad 400 x 400mm		1	Y						
SUNLU PLA 3D Printer Filament,		4	Y						
Maiti King	1248LMDF	12mm 4 X 8 Ultralite M.D.F	2	Y					
	148LMDF	25mm (1") 4 X 8 Ultralite M.D	24	Y					
	4410F	4X4 10' #2&BTR KD FIR	4	Y					
	FUEL	FUEL SURCHARGE	1	Y					
	148ACR	31/32 4x8AC Radiata ply	2	Y					
	2410F	2X4 10' #2&BTR DOUG KD I	30	Y					
	Clear Easy to Form PETG Sheet, 48"X96" 0.03 thick		2	Y					
	Styrene Black 48"x96"x0.04		5	Y					
	4lb 24"x48"x0.04"	Corafom/Duraboard U40	8	Y					
	4lb 48"x96"x01"	Corafom/Duraboard U40	1	Y					
	4lb 48"x96"x03"	Corafom/Duraboard U40	3	Y					
	Costa Perez	3 Pies and Drink	Dominos Pizza	4	Y				

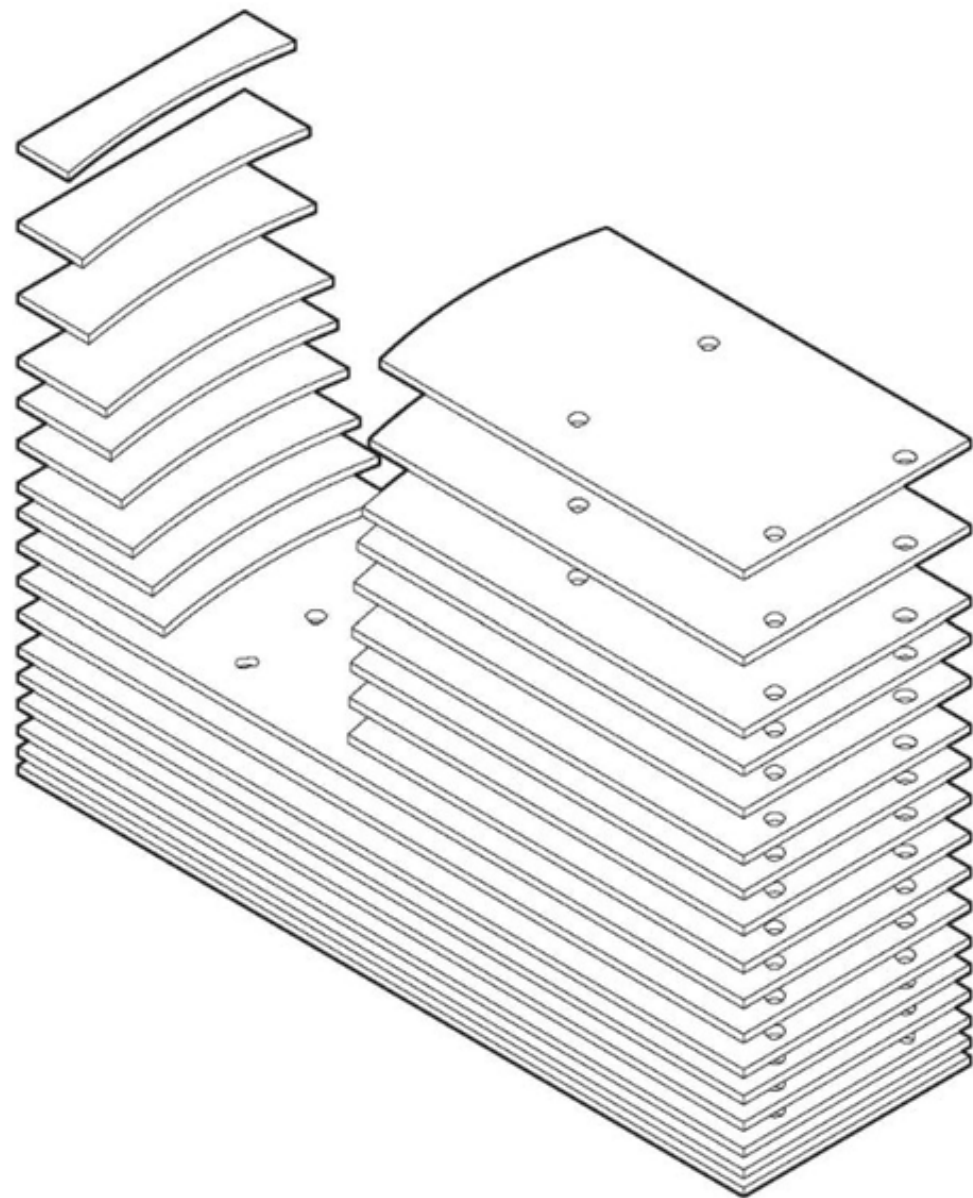
## DISPLAY MODEL

- LUNAR BASE CHUNK
- CONSTRUCTION SEQUENCE



CHUNK MODEL 1/4 FT : 1 FT

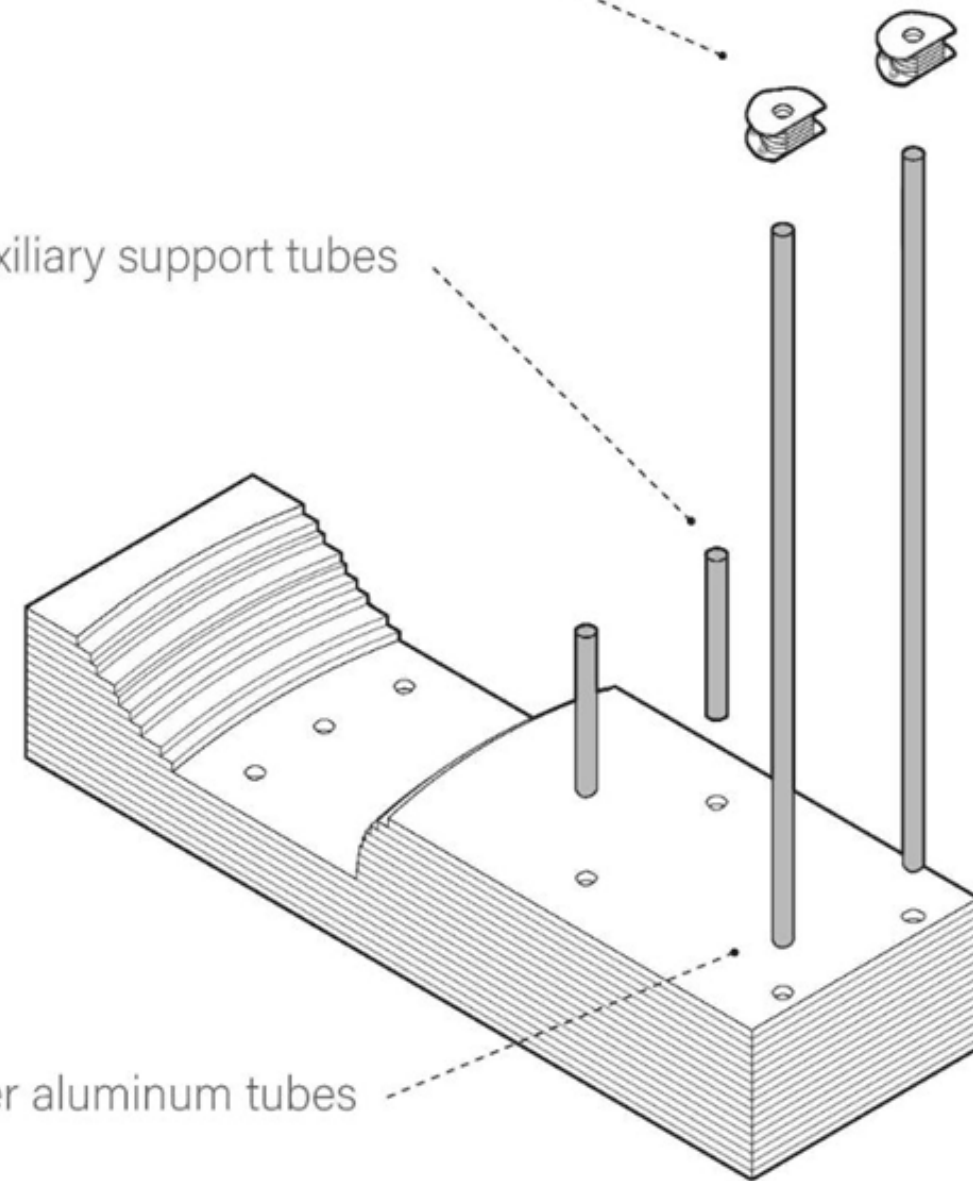




Base: 1" layered plywood

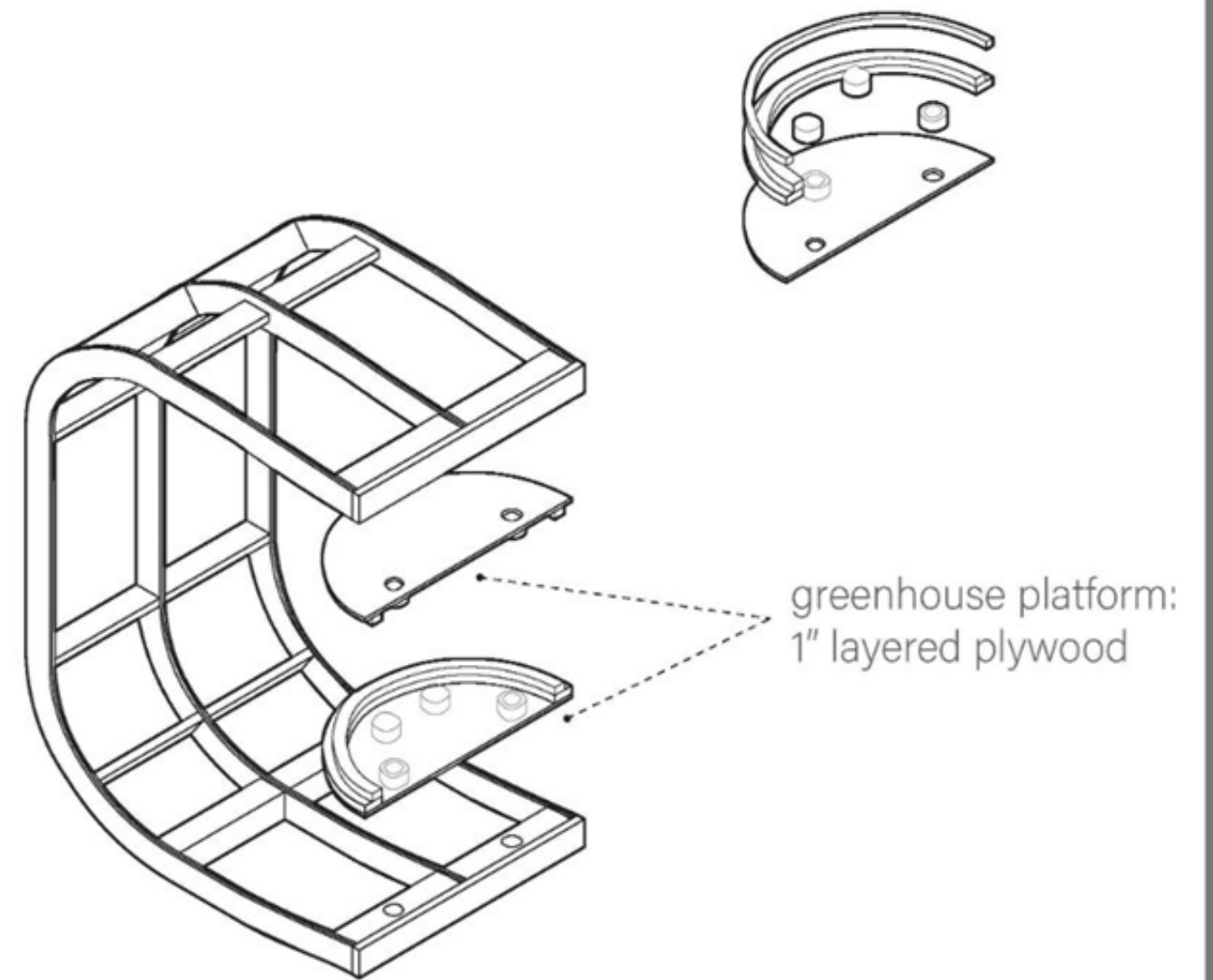
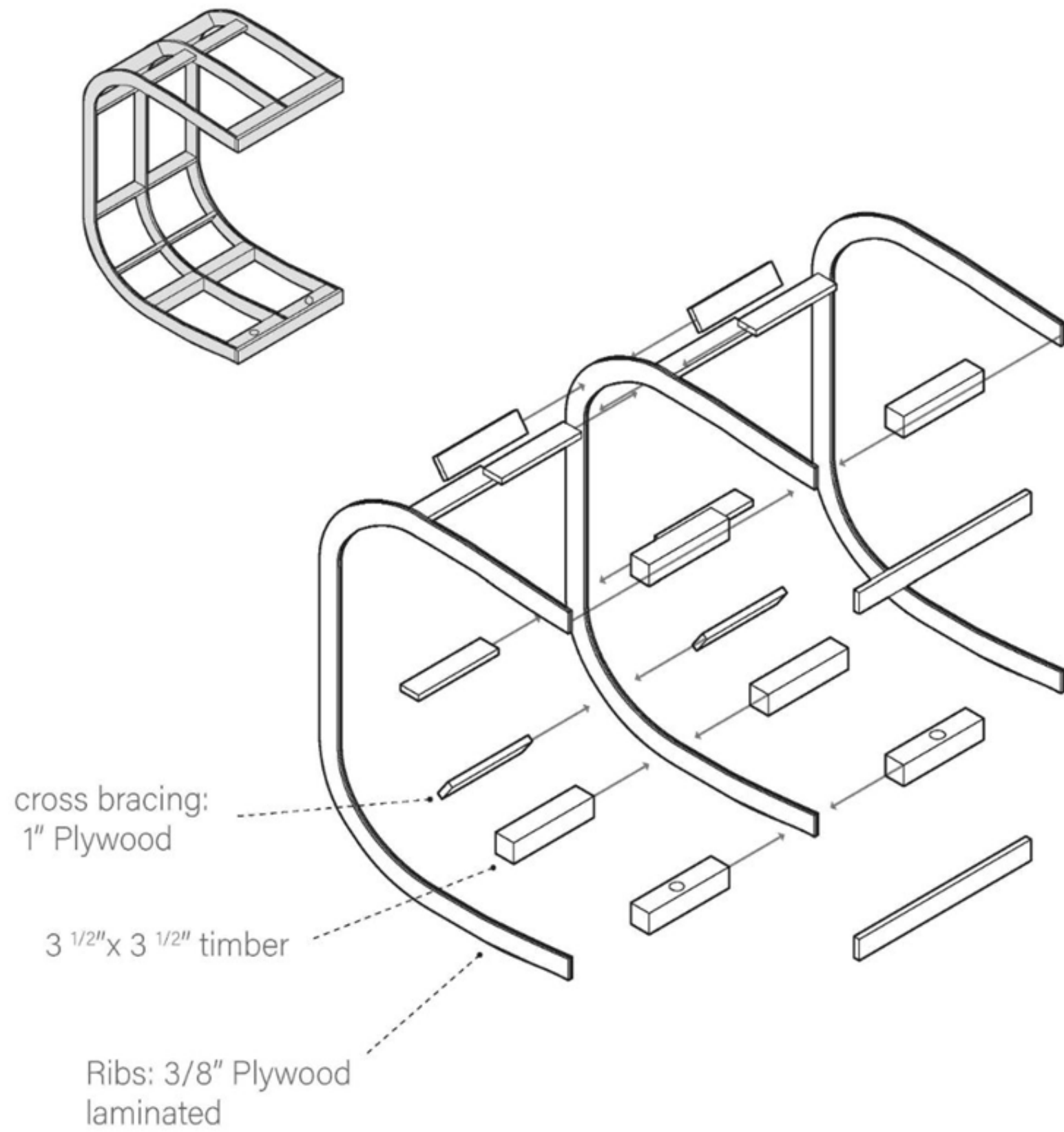
Base Seismic isolators

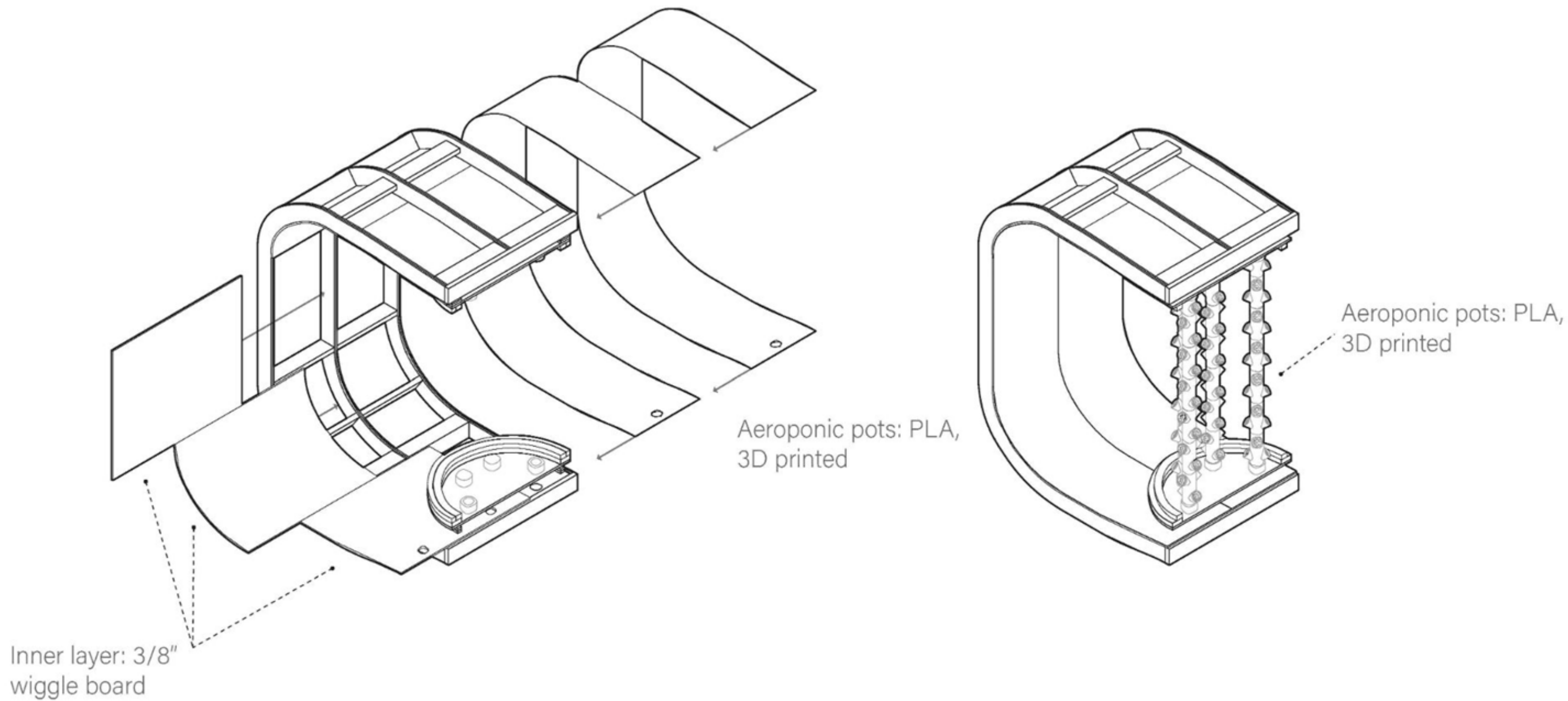
Auxiliary support tubes

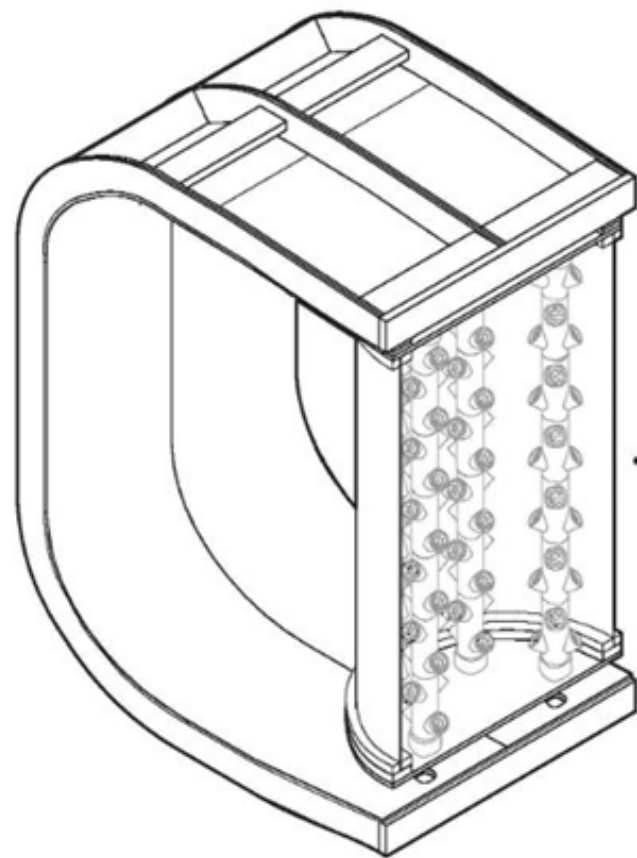


2" diameter aluminum tubes

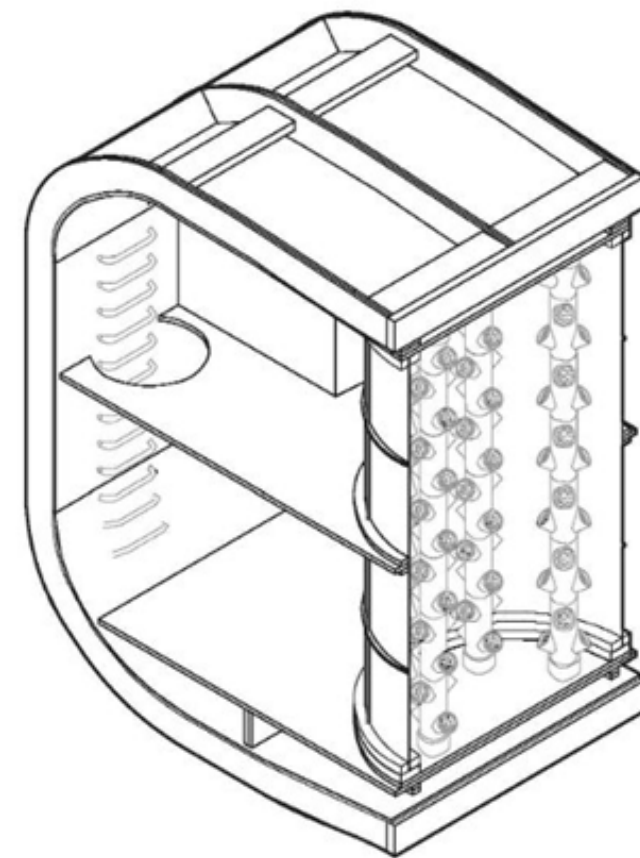
vertical supports



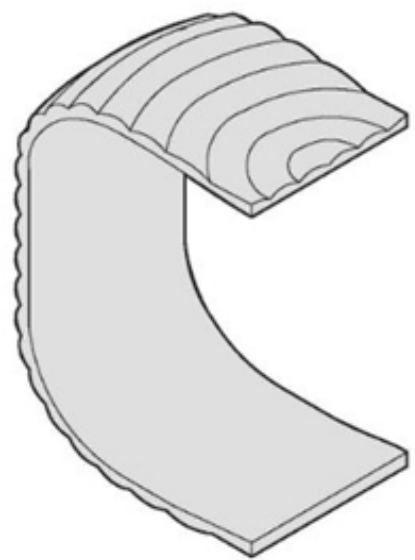




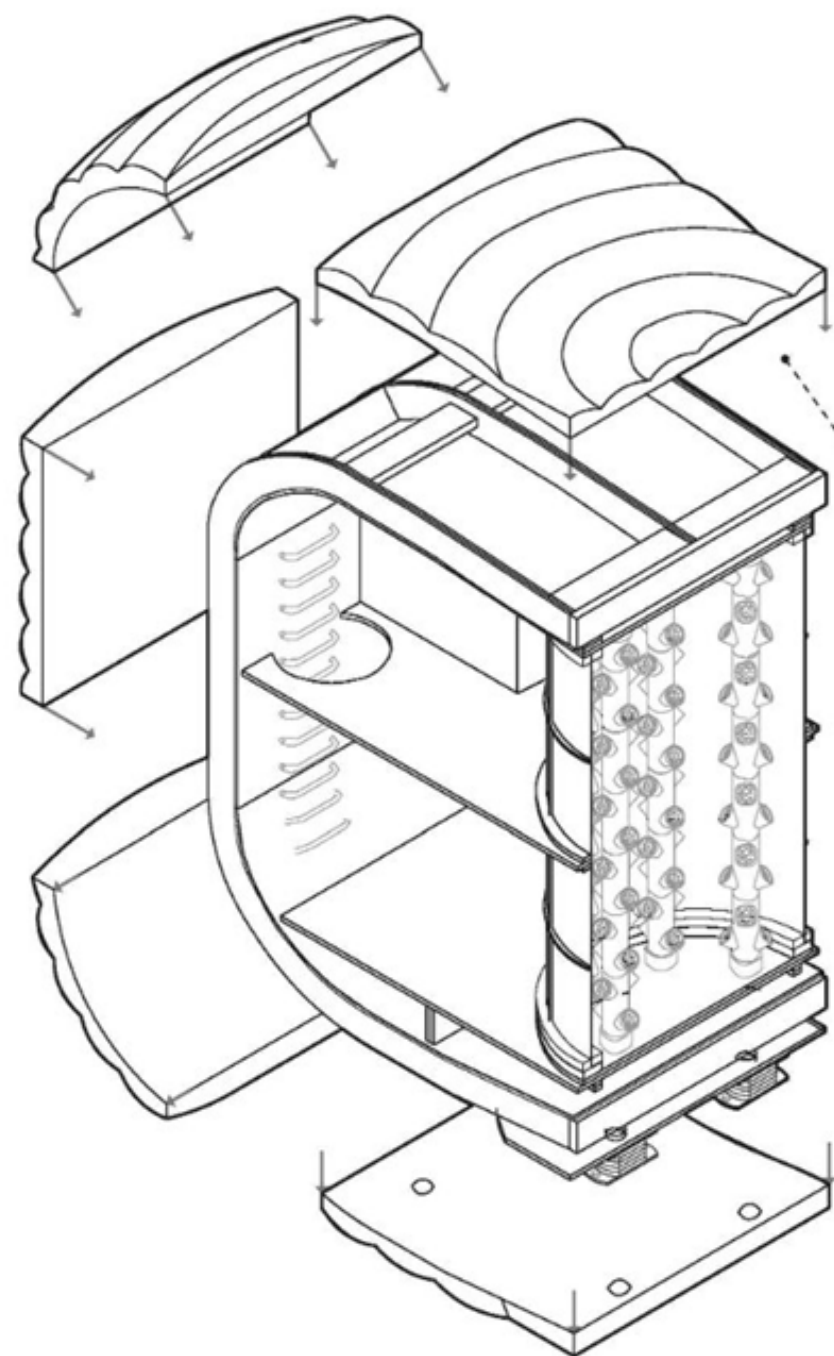
mylar transparent layer:  
1/32" PTEG



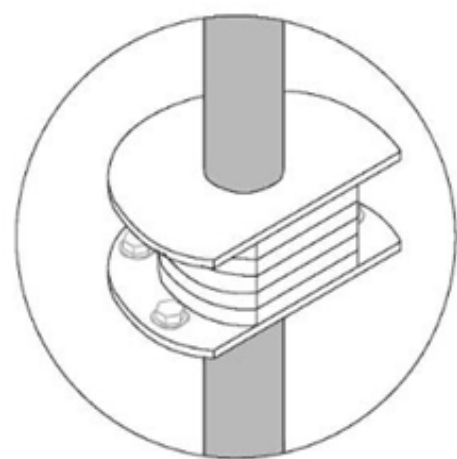
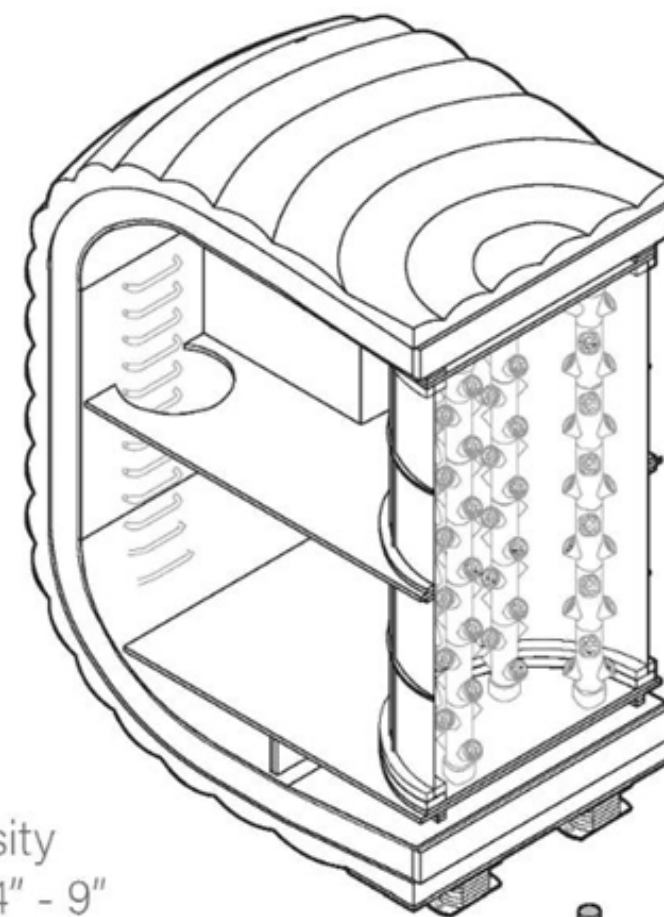




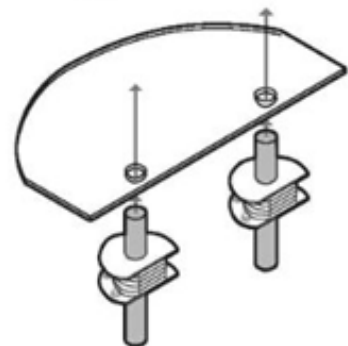
Inflatable section



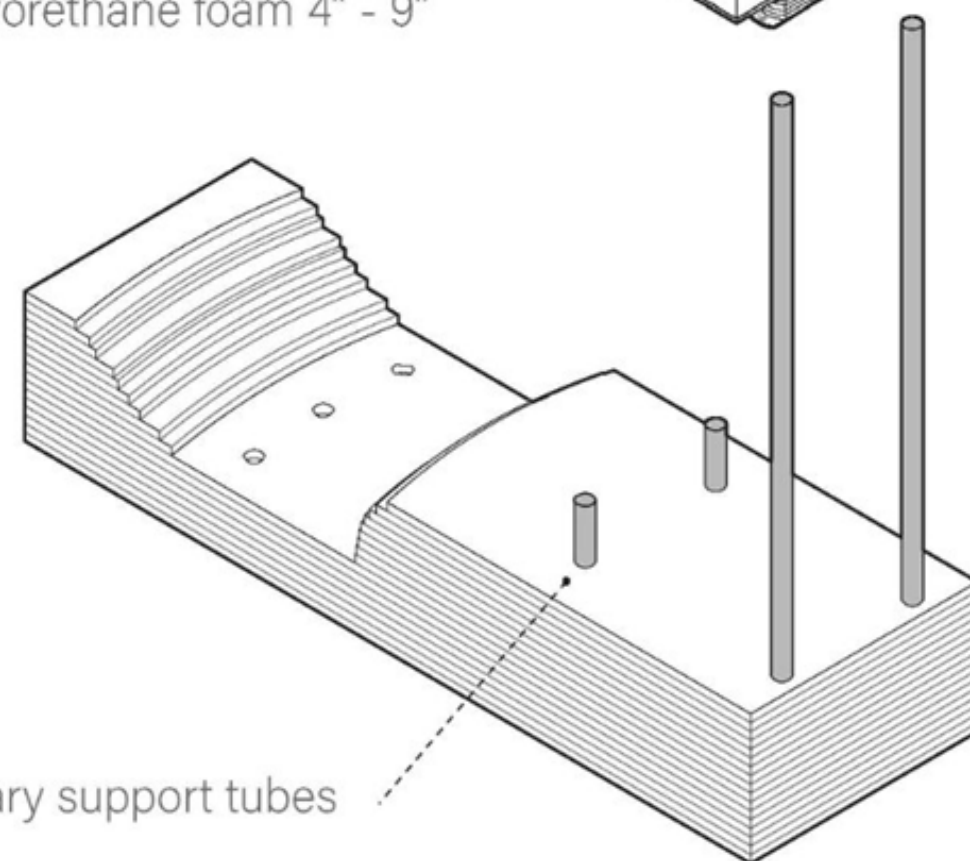
Inflatable: High density Polyurethane foam 4" - 9"



Base seismic isolator:  
PLA 3D printed



Auxiliary support tubes

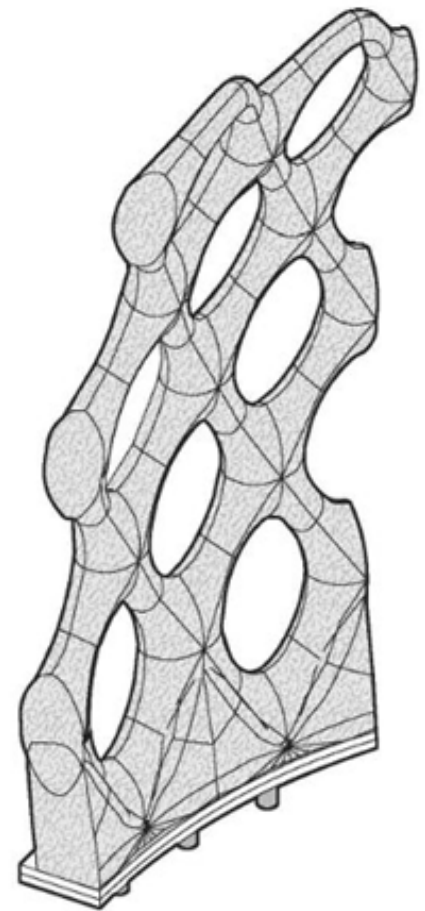
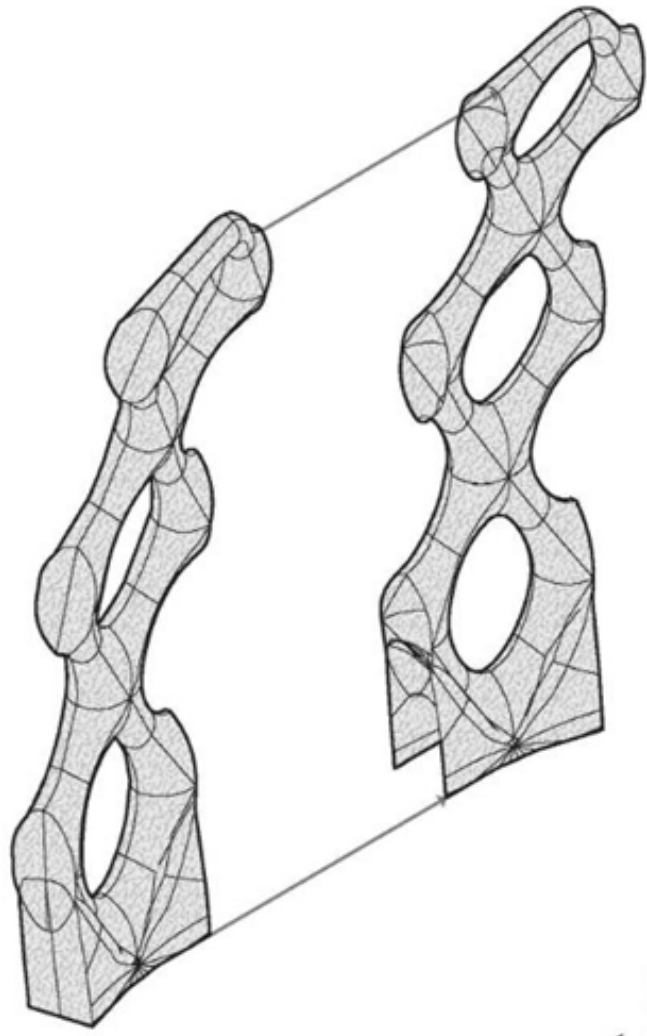
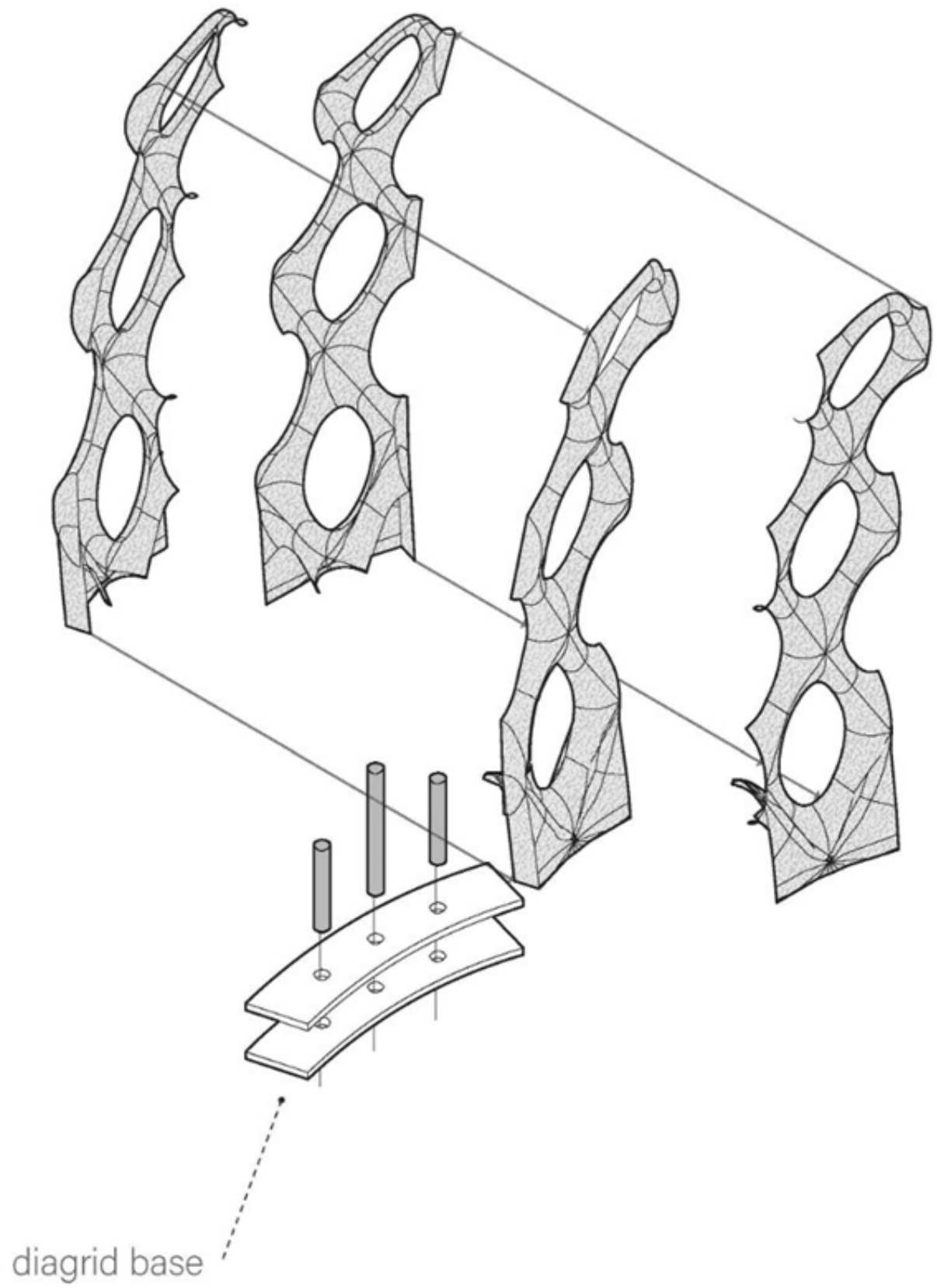




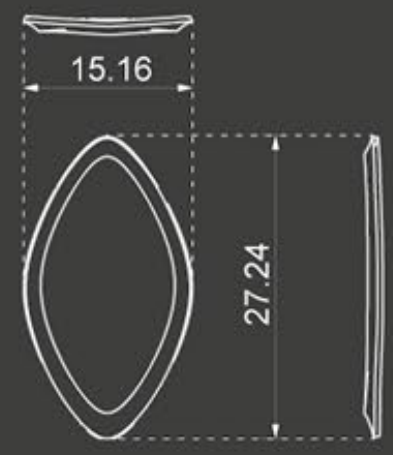
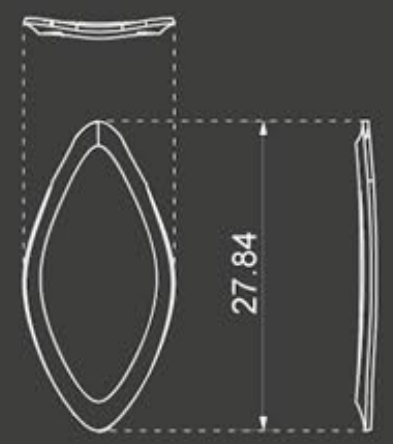
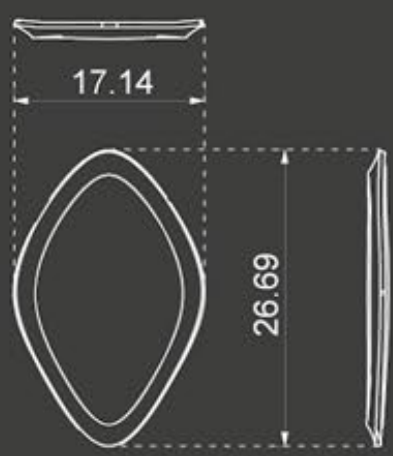
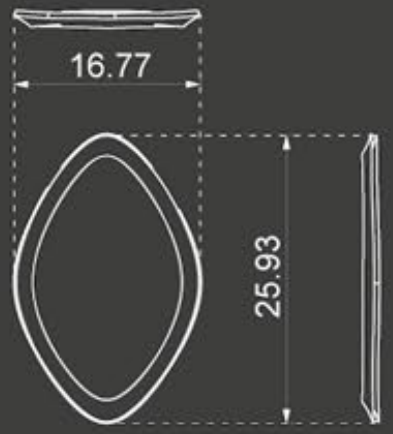
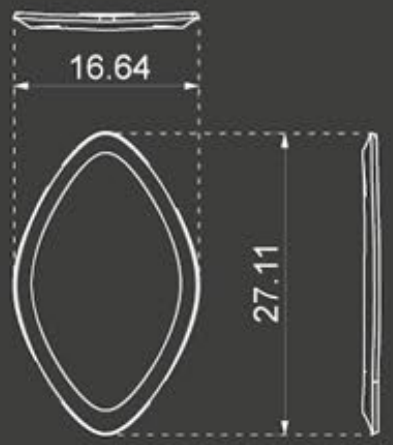
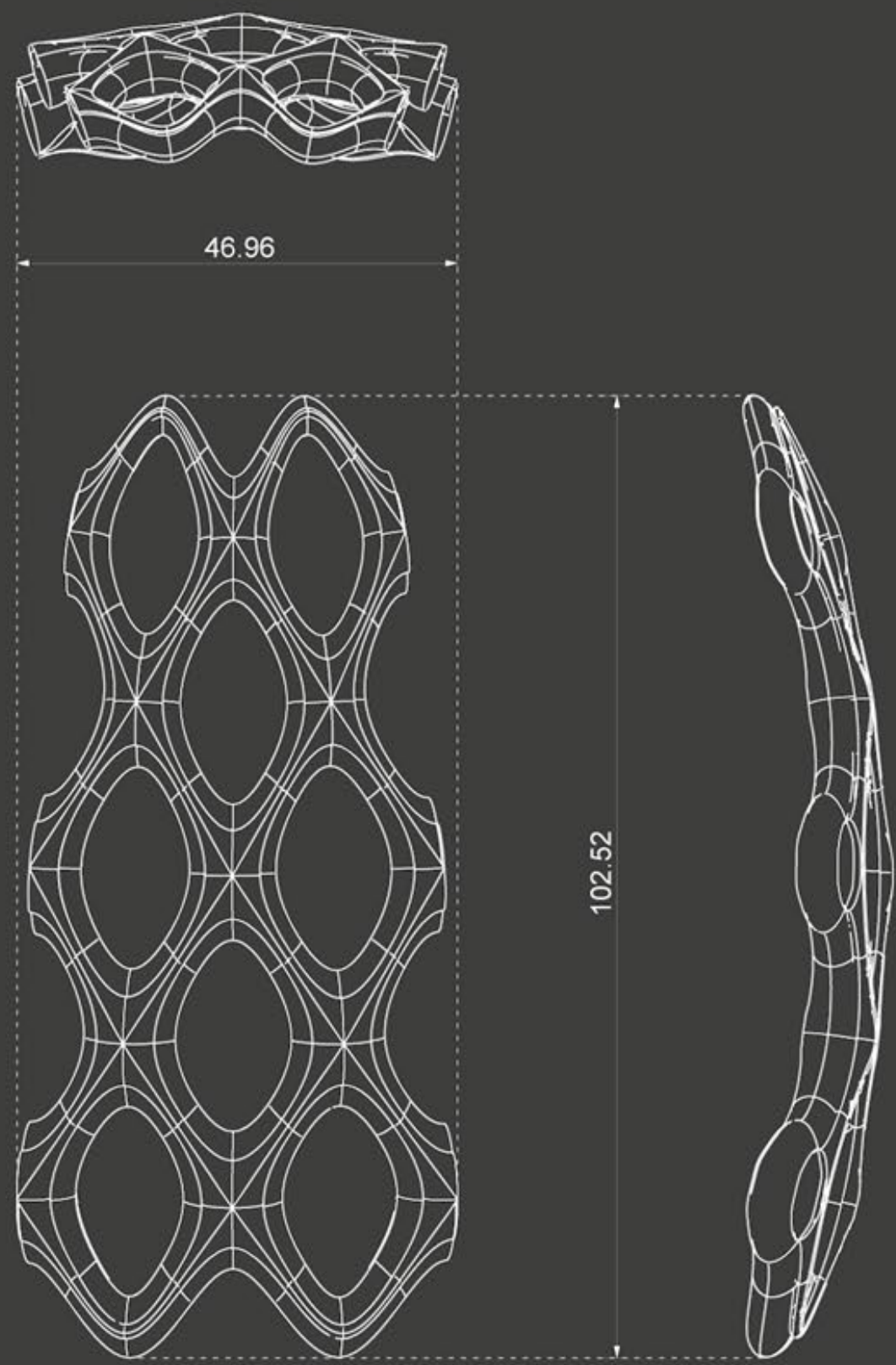




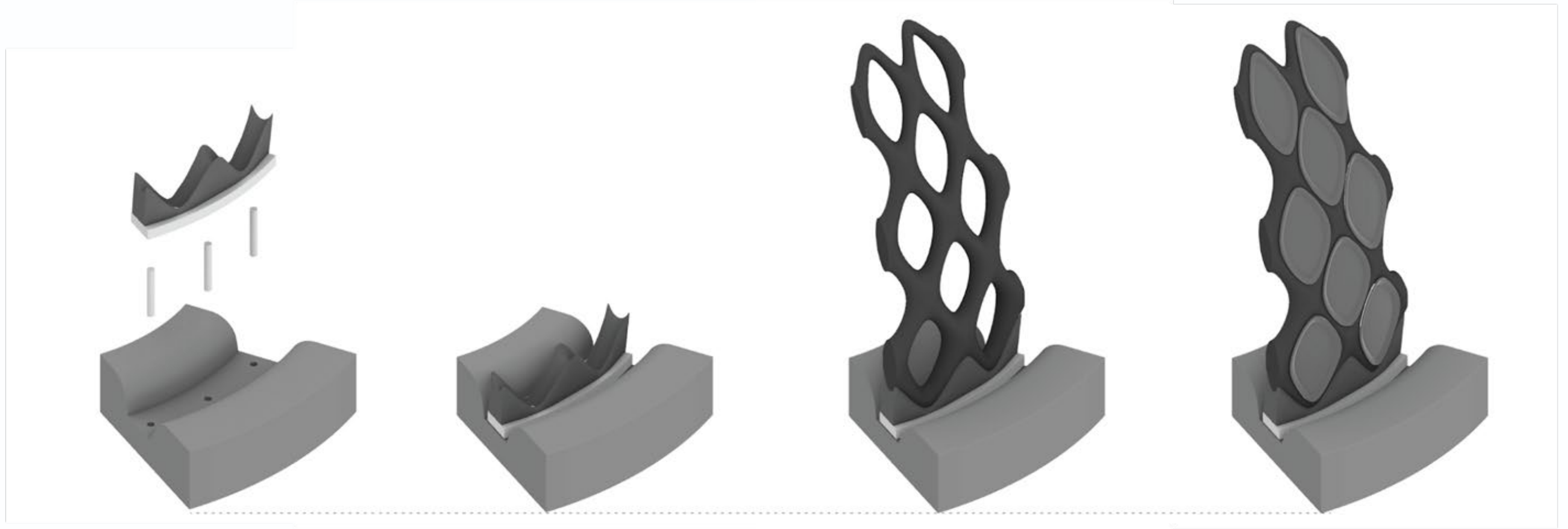
Regolith sintered diagrid structure:  
cotton pulp & epoxy resin mix

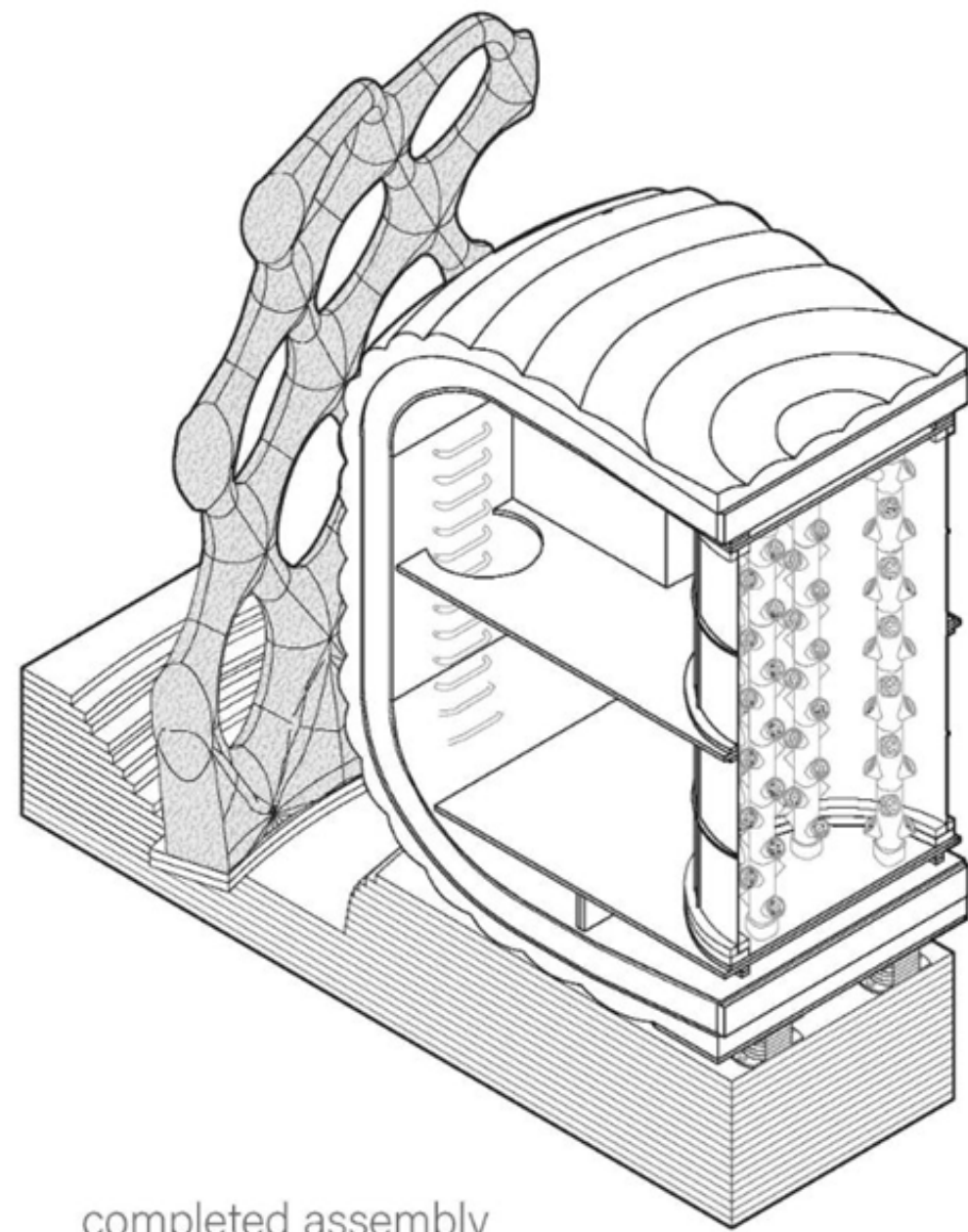
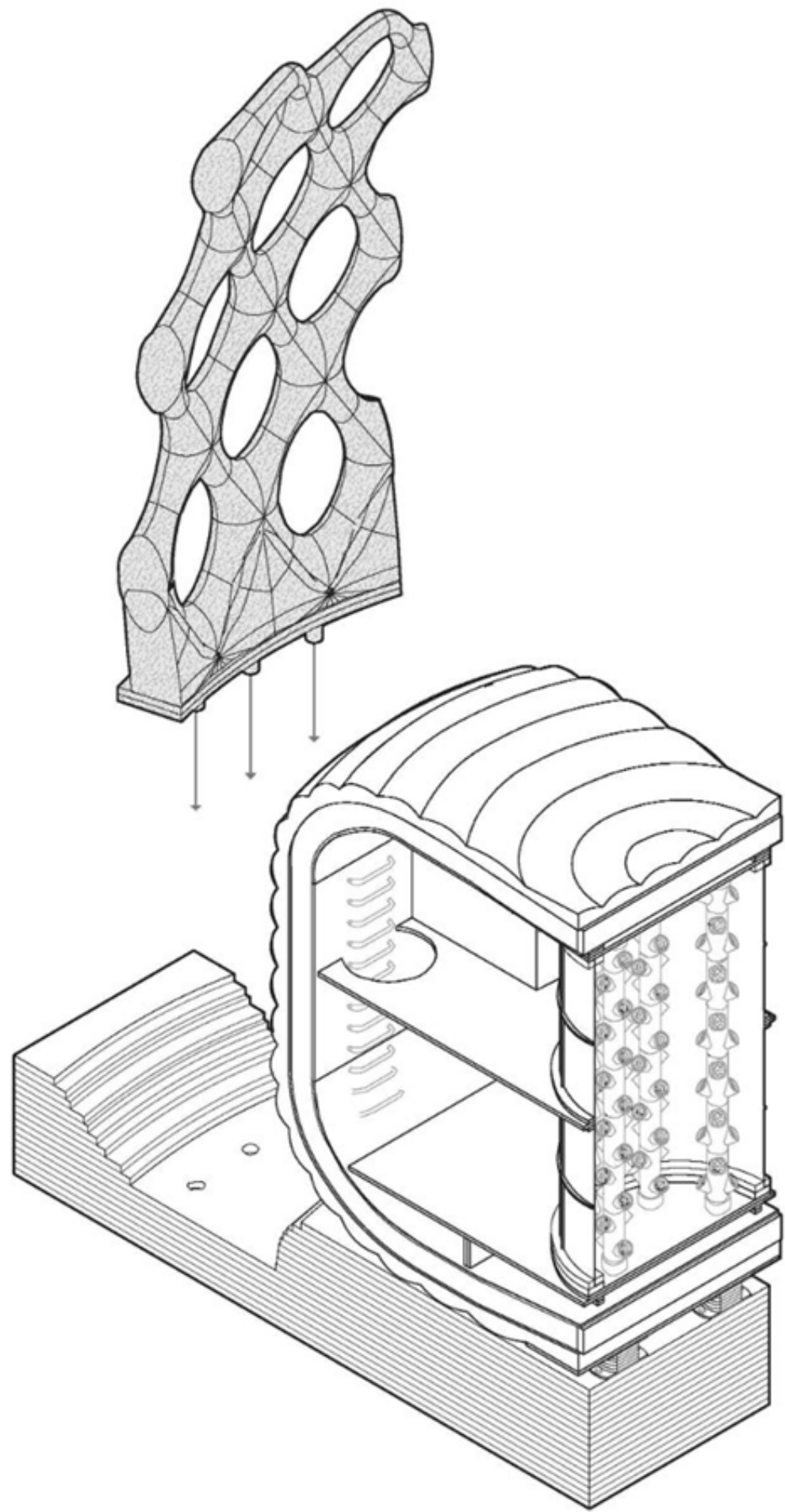


# Structure Construction Document



# Assembly Sequence



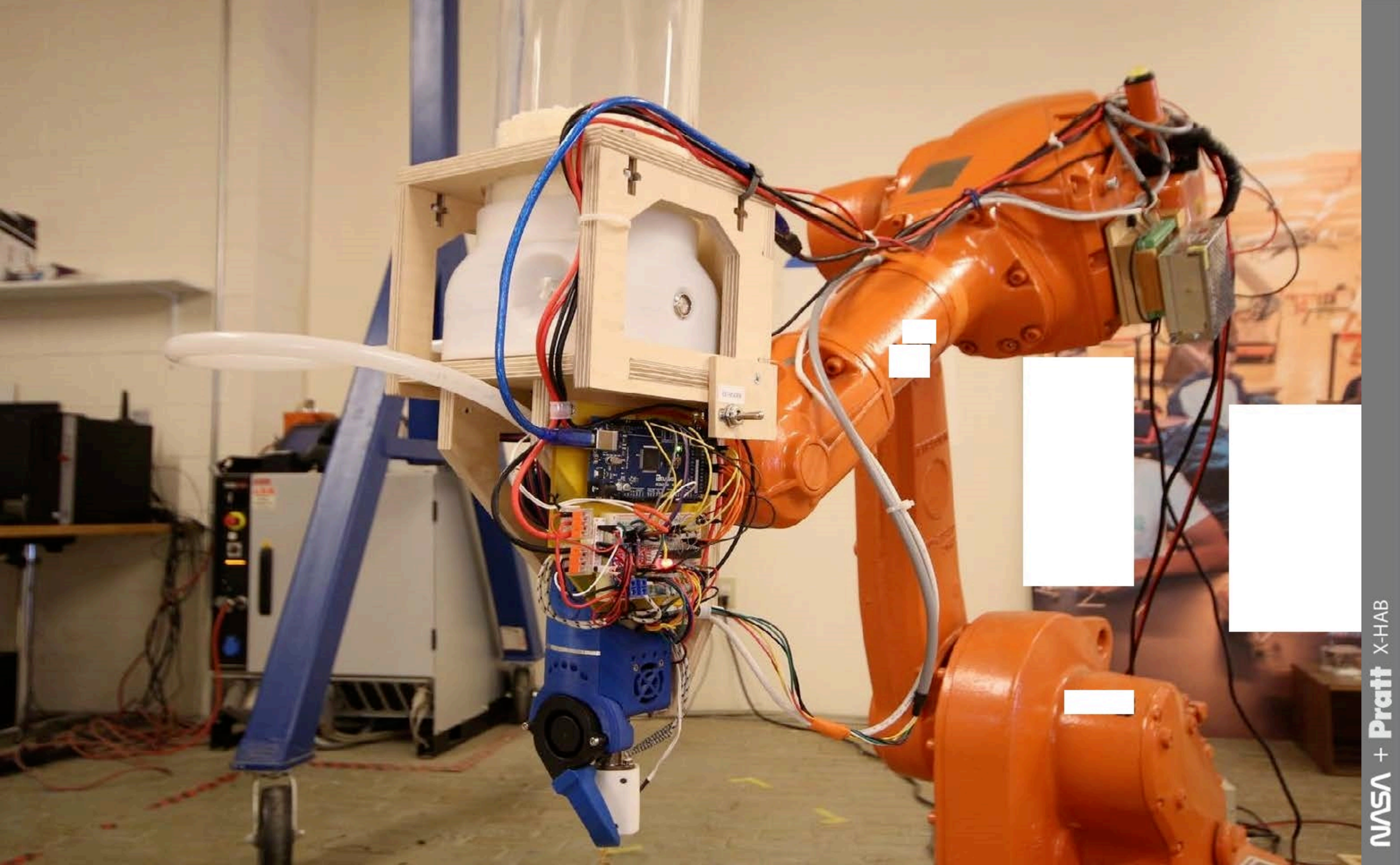


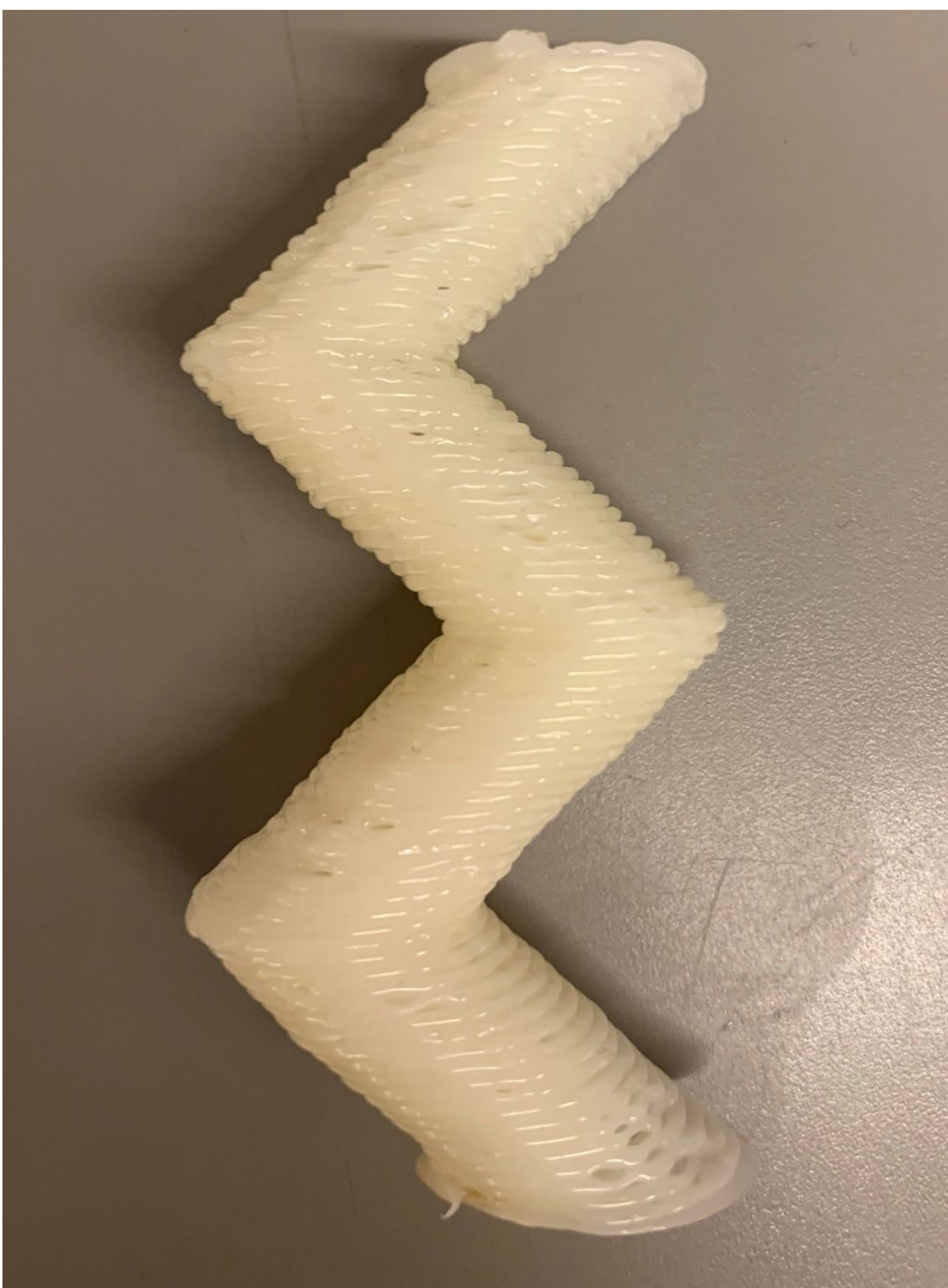
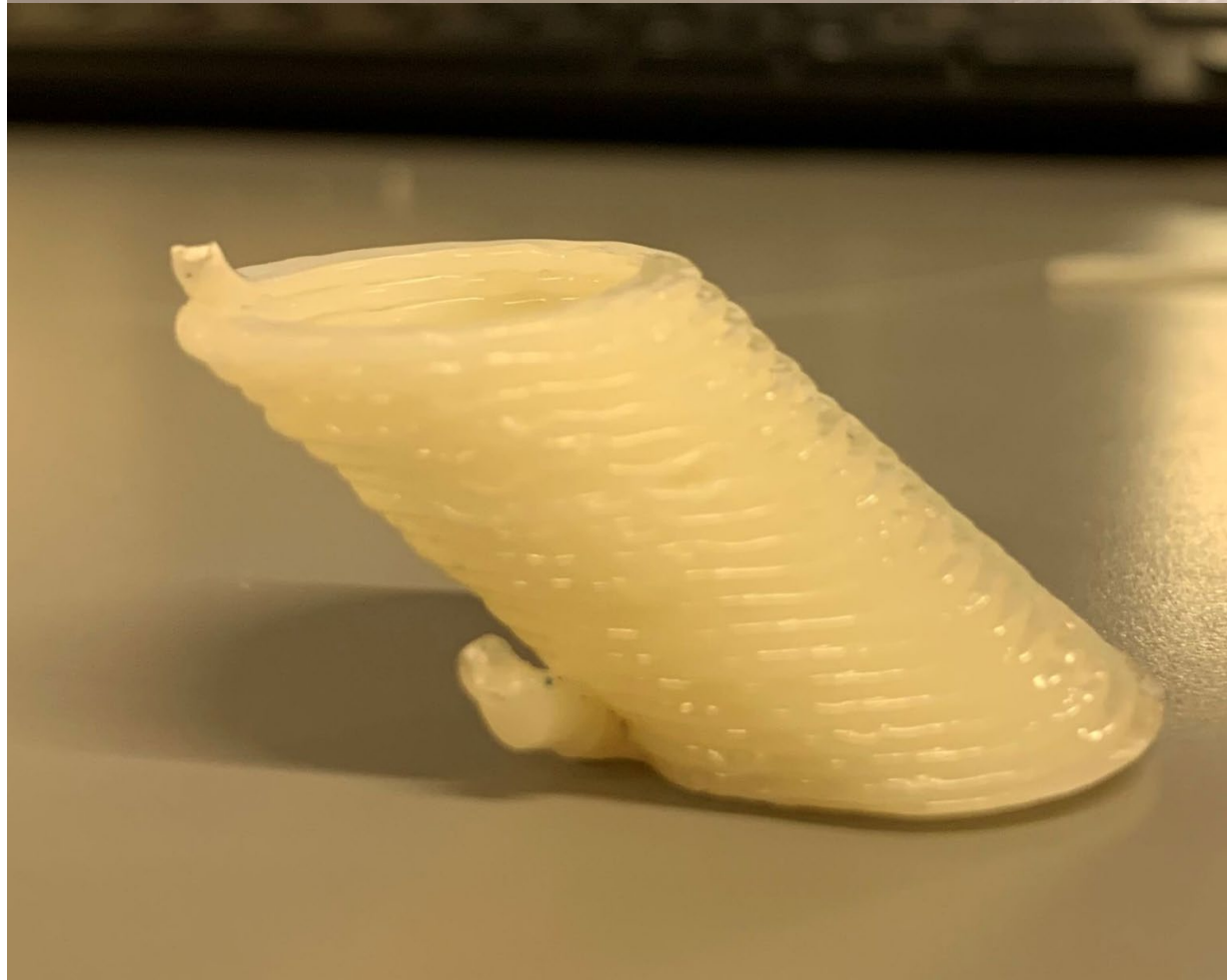
completed assembly



# RESEARCH

- 3D PRINTING AND ROBOTICS













































# THANK YOU!

Mark Parsons & Michael Morris - Leading us through this amazing project.

Rodrigo Guajardo - Constantly helping us with any building problems we may have had and trusting us with all of his tools and machines.

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Dr. Holbert and NASA - Answering any questions and providing us with amazing feedback to continue our design throughout our journey in the NASA XHab Studio

Dalma Foldesi and Jung In Seo - helping with material studies of the diagrid structure using their own ceramic printing research

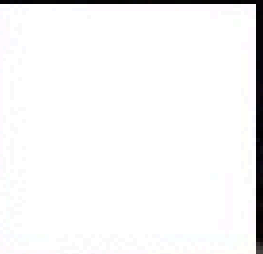
Stiegelbauer - providing us with the facilities to vacuum form the large molds for our diagrid model

Big Rep - giving us our first larger scale 3d prints in our first semester

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Genesis Villacis - Jacob Biletsky - Keshan Goberdhan - Maiti King - Michael South - Quinten Oxender



oasis

Thank You

