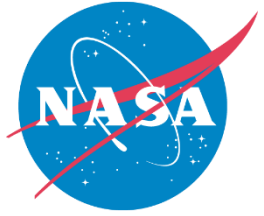


Preliminary Results of UAS Quadcopter Aeroacoustic Testing

Nicole Pettingill, Nikolas Zawodny, Christopher Thurman
NASA Langley Research Center

October 20, 2021
Acoustics Technical Working Group Meeting

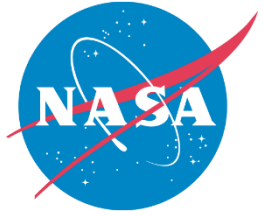
Presentation Outline



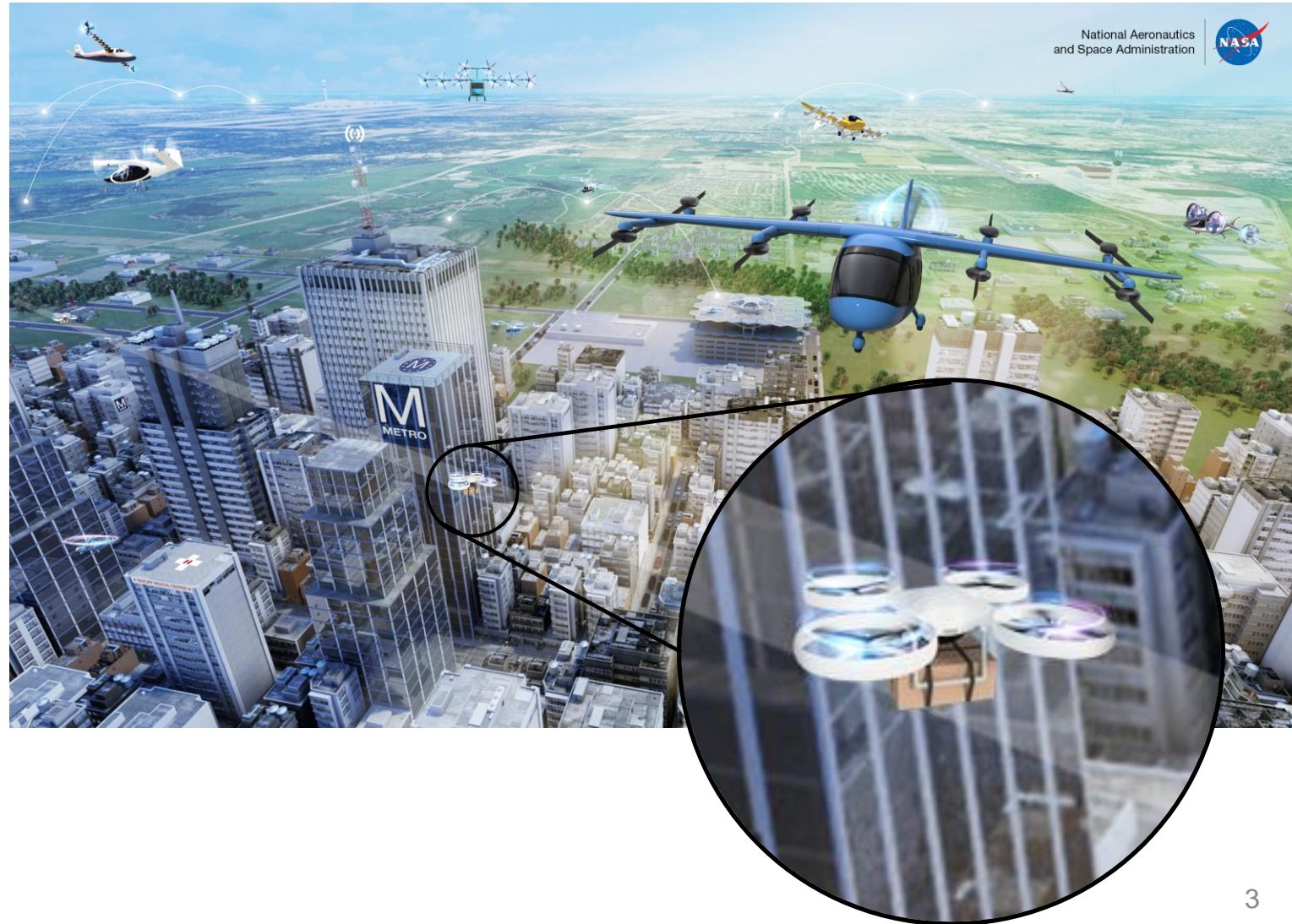
- Introduction
- Background
- Facility and hardware set up
- Preliminary results
 - Hover
 - Forward Flight
 - Beamforming
- Conclusions and future work



Introduction



- **Advanced Air Mobility (AAM)** is working to create **safe, sustainable, accessible, and affordable** aviation to move **people** and **packages**.
- The AAM industry motivates us to **characterize noise sources** to assess the **community impact** of these new vehicle concepts.
- **Noise** may be a **key barrier** for **community acceptance**, and **rotors** contribute significantly to the noise signature of these vehicles.
- **Wind tunnel tests** of small rotors are beneficial in assessing the **potential noise impact** of both **small unmanned aerial vehicles (sUAS)** and **larger urban air mobility (UAM) vehicles**



Past Test

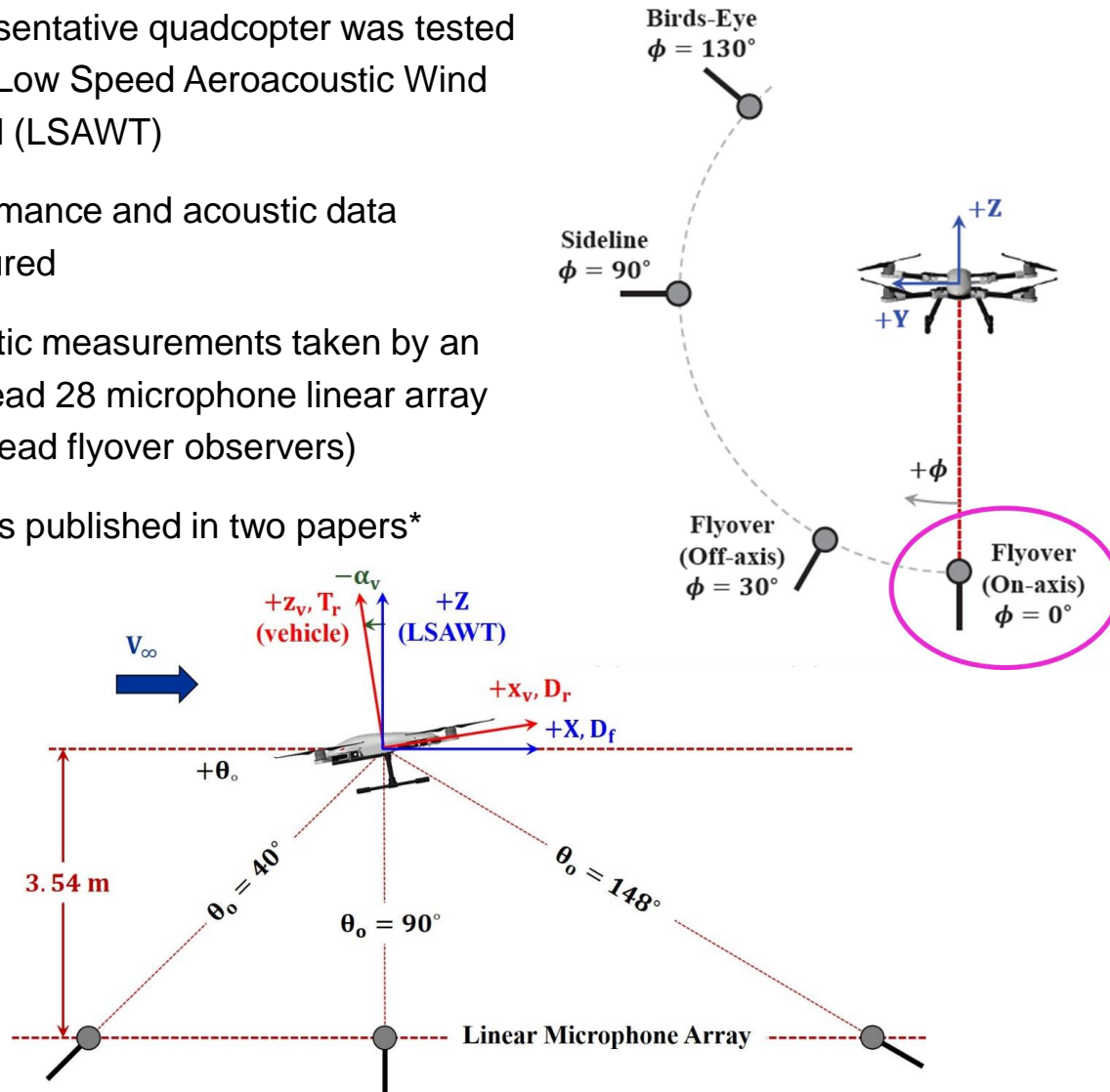
LSAWT 2017

Pettingill, N. A. & Zawodny, N. S. "Identification and Prediction of Broadband Noise for a Small Quadcopter". VFS Forum 75 2019.

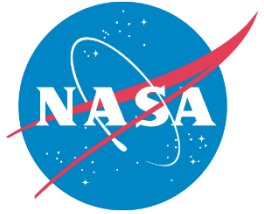
Zawodny, N. S. & Pettingill, N. A., "Acoustic Wind Tunnel Measurements of a Quadcopter in Hover and Forward Flight Conditions". 47th InterNoise 2018.



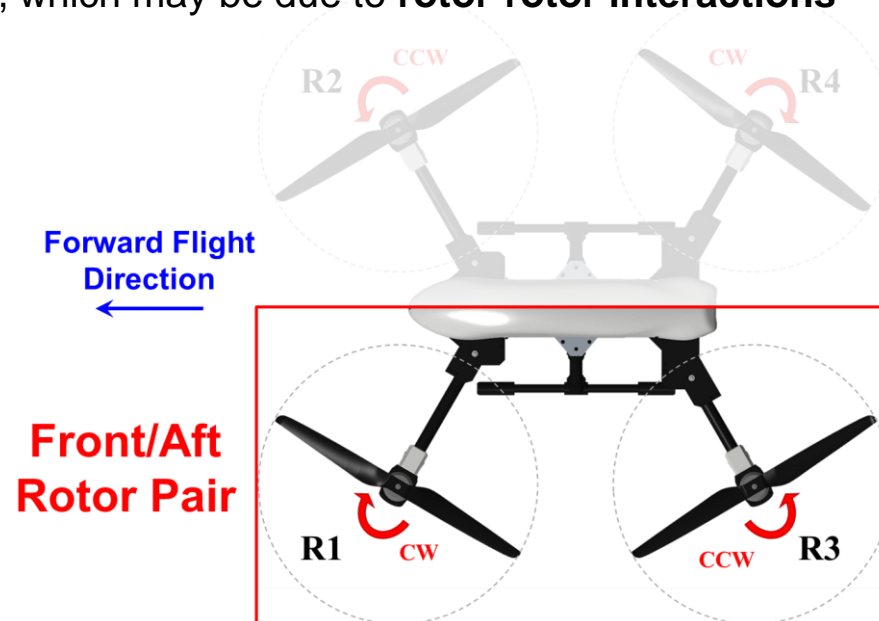
- Representative quadcopter was tested in the Low Speed Aeroacoustic Wind Tunnel (LSAWT)
- Performance and acoustic data measured
- Acoustic measurements taken by an overhead 28 microphone linear array (overhead flyover observers)
- Results published in two papers*



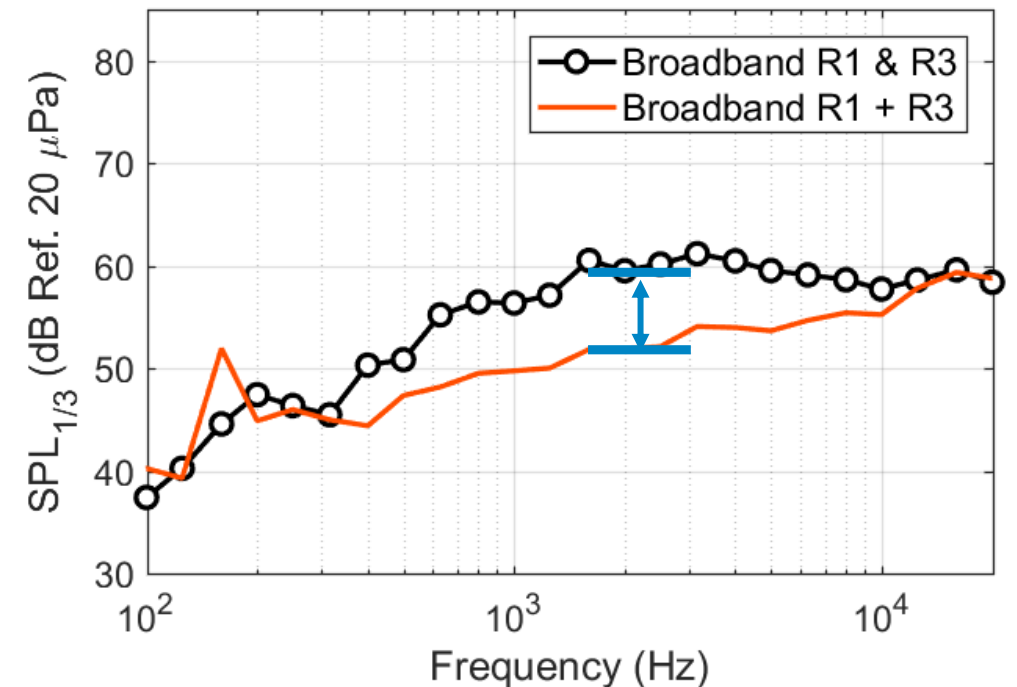
Past Test LSAWT 2017



- Noise sources investigated were **self-noise**, **rotor-airframe interactions** and possible **rotor-rotor interactions**
- Rotor-rotor interactions in forward flight
 - Compared acoustics of *one simultaneous operation* case of front/aft rotor pair (R1 & R3) against superimposed result of *two individual operation* cases (R1 + R3)
 - Identified additional broadband noise for R1 & R3 vs. R1 + R3 at high thrust setting, which may be due to **rotor-rotor interactions**

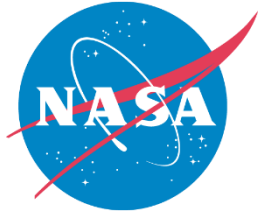


Broadband Noise at 10 lb condition



Broadband noise due to multirotor interaction effects between simultaneously operating rotors

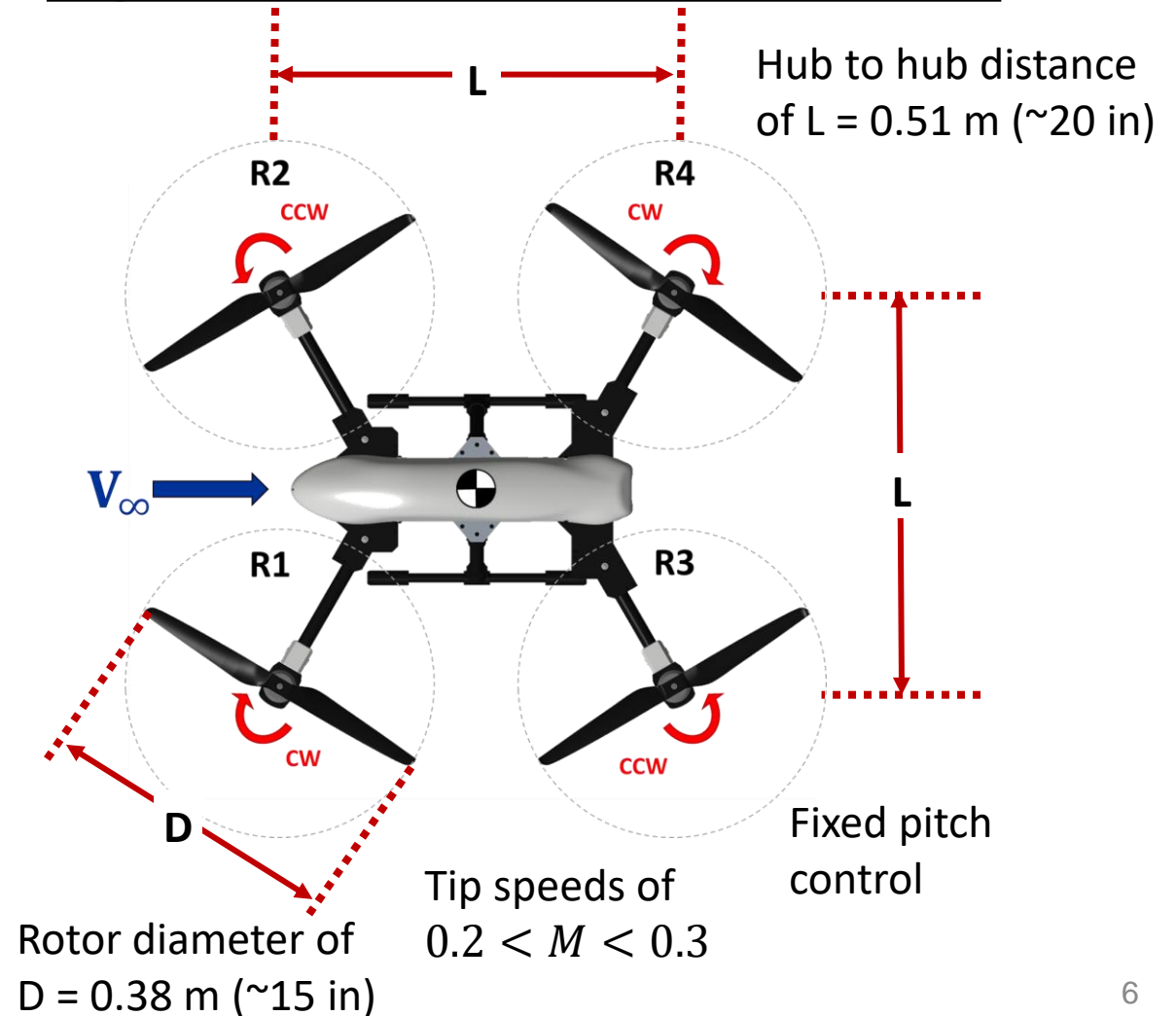
Current Test Vehicle and Hardware



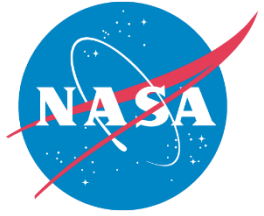
- Quadcopter: SUI Endurance
- Three blade sets
 - T-Motor COTS blade set
 - Optimum blade design:
 - ProtoLabs SLA with glass grit
 - ProtoLabs SLS “rough blade”
- Two hubs
 - COTS
 - SLA in-house hub
- Cylinder Spacers
 - Baseline (0.15R distance from rotor to airframe)
 - 2.5 inch spacer (0.48R)
 - 1.25 inch spacer (0.30R)



Representative Vehicle Characteristics



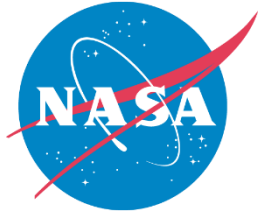
Current Test Vehicle and Hardware



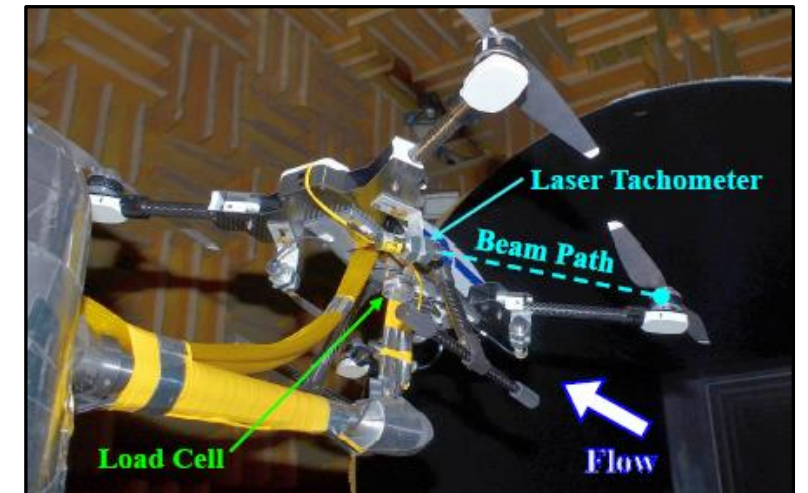
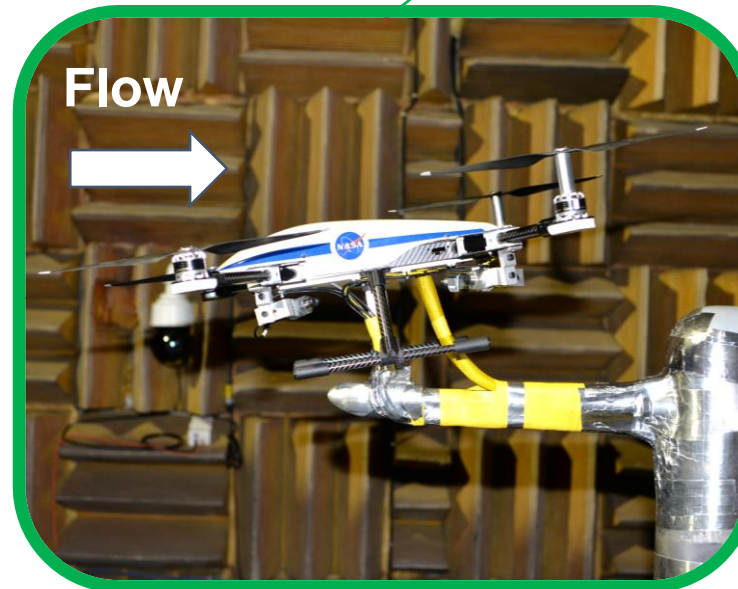
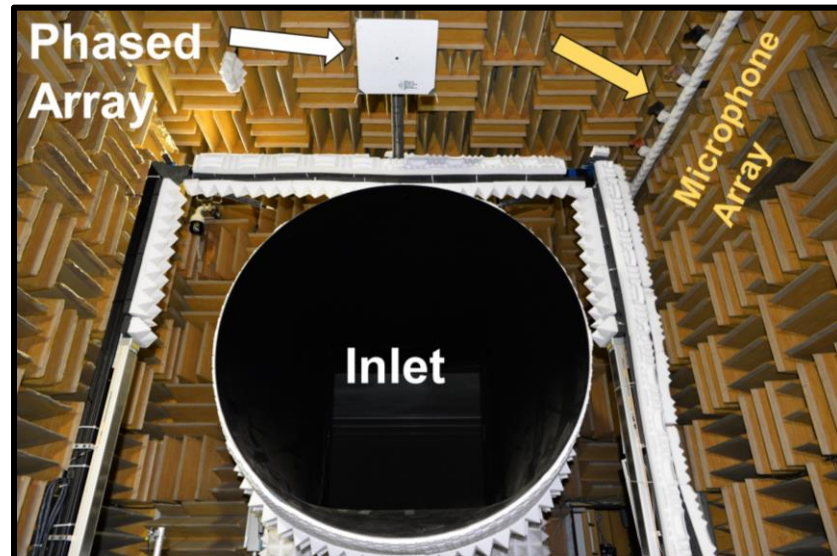
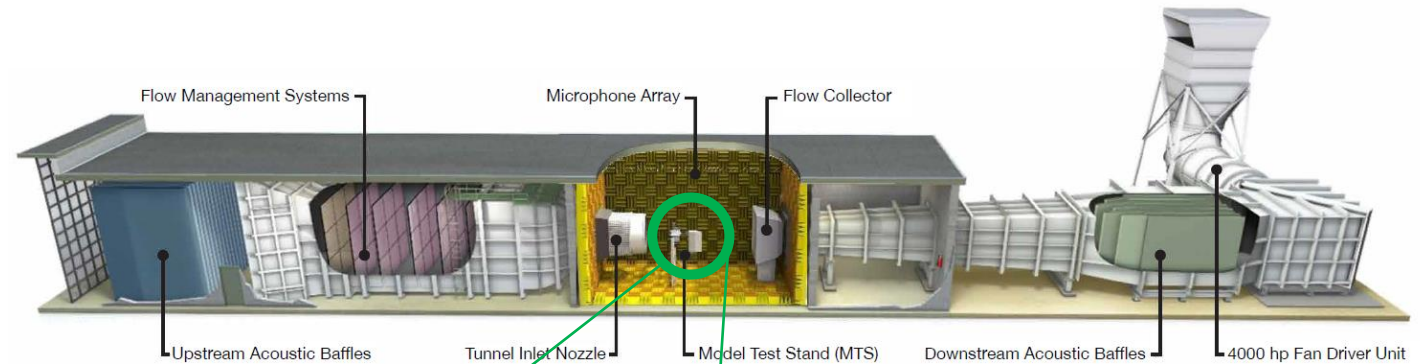
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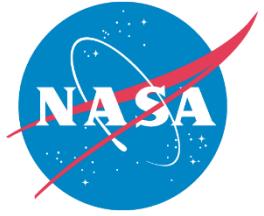
Low Speed Aeroacoustic Tunnel LSAWT 2021



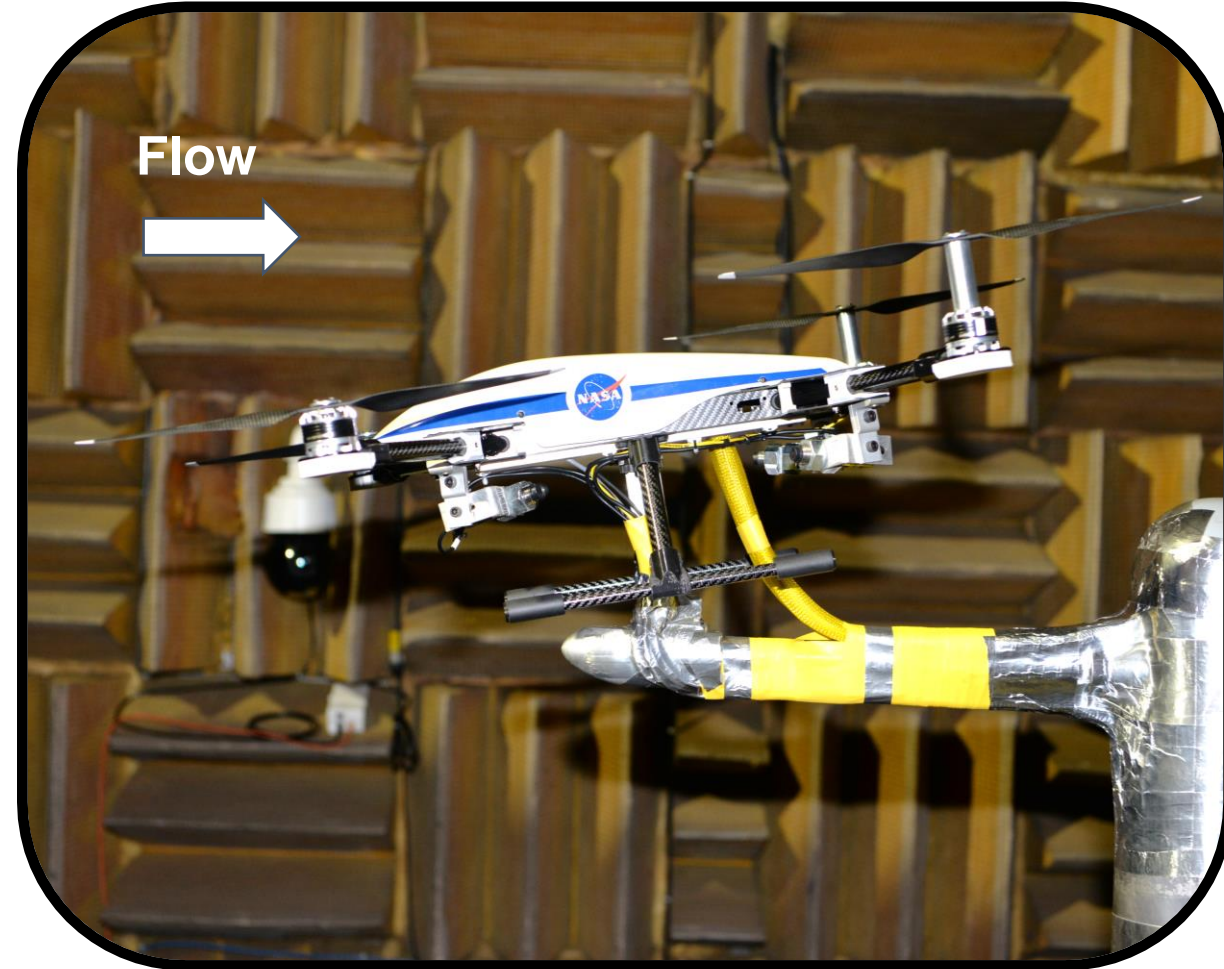
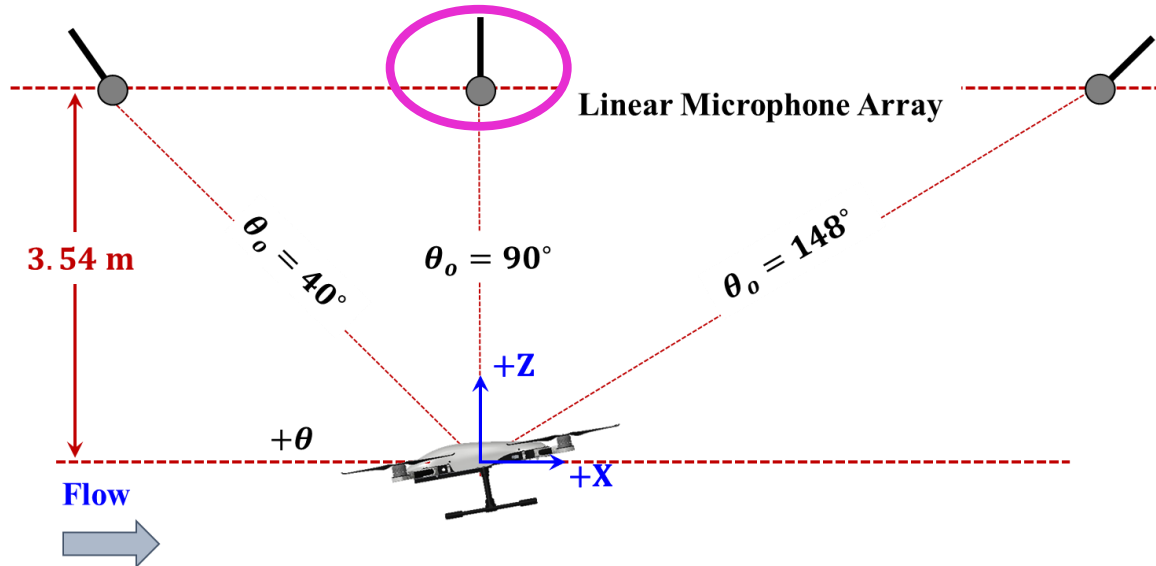
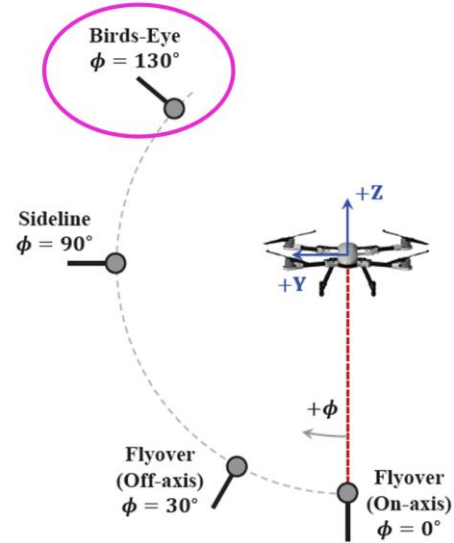
- LSAWT is an **open-circuit free jet wind tunnel**
- Test section dim: **5.6 m length, 1.93 m inlet diameter**
- Acoustically treated (**cutoff down to 250 Hz**)
- Acoustic measurements taken by a **28 microphone linear array**
- **Phased array** installed **1.25 m away** from the rotor plane



Low Speed Aeroacoustic Tunnel LSAWT 2021

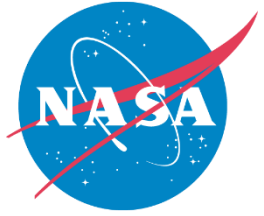


- Vehicle remained in upright orientation (“Birds-Eye” array location)
- The vehicle pitch angle was changed for the various flight conditions:
 - **hover (0 deg.)**
 - forward flight (4 deg.)
 - **forward flight (10 deg.)**



Results

Comparison to 2017 Test



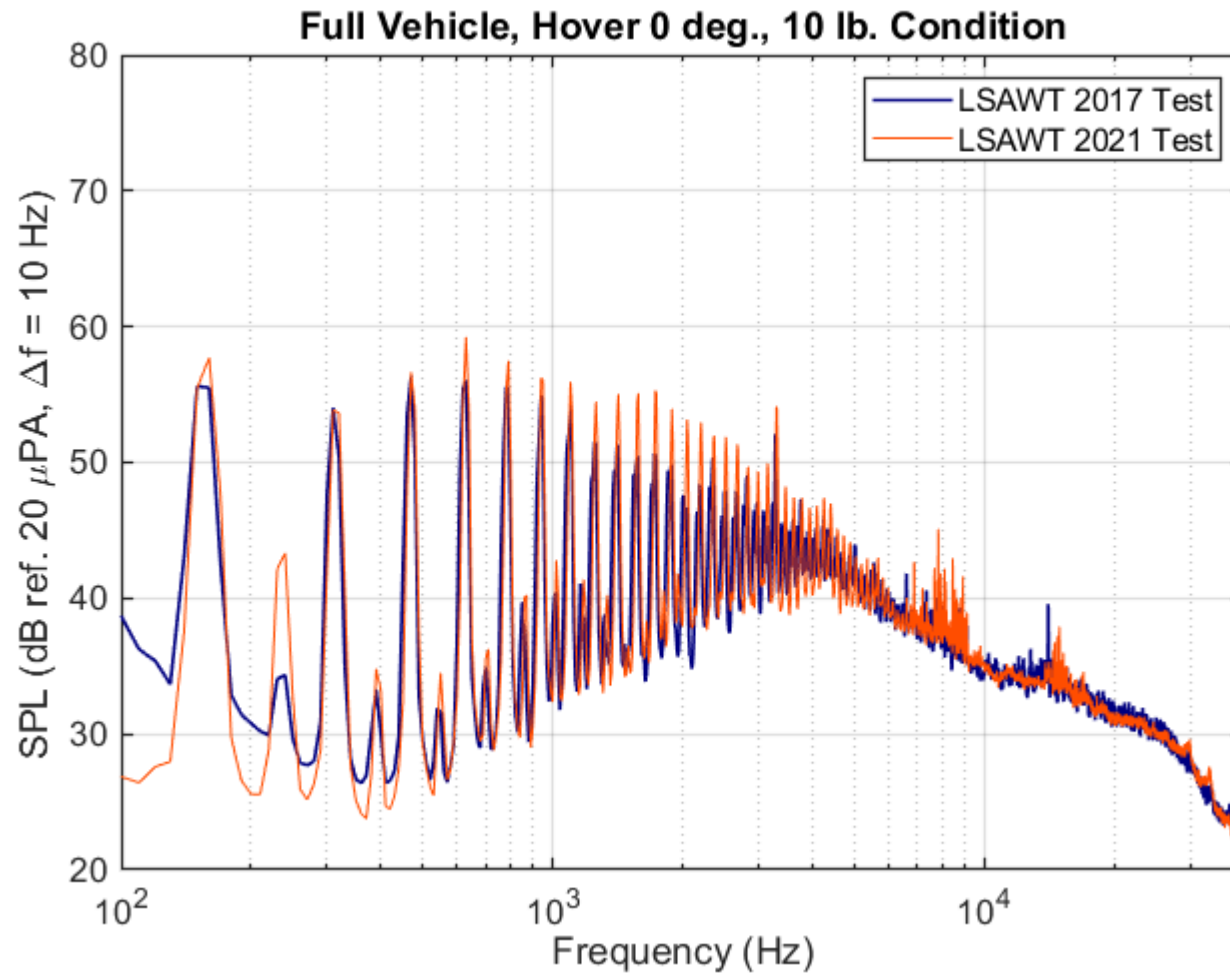
Overhead
microphone
($\theta_o = 90$ deg.)

Hover

$\alpha_V = 0$ deg.

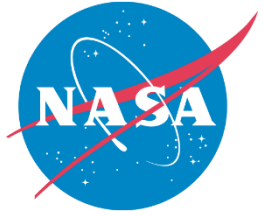
T = 10 lb.

$M_\infty = 0.0$



Results

Comparison to 2017 Test



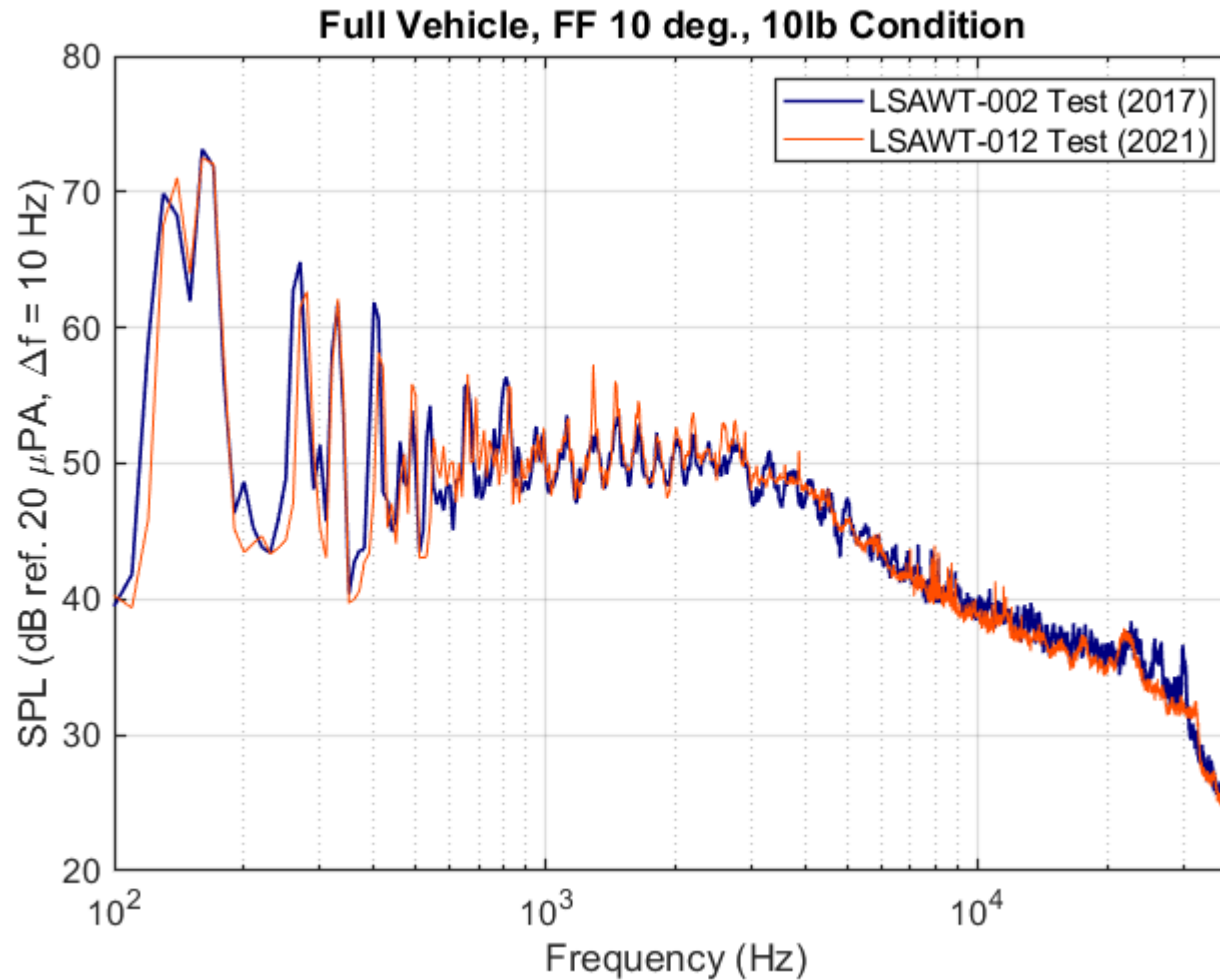
Overhead
microphone
($\theta_o = 90$ deg.)

Forward Flight

$\alpha_V = -10$ deg.

T = 10 lb.

$M_\infty = 0.046$



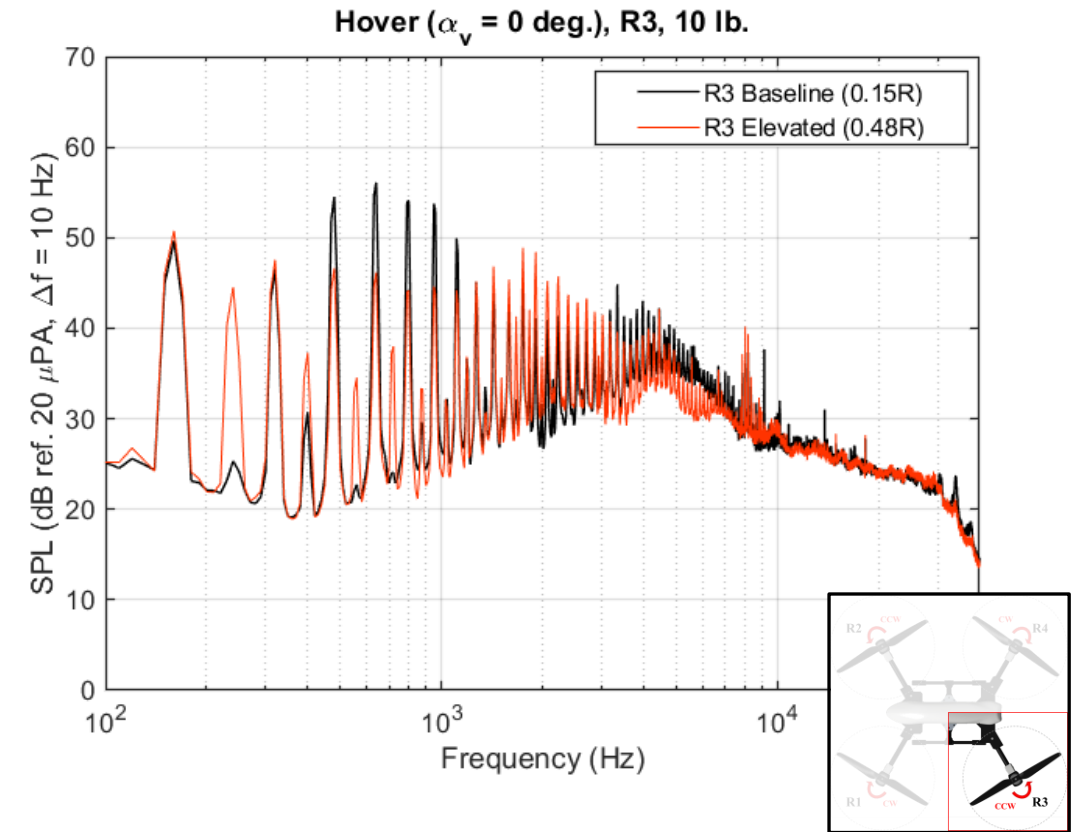
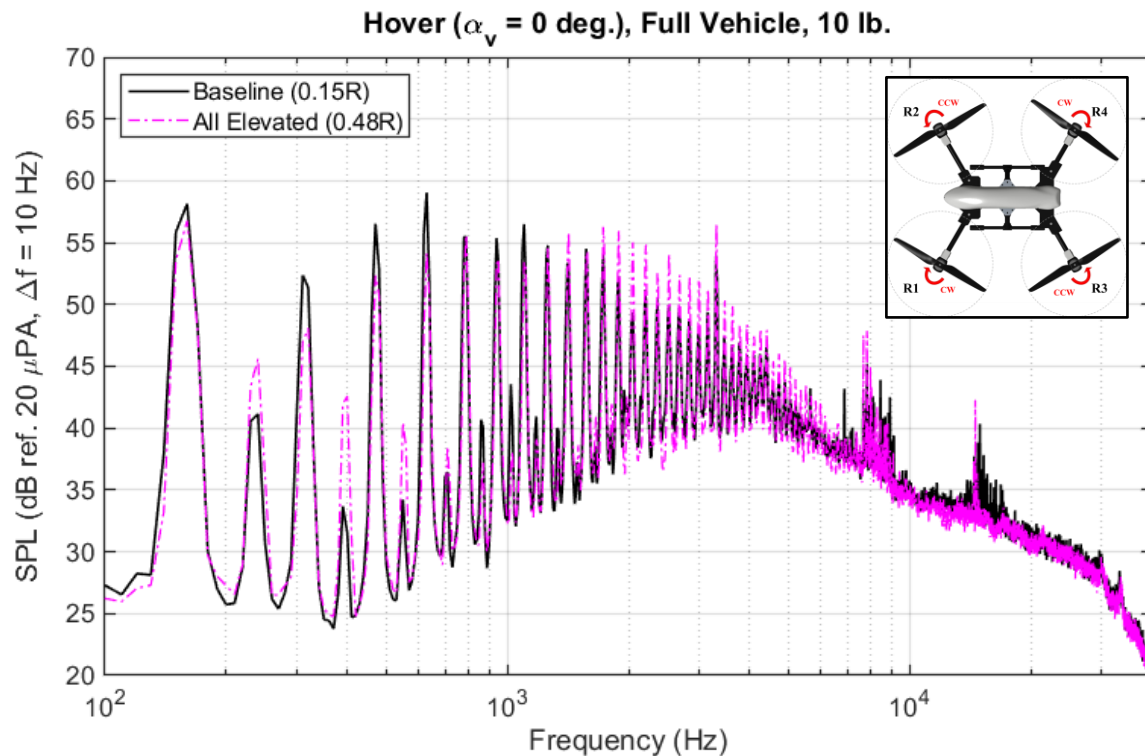
Hover Results

Using the cylinder standoffs in hover



Rotor standoffs were placed on **all rotors** to elevate the rotors from the airframe

There is not a significant noise reduction elevating the rotors in hover, though the amplitudes of 2nd - 4th BPF are reduced

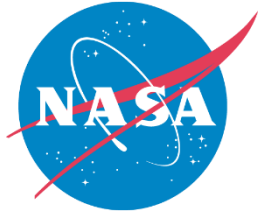


A rotor standoff was placed on **R3** to elevate it from the airframe

Individual rotor better shows possible improvement on rotor airframe noise for 3rd-6th BPF harmonics (between 480 - 1 kHz)

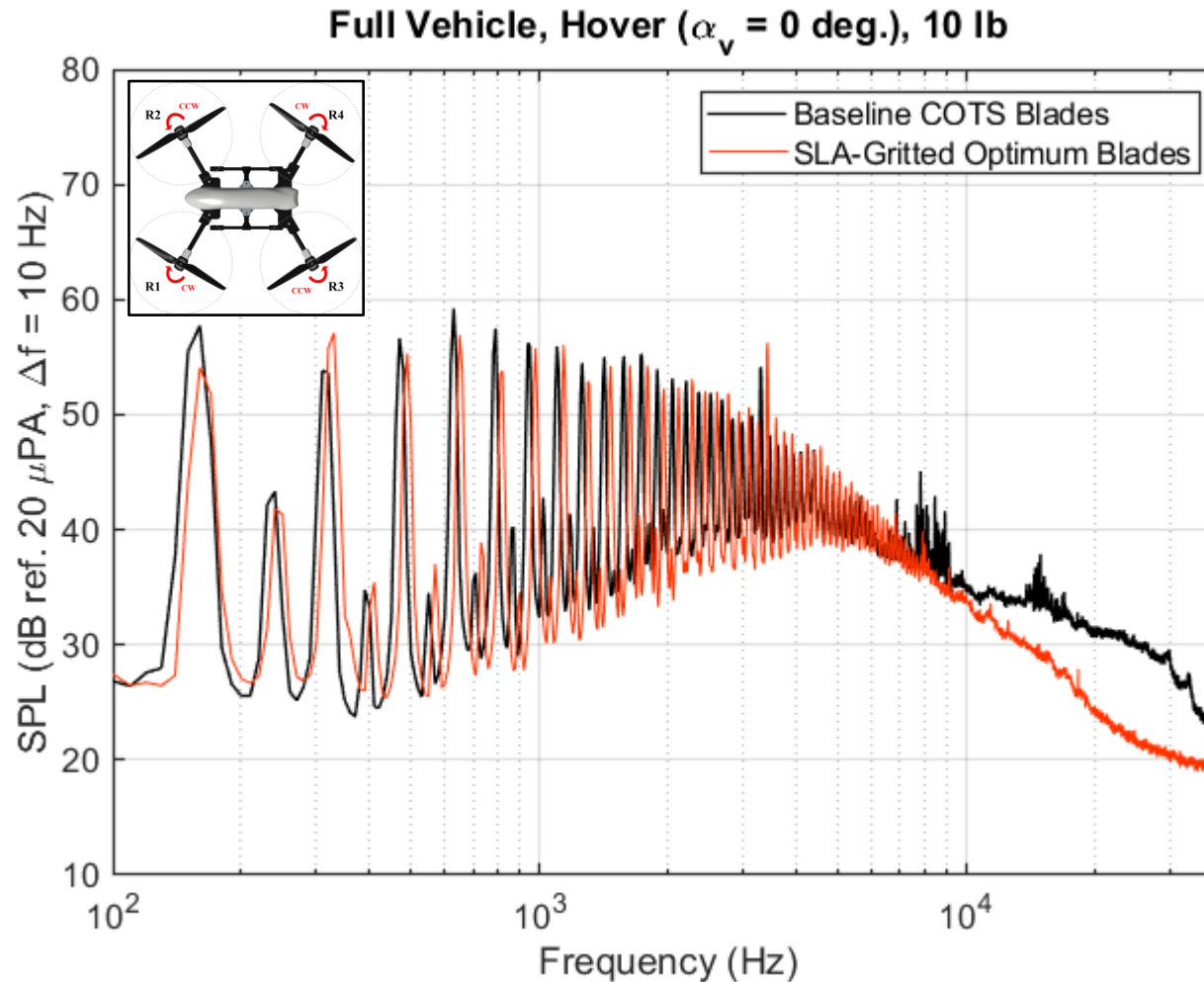
Hover Results

Replacing the blades with SLA – gritted blades



T-motor COTS blades were replaced with **optimum design blades**

These SLA blades were gritted with a glass grit to create a “trip” to prevent laminar boundary layer vortex shedding behavior

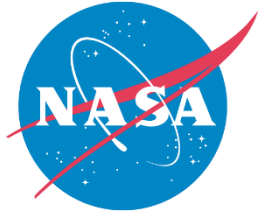


SLA-Gritted blades provide broadband noise reduction at frequencies higher than **10 kHz**

However, these blades were difficult to trim in the full vehicle configuration

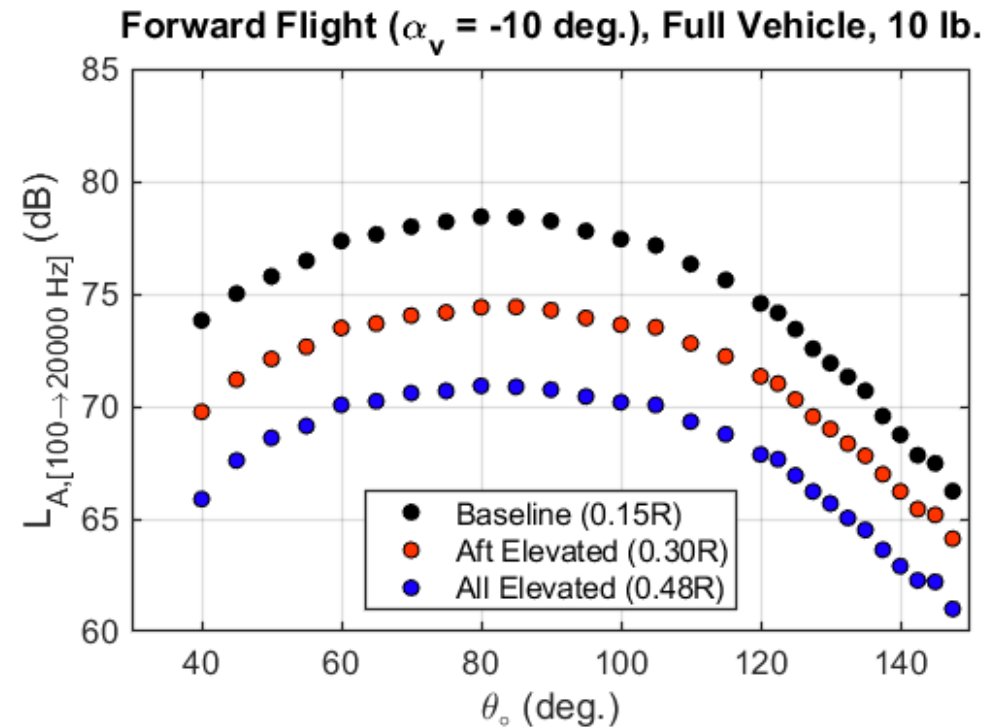
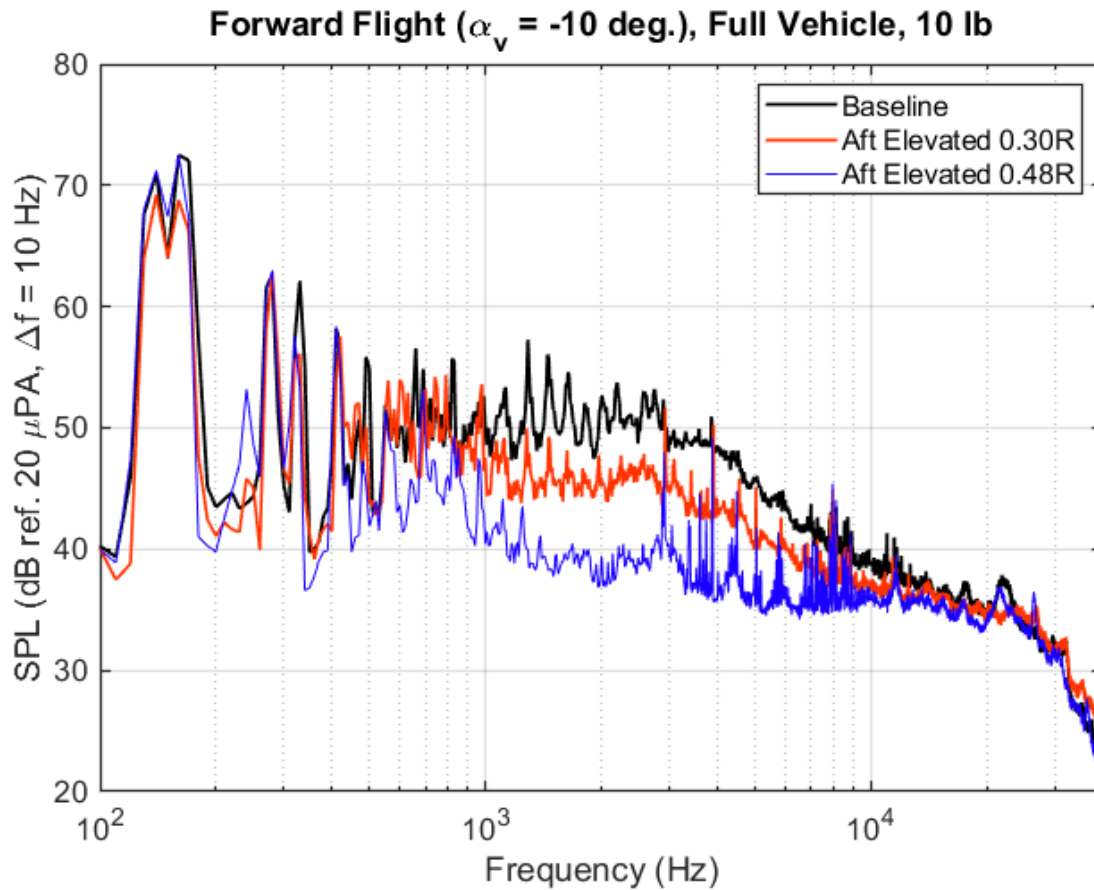
Forward Flight Results

Using the cylinder standoffs in forward flight



Rotor standoffs were placed on **aft rotors (R3 & R4)** to elevate the rotors from the airframe

Between **1 and 9 kHz** there is a decrease of broadband noise content (**up to ~10 dB**)



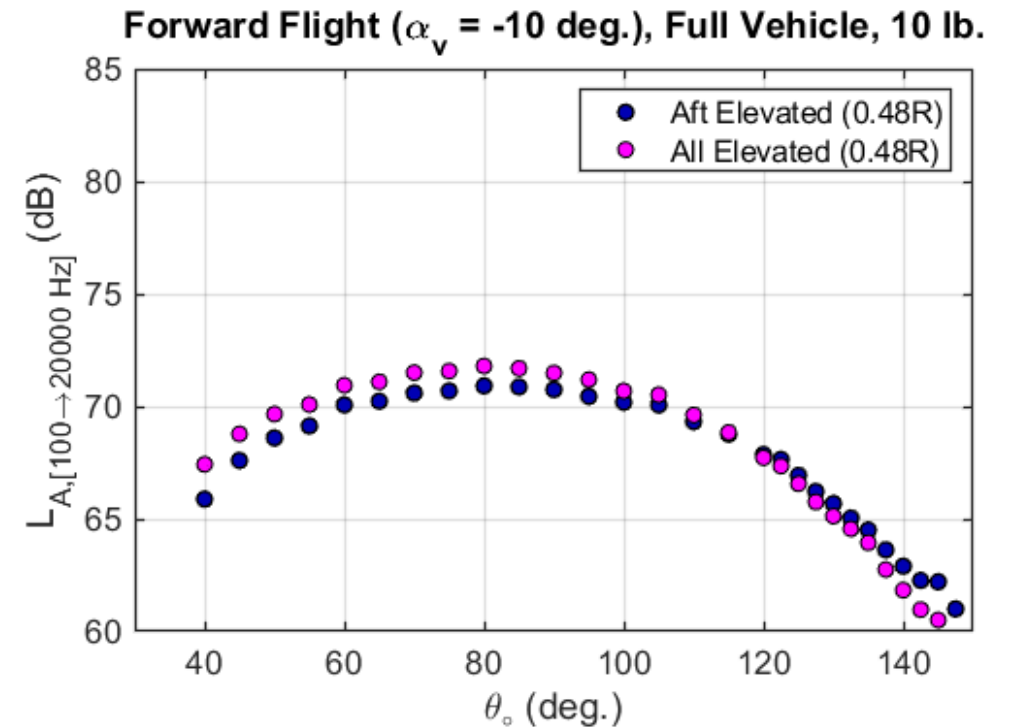
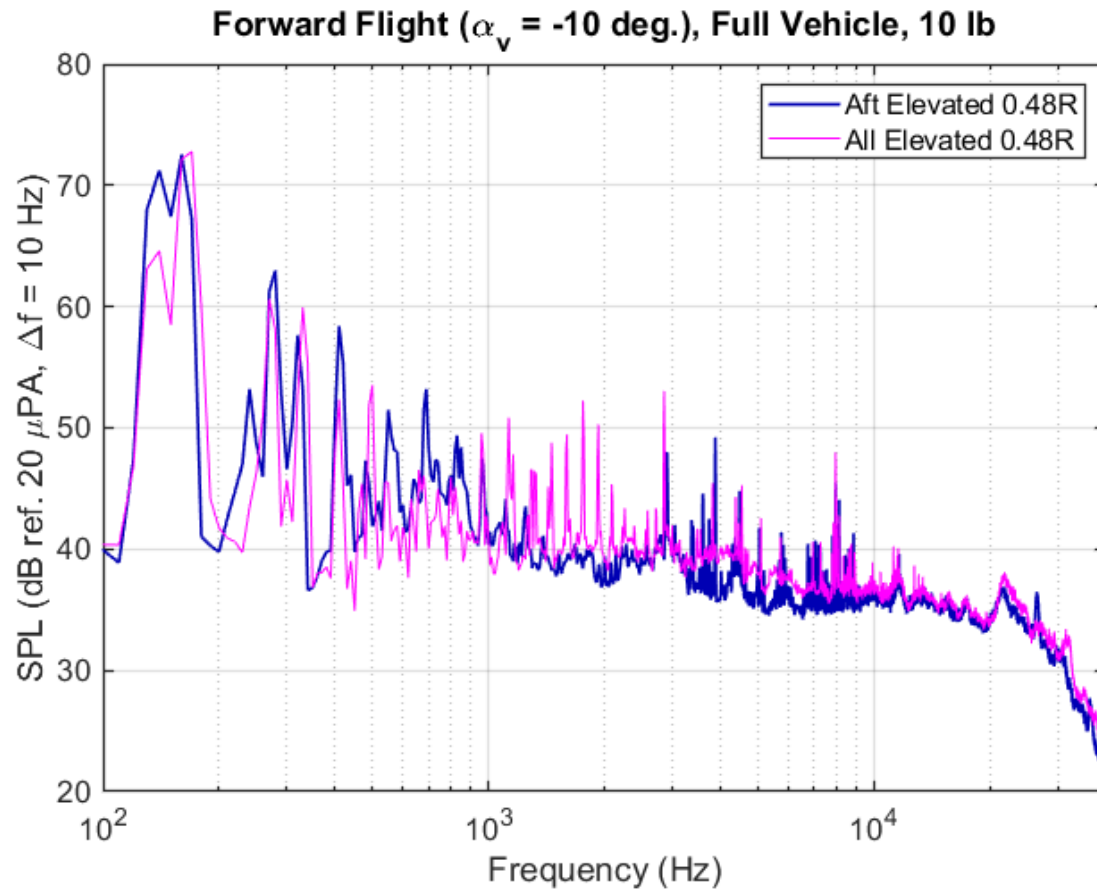
A-weighted integrated levels show a reduction of up to **8 dB**, when including all content between **0.1 and 20 kHz**

Forward Flight Results

Using the cylinder standoffs in forward flight



Rotor standoffs were placed on **all rotors** to elevate the rotors from the airframe

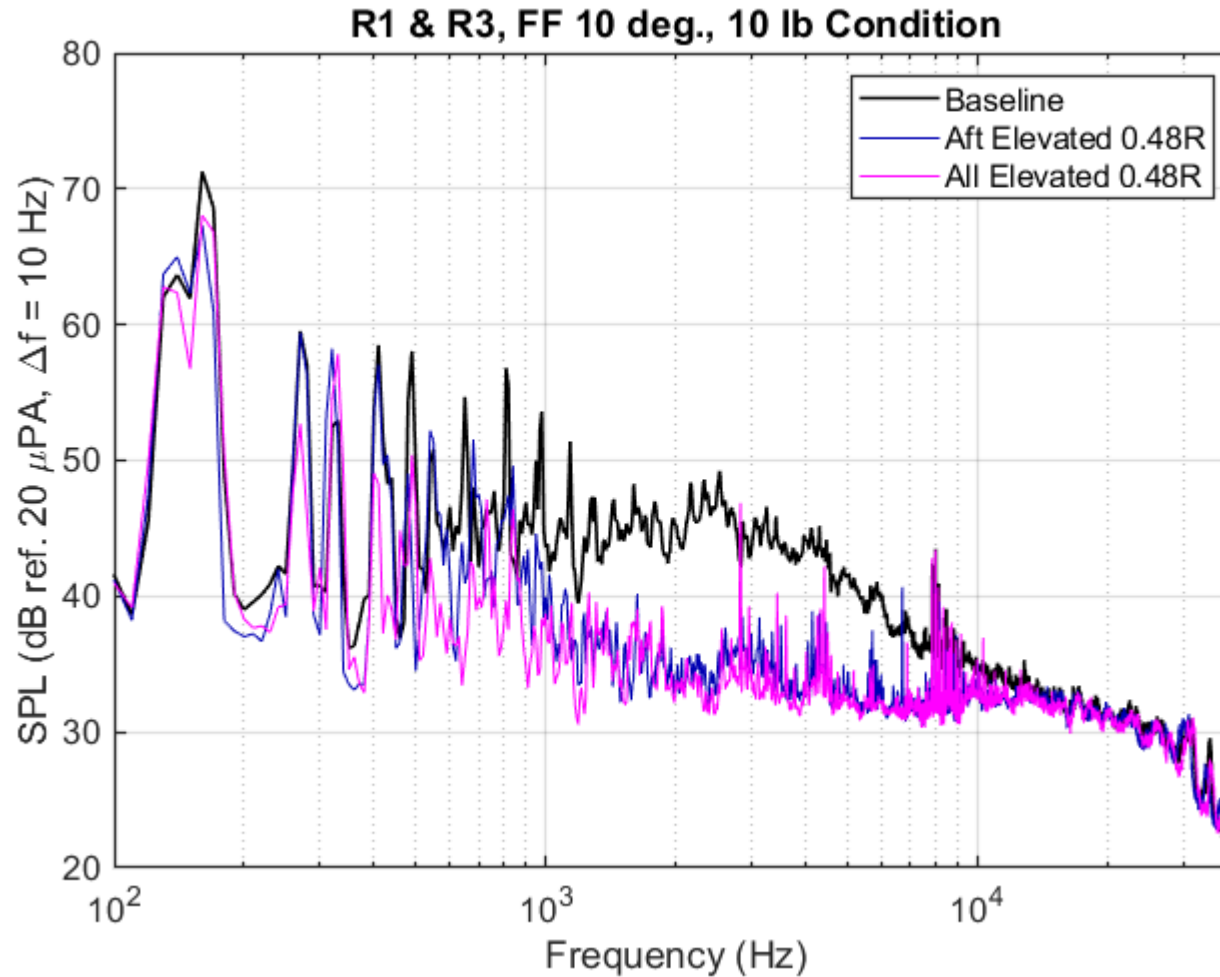
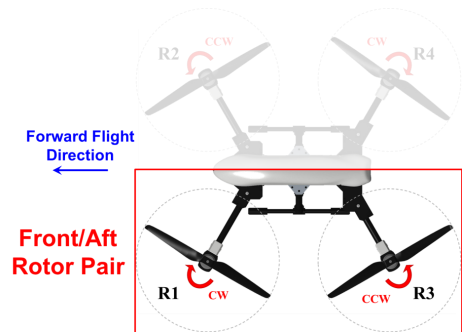
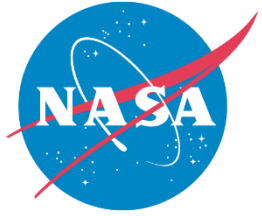


Broadband noise levels between **1 and 9 kHz** have minimal difference when comparing spectra

Additional harmonics present at mid-frequencies could be due to cylinders oscillating

Forward Flight Results

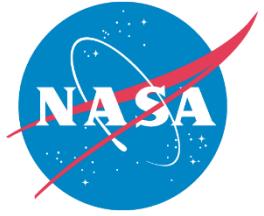
Using the cylinder standoffs (R1 & R3)



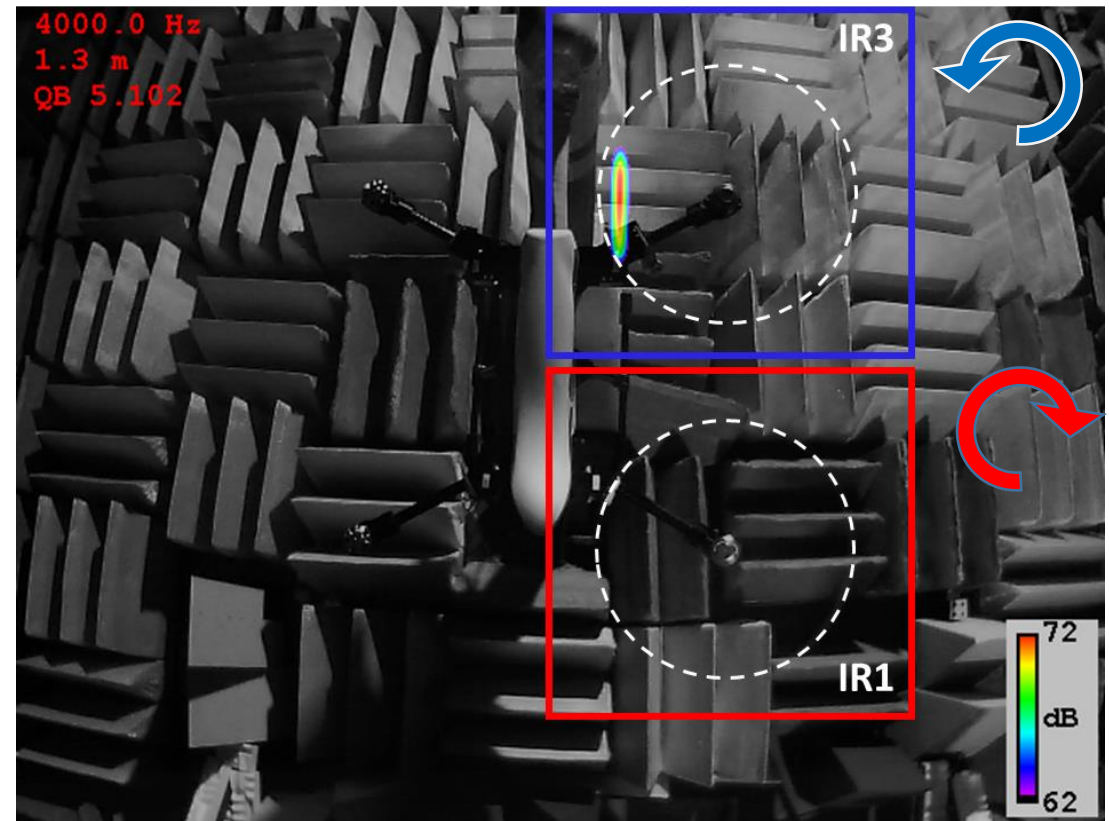
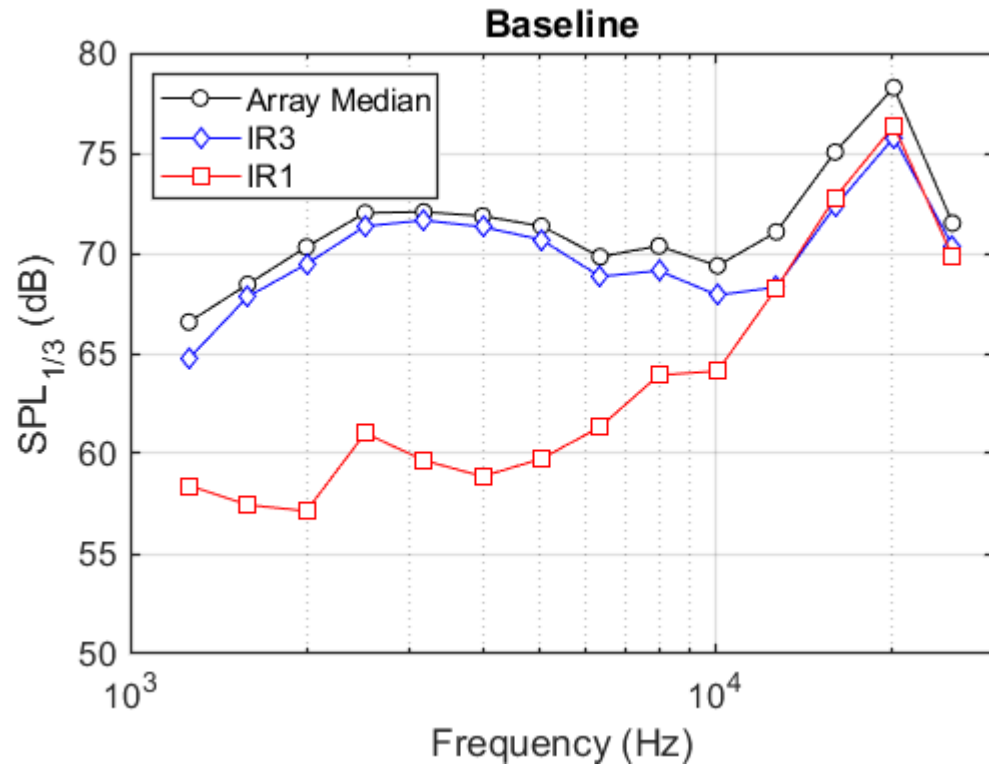
Spectral trend is similar to full vehicle configuration

Beamforming Results

Using the cylinder standoffs (R1 & R3)

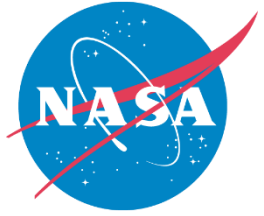


Baseline: 4 kHz

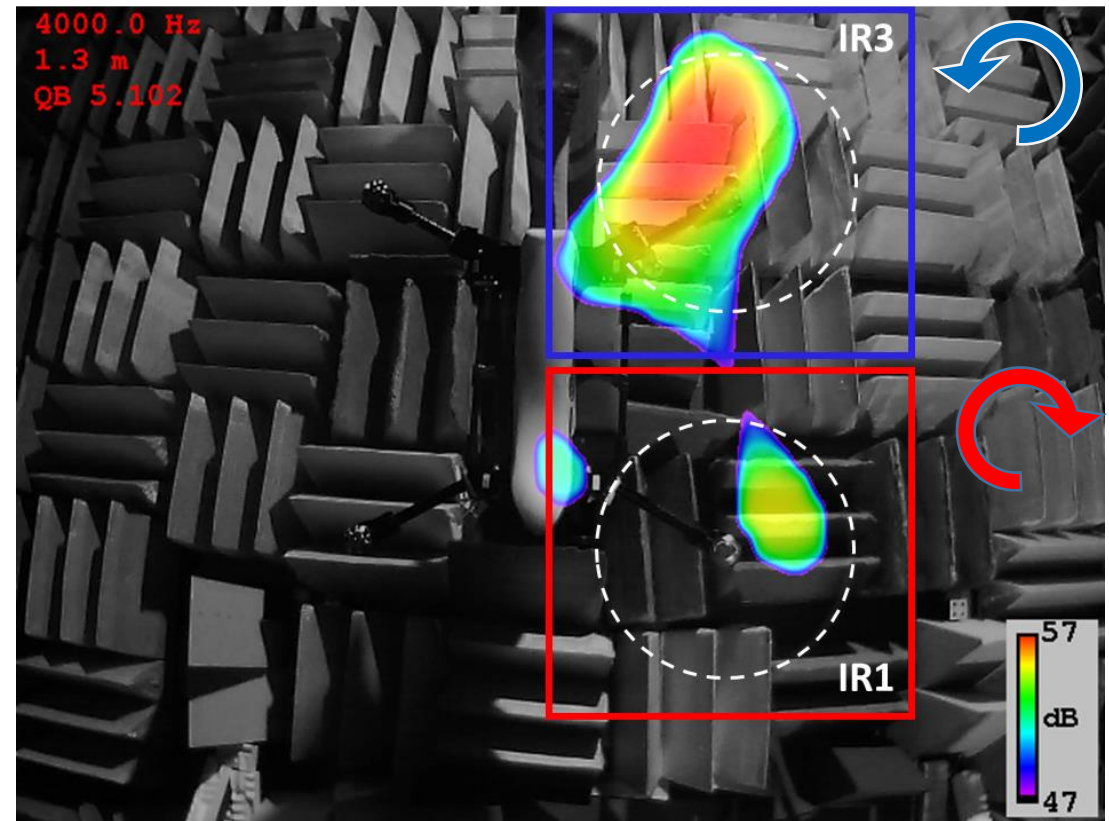
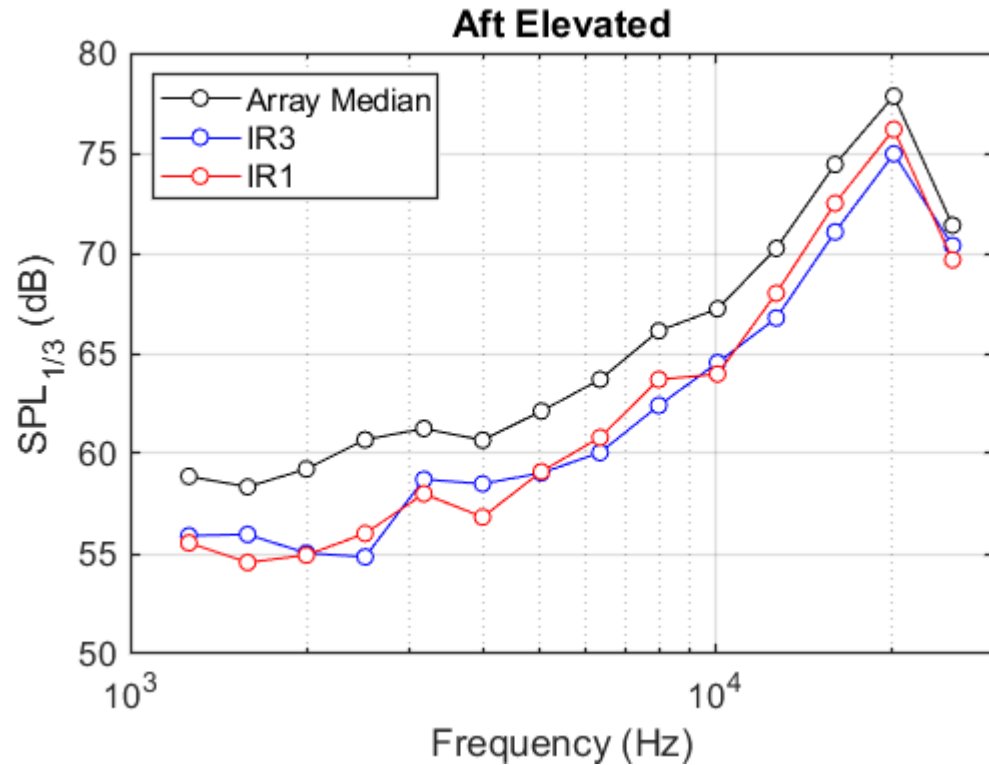


Beamforming Results

Using the cylinder standoffs (R1 & R3)

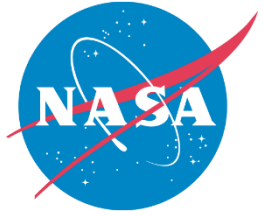


Aft Elevated: 4 kHz

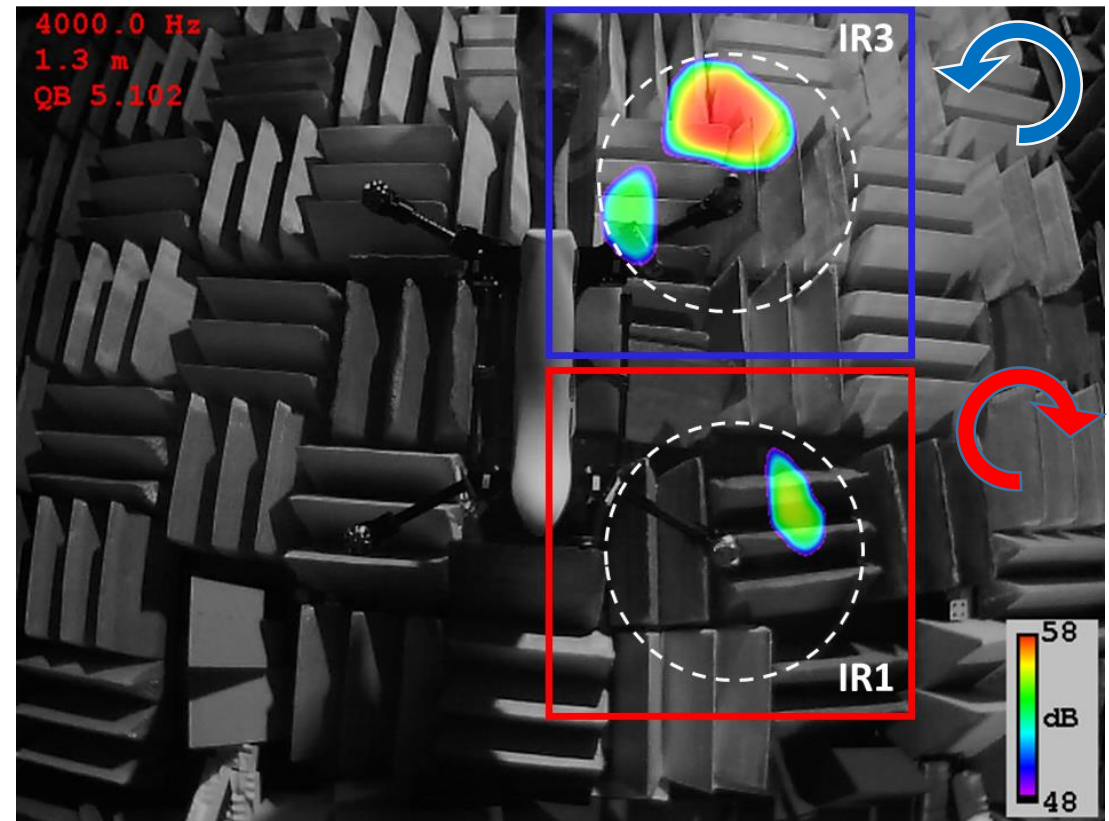
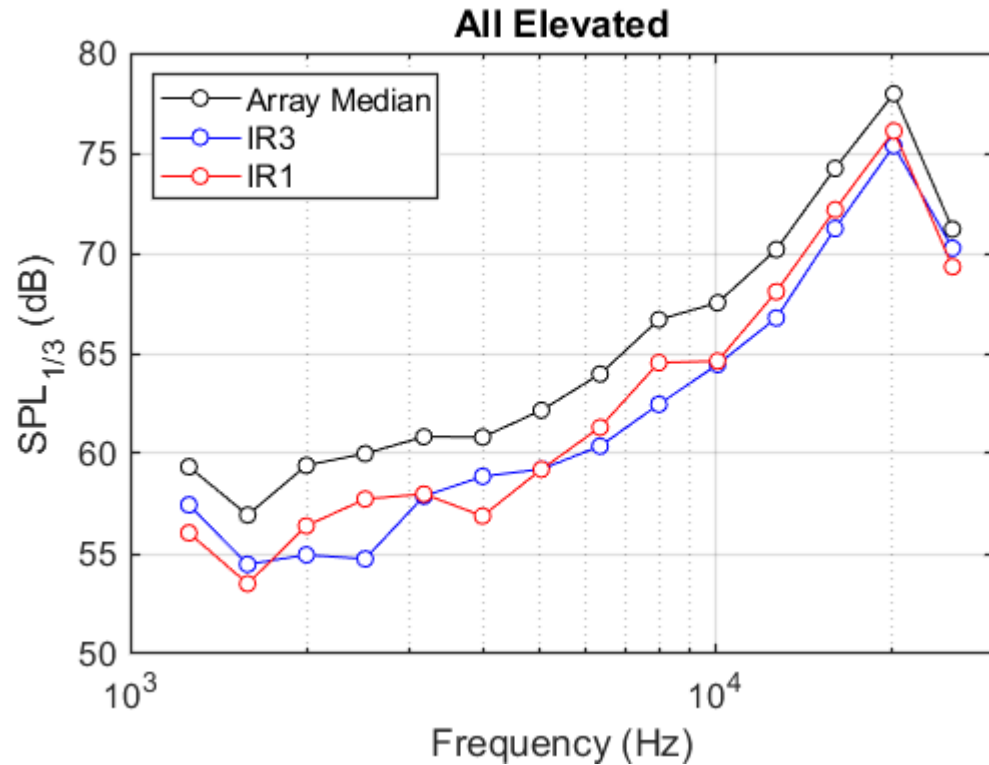


Beamforming Results

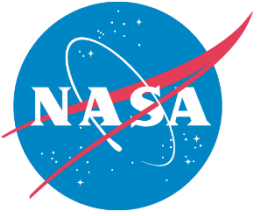
Using the cylinder standoffs (R1 & R3)



All Elevated: 4 kHz

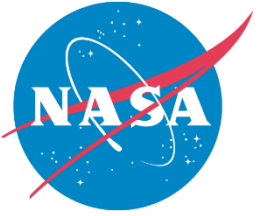


Conclusions



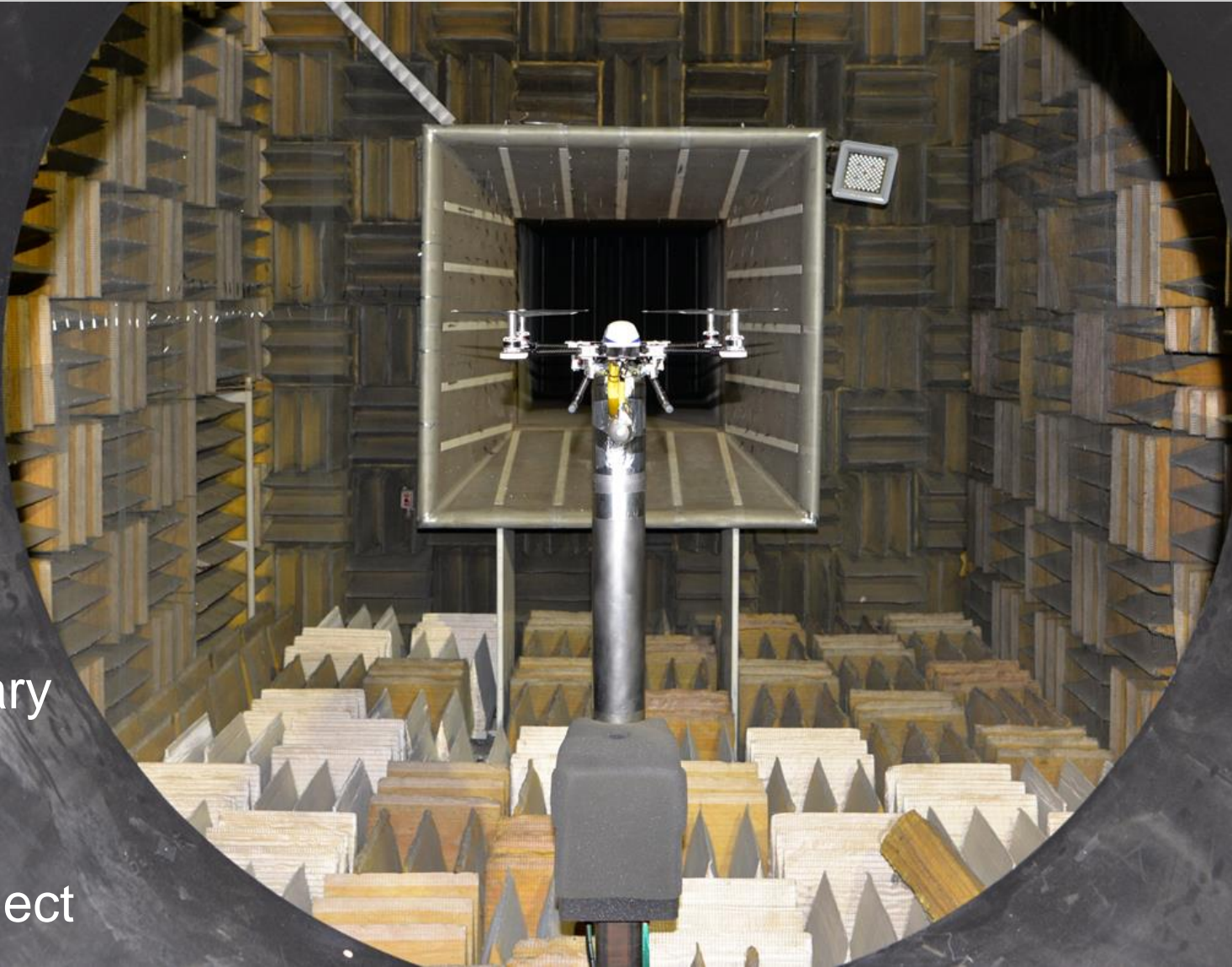
- Hover
 - Elevating rotors did not show a significant noise reduction in full vehicle hover flight conditions
 - When examining single R3 elevated case, elevating the rotor reduced the amplitude of the 4th-6th BPF harmonics
- Forward Flight
 - Elevating rotors (both aft-elevated and all-elevated) reduced mid-frequency broadband noise around 1-9 kHz
 - By elevating rotors could be reducing noise related to:
 - Rotor-airframe interaction noise
 - Rotor-rotor interaction noise
 - Rotor-airframe-rotor interaction noise
 - Individual aft rotor noise contribution

Future Work



- Periodic and broadband noise extraction using TTL signal
- Interrogate additional thrust and flight conditions
- Use low-fidelity tools to help identify noise sources
- Planning to submit papers to future conferences

Acknowledgments



Funding
Revolutionary
Vertical Lift
Technology
(RVLT) Project

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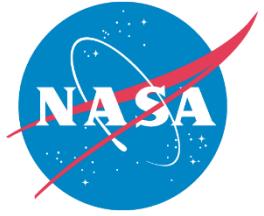
Thank you, any questions?



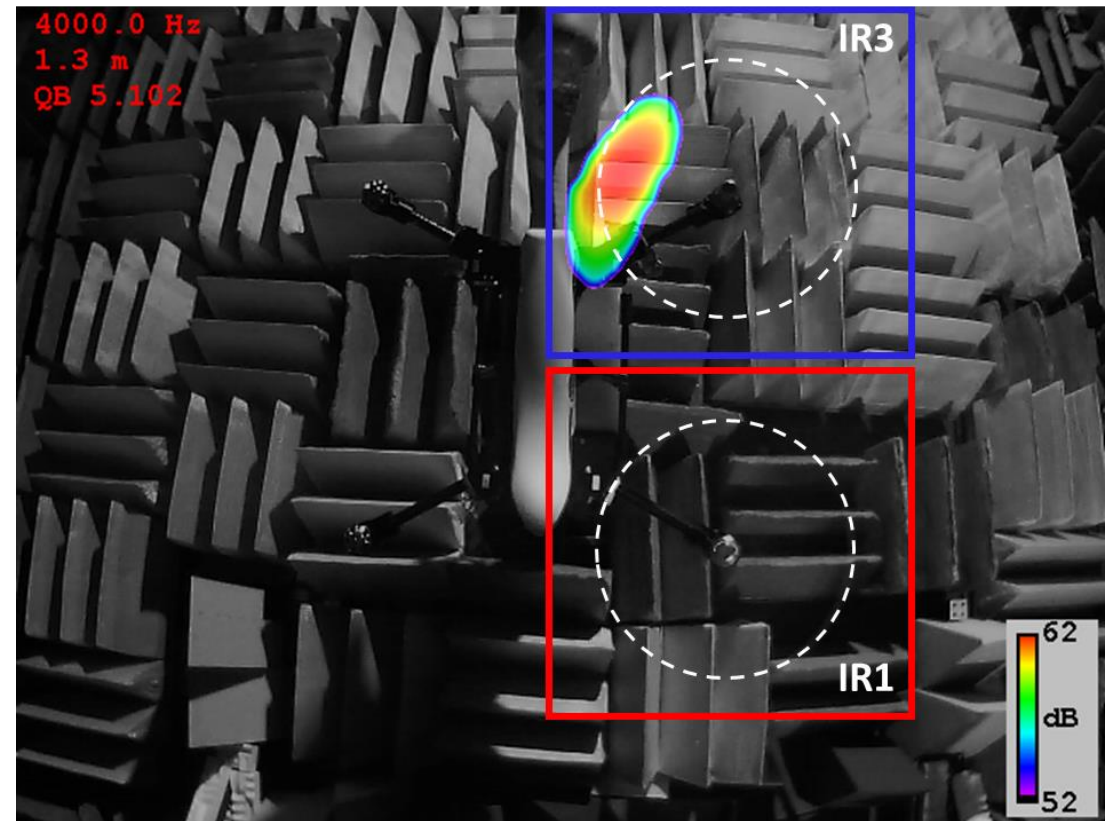
Extra Slides



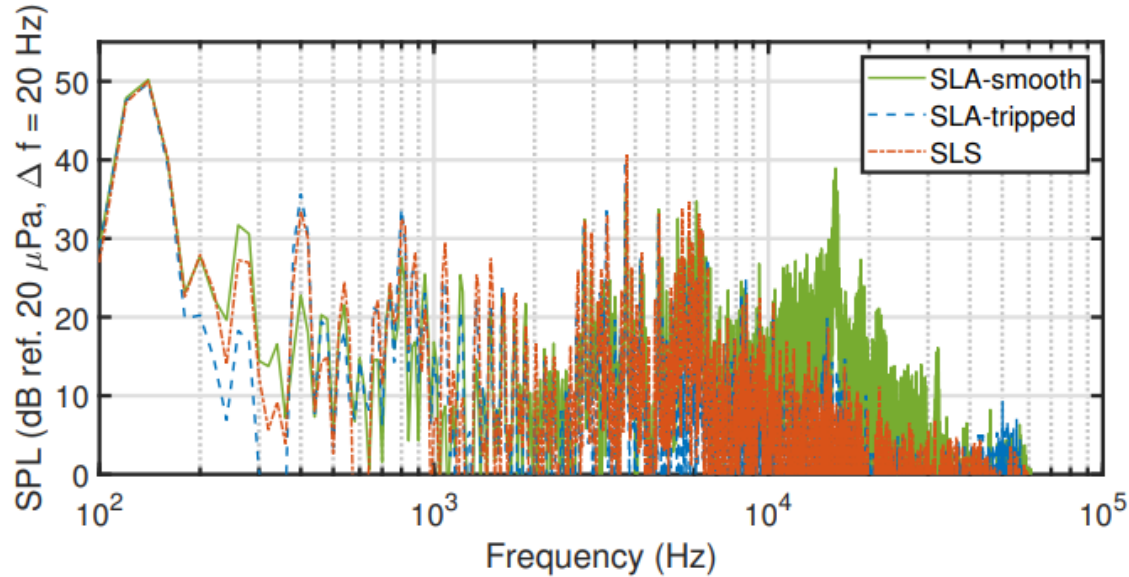
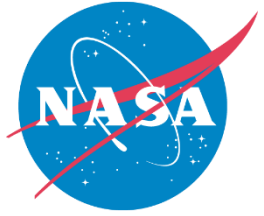
Beamforming Results Using the cylinder standoffs (R1 & R3)



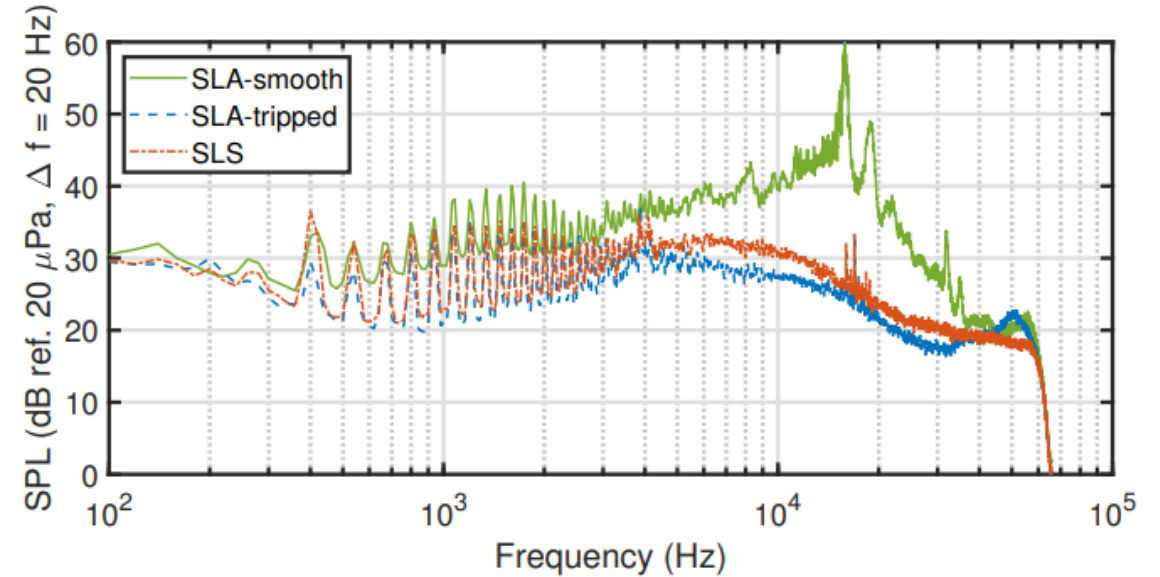
Aft Elevated (med. cyl) : 4 kHz



SHAC Testing Blade Set Comparison



(a) Tonal noise.



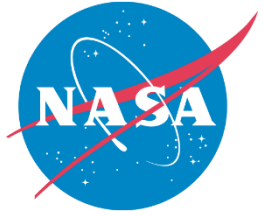
(b) Broadband noise.

Blade sets were tested in the Small Hover Anechoic Chamber (SHAC) prior to being placed on vehicle

SLA blades had a glass grit applied to them (and referred to as “SLA-tripped”), as it was found to reduce laminar boundary layer vortex shedding (LBLVS) broadband noise between **4 and 30 kHz**

Forward Flight Results

Using the cylinder standoffs in forward flight



Unweighted integrated levels of various elevation configurations:

