



Rotating Balance Design and Production, GRC-419R

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*12th International Symposium on Strain-Gage Balances
Buffalo, NY
May 23-25, 2022*





Collaborators

- **Langley Research Center**
 - Devin Burns
 - Peter Parker
 - Sean Commo
 - Donny Harper
- **Glenn Research Center:**
 - Mark Woike (retired)
 - Jonathon Ponder
 - Tony Shook
 - Joe Dussling
 - Jim Buckley
 - Scott Metzger
- **Modern Machine & Tool**
 - Dennis Yates
 - Yousuf Mohammad
 - Kevin Bloxom
 - Mark Roth
 - Howard Walls
- **And Others**

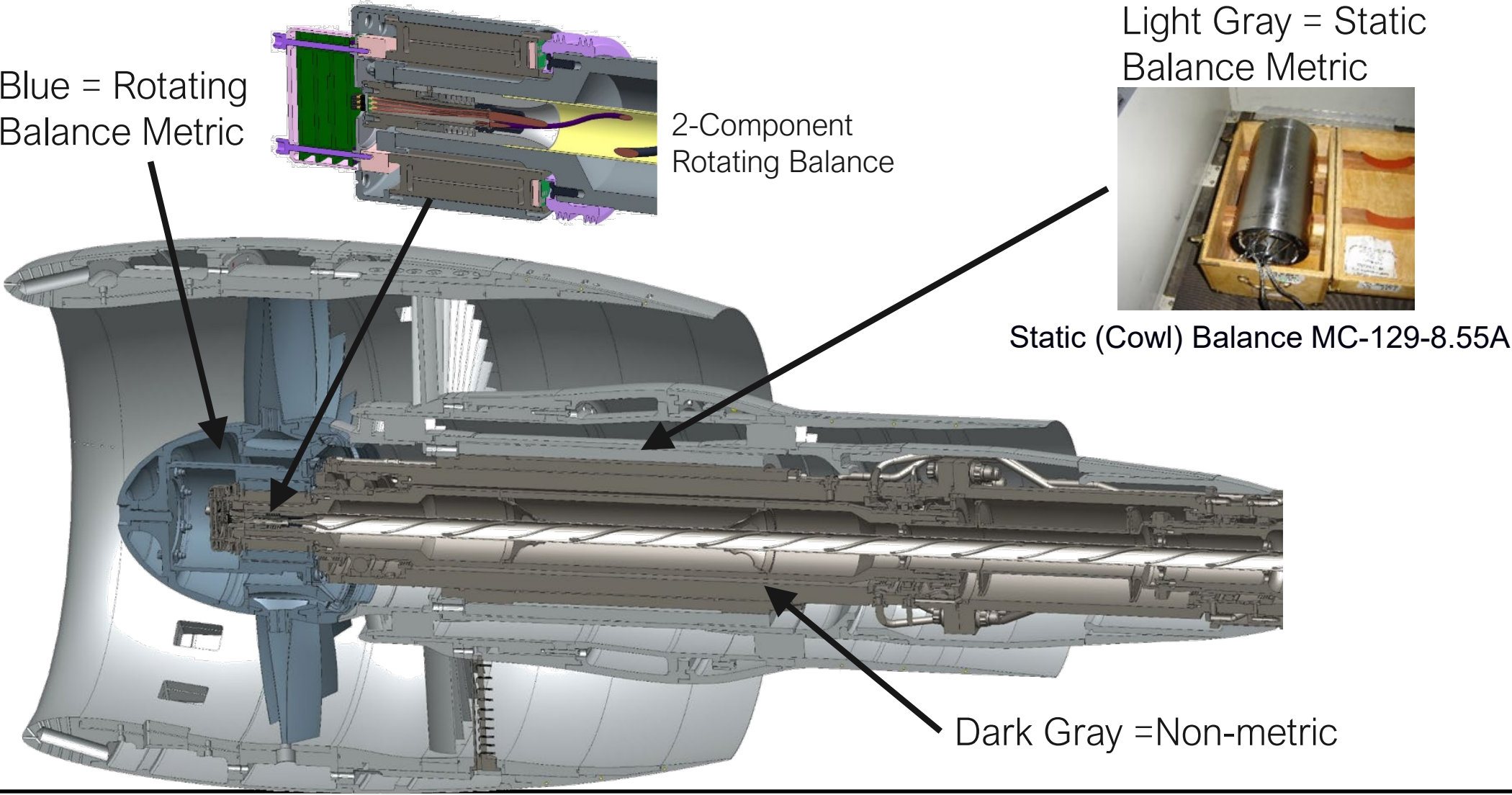


Project Overview

Four (x4) new rotating balances are in various stages of design and production

- **(x2) Two-component small form factor rotating balances, GRC-517R-A&B for advanced turbofan testing at NASA Glenn Research Center**
- **(x1) Two-component rotating balance GRC-419R for boundary layer ingestion testing at NASA Glenn Research Center**
- **(x1) Two-component reduced diameter balance for tail cone thruster testing at NASA Ames Research Center**
- **(x1) Six-component balance Unducted Single Fan, USF at NASA Glenn Research Center**

- **Force balances provide a measure of propulsion performance independent from flow field measurements.**
 - System performance (net thrust – drag) is only measured with force balances.
 - Fan efficiency measurements based on rotor torque are more accurate than pressure/temperature-based measurements.
- **New two-component rotating balances are being required for the testing of fan concepts being developed under several NASA Aeronautical Research Mission Directorate (ARMD) and Advanced Air Transport Technology (AATT) Projects**
 - Higher bypass ratio fans with smaller engine cores (GRC-517Rs)
 - **Boundary layer ingestion tolerant fans (GRC-419R)**
 - Hybrid electric propulsion concepts (tail cone thruster, etc.)
 - Unducted single fan (GRC-222R)
- **Need to interface to new state-of-the-art FPGA telemetry systems that have been developed for fan testing at NASA GRC**



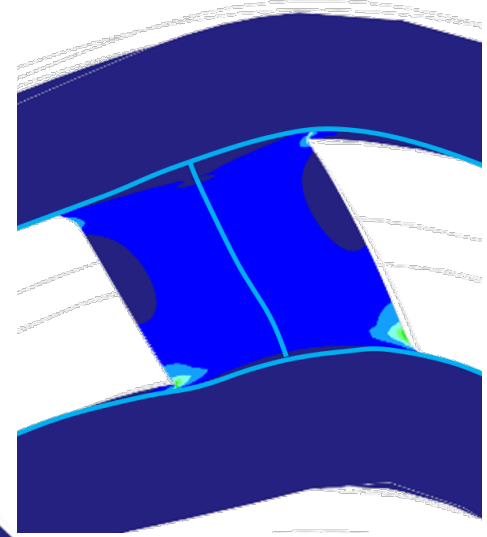
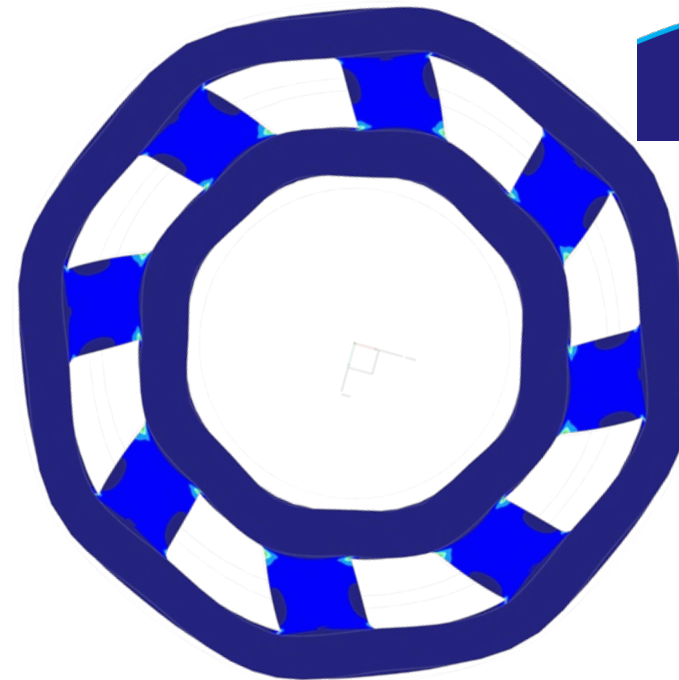
Rotating Balance Design Overview

- Spoke wheel design, with both forward and aft beam groups
- Two measurement components:
 - Torque and Thrust
- Thick “bulkhead” behind beams
- Keyways to transmit torque loads



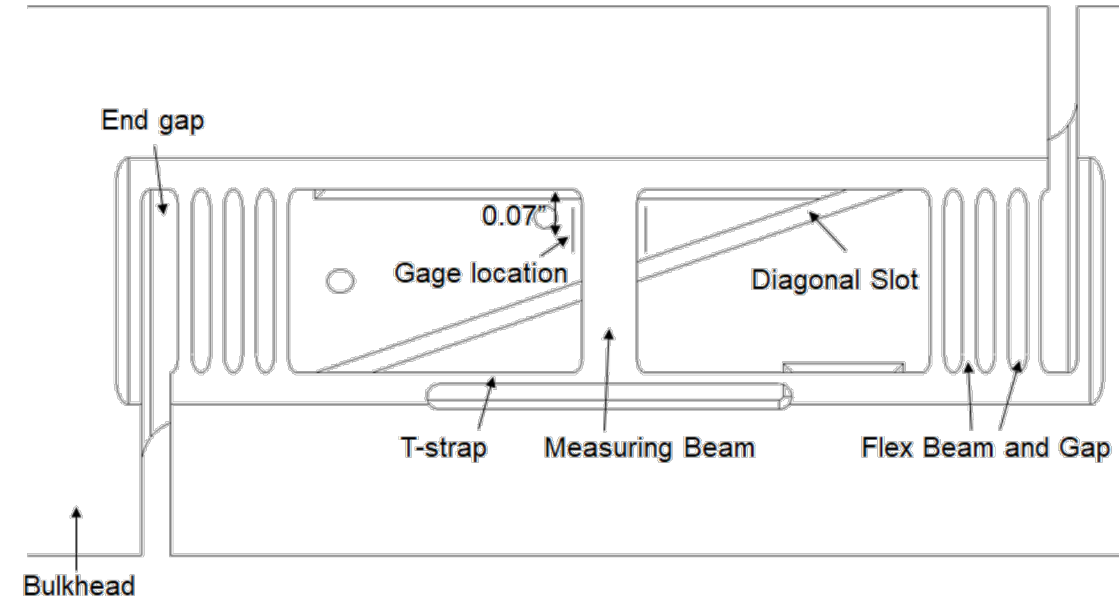
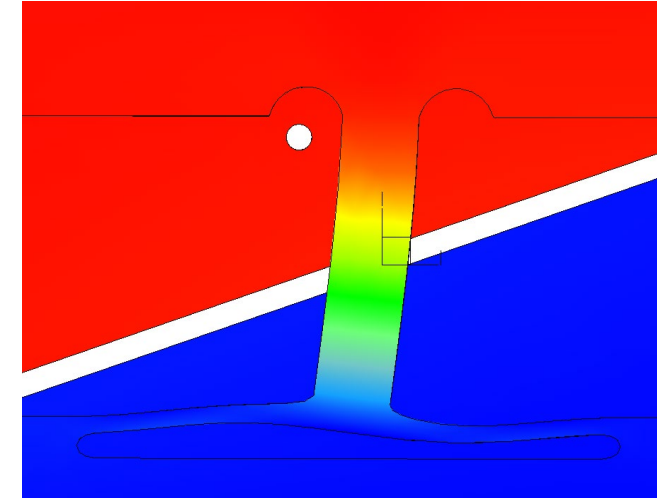
Finite Element Analysis Observations

- Double bending behavior was initially expected due to torque load
- FEA revealed warping behavior of the outer and inner diameters
 - Warping of outer diameter reduces double bending behavior of beams



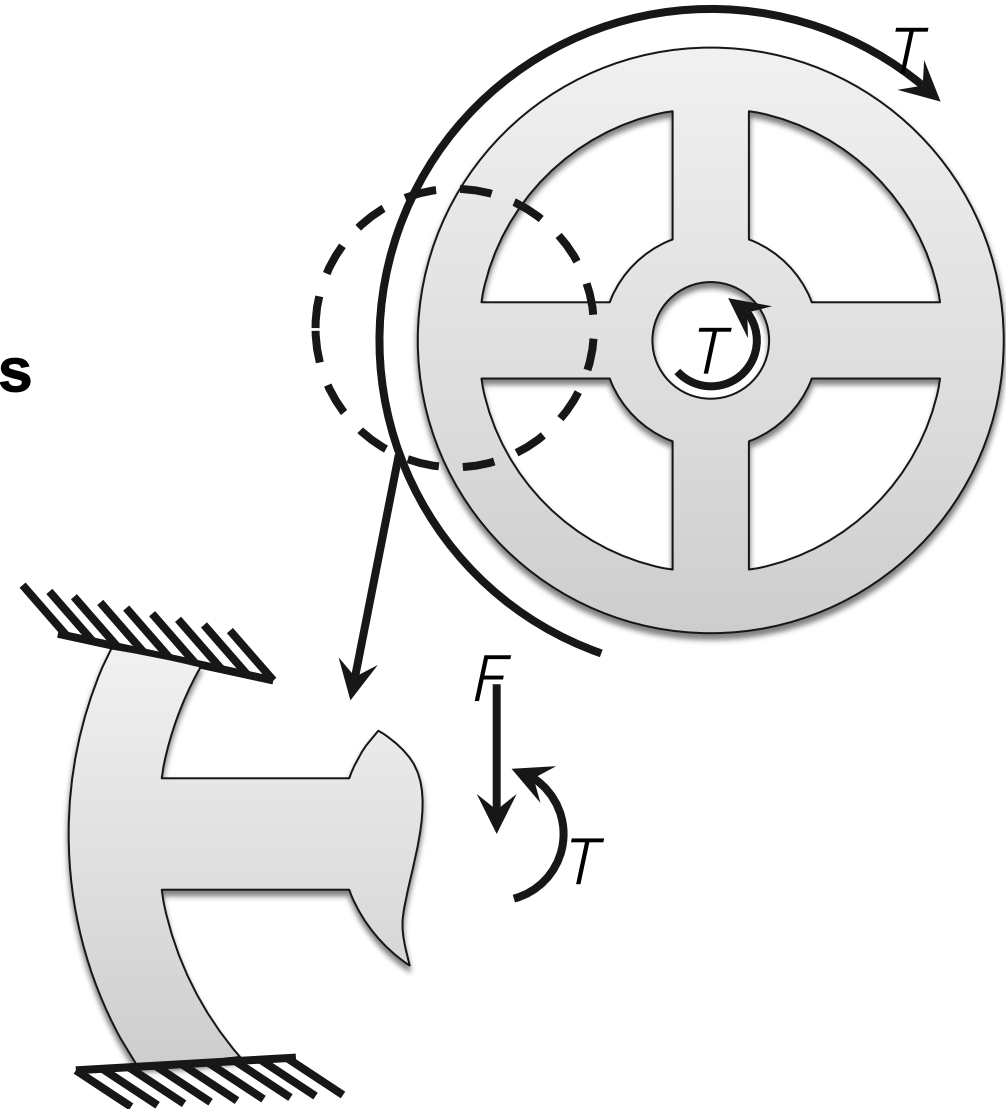
Analytical Model – T-Strap

- Behavior of the outer diameter is similar to another known balance feature, the T-Strap
- A T-strap is a design used to reduce normal force interactions on the axial measuring beam
- This design feature reduces the double bending of the axial beam
- See NASA/TM–2019-220248 for more details



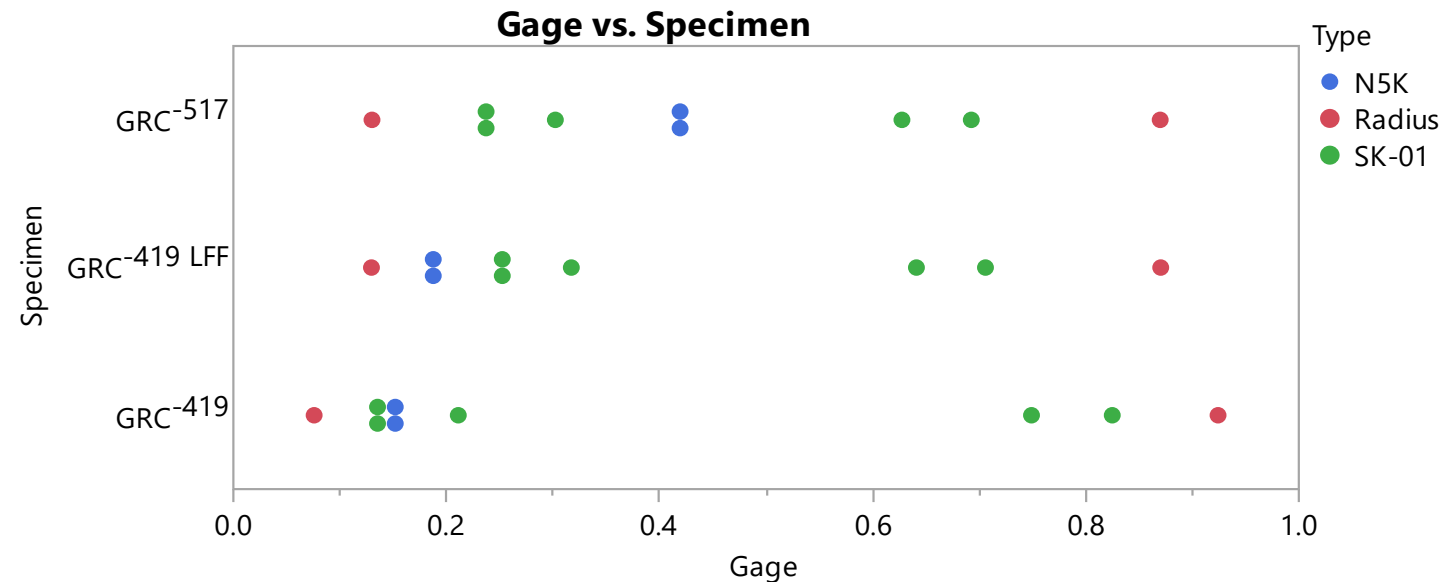
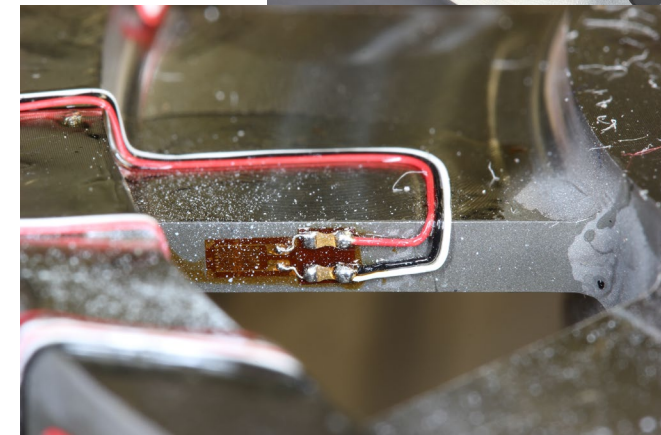
T-Strap Applied to Rotating Balances

- A single spoke of the rotating balance can be viewed as a T-Strap
- Modification to the T-Strap calculations involves reevaluating the derivation to include torque at balance center
- Assumption is made on effective strap width



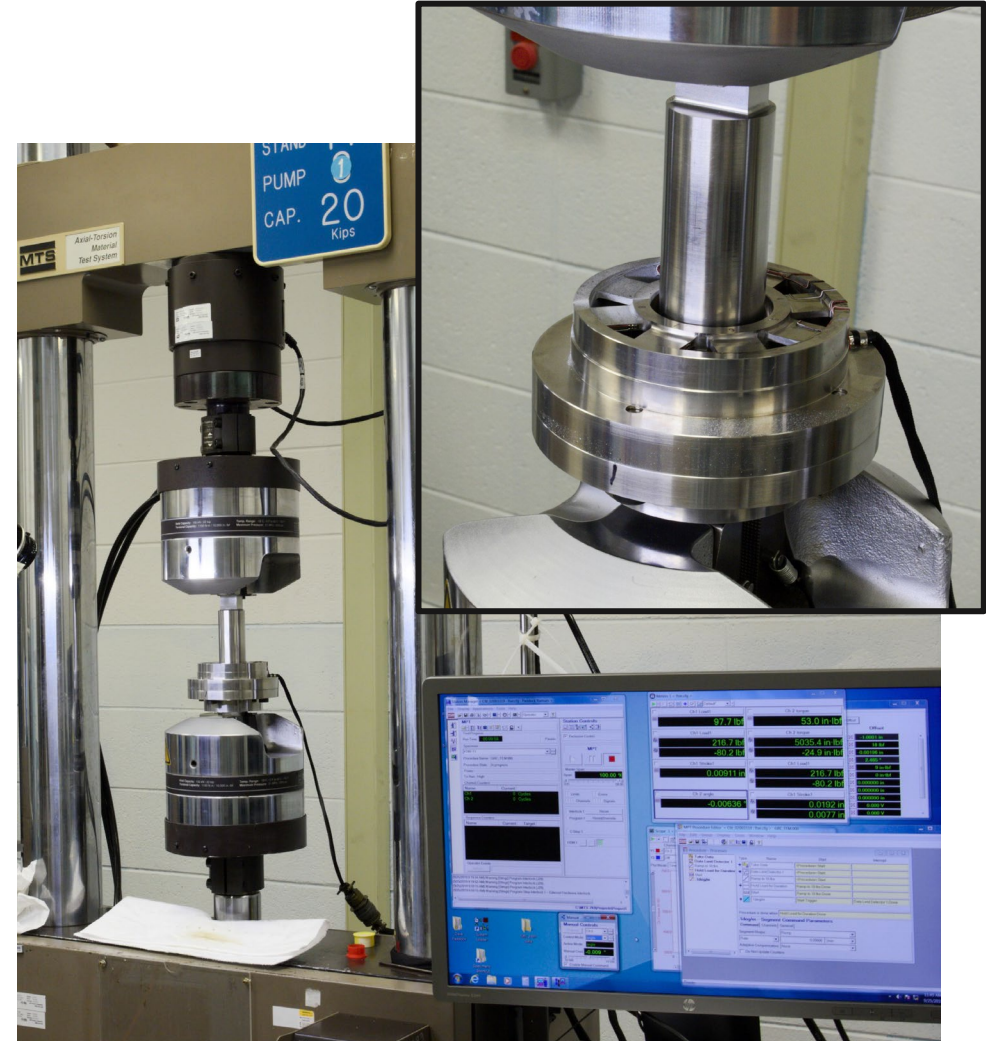
Test Specimens

- 17-4PH conventionally machined using mill/lathe operations, no EDM
- 8 strain gages placed at various locations with two locations per specimen having replicates



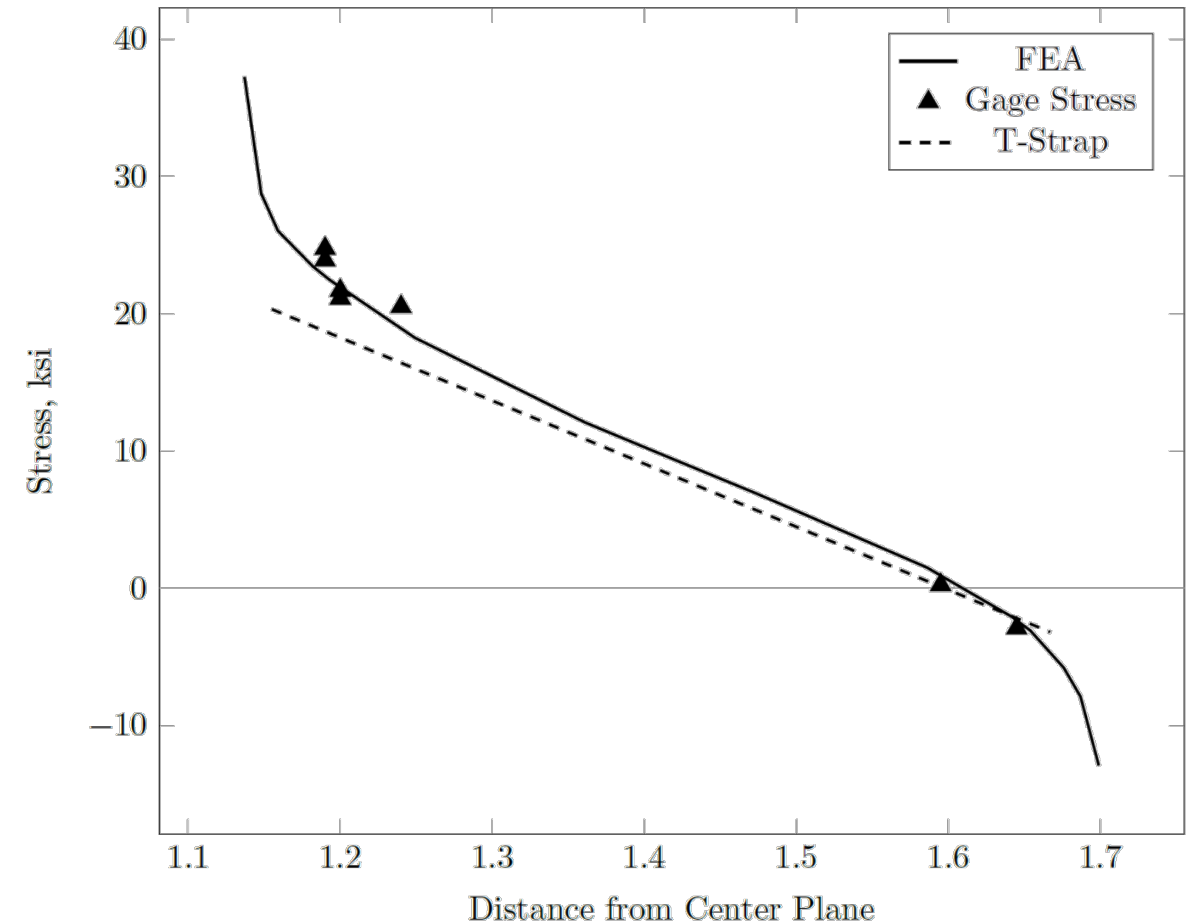
Test Method

- MTS Tension-Torsion machine was used to apply loads to specimens
- Torque was only applied to the specimen, small tension load to engage grippers
- Maximum torque was scaled from balance design loads based on difference in material properties



Model Validation Results

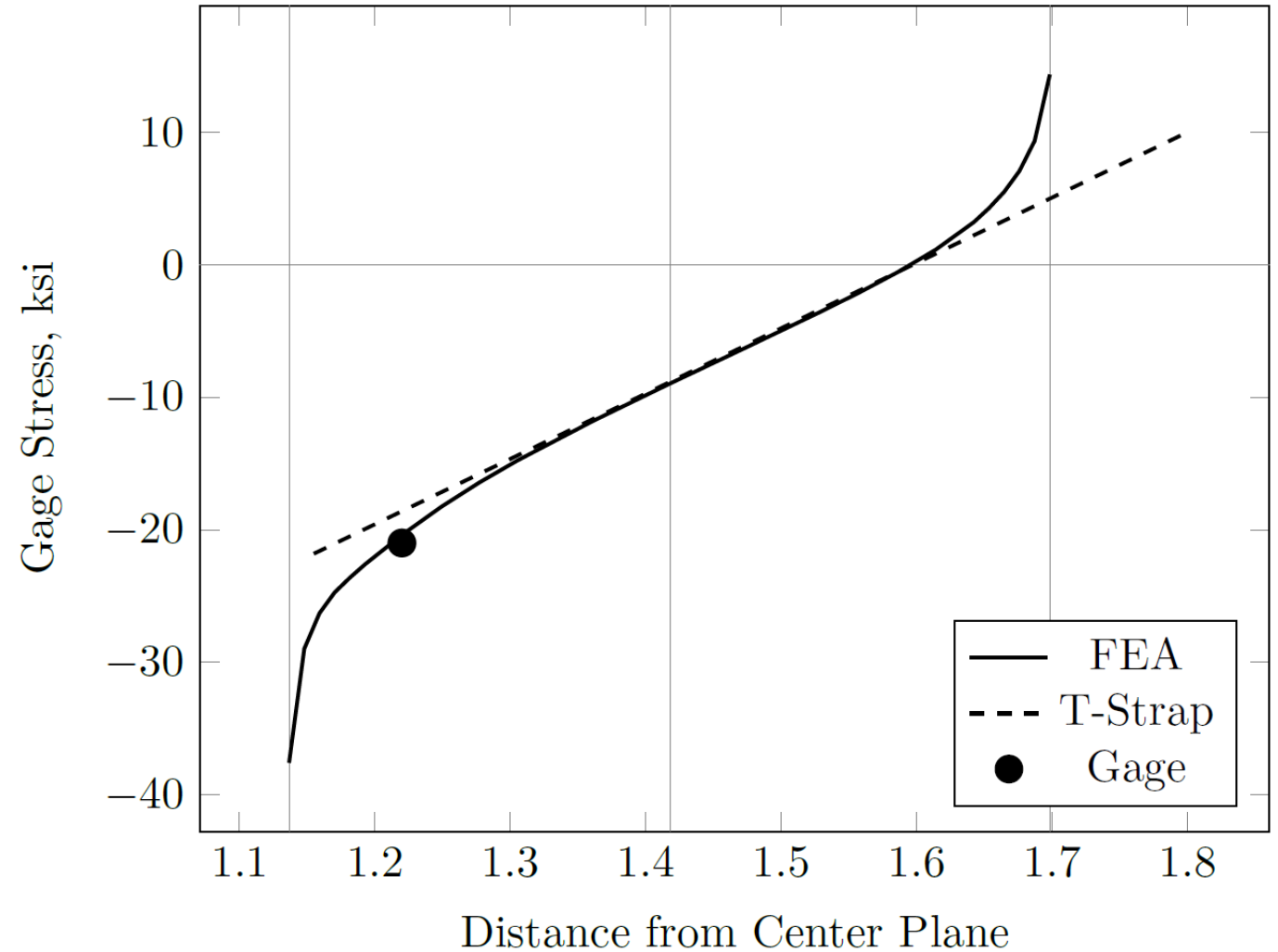
- **FEA conducted on test specimen**
 - Constraints applied dowels
 - Stress measurements taken along beam length for torque
- **Gage data taken for maximum torque load applied**
- **Stress gradient illustrated large reduction of double bending due to torque**



GRC-419R Test Specimen

Model Fit on GRC-419R Calibration Data

- **FEA conducted on full-span balance**
 - Constraints applied to keys and mating surfaces to replicate fit
 - Stress measurements taken along beam length for torque
- **Gage data taken for maximum torque load applied during calibration**



Calibration Summary

- **Broken into multiple phases:**
 - Phase 1: Gaged and wired
 - Phase 2: Temperature Loadings
 - Phase 3: PCBs Integrated
- **Outputs at full scale loads:**

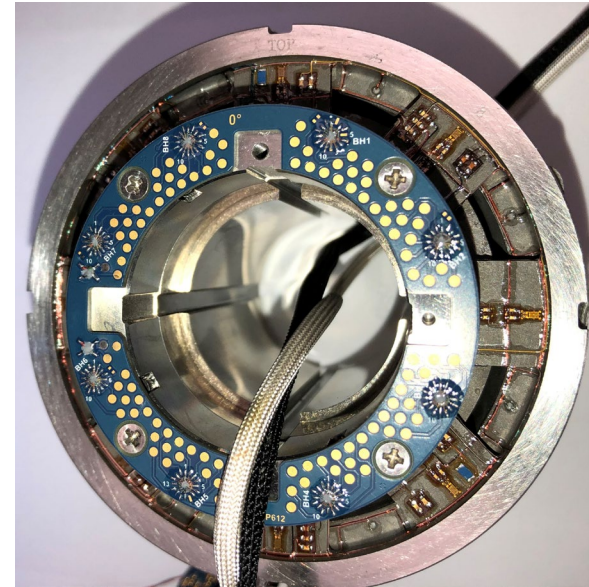
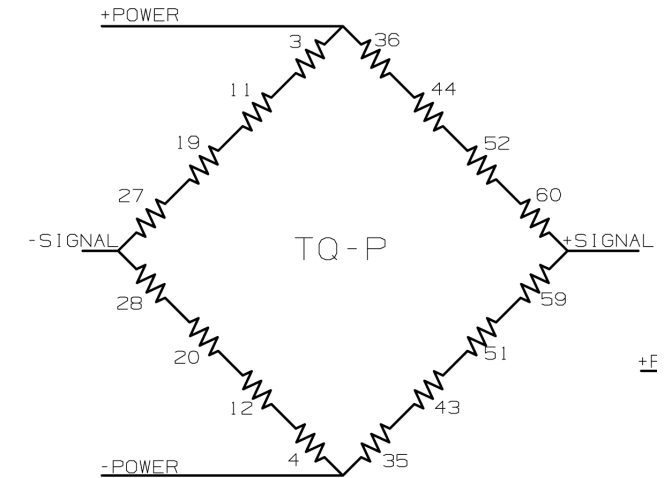
	Output, $\mu V/V$	
	Primary	Secondary
Torque	1,685	1,756
Thrust	914	928

- **No interactions to out-of-plane forces and moments**



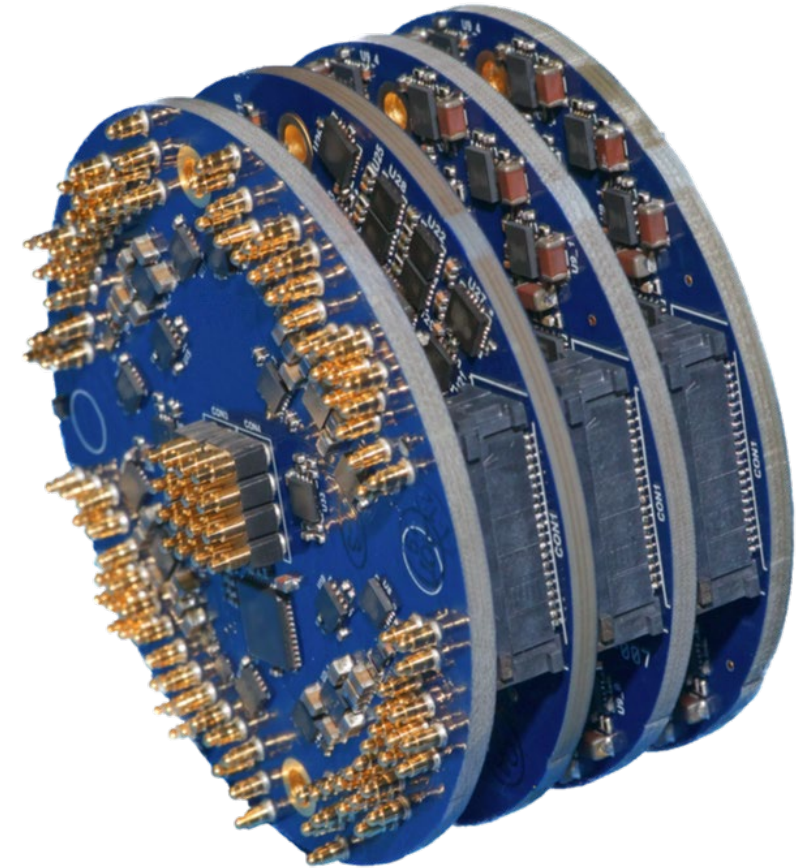
Balance Gaging and Integration

- **Gaging of this balance had to follow strict requirements of the telemetry system**
- **Wiring and terminal placements were predefined to ease PCB integration**
- **Communication between Telemetry Team, Balance Team, and Fabrication was critical**



Telemetry System

- Utilizes a custom telemetry system to condition and acquire balance signals and fan blade strain gauges
- GRC-419R and GRC-517R use a common telemetry system



Temperature Model

- **Linear temperature correction to the sensitivity constant:**
$$SC_{@T} = SC_{@RT}(1 - K(T_{op} - T_{ref}))$$
- **All hardware pre-heated in oven and moved to calibration stand**
- **Temperature corrected residuals were within 0.2%F.S.**



Summary

- **GRC-419R project required high level of integration between all team members**
 - Complex model integration
 - Embedded electronics interfacing
 - Multiple mating interfaces
- **Modifications to analytical methods allowed for prediction of beam stresses for rapid design space exploration**
 - Validated analytical modes and FEA models with fast/low-cost testing
- **Successfully calibrated and temperature corrected balance to below 0.25% F.S.**