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# Towards an Implementation of Differential Dynamic Logic in PVS

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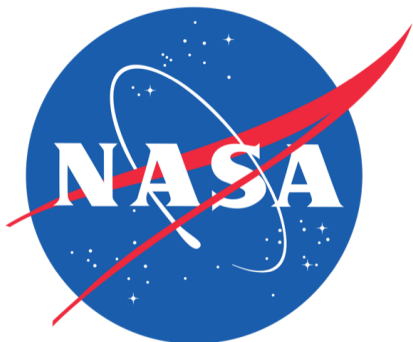
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# Overview

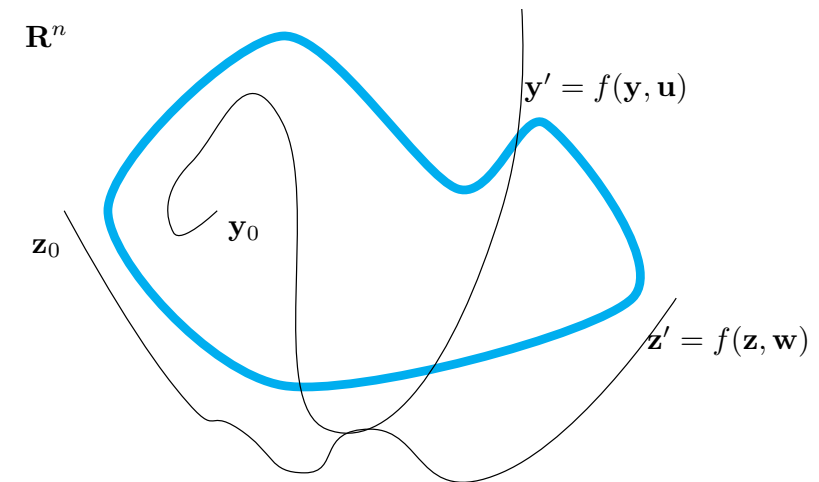
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- **dL**: Differential Dynamic Logic for hybrid programs [1]
- **PVS**: Interactive theorem prover [2]

## Result: Embedding of dL in PVS

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- Formally verified soundness of **dL**
- Fully operational in **PVS**
- Leveraging features of **PVS** to extend **dL**

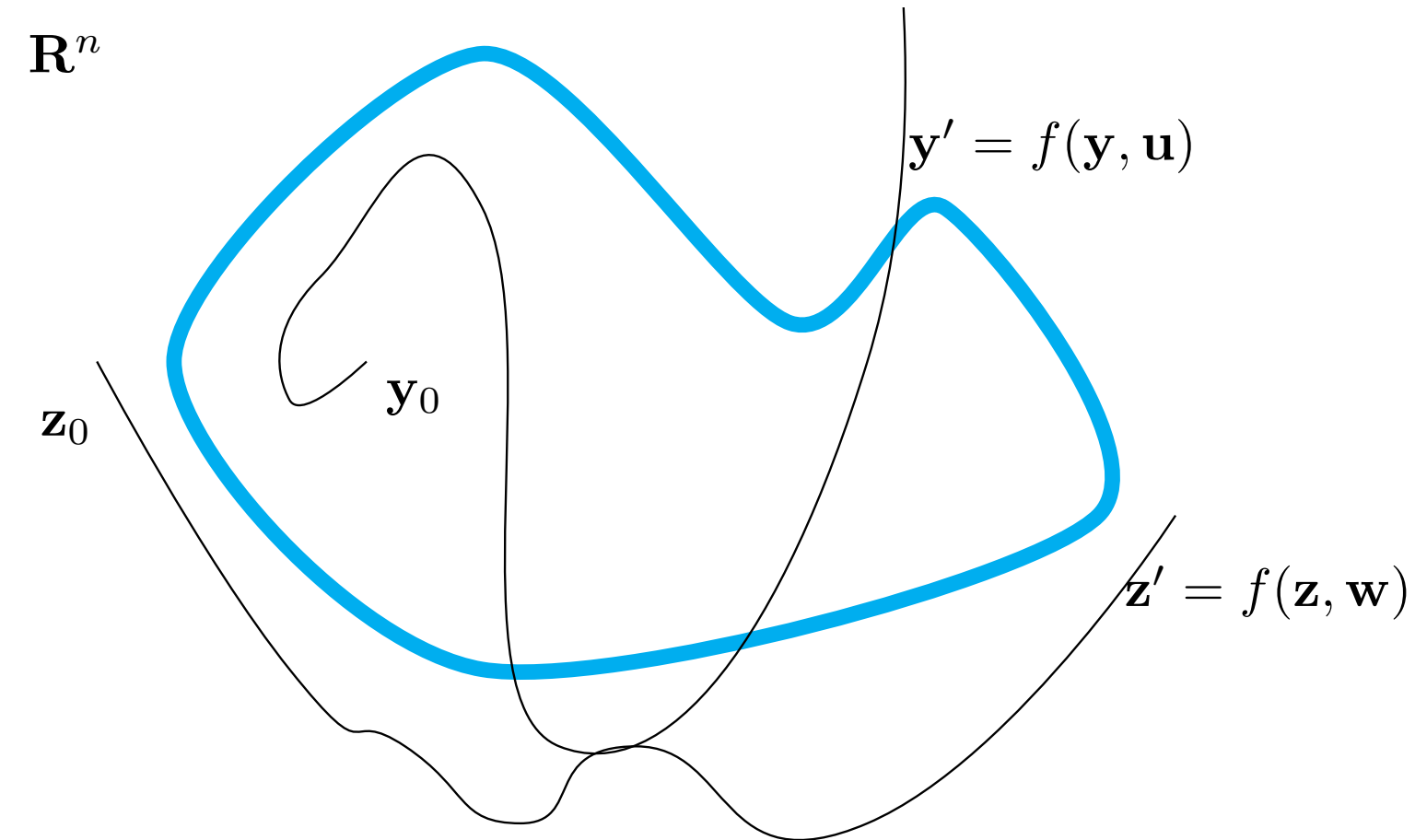


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[1] Differential Dynamic Logic website, André Platzer: <https://symbolaris.com/logic/dL.html>

[2] PVS website, SRI International: <https://pvs.csl.sri.com>

# Hybrid Systems



- **Hybrid system:** dynamical system that exhibits
  - Continuous behavior
  - Discrete behavior

## Want

- **Formal specification** of hybrid systems
- **Formal reasoning** of hybrid systems

# Hybrid Programs

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Hybrid programs allow **formal specification** of hybrid systems:

- Discrete jump set:

$$(x_1 := \theta_1, \dots, x_n := \theta_n)$$

- Differential equations:

$$\{x'_1 := \theta_1, \dots, x'_n := \theta_n \ \& \ \chi\}$$

- $\{x_i\}_{i=1}^n$  variables
- $\{\theta_i\}_{i=1}^n$  assignments (ex. – functions of past variable assignments)
- $\chi$  first order formula that describes domain

# Hybrid Programs (continued)

For hybrid programs  $Hp_1, Hp_2$ , first-order formula  $\chi$ :

- Union

$$(Hp_1 \cup Hp_2)$$

- Sequence

$$(Hp_1; Hp_2)$$

- Repeat

$$(Hp_1)^*$$

- Test

$$(? \chi)$$

Example:

$$((a := a + 1); \{x' = v, v' = a\})^*$$

# dL: Differential Dynamic Logic

**dL** allows **formal reasoning** of hybrid programs:

- For hybrid program  $Hp$  and predicate  $P$

- All runs

$$[Hp]P$$

- Some runs

$$\langle Hp \rangle P$$

Example: Let

$$Hp \equiv ((a := a + 1); \{x' = v, v' = a\})^*$$

$$P = (x = 10),$$

then

$$\vdash \langle Hp \rangle P$$

$$\not\vdash [Hp]P$$

# dL: Differential Dynamic Logic

**dL** allows **formal reasoning** of hybrid programs:

- For hybrid program  $Hp$  and predicate  $P$ 
  - All runs

$$[Hp]P$$

- Some runs

$$\langle Hp \rangle P$$

Another example:

$$x \geq 1 \wedge v \geq 0 \wedge a \geq 0 \vdash$$

$$\left[ \left( (a := a + 1); \{x' = v, v' = a\} \right)^* \right] (x \geq 1)$$

# dL: Differential Dynamic Logic – Rule Schema [3]

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Union axiom:

$$\frac{[Hp_1]P \wedge [Hp_2]P}{[Hp_1 \cup Hp_2]P}$$

Loop rule:

$$\frac{\Gamma \vdash J \quad J \vdash [\alpha]J \quad J \vdash P}{\Gamma \vdash [\alpha^*]P}$$

Differential invariant  
rule:

$$\frac{\Gamma, q(x) \vdash p(x) \quad q(x) \vdash [x' := f(x)](p(x))'}{\Gamma \vdash [x' = f(x) \& q(x)]p(x)}$$

...and many more! [4]

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[3] André Platzer. 2018. Logical Foundations of Cyber-Physical Systems. Springer, Cham. <https://doi.org/10.1007/978-3-319-63588-0>

[4] dL "Cheat Sheet," André Platzer, <https://symbolaris.com/logic/dL-sheet.pdf>



# KeYmeara X

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- KeYmeara X: formal verification tool for hybrid systems implementing **dL**
- Verification of:
  - Railway systems [5]
  - Automotive systems [6]
  - Aviation transportation systems [7]
  - Autonomous robotics [8]
  - Etc.

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[5] André Platzer and Jan-David Quesel. European Train Control System: A case study in formal verification. *11th International Conference on Formal Engineering Methods, ICFEM, Rio de Janeiro, Brazil, 2009*

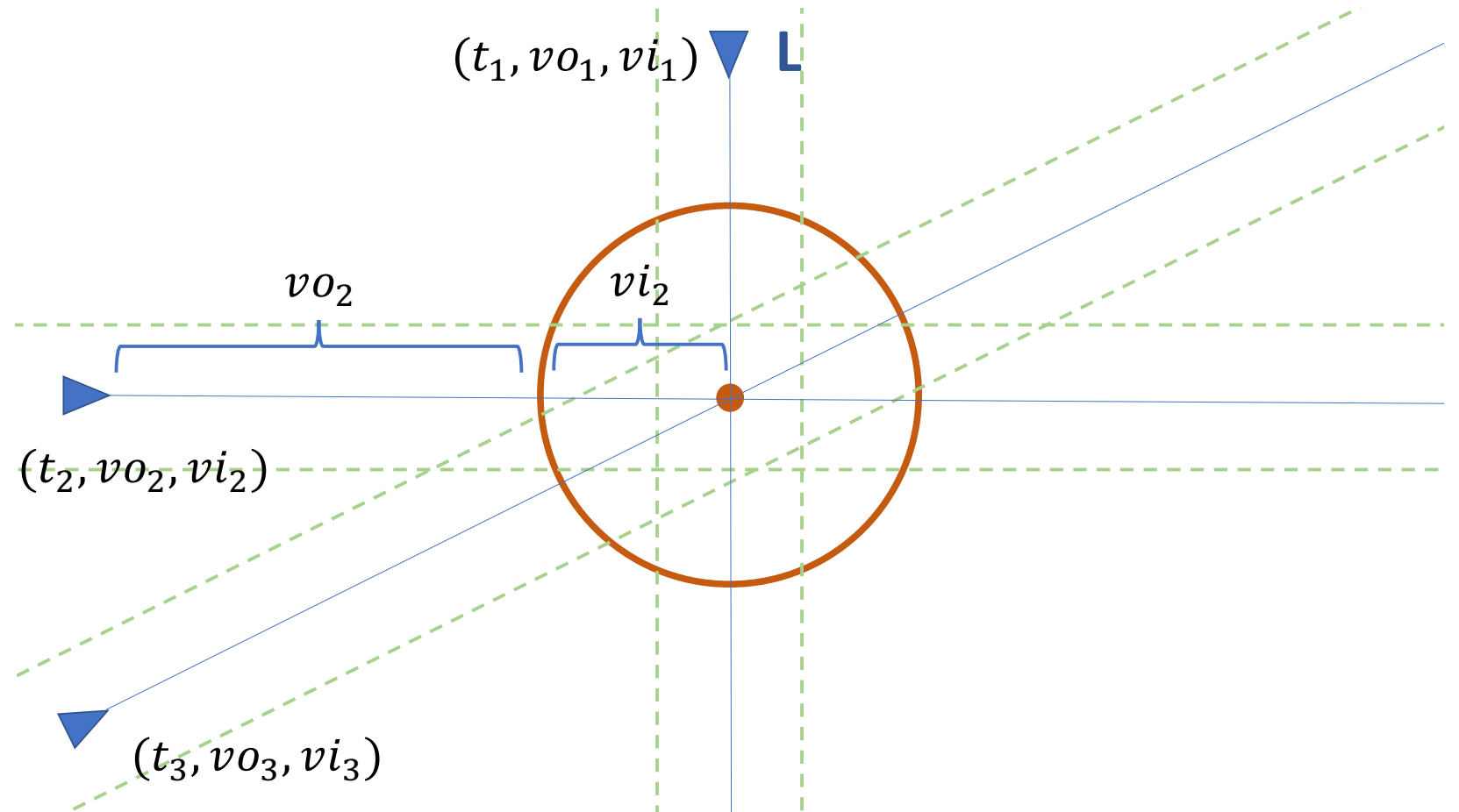
[6] Sarah M. Loos, André Platzer, and Ligia Nistor. Adaptive cruise control: Hybrid, distributed, and now formally verified. *17th International Symposium on Formal Methods, FM, Limerick, Ireland, 2011*

[7] André Platzer and Edmund M. Clarke. Formal verification of curved flight collision avoidance maneuvers: A case study *16th International Symposium on Formal Methods, FM, Eindhoven, Netherlands 2009*

[8] Stefan Mitsch, Khalil Ghorbal and André Platzer. On provably safe obstacle avoidance for autonomous robotic ground vehicles *Robotics: Science and Systems, RSS, 20139, 2013*

# Outline

- Introduction
  - Hybrid programs
  - **dL**
- **dL** in PVS
  - PVS
  - Extensions of **dL** in PVS
  - Examples
- Concluding remarks



# PVS

- “Prototype Verification System” developed by SRI International
- Interactive theorem prover
  - Higher order logic
  - Completely typed, dependent types
- Automation
  - Customizable tactics and strategies
- PVSio animation and rapid prototyping
- NASA PVS library [9]
  - 58 libraries
- Visual studio code extension [10]

```
deriv_test :
{-1}  b >= 0
{-2}  b > 0
{-3}  c /= 0
|-----
[1]   deriv(LAMBDA (x: real): cos(x ^ 10 + b) + exp(x ^ 2) / c) =
      LAMBDA (x: real):
      -sin(x ^ 10 + b) * 10 * x ^ 9 + exp(x ^ 2) * 2 * x / c

>> [(deriv)]
Q.E.D.█
```

[9] NASALib, maintained by NASA Langley Formal Methods Group: <https://github.com/nasa/pvslib>

[10] VSCode-PVS, Paolo Masci: <https://github.com/nasa/vscode-pvs>

# PVS – Prototype Verification System

## Specification (.pvs)

```
8   % Define half
9   half(a:real,b:real | b>a):
10      {r:real | abs(a-r) = abs(b-r)} =
11      (a+b)/2
12
13  % Theorem about half
14  prove | show-prooflite
15  half_sq: THEOREM
16      FORALL(a:real,b:real | b>a):
17          EXISTS(n:posnat):
18              a>n AND b>n
19              IMPLIES half(a,b) < half(a^n,b^n)
```

## Interactive theorem prover

```
half_sq.1.1 :
{-1}  b < b ^ 2
[-2]  a < a ^ 2
[-3]  a > 2
[-4]  b > 2
-----
[1]   half(a, b) < half(a ^ 2, b ^ 2)

>> (expand "half")
- Ctrl+SPACE shows the full list of commands.
- TAB autocompletes commands. Double click expands definitions.
```

# PVS – Prototype Verification System

## Proof (.prf)

```
7 half_sq : PROOF
8 (then (skip)(inst 1 "2")(flatten)
9   (spread (case "a<a^2")
10    ((spread (case "b<b^2")
11     ((then (expand "half")(mult-by 1 "2")(assert))
12      (then (div-by 1 "b")(grind))))
13    (then (div-by 1 "a")(grind))))))
14 QED half_sq
```

## Interactive theorem prover

```
half_sq.1.1 :
{-1} b < b ^ 2
[-2] a < a ^ 2
[-3] a > 2
[-4] b > 2
|
[1] half(a, b) < half(a ^ 2, b ^ 2)

>> (expand "half")
```

- Ctrl+SPACE shows the full list of commands.
- TAB autocompletes commands. Double click expands definitions.

# Hybrid Programs in PVS

## Values of variables

```
Environment : TYPE = [nat->real]
%For example:
x: nat = 0
y: nat = 1
env: Environment = (LAMBDA(i:nat): 0)
  WITH [(x) := 10, (y) := -sqrt(5)]
```

## Assignments

```
Assigns      : TYPE = MapExprInj
ODEs         : TYPE = MapExprInj
%For example
exp_ex: ODEs
= (: (x, val(x)), (y, val(y)+cnst(1)) :)
```

## Functions on environments

```
%Predicates
BoolExpr     : TYPE = [Environment->bool]
%Quantified boolean expressions
QBoolExpr    : TYPE = [real->BoolExpr]
%Real-valued functions
RealExpr     : TYPE = [Environment->real]
%For example
val(i:nat): RealExpr
= LAMBDA(env:Environment): env(i)
```

# Hybrid Programs in PVS

## Syntax of hybrid programs

```
HP : DATATYPE
BEGIN
  IMPORTING hp_def
  ASSIGN(assigns:Assigns) : assign?
  DIFF(odes:ODEs,be:BoolExpr) : diff?
  TEST(be:BoolExpr) : test?
  SEQ(stm1,stm2:HP) : seq?
  UNION(stm1,stm2:HP) : union?
  STAR(stm:HP) : star?
END HP
```

## Semantics of hybrid programs

```
semantic_rel(hp:HP)(envi:Environment)
  (envo:Environment):
  INDUCTIVE bool = ...
```

## Semantics of `ASSIGN(l:MapExprInj)`

```
(FORALL (i:below(length(l))) :
LET (k,re) = nth(l,i) IN
envo(k) = re(envi)) AND
FORALL (i:(not_in_map(l))) :envo(i) = envi(i))
```

# Hybrid Programs in PVS

---

Recall:

$$x \geq 1 \wedge v \geq 0 \wedge a \geq 0 \vdash$$

$$\left[ \left( (a := a + 1); \{x' = v, v' = a\} \right)^* \right] (x \geq 1)$$

In PVS:

```
hp_ex: LEMMA
LET alpha = STAR(SEQ(ASSIGN( (: a, val(a) + cnst(1) :)),
DIFF( (: (x, val(v)), (v, val(a)) :) ))) IN
| (: :) |- (: DLIMPLIES( (: val(x) >= cnst(1),
val(v) >= cnst(0), val(a) >= cnst(0) :),
ALLRUNS(alpha, val(x) >= cnst(1))):)
```



# dL in PVS- Results

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- **Formal verification** of soundness of **dL**<sup>[11]</sup>
- **Fully operational** embedding **dL**
- **Extensions of dL in PVS**

---

[11] Previous Formal Verification of soundness of **dL** in Coq and Isabelle/Hol:

Brandon Bohrer, Vincent Rahli, Ivana Vukotic, Marcus Völp, and André Platzer. 2017. Formally verified differential dynamic logic.

In Proceedings of the 6th ACM SIGPLAN Conference on Certified Programs and Proofs.208–221. <https://doi.org/10.1145/3018610.3018616>

# Formal Verification of Soundness of *dL*

Loop rule:

```
dL_loop : LEMMA
  FORALL (Gamma,Delta)(J,P)(A):
    (Gamma |- cons(J,Delta)) AND
    (J |- P) AND
    (J |- ALLRUNS(A,J)) IMPLIES
    (Gamma |- cons(ALLRUNS(STAR(A),P),Delta))
```

Differential  
invariant  
rule:

```
dL_dI: LEMMA
  FORALL (P:(ddl_dom?))(Gamma,Delta)(nnP,Q)(ode:ODEs):
    derivable_up_nqbool?(max_var(ode),P)(nnP) AND
    ( cons(Q,Gamma) |- cons(nqb_to_be(nnP),Delta) ) AND
    ( Q |- SUB_DIFT(P,ode)(nnP) ) IMPLIES
    ( Gamma |-
      cons(ALLRUNS(DIFF(ode,DLAND(P,Q)),nqb_to_be(nnP)),Delta) )
```

81 proven rules/axioms of *dL* in PVS

# Fully Operational Embedding of **dL**

- Proof rules implemented as strategies in PVS
  - Fully operational **dL** within interactive prover console of PVS

```
discrete_loop_ex :
```

```
{1}  ┌
      (: val(x) >= cnst(1), val(v) >= cnst(0), val(a) >= cnst(0) :) |-
      (: ALLRUNS(STAR(SEQ(ASSIGN(: (a, val(a) + cnst(1)) :)),
                        DIFF(: (x, val(v)), (v, val(a)) :),
                        DLBOOL(TRUE))))),
      val(x) >= cnst(1)) :)
```

```
>> (dl-loop "val(x) >= cnst(1) AND val(v) >= cnst(0) AND val(a) >=cnst(0)")
```

# Fully Operational Embedding of **dL**

- Proof rules implemented as strategies in PVS
  - Fully operational **dL** within interactive prover console of PVS

```
discrete_loop_ex.1 :
```

```
┌  
{1}  ((: val(x) >= cnst(1), val(v) >= cnst(0), val(a) >= cnst(0) :) |-  
      (: DLAND(val(x) >= cnst(1),  
              DLAND(val(v) >= cnst(0), val(a) >= cnst(0))) :))
```

```
>> ((dl-assert)
```

# Fully Operational Embedding of **dL**

---

- Proof rules implemented as strategies in PVS
  - Fully operational **dL** within interactive prover console of PVS

```
discrete_loop_ex.2 :
```

```
┌  
{1}  ((: DLAND(val(x) >= cnst(1),  
            DLAND(val(v) >= cnst(0), val(a) >= cnst(0))) :)  
      |- (: val(x) >= cnst(1) :))
```

```
>> (dl-assert)
```

# Fully Operational Embedding of **dL**

- Proof rules implemented as strategies in PVS
  - Fully operational **dL** within interactive prover console of PVS

```
discrete_loop_ex.3 :
```

```
┌───  
{1} ((: DLAND(val(x) >= cnst(1),  
          DLAND(val(v) >= cnst(0), val(a) >= cnst(0))) :)  
    └─  
      (: ALLRUNS(SEQ(ASSIGN((: (a, val(a) + cnst(1)) :)),  
                  DIFF((: (x, val(v)), (v, val(a)) :), DLB00L(TRUE))),  
        DLAND(val(x) >= cnst(1),  
              DLAND(val(v) >= cnst(0), val(a) >= cnst(0)))) :))
```

```
>> █
```

# Fully Operational Embedding of **dL**

---

- Proof rules implemented as strategies in PVS
  - Fully operational **dL** within interactive prover console of PVS

```
diff_inv_ex :
```

```
┌  
{1} ((: val(x) >= cnst(1), val(a) >= cnst(0) :) |-  
      (: ALLRUNS(DIFF((: (x, val(v)), (v, val(a)) :), val(v) >= cnst(0)),  
                val(x) >= cnst(1)) :))
```

```
>> (dl-diffinv)
```

# Fully Operational Embedding of **dL**

---

- Proof rules implemented as strategies in PVS
  - Fully operational **dL** within interactive prover console of PVS

```
diff_inv_ex.1 :
```

```
┌  
{1} ((: val(v) >= cnst(0), (val(x) >= cnst(1)), val(a) >= cnst(0) :) |-  
      (: (val(x) >= cnst(1)) :))
```

```
>> (dl-assert)
```



# Fully Operational Embedding of **dL**

---

- Proof rules implemented as strategies in PVS
  - Fully operational **dL** within interactive prover console of PVS

```
diff_inv_ex.2 :
```

```
  |-----  
{1}  ((: val(v) >= cnst(0) :) |- (: val(v) >= cnst(0) :))
```

```
>> (dl-assert)
```

```
Q.E.D. █
```

# dL in PVS – Generalized Reasoning of Hybrid Programs

- **Fully typed** specification of hybrid programs
  - Reasoning at the type level (properties of groups of hybrid programs)
  - Reasoning for arbitrary hybrid programs (e.g., arbitrarily many variables)

```
behind: TYPE
= {hp: (diff?) |
  | (: behind?(odes(hp)) :) |- (: ALLRUNS(hp,behind?(odes(hp))) :)}

slow: TYPE
= {hp: (diff?) |
  | (: :) |- (: slower?(odes(hp)) :)}
```

- A hybrid program of type **slow** is always of type **behind**

```
slow_is_behind: JUDGEMENT
| slow SUBTYPE_OF behind
```

# Summary

- **dL**: Differential Dynamic Logic for hybrid programs
- **PVS**: Interactive theorem prover

## Result: Embedding of dL in PVS

- Formal verification **dL** (done)
- Fully operational in **PVS** (close)
- Leveraging features of **PVS** to extend **dL** (ongoing)

