

# A Partitioned - Task Parallel Implementation of the NASA Multiscale Analysis Tool for High Performance Computing

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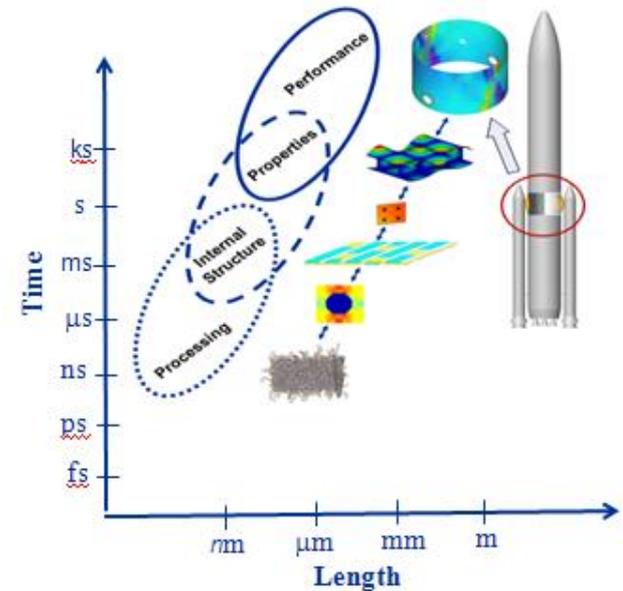
2022 American Society for Composites Conference,  
September 19-21, 2022, Tucson, Arizona

# Introduction

- Massively multiscale modeling often constrained by scalability issues
- Real engineering problems with multiscale models are still computationally infeasible
- NASA Vision 2040 recognizes following gaps under Key Element 9: Computational Infrastructure
  - Scalability and Computational Efficiency
  - Linkage and Integration
- Multiple scales and their interdependence (hierarchical task dependence) poses additional restrictions in terms of implementation
  - Efficient parallelization of hierarchical tasks still an open problem in computer science

# NASA Multiscale Analysis Tool (NASMAT)

- Successor to MAC/GMC and FEAMAC toolsets
- Designed to support massively multiscale modeling (M3) on high-performance computing (HPC) systems
  - Solves real, large-scale, non-linear, thermo-mechanical problems
- Modular design to support “plug-and-play” capabilities
  - Operational components categorized into NASMAT procedures
- Developed for enhanced interoperability
  - Integrates with 3<sup>rd</sup> party structural analysis codes (e.g., FEA)
  - Library of constitutive laws/damage models
  - Data output in HDF5 file format
- Ideal for “design with” or “design of” the material
  - Enables Integrated Computational Materials Engineering (ICME)
  - Developed to support NASA Vision 2040

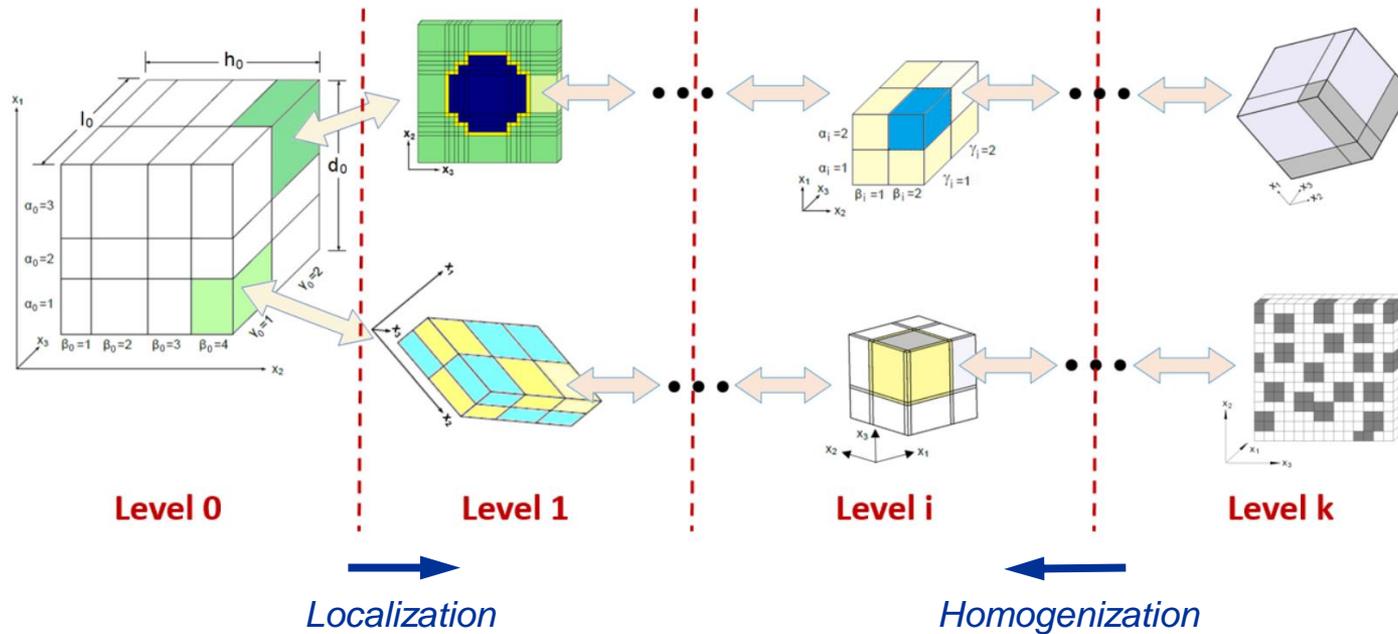


**Multiscale  
localization/homogenization**

Liu, Xuan, et al. *Vision 2040: a roadmap for integrated, multiscale modeling and simulation of materials and systems*. NASA/CR-2018-219771.

# Multiscale Recursive Micromechanics (MsRM)

- Suite of micromechanics theories available
- Recursive in nature
- Arbitrary number of scales

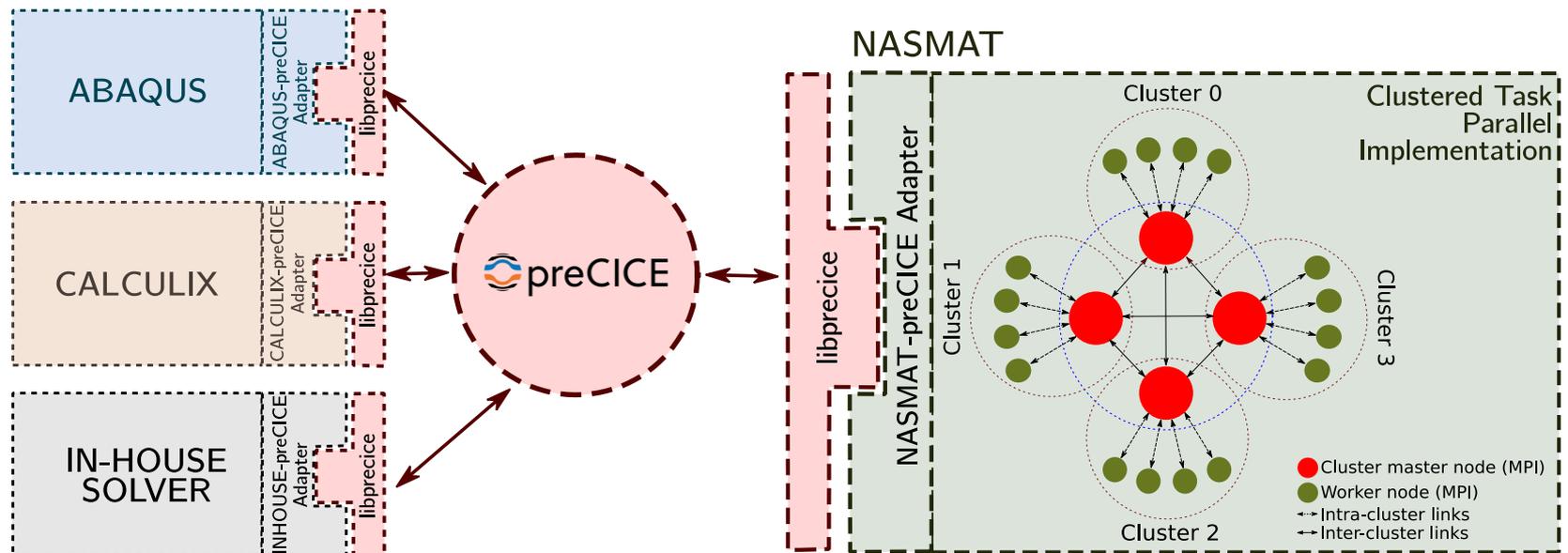


# Current Challenges and Shortcoming

- Undertaking massively multiscale modeling still a challenge in terms of computational feasibility
- Conventional Monolithic approach (UMAT-like)
  - Heavily constrained by architecture of macro solver
  - Limits parallelization opportunities (not more than 1 core/thread available)
  - Introduce macro solver specific changes
  - Disparate resource management (reduced parallelization efficiency)
- Adapting to heterogenous high performance computing system (CPU/GPU, multi core/threads etc.)

# Solution

- A partitioned task-parallel architecture is proposed
- Task-parallel architecture - internal NASMAT parallelization
- Partitioned architecture – external integration with macro solver
- Modular and scalable architecture

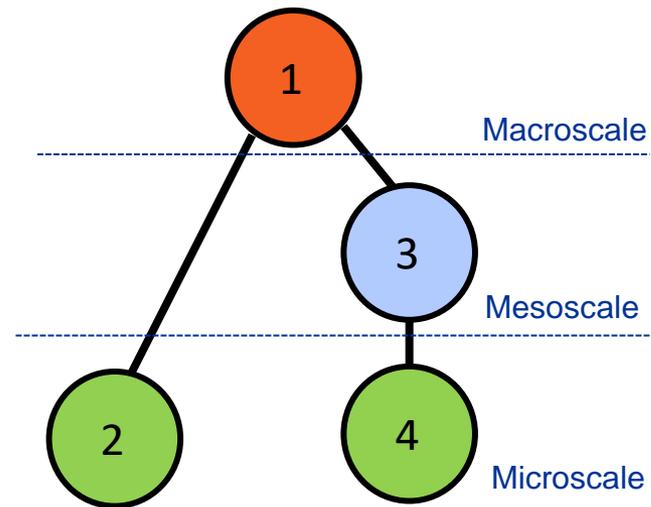
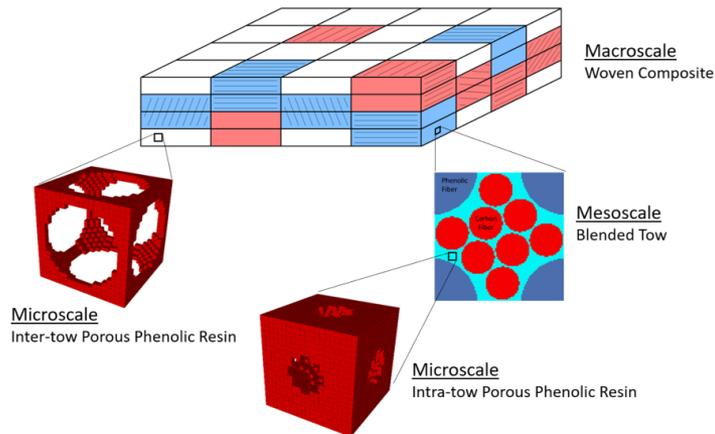


Planas, J., et al., (2009). Hierarchical Task-Based Programming With Starss. The International Journal of High Performance Computing Applications, 23(3), 284–299. <https://doi.org/10.1177/1094342009106195>

# NASMAT 'Task-Parallel' Architecture

## Task-Parallel

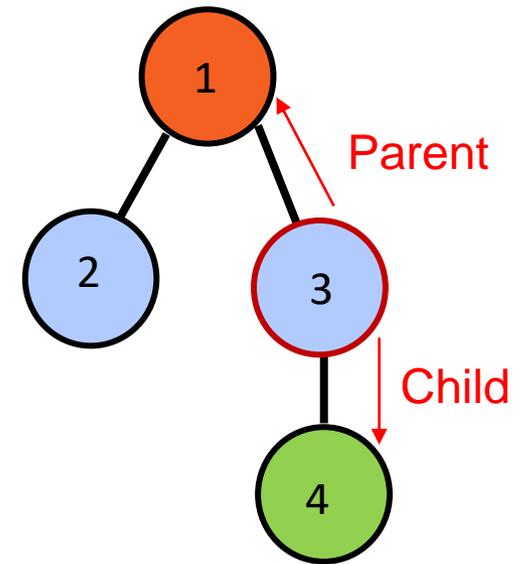
- Corresponds to the parallelization scheme adopted within NASMAT
- Abstracted definition of Task - refers to a *homogenization/localization* call
- Multiscale RUC architecture is defined as a tree



Example Tree for 3 scale system (Only unique RUCs represented)

# NASMAT 'Task-Parallel' Architecture

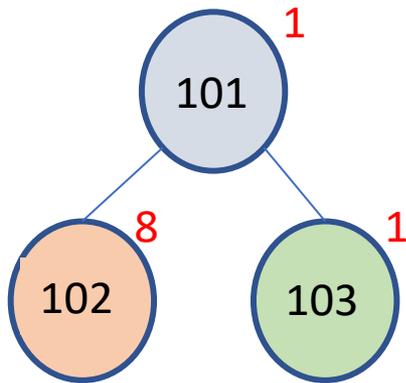
- Each RUC tree is decomposed into Nodes
- Parent-Child relationships are established between *Nodes*
  - Ex: *Node3* : Parent-*Node1*, Child-*Node4*
  - Each Node may have multiple children
- Different Master-Worker based parallelization is adopted to undertake homogenization/localization task
  - MPI based
  - OpenMP based
- Looping order decided based on type of task (Homogenization/Localization)



Example Tree

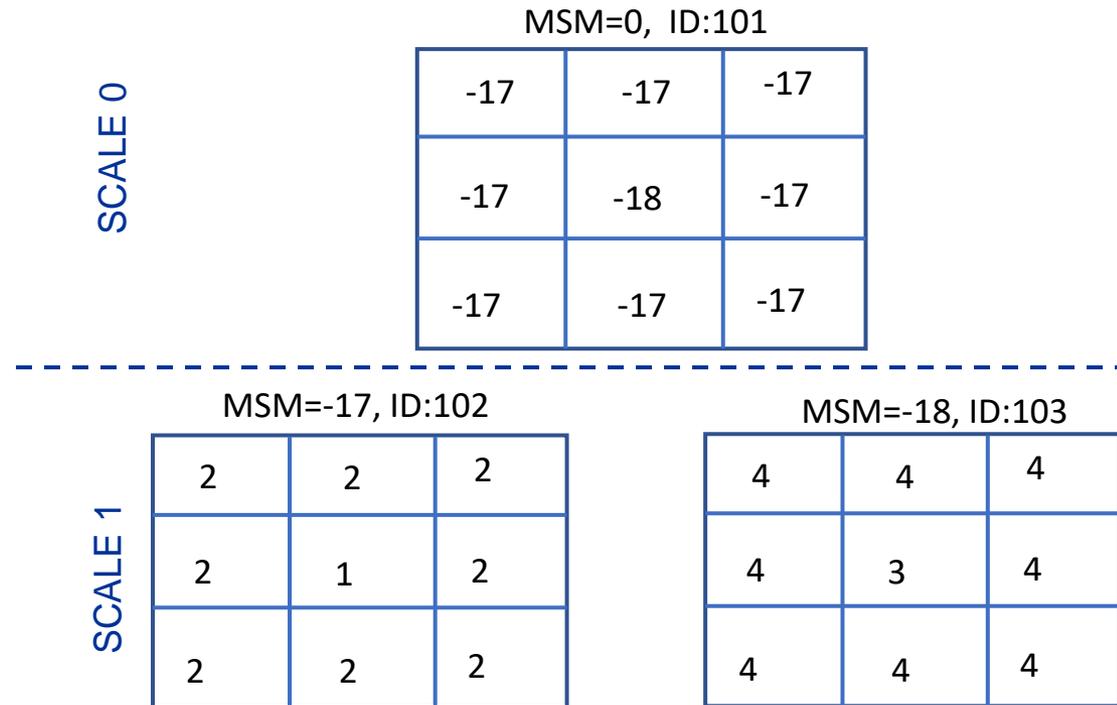
# NASMAT 'Task-Parallel' Architecture: Algorithm

- Example: RUC tree with 2 scales with 9 subcell each



Tree Diagram: Runtime

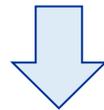
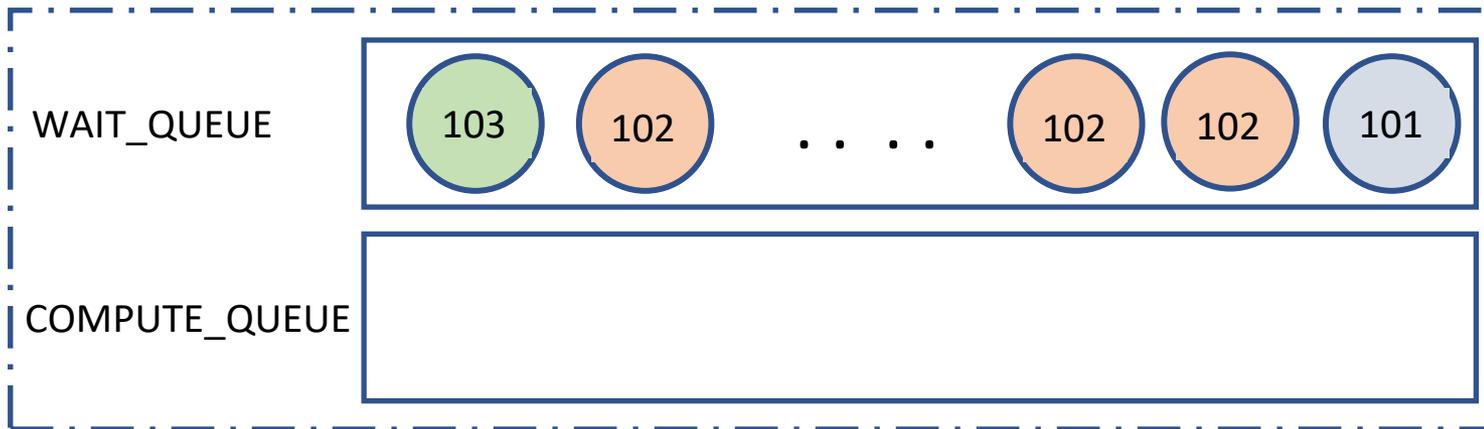
Total tasks: 10



Positive material Tags: Constitutive models  
 Negative material Tags: RUC

# NASMAT 'Task-Parallel' Architecture: Algorithm

## Initialization



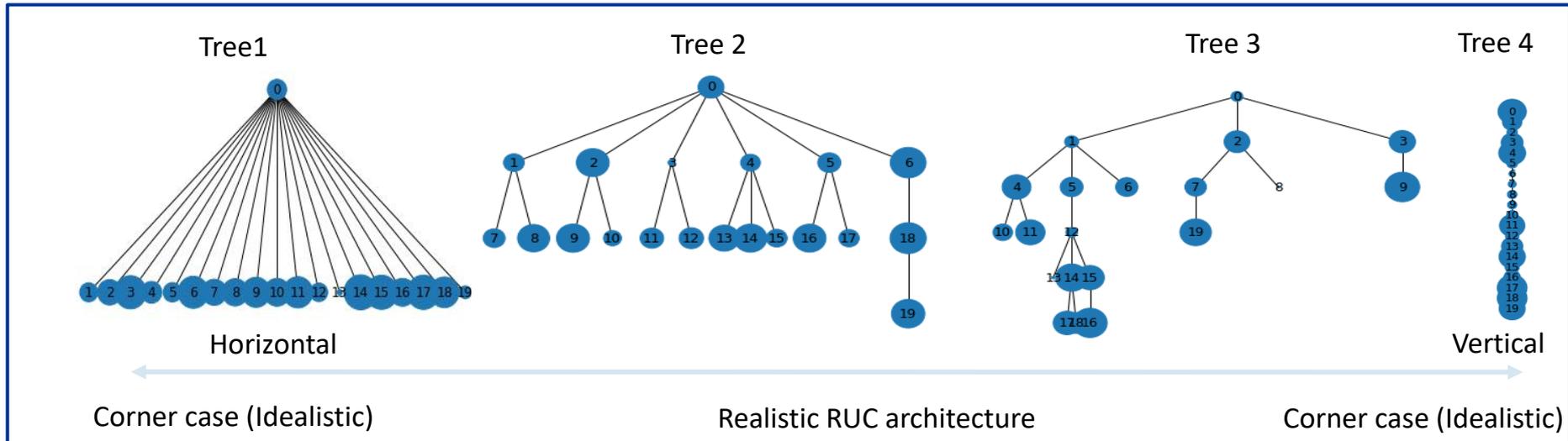
ALL RUCs that has no child or all child already homogenized added to COMPUTE\_QUEUE. Continues until WAIT\_QUEUE is empty

## Runtime



# Comparison of two different scheme for Homogenization Task

- Parallelization scheme
  - Tree Level
    - Each RUC associated with a macro GP is given “n” CPUs
  - Accumulated Tree scheme
    - All nodes from all macro GP are accumulated and distributed parallelization is undertaken with “n” CPUs

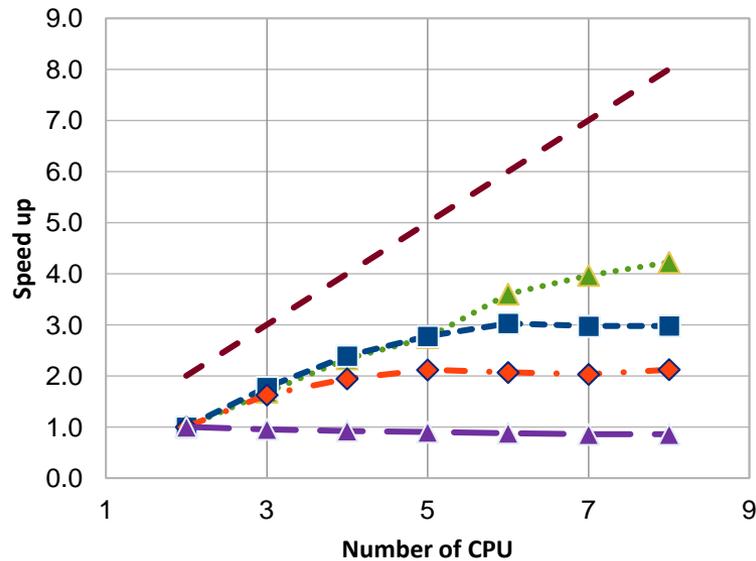


Each tree contains 20 nodes with DOF varying from 100-100K ((equivalent unit cell distribution) with 100 macro GP

# Comparison of two different scheme for Homogenization Task: Results

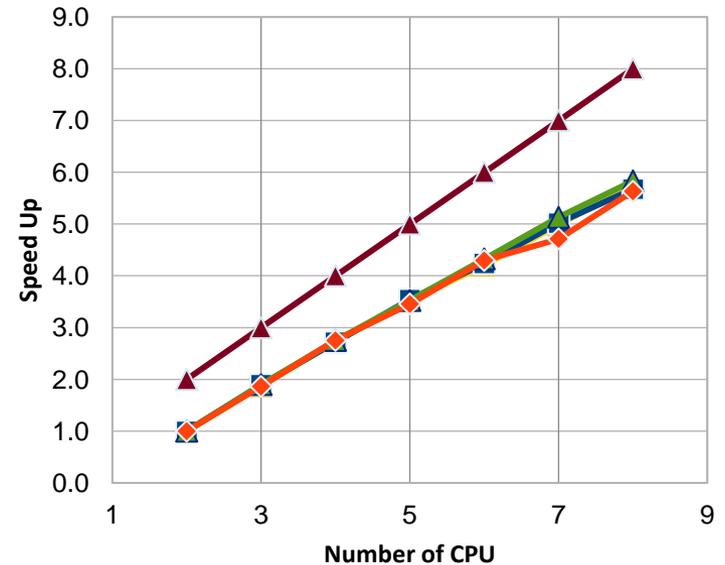
Micromechanics model: GMC 2D – Linear Elastic Homogenization

### Tree-level



— Ideal —•— Tree1 —■— Tree2 —◇— Tree3 —▲— Tree4

### Accumulated Tree-level

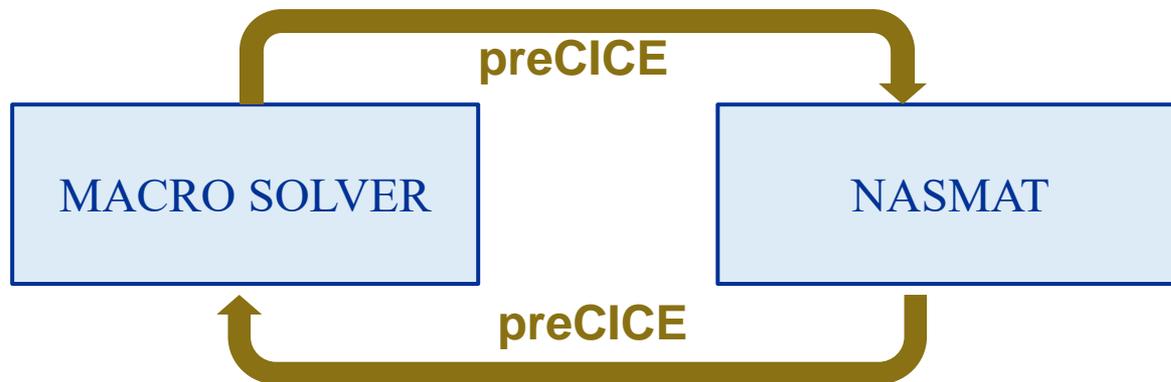


—▲— Ideal —▲— Tree1 —■— Tree2 —▲— Tree3 —◇— Tree4

- Scaling is RUC architecture independent for Accumulated Tree-Level scheme

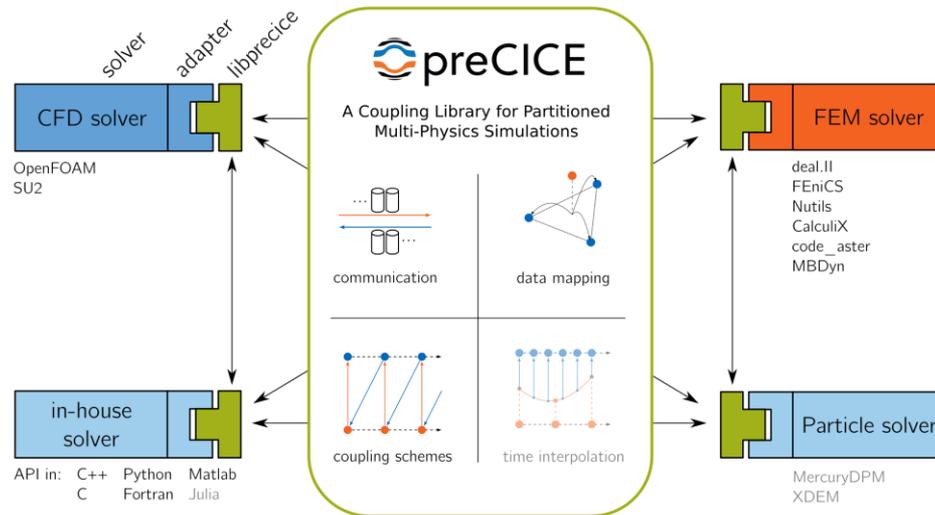
# NASMAT 'Partitioned' Architecture

- Corresponds to the way NASMAT interacts with macro solver
- FSI (Fluid Structure Interaction)-like modeling approach
- Two separate processes are used for macro and multiscale solvers (Staggered scheme) – communication protocol established between the two processes
- Architecture and implementation are macro-solver independent
- Implemented using **preCICE** (open-source coupling library)



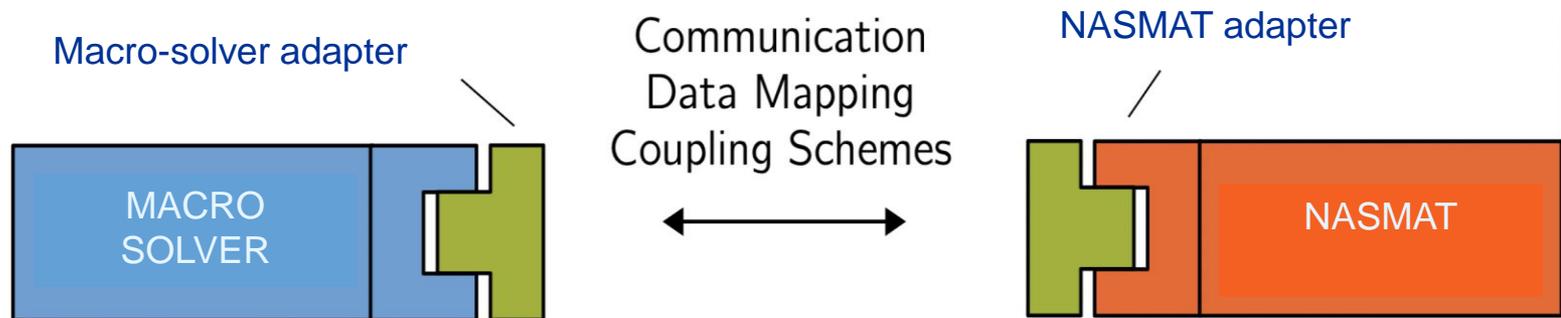
# preCICE: Precise Code Interaction Coupling Environment

- Couples existing programs (solvers) which simulate a subpart of the complete physics involved in a simulation
- Open-source library
- High-level API calls – Multiple language support
- Minimally invasive integration
- Developed at University of Stuttgart and Technical University of Munich



Chourdakis G, *et al.* preCICE v2: A sustainable and user-friendly coupling library Open Res Europe 2022, 2:51

# NASMAT-preCICE Integration



## Macro Solver:

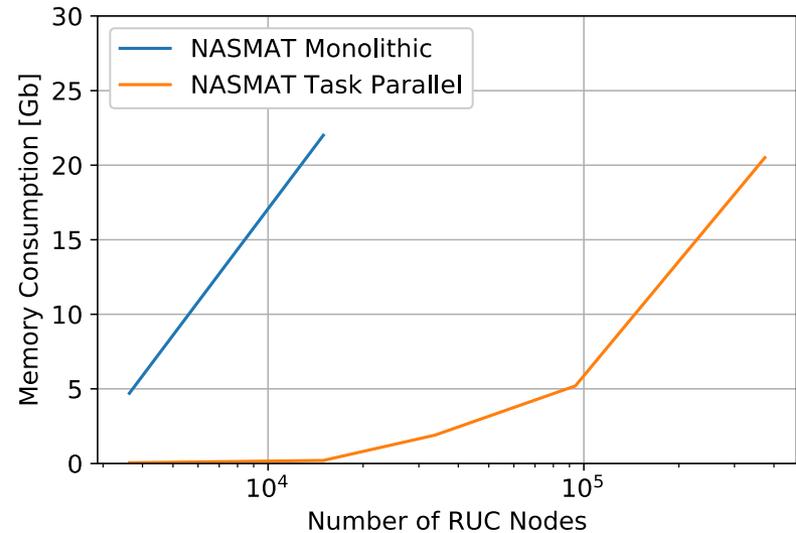
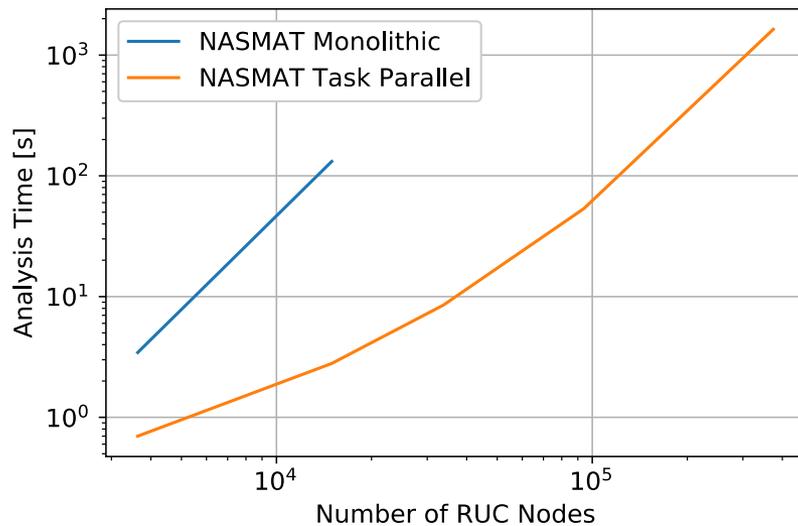
1. Macro solver can be written in any language supported by preCICE API
2. preCICE adapter for Calculix is readily available

## NASMAT

1. preCICE adapter for NASMAT is implemented
2. preCICE adapter calls NASMAT libraries – no changes to original codebase

# Comparison of NASMAT Monolithic vs NASMAT Task Parallel

Homogenization task for GMC 2D with an RUC with 3 levels



- Significant improvement in terms of analysis time and memory requirement [ $\sim 1$  order of magnitude] for GMC2D models

# Summary and Conclusions

- NASMAT Partitioned Task-Parallel architecture addresses the scalability and integration associated with massively multiscale modeling architectures
- Macro-solver integration of NASMAT through preCICE, an open source coupling library allows for easy integration of NASMAT to any third-party external library
- Task-based parallelization of homogenization/localization calls allows for various shades of parallelization
- In comparison to previous iteration of NASMAT, the proposed architecture shows significant ( $\sim 1$  order of magnitude) reduction in analysis time and memory requirement

# Future Work

- Extending task parallel implementation to HFGMC micromechanics models within NASMAT
- Improving memory efficiency of task parallel implementation using shared memory within MPI
- Building preCICE adapter for ABAQUS

# Acknowledgements

- Primary NASMAT development has been supported through the NASA Aeronautics Research Mission Directorate's (ARMD's) Transformational Tools and Technologies (TTT) Project.
- Ibrahim Kaleel's research was supported by an appointment to the NASA Postdoctoral Program at the NASA Glenn Research Center, administered by Oak Ridge Associated Universities under contract with NASA.



***Thank You For Your Attention***



# Extra Slides

# Task Parallel Flowchart

