

RECENT DEVELOPMENTS IN BOUNDARY COUPLING FOR HYPERBOLICALLY GENERATED OVERSET GRIDS

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Solution Technology, Suffolk, VA, Nov 1-3, 2022

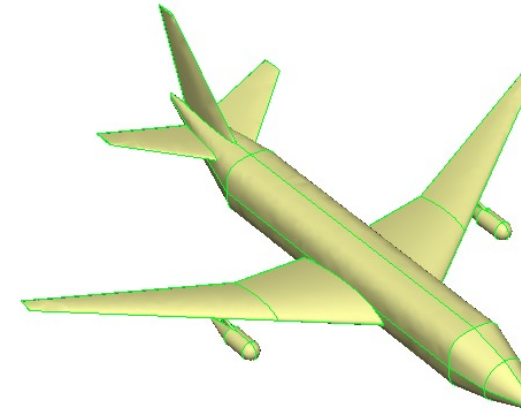
INTRODUCTION



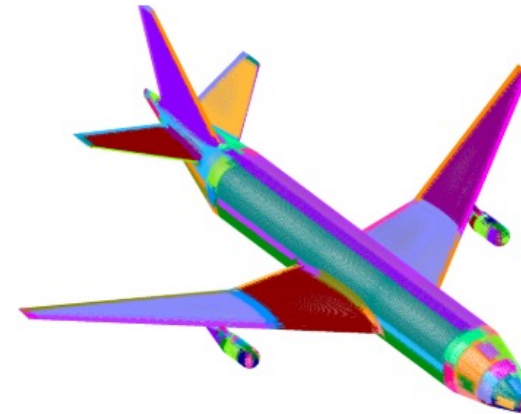
- Overview of Automatic Grid Generation
- Loosely Coupled Boundary Conditions (LCBC)
 - Surface Mesh Coupling
 - Volume Mesh Coupling
 - Face Mesh Reconstruction
- Investigation of Solution Runs with Automatic Meshes
- Concluding Remarks

AUTOMATIC OVERSET MESH GENERATION (1)

- Structured overset mesh generation is an exceedingly tedious task
- Recent advances made in automation [1,2]
- Surface mesh generated for each face, edge, node of Boundary Representation (BRep) solid
- Significant reduction in time and effort (~weeks/days to ~days/hours)



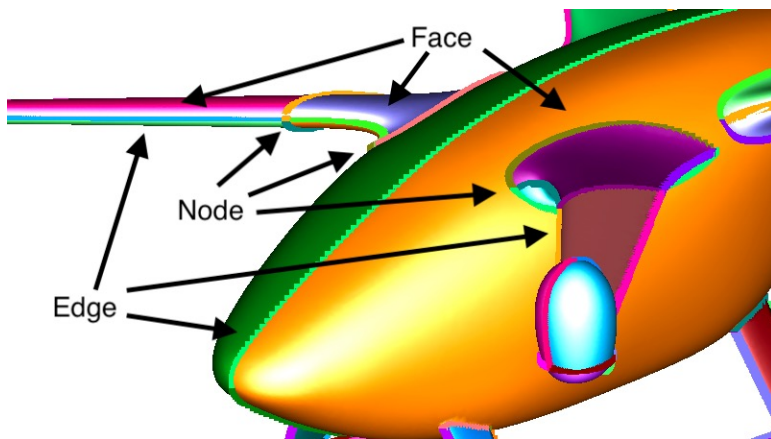
**BRep solid of
generic airplane**



**Auto generated
surface mesh of
airplane**

1. Chan, W. M., Pandya, S. A., and Haines, R., “Automation of Overset Structured Surface Mesh Generation on Complex Geometries”, AIAA Paper 2019-3671, June 2019. <https://doi.org/10.2514/6.2019-3671>.
2. Chan, W. M., Pandya, S. A., & Chuen, A. M., “Automation of Overset Structured Mesh Generation on Boundary Representation Geometries”, AIAA Paper 2022-3607, June 2022. <https://doi.org/10.2514/6.2022-3607>.

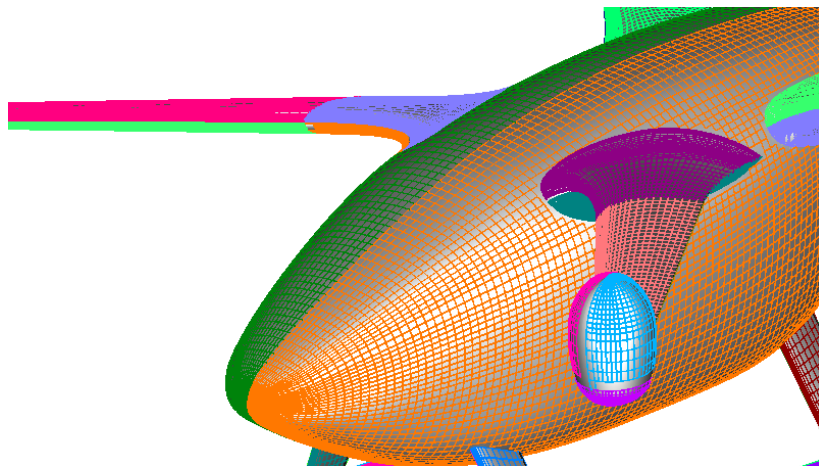
AUTOMATIC OVERSET MESH GENERATION (2)



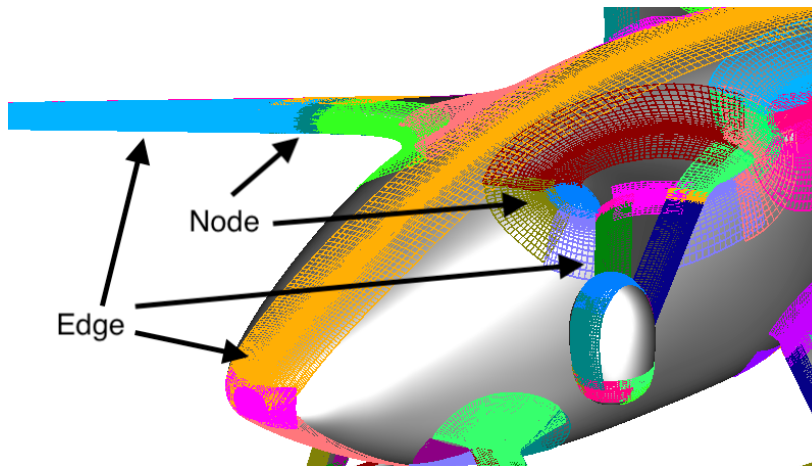
BRep Faces, Edges, Nodes

Surface
Domain
Decomposition

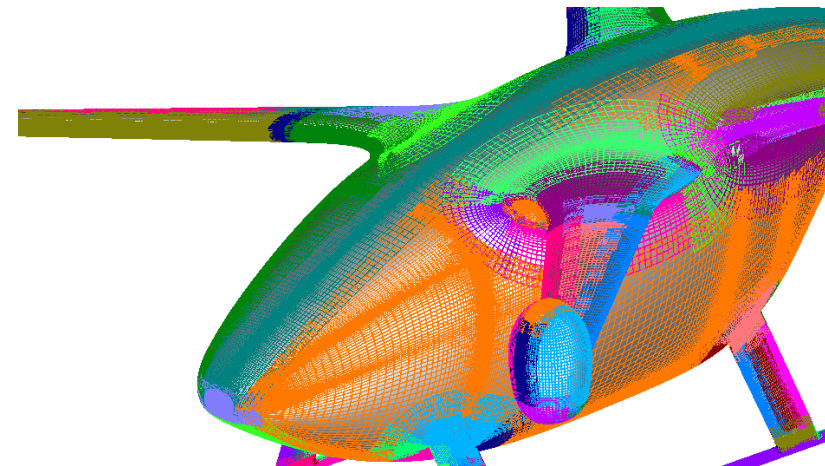
Surface
Mesh
Generation



Face Meshes

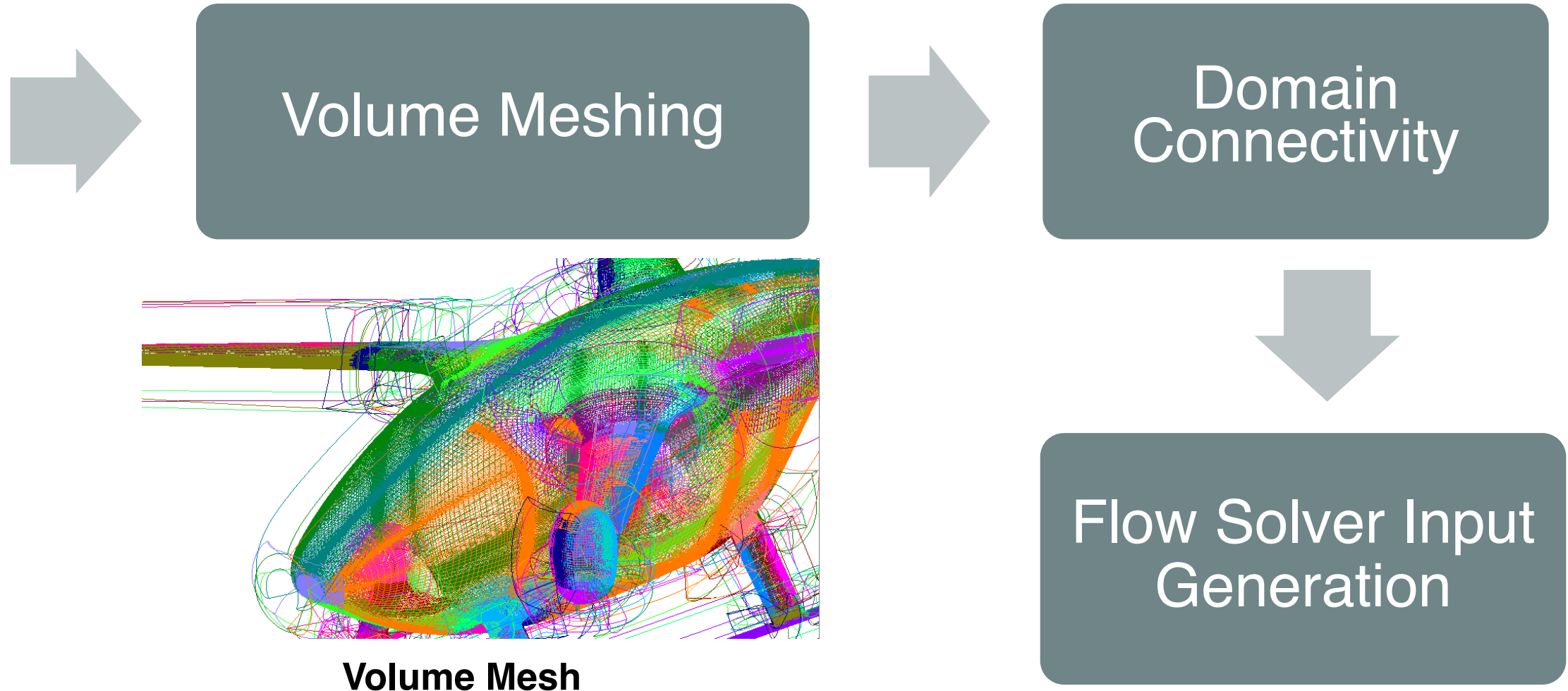


Edge & Node Meshes

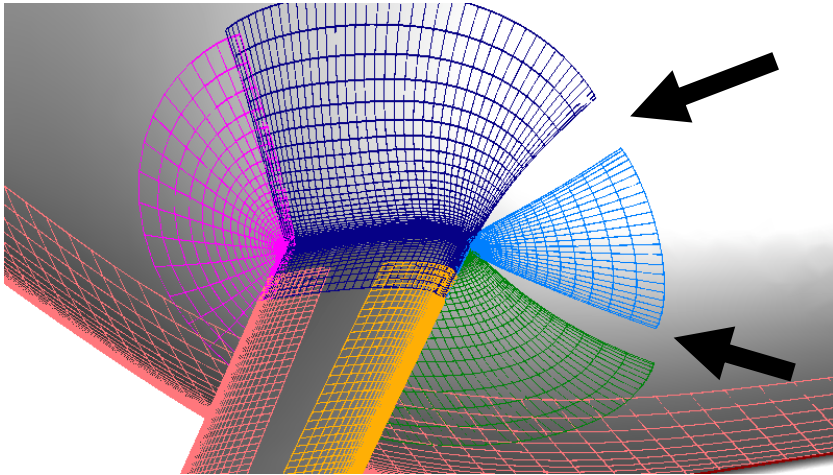


Surface Mesh

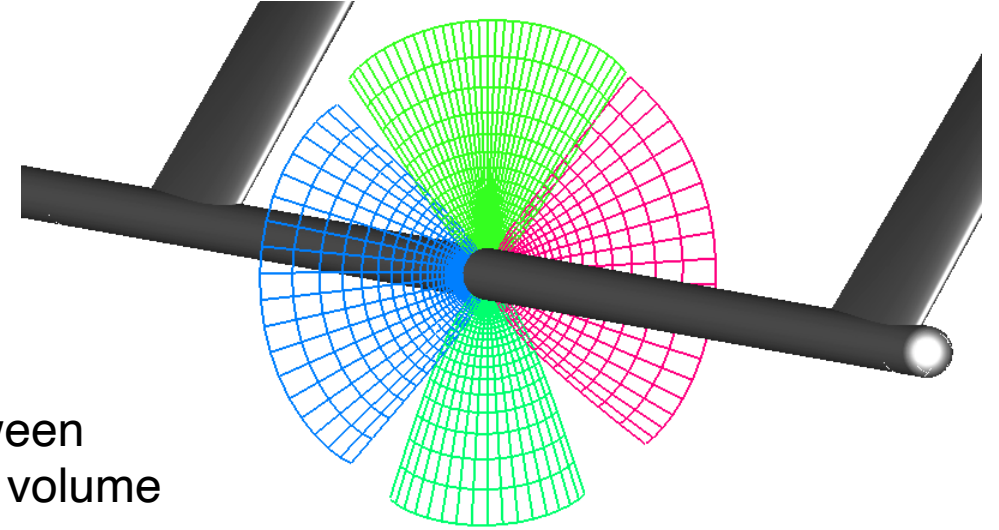
AUTOMATIC OVERSET MESH GENERATION (3)



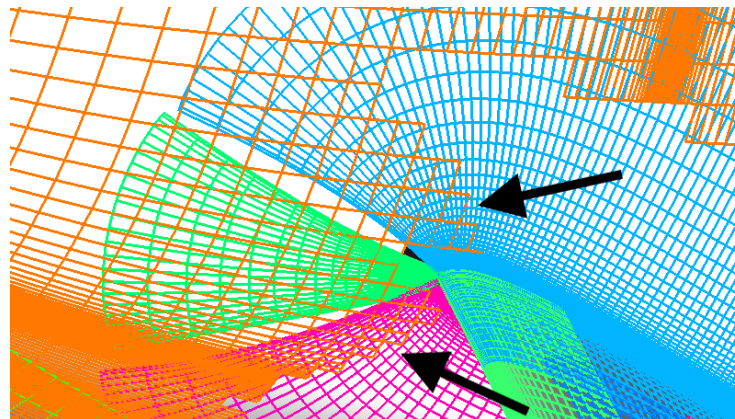
OVERLAP ISSUES IN HYPERBOLIC SURFACE & NEAR-BODY VOLUME MESHES



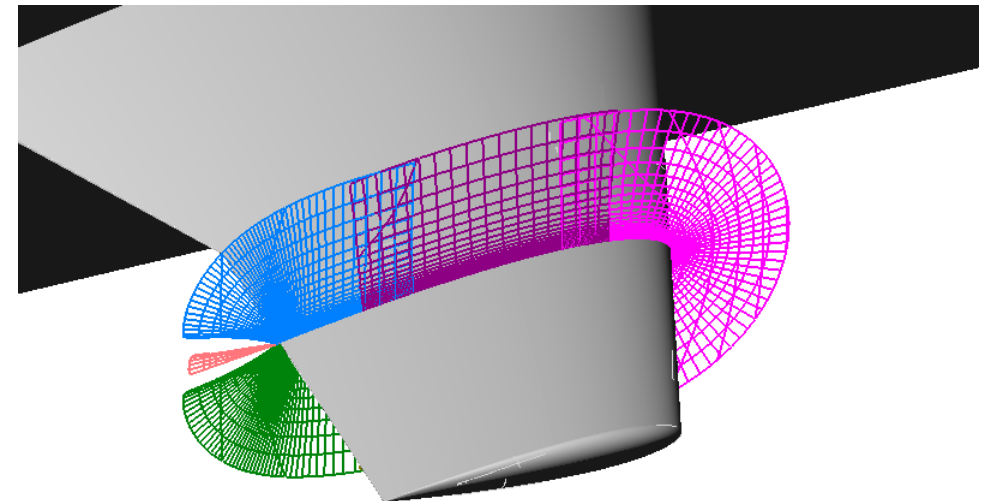
Gaps from splay between hyperbolic collar meshes with overlapping initial curves



Gaps between hyperbolic volume meshes

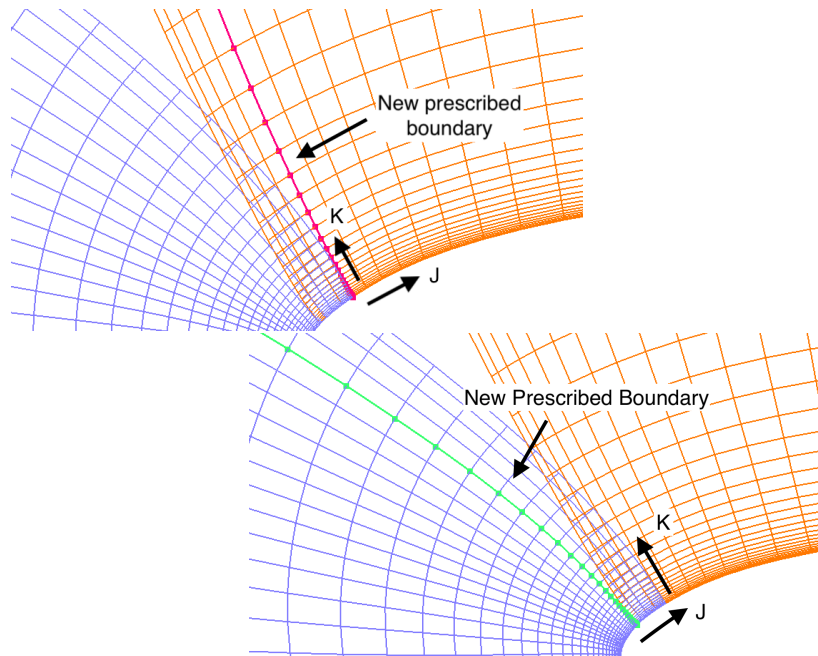


Face mesh (orange) filling in gaps between collar meshes

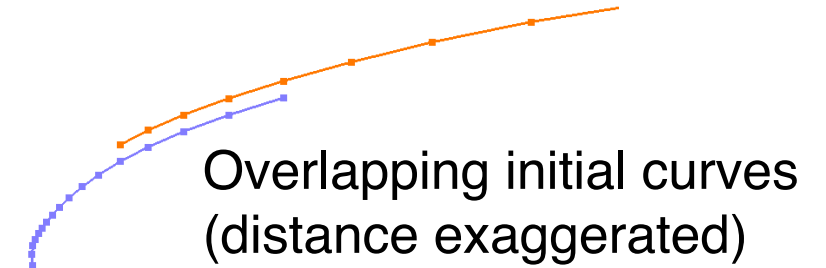
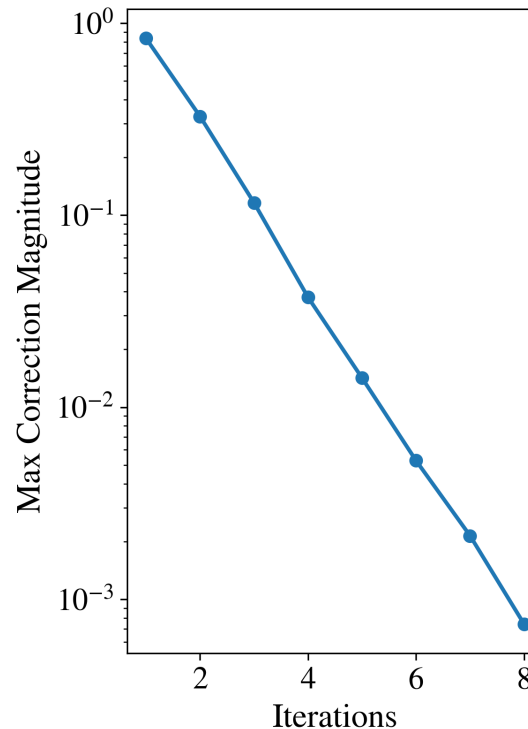


LOOSELY COUPLED BOUNDARY CONDITIONS

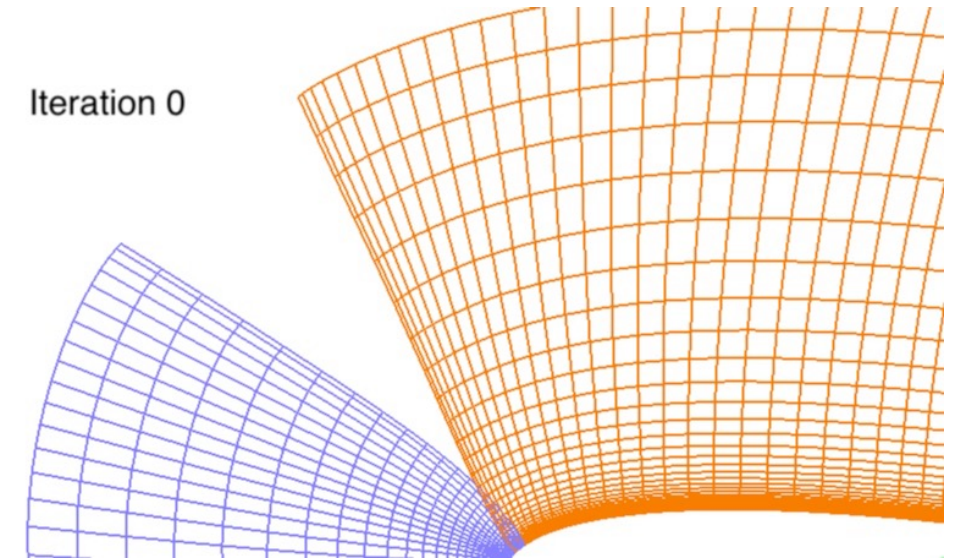
- Hyperbolic grids coupled to neighbors through forced boundaries along marching direction
- Boundaries follow internal grid line of neighbors



Magenta/green boundary curve extracted for blue/orange mesh



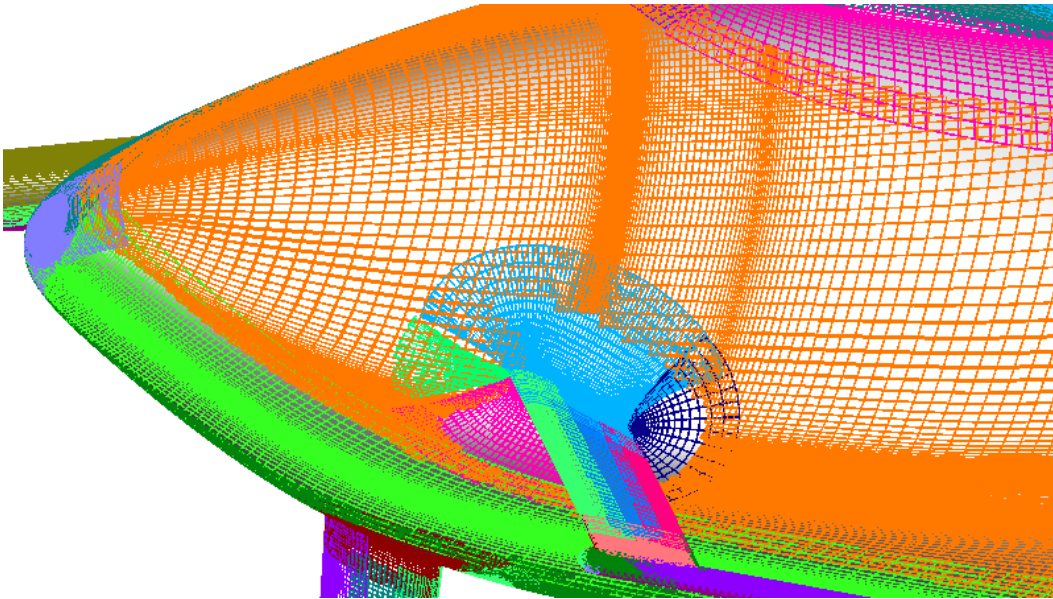
Iteration 0



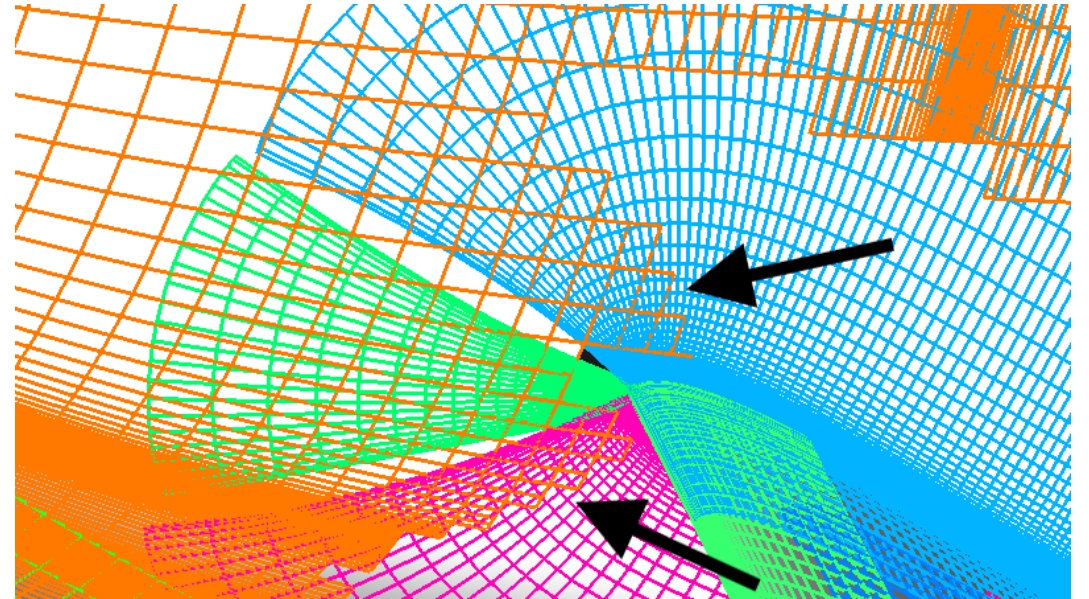
5 pt overlap maintained across marching direction at final iteration

3. Chuen, A. M., & Chan, W. M., "Overlap Preservation Using Loosely-Coupled Boundary Conditions for Body-Fitted Structured Overset Grids", AIAA 2022-0216, January 2022. <https://doi.org/10.2514/6.2022-0216>

6-PAX QUAD SURFACE MESH – WITHOUT LCBC

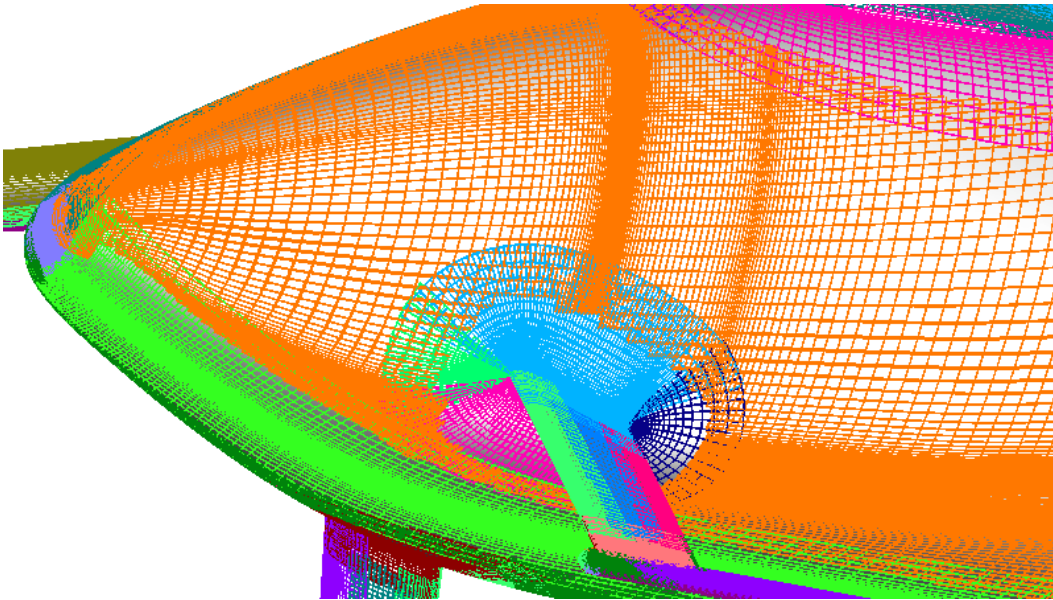


**Hyperbolic meshes generated
around strut-body junction**

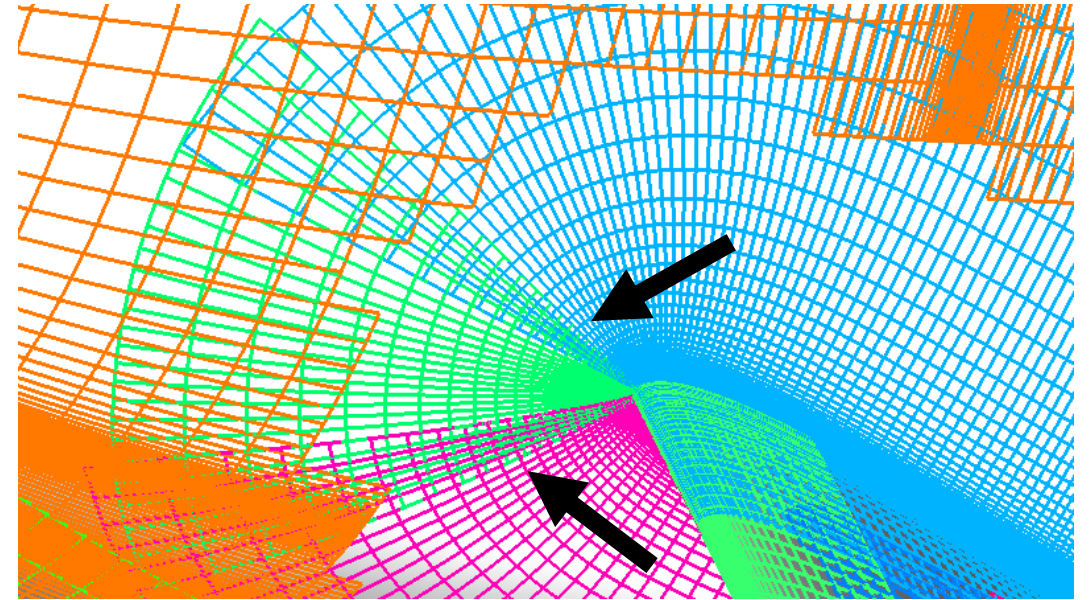


**Coarser face meshes forced into
gap between hyperbolic meshes**

6-PAX QUAD SURFACE MESH – WITH LCBC



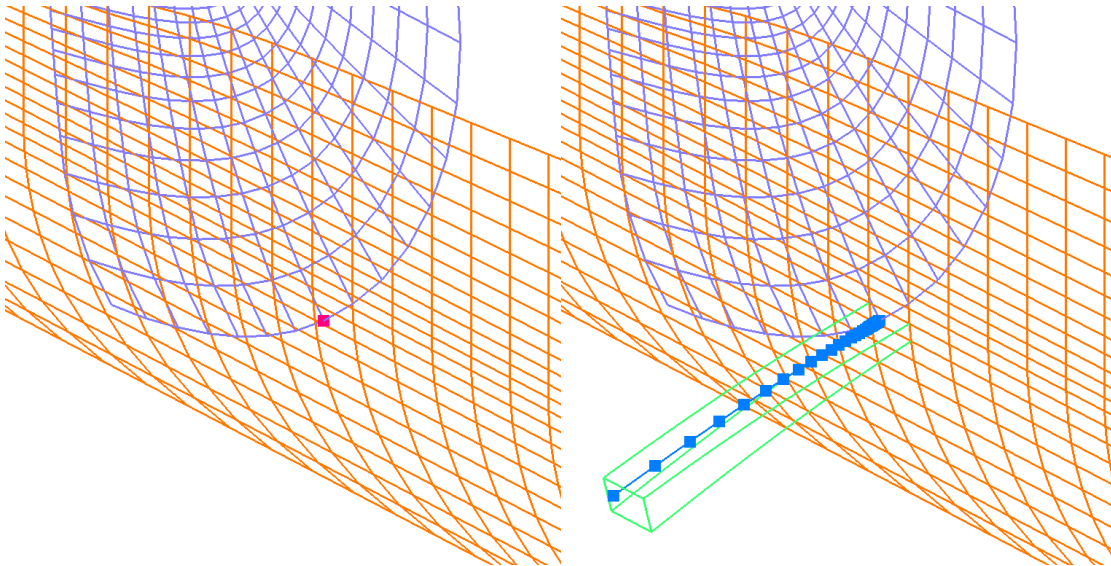
**Hyperbolic meshes generated
around strut-body junction**



**Coarser face meshes can be
retracted from overlap region**

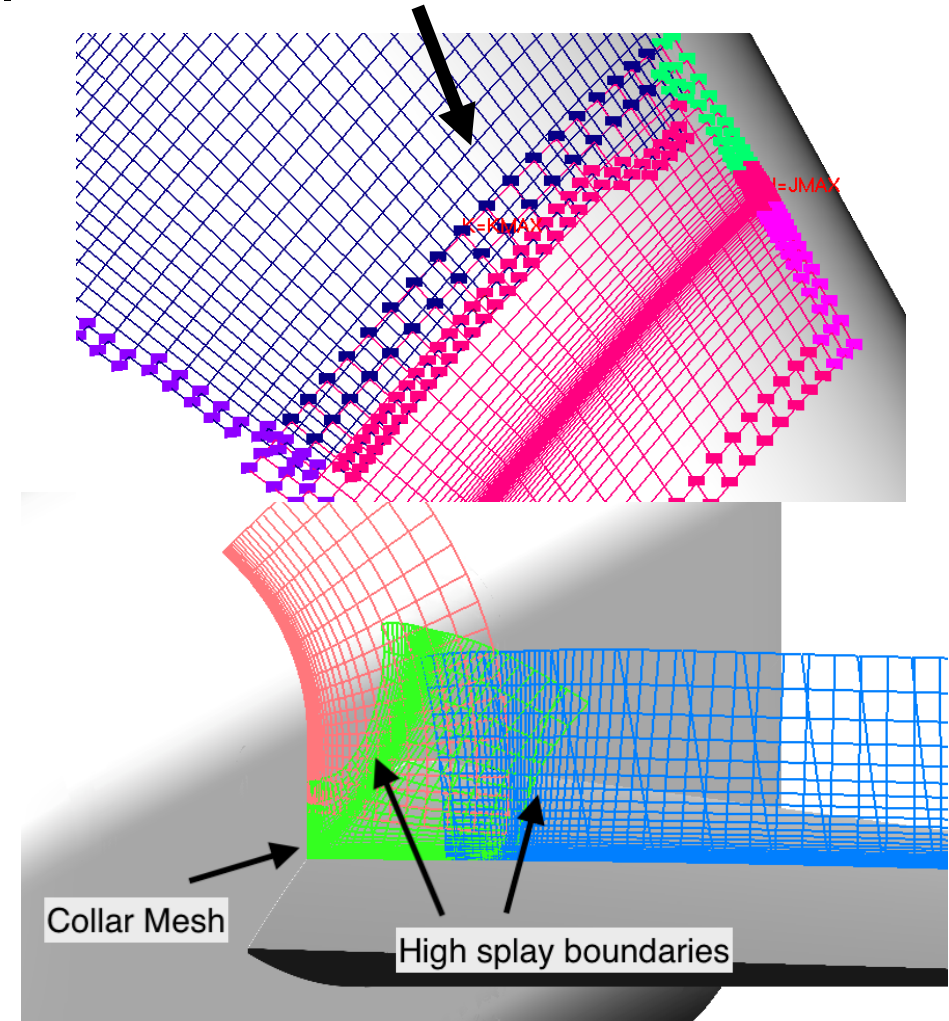
LCBC FOR VOLUME MESH GENERATION

- Increased complexity due to additional deg. of freedom & overlap w/ multiple grids
- Requires surface domain connectivity
- Collar meshes are excluded from LCBC



Boundary curve from orange mesh applied to blue mesh fringe-point boundary

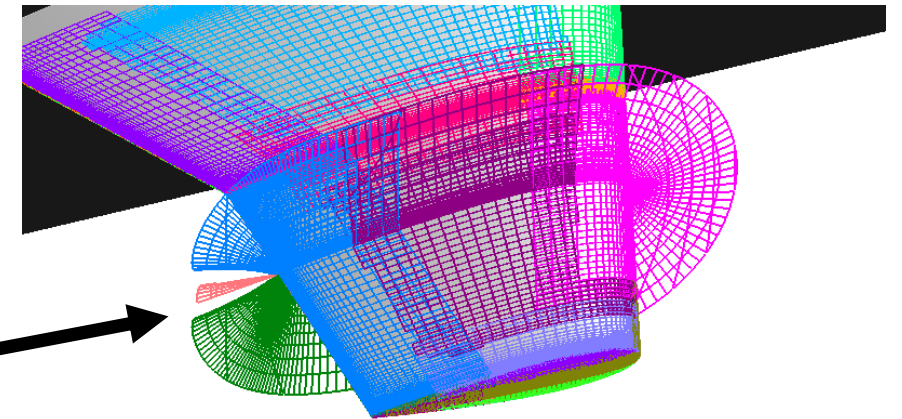
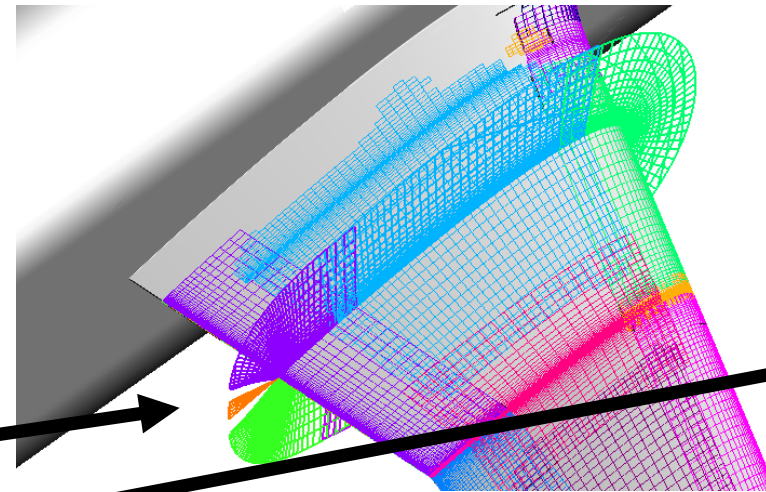
Coupling occurs at all four boundaries of initial surface



JUNCTURE FLOW MODEL WING – WITHOUT LCBC

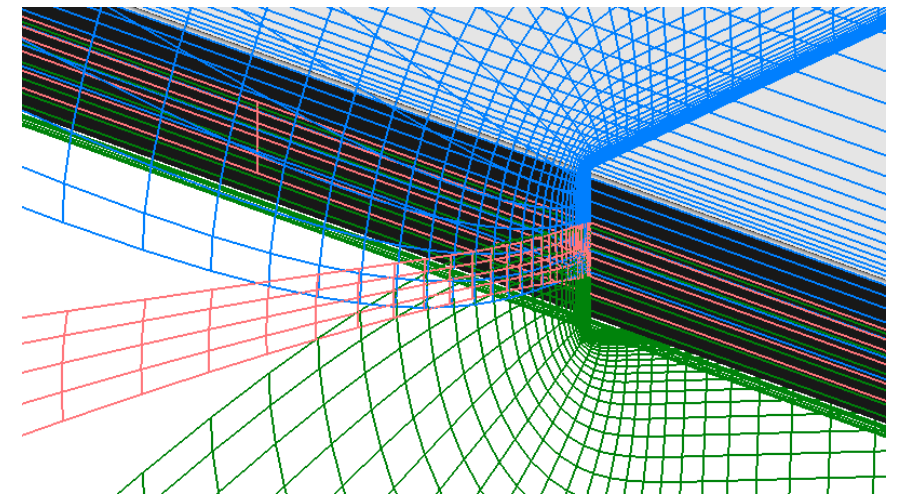
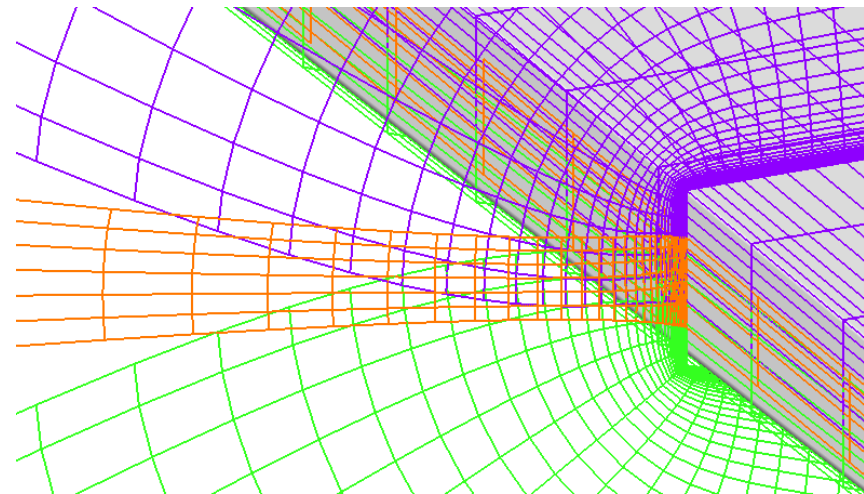
$Y = 550$

$Y = 1150$



Large gaps develop in
trailing edge wake

Mesh divergence occurs
near-wall in wake

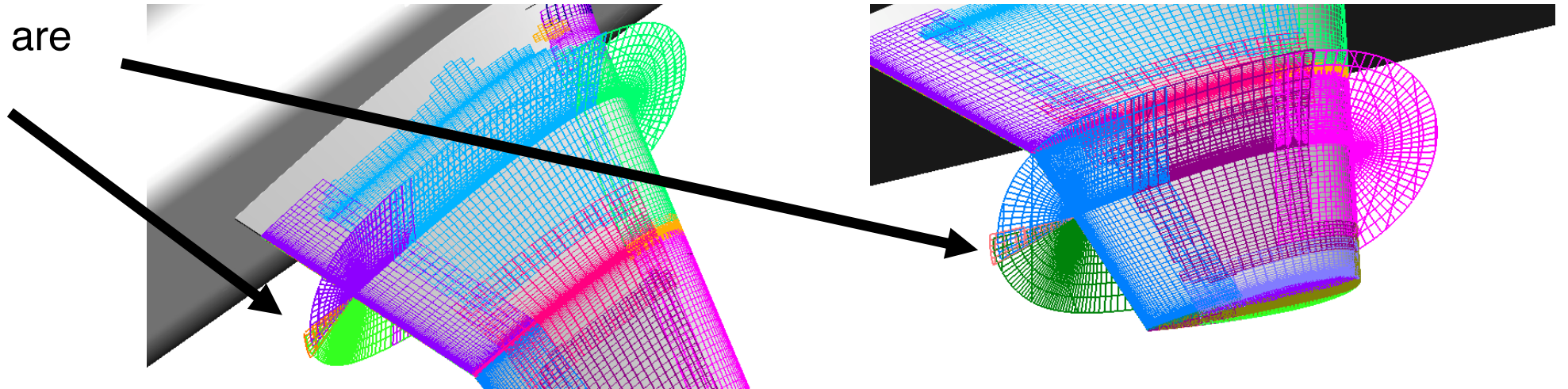


JUNCTURE FLOW MODEL WING – WITH LCBC

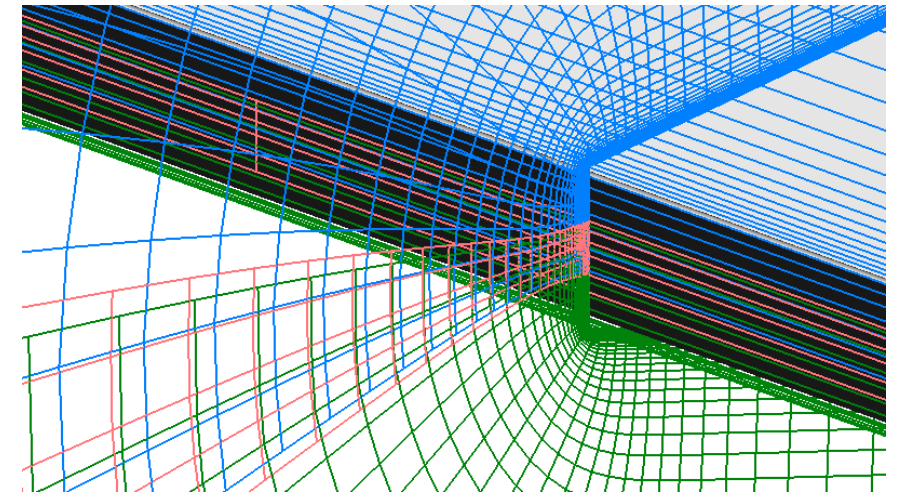
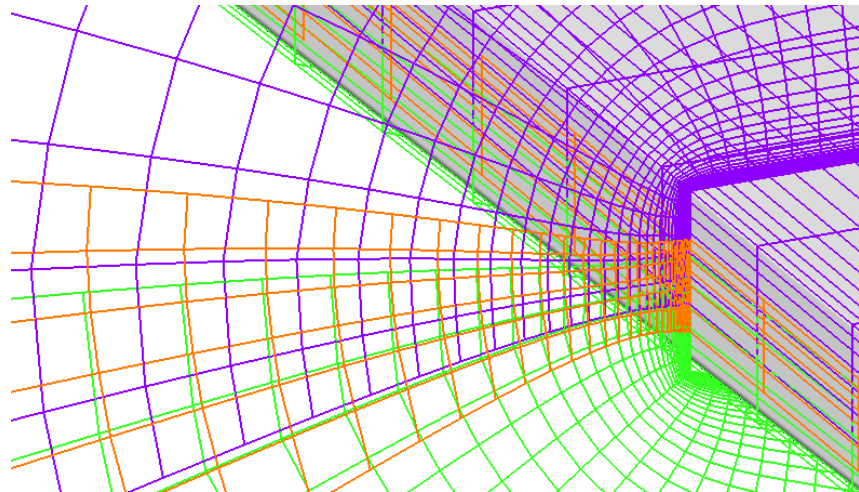
Trailing edge gaps are closed

$Y = 550$

$Y = 1150$

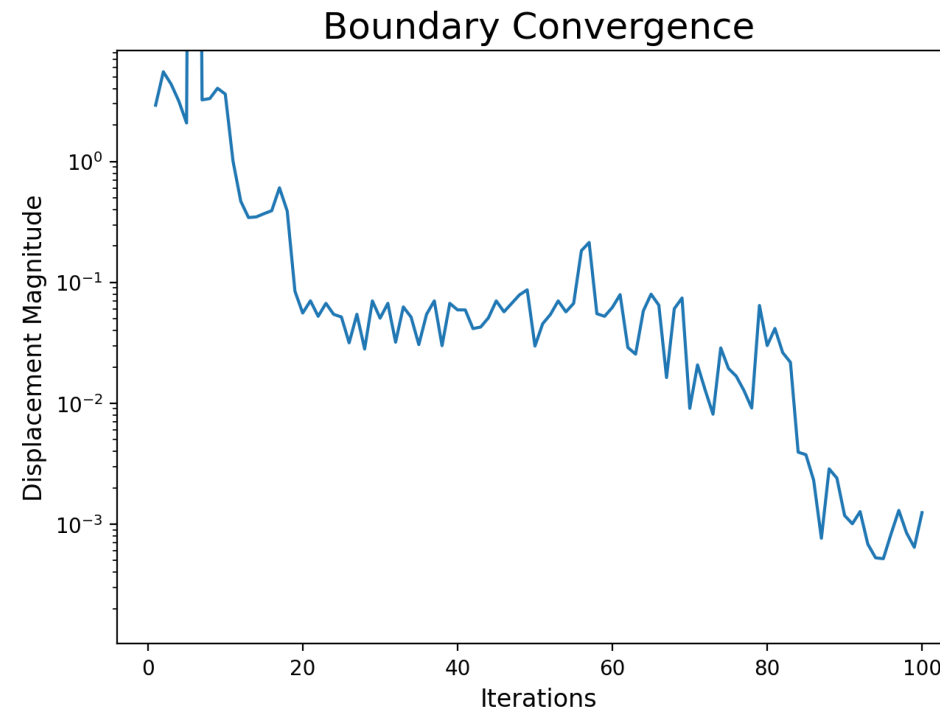
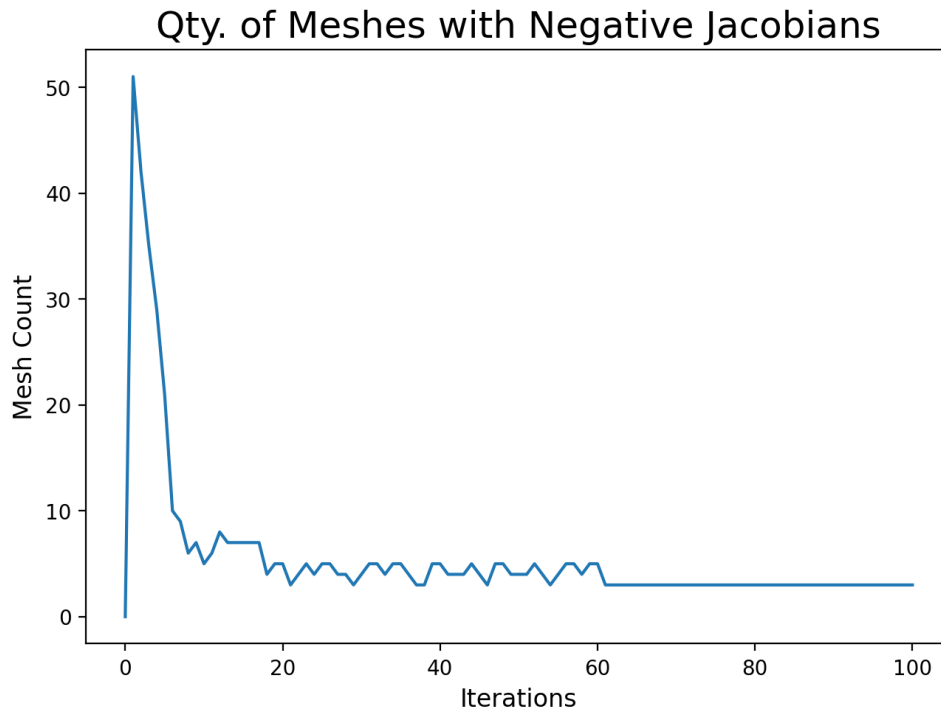
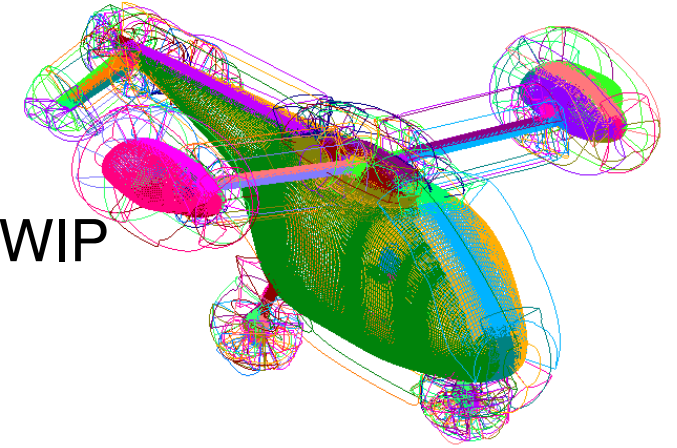


Overlap consistent with initial surface maintained across marching direction



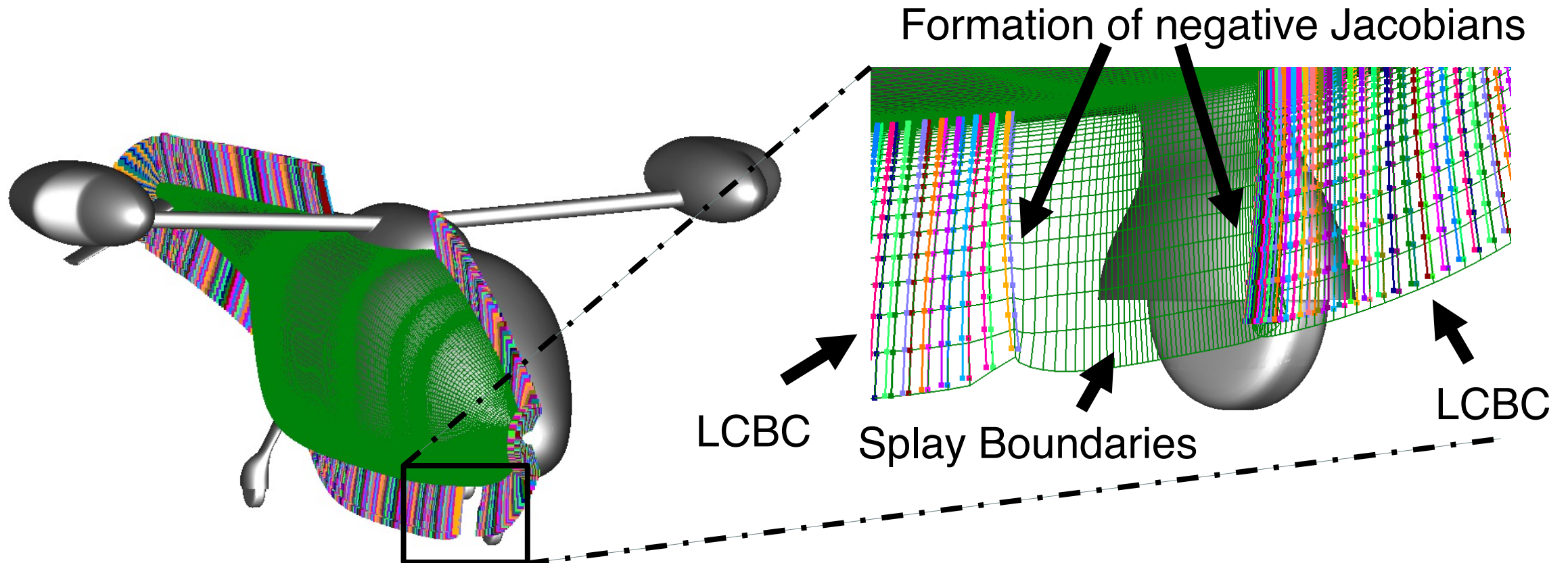
VOLUME MESH LCBC CONVERGENCE BEHAVIOR

- Side-By-Side Hybrid Vehicle
- 100 iterations, 7.8 h wall time (2019 MacBook Pro)
- Algorithmic improvements to reduce wall time/convergence is WIP
- Convergence more difficult due to more deg. of freedom & complex boundaries



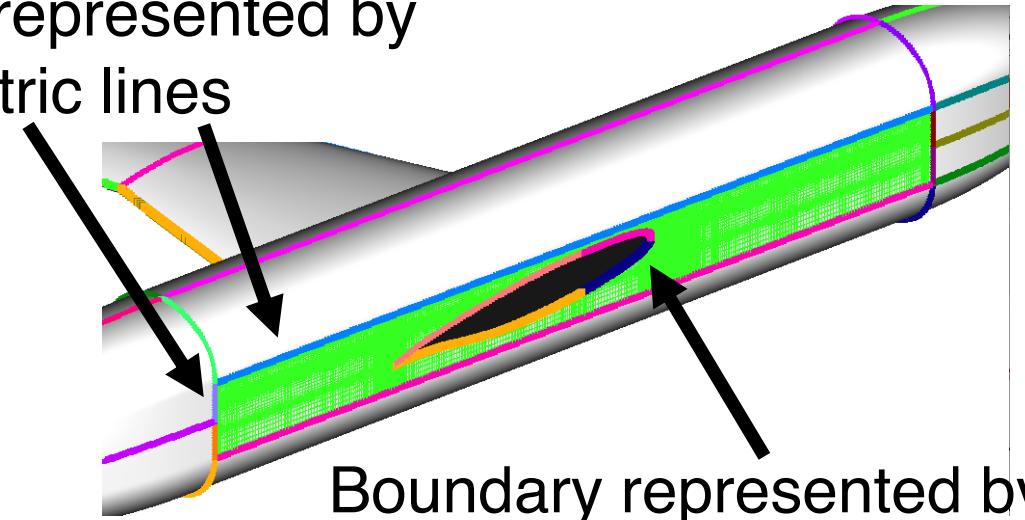
SOURCES OF CONVERGENCE DIFFICULTY

- Mix of LCBC and splay at hole boundaries can affect convergence
- Current investigations ongoing to evaluate best approach to treat hole boundaries



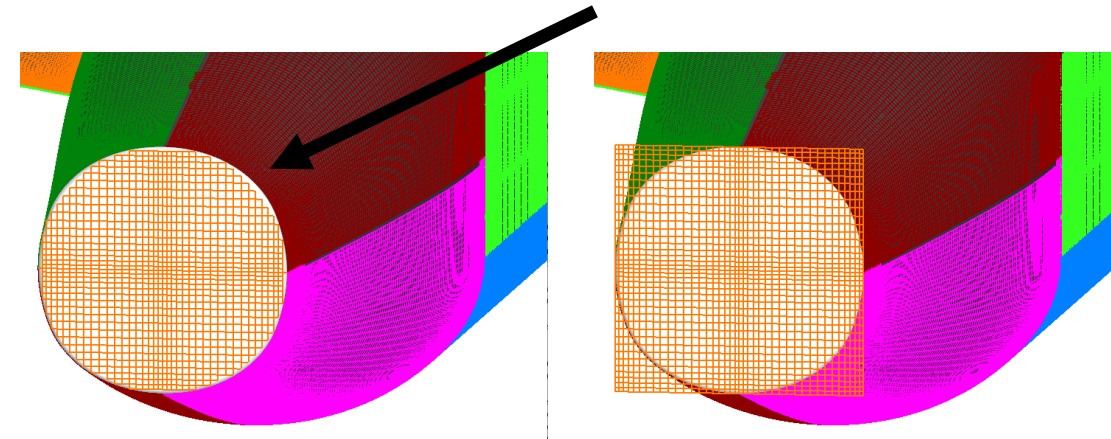
FACE MESH BOUNDARY REPRESENTATION

Boundary represented by
isoparametric lines



Boundary represented by
non-isoparametric lines

- Some boundaries on face mesh only represented by IBLANKS (on/off geometry) but not by discrete parametric (grid) lines
 1. **Junction regions** (e.g. wing roots, tail roots, etc.)
 2. **Trimmed faces** (e.g. wing tips, blunt tails, etc.)
- Non-isoparametric boundaries not compatible with LCBC, esp. **trimmed faces**
- Junction regions not an issue due to no coupling at collar meshes

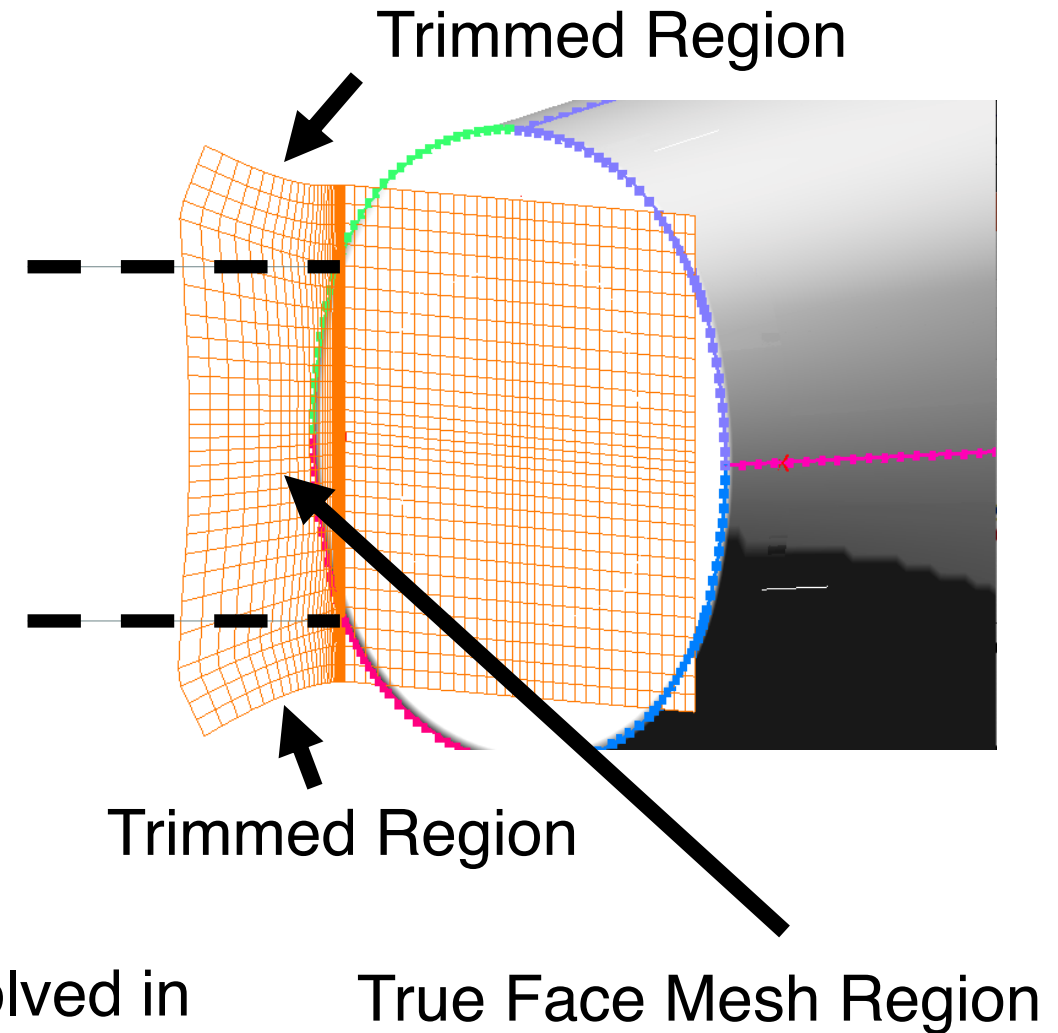
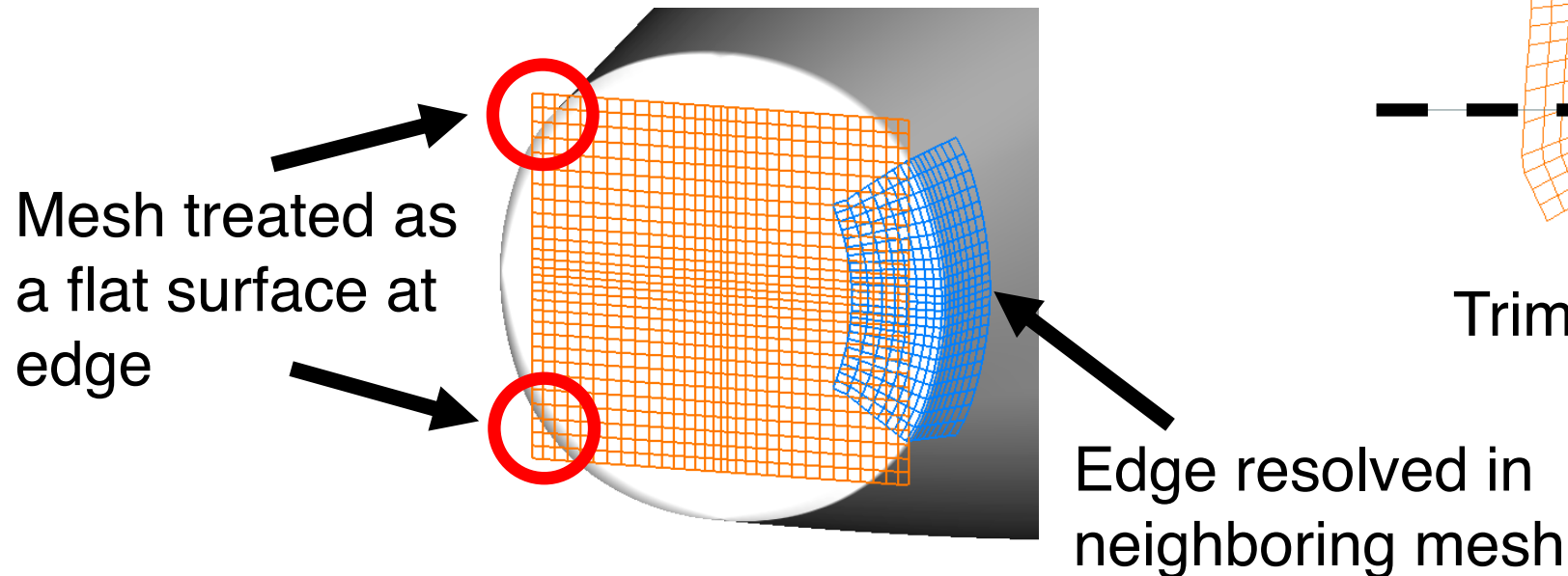


Trimmed face

Untrimmed face

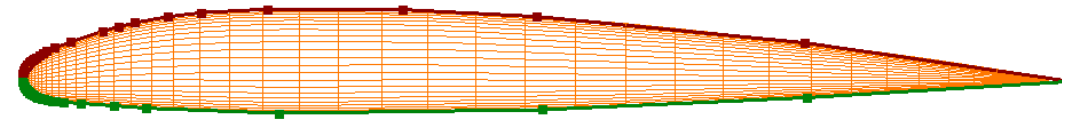
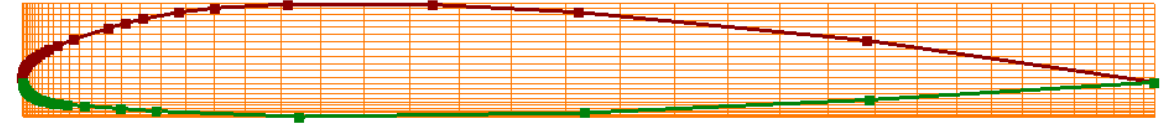
LCBC AND FACE MESH BOUNDARIES

- Hole/trimmed regions do not correspond with real geometry
- If LCBC is applied, negative Jacobians/cell volumes can be introduced into hole/trimmed regions

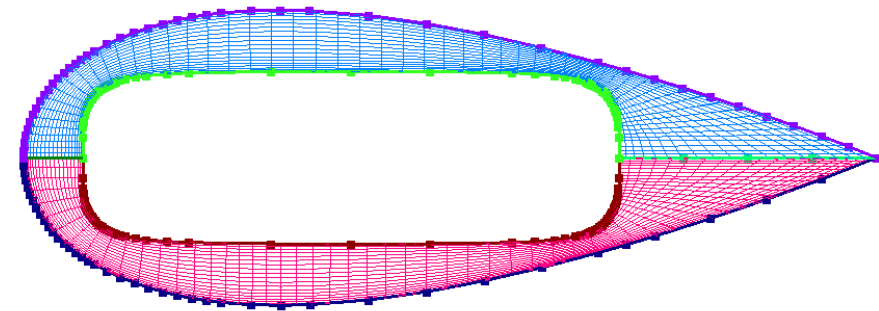
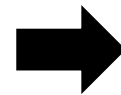
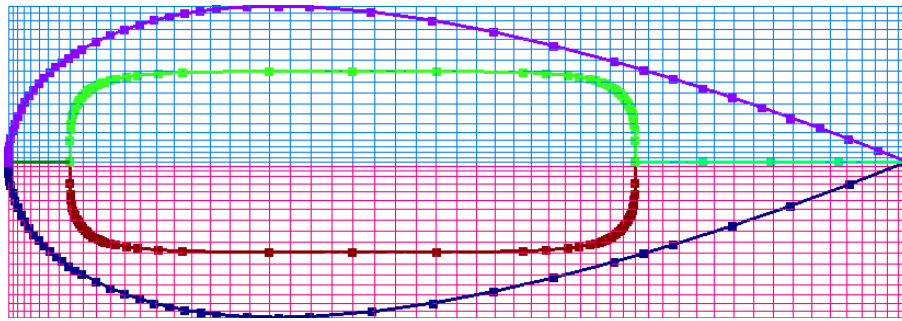


FACE MESH RECONSTRUCTION

- Rebuild face mesh such that external boundaries lie on or within bounding curves
- Along longer dimension, retract normal grid line to within boundary
- Do Transfinite Interpolation (TFI) if face mesh is bounded by 4 non-degenerate edge curves

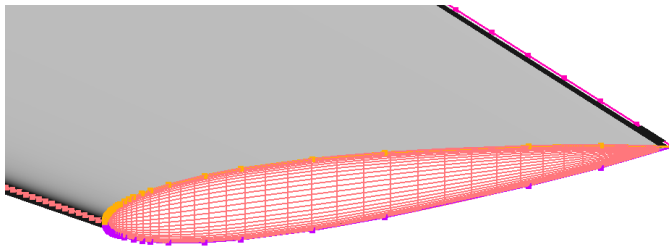
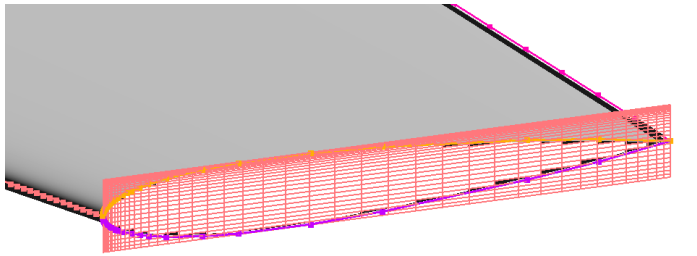


General Reconstruction

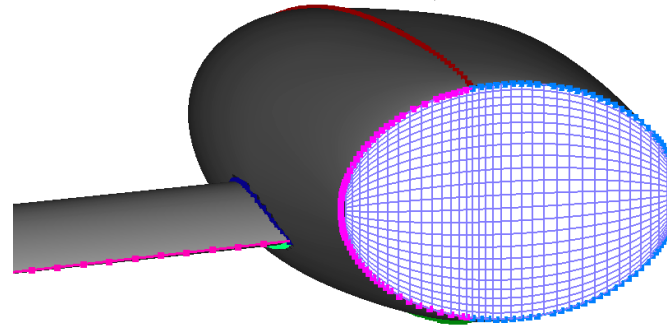
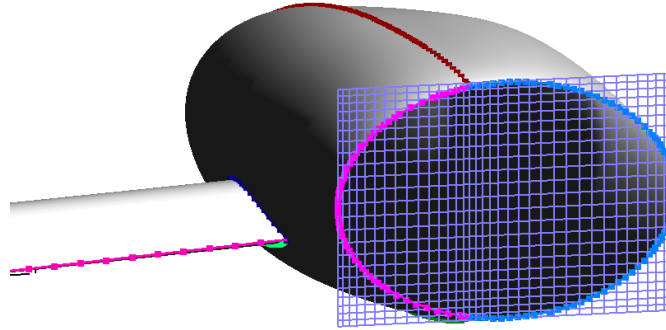


TFI Reconstruction

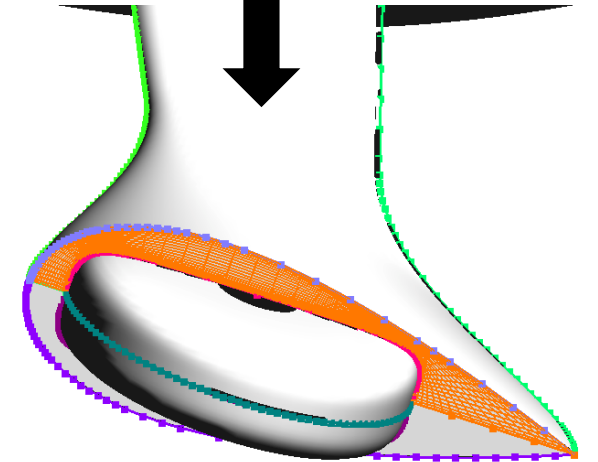
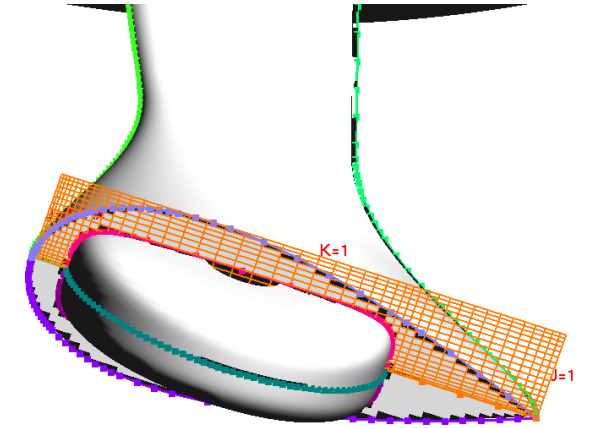
FACE MESH RECONSTRUCTION EXAMPLES



Wing Tip Face



Engine Fairing Tail



Landing Gear

HYBRID SEMI-AUTOMATIC GRID GENERATION

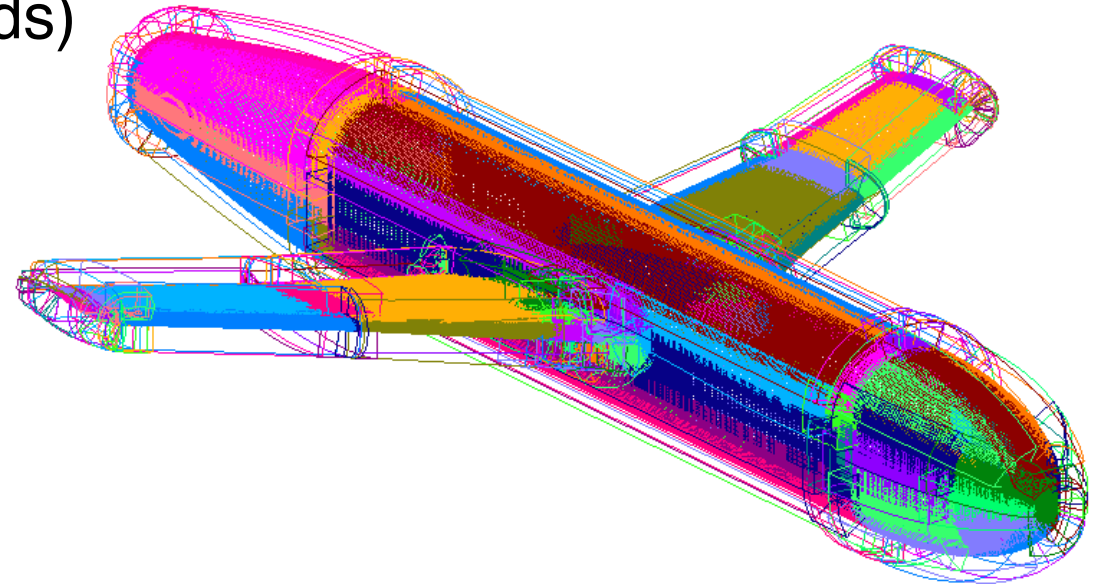
- Hybrid approach uses auto-generated meshes followed by manual repairs on a few defective meshes
- Flow solutions can now be computed on resulting meshes
- How do auto meshes affect accuracy, convergence, efficiency?

Automated Steps	Manual Steps
• Surface Mesh Generation • Volume Mesh Generation • Flow Solver Input File • Aero-loads Computation Input File	• Hole Cutting/Domain Connectivity* • Negative Jacobian volume mesh repair

*Work still underway in automating domain connectivity along with mesh generation

GRID GENERATION – JUNCTURE FLOW MODEL (JFM) F6 WING

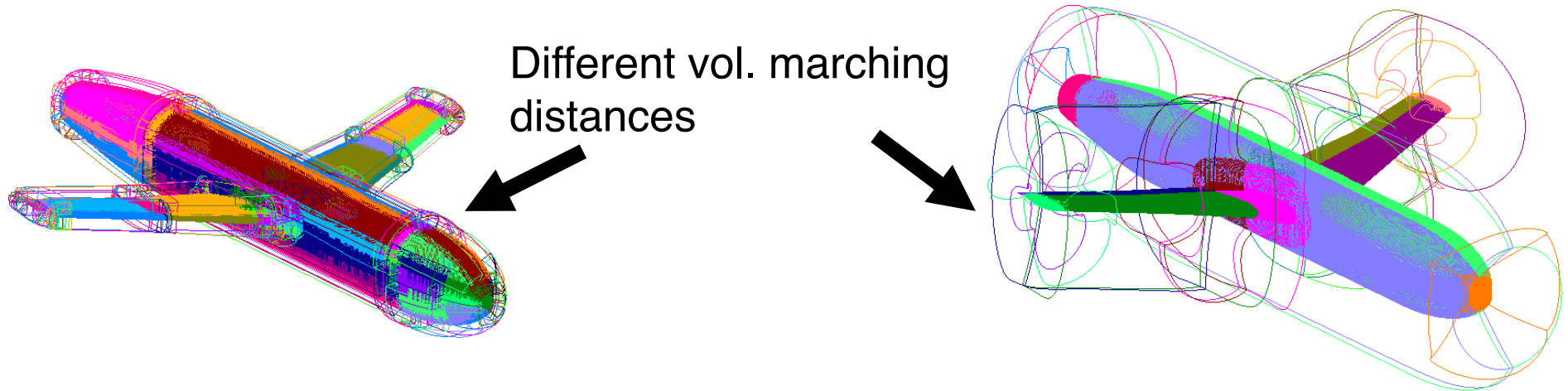
- Auto surface and volume mesh w/ LCBC
(2.5 h, 2019 MacBook Pro, 10 OMP threads)
 - Surface Mesh: 4 min 33 s
 - Volume Mesh: 40 s
 - Volume Mesh LCBC: 2.5 h
- Manual steps (~2 hrs):
 - Collar mesh repair (10 meshes)
 - Regenerate coupled meshes for overlap improvement (9 meshes)
 - XRAYs for hole-cutting with DCF



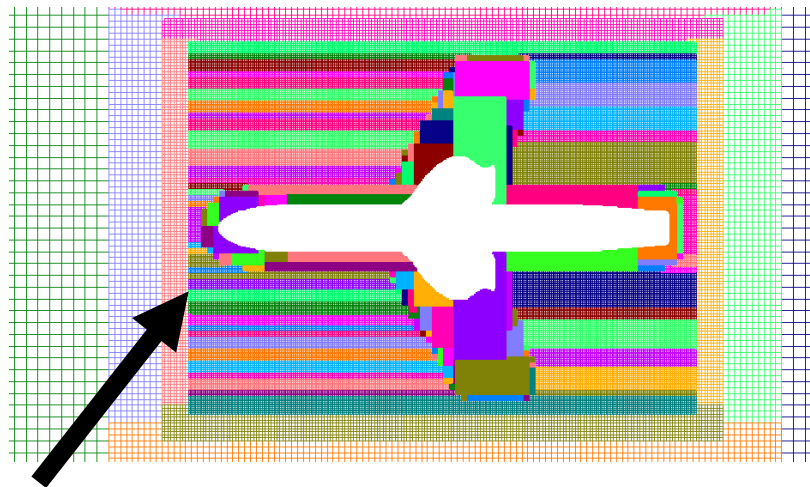
Automatically generated volume mesh

GRID COMPARISONS – JFM F6 (1)

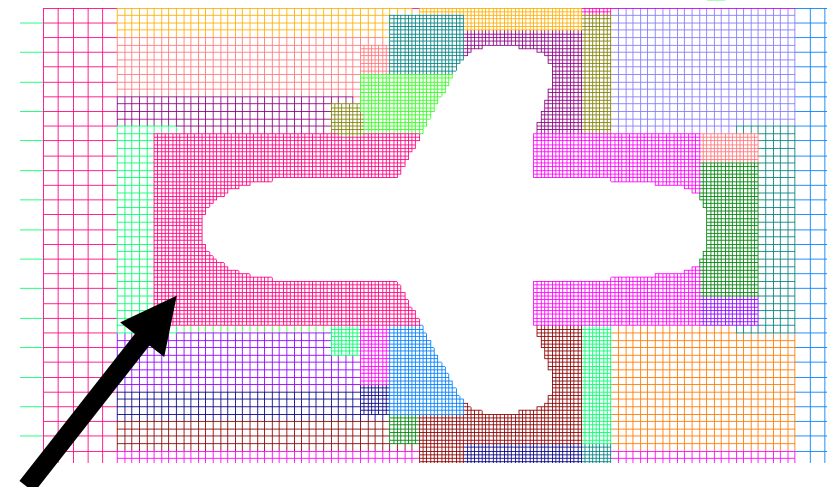
Near-Body



Off-Body



$\Delta s_{min} = 12.5mm$ Automatic

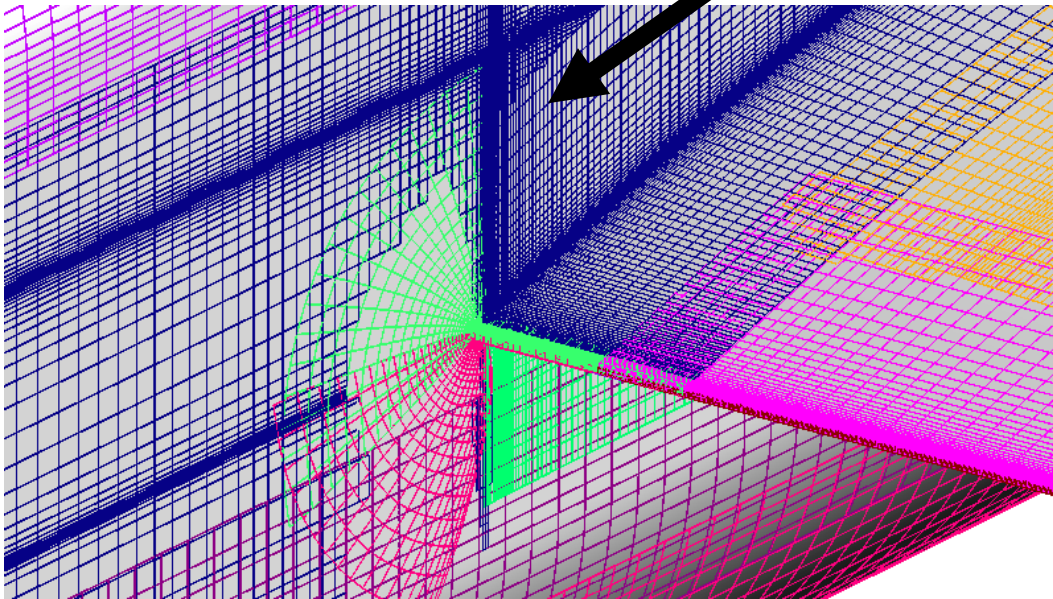


$\Delta s_{min} = 40.0mm$ Manual [4]

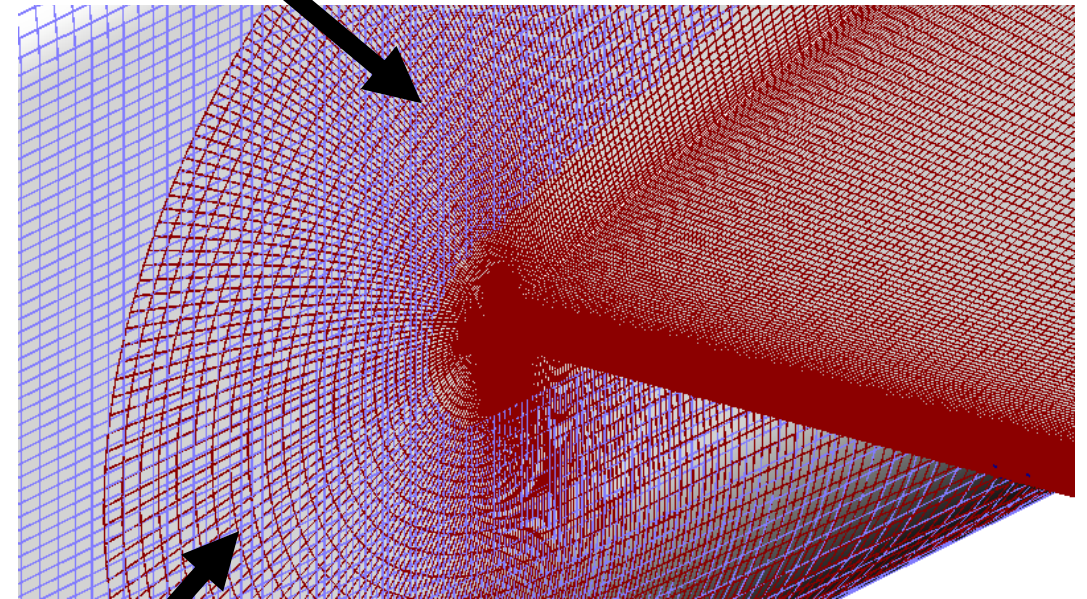
4. Lee, H. C., & Pulliam, T. H., “Overflow Junction Flow Computations Compared with Experimental Data”, AIAA 2019-0080, January 2019. <https://doi.org/10.2514/6.2019-0080>

GRID COMPARISONS – JFM F6 (2)

Finer mesh resolution in juncture
region in manual mesh



Automatic



Manual

Manual meshes contain more
overlap in junction regions

GRID COMPOSITION – JFM F6

- Differences can be attributed to...
 - NB volume marching distances/off-body mesh generation (blue)
 - Surface mesh topology

	Automatic			Manual		
	Near-Body	Off-Body	Total	Near-Body	Off-Body	Total
Surface Points	465K	-	-	578K	-	-
Grid Count	180	739	919	17	158	175
Grid Points	29.8M	30.7M	60.5M	48.9M	1.98M	50.9M
Fringe Points	4.85M	10.5M	15.3M	3.28M	829K	4.11M
Blanked Points	4.4M	3.83M	8.23M	524K	145K	669K

COMPUTATIONAL EFFICIENCY – JFM F6

- Medium resolution, 280 Intel Broadwell Cores, 14.3K steps
- Load balancing in OVERFLOW results in roughly similar resource utilization

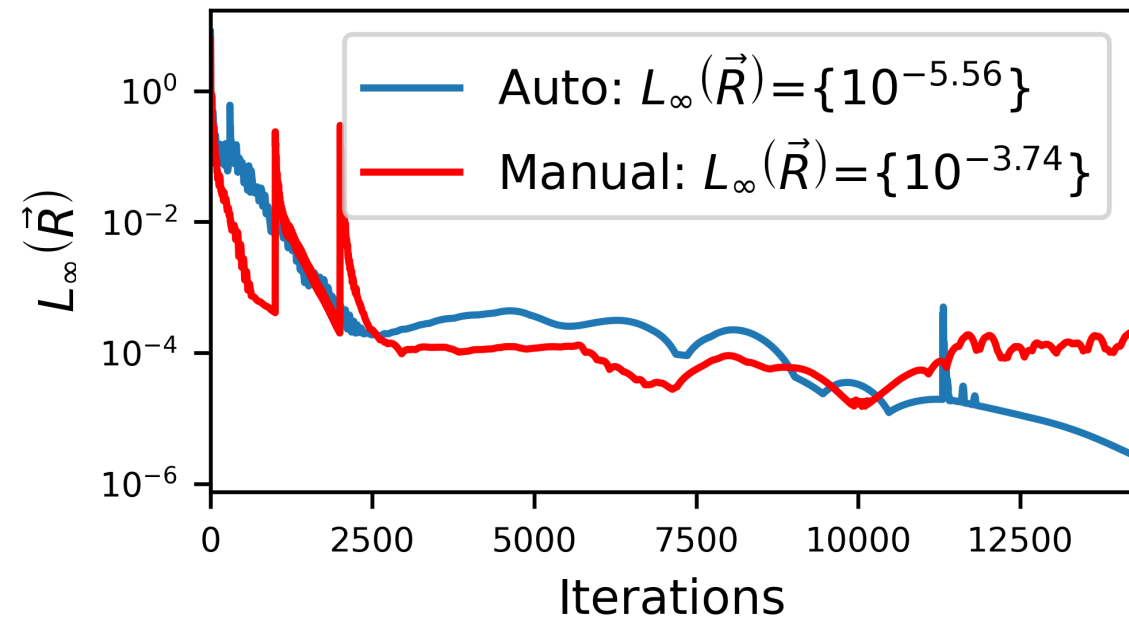
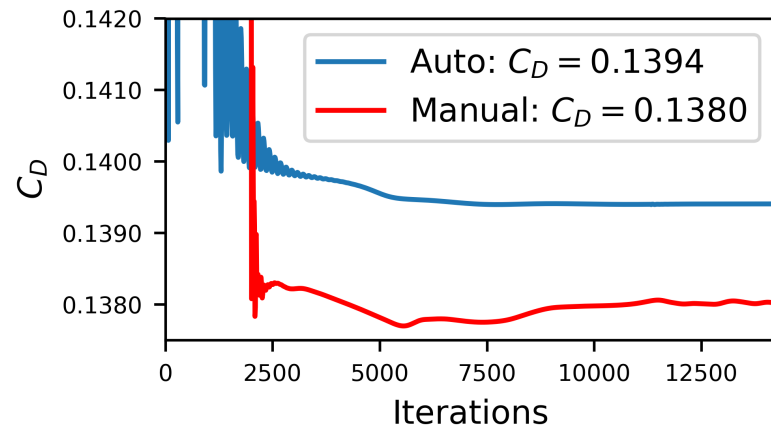
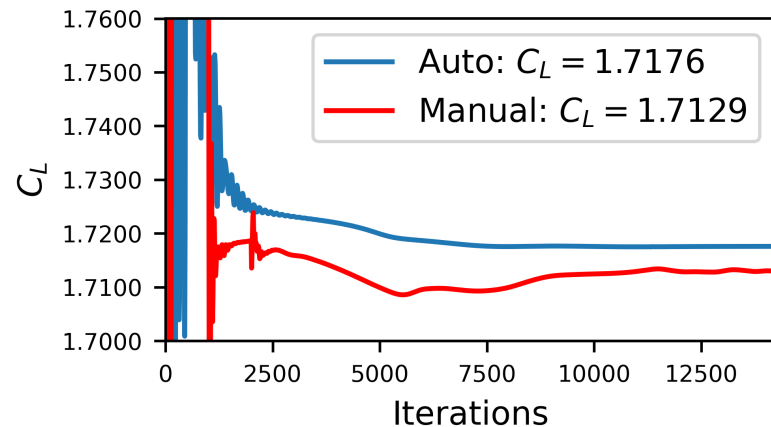
		Automatic	Manual
Before MPI-Splitting	# Grids	919	178
	Total Point Ct.	60.5M	50.9M
After MPI-Splitting	# Grids	1395	949
	Total Point Ct.	66.2M	65.2
	Avg. Pts per Group	298K	294K
	Chimera Boundary Exchange Time/Step	7.86E-02s	3.38E-02s
	Parallel Efficiency	91.4%	93.7%
	Wall Time	7 h 21 min	6 h 50 min

Only 2.3x
increase in
wall-time vs
3.7x increase
in fringe pts



SOLUTION AND CONVERGENCE – JFM F6

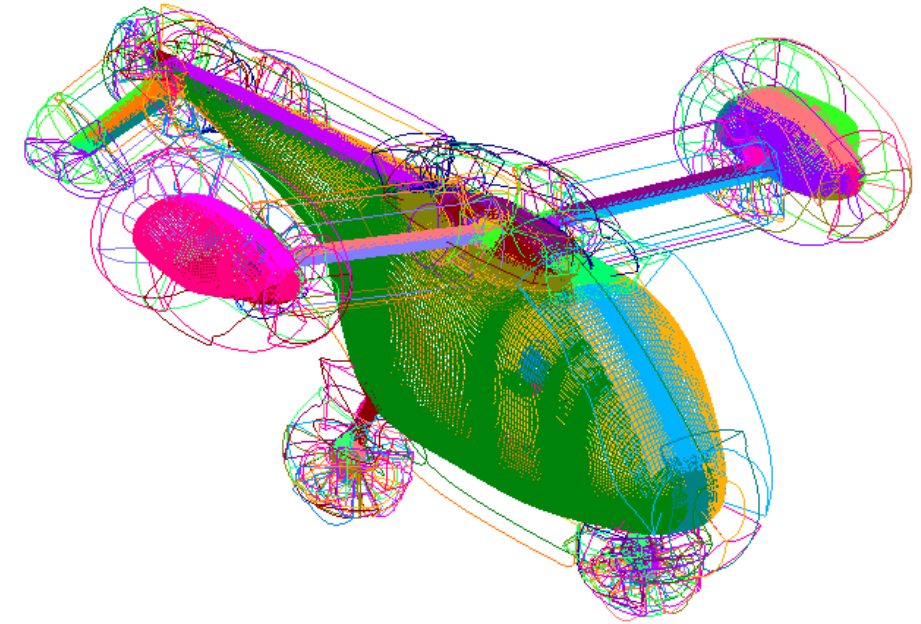
- Flow conditions: free air, $M_\infty = 0.189$, $\alpha = 5.0^\circ$, 14.3K steps
- 3rd Order Roe Scheme, ARC3D diagonalized Beam-Warming scalar pentadiagonal scheme, SARC-QCR2013V



$$\Delta C_L = 0.2\%, \Delta C_D = 1\%$$

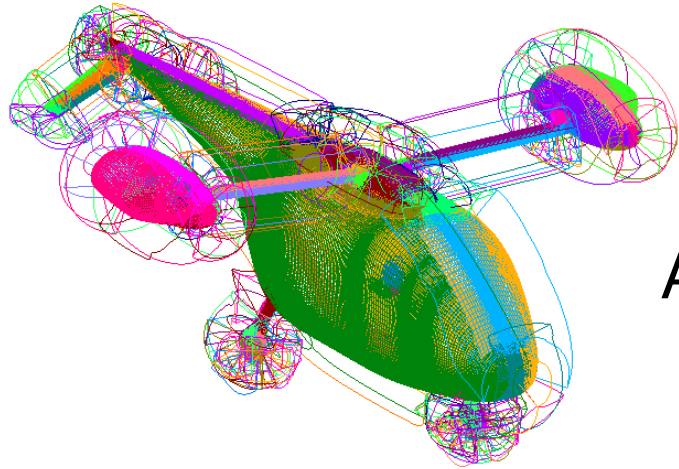
GRID GENERATION – SIDE-BY-SIDE HYBRID (AUTOMATIC)

- Surface & volume mesh generation w/ LCBC (7.8 h, 2019 MacBook Pro, 10 OMP threads):
 - Surface Mesh: 3 min
 - Volume Mesh: 12 s
 - Volume Mesh LCBC: 7.8 h
- Manual steps (~4 hrs):
 - Collar mesh repair (3 meshes)
 - Regenerate various meshes for overlap improvement (36 meshes)
 - XRAYs for hole-cutting with DCF
- Flow Solution Comparison WIP

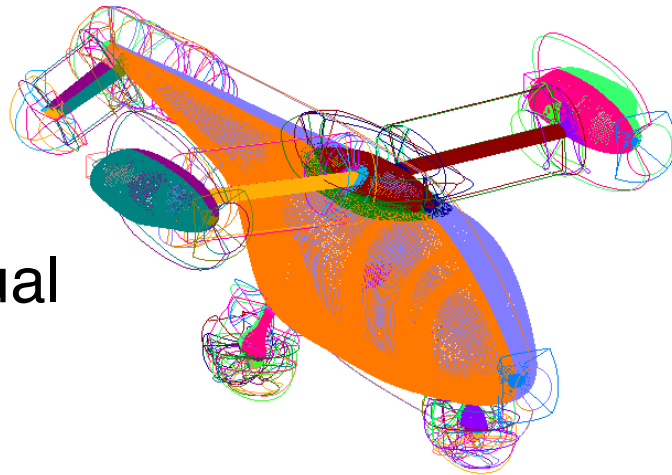


Automatically generated volume mesh

GRID COMPARISONS – SIDE-BY-SIDE HYBRID (1)



Automatic



Manual

Volume meshes generated for
Side-By-Side Hybrid

Comparison of Auto vs. Manual mesh generation time (assuming 8 h worked per day)

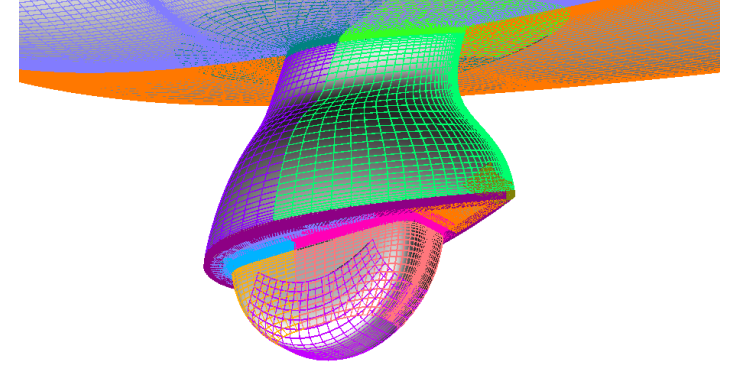
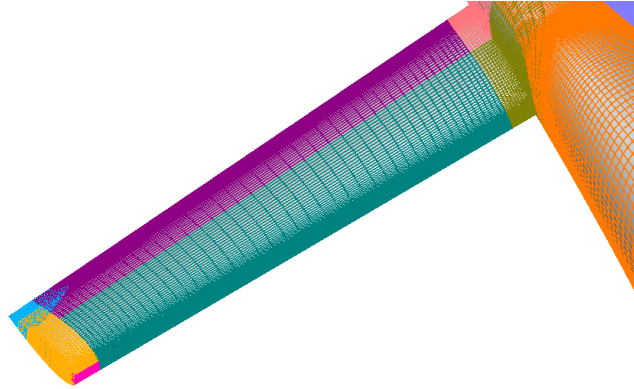
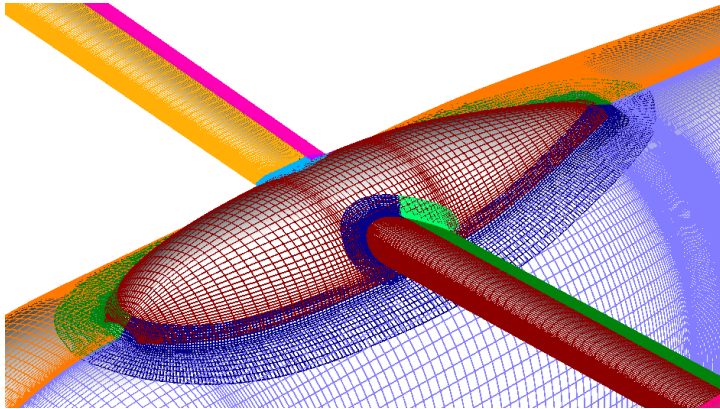
Steps	Automatic	Manual
Surface Meshing	3 min (C)	2-3 wks (M)
Volume Meshing	12 s (C)	1 d (M)
Volume Mesh LCBC	7.8 h (C)	-
Volume Mesh Repair	1-2 h (M)	-
Domain Connectivity	2 h (M)	2 h (M)
Flow Solver Inputs	10 min (M)	30 min (M)
Total Turnaround Time	1-2 d	3 wks

(C): CPU wall-clock time

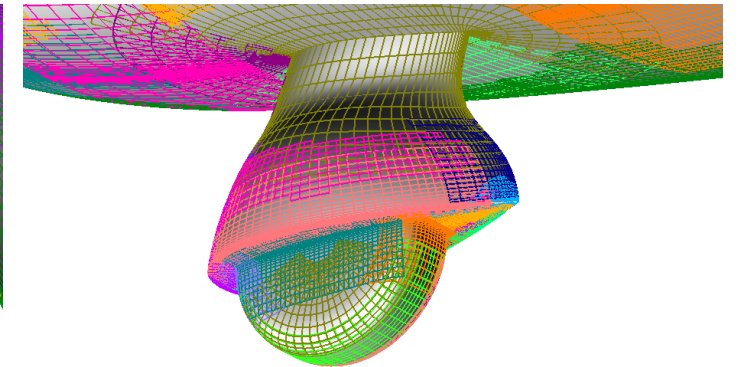
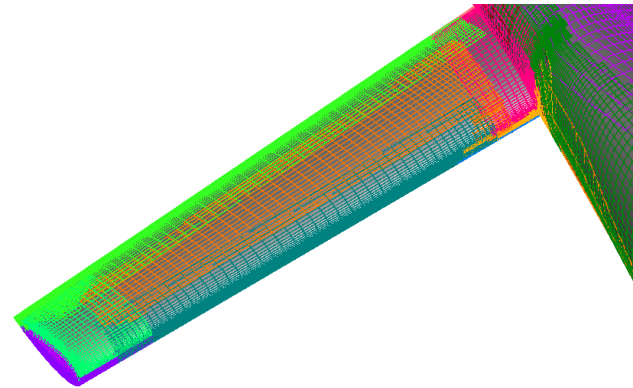
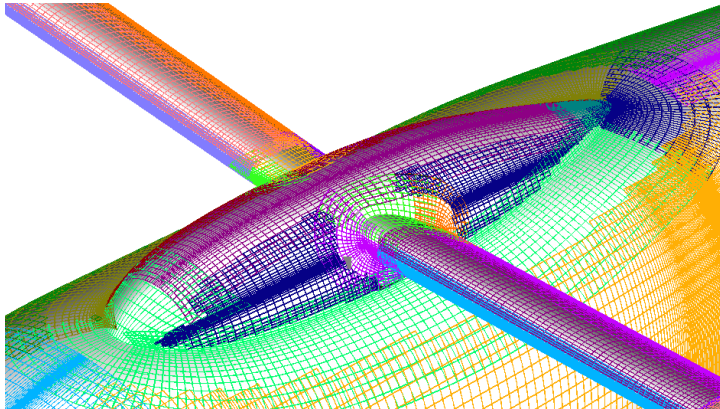
(M): Manual labor time

GRID COMPARISONS – SIDE-BY-SIDE HYBRID (2)

Manual



Automatic



SBS Center Pod

Right Tail

Front Landing Gear

GRID COMPOSITION – SBS HYBRID

- Used same XRAY cutters & off-body generation inputs
- Differences mainly attributed to surface mesh approach (blue)
 - Refinement of collar meshes
 - Surface topology decomposition

	Automatic			Manual		
	Near-Body	Off-Body	Total	Near-Body	Off-Body	Total
Surface Points	319K	-	-	394K	-	-
Grid Count	162	252	414	86	241	327
Grid Points	20.1M	7.77M	27.9M	24.8M	8.07M	32.9M
Fringe Points	3.40M	2.55M	5.95M	3.21M	2.55M	5.76M
Blanked Points	1.15M	467K	1.62M	1.77M	465K	2.24M

COMPUTATIONAL EFFICIENCY – SIDE-BY-SIDE HYBRID

- 160 Intel Ivy Bridge Cores, 15K steps
- Load balancing in OVERFLOW results in roughly similar resource utilization

		Automatic	Manual
Before MPI-Splitting	# Grids	414	327
	Total Point Ct.	27.9M	32.9M
After MPI-Splitting	# Grids	686	702
	Total Point Ct.	31.9M	38.5M
	Avg. Pts per Group	251K	304K
	Chimera Boundary Exchange Time/Step	3.20E-02s	2.64E-02s
	Parallel Efficiency	94.9%	94.4%
	Wall Time	3 h 50 min	3 h 27 min

CONCLUDING REMARKS

- Presented loosely-coupled boundary conditions (LCBC) for hyperbolic mesh generation (surface and volume)
- Introduced face mesh reconstruction to improve volume LCBC robustness
- Presented preliminary flow solution comparisons between automatically and manually generated grids
- Automatic meshes shows comparable capability in computing flow solutions (convergence, accuracy, efficiency)
- Hybrid auto/manual approach enables significant reductions in turnaround time to perform overset CFD analysis

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