

## Characterization of Urban Air Mobility Vehicle Operational Noise and Community Noise Impact



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### AAM and UAM



- Advanced Air Mobility (AAM) missions characterized by < 300-500 nm range</li>
- Vehicles require increased automation and are likely electric or hybrid-electric
- Rural and urban operations are included
- Missions can be public transportation, cargo delivery, air taxi, or emergency response
- Urban Air Mobility (UAM) is a subset of AAM and is a segment that is projected to have high economic benefit and be the most difficult to develop
  - UAM requires an airspace system to handle high-density operations
  - UAM requires an advanced urbancapable vehicle
  - UAM vehicle variants can target other missions



The Revolutionary Vertical Lift Technology Project and Transformational Tools and Technologies Project are two of seven NASA projects that support the AAM Mission.

## NASA Toolchain for Analysis of Noise and Performance of VTOL Vehicles



#### **Example Concept Vehicles**





#### <u>Quadrotor</u>†

- All-electric variant
- 3-bladed rotors
- 6469 lb. GTOW
- V<sub>max</sub> 109 KTAS



#### Lift Plus Cruise<sup>+</sup>

- Turboelectric variant
- (8) 2-bladed lifting rotors
- 3-bladed pusher propeller
- 5903 lb. GTOW
- V<sub>max</sub> 123 KTAS
- Both vehicles sized for 1200 lb. payload (up to six passengers) executing a representative mission profile.<sup>‡</sup>

<sup>+</sup> Silva et al., "VTOL Urban Air Mobility Concept Vehicles for Technology Development," AIAA Aviation Forum, Atlanta, GA, June 2018, AIAA-2018-3847, <u>https://doi.org/10.2514/6.2018-3847</u>.

<sup>‡</sup> Patterson et al., "A Proposed Approach to Studying Urban Air Mobility Missions Including an Initial Exploration of Mission Requirements," AHS International 74th Annual Forum, Phoenix, AZ, May 2018

#### **Source Noise Prediction**





- Quadrotor was trimmed utilizing collective pitch control and constant RPM. The same trim mode was used for all speeds.
- Lift plus Cruise was trimmed utilizing collective pitch control with constant RPM. Three different trim modes used for low, moderate, and high speeds.

## **Experimental Databases for Validation of Noise Prediction Models**



• Recent isolated propellers and rotors



Ideally Twisted Rotor AIAA-2021-1928



Optimized Proprotor NASA ATWG Spring and Fall 2022



Cruise and High Lift Propellers AIAA-2018-3448

#### • Recent installed propellers and rotors



Rotor-Airframe Interaction 73<sup>rd</sup> AHS Forum 2017



Pusher Configuration 77<sup>th</sup> VFS Forum 2021



Tractor Configuration AIAA-2021-0714

## **Experimental Databases for Validation of Noise Prediction Models**



#### ... more installed propellers, rotors, ducted rotors and tiltrotors



Tilting Proprotor Aero Performance - Summer 2022 Acoustic Test – 2025



Ducted Speaker & Rotor NASA ATWG Spring 2022



Tilt Duct Acoustic Test (40'x80') FY 23-25



Quadrotor – Blade Sets & Standoffs AIAA-2022-3110 & InterNoise 2022



Multirotor Test Bed Acoustic Test (40'x80') FY 23-25



Tiltwing Acoustic Test (14'x22') FY 23-25

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#### **Utilization of Source Noise Predictions**



#### **Utilization of Source Noise Predictions**









- 14 CFR Part 135 Air Carrier and Operator Certification requires noise type certification
  - 14 CFR Part 36 is the U.S. equivalent to ICAO Annex 16
- Noise certification applicability for AAM
  - Limited to "fitting" vehicle types into existing Part 36
  - Statutory requirement (U.S.C. 44715) to develop noise a noise certification process for all aircraft
  - Long term approach: develop updated certification process informed by research to better understand unique noise characteristics and flight profiles
  - Interim approach: certification on case-by-case basis (rules of particular applicability RPA) via G-3 Issue Paper and followed by rulemaking actions (notice of proposed rulemaking and final rule)
- NASA process for noise certification analyses



#### Noise Certification Standards for Helicopters (Appendix H)





Figure H1. Comparison of Measured and Reference Takeoff Profiles



Figure H2. Comparison of Measured and Reference Flyover Profiles

Source: https://federalregister.gov/a/04-12069



Figure H3. Comparison of Measured and Reference Approach Profiles



### Noise Certification Standard for Light (< 7000 lbs) Helicopters (App J)

- Level overflight at 492 ft (150 m) altitude
- Single 4-ft microphone directly below flight path
- No lower weight limit
  - Matternet delivery drone (29 lbs) recently certified under RPA based on Appendix J.





#### Noise Certification Standards for Tiltrotors (Appendix K)





Figure K1. Comparison of Measured and Reference Takeoff Profiles



Figure K2. Comparison of Measured and Reference Flyover Profiles

Source: <u>https://federalregister.gov/a/2013-00111</u>



Figure K3. Comparison of Measured and Reference Approach Profiles











Lopes, Ingraham, Zawodny, "Status of UAM Proprotor Design Validation Campaign: Available Data and Computational Tools," NASA Acoustics Technical Working Group Meeting, Oct 2022

#### **Perception-Influenced Acoustic Design – Isolated Proprotor**





Lopes, Ingraham, Zawodny, "Status of UAM Proprotor Design Validation Campaign: Available Data and Computational Tools," NASA Acoustics Technical Working Group Meeting, Oct 2022





#### Auralization & Psychoacoustics



**Auralization** 

Rizzi, Sahai, "Auralization of air vehicle noise for community noise assessment," *CEAS Aeronautical Journal*, 2019, https://doi.org/10.1007/s13272-019-00373-6/







Synthesis of Loading and Thickness Noise using ANOPP2 Farassat's Formulation 1A Internal Functional Module (AF1AIFM)



Quadrotor Periodic

Krishnamurthy, Tuttle, Rizzi, "A Synthesis Plugin for Steady and Unsteady Loading and Thickness Noise Auralization", AIAA AVIATION 2020, AIAA-2020-2597, June 2020. https://doi.org/10.2514/6.2020-2597



Self Noise Sound Pressure Predictions from ANOPP2 Self Noise Internal Functional Module (ASNIFM)



Krishnamurthy, Aumann, Rizzi, "A Synthesis Plugin for Auralization of Rotor Self Noise", AIAA AVIATION 2021, AIAA-2021-2211, August 2021. https://doi.org/10.2514/6.2021-2211

Level Flyover

#### **Psychoacoustic Studies Utilizing Auralizations**

Not at all

How annoying was the sound to you?

Moderately

OK

Extrem



- Test of UAM Sound Quality (completed July 2022)
  - Objective: Investigate how annoyance varies with sound quality.
  - Generated test stimuli spanning a range of loudness, sharpness, tonality, fluctuation strength, and impulsiveness.

Christian, Boucher, Begault, Rafaelof, Rizzi, Krishnamurthy, "Initial Results from a Psychoacoustic Test for UAM Sound Quality," NASA Acoustics Technical Working Group Meeting, Oct 2022

- Test of Noise and Numbers (January 2023)
  - Objective: Investigate how annoyance varies with number of operations, spacing between operations, and makeup of the fleet.
- Test of Detection, Noticeability, and Annoyance (Sept 2023)
  - Objective: Investigate how annoyance varies in presence of masking noise, e.g., cityscape.
- Cooperative Human Response Study
  - Objective: Verify consistency of remote test platform with prior lab results (Oct 2022).
  - Objectives under consideration include annoyance between geographically distinct communities, near vertiports, number of events, different soundscapes, relative to existing aircraft noise sources (2024).

#### Exterior Effects Room (EER) at NASA Langley



#### Remote Psychoacoustic Testing Platform



#### **Utilization of Source Noise Predictions**





**Operational Fleet Noise Assessments** 



#### **UAM Operational Fleet Noise Assessments**



- FAA Aviation Environmental Design Tool (AEDT) is the required tool to assess aircraft noise and other environmental impact due to federal actions at a civilian airport or vertiport, or in the U.S. airspace for commercial flight operations
- Obstacles to using AEDT for assessing UAM operations include:
  - No available noise-power-distance data for UAM vehicles (whether modeled as fixed-wing or rotary-wing aircraft in AEDT)
  - When modeled as fixed-wing aircraft, there are no performance data available to determine engine power, and unclear if engine power is a good predictor of noise
  - When modeled as rotary-wing aircraft, the number of operating modes within AEDT are limited to a few that are appropriate for typical helicopter operations, but may be insufficient for describing UAM operations
- Technical approach includes:
  - $\circ~$  Develop means to generate fixed-wing and rotary-wing NPD data from prediction+
  - Develop means to model UAM operations in AEDT fixed-wing<sup>‡</sup>, rotary-wing, and hybrid modes
  - o Identify best modeling practices through comparison using simulation methods

<sup>+</sup> Rizzi, Letica, Boyd, Lopes, "Prediction-Based Approaches for Generation of Noise-Power-Distance Data with Application to Urban Air Mobility Vehicles," 28<sup>th</sup> AIAA/CEAS Aeroacoustics Conference, Southampton, UK, June 2022, AIAA-2022-2839, <u>https://doi.org/10.2514/6.2022-2839</u>.

‡ Rizzi, Rafaelof, "Community Noise Assessment of Urban Air Mobility Vehicle Operations using the FAA Aviation Environmental Design Tool," InterNoise 2021, Virtual, 2021.

<sup>‡</sup> Rizzi, Rafaelof, "Second Generation UAM Community Noise Assessment using the FAA Aviation Environmental Design Tool," AIAA SciTech Forum, San Diego, CA, Jan 2022, AIAA-2022-2167, <u>https://doi.org/10.2514/6.2022-2167</u>.

#### **UAM Operational Fleet Noise Assessments**











-97.2 -97 -96.8 -96.6 -96.4 Longitude (Deg. W) Establish aircraft operational states for the flight conditions

60

90

30

#### **Utilization of Source Noise Predictions**







- Model Predictive Path Integral Control (MPPI)
  - $\circ~$  Sample thousands of control sequences,  $\pmb{\nu}_t \sim \mathcal{N}(\pmb{u}_t, \pmb{\Sigma})$  , propagate trajectories in parallel
  - $\circ~$  Exponential cost-weighted averaging to update mean of optimal control distribution,  ${m u}_t$
  - Propagate mean optimal control sequence to obtain nominal trajectory



**Figure credit:** J Pravitra, KA Ackerman, N Hovakimyan, EA Theodorou, "L1-Adaptive MPPI Architecture for Robust and Agile Control of Multirotors," IROS, 2020.

#### Simulation Results – Video (monopole source)





#### Simulation Results – Video (directive source)







#### **Utilization of Source Noise Predictions**



# Generate predicted helicopter ground noise footprint based on:

- Vehicle attitude in real time
- Flight-test-generated vehicle noise spheres<sup>1</sup>



- Helicopter noise spheres: Eric Greenwood, "Real time helicopter noise modeling for pilot community noise awareness," in *Noise-Con 2017*, June 2017.
- 2. Acoustic flight simulator: A. C. Trujillo and D. R. Hill, "Acoustic Flight Simulator Architecture, Noise Training Aid Manual, and Its Training Benefits," NASA-TM-2021-0014096, October 2021.



- 3. Trajectory generation: K. A. Ackerman, I. M. Gregory, E. Theodorou, and N. Hovakimyan, "A Model Predictive Control Approach for In-Flight Acoustic Constraint Compliance," AIAA 2021-1958, *AIAA Scitech 2021 Forum*, January 2021.
- 4. UAM noise extrapolation to ground: *Advanced Acoustic Model (AAM)*, Volpe, December 2020
- Rizzi, Letica, Boyd, Lopes, "Prediction-Based Approaches for Generation of Noise-Power-Distance Data with Application to Urban Air Mobility Vehicles," AIAA-2022-2839, 28th AIAA/CEAS Aeroacoustics Conference, Southampton, UK, June 2022.

- Generate predicted **UAM** ground noise footprint at each timestamp based on:
- Detailed trajectory from simulation<sup>3</sup>
- Generated UAM noise spheres
- Extrapolated to ground using modeling techniques<sup>4</sup>



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#### **Utilization of Source Noise Predictions**







The work presented herein was primarily supported by the NASA Revolutionary Vertical Lift Technology Project and the Transformational Tools and Technologies Project.

## **Backup Slides**



#### **Perception-Influenced Acoustic Design**

Design and Mission Vehicle Dynamics, Update Design Acoustic Prediction Objective Function (F) Performance, Loads (e.g., F1A) (e.g., OASPL) (e.g., Blade (e.g., BEMT) Shape) No How F Changes with Vehicle's How F Changes with How F Changes with Design and Vehicle Dynamics, Seed Objective Function Acoustic Prediction Mission (e.g., dF/dOASPL = 1) Performance, Loads Parameters (e.g., dF/dF1A) (e.g., dF/dBEMT) (e.g., dF/dBlade Shape) Yes COPR-3 Optimized 20μPa) **Baseline (C24ND)** 120 **No Acoustic Constraint OASPL Constraint (COPR3)** 1/3-Octave SPL (dB, ref: 100 80 60 40 20 Center Band Frequency (Hz)  $10^{2}$ 10<sup>4</sup>

Zawodny, Lopes, Ingraham, "Preliminary Results of Adjoint-Based Proprotor Designs," NASA Acoustics Technical Working Group Meeting, April 2022









### Overall sound pressure level (OASPL) at both observers

