Gecko Mobility Aids for a Common Habitat Architecture

Robert L. Howard, Jr., Ph.D. and Stephen McNierney, National Aeronautics and Space Administration

Cade Shuck and Sebastian Boal, Rhode Island School of Design



Common Habitat Architecture

Background

and 1g.

of eight

· Common Habitat is based on the use of the SLS core stage liquid oxygen (LOX) tank as the primary structure for the pressure vessel



use in microgravity, 1.6g, 3/8g, Common Habitat has a horizontal orientation divided into three decks, an upper deck mid deck and lower deck, with sufficient habitation accommodation for a crew size



- Handrails and footrails not ideal for the Common Habitat · Limited to specific placement and cannot be everywhere a crew member might venture
- · Possible injuries: back pain, shin splints, stress fractures, tendinosis or tendinitis, and compartment syndrome



Callouses, red marks soreness and other discomfort even to the point of blistering and pleeding. Unsafe (trip hazard) when Common Habitat placed in a gravity environment (Moon and Mars surface)

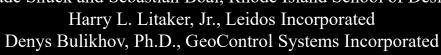
ISS crew comments suggest risk of catching foot or wrist in awkward position with risk of fracture

 Possible loss of mission if occurs near end of transit to Mars Possible loss of crew if shortly before Orion splashdown (unable to safely egress capsule in a contingency)

Full paper available at https://ntrs.nsas.gov



The Common Habitat is not part of the current NASA reference architectures for exploration of the Moon and Mars. It is instead an ongoing study of potential options that - should viability be demonstrated - could potentially be applied to human exploration programs.



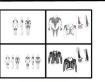




Gecko Grippers

· Developed by JPL, fabricated from a space-rated silicon polymer, and intended for use as robotic end effectors

- Biomimicry of gecko foot pads
- Uses Van der Waals forces to stick to objects when subjected to a shear force
- Test article demonstrated on the International Space Station
- Astrobee robots equipped with grippers used them on ISS to perch on surfaces
- Grippers applied in this research to crew clothing as a restraint and mobility aid



- demonstrator created Initial design concepts for complete uniform Prototypes developed
 - under ICA funding • JPL gripper pads adhered to commercial clothing items

Glove proof of concept

 Long sleeve, short sleeve, shorts, trousers, gauntlets, gloves, finger cots. booties (3 styles)

1g Test and Results

· Tested postures or crew motions using geckoequipped clothing to detect presence or absence of adhesive forces

Key lessons learned:

- Very light forces difficult to perceive in 1g and did not interfere with motion in gravity environmen
- Finger cots annoving to don/doff need a device to assist or inferior to gloves/gauntlets
- Footwear needs coverage on toes, ball of foot, and heel; coverage on arch also useful; walking in
- microgravity probably possible but could easily be knocked off feet · Crawling possible with combination of gloves/gauntlets/finger cots and
- footwear Grippers on backside of gauntlets
- support crawling when hands needed to hold something
- Loose clothing interferes with the function of the gecko grippers (shear force not maintained)
- Lining elbow and knee pads up with body correctly requires precise fit
- · Shirt is only useful when in combination with other clothing (cannot create shear by itself)
- · Trousers (preferable over shorts and shirts work well in
- combination · Thigh pads more useful on trouser and shorts than buttocks pade
- · Works best on smooth, hard surfaces





Acknowledgments Ethan Schaler, Paul Glick NASA Jet Propulsion Laboratory



