

1 Helheim Glacier ice velocity variability responds
2 to runoff and terminus position, but at different
3 timescales

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11 **Abstract**

12 The Greenland Ice Sheet discharges ice to the ocean through hundreds
13 of outlet glaciers. Recent acceleration of Greenland outlet glaciers has
14 been linked to both oceanic and atmospheric drivers. Here, we leverage
15 temporally dense observations, regional climate model output, and newly
16 developed time series analysis tools to assess the most important forcings
17 causing ice flow variability at one of the largest Greenland outlet glaciers,
18 Helheim Glacier, from 2009 to 2017. We find that ice speed correlates
19 most strongly with catchment-integrated runoff at seasonal to interan-
20 nual scales, while multi-annual flow variability correlates most strongly
21 with multi-annual terminus variability. The disparate time scales and the
22 influence of subglacial topography on Helheim Glacier’s dynamics high-
23 light different regimes that can inform modeling and forecasting of its
24 future. Notably, our results suggest that the recent terminus history ob-
25 served at Helheim is a response to, rather than the cause of, upstream
26 changes.

27 **1 Introduction**

28 In recent decades, several glaciers draining the Greenland Ice Sheet have accel-
29 erated, increasing their contribution to global mean sea-level rise (Rignot and
30 Kanagaratnam, 2006; Rignot et al., 2011; Bevan et al., 2012). The observed
31 acceleration of outlet glaciers and the ice sheet interior has been attributed to
32 warmer ocean waters melting glacier fronts (Murray et al., 2010; Rignot et al.,
33 2012) as well as increased surface melt (Joughin et al., 2008; Doyle et al., 2014).
34 Numerical models and indirect observations indicate that increasing runoff could

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35 enhance solid ice loss by lubricating the glacier bed and warming the ice such
36 that it deforms more readily (Reeh and Olesen, 1986; Krabill et al., 1999; Parizek
37 and Alley, 2004; Phillips et al., 2010; Poinar et al., 2017). However, in situ ob-
38 servations of the Greenland Ice Sheet margin have found limited evidence for
39 annual-scale acceleration of ice flow driven by increasing runoff (Stevens et al.,
40 2016; Nienow et al., 2017). At marine outlets including Helheim Glacier, obser-
41 vations show that ice flow speed (and therefore mass discharge) correlates most
42 strongly with iceberg calving activity rather than runoff (Howat et al., 2005;
43 Joughin et al., 2008; Nettles et al., 2008; Kehrl et al., 2017; Vijay et al., 2019).

44 Helheim Glacier is one of the highest-flux outlets of the Greenland Ice Sheet,
45 in recent years matching or surpassing Sermeq Kujalleq (Jakobshvan Isbræ) in
46 solid ice discharge (Mankoff et al., 2020b). Its dynamics through the early
47 21st century showed pronounced variability, including episodes of multi-annual
48 retreat and readvance (Howat et al., 2005, 2007; Bevan et al., 2012) and net
49 mass gain while most Greenland outlet glaciers were losing mass (Howat et al.,
50 2011). Sediment records from the past century suggest that Helheim responds
51 to atmospheric and oceanic variability on time scales of a few years (Andresen
52 et al., 2012), highlighting the importance of understanding its dynamics on
53 seasonal to multi-annual time scales. The high ice flux through Helheim Glacier
54 (Rignot et al., 2004; Mankoff et al., 2019), its recent variability (Stearns and
55 Hamilton, 2007; Howat et al., 2005, 2007), and its sensitivity to short-term
56 variation in climate forcings (Nick et al., 2009; Andresen et al., 2012) motivate
57 a quantitative comparison of hypothesized controls on velocity variability.

58 Processes contributing to velocity variability operate at different time scales.
59 For example, fracture-driven changes in stress balance can be nearly instantane-
60 ous and propagate rapidly, shaping velocity on the order of hours to days
61 (Das et al., 2008; Nettles et al., 2008; Cassotto et al., 2019), while changes in
62 the subglacial drainage system may take days to months (Meier et al., 1994;
63 Kamb et al., 1994; Shepherd et al., 2009; Bartholomew et al., 2010; Pimentel
64 and Flowers, 2011) and response to changing upstream snow accumulation can
65 take many years (Weertman, 1958; Nye, 1960; van der Veen, 2001). Observa-
66 tions that permit a detailed understanding of one process – such as intensive field
67 study of a calving front – may not be sufficient to contextualize influences from
68 processes operating at other scales. Accounting for the relative influence of each
69 process, for example to develop accurate predictive models, requires synthesising
70 observations and inference across time scales. Here, we apply the flexible
71 time series analysis tools developed by Riel et al. (2021) to publicly available
72 velocity fields (Joughin et al., 2020) and correlate the results with temporally
73 dense climate model output (Van Meijgaard et al., 2008; Noël et al., 2018) and
74 terminus observations (Stearns and Ultee, 2021) to study the forcings of and
75 responses to velocity variability at Helheim over multiple temporal scales.

76 2 Methods

77 2.1 Inference framework

78 We investigate correlations between surface velocity and several factors hypoth-
79 esized to drive its variability at seasonal to multi-annual scales. Limited time-
80 dependent data precludes us from studying the effect of ice mélange, ocean

81 temperature, and surface damage directly. Here, we assume that the primary
82 effect of those three variables is on the rate of calving, and we restrict analysis of
83 ocean-driven processes in the present study to the relationship between glacier
84 terminus position and surface ice velocity. We focus our analysis on time scales
85 of months to years. As such, we do not consider the flow response to individual
86 calving events (Murray et al., 2015) or tidal variation (de Juan et al., 2010;
87 Voytenko et al., 2015), which have been described elsewhere. We also disregard
88 any connection between terminus position and topography (via ice thickness),
89 which has been explored in Kehrl et al. (2017).

90 We investigate three factors varying in time (surface mass balance, runoff,
91 and width-averaged terminus position) and one varying in space (subglacial
92 topography). We examine subglacial topography qualitatively, rather than con-
93 structing a time series representation such as grounding-line depth, to allow a
94 more holistic consideration of the glacier geometry beyond the near-terminus
95 region. To quantify the strength of the temporal variables' relationship with ve-
96 locity, we compute their cross-correlation as described below. We interpret the
97 qualitative effect of local topography on velocity variation by analysing spatial
98 patterns in the cross-correlations computed for the temporal variables.

99 **2.2 Catchment data**

100 We produce a one-dimensional time series for each catchment variable. We in-
101 tegrate monthly surface mass balance and runoff derived from Noël et al. (2018)
102 over the Helheim Glacier catchment defined by Mankoff et al. (2020a). The time
103 series of calving front position is a width-averaged distance from an upstream
104 flux gate, identified from satellite imagery with variable temporal resolution
105 (Stearns and Ultee, 2021). For the present study of seasonal to multi-annual
106 time scales, we apply a 10-day smoothing window to the terminus record. We
107 trim all time series to the period for which data is available for all variables:
108 2009-2017. We interpolate a piecewise linear time-continuous function for each
109 time series using the `Interp1d` class of SciPy v1.4.1 (Virtanen et al., 2020, and
110 see Supplementary Text S4). Finally, we sample the interpolated function at
111 a frequency matching the average time between velocity observations: approxi-
112 mately 3 days.

113 To isolate multi-annual variability from shorter-term signals (Section 3.3),
114 we apply a 1-year moving average filter to the surface mass balance, runoff, and
115 terminus position data. The isolated long-term-varying components are shown
116 as light curves in Figure 1E-G.

117 **2.3 Producing temporally continuous velocity functions**

118 We use frequent observations and spline interpolation to produce time-continuous
119 estimates of ice surface velocity. We stack all available InSAR-derived glacier
120 site velocity observations from Joughin et al. (2020) and extract 1-dimensional
121 time series of velocity at points spaced at 1 km intervals along a central flowline
122 (as defined in Felikson et al., 2021). We define an upstream limit to our analysis
123 by the area for which there are sufficient velocity observations to constrain a
124 time-continuous fit. The selected points are shown in Figure 1A-B.

125 We then construct a continuous function that best fits the observed val-
126 ues at each point. Following Riel et al. (2021), we perform a regularized least

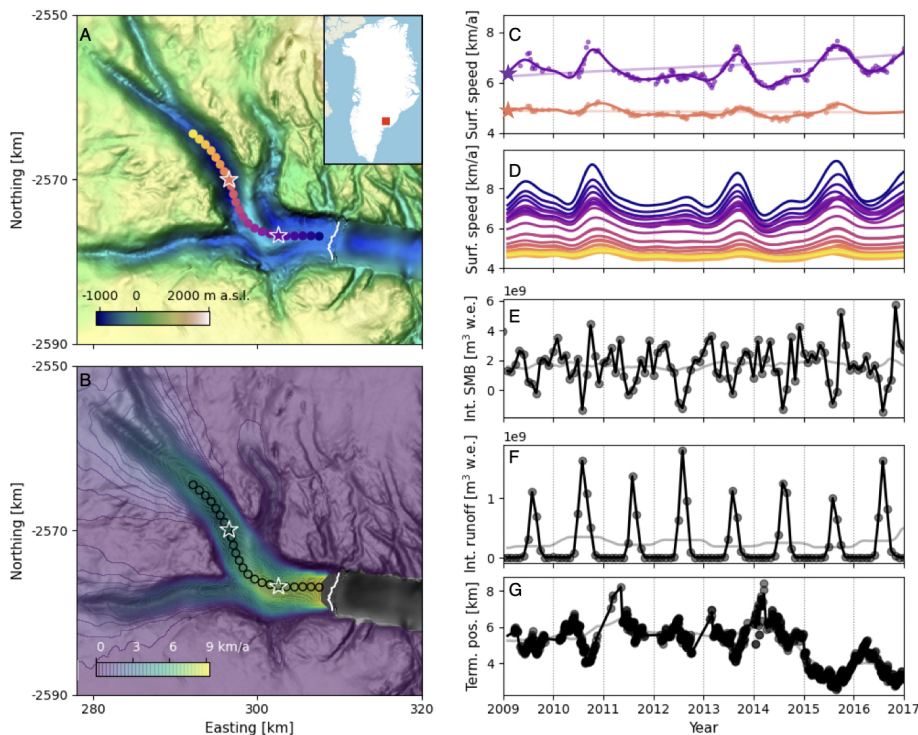


Figure 1: The physical setting of Helheim Glacier studied here. (A) Hillshade map of Helheim Glacier subglacial topography from Morlighem et al. (2017) with 2009 terminal edge from Joughin et al. (2020) in white, points along central flowline in bright colors, and inset map of Helheim Glacier location within Greenland; (B) Mean ice surface speed as of 2016 (ENVEO, 2017), with flowline points outlined; (C) Ice surface speed at two locations (starred on panels A-B) from Joughin et al. (2020) (points) and B-spline smooth approximation to each time series (curves); (D) B-spline continuous velocity functions for each point along the flowline in panel A, with curve color indicating which point is represented; (E) Catchment-integrated surface mass balance from RACMO; (F) Catchment-integrated runoff from RACMO (Noël et al., 2018); and (G) Width-averaged terminus position, relative to a fixed gate on the glacier (larger numbers indicate advance). In panels E-G, data from the original source is plotted as points, and dark lines show the values of 1d-interpolated functions used to determine signal cross-correlation. In panels C and E-G, light curves show the long-term-varying component of each signal. Long-term-varying velocity is shown with a zoomed y axis in Supplementary Figure S5.

127 squares regression that estimates the optimal linear combination of representa-
 128 tive time functions (linear polynomials, B-splines, and integrated B-splines of
 129 pre-defined center times and scales) to fit the data at each point. The result-
 130 ing function is an optimized superposition of linear trend, seasonal variability,
 131 and secular change, which facilitates later decomposition into components of
 132 interest. For example, in Section 3.3 we extract the long-term-varying signal
 133 to analyse cross-correlations of multi-annual change. Example observations and
 134 constructed continuous functions are shown in Figure 1C.

135 2.4 Normalized cross-correlation

136 Finally, we find and compare the cross-correlations describing ice speed response
 137 to each variable at each point. We sample each time-continuous function at reg-
 138 ular intervals. Dickey-Fuller and KPSS tests applied using the Python package
 139 statsmodels v0.12.2 (Seabold and Perktold, 2010) indicate that the raw time
 140 series are non-stationary — that is, their means and/or variances change over
 141 time, which can produce spurious results in cross-correlation analysis (Shumway
 142 and Stoffer, 2017). In sections 3.1-3.2, we enforce stationarity by differencing:

$$f_i = \hat{f}_i - \hat{f}_{i-1}, \quad (1)$$

143 where \hat{f}_i is the i^{th} point in the raw time series and f is the differenced time
 144 series. We elect not to difference the long-term-varying series tested in section
 145 3.3, as doing so would remove the signal of interest.

146 We compute the normalized cross-correlation at lag k ,

$$XCorr(f, v)_k = \frac{1}{N} \sum_{i=1}^N \frac{f_{i+k} - \bar{f}}{\sigma(f)} \frac{v_i - \bar{v}}{\sigma(v)}, \quad (2)$$

147 for $k \in [-N, N]$, where ice speed v and variable f are each time series of
 148 length N , differenced as in Eqn. 1, with means (\bar{v} , \bar{f}) and standard deviations
 149 ($\sigma(v)$, $\sigma(f)$). With this convention, a lag $k < 0$ refers to a cross-correlation with
 150 the velocity series offset backward in time; that is, strong cross-correlations at
 151 negative lag indicate that a change is observed first in the velocity signal and
 152 a similar change is observed later in the variable f signal. The normalized
 153 cross-correlation may take values between ± 1 , and a cross-correlation at lag k
 154 between two signals without autocorrelation is statistically significant at the
 155 95% confidence level if it exceeds $1.96/\sqrt{N - k}$.

156 Each of the signals we study here includes some moderate to strong auto-
 157 correlation. Therefore, we correct the significance limits for each variable by
 158 a factor $\sqrt{(1 + ab)/(1 - ab)}$ where $a = 0.99$ is the lag-1 autocorrelation in the
 159 velocity signal and b is the lag-1 autocorrelation for the variable f , following
 160 Dean and Dunsmuir (2016). Autocorrelation functions and resulting correction
 161 factors for each variable are shown in Supplementary Figure S1.

162 Because we anticipate multiple influences on observed surface velocity, we
 163 do not expect the magnitude of correlations to be close to 1. Rather, we identify
 164 the largest-magnitude statistically significant correlations for each variable at
 165 each point, and we compare their relative strength. From the full time series
 166 (Section 3.1) and then from annual subsets (Section 3.2) and from series filtered
 167 to show only multi-annual variability (Section 3.3), we identify the largest mag-
 168 nitude of cross-correlation between the series and the lag in days at which that

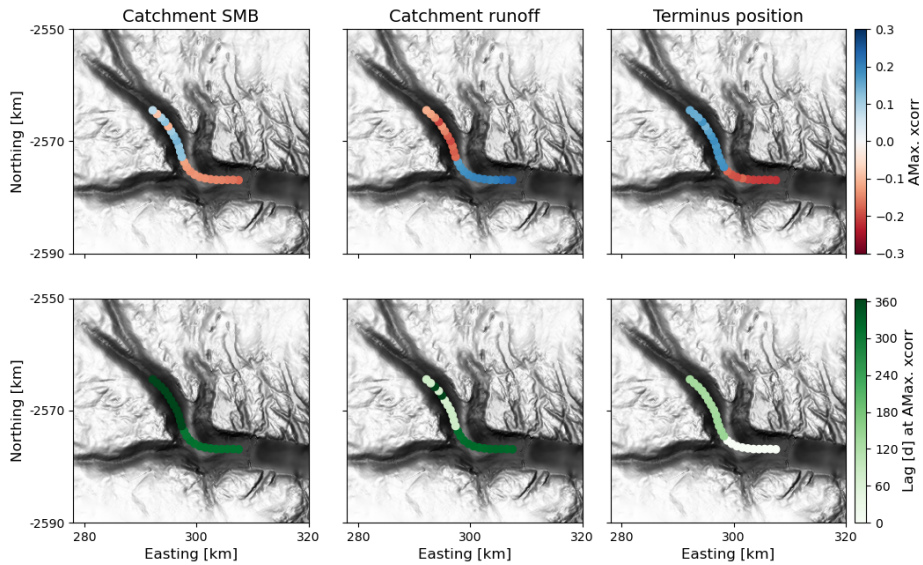


Figure 2: The cross-correlation of largest absolute value (“AMax. xcorr”) (top row) between ice surface speed and each variable (columns), and the lag in days (bottom row) at which that cross-correlation is found. Circles indicate values that are significant at the 95% confidence level; all values plotted here are significant, in contrast with Figure S6. For along-flow view, see Figure S7.

169 extreme value occurs. We restrict our analysis to positive lag values, consis-
 170 tent with determining which variables could be forcing (rather than responding
 171 to) velocity variability at Helheim (Supplementary Text S1). We present full
 172 correlograms with both positive and negative lag values in the supplement.

173 3 Results

174 3.1 Seasonal to interannual velocity variability responds 175 most strongly to runoff

176 The normalized, single-differenced cross-correlations with ice surface speed are
 177 distinct for each variable. The weakest cross-correlations, in terms of mean
 178 magnitude of maximal values along the flowline, are with catchment-integrated
 179 surface mass balance (Fig. 2, left column). For that variable, correlations with
 180 velocity range from -0.17 near the terminus to 0.13 farther up the flowline.
 181 Cross-correlation of ice surface speed with catchment-integrated runoff (Fig.
 182 2, center column) is stronger, ranging from -0.20 to 0.25 . Terminus position
 183 (Fig 2, right column) also shows comparatively strong cross-correlations with
 184 velocity. The strongest correlation is -0.22 , found near the terminus, and the
 185 strongest positive correlation is 0.18 , found 14 km upstream from the terminus.
 186 However, the strongest cross-correlations with terminus position are found at 0
 187 lag at all points on the lower 10 km of the glacier trunk. This suggests that
 188 terminus position and velocity change simultaneously, or influence each other
 189 over time scales shorter than the temporal resolution of our data, such that a

190 clear forcing on velocity by terminus position is not apparent at this scale.

191 At every point, the magnitude of strongest cross-correlation with velocity is
192 larger for runoff than for surface mass balance, on average 1.2 times larger over
193 the flowline, and this difference exceeds the significance limit for most points
194 on the flowline. The cross-correlation between terminus position and velocity is
195 similar in magnitude to that of runoff, but the former may instead be a response
196 to velocity changes. We infer that runoff is at least as important as terminus
197 position in controlling seasonal to interannual ice surface velocity variability
198 along the main trunk of Helheim Glacier.

199 **3.2 No year in which terminus position is more important** 200 **than runoff**

201 Because Helheim Glacier is a complex system that changes over time, the multi-
202 year bulk analysis of section 3.1 may not capture important interannual changes
203 in the dominant sources of its velocity variability. To study year-to-year changes
204 in more detail, we computed the cross-correlation between single-year subsets
205 of the variables we studied in section 3.1. Cross-correlations of these single-year
206 subsets are generally stronger than those found over the full time period.

207 The patterns of cross-correlation between single-year sections of the signals
208 vary from year to year, as shown in Figure 3. For example, in 2009 the cross-
209 correlation between runoff and surface speed for all points along the flowline is
210 strongest at a lag of around 60 days, with a significant minimum following at
211 longer lag times. In 2010, 2011, 2014, and 2016, an initial negative correlation
212 around 60 days lag is followed by a small maximum around 200 days. In 2012,
213 cross-correlations with velocity at different points along the flowline show differ-
214 ent patterns of maxima and minima, for both surface mass balance and runoff.
215 There are statistically significant correlations between runoff and surface speed
216 every year, for every point along the flowline.

217 We find that the normalized cross-correlation of terminus position and ice
218 surface speed is low at every point along the flowline and for almost every year
219 2009-2016. Only four of the eight years we study show correlations signifi-
220 cantly different from zero for one or more points along the flowline. Stronger
221 correlations with terminus position, some of which are significant, are evident
222 for negative lags (Supplementary Figure S3), indicating that terminus position
223 may be responding to velocity variation rather than vice versa. For every year
224 and every point we study, the positive-lag correlation of ice surface speed with
225 catchment-integrated runoff is stronger than that with terminus position. In
226 most years and for most points, the correlation with runoff is stronger than
227 that with terminus position for both positive and negative lags (Figure S3).

228 **3.3 Multi-annual velocity variability correlates with ter-** 229 **minus position**

230 We see a strong and statistically significant correlation between the long-term-
231 varying components of ice speed and terminus position. The correlation between
232 these two component signals is much stronger than between the corresponding
233 full signals (Figures 2, 4 and S6), with values along the lower trunk averaging
234 -0.8 , all for non-negative lags. A cross-correlation stronger than that for the
235 full signals is also seen for long-term-varying surface mass balance, ranging from

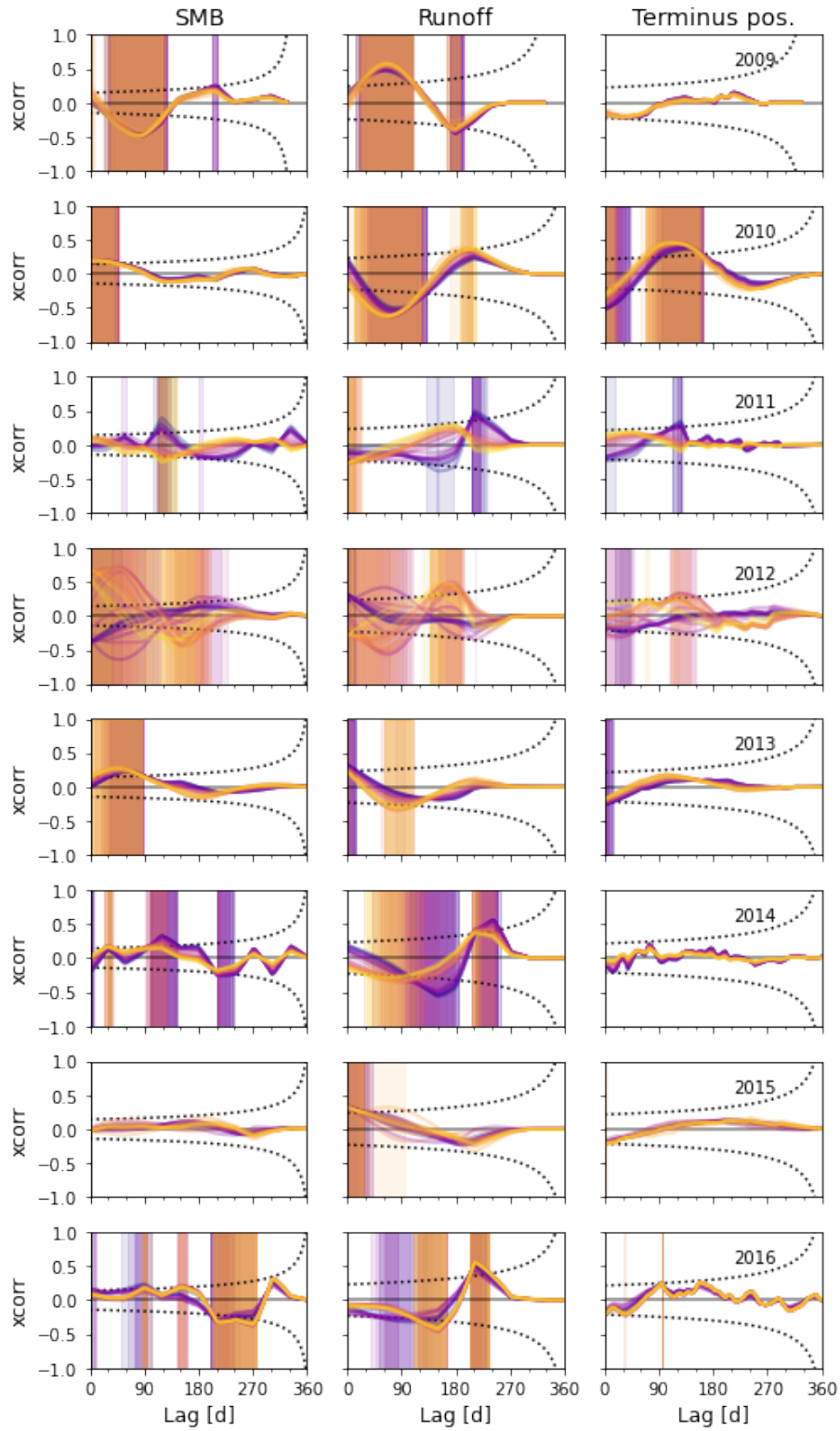


Figure 3: Annual patterns of cross-correlation between surface speed and system variables for (left) surface mass balance, (center) runoff, and (right) terminus position, sampled at 1 km intervals along the flowline shown in Figure 1. Dotted curves indicate 95% confidence intervals around $XCorr(f, v) = 0$, modified for autocorrelated data as described in Section 2.4; shading indicates statistically significant difference from zero. Color of lines and shading indicates location of the example point along the flowline, matching Figure 1A, C, and D.

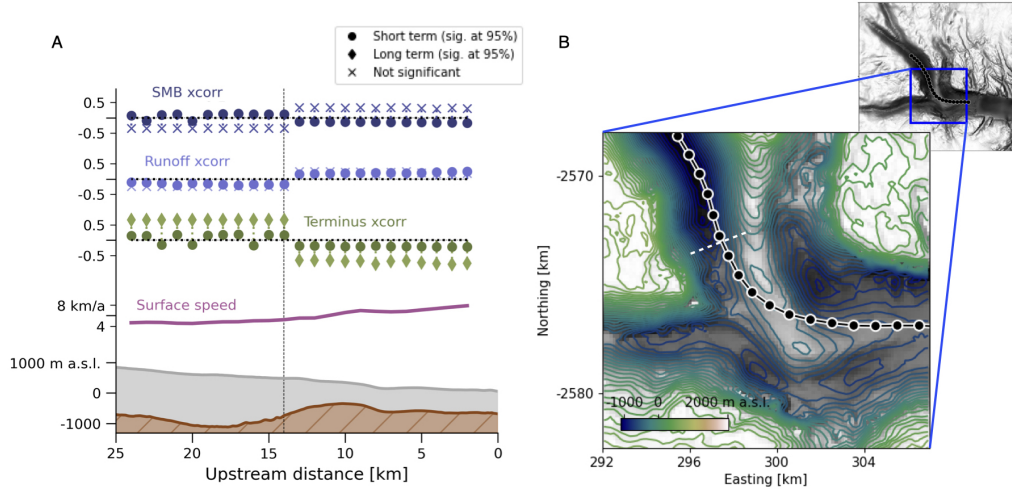


Figure 4: Influence of a subglacial ridge on Helheim Glacier dynamics. A) Ice speed cross-correlation with each variable tested, for each point along the flowline, vertically offset for legibility. Variable labels coincide with zero cross-correlation and minor ticks indicate $XCorr(f, v) = \pm 0.5$. Darker circles are cross-correlations of the full signals (as reported in Figure 2 and Section 3.1). Lighter diamonds show results filtered to isolate long-term variability (as in Section 3.3 and Figure S6). Results not significantly different from 0 are assigned a cross marker, as in Figure S6. Lower portion shows bed topography (brown), ice surface (grey), and mean surface speed (purple) along the flowline. Vertical marker indicates position of sign changes in cross-correlation for multiple variables. B) Enlarged contour map of the Helheim Glacier trough around the bedrock bump. Outlined points show locations where velocity was extracted along the flowline; a dashed white line across the direction of flow indicates the approximate location of the dashed line in panel A. Background image is a black and white hillshade of the topography as in Figure 2; contours show intervals of approximately 60 meters elevation. Contour colormap and flowline points (black) are consistent with Figure 1A.

236 -0.54 to 0.54, but due to strong autocorrelation none of the values is significantly
 237 different from 0. The correlation between long-term-varying components of ice
 238 speed and runoff is comparable to that between the full signals, ranging from
 239 -0.29 to 0.29, but not significantly different from 0. We infer that terminus
 240 position variability is the only one of our variables that is important for Helheim
 241 Glacier’s dynamics at multi-annual time scales (here 2009-2017).

242 3.4 Subglacial topography modulates velocity response to 243 each variable

244 The flowline we examine flows through a trough with a pronounced ridge in its
 245 subglacial topography. The ridge creates a steep along-flow thickness gradient
 246 as well as a lateral constriction (Figure 4B). For all three variables, the flowline
 247 separates into two segments with opposite sign of maximum cross-correlation.

248 We find changes in sign of absolute maximum cross-correlation with velocity at
249 14 km upstream from the terminus—coincident with the upstream edge of the
250 subglacial ridge (Figures 2, 4, and S6). We also find step changes in the lag
251 at peak cross-correlation aligned with the ridge. The spatial pattern of cross-
252 correlation is similar for both seasonal and multi-annual signals (Sections 3.1-
253 3.3). These patterns suggest that the dynamics of the upstream and downstream
254 segments of the flowline are fundamentally different from one another. We
255 interpret that the bedrock ridge is an obstacle to the propagation of traveling
256 waves (Nye, 1960; Fowler, 1982; Weertman and Birchfield, 1983). For example,
257 adjustment in the glacier stress balance due to changes in ice accumulation
258 (related to surface mass balance) would propagate as a kinematic wave from
259 the accumulation zone to the ablation zone, and that wave could be obstructed
260 by the vertical and lateral constriction of the ridge. Similarly, changes at the
261 terminus can initiate upstream-propagating kinematic (Felikson et al., 2021) or
262 dynamic waves (Amundson et al., 2022), which could be slowed by the steeper
263 bed slopes around the ridge. We would also expect wave-like propagation of
264 changing basal friction due to seasonal runoff input. The bedrock ridge modifies
265 bed slope and ice overburden pressure, which will modify the hydraulic potential
266 gradient and therefore also the direction of subglacial water flow around it.

267 4 Discussion

268 Our analysis illustrates that Helheim Glacier is a dynamic system with more
269 than one important control on its velocity. We find that seasonal-scale variations
270 in ice surface speed respond more strongly—that is, have larger cross-correlation
271 values at strictly positive lag times—to catchment-integrated runoff than to
272 terminus position, for the full period 2009-2017 (Figure 2) and for every year in it
273 (Figure 3). At the multi-annual scale we find stronger correlation with terminus
274 position than with runoff (Figure 4), in agreement with earlier work relating
275 ice velocity to ice thickness and glacier terminus position on Alaskan tidewater
276 glaciers (Meier and Post, 1987; O’Neel et al., 2005). Our results support previous
277 findings that increasing meltwater supply can enhance seasonal speedups in
278 ice flow, but does not contribute to multi-annual acceleration (summarized in
279 Nienow et al., 2017). Our analysis also supports the hypothesis of Enderlin
280 et al. (2018) that distinct variables could drive different timescales of velocity
281 variability at Columbia Glacier, Alaska.

282 It is tempting to attribute physical meaning to the lag times of strongest
283 cross-correlation. For example, the 60-day lag time in cross-correlation between
284 runoff and ice surface speed that we observe in many years (Figure 3) could
285 reflect the time required for water input to induce large-scale changes in sub-
286 glacial water pressure, and therefore ice sliding velocity. That interpretation
287 would agree with the model results of Poinar et al. (2019), who applied low-
288 elevation meltwater input to an idealized Southeast Greenland outlet glacier
289 and found that domain-averaged subglacial water pressure peaked 60 days into
290 the melt season. The range of lag times for the handful of significant cross-
291 correlations between speed and terminus position, 3-100 days, also aligns with
292 theoretical results on the speed of dynamic wave propagation upstream from
293 a calving terminus (Amundson et al., 2022). However, we caution that single-
294 differencing the signals in Sections 3.1-3.2 produces different phase shifts in

295 signals with different shapes (Supplementary Text S3 and Figure S4), which
296 complicates the interpretation of lag times. We therefore refrain from more
297 detailed interpretation of the lag times.

298 The correlation of runoff with seasonal-scale velocity variation described in
299 Section 3.1 is consistent with observations of land-terminating margins of the
300 Greenland Ice Sheet (Joughin et al., 2008) and some marine outlets on Green-
301 land’s west coast (Sole et al., 2011; Moon et al., 2015), as well as inference
302 of surface-melt-induced acceleration (Andersen et al., 2011) and dynamic thin-
303 ning (Bevan et al., 2015) at Helheim. Because we analyse remote sensing and
304 climate model output data, the significant cross-correlations we find are at sea-
305 sonal and longer timescales; this complements the shorter-timescale correlations
306 previously found in field data (Nettles et al., 2008; de Juan et al., 2010; An-
307 dersen et al., 2010, 2011; Stevens et al., 2022). In agreement with Kehrl et al.
308 (2017), we find that 2010 and 2013 are the years for which ice surface speed at
309 Helheim is most correlated with terminus position (Fig. 3 and S3). However,
310 our quantitative comparison shows that, in all years, Helheim’s speed is at least
311 as correlated with runoff as with terminus position.

312 Our conclusions differ from previous studies including Moon et al. (2014)
313 and Vijay et al. (2019), which infer that terminus changes are the strongest
314 control on Helheim’s velocity during most years. Moon et al. (2014) studied
315 Helheim terminus changes for the time period from 2009 to 2013 and Vijay
316 et al. (2019) studied Helheim terminus changes for the time period from 2015 to
317 2017. Despite contrasting conclusions, we identify some overlap in our findings.
318 For example, Moon et al. (2014, in their supplemental figure S35) find that
319 terminus position was the primary control on velocity in 2010, and our results
320 show that correlation between velocity and terminus position was strongest in
321 2010 (Fig. 3). In 2015 and 2016, we find strong correlation between velocity and
322 runoff and weaker correlation between velocity and terminus positions, and in
323 those years the time series presented in Vijay et al. (2019, in their supplemental
324 figure S28) show seasonal acceleration at Helheim appearing to coincide with
325 melt onset and little change in terminus. We attribute our differing conclusions
326 in part to contrasting methods: our approach focuses on statistically significant
327 cross-correlations at a single glacier, while Moon et al. (2014) and Vijay et al.
328 (2019) manually identified relationships within the context of a larger set of
329 Greenland outlet glaciers.

330 The relative importance of each driver at Helheim Glacier likely does not
331 translate to other outlets or other time periods. For example, our findings
332 at Helheim contrast those of King et al. (2020), who found that regionally
333 aggregated trends in Greenland Ice Sheet discharge correlated most strongly
334 to glacier front position. Ice velocity at Helheim may be unusually sensitive
335 to catchment-integrated runoff because of the presence of a large firn aquifer
336 that allows hydrofracturing of deep crevasses and enhances deformational ice
337 motion (Poinar et al., 2017; Miller et al., 2020). The lower trunk of the glacier
338 was also near flotation during the time period we study here (Kehrl et al.,
339 2017), which could render it especially sensitive to both changing basal water
340 pressure (runoff) and calving activity (Andersen et al., 2010; Cassotto et al.,
341 2019). Finally, the spatial pattern of our results highlights the role of unique
342 subglacial topography in shaping the dynamic response to forcing (Enderlin
343 et al., 2013, 2018; Khan et al., 2014; Felikson et al., 2017, 2021; Catania et al.,
344 2018).

345 One explanation for the comparatively weak positive-lag correlation between
346 seasonally varying ice surface speed and terminus position throughout our study
347 period is that the sensitivity of surface speed to terminus position is itself deter-
348 mined by the terminus position (Cassotto et al., 2019), and that the terminus
349 did not reach a hypothetical critical position during the time we observed. From
350 2009-2014, the observed terminus positions oscillated around a steady mean po-
351 sition at approximately 6 km forward of our reference position; a period of
352 multi-annual retreat beginning in late 2014 reflects a multi-annual acceleration
353 on the lower glacier trunk beginning around the same time (Figure 1D and G). If
354 the terminus had reached a critical position that increased the sensitivity of sur-
355 face speed to terminus change, we would expect to see change in the correlation
356 between those variables as terminus position changed over time. Instead we find
357 that the annual cross-correlation between surface speed and terminus position
358 is no stronger in 2015 and 2016 than in previous years (Figure 3). In several
359 years throughout the 2009-2017 period, there are significant cross-correlations
360 between ice surface speed and terminus position, but they occur at negative lag
361 times (Figure S3). That suggests that terminus position is responding to, rather
362 than driving, seasonal velocity variability.

363 A second explanation for the weak correlation between ice surface speed and
364 terminus position is that iceberg calving is episodic and discontinuous. Field
365 observations of Helheim Glacier at finer temporal scales than we study here
366 have found that calving activity was an important control on velocity at the
367 timescale of minutes to hours (Nettles et al., 2008; de Juan et al., 2010), and
368 that runoff during the melt season contributes to daily velocity increases (An-
369 dersen et al., 2010, 2011; Stevens et al., 2022). Thus, even with our temporally
370 dense records—average 3 days between measurements—we may more realisti-
371 cally expect to see responses to runoff than to iceberg calving. Further, we
372 analyse a width-averaged terminus position, which will not capture differing
373 dynamic responses to iceberg calving at different points along the face. Extend-
374 ing our methodology to analyse the fine spatial and temporal scales captured in
375 field observations could provide a fuller picture of the forcings driving velocity
376 variability (building on Podrasky et al., 2012, for example).

377 In this work, we have assumed that terminus position evolves independently
378 from catchment-integrated runoff. This choice ignores the established connec-
379 tion between calving rate and subglacial discharge at the terminus (Bartholo-
380 maus et al., 2013; Cook et al., 2014; Slater et al., 2015; Fried et al., 2018; van
381 Dongen et al., 2020). Modelling efforts suggest that the calving response to
382 subglacial discharge depends on the subglacial hydrologic system near the ter-
383 minus, in particular whether melt is localized to channels (Slater et al., 2015;
384 Todd et al., 2018; van Dongen et al., 2020). Subglacial discharge also affects
385 calving through its influence on the vertical pattern of submarine melt (Motyka
386 et al., 2003; Jenkins, 2011; O’Leary and Christoffersen, 2013; Luckman et al.,
387 2015; Slater et al., 2015; Ma and Bassis, 2019). However, recent observations
388 have found no evidence for a melt-induced enhancement of calving at Helheim
389 Glacier, perhaps because of its broad and deep terminus (Everett et al., 2021).
390 As additional observations of the near-terminus environment become available,
391 future work may apply multivariate statistical methods to assess whether runoff
392 and calving activity reinforce or oppose one another in forcing ice surface veloc-
393 ity variability.

394 Although we have focused here on cross-correlations unique to Helheim dur-

395 ing the 2009-2017 period, our methods can be used to investigate any glacier
396 with a sufficient observational record. The statistical inference approach can
397 also be applied to time series generated by different interpolation methods (e.g.
398 Shekhar et al., 2020). We do not anticipate a strong dependence of the cross-
399 correlation results on interpolation method (Supplementary Text S3). Never-
400 theless, future studies could benefit from more sophisticated data processing or
401 more detailed numerical modelling than we have presented here. For example,
402 we produced time series of both surface mass balance and runoff integrated over
403 the whole Helheim catchment. We suspect that integrating both fields over only
404 the portion of the catchment that is upstream of each point along the flowline
405 would provide more spatially refined information. The advantages to be gained
406 by additional data processing, however, should be weighed against the major
407 uncertainties remaining from unconstrained processes. For example, our work
408 has not accounted for the changing state of the en/subglacial hydrologic system
409 over the melt season, nor for the effect of the Helheim catchment’s firn aquifer
410 (Miller et al., 2020) on both glacial hydrology and dynamics. To do so would
411 likely require the use of a glacial hydrology model (such as Werder et al., 2013).
412 Future efforts could also explore the use of Bayesian methods to account for un-
413 certainties in climate-model-derived runoff, which can be as large as 20% (van
414 As et al., 2018; Noël et al., 2019).

415 The eight-year period of overlapping observations we studied, 2009-2017,
416 necessarily limits our ability to resolve longer-term variability that may be im-
417 portant for glacier dynamics. For example, we found that surface mass balance
418 had the lowest cross-correlations with velocity among the three variables we
419 tested, but that finding does not preclude surface mass balance driving velocity
420 variation at decadal and longer time scales. Ice core and radar reconstruc-
421 tions have shown that Greenland surface mass balance varies at multi-annual
422 to multi-decadal time scales, correlated with the North Atlantic Oscillation, At-
423 lantic Multidecadal Oscillation, and Greenland Blocking Index (Mernild et al.,
424 2015; Lewis et al., 2017). The known long-term variability of surface mass bal-
425 ance, combined with Helheim Glacier’s large accumulation area and the long
426 climatic response time of glacier flow (Nye, 1960; Harrison et al., 2001), suggest
427 that correlations between surface mass balance and ice velocity may well be
428 found in records longer than those we have studied here.

429 Our results show that numerical ice flow modeling experiments will require
430 multiple forcing mechanisms to capture the dynamics of Helheim Glacier. Sev-
431 eral state-of-the-art studies, including the standard experiments performed by
432 several numerical models as part of the the Ice Sheet Modeling Intercomparison
433 for the Coupled Model Intercomparison Project Phase 6 (“ISMIP6”, Nowicki
434 et al., 2020), have used projections of outlet glacier terminus positions to force
435 Greenland Ice Sheet mass change simulations (Choi et al., 2017; Morlighem
436 et al., 2019). Our results show that this approach is a good strategy for pro-
437 jections of multi-annual changes of glaciers like Helheim. However, if future
438 ice sheet modeling efforts seek to reproduce seasonal velocity changes, runoff
439 forcing must be included. The continued development of subglacial hydrology
440 models (Pimentel and Flowers, 2011; Werder et al., 2013) and efforts to couple
441 them with ice dynamics models (Aschwanden et al., 2016; Brinkerhoff et al.,
442 2021) are therefore vital to refining our understanding of the future evolution
443 of the Greenland Ice Sheet.

444 5 Conclusions

445 We have computed normalized cross-correlations between three catchment vari-
446 ables (surface mass balance, runoff, and terminus positions) and ice surface
447 speed of Helheim Glacier, revealing the dominant controls on velocity variabil-
448 ity at multiple time scales. We find that ice speed responds most strongly to
449 catchment-integrated runoff at seasonal scale. The strongest cross-correlations
450 between ice speed and terminus position occur at 0-day or negative lag times,
451 suggesting that terminus position is responding to rather than driving seasonal
452 velocity variability. At multi-annual scale, ice speed variability shows stronger
453 correlation with terminus position change. We find distinct patterns in corre-
454 lation along upstream and downstream portions of the glacier trunk, separated
455 by a subglacial ridge. The time scale separation of major sources of variability,
456 and the role of underlying topography, are important considerations in design-
457 ing numerical ice flow simulators to project the future evolution of large outlet
458 glaciers.

459 Data availability

460 Terminus position data is available as a supplement to this manuscript and de-
461 posited at Zenodo <https://doi.org/10.5281/zenodo.5062050>. MEaSUREs
462 velocity data is publicly available through the National Snow and Ice Data
463 Center: <https://nsidc.org/data/NSIDC-0481/versions/1>

464 Code availability

465 All code used in this analysis is available via GitHub and archived on Zenodo.
466 Construction of the time-continuous velocity functions: <https://doi.org/10.5281/zenodo.4474829>.
467 Along-flowline data extraction and cross-correlation: <https://doi.org/10.5281/zenodo.4707999>.
468 Data pre-processing and visual-
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473 derived terminus positions and guided its interpretation. BR developed soft-
474 ware used to construct time-continuous velocity functions. LU performed quan-
475 titative analysis and produced manuscript figures. LU and DF drafted the
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