



Horizontally Oriented Inflatable Deep Space Habitat

Oklahoma State University



OSU Xhab 2013

OSU XHab Team

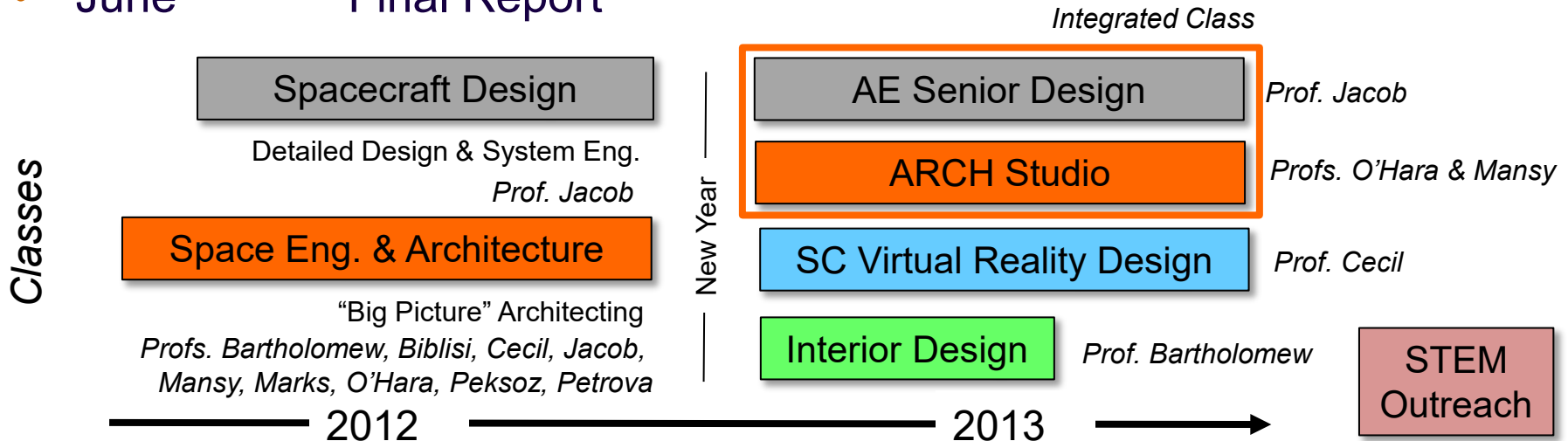
*School of Mechanical & Aerospace Engineering
Oklahoma State University*

Final Report



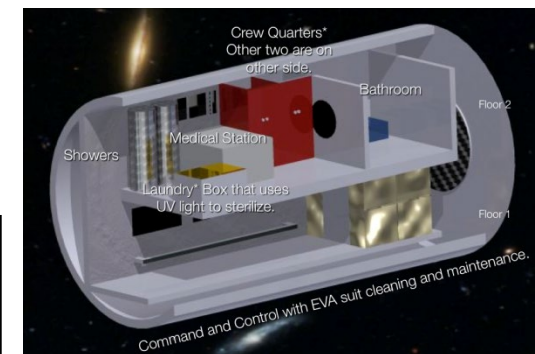
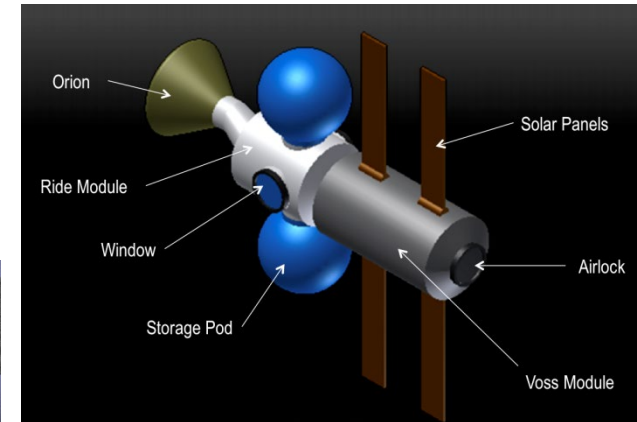
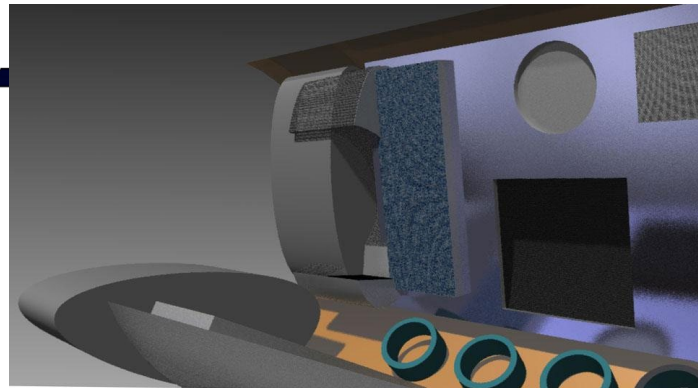
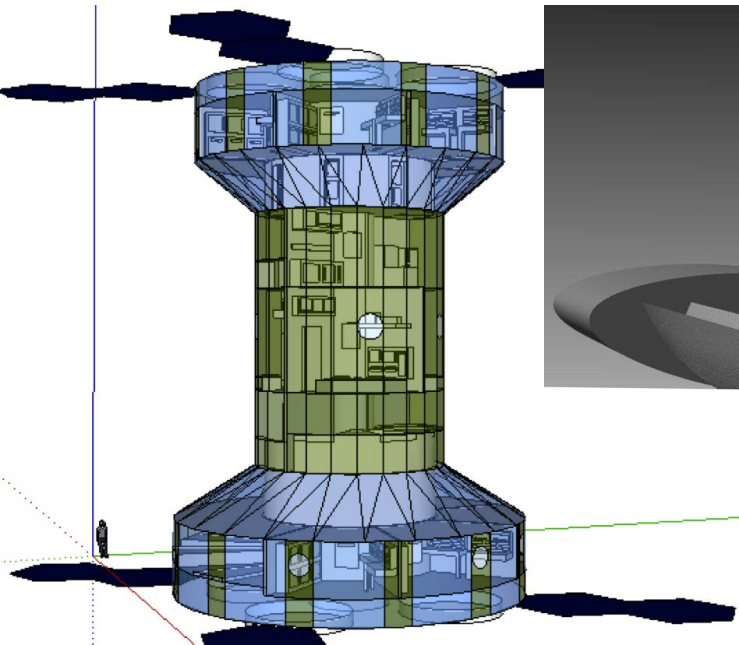
Schedule

- Aug. 22 Space Engineering & Architecture Kickoff
- Oct. 23 SDR
- Nov. 27 PDR
- Dec. 13 CDR
- Jan. 15 Detailed Design Complete, Start Analog Construction
- Feb. 28 Progress Checkpoint Review 1
- Mar. 28 Progress Checkpoint Review 2
- *March/April Visit to NASA MSFC*
- May Demonstration
- June Final Report



Outreach

- High School Space Habitat Innovation Challenge
- 25 groups involved (~125 students) from NASA INSPIRE and Explorer Schools
- 7 teams submitted proposals; down selected to top 3 – final presentations next week



- <https://www.youtube.com/watch?v=HHiAezyBI-k>



- Visit to MSFC in April and June

Team Members

Calvin Brown (Aero/Mech)

Chief Engineer

Kyle Bruggemeyer (Aero/Mech)

Electrical Sys.

Caleb Goulden (Aero/Mech)

Electrical/HVAC Sys.

Aaron Guthridge (Arch)

HVAC Sys.

Ethan Scott (Aero/Mech)

HVAC Sys.

Sam Rose (Aero/Mech)

HVAC Sys.

Colt Wilkens (Electrical Eng)

Electrical Sys.

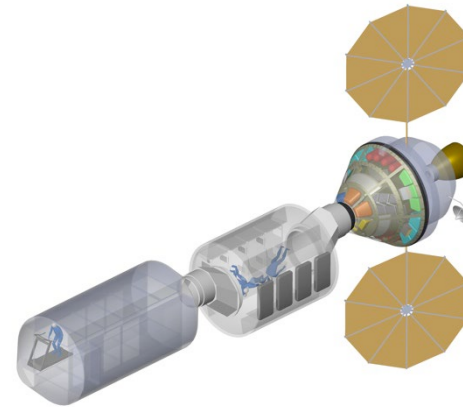
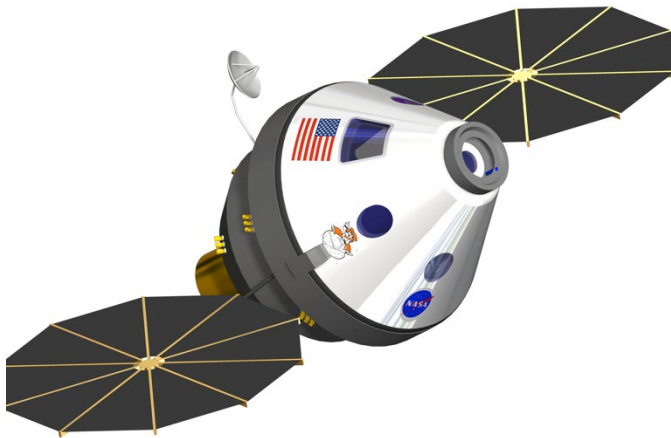
Ben Loh (Aero/Mech)

Virtual Reality/Teaching Assistant



Habitation Functionality

- Provide Living Accommodations for crew members for extended mission duration
 - *4 crews members on 60 day mission at Earth-Moon L2*
- 'Core module' based on ISS Node 1 with avionics, power and simple air handling only -- will borrow ECLSS life support from the MPCV capsule or the 'augmentation module'
- 'Augmentation module' based on a Multipurpose Logistics Module with a closed ECLSS (life support system)



STAFFORD DEEP SPACE HABITAT

POGUE

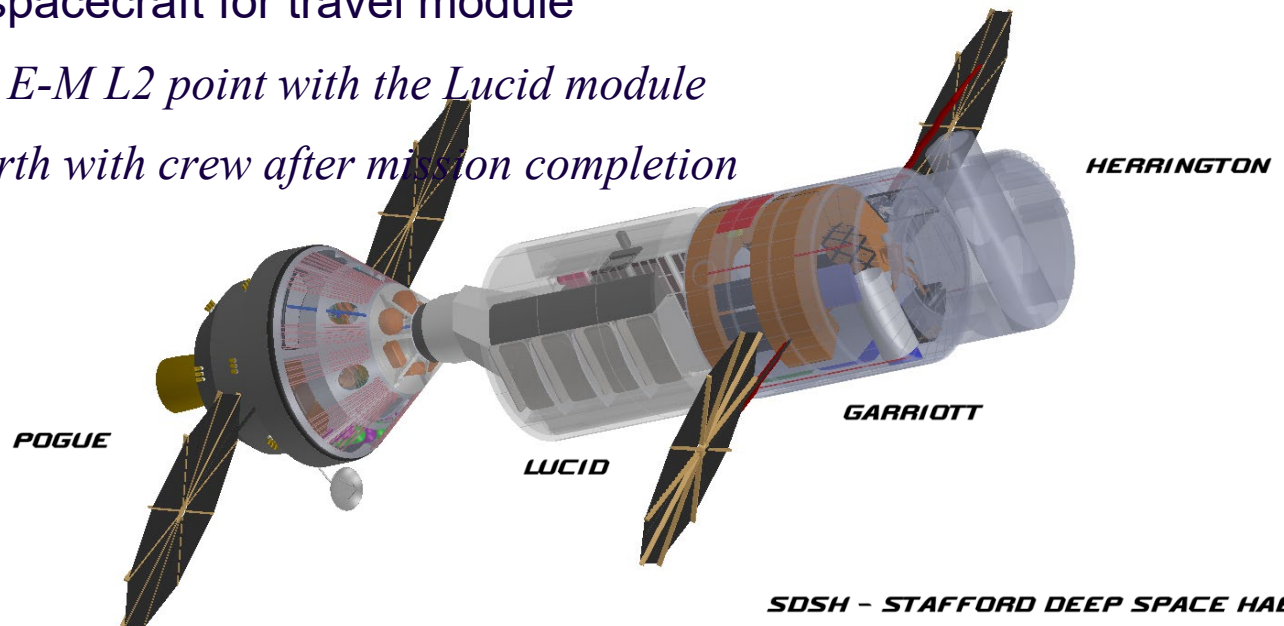
LUCID

GARRIOTT

HERRINGTON

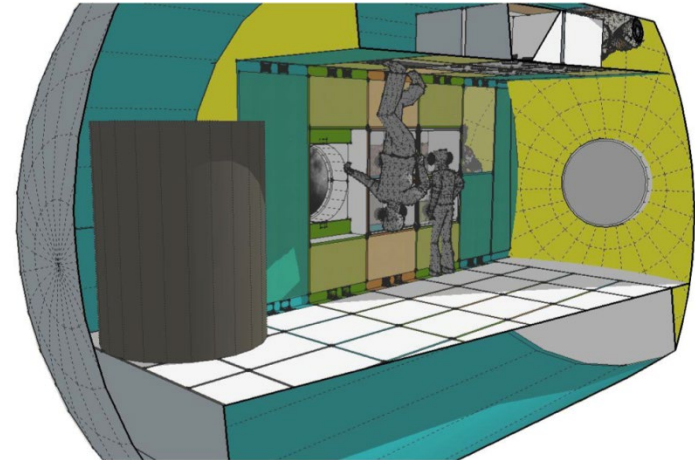
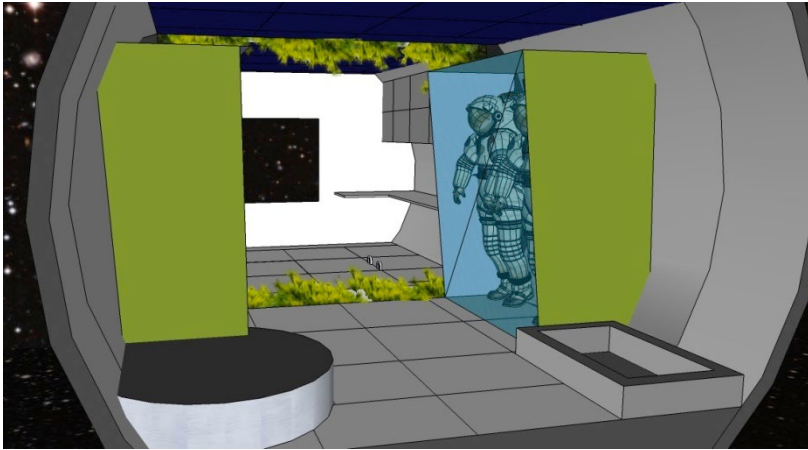
SDSH - STAFFORD DEEP SPACE HABITAT

- Lucid (Node 1) as the living module
 - *This will contain the galley and all sleeping quarters*
 - *It will be attached to Pogue during transit*
 - *Left at E-M L2 with Garriott*
- Garriott (MPLM) for labs and equipment
 - *Contains separate life support system for extended use*
 - *Stays at E-M L2 with Lucid module*
- Pogue (MPCV) spacecraft for travel module
 - *Travels to the E-M L2 point with the Lucid module*
 - *Returns to Earth with crew after mission completion*



Interior Design

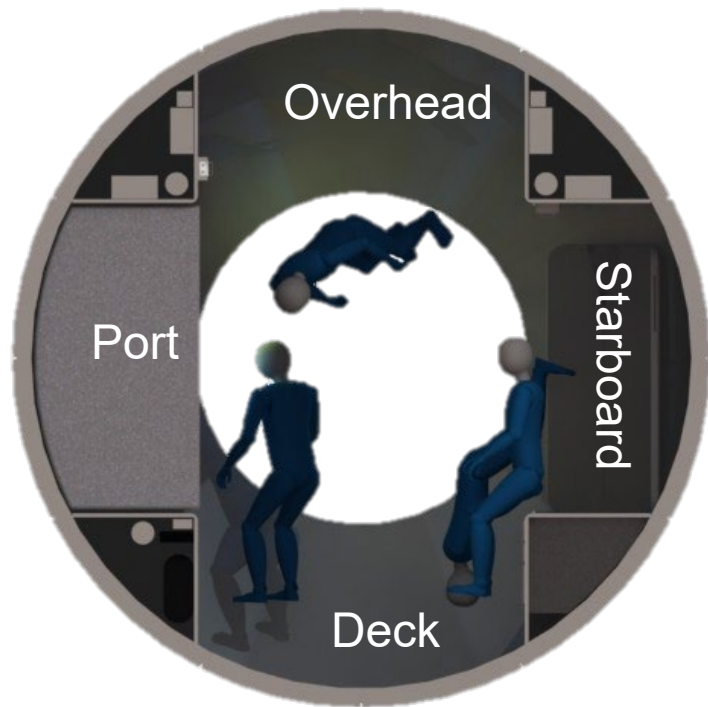
- Interior design presentations on Feb. 5
- Focus on overall interior design concepts for Node 1 and MPLM



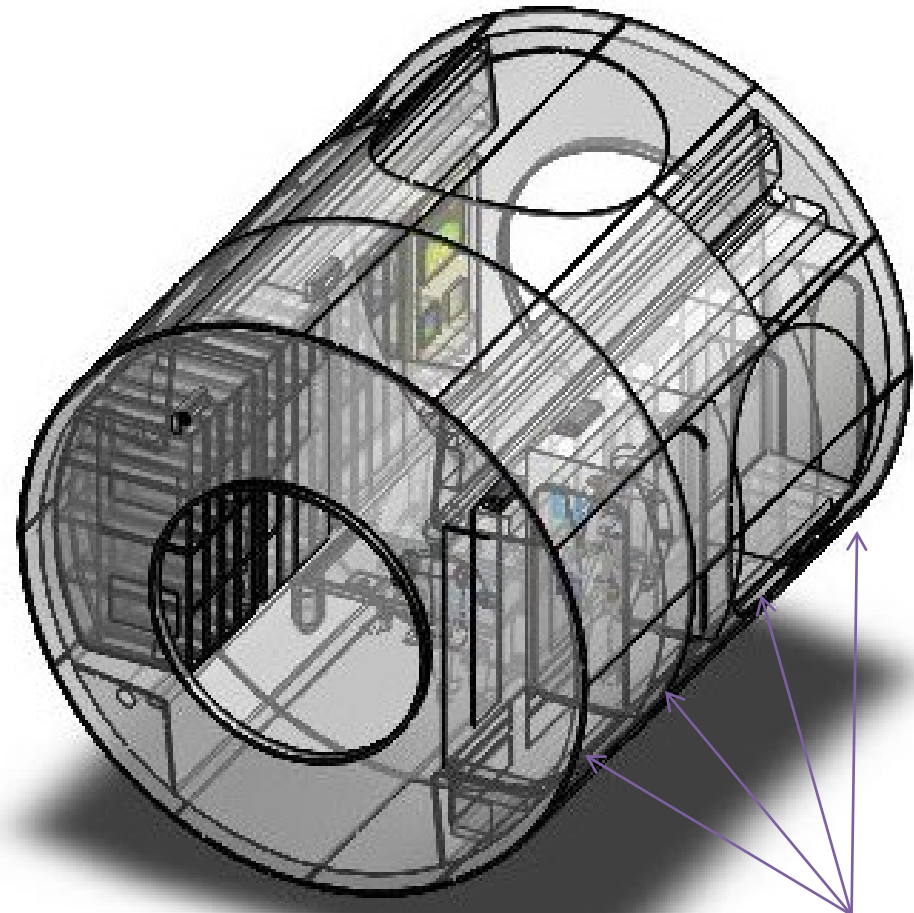
- Individual presentations can be viewed at the links below:
 - http://ra.okstate.edu/STW_HES/NASA_Presentations/Atlas/video.html
 - http://ra.okstate.edu/STW_HES/NASA_Presentations/Group4/video.html
 - http://ra.okstate.edu/STW_HES/NASA_Presentations/Luna/video.html
 - http://ra.okstate.edu/STW_HES/NASA_Presentations/Rhea/video.html
 - http://ra.okstate.edu/STW_HES/NASA_Presentations/Group3/video.html

Node 1 (Original Design)

OSU Xhab's Node 1



Front Plane View



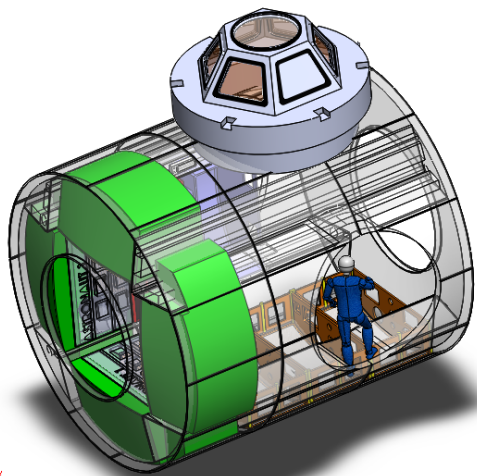
Abstract Profile View

Sleeping Quarter

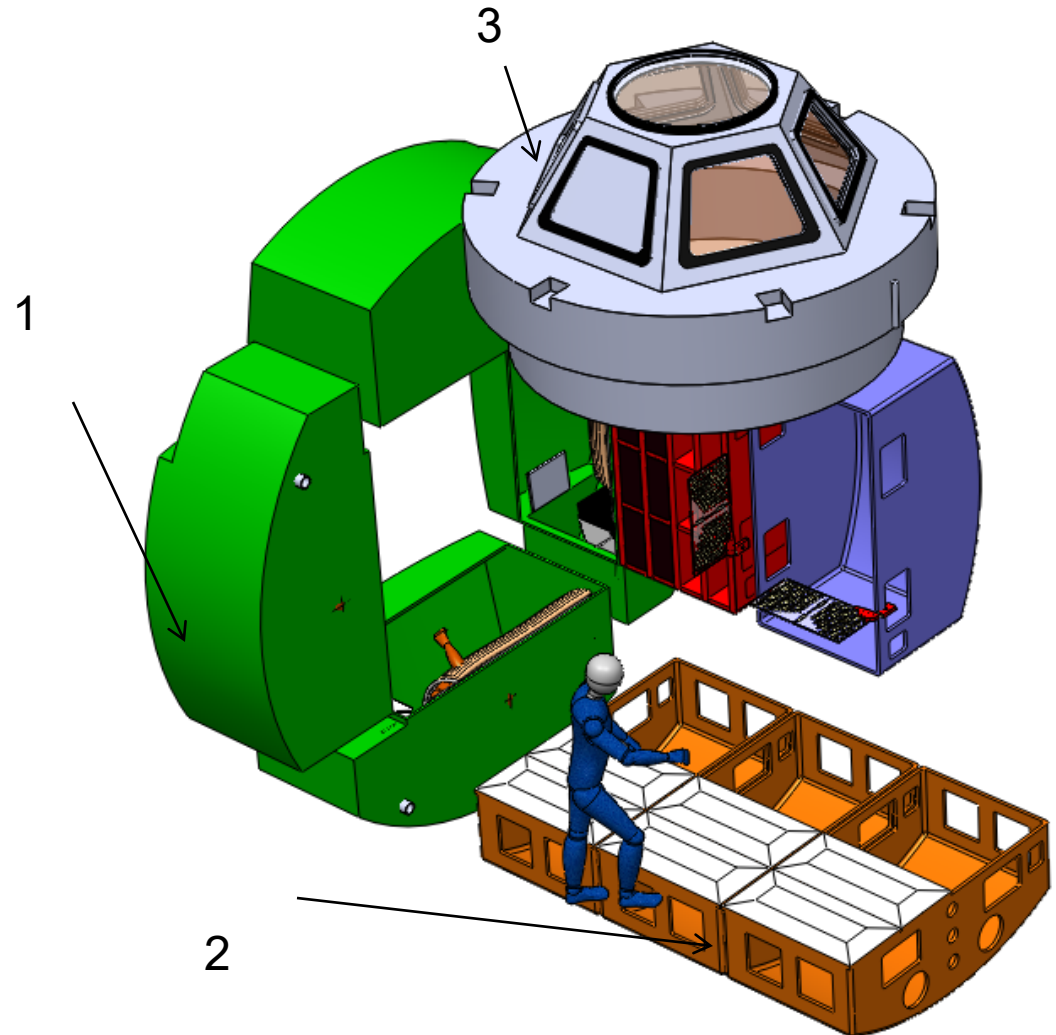
Team Node 1 (Overview)

Goal: Enhance OSU Xhab's components in Node 1 and create virtual environment to simulate astronaut's activities

1. Sleeping Quarter
2. Floor Storage Rack
3. Added Cupola



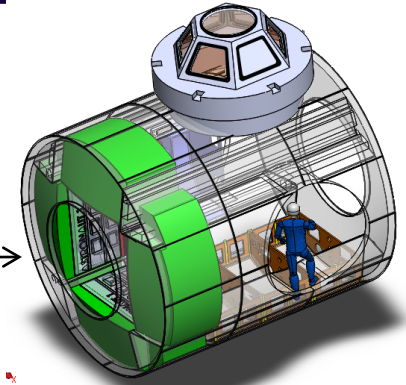
Overview



Sleeping Quarter “Box”

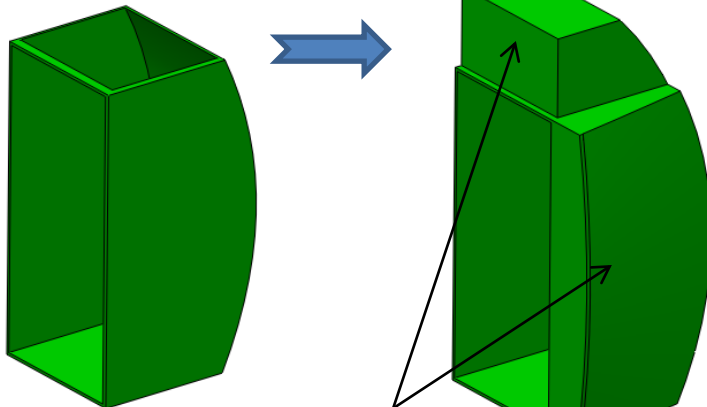
- ❑ **Original design concerns**
 - ❖ Rack bay design
 - ❖ Acoustic and lighting disturbance
 - ❖ Proper air circulation prevent asphyxiation

End of the dome →

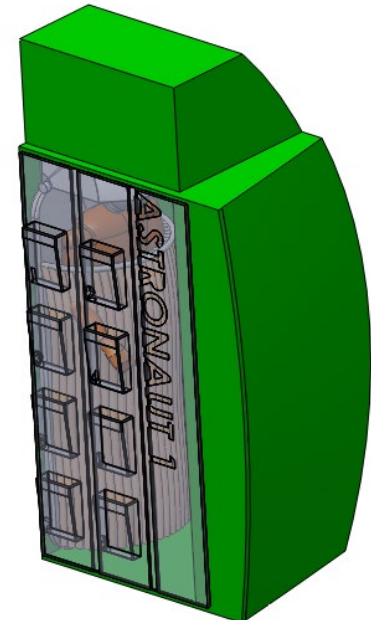
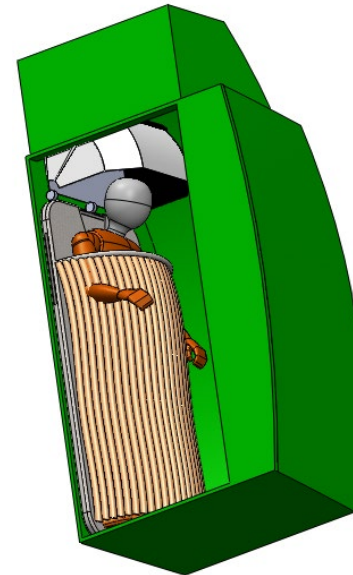


- ❑ Re-located at the end-dome
- ❑ Hinged composite door panels with storage pockets

Original Design (2m³)

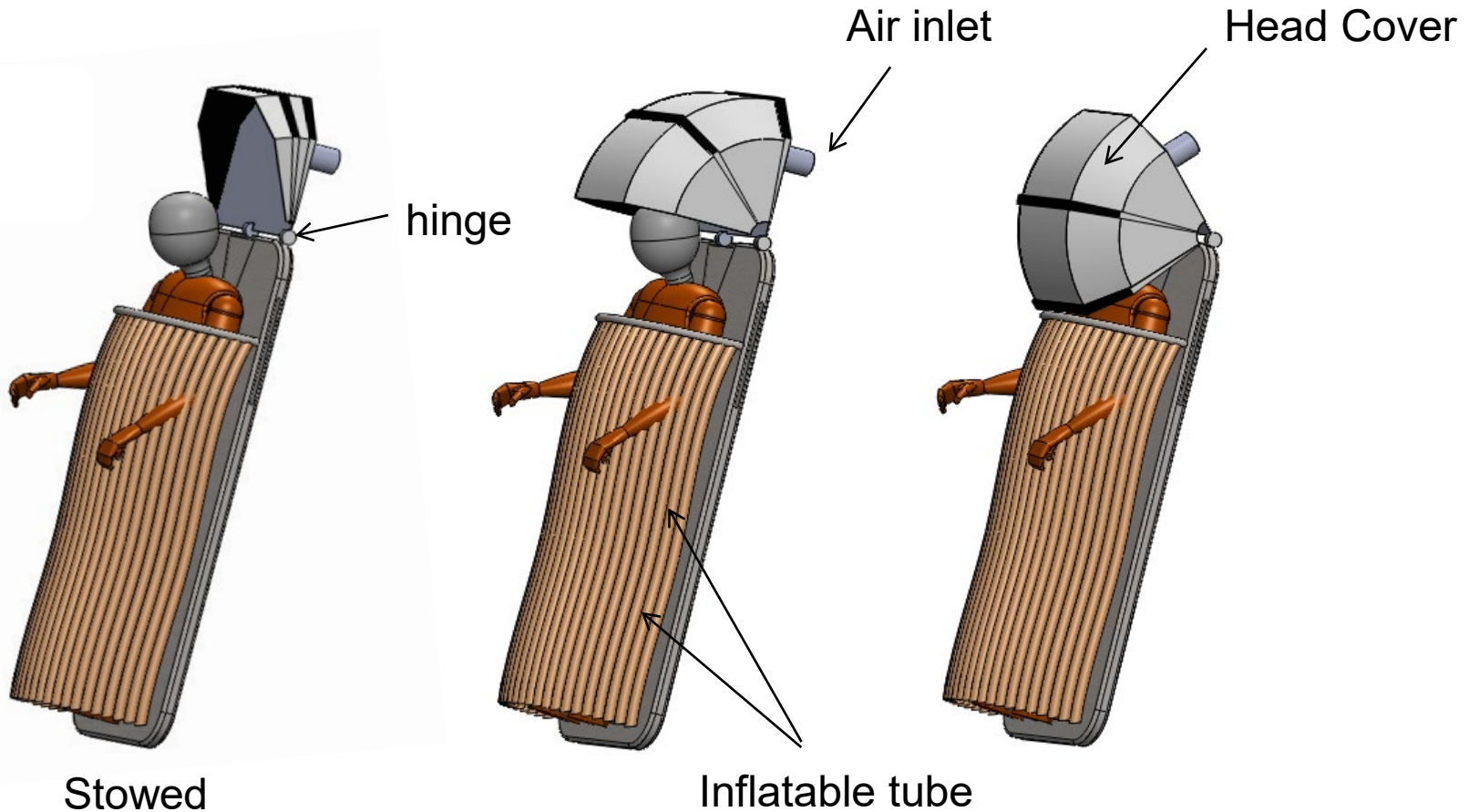


Added Volume (~40%)



Sleeping Head Cover

- ❑ A foldable head cover made of acoustic fabric/foam
- ❑ Completely cover the astronauts head and partial upper body section
- ❑ Air will flow into the cover to enhance air quality
- ❑ Blanket made of series of inflatable tubes with adjustable air pressure



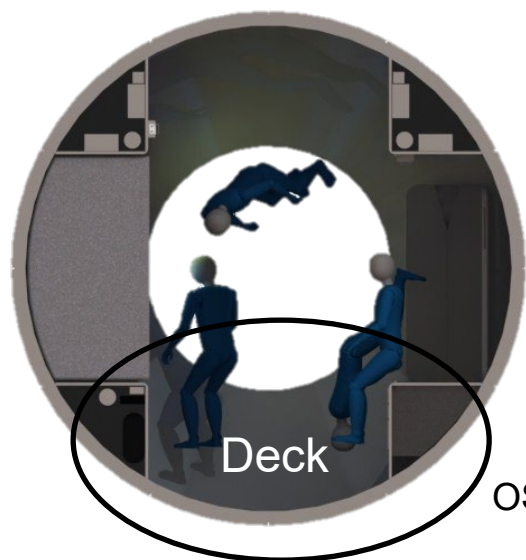
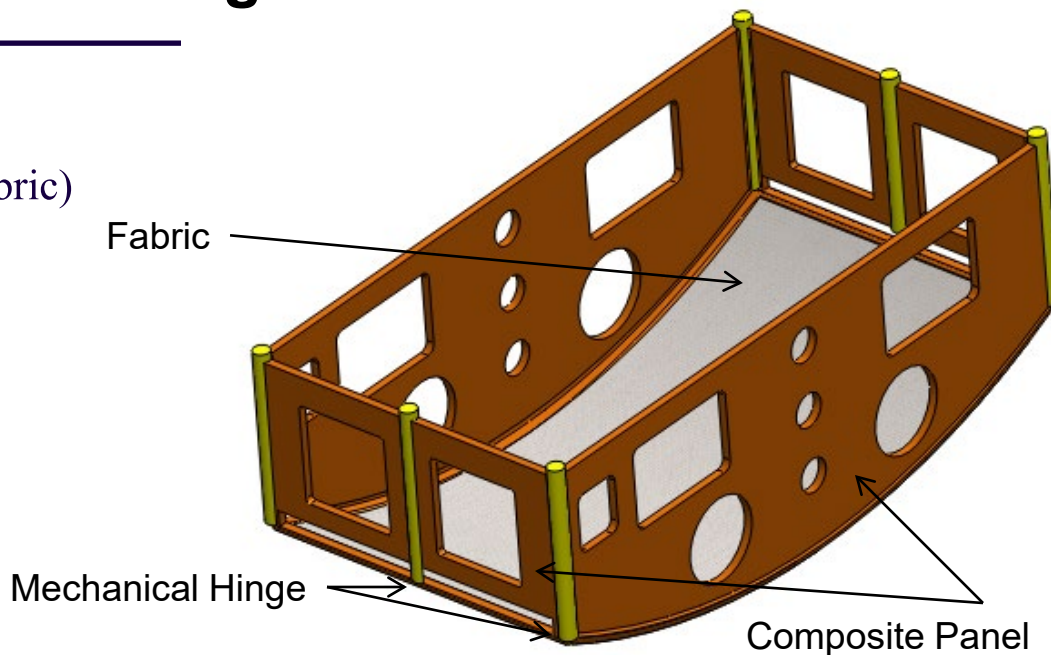
Floor Storage Rack

Utilize floor space

- ❖ Lightweight (composite panel + fabric)
- ❖ Foldable

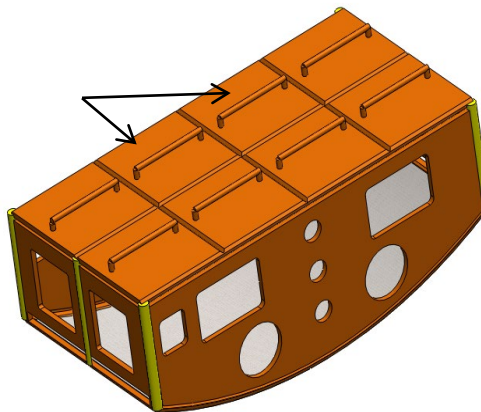
Multiple storage components

- ❖ Space suits
- ❖ Equipment, food



OSU Xhab's Node 1

Hinged panel



Installation of a rack in the U.S. Lab prior to launch.

❑ Gaming Software

❑ Capabilities

❖ *Import CAD Models*

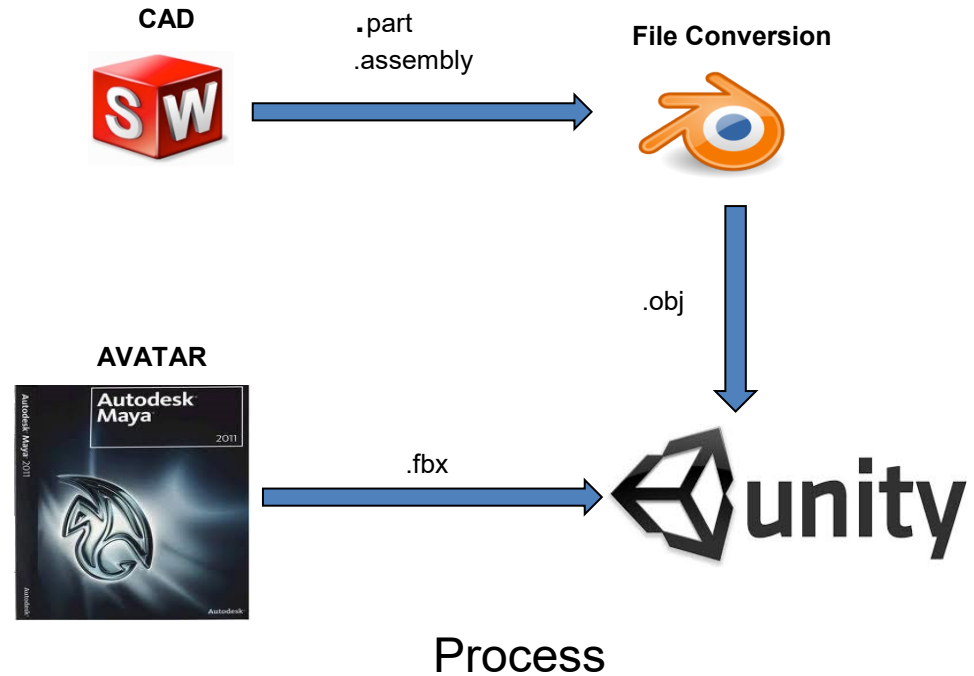
❖ *Simulation*

❑ Features

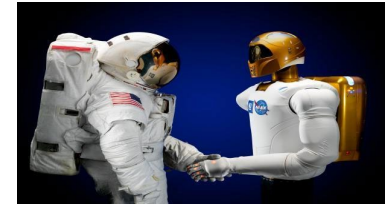
❖ *Character presets*

❖ *Animation presets*

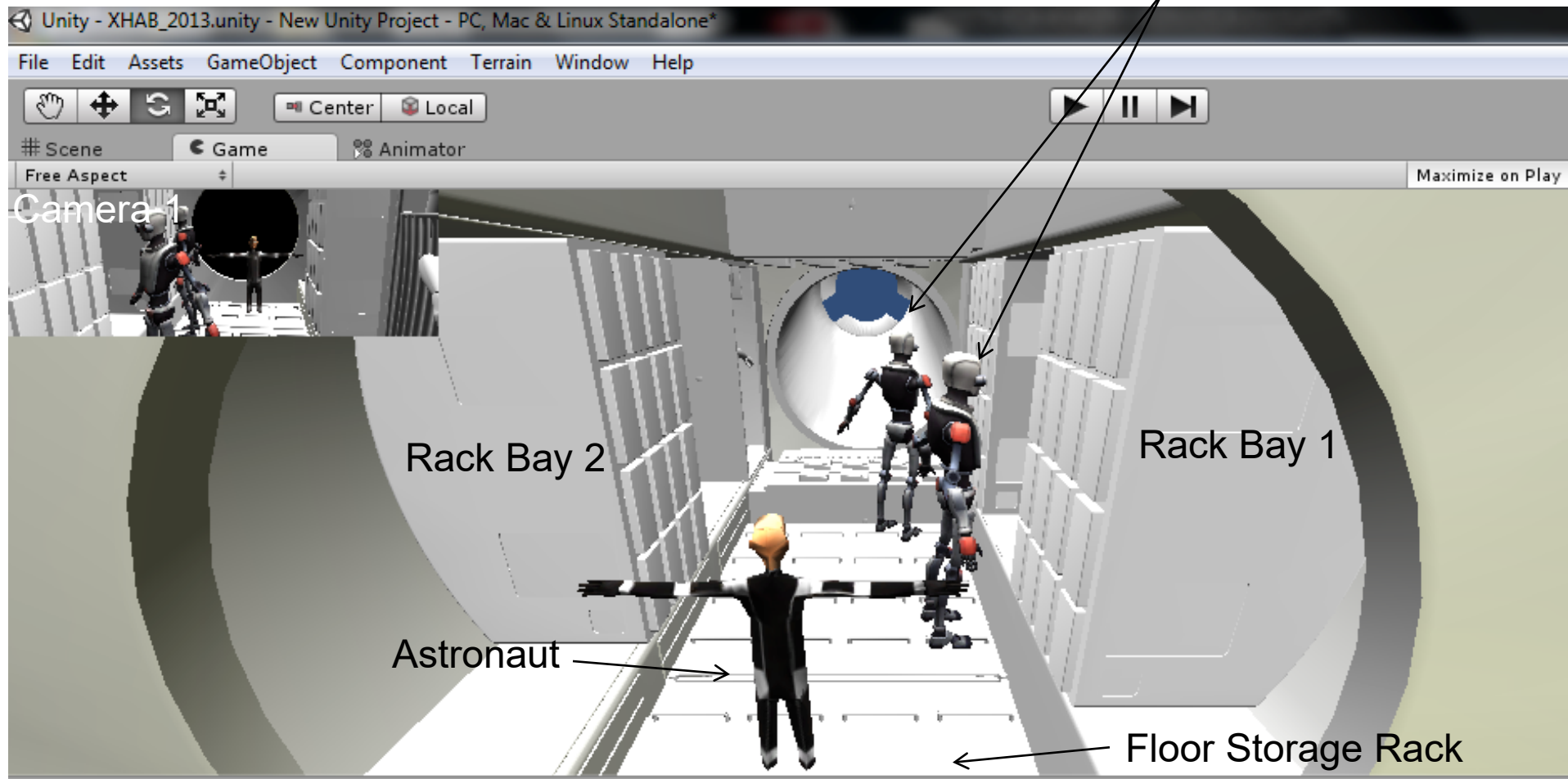
❖ *Great website software support*



- ☐ Screen shoot from the simulation
- ☐ Simulate robot and astronaut activities inside the Node 1

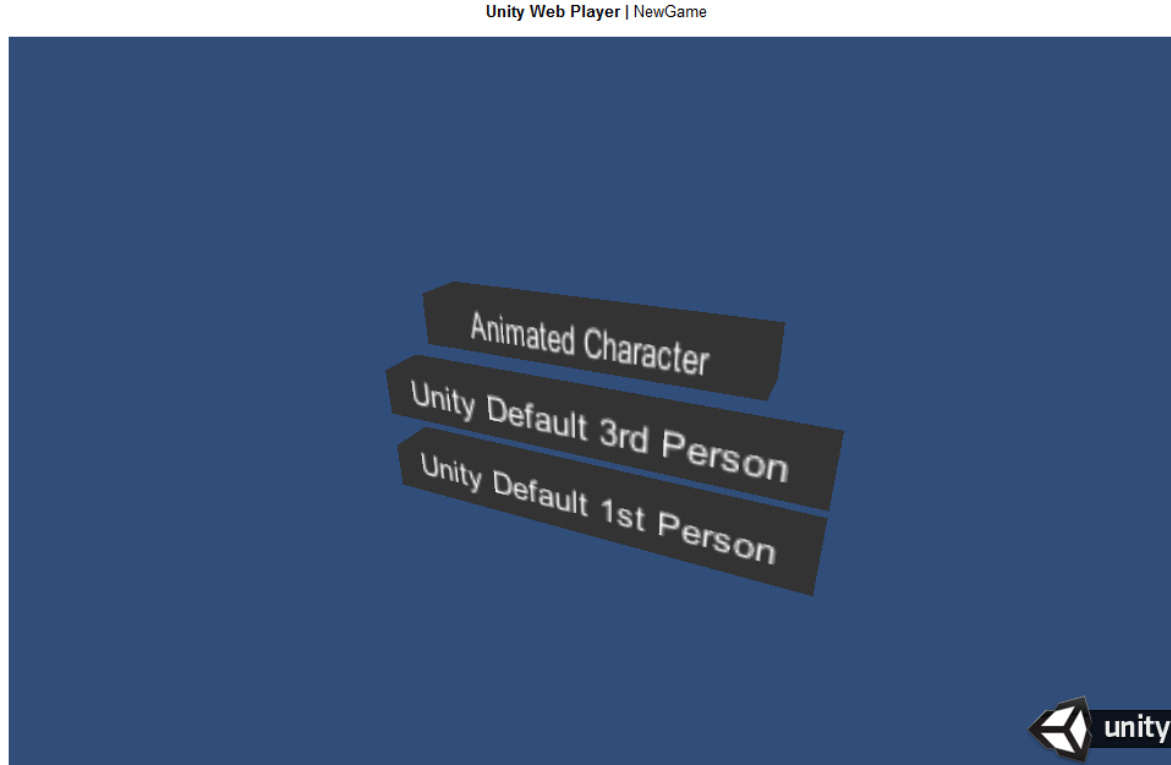


ROBOT (simulate Robonaut)



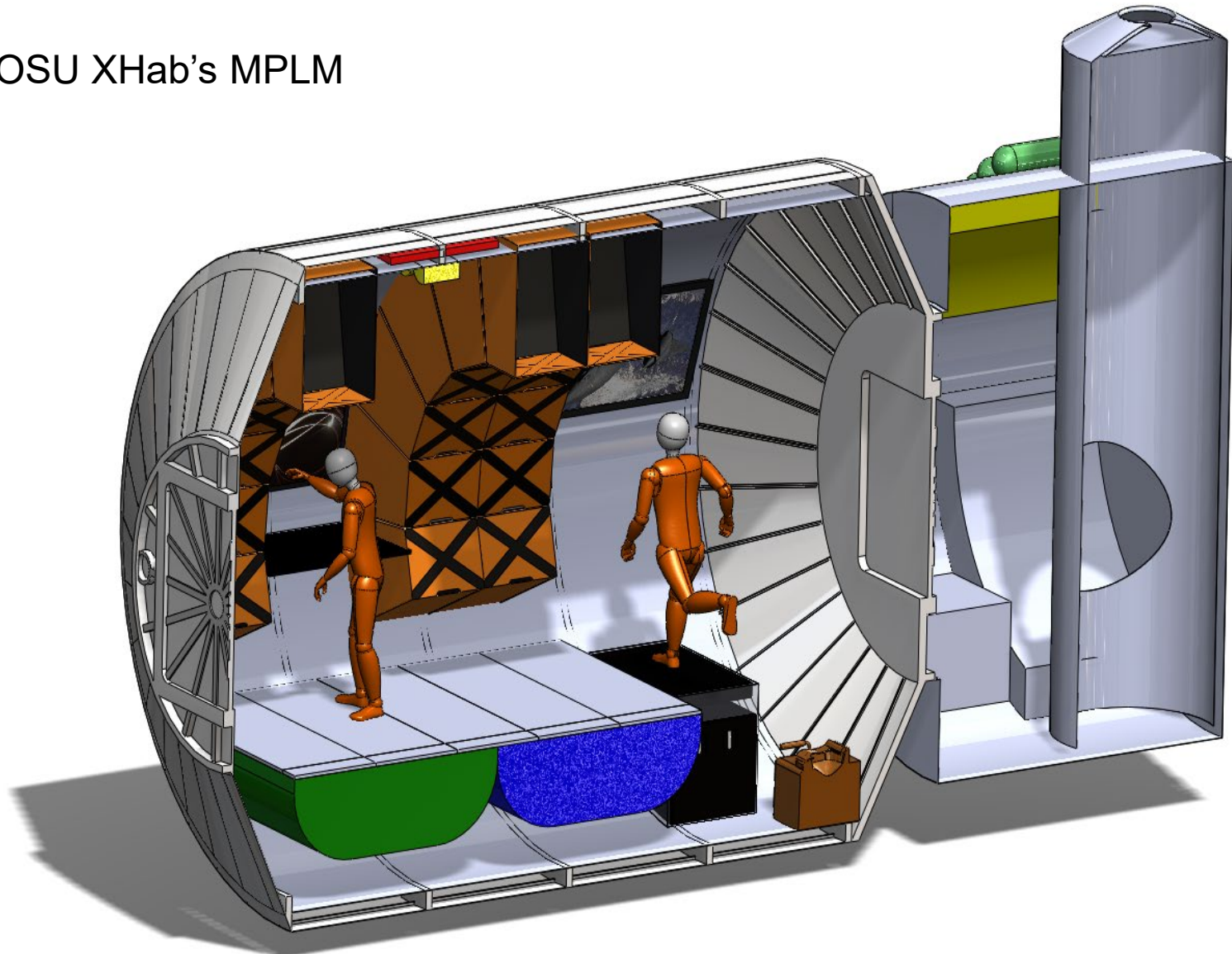
Future work

- Simulate object interaction inside the space habitat
<http://fpst.atwebpages.com/CharactersPresentation.html>



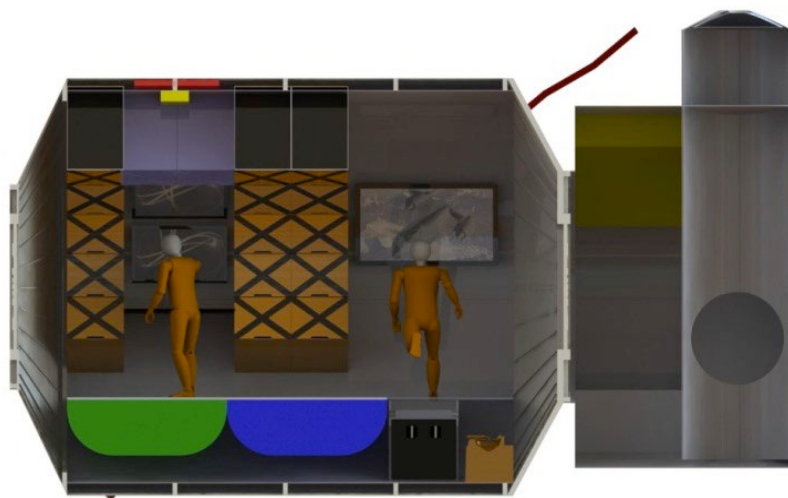
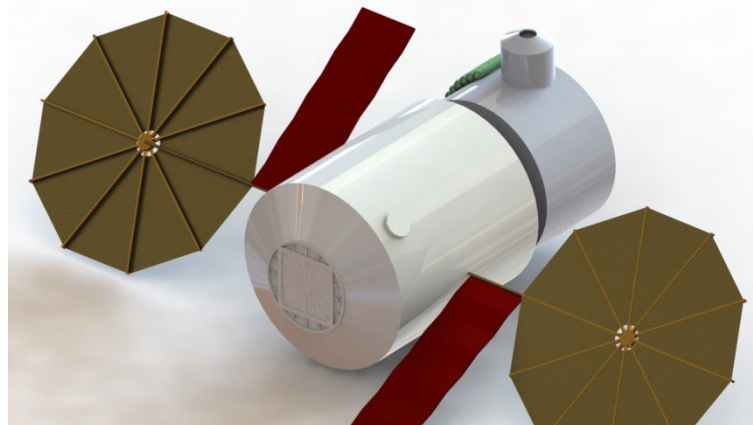
MPLM (Fall Design)

OSU XHab's MPLM



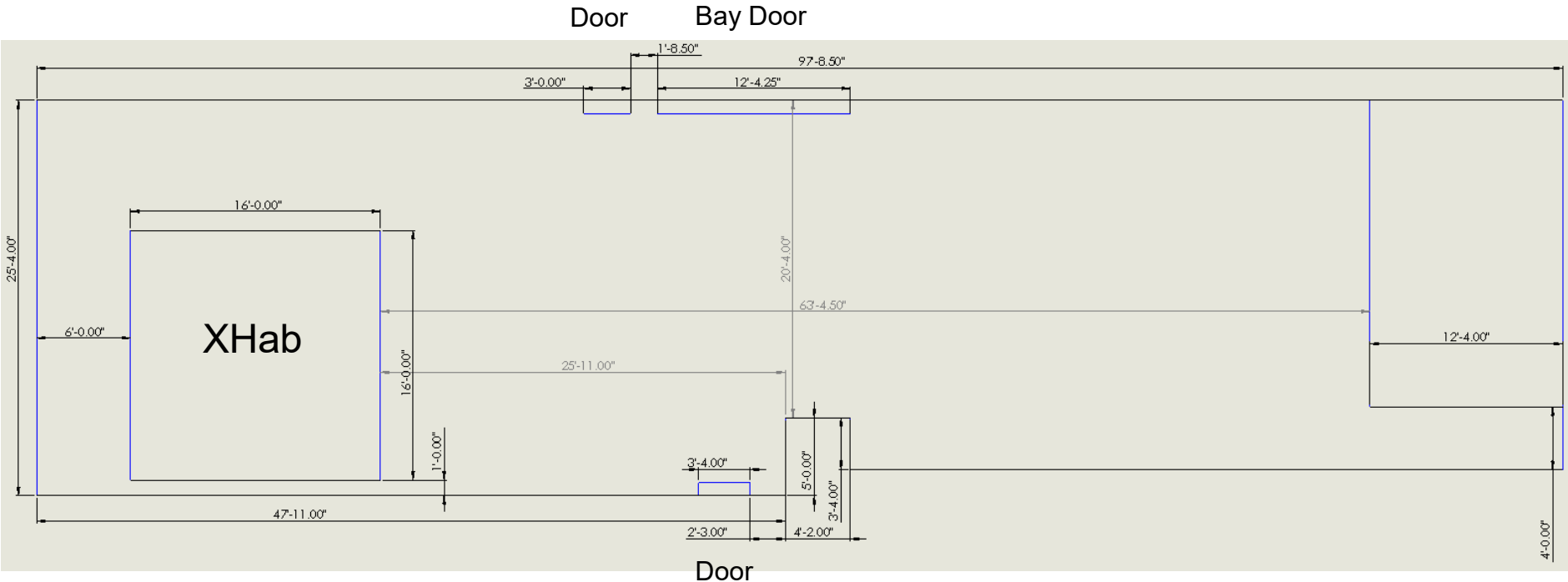
Module For Analog

- MPLM
- Includes:
 - *Workout*
 - *Lab Stations*
 - *Computer Station, Aeroponics, Glove Box*
 - *Hygiene*
 - *Toilet, Shower*
 - *Storage*
 - *Small to Large Items*
 - *HVAC*
 - *Lighting*
 - *Interior Design Group Project*



Richmond Facility Layout

- Large Open High Bay Area, Large Bay Door For Unloading Larger Items

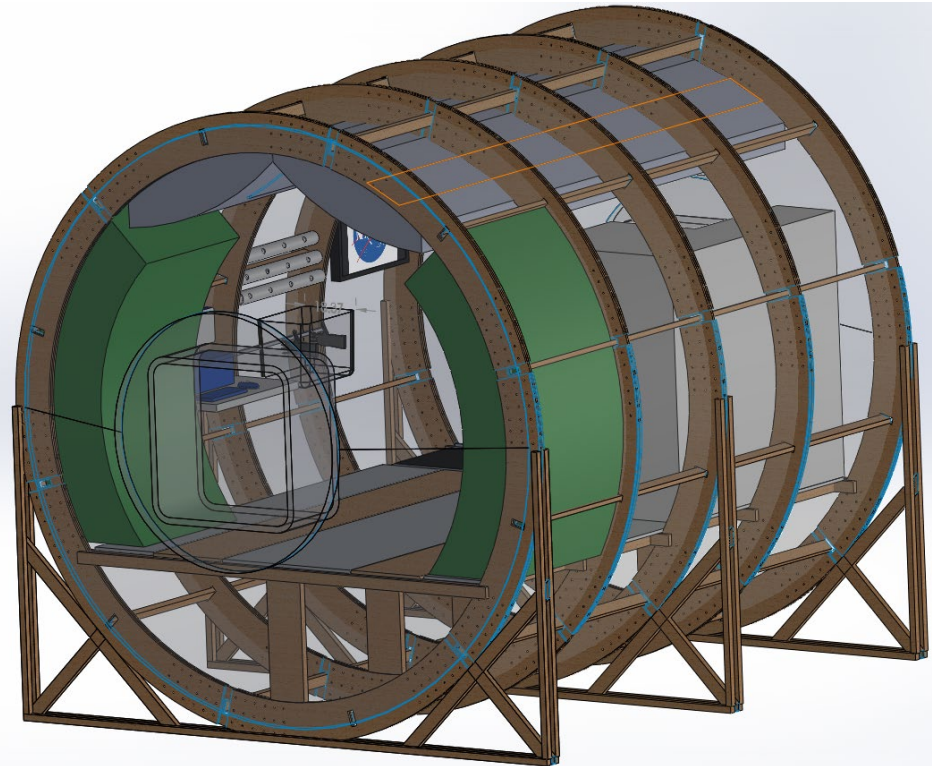
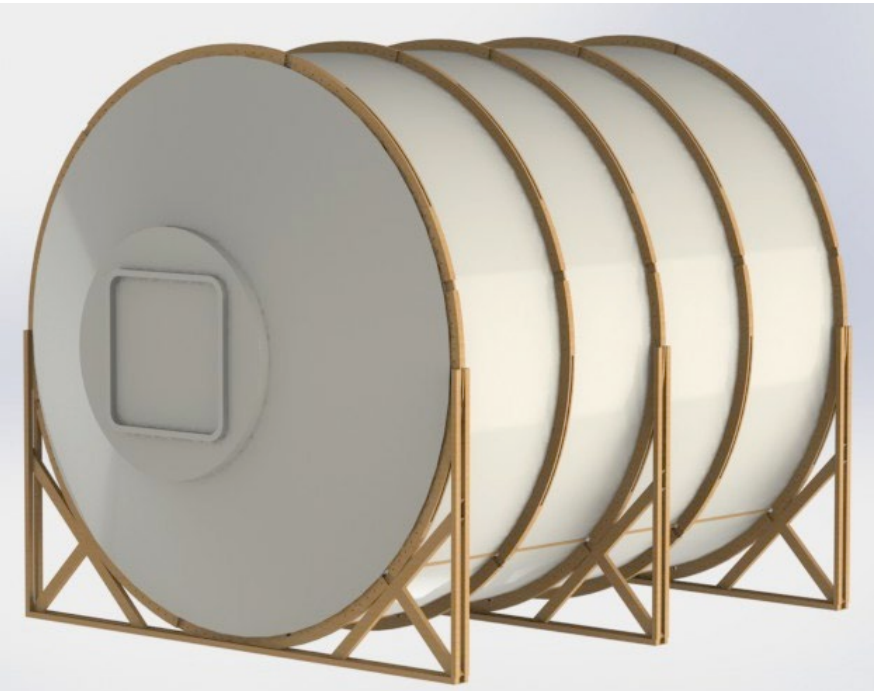


- Plenty Of Space To Expand If Desired (60ft of open space in front of analog)



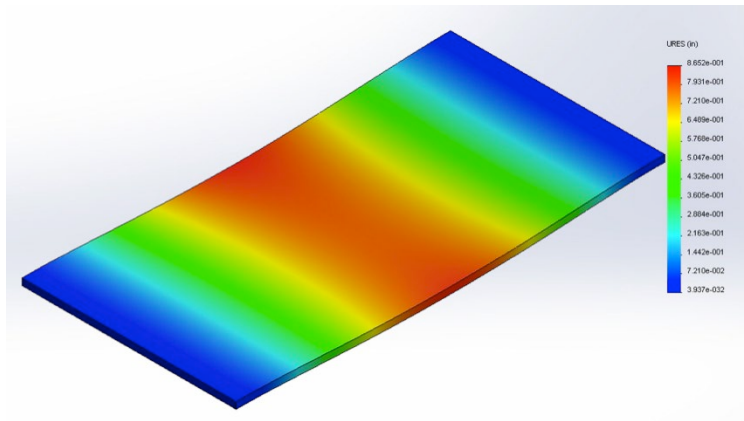
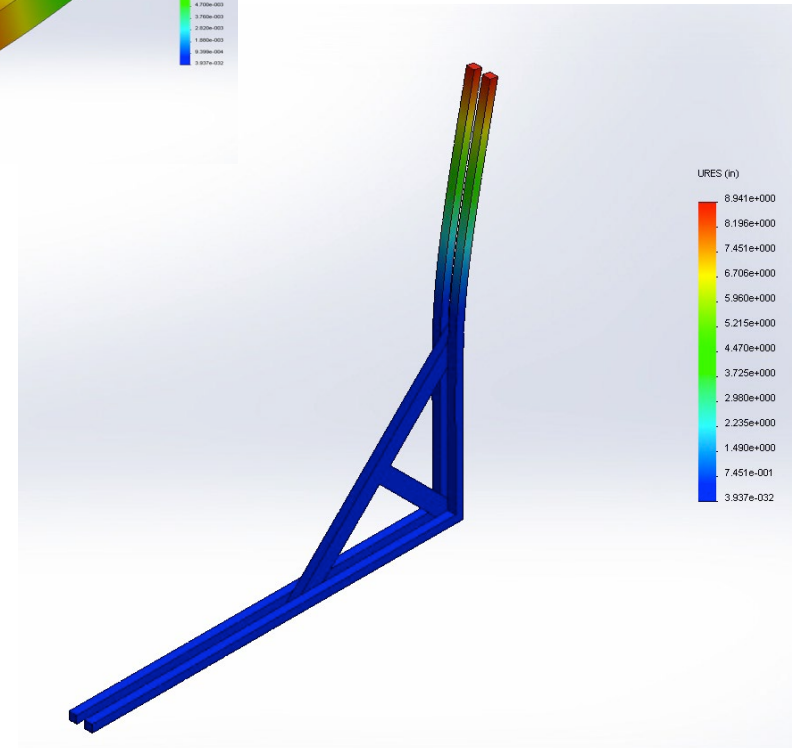
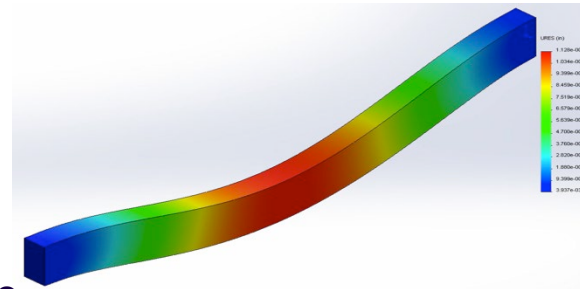
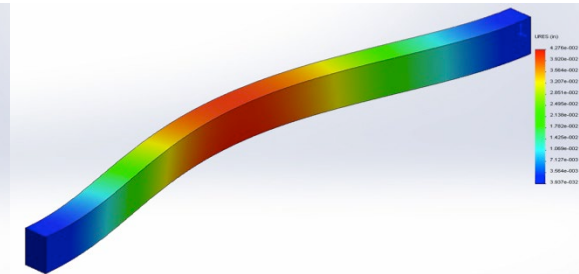
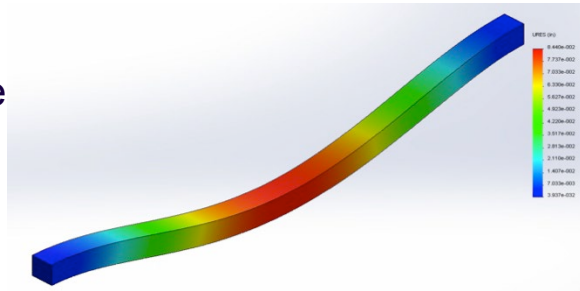
Earth Analog Concept

- Earth Analog of Garriot (MPLM)
 - *Main structure is wooden: 5 ring frames with 12 evenly spaced stringers; floor substructure wood with wood and metal panels*
 - *Skin is foam core and foam insulation*



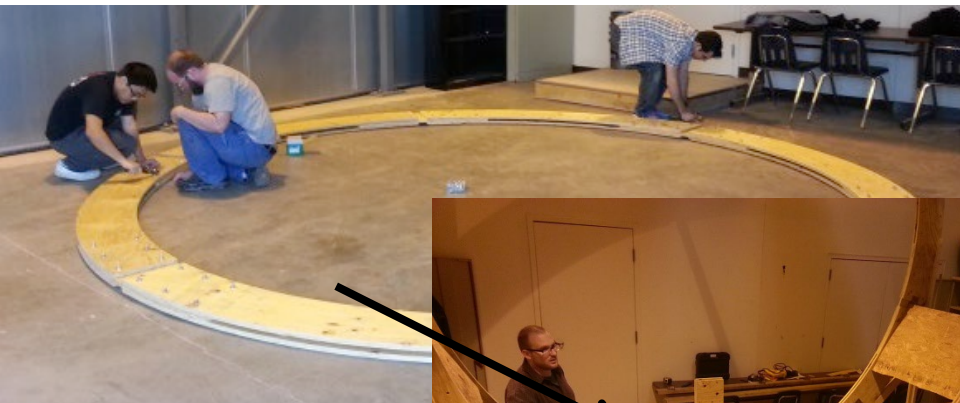
Structural Analysis

- FEA On 2"x2", 2"x4", Floor Panels and Supporting Structure
- Obtained/Estimated Pine and Plywood material characteristics (Matweb)
- 500 lbf point loads at worst case loading positions
- Minimal deflections, well within limits of safety
- Floor panel and support structure had largest deflections (support used 1000 lbf) but still did not fail



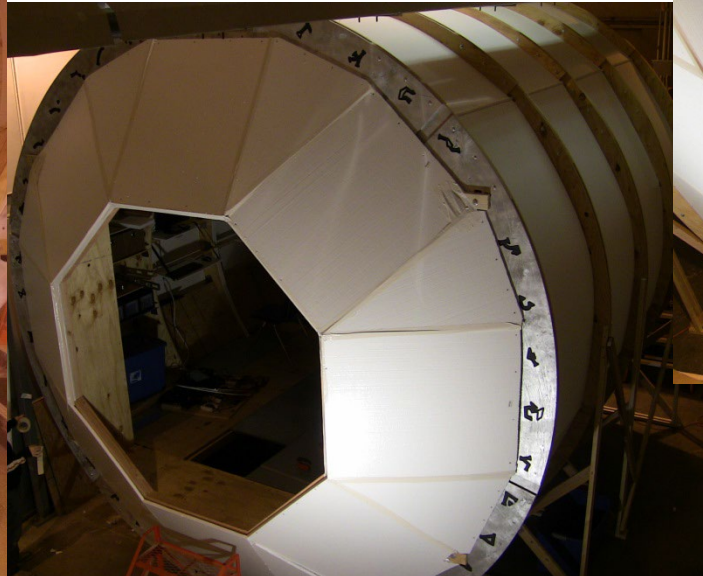
Fabrication

- Used CNC router for cutting circular frame out of plywood.
 - *Assembled rings horizontally and then rotated them to be vertical*
 - *Used 2x4s and metal brackets to brace the rings together*
- Used 2x4s for construction of the floor
 - *Aluminum covered wood plates along with plywood for floor covering*



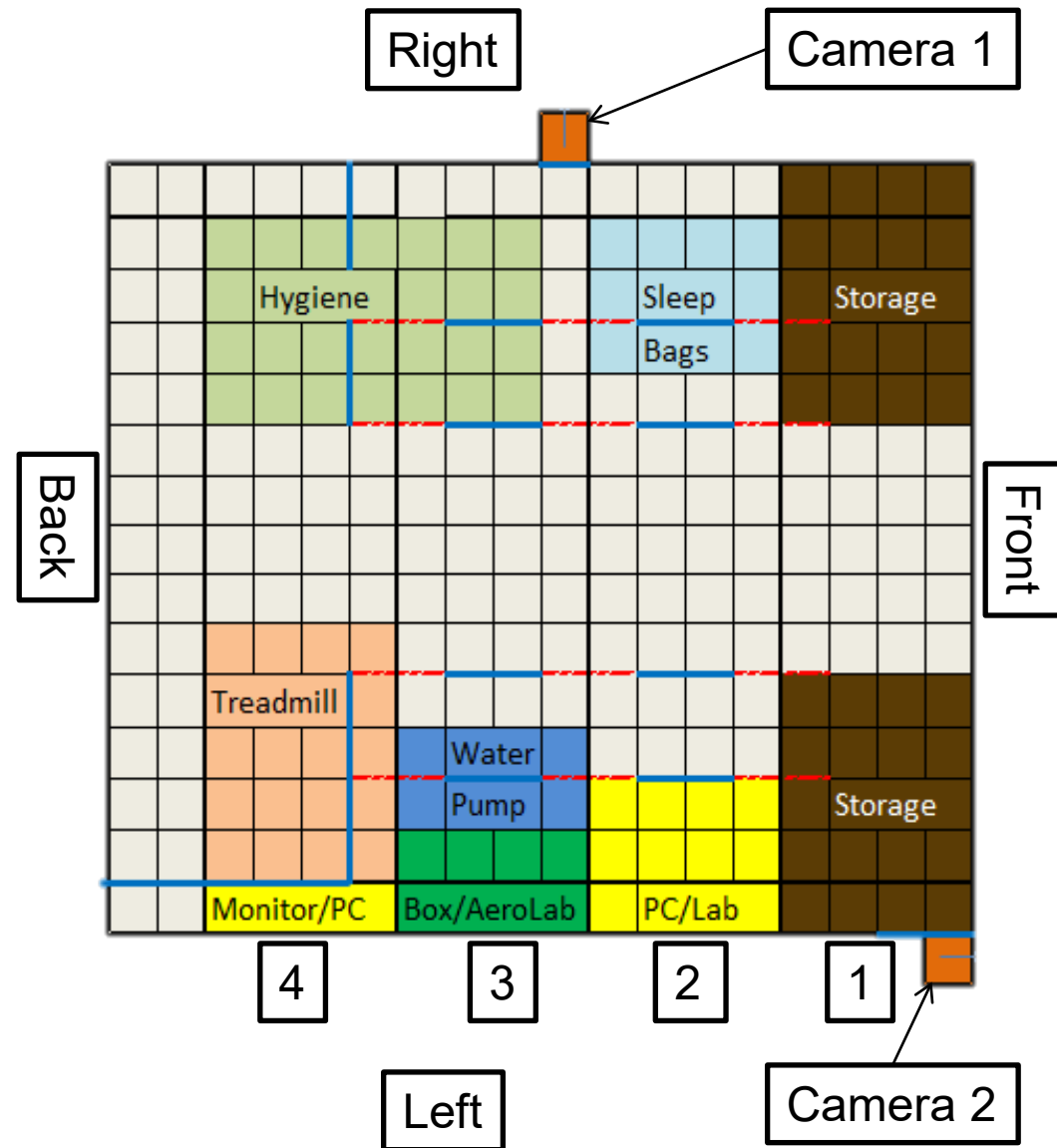
Fabrication

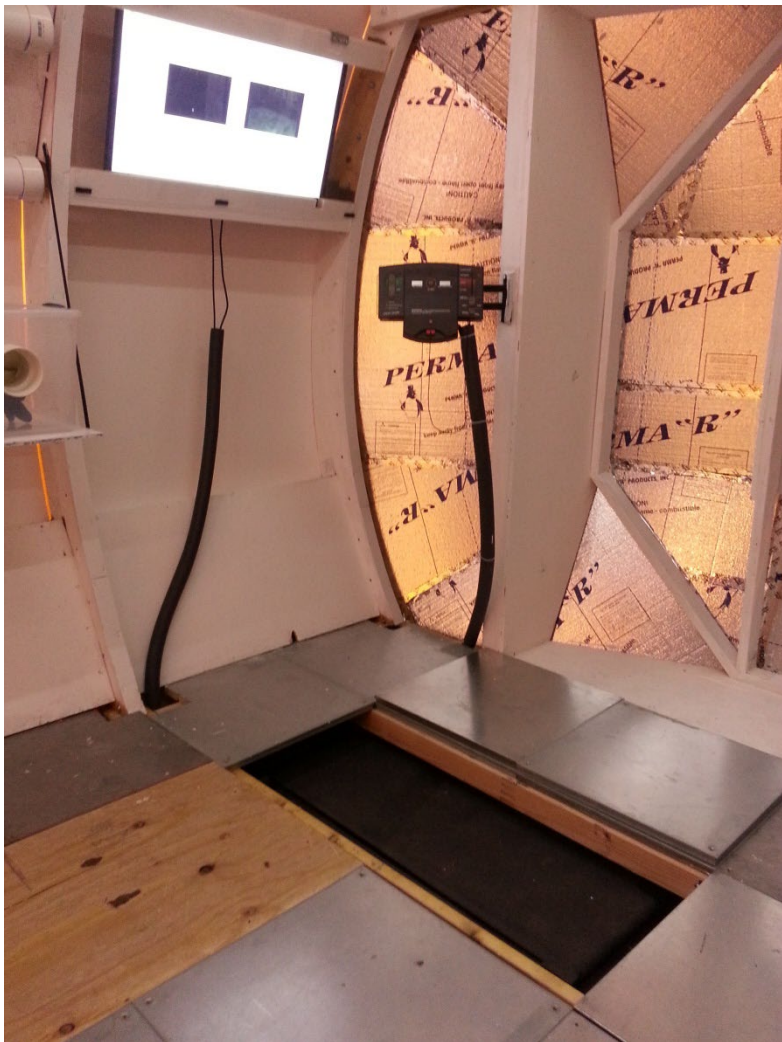
- Foam board for exterior skin
- 2x4s for frames of end caps
 - *Star foam sheets for covering*



Interior Planning

- Ring 1
 - *Small storage and large storage(under the floor)*
- Ring 2
 - *PC and sleeping area*
- Ring 3
 - *Aeroponics (water pump under the floor) and glove box*
 - *Hygiene Module will be in both Ring 3 & 4*
- Ring 4
 - *Treadmill and monitor for virtual window*

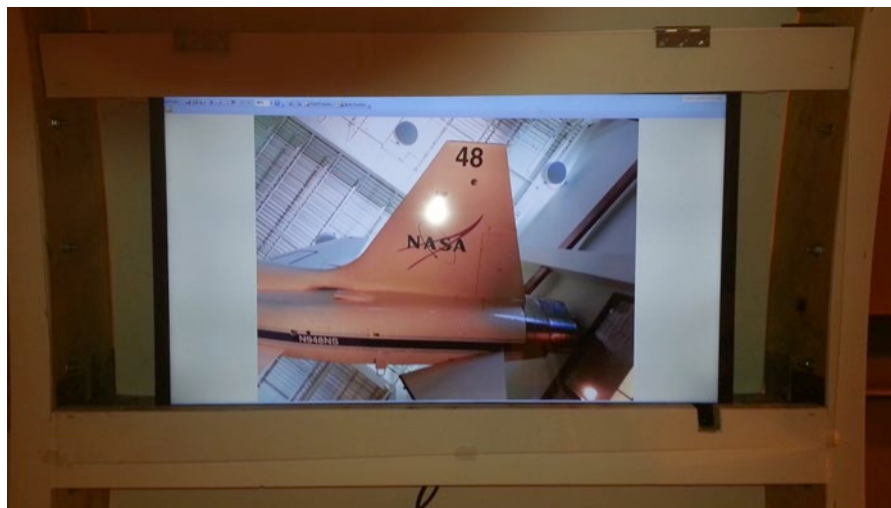




- Colbert Treadmill
 - *Designed to help reduce possible muscle atrophy in space*
 - *Mounted under the floor for easy access and to save space when not in use*
 - *Can be accessed via the floor access magnets*
 - *Control panel to the side to adjust speed*
 - *In zero gravity, straps will hold you down to allow you to run*

Viewing Screen

- Virtual Window
 - 39" television
 - 2 webcams with fisheye lensed attachments
 - Controlled via net top computer
 - User interfaces via wireless keyboard and mouse
 - Window doubles as lighting diagnostic tool

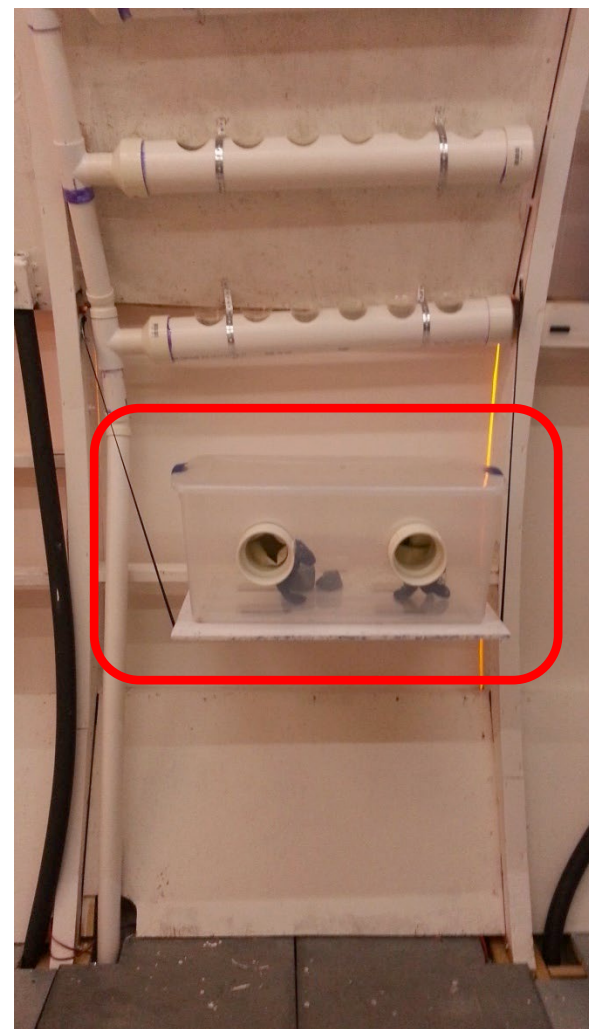


Aeroponics



- Design
 - $\frac{1}{2}$ " inner tube (pvc)
 - $\frac{1}{16}$ " holes for mist
 - 2" outer return tube (pvc)
 - 3 racks of 6 plants
 - UV lighting to stimulate growth
 - Gravity based return system
- Water supply
 - $\frac{1}{6}$ hp pump
 - 25 gallon tank filled with about 5 gallons
 - Stored under floor for convenience

- Glove box
 - *Primary use as a clean environment work station capable of holding toxic test subjects as well*
 - *Removable via hook and loop tape and capable of being stored underneath the floor*
 - *Stand can then be used as a secondary work environment*
 - *Stand can also be stowed against the wall to enlarge the room*



Lab Work Station/Rovio



- Workstation
 - *Designed for working with lab statistics, rovio control, other needs*
 - *In the Earth analog, designed for comfortable standing position*
 - *Through the computer mounted beneath the floor the user can control Rovio and receive live video feed from outside the habitat*
 - *Keyboard table stores upward for increased space*

- Planned design
 - *Lifted up from the floor and locked in place when in use and easily stores under the floor when not in use*
- Hygiene Module
 - *Used Hygiene Module to save time and resources*
 - *On loan from Stafford Museum in Weatherford*
 - *Contains a shower and bathroom station*
 - *Internal drawers in the bathroom for storage*



Small Storage



- Located along the circumference entering the habitat
 - *Contains small items such as flashlights, toothbrushes, etc.*
- Several removable bins (0.5 ft³) to hold small items
- Larger bins to hold medium sized items (4.7 ft³)

Additional Storage

- Small-Moderate Storage
 - *Form fitting storage will be installed inside around the wall of the module*
- Design
 - *Use of lightweight (possibly fabric) materials with lightweight inserts color coded for the contents*
 - *Contents can range from clothing, repair tools, personal effects, lab equipment and many other possibilities*



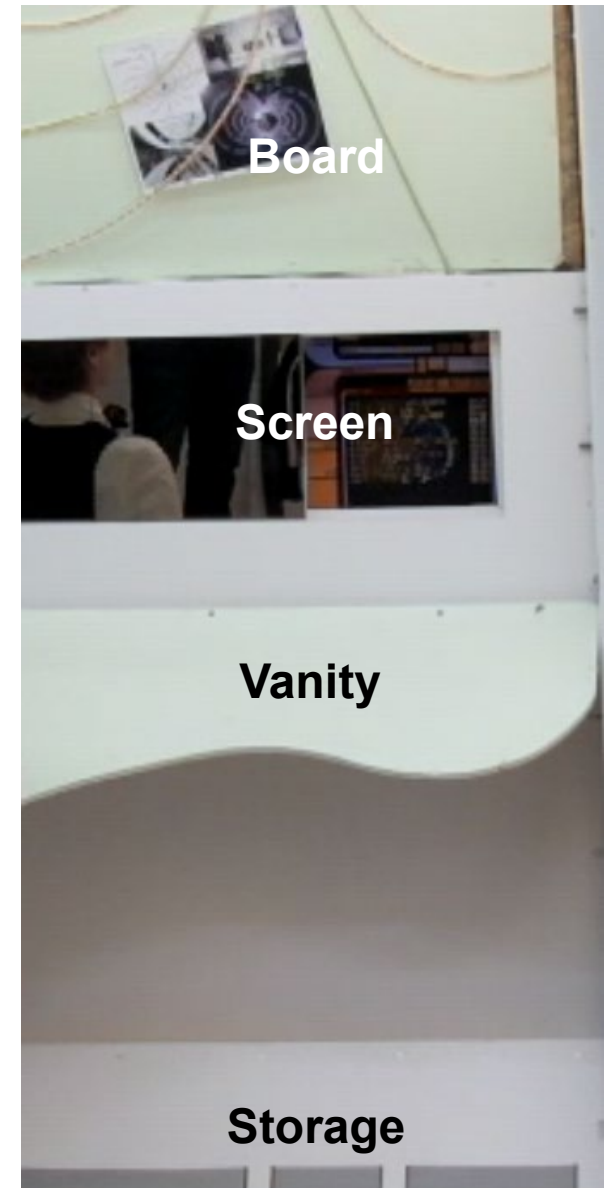
Large Storage

- Large items are placed under removable floor panels
 - *Total volume is 184 ft³*
 - *For everything from spacesuit storage and replacement parts for the habitat to large cargo items and stowaways*



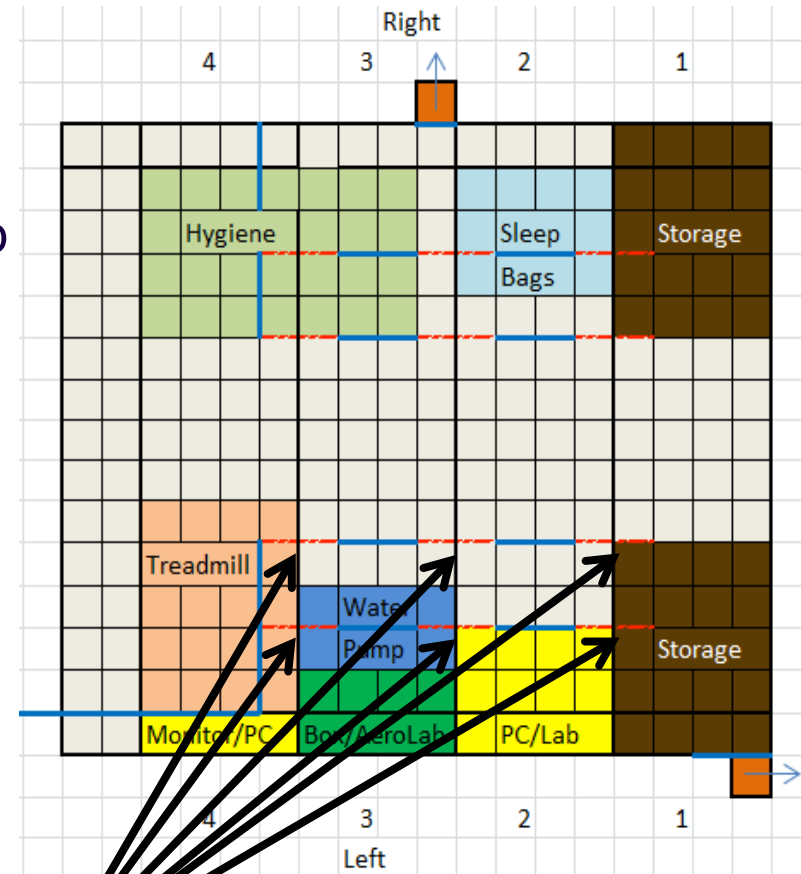
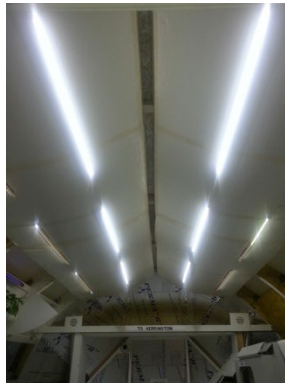
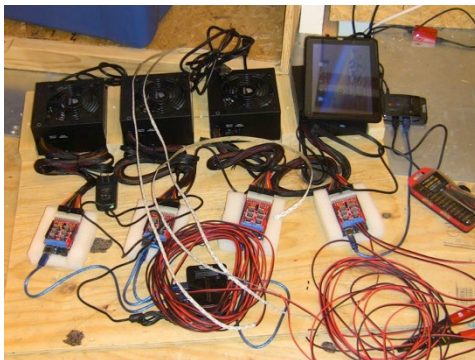
Personal Quarters

- Sleeping arrangements
 - *Mock up of one persons quarters*
 - *Board*
 - *Color*
 - *Based on aurora borealis*
 - *Provides a distraction from the typically sterile environment of the habitat*
 - *Doubles as a means to store personal items*
 - *Mirrors*
 - *For grooming; also act as viewing screen for skype, etc.*
 - *Sleeping bag mounted to extendible wall(not pictured)*



Lighting

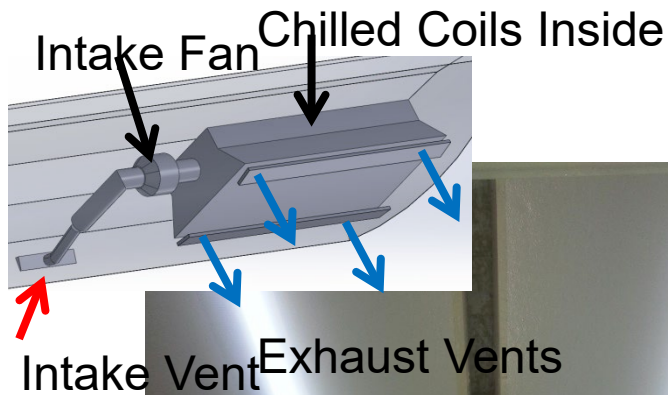
- LED Strip lights
- 4 rows split into 3rds
- Controlled using a custom Android app
 - *Sends data over serial communication*
 - *Server then relays information to the Arduinos*
- 4 Arduinos(1 per row) with power shields
 - *Power shields allow amperage control along 12 volt rails*



LED placement (red is LED, blue is wire) mirrored over the middle of the habitat

- Use of Active Chilled Beams desired

- *Outside ability to afford with budget*
- *Volumetric mock up made*

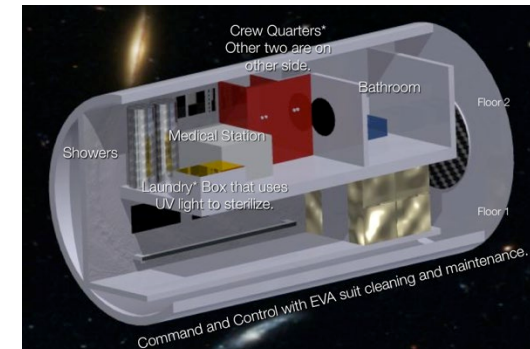
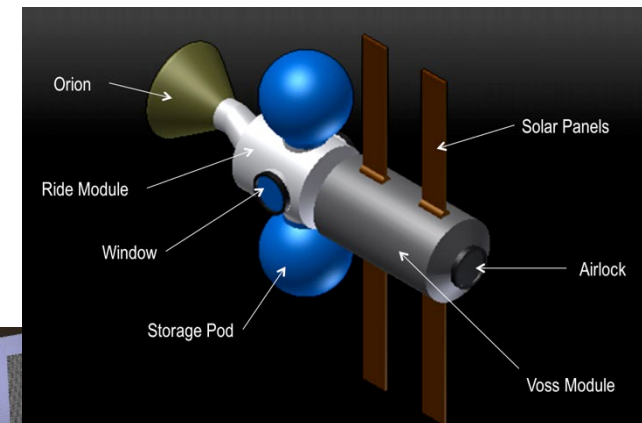
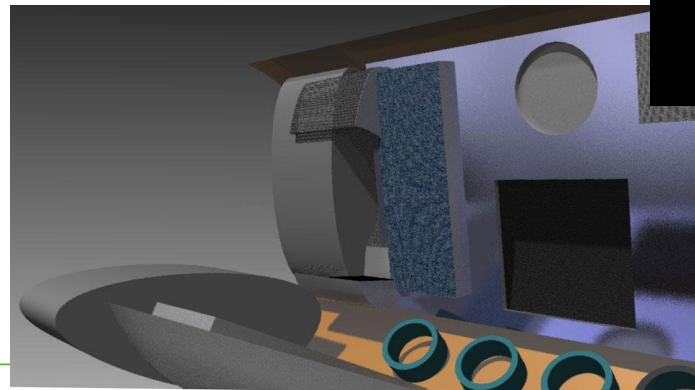
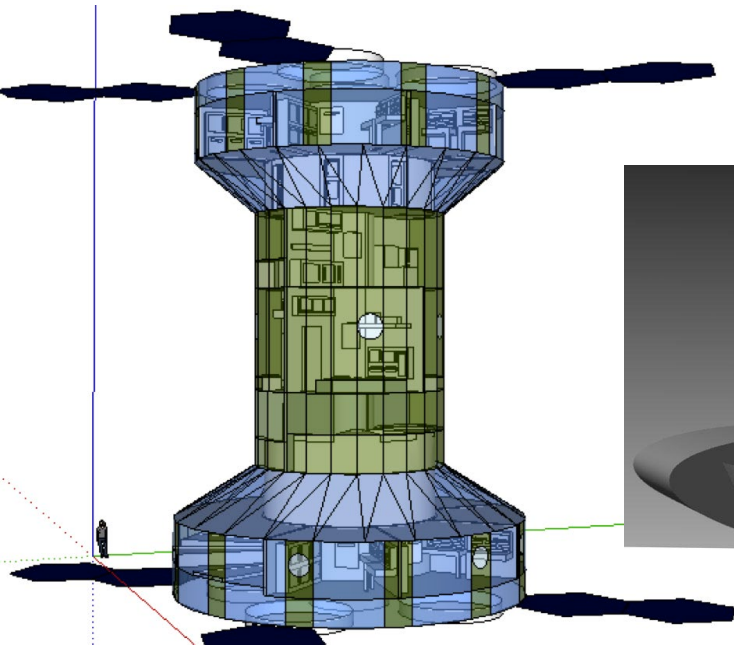


- Used spare AC unit for air circulation within module

- *Added water tank with pump for cooling effect*
- *Ice packs added to water for colder water circulation*



- High School Space Habitat Innovation Challenge
- 25 groups involved (~125 students) from NASA INSPIRE and Explorer Schools
- 7 teams submitted proposals; down selected to top 3 – winners travel to MSFC in June



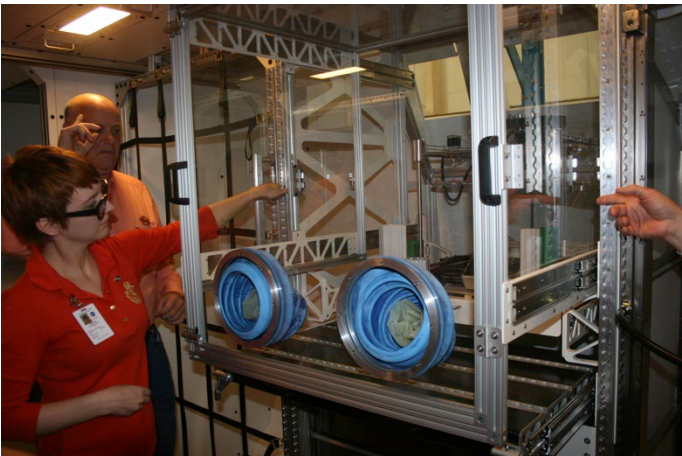
- <https://www.youtube.com/watch?v=HHiAezyBI-k>

Testing and Demonstration

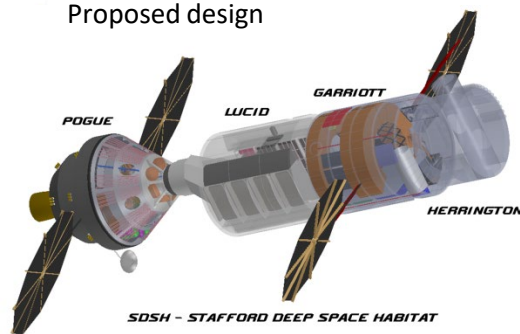


Trips

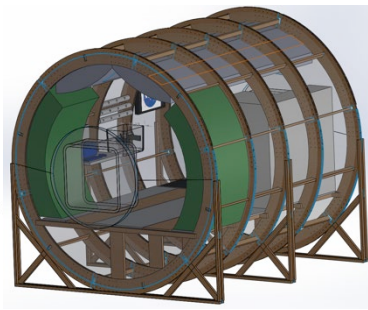
- Visits to NASA MSFC, Cosmosphere, and Stafford Museum



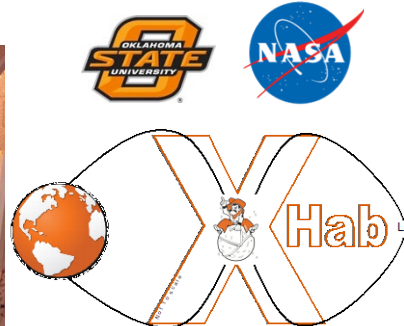
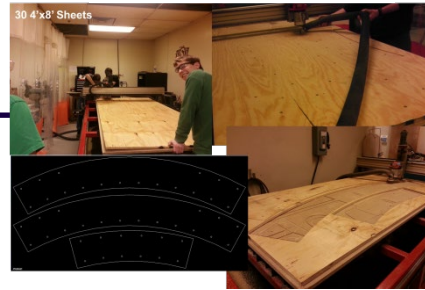
Proposed design



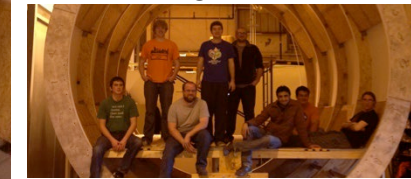
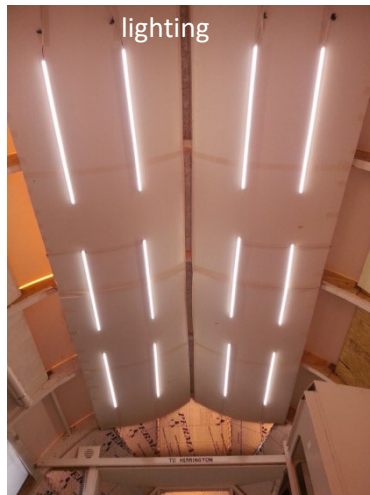
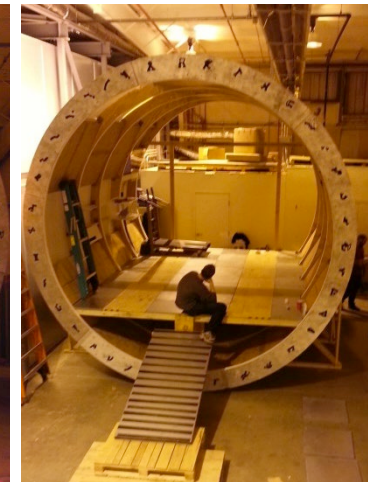
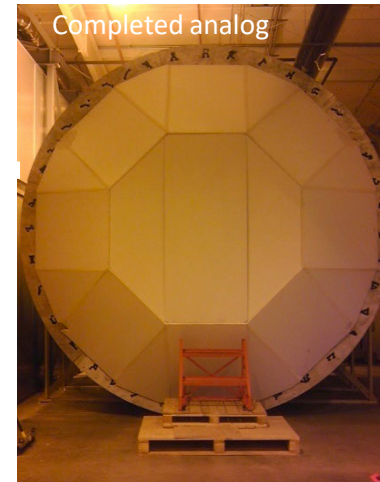
Earth analog



Manufacturing



Development of an
Earth analog for
Horizontal habitability
Layout studies of a
deep space habitat





Oklahoma State University XHab Video Tour

OSU XHab Team
School of Mechanical & Aerospace Engineering

Spring 2013

SPACEX



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Thank You

