





Find My Astronaut Photo

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Overview





A Brief History of Astronaut Photography

Barriers to Geolocation

The Find My Astronaut Photo Framework

Finding a Discriminative Matcher

The AIMS Dataset



Results

A Brief History of Astronaut Photography

- Astronauts have taken photos of the Earth from space for over 60 years
- The Earth Science and Remote Sensing (ESRS) Unit at JSC, manages the collection and hosting of Earth observation images from the ISS and past NASA spacecraft
- Imagery is used for research, disaster response, and public engagement



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A Brief History of Astronaut Photography



A Brief History of Astronaut Photography

- Today, astronaut photography primarily takes place from the International Space Station (ISS)
 - 400 km above Earth's surface in Low Earth Orbit
 - Orbits the Earth 16 times per 24 hours









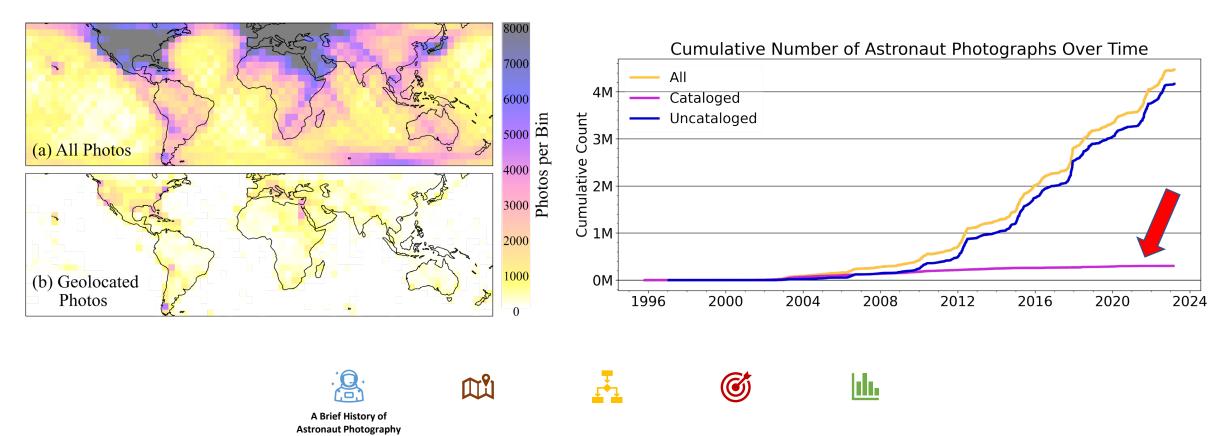






A Brief History of Astronaut Photography

- Global, 4 million photo collection, increasing by 100,000 photos every 6 months
- Missing critical geolocation data for 90% of images
 - 10% of existing geolocation data is from manual human search and labeling





Astronaut Photo

Acquisition Conditions

Known spacecraft position and attitude

Known camera orientation







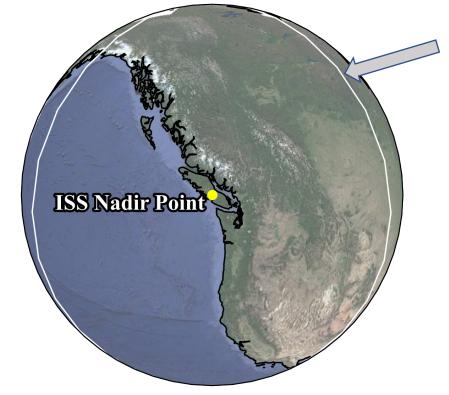


Barriers to Geolocation



ISS062-E-40033 02/20/2020 NIKON D5, Focal Length: 400 mm Shutter: 1/1000 Aperture: 8.0 ISO Speed: 400 Focus Mode: AF-S





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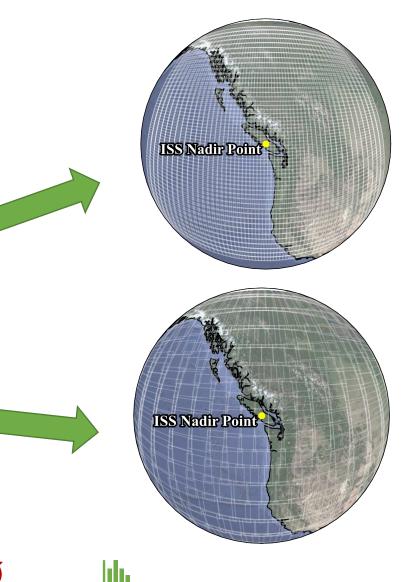




The Find My Astronaut Photo Framework Extent of visible Earth area

- **1. Discretize visible Earth area** into patches based on camera focal length
 - Different focal lengths will result in different ground fields of view and different patches





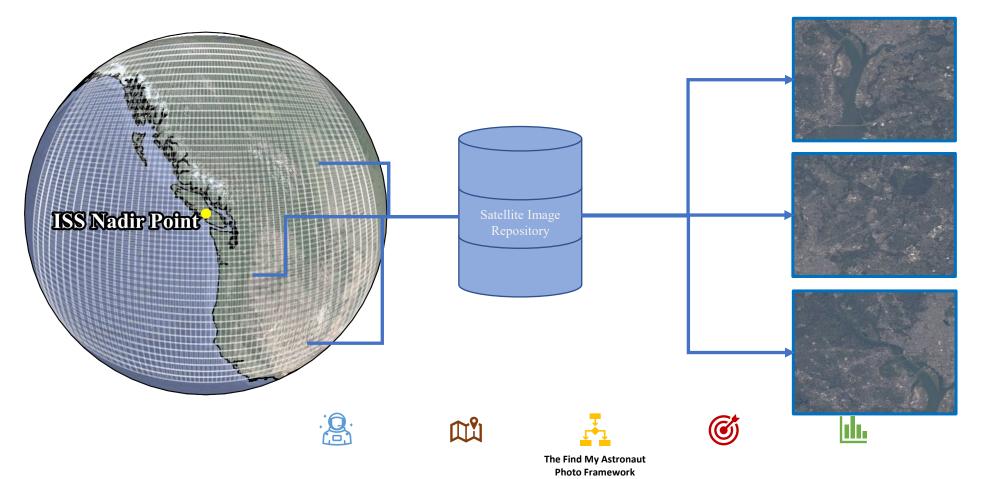
The Find My Astronaut Photo Framework

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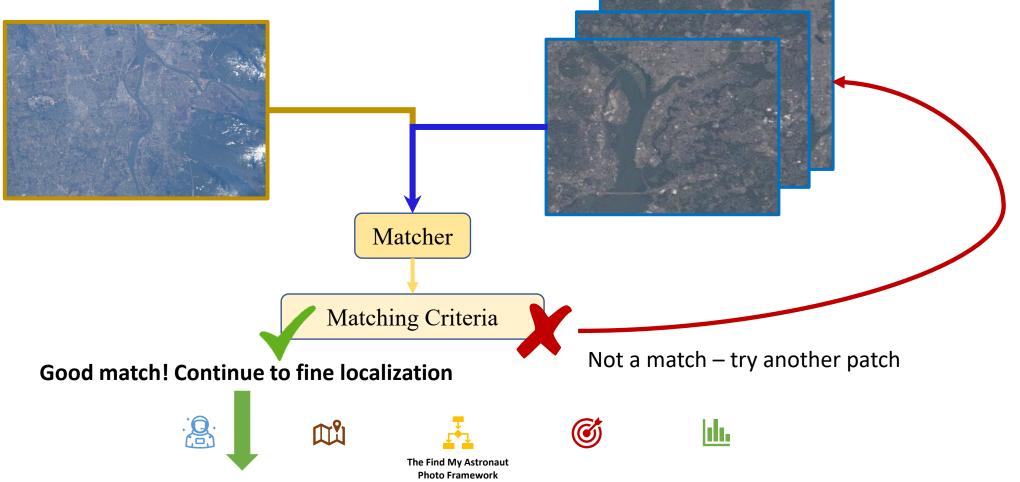
400 mm

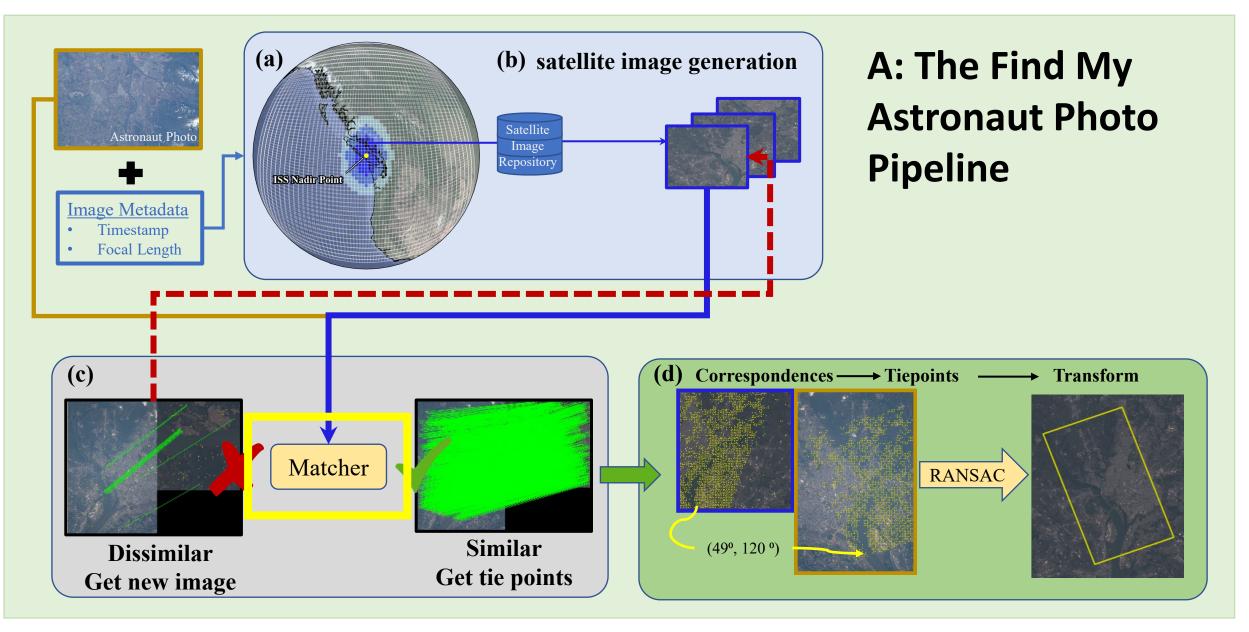
100 mm

- 2. For each patch, generate a **satellite reference image** with the extent of the patch
 - Satellite images are geolocated during acquisition



3. Using an image matching method, determine if the patch represents the same physical location on Earth





Challenge

- Finding the **best** match requires checking each patch
 - For higher focal length imagery, there can be 10,000+ patches
 - Checking just one patch is resource intensive

Requirement

 Matcher must be discriminative we can determine criteria such that we need not visit every patch if we find a good match (early stopping)



Challenge

• Many areas on Earth appear similar or have little texture

Requirement

Finding a Discriminative Matcher

• Matcher and matching criteria must minimize false positives



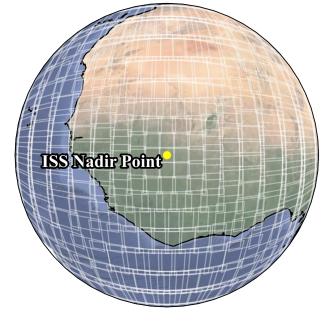
Challenge

 Each astronaut photo has a unique set of patches that vary in scale and location



Requirement

- We cannot precompute features for patches no static database
- Scale robustness allows for more leniency in patch generation



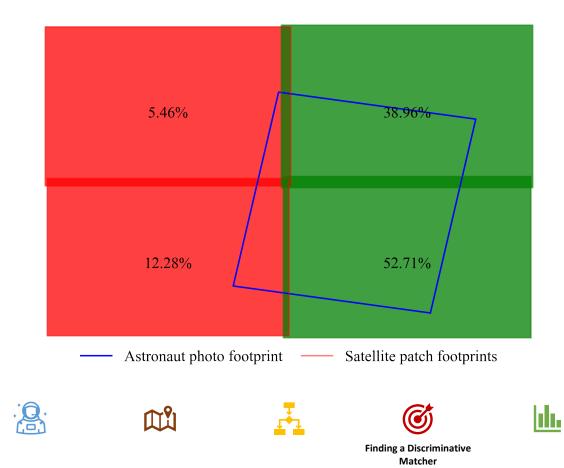


Challenge

• Patches will have incomplete overlap with astronaut photos

Requirement

• Matcher must be robust to "occlusion"

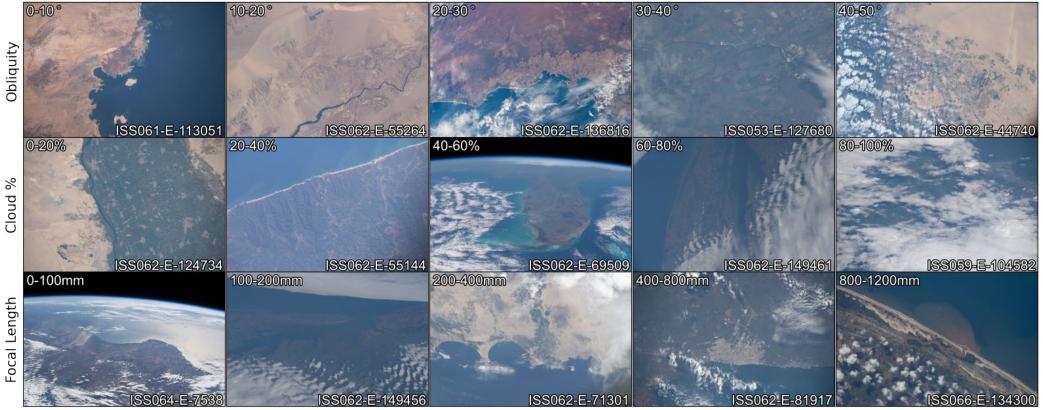


Challenge

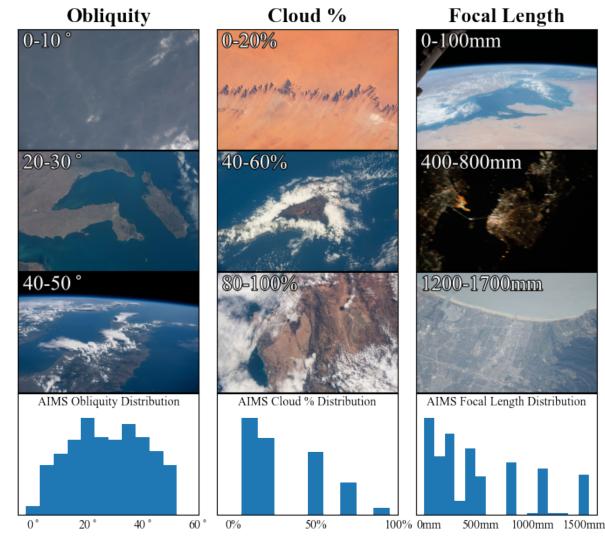
- No canonical orientation (North is not always up)
- Variable illumination conditions and seasonality
- Can be nadir or highly oblique

Requirement

• Robust to rotation, illumination, occlusion, and viewing angle



Astronaut Image Matching Subset (AIMS)



- 323 astronaut photographs with expert human ٠ localization information
- Variation across ٠
 - Obliguity •
 - Cloud % (occlusion)
 - Focal length (field of view/scale)
 - Orientation (North angle)
- Astronaut photos, patch definitions, ground • truth correct patches, satellite reference images released
- Evaluative dataset for image matching ٠

| Input | Astronaut photo, indexed satellite ref. images |
|---------|--|
| Output | Index of best matching reference image |
| Scoring | Precision/Recall |

https://eol.jsc.nasa.gov/BeyondThePhotography/AstronautPhotographyImageMatchingSubset

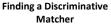




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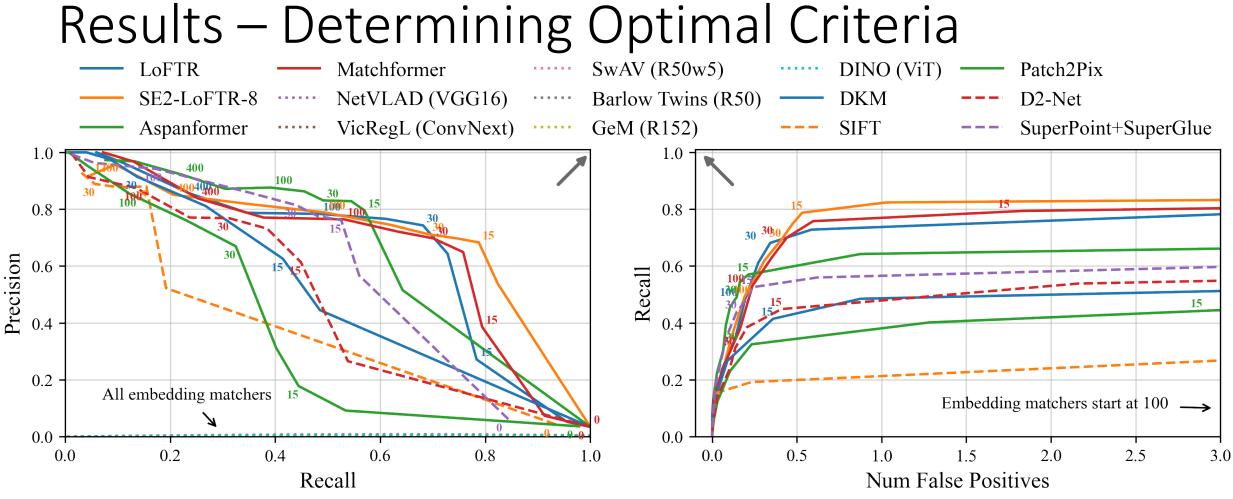


Evaluation

- 1. Run the Find My Astronaut Photo Pipeline on the AIMS set with each of the matchers to find optimal match criteria
- 2. Compare models using the optimal criteria for each method
- 3. For best performing class, evaluate the impact of **image size** and **relative scale**

| Matcher Type | Embedding-based | Detector-based | Detector-free | |
|----------------|--------------------------|------------------------|---------------|--|
| Match Criteria | L2 Distance | Number of Inliers | | |
| | Top-1 | | | |
| Matcher | NetVLAD (VGG16) | SIFT | LoFTR | |
| | GeM (Resnet-152) | SuperPoint + SuperGlue | SE2-LoFTR-8 | |
| | DINO (VIT) | D2-Net | Matchformer | |
| | SwAV (Resnet-50 Wide-5) | | Aspanformer | |
| | Barlow Twins (Resnet 50) | | Patch2Pix | |
| | VicRegL (ConvNext) | | DKM (v2) | |
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Finding a Discriminative Matcher



• Embedding based matchers are not discriminate enough in this setting

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• Using **number of inliers** as matching criteria, detector free matchers offer the best trade off between precision and recall

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Results

Results - AIMS Set Performance

| | Average Precision | | | | | |
|------------|-------------------|-------|------|-------|--------|------|
| AIMS Split | SE2-L | Aspan | MF | SP-SG | D2-Net | DKM |
| 1.0x scale | 0.61 | 0.48 | 0.56 | 0.49 | 0.39 | 0.38 |
| 1.5x scale | 0.52 | 0.33 | 0.44 | 0.50 | 0.43 | 0.32 |
| 2.0x scale | 0.25 | 0.21 | 0.21 | 0.41 | 0.37 | 0.25 |
| Low cloud | 0.62 | 0.50 | 0.56 | 0.52 | 0.40 | 0.42 |
| High cloud | 0.49 | 0.36 | 0.54 | 0.31 | 0.28 | 0.14 |
| North up | 0.62 | 0.47 | 0.55 | 0.56 | 0.47 | 0.47 |
| All other | 0.51 | 0.09 | 0.06 | 0.14 | 0.06 | 0.04 |

- Detector based matchers most robust to scale changes
- Matchformer is most robust to occlusion
- SE2-LoFTR is most robust to rotation (it is trained specifically for this setting)
- Other matchers are quite poor for large rotations

We choose **SE2-LoFTR** to power Find My Astronaut Photo









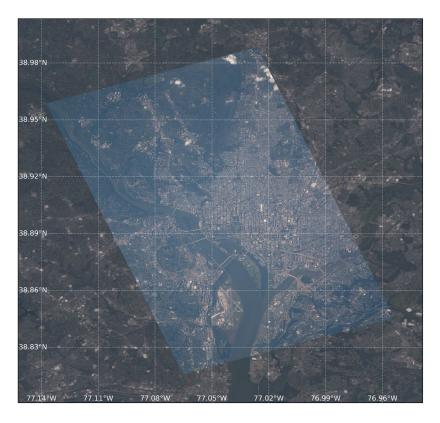


Acknowledgements and Next Steps

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Total Images Found: 57,354

- Explore additional matchers and matching methods
- Engineering improvements to the pipeline to increase per photo speed
- Add support for nighttime photography



Results

Thanks to the Image Matching Workshop organizers, reviewers, and the image matching community!

https://eol.jsc.nasa.gov/

