Limits On Lunar Reorientation From Small(er) Craters

Fig A: Lunar terrain slope based on: SLDEM2015 (60S to 60N) + LOLA (60-90)





Fig D: Degree-2 power of each crater sorted by size. A calibration is needed to approximate the point-mass (spherical cap) method to GRAIL-based modeling.

Fig E: Pole movement accumulated by crater size; from diameter 20 km to 1 km. The influence of craters not considered in the SV22 study contribute to <2.2° degrees.

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Fig B: Size frequency distribution of lunar craters. Larger craters are modeled directly from a GRAIL gravity map (using the SV22 method), while the smaller craters are forward modeled using a digital elevation model, surface density, porosity a geometrical shape approximating the crater and a cross-calibration with the SV22 metho

[#] Are craters with D<20km significant for the Moon's True Polar Wander? a. Extend the method from SV22 to limits of GRAIL effective resolution. [§]b. Forward model craters with point-mass approximation & calibrate. ² The maximum net influence of ~1.3M craters between $20 > D \ge 1$ km on ^a the pole position is between ~1.29-2.15° in latitude. §Cratering reoriented the Moon, changed the illumination conditions of [¥]its polar regions, and therefore the time-history of polar volatiles.





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Craters between 20 to 1200 km in diameter (D) are a significant contributor to the Moon's True Polar Wander (Smith, Viswanathan et al. 2022/PSJ).

n = 38,822







Fig C: Spatial distribution of 1.29M craters in 1 < D < 20 km from Robbins (2019)

Craters with D<20 km exist in areas showing no crater in SV22.

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