DSMC simulation of etch pit formation through active sites in carbon fiber microstructures

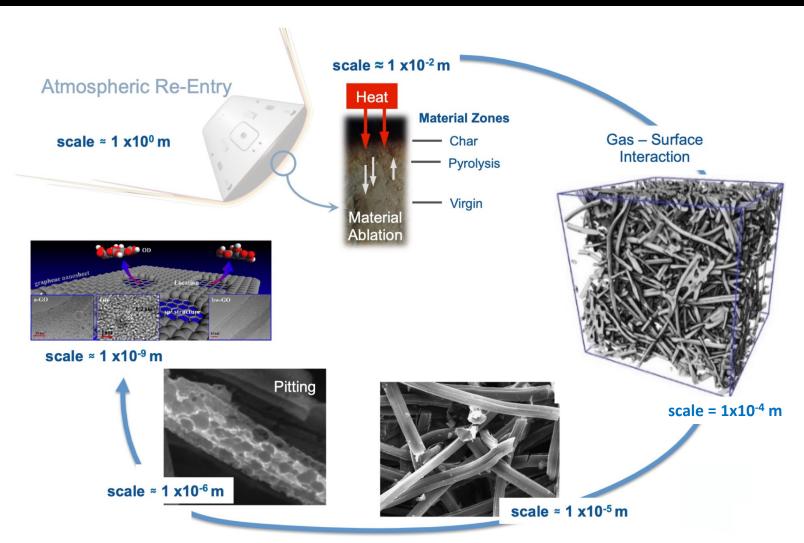
Krishnan Swaminathan Gopalan, Simon Schmitt, and Arnaud Borner

Analytical Mechanics Associates Inc.

Thermal Protection Materials Branch, NASA Ames Research Center, Moffett Field, CA, 94035, USA

Motivation





Overall Objective:

Model the degradation of carbon ablators due to oxidation and characterize their failure mechanisms.

Current Work Objectives:

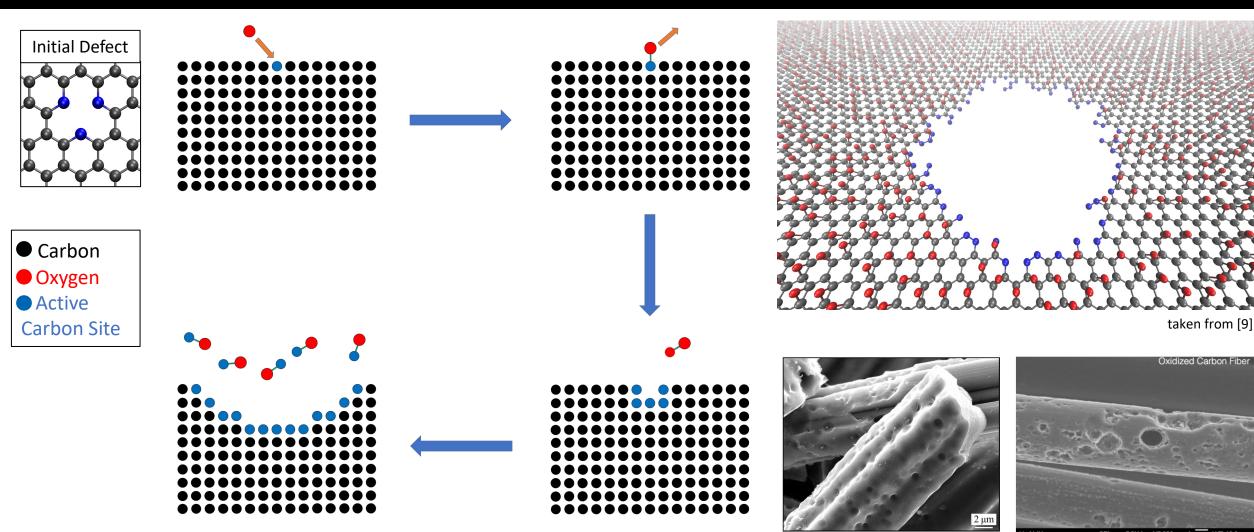
- Implement active-site capability in DSMC and capture the pitting process.
- Analyze the changes in reactivity due to active sites.

^[1] F. Panerai, et al. In: Proceedings of the 44th AIAA Thermophysics Conference. 2013, pp. 1–14

^[2] F. Panerai et al. In: International Journal of Heat and Mass Transfer 108 (2017), pp. 801–811. doi: 10.1016/j.ijheatmasstransfer.2016. 12.048.

Pitting in Carbon Surface Oxidation





^[9] Simon Schmitt (2020), PhD thesis.

taken from [11]

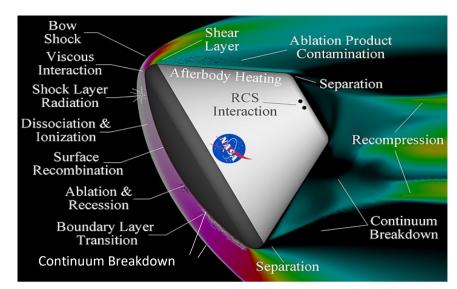
taken from [10]

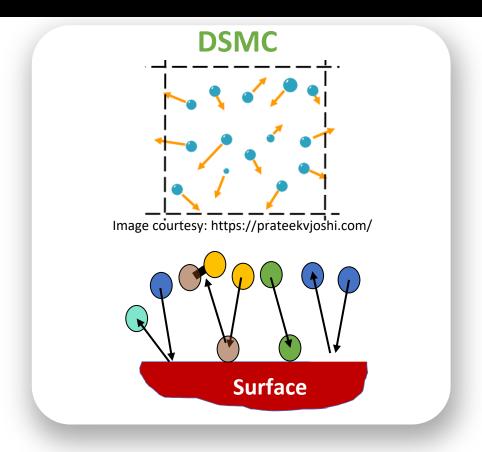
³

DSMC – SPARTA [4]



Continuum breakdown



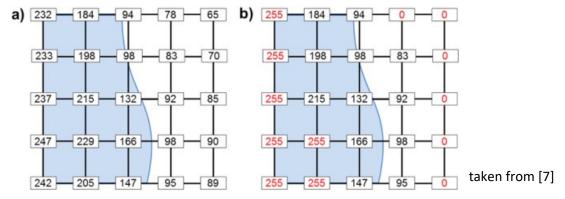


- CFD is not valid in regions of continuum breakdown
- DSMC (direct simulation Monte Carlo) is a stochastic, particle-based method to solve the Boltzmann equation
- DSMC is valid in all regimes: continuum, rarefied and transition (however computational cost increases with density)

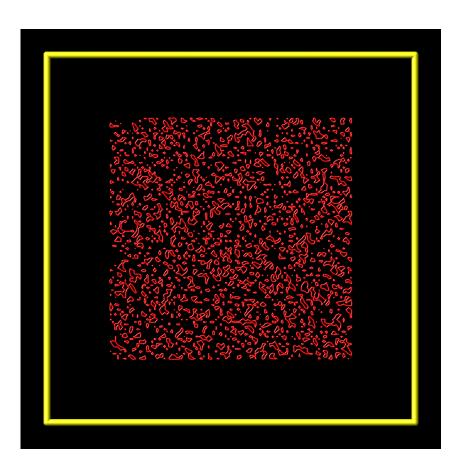
Ablation with implicit surfaces in SPARTA



- Geometry of individual elements inferred from 2D or 3D input file with pixel or voxel micro-CT data
- Choice of threshold determines solid-gas boundary



- Triangulation of level-set surface computed by Marching Squares (MS; in 2D) or Marching Cubes (MC; in 3D) algorithms
- Up to 15 triangles per cell, entirely contained within grid cell
- MC is inherently parallel
- Implementation of MC in SPARTA includes topological and robustness enhancements to guarantee watertightness [8]

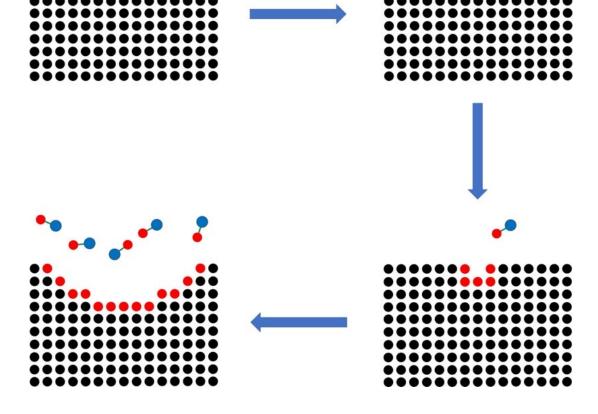


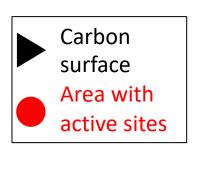
Active Site Implementation in SPARTA

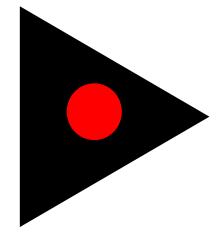


Guiding Principle:

- New surface quantity called "active site fraction" (ASF) = fraction of surface element area with active sites
- Based on ASF, gas particles collide either with active or passive site
- Reactivity at active sites is much higher than at passive sites, and the reaction rate for oxidation (CO formation) is scaled accordingly

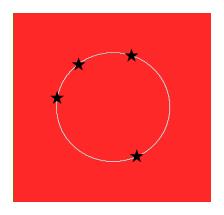


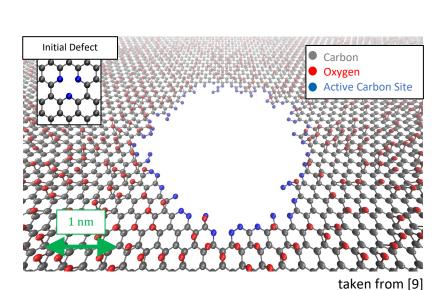




Active Site Implementation in SPARTA







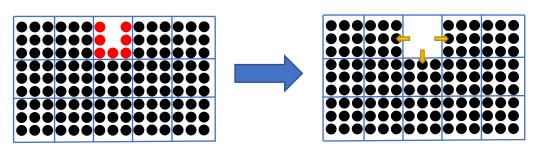
Methodology:

- Initialization
 - Defects are randomly distributed on a few surface elements based on user input defect density.
 - Active site fraction for these surface elements are set to a small number.

- Change in ASF (within a grid cell) due to reactions
 - This step is complex, as the increase or decrease of active sites due to a carbon removal depends on the actual geometry.
 - Currently ASF remains unchanged due to reactions.
 - ❖ Will use kMC simulations to get realistic values for change in ASF.

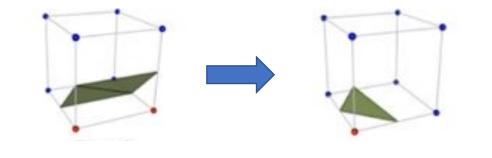
Active Site Implementation in SPARTA





Methodology:

- Propagation to neighboring elements
 - When a grid cell is fully consumed (ablated), ASF of all neighboring elements are initialized to a small value.



- Continuation through ablate step in DSMC
 - Before ablate ASF of surface elements within a cell is averaged.
 - After ablate ASF of new surface elements is set to this averaged value.

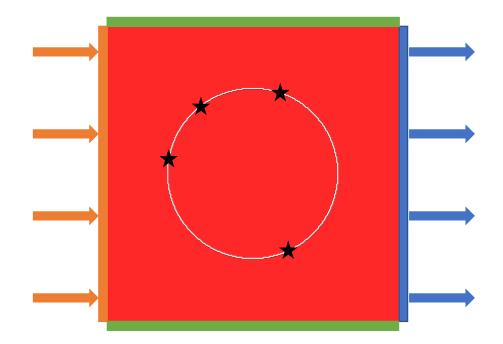
taken from [8]

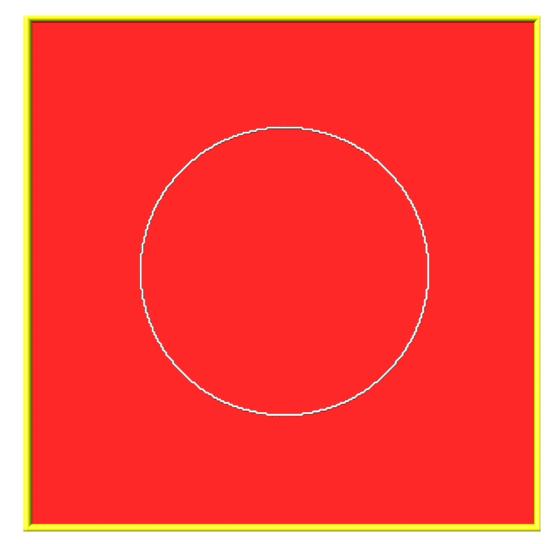
DSMC Results – 2D



Simulation setup:

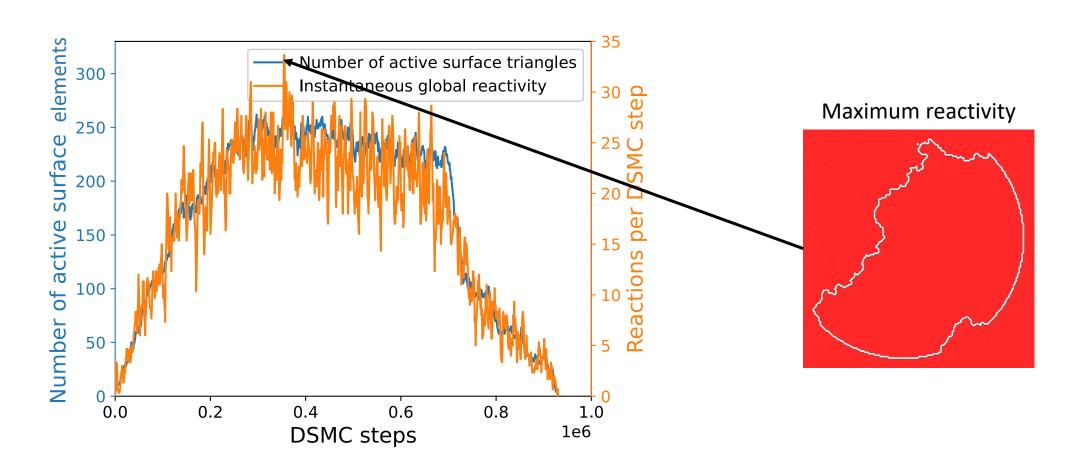
- Atomic Oxygen particle inflow
- O/CO particle outflow
- Periodic BC
- Initial active sites





Evolution of active surfaces vs reactions





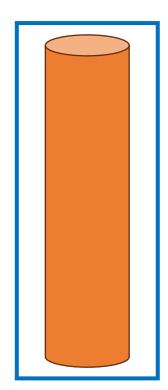
Pitting causes nonlinear variation in reactivity due to active site evolution and flow-geometry interactions

Pitting Simulation Results – Single Fiber



Simulation setup:

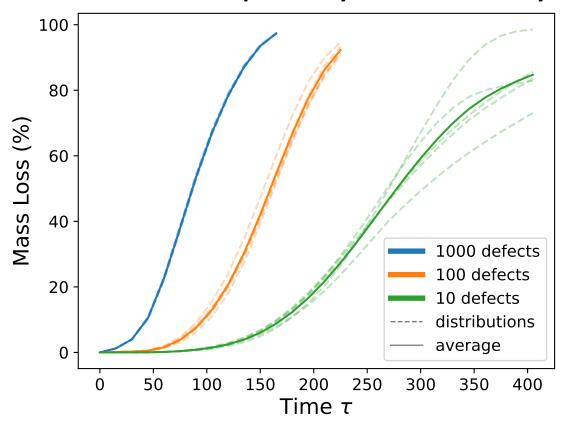
- Cylindrical fiber, 10 μm diameter, 100 μm length
- 0.5 μm voxel size
- Constant oxygen pressure
- Varying number of defects and distributions



Pitting Simulation Results – Single Fiber



Ablation rate dependency on defect density



- Pitting fragments fiber into chunks
- Higher number of pits cause faster ablation
- Variance with pit distribution is inversely related to number of pits

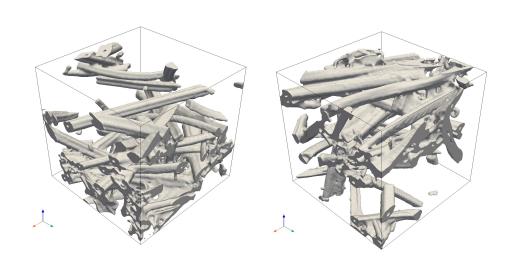
Pitting Simulation Results – FiberForm

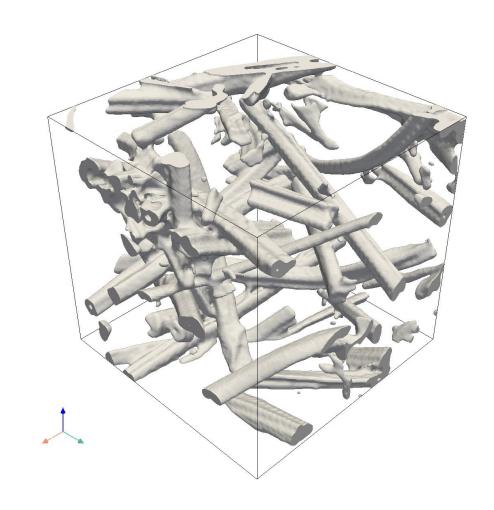


Simulation setup:

- Three 200^3 voxel substructures from FiberForm μCT scan
- 0.65 μm voxel size
- Constant oxygen pressure
- Varying number of defects and distributions

Other Substructures

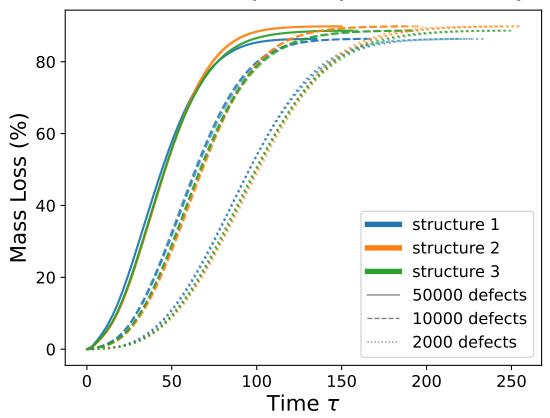




Pitting Simulation Results – FiberForm



Ablation rate dependency on defect density



- Higher the number of defects/active sites, faster the ablation.
- Variance with pit distribution generally very low.
- Variance between different substructures is also low.

Summary



- Active-site-fraction feature was implemented in DSMC code SPARTA to simulate the formation of etch pits
 due to oxidation of carbon ablators.
- Simulations of pitting were performed for a single fiber and FiberForm.
 - Reactivity is directly linked to the active surface elements.
 - Pitting causes nonlinear variation in reactivity due to active site evolution and flow-geometry interactions.
 - Pitting fragments fiber into chunks.
- Effect of the defect density and structure variation was also investigated.
 - Total ablation time decreases with increasing number of defects.
 - Variance with pit distribution is inversely related to number of pits.
 - Larger structures has smaller variance with pit distribution.
 - Different fiber substructures also have low variance in the total ablation time.

Future Work



Improve active-site feature in SPARTA to be more physically accurate.

- Change in ASF within a grid cell due to reactions
 - Currently performing kMC simulations to get realistic values.
- Propagation to neighboring elements
 - > Pits grow faster in the in-plane direction than the in-depth direction.
 - Propagate the pits in the in-plane direction before the cell is fully depleted.

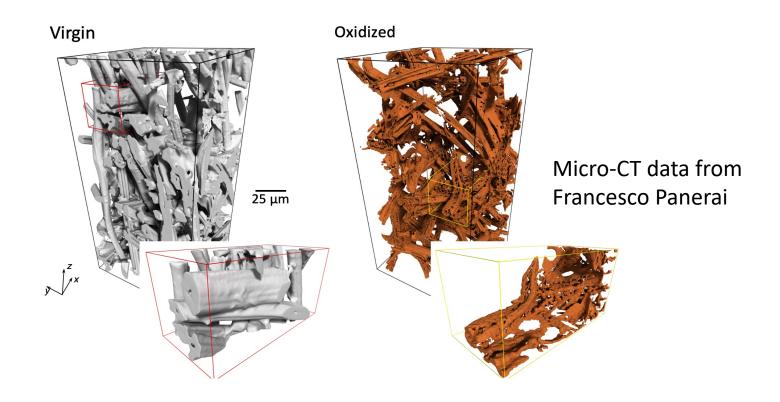
90% 85% 80% 75%

In-plane propagation at a cell depletion of

Future Work

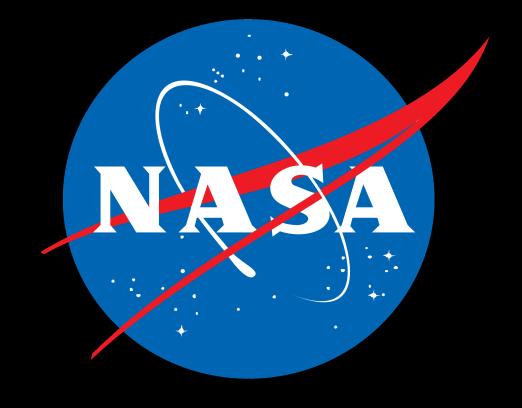


- Compare pitted FiberForm structures from SPARTA with experiments
- Analyze the distribution of pit sizes and growth rates of the pits.



Thank You Questions?

National Aeronautics and Space Administration



Ames Research Center
Entry Systems and Technology Division



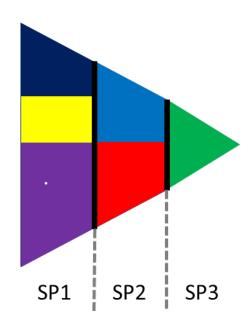
Backup Slides

Surface chemistry framework in DSMC [5]



- Methodology to represent surface sites similar to Marschall, Maclean and Driver [6] for CFD.
- Particles adsorb (deleted) and desorb (created) on the surface, surface element stores adsorbed particle concentration.
- Surface reactions based on concentration within surface element.
- Multiple triangulated elements (like cells) on surfaces
- Langmuir model for surface sites.

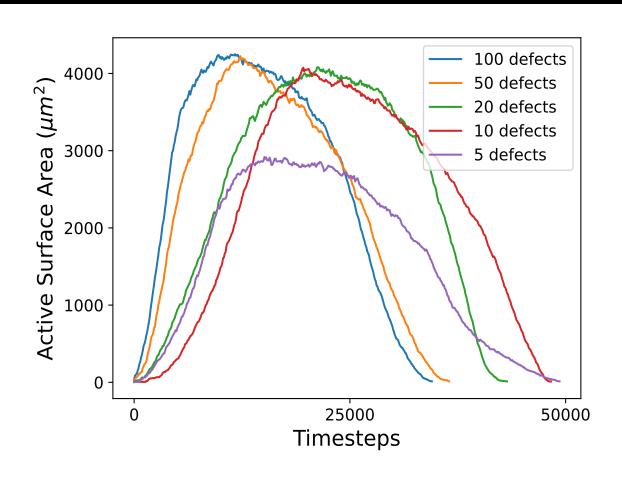
Environments					<u>Phases</u>	Site Sets
Gas	GP1					$N_{ss, SP1} = 3$ $N_{ss, SP2} = 2$
Surface	SP1	SP2		SP3	N _{SP} = 3	$N_{ss, SP2} = 2$ $N_{ss, SP3} = 1$
Bulk	BP1			BP2	N _{BP} = 2	
taken from Marschall and Mac						

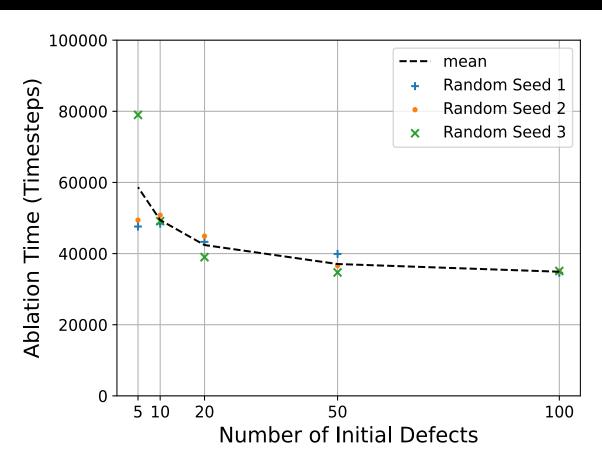


^[5] Swaminathan Gopalan, K., & Stephani, K. A. (2018). Development of a detailed surface chemistry framework in DSMC. In 2018 AIAA Aerospace Sciences Meeting (p. 0494).

Total ablation time







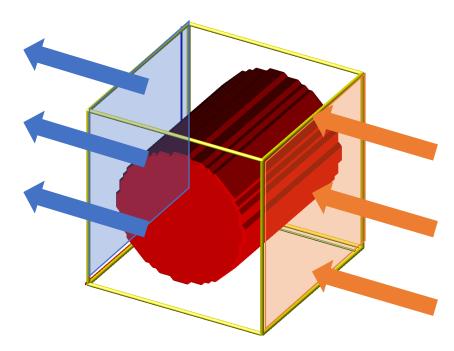
Total ablation time decreases with increasing number of defects.

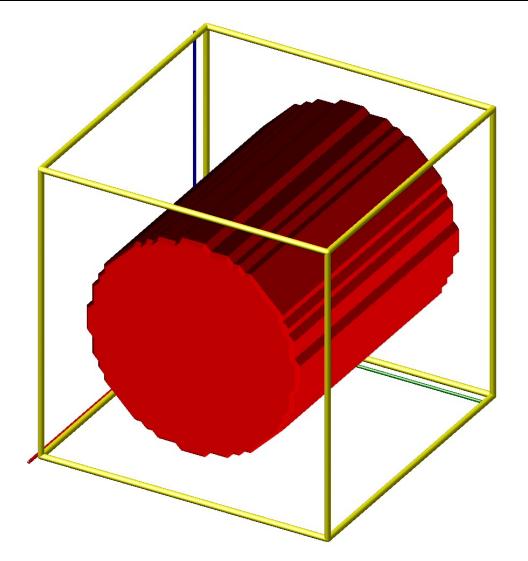
DSMC Results – 3D



Simulation setup:

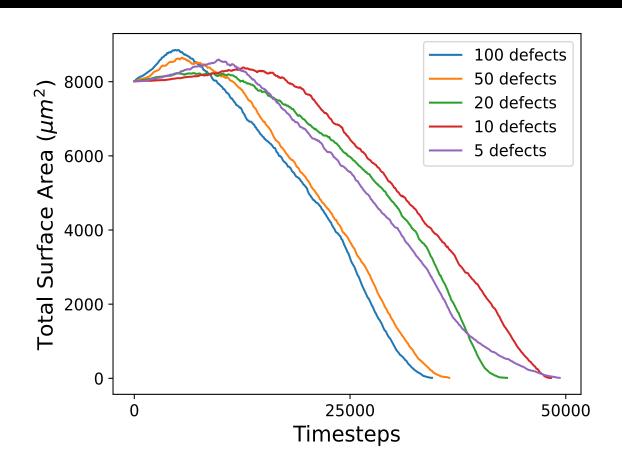
- Atomic Oxygen particle inflow
- O/CO particle outflow
- Periodic BC everywhere else
- Random distribution of initial active sites

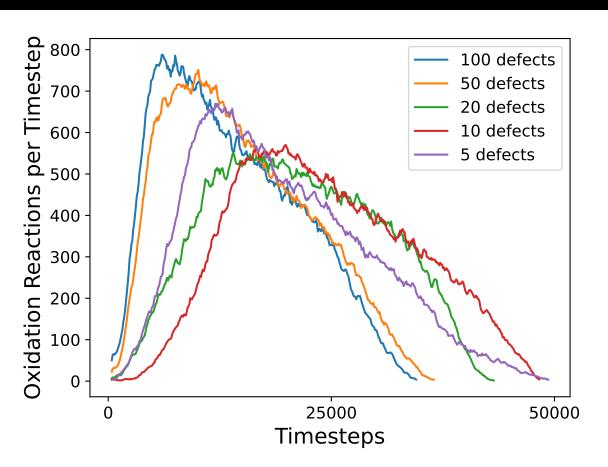




Effect of defect density



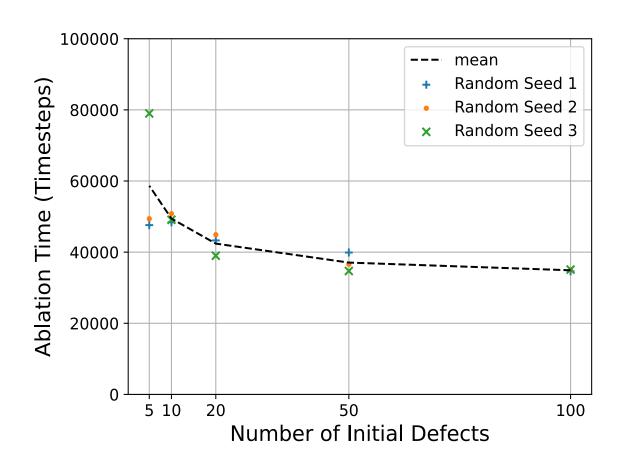




- Total surface area initially increases with material removal.
- Peak in reactivity occurs earlier with increasing number of defects.
- Reactivity decreases after the peak due to decreasing surface area.

Total ablation time





Total ablation time decreases with increasing number of defects.