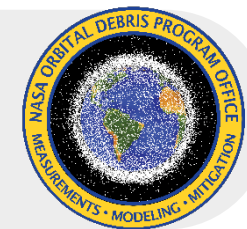




National Aeronautics and Space Administration

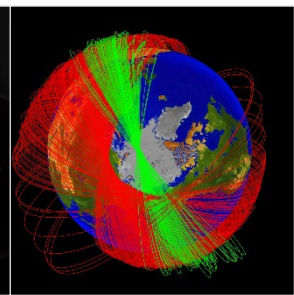
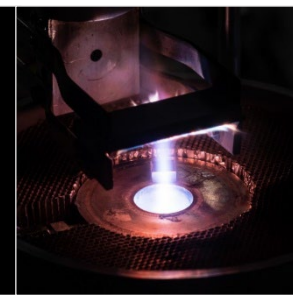
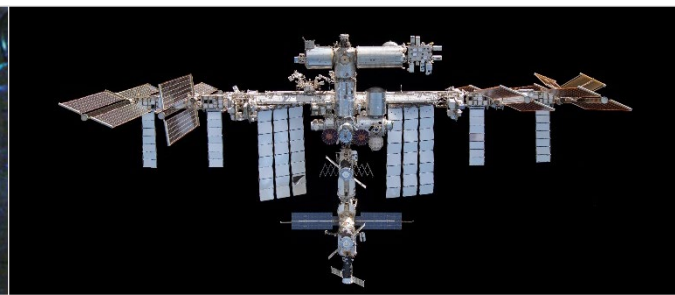
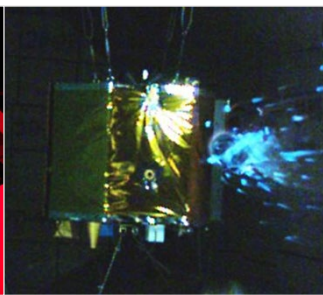
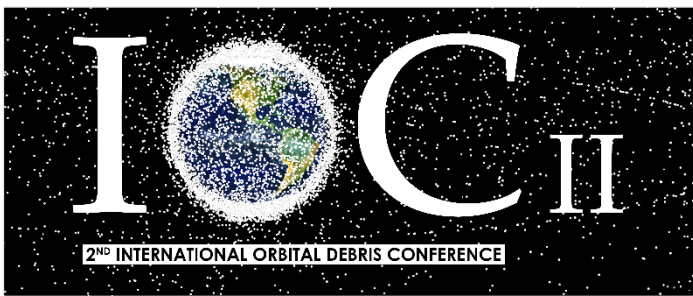


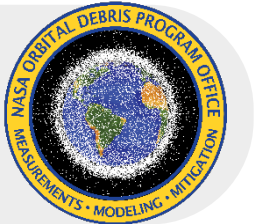
An Approach to Shape Parameterization Using Laboratory Hypervelocity Impact Experiments

John H. Seago

ERC—Jacobs JETS II Contract

NASA Orbital Debris Program Office



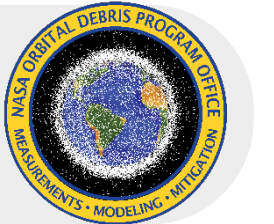


SOCIT & DebrisSat Impact Experiments

- **Satellite Orbital Debris Characterization Impact Test (SOCIT) hypervelocity impact test series**
 - December 1991 to January 1992
 - Fourth test (SOCIT4) targeted a flight-ready Navy Transit satellite bus
- **Current breakup models like the NASA Standard Satellite Breakup Model (SSBM) use SOCIT4 test results**
 - About 59% of the spacecraft's total mass analyzed
 - ~810 recorded fragments or fragments groups
- **DebrisSat experiment builds upon the previous impact test data by utilizing more modern materials typical of low Earth orbit (LEO) satellites today**
 - Better represents evolving materials and technology that may fragment differently
- **DebrisSat's post-impact processing targets collection of fragments greater than or equal to 2 mm**
 - 205K+ individual fragments recorded thus far
 - ~60K have mass, dimensions, primary material, shape recorded

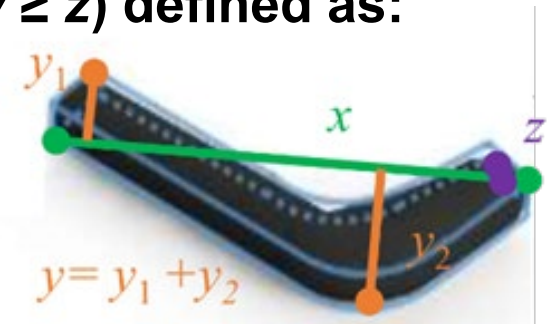
SSBM well represented the major in 2009 on-orbit collision involving Cosmos 2251
– a legacy spacecraft

High area-to-mass ratio materials not well represented in collisions with *Fengyun-1C* (2007) and Iridium 33 (2009)



SOCIT & DebrisSat Fragment Datasets

- **Fragment database records involving shape assessment**
 - Mass, dimensions, volume, primary material, shape designation (from inspection)
- **Estimated size and shape**
 - DebrisSat: point-clouds from imagery
 - SOCIT: manually measured with calipers
- **Mutually perpendicular Orthogonal-projection measurements ($x \geq y \geq z$) defined as:**
 - x is the longest projected dimension across the fragment
 - y is the longest projected dimension orthogonal to x
 - z is the longest projected dimension orthogonal to the x - y plane
- **Average of these orthogonal projections produces a characteristic length, L_c ,**
 - A standard metric of size for space-debris observations
 - Independent of the aspect angle or remotely sensed object





Fragments As Cylindrical Shapes

Rod-like (straight)



Rod-like (bent)

Nugget-like



- Rod-like
 - One “much longer” dimension
- Plate-like
 - One “much shorter” dimension
- Nugget-like
 - All dimensions similar
- Flexible
 - Shape changes or doesn’t hold

Plate-like (straight)

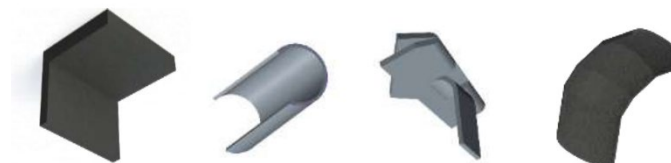


Plate-like (bent)



Simplified Shapes Categories

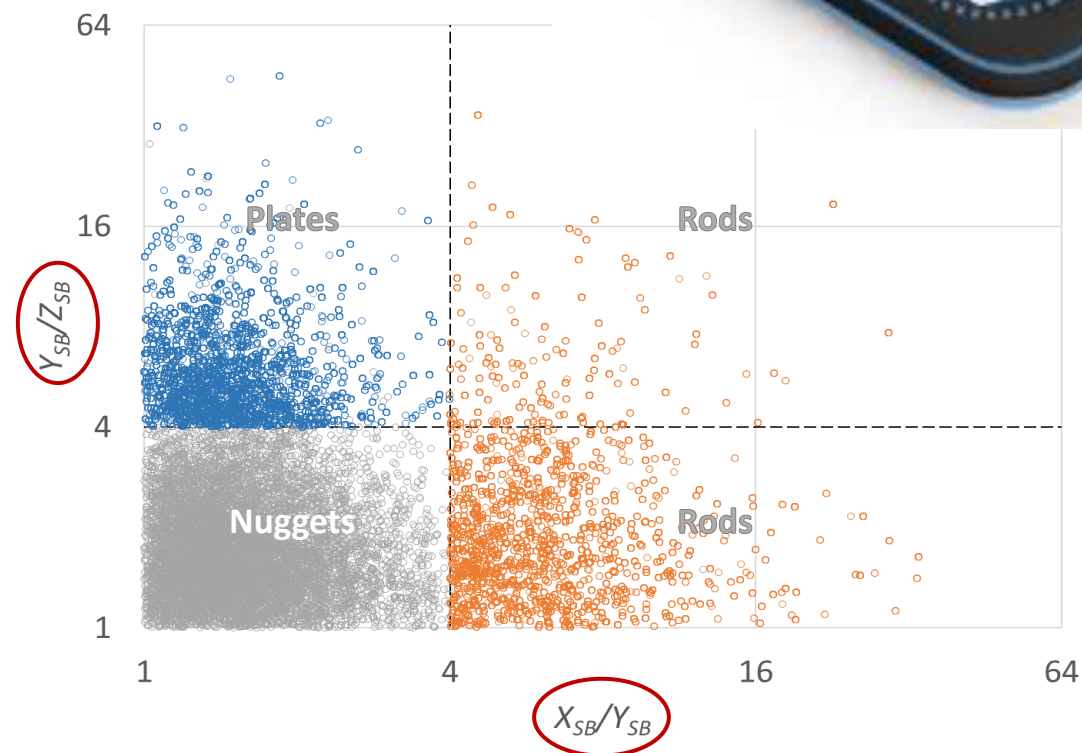
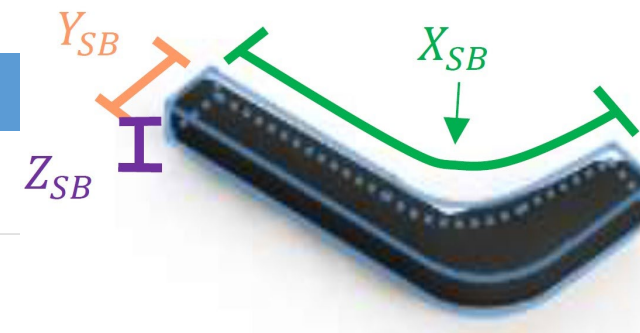
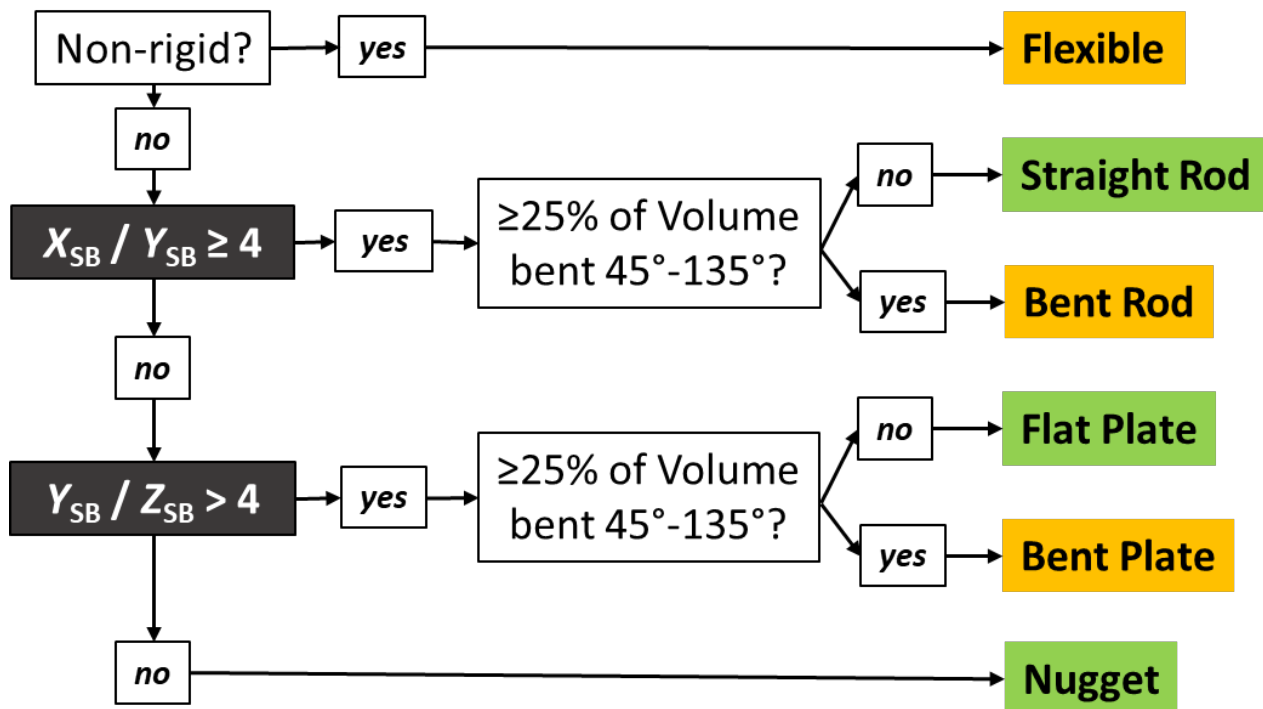
SOCIT		%	DebrisSat		%	Simplified
- Flat Plate - Flake	(1%) (13%)	14%	Flat Plate	(36%)	36%	Plate
Curled Plate	(1%)	1%	- Flexible - Bent Plate	(1%) (2%)	3%	Plate (Bent)
- Box - Sphere - Box & Plate - Nugget - Other	(0.3%) (<0.1%) (<0.1%) (59%) (23%)	83%	Parallelepiped/nugget/spheroid	(19%)	19%	Nugget
			Bent needle/rod/cylinder	(11%)	11%	Rod (Bent)
- Rod - Cylinder	(2%) (0.3%)	2%	Straight needle/rod/cylinder	(31%)	31%	Rod
	(100%)	100%		(100%)	100%	

SOCIT's 10 categories and DebrisSat's 6 categories simplified to 3 Right Circular Cylinder (RCC) proportions (plates, nuggets, rods) for intercomparison



Assigning Shapes with Dimensions

Ideal Decision logic for characterizing *DebrisSat* shapes based on $X_{SB} \geq Y_{SB} \geq Z_{SB}$



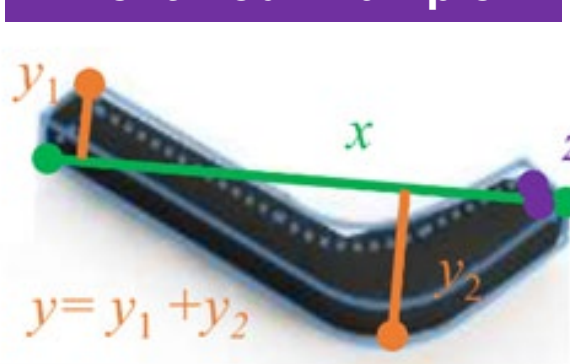
SOCIT defined 10 shape categories and mostly relied on individual judgments



Assigning Shapes with Dimensions

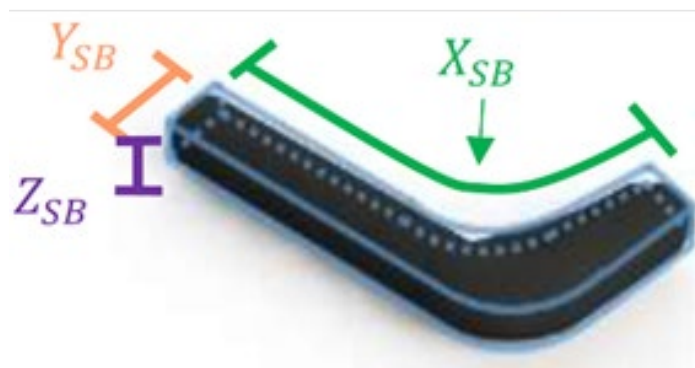
Bent Rod Example

Orthogonal-projections
($x \geq y \geq z$)



Recorded in
Database, with
 $L_c = (x + y + z)/3$

Solid-body
dimensions
($X_{SB} \geq Y_{SB} \geq Z_{SB}$)

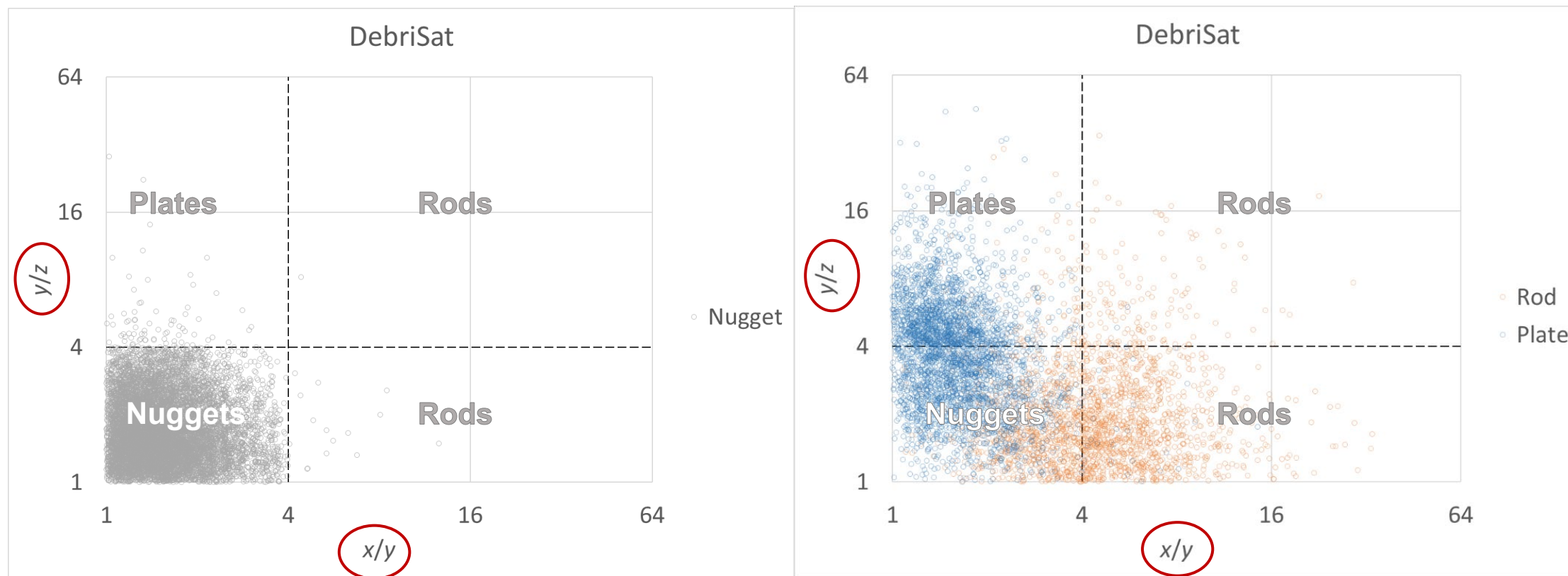


Estimated during
inspection,
not recorded

Most fragment bending thought to occur during impact with foam catch system



Can Orthogonal Projection Assign Shape?



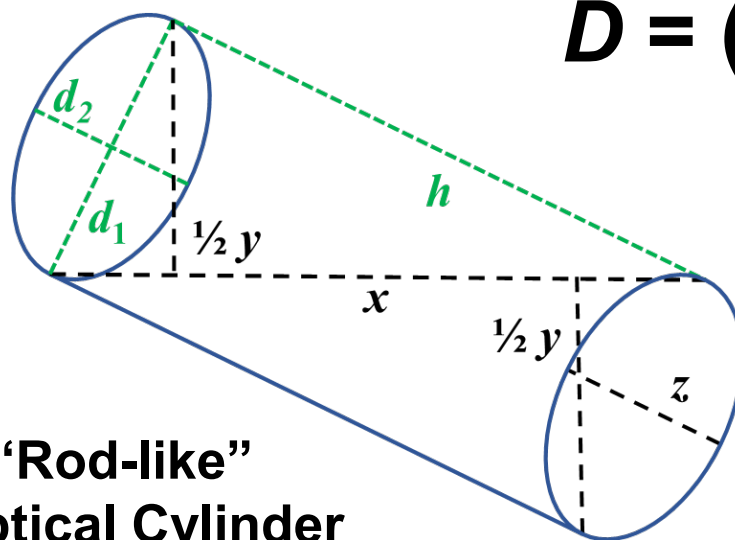
% Agreement	Plates	Nuggets	Rods
SOCIT	43%	94%	69%
DebrisSat	76%	99%	67%



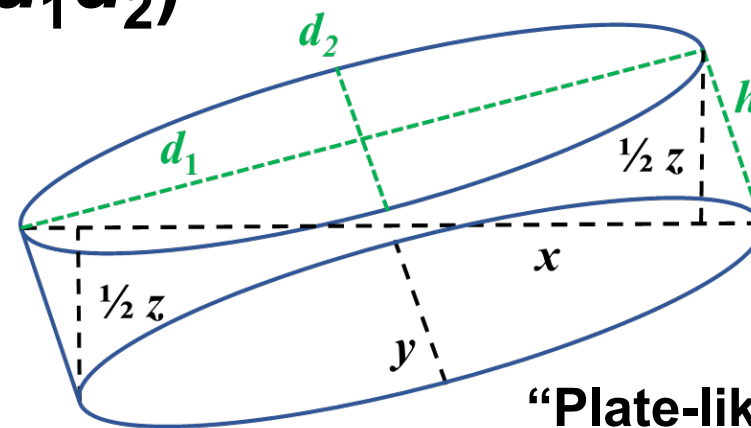
Cylindrical Shape Based on $(x \geq y \geq z)$

Ratio of Length-to-Diameter $L:D \equiv h \div D$

$$D = (d_1 d_2)^{1/2}$$

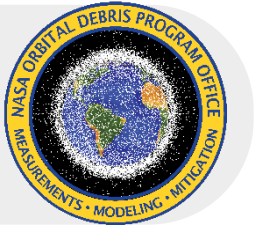


**“Rod-like”
Elliptical Cylinder**
 $h > D = (d_1 d_2)^{1/2}$



**“Plate-like”
Elliptical Cylinder**
 $h < D = (d_1 d_2)^{1/2}$

A cylindrical shape can be imagined to enclose a fragment,
then a RCC shape can be characterized by $L:D$



Cylindrical Shape Based on $(x \geq y \geq z)$

Ratio of Length-to-Diameter $L:D \equiv h \div D$

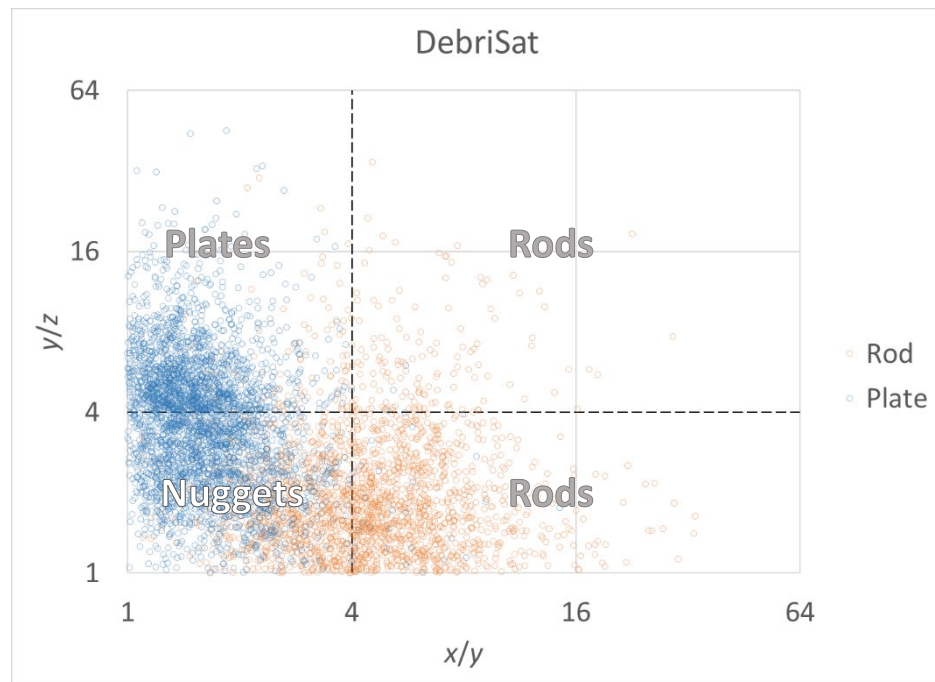
$$D = (d_1 d_2)^{1/2}$$

	“Rod-like”	“Plate-like”
$h^2 =$	$\frac{1}{2} \left(1 + \sqrt{1 - \left(\frac{y}{x} \right)^2} \right) x^2$	$\frac{1}{2} \left(1 - \sqrt{1 - \left(\frac{z}{x} \right)^2} \right) x^2$
$d_1 =$	$\frac{yx}{2h}$	$\frac{zx}{2h}$
$d_2 =$	z	y

Plane geometry can transform orthogonal projections $(x \geq y \geq z)$ to (h, d_1, d_2) defining $L:D$

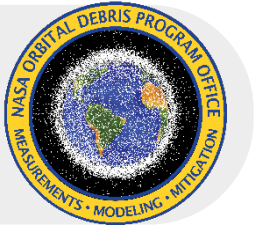


Cylindrical Shape Based on $(x \geq y \geq z)$



	Plates		Rods	
	$(x \geq y \geq z)$	(h, d_1, d_2)	$(x \geq y \geq z)$	(h, d_1, d_2)
SOCIT	43%	75%	69%	69%
DebrisSat	76%	92%	67%	88%
DebrisSat (w/o CFRP)	37%	75%	26%	67%
DebrisSat (w/o CFRP, unbent only)	46%	84%	57%	83%
DebrisSat (w/o CFRP, bent only)	16%	56%	16%	62%

For RODS & PLATES, transformation of $(x \geq y \geq z)$ to (h, d_1, d_2) correlates better to inspector-assigned shapes using the DebrisSat Shape Logic Rubric



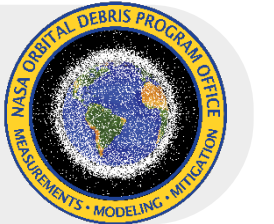
Cylindrical Shape Based on Volume

Geometric Volume of a Cylinder $V \equiv \frac{1}{4} \pi D^2 h$

$$D = (d_1 d_2)^{1/2}$$

	Flat Plate	Nugget/ Spheroid	Straight Rod
$L:D$	$\frac{4 V}{\pi} (d_1 d_2)^{-\frac{3}{2}}$	$\sqrt{\frac{\pi y^3}{4 V}}$	$\sqrt{\frac{\pi h^3}{4 V}}$

Volume can be substituted into the $L:D$ ratio through a change of variable(s) to estimate $L:D = f(V)$.



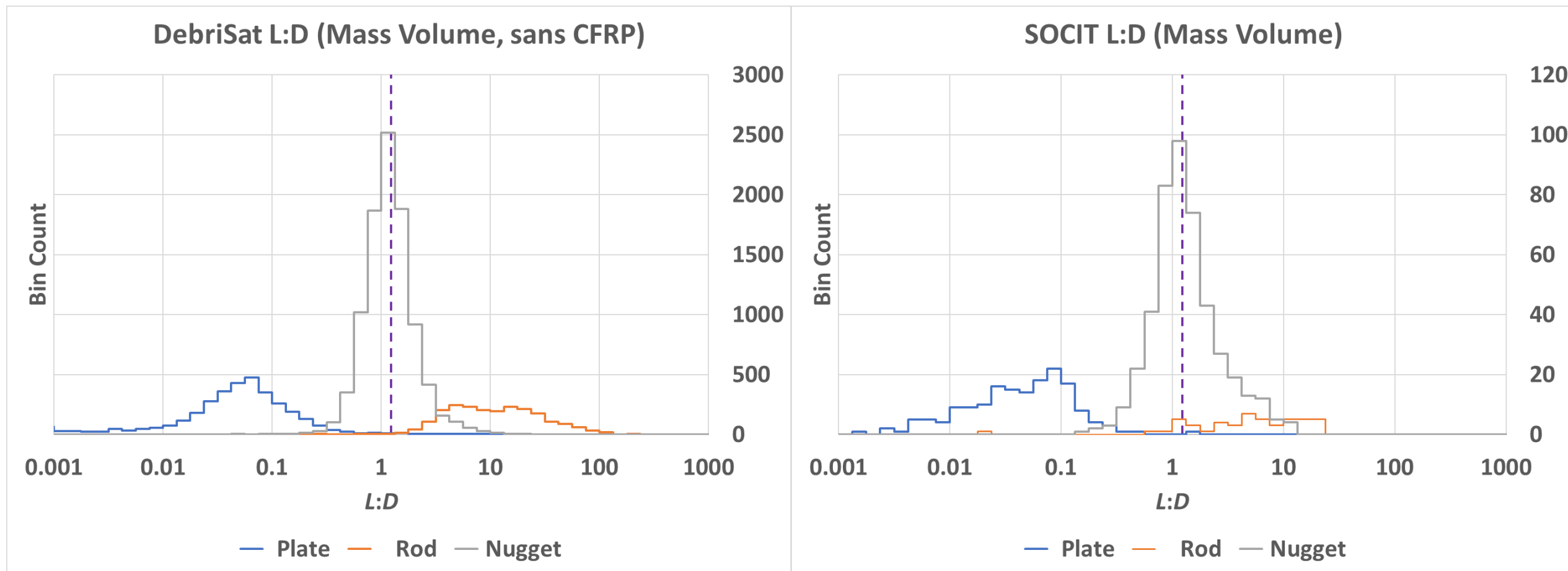
Cylindrical Shape Based on Volume

Geometric Volume of a Cylinder $V \equiv \frac{1}{4} \pi D^2 h$

Volume Type	Expression	Advantages	Disadvantages
Geometric	$\frac{1}{4} \pi d_1 d_2 h$	• Definable for all usable fragments from $x \geq y \geq z$ alone	• Assumes a cylindrically shaped fragment orthogonally measured
Bulk	"Measured"	• Based on observed fragment dimensions (actual shape) • Distributionally well-behaved	• SOCIT records no bulk volumes • Only DebrisSat has measured volumes
Mass	m / ρ	• Definable for all usable fragments • Explicit function of mass • Conservative risk assessments	• Fragment densities approximate, based only on primary material • Materials not always accurate • Shape distributions spread out



Distributions of Simplified Shape

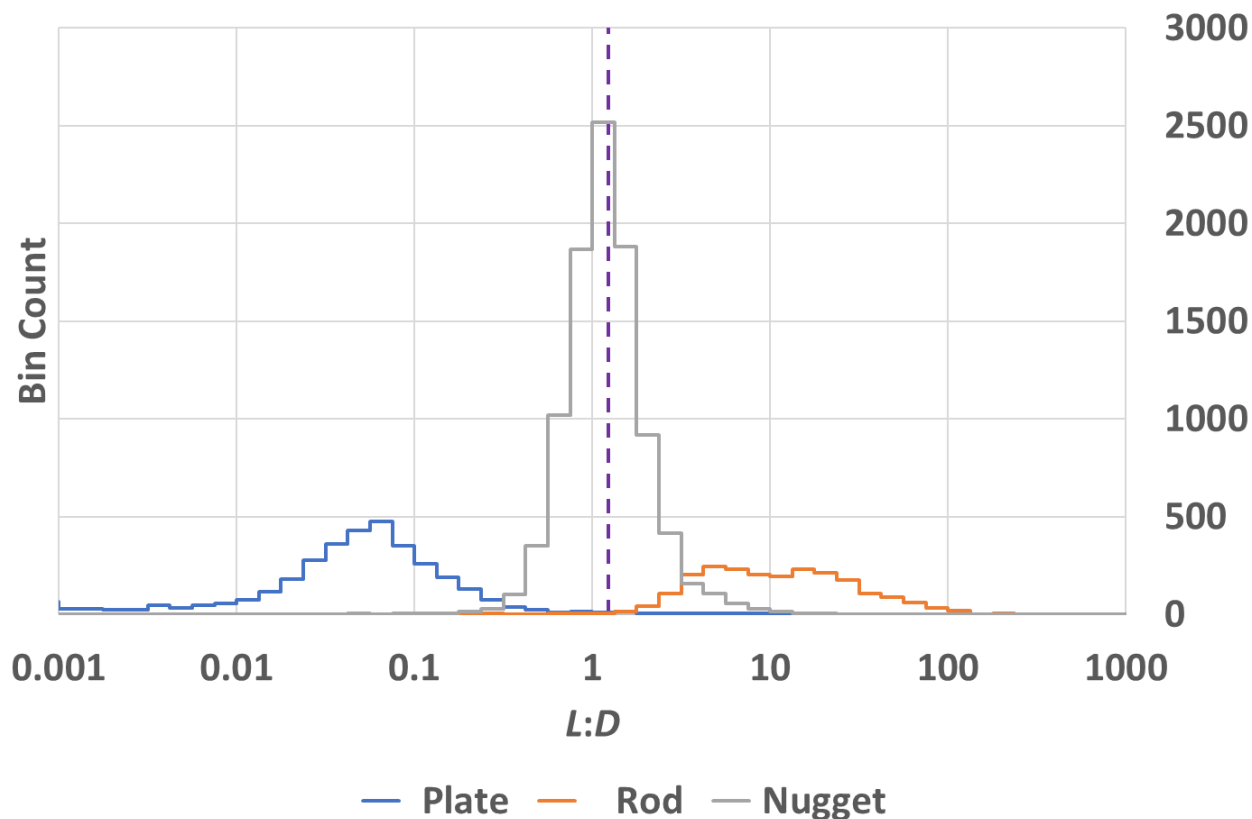


Distributions of estimated $L:D$ ratio based on $V = m/\rho$ (with bent shapes omitted)
CFRP omitted from DebrisSat & SOCIT counts based on groups
Dashed vertical indicates stubby rod with spherical volume

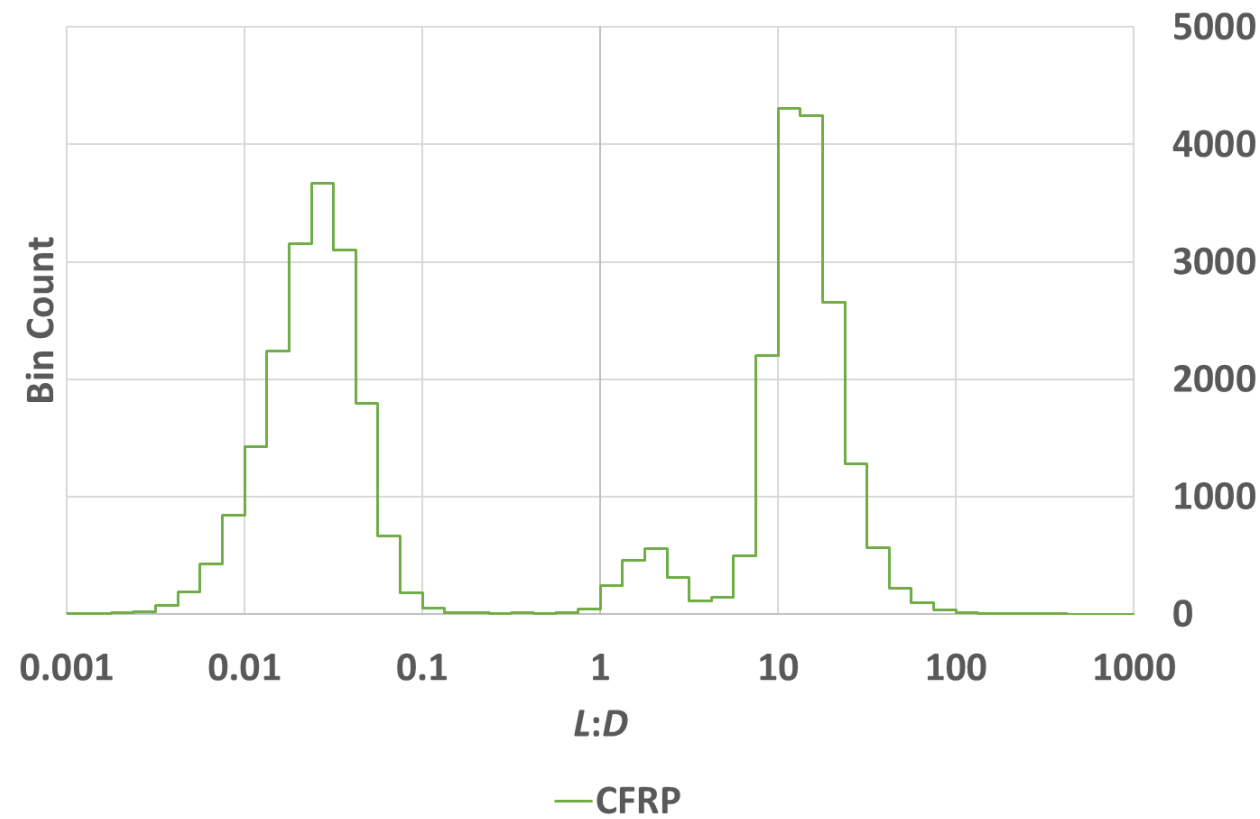


Distributions of Simplified Shape

DebrisSat L:D (Mass Volume, sans CFRP)



DebrisSat L:D (Mass Volume, CFRP only)



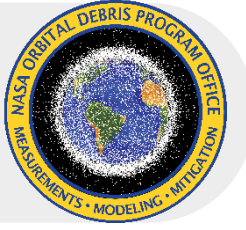
Distributions of estimated $L:D$ ratio based on $V = m/\rho$ (with bent shapes omitted)



Simplified Density Categories

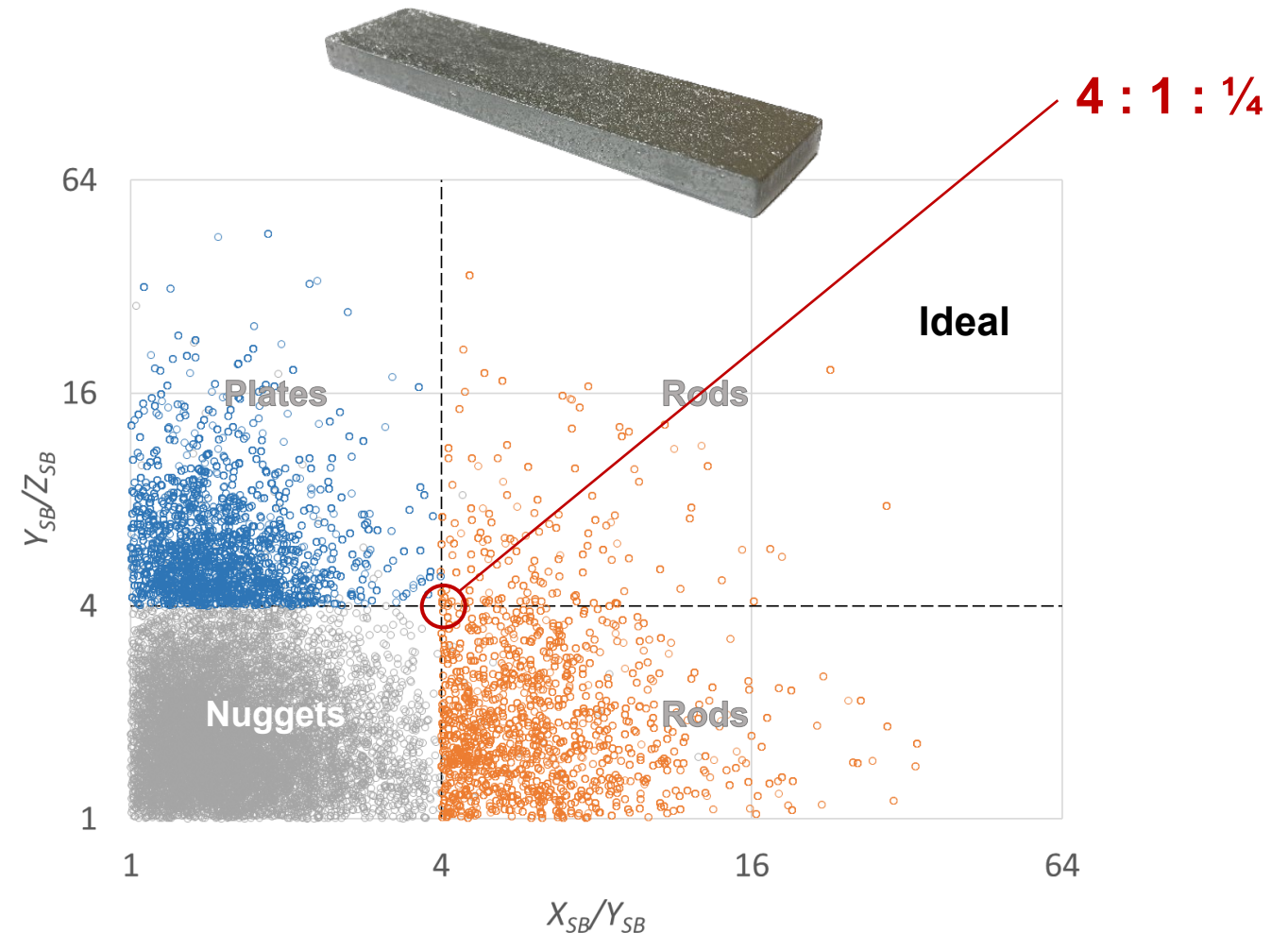
SOCIT Material	%	DebrisSat Material	%*	Category	Density
		○ CFRP	61%	CFRP	1.5 g/cm ³
- Fiberglass - Phenolic/Plastic	8% 68%	- Epoxy - Polyimide film - Para-aramid synthetic fiber - Multi-Layer Insulation, MLI - Printed Circuit Board, PCB - Plastic - Silicon	6% 0.8% 0.4% 4% 1% 6% 0.8%	Low Density (LD)	< 2 g/cm ³
- Al - Other	22% 1%	- Al - Glass - Metal - Solar Cell	5% 1% 2% 0.4%	Medium-Low Density (MD-lo)	2–4 g/cm ³
		○ Titanium	1%	Medium-High Density (MD-hi)	4–6 g/cm ³
- Copper - Steel	0.3% 0.7%	- Copper - Steel	9% 2%	High Density (HD)	> 6 g/cm ³
	100%		100%		

*DebrisSat database contents as of 27 January 2023



RCC $L:D$ Ratio Definitions: Why 3 Groups?

- $L:D$ estimates collect into three populations
 - Inspector's designated shape predestines magnitude of $L:D$ ratio
 - Fragment's relative dimensions add precision to $L:D$ estimate.
- Hypothetical fragment
 - $X_{SB}/Y_{SB} = Y_{SB}/Z_{SB} = 4$
- Different $L:D$ based on assigned shape
 - $L:D_{\text{plate}} = 1:8 (< 1)$
 - $L:D_{\text{rod}} = 8:1 (> 1)$
 - $L:D_{\text{nugget}} \approx 27:10 (\sim 1)$





RCC $L:D$ Ratio Definitions: Why 3 Groups?



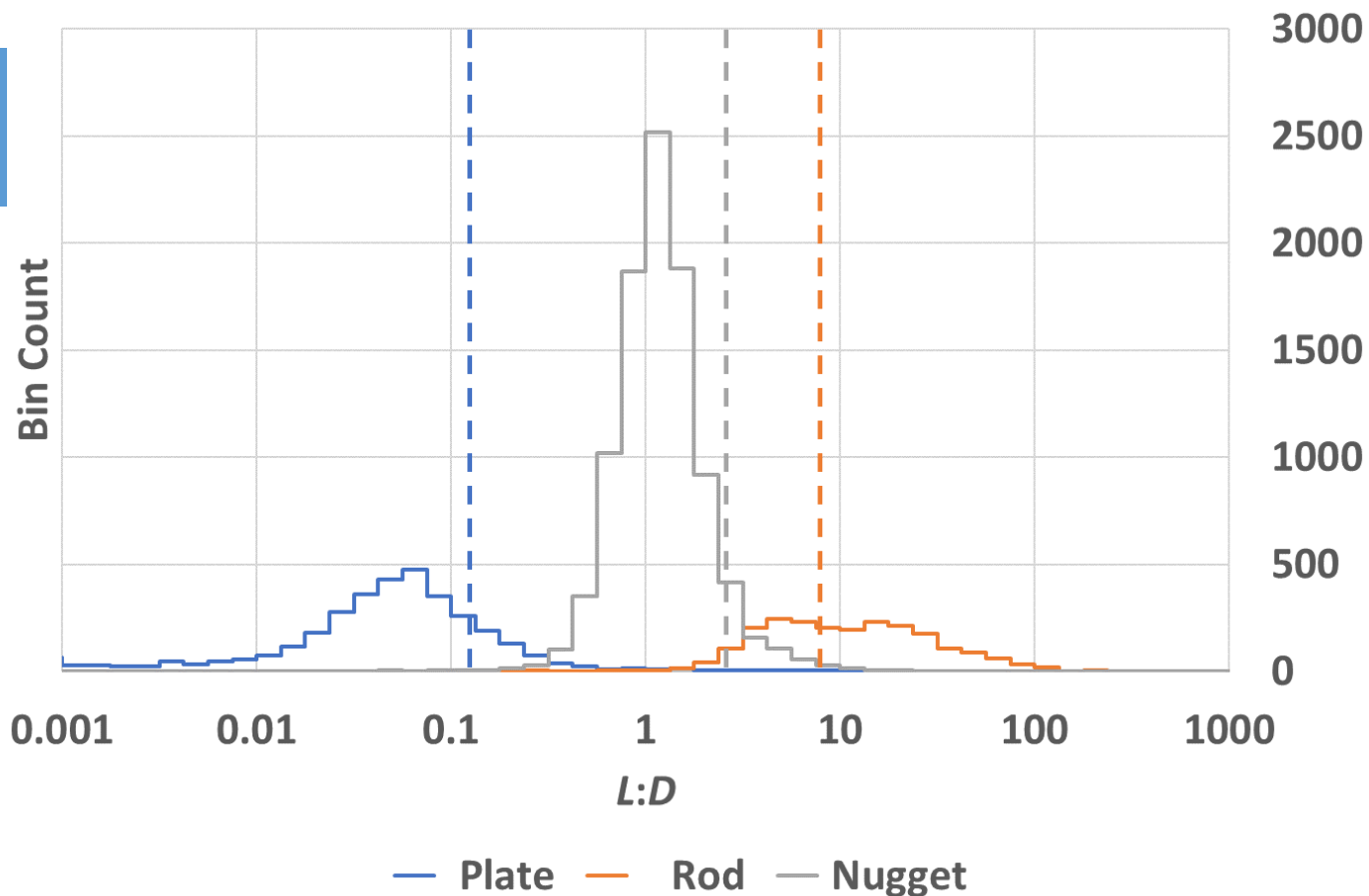
DebrisSat $L:D$ (Mass Volume, sans CFRP)

$$L:D_{ave} = \frac{\sum_{i=1}^{nbins} n_i \cdot (L:D)_i}{\sum_{i=1}^{nbins} n_i}$$

Ave. $L:D_{plate} = 1:19$

Ave. $L:D_{nugget} = 1:1$

Ave. $L:D_{rod} = 15:1$



$L:D$ ratios of the
borderline (4 : 1 : ¼)
shape

$L:D_{plate} = 1:8 (< 1)$

$L:D_{nugget} \approx 27:10 (\sim 1)$

$L:D_{rod} = 8:1 (> 1)$

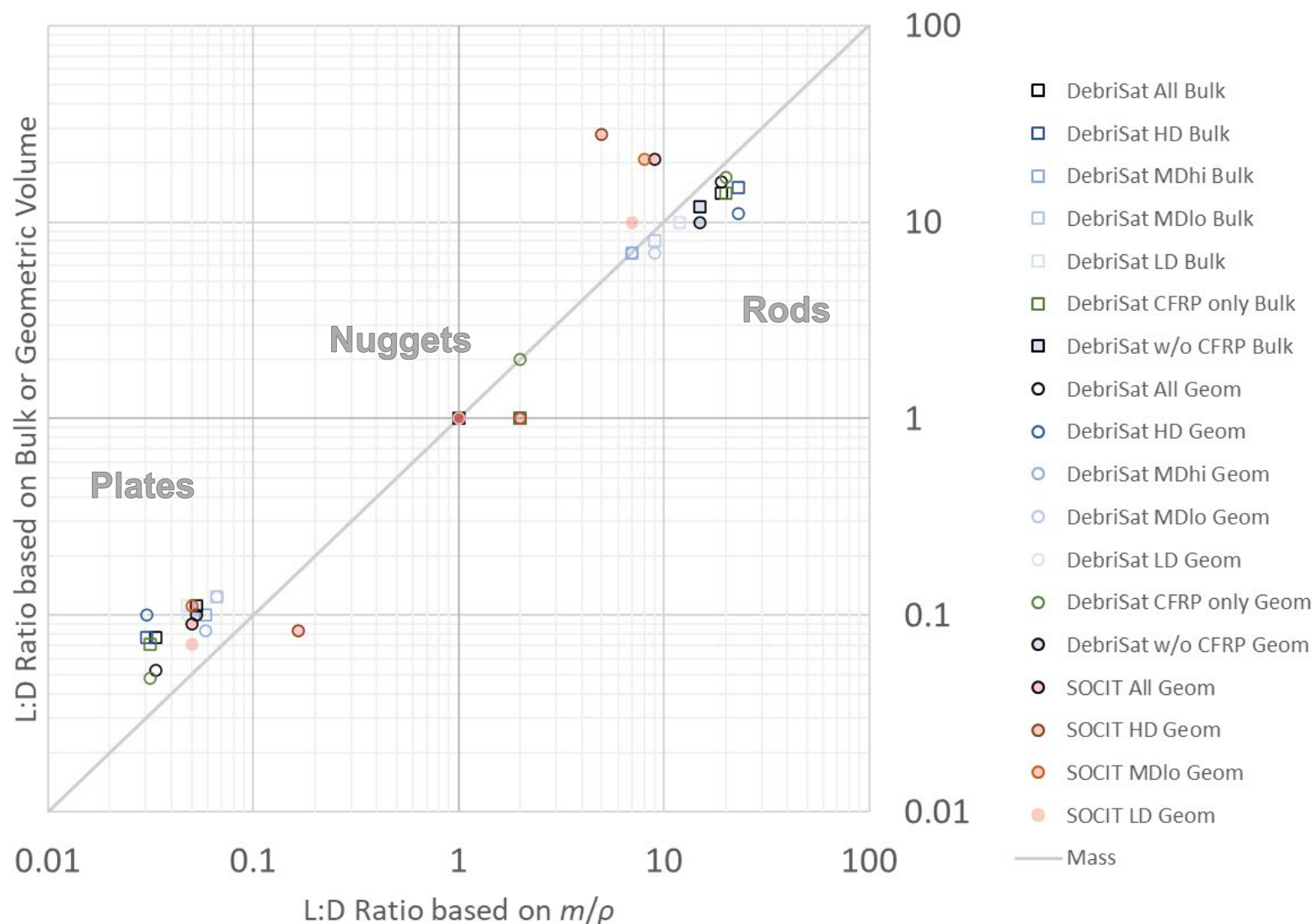


Average $L:D$ from Different Estimators

		Mass-based, $V = m/\rho$			Bulk, V “observed”			Geometric, $V = \frac{1}{4} \pi h d_1 d_2$		
		Plates	Nuggets	Rods	Plates	Nuggets	Rods	Plates	Nuggets	Rods
SOCIT	All	1:20	1:1	9:1	--	--	--	1:11	1:1	21:1
DebrisSat	All	1:30	2:1	19:1	1:13	1:1	14:1	1:19	1:1	16:1
DebrisSat	w/o CFRP	1:19	1:1	15:1	1:9	1:1	12:1	1:10	1:1	10:1
DebrisSat	CFRP only	1:32	2:1	20:1	1:14	1:1	14:1	1:21	2:1	17:1
SOCIT	LD	1:20	1:1	7:1	--	--	--	1:14	1:1	10:1
DebrisSat	LD	1:21	1:1	12:1	1:9	1:1	10:1	1:10	1:1	10:1
SOCIT	MDlo	1:20	2:1	8:1	--	--	--	1:9	1:1	21:1
DebrisSat	MDlo	1:15	1:1	9:1	1:8	1:1	8:1	1:8	1:1	7:1
DebrisSat	MDhi	1:17	1:1	7:1	1:10	1:1	7:1	1:12	1:1	7:1
SOCIT	HD	1:6	1:1	11:1	--	--	--	1:12	1:1	28:1
DebrisSat	HD	1:33	2:1	23:1	1:13	1:1	15:1	1:10	1:1	11:1



Average $L:D$ from Different Estimators



- **Notable correlation/consistency between DebrisSat $L:D$ estimates based on V_{bulk} & V_{geom}**
- **SOCIT Geometric values**
 - Plates well matched
 - Except MD_lo
 - Rods seem outlying
 - Few rods (2%) = uncertainty
- **No SOCIT $L:D$ estimates based on bulk volume (unavailable)**

Conclusions & Future Work

- **RCCs are an advantageous shape model**
 - Practical for hypervelocity-impact testing
 - Characterize shapes w one parameter $L:D$
- **RCCs use different $L:D$ estimators for rods, plates, and nuggets**
 - Inspectors' shape designation predestines the scope of population values
 - Suggests that entire shape category might be represented by a sample mean or simple distribution
- **Volume can be leveraged to provide more than one type of $L:D$ estimate for intercomparisons**
 - Geometric (cylindrical) volume depends only on physical dimensions
 - May be an option for SOCIT data without measured (bulk) volume
 - Mass-based volume (m/ρ) least dependent upon dimensional data
 - Likely the best option going forward for impact fragments bent during capture

SOCIT and DebrisSat $L:D$ distributions comparable when CFRP is excluded because CFRP as a material category has exceptional fragmentation behavior