



Overview of the Integrated Adaptive Wing Technology Maturation Wind-tunnel Test Objectives

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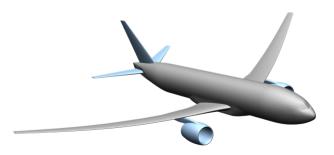


Outline



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- (1) Introduction and Background
- (2) Wind-tunnel Test Article
 - a) Design, modeling, and characterization
- (3) Test Plan
- (4) Questions





IAWTM Overview



- (1) NASA Advanced Air Transport Technology (AATT) project
 - Higher Aspect Ratio Optimal Wing technical challenge: Enable a 1.5-2X increase in the aspect ratio of a lightweight wing with safe flight control and structures
- (2) Approach
 - Cooperative agreement between NASA and Boeing to develop and test control technologies to meet multiple objectives:
 - Drag optimization
 - Maneuver load alleviation
 - Gust load alleviation
 - Flutter suppression
- (3) Purpose
 - Decrease cost of vehicle operation by reducing induced drag and structural weight penalties normally associated with a high-aspect ratio wing





IAWTM Overview, cont.



(4) IAWTM vehicle

- Aspect ratio 13.5 wing of a modern transport configuration based on the Common Research Model (CRM)
- Aspect ratio is a 1.5X increase over the nominal aspect ratio 9 CRM wing
- (5) Analysis and testing
 - Full-scale analysis
 - Evaluation of performance using a high fidelity 6DOF simulation and development of multiobjective control law
 - Model-scale testing
 - Wind tunnel test to be conducted at the NASA Langley Transonic Dynamics Tunnel (TDT)
 - Two phases (open- and closed-loop), each 18 days



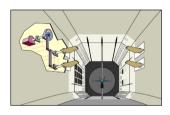


Test Objectives



- (1) Drag optimization at off nominal conditions
 - Drag measured with balance (5-component)
- (2) Maneuver load alleviation
 - Load reduction measured with model strain sensors
- (3) Gust load alleviation
 - Gust excitation provided by TDT airstream oscillation system (AOS)
 - Upstream vane sensor to serve as surrogate LIDAR gust detector for predictive gust load alleviation
- (4) Active flutter suppression
 - Modal suppression important at all operating conditions due to low structural stiffness and damping

TDT AOS

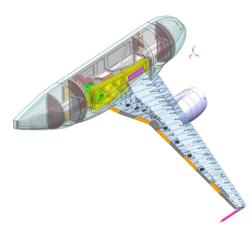




Wind-tunnel Test Article Overview



- Semispan dynamically scaled wing for testing at NASA Transonic Dynamics Tunnel (TDT)
 - Spar-pod construction (aluminum spar, carbon fiber skins) with flow-through engine nacelle and nonmetric fuselage
 - 10 active control surfaces and large number of sensors (accelerometers, strain gages, distributed strain sensors, balance, gust vane sensor)
- Removable tip ballast designed to lower the flutter frequency and dynamic pressure for AFS testing

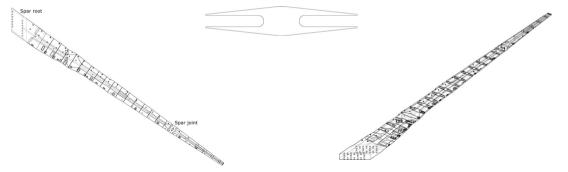




Spar Design



- Equivalent beam model provided target spanwise bending and torsional stiffness distributions
 - Modified I-beam cross section developed to improve stiffness matching and remain inside the wing OML
 - 25 equally distributed spanwise design stations used for stiffness matching, with linear taper between those cross sections
- Due to spar length, fabricated in two pieces and permanently bonded and fastened at spar joint



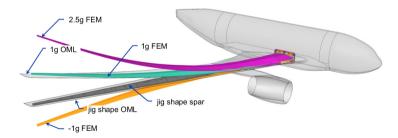


Static Aeroelastic Wing Deformation



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 Equivalent beam deformations (FEM) for several critical flight conditions illustrate representative static aeroelastic deformation of the model

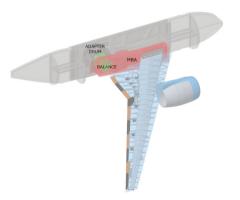




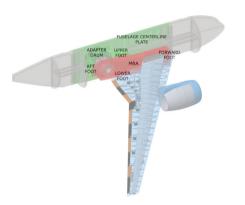
Balance Adapter Design



• To support both aerodynamic performance data acquisition using a balance and dynamic aeroelastic testing, a balance adapter will be used to engage/disengage the balance on the model load path



Shims-off configuration



Shims-on configuration

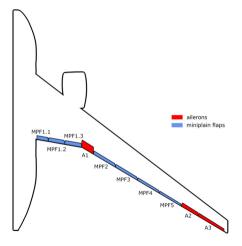


Control Surfaces



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- 10 trailing edge distributed control surfaces
 - 3 hydraulically actuated ailerons (faster response)
 - 7 electric servo-actuated miniplain flaps (slower response)

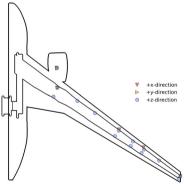




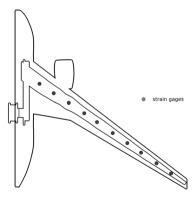
Sensors



Sensors: 3 triaxial and 13 single axis accelerometers, 10 full-bridge strain gages, Q-flex inclinometer,
 8 balance-based loads, gust vane sensor



Accelerometers



Strain gages



Wind-tunnel Test Article Model Preparation Area



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Source: NASA



Pretest Analytical Work



(1) Tools

- FUN3D
- VSPAERO
- MSC Nastran
- Simulink
- ZAERO

(2) Studies

- Gust vane modeling
- Control surface aerodynamic database
- Flutter boundary
- Development of ASE models
- Buffet onset
- Critical Mach number
- Wind tunnel wall interference modeling
- Control surface reversal boundary
- Closed-loop controllers developed by Boeing and NASA



Model Characterization



- (1) Ground vibration test
 - TDT model preparation area, mounted to backstop
 - TDT test section, mounted to tunnel sidewall support
- (2) Measured mass properties database
- (3) Actuator checkout and performance characterization
- (4) Static load testing
 - Strain gage calibration, model validation, digital image correlation checkout



Backstop GVT



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- (1) GVT in TDT MPA of three model configurations
 - Shims-off
 - Shims-on
 - Shims-on, ballast-on
- (2) Several other parameters were varied during testing to assess modal impact
 - Control surfaces taped OR actuators on
 - Skin pods untaped OR taped
 - Shaker OR hammer excitation
- (3) Equipment
 - 3x shakers
 - Impact hammer
 - >100 externally-instrumented accelerometer signals

Source: NASA



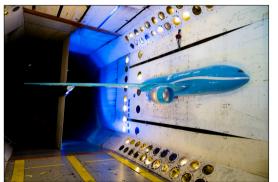


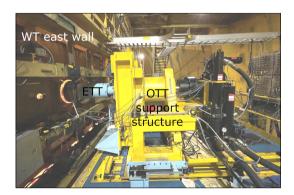
Test Section GVT



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 After MPA GVT, most significant structural uncertainty is associated with test section boundary condition, with the test article mounted to the sidewall support



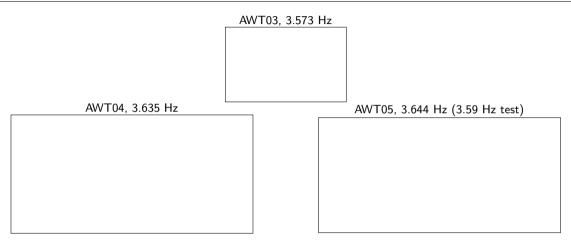


Source: NASA



FEM Normal Modes Comparison Shims-off configuration, first vertical bending



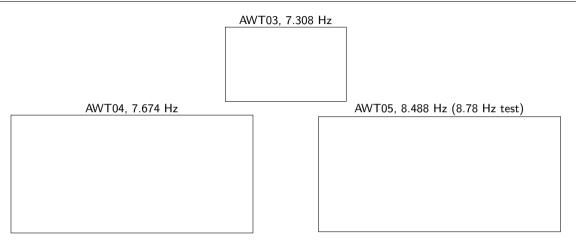


Source: D. Ortega, Boeing, AWT03 ASE State-Space Modeling, AWT04 Modal Correlated FEM Review, and AWT05 GVT2 in TDT Modal Correlation FEM Review



FEM Normal Modes Comparison Shims-off configuration, vehicle pitch





Source: D. Ortega, Boeing, AWT03 ASE State-Space Modeling, AWT04 Modal Correlated FEM Review, and AWT05 GVT2 in TDT Modal Correlation FEM Review

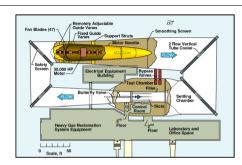


NASA Langley Transonic Dynamics Tunnel



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- TDT is a unique WT facility that contains several features essential for aeroservoelastic testing
 - Configured to perform higher risk aeroelastic testing
 - Direct view of the test article from the control room
 - Bypass valves that can rapidly lower test section dynamic pressure in the case of an instability
 - Downstream safety screen to protect the drive motor and fan blades
 - Hydraulic power supply for the test article available for high speed actuation of control surfaces
 - Airstream oscillation system with upstream gust vanes to provide gust excitation for GLA testing
 - Heavy gas (R134a) test medium to match fluid-structure scaling parameters important to aeroelastic response and flutter

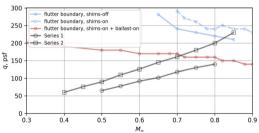




Planned Test Points and Predicted Flutter Boundaries Phase 1



- Phase 1 testing will target open-loop aerodynamic and aeroelastic characterization
 - Each series corresponds to a different initial wind-off pressure
 - At each point, control surface static schedules and dynamic sweeps will be conducted for aerodynamic model verification and updating
 - Data is also planned to be acquired at several test article AOAs and multiple surfaces active for interaction testing
- Flutter mechanism for shims-off and shims-on configurations is a hump mode, and since the as-built model structural damping is quite low, real-time monitoring will be essential





Summary



- IAWTM wind-tunnel test article has been designed to meet test objectives targeting active control techniques for a highly flexible, high aspect ratio, wing
 - Overview of model scaling, structural design, instrumentation, and control systems demonstrates the complexity of the test article
- Significant pretest analysis and characterization work has been completed in preparation for Phase 1 open-loop testing
- Lessons learned and data acquired during the preparation and conduct of the wind tunnel experiment will be directly applicable to improvements in aeroelastic modeling and testing of high aspect ratio, highly flexible wings



Acknowledgments



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Special thanks to IAWTM team members from Boeing Research & Technology, NextGen Aeronautics, NASA Langley Research Center, NASA Ames Research Center, and NASA Armstrong Flight Research Center









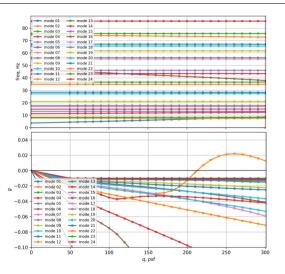
Questions?



Example Pretest Flutter Analysis, $M_{\infty}=0.85$ Shims-off configuration



- Hump flutter mechanism occurs at $q_{\infty} \approx 212$ psf with a flutter frequency of $f \approx 7.35~{\rm Hz}$

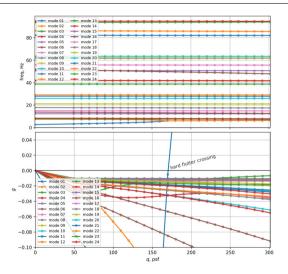




Example Pretest Flutter Analysis, $M_{\infty}=0.70$ Shims-on, ballast-on configuration



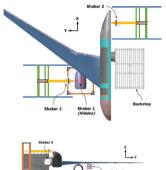
- Hard flutter mechanism occurs at $q_\infty\approx 170$ psf with a flutter frequency of $f\approx 6.01~{\rm Hz}$

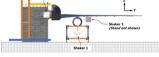










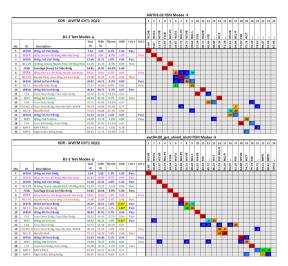




Backstop Model Modes Pre- and Post-FEM Scrub Shims-off configuration



- Pre- and post-FEM scrub tables summarizing frequency error and cross-orthogonality between FEM and test modes
 - Scrub led to significant improvements in XOR and frequency matching
- Planned configuration for drag optimization testing

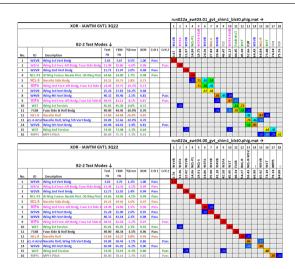




Backstop Model Modes Pre- and Post-FEM Scrub Shims-on configuration



Planned configuration for MLA and GLA testing

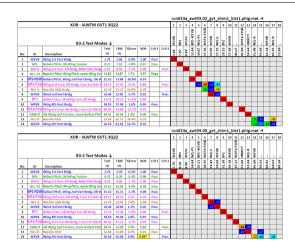




Backstop Model Modes Pre- and Post-FEM Scrub Shims-on, ballast-on configuration



Planned configuration for flutter suppression testing





Test Section Model Modes, Configurations 1 and 2 Backstop GVT-calibrated model



Shim Off (B1)		Shim On (B2)				
No.	Freq	No.	Freq	ID	Description	
1	3.63	1	3.65	W1VB	Wing 1st Vert Bndg	
2	7.67	2	7.92	VP	Vehicle Pitch	
3	8.28	3	8.45	W1FA	Wing 1st Fore-Aft Bndg, Vehicle 1st Fore-Aft Bndg	
4	11.20	4	11.25	W2VB	Wing 2nd Vert Bndg	
5	13.11			F1SB	Fuse 1st Side Bndg, Wing 1st Fore-Aft Bndg	
6	14.80	5	14.93	NCL-P1	IB Wing Torsion, Nacelle Pitch, Wind 2nd Vert Bndg IP	
7	16.85	7	17.12	NCL-P2	IB Wing Torsion, Nacelle Pitch, Wind 2nd Vert Bndg OOP	
8	17.80	6	15.19	W2FA	Wing 2nd Fore-Aft Bndg	
9	21.07	8	21.14	NCL-S1	Nacelle Side Bndg	
10	27.16	9	27.69	W3VB	Wing 3rd Vert Bndg	
11	28.45	10	28.72	ETT-AX	ETT Struct Axial, Nacelle Side Bndg	
12	34.87			F1RB	Fuse Roll Bndg, MBA Pitch, W2FA	
13	36.61	11	36.53	W3FA1	Wing 3rd Fore-Aft Bndg, Fuse Side Bndg OOP	
		12	43.12	W3FA2	Wing 3rd Fore-Aft Bndg, Fuse Side Bndg IP	
14	43.08	13	43.95	W4VB	Wing 4th Vert Bndg	
15	45.73			W3FA-W1T	Wing 3rd Fore-Aft Bndg, Wing 1st Torsion	
16	46.44	14	46.35	W1T	Wing 1st Torsion	
17	55.17	15	55.45	NCL-R1	Nacelle Roll, W3FA In-Phase (IP)	
		16	57.20	F2SB	Fuse 2nd Side Bndg, W3FA	
18	56.24			NCL-R2	Nacelle Roll, W3FA Out-of-Phase (OOP)	
19	61.67	17	61.80	FD1	Fuse Main Door Bndg	
20	65.55	18	65.27	W5VB	Wing 5th Vert Bndg	
21	67.08			W5VB-F1RB	Wing 5th Vert Bndg, Fuse Roll Bndg	
22	74.60	19	74.56	W2T	Wing 2nd Torsion	
23	75.65			ETT-FA	ETT Struct Fore-Aft Bndg	
24	85.68	20	80.03	W4FA	Wing 4th Fore-Aft Bndg	
		21	91.20	W4FA-F1RB	Fuse Roll Bndg, W4FA	
		22	95.32	W6VB	Wing 6th Vert Bndg	
		23	98.93	MPF3P	MPF3 Pitch	
		24	99.65	MPF3P-F1RB	MPF3 Pitch, Fuse Roll Bndg	



FEM Normal Modes Comparison Shims-off configuration, first fore-aft bending



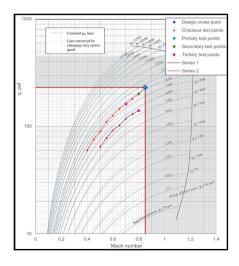
	AWT03, 7.730 Hz				
AWT04, 8.276 Hz		AWT05, 8.059 Hz (7.89 Hz test)			

Source: D. Ortega, Boeing, AWT03 ASE State-Space Modeling, AWT04 Modal Correlated FEM Review, and AWT05 GVT2 in TDT Modal Correlation FEM Review



Planned Wind-tunnel Test Conditions



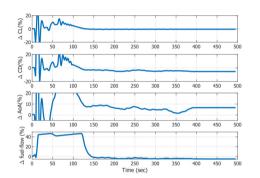


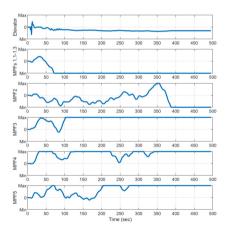


Simulated Full-Scale Fuel Burn Minimization Controller



• $M_{\infty} = 0.85$, $q_{\infty} = 230$ psf



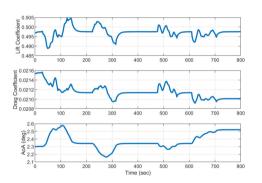


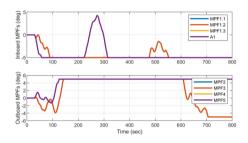


Simulated Model-Scale Drag Minimization Controller



• $M_{\infty}=0.85,\ q_{\infty}=230$ psf for shims-off configuration







Simulated Model-Scale Gust Load Alleviation Controller



• $M_{\infty}=0.70,\ q_{\infty}=190$ psf for shims-on configuration

