



# LaRC Shape Memory Polymer Composite for Aerospace Applications

Jin Ho Kang<sup>1\*</sup>, Keith L. Gordon<sup>1</sup>, Emilie J. Siochi<sup>1</sup>, Travis L. Turner<sup>2</sup>, Sheila A. Thibeault<sup>1</sup>, Jeffrey A. Hinkley<sup>3</sup>, Juan M. Fernandez<sup>4</sup>, Andrew F. Paddock<sup>5</sup>, Joshua E. Salazar<sup>4</sup> and Olive Stohlman<sup>4</sup>

<sup>1</sup>Advanced Materials and Processing Branch, NASA Langley Research Center, Hampton, VA 23681

<sup>2</sup>Structural Acoustics Branch, NASA Langley Research Center, Hampton, VA 23681

<sup>3</sup>Distinguished Research Associate, NASA Langley Research Center, Hampton, VA 23681

<sup>4</sup>Structural Dynamics Branch, NASA Langley Research Center, Hampton, VA 23681

<sup>5</sup>Mechanical Systems Branch, NASA Langley Research Center, Hampton, VA 23681

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\*Specific vendor and manufacturer names are used only to accurately describe the test hardware or software. The use of vendor and manufacturer names does not constitute an official endorsement, either expressed or implied, by the National Aeronautics and Space Administration nor does it imply that the specified equipment or software is the best available.



\*Corresponding author: jin.h.kang@nasa.gov

\*All Image Credit: NASA



# Outline

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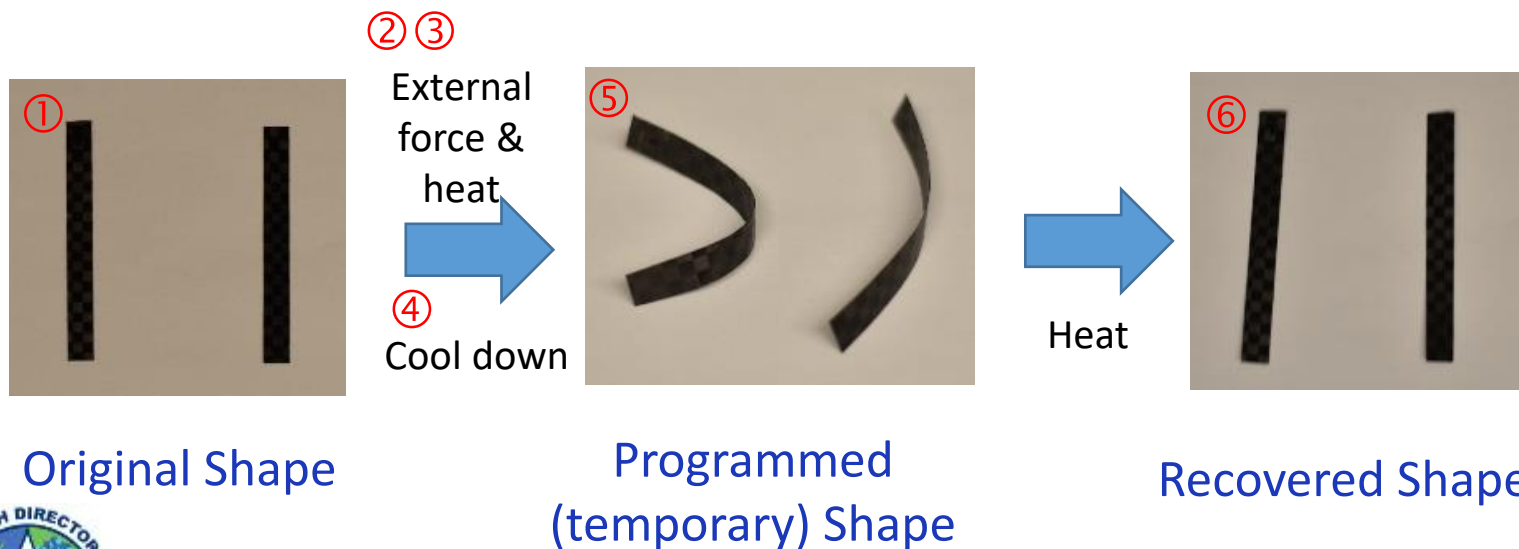
1. Introduction : LaRC Shape Memory Polymers
2. Application 1 : Adaptive Air Foil System
3. Application 2 : Origami-Based Deployable Structure
4. Application 3 : Deployable Reflector Antenna
5. Summary and Future Work



# Introduction

## Shape Memory Polymer (SMP)?

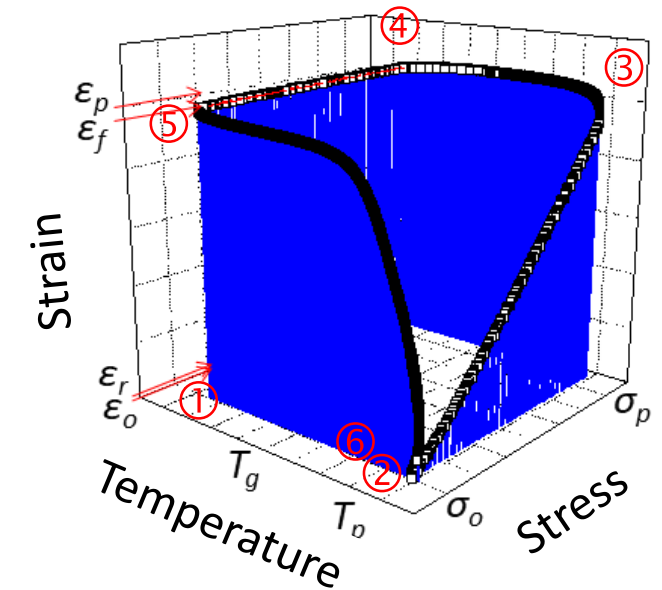
- Smart material that has the ability to return from a programmed (temporary) shape to its original (permanent) shape when induced by an external stimulus, such as temperature change and electric field



Original Shape

Programmed  
(temporary) Shape

Recovered Shape



Demonstration of shape recovery of LSMPC



# Introduction

## Applications of SMPs

- Morphing structures and packaging
- Self-deploying space structures
- Intelligent medical devices
- Smart fabrics, etc.

## Advantages and Disadvantages of SMPs

- SMP Advantages
  - Lightweight
  - Tailorable
  - Conformable
- SMP Disadvantages
  - Low recovery stress
  - Slow response time
  - Complicated process



***Series of LaRC SMPs:  
Carbonaceous Nanoinclusion, Fiber Reinforcement + Thermosetting SMP***

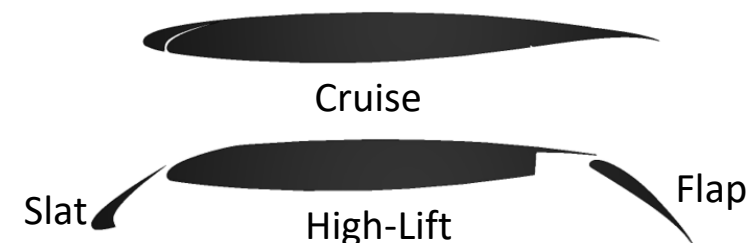


# Application 1 : Adaptive Airfoil System

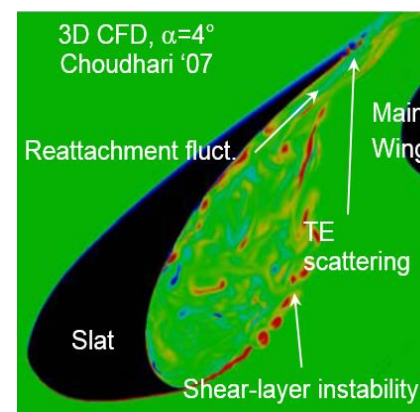
## Motivation

- Slat, leading edge high lift system deploys away from the main wing in the high-lift configuration
- Geometric discontinuities of edge, gap and cavity cause considerable unsteadiness to generate significant acoustic noise
- Slat cove filler (SCF) reduces the unsteady aerodynamics
- SCF should sustain the aerodynamic load when deployed and remain hidden between the slat and the main wing when stowed for cruise
- Additionally, requires weight-efficiency, passivity (no requirement for auxiliary support systems), durability and fail-safety
- New SMP composite (SMPC) with large stiffness change for the SCF application

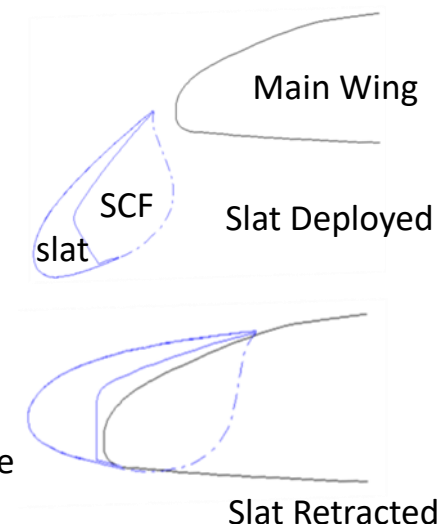
\*Project PI: Dr. Mia Siochi



Schematic of a three-element airfoil system in the retracted (cruise) and deployed (high-lift) configurations [1]



Flow vorticity in the vicinity of the deployed, leading-edge slat [1]

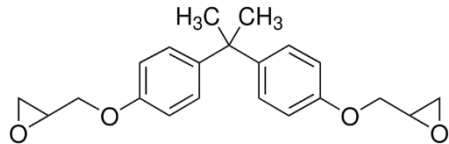


# Materials

## 1. Preparation of homogeneous nanocomposite

- Dispersion interaction
- Donor-Acceptor interaction
- In-situ polymerization under sonication and shear

## 2. Matrix: Epoxy-based shape memory polymer (LaRC-SMP)



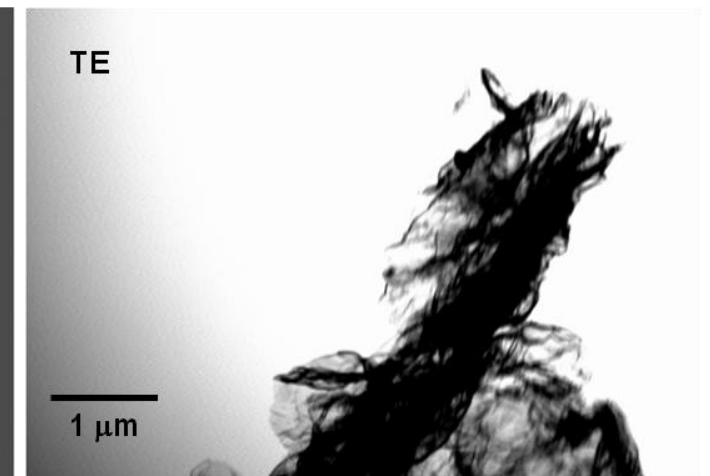
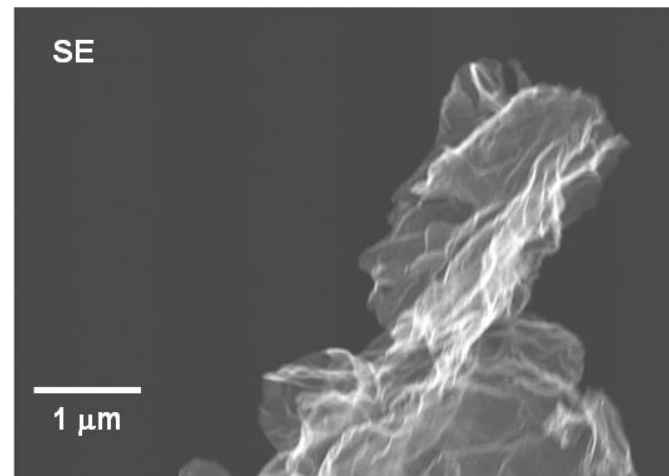
Diglycidyl ether of bisphenol A (DEGBA)

Triglycidyl Ether of p-Aminophenol

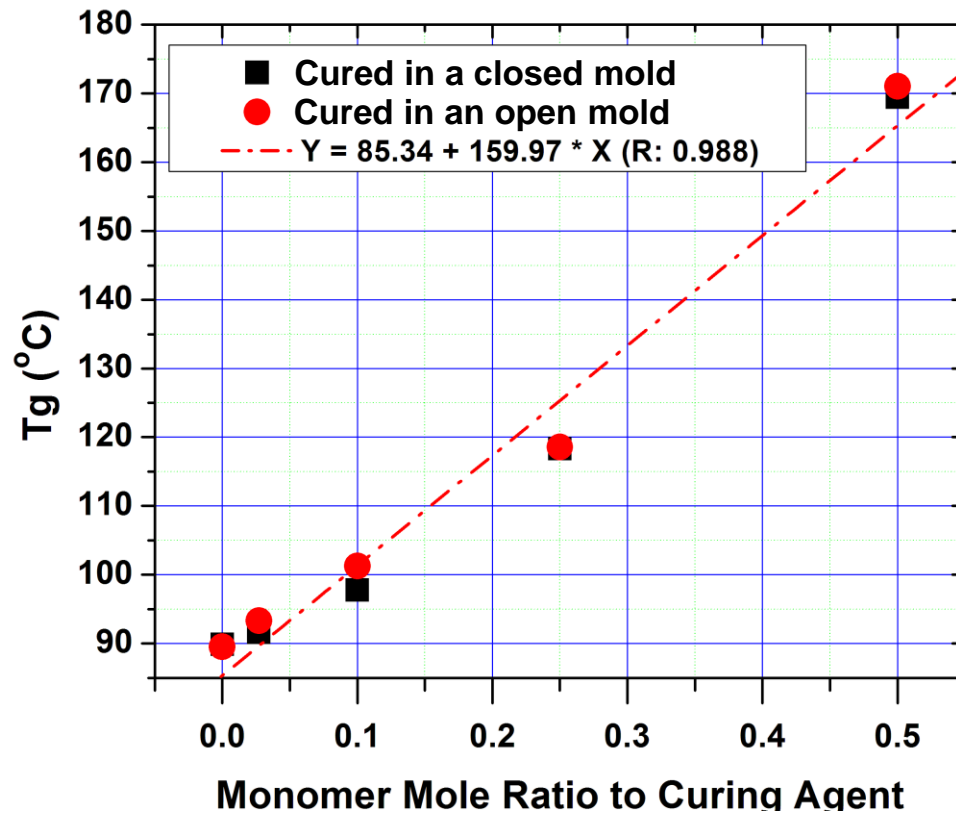
4,4'-Methylenebis[N,N-bis(2,3-epoxypropyl)aniline]

**3. Inclusion:** Reduced graphene oxide (RGO), carbon nanotube (CNT), iron oxides

**4. Reinforcing Fabric:** Kevlar<sup>®</sup>, carbon fiber (CF), carbon nanotube sheet (CNS)



# Tailoring Properties - 1 : Glass Transition Temperature



Monomer of matrix resin  
→ DGEBA (x) based

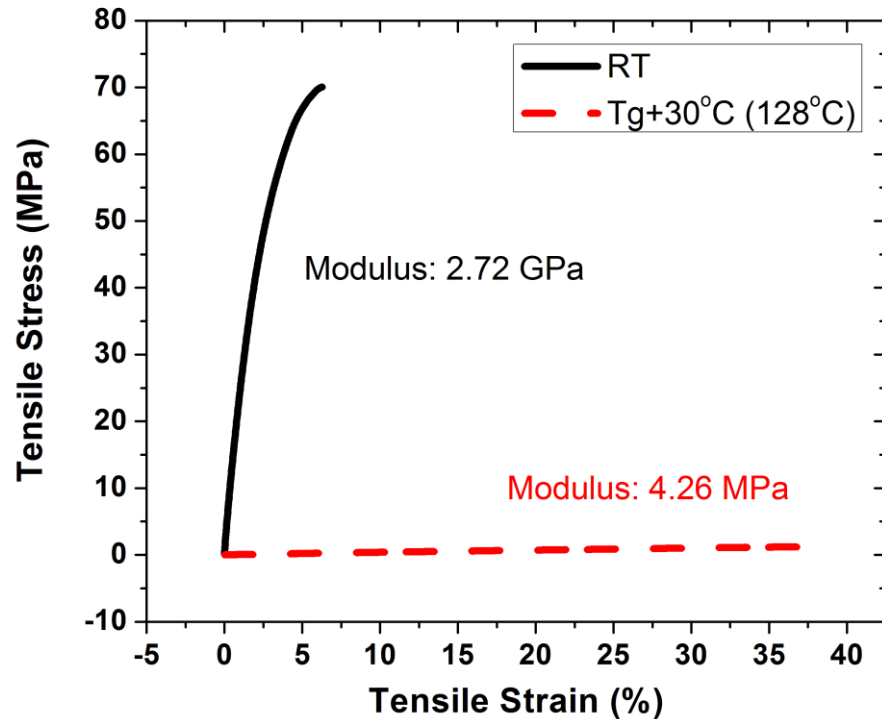
*Tailoring Tg:  
from 90°C to 150°C*



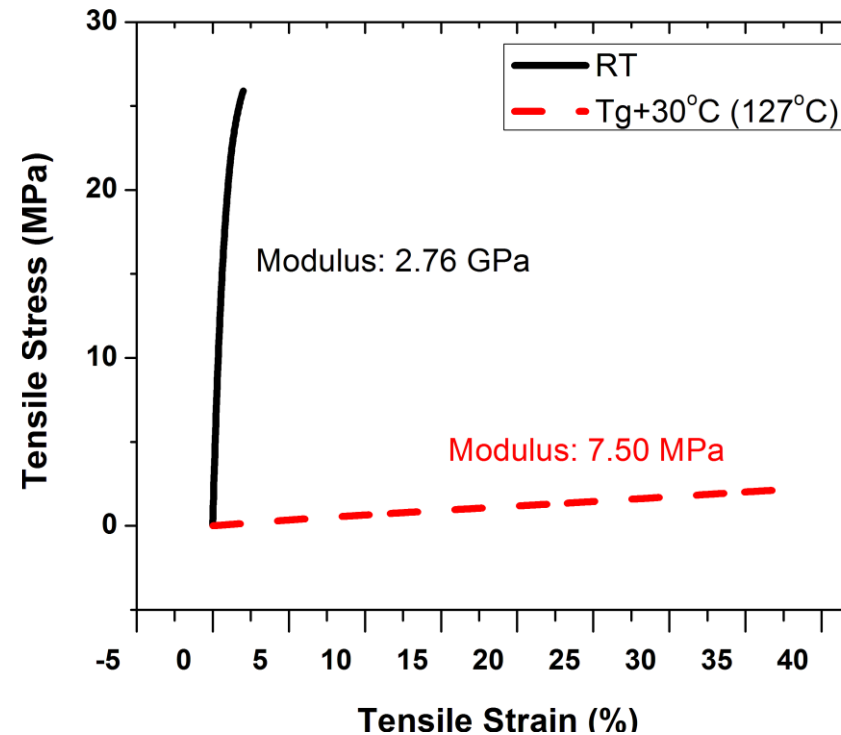
• DSC heating rate of 10 °C/min

# Tailoring Properties - 2 : Mechanical Properties

Pristine LaRC SMP



LaRC SMPC\*



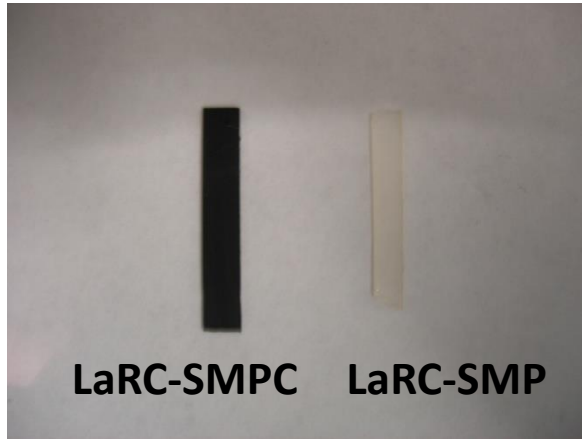
LaRC-SMP has elastic property with large elongation above glass transition temperature

- Strain rate of 10%/min

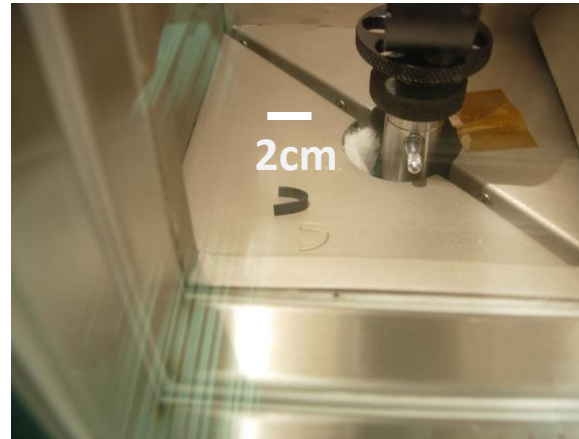
\*SMPC: Shape Memory Polymer Composite



# Thermally Activated Shape Memory Effect (SME)



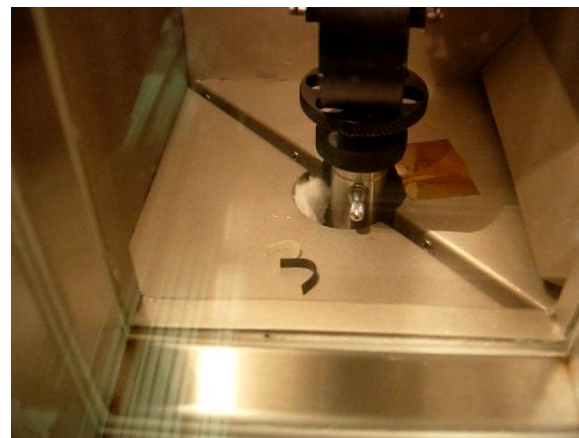
Permanent Shape,  $T < T_g$



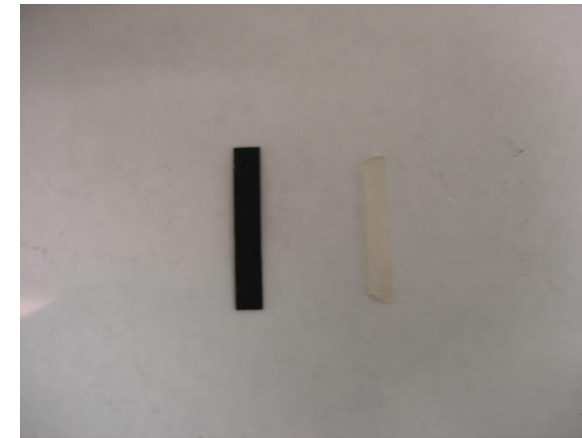
Programming (Deformation),  $T > T_g$



Temporary Shape,  $T < T_g$

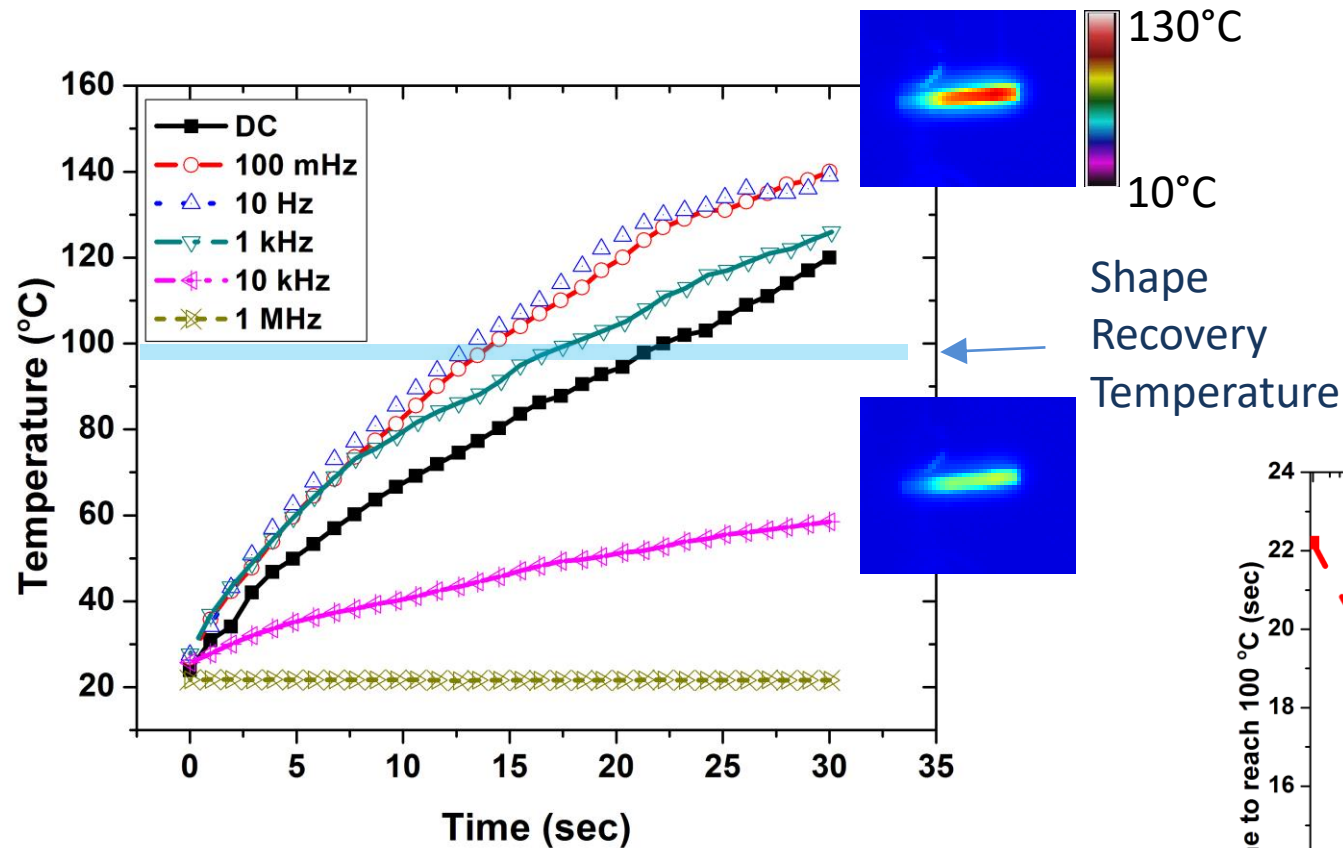


Shape Recovery,  $T > T_g$

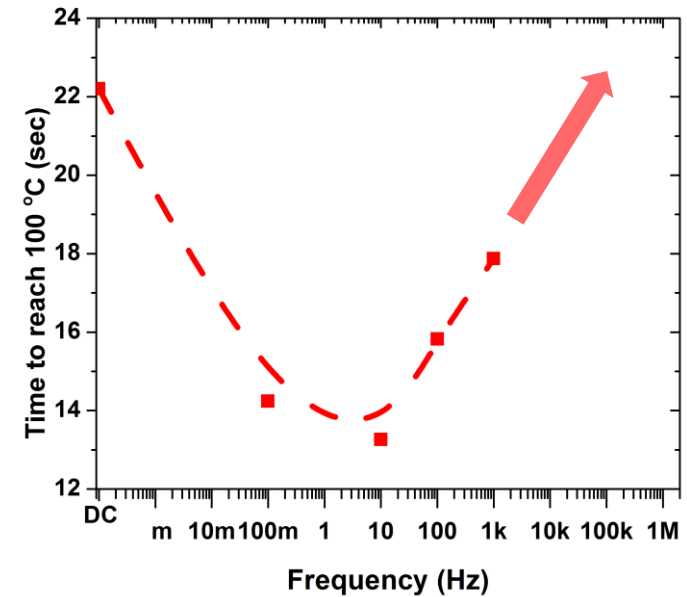


Recovered Permanent Shape,  $T < T_g$

# Tailoring Response Time – 1 : AC Electric Field

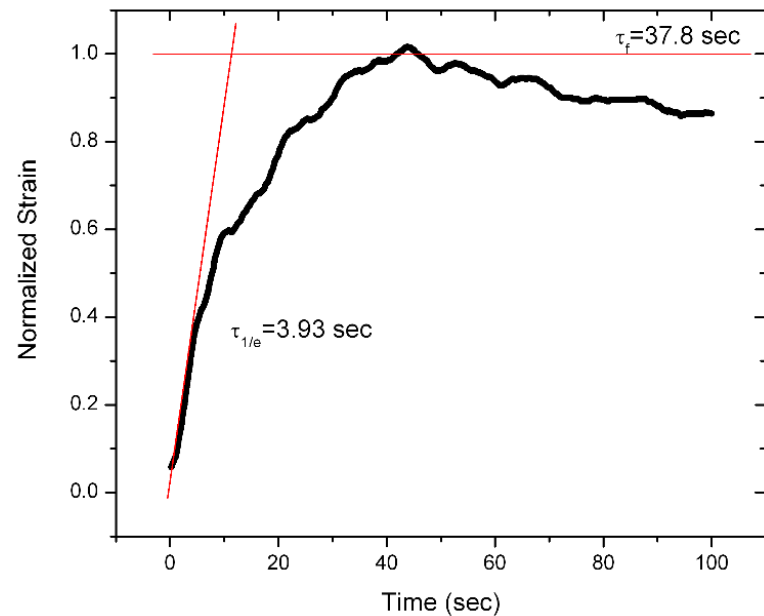


Response time:  
22 sec (DC) → 13 sec (10 Hz)

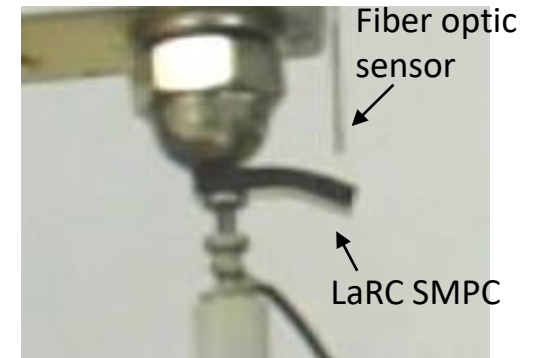
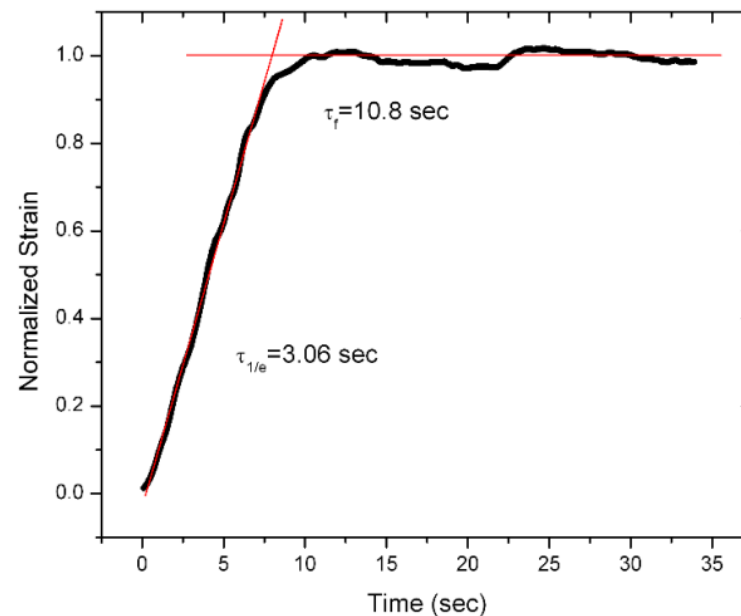


# Tailoring Response Time – 2 : Metal Electrodes

Conventional metal (Au/Cr) electrode  
LaRC SMPC

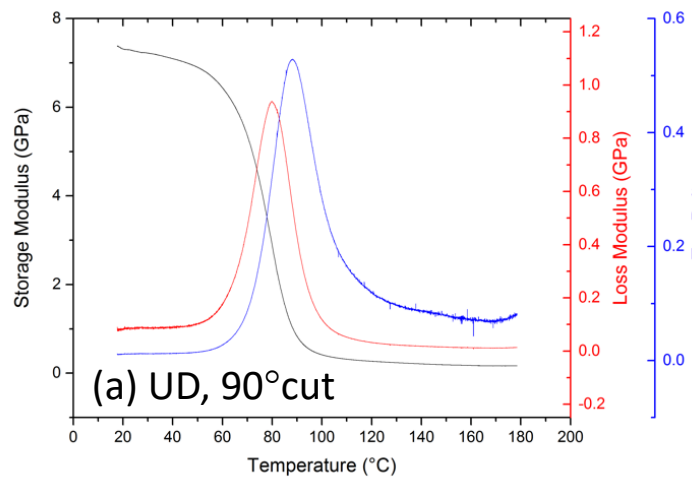
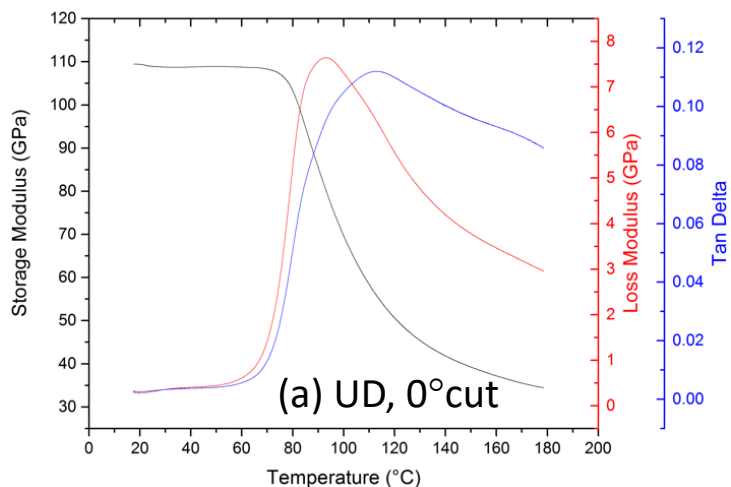


Elastic titanium sheet laminated  
LaRC SMPC

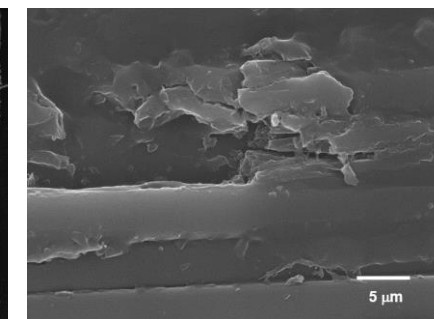
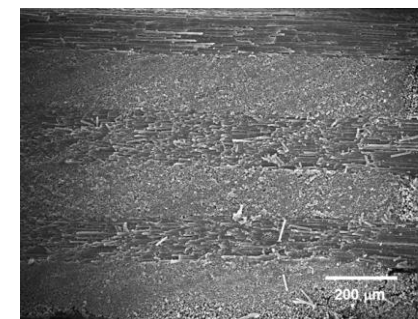
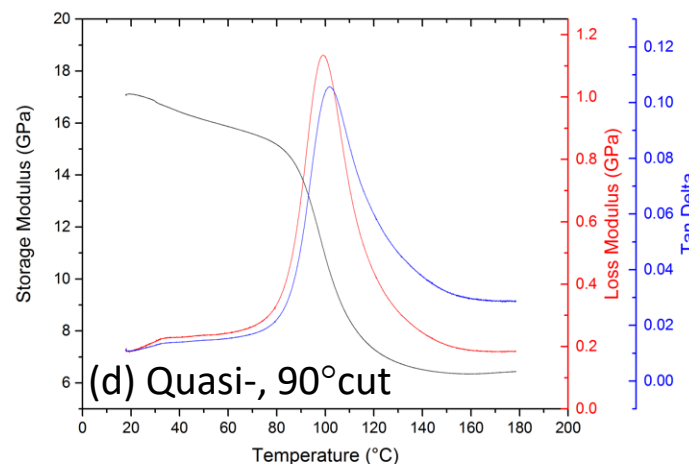
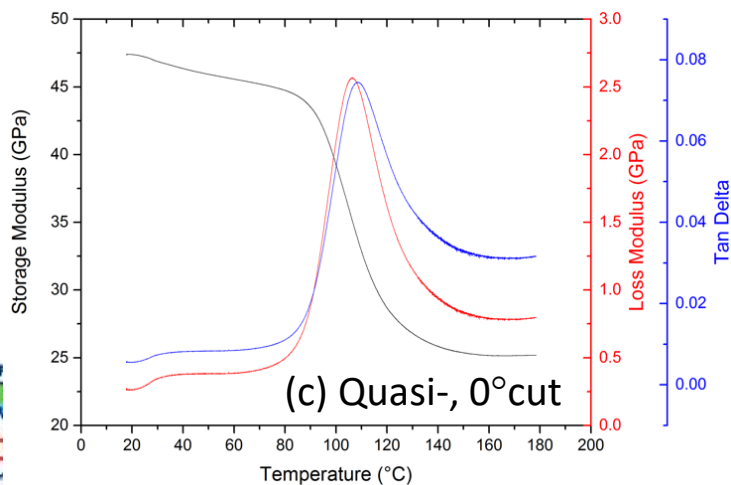
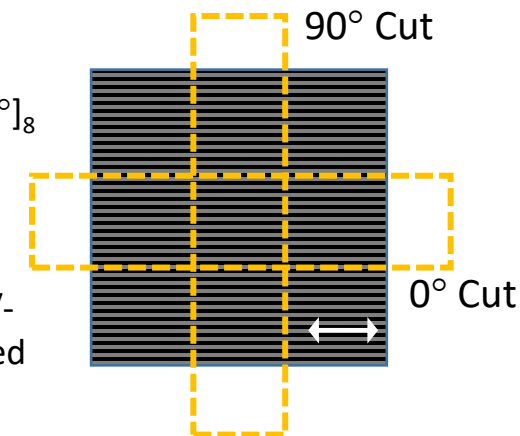


The final recovery time ( $\tau_f$ ) of the LaRC SMPC laminated with the elastic titanium alloy sheet was about 10.8 sec, over 3 times faster than that of unlaminated LaRC-SMPC (37.8 sec)

# Tailoring Dynamic Mechanical Properties 1 : Carbon Fiber



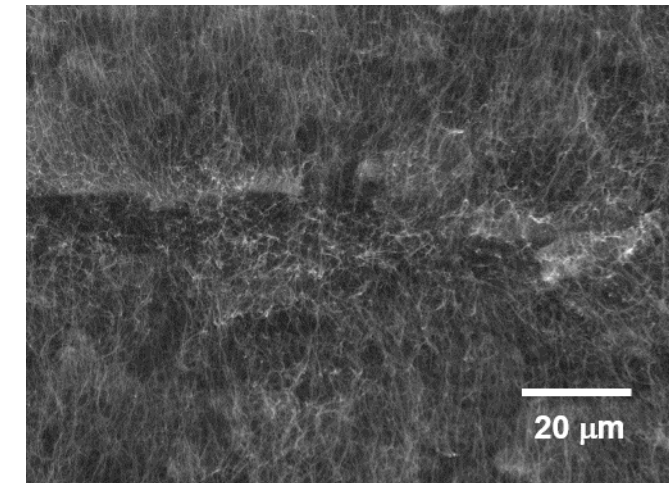
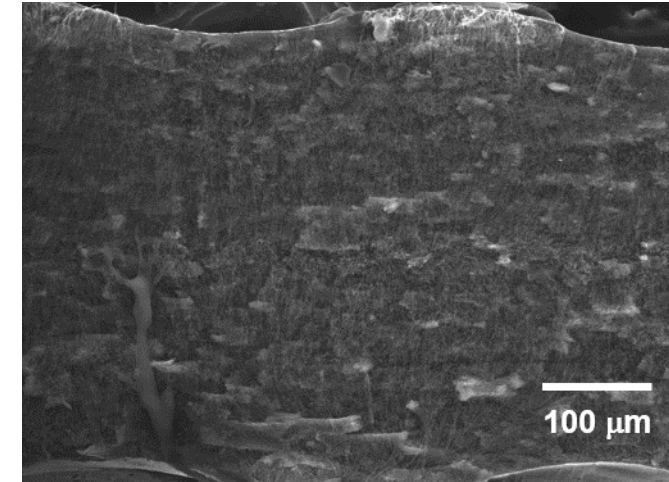
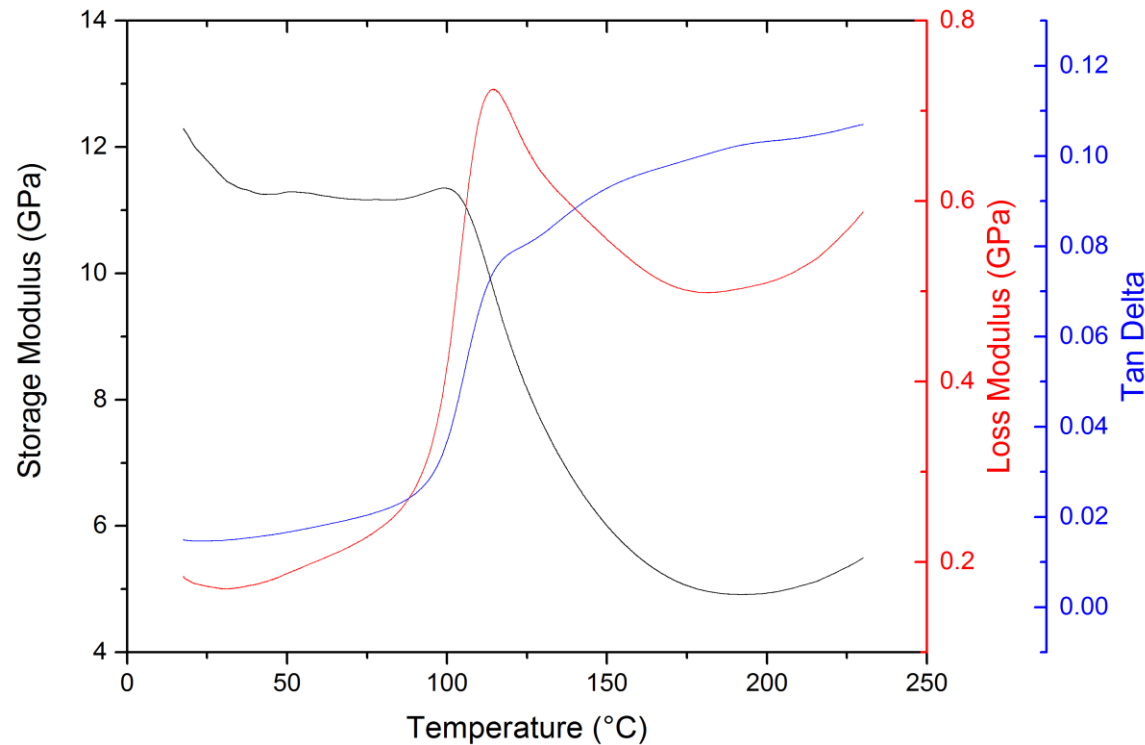
(a-b) CF uni-directional (UD),  $[0^\circ]_8$  reinforced SMP composite,  
 (c-d) CF quasi-isotropic,  $[+45^\circ/0^\circ/-45^\circ/90^\circ]_{2s}$  reinforced SMP composite



Cross-sectional SEM images of CF fabric reinforced SMPC

CF reinforced SMPC has high elastic modulus of about 50 ~ 110 GPa

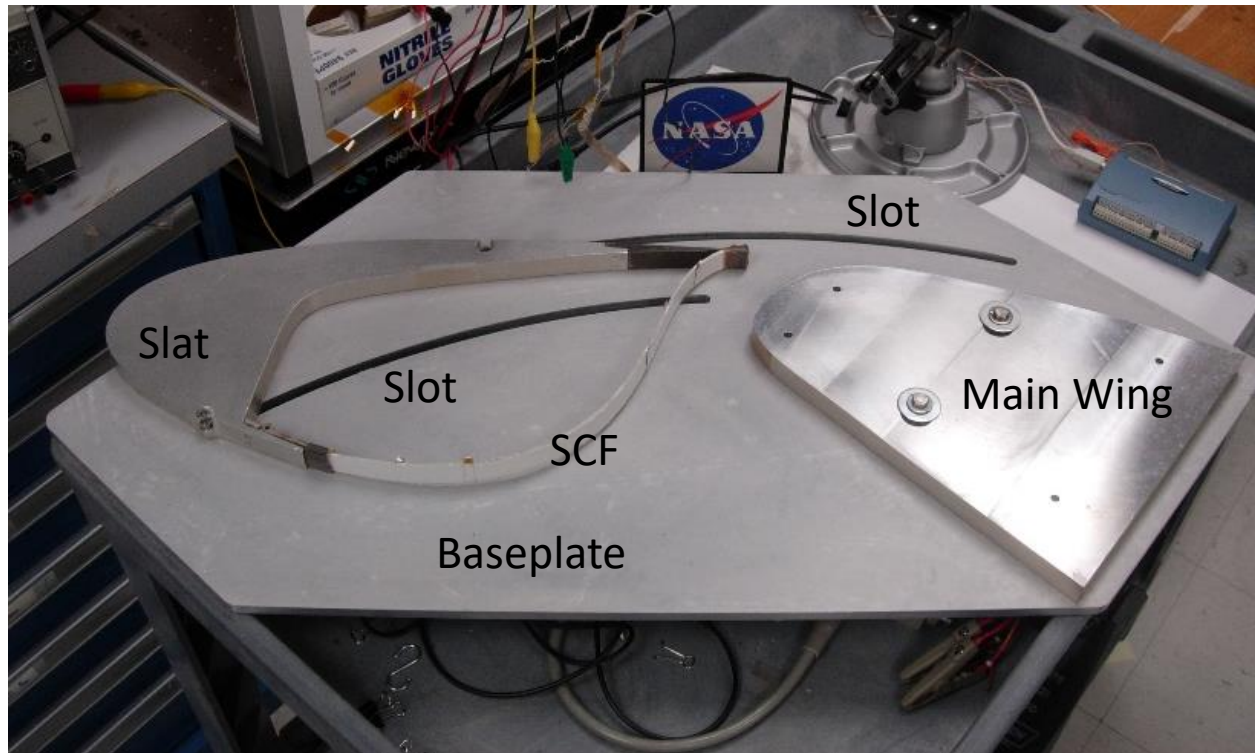
# Tailoring Dynamic Mechanical Properties 2 : CNS



Cross-sectional SEM images of CNS reinforced SMPC

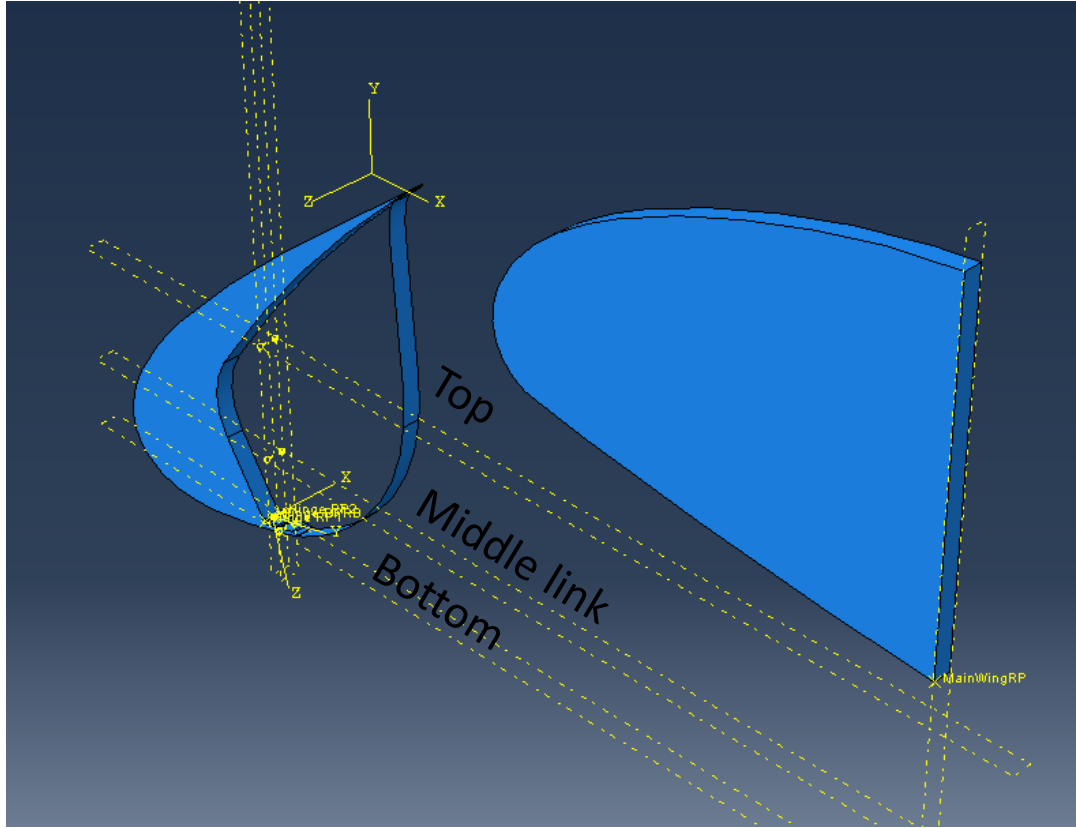
Carbon Nanotube Sheet (CNS) reinforced SMPC has lower elastic modulus than CF reinforced SMPC

# Bench-Top Demonstration Model



A bench-top test apparatus, based on the 30P30N airfoil, was developed at 75% scale to assess the operational viability of the LaRC SMPC based slat-cove filler (SCF) prototypes

# Designing SCF Conformation by Computational Modeling

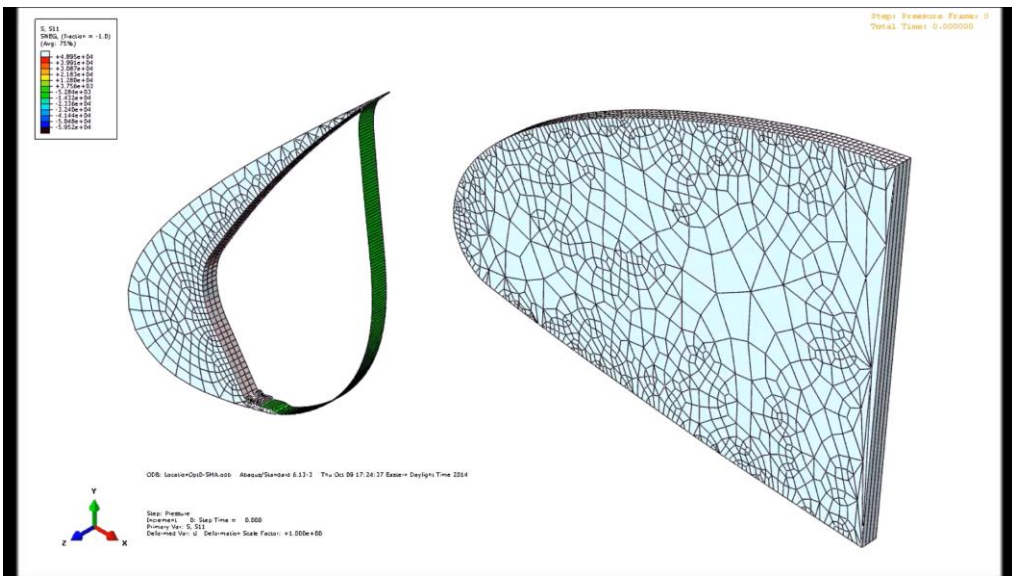


Using the Abaqus finite element analysis program, SCF dimensions and the segmented (top, mid-link and bottom section) configuration from previous work, the design of the SCF incorporating the SMP material was studied



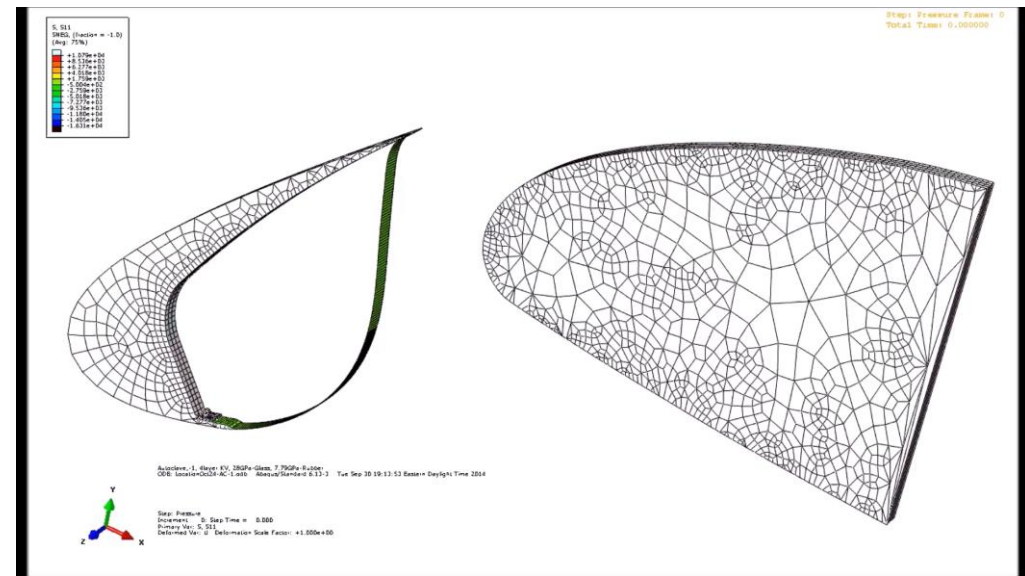
# Designing SCF Conformation by Computational Modeling

Computation modeling of SMP SCF actuation shows unsuccessful deployment with no mid-link



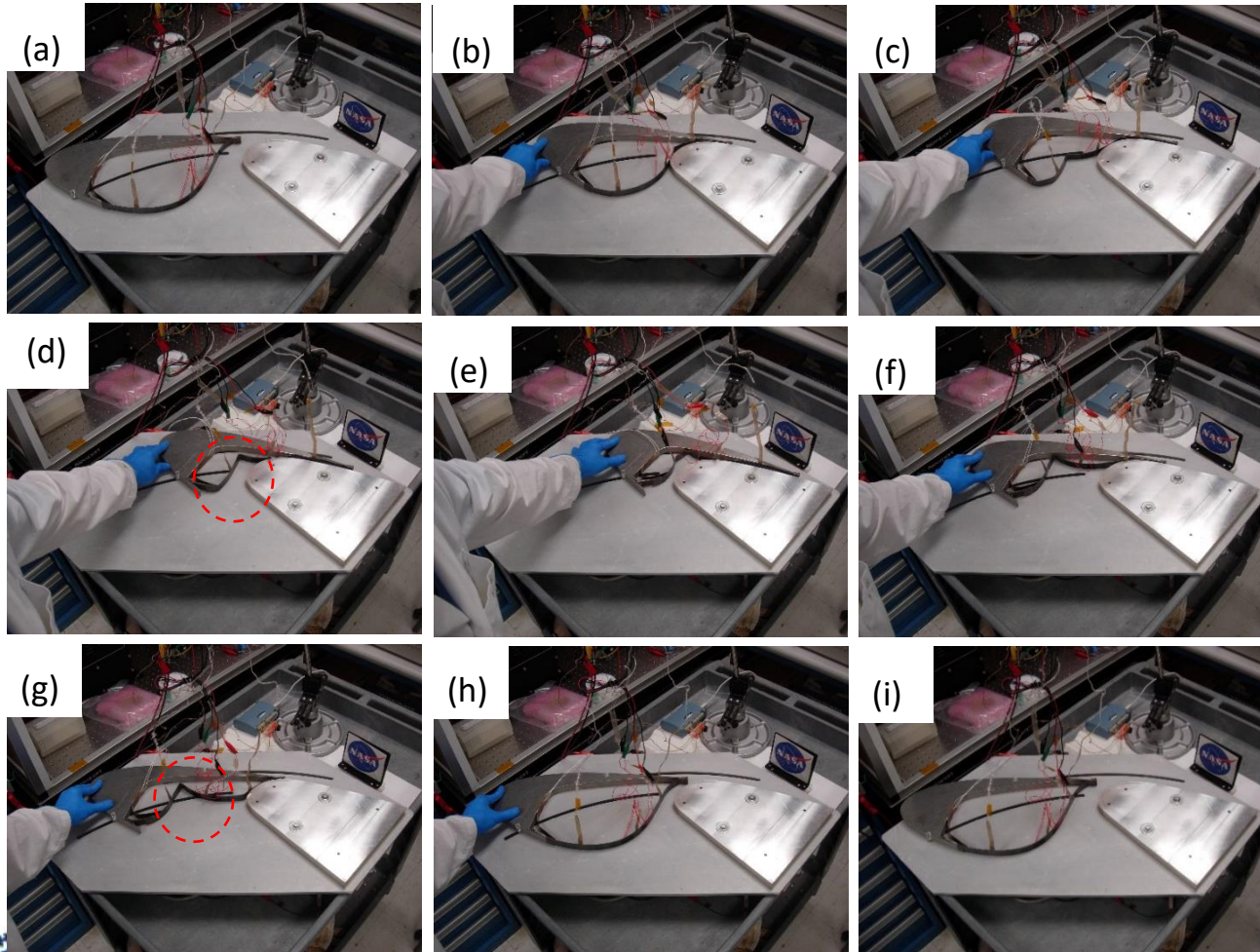
No mid-link →  
Deployment failed

Computation modeling of SMP SCF actuation shows successful deployment with a mid-link

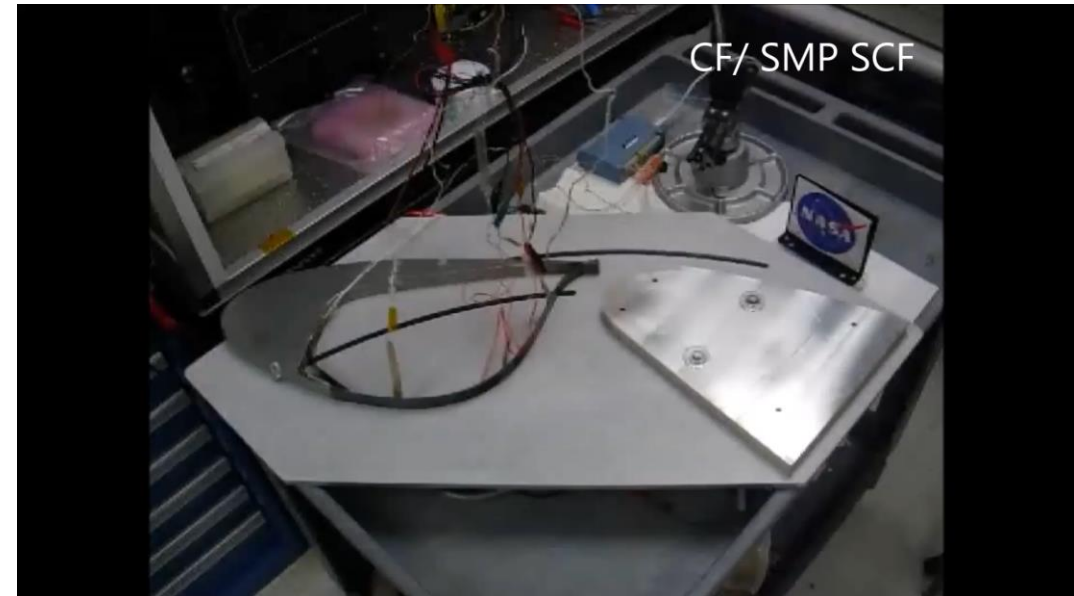


A mid-link (Length: 3", mean location from bottom: 6.5")  
→ Successful deployment

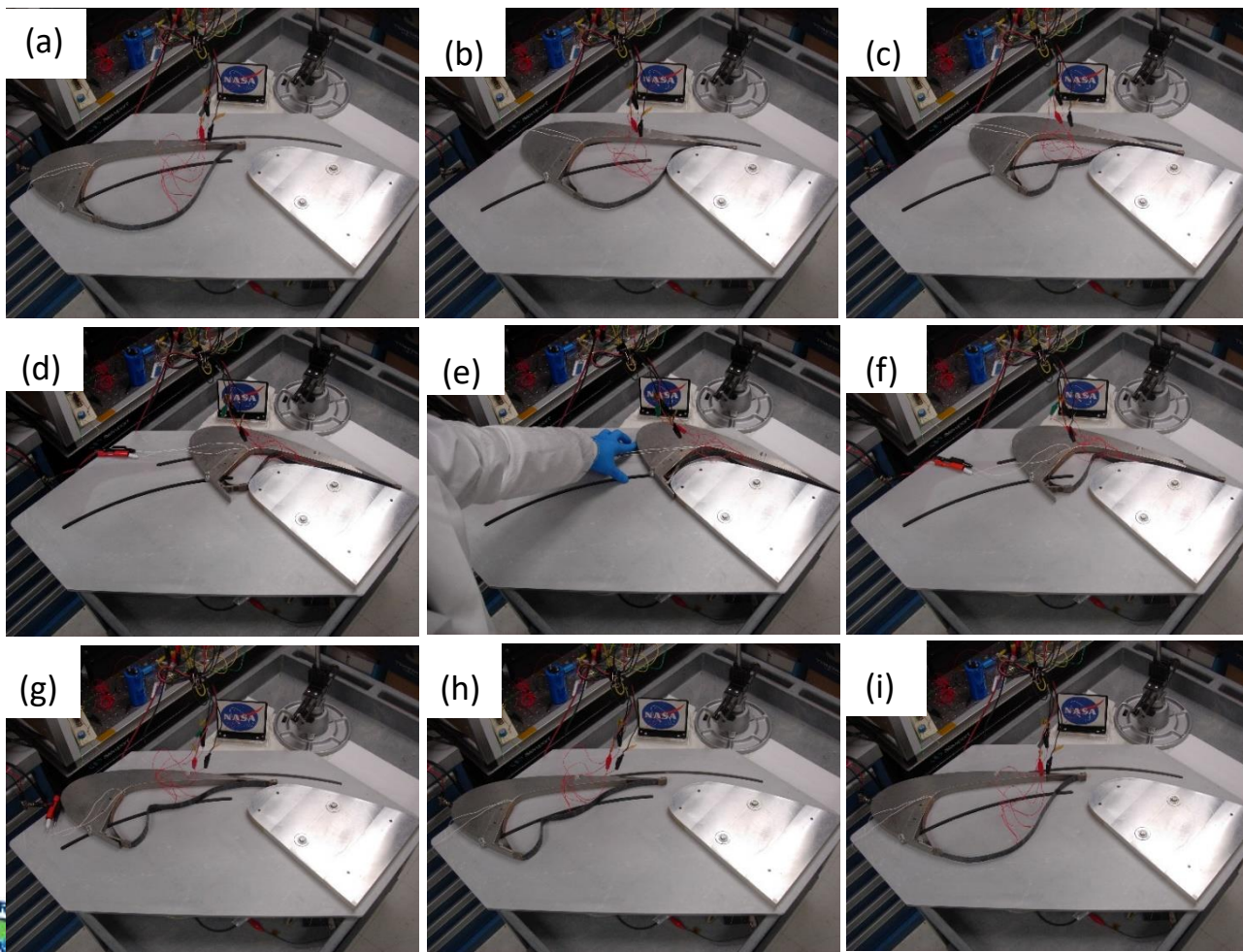
# Bench-Top Demonstration of SCF Fabricated with SMPC-1



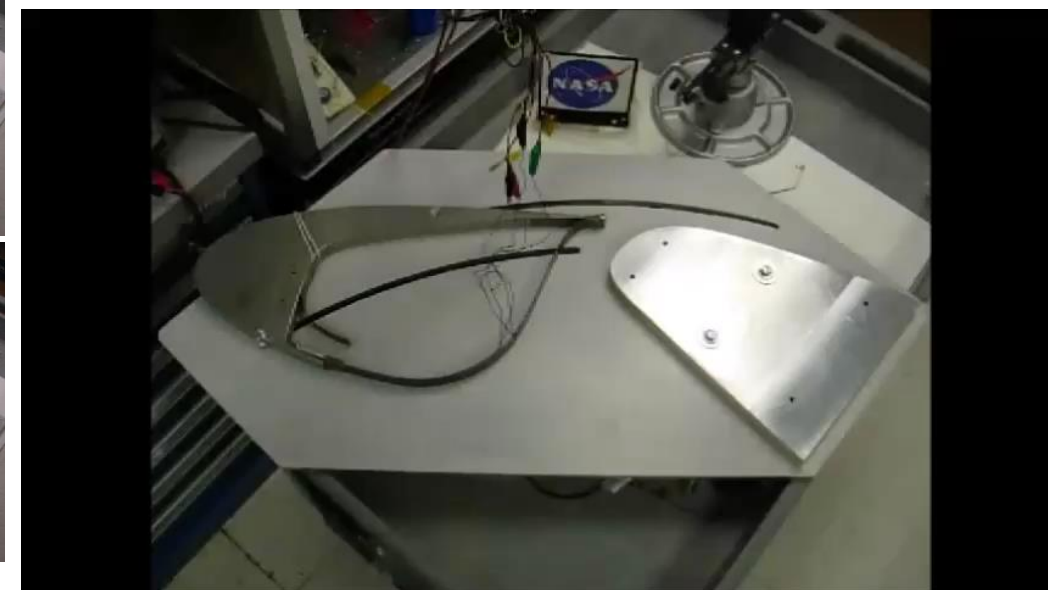
Bench-top demonstration of SCF fabricated with CF/SMPC. (a) before retraction, (b-h) full process of stowage and deployment, and (i) yielding no permanent damage after runs. However, there were kinks in bending



# Bench-Top Demonstration of SCF Fabricated with SMPC-2



Bench-top demonstration of SCF fabricated with Carbon nanotube sheet (CNS)/SMPC. (a) before retraction, (b-i) full process of stowage and deployment with no damage and no kink. However, deployment was sluggish





# Lessons from Adaptive Airfoil System Application

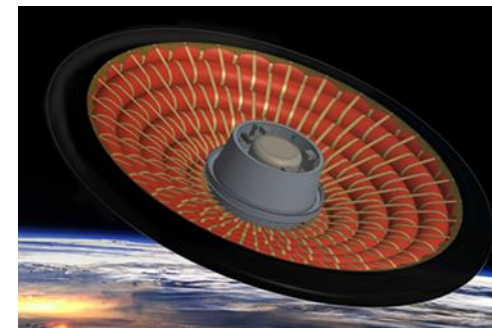
1. A new series of shape memory polymer composites (LaRC SMPC) fabricated with elastic layers and different fibers [Kevlar<sup>®</sup>, carbon fiber (regular and thin ply), carbon nanotubes sheet] was developed for adaptive airfoil system application to reduce aircraft noise.
2. The performance of slat-cove filler prototypes fabricated using various LaRC SMPC compositions was investigated with a bench-top apparatus that was representative of modern transport-class airframe geometry.
3. The SCFs made of Kevlar<sup>®</sup> fiber fabric or CF fabric infused SMPC kinked in simulated operation, which can be a critical mechanical problem for this application. The SCF made of CNS/SMP composite can be autonomously deployed and stowed without kinking, but deployment was sluggish compared to the CF/SMP composite.
4. A balance of strain capability, redeployment speed and steady aero-load sustainment remained elusive in this study. Among the lessons learned in this materials development effort is the need to assess material properties in simulated use conditions. In this case, investigation of the SCF fabricated with LaRC SMPC under simulated aerodynamic load exposed shortcomings in the material that would not have otherwise been noted.



# Application 2 : Origami-Based Deployable Structure

## Motivation

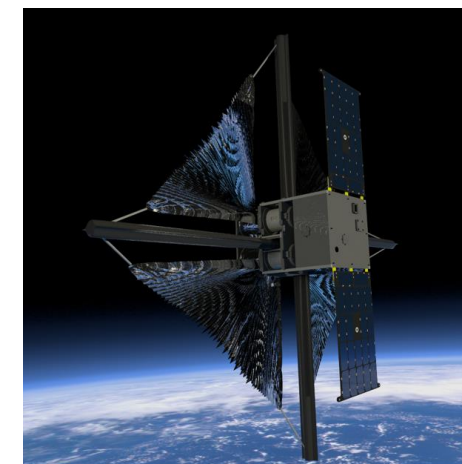
- Due to the confined volume of standardized launch vehicle cargos, large space structures are needed to be packed in a small volume and footprint before launch and are deployed or inflated into required geometry at the mission location.
- Inflatable structures need a continuous gas supplement to replace slow leakage of gas used for inflation or temperature adjustments to maintain required inflation pressure. High kinetic energy micrometeoroids can cause a catastrophic failure.
- Deployable composite tubular boom is an excellent lightweight system to hold relatively low mass payloads such as solar sails or solar arrays. However, its buckling load is not sufficient for load bearing structures like surface habitats.
- New origami-based SMP composite (SMPC) was developed for deployable load bearing structures.



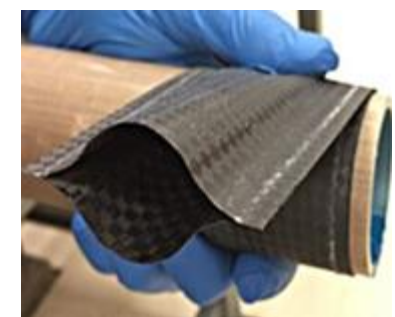
Low-Earth Orbit Flight Test of an Inflatable Decelerator (LOFTID)



Inflatable habitat



Deployment of solar sail membranes and composite booms



Collapsible tubular mast boom rolled up for storage



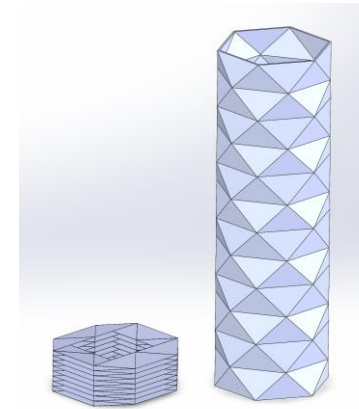
\*Project PI: Drs. Keith Gordon/Jin Ho Kang

# Potential Applications

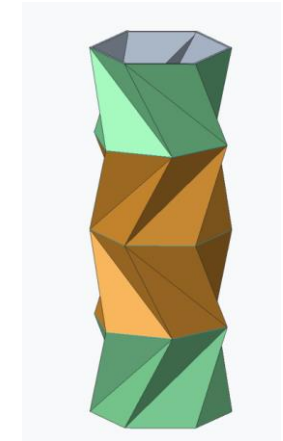
## Origami Patterns

*“Ori” meaning to fold and “Kami” meaning paper in Japanese*

- Miura-Ori pattern, Square twist pattern, Radial Flash Pattern, Tachi-Miura Polyhedron Pattern, Yoshimura Pattern, Kresling Pattern



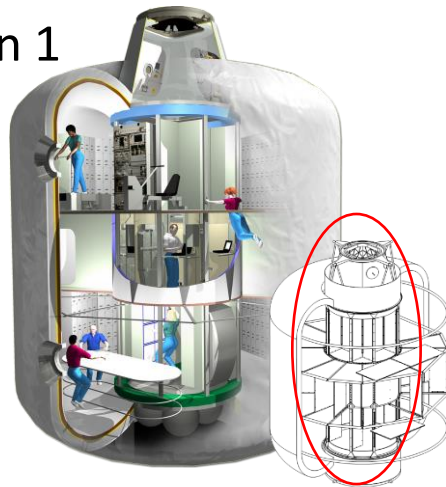
Yoshimura



Kresling

## Potential Target Applications

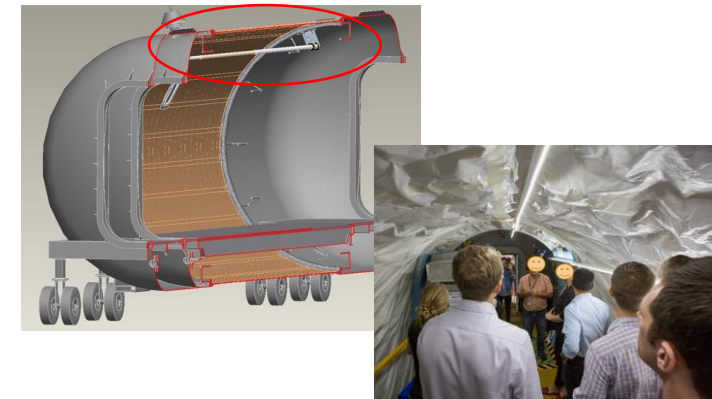
Application 1  
(core structure)



Application 2 (legs)



Application 3 (beam)



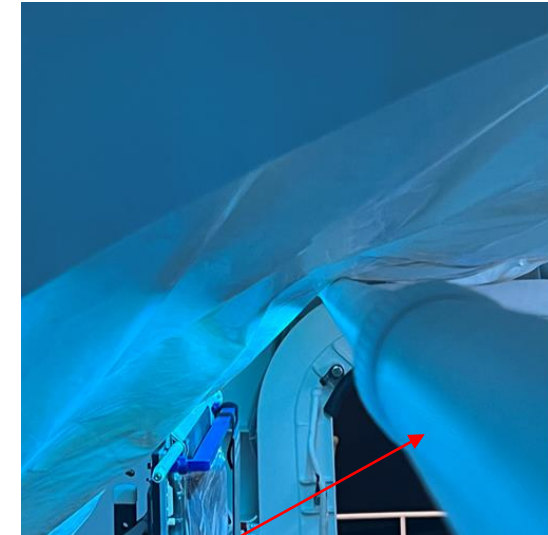
# Potential Applications

## Potential Application

- Support beams for habitat



xHab



Support Beams

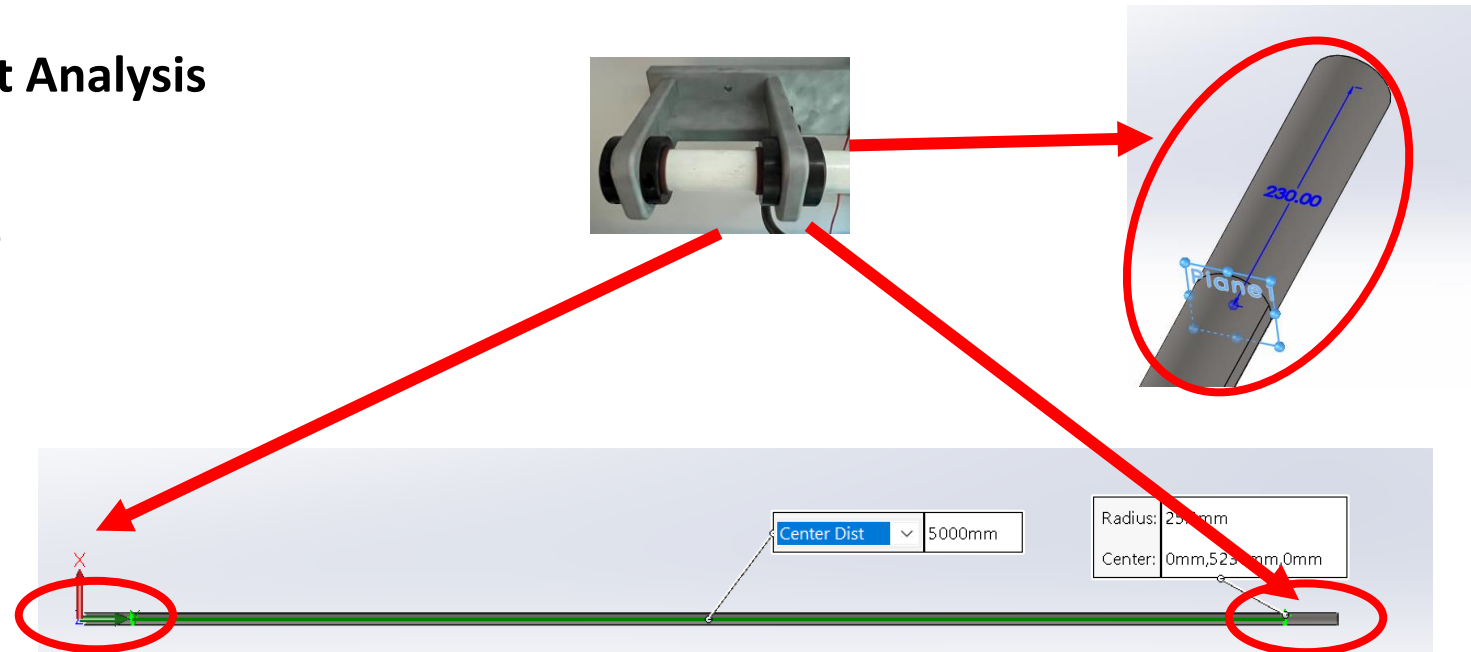
- Currently, beams are installed after expansion, but origami beams would deploy together with the habitat deployment.
- Beams need to hold their own weight and the weight of the heat blanket + restraint layer in case of >90% pressure drop, causing sagging.
- Will be replacing the function of both the light emitting diode (LED) beams on the inside and the exterior aluminum beams that hold the heat blanket.

# Design Optimization

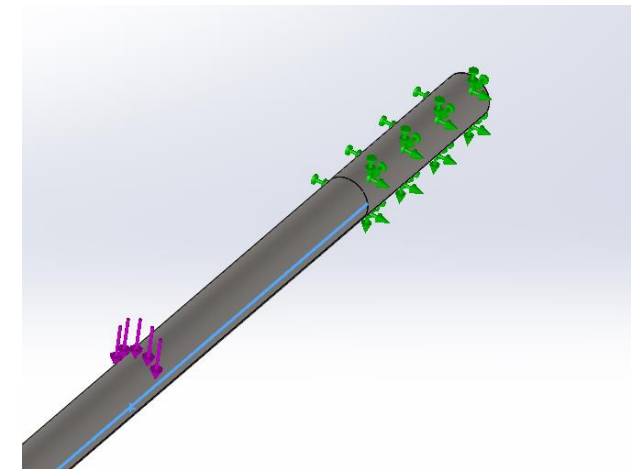
## Design Optimization by Finite Element Analysis (FEA) model

- Material comparison - simplified pipe

Dimension	Value	Unit
Length between grips	5	m
Grip length	0.23	m
Total length	5.46	m
Outer diameter	0.051	m
Thickness	0.001	m



- Split line along middle of model (blue) – force from soft goods pressing down all of top half, which is worst case.
- 1180 N force applied along the 5 m area between grips
- 1.62 m/s gravity applied to whole model
- 12 mm mesh size

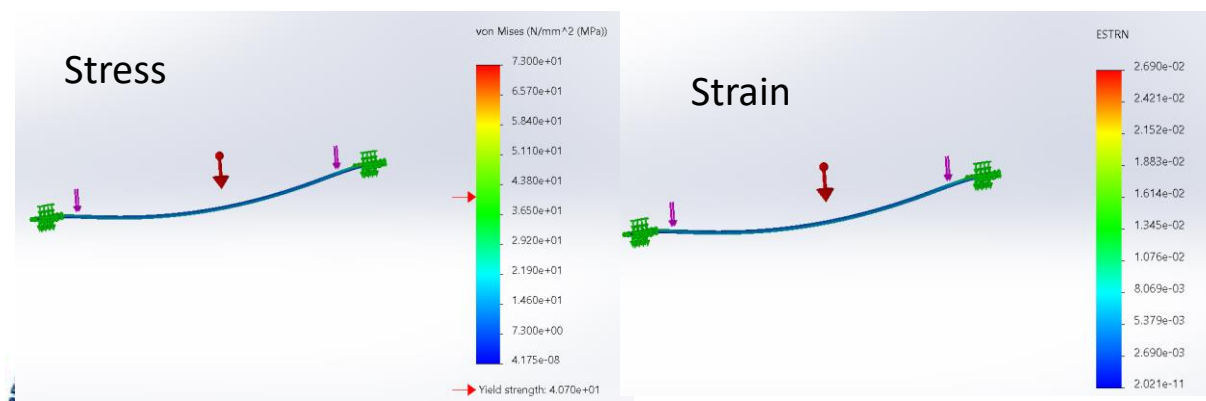




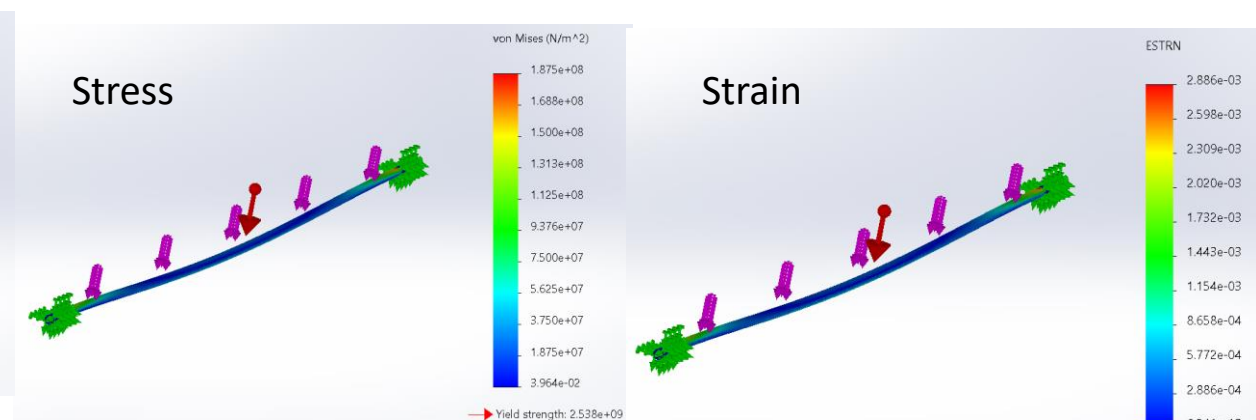
# Design Optimization

## Design Optimization by FEA model

Materials	Analysis	Simulation Max Value	Material Yield Properties	Safety factor (SF)	Optimized Weight
Polyvinyl Chloride (PVC, current)	Stress	65 MPa	40.7 MPa	0.6	12.9 kg (SF ~ 2.0)
	Strain	2.4 %	6%	2.5	
Aluminum 6061 T6	Stress	175 MPa	275 MPa	1.6	3.22 kg (SF ~ 2.2)
	Strain	0.22	7.87%	35.8	
CF/Epoxy SMP (*IM7/8552)	Stress	163 MPa	2538 MPa	13.5	0.164 kg (SF ~ 5.3)
	Strain	0.3 %	1.5%	5	



PVC Pipe (current)

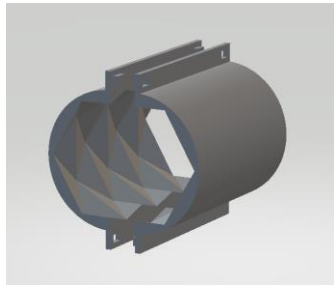


CF / Epoxy Pipe



# Fabrication of Prototype

## Yoshimura Pattern Beam



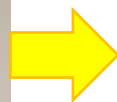
2.4"D x 4.6" H x 0.017"T

# Evaluation of Deployment (Shape Memory Effect)

## Yoshimura Patterned SMPC Beam



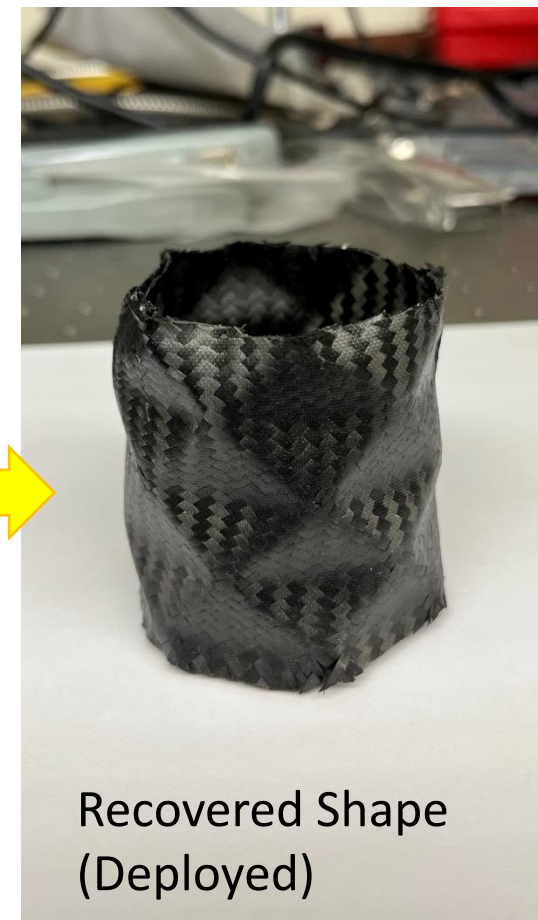
Original Shape



Programmed Shape  
(Stowed)



Deployment  
(Recovering Process)

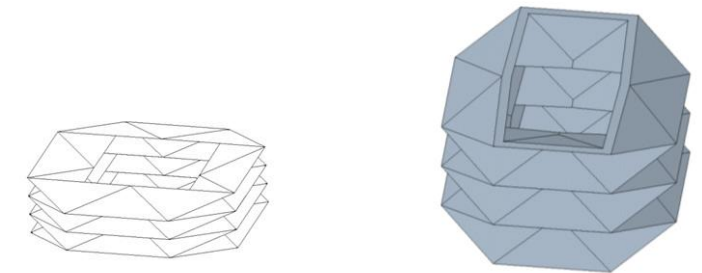


Recovered Shape  
(Deployed)

Packing Efficiency ~ 13%

# Lessons from Origami-Based SMPC

1. Novel origami-based deployable and rigidizable shape memory composite was developed for load bearing space structures.
2. Potential applications include core structure or floor beams, anti-sagging ceiling beam and supporting legs.
3. Sub-scale size origami SMPC beam was fabricated and deployment was demonstrated.
4. There was technical difficulty to fold in designed folding lines.
5. Hybrid resins system may solve the folding issue.



# Application 3 : Deployable Reflector Antenna

## Motivation

- Current launch vehicle fairing can accommodate fixed solid reflector antennas of 4-meter diameter.
- Typical architecture of deployable solid surface reflector is to have a central hub surrounded by a series of petals or gores supported on a deployable metering structure
- Those designs limit size to less than 10 meters in diameter due to high mass and mechanical complexity.
- An on-orbit servicing, assembly and manufacturing mission (OSAM-1) is planned to demonstrate in-space assembly of a 3-meter reflector antenna from seven 1-meter size hexagonal rigid panels using Space Infrastructure Dexterous Robot (SPIDER) by MAXAR Technologies.
- LaRC and MAXAR established a new collaboration effort of new advanced packaging method using flexible composite technology.
- A shape memory polymer composite tubular hinge was developed for this application.



Space Infrastructure Dexterous Robot (SPIDER) in the OSAM-1 spacecraft

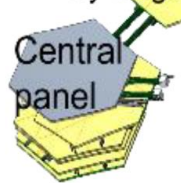
\*Project PI: Dr. Juan Fernandez

# Architecture Design

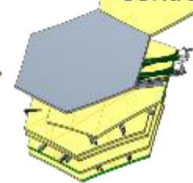
**Stowed configuration**



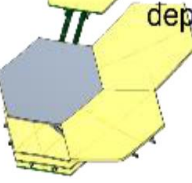
Outermost panel deployed by hinges



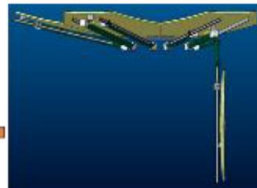
Outermost panel fixed to central panel



3 side panels deployed

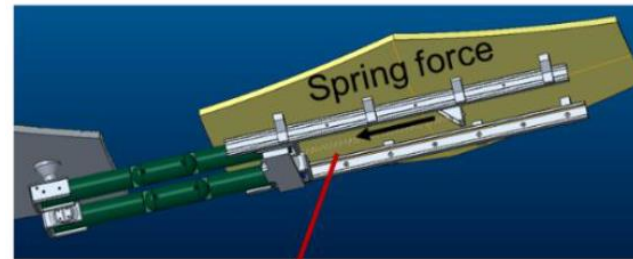


**Deployed configuration**

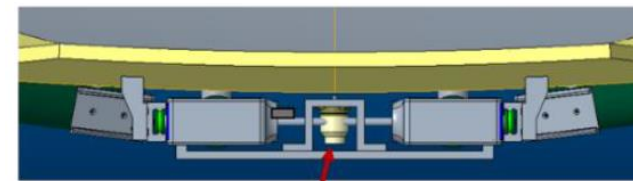


Deployment sequence of last panel

Deployment sequence of a concentrically stacked seven-panel reflector by SMC hinges. Side panel deployment occurs one at a time from the outermost panel until all are fixed to the central panel.

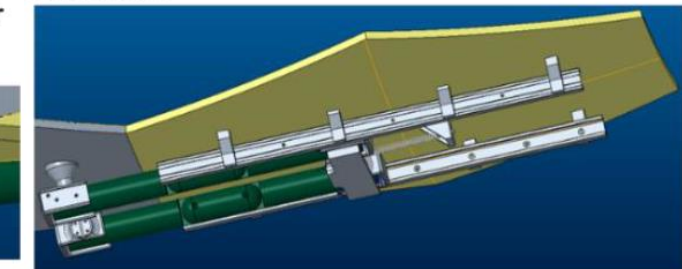
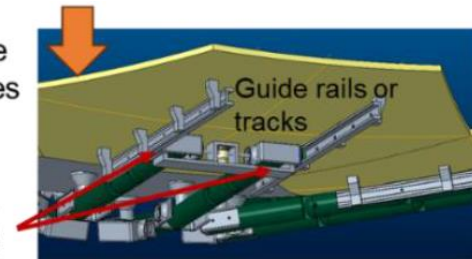


Constant force spring reel acts along tubular hinge axis when the hinges are deployed.



Hold-down release mechanism for launch fixes hinge end fittings to the side hex panel.

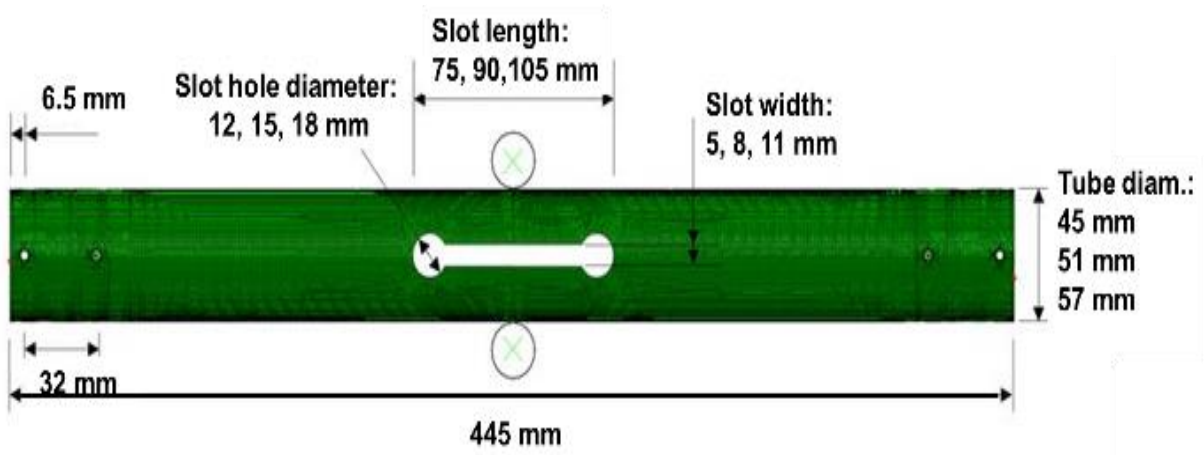
Upon release, the spring force closes the panel gap by translating the hinge end fittings along the straight rails/tracks



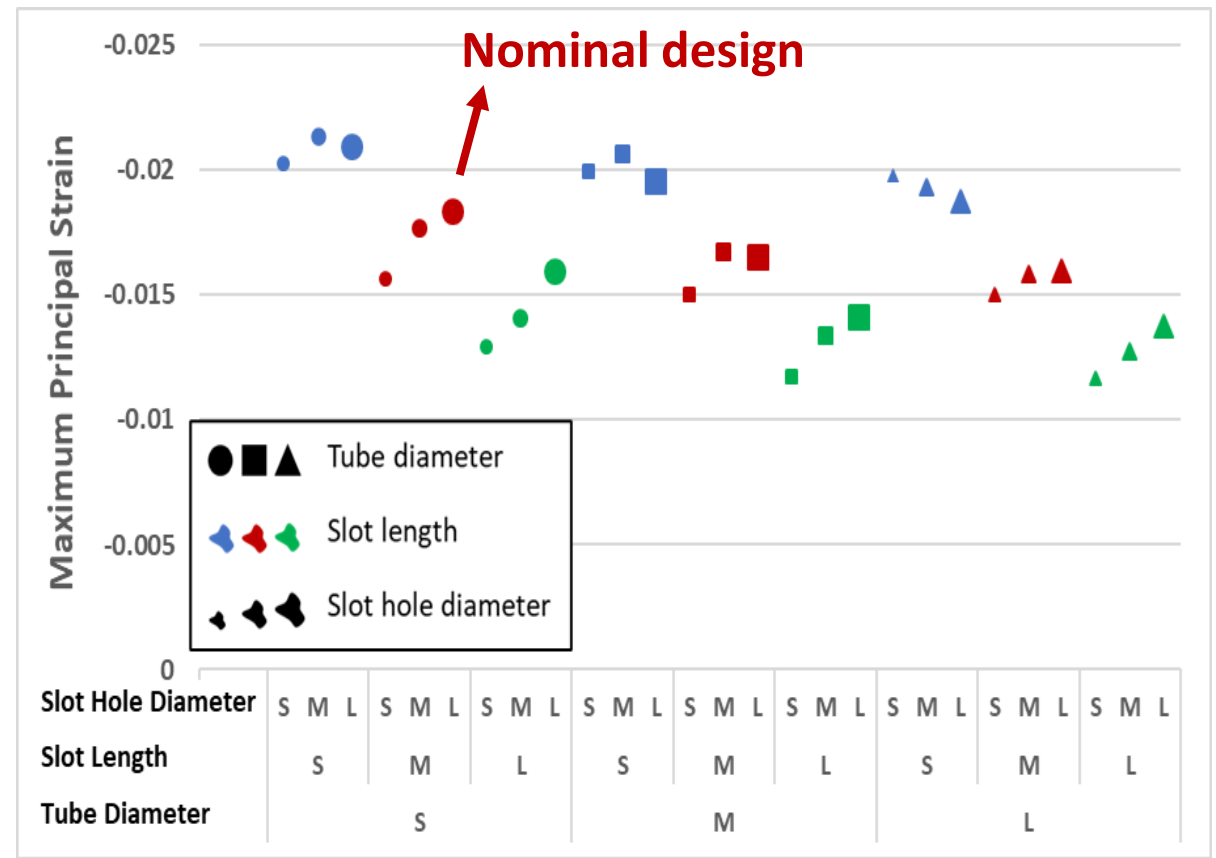
Secondary spring-loaded mechanism to close the initial inter-panel gap left by the pair of hinges.

The use of a new SMPC with integrated heating and sensing capabilities was developed to reduce part count (complexity), power requirements, and cost of larger antenna reflectors, while enabling a high deployed stiffness solution with predictable and controlled deployment dynamics

# SMPC Tubular Hinge Design and Test



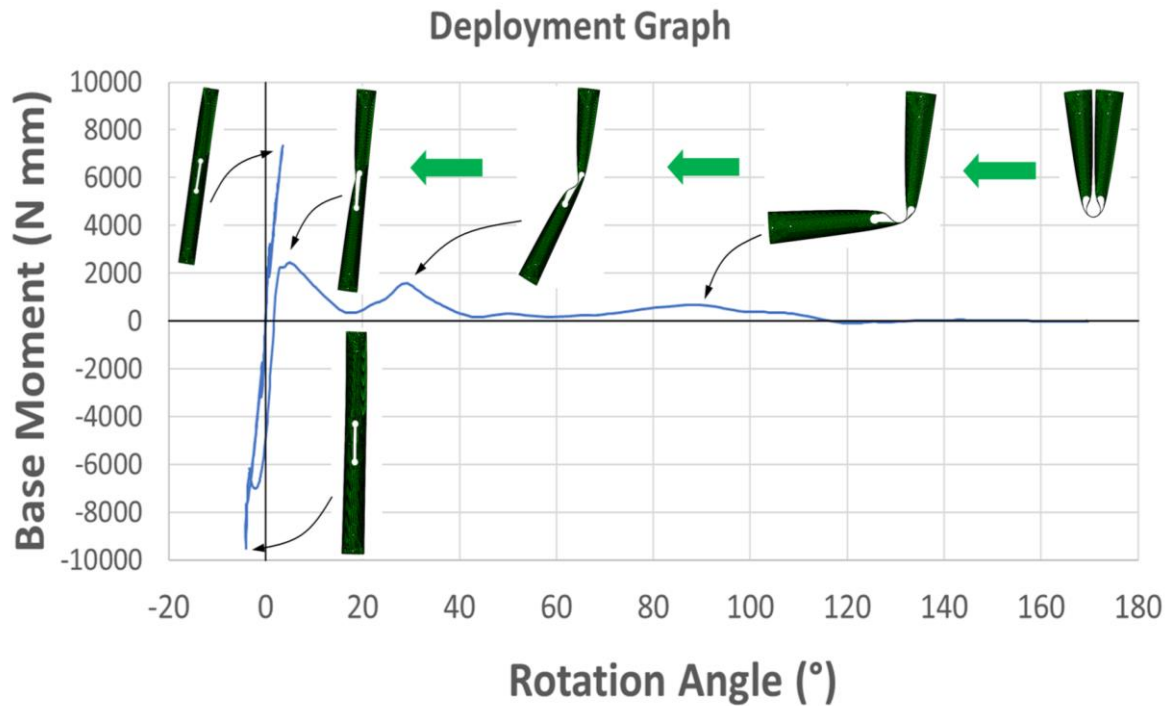
Three independent parameters: tube diameter, hinge slot length, and the diameter at the end of the dogbone slot (with the slot width being proportional to it) with three different dimensions (small, medium and large) generated a total of 27 analysis cases.



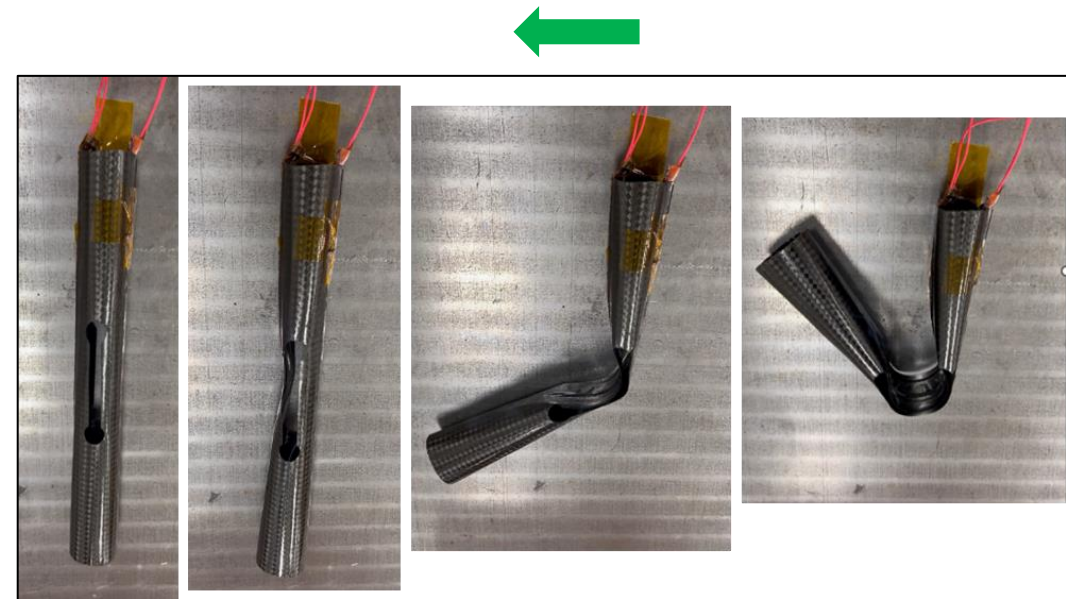
Folded strains between 1.2% to 2.2% are expected, suggesting the use of intermediate modulus CF laminates with high strain to failure or elastomeric-like resin



# SMPC Tubular Hinge Design and Test



Deployment moment-rotation relationship graph showing final moment peaks when the hinge snaps through

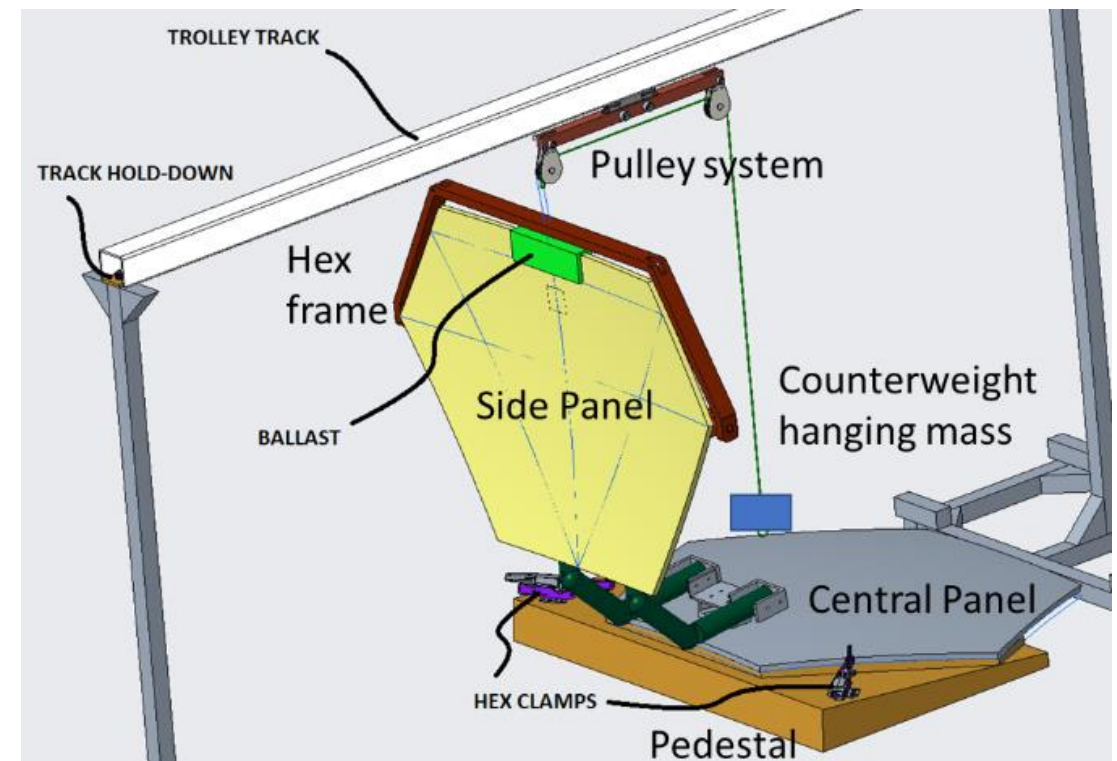


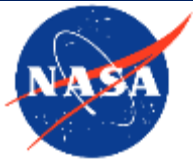
Test article deployed using the embedded heaters locking into the final straight configuration

Large peak moments after hinges reach final straight configuration at 0° angle  
Hinge vibrates back and forth until the kinetic energy dissipates

# Lessons from Deployable Reflector Antenna

1. New architecture for solid surface antenna reflector that combines deployment of unit cells of vertically-stacked, seven-hexagonal panel sub-reflectors compatible with robotic assembly into larger version.
2. Parametric study helped in SMC hinge design with baseline case showing acceptable folding strains, sufficient stiffness and low deployment dynamics.
3. There was an interfacial delamination issue between the heater tape and SMPC layer.
4. Final 3-m scale test article and test configuration presented will be used to demonstrate efficient stowage with minimal constrains, controlled deployment, and maintain necessary shape accuracy of  $< 3$  mm root mean square (RMS) error in a relevant environment.





# Summary and Future Works

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1. Series of novel LaRC shape memory polymer composites (LaRC SMPC) were developed for various applications from terrestrial to space applications, such as adaptive airfoil system (slat cove filer), origami-based SMPC beam in a space habitat and deployable reflector antenna.
2. The exotic properties of shape memory effect, stowage/deployment capabilities, relatively fast response time, large recovery stress, tailorability were successfully characterized.
3. Some promising demonstration tests of application were achieved, but there still remains room to solve the engineering problems such as long-term durability of multiple deployments.
4. Improved interfacial strength between CF and SMP or between SMP and heater may mitigate the current issues.



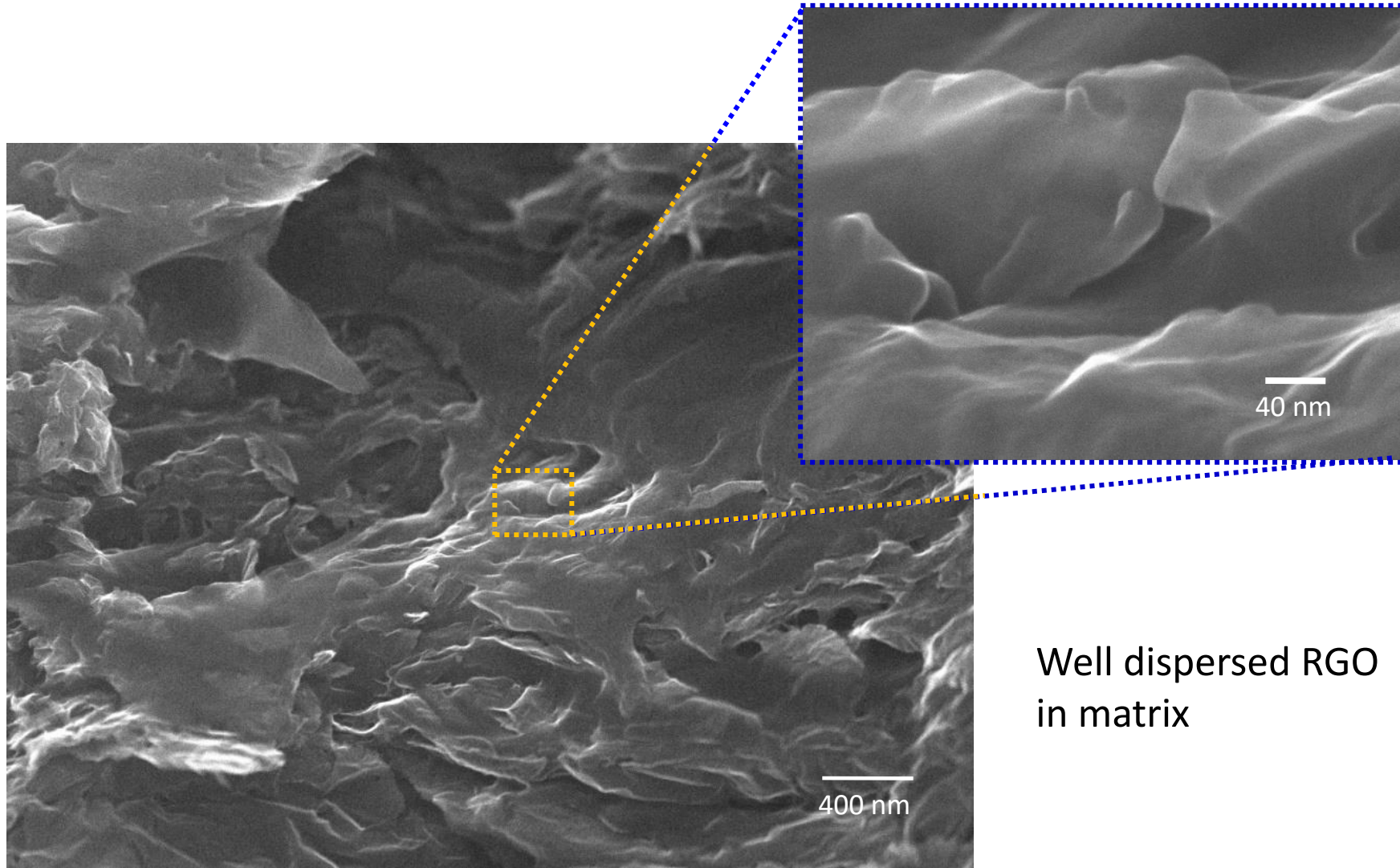


# Backup

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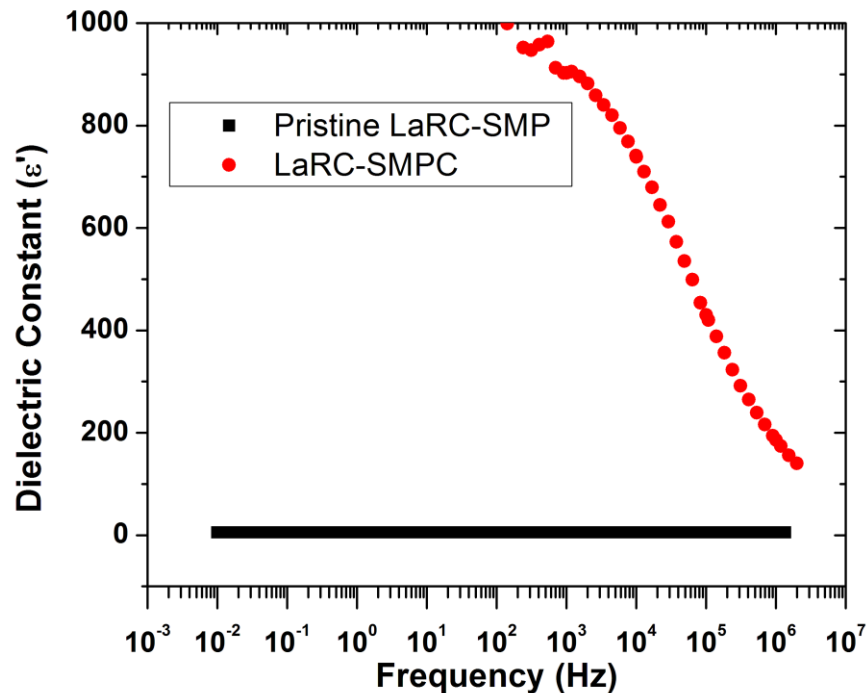
# Morphology of LaRC SMPC (2% RGO)



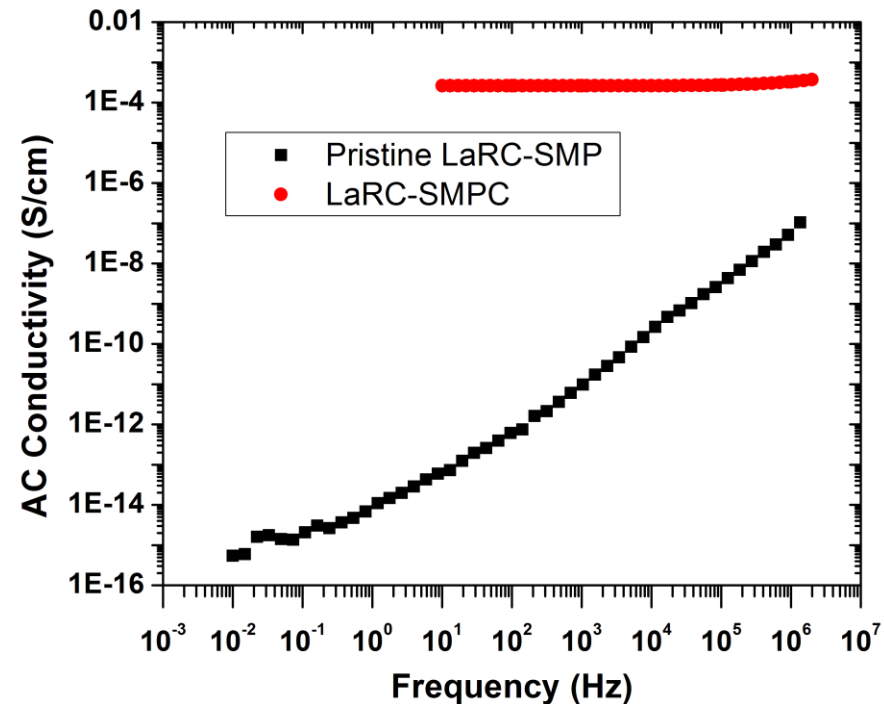
Well dispersed RGO  
in matrix

# Tailoring Properties – 3 : Electrical Properties

Dielectric constant

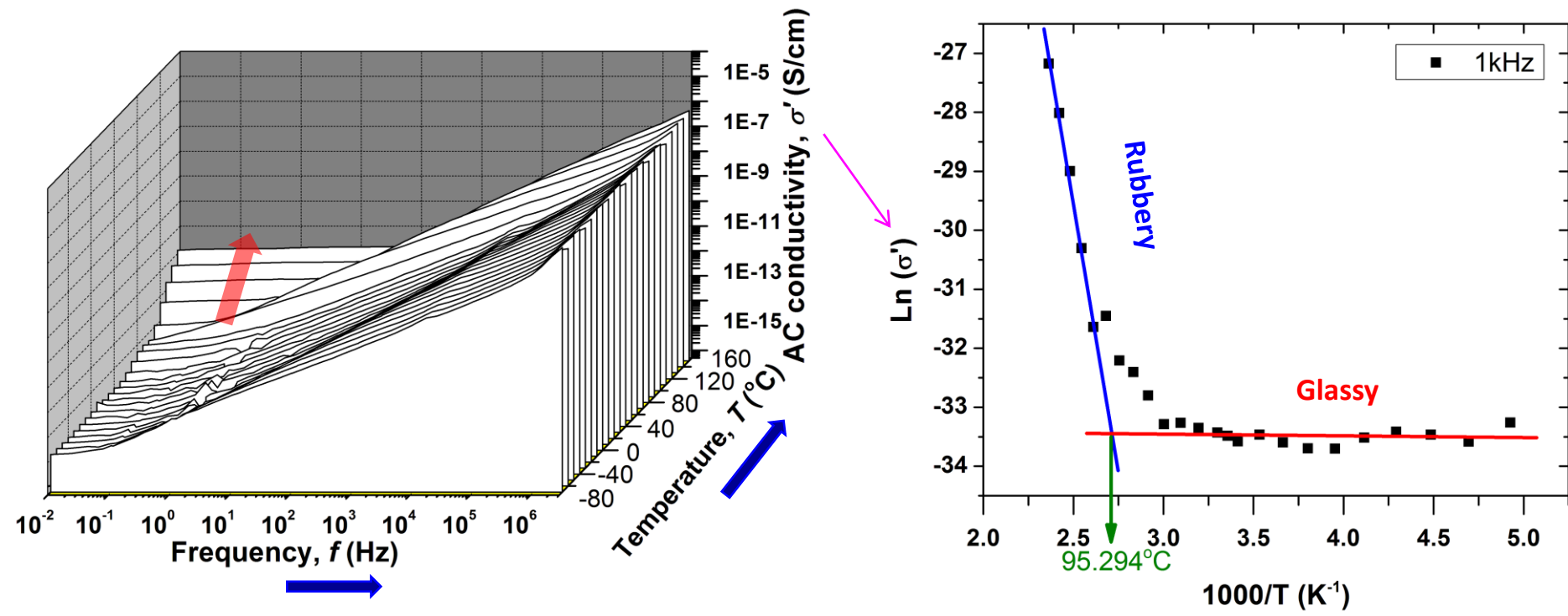


AC conductivity



LaRC SMPC has high electrical conductivity and high dielectric constant

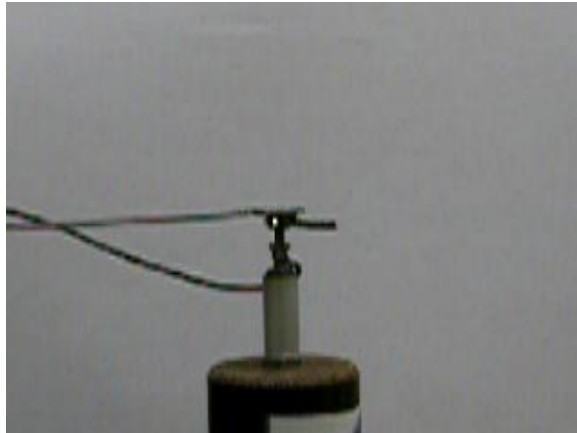
# AC Conductivity of LaRC SMP



LaRC SMPC has high electrical conductivity and glass transition temperature of about  $95^\circ\text{C}$

# Electric Field Activated Shape Memory Effect

Voltage ON



Voltage OFF - Cooling



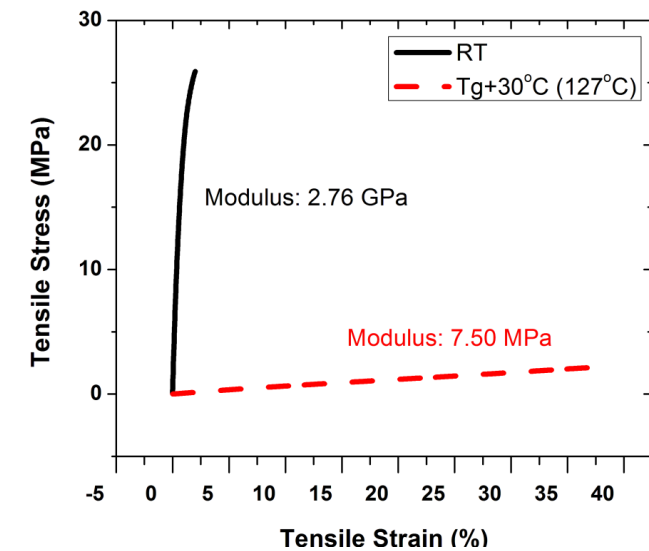
Cooling → Voltage ON again



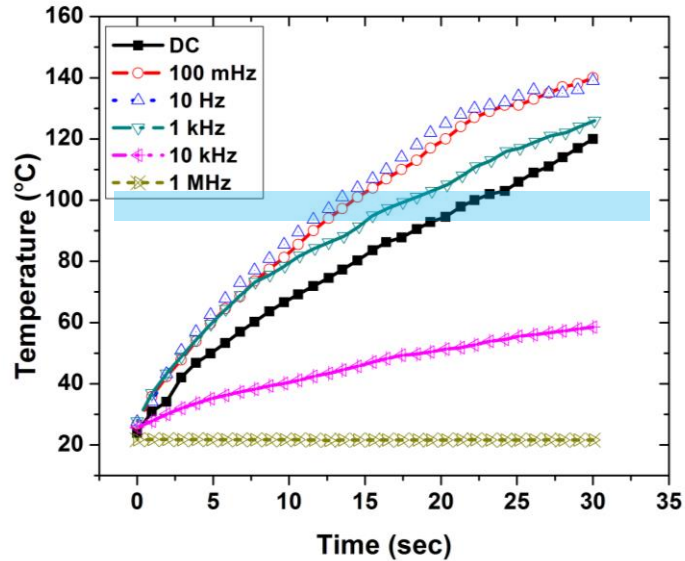
Voltage OFF - Cooling



DC 13V (0.01 MV/m)  
Cr/Au Electroded



# Mechanism of Effect of AC Electric Field on SME



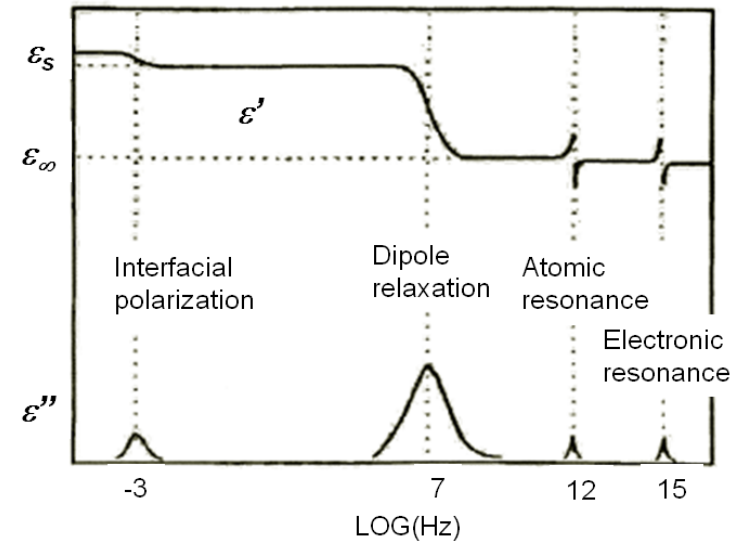
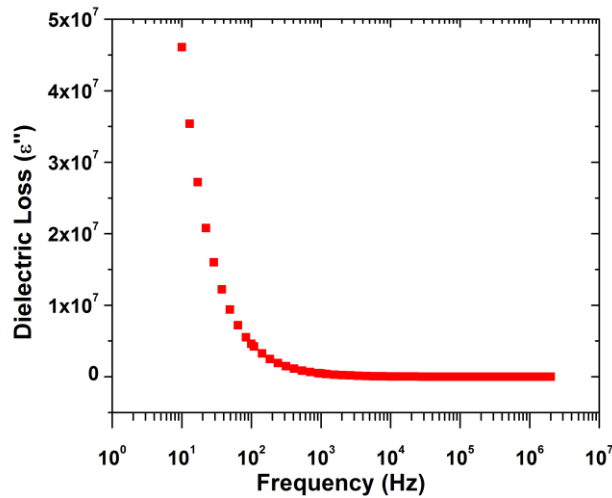
Loss Heating from dipole orientation

$$P = K f E^2 \epsilon''$$

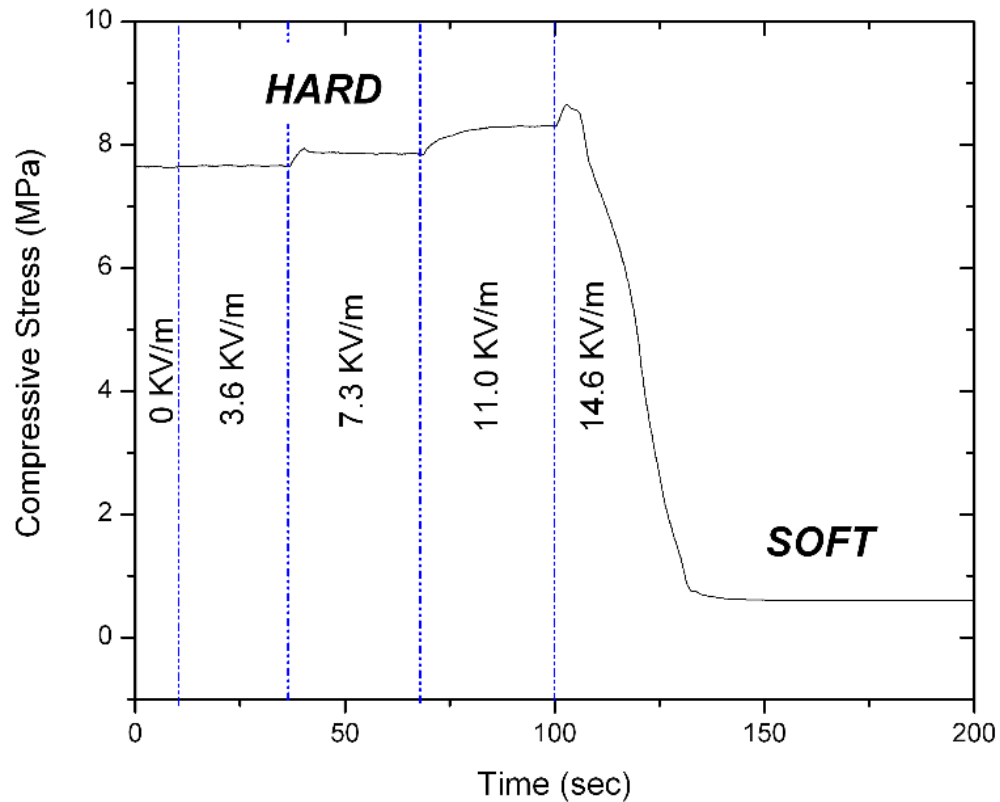
Joule heating from DC

$$Q = I^2 \cdot R \cdot t = V \cdot I \cdot t = \frac{V^2}{R} \cdot t.$$

$$P = V \cdot I = \frac{V^2}{R}.$$

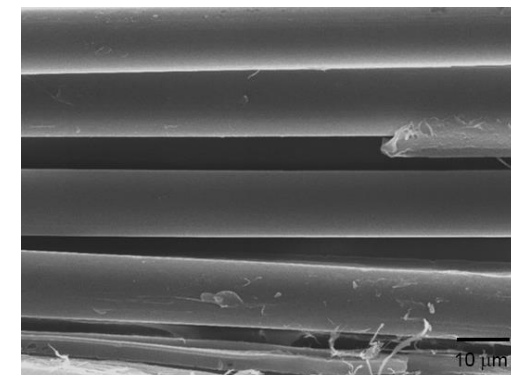
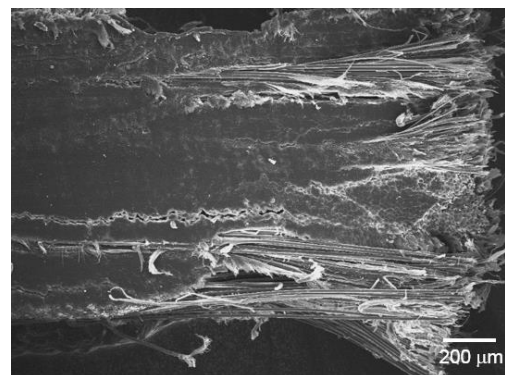
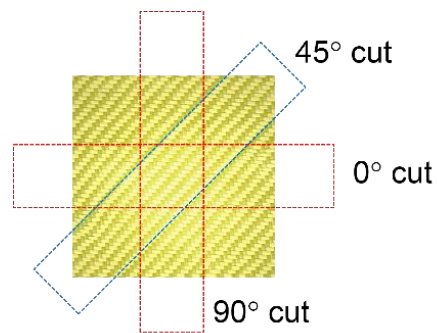
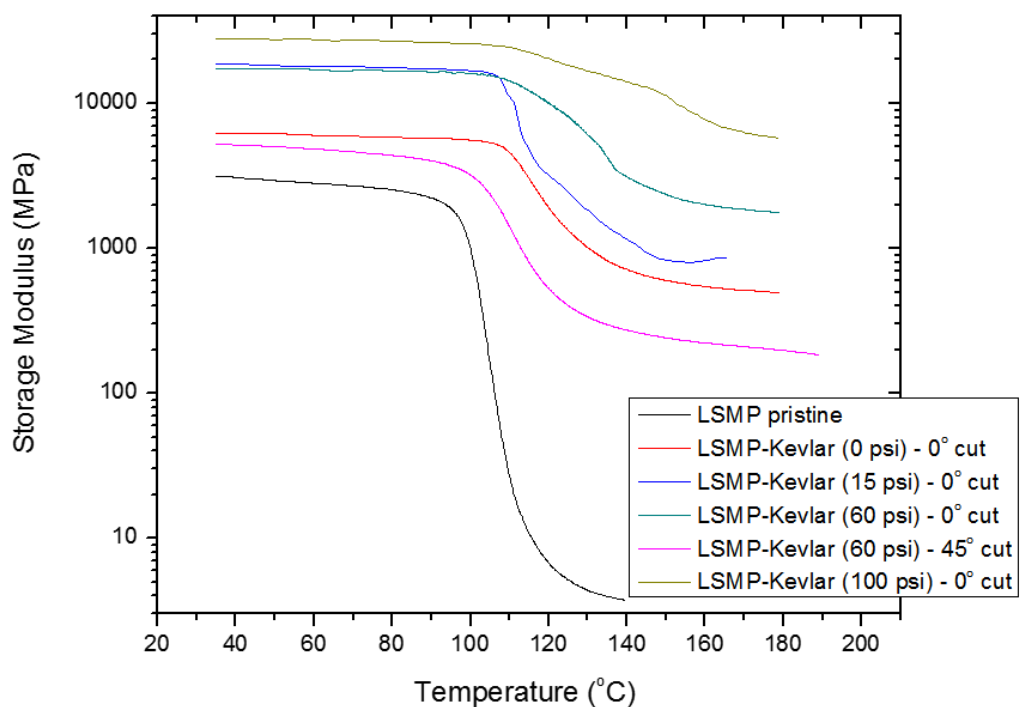


# Effect of DC Electric Field on SMPC



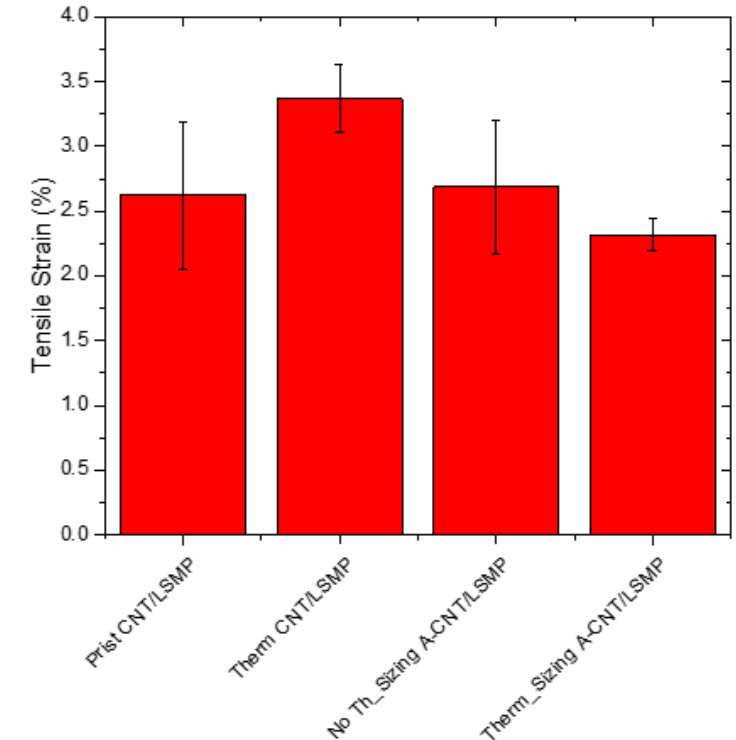
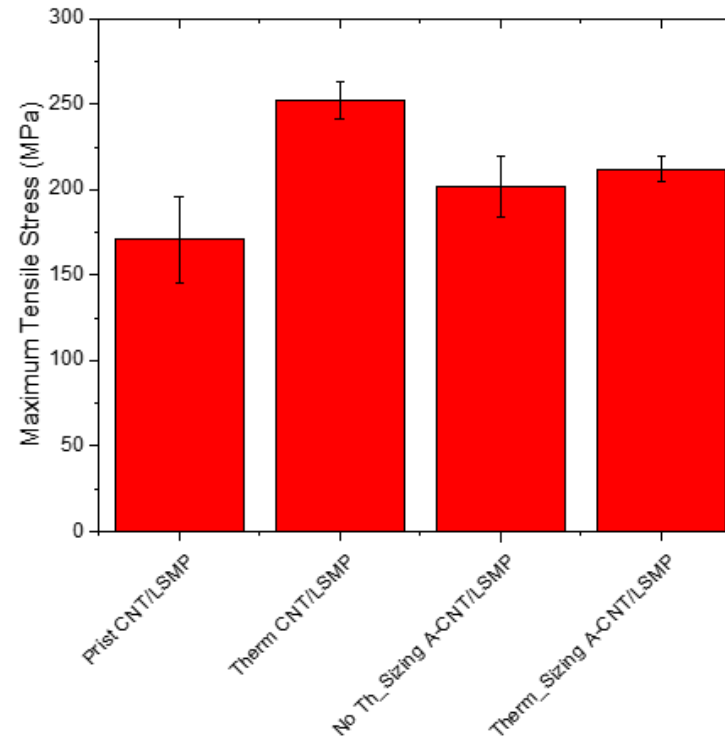
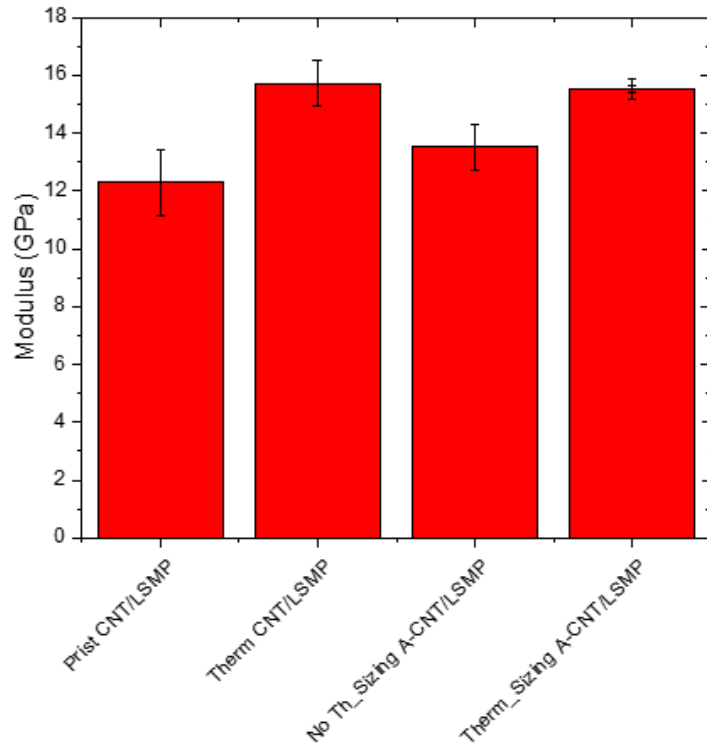
Mechanical stiffness change of LaRC-SMPC under applied DC electric field

# Dynamic Mechanical Analysis of Kevlar<sup>®</sup> Reinforced SMPC



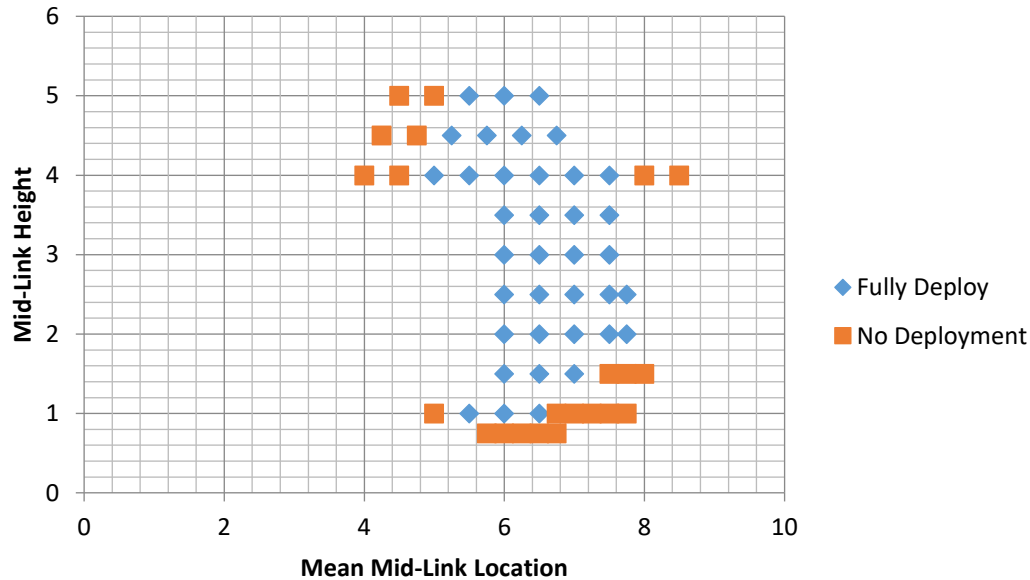
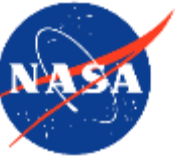
Cross-sectional SEM images of Kevlar<sup>®</sup> fabric reinforced SMPC

# Mechanical Properties of CNS Reinforced SMPC

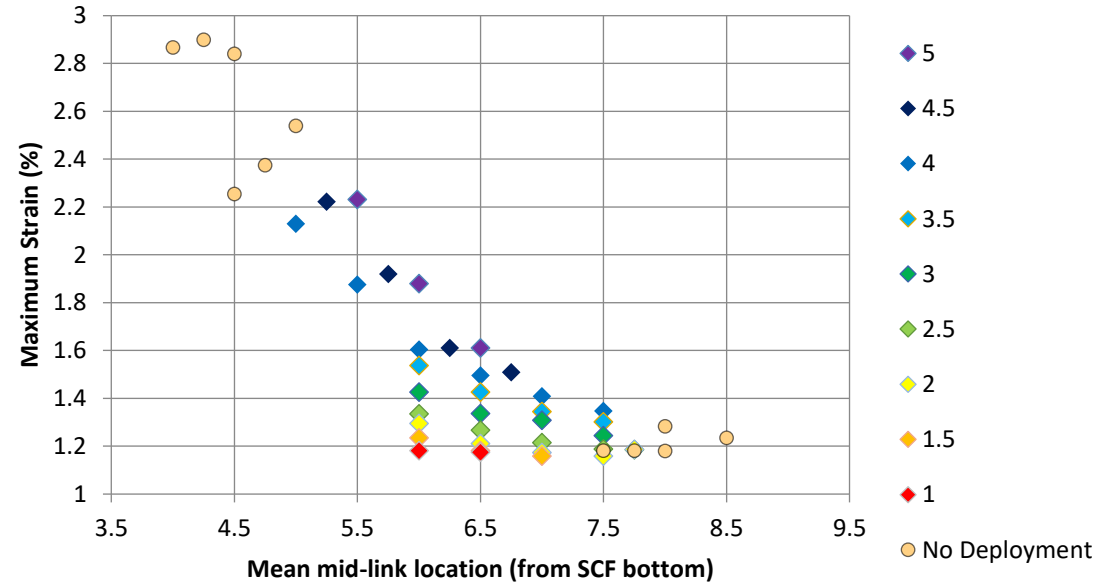


In order to increase interfacial strength between CNTs and SMP resin, CNT sheets were modified by three different methods: (1) thermal treatment at 250°C for 1 hr, (2) sizing treatment (epoxy based sizing material) without thermal treatment, and (3) sizing treatment (epoxy based sizing material) after thermal treatment at 250°C for 1 hr.

# Designing SCF Conformation by Computational Modeling



Optimization of mid-link height and location for successful deployment.

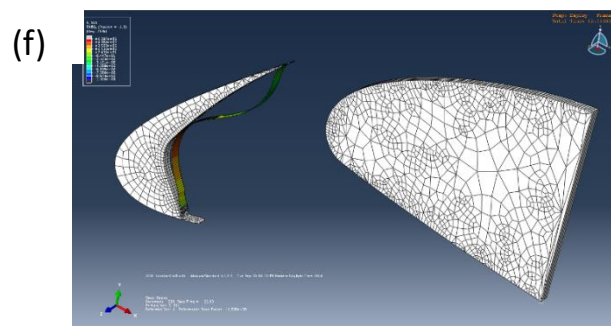
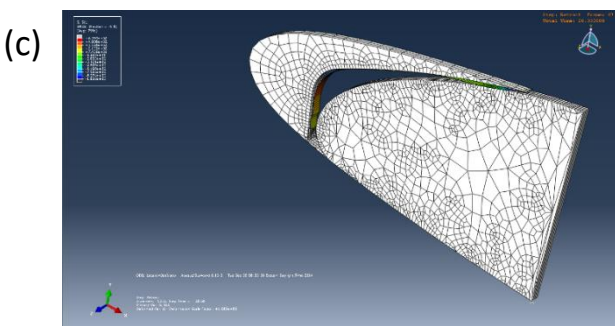
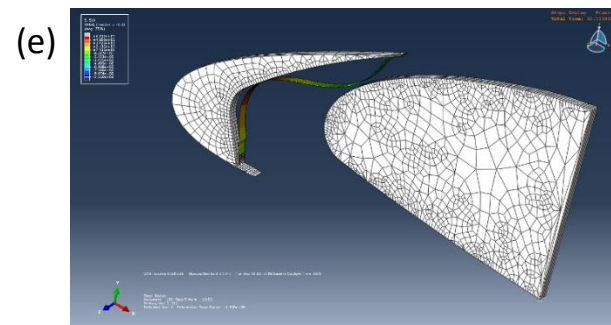
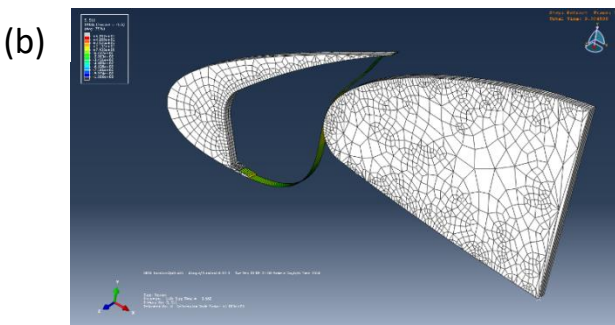
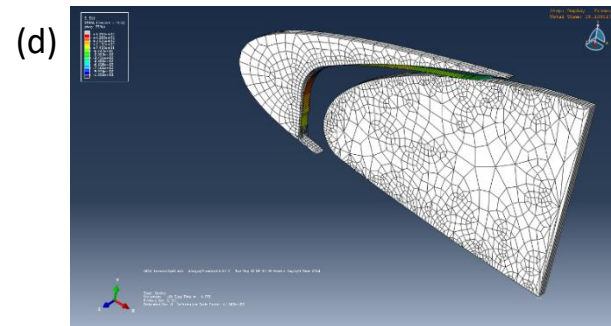
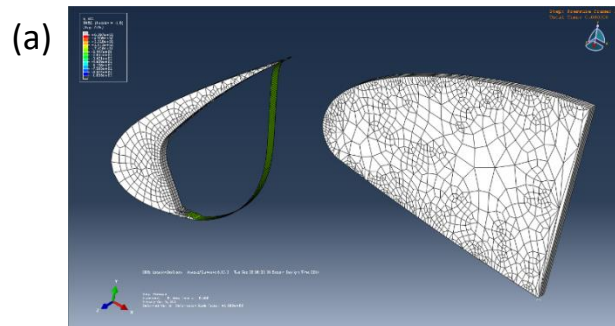


Maximum strain verses mid-link location for various mid-link sizes

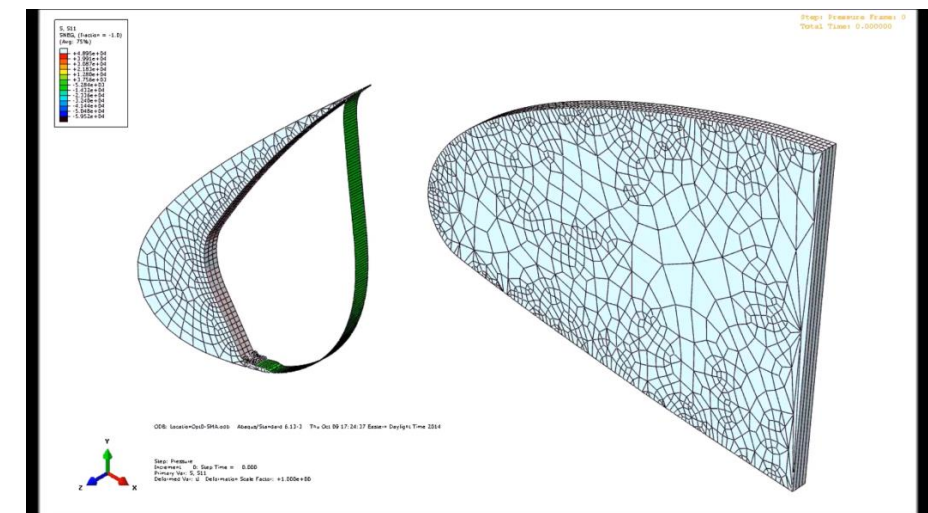
Because the preferred maximum strain is below 2% for composite materials, the optimized mid-link location and size was about 15.24 to 19.05 cm (6 to 7.5 inches) and about 3.81 to 12.7 cm (1.5 to 5 inches), respectively. The optimized parameters were employed for the fabrication of SCF.



# Designing SCF Conformation by Computational Modeling



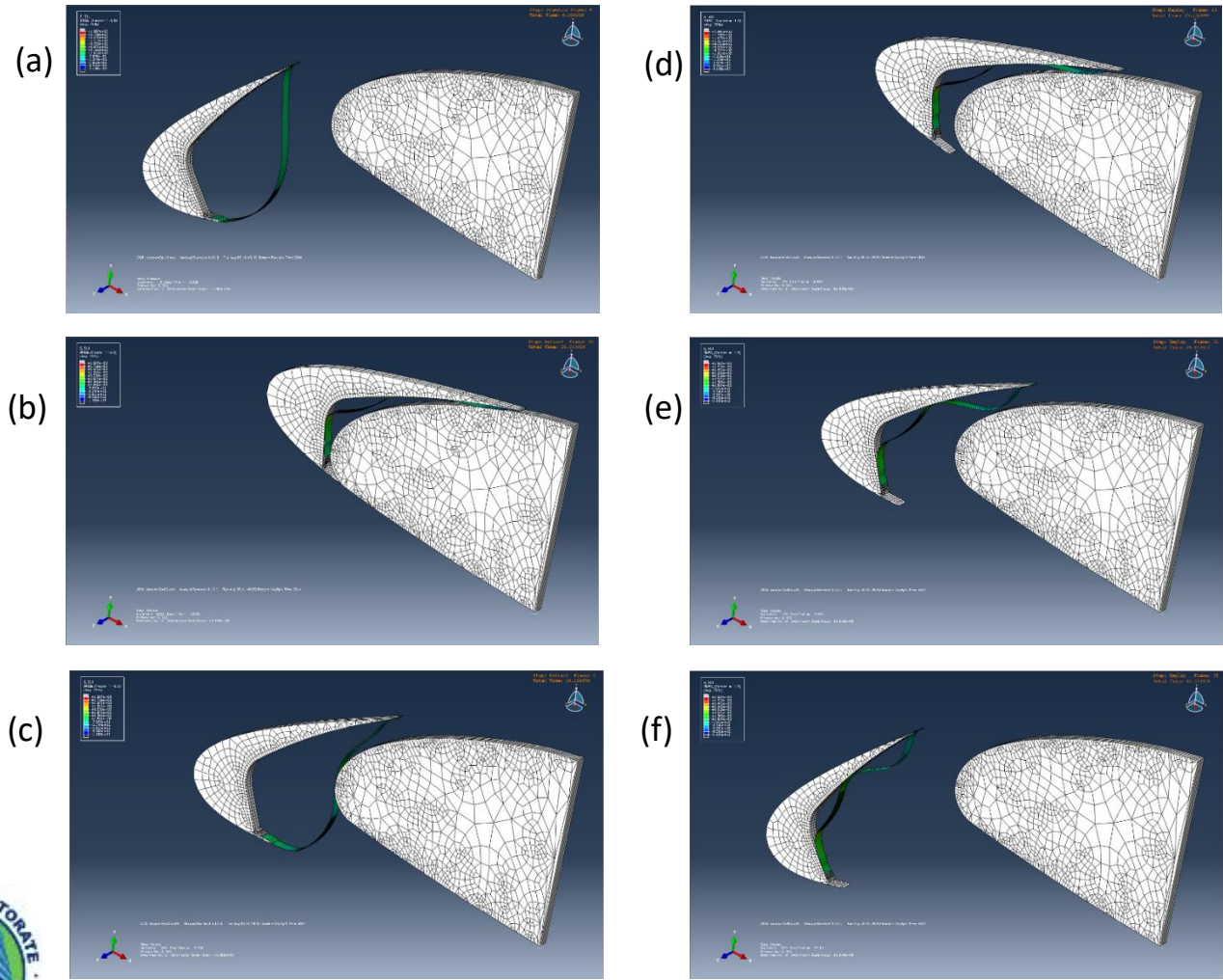
Computation modeling of SMP SCF actuation shows unsuccessful deployment with no mid-link. (a –c) retraction, and (d-f) deployment.



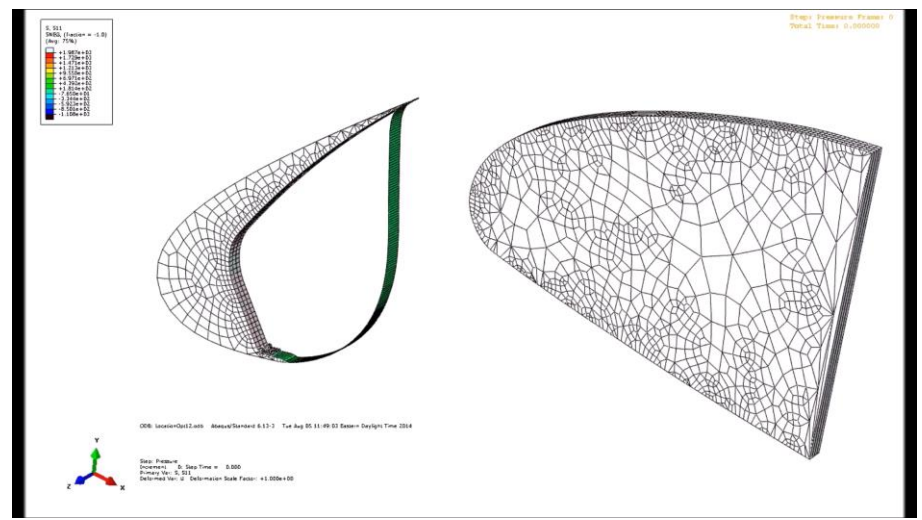
No mid-link →  
Deployment failed



# Designing SCF Conformation by Computational Modeling



Computation modeling of SMP SCF actuation shows unsuccessful deployment with a mid-link (Length: 4", mean location from bottom: 4"). (a –c) retraction, and (d-f) deployment.

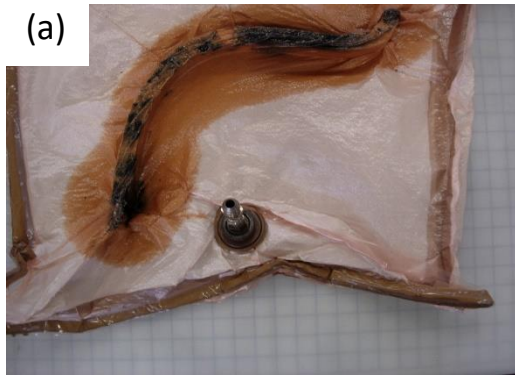


A mid-link (Length: 4", mean location from bottom: 4")  
→ Deployment failed



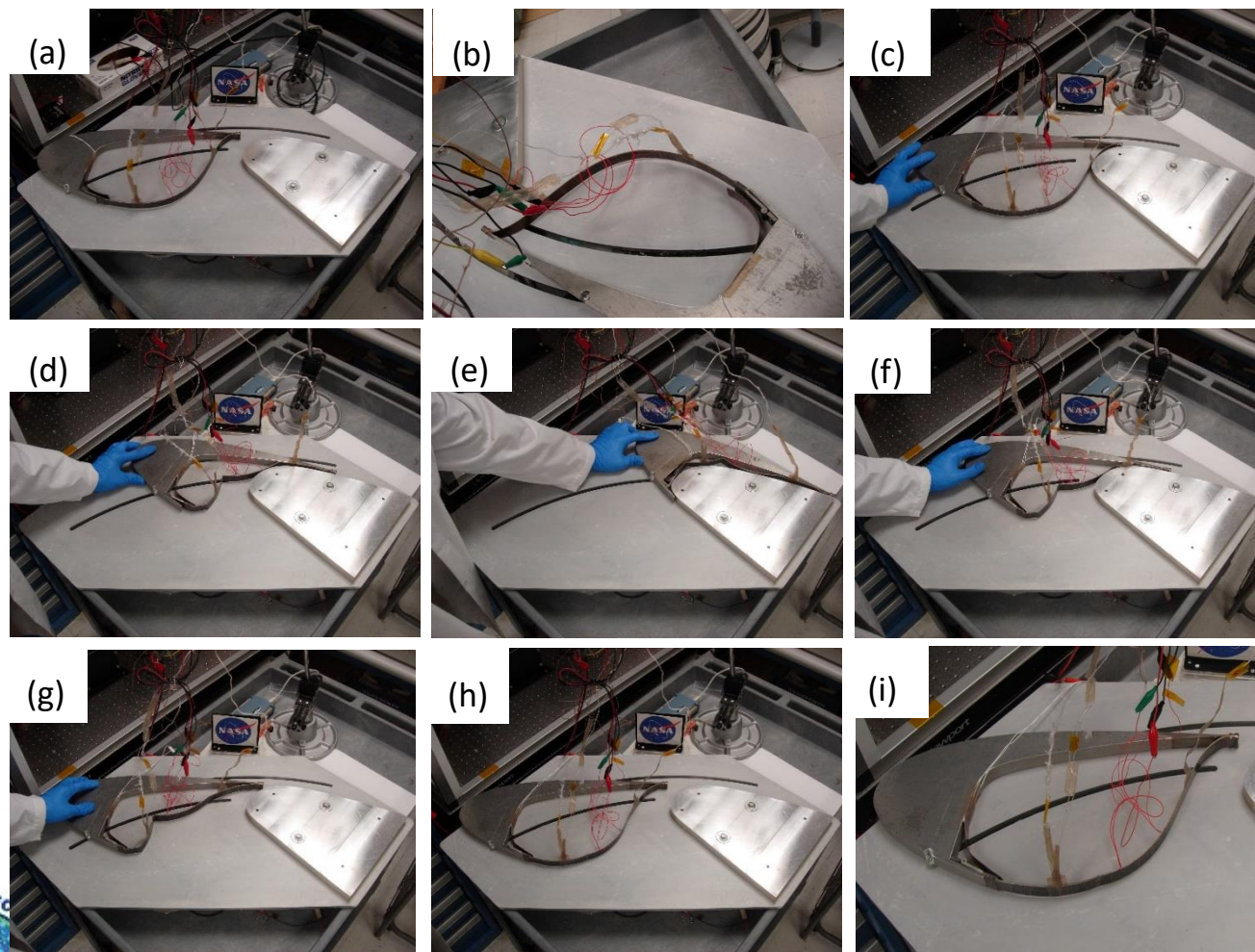


# Fabrication of SCF using SMPC

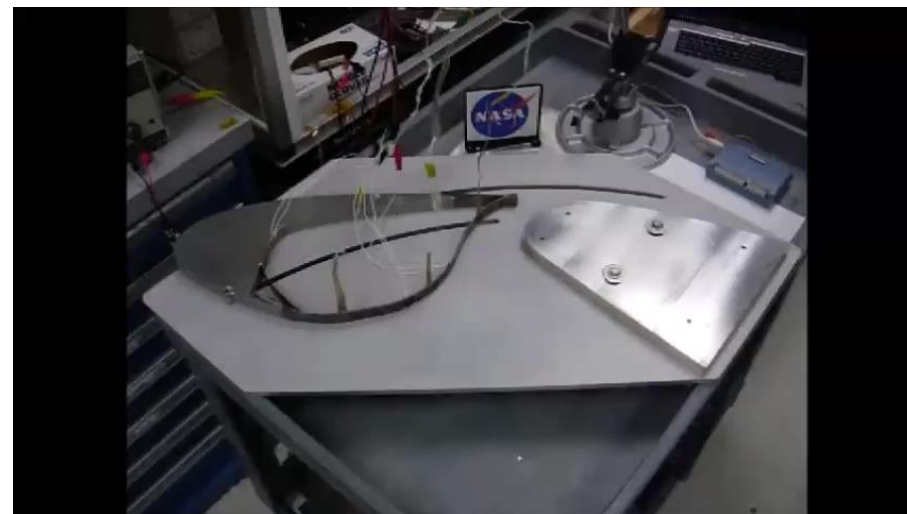


Fabrication of SCF using SMP composite. (a) sample mold in breathing fabric after curing in autoclave, (b) SMP SCF in aluminum mold, (c-d) retrieving SMP SCF sample from the aluminum mold.

# Bench-Top Demonstration of SCF Fabricated with SMPC-1



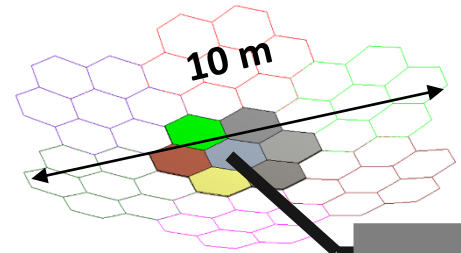
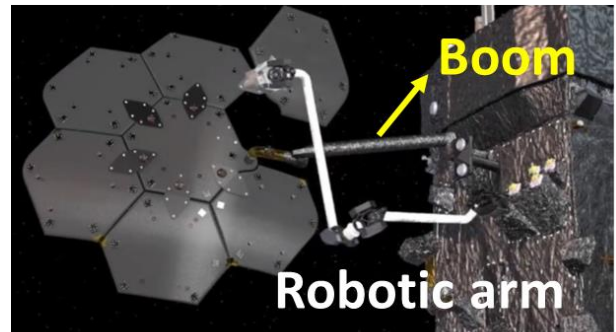
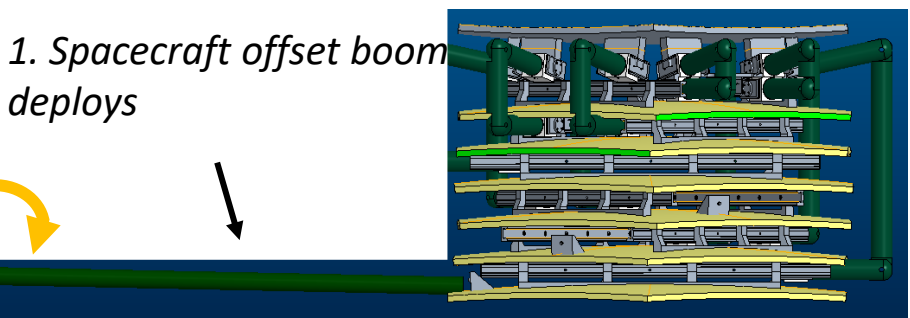
Bench-top demonstration of SCF fabricated with Kevlar<sup>®</sup> fiber/SMPC. (a) before retraction, (b) heating tapes in top and bottom sections, Nitinol spring, (c-h) full process of stowage and deployment, and (i) yielding a **permanent damage** after runs



# Scalable Architecture Using Robotic In-Space Assembly



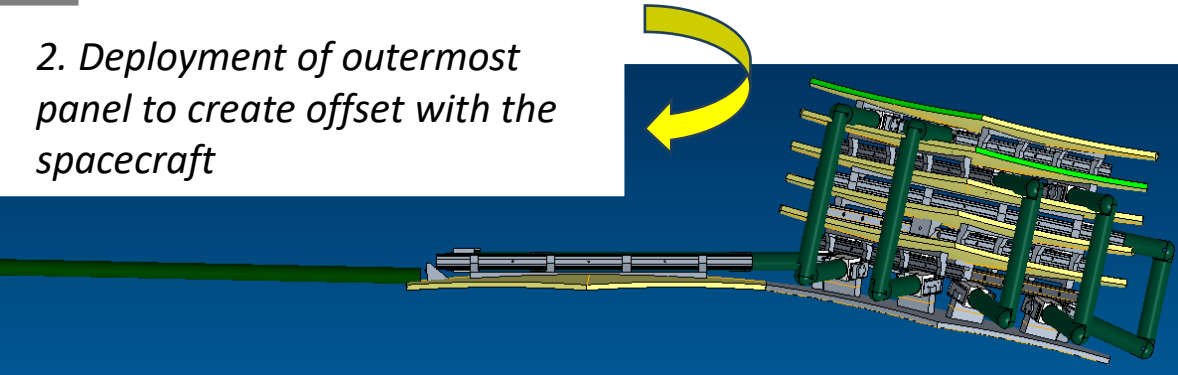
Spacecraft (s/c)  
- Not to scale



s/c



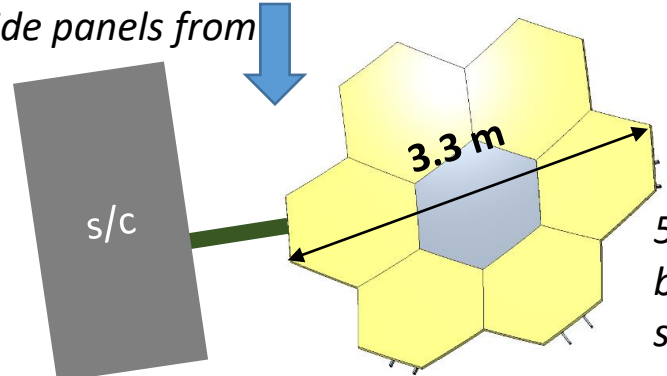
s/c



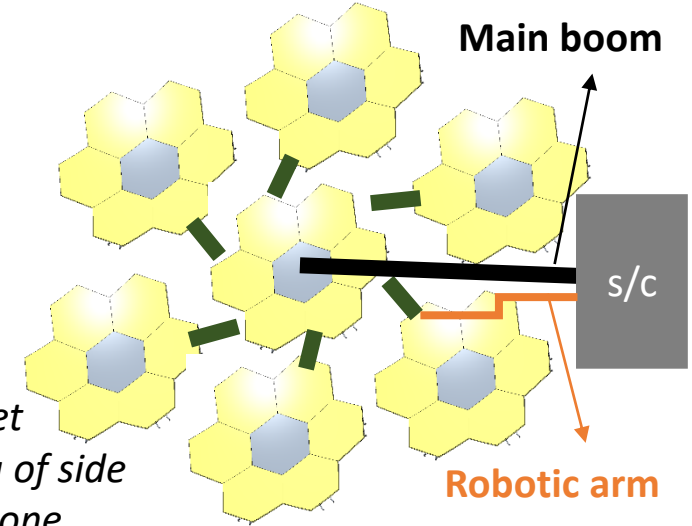
6. Robotic arm uses SPIDER-like Interconnect Assembly plates to fix certain hexagonal side panels for additional global stiffness of the 10 m reflector

3. Deployment of rest of side panels from central one

4. Deployed 3.3 m sub-reflector with offset boom ready to be robotically assembled to the rest

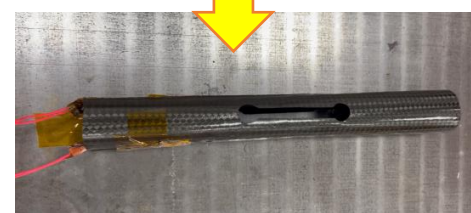
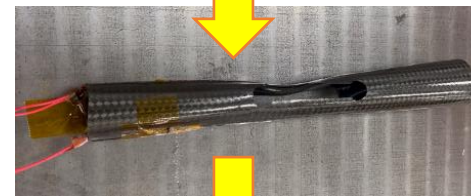
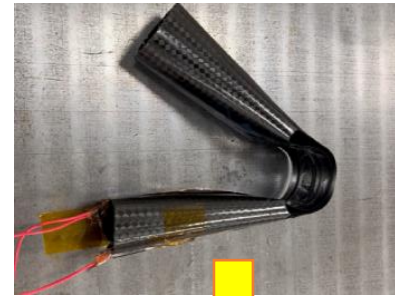
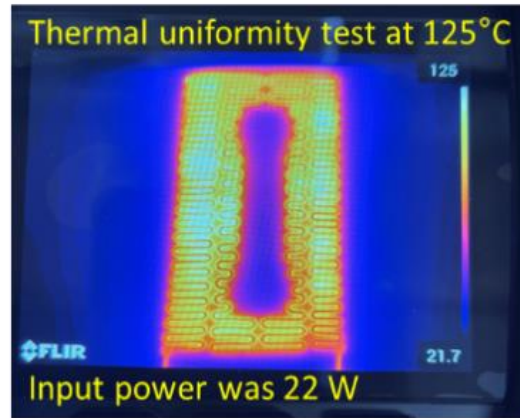


5. Robotic arm uses offset booms to initiate mating of side sub-reflectors to central one

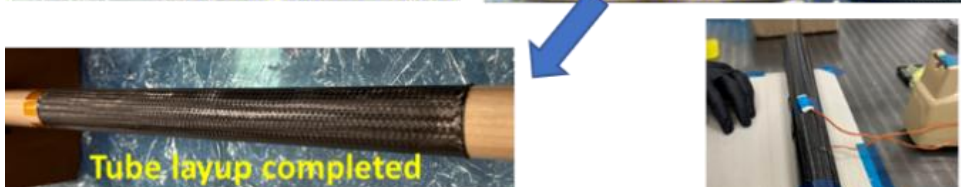
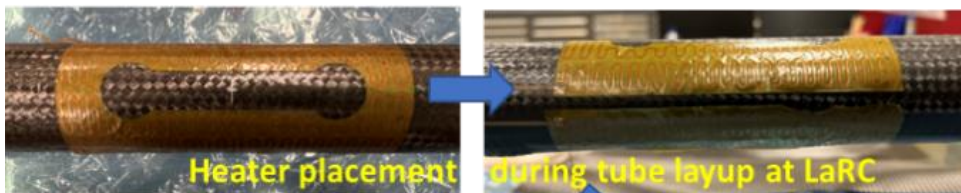


Ref. J. M. Fernandez et al., 41<sup>st</sup> ESA Antenna Workshop on Large Deployable Antennas, Sept. 2023, ESA-ESTEC in Noordwijk, The Netherlands

# SMPC Tubular Hinge Fabrication and Test



- 26- $\mu\text{m}$  thick heaters have a serpentine shape to increase flexibility without yielding the conductive Copper layer.
- New shape memory composite material developed at NASA produces self-actuation of hinge under thermal input of heaters and sensor control.
- Low power actuation of  $< 100$  W per SMC hinge or  $< 200$  W per panel.
- Controlled self-deployment of hinge over 10 – 15 seconds without final shock.



Hinge temperature uniformity test

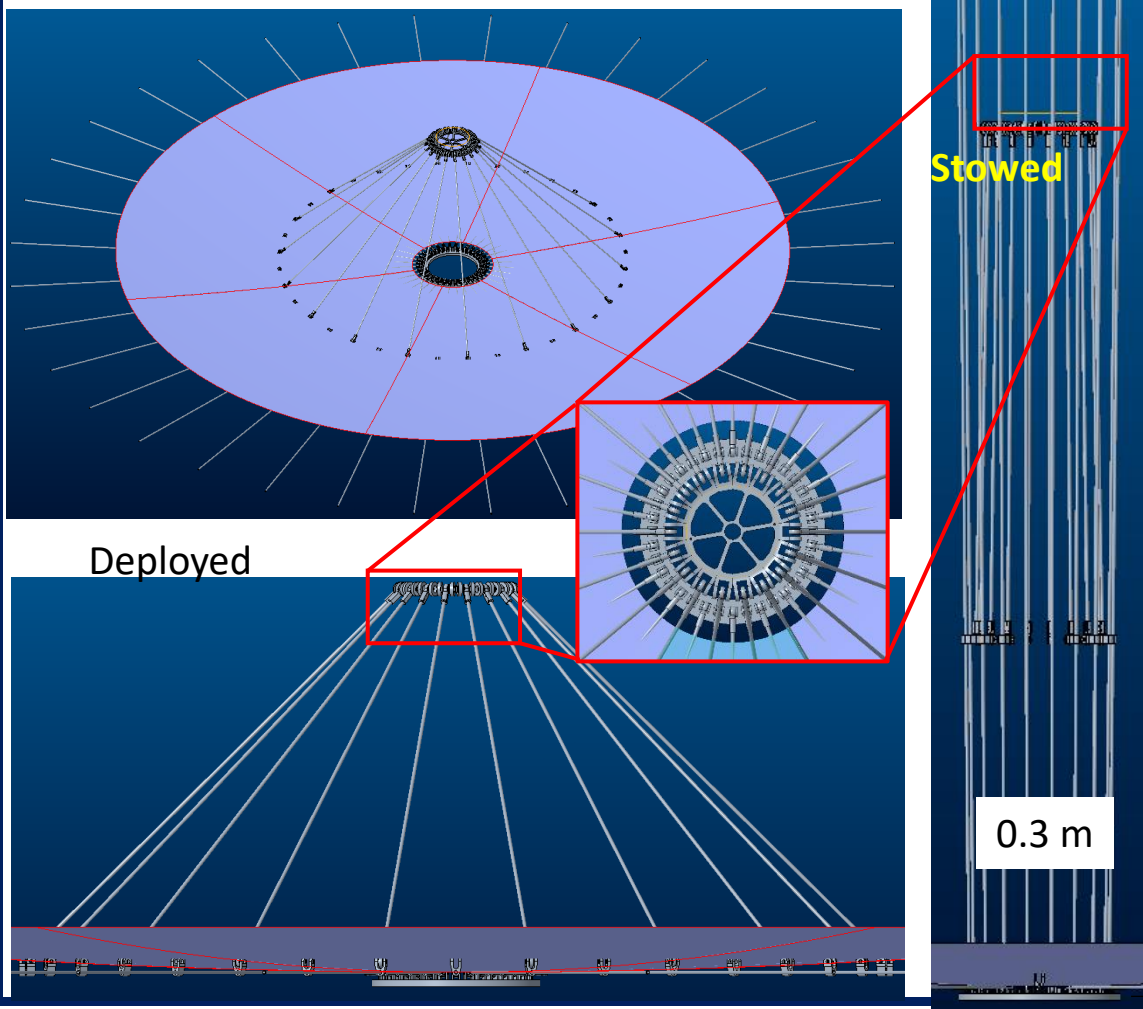


• Thin film heaters were fabricated by Pennsylvania State University under a Collaboration Research Agreement.

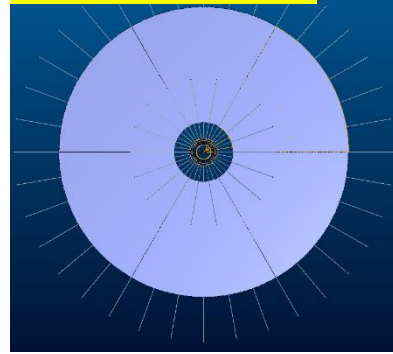


# Design 2: Umbrella-Folded Reflector Packaging Scheme

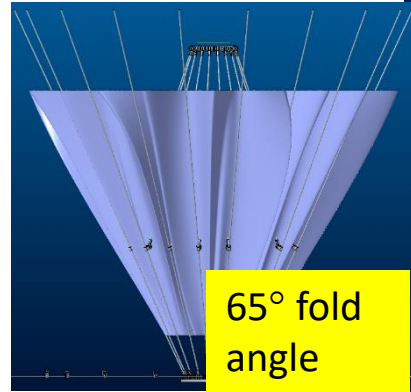
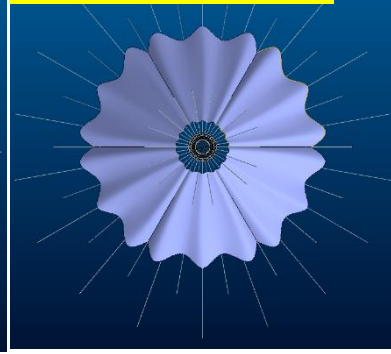
3 meter-diameter thin-shell reflector with ground support equipment (GSE) push rods for folding like an umbrella



0° fold angle



40° fold angle



65° fold angle



1/6 Gore of 3 meter-paraboloid dish was fabricated for folding test

