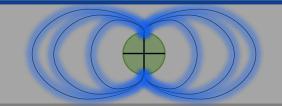


OS Dependencies on CPU SEFIs

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Acronym List

OS: Operating System **SoC:** System-on-Chip SoCs: Systems-on-Chip TFTP: Trivial File Transfer Protocol **MM:** Matrix Multiplication **<u>SEFI</u>**: Single-Event Functional Interrupt **<u>CPU</u>**: Central Processing Unit **<u>RAM</u>**: Random-Access Memory **<u>TLYF</u>:** Test Like You Fly **TFTP:** Trivial File Transfer Protocol





- Linux operating system configuration variables
 - Which one has most affect?
 - How is this information useful to reliability/availability?
- Experimental controls
 - How was the test designed?
 - How do we control the experiment to know what we were finding?
- Where do we go from here?
 - How does this help us with standardization?
 - Future work



Problem Statement

- SoCs are complex
 - Hard to test
 - Hard to isolate complications and subsystems



- Current Fix: "Test as you Fly" or "Test Like You Fly" (TLYF)
 - Test the exact configuration and software as is going to be on mission
 - Any change, even compilation/optimization flags, could invalidate tests
- Need to find and standardize experimental controls
 - Control and isolate experimental variables to observe effects
 - Find correlations between isolated subsystems and reliability

SoCs: Systems-on-Chip



What do we already know?

- Linux system memory in two key parts
 - User space
 - Kernel space
- Hardware drivers exist in kernel space
 - Necessary to bridge the gap between hardware and OS
 - Huge part of the kernel are drivers
- Driver crash or failure can lead to kernel panic
 - Hangs entire system
 - \Rightarrow Drivers leading cause of significant kernel failures

USER SPACE KERNEL SPACE	Address	Data	
	0000 0000	ΥΥΥΥ ΥΥΥΥ	
	0000 0001	ΥΥΥΥ ΥΥΥΥ	
	XXXX XXXX	ΥΥΥΥ ΥΥΥΥ	
	XXXX XXX(X+1)	ΥΥΥΥ ΥΥΥΥ	
	FFFF FFFF	ΥΥΥΥ ΥΥΥΥ	
		*simplified for illustration	

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Linux Setup

- PYNQ-Z2 SoC
 - Artix-7 FPGA fabric
 - Dual-core ARM Cortex-A9 processor



- Generate Buildroot Linux images for **16 configurations**
 - Ensure minimalist Linux image with as many parts known as possible
 - Use same first-stage bootloader (boot.bin) for all configurations
- Initramfs
 - Load entire image in RAM via TFTP boot
 - Refresh each reboot to fresh image.
 - Operations and driver setup run with initscripts
- Expect drivers to have impact on system reliability

SoC: System-on-Chip **TFTP**: Trivial File Transfer Protocol



OS Variables



L2 Cache	Operation	Num. Drivers	Loaded State
ON	MM		LOADED
ON	MM	LARGE	UNLOADED
ON	500 × 500 MM	JIVIALL	Drivers LOADED
ON	MM	Built-In SMALL LC	unloaded UNLOADED
ON	IDLE	LARGE	LOADED
ON (IDLE	LARGE	UNLOADED
ON	Sleep 10 sec IDLE	SMALL	LOADED
ON	IDLE	SMALL 10	UNLOADED
OFF	MM		Drivers LOADED
OFF	MM	LARGE	UNLOADED
OFF	MM	SMALL	LOADED
OFF	MM	SMALL	UNLOADED
OFF	IDLE	LARGE	LOADED
OFF	IDLE	LARGE	UNLOADED
OFF	IDLE	SMALL	LOADED
OFF	IDLE	SMALL	UNLOADED

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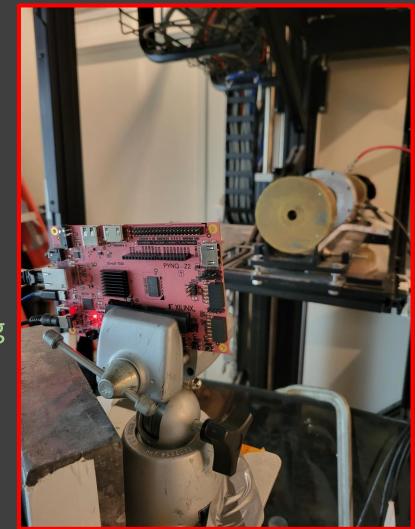
MM: Matrix Multiplication



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Methodology

- MGH Proton Therapy Clinic
 - 200 MeV p^+
 - ~ $10^8 \frac{p^+}{cm^2 s}$ flux
- System booted and stable between each run
 - Power cycle via web-powered power switch
 - Image pulled from host computer via TFTP boot in u-boot
 - Beam only on when operations began for fluence tracking
- ~15 runs for each configuration



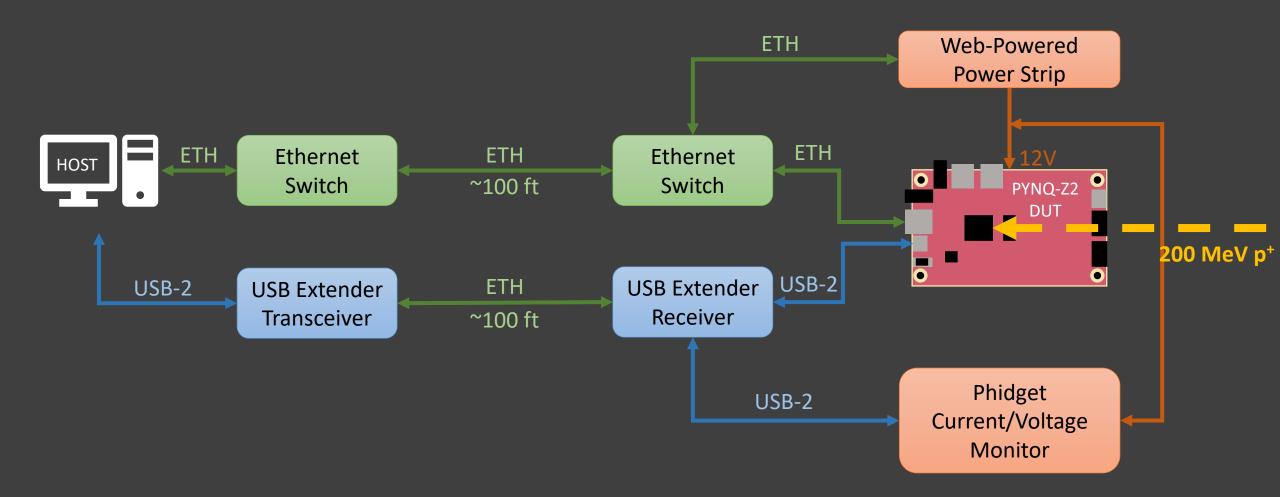
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TFTP: Trivial File Transfer Protocol



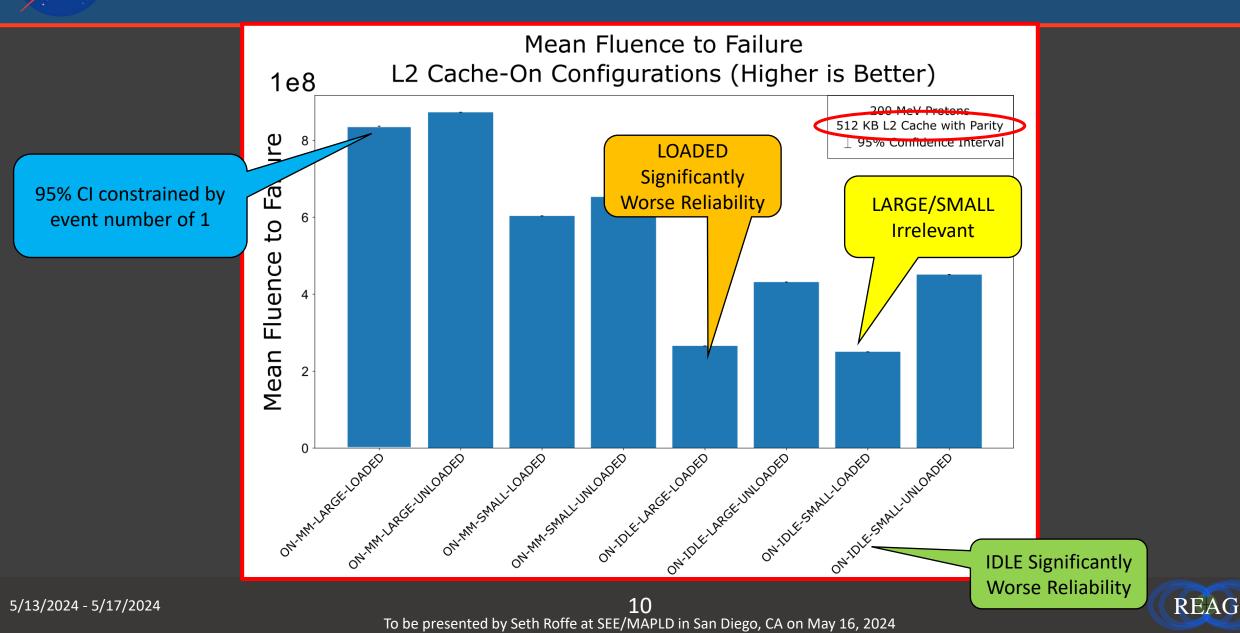


Experimental Setup

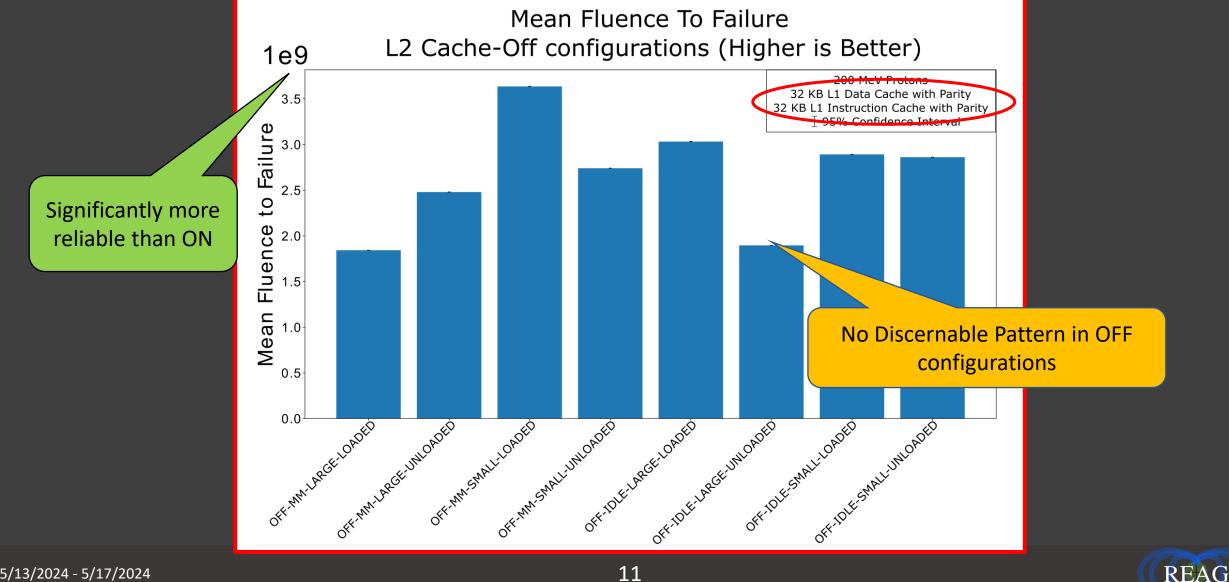




Mean Fluence to Failure (Cache ON)



Mean Fluence to Failure (Cache OFF)

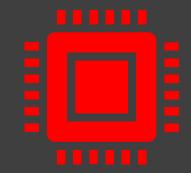


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Extrapolations and Implications

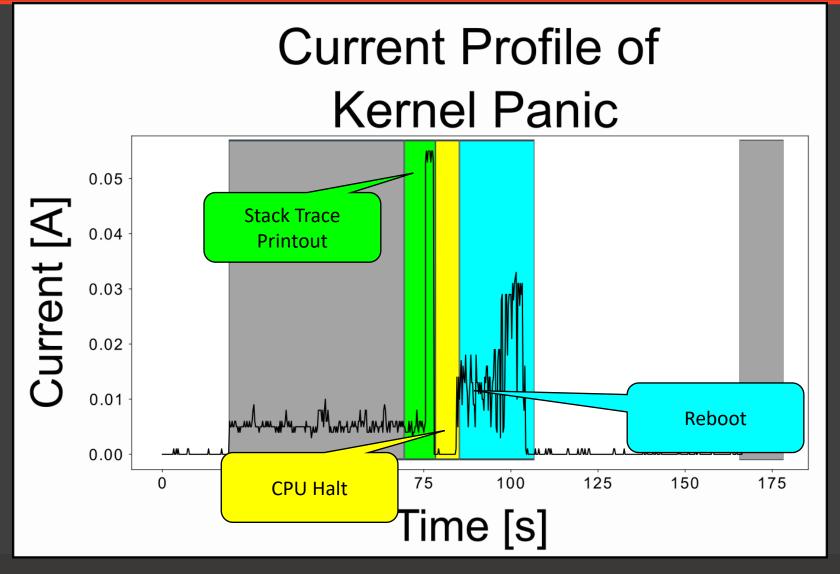
- Reliability/Available more easily understood when L2-Cache is ON
- LARGE/SMALL show no significant difference
 - May be a sample size problem
- Drivers do have an effect via LOADED with insmod
 - Unload unused drivers when not needed
- IDLE significantly more vulnerable to SEFI than MM
 - Critical data flushed in L2 when math is being performed
 - Current operations have an impact on the reliability
- Understanding the memory hierarchy is critical



MM: Matrix Multiplication **SEFI:** Single-Event Functional Interrupt



Some Extra Interesting Results

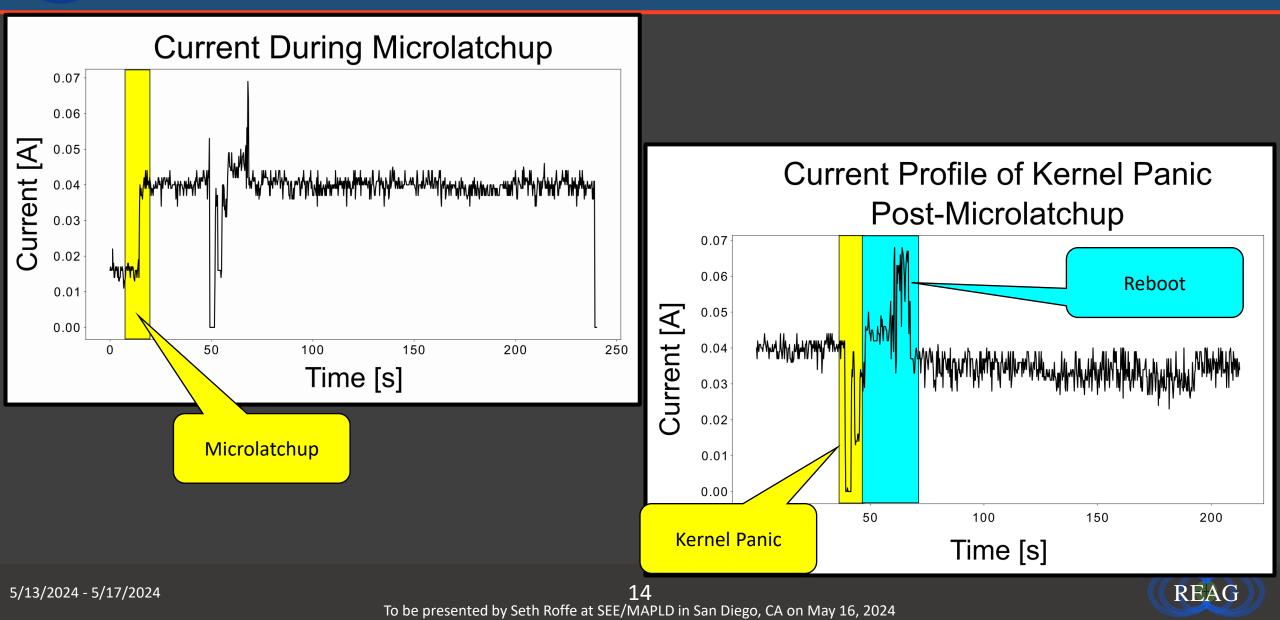


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Conclusions and Future Work

- Things are hard
 - Many variables to keep track of
 - TLYF is not as effective as we may think
- Replication for better statistics
- Extend to other Architectures
 - RISC-V
 - GPUs and other Accelerators
- Optimize test procedures
 - Design specific TLYF to ensure coverage
 - Compile dependencies of a system







Thank you for your time!

Questions? Comments? Philosophies?

Single Event Effects (SEE) Symposium Military & Aerospace Programmable Logic Devices (MAPLD) Combined Workshop



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